6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

General Description

The MAX14483 is a 6-channel, 3.75kV_{RMS} digital galvanic isolator using Maxim's proprietary process technology. The six signal channels are individually optimized for SPI applications and include very low propagation delay on the SDI, SDO, and SCLK channels. The SDO channel's tri-state control is enabled by the \overline{CS} input as well as a second enable control input pin (SDOEN), allowing a single MAX14483 to isolate multiple SPI devices. To simplify system design, an open drain FAULT output can be wire ORed with error outputs from other devices. In addition, an auxiliary channel (AUX) is available for passing timing or control signals from the master side to the slave side and power monitors (SAA, SBA) are provided for both power domains to signal if the opposite side of the isolator is ready for operation. Independent 1.71V to 5.5V supplies on each side of the isolator also make the device suitable for use as a level translator.

The MAX14483 has an isolation rating of $3.75 kV_{RMS}$ for 60 seconds and is available in a 20-pin SSOP package with 5.5mm of creepage and clearance. The package material has a minimum comparative tracking index (CTI) of 400V, which gives it a group 2 rating in creepage tables.

The MAX14483 is rated for operation at ambient temperatures of -40°C to +125°C.

Applications

- Programmable Logic Controllers
- Industrial Automation
- Process Automation
- Building Automation
- Robotics
- General SPI-bus Isolation

Benefits and Features

- Saves Space and Components
 - 6 Isolated Channels in a 20-SSOP Package
- Low Propagation Delay on SCLK, SDI, and SDO
 - Up to 100MHz Clock, 200Mbps Data Rate
 - 10ns Typical Propagation Delay
 - · 2ns Maximum Pulse Width Distortion
 - 250ps Typical Peak Jitter
- Robust Galvanic Isolation of Digital Signals
 - Withstands 3.75kV_{RMS} for 60s (VISO)
 - Continuously Withstands 450V_{RMS} (V_{IOWM})
 - Withstands ±10kV Surge between GNDA and GNDB with 1.2/50µs Waveform
 - High CMTI (50kV/µs, Typical)
- Flexible System Design
 - Wide 1.71V to 5.5V Voltage Range on Each Side
 - SDOEN Control Pin for Sharing Isolators
 - Open Drain FAULT Channel for Shared Interrupt on Master Side
 - · Auxiliary Channel for Timing or Control
- Low Power Consumption
 - 1.53mW per Channel at SCLK = 10MHz with V_{DD} = 3.3V
 - 0.77mW per Channel at SCLK = 10MHz with V_{DD} = 1.8V

Safety Regulatory Approvals (Pending)

- UL According to UL1577
- cUL According to CSA Bulletin 5A

<u>Ordering Information</u> and <u>Typical Operating Circuits</u> appear at end of data sheet.



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Absolute Maximum Ratings

V _{DDA} to GNDA, V _{DDB} to GNDB0.3V to +6V	Short Circuit Continuous Current (OFAULT) 100mA
ICS, ISCLK, ISDI, IAUX, SDOEN, OFAULT	Continuous Power Dissipation
to GNDB0.3V to +6V	Single Layer Board T _A = +70°C640mW
OSDO, SAA to GNDB0.3V to (V _{DDB} + 0.3V)	Derate above +70°C8mW/°C
ISDO, IFAULT, IRDY to GNDA0.3V to +6V	Multilayer Board T _A = +70°C964mW
OCS, OSCLK, OSDI, OAUX, SBA	Derate above +70°C12mW/°C
to GNDA0.3V to (V _{DDA} + 0.3V)	Operating Temperature Range40°C to +125°C
Short-Circuit Duration	Maximum Junction Temperature+150°C
OCS, OSCLK, OSDI, OAUX, SBA to V _{DDA}	Storage Temperature Range60°C to +150°C
or GNDAContinuous	Soldering Temperature (reflow)+260°C
OSDO, SAA to V _{DDB} or GNDBContinuous	

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Thermal Characteristics

Thermal Resistance, Single Layer Board

 Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

DC Electrical Characteristics

 $(V_{DDA} - V_{GNDA} = 1.71V \text{ to } 5.5V, V_{DDB} - V_{GNDB} = 1.71V \text{ to } 5.5V, T_A = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ unless otherwise noted}. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^{\circ}\text{C}, \text{ unless otherwise noted}.) (Note 1)$

PARAMETER	SYMBOL	CONDITIC	NS	MIN	ТҮР	MAX	UNITS
POWER SUPPLY	·	·					
Supply Voltage	V _{DDA}	Relative to GNDA		1.71		5.5	V
	V _{DDB}	Relative to GNDB		1.71		5.5	V
Undervoltage-Lockout Threshold	V _{UVLO} _	V _{DD} _rising		1.5	1.6	1.66	V
Undervoltage-Lockout Threshold Hysteresis	V _{UVLO_HYST}				45		mV
		$\overline{\text{IRDY}} = 0V, \overline{\text{SDOEN}} =$	V _{DDA} = 5V		1.07	1.86	
		0V, all other inputs = 500kHz square wave,	V _{DDA} = 3.3V		1.04	1.81	
			V _{DDA} = 2.5V		1.03	1.79	
Supply Current Side A		C _L = 0pF	V _{DDA} = 1.8V		1.00	1.59	mA
(Note 2)	IDDA	10MHz square wave	V _{DDA} = 5V		1.71	2.59	
		on ISCLK, 5MHz	V _{DDA} = 3.3V		1.46	2.32	
		square wave on ISDO and ISDI, all other	V _{DDA} = 2.5V		1.39	2.21	
		inputs = 0V, $C_L = 0pF$	V _{DDA} = 1.8V		1.30	1.94	

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DC Electrical Characteristics (continued)

 $(V_{DDA} - V_{GNDA} = 1.71V \text{ to } 5.5V, V_{DDB} - V_{GNDB} = 1.71V \text{ to } 5.5V, T_A = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ unless otherwise noted}. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^{\circ}\text{C}, \text{ unless otherwise noted}.) (Note 1)$

PARAMETER	SYMBOL	CONDITIC	NS	MIN	TYP	MAX	UNITS
		$\overline{\text{IRDY}} = 0V, \overline{\text{SDOEN}} =$	V _{DDB} = 5V		0.92	1.64	
		0V, all other inputs =	V _{DDB} = 3.3V		0.90	1.59	
			V _{DDB} = 2.5V		0.88	1.57	
Supply Current Side B		C _L = 0pF	V _{DDB} = 1.8V		0.86	1.27	
(Note 2)	IDDB	10MHz square wave	V _{DDB} = 5V		1.46	2.30	mA
		on ISCLK, 5MHz	V _{DDB} = 3.3V		1.33	2.18	
		square wave on ISDO and ISDI, all other	V _{DDB} = 2.5V		1.33	2.14	
		inputs = 0V, $C_L = 0pF$	V _{DDB} = 1.8V		1.28	1.80	
LOGIC INPUTS AND OUTPUTS							
		2.25V ≤ V _{DD} _ ≤ 5.5V		0.7 x V _{DD} _			
Input High Voltage	V _{IH}	1.71V ≤ V _{DD} _ < 2.25V		0.75 x V _{DD} _			V
		$2.25V \le V_{DD} \le 5.5V$				0.8	v
Input Low Voltage	VIL	1.71V ≤ V _{DD} < 2.25V				0.7	
Input Hysteresis	V _{HYS}				410		mV
Input Pullup Current (Note 3)	I _{PU}	IAUX, ICS, SDOEN, IRI	YC	-10	-5	-1.5	μA
Input Pulldown Current (Note 3)	I _{PD}	IFAULT, ISDO, ISDI, IS	CLK	1.5	5	10	μA
Input Capacitance	C _{IN}	f _{SW} = 1MHz			2		pF
Output Voltage High (Note 3)	V _{OH}	V _O _relative to GND_ I _O _ = 4mA source		V _{DD} 0.4			v
Output Voltage Low (Note 3)	V _{OL}	V _O _ relative to GND_ I _O _ = 4mA sink				0.4	V
Output High-Impedance Leakage Current (Note 3)	I _{OL}	OSDO, OFAULT		-1		1	μA

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Dynamic Characteristics

 $(V_{DDA} - V_{GNDA} = 1.71V \text{ to } 5.5V, V_{DDB} - V_{GNDB} = 1.71V \text{ to } 5.5V, C_L = 15\text{pF}, T_A = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ unless otherwise noted}. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^{\circ}\text{C}, \text{ unless otherwise noted}.) (Note 2)$

PARAMETER	SYMBOL	C	ONDITIONS	MIN	TYP	MAX	UNITS
LOW DATA RATE CHANNELS	- IFAULT, OF	AULT, IAUX, OA	UX, ĪCS, OCS				
Common-Mode Transient Immunity	СМТІ	I_ = GND_ or V	_{DD_} (Note 4)		50		kV/µs
Maximum Data Rate	DR _{MAX}			25			Mbps
Minimum Pulse Width	PW _{MIN}	I_ to O_				40	ns
Glitch Rejection		I_ to O_		10	17	29	ns
			$4.5V \le V_{DD} \le 5.5V$	17.4	23.9	32.5	
		I_ to O_,	$3.0V \le V_{DD} \le 3.6V$	17.6	24.4	33.7	
	touu	C _L = 15pF	$2.25V \le V_{DD} \le 2.75V$	18.3	25.8	36.7	ns
	^t PLH		1.71V ≤ V _{DD} _ ≤ 1.89V	20.7	29.6	43.5	
Propagation Delay (Figure 1)		IFAULT to OFAULT	Open drain output, $R_{pullup} = 10k\Omega$, $C_L = 15pF$		150		
		I_to O_, C _L = 15pF	$4.5V \le V_{DD} \le 5.5V$	16.9	23.4	33.6	_
			$3.0V \le V_{DD} \le 3.6V$	17.2	24.2	35.1	
	t _{PHL}		2.25V ≤ V _{DD} ≤ 2.75V	17.8	25.4	38.2	ns
				1.71V ≤ V _{DD} ≤ 1.89V	19.8	29.3	45.8
Pulse Width Distortion	PWD	t _{PLH} - t _{PHL}			0.4	4	ns
		$4.5V \le V_{DD} \le 5$	5.5V			15.1	
	tanu	$3.0V \le V_{DD} \le 3$	3.6V			15	
	^t SPLH	$2.25V \le V_{DD} \le$	2.75V			15.4	
Propagation Delay Skew		1.71V ≤ V _{DD} _ ≤	1.89V			20.5	
Part-to-Part (Same Channel)		$4.5V \le V_{DD} \le 5$	5.5V			13.9	ns
	t	$3.0V \le V_{DD} \le 3$	3.6V			14.2	
	t _{SPHL}	2.25V ≤ V _{DD} _ ≤	2.75V			16]
		1.71V ≤ V _{DD} _ ≤	1.89V			21.8	
Propagation Delay Skew	^t SCSLH	1.71V ≤ V _{DD} _ ≤	5.5V			2	ns
Channel-to-Channel (Same Direction)	^t SCSHL	1.71V ≤ V _{DD} _≤	5.5V			2	115

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Dynamic Characteristics (continued)

 $(V_{DDA} - V_{GNDA} = 1.71V \text{ to } 5.5V, V_{DDB} - V_{GNDB} = 1.71V \text{ to } 5.5V, C_L = 15\text{pF}, T_A = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ unless otherwise noted}. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^{\circ}\text{C}, \text{ unless otherwise noted}.) (Note 2)$

PARAMETER	SYMBOL	С	ONDITIONS	MIN	ТҮР	MAX	UNITS
		$4.5V \le V_{DD} \le 5$	5.5V			13.9	
		$3.0V \le V_{DD} \le 3$	3.6V			13.7]
	^t SCOLH	2.25V ≤ V _{DD} _ ≤			14.2]	
Propagation Delay Skew		1.71V ≤ V _{DD} _ ≤	1.89V			19.4	
Channel-to-Channel (Opposite Direction)		$4.5V \le V_{DD} \le 5.5V$				13	ns
($3.0V \le V_{DD_{-}} \le 3$	3.6V			12.9	
	^t SCOHL	2.25V ≤ V _{DD} _ ≤	2.75V			14.4	
		1.71V ≤ V _{DD} _ ≤	1.89V			20.1]
Peak Eye Diagram Jitter	T _{JIT(PK)}	25Mbps			250	-	ps
		$4.5V \le V_{DD} \le 5$	5.5V			1.6	
		$3.0V \le V_{DD} \le 3$	3.6V			2.2]
Rise Time (Figure 1)	t _R	2.25V ≤ V _{DD} _ ≤	2.75V			3	ns
		$1.71V \le V_{DD} \le 1.89V$				4.5	1
		$4.5V \le V_{DD} \le 5$	5.5V			1.4	
		$3.0V \le V_{DD} \le 3.6V$				2	ns
Fall Time (Figure 1)	t _F	2.25V ≤ V _{DD} ≤			2.8		
		1.71V ≤ V _{DD} _ ≤	1.89V			5.1	
SPI DATA RATE CHANNELS	S - ISDI, OSDI, I	SDO, OSDO, ISO	LK, OSCLK				
Common-Mode Transient Immunity	СМТІ	I_ = GND_ or V _I	DD_(Note 4)		50		kV/µs
		2.25V ≤ V _{DD} ≤	5.5V	200			
Maximum Data Rate	DR _{MAX}	1.71V ≤ V _{DD} ≤	1.89V	150			Mbps
	514		$2.25V \le V_{DD} \le 5.5V$			5	
Minimum Pulse Width	PW _{MIN}	I_ to O_	1.71V ≤ V _{DD} ≤ 1.89V			6.67	ns
			4.5V ≤ V _{DD} ≤ 5.5V	4.1	5.4	9.2	
		I_ to O_,	$3.0V \le V_{DD} \le 3.6V$	4.2	5.9	10.2	1
	^t PLH	C _L = 15pF	2.25V ≤ V _{DD} ≤ 2.75V	4.9	7.1	13.4	
Propagation Delay (Figure 1)			1.71V ≤ V _{DD} ≤ 1.89V	7.1	10.9	20.3	-
			$4.5V \le V_{DD} \le 5.5V$	4.3	5.6	9.4	ns
		I_ to O_,	$3.0V \le V_{DD} \le 3.6V$	4.4	6.2	10.5	1
	^t PHL	$\overline{C_L} = 15pF$	2.25V ≤ V _{DD} ≤ 2.75V	5.1	7.3	14.1	1
				7.2	10.9	21.7	1
Pulse Width Distortion	PWD	t _{PLH} - t _{PHL}	_		0.3	2	ns

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Dynamic Characteristics (continued)

 $(V_{DDA} - V_{GNDA} = 1.71V \text{ to } 5.5V, V_{DDB} - V_{GNDB} = 1.71V \text{ to } 5.5V, C_L = 15\text{pF}, T_A = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ unless otherwise noted}. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^{\circ}\text{C}, \text{ unless otherwise noted}.) (Note 2)$

PARAMETER	SYMBOL	cc	NDITIONS	MIN	ТҮР	MAX	UNITS	
		$4.5V \le V_{DD} \le 5.$	5V			3.7		
		$3.0V \le V_{DD} \le 3.$	6V			4.3		
	tSPLH	$2.25V \le V_{DD} \le 2.75V$				6		
Propagation Delay Skew		1.71V ≤ V _{DD} _ ≤ 7	I.89V			10.3		
Part-to-Part (Same Channel)		$4.5V \le V_{DD} \le 5.$	5V			3.8	ns	
		$3.0V \le V_{DD} \le 3.$	6V			4.7		
	tSPHL	2.25V ≤ V _{DD} _ ≤ 2	2.75V			6.5		
		1.71V ≤ V _{DD} _ ≤ 7	I.89V			11.5		
Propagation Delay Skew	t _{SCSLH}					2		
Channel-to-Channel (Same Direction)	t _{SCSHL}					2	ns	
		$4.5V \le V_{DD} \le 5.$	5V			2.9		
		$3.0V \le V_{DD} \le 3.$				3.4	-	
	t _{SCOLH}	2.25V ≤ V _{DD} ≤ 2				4.9		
Propagation Delay Skew		1.71V ≤ V _{DD} ≤ 1			10.2			
Channel-to-Channel (Opposite Direction)		4.5V ≤ V _{DD} ≤ 5.	5V	3.2			ns	
		$3.0V \le V_{DD} \le 3.$			3.8			
	^t SCOHL	2.25V ≤ V _{DD} ≤ 2.75V			5.3		5.3	
			I.89V			10.9	1	
Peak Eye Diagram Jitter	T _{JIT(PK)}	200Mbps			250		ps	
Clock Jitter RMS	T _{JCK(RMS)}	500kHz Clock Inp	out, Rising/Falling Edges		6.5		ps	
		4.5V ≤ V _{DD} _ ≤ 5.	5V			1.6		
Diag Time		$3.0V \le V_{DD} \le 3.6V$				2.2]	
Rise Time	t _R	2.25V ≤ V _{DD} ≤ 2.75V				3	ns	
		1.71V ≤ V _{DD} ≤ 1.89V				4.5		
		$4.5V \le V_{DD} \le 5.$	5V			1.4		
Fall Time	+_	$3.0V \le V_{DD} \le 3.6V$				2	1	
	t _F	$2.25V \le V_{DD} \le 2$	2.75V			2.8	ns	
		$1.71V \le V_{DD} \le C$	I.89V			5.1		
		ICS or SDOEN	$4.5 V \leq V_{DD} \leq 5.5 V$			31.3		
Enable to Data Valid	t	falling to OSDO	$3.0V \le V_{DD} \le 3.6V$			34.8	ne	
	t _{EN}	valid,	$2.25V \le V_{DD} \le 2.75V$			40.0	ns	
		C _L = 15pF	1.71V ≤ V _{DD} _ ≤ 1.89V			51.8	1	
		ICS or SDOEN	$4.5V \le V_{DD} \le 5.5V$			33.9		
Disable to Tri-state	tro	rising to OSDO	$3.0V \le V_{DD} \le 3.6V$			38.6		
	trri	tristate, C _L = 15pF	$2.25V \le V_{DD} \le 2.75V$			44.4	ns	
	C		1.71V ≤ V _{DD} ≤ 1.89V			55		

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Dynamic Characteristics (continued)

 $(V_{DDA} - V_{GNDA} = 1.71V \text{ to } 5.5V, V_{DDB} - V_{GNDB} = 1.71V \text{ to } 5.5V, C_L = 15\text{pF}, T_A = -40^\circ\text{C} \text{ to } +125^\circ\text{C}, \text{ unless otherwise noted}. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^\circ\text{C}, \text{ unless otherwise noted}.) (Note 2)$

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
CONTROL AND MONITOR CH	IANNELS - IR	DY, SDOEN, SAA, SBA	·			
Common-Mode Transient Immunity	CMTI	I_ = GND_ or V _{DD} _ (Note 4)		50		kV/µs
Glitch Rejection		SDOEN	10	17	29	ns
Propagation Delay	t _{PLH}	IRDY low to high		100		
	t _{PHL}	IRDY high to low		100		- µs
		$4.5V \le V_{DD} \le 5.5V$			1.6	
Rise Time	+_	$3.0V \le V_{DD} \le 3.6V$			2.2	ns
Rise Time	t _R	$2.25V \le V_{DD} \le 2.75V$			3	
		$1.71V \le V_{DD} \le 1.89V$			4.5	
		$4.5V \le V_{DD} \le 5.5V$			1.4	
Fall Time	↓ <u>+</u>	$3.0V \le V_{DD} \le 3.6V$			2	
	t _F	$2.25V \le V_{DD} \le 2.75V$			2.8	– ns
		1.71V ≤ V _{DD} _ ≤ 1.89V			5.1	

Note 1: All devices are 100% production tested at T_A = +25°C. Specifications over temperature are guaranteed by design.

Note 2: Not production tested. Guaranteed by design and characterization.

Note 3: All currents into the device are positive. All currents out of the device are negative. All voltages are referenced to their respective ground (GNDA or GNDB), unless otherwise noted.

Note 4: CMTI is the maximum sustainable common-mode voltage slew rate while maintaining the correct output. CMTI applies to both rising and falling common-mode voltage edges. Tested with the transient generator connected between GNDA and GNDB (V_{CM} = 1000V).

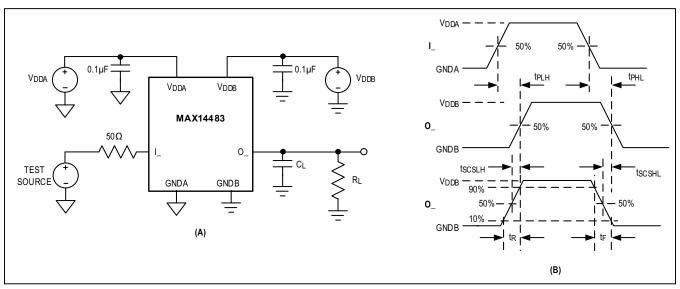


Figure 1. Test Circuit (A) and Timing Diagram (B)

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ESD Protection

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
ESD		Human Body Model, all pins		±4		kV

Insulation Characteristics

Table 1. 20-pin SSOP Insulation Characteristics

PARAMETER	SYMBOL	CONDITIONS	VALUE	UNITS
Partial Discharge Test Voltage	V _{PR}	Method B1 = V _{IORM} x 1.875 (t = 1s, partial discharge < 5pC)	1050	VP
Maximum Repetitive Peak Isolation Voltage	V _{IORM}	(Note 5)	560	V _P
Maximum Working Isolation Voltage	VIOWM	Continuous RMS voltage (Note 5)	400	V _{RMS}
Maximum Transient Isolation Voltage	V _{IOTM}	t = 1s	5300	VP
Maximum Withstand Isolation Voltage	V _{ISO}	f _{SW} = 60Hz, duration = 60s (Note 5, 6)	3750	V _{RMS}
Maximum Surge Isolation Voltage	V _{IOSM}	Basic Insulation, 1.2/50µs pulse per IEC61000-4-5	10	kV
		V _{IO} = 500V, T _A = 25°C	>10 ¹²	
Insulation Resistance	R _{IO}	V _{IO} = 500V, 100°C ≤ T _A ≤ 125°C	>10 ¹¹	Ω
		V _{IO} = 500V, T _S = 150°C	>10 ⁹	
Barrier Capacitance Side A to Side B	CIO	f _{SW} = 1MHz (Note 7)	1.5	pF
Minimum Creepage Distance	CPG	SSOP	5.5	mm
Minimum Clearance Distance	CLR	SSOP	5.5	mm
Internal Clearance		Distance through insulation	0.015	mm
Comparative Tracking Index	СТІ	Material Group II (IEC 60112)	>400	
Climate Category			40/125/21	
Pollution Degree (DIN VDE 0110, Table 1)			2	

Note 5: V_{ISO} , V_{IOWM} , and V_{IORM} are defined by the IEC 60747-5-5 standard. **Note 6:** Product is qualified at V_{ISO} for 60s and 100% production tested at 120% of V_{ISO} for 1s. **Note 7:** Capacitance is measured with all pins on side A and side B tied together.

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Safety Limits

Damage to the IC can result in a low-resistance path to ground or to the supply and, without current limiting, the MAX14483 could dissipate excessive amounts of power. Excessive power dissipation can damage the die and result in damage to the isolation barrier, potentially causing downstream issues. <u>Table 2</u> shows the safety limits for the MAX14483.

The maximum safety temperature (T_S) for the device is the 150°C maximum junction temperature specified in the <u>Absolute Maximum Ratings</u>. The power dissipation (P_D) and junction-to-ambient thermal impedance (θ_{JA}) determine

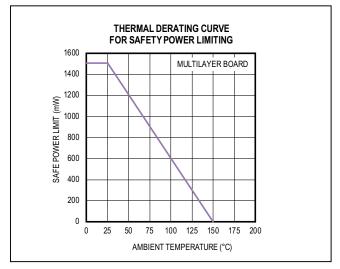


Figure 2. Thermal Derating Curve for Safety Power Limiting

the junction temperature. Thermal impedance values $(\theta_{JA} \text{ and } \theta_{JC})$ are available in the <u>Package Thermal</u> <u>Characteristics</u> section of the datasheet and power dissipation calculations are discussed in the Calculating Power Dissipation section. Calculate the junction temperature (T_J) as:

$$T_J = T_A + (P_D \times \theta_{JA})$$

<u>Figure 2</u> and <u>Figure 3</u> show the thermal derating curve for safety limiting the power and the current of the device. Ensure that the junction temperature does not exceed 150° C.

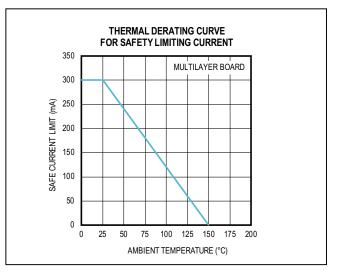


Figure 3. Thermal Derating Curve for Safety Current Limiting

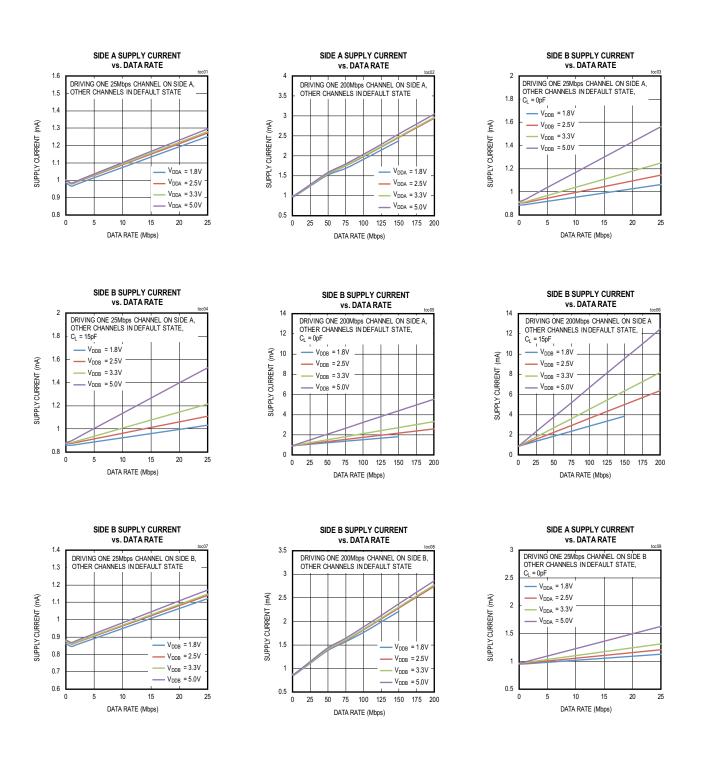
Table 2. Safety Limiting Values for the MAX14483

PARAMETER	SYMBOL	TEST CONDITIONS	MAX	UNIT
Safety Current on Any Pin	IS	T _J = 150°C, T _A = 25°C, Multilayer Board	300	mA
Total Safety Power Dissipation	PS	T _J = 150°C, T _A = 25°C, Multilayer Board	1506	mW
Maximum Safety Temperature	T _S		150	°C

6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Typical Operating Characteristics

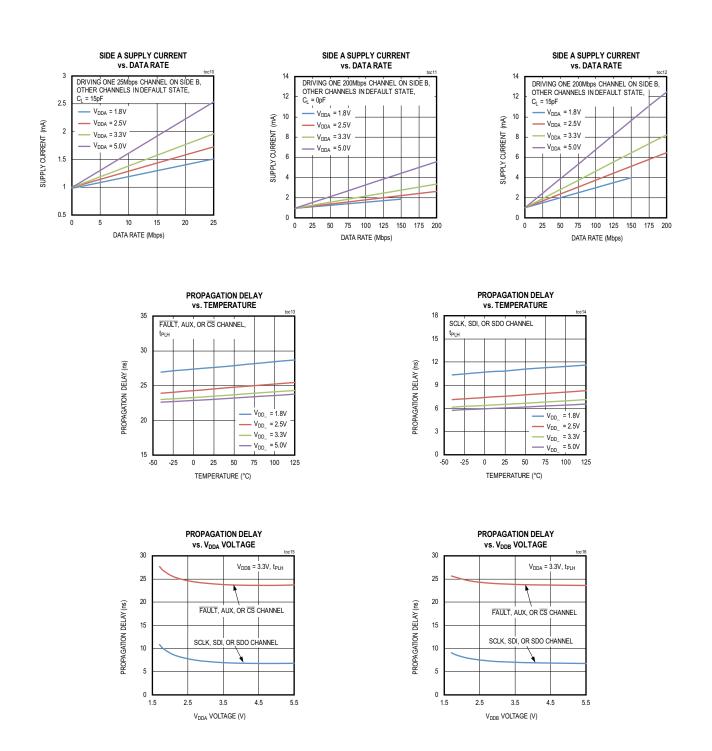
(V_{DDA} - V_{GNDA} = +3.3V, V_{DDB} - V_{GNDB} = +3.3V, V_{GNDA} = V_{GNDB}, T_A = +25°C, unless otherwise noted.)



6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Typical Operating Characteristics (continued)

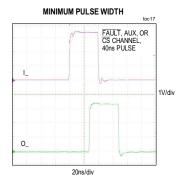
(V_{DDA} - V_{GNDA} = +3.3V, V_{DDB} - V_{GNDB} = +3.3V, V_{GNDA} = V_{GNDB}, T_A = +25°C, unless otherwise noted.)

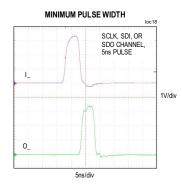


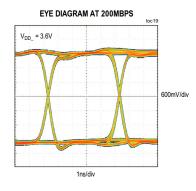
6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

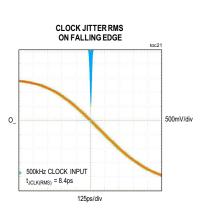
Typical Operating Characteristics (continued)

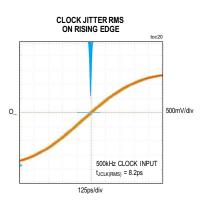
 $(V_{DDA} - V_{GNDA} = +3.3V, V_{DDB} - V_{GNDB} = +3.3V, V_{GNDA} = V_{GNDB}, T_A = +25^{\circ}C$, unless otherwise noted.)

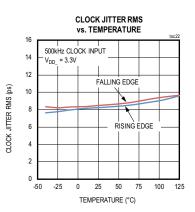












6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

TOP VIEW 20 VDDB 1 Vdda MAX14483 19 SAA IRDY 2 18 OFAULT IFAULT 3 17 OSDO ISDO 4 16 IAUX OAUX 5 15 ISDI OSDI 6 14 ISCLK OSCLK 7 OCS 8 13 ICS 12 SDOEN SBA 9 11 GNDB GNDA 10 **20 SSOP**

Pin Configurations

Pin Description

PIN	NAME	FUNCTION	REFERENCE
SIDE A (SPI SLAVE)		
1	V _{DDA}	Power Supply. Bypass $V_{\mbox{DDA}}$ with a $0.1\mu\mbox{F}$ ceramic capacitor as close as possible to the pin.	GNDA
2	ĪRDY	Ready Input. Assert \overline{IRDY} low when Side A is ready for communication. When \overline{IRDY} is high, SAA is low and Side B outputs are in their default state (\overline{OFAULT} is low and OSDO is low when enabled). When \overline{IRDY} is low, and Side A power is valid, SAA is high and Side B outputs operate normally. If the ready function is not required, tie \overline{IRDY} to GNDA.	GNDA
3	IFAULT	Input to FAULT channel; has a weak internal pulldown.	GNDA
4	ISDO	Input to SDO channel; has a weak internal pulldown. Connect to MISO of slave device(s).	GNDA
5	OAUX	Output of AUX channel.	GNDA
6	OSDI	Output of SDI channel. Connect to MOSI of slave device(s).	GNDA
7	OSCLK	Output of SCLK channel. Connect to SCLK of slave device(s).	GNDA
8	OCS	Output of \overline{CS} channel. Connect to \overline{CS} of slave device(s).	GNDA

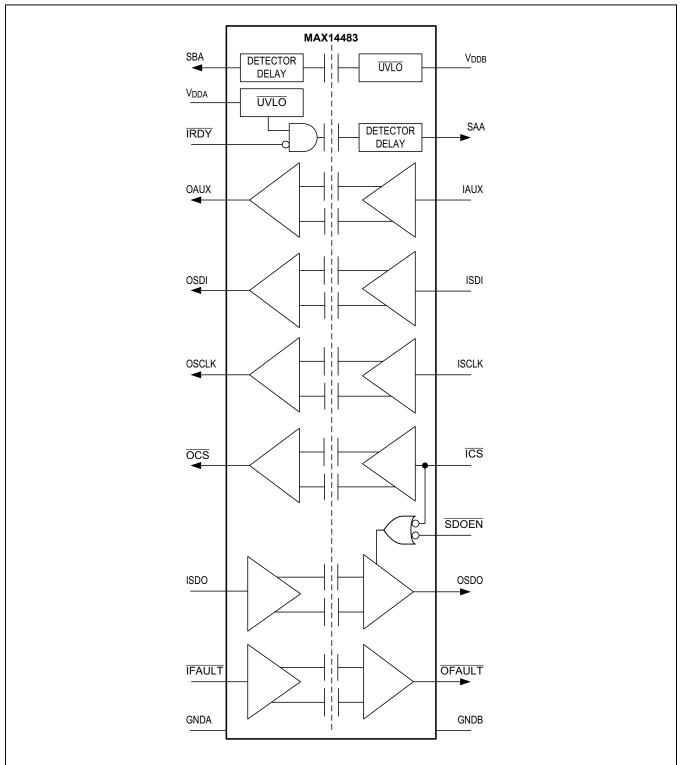
6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Pin Description (continued)

PIN	NAME	FUNCTION	REFERENCE
9	SBA	Side B Active. SBA is high when Side B has power and is operating normally. When Side B is not powered, SBA is set low and all Side A outputs are in their default state. A nominal 100µs delay is added between the detection of Side B power and the asser- tion of SBA. This allows time for the power supply to settle, and ensures a minimum low pulse width for SBA.	GNDA
10	GNDA	Power and Signal Ground for Side A	GNDA
SIDE B (SPI MASTER)		
20	V _{DDB}	Power Supply. Bypass $V_{\mbox{DDB}}$ with a $0.1\mu\mbox{F}$ ceramic capacitor as close as possible to the pin.	GNDB
19	SAA	Side A Active. SAA is high when Side A has power, is operating normally, and \overline{IRDY} is low. When Side A is not powered, SAA is set low and all Side B outputs are in their default state (\overline{OFAULT} is low and OSDO is low when enabled). A nominal 100µs delay is added between the detection of Side A power and the assertion of SAA. This allows time for the power supply to settle, and ensures a minimum low pulse width for SAA.	GNDB
18	OFAULT	Output of FAULT channel. Open Drain Output	GNDB
17	OSDO	Output of SDO channel. Tri-stated when ICS and SDOEN are both high. Connect to MISO of SPI master.	GNDB
16	IAUX	Input to AUX channel; has a weak internal pullup to V _{DDB}	GNDB
15	ISDI	Input to SDI channel; has a weak internal pulldown. Connect to MOSI of SPI master.	GNDB
14	ISCLK	Input to SCLK channel; has a weak internal pulldown. Connect to SCLK of SPI master.	GNDB
13	ĪCS	Input to \overline{CS} channel; has a weak internal pullup to V _{DDB} . Connect to \overline{CS} output or GPO of SPI master. When \overline{ICS} is low, OSDO output is enabled.	GNDB
12	SDOEN	SDO Enable; has a weak internal pullup to V _{DDB} . When SDOEN is low, the OSDO output is enabled, allowing the SDO channel to be used with multiple side A SPI slaves.	GNDB
11	GNDB	Power and Signal Ground for Side B	GNDB

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Functional Diagram



6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Detailed Description

The MAX14483 is a 6-channel, 3.75kV_{RMS} digital galvanic isolator using Maxim's proprietary process technology. The six signal channels are individually optimized for SPI applications and include very low propagation delay on the SDI, SDO, and SCLK channels. The SDO channel's tri-state control is enabled by the \overline{CS} input as well as a second enable control input pin (SDOEN), allowing a single MAX14483 to isolate multiple SPI devices. To simplify system design, an open drain FAULT output can be wire ORed with error outputs from other devices. In addition, an auxiliary channel (AUX) is available for passing timing or control signals from the master side to the slave side and power monitors (SAA, SBA) are provided for both power domains to signal that the opposite side of the isolator is ready for operation. Independent 1.71V to 5.5V supplies on each side of the isolator also make the device suitable for use as a level translator.

The MAX14483 offers low-power operation, high electromagnetic interference (EMI) immunity, and stable temperature performance through Maxim's proprietary process technology. The device isolates different ground domains and blocks high-voltage/high-current transients from sensitive or human interface circuitry.

The MAX14483 is available with a maximum data rate of 200Mbps (SPI Data Rate Channels). The device has two supply inputs (V_{DDA} and V_{DDB}) that independently set the logic levels on either side of device. V_{DDA} and V_{DDB} are referenced to GNDA and GNDB, respectively.

The MAX14483 also features an internal refresh circuit to ensure output accuracy when an input remains in the same state indefinitely.

Digital Isolation

The MAX14483 provides galvanic isolation for digital signals that are transmitted between two ground domains. The device withstands up to $560V_{PEAK}$ of continuous isolation and up to $3.75kV_{RMS}$ for up to 60 seconds in the 20-pin SSOP package, which has 5.5mm of creepage and clearance. The package material has a minimum comparative tracking index (CTI) of 400V, giving it a group 2 rating in creepage tables.

Level-Shifting

The wide supply voltage range of both V_{DDA} and V_{DDB} allows the MAX14483 to be used for level translation in addition to isolation. V_{DDA} and V_{DDB} can be independently set to any voltage from 1.71V to 5.5V. The supply voltage sets the logic level on the corresponding side of the isolator.

Isolation Channels

The MAX14483 has three types of channels (<u>Table 3</u>). Low Data Rate Channels are <u>FAULT</u>, AUX and <u>CS</u>. SPI Data Rate Channels are <u>SCLK</u>, SDI, and SDO. Control and Monitor Channels are <u>IRDY</u>, <u>SDOEN</u>, SAA and SBA. Different types of channels have different electrical specifications.

Low Data Rate Channels

The Low Data Rate Channels are \overline{FAULT} , AUX, and \overline{CS} . Each channel is unidirectional; it only passes data in one direction, as indicated in the functional diagram. Each channel has a maximum data rate of 25Mbps. The \overline{FAULT} and AUX channels are designed to support SPI devices which require control signals beyond the standard 4-wire SPI bus. The output drivers of AUX and \overline{CS} channels are push-pull, eliminating the need for pullup resistors. The \overline{FAULT} channel output is open drain and requires a pullup resistor. All the outputs are able to drive both TTL and CMOS logic inputs. The input channels have an integrated glitch filter to help operate in noisy environments and avoid false triggering.

SPI Data Rate Channels

The SPI Data Rate Channels are SCLK, SDI, and SDO; these channels are designed to support standard 4-wire SPI bus signals (\overline{CS} is considered as a Low Data Rate Channel). Each channel is unidirectional; it only passes data in one direction, as indicated in the functional diagram. Each channel has been optimized for fast data rate and minimal skew between channels, with a maximum data rate of 200Mbps and maximum channel-to-channel propagation delay skew of only 10.2ns with V_{DD} = 1.8V. The output driver of each channel is push-pull, eliminating the need for pullup resistors. The outputs are able to drive both TTL and CMOS logic inputs.

6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Control and Monitor Channels

The Control and Monitor Channels are IRDY, SDOEN, SAA and SBA. Each channel is unidirectional; it only passes data in one direction, as indicated in the functional diagram. The monitor channels (SAA, SBA) are designed to pass essentially DC signals and have significantly longer propagation delays than other channels, meaning they should not be used for data signals. The outputs are able to drive both TTL and CMOS logic inputs. SAA and SBA are set high when their respective opposite side of the isolator has power and is operating normally. When Side A or Side B is not powered, SAA or SBA is set low and all outputs are set to their default state (OSDO is high impedance when disabled). A nominal 100µs delay is added between the detection of the opposite side power and the assertion of SAA or SBA. This allows time for the power supply to settle, and ensures a minimum low pulse width for SAA and SBA. The control channels (IRDY, SDOEN) have an integrated glitch filter. IRDY is an external input from the A side circuits (such as a Digital I/O device) to indicate that these devices are powered and active, allowing the B side circuit (such as a MCU SPI Master) to initiate data transfer across the isolation barrier. SDOEN is an output enable control for OSDO. SDOEN allows the B side of the MAX14483 to be shared with multiple SPI devices on the A side by enabling OSDO when ICS is not asserted. The A side SPI devices can be configured either in the daisy chain mode, where a single \overline{CS} signal enables all Side A devices as well as the OSDO output, or in the independent slave mode, where one Side A device uses the \overline{CS} channel in the MAX14483 and the rest of the Side A devices have their own \overline{CS} isolator channels, external to the MAX14483. The independent slave mode requires OSDO to be enabled any time one of the \overline{CS} signals is asserted, which can be accomplished by

· · · · · · · · · · · · · · · · · · ·							
CHANNEL TYPE	CHANNEL	OUTPUT DEFAULT	INPUT CURRENT SOURCE	GLITCH FILTER			
Low Data Rate	FAULT	Low	Pull Down	Yes			
Low Data Rate	AUX	High	Pull Up	Yes			
Low Data Rate	CS	High	Pull Up	Yes			
SPI Data Rate	SDI	Low	Pull Down	No			
SPI Data Rate	SCLK	Low	Pull Down	No			
SPI Data Rate	SDO	Low	Pull Down	No			
Control and Monitor	SDOEN	Input Only	Pull Up	Yes			
Control and Monitor	IRDY	Input Only	Pull Up	Yes			
Control and Monitor	trol and Monitor SAA High when Side A has power, is operating normally, and IRDY is low. Low when Side A is not powered or IRDY is high.		N/A	N/A			
Control and Monitor	SBA	High when Side B has power and is operating normally. Low when Side B is not powered.	N/A	N/A			

Table 3. Channel Summary

Table 4. Output Behavior During Undervoltage Conditions

V _{IN} _	- V _{DDA}	V _{DDB}	V _{OUTA}	SDO ENABLE	V _{OUTB}	
I_			0_		OSDO	OFAULT
	Powered	Powered	1	0	Hi-Z	1
I			1	1	1	1
0	Powered	Powered	0	0	Hi-Z	0
			0	1	0	0
х	Undervoltage	Powered	Default	0	Hi-Z	Default
			Default	1	Default	Default
х	Powered	Undervoltage	Default	0	Hi-Z	Default
			Default	1	Default	Default

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connecting a GPO pin to $\overline{\text{SDOEN}}$ and asserting it any time any $\overline{\text{CS}}$ signal is asserted. In the case that the B side of the MAX14483 is not shared with multiple SPI devices, there is no need for OSDO to be high impedance, and $\overline{\text{SDOEN}}$ can be permanently connected to GNDB. Refer to <u>Typical</u> <u>Operating Circuits</u> for details.

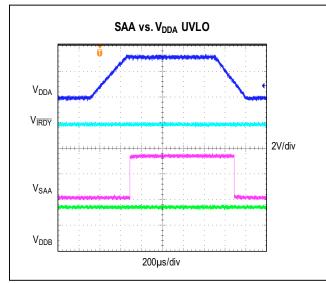


Figure 4. VDDA - UVLO Controlling SAA Signal

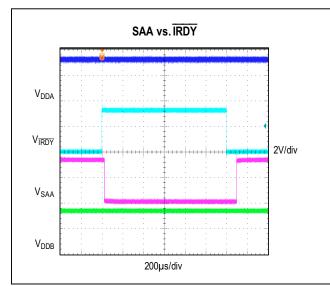


Figure 5. IRDY Controlling SAA Signal

Startup and Undervoltage-Lockout

The V_{DDA} and V_{DDB} supplies are both internally monitored for undervoltage conditions. Undervoltage events can occur during power-up, power-down, or during normal operation due to a sagging supply voltage. When an undervoltage condition is detected on either supply, all outputs go to their default states regardless of the state of the inputs (Table 4). Figure 4 through Figure 6 show the behavior of the SAA and SBA signals during power-up, power-down and IRDY toggling.

Applications Information

Power-Supply Sequencing

The MAX14483 does not require special power supply sequencing. The logic levels are set independently on either side by V_{DDA} and V_{DDB} . Each supply can be present over the entire specified range regardless of the level or presence of the other supply.

Power-Supply Decoupling

To reduce ripple and the chance of introducing data errors, bypass V_{DDA} and V_{DDB} with 0.1µF low-ESR ceramic capacitors to GNDA and GNDB, respectively. Place the bypass capacitors as close to the power supply input pins as possible.

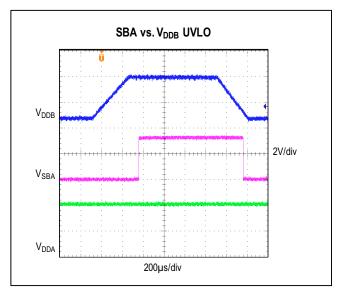


Figure 6. V_{DDB} - UVLO Controlling SBA Signal

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Layout Considerations

The PCB designer should follow some critical recommendations in order to get the best performance from the design.

- Keep the input/output traces as short as possible. Avoid using vias to make low-inductance paths for the signals.
- Have a solid ground plane underneath the high-speed signal layer.
- Keep the area underneath the MAX14483 free from ground and signal planes. Any galvanic or metallic connection between the Side A and the Side B defeats the isolation.

Calculating Power Dissipation

The required current for a given supply (V_{DDA} or V_{DDB}) can be estimated by summing the current required for each channel. The supply current for a channel depends on whether the channel is an input or an output, the channel's data rate, and the capacitive or resistive load if it is an output. The typical current for an input or output at any data rate can be estimated from the graphs in Figure 7 and Figure 8. Please note the data in Figure 7 and Figure 8 are extrapolated from the supply current measurements in a typical operating condition.

The total current for a single channel is the sum of the "no load" current (shown in <u>Figure 7</u> and <u>Figure 8</u>), which is a function of Voltage and Data Rate, and the "load current", which depends on the type of load. Current into a capacitive load is a function of the load capacitance, the switching frequency, and the supply voltage.

$$I_{CL} = C_L \times f_{SW} \times V_{DD}$$

where

I_{CL} is the current required to drive the capacitive load.

C_L is the load capacitance on the isolator's output pin.

f_{SW} is the switching frequency (bits per second / 2).

 $V_{\mbox{\scriptsize DD}}$ is the supply voltage on the output side of the isolator.

Current into a resistive load depends on the resistance, the supply voltage and the average duty cycle of the data waveform. The DC load current can be conservatively estimated by assuming the output is always high.

 $I_{RL} = V_{DD} \div R_L$

where

I_{RL} is the current required to drive the resistive load.

 $\mathsf{V}_{\mathsf{D}\mathsf{D}}$ is the supply voltage on the output side of the isolator.

 R_L is the load resistance on the isolator's output pin.

In the case of an SPI bus which often has intermittent read or write cycles, one other factor to consider is the active duty cycle percentage as well as the typical active current.

Example (shown in Figure 9): An SPI Master running at 10MHz and with 8-bit data package. The MAX14483 is operating with $V_{DDB} = 2.5V$, $V_{DDA} = 3.3V$, SCLK operating at 20Mbps with a 15pF load, SDI and SDO channels operating in 8-bit data frame at 10Mbps with a 15pF load on each, \overline{CS} operating at effective rate of 2.5Mbps (20Mbps divide by 8) with a 15pF load, and AUX channel operating at 1Mbps with a 10pF load. Channels SAA and SBA are not in use and FAULT drives a resistive load when active. Refer to Table 5 and Table 6 for V_{DDA} and V_{DDB} supply current calculation worksheets.

V_{DDA} must supply:

- ISDO operating at 3.3V and 10Mbps, consuming 0.24mA, estimated from Figure 7.
- IFAULT operating at 3.3V and DC, consuming 0.14mA, estimated from Figure 7.
- OAUX operating at 3.3V and 1Mbps, consuming 0.19mA, estimated from Figure 8. I_{CL} on OAUX for 10pF capacitor at 3.3V is 0.017mA.
- OSDI operating at 3.3V and 10Mbps, consuming 0.30mA, estimated from <u>Figure 8</u>. I_{CL} on OSDI for 15pF capacitor at 3.3V is 0.25mA.
- OSCLK operating at 3.3V and 20Mbps, consuming 0.42mA, estimated from <u>Figure 8</u>. I_{CL} on OSCLK for 15pF capacitor at 3.3V is 0.50mA.
- OCS operating at 3.3V and 2.5Mbps, consuming 0.21mA, estimated from Figure 8. I_{CL} on OCS for 15pF capacitor at 3.3V is 0.062mA.

Total current for side A = 2.33mA, typical.

V_{DDB} must supply:

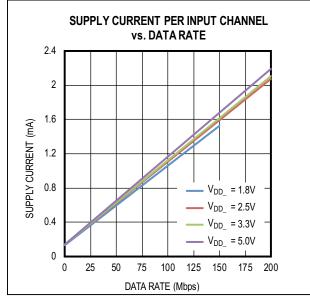
- IAUX operating at 2.5V and 1Mbps, consuming 0.15mA, estimated from Figure 7.
- ISDI operating at 2.5V and 10Mbps, consuming 0.23mA, estimated from Figure 7.
- ISCLK operating at 2.5V and 20Mbps, consuming 0.33mA, estimated from Figure 7.
- ICS operating at 2.5V and 2.5Mbps, consuming 0.16mA, estimated from Figure 7.
- OSDO operating at 2.5V and 10Mbps, consuming 0.27mA, estimated from <u>Figure 8</u>. I_{CL} on OSDO for 15pF capacitor at 2.5V is 0.19mA.
- OFAULT operating at 2.5V and 1Mbps, consuming 0.18mA, estimated from Figure 8. I_{RL} on OFAULT for 10kΩ resistor at 2.5V is 0.25mA.

Total current for side B = 1.76mA, typical.

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SUPPLY CURRENT PER OUTPUT CHANNEL

vs. DATA RATE





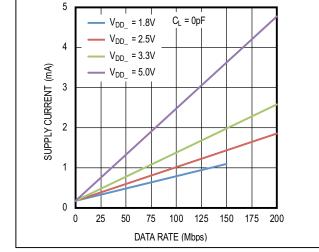


Figure 8. Supply Current Per Output Channel

Table 5. Side A Supply Current Calculation Worksheet

SIDE A V _{DDA} = 3.3V					3.3V	
Channel	IN/OUT	Data Rate (Mbps)	Load Type	Load	"No Load" Current (mA)	Load Current (mA)
OAUX	OUT	1	Capacitive	10pF	0.19	3.3V × 0.5MHz × 10pF = 0.017
OSDI	OUT	10	Capacitive	15pF	0.30	3.3V × 5MHz × 15pF = 0.25
OSCLK	OUT	20	Capacitive	15pF	0.42	3.3V × 10MHz × 15pF = 0.50
OCS	OUT	2.5	Capacitive	15pF	0.21	3.3V × 1.25MHz × 15pF = 0.062
ISDO	IN	10			0.24	
IFAULT	IN	0			0.14	
Total: 2.33mA						

Table 6. Side B Supply Current Calculation Worksheet

SIDE B	V _{DDB} = 2.5V					
Channel	IN/OUT	Data Rate (Mbps)	Load Type	Load	"No Load" Current (mA)	Load Current (mA)
IAUX	IN	1			0.15	
ISDI	IN	10			0.23	
ISCLK	IN	20			0.33	
ĪCS	IN	2.5			0.16	
OSDO	OUT	10	Capacitive	15pF	0.27	2.5V × 5MHz × 15pF = 0.19
OFAULT	OUT	0	Resistive	10kΩ	0.18	2.5V ÷ 10kΩ = 0.25
	Total: 1.76mA					

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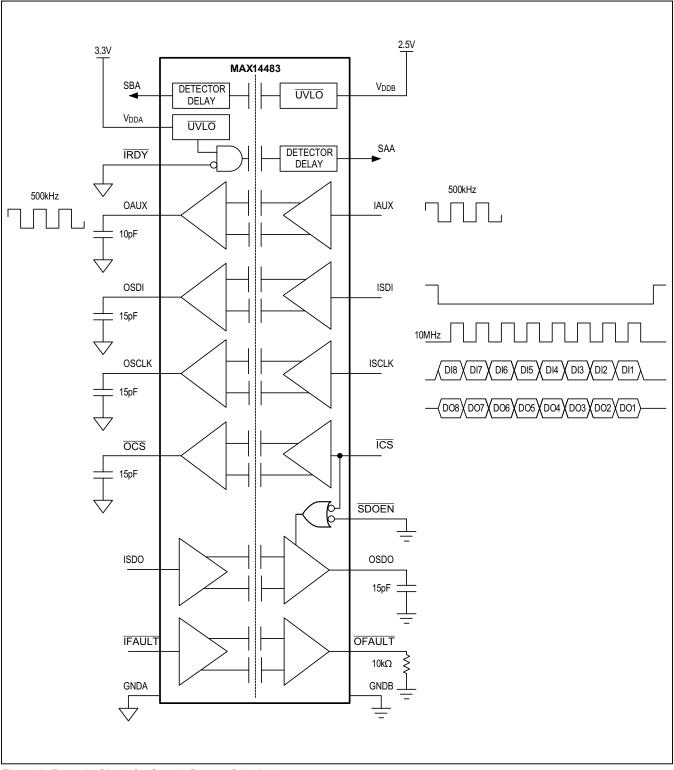
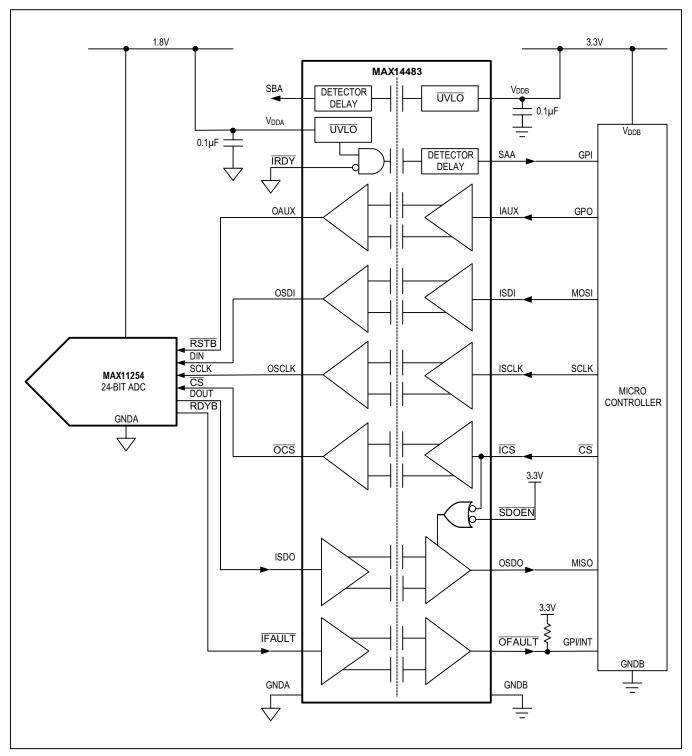


Figure 9. Example Circuit for Supply Current Calculation

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Typical Operating Circuit

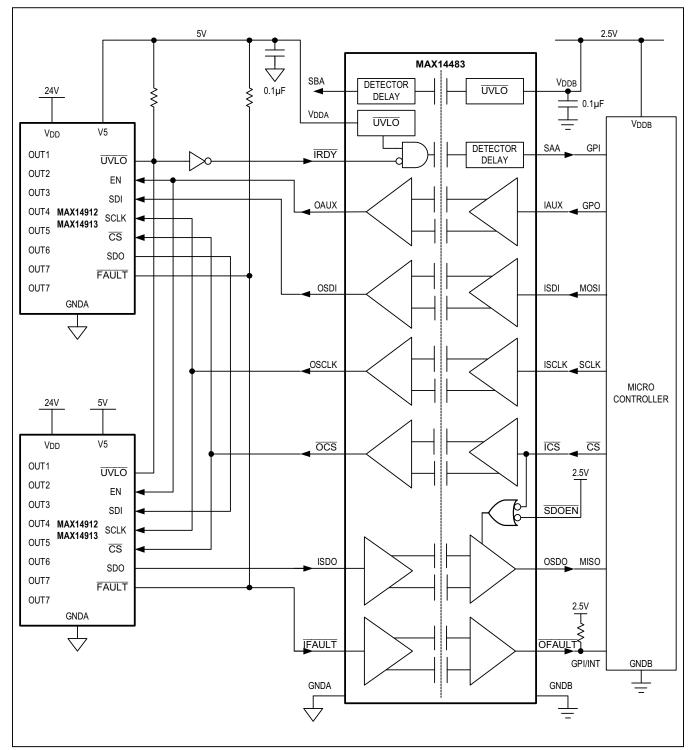
Isolated SPI Interface



6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Typical Operating Circuit (continued)

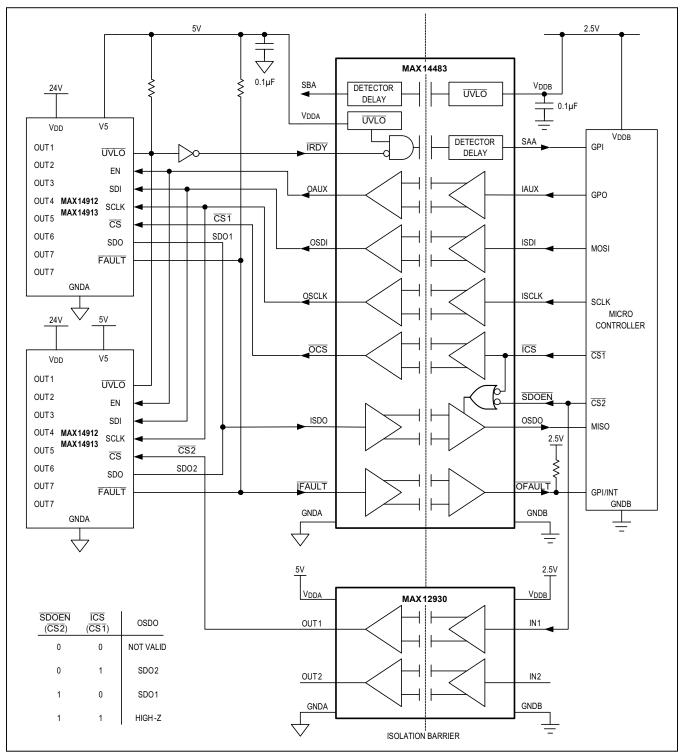
Isolated SPI Daisy Chain, 16 Digital Outputs



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Typical Operating Circuit (continued)

Isolated Independent Slave SPI Bus, 16 Digital Outputs



6-Channel, Low-Power, 3.75kV_{RMS}, SPI Digital Isolator

Ordering Information

PART	ISOLATION VOLTAGE (KVRMS)	TEMP RANGE (°C)	PIN-PACKAGE	
MAX14483AAP+	3.75	-40 to +125	20-SSOP	

Chip Information

PROCESS: BiCMOS

Package Information

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
20 SSOP	A20MS+7	<u>21-0056</u>	<u>90-0094</u>

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Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	08/17	Initial release	_
1	2/18	Updated <i>Electrical Characteristics</i> table, <i>Typical Operating Characteristics</i> , and <i>Detailed Description</i> section	1–20

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