

16 V Rail-to-Rail, Zero-Drift, Precision Instrumentation <u>Amplifier</u>

AD8230

FEATURES

Resistor programmable gain range: 10^1 to 1000 Supply voltage range: ± 4 V to ± 8 V Rail-to-rail input and output Maintains performance over -40° C to $+125^{\circ}$ C Excellent ac and dc performance 110 dB minimum CMR @ 60 Hz, G = 10 to 1000 10 μ V maximum offset voltage (RTI, ± 5 V operation) 50 nV/°C maximum offset drift 20 ppm maximum gain nonlinearity

APPLICATIONS

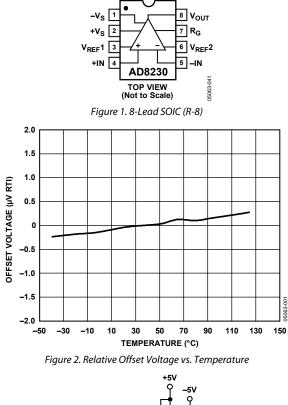
Pressure measurements Temperature measurements Strain measurements Automotive diagnostics

GENERAL DESCRIPTION

The AD8230 is a low drift, differential sampling, precision instrumentation amplifier. Auto-zeroing reduces offset voltage drift to less than 50 nV/°C. The AD8230 is well-suited for thermocouple and bridge transducer applications. The AD8230's high CMR of 110 dB (minimum) rejects line noise in measurements where the sensor is far from the instrumentation. The 16 V rail-to-rail, common-mode input range is useful for noisy environments where ground potentials vary by several volts. Low frequency noise is kept to a minimal 3 μ V p-p, making the AD8230 perfect for applications requiring the utmost dc precision. Moreover, the AD8230 maintains its high performance over the extended industrial temperature range of -40° C to +125°C.

Two external resistors are used to program the gain. By using matched external resistors, the gain stability of the AD8230 is much higher than instrumentation amplifiers that use a single resistor to set the gain. In addition to allowing users to program the gain between 10^1 and 1000, users can adjust the output offset voltage.





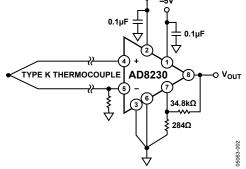


Figure 3. Thermocouple Measurement

The AD8230 is versatile yet simple to use. Its auto-zeroing topology significantly minimizes the input and output transients typical of commutating or chopper instrumentation amplifiers. The AD8230 operates on ± 4 V to ± 8 V (+8 V to +16 V) supplies and is available in an 8-lead SOIC.

Rev. B

Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.

 One Technology Way, P.O. Box 9106, Norwood, MA 02062-9106, U.S.A.

 Tel: 781.329.4700
 www.analog.com

 Fax: 781.461.3113
 ©2004–2007 Analog Devices, Inc. All rights reserved.

¹ The AD8230 can be programmed for a gain as low as 2, but the maximum input voltage is limited to approximately 750 mV.

TABLE OF CONTENTS

Features
Applications1
General Description 1
Connection Diagram 1
Revision History
Specifications
Absolute Maximum Ratings 5
Thermal Characteristics 5
ESD Caution 5
Typical Performance Characteristics
Theory of Operation11
Setting the Gain11

Level-Shifting the Output12Source Impedance and Input Settling Time12Input Voltage Range13Input Protection13Power Supply Bypassing13Power Supply Bypassing for Multiple Channel Systems13Layout14Applications15Ordering Guide15

REVISION HISTORY

9/07—Rev. A to Rev. B	
Changes to Features and Layout	1
Changes to Table 1	3
Changes to Table 2	4
Changes to Layout	
Inserted Figure 13, Figure 14, and Figure 15; Renumbered	
Sequentially	7
Changes to Figure 16 and Figure 19	8
Updated Outline Dimensions	15

7/05—Rev. 0 to Rev. A

Changes to Excellent AC and DC Performance1
Changes to Table 1
Changes to Table 24
Changes to Figure 7 and Figure 86
Changes to Figure 10 and Figure 117
Changes to Level-Shifting the Output Section
Changes to Figure 31 11
Inserted Figure 32 and Figure 33; Renumbered Sequentially 11
Changes to Source Impedance and Input Settling Time Section,
Input Protection Section and Power Supply Bypassing for
Multiple Channel Systems Section 12
Changes to Figure 36 13
Changes to Applications Section 13

10/04—Revision 0: Initial Version

SPECIFICATIONS

 $V_{\text{S}}=\pm5\text{ V}, V_{\text{REF}}=0\text{ V}, R_{\text{F}}=100\text{ k}\Omega, R_{\text{G}}=1\text{ k}\Omega \text{ (@ }T_{\text{A}}=25^{\circ}\text{C}, \text{G}=202, R_{\text{L}}=10\text{ k}\Omega, \text{unless otherwise noted)}.$

Table 1.

Parameter	Conditions	Min	Тур	Max	Unit
VOLTAGE OFFSET					
RTI Offset, Vosi	$V_{+IN} = V_{-IN} = 0 V$			10	μV
Offset Drift	$V_{+IN} = V_{-IN} = 0 V,$			50	nV/°C
	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$				
COMMON-MODE REJECTION (CMR)					
CMR to 60 Hz with 1 k Ω Source Imbalance	$V_{CM} = -5 V \text{ to } +5 V$	110	120		dB
VOLTAGE OFFSET RTI vs. SUPPLY (PSR)					
G = 2		120	120		dB
G = 202		120	140		dB
GAIN	$G = 2(1 + R_F/R_G)$				
Gain Range		10 ¹		1000	V/V
Gain Error ²					
G = 2			0.01	0.04	%
G = 10			0.01	0.04	%
G = 100			0.01	0.04	%
G = 1000			0.02	0.05	%
Gain Nonlinearity				20	ppm
Gain Drift					
G = 2, 10, 102				14	ppm/°C
G = 1002				60	ppm/°C
INPUT					
Input Common-Mode Operating Voltage Range		-Vs		+Vs	V
Over Temperature	$T = -40^{\circ}C \text{ to } +125^{\circ}C$	-Vs		+Vs	V
Input Differential Operating Voltage Range			750		mV
Average Input Offset Current ³	$V_{CM} = 0 V$		33	300	pА
Average Input Bias Current ³	$V_{CM} = 0 V$		0.15	1	nA
OUTPUT					
Output Swing		$-V_{s} + 0.1$		$+V_{s} - 0.2$	V
Over Temperature	$T = -40^{\circ}C \text{ to } +125^{\circ}C$	$-V_{s} + 0.1$		$+V_{s} - 0.2$	V
Short-Circuit Current			15		mA
REFERENCE INPUT					
Voltage Range⁴		$-V_{s} + 3.5$		+Vs - 2.5	V
NOISE					
Voltage Noise Density, 1 kHz, RTI	$V_{IN+}, V_{IN-}, V_{REF} = 0 V$		240		nV/√Hz
Voltage Noise	f = 0.1 Hz to 10 Hz		3		μV p-p
SLEW RATE	V _{IN} = 500 mV, G = 10		2		V/μs
INTERNAL SAMPLE RATE	· · ·		6		kHz
POWER SUPPLY					
Operating Range (Dual Supplies)		±4		±8	v
Operating Range (Single Supply)		8		16	v
Quiescent Current	T = -40°C to +125°C	-	2.7	3.5	mA
TEMPERATURE RANGE					
Specified Performance		-40		+125	°C

¹ The AD8230 can operate as low as G = 2. However, since the differential input range is limited to approximately 750 mV, the AD8230 configured at G < 10 does not make use of the full output voltage range. ² Gain drift is determined by the TC match of the external gain setting resistors. ³ Differential source resistance less than 10 k Ω does not result in voltage offset due to input bias current or mismatched series resistors.

 4 For G < 10, the reference voltage range is limited to $-V_{\text{S}}$ + 4.24 V to +V_{\text{S}} – 2.75 V.

 $V_S = \pm 8 \text{ V}, V_{REF} = 0 \text{ V}, R_F = 100 \text{ k}\Omega, R_G = 1 \text{ k}\Omega \text{ (} @ T_A = 25^{\circ}\text{C}, G = 202, R_L = 10 \text{ k}\Omega, \text{ unless otherwise noted}\text{)}.$

Table 2.

Offset Drift V_{+IN} T = -COMMON-MODE REJECTION (CMR)VCMR to 60 Hz with 1 k Ω Source ImbalanceVVOLTAGE OFFSET RTI vs. SUPPLY (PSR)GG = 2G = 202	$= V_{-IN} = 0 V$ = V_{-IN} = 0 V, -40°C to +125°C = -8 V to +8 V 2(1 + R _F /R _G)	110 120 120 10 ¹	120 120 140 0.01 0.01 0.02	20 50 1000 0.04 0.04 0.04 0.05 20	μV nV/°C dB dB dB V/V % % % % % 9%
Offset Drift V_{+N} T = -COMMON-MODE REJECTION (CMR)TCMR to 60 Hz with 1 k Ω Source Imbalance V_{CM} VOLTAGE OFFSET RTI vs. SUPPLY (PSR)GG = 2GG = 202Gain RangeGain RangeGain Error ² G = 2G = 100G = 100G = 1000Gain NonlinearityGain DriftG = 2, 10, 102Gain Carlot	$= V_{-IN} = 0 V,$ -40°C to +125°C = -8 V to +8 V	120 120	120 140 0.01 0.01 0.01	50 1000 0.04 0.04 0.04 0.04 0.05	nV/°C dB dB dB V/V % % %
T = - COMMON-MODE REJECTION (CMR) CMR to 60 Hz with 1 kΩ Source Imbalance VotTAGE OFFSET RTI vs. SUPPLY (PSR) $G = 2$ $G = 202$ GAIN Gain Range Gain Error ² $G = 2$ $G = 10$ $G = 100$ $G = 1000$ Gain Nonlinearity Gain Drift $G = 2, 10, 102$	-40°C to +125°C = −8 V to +8 V	120 120	120 140 0.01 0.01 0.01	1000 0.04 0.04 0.04 0.04 0.05	dB dB dB V/V % % % %
COMMON-MODE REJECTION (CMR) CMR to 60 Hz with 1 kΩ Source Imbalance V_{CM} VOLTAGE OFFSET RTI vs. SUPPLY (PSR) G = 2 G = 202GGAIN Gain Range Gain Error² G = 2 G = 10 G = 100 G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102G	= -8 V to +8 V	120 120	120 140 0.01 0.01 0.01	0.04 0.04 0.04 0.05	dB dB V/V % % %
$\begin{array}{c} \mbox{CMR to 60 Hz with 1 k\Omega Source Imbalance} & V_{CM} \\ \hline \mbox{VOLTAGE OFFSET RTI vs. SUPPLY (PSR)} & G = 2 \\ \hline \mbox{G} = 202 & G \\ \hline \mbox{Gain Range} & G \\ \hline \mbox{Gain Range} & G \\ \hline \mbox{Gain Error}^2 & G = 2 \\ \hline \mbox{G} = 100 & G \\ \hline \mbox{G} = 100 & G \\ \hline \mbox{G} = 1000 & G \\ \hline \mbox{Gain Nonlinearity} & G \\ \hline \mbox{Gain Drift} & G = 2, 10, 102 & G \\ \hline \mbox{With 1 k} & \Omega \\ \hline \mbox{CM to CM} & \Omega \\ \hline \mbox{CM to CM}$		120 120	120 140 0.01 0.01 0.01	0.04 0.04 0.04 0.05	dB dB V/V % % %
VOLTAGE OFFSET RTI vs. SUPPLY (PSR) $G = 2$ $G = 202$ $G = 2$ GAIN $G = 10$ Gain Range Gain Error ² $G = 2$ $G = 10$ $G = 100$ $G = 1000$ $G = 1000$ Gain Nonlinearity Gain Drift $G = 2, 10, 102$		120 120	120 140 0.01 0.01 0.01	0.04 0.04 0.04 0.05	dB dB V/V % % %
$G = 2$ $G = 202$ GAIN $G = 2$ Gain Range $Gain Error^2$ $G = 2$ $G = 10$ $G = 100$ $G = 100$ $G = 1000$ $Gain Nonlinearity$ Gain Drift $G = 2, 10, 102$	2(1 + R⊧/R _G)	120	140 0.01 0.01 0.01	0.04 0.04 0.04 0.05	dB V/V % % % %
$G = 202$ $G = 2$ Gain Range $Gain Error^2$ $G = 2$ $G = 10$ $G = 100$ $G = 1000$ $G = 1000$ $Gain Nonlinearity$ $Gain Drift$ $G = 2, 10, 102$	2(1 + R _F /R _G)	120	140 0.01 0.01 0.01	0.04 0.04 0.04 0.05	dB V/V % % % %
GAIN $G = 1$ Gain RangeGain Error ² G = 2G = 10G = 100G = 1000G = 1000Gain NonlinearityGain DriftG = 2, 10, 102	2(1 + R _F /R _G)		0.01 0.01 0.01	0.04 0.04 0.04 0.05	V/V % % %
Gain Range Gain Error ² G = 2 G = 10 G = 100 G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102	2(1 + R⊧/R ₆)	101	0.01 0.01	0.04 0.04 0.04 0.05	% % % %
Gain Error ² G = 2 G = 10 G = 100 G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102		101	0.01 0.01	0.04 0.04 0.04 0.05	% % % %
G = 2 G = 10 G = 100 G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102			0.01 0.01	0.04 0.04 0.05	% % %
G = 10 G = 100 G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102			0.01 0.01	0.04 0.04 0.05	% % %
G = 100 G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102			0.01	0.04 0.05	% %
G = 1000 Gain Nonlinearity Gain Drift G = 2, 10, 102				0.05	%
Gain Nonlinearity Gain Drift G = 2, 10, 102			0.02		
Gain Drift G = 2, 10, 102				20	ppm
G = 2, 10, 102					
G=1002				14	ppm/°C
				60	ppm/°C
INPUT					
Input Common-Mode Operating Voltage Range		-Vs		+Vs	V
	–40°C to +125°C	$-V_S$		+Vs	V
Input Differential Operating Voltage Range	<u></u>		750	200	mV
5 1	= 0 V		33	300	pA
	= 0 V		0.15	1	nA
OUTPUT Output Suring		N . 0.1			
Output Swing	10°C to 125°C	$-V_{s} + 0.1$		$+V_{s} - 0.2$	V
	–40°C to +125°C	$-V_{s} + 0.1$	15	$+V_{s}-0.4$	V
Short-Circuit Current REFERENCE INPUT			15		mA
Voltage Range ⁴		-Vs + 3.5		+Vs - 2.5	v
NOISE		$-v_{5} + 3.3$		$+v_{S}-2.3$	
	$V_{IN-}, V_{REF} = 0 V$		240		nV/√Hz
- ,	0.1 Hz to 10 Hz		240 3		μV p-p
	= 500 mV, G = 10				
INTERNAL SAMPLE RATE	- 500 mv, G = 10		2		V/µs kHz
POWER SUPPLY			0		
Operating Range (Dual Supplies)		±4		±8	v
Operating Range (Single Supplies)		±4 8		±0 16	v
	–40°C to +125°C	0	3.2	4	mA
TEMPERATURE RANGE	-+0 C 10 + 123 C		5.2	4	
Specified Performance		-40		+125	°C

¹ The AD8230 can operate as low as G = 2. However, since the differential input range is limited to approximately 750 mV, the AD8230 configured at G < 10 does not make use of the full output voltage range.

² Gain drift is determined by the TC match of the external gain setting resistors. ³ Differential source resistance less than 10 k Ω does not result in voltage offset due to input bias current or mismatched series resistors.

 4 For G < 10, the reference voltage range is limited to $-V_S$ + 4.24 V to $+V_S$ – 2.75V.

ABSOLUTE MAXIMUM RATINGS

Table 3.

Parameter	Rating
Supply Voltage	±8 V, +16 V
Internal Power Dissipation	304 mW
Output Short-Circuit Current	20 mA
Input Voltage (Common-Mode)	±Vs
Differential Input Voltage	±Vs
Storage Temperature Range	–65°C to +150°C
Operational Temperature Range	–40°C to +125°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL CHARACTERISTICS

Specification is for device in free air SOIC.

Table 4.

Parameter	Value	Unit
θ_{JA} (4-Layer JEDEC Board)	121	°C/W

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

TYPICAL PERFORMANCE CHARACTERISTICS

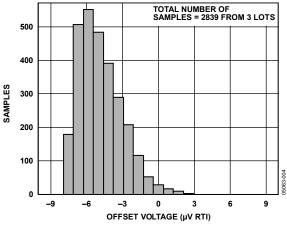
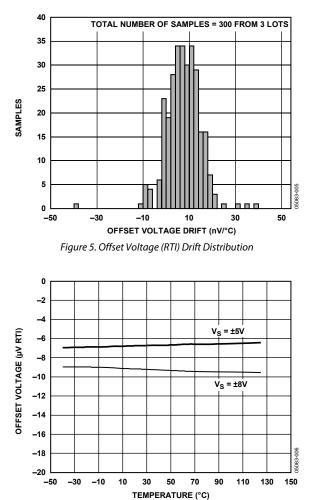
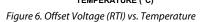


Figure 4. Offset Voltage (RTI) Distribution at ± 5 V, CM = 0 V, T_A = 25 °C





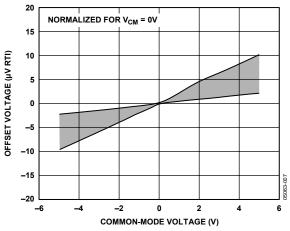


Figure 7. Offset Voltage (RTI) vs. Common-Mode Voltage, $V_s = \pm 5 V$

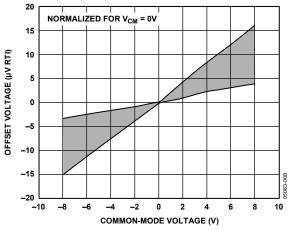


Figure 8. Offset Voltage (RTI) vs. Common-Mode Voltage, $V_s = \pm 8 V$

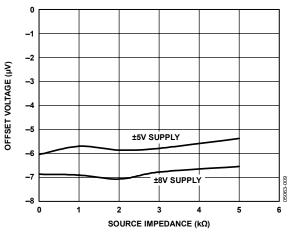
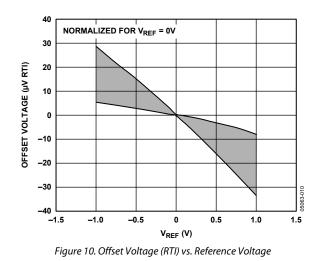
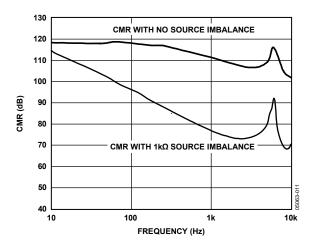
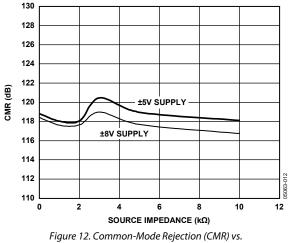


Figure 9. Offset Voltage (RTI) vs. Source Impedance, 1 µF Across Input Pins









Source Impedance, 1.1 µF Across Input Pins

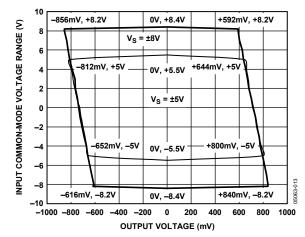


Figure 13. Input Common-Mode Voltage Range vs. Output Voltage, G = 2

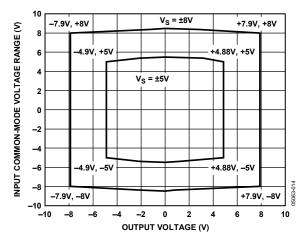


Figure 14. Input Common-Mode Voltage Range vs. Output Voltage, G = 10

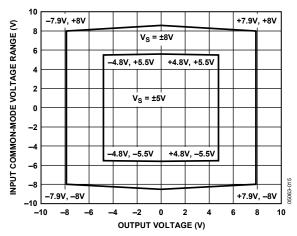
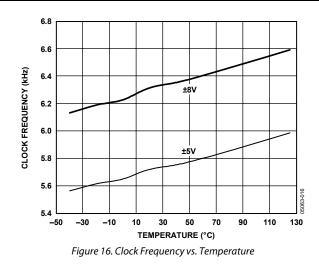
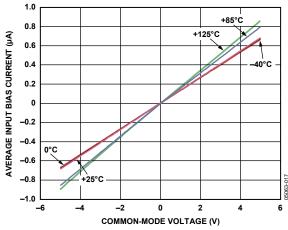
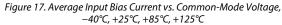
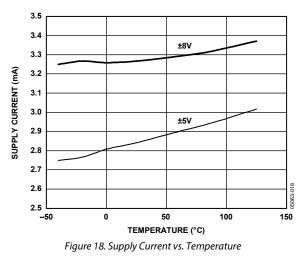


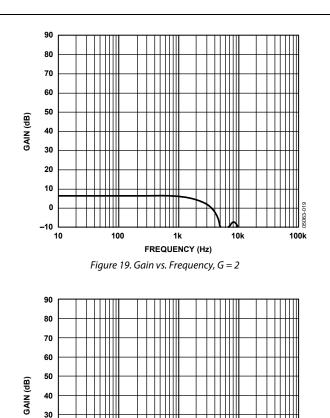
Figure 15. Input Common-Mode Voltage Range vs. Output Voltage, G = 100











40

30

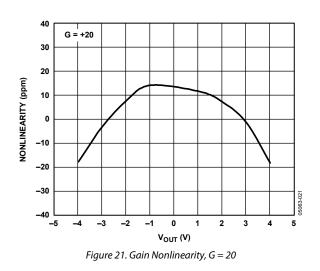
20

10

0

-10 L 10

100



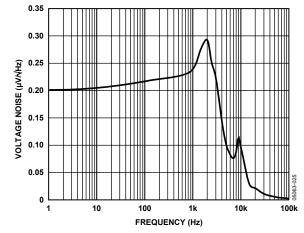
1k

FREQUENCY (Hz)

Figure 20. Gain vs. Frequency, G = 10

10k

100k





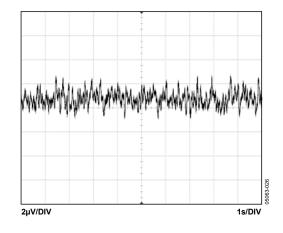
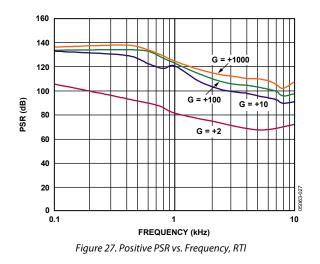
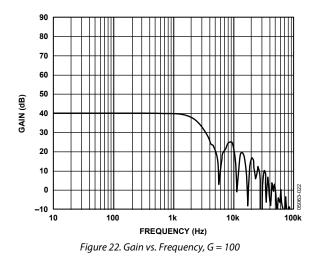
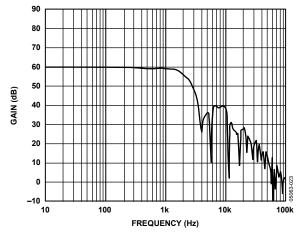


Figure 26. 0.1 Hz to 10 Hz RTI Voltage Noise, G = 100









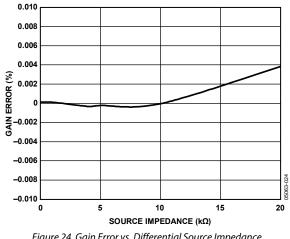
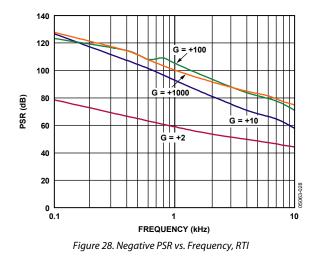
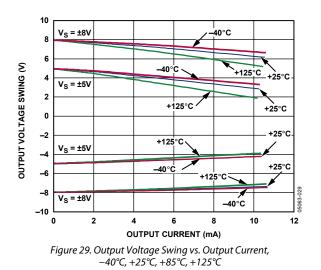


Figure 24. Gain Error vs. Differential Source Impedance





THEORY OF OPERATION

Auto-zeroing is a dynamic offset and drift cancellation technique that reduces input-referred voltage offset to the μ V level and voltage offset drift to the nV/°C level. A further advantage of dynamic offset cancellation is the reduction of low frequency noise, in particular the 1/f component.

The AD8230 is an instrumentation amplifier that uses an auto-zeroing topology and combines it with high commonmode signal rejection. The internal signal path consists of an active differential sample-and-hold stage (preamp) followed by a differential amplifier (gain amp). Both amplifiers implement auto-zeroing to minimize offset and drift. A fully differential topology increases the immunity of the signals to parasitic noise and temperature effects. Amplifier gain is set by two external resistors for convenient TC matching.

The signal sampling rate is controlled by an on-chip, 6 kHz oscillator and logic to derive the required nonoverlapping clock phases. For simplification of the functional description, two sequential clock phases, A and B, are shown to distinguish the order of internal operation, as depicted in Figure 30 and Figure 31, respectively.

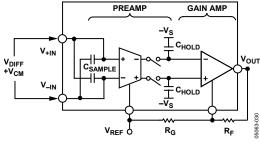


Figure 30. Phase A of the Sampling Phase

During Phase A, the sampling capacitors are connected to the inputs. The input signal's difference voltage, V_{DIFF}, is stored across the sampling capacitors, C_{SAMPLE}. Because the sampling capacitors only retain the difference voltage, the common-mode voltage is rejected. During this period, the gain amplifier is not connected to the preamplifier so its output remains at the level set by the previously sampled input signal held on C_{HOLD}, as shown in Figure 30.

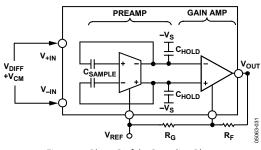


Figure 31. Phase B of the Sampling Phase

In Phase B, the differential signal is transferred to the hold capacitors refreshing the value stored on C_{HOLD} . The output of the preamplifier is held at a common-mode voltage determined by the reference potential, V_{REF} . In this manner, the AD8230 is able to condition the difference signal and set the output voltage level. The gain amplifier conditions the updated signal stored on the hold capacitors, C_{HOLD} .

SETTING THE GAIN

Two external resistors set the gain of the AD8230. The gain is expressed in the following equation:

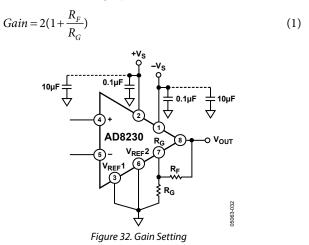


Table 5. Gains Using Standard 1% Resistors

Gain	RF	Rg	Actual Gain			
2	0 Ω (short)	None	2			
10	8.06 kΩ	2 kΩ	10			
50	12.1 kΩ	499 Ω	50.5			
100	9.76 kΩ	200 Ω	99.6			
200	10 kΩ	100 Ω	202			
500	49.9 kΩ	200 Ω	501			
1000	100 kΩ	200 Ω	1002			
			•			

Figure 32 and Table 5 provide an example of some gain settings. As Table 5 shows, the AD8230 accepts a wide range of resistor values. Because the instrumentation amplifier has finite driving capability, ensure that the output load in parallel with the sum of the gain setting resistors is greater than $2 \text{ k}\Omega$.

$$R_L || (R_F + R_G) > 2 k\Omega \tag{2}$$

Offset voltage drift at high temperature can be minimized by keeping the value of the feedback resistor, R_F , small. This is due to the junction leakage current on the R_G pin, Pin 7. The effect of the gain setting resistor on offset voltage drift is shown in Figure 33. In addition, experience has shown that wire-wound resistors in the gain feedback loop may degrade the offset voltage performance.

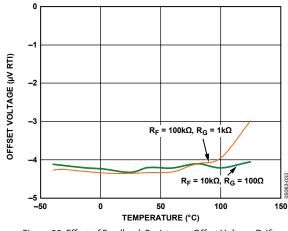


Figure 33. Effect of Feedback Resistor on Offset Voltage Drift

LEVEL-SHIFTING THE OUTPUT

A reference voltage, as shown in Figure 34, can be used to level-shift the output. The reference voltage, V_R , is limited to $-V_S + 3.5 V$ to $+V_S - 2.5 V$. (For G < 10, the reference voltage range is limited to $-V_S + 4.24 V$ to $+V_S - 2.75 V$.) Otherwise, it is nominally tied to midsupply. The voltage source used to level-shift the output should have a low output impedance to avoid contributing to gain error. In addition, it should be able to source and sink current. To minimize offset voltage, the V_{REF} pins should be connected either to the local ground or to a reference voltage source that is connected to the local ground.

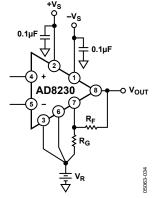


Figure 34. Level-Shifting the Output

The output can also be level-shifted by adding a resistor, R_0 , as shown in Figure 35. The benefit is that the output can be level-shifted to as low as 100 mV of the negative supply rail and to as high as 200 mV of the positive supply rail, increasing unipolar output swing. This can be useful in applications, such as strain gauges, where the force is only applied in one direction. Another benefit of this configuration is that a supply rail can be used for $V_{R'}$ eliminating the need to add an additional external reference voltage.

The gain changes with the inclusion of Ro. The full expression is

$$V_{OUT} = 2\left(\frac{R_F}{R_G || R_O} + 1\right) V_{IN} - \frac{R_F}{R_O} V_{R'} = 2\left(\frac{R_F(R_G + R_O)}{R_G R_O} + 1\right) V_{IN} - \frac{R_F}{R_O} V_{R'}$$
(3)

The following steps can be taken to set the gain and level-shift the output:

1. Select an R_F value. Table 5 shows R_F values for various gains.

2. Solve for R₀ using Equation 4.

$$R_{O} = -\frac{V_{R'} \times R_{F}}{V_{DESIRED-LEVEL}}$$
(4)

where:

 V_{R} is a voltage source, such as a supply voltage. V_{DESIRED-LEVEL} is the desired output bias voltage.

3. Solve for R_G.

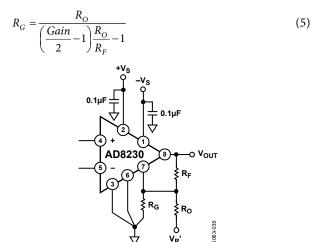


Figure 35. Level-Shifting the Output Without an Additional Voltage Reference

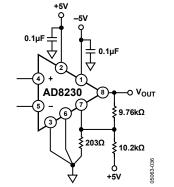


Figure 36. An AD8230 with its Output Biased at -4.8 V; G = 100; V_{DESIRED-LEVEL} = -4.8 V

SOURCE IMPEDANCE AND INPUT SETTLING TIME

The input stage of the AD8230 consists of two actively driven, differential switched capacitors, as described in Figure 30 and Figure 31. Differential input signals are sampled on C_{SAMPLE} such that the associated parasitic capacitances, 70 pF, are balanced between the inputs to achieve high common-mode rejection. On each sample period (approximately 85 µs), these parasitic capacitances must be recharged to the common-mode voltage by the signal source impedance (10 k Ω maximum). If resistors and capacitors are used at the input of the AD8230, care should be taken to maintain close match to maximize CMRR.

INPUT VOLTAGE RANGE

The input common-mode range of the AD8230 is rail to rail. However, the differential input voltage range is limited to approximately 750 mV. The AD8230 does not phase invert when its inputs are overdriven.

INPUT PROTECTION

The input voltage is limited to within 0.6 V beyond the supply rails by the internal ESD protection diodes. Resistors and low leakage diodes can be used to limit excessive, external voltage and current from damaging the inputs, as shown in Figure 37. Figure 39 shows an overvoltage protection circuit between the thermocouple and the AD8230.

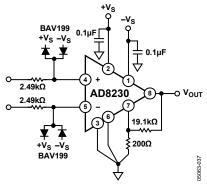


Figure 37. Overvoltage Input Protection

POWER SUPPLY BYPASSING

A regulated dc voltage should be used to power the instrumentation amplifier. Noise on the supply pins can adversely affect performance. Bypass capacitors should be used to decouple the amplifier.

The AD8230 has internal clocked circuitry that requires adequate supply bypassing. A 0.1 μ F capacitor should be placed as close to each supply pin as possible. As shown in Figure 32, a 10 μ F tantalum capacitor can be used further away from the part.

POWER SUPPLY BYPASSING FOR MULTIPLE CHANNEL SYSTEMS

The best way to prevent clock interference in multichannel systems is to lay out the PCB with a star node for the positive supply and a star node for the negative supply. Using such a technique, crosstalk between clocks is minimized. If laying out star nodes is not feasible, use wide traces to minimize parasitic inductance and decouple frequently along the power supply traces. Examples are shown in Figure 38. Care and forethought go a long way in maximizing performance.

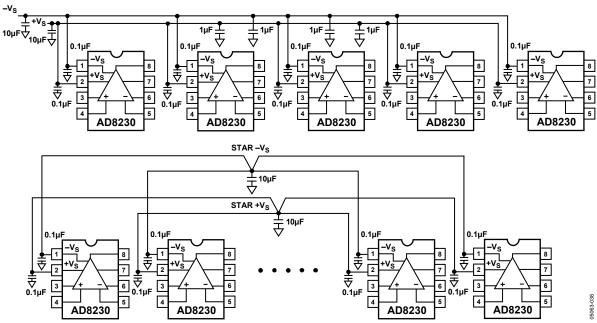


Figure 38. Use Star Nodes for $+V_s$ and $-V_s$ or Use Thick Traces and Decouple Frequently Along the Supply Lines

LAYOUT

The AD8230 has two reference pins: V_{REF1} and V_{REF2} . V_{REF1} draws current to set the internal voltage references. In contrast, V_{REF2} does not draw current. It sets the common mode of the output signal. As such, V_{REF1} and V_{REF2} should be star-connected to ground (or to a reference voltage). In addition, to maximize CMR, the trace between V_{REF2} and the gain resistor, R_G , should be kept short.

APPLICATIONS

The AD8230 can be used in thermocouple applications, as shown in Figure 3 and Figure 39. Figure 39 is an example of such a circuit for use in an industrial environment. Series resistors and low leakage diodes serve to clamp overload voltages (see the Input Protection section for more information).

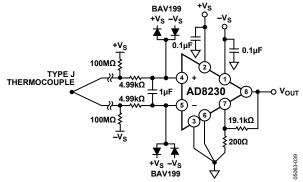


Figure 39. Type J Thermocouple with Overvoltage Protection and RFI Filter

An antialiasing filter reduces unwanted high frequency signals. The matched 100 M Ω resistors serve to provide input bias current to the input transistors and serve as an indicator as to when the thermocouple connection is broken. Well-matched 1% 4.99 k Ω resistors are used to form the antialiasing filter. It is good practice to match the source impedances to ensure high CMR. The circuit is configured for a gain of 193, which provides an overall temperature sensitivity of 10 mV/°C.

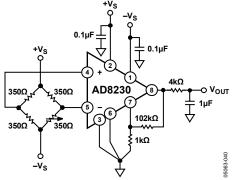
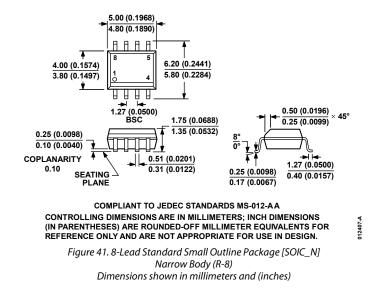


Figure 40. Bridge Measurement with Filtered Output

Measuring load cells in industrial environments can be a challenge. Often, the load cell is located some distance away from the instrumentation amplifier. The common-mode potential can be several volts, exceeding the common-mode input range of many 5 V auto-zero instrumentation amplifiers. Fortunately, the wide common-mode input voltage range of the AD8230 spans 16 V, relieving designers of having to worry about the common-mode range.

OUTLINE DIMENSIONS



ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
AD8230YRZ ¹	-40°C to +125°C	8-Lead SOIC_N	R-8
AD8230YRZ-REEL ¹	-40°C to +125°C	8-Lead SOIC_N, 13" Tape and Reel	R-8
AD8230YRZ-REEL71	-40°C to +125°C	8-Lead SOIC_N, 7" Tape and Reel	R-8
AD8230-EVAL		Evaluation Board	

¹ Z = RoHS Compliant Part.

NOTES

©2004–2007 Analog Devices, Inc. All rights reserved. Trademarks and registered trademarks are the property of their respective owners. D05063-0-9/07(B)

Rev. B | Page 16 of 16

www.analog.com