# XinaBox Datasheet OC06 - Stepper Driver



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### Overview

The OC06 xCHIP uses DRV8825 Stepper Motor Controller to precisely drive and control a connected stepper motor. The DRV8825 is interfaced with I2C through a PCA9554A I/O Expander which provides all the required control signals.

#### **Product Highlights**

- Stepper Motor Controller/Driver
- Connects a Single Stepper via Screw Terminals
- External Motor Supply Input via Screw Terminal (Max 47 V)
- 2.5 A Continuous Motor Output Current
- Built-In Microstepping Indexer
- Up to 1/32 Microstepping

## **Applications**

- Robotics
- Precision Control
- Accurate Positional Control Systems
- CNC Machines

# **Specifications**

#### **DRV8825**

- PWM Microstepping Stepper Motor Driver:
  - 1. Built-In Microstepping Indexer
  - 2. Up to 1/32 Microstepping
- Multiple Decay Modes:
  - 1. Mixed Decay
  - 2. Slow Decay
  - 3. Fast Decay
  - 8.2-V to 45-V Operating Supply Voltage Range
- 2.5-A Maximum Drive Current at 24 V and
- Low Current Sleep Mode
- Protection Features:
  - 1. Overcurrent Protection (OCP)
  - 2. Thermal Shutdown (TSD)
  - 3. VM Undervoltage Lockout (UVLO)
  - 4. Fault Condition Indication Pin (nFAULT)

#### PCA9554A

- 400-kHz Fast I<sup>2</sup>C Bus
- Three Hardware Address Pins Allow up to Eight I<sup>2</sup>C Addresses
- Internal Power-On Reset
- No Glitch on Power Up
- Latched Outputs With High-Current Drive

#### **External Links**

#### **GitHub**

OC06 on GitHub (https://github.com/xinabox/xOC06)

# OC06 - Stepper Driver (DRV8825, PCA9554A)





	Back	
	⊠CHIP	
Main Category	Output	
Sub Category	Control	
Introduced	1 January 2017	
Current version	1.0.0	
Current version date	1 January 2017	
Dimensions		

Size	2x2U (32x32mm)
Weight	6 g
Height	12.1/8.4/2.1 mm
Non-⊠BUS Connections	
North	Terminal Block
Main Chip Set	
Main Chip	PCA9554A/DRV8825
I <sup>2</sup> C Configuration	
Default Address	0x38
Alternative Addresses	0x39; 0x3A; 0x3B; 0x3D; 0x3E; 0x3F
Change Setting	Solder Pads