## Data Sheet

## FEATURES

24 GHz to $\mathbf{2 4 . 2 5} \mathbf{~ G H z}$ voltage controlled oscillator (VCO)
2-channel 24 GHz power amplifier (PA) with 8 dBm output Single-ended outputs
2-channel muxed outputs with mute function
Programmable output power
N divider output (frequency discriminator)
24 GHz local oscillator (LO) output buffer
250 MHz signal bandwidth
Power control detector
Auxiliary 8-bit ADC
$\pm 5^{\circ} \mathrm{C}$ temperature sensor
4-wire serial peripheral interface (SPI)
Electrostatic discharge (ESD) performance
Human body model (HBM): 2000 V
Charged device model (CDM): 250 V
Qualified for automotive applications

## APPLICATIONS

Automotive radars
Industrial radars
Microwave radar sensors

Industrial sensors
Precision instrumentation
Tank level sensors
Smart sensors
Door opening
Energy saving
Commercial sensors: object detection and tracking
Cars, boats, aircraft, and UAVs (drones): collision avoidance
Intelligent transportation systems: intelligent traffic monitoring and control
Surveillance and security

## GENERAL DESCRIPTION

The ADF5901 is a 24 GHz Tx monolithic microwave integrated circuit (MMIC) with an on-chip, 24 GHz VCO with PGA and dual Tx channels for radar systems. The on-chip, 24 GHz VCO generates the 24 GHz signal for the two Tx channels and the LO output. Each Tx channel contains a power control circuit. There is also an on-chip temperature sensor.
Control of all the on-chip registers is through a simple 4-wire interface.

The ADF5901 comes in a compact 32 -lead, $5 \mathrm{~mm} \times 5 \mathrm{~mm}$ LFCSP package.

FUNCTIONAL BLOCK DIAGRAM


Rev. B

## ADF5901

## TABLE OF CONTENTS

Features ..... 1
Applications .....  1
General Description .....  1
Functional Block Diagram ..... 1
Revision History ..... 2
Specifications ..... 3
Timing Specifications .....  4
Absolute Maximum Ratings ..... 6
ESD Caution .....  6
Pin Configuration and Function Descriptions ..... 7
Typical Performance Characteristics ..... 9
Theory of Operation ..... 11
Reference Input Section ..... 11
RF INT Divider ..... 11
INT, FRAC, and R Relationship ..... 11
R Counter ..... 11
Input Shift Register ..... 11
Program Modes ..... 11
Register Maps ..... 13
Register 0 ..... 15
Register 1 ..... 16
REVISION HISTORY
8/2017—Rev. A to Rev. B
Changes to Figure 17. ..... 13
Changes to Figure 20 ..... 17
Updated Outline Dimensions ..... 27
Changes to Ordering Guide ..... 27
7/2016-Rev. 0 to Rev. A
Changes to Applications Section ..... 1
Register 2 ..... 17
Register 3 ..... 18
Register 4 ..... 19
Register 5 ..... 20
Register 6 ..... 20
Register 7 ..... 21
Register 8 ..... 22
Register 9 ..... 22
Register 10 ..... 23
Register 11 ..... 23
Initialization Sequence ..... 23
Recalibration Sequence ..... 23
Temperature Sensor ..... 24
RF Synthesis: a Worked Example ..... 24
Applications Information ..... 25
Application of the ADF5901 in FMCW Radar ..... 25
Outline Dimensions ..... 26
Ordering Guide ..... 26
Automotive Products ..... 26
Changes to Initialization Sequence Section and Recalibration Sequence Section ..... 23
12/2015—Revision 0: Initial Version

## SPECIFICATIONS

$\mathrm{AHI}=\mathrm{TX} \_\mathrm{AHI}=\mathrm{RF} \_\mathrm{AHI}=\mathrm{VCO} \_\mathrm{AHI}=\mathrm{DVDD}=3.3 \mathrm{~V} \pm 5 \%, \mathrm{AGND}=0 \mathrm{~V}, \mathrm{dBm}$ referred to $50 \Omega, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MAX}}$ to $\mathrm{T}_{\mathrm{MIN}}$, unless otherwise noted. Operating temperature range is $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$.

Table 1.

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| OPERATING CONDITIONS RF Frequency Range | 24 |  | 24.25 | GHz |  |
| VCO CHARACTERISITICS <br> $V_{\text {tune }}$ <br> Vtune Impedance <br> VCO Phase Noise Performance <br> At 100 kHz Offset <br> At 1 MHz Offset <br> At 10 MHz Offset <br> Amplitude Noise <br> Static Pulling fvco Change vs. Load <br> Dynamic Pulling Tx On/Off Switch Change Dynamic Pulling Tx to Tx Switch Change Pushing fvco Change vs. AHI Change Spurious Level Harmonics Spurious Level Nonharmonics | $1$ | 100 <br> -88 <br> -108 <br> -128 <br> -150 <br> $\pm 2$ <br> $\pm 10$ <br> $\pm 5$ <br> $\pm 5$ <br> -30 <br> <-70 | 2.8 | V <br> $\mathrm{k} \Omega$ <br> $\mathrm{dBc} / \mathrm{Hz}$ <br> $\mathrm{dBc} / \mathrm{Hz}$ <br> $\mathrm{dBc} / \mathrm{Hz}$ <br> $\mathrm{dBc} / \mathrm{Hz}$ <br> MHz <br> MHz <br> MHz <br> MHz/V <br> dBC <br> dBc | At 1 MHz offset <br> Open-loop into 2:1 voltage standing wave ratio (VSWR) load <br> Open-loop <br> Open-loop <br> Open-loop |
| POWER SUPPLIES <br> AHI, TX_AHI, RF_AHI, VCO_AHI, DVDD <br> Total Current, Itotal ${ }^{1}$ <br> Software Power-Down Mode <br> Hardware Power-Down Mode | 3.135 | $\begin{aligned} & 3.3 \\ & 170 \\ & 500 \\ & 200 \\ & \hline \end{aligned}$ | 3.465 | V <br> mA <br> $\mu \mathrm{A}$ <br> $\mu \mathrm{A}$ |  |
| Tx OUTPUT <br> Output Power <br> Output Impedance <br> On/Off Isolation <br> Tx to Tx Isolation <br> Power-Up/Power-Down Time | 2 | $\begin{aligned} & 8 \\ & 50 \\ & 30 \\ & 25 \\ & 200 \\ & \hline \end{aligned}$ | 10 | dBm <br> $\Omega$ <br> dB <br> dB <br> ns | Single Tx output switched on/off |
| LO OUTPUT <br> Output Power <br> Output Impedance On/Off Isolation | -7 | $\begin{array}{r} -1 \\ 50 \\ 30 \\ \hline \end{array}$ | +5 | dBm <br> $\Omega$ <br> dB |  |
| AUX PIN OUTPUT <br> Output Power Output Frequency Divide by 2 Output Divide by 4 Output Output Impedance On/Off Isolation AUX to LO Isolation | $\begin{aligned} & -9 \\ & 12 \\ & 6 \end{aligned}$ | $-5$ $\begin{aligned} & 200 \\ & 30 \\ & 30 \end{aligned}$ | 0 $\begin{aligned} & 12.125 \\ & 6.0625 \end{aligned}$ | dBm <br> GHz <br> GHz <br> $\Omega$ <br> dB <br> dB | Single-ended <br> Differential |
| TEMPERATURE SENSOR <br> Analog Accuracy <br> Digital Accuracy Sensitivity |  | $\begin{aligned} & \pm 5 \\ & \pm 5 \\ & 6.4 \end{aligned}$ |  | ${ }^{\circ} \mathrm{C}$ ${ }^{\circ} \mathrm{C}$ $\mathrm{mV} /{ }^{\circ} \mathrm{C}$ | Following one-point calibration Following one-point calibration |

## ADF5901

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| ADC |  |  |  |  |  |
| Resolution |  | 8 |  | Bits |  |
| Integral Nonlinearity (INL) |  | $\pm 1$ |  | LSB |  |
| Differential Nonlinearity (DNL) |  | $\pm 1$ |  | LSB |  |
| Least Significant Bit (LSB) |  | 7.4 |  | mV |  |
| REFIN CHARACTERISITICS |  |  |  |  |  |
| REFin Input Frequency | 10 |  | 260 | MHz | -5 dBm minimum to +9 dBm maximum biased at AHI/2 (ac coupling ensures $1.8 / 2$ bias); for frequencies $<10 \mathrm{MHz}$, use a dc-coupled, CMOScompatible square wave with a slew rate > $25 \mathrm{~V} / \mu \mathrm{s}$ |
| REFIN Input Capacitance |  |  | 1.2 | pF |  |
| REFII Input Current |  |  | $\pm 100$ | $\mu \mathrm{A}$ |  |
| LOGIC INPUTS |  |  |  |  |  |
| Input Voltage |  |  |  |  |  |
| High ( $\mathrm{V}_{1}$ ) | 1.4 |  |  | V |  |
| Low ( $\mathrm{V}_{\text {LI }}$ ) |  |  | 0.6 | V |  |
|  |  |  | $\pm 1$ | $\mu \mathrm{A}$ |  |
| Input Capacitance ( $\mathrm{Clin}_{\text {) }}$ |  |  | 10 | pF |  |
| LOGIC OUTPUTS |  |  |  |  |  |
| Output Voltage |  |  |  |  |  |
| High (VoH) ${ }^{2}$ | $\begin{aligned} & V_{D D}- \\ & 0.4 \end{aligned}$ |  |  | V |  |
| Low (VoL) |  |  | 0.4 | V |  |
| Output Current |  |  |  |  |  |
| High (Іон) |  |  | 500 | $\mu \mathrm{A}$ |  |
| Low (loL) |  |  | 500 | $\mu \mathrm{A}$ |  |

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C} ; \mathrm{AHI}=3.3 \mathrm{~V} ; \mathrm{f}_{\text {REFIN }}=100 \mathrm{MHz} ; \mathrm{RF}=24.125 \mathrm{GHz}$ following initialization sequence in the Initialization Sequence section.
${ }^{2} V_{D D}$ selected from IO level bit (DB11 in Register 3).

## TIMING SPECIFICATIONS

$\mathrm{AHI}=\mathrm{TX} \_\mathrm{AHI}=\mathrm{RF} \_\mathrm{AHI}=\mathrm{VCO} \_\mathrm{AHI}=\mathrm{DVDD}=3.3 \mathrm{~V} \pm 5 \%, \mathrm{AGND}=0 \mathrm{~V}, \mathrm{dBm}$ referred to $50 \Omega, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Operating temperature range is $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$.

Table 2. Write Timing

| Parameter | Limit at $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {MAX }}$ | Unit | Description |
| :---: | :---: | :---: | :---: |
| $\mathrm{t}_{1}$ | 20 | ns min | LE setup time |
| $\mathrm{t}_{2}$ | 10 | ns min | DATA to CLK setup time |
| $\mathrm{t}_{3}$ | 10 | ns min | DATA to CLK hold time |
| $\mathrm{t}_{4}$ | 25 | ns min | CLK high duration |
| $\mathrm{t}_{5}$ | 25 | ns min | CLK low duration |
| $\mathrm{t}_{6}$ | 10 | $n \mathrm{n}$ min | CLK to LE setup time |
| $\mathrm{t}_{7}$ | 20 | ns min | LE pulse width |
| $\mathrm{t}_{8}$ | 10 | ns max | LE setup time to DOUT |
| $\mathrm{t}_{9}$ | 15 | ns max | CLK setup time to DOUT |

## Data Sheet <br> ADF5901

## Write Timing Diagram



Figure 2. Write Timing Diagram


Figure 3. Load Circuit for DOUT/MUXOUT Timing, $C_{L}=10 \mathrm{pF}$

## ABSOLUTE MAXIMUM RATINGS

Table 3.

| Parameter | Rating |
| :---: | :---: |
| AHI to GND | -0.3 V to +3.9 V |
| AHI to TX_AHI | -0.3 V to +0.3 V |
| AHI to RF_AHI | -0.3 V to +0.3 V |
| AHI to VCO_AHI | -0.3 V to +0.3 V |
| AHI to DVDD | -0.3 V to +0.3 V |
| $V_{\text {tune }}$ to GND | -0.3 V to +3.6 V |
| Digital Input/Output Voltage to GND | -0.3 V to DVDD +0.3 V |
| Operating Temperature Range | $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Maximum Junction Temperature | $150^{\circ} \mathrm{C}$ |
| $\theta_{\mathrm{JA}}$ Thermal Impedance ${ }^{1}$ (Paddle Soldered) | $40.83{ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Reflow Soldering |  |
| Peak Temperature | $260^{\circ} \mathrm{C}$ |
| Time at Peak Temperature | 40 sec |
| Transistor Count |  |
| CMOS | 177,381 |
| Bipolar | 2315 |
| ESD |  |
| Charged Device Model | 250 V |
| Human Body Model | 2000 V |

${ }^{1}$ Two signal planes (that is, on top and bottom surfaces of the board), two buried planes, and nine vias.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Table 4. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| $\begin{aligned} & 1,3,6,8 \\ & 10,12,13 \\ & 19 \end{aligned}$ | GND | RF Ground. Tie all ground pins together. |
| 2 | TXout 1 | 24 GHz Tx Output 1. |
| 4,5 | TX_AHI | Voltage Supply for the Tx Section. Connect decoupling capacitors ( $0.1 \mu \mathrm{~F}, 1 \mathrm{nF}$, and 10 pF ) to the ground plane as close as possible to this pin. TX_AHI must be the same value as AHI. |
| 7 | TXout2 | 24 GHz Tx Output 2. |
| 9 | ATEST | Analog Test Pin. |
| 11 | LOout | LO Output. |
| 14 | RF_AHI | Voltage Supply for the RF Section. Connect decoupling capacitors ( $0.1 \mu \mathrm{~F}, 1 \mathrm{nF}$, and 10 pF ) to the ground plane as close as possible to this pin. RF_AHI must be the same value as AHI. |
| 15 | REFIN | Reference Input. This pin is a CMOS input with a nominal threshold of DVDD/2 and a dc equivalent input resistance of $100 \mathrm{k} \Omega$. See Figure 14. This input can be driven from a TTL or CMOS crystal oscillator, or it can be ac-coupled. |
| 16 | AHI | Voltage Supply for the Analog Section. Connect decoupling capacitors ( $0.1 \mu \mathrm{~F}, 1 \mathrm{nF}$, and 10 pF ) to the ground plane as close as possible to this pin. |
| 17 | DVDD | Digital Power Supply. This supply may range from 3.135 V to 3.465 V . Place decoupling capacitors ( $0.1 \mu \mathrm{~F}, 1 \mathrm{nF}$, and 10 pF ) to the ground plane as close as possible to this pin. DVDD must be the same value as AHI. |
| 18 | VREG | Internal 1.8V Regulator Output. Connect a 220 nF capacitor to ground as close as possible to this pin. |
| 20 | CE | Chip Enable. A logic low on this pin powers down the device. Taking the pin high powers up the device, depending on the status of the power-down bit, PD1. |
| 21 | CLK | Serial Clock Input. This serial clock input clocks in the serial data to the registers. The data is latched into the 32-bit shift register on the CLK rising edge. This input is a high impedance CMOS input. |
| 22 | DATA | Serial Data Input. The serial data is loaded MSB first with the four LSBs as the control bits. This input is a high impedance CMOS input. |
| 23 | LE | Load Enable, CMOS Input. When LE goes high, the data stored in the shift registers is loaded into one of the 16 latches with the latch selected via the control bits. |
| 24 | DOUT | Serial Data Output. |
| 25 | MUXOUT | Multiplexer Output. This multiplexer output allows either the scaled RF or the scaled reference frequency to be accessed externally. |
| 26 | Rset | Resistor Setting Pin. Connecting a $5.1 \mathrm{k} \Omega$ resistor between this pin and GND sets an internal current. The nominal voltage potential at the $\mathrm{R}_{\text {set }}$ pin is 0.62 V . |
| 27 | AUX | Auxiliary Output. The VCO/2 output or VCO/4 is available. |
| 28 | $\overline{\text { AUX }}$ | Complementary Auxiliary Output. The VCO/2 output or VCO/4 is available. |


| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 29 | V $_{\text {TUNE }}$ | Control Input to the VCO. This voltage determines the output. |
| 30 | VCO_AHI | Voltage Supply for the VCO Section. Connect decoupling capacitors ( $0.1 \mu \mathrm{FF}, 1 \mathrm{nF}$, and 10 pF) to the ground <br> plane as close as possible to this pin. VCO_AHI must be the same value as AHI. |
| 31 | C1 | Decoupling Capacitor 1. Place a 47 nF capacitor to ground as close as possible to this pin. <br> 32 |
|  | C2 | Decoupling Capacitor 2. Place a 220 nF capacitor to ground as close as possible to this pin. |
| Exposed Pad. The LFCSP has an exposed pad that must be connected to GND. |  |  |

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 5. Tx Output Power vs. Output Frequency


Figure 6. Transmitter 1 (Tx1) Output Power Variation with Temperature and Supply vs. Output Frequency


Figure 7. Tx Output Power vs. Tx Amplitude Calibration Reference Code


Figure 8. LO Output Power vs. Output Frequency


Figure 9. AUX/AUX Output Power vs. Output Frequency with Divide by 2 Selected


Figure 10. AUX/AUX Output Power vs. Output Frequency with Divide by 4 Selected


Figure 11. VTune Frequency Range


Figure 12. Open-Loop Phase Noise on Tx1 Output at 24.125 GHz


Figure 13. ATEST Voltage and ADC Code vs. Temperature

## THEORY OF OPERATION

## REFERENCE INPUT SECTION

The reference input stage is shown in Figure 14. SW1 and SW2 are normally closed switches. SW3 is normally open. When power-down is initiated, SW3 is closed and SW1 and SW2 are opened. This configuration ensures that there is no loading of the $\mathrm{REF}_{\text {IN }}$ pin on power-down.


Figure 14. Reference Input Stage

## RF INT DIVIDER

The RF INT counter allows a division ratio in the RF feedback counter. Division ratios from 75 to 4095 are allowed.

## INT, FRAC, AND R RELATIONSHIP

Generate the RF VCO frequency (RFout) using the INT and FRAC values in conjunction with the R counter, as follows:

$$
\begin{equation*}
R F_{\text {OUT }}=f_{\text {REF }} \times\left(I N T+\left(F R A C / 2^{25}\right)\right) \times 2 \tag{1}
\end{equation*}
$$

where:
$R F_{\text {out }}$ is the output frequency of internal VCO.
$f_{R E F}$ is the internal reference frequency.
INT is the preset divide ratio of the binary 12-bit counter
( 75 to 4095).
$F R A C$ is the numerator of the fractional division ( 0 to $2^{25}-1$ ).

$$
\begin{equation*}
f_{R E F}=R E F_{I N} \times((1+D) /(R \times(1+T))) \tag{2}
\end{equation*}
$$

where:
$R E F_{\text {IN }}$ is the reference input frequency.
$D$ is the $\mathrm{REF}_{\text {IN }}$ doubler bit ( 0 or 1 ).
$R$ is the preset divide ratio of the binary, 5-bit, programmable reference counter (1 to 32).
$T$ is the $\mathrm{REF}_{\text {IN }}$ divide by 2 bit ( 0 or 1 ).


Figure 15. RF N Divider


Figure 16. Reference Divider

## R COUNTER

The 5-bit R counter allows the input reference frequency ( $\mathrm{REF}_{\text {IN }}$ ) to be divided down to supply the reference clock to the VCO calibration block. Division ratios from 1 to 32 are allowed.

## INPUT SHIFT REGISTER

The ADF5901 digital section includes a 5-bit RF R counter, a 12 -bit RF N counter, and a 25 -bit FRAC counter. Data is clocked into the 32 -bit input shift register on each rising edge of CLK. The data is clocked in MSB first. Data is transferred from the input shift register to one of 12 latches on the rising edge of LE. The destination latch is determined by the state of the five control bits (C5, C4, C3, C2, and C1) in the input shift register. These are the five LSBs (DB4, DB3, DB2, DB1, and DB0, respectively), as shown in Figure 2. Table 5 shows the truth table for these bits. Figure 17 and Figure 18 show a summary of how the latches are programmed.

## PROGRAM MODES

Table 5 and Figure 19 through Figure 30 show how to set up the program modes in the ADF5901.
Several settings in the ADF5901 are double buffered. These include the LSB fractional value, R counter value ( R divider), reference doubler, clock divider, RDIV2, and MUXOUT. This means that two events must occur before the device uses a new value for any of the double-buffered settings. First, the new value is latched into the device by writing to the appropriate register. Second, a new write must be performed on Register R5.
For example, updating the fractional value can involve a write to the 13 LSB bits in Register R6 and the 12 MSB bits in Register R5. Write to Register R6 first, followed by the write to Register R5. The frequency change begins after the write to Register R0. Double buffering ensures that the bits written to in Register R6 do not take effect until after the write to Register R5.

Table 5. C5, C4, C3, C2, and C1 Truth Table

| Control Bits |  |  |  |  | Register |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C5 (DB4) | C4 (DB3) | C3 (DB2) | C2 (DB1) | C1 (DBO) |  |
| 0 | 0 | 0 | 0 | 0 | R0 |
| 0 | 0 | 0 | 0 | 1 | R1 |
| 0 | 0 | 0 | 1 | 0 | R2 |
| 0 | 0 | 0 | 1 | 1 | R3 |
| 0 | 0 | 1 | 0 | 0 | R4 |
| 0 | 0 | 1 | 0 | 1 | R5 |
| 0 | 0 | 1 | 1 | 0 | R6 |
| 0 | 0 | 1 | 1 | 1 | R7 |
| 0 | 1 | 0 | 0 | 0 | R8 |
| 0 | 1 | 0 | 0 | 1 | R9 |
| 0 | 1 | 0 | 1 | 0 | R10 |
| 0 | 1 | 0 | 1 | 1 | R11 |

## REGISTER MAPS





REGISTER 3 (R3)

| Reserved |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | muxout ${ }^{\text {DBR }}{ }^{1}$ |  |  |  |  | READBACK CONTROL |  |  |  |  |  | CONTROLBITS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | M3 | M2 | M1 | мо | 10L | RC5 | RC4 | RC3 | RC2 | RC1 | RC0 | c5(0) | C4(0) | C3(0) | C2(1) | C1(1) |


| REGISTER 4 (R4) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RESERVED |  |  |  |  |  |  |  |  |  |  | Reserved |  |  |  |  |  | analog test bus |  |  |  |  |  |  |  |  |  | $\begin{gathered} \text { CONTROL } \\ \text { BITS } \end{gathered}$ |  |  |  |  |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 |  |  | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | NDM | 0 | 0 | 0 | 0 | TBA | TBP | AB9 | AB8 | AB7 | AB6 | AB5 | AB4 | AB3 | AB2 | AB1 | ABO | $5(0)$ | C4(0) | C3(1) | C2(0) | C1(0) |


| REGISTER 5 (R5) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RESERVED |  |  | INTEGER WORD |  |  |  |  |  |  |  |  |  |  |  | FRAC MSB WORD |  |  |  |  |  |  |  |  |  |  |  | $\begin{gathered} \text { CONTROL } \\ \text { BITS } \end{gathered}$ |  |  |  |  |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | N11 | N10 | N9 | N8 | N7 | N6 | N5 | N4 | N3 | N2 | N1 | No | F24 | F23 | F22 | F21 | F20 | F19 | F18 | F17 | F16 | F15 | F14 | F13 | C5(0) | C4(0) | C3(1) | C2(0) | C1(1) |


| REGISTER 6 (R6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RESERVED |  |  |  |  |  |  |  |  |  |  |  |  |  | FRAC LSB WORD DBR ${ }^{1}$ |  |  |  |  |  |  |  |  |  |  |  |  | CONTROL BITS |  |  |  |  |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | F12 | F11 | F10 | F9 | F8 | F7 | F6 | F5 | F4 | F3 | F2 | F1 | F0 | C5(0) | C4(0) | C3(1) | C2(1) | C1(0) |

${ }^{1}$ DBR = DOUBLE BUFFERED REGISTER-BUFFERED BY THE WRITE TO REGISTER 5.
Figure 17. Register Summary (Register 0 to Register 6)

REGISTER 7 (R7)

| RESERVED |  |  |  |  |  |  |  | CLOCK DIVIDER DBR ${ }^{1}$ |  |  |  |  |  |  |  |  |  |  |  |  |  | R DIVIDER |  |  | DBR ${ }^{1}$ |  | CONTROL BITS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 |  |  | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 |  |  | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | MR | 1 | C1D11 | C1D10 | C1D9 | C1D8 | C1D7 | C1D6 | C1D5 | C1D4 | C1D3 | C1D2 | C1D1 | C1D0 | RD2 | RD | R4 | R3 | R2 | R1 | R0 | C5(0) | C4(0) | C3(1) | C2(1) | C1(1) |

REGISTER 8 (R8)


REGISTER 9 (R9)


REGISTER 10 (R10)


REGISTER 11 (R11)


Figure 18. Register Summary (Register 7 to Register 11)


Figure 19. Register 0 (RO)

## REGISTER 0

## Control Bits

With Bits[C5:C1] set to 00000, Register R0 is programmed.
Figure 19 shows the input data format for programming this register.

## Auxiliary Buffer Gain

Bits[DB23:DB21] set the auxiliary output buffer gain (see Figure 19).

## Auxiliary Divide by 2

Bit DB20 selects the auxiliary output divider. Setting this bit to 0 selects divide by 2 ( 6 GHz output). Setting the bit to 1 selects divide by 1 ( 12 GHz output).

## Power-Up R Counter

Bit DB15 provides the power-up bit for the R counter block. Setting this bit to 0 performs a power-down of the counter block. Setting this bit to 1 returns the counter block to normal operation.

## Power-Up N Counter

Bit DB14 provides the power-up bit for the N counter block. Setting this bit to 0 performs a power-down of the counter block. Setting this bit to 1 returns the counter block to normal operation.

## Tx2 Amplitude Calibration

Bit DB12 provides the control bit for amplitude calibration of the Transmitter 2 (Tx2) output. Set this bit to 0 for normal operation. Setting this bit to 1 performs an amplitude calibration of the Tx2 output.

## Tx1 Amplitude Calibration

Bit DB11 provides the control bit for amplitude calibration of the Tx1 output. Set this bit to 0 for normal operation. Setting this bit to 1 performs an amplitude calibration of the Tx1 output.

## Power-Up VCO

Bit DB10 provides the power-up bit for the VCO. Setting this bit to 0 performs a power-down of the VCO. Setting this bit to 1 performs a power-up of the VCO.

## ADF5901

## VCO Calibration

Bit DB9 provides the control bit for frequency calibration of the VCO. Set this bit to 0 for normal operation. Setting this bit to 1 performs a VCO frequency and amplitude calibration.

## Power-Up ADC

Bit DB8 provides the power-up bit for the ADC. Setting this bit to 0 performs a power-down of the ADC. Setting this bit to 1 performs a power-up of the ADC.

## Power-Up Tx2 Output

Bit DB7 provides the power-up bit for the Tx2 output. Setting this bit to 0 performs a power-down of the Tx2 output. Setting this bit to 1 performs a power-up of the Tx2 output. Only one Tx output can be powered up at any time, either Tx1 (DB6) or Tx2 (DB7).

## Power-Up Tx 1 Output

Bit DB6 provides the power-up bit for the Tx1 output. Setting this bit to 0 performs a power-down of the Tx1 output. Setting this bit to 1 performs a power-up of the Tx1 output. Only one Tx output can be powered up at any time, either Tx1 (DB6) or Tx2 (DB7).

## Power-Up LO Output

Bit DB5 provides the power-up bit for the LO output. Setting this bit to 0 performs a power-down of the LO output. Setting this bit to 1 performs a power-up of the LO output.

## REGISTER 1

## Control Bits

With Bits[C5:C1] set to 00001, Register R1 is programmed. Figure 20 shows the input data format for programming this register.

## Tx Amplitude Calibration Reference Code

Bits[DB12:DB5] set the Tx amplitude calibration reference code (see Figure 20) for the two Tx outputs during calibration. Calibrate the output power on the Tx outputs from -20 dBm to 8 dBm by setting the Tx amplitude calibration reference code (see Figure 7).

| RESERVED |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Tx AMP CAL REF CODE |  |  |  |  |  |  |  | CONTROL BITS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | TAR7 | TAR6 | TAR5 | TAR4 | TAR3 | TAR2 | TAR1 | TARO | C5(0) | C4(0) | C3(0) | C2(0) | C1(1) |



Figure 20. Register 1 (R1)


Figure 21. Register 2 (R2)

## REGISTER 2

## Control Bits

With Bits[C5:C1] set to 00010, Register R2 is programmed.
Figure 21 shows the input data format for programming this register.

## ADC Start

Bit DB15 starts the ADC conversion. Setting this bit to 1 starts an ADC conversion.

## ADC Average

Bits[DB14:DB13] program the ADC average, which is the number of averages of the ADC output (see Figure 21).

## ADC Clock Divider

Bits[DB12:DB5] program the clock divider, which is used as the sampling clock for the ADC (see Figure 21). The output of the R divider block clocks the ADC clock divider. Program a divider value to ensure the ADC sampling clock is 1 MHz .

## ADF5901



Figure 22. Register 3 (R3)

## REGISTER 3

## Control Bits

With Bits[C5:C1] set to 00011, Register R3 is programmed.
Figure 22 shows the input data format for programming this register.

## MUXOUT Control

Bits[DB15:DB12] control the on-chip multiplexer of the ADF5901. See Figure 22 for the truth table.

## Input/Output (IO) Level

Bit DB11 controls the DOUT logic levels. Setting this bit to 0 sets the DOUT logic level to 1.8 V . Setting this bit to 1 sets the DOUT logic level to 3.3 V .

## Readback Control

Bits[DB10:DB5] control the readback data to DOUT on the ADF5901. See Figure 22 for the truth table.


Figure 23. Register 4 (R4)


Figure 24. Register 5 (R5)

## REGISTER 4

## Control Bits

With Bits[C5:C1] set to 00100, Register R4 is programmed.
Figure 23 shows the input data format for programming this register.

## N Divider to MUXOUT Enable

Bit DB21 controls the internal N divider signal for MUXOUT. Setting this bit to 0 enables the internal N divider signal to MUXOUT. Setting this bit to 1 returns the device to normal operation.

## Test Bus to ADC

Bit DB16 controls the ATEST pin. Set this bit to 0 for normal operation. Setting this bit to 1 connects the analog test bus to the ADC input.

## Test Bus to Pin

Bit DB15 controls the ATEST pin. Setting this bit to 0 sets the ATEST pin to high impedance. Setting this bit to 1 connects the analog test bus to the ATEST pin.

## Analog Test Bus

Bits[DB14:DB5] control the analog test bus. This analog test bus allows access to internal test signals for the temperature sensor. See Figure 23 for the truth table.

## ADF5901

## REGISTER 5

## Control Bits

With Bits[C5:C1] set to 00101, Register R5 is programmed. Figure 24 shows the input data format for programming this register.

## 12-Bit Integer Value (INT)

These 12 bits (Bits[DB28:DB17]) set the INT value, which determines the integer part of the RF division factor. This INT value is used in Equation 5. See the RF Synthesis: a Worked Example section for more information. All integer values from 75 to 4095 are allowed.

## 12-Bit MSB Fractional Value (FRAC)

These 12 bits (Bits[DB16:DB5]), together with Bits[DB17:DB5] (FRAC LSB word) in Register R6, control what is loaded as the FRAC value into the fractional interpolator. This FRAC value partially determines the overall RF division factor. It is also used in Equation 1. These 12 bits are the most significant bits (MSB) of the 25-bit FRAC value, and Bits[DB17:DB5] (FRAC LSB word) in Register R6 are the least significant bits (LSB). See the RF Synthesis: a Worked Example section for more information.

## REGISTER 6

## Control Bits

With Bits[C5:C1] set to 00110, Register R6 is programmed. Figure 25 shows the input data format for programming this register.

## 13-Bit LSB FRAC Value

These 13 bits (Bits[DB17:DB5]), together with Bits[DB16:DB5] (FRAC MSB word) in Register R5, control what is loaded as the FRAC value into the fractional interpolator. This FRAC value partially determines the overall RF division factor. It is also used in Equation 1. These 13 bits are the least significant bits (LSB) of the 25-bit FRAC value, and Bits[DB14:DB3] (FRAC MSB word) in Register R5 are the most significant bits (MSB). See the RF Synthesis: a Worked Example section for more information.



Figure 26. Register 7 (R7)

## REGISTER 7

## Control Bits

With Bits[C5:C1] set to 00111, Register R7 is programmed. Figure 26 shows the input data format for programming this register.

## Master Reset

Bit DB25 provides a master reset bit for the device. Setting this bit to 1 performs a reset of the device and all register maps. Setting this bit to 0 returns the device to normal operation.

## Clock Divider

Bits[DB23:DB12] set a divider for the VCO frequency calibration. Load the divider such that the time base is $10 \mu$ (see Figure 26).

## Reference Doubler

Setting DB10 to 0 feeds the REF in signal directly to the 5-bit R counter, disabling the doubler. Setting this bit to 1 multiplies the $\mathrm{REF}_{\text {IN }}$ frequency by a factor of 2 before the $\mathrm{REF}_{\text {IN }}$ signal is fed into the 5-bit R counter.

The maximum allowable REF $_{\text {IN }}$ frequency when the doubler is enabled is 50 MHz .

## 5-Bit R Divider

The 5-bit R counter allows the input reference frequency ( $\mathrm{REF}_{\text {IN }}$ ) to be divided down to produce the reference clock to the VCO calibration block. Division ratios from 1 to 31 are allowed.

## Divide by 2 (RDIV2)

Setting the DB11 bit to 1 inserts a divide by 2 toggle flip flop between the R counter and VCO calibration block.


| FC9 | FC8 | $\ldots$ | FC4 | FC3 | FC2 | FC1 | FC0 | FREQUENCY CAL <br> DIVIDER |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| 0 | 0 | $\ldots$ | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | $\ldots$ | 0 | 0 | 0 | 0 | 1 | 1 |
| 0 | 0 | $\ldots$ | 0 | 0 | 0 | 1 | 0 | 2 |
| . | . | $\ldots$ | . | . | . | . | . | $\ldots$ |
| . | . | $\ldots$ | . | . | . | . | . | $\ldots$ |
| 1 | 1 | $\ldots$ | 1 | 1 | 1 | 0 | 1 | 1021 |
| 1 | 1 | $\ldots$ | 1 | 1 | 1 | 1 | 0 | 1023 |
| 1 | 1 | $\ldots$ | 1 | 1 | 1 | 1 | 1 | 1024 |

Figure 27. Register 8 (R8)


Figure 28. Register 9 (R9)

## REGISTER 8

## Control Bits

With Bits[C5:C1] set to 01000, Register R8 is programmed. Figure 27 shows the input data format for programming this register.

## Frequency Calibration Clock

Bits[DB14:DB5] set a divider for the VCO frequency calibration clock. Load the divider such that the time base is $10 \mu \mathrm{~s}$ (see Figure 27).

## REGISTER 9

## Control Bits

With Bits[C5:C1] set to 01001, Register R9 is programmed.
Figure 28 shows the input data format for programming this register.


Figure 29. Register 10 (R10)


Figure 30. Register 11 (R11)

## REGISTER 10

## Control Bits

With Bits[C5:C1] set to 01010, Register R10 is programmed. Figure 29 shows the input data format for programming this register.

## REGISTER 11

## Control Bits

With Bits[C5:C1] set to 01011, Register R11 is programmed. Figure 30 shows the input data format for programming this register.

## Counter Reset

Bit DB5 provides a counter reset bit for the counters. Setting this bit to 1 performs a counter reset of the device counters. Setting this bit to 0 returns the device to normal operation.

## INITIALIZATION SEQUENCE

After powering up the device, administer the following programming sequence. The following sequence locks the VCO to 24.125 GHz with a 100 MHz reference and a 50 MHz reference divider frequency:

1. Write 0x02000007 to Register R7 to perform a master reset.
2. Write 0 x 0000002 B to Register R11 to reset the counters.
3. Write $0 \times 0000000 \mathrm{~B}$ to Register R11 to enable the counters.
4. Write 0x1D32A64A to Register R10.
5. Write 0x2A20B929 to Register R9.
6. Write 0 x 40003 E 88 to Register R8 to set the frequency calibration divider clock to 100 kHz .
7. Write $0 \times 809$ FE520 to Register R0 to power up the device and LO ( $10 \mu \mathrm{~s}$ ).
8. Write 0x011F4827 to Register R7 to set the R counter clock to 50 MHz and the calibration clock to 100 kHz .
9. Write $0 x 00000006$ to Register R6 to set the LSB FRAC $=0$.
10. Write 0x01E28005 to Register R5 to set INT $=241$ and MSB FRAC $=1024$. Therefore, $\mathrm{N}=240.25$.
11. Write 0x00200004 to Register R4 to set the ATEST pin to high impedance.
12. Write $0 \times 01890803$ to Register R3 to set the IO level to $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V}$.
13. Write 0x00020642 to Register R2 to set the ADC clock to 1 MHz .
14. Write 0xFFF7FFE1 to Register R1 to set the Tx amplitude level.
15. Write 0x809FE720 to Register R0 to set the VCO frequency calibration ( $800 \mu \mathrm{~s}$ ).
16. Write 0x809FE560 to Register R0 to power Tx1 on, Tx2 off, and LO on.
17. Write 0x809FED60 to Register R0 to set the Tx1 amplitude calibration ( $400 \mu \mathrm{~s}$ ).
18. Write 0x809FE5A0 to Register R0 to turn Tx1 off, Tx2 on, and LO on.
19. Write $0 \times 809$ FF5A0 to Register R0 to set the Tx2 amplitude calibration ( $400 \mu \mathrm{~s}$ ).
20. Write $0 \times 2800 \mathrm{~B} 929$ to Register R9.
21. Write $0 \times 809 \mathrm{~F} 25 \mathrm{~A} 0$ to Register R0 to disable the R and N counters.

## RECALIBRATION SEQUENCE

The ADF5901 can be recalibrated after the initialization sequence is complete and the device is powered up. The recalibration sequence must be run for every $10^{\circ} \mathrm{C}$ temperature change; the temperature can be monitored using the temperature sensor (see the Temperature Sensor section).

1. Write $0 \times 809 \mathrm{FE} 520$ to Register R0 to enable the counters. Tx1 and Tx2 are off, and LO is on.
2. Write 0x2A20B929 to Register R9.
3. Write 0xFFF7FFE1 to Register R1 to set the Tx amplitude level.
4. Write 0x809FE720 to Register R0 to set the VCO frequency calibration ( $800 \mu \mathrm{~s}$ ).
5. Write $0 \times 809 \mathrm{FE} 560$ to Register R0 to power Tx1 on, Tx2 off, and LO on.
6. Write $0 \times 809$ FED60 to Register R0 to set the Tx1 amplitude calibration ( $400 \mu \mathrm{~s}$ ).
7. Write 0 x 89 FE 5 A 0 to Register R0 to power Tx1 off, Tx2 on, and LO on.
8. Write 0x809FF5A0 to Register R0 to set the Tx2 amplitude calibration ( $400 \mu \mathrm{~s}$ ).
9. Write 0x2800B929 to Register R9.
10. Write 0x809F25A0 to Register R0 to disable the R and N counters.

## TEMPERATURE SENSOR

The ADF5901 has an on-chip temperature sensor that can be accessed on the ATEST pin or as a digital word on DOUT following an ADC conversion. The temperature sensor operates over the full operating temperature range of $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$.
The accuracy can be improved by performing a one-point calibration at room temperature and storing the result in memory.
With the temperature sensor on the analog test bus and test bus connected to the ATEST pin (Register 4 set to 0x0000A064) the ATEST voltage can be converted to temperature with the following equation:

$$
\begin{equation*}
\text { Temperature }\left({ }^{\circ} \mathrm{C}\right)=\frac{\left(V_{\text {ATEST }}-V_{\text {OFF }}\right)}{V_{\text {GAIN }}} \tag{3}
\end{equation*}
$$

where:
$V_{\text {ATEST }}$ is the voltage on the ATEST pin.
$V_{\text {OFF }}=0.699 \mathrm{~V}$, the offset voltage.
$V_{\text {GAIN }}=6.4 \times 10^{-3}$, the voltage gain.
The temperature sensor result can be converted to a digital word with the ADC and readback on DOUT with the following sequence:

1. Write 0x809FA5A0 to Register R0 to enable the counters.
2. Write $0 \times 00012064$ to Register R4 to connect the analog test bus to the ADC and $\mathrm{V}_{\text {TEMP }}$ to the analog test bus.
3. Write $0 \times 00028 \mathrm{C} 82$ to Register R2 to start the ADC conversion.
4. Write 0x018902C3 to Register R3 to set the output ADC data to DOUT.
5. Read back DOUT.
6. Write 0x809F25A0 to Register R0 to disable R and N counters.

Convert the DOUT word to temperature with the following equation:

$$
\begin{equation*}
\text { Temperature }\left({ }^{\circ} \mathrm{C}\right)=\frac{\left(\left(A D C \times V_{L S B}\right)-V_{\text {OFF }}\right)}{V_{G A I N}} \tag{4}
\end{equation*}
$$

where:
$A D C$ is the ADC code read back on DOUT.
$V_{L S B}=7.33 \mathrm{mV}$, the ADC LSB voltage.
$V_{\text {OFF }}=0.699 \mathrm{~V}$, the offset voltage.
$V_{\text {GAIN }}=6.4 \times 10^{-3}$, the voltage gain.

## RF SYNTHESIS: A WORKED EXAMPLE

The following equation governs how to program the ADF5901:

$$
\begin{equation*}
R F_{\text {OUT }}=\left(I N T+\left(F R A C / 2^{25}\right)\right) \times\left(f_{\text {REF }}\right) \times 2 \tag{5}
\end{equation*}
$$

where:
$R F_{\text {out }}$ is the RF frequency output.
$I N T$ is the integer division factor.
$F R A C$ is the fractionality.

$$
\begin{equation*}
f_{R E F}=R E F_{I N} \times((1+D) /(R \times(1+T))) \tag{6}
\end{equation*}
$$

where:
$R E F_{\text {IN }}$ is the reference frequency input.
$D$ is the reference doubler bit, DB10 in Register R7 (0 or 1).
$R$ is the reference division factor.
$T$ is the reference divide by 2 bit, DB11 in Register R7 ( 0 or 1).
For example, in a system where a 24.125 GHz RF frequency output ( $\mathrm{RFOut}_{\text {) }}$ is required and a 100 MHz reference frequency input ( $\mathrm{REF}_{\text {IN }}$ ) is available, $\mathrm{f}_{\text {REF }}$ is set to 50 MHz .
From Equation 6,

$$
f_{R E F}=(100 \mathrm{MHz} \times(1+0) /(1 \times(1+1))=50 \mathrm{MHz}
$$

From Equation 5,

$$
24.125 \mathrm{GHz}=50 \mathrm{MHz} \times\left(N+F R A C / 2^{25}\right) \times 2
$$

Calculating the N and FRAC values,

$$
\begin{aligned}
& N=\operatorname{int}\left(R F_{\text {OUT }} /\left(f_{\text {REF }} \times 2\right)\right)=241 \\
& F R A C=F_{\text {MSB }} \times 2^{13}+F_{L S B} \\
& F_{M S B}=\operatorname{int}\left(\left(\left(R F_{\text {OUT }} /\left(f_{\text {REF }} \times 2\right)\right)-\mathrm{N}\right) \times 2^{12}\right)=1024 \\
& F_{\text {LSB }}=\operatorname{int}\left(\left(\left(\left(\left(R F_{\text {OUT }} /\left(f_{\text {REF }} \times 2\right)\right)-\mathrm{N}\right) \times 2^{12}\right)-F_{M S B}\right) \times 2^{13}\right)=0
\end{aligned}
$$

where:
$F_{M S B}$ is the 12-bit MSB FRAC value in Register R5.
$F_{L S B}$ is the 13-bit LSB FRAC value in Register R6.
$\operatorname{int}()$ makes an integer of the argument in parentheses.

## APPLICATIONS INFORMATION

APPLICATION OF THE ADF5901 IN FMCW RADAR
Figure 31 shows the application of the ADF5901 in a frequency modulated continuous wave (FMCW) radar system.

In the FMCW radar system, the ADF4159 generates the sawtooth or triangle ramps necessary for this type of radar to operate.
The ADF4159 controls the $\mathrm{V}_{\text {TUNE }}$ pin on the ADF5901 (Tx) MMIC and thus the frequency of the VCO and the Tx output signal on TX ${ }_{\text {out }} 1$ or TXout2. The LO signal from the ADF5901 is fed to the LO input on the ADF5904.

The ADF5904 downconverts the signal from the four receiver antennas to baseband with the LO signal from the Tx MMIC.

The downconverted baseband signals from the four receiver channels on the ADF5904 are fed to the ADAR7251 4-channel, continuous time, $\Sigma-\Delta$ analog-to-digital converter (ADC).
A digital signal processor (DSP) follows the ADC to handle the target information processing.


## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-220-WHHD-5.
Figure 32. 32-Lead Lead Frame Chip Scale Package [LFCSP]
$5 \mathrm{~mm} \times 5 \mathrm{~mm}$ Body and 0.75 mm Package Height (CP-32-12)

## ORDERING GUIDE

| Model $^{1}$ | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| ADF5901ACPZ | $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$ | 32 -Lead Lead Frame Chip Scale Package [LFCSP] | CP-32-12 |
| ADF5901ACPZ-RL7 | $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$ | 32 -Lead Lead Frame Chip Scale Package [LFCSP] | CP-32-12 |
| ADF5901WCCPZ | $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$ | 32 -Lead Lead Frame Chip Scale Package [LFCSP] | CP-32-12 |
| ADF5901WCCPZ-RL7 | $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$ | $32-$ Lead Lead Frame Chip Scale Package [LFCSP] | CP-32-12 |
| EV-ADF5901SD2Z |  | Evaluation Board |  |

${ }^{1} Z=$ RoHS Compliant Part.

## AUTOMOTIVE PRODUCTS

The ADF5901W models are available with controlled manufacturing to support the quality and reliability requirements of automotive applications. Note that these automotive models may have specifications that differ from the commercial models; therefore, designers should review the Specifications section of this data sheet carefully. Only the automotive grade products shown are available for use in automotive applications. Contact your local Analog Devices account representative for specific product ordering information and to obtain the specific Automotive Reliability reports for these models.

