Ultrasonic sensor
UB500-F42-E6-V15

Dimensions

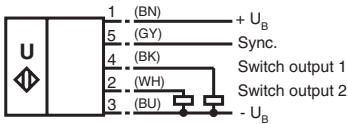## Features

- 2 independent switch outputs
- Extremely small unusable area
- TEACH-IN
- Interference suppression (adjustable switching treshold tracking and angle of divergence of sound beam)
- Temperature compensation
- Synchronisation options
- NO/NC selectable

$C \epsilon$

Technical data

General specifications

Sensing range	30 ... 500 mm
Adjustment range	50 ... 500 mm
Unusable area	0 ... 30 mm
Standard target plate	100 mm x 100 mm
Transducer frequency	approx. 390 kHz
Response delay	approx. 50 ms

Indicators/operating means

LED yellow 1	permanent: switching state switch output 1 flashing: TEACH-IN function
LED yellow 2	permanent: switching state switch output 2 flashing: TEACH-IN function
LED red	"Error", object uncertain in TEACH-IN function: No object detected

Electrical specifications

Operating voltage	10 ... 30 V DC , ripple 10 %$_{SS}$
No-load supply current I_0	$\leq$ 50 mA

Input/Output

Synchronisation	1 synchro input 0-level: $-U_B$...+1 V; 1-level: +4 V...$+U_B$ input impedance: > 12 Ω synchronisation pulse: $\geq$ 100 µs; synchronisation pulse interval: $\geq$ 2 ms
Synchronisation frequency	
Common mode operation	$\leq$ 95 Hz
Multiplex operation	$\leq$ 95/n Hz, n = number of sensors

Output

Output type	2 switch outputs pnp, normally open/close selectable
Repeat accuracy	$\leq$ 0,5 % of switching point
Rated operational current I_e	200 mA , short-circuit/overload protected
Voltage drop U_d	$\leq$ 2,5 V
Switching frequency f	$\leq$ 8 Hz
Range hysteresis H	1 % of the set operating distance
Temperature influence	$\pm$ 1 % of full-scale value

Standard conformity

Standards	EN 60947-5-2

Ambient conditions

Ambient temperature	-25 ... 70 °C (248 ... 343 K)
Storage temperature	-40 ... 85 °C (233 ... 358 K)

Mechanical specifications

Protection degree	IP65
Connection	connector V15 (M12 x 1), 5 pin
Material	
Housing	PBT
Transducer	epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT
Mass	140 g

Electrical connection

Standard symbol/Connections:
(version E6, pnp)

Pin	Colour	Function
1	(BN)	+ U_B
5	(GY)	Sync.
4	(BK)	Switch output 1
2	(WH)	Switch output 2
3	(BU)	- U_B

Core colours in accordance with EN 60947-5-2.

Connector V15

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2003-03-25

Notes

Parameterization:

You can use 2 keys to parameterize the sensor. In order to start the switch point 1 learning mode, press the A1 key; in order to start the switch point 2 learning mode, press the A1 key.

If you keep both keys pressed as you switch on the power supply, the sensor will switch over to the sensitivity adjustment mode of operation.

In case the parameterization procedure is not completed within 5 minutes, the sensor will discontinue the process and retain all previous settings.

Teaching in switch points:

Teaching in A1 switch point by pressing A1 key

Keep A1 key > pressed for 2 s	The sensor enters the switch point 1 learning mode
Position target object in the desired distance	The sensor indicates via LED lights whether the target object has been detected. In case the object has been detected, the yellow LED will flash; if the object has not been detected, the red LED flashes.
Briefly press the A1 key	The sensor completes the switch point 1 teach-in process and saves this value in non-volatile memory. In the event of an uncertain object (flashing red LED), the value learned is invalid. The system exits the teach-in mode.

Analogously, the A2 switch point is learned in the same fashion as described above using the A2 key.
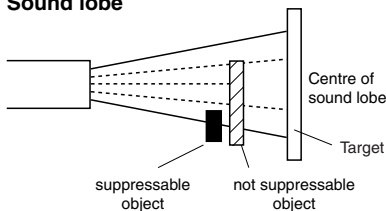
Suppression of disturbing targets

Some types of installation or particular conditions during operation of an ultrasonic sensor may admit that undesired objects (such as shelf brow posts, edges of machines) are closer than the actual target as they enter the recording range. In this case, the sensor would normally detect these objects rather than the desired target. So in order to ensure an error-free operation, in may be necessary to suppress those objects.

Objects can be suppressed if they meet the following conditions:
- The disturbing target must not hide the actual target completely.
- The amplitude of the disturbing signal must be smaller than the amplitude of the desired signal.
- The disturbing target must remain in the edge region of the sound lobe and must not enter its center.
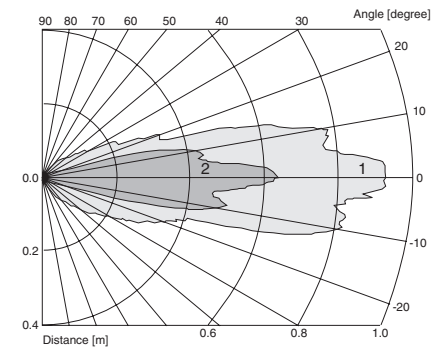
Sound lobe

The suppression of the disturbing target is effected through reduction of the response sensitivity. This figure shows its effect on the response characteristics of the sensor. The sensor is preset on step 1 by the manufacturer.
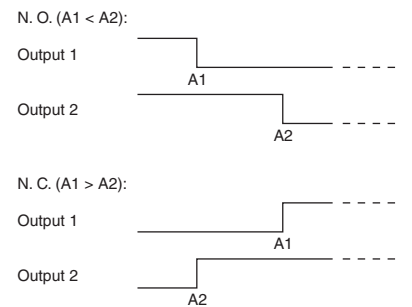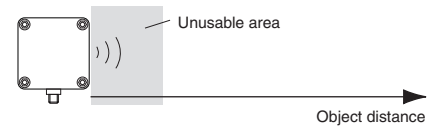
Model number

UB500-F42-E6-V15

Characteristic curves/additional information

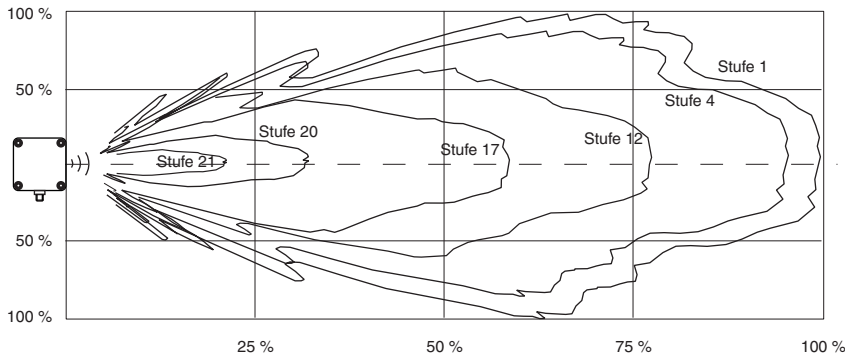### Characteristic response curve

Curve 1: flat surface 100 mm x 100 mm
Curve 2: round bar, Ø 25 mm

Switching output programmation

A1 → ∞ , A2 → ∞ : Object presence detection
Both outputs are active if Object within detection range.

Note:
→ ∞ means: cover transducer surface with your hand, while programming the output.
If A1 = A2, the output work like A1 < A2

Sensitivity adjustment for suppression of disturbing targets

Remove the actual target object from the detection range.

Keep A1 and A2 keys pressed as you switch on power supply.	The sensor enters the sensitivity adjustment mode of operation. The sensor sensitivity can be adjusted in 24 steps. Step 1 = high response Step 24 = low response
Briefly press the A1 key	Response is increased. The LED lights indicate the actual state of the sensor. - flashing red: no disturbing target detected - flashing yellow: disturbing target detected - permanent red: upper setting limit is reached.
Briefly press the A2 key	Response is decreased. The LED lights indicate the actual state of the sensor. - flashing red: no disturbing target detected - flashing yellow: disturbing target detected - permanent red: lower setting limit is reached.
Press both A1 and A2 keys at once	Exiting sensitivity adjustment. The sensor response is saved in non-volatile memory. In the event the sensitivity adjustment is not exited through this procedure, the sensor will exit this operation mode automatically after 5 minutes, and the previous sensitivity value remains valid.

Synchronization

In order to prevent conflicts, the sensor is equipped with a synchronization connection. In case this is unwired, the sensor function is based on an intern clock rate. Several sensors can be synchronized through the following methods:

External synchronization:
The sensor can be synchronized by application of external square wave voltage. A synchronizing pulse at the synchronization input triggers a measuring cycle. The pulse width needs to be bigger than 100µs. The measuring cycle is started with the falling edge. A low level > 1 s or an open synchronization input causes the sensor to operate at normal operating mode. A high level at the synchronization input deactivates the sensor.

There are two possible operation modes:
- Several sensors are controlled by the same synchronization signal. The sensors function in common mode.
- The respective synchronizing pulses are directed to just one sensor each cyclically. The sensors function in multiplex mode.

Self synchronization:
The synchronization connections of up to 5 sensors offering a self synchronization option are interconnected. After switching on power supply, these sensors function in the multiplex mode. The response delay increases according to the number of sensors to be synchronized. During the teach-in process no synchronization can be performed and vice versa. For teaching in switch points, the sensors need to be operated in an unsynchronized state.

Note:

If the option for synchronization is not used, the synchronization input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

Accessories

Mounting aids

MH 04-3505

Cable sockets [*]

V15-G-2M-PVC
V15-W-2M-PUR

[*] For additional cable sockets see section „Accessories".