

AS7263

6-Channel NIR Spectral_ID Device with **Electronic Shutter and Smart Interface**

General Description

The AS7263 is a digital 6-channel spectrometer for spectral identification in the near IR (NIR) light wavelengths. AS7263 consists of 6 independent optical filters whose spectral response is defined in the NIR wavelengths from approximately 600nm to 870nm with full-width half-max (FWHM) of 20nm. An integrated LED driver with programmable current is provided for electronic shutter applications.

The AS7263 integrates Gaussian filters into standard CMOS silicon via Nano-optic deposited interference filter technology and is packaged an LGA package that provides a built in aperture to control the light entering the sensor array.

Control and Spectral data access is implemented through either the I²C register set, or with a high level AT Spectral Command set via a serial UART.

Ordering Information and Content Guide appear at end of datasheet.

Key Benefits & Features

The benefits and features of AS7263, 6-Channel NIR Spectral_ID Device with Electronic Shutter and Smart Interface are listed below:

Figure 1: **Added Value of Using AS7263**

| Benefits | Features |
|---|---|
| Compact 6-channel spectrometry solution | 6 near-IR channels: 610nm, 680nm, 730nm, 760nm, 810nm and 860nm, each with 20nm FWHM |
| Simple text-based command interface via UART, or direct register read and write with interrupt on sensor ready option on I²C | UART or I ² C slave digital Interface |
| Lifetime-calibrated sensing with no drift over time or temperature | NIR filter set realized by silicon interference filters |
| No additional signal conditioning required | 16-bit ADC with digital access |
| Electronic shutter control/synchronization | Programmable LED drivers |
| Low voltage operation | • 2.7V to 3.6V with I ² C interface |
| Small, robust package, with built-in aperture | • 20-pin LGA package 4.5mm x 4.7mm x 2.5mm, -40°C to 85°C temperature range |



Applications

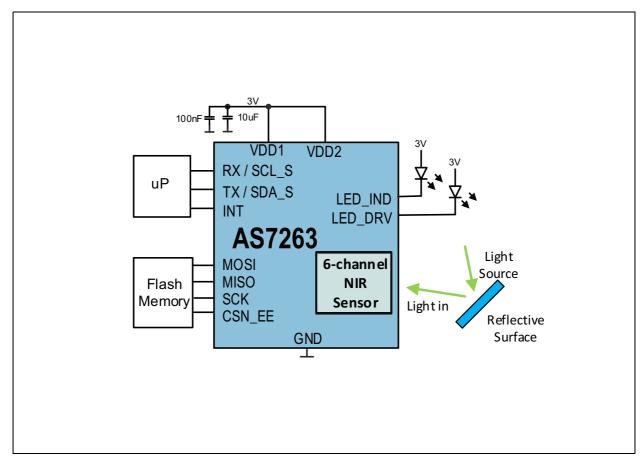
The AS7263 applications include:

- Product authentication
- Bank note/document validation
- Chemical analysis
- Food/beverage safety

Block Diagram

The functional blocks of this device are shown below:

Figure 2: AS7263 NIR Spectral_ID System



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Pin Assignment

The device pin assignments are described below.

Figure 3: Pin Diagram (Top View)

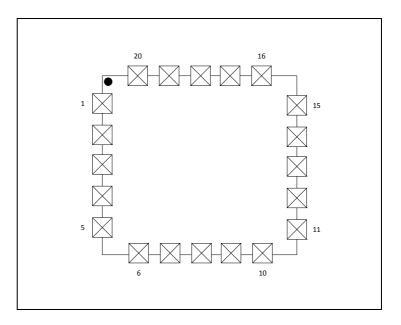


Figure 4: Pin Description

| Pin Number | Pin Name | Description |
|------------|----------|---|
| 1 | NF | Not Functional. Do not connect. |
| 2 | RESN | Reset, Active LOW |
| 3 | SCK | SPI Serial Clock |
| 4 | MOSI | SPI Master Out Slave In |
| 5 | MISO | SPI Master In Slave Out |
| 6 | CSN_EE | Chip Select for External Serial Flash Memory, Active LOW |
| 7 | CSN_SD | Chip Select for SD Card Interface, Active LOW |
| 8 | I2C_ENB | Select UART (Low) or I ² C (High) Operation |
| 9 | NF | Not Functional. Do not connect. |
| 10 | NF | Not Functional. Do not connect. |
| 11 | RX/SCL_S | RX (UART) or SCL_S (I ² C Slave) Depending on I ² C_ENB |
| 12 | TX/SDA_S | TX (UART) or SDA_S (I ² C Slave) Depending on I ² C_ENB |
| 13 | INT | Interrupt, Active LOW |
| 14 | VDD2 | Voltage Supply |

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| Pin Number | Pin Name | Description |
|------------|----------|---|
| 15 | LED_DRV | LED Driver Output for Driving LED, Current Sink |
| 16 | GND | Ground |
| 17 | VDD1 | Voltage Supply |
| 18 | LED_IND | LED Driver Output for Indicator LED, Current Sink |
| 19 | NF | Not Functional. Do not connect. |
| 20 | NF | Not Functional. Do not connect. |

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Absolute Maximum Ratings

Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated under Electrical Characteristics is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. The device is not designed for high energy UV (ultraviolet) environments, including upward looking outdoor applications, which could affect long term optical performance.

Figure 5:
Absolute Maximum Ratings

| Symbol | Parameter | Min | Max | Units | Comments | | | | | | | | |
|----------------------|--|-------------|--------------|-----------|---|--|--|--|--|--|--|--|--|
| | Electrical Parameters | | | | | | | | | | | | |
| V _{DD1_MAX} | Supply Voltage VDD1 | -0.3 | 5 | V | Pin VDD1 to GND | | | | | | | | |
| V _{DD2_MAX} | Supply Voltage VDD2 | -0.3 | 5 | V | Pin VDD2 to GND | | | | | | | | |
| V _{DD_IO} | Input/Output Pin Voltage | -0.3 | VDD+0.3 | V | Input/Output Pin to GND | | | | | | | | |
| I _{SCR} | Input Current (latch-up immunity) | ± | 100 | mA | JESD78D | | | | | | | | |
| | Electrostatic Discharge | | | | | | | | | | | | |
| ESD _{HBM} | ESD _{HBM} Electrostatic Discharge HBM | | | V | JS-001-2014 | | | | | | | | |
| ESD _{CDM} | Electrostatic Discharge CDM | ± 500 | | V | JSD22-C101F | | | | | | | | |
| | Temperatu | re Ranges a | nd Storage C | onditions | | | | | | | | | |
| T _{STRG} | Storage Temperature Range | -40 | 85 | °C | | | | | | | | | |
| T _{BODY} | Package Rody | | 260 | °C | IPC/JEDEC J-STD-020 The reflow peak soldering temperature (body temperature) is specified according to IPC/JEDEC J-STD-020 "Moisture/Reflow Sensitivity Classification for Non-hermetic Solid State Surface Mount Devices." | | | | | | | | |
| RH _{NC} | Relative Humidity (non-condensing) | 5 85 | | % | | | | | | | | | |
| MSL | Moisture Sensitivity Level | 3 | | | Maximum floor life time of 168 hours | | | | | | | | |

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Electrical Characteristics

All limits are guaranteed with VDD = VDD1 = VDD2 = 3.3V, T_{AMB} =25°C. The parameters with min and max values are guaranteed with production tests or SQC (Statistical Quality Control) methods.

Figure 6: Electrical Characteristics of AS7263

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | | | | | |
|-------------------------------------|--|----------------------------|------|-----|------|------|--|--|--|--|--|
| General Operating Conditions | | | | | | | | | | | |
| VDD1 /VDD2 | Voltage Operating Supply | UART Interface | 2.97 | 3.3 | 3.6 | V | | | | | |
| VDD1 /VDD2 | Voltage Operating Supply | I ² C Interface | 2.7 | 3.3 | 3.6 | V | | | | | |
| T _{AMB} | Operating Temperature | | -40 | 25 | 85 | °C | | | | | |
| I _{VDD} | Operating Current | | | | 5 | mA | | | | | |
| I _{STANDBY} ⁽¹⁾ | Standby Current | | | 12 | | μΑ | | | | | |
| | | Internal RC Oscillator | | | | | | | | | |
| F _{OSC} | Internal RC Oscillator Frequency | | 15.7 | 16 | 16.3 | MHz | | | | | |
| t _{JITTER} (2) | Internal Clock Jitter | @25°C | | | 1.2 | ns | | | | | |
| | | Temperature Sensor | • | | 1 | ı | | | | | |
| D _{TEMP} | Absolute Accuracy of the Temperature Measurement | | -8.5 | | 8.5 | °C | | | | | |
| | | Indicator LED | I | | | | | | | | |
| I _{IND} | LED Current | | 1 | 4 | 8 | mA | | | | | |
| I _{ACC} | Accuracy of Current | | -30 | | 30 | % | | | | | |
| V _{LED} | Voltage Range of Connected LED | Vds of current sink | 0.3 | | VDD | V | | | | | |
| | | LED_DRV | | | | | | | | | |
| I _{LED1} | LED Current | 12.5, 25, 50 or 100 | 12.5 | | 100 | mA | | | | | |
| I _{ACC} | Accuracy of Current | | -10 | | 10 | % | | | | | |
| V _{LED} | Voltage Range of Connected LED | Vds of current sink | 0.3 | | VDD | V | | | | | |

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| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | | | | | | |
|-----------------------------------|--------------------------------|---------------|-------------|-----|--------------|------|--|--|--|--|--|--|
| | Digital Inputs and Outputs | | | | | | | | | | | |
| I _{IH} , I _{IL} | Logic Input Current | Vin=0V or VDD | -1 | | 1 | μΑ | | | | | | |
| I _{ILRESN} | Logic Input Current (RESN pin) | Vin=0V | -1 | | -0.2 | mA | | | | | | |
| V _{IH} | CMOS Logic High Input | | 0.7* VDD | | VDD | V | | | | | | |
| V _{IL} | CMOS Logic Low Input | | 0 | | 0.3* VDD | V | | | | | | |
| V _{OH} | CMOS Logic High Output | I=1mA | | | VDD - 0.4 | V | | | | | | |
| V _{OL} | CMOS Logic Low Output | I=1mA | | | 0.4 | V | | | | | | |
| t _{RISE} (2) | Current Rise Time | C(Pad)=30pF | | | 5 | ns | | | | | | |
| t _{FALL} ⁽²⁾ | Current Fall Time | C(Pad)=30pF | | | 5 | ns | | | | | | |

Note(s):

- 1. 15µA over temperature
- 2. Guaranteed, not tested in production



Timing Characteristics

Figure 7: AS7263 I²C Slave Timing Characteristics

| Symbol | Parameter | Condition | Min | Тур | Max | Unit | | | | | |
|---------------------|--|--|-----|-----|-----|------|--|--|--|--|--|
| | I ² C Interface | | | | | | | | | | |
| f _{SCLK} | SCL Clock Frequency | | 0 | | 400 | kHz | | | | | |
| t _{BUF} | Bus Free Time Between a STOP and START | | 1.3 | | | μs | | | | | |
| t _{HS:STA} | Hold Time (Repeated) START | | 0.6 | | | μs | | | | | |
| t _{LOW} | LOW Period of SCL Clock | | 1.3 | | | μs | | | | | |
| t _{HIGH} | HIGH Period of SCL Clock | | 0.6 | | | μs | | | | | |
| t _{SU:STA} | Setup Time for a Repeated START | | 0.6 | | | μs | | | | | |
| t _{HS:DAT} | Data Hold Time | | 0 | | 0.9 | μs | | | | | |
| t _{SU:DAT} | Data Setup Time | | 100 | | | ns | | | | | |
| t _R | Rise Time of Both SDA and SCL | | 20 | | 300 | ns | | | | | |
| t _F | Fall Time of Both SDA and SCL | | 20 | | 300 | ns | | | | | |
| t _{SU:STO} | Setup Time for STOP Condition | | 0.6 | | | μs | | | | | |
| C _B | Capacitive Load for Each Bus Line | CB — total capacitance of one bus line in pF | | | 400 | pF | | | | | |
| C _{I/O} | I/O Capacitance (SDA, SCL) | | | | 10 | pF | | | | | |

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Figure 8: I²C Slave Timing Diagram

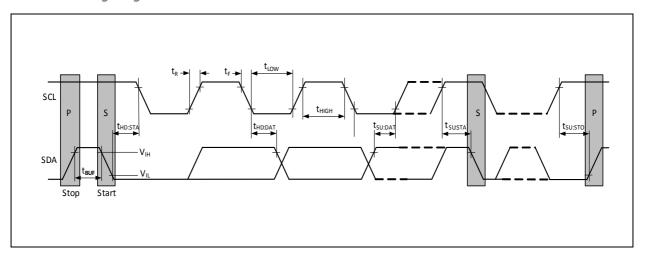


Figure 9: AS7263 SPI Timing Characteristics

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit | | | | | | |
|-----------------------|---------------------|---|-----|-----|-----|------|--|--|--|--|--|--|
| | SPI Interface | | | | | | | | | | | |
| f _{SCK} | Clock Frequency | | 0 | | 16 | MHz | | | | | | |
| t _{SCK_H} | Clock High Time | | 40 | | | ns | | | | | | |
| t _{SCK_L} | Clock Low Time | | 40 | | | ns | | | | | | |
| t _{SCK_RISE} | SCK Rise Time | | 5 | | | ns | | | | | | |
| t _{SCK_FALL} | SCK Fall Time | | 5 | | | ns | | | | | | |
| t _{CSN_S} | CSN Setup Time | Time between CSN high-low transition to first SCK high transition | 50 | | | ns | | | | | | |
| t _{CSN_H} | CSN Hold Time | Time between last SCK falling edge and CSN low-high transition | 100 | | | ns | | | | | | |
| t _{CSN_DIS} | CSN Disable Time | | 100 | | | ns | | | | | | |
| t _{DO_S} | Data-Out Setup Time | | 5 | | | ns | | | | | | |
| t _{DO_H} | Data-Out Hold Time | | 5 | | | ns | | | | | | |
| t _{DI_V} | Data-In Valid | | 10 | | | ns | | | | | | |

Note(s):

1. Guaranteed, not tested in production

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Figure 10: **SPI Master Write Timing Diagram**

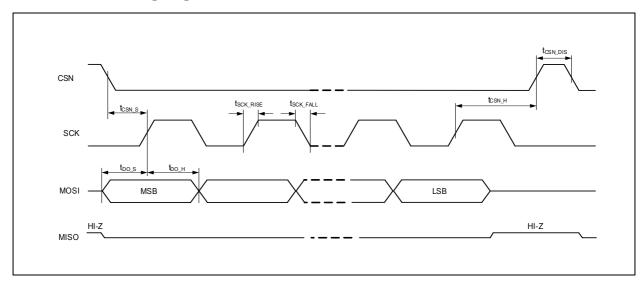
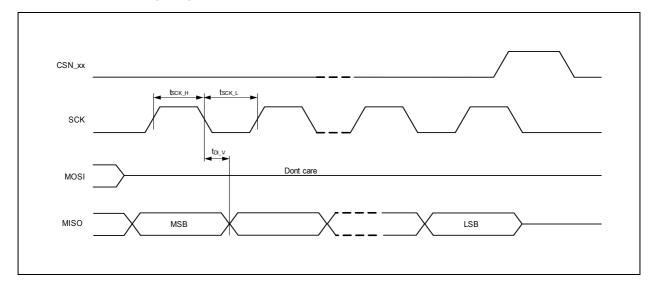


Figure 11: **SPI Master Read Timing Diagram**



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Optical Characteristics

Figure 12: Optical Characteristics of AS7263 (Pass Band)⁽¹⁾

| Symbol | Parameter | Test Conditions | Channel (nm) | Min | Тур | Max | Unit |
|--------|---------------------------|------------------------------------|-----------------|-----|------------------------------------|-----|----------------------------------|
| R | Channel R | Incandescent ^{(2), (4)} | 610 | | 35 ^{(3),(4)} | | counts/ (μW/cm ²) |
| S | Channel S | Incandescent (2), (4) | 680 | | 35 ^{(3),(4)} | | counts/ (μW/cm ²) |
| Т | Channel T | Incandescent (2), (4) | 730 | | 35 ^{(3),(4)} | | counts/ (μW/cm ²) |
| U | Channel U | Incandescent (2), (4) | 760 | | 35 ^{(3),(4)} | | counts/ (μW/cm ²) |
| V | Channel V | Incandescent ^{(2), (4)} | 810 | | 35 ^{(3),(4)} | | counts/ (μW/cm ²) |
| w | Channel W | Incandescent ^{(2), (4)} | 860 | | 35 ⁽³⁾ , ⁽⁴⁾ | | counts/ (μW/cm ²) |
| FWHM | Full Width Half Max | | 20 | | 20 | | nm |
| Wacc | Wavelength Accuracy | | | | ±5 | | nm |
| dark | Dark Channel Counts | GAIN=64, T _{AMB} =25°C | | | | 5 | counts |
| f | Angle of Incidence | On the sensors | | | ±20.0 | | deg |

Note(s):

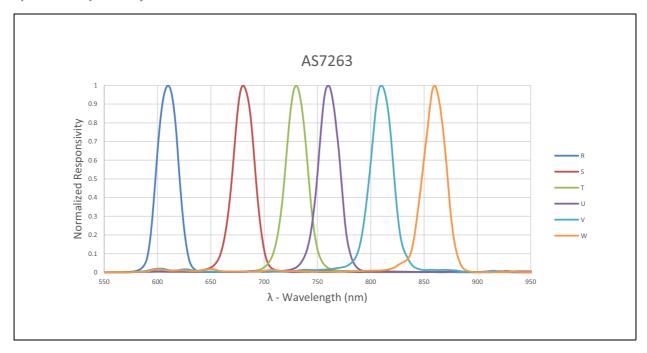
- 1. Calibration & measurements are made using diffused light.
- 2. Each channel is tested with GAIN = 16x, Integration Time (INT_T) = 166ms and VDD = VDD1 = VDD2 = 3.3V, T_{AMB} =25°C.
- 3. The accuracy of the channel counts/ μ W/cm² is $\pm 12\%$.
- 4. The light source is an incandescent light with an irradiance of $\sim 1500 \mu W/cm^2$ (300-1000nm). The energy at each channel (R, S, T, U, V, W) is calculated with a ±33nm bandwidth around the center wavelengths (610, 680, 730, 760, 810, 860nm).

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Typical Operating Characteristics

Figure 13: Spectral Responsivity

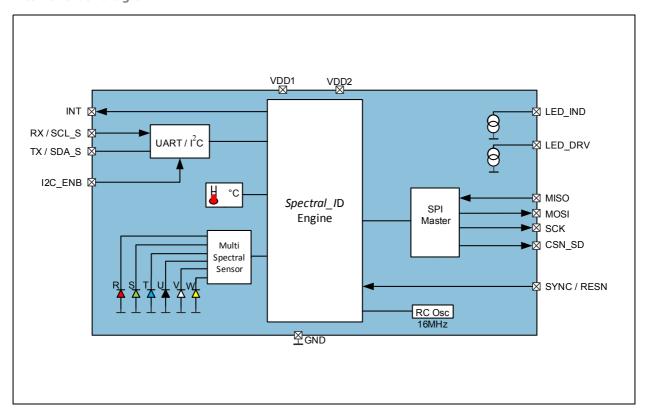


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Detailed Description

Figure 14: Internal Block Diagram



6-Channel NIR Spectral_ID Detector

The AS7263 6-channel Spectral_ID is a next-generation digital spectral sensor device. Each channel has a Gaussian filter characteristic with a full width half maximum (FWHM) bandwidth of 20nm. The channels are spaced roughly at 50nm intervals in the NIR spectrum: R, S, T, U, V, W. The sensor contains analog-to-digital converters (16-bit resolution ADC), which integrate the current from each channel's photodiode. Upon completion of the conversion cycle, the integrated result is transferred to the corresponding data registers. The transfers are double-buffered to ensure that the integrity of the data is maintained.

Interference filters enable high temperature stability and eliminate lifetime drift. Filter accuracy will be affected by the angle of incidence, and require 0° angle of incidence $\pm 20.0^\circ$ for specified accuracy. Angles of light beyond this will shift the spectral response of the filters. The LGA package aperture assists in the control of the light input, helping to maintain the proper angle of incidence at the sensors.

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Data Conversion Description

AS7263 spectral conversion is implemented via two photodiode banks per device. Bank 1 consists of data from the S, T, U, V photodiodes. Bank 2 consists of data from the R, T, U, W photodiodes. Spectral conversion requires the integration time (IT in ms) set to complete. If both photodiode banks are required to complete the conversion, the 2nd bank requires an additional IT ms. Minimum IT for a single bank conversion is 2.8 ms. If data is required from all 6 photodiodes then the device must perform 2 full conversions (2 x Integration Time).

The spectral conversion process is controlled with BANK Mode settings as follows:

BANK Mode 0: Data will be available in registers S, T, U & V (R and W registers will be zero)

BANK Mode 1: Data will be available in registers R, T, U & W (V and W registers will be zero)

BANK Mode 2: Data will be available in registers R, S, T, U, V & W

When the bank setting is Mode 0, Mode 1, or Mode 2, the spectral data conversion process operates continuously, with new data available after each IT ms period. In the continuous modes, care should be taken to assure prompt interrupt servicing so that integration values from both banks are all derived from the same spectral conversion cycle.

BANK Mode 3: Data will be available in registers R, S, T, U, V & W in One-Shot mode

When the bank setting is Mode 3, the device operates in One-Shot mode. Spectral conversion occurs only when bit 0 of the control register (1SHOT) is set to 1. The 1SHOT bit in the control register is subsequently cleared by hardware at the same time the DATA_RDY bit is set to 1 indicating the availability of spectral conversion result data. The One-Shot mode is intended for use when it is critical to ensure that spectral conversion results are obtained contemporaneously.

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Figure 15: Photo Diode Array

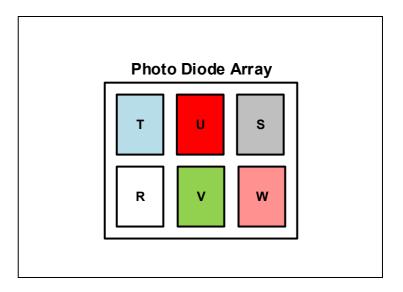
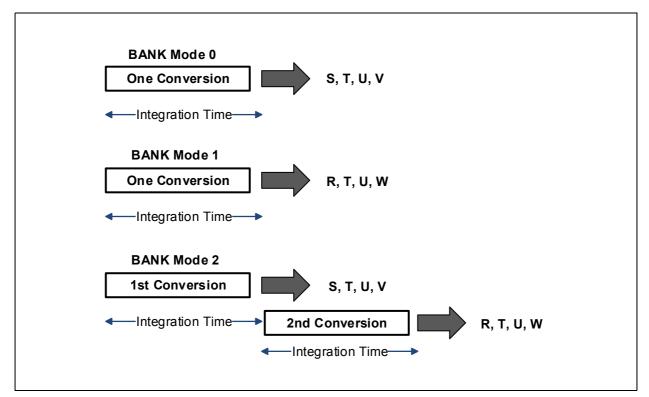


Figure 16: Bank Mode and Data Conversion



RC Oscillator

The timing generation circuit consists of an on-chip 16MHz, temperature compensated oscillator, which provides the master clock for the AS7263.

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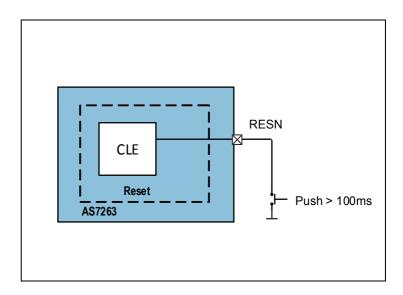
Temperature Sensor

The Temperature Sensor is constantly measuring the on-chip temperature and enables temperature compensation procedures.

Reset

Pulling down the RESN pin for longer than 100ms resets the AS7263.

Figure 17: Reset Circuit



Indicator LED

The LED, connected to pin LED_IND, can be used to indicate programming progress of the device.

While programming the AS7263 via the external SD card the indicator LED starts flashing (500ms pulses). When programming is completed the indicator LED is switched off. The LED (LED0) can be turned ON/OFF via AT commands or via I²C register control. The LED sink current is programmable from 1mA, 2mA, 4mA and 8mA.

Electronic Shutter with LED_DRV Driver Control

There are two LED driver outputs that can be used to control up to 2 LEDs. This will allow different wavelength light sources to be used in the same system. The LED output sink currents are programmable and can drive external LED sources: LED_IND from 1mA, 2mA, 4mA and 8mA and LED_DRV from 12.5mA, 25mA, 50mA and 100mA. The sources can be turned off and on via I²C registers control or AT commands and provides the device with an electronic shutter.

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Interrupt Operation

If BANK is set to Mode 0 or Mode 1 then the data is ready after the 1st integration time. If BANK is set to Mode 2 or Mode 3 then the data is ready after two integration times. If the interrupt is enabled (INT = 1) then when the data is ready, the INT line is pulled low and DATA RDY is set to 1. The INT line is released (returns high) when the control register is read. DATA_RDY is cleared to 0 when any of the sensor registers R, S, T, U, V, W are read. Since each sensor value is 2 bytes, after the 1st byte is read the 2nd byte is shadow-protected in case an integration cycle completes just after the 1st byte is read.

In continuous spectral conversion mode (BANK setting of Mode 0, Mode 1, or Mode 2), the sensors continue to gather information at the rate of the integration time, hence if the sensor registers are not read when the interrupt line goes low, it will stay low and the next cycle's sensor data will be available in the registers at the end of the next integration cycle. When the control register BANK bits are written with a value of Mode 3, One-Shot Spectral Conversion mode is entered. When a single set of contemporaneous sensor readings is desired, writing BANK Mode 3 to the control register immediately triggers exactly two spectral data conversion cycles. At the end of these two conversion cycles, the DATA_RDY bit is set as for the other BANK modes. To perform a new One-Shot sequence, the control register BANK bits should be written with a value of Mode 3 again. This process may continue until the user writes a different value into the BANK bits.

I²C Slave Interface

If selected by the I2C_ENB pin setting, interface and control can be accomplished through an I²C compatible slave interface to a set of registers that provide access to device control functions and output data. These registers on the AS7263 are, in reality, implemented as *virtual* registers in software. The actual I²C slave hardware registers number only three and are described in the table below. The steps necessary to access the virtual registers defined in the following are explained in pseudocode for external I²C master writes and reads below.

I²C Feature List

- Fast mode (400kHz) and standard mode (100kHz) support.
- 7+1-bit addressing mode.
- Write format: Byte.
- Read format: Byte.
- SDA input delay and SCL spike filtering by integrated RC-components.

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Figure 18:

I²C Slave Device Address and Physical Registers

| Entity | Description | Note |
|---|--|--|
| Device Slave Address | 8-bit Slave Address | Byte = 1001 001x x= 1 for Master Read (byte = 93 hex) x= 0 for Master Write (byte = 92 hex) |
| STATUS Register | I ² C slave interface STATUS register. Read-only. | Register Address = 0x00 Bit 1: TX_VALID 0 -> New data may be written to WRITE register 1 -> WRITE register occupied. Do NOT write. Bit 0: RX_VALID 0 -> No data is ready to be read in READ register. 1 -> Data byte available in READ register. |
| WRITE Register I ² C slave interface WRITE register. Write-only. | | Register Address = 0x01 8-Bits of data written by the I ² C Master intended for receipt by the I ² C slave. Used for both <i>virtual</i> register addresses and write data. |
| READ Register | I ² C slave interface READ register. Read-only. | Register Address = 0x02 8-Bits of data to be read by the I ² C Master. |

I²C Virtual Register Write Access

Figure 19 shows the pseudocode necessary to write virtual registers on the AS7263. Note that, because the actual registers of interest are realized as virtual registers, a means of indicating whether there is a pending read or write operation of a given virtual register is needed. To convey this information, the most significant bit of the virtual register address is used as a marker. If it is 1, then a write is pending, otherwise the slave is expecting a virtual read operation. The pseudocode illustrates the proper technique for polling of the I²C slave status register to ensure the slave is ready for each transaction.

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Figure 19:

I²C Virtual Register Byte Write

Pseudocode

Poll I²C slave STATUS register;

If TX_VALID bit is 0, a write can be performed on the interface;

Send a virtual register address and set the MSB of the register address to 1 to indicate the pending write; Poll I²C slave STATUS register;

If TX_VALID bit is 0, the virtual register address for the write has been received and the data may now be written; Write the data.

Sample Code:

```
#define I2C_AS72XX_SLAVE_STATUS_REG0x00
#define I2C_AS72XX_SLAVE_WRITE_REG0x01
#define I2C_AS72XX_SLAVE_READ_REG0x02
#define I2C_AS72XX_SLAVE_TX_VALID0x02
#define I2C_AS72XX_SLAVE_RX_VALID0x01
void i2cm_AS72xx_write(uint8_t virtualReg, uint8_t d)
{
        volatile uint8_tstatus;
        while (1)
        // Read slave I<sup>2</sup>C status to see if the write buffer is ready.
        status = i2cm_read(I2C_AS72XX_SLAVE_STATUS_REG);
        if ((status & I2C_AS72XX_SLAVE_TX_VALID) == 0)
                 // No inbound TX pending at slave. Okay to write now.
                 break;
        // Send the virtual register address (setting bit 7 to indicate a pending write).
        i2cm_write(I2C_AS72XX_SLAVE_WRITE_REG, (virtualReg | 0x80));
        while (1)
        // Read the slave I2C status to see if the write buffer is ready.
        status = i2cm_read(I2C_AS72XX_SLAVE_STATUS_REG);
        if ((status & I2C_AS72XX_SLAVE_TX_VALID) == 0)
                 // No inbound TX pending at slave. Okay to write data now.
                 break;
        }
        // Send the data to complete the operation.
        i2cm_write(I2C_AS72XX_SLAVE_WRITE_REG, d);
```

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I²C Virtual Register Read Access

Figure 20 shows the pseudocode necessary to read virtual registers on the AS7263. Note that in this case, reading a virtual register, the register address is not modified.

Figure 20: I²C Virtual Register Byte Read

Pseudocode

```
Poll I<sup>2</sup>C slave STATUS register;
If TX_VALID bit is 0, the virtual register address for the read may be written;
Send a virtual register address;
Poll I<sup>2</sup>C slave STATUS register;
If RX_VALID bit is 1, the read data is ready;
Read the data.
                                                 Sample Code:
uint8_t i2cm_AS72xx_read(uint8_t virtualReg)
        volatile uint8_t status, d;
        while (1)
         // Read slave I2C status to see if the read buffer is ready.
         status = i2cm_read(I2C_AS72XX_SLAVE_STATUS_REG);
         if ((status & I2C_AS72XX_SLAVE_TX_VALID) == 0)
                 // No inbound TX pending at slave. Okay to write now.
                 break;
         }
        // Send the virtual register address (setting bit 7 to indicate a pending write).
        i2cm_write(I2C_AS72XX_SLAVE_WRITE_REG, virtualReg);
        while (1)
         // Read the slave I<sup>2</sup>C status to see if our read data is available.
         status = i2cm_read(I2C_AS72XX_SLAVE_STATUS_REG);
         if ((status & I2C_AS72XX_SLAVE_RX_VALID) != 0)
                 // Read data is ready.
                 break;
        // Read the data to complete the operation.
        d = i2cm_read(I2C_AS72XX_SLAVE_READ_REG);
         return d;s
```

The details of the i2cm_read() and i2cm_write() functions in previous Figures are dependent upon the nature and implementation of the external I²C master device.

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I²C Virtual Register Set

The figure below provides a summary of the AS7263 I²C register set. Figures after that provide additional details. All register data is hex or, where noted, 32-bit floating point, and all multi-byte entities are Big Endian (most significant byte is situated at the lowest register address).

Figure 21: I²C Register Set Overview

| Addr | Name | <d7></d7> | <d6></d6> | <d5></d5> | <d4></d4> | <d3></d3> | <d2></d2> | <d1></d1> | <d0></d0> | | | | |
|---------------|-------------------|-----------|-------------------------------|------------|-------------|------------|-----------|--------------|-----------|--|--|--|--|
| | Version Registers | | | | | | | | | | | | |
| 0x00: 0x01 | HW_Version | | Hardware Version | | | | | | | | | | |
| 0x02: 0x03 | FW_Version | | | | Firmwa | re Versior | ı | | | | | | |
| | | | Co | ontrol Reg | gisters | | | | | | | | |
| 0x04 | Control_Setup | RST | INT | GA | AIN | Ва | nk | DATA_ RDY | RSVD | | | | |
| 0x05 | INT_T | | | | Integra | ation Time | | | | | | | |
| 0x06 | Device_Temp | | | | Device T | emperatu | re | | | | | | |
| 0x07 | LED_Control | RS | RSVD ICL_DRV LED_ DRV ICL_IND | | | | IND | LED_IND | | | | | |
| | l | | Senso | r Raw Dat | a Register | rs | | | | | | | |
| 0x08 | R_High | | | C | Channel R I | High Data | Byte | | | | | | |
| 0x09 | R_Low | | | (| Channel R | Low Data | Byte | | | | | | |
| 0x0A | S_High | | | (| Channel S I | High Data | Byte | | | | | | |
| 0x0B | S_Low | | | (| Channel S | Low Data | Byte | | | | | | |
| 0x0C | T_High | | | (| Channel T I | High Data | Byte | | | | | | |
| 0x0D | T_Low | | | (| Channel T | Low Data | Byte | | | | | | |
| 0x0E | U_High | | | C | Thannel U I | High Data | Byte | | | | | | |
| 0x0F | U_Low | | | (| Channel U | Low Data | Byte | | | | | | |
| 0x10 | V_High | | | C | Channel V I | High Data | Byte | | | | | | |
| 0x11 | V_Low | | | (| Channel V | Low Data | Byte | | | | | | |
| 0x12 | W_High | | | C | hannel W | High Data | Byte | | | | | | |
| 0x13 | W_Low | | | C | Channel W | Low Data | Byte | | | | | | |

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| Addr | Name | <d7></d7> | <d6></d6> | <d5></d5> | <d4></d4> | <d3></d3> | <d2></d2> | <d1></d1> | <d0></d0> | | | |
|---------------|---|-----------|-----------------------------------|-----------|--------------|-----------|-------------|-----------|-----------|--|--|--|
| | Sensor Calibrated Data Registers | | | | | | | | | | | |
| 0x14: 0x17 | R Cal Channel R Calibrated Data (float) | | | | | | | | | | | |
| 0x18: 0x1B | S_Cal | | Channel S Calibrated Data (float) | | | | | | | | | |
| 0x1C: 0x1F | T_Cal | | | Chai | nnel T Calil | brated Da | ta (float) | | | | | |
| 0x20: 0x23 | U_Cal | | | Char | nnel U Cali | brated Da | ta (float) | | | | | |
| 0x24: 0x27 | V_Cal | | Channel V Calibrated Data (float) | | | | | | | | | |
| 0x28: 0x2B | W_Cal | | | Char | nel W Cali | brated Da | ita (float) | | | | | |

Detailed Register Description

Figure 22: HW Version Registers

| Ad | dr: 0x00 | | HW_ | Version |
|------------|----------------------|---------|--------|--------------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | Device Type | 0100000 | R | Device type number |
| Addr: 0x01 | | | | |
| Ad | dr: 0x01 | | HW_ | Version |
| Ad Bit | dr: 0x01 Bit Name | Default | HW_' | Version Bit Description |

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Figure 23: FW Version Registers

| Addr | : 0x02 | | FW_\ | /ersion |
|------|------------------|---------|--------|---------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 7:6 | Minor Version | | R | Minor Version [1:0] |
| 5:0 | Sub Version | | R | Sub Version |
| Addr | : 0x03 | | FW_\ | /ersion |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:4 | Major Version | | R | Major Version |
| 3:0 | Minor Version | | R | Minor Version [5:2] |

Figure 24: Control Setup Register

| Addr: 0x | Addr: 0x04/0x84 | | Control_Setup | | |
|----------|-----------------|---------|---------------|---|--|
| Bit | Bit Name | Default | Access | Bit Description | |
| 7 | RST | 0 | R/W | Soft Reset, Set to 1 for soft reset, goes to 0 automatically after the reset | |
| 6 | INT | 0 | R/W | Enable interrupt pin output (INT), 1: Enable, 0: Disable | |
| 5:4 | GAIN | 0 | R/W | Sensor Channel Gain Setting (all channels) 'b00=1x; 'b01=3.7x; 'b10=16x; 'b11=64x | |
| 3:2 | BANK | 10 | R/W | Data Conversion Type (continuous) 'b00=Mode 0; 'b01=Mode 1; 'b10=Mode 2; 'b11=Mode 3 One-Shot | |
| 1 | DATA_RDY | 0 | R/W | 1: Data Ready to Read, sets INT active if interrupt is enabled. Can be polled if not using INT. | |
| 0 | RSVD | 0 | R | Reserved; Unused | |

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Figure 25: Integration Time Register

| Addr: (| Addr: 0x05/0x85 | | INT_T | |
|---------|-----------------|---------|--------|---|
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | INT_T | 0xFF | R/W | Integration time = <value> * 2.8ms</value> |

Figure 26: Device Temperature Register

| Addr: 0x06 | | | Device_Temp | |
|------------|-------------|---------|-------------|-----------------------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | Device_Temp | | R | Device temperature data byte (°C) |

Figure 27: LED Control Register

| Addr: | Addr: 0x07/0x87 | | LED Control | | |
|-------|-----------------|---------|-------------|---|--|
| Bit | Bit Name | Default | Access | Bit Description | |
| 7:6 | RSVD | 0 | R | Reserved | |
| 5:4 | ICL_DRV | 00 | R/W | LED_DRV current limit 'b00=12.5mA; 'b01=25mA; 'b10=50mA; 'b11=100mA | |
| 3 | LED_DRV | 0 | R/W | Enable LED_DRV 1: Enabled; 0: Disabled | |
| 2:1 | ICL_IND | 00 | R/W | LED_IND current limit 'b00=1mA; 'b01=2mA; 'b10=4mA; 'b11=8mA | |
| 0 | LED_IND | 0 | R/W | Enable LED_IND 1: Enabled; 0: Disabled | |

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Figure 28: Sensor Raw Data Registers

| Add | r: 0x08 | | R_Hiç | gh |
|-----|----------|---------|--------|--------------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | R_High | | R | Channel R High Data Byte |
| Add | r: 0x09 | | R_Lo | w |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | R_Low | | R | Channel R Low Data Byte |
| Add | r: 0x0A | | S_Hiç | gh |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | S_High | | R | Channel S High Data Byte |
| Add | r: 0x0B | | S_Lo | w |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | S_Low | | R | Channel S Low Data Byte |
| Add | r: 0x0C | | T_Hiç | gh |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | T_High | | R | Channel T High Data Byte |
| Add | r: 0x0D | | T_Lo | w |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | T_Low | | R | Channel T Low Data Byte |
| Add | r: 0x0E | | U_Hiç | gh |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | U_High | | R | Channel U High Data Byte |
| Add | r: 0x0F | | U_Lo | w |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | U_Low | | R | Channel U Low Data Byte |

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| Add | r: 0x10 | V_High | | jh |
|-----|-------------------|---------|-----------|--------------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | V_High | | R | Channel V High Data Byte |
| Add | r: 0x11 | | V_Lo | w |
| Bit | Bit Name | Default | Access | Bit Description |
| 7:0 | V_Low | | R | Channel V Low Data Byte |
| Add | r: 0x12 | | W_Hi | gh |
| Bit | Bit Name | Default | Access | Bit Description |
| | | | | |
| 7:0 | W_High | | R | Channel W High Data Byte |
| | W_High r: 0x13 | | R W_Lo | - , |
| | - | Default | | - , |

Figure 29: Sensor Calibrated Data Registers

| Addr: 0> | x14:0x17 | R_Cal | | |
|----------|----------|---------|--------|-----------------------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 31:0 | R_Cal | | R | Channel R Calibrated Data (float) |
| Addr: 0x | 18:0x1B | | S_Ca | |
| Bit | Bit Name | Default | Access | Bit Description |
| 31:0 | S_Cal | | R | Channel S Calibrated Data (float) |
| Addr: 0x | 1C:0x1F | | T_Cal | |
| Bit | Bit Name | Default | Access | Bit Description |
| 31:0 | T_Cal | | R | Channel T Calibrated Data (float) |
| Addr: 0> | (20:0x23 | U_Cal | | |
| Bit | Bit Name | Default | Access | Bit Description |
| 31:0 | U_Cal | | R | Channel U Calibrated Data (float) |

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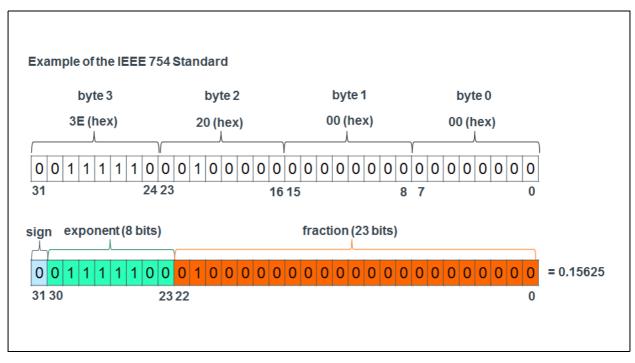


| Addr: 0 | x24:0x27 | | V_Ca | |
|----------|----------|---------|--------|-----------------------------------|
| Bit | Bit Name | Default | Access | Bit Description |
| 31:0 | V_Cal | | R | Channel V Calibrated Data (float) |
| Addr: 0x | 28:0x2B | | W_Ca | I |
| Bit | Bit Name | Default | Access | Bit Description |
| 31:0 | W_Cal | | R | Channel W Calibrated Data (float) |

4-Byte Floating-Point (FP) Registers

Several 4-byte registers (hex) are shown in the tables. Here is an example of how the registers are used to represent floating point data (based on the IEEE 754 standard):

Figure 30: **Example of the IEEE 754 Standard**



The floating point (FP) value assumed by 32 bit binary32 data with a biased exponent e (the 8 bit unsigned integer) and a 23 bit fraction is (for the above example).

FPvalue =
$$(-1)^{\text{sign}} \left(1 + \sum_{i=1}^{23} (b_{23-i})(2^{-i}) \right) x 2^{(e-127)}$$

FPvalue =
$$(-1)^0 \left(1 + \sum_{i=1}^{23} (b_{23-i})(2^{-i})\right) x 2^{(124-127)}$$

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FPvalue =
$$(1)x(1+2^{-2})x2^{(-3)} = 0.15625$$

UART Interface

If selected by the I2C_ENB pin setting, the UART module implements the TX and RX signals as defined in the RS-232 / V.24 standard communication protocol.

It has on both, receive and transmit path, a 16 entry deep FIFO. It can generate interrupts as required.

UART Feature List¹

- Full Duplex Operation (Independent Serial Receive and Transmit Registers) with FIFO buffer of 8 byte for each.
- At a clock rate of 16MHz it supports communication at 115200Baud.
- Supports Serial Frames with 8 Data Bits, 1 Parity Bit and 1 Stop Bit.
- High Resolution Baud Rate Generator.

Theory of Operation

Transmission

If data is available in the transmit FIFO, it will be moved into the output shift register and the data will be transmitted at the configured Baud Rate, starting with a Start Bit (logic zero) and followed by a Stop Bit (logic one).

Reception

At any time, with the receiver being idle, if a falling edge of a start bit is detected on the input, a byte will be received and stored in the receive FIFO. The following Stop Bit will be checked to be logic one.

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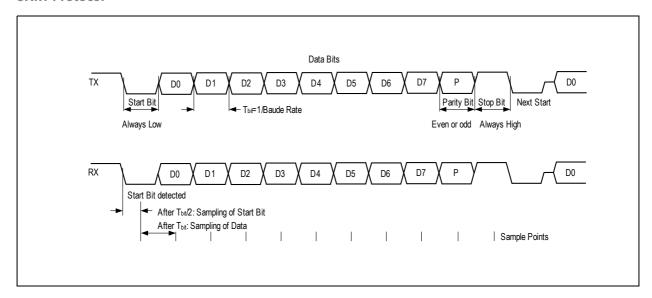
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^{1.} With UART operation, min VDD of 2.97V is required as shown in Electrical Characteristics Figures.



Figure 31: UART Protocol



AT Command Interface

The microprocessor interface to control the NIR *Spectral_ID* Sensor is via the UART, using the AT Commands across the UART interface.

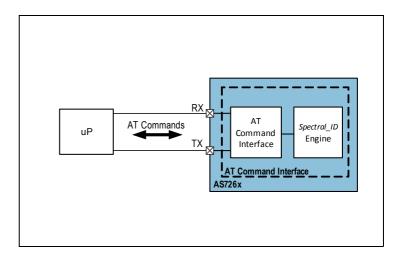
The 6-channel *Spectral_ID* sensor provides a text-based serial command interface borrowed from the "AT Command" model used in early Hayes modems.

For example:

- Read DATA value: ATDATA → <data>OK
- Set the gain of the sensor to 1x: ATGAIN =0 \rightarrow OK

The "AT Command Interface Block Diagram", shown below between the network interface and the core of the system, provides access to the *Spectral_ID* engine's control and configuration functions.

Figure 32: AT Command Interface Block Diagram



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In the Figure below, numeric values may be specified with no leading prefix, in which case they will be interpreted as decimals, or with a leading "0x" to indicate that they are hexadecimal numbers, or with a leading "'b" to indicate that they are binary numbers. The commands are loosely grouped into functional areas. Texts appearing between angle brackets ('<' and '>') are commands or response arguments. A carriage return character, a linefeed character, or both may terminate commands and responses. Note that any command that encounters an error will generate the "ERROR" response shown, for example, in the NOP command at the top of the first table, but has been omitted elsewhere in the interest of readability and clarity.

Figure 33: AT Commands

| Command | Response | Description / Parameters | | | |
|----------------------------|---|--|--|--|--|
| | Spectral Data per Channel | | | | |
| ATDATA | <r_value>, <s_value>, <t_value>, <u_value>, <v_value>, <v_value>, <w_value> OK</w_value></v_value></v_value></u_value></t_value></s_value></r_value> | Read R, S, T, U, V & W data. Returns comma-separated 16-bit integers. | | | |
| ATCDATA | <cal_r_value>, <cal_s_value>, <cal_t_value>, <cal_u_value>, <cal_v_value>, <cal_w_value> OK</cal_w_value></cal_v_value></cal_u_value></cal_t_value></cal_s_value></cal_r_value> | Read calibrated R, S, T, U, V & W data. Returns comma-separated 32-bit floating point values. | | | |
| | S | ensor Configuration | | | |
| ATINTTIME= <value></value> | ОК | Set sensor integration time. Values should be in the range [1 255], with integration time = <value> * 2.8ms.</value> | | | |
| ATINTTIME | <value> OK</value> | Read sensor integration time, with integration time = <value> * 2.8ms.</value> | | | |
| ATGAIN= <value></value> | ОК | Set sensor gain: 0=1X, 1=3.7x, 2=16x, 3=64x | | | |
| ATGAIN | <value>OK</value> | Read sensor gain setting, returning 0, 1, 2, or 3 as defined immediately above. | | | |
| ATTEMP | <value>OK</value> | Read temperature of chip in degree Celsius | | | |

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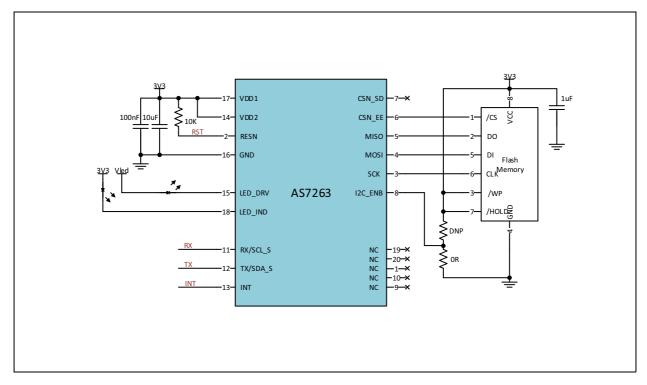
| Command | Response | Description / Parameters | | |
|--------------------------|---|--|--|--|
| ATTCSMD= <value></value> | ОК | Set Sensor Mode 0 = BANK Mode 0; 1 = BANK Mode 1; 2 = BANK Mode 2; 3 = BANK Mode 3 One-Shot; 4 = Sensors OFF In One-Shot mode, each ATTCSMD=3 command triggers a One-Shot reading | | |
| ATTCSMD | <value> OK</value> | Read Sensor Mode, see above | | |
| ATBURST= <value></value> | ОК | <value>= # of samples (ATBURST=1 means run until ATBURST=0 is received (a special case for continuous output)</value> | | |
| LED Driver Controls | | | | |
| ATLED0= <value></value> | ОК | Sets LED_IND: 100=ON, 0=OFF | | |
| ATLED0 | <100 0>OK | Reads LED_IND setting: 100=ON, 0=OFF | | |
| ATLED1= <value></value> | ОК | Sets LED_DRV: 100=ON, 0=OFF | | |
| ATLED1 | <100 0>OK | Reads LED_DRV setting: 100=ON, 0=OFF | | |
| ATLEDC= <value></value> | ОК | Sets LED_IND and LED_DRV current LED_IND: bits 3:0; LED_DRV: 7:4 bits LED_IND: 'b00=1mA; 'b01=2mA; 'b10=4mA; 'b11=8ma LED_DRV: 'b00=12.5mA; 'b01=25mA; 'b10=50mA; 'b11=100mA | | |
| ATLEDC | <value>OK</value> | Reads LED_IND and LED_DRV current settings as shown above | | |
| | NOP, Ve | rsion Access, System Reset | | |
| AT | OK → Success ERROR → Failure | NOP | | |
| ATRST | None | Software Reset – no response | | |
| ATVERSW | <swversion#>→OK ERROR → Failure</swversion#> | Returns the system software version number | | |
| ATVERHW | $<$ HWversion# $>\rightarrow$ OK ERROR \rightarrow Failure | Returns the system hardware revision and product ID, with bits 7:4 containing the part ID, and bits 3:0 yielding the chip revision value. | | |
| | | Firmware Update | | |
| ATFWU= <value></value> | ОК | <pre><value>= 16-bit checksum. Initial the firmware update process. Bytes that follow is always 56k bytes</value></pre> | | |
| ATFW= <value></value> | ОК | Download new firmware Up to 7 Bytes represented as hex chars with no leading or trailing 0x. Repeat command till all 56k bytes of firmware are downloaded | | |
| ATFWS | ок | Causes the active image to switch between the two possible current images and then resets the IC | | |

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Application Information

Figure 34: AS7263 Typical Application Circuit

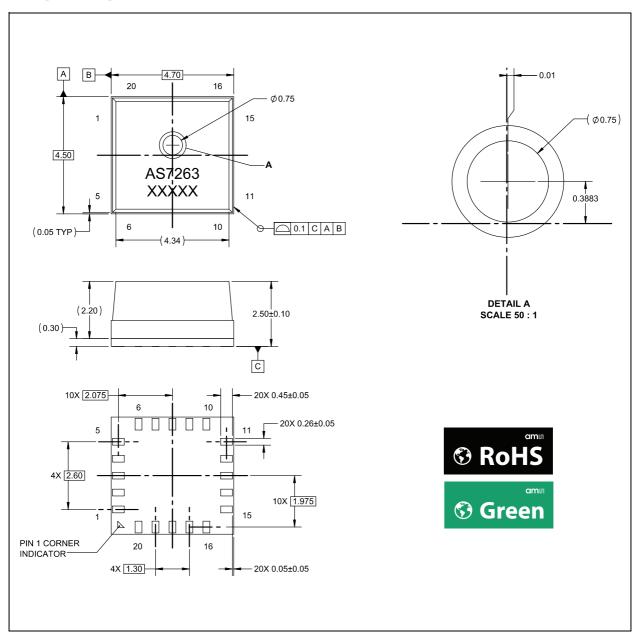


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Package Drawings & Markings

Figure 35: Package Drawing LGA



Note(s):

1. XXXXX = tracecode

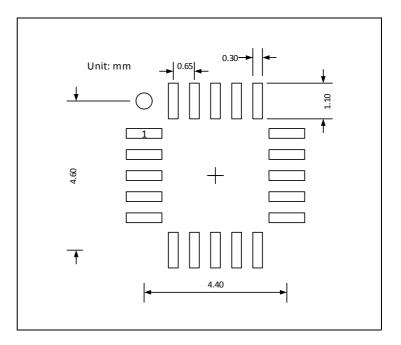
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PCB Pad Layout

Suggested PCB pad layout guidelines for the LGA device are shown.

Figure 36: Recommended PCB Pad Layout

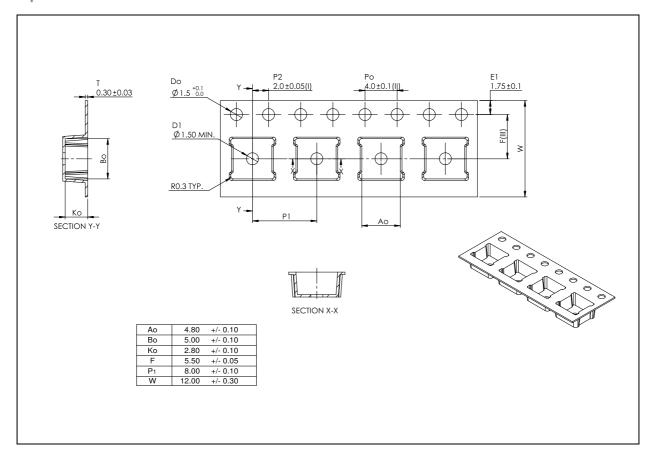


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Mechanical Data

Figure 37: **Tape & Reel Information**



Note(s):

- 1. Each reel contains 2000 parts.
- 2. Measured from centreline of sprocket hole to centreline of pocket.
- 3. Cumulative tolerance of 10 sprocket holes is ± 0.20 .
- 4. Other material available.
- 5. All dimensions in millimeters unless otherwise stated.

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Storage & Soldering Information

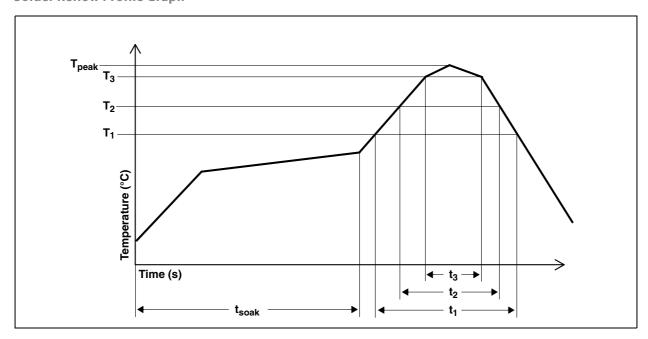
Soldering Information

The module has been tested and has demonstrated an ability to be reflow soldered to a PCB substrate. The solder reflow profile describes the expected maximum heat exposure of components during the solder reflow process of product on a PCB. Temperature is measured on top of component. The components should be limited to a maximum of three passes through this solder reflow profile.

Figure 38: Solder Reflow Profile

| Parameter | Reference | Device |
|--|-------------------|----------------|
| Average temperature gradient in preheating | | 2.5°C/s |
| Soak time | t _{soak} | 2 to 3 minutes |
| Time above 217°C | t ₁ | Max 60 s |
| Time above 230°C | t ₂ | Max 50 s |
| Time above T _{peak} -10°C | t ₃ | Max 10 s |
| Peak temperature in reflow | T _{peak} | 260° C |
| Temperature gradient in cooling | | Max -5°C/s |

Figure 39: Solder Reflow Profile Graph



Note(s):

1. Not to scale - for reference only.

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Manufacturing Process Considerations

The AS7263 package is compatible with standard reflow no-clean and cleaning processes including aqueous, solvent or ultrasonic techniques. However, as an open-aperture device, precautions must be taken to avoid particulate or solvent contamination as a result of any manufacturing processes, including pick and place, reflow, cleaning, integration assembly and/or testing. Temporary covering of the aperture is allowed. To avoid degradation of accuracy or performance in the end product, care should be taken that any temporary covering and associated sealants/debris are thoroughly removed prior to any optical testing or final packaging.

Storage Information

Moisture Sensitivity

Optical characteristics of the device can be adversely affected during the soldering process by the release and vaporization of moisture that has been previously absorbed into the package. To ensure the package contains the smallest amount of absorbed moisture possible, each device is baked prior to being dry packed for shipping.

Devices are dry packed in a sealed aluminized envelope called a moisture-barrier bag with silica gel to protect them from ambient moisture during shipping, handling, and storage before use.

Shelf Life

The calculated shelf life of the device in an unopened moisture barrier bag is 12 months from the date code on the bag when stored under the following conditions:

• Shelf Life: 12 months

• Ambient Temperature: <40°C

• Relative Humidity: <90%

Rebaking of the devices will be required if the devices exceed the 12 month shelf life or the Humidity Indicator Card shows that the devices were exposed to conditions beyond the allowable moisture region.

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Floor Life

The module has been assigned a moisture sensitivity level of MSL 3. As a result, the floor life of devices removed from the moisture barrier bag is 168 hours from the time the bag was opened, provided that the devices are stored under the following conditions:

• Floor Life: 168 hours

• Ambient Temperature: <30°C

• Relative Humidity: <60%

If the floor life or the temperature/humidity conditions have been exceeded, the devices must be rebaked prior to solder reflow or dry packing.

Rebaking Instructions

When the shelf life or floor life limits have been exceeded, rebake at 50°C for 12 hours.

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Ordering & Contact Information

Figure 40:

Ordering Information (1) (2)

| Ordering Code | Package | Marking | Description | Delivery Form | Delivery Quantity |
|------------------|------------|---------|--|------------------|----------------------|
| AS7263-BLGT | 20-pin LGA | AS7263 | 6-Channel NIR Spectral_ID Device with Electronic Shutter & Smart Interface | Tape & Reel | 2000 pcs/reel |

Note(s):

- 1. Required companion serial flash memory (must be ams verified) is ordered from the flash memory supplier (e.g. AT25SF041-SSHD-B from Adesto Technologies)
- 2. AS7263 flash memory software is available from ams.

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|--|------|
| Initial production version for release | |
| Completely revised version | |

Note(s):

- 1. Page and figure numbers for the previous version may differ from page and figure numbers in the current revision.
- 2. Correction of typographical errors is not explicitly mentioned.

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