

# HEF4013B

## Dual D-type flip-flop

Rev. 9 — 10 December 2015

Product data sheet

## 1. General description

The HEF4013B is a dual D-type flip-flop that features independent set-direct input (SD), clear-direct input (CD), clock input (CP) and outputs (Q,  $\bar{Q}$ ). Data is accepted when CP is LOW and is transferred to the output on the positive-going edge of the clock. The active HIGH asynchronous CD and SD inputs are independent and override the D or CP inputs. The outputs are buffered for best system performance. The clock input's Schmitt-trigger action makes the circuit highly tolerant of slower clock rise and fall times.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

## 2. Features and benefits

- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from  $-40\text{ }^{\circ}\text{C}$  to  $+125\text{ }^{\circ}\text{C}$
- Complies with JEDEC standard JESD 13-B

## 3. Applications

- Counters and dividers
- Registers
- Toggle flip-flops

## 4. Ordering information

**Table 1. Ordering information**

All types operate from  $-40\text{ }^{\circ}\text{C}$  to  $+125\text{ }^{\circ}\text{C}$

Type number	Package		
	Name	Description	Version
HEF4013BT	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1
HEF4013BTT	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1



5. Functional diagram

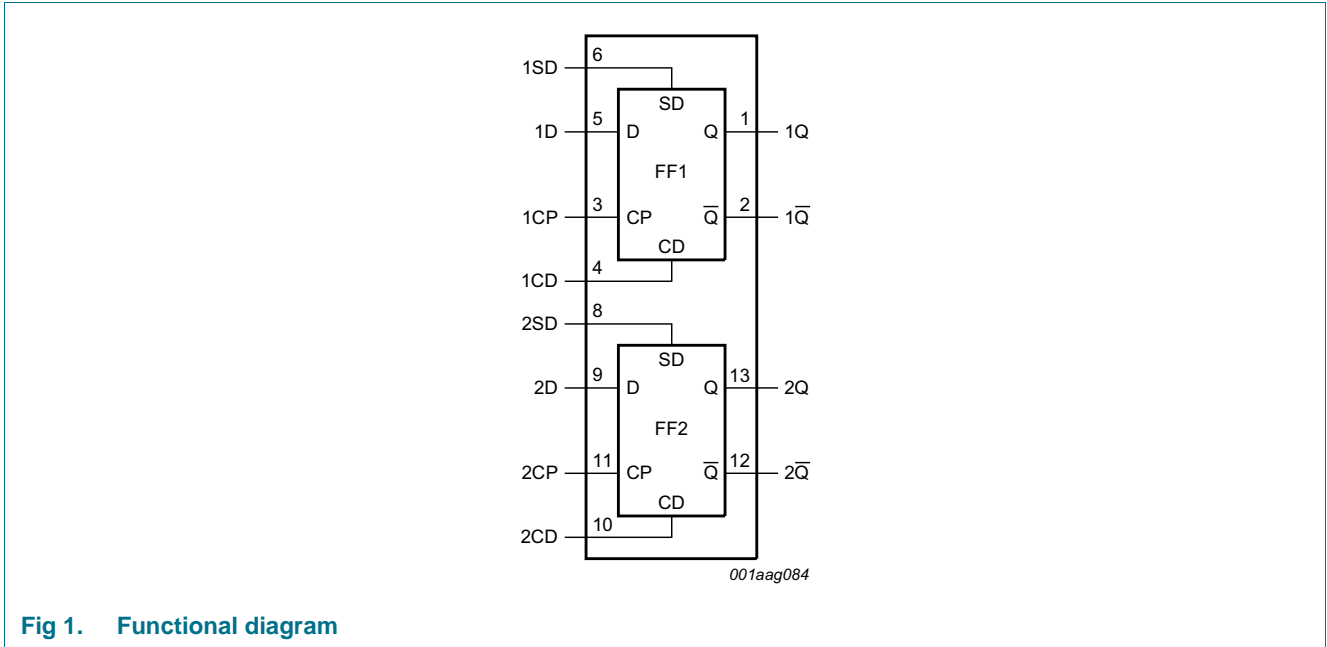


Fig 1. Functional diagram

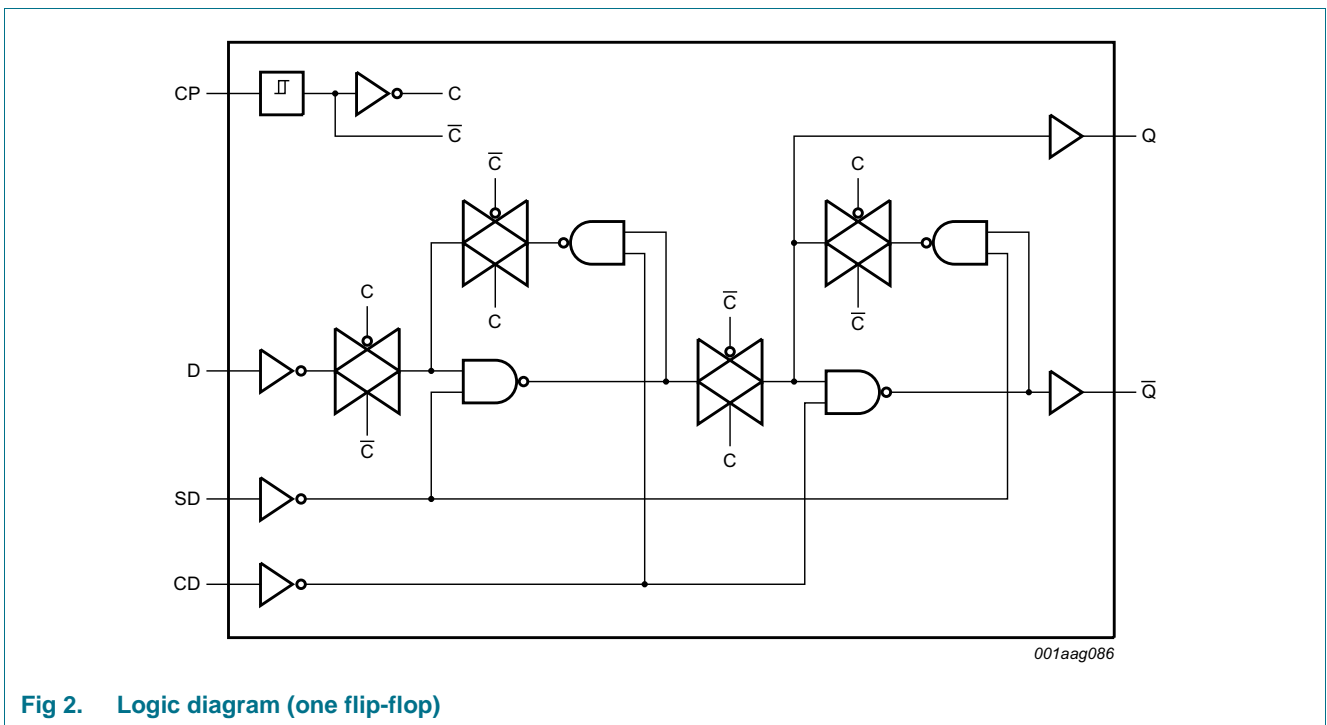


Fig 2. Logic diagram (one flip-flop)

## 6. Pinning information

### 6.1 Pinning

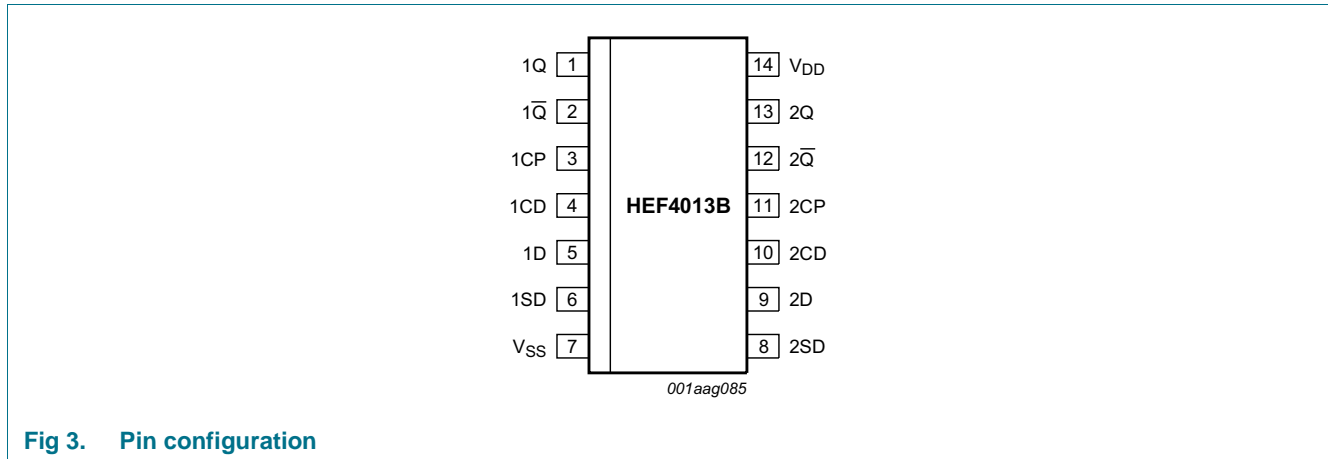


Fig 3. Pin configuration

### 6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
1Q, 2Q	1, 13	true output
1Q̄, 2Q̄	2, 12	complement output
1CP, 2CP	3, 11	clock input (LOW to HIGH edge-triggered)
1CD, 2CD	4, 10	asynchronous clear-direct input (active HIGH)
1D, 2D	5, 9	data input
1SD, 2SD	6, 8	asynchronous set-direct input (active HIGH)
V <sub>SS</sub>	7	ground (0 V)
V <sub>DD</sub>	14	supply voltage

## 7. Functional description

Table 3. Function table<sup>[1]</sup>

Control			Input	Output	
nSD	nCD	nCP	nD	nQ	nQ̄
H	L	X	X	H	L
L	H	X	X	L	H
H	H	X	X	H	H
L	L	↑	L	L	H
L	L	↑	H	H	L

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; ↑ = LOW-to-HIGH clock transition.

## 8. Limiting values

**Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to  $V_{SS} = 0$  V (ground).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
$I_{IK}$	input clamping current	$V_I < -0.5$ V or $V_I > V_{DD} + 0.5$ V	-	$\pm 10$	mA
$V_I$	input voltage		-0.5	$V_{DD} + 0.5$	V
$I_{OK}$	output clamping current	$V_O < -0.5$ V or $V_O > V_{DD} + 0.5$ V	-	$\pm 10$	mA
$I_{I/O}$	input/output current		-	$\pm 10$	mA
$I_{DD}$	supply current		-	50	mA
$T_{stg}$	storage temperature		-65	+150	°C
$T_{amb}$	ambient temperature		-40	+125	°C
$P_{tot}$	total power dissipation	$T_{amb} = -40$ °C to +125 °C			
		SO14 <a href="#">[1]</a>	-	500	mW
		TSSOP14 <a href="#">[2]</a>	-	500	mW
$P$	power dissipation	per output	-	100	mW

[1] For SO14 packages: above  $T_{amb} = 70$  °C,  $P_{tot}$  derates linearly with 8 mW/K.

[2] For TSSOP14 packages: above  $T_{amb} = 60$  °C,  $P_{tot}$  derates linearly with 5.5 mW/K.

## 9. Recommended operating conditions

**Table 5. Recommended operating conditions**

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		3	15	V
$V_I$	input voltage		0	$V_{DD}$	V
$T_{amb}$	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{DD} = 5$ V	-	3.75	$\mu\text{s/V}$
		$V_{DD} = 10$ V	-	0.5	$\mu\text{s/V}$
		$V_{DD} = 15$ V	-	0.08	$\mu\text{s/V}$

## 10. Static characteristics

**Table 6. Static characteristics**

$V_{SS} = 0\text{ V}$ ;  $V_I = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	$T_{amb} = -40\text{ °C}$		$T_{amb} = +25\text{ °C}$		$T_{amb} = +85\text{ °C}$		$T_{amb} = +125\text{ °C}$		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
$V_{IL}$	LOW-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
$V_{OH}$	HIGH-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
$V_{OL}$	LOW-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
$I_{OH}$	HIGH-level output current	$V_O = 2.5\text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
		$V_O = 4.6\text{ V}$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		$V_O = 9.5\text{ V}$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		$V_O = 13.5\text{ V}$	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
$I_{OL}$	LOW-level output current	$V_O = 0.4\text{ V}$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
		$V_O = 0.5\text{ V}$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		$V_O = 1.5\text{ V}$	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
$I_I$	input leakage current		15 V	-	$\pm 0.1$	-	$\pm 0.1$	-	$\pm 1.0$	-	$\pm 1.0$	$\mu\text{A}$
$I_{DD}$	supply current	all valid input combinations; $ I_O  = 0\text{ A}$	5 V	-	1.0	-	1.0	-	30	-	30	$\mu\text{A}$
			10 V	-	2.0	-	2.0	-	60	-	60	$\mu\text{A}$
			15 V	-	4.0	-	4.0	-	120	-	120	$\mu\text{A}$
$C_I$	input capacitance		-	-	-	7.5	-	-	-	-	pF	

## 11. Dynamic characteristics

**Table 7. Dynamic characteristics**

$T_{amb} = 25\text{ }^{\circ}\text{C}$ ; unless otherwise specified. For test circuit see [Figure 6](#).

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula	Min	Typ	Max	Unit
t <sub>PHL</sub>	HIGH to LOW propagation delay	nCP to nQ, nQ̄; see <a href="#">Figure 4</a>	5 V <a href="#">[1]</a>	$83 + 0.55 \times C_L$	-	110	220	ns
			10 V	$34 + 0.23 \times C_L$	-	45	90	ns
			15 V	$22 + 0.16 \times C_L$	-	30	60	ns
		nSD to nQ̄	5 V <a href="#">[1]</a>	$73 + 0.55 \times C_L$	-	100	200	ns
			10 V	$29 + 0.23 \times C_L$	-	40	80	ns
			15 V	$22 + 0.16 \times C_L$	-	30	60	ns
		nCD to nQ	5 V <a href="#">[1]</a>	$73 + 0.55 \times C_L$	-	100	200	ns
			10 V	$29 + 0.23 \times C_L$	-	40	80	ns
			15 V	$22 + 0.16 \times C_L$	-	30	60	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	nCP to nQ, nQ̄; see <a href="#">Figure 4</a>	5 V <a href="#">[1]</a>	$68 + 0.55 \times C_L$	-	95	190	ns
			10 V	$29 + 0.23 \times C_L$	-	40	80	ns
			15 V	$22 + 0.16 \times C_L$	-	30	60	ns
		nSD to nQ	5 V <a href="#">[1]</a>	$48 + 0.55 \times C_L$	-	75	150	ns
			10 V	$24 + 0.23 \times C_L$	-	35	70	ns
			15 V	$17 + 0.16 \times C_L$	-	25	50	ns
		nCD to nQ̄	5 V <a href="#">[1]</a>	$33 + 0.55 \times C_L$	-	60	120	ns
			10 V	$19 + 0.23 \times C_L$	-	30	60	ns
			15 V	$12 + 0.16 \times C_L$	-	20	40	ns
t <sub>t</sub>	transition time	see <a href="#">Figure 4</a>	5 V <a href="#">[1]</a>	$10 + 1.00 \times C_L$	-	60	120	ns
			10 V	$9 + 0.42 \times C_L$	-	30	60	ns
			15 V	$6 + 0.28 \times C_L$	-	20	40	ns
t <sub>su</sub>	set-up time	nD to nCP; see <a href="#">Figure 4</a>	5 V		40	20	-	ns
			10 V		25	10	-	ns
			15 V		15	5	-	ns
t <sub>h</sub>	hold time	nD to nCP; see <a href="#">Figure 4</a>	5 V		20	0	-	ns
			10 V		20	0	-	ns
			15 V		15	0	-	ns
t <sub>w</sub>	pulse width	nCP input LOW; see <a href="#">Figure 4</a>	5 V		60	30	-	ns
			10 V		30	15	-	ns
			15 V		20	10	-	ns
		nSD input HIGH; see <a href="#">Figure 5</a>	5 V		50	25	-	ns
			10 V		24	12	-	ns
			15 V		20	10	-	ns
		nCD input HIGH; see <a href="#">Figure 5</a>	5 V		50	25	-	ns
			10 V		24	12	-	ns
			15 V		20	10	-	ns

**Table 7. Dynamic characteristics ...continued**  
*T<sub>amb</sub> = 25 °C; unless otherwise specified. For test circuit see Figure 6.*

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula	Min	Typ	Max	Unit
t <sub>rec</sub>	recovery time	nSD input; see Figure 5	5 V		+15	-5	-	ns
			10 V		15	0	-	ns
			15 V		15	0	-	ns
		nCD input; see Figure 5	5 V		40	25	-	ns
			10 V		25	10	-	ns
			15 V		25	10	-	ns
f <sub>clk(max)</sub>	maximum clock frequency	see Figure 4	5 V		7	14	-	MHz
			10 V		14	28	-	MHz
			15 V		20	40	-	MHz

[1] Typical values of the propagation delays and output transition times can be calculated with the extrapolation formulas. C<sub>L</sub> is given in pF.

**Table 8. Dynamic power dissipation**  
*V<sub>SS</sub> = 0 V; t<sub>r</sub> = t<sub>f</sub> ≤ 20 ns; T<sub>amb</sub> = 25 °C.*

Symbol	Parameter	V <sub>DD</sub>	Typical formula	Where
P <sub>D</sub>	dynamic power dissipation	5 V	$P_D = 850 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2 \mu W$	f <sub>i</sub> = input frequency in MHz; f <sub>o</sub> = output frequency in MHz; C <sub>L</sub> = output load capacitance in pF; Σ(f <sub>o</sub> × C <sub>L</sub> ) = sum of the outputs; V <sub>DD</sub> = supply voltage in V.
		10 V	$P_D = 3600 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2 \mu W$	
		15 V	$P_D = 9000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2 \mu W$	

12. Waveforms

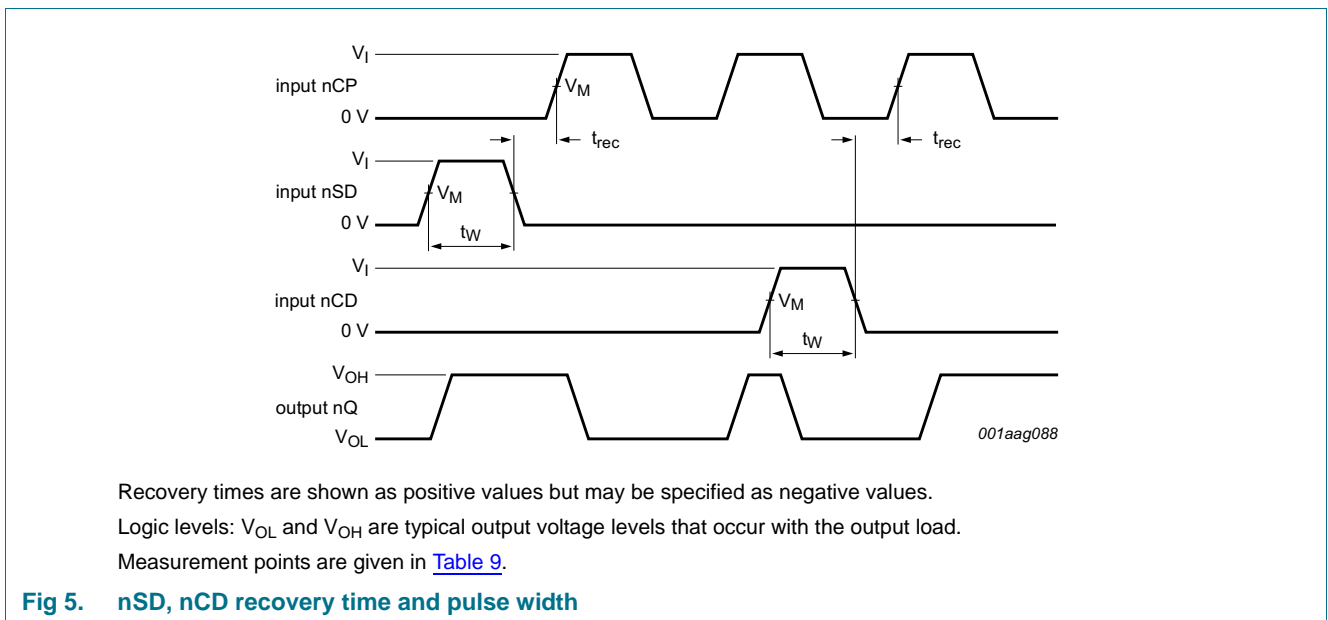
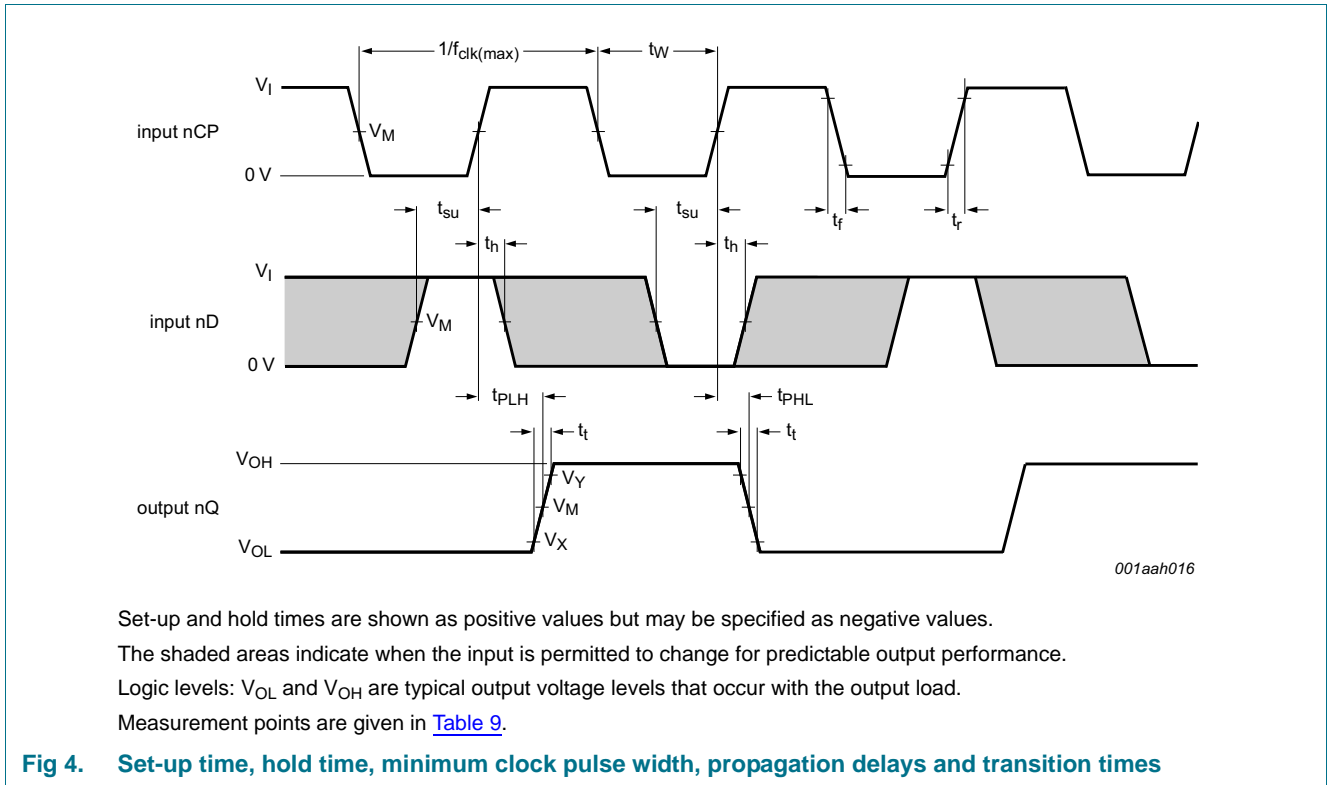
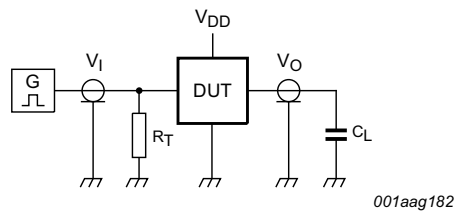


Table 9. Measurement points

Supply voltage	Input	Output		
$V_{DD}$	$V_M$	$V_M$	$V_X$	$V_Y$
5 V to 15 V	$0.5V_{DD}$	$0.5V_{DD}$	$0.1V_{DD}$	$0.9V_{DD}$





Test and measurement data is given in [Table 10](#);

Definitions test circuit:

DUT = Device Under Test.

$R_T$  = Termination resistance should be equal to output impedance  $Z_o$  of the pulse generator.

$C_L$  = Load capacitance including jig and probe capacitance.

**Fig 6. Test circuit for measuring switching times**

**Table 10. Test data**

Supply voltage	Input		Load
$V_{DD}$	$V_I$	$t_r, t_f$	$C_L$
5 V to 15 V	$V_{SS}$ or $V_{DD}$	$\leq 20$ ns	50 pF

### 13. Application information

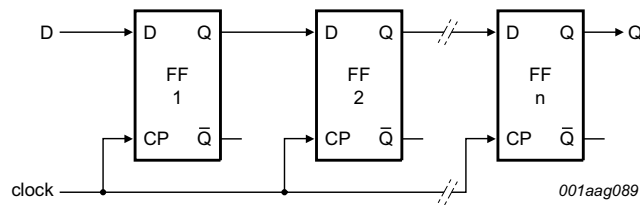


Fig 7. N-stage shift register

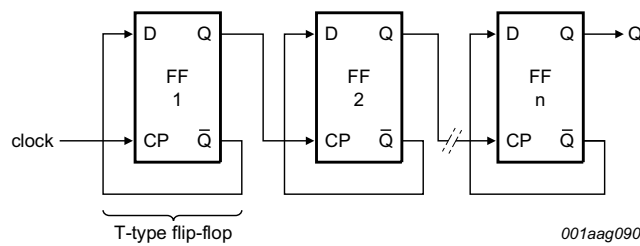


Fig 8. Binary ripple up-counter; divide-by- $2^n$

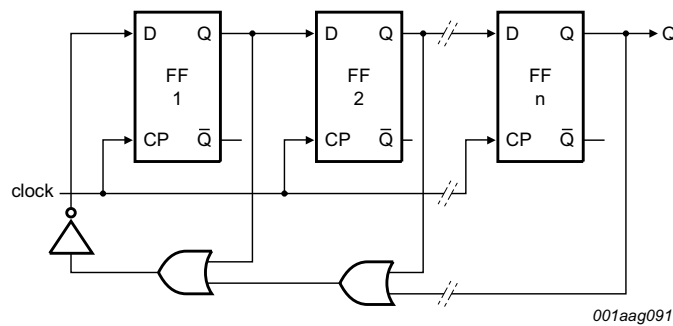


Fig 9. Modified ring counter; divide-by- $(n + 1)$

14. Package outline

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1

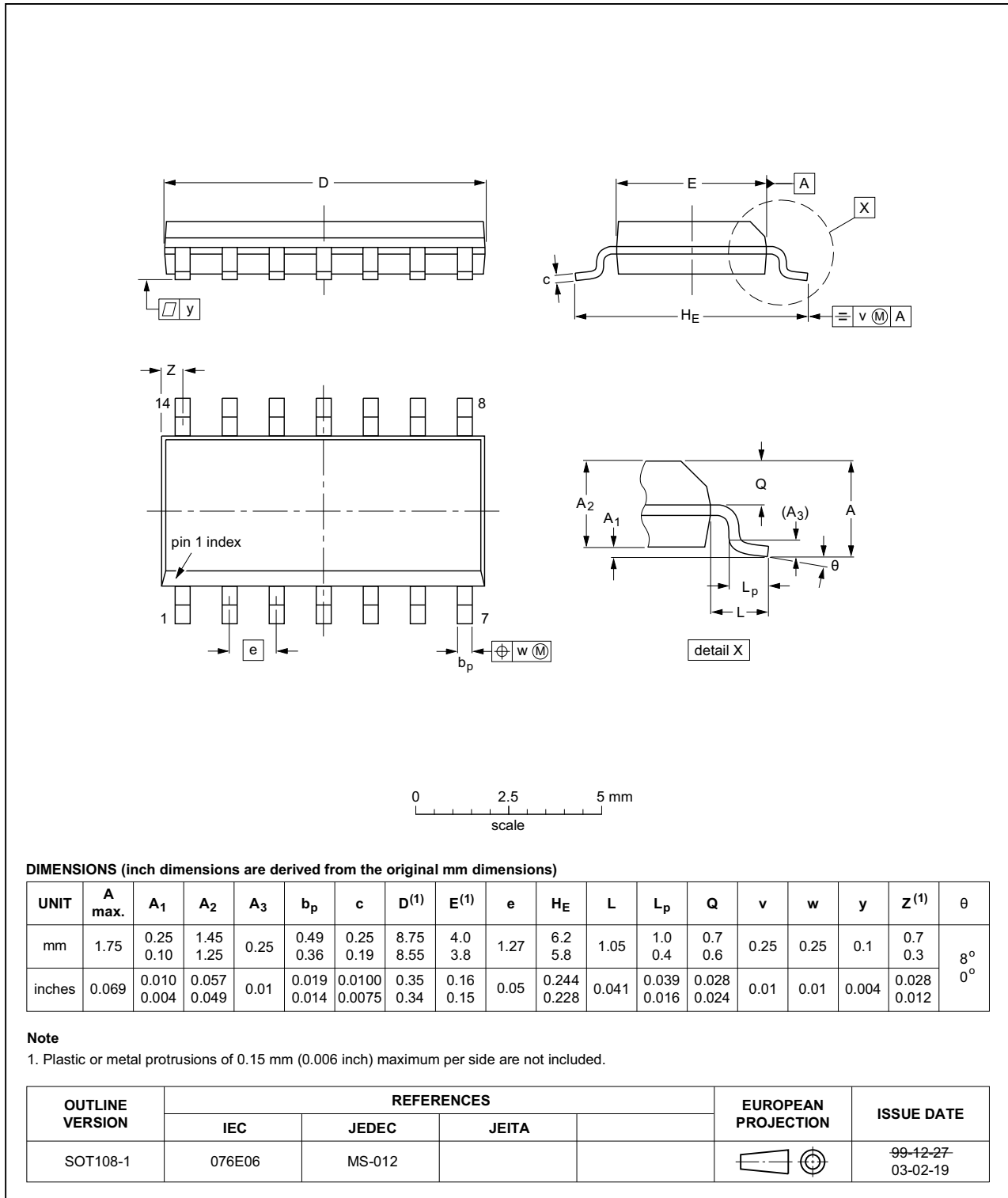


Fig 10. Package outline SOT108-1 (SO14)

TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1

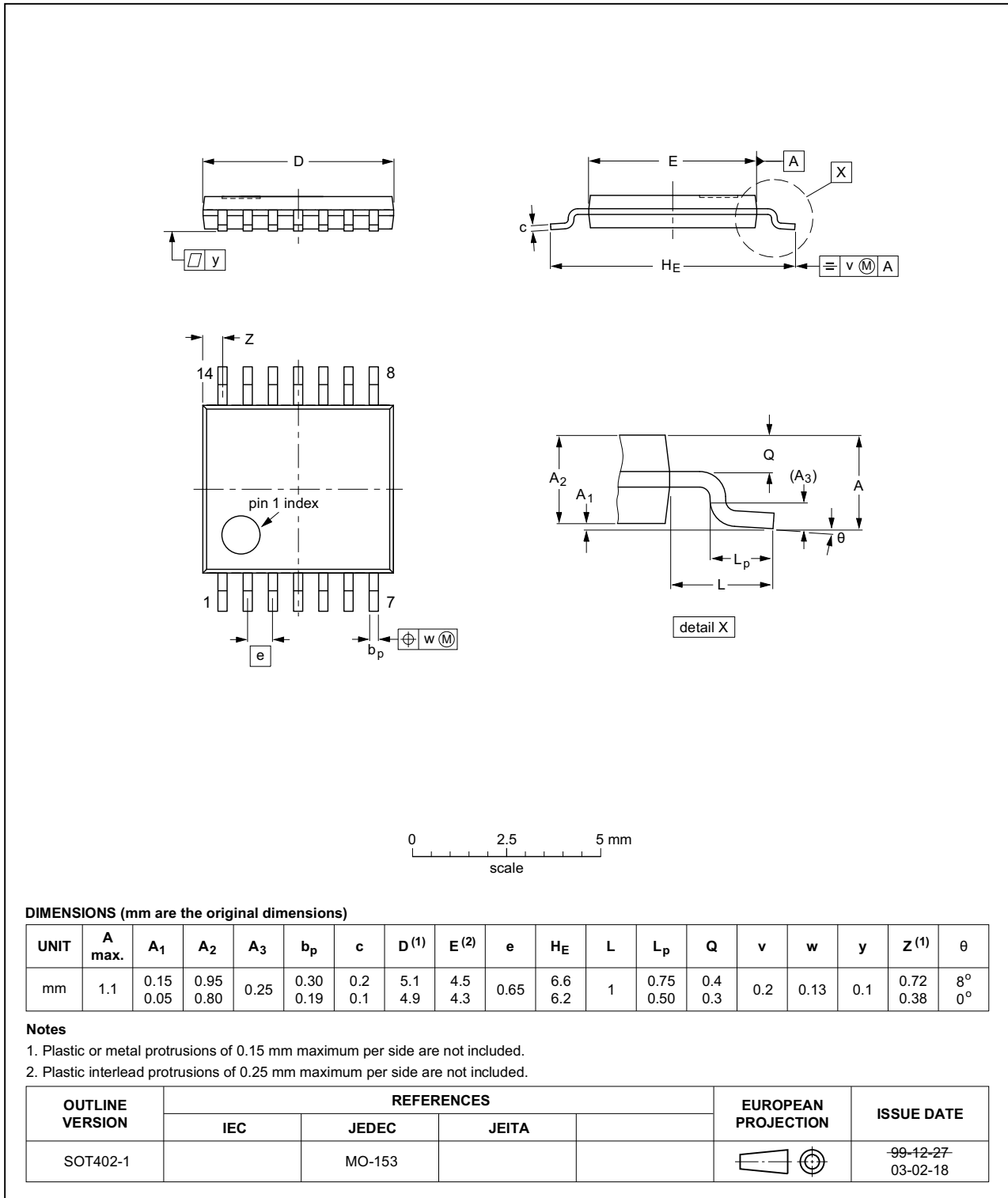


Fig 11. Package outline SOT402-1 (TSSOP14)

## 15. Abbreviations

Table 11. Abbreviations

Acronym	Description
DUT	Device Under Test

## 16. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4013B v.9	20151210	Product data sheet	-	HEF4013B v.8
Modifications:	<ul style="list-style-type: none"> <li>Type number HEF4013BP (SOT27-1) removed.</li> </ul>			
HEF4013B v.8	20111121	Product data sheet	-	HEF4013B v.7
Modifications:	<ul style="list-style-type: none"> <li>Legal pages updated.</li> <li>Changes in "General description", "Features and benefits" and "Applications".</li> </ul>			
HEF4013B v.7	20110913	Product data sheet	-	HEF4013B v.6
HEF4013B v.6	20091027	Product data sheet	-	HEF4013B v.5
HEF4013B v.5	20090619	Product data sheet	-	HEF4013B v.4
HEF4013B v.4	20080515	Product data sheet	-	HEF4013B_CNV v.3
HEF4013B_CNV v.3	19950101	Product specification	-	HEF4013B_CNV v.2
HEF4013B_CNV v.2	19950101	Product specification	-	-

## 17. Legal information

### 17.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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