Vision System FH Series

OMRON

AI-based defect detection that exceeds the ability of expert inspectors





A better option for inspections requiring high sensitivity

Meeting sensory inspection needs amid a shortage of skilled inspectors

Skilled inspectors are hard to come by these days, and labor costs have risen sharply. Manufacturers are now facing intense pressure to automate processes that rely on the senses of experienced human workers. Particularly when it comes to visual inspection, it's important to reliably identify subtle defects even on flexible lines producing a wide range of items. Traditionally, the sensitivity and knowledge of technicians with long-term experience has been key. However, artificial intelligence is now reaching the stage where it can recognize object features as well as humans and automatically learn criteria. While a lot of Al solutions faces challenges with large amounts of image data, specialized hardware and engineering expertise, Omron is making great progress in enabling its widespread use.



Barriers to automation

Defect detection dependent on human senses

2

Inspection criteria dependent on workers' expertise

Shortage of engineers who examine automation

AI reproduces human sensibility and experience

To solve these challenges, Omron developed new defect detection AI that reproduces the techniques of skilled inspectors. This AI is now part of the FH Vision System.

AI captures defects with human-like sensitivity

Al identifies good products as well as experienced inspectors

No special environment is required

AI captures defects with human-like sensitivity

Defect detection tasks that rely on human sensibility are a challenge to automate. Fortunately, powerful new AI technology can match the skills and capabilities of experienced inspectors.



Automating human vision-based inspection with the FH Series

The latest capabilities of the FH Vision System include a new AI-based image filter that reproduces the technique that skilled inspectors use to identify a defect on any product background. Scratches and blemishes that were once difficult to capture can now be identified even without the use of samples or adjustment.





Captured image



Previous detection image Cannot separate a scratch from noise



Detection image Can detect a scratch only



Al reproduces human expertise through learned criteria

AI Scratch Detect Filter *1

The AI Scratch Defect Filter learns by means of images in which human inspectors noticed defects. Whereas previous inspection methods found the unexpected size, shape or color of a particular defect to be a barrier to automation, AI successfully extracts abnormalities by judging their features without definition. The learned data facilitates defect detection on processed surfaces and other uneven backgrounds that previously posed an insurmountable challenge.

Captured image



Extracted scratch (internal image)

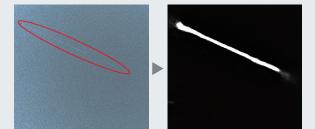


*1. The FH-UMAI1 Scratch Detect AI Software Installer is required to use AI Scratch Detect Filter.

Automatic detection of various defects without definition and learning

Regardless of material type, color, or size, defects can be extracted reliably without previously required definition and adjustment.

Scratch on sandblasted metal

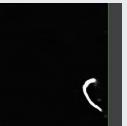


Scratch on resin products



Black scratch on hairline finish





White scratch on shaded hairline finish



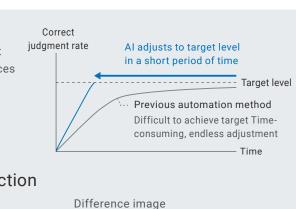


Al identifies good products as well as experienced inspectors

Sensory inspection requires a certain tolerance for variations that don't pass a certain threshold. Determining what variations are acceptable is a key capability of expert inspectors and poses a challenge for automated inspection systems.



Omron's AI Fine Matching tool learns from the image data of non-defective products to quickly acquire the "expertise" that inspectors develop over the course of many years. This reduces costs and boosts productivity through automation.



The FH Series can determine acceptable variation tolerances.

Target inspection level: Reduce overdetection

		Previous automation method	AI automation method
Contamination inspection of LED modules	Captured image	Detects position differences, not foreign materials, as defects	Detects foreign materials only and ignores position differences
Defective product With foreign materials		Overdetection	Detects foreign material only
Non-defective product Position difference of die		Overdetection	Judges as non-defective product
Non-defective product Position difference and light variation of surrounding part		Overdetection	Judges as non-defective product

Al reduces overdetection

Al Fine Matching

Al Fine Matching identifies a future that is not included in good products as a defect.

AI learns images of good products with variations, and generates an AI model.

Every time an inspection is carried out, AI reconstructs a model that is presumed to be a good product. Al extracts a difference between the reconstructed good product image and a captured image to identify a defect, reducing overdetection.

Captured image



Shifted to upper right





Al model

Reconstructed good product image





Reconstructs a good product image considering different views of holes

Al makes it easy to avoid overdetection PATENT PENDING

Three quick steps on the settings screen guide the user through the process of creating the good product model with the minimum number of images.

Prepare images 1

Although standard AI processing requires a huge number of images for learning, the FH Series requires only 100 to 200 images.

Good product image

Defective product image





2 Create model

The system suggests images to learn, helping to complete the good product model.

Al makes it easy



3 Check results

Test is automatically performed using images prepared in Step 1. You don't need to adjust parameters for differential inspections.

Al makes it easy



Correlation score Image A:10 Image B:150

When a good product is judged as defective, AI gives each image a correlation score to visualize the degree of overdetection. This facilitates selecting images that need to be learned to reduce overdetection.

*1. "Patent pending" means that we applied for a patent in Japan, and "Patented" means that we obtained a patent in Japan. (as of May 2020)

No special environment is required

With the FH Series, there's no need for high-end hardware or specialized engineers who can configure the system to suit your needs. Our general-purpose vision system makes it easier than ever to introduce AI into production sites.

Vision controller with AI functionality

Artificial intelligence has traditionally required a high-end environment, but our lightweight creative solution comes in the form of user-friendly processing items that have been integrated into our popular FH Series hardware.

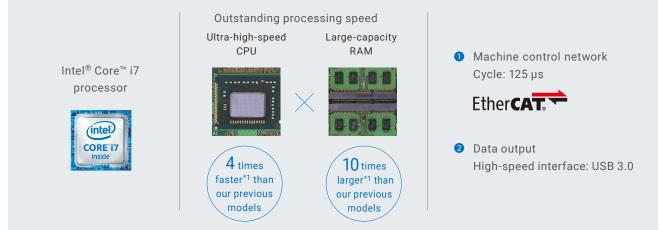
No special hardware for AI required

It used to be difficult to introduce AI technology to many inspection processes because of its hardware requirements. The FH Series does not require special hardware, facilitating the introduction of this technology. The FH Series does not require special hardware, facilitating introduction.

No AI engineer required

In order to reliably use AI technology in processes, the engineer used to have not only image processing skills but also programming and maintenance skills. With the FH Series, however, you can use AI technology just like operating a standard vision sensor. No dedicated AI engineer is required.





*1. The FH-5550 Controller is compared with the FH-3050 Controller.

High-resolution cameras

We offer a range of cameras that can capture high-resolution images suitable for sensory inspection at high speeds.

20.4 Mpix

Ultra-high-speed sensing technology in a compact design

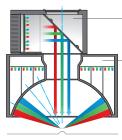
There was a trade-off between high-resolution image capture like the human eye and inspection processing speed. We use new CMOS image elements and dual transfer technology to capture high-resolution images while transferring images at high speeds. This facilitates applications that previously required multiple cameras or a mechanism to move a camera.

MDMC light with flexible lighting patterns

This light can be adjusted to defects by combining the illumination colors and angles like humans do. Even if new objects or inspection items are added after installation, there is no need to add or change the light-just change the illumination pattern. The illumination patterns can be registered as settings, facilitating duplicating production lines.

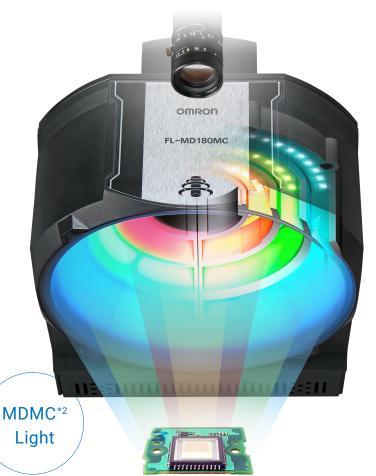
Illumination structure

You can choose the best pattern by combining illumination directions x full color RGB x 128 brightness levels of 13 blocks.



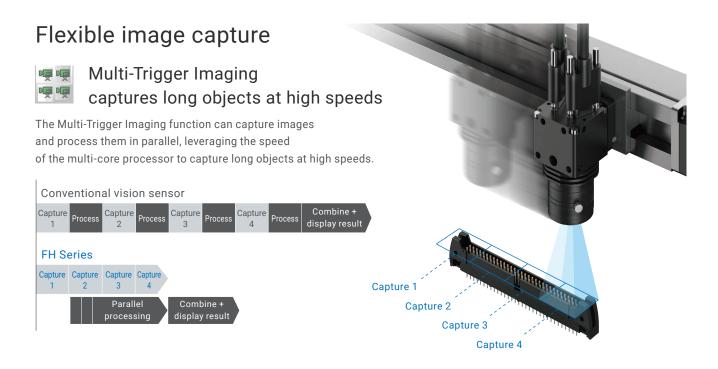
Full color coaxial light

Full color 3-tier x 4-block dome light



*2. MDMC...Multi-Direction Multi-Color

Software for flexible automation





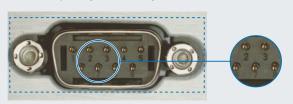
Camera Image Input HDR optimizes contrast

Camera Image Input HDR helps create optimized HDR images under variable ambient conditions. Once you specify the optimum area to capture on the image, the FH Series automatically adjusts the shutter speed while capturing images and combining the images.

Adjusts brightness to suit your specified area

Optimized for the entire field of view

While the contrast around the pins is low, reduced reflection enables capturing a clear image of the entire connector.



Detects low-contrast defects in high-contrast mode





Low contrast makes the surface appear uniform.

Optimized for the connector

Although reflection occurs at the surrounding part, a clear image of the pins can be captured.



HDR high-contrast image



Increased contrast reveals many scratches and blemishes.

Parallel processing for different inspections

Multi-Line Random-Trigger inspects at up to four different timings

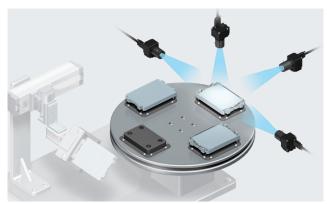
A single controller can perform inspections at different points at different timings. Controllers installed for each process can be integrated into one, reducing initial costs and saving space.

Reding characters (DCP) CS1 code inspection DCT 90924350 Description <t

Packaging process of pharmaceuticals

Contamination inspection of beverage containers A single controller that can control each line saves initial costs and space.

Appearance inspection of rechargeable battery cells Four cameras can be connected to one controller, enabling simultaneous inspection of dents and scratches from four directions.

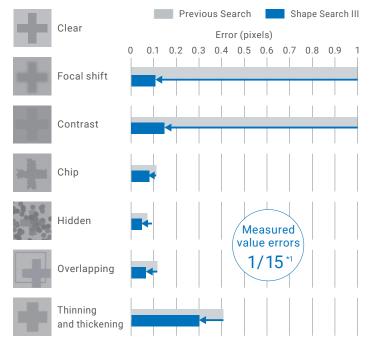


High-speed, high-precision positioning

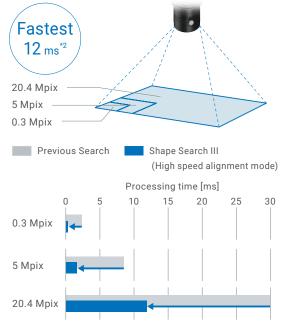


Shape Search III is robust against shape variations

High-precision and robust positioning is possible even under the adverse conditions, such as changes in environments and materials.



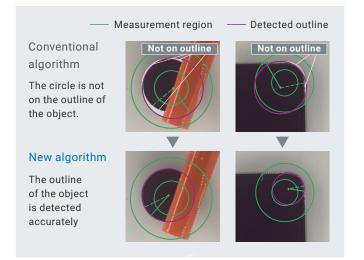
A 20.4 Mpix camera can search a positioning mark in as fast as 12 ms^{*2}, and a 5 Mpix camera, widely used for alignment applications, in as fast as 2 ms.



*1. The value measured under our specified conditions is provided for reference. *2. The value measured under our specified conditions is provided for reference. 20.4 Mpix camera.

Circular Scan Edge Position accurately estimates the center and radius of a circle

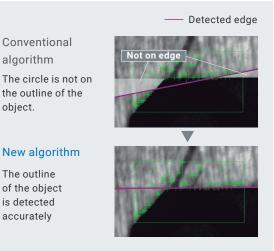
The new algorithm accurately detects a whole circle from a part of the circle.





Scan Edge Position removes noise to detect edges

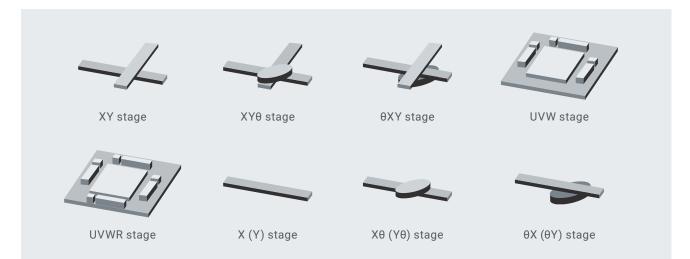
This algorithm accurately estimates lines even when the edges are unclear due to variations in objects or disturbance.





Stage Data calculates for various stages

The popular single axis + θ axis stages as well as UVW stages can be used. The use of the same axis for both handling and positioning simplifies machine configuration.



Robot Setting Tool simplifies connecting robots

Communication programs to connect robots from various vendors and FH flowcharts required for robot applications are provided free of charge. You can quickly set up robot vision applications.

Applications

Pick



Place



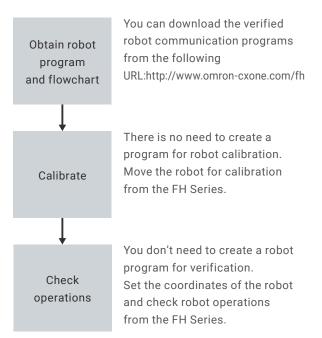
Offset compensation



Combination



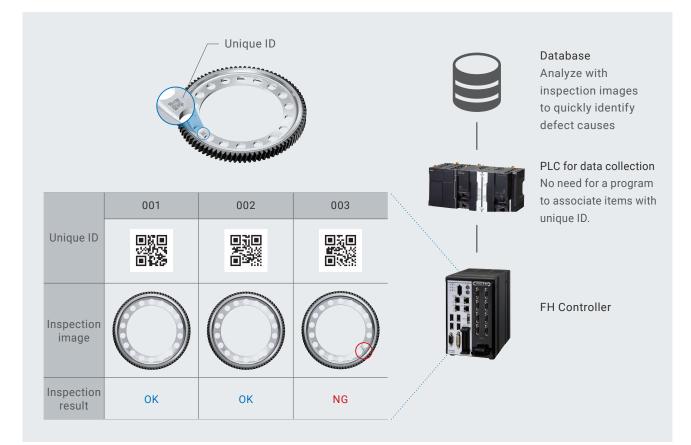
Simple set-up steps



Unique identification and quality control

Unique ID associated with inspection image and result

The FH Series can associate a unique ID with the inspection image and result, and then output them to the host device. You can immediately find required inspection images and quickly identify causes of fails.



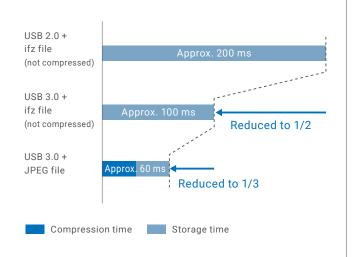
High-speed image storage

The amount of inspection image data required for defect cause analysis can be so large that conventional controllers are unable to store it given their storage time and capacity constraints.

The high-speed, large-capacity controller has USB 3.0 ports and the improved algorithm to compress image data at high speeds, enabling all images to be stored to meet increasing needs in quality control.

The times in the right figure provided for reference only and their accuracy cannot be guaranteed. They are measured under the following conditions: •FH-5050 Controller

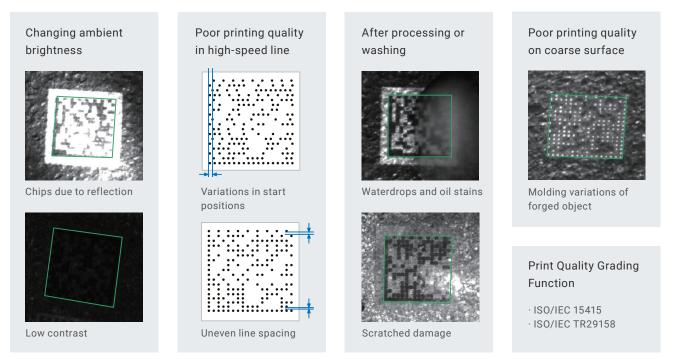
- •5 Mpix monochrome images
- •Size of converted JPEG file: 0.6 MB





2D Code II provides powerful code reading

The FH Series incorporates a dedicated algorithm for reliable and fast 2D code reading even under variable ambient brightness or adverse conditions such as after processing or washing.



*1. The average value measured under our specified conditions is provided for reference.

AB

Character Inspection reads special fonts

Character Inspection recognizes special fonts and non-alphanumeric characters based on pattern search using the dictionary set up by the user.

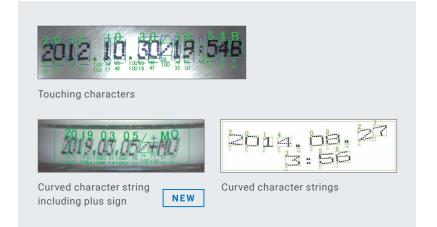


Japanese characters



OCR reliably reads difficult-to-read characters

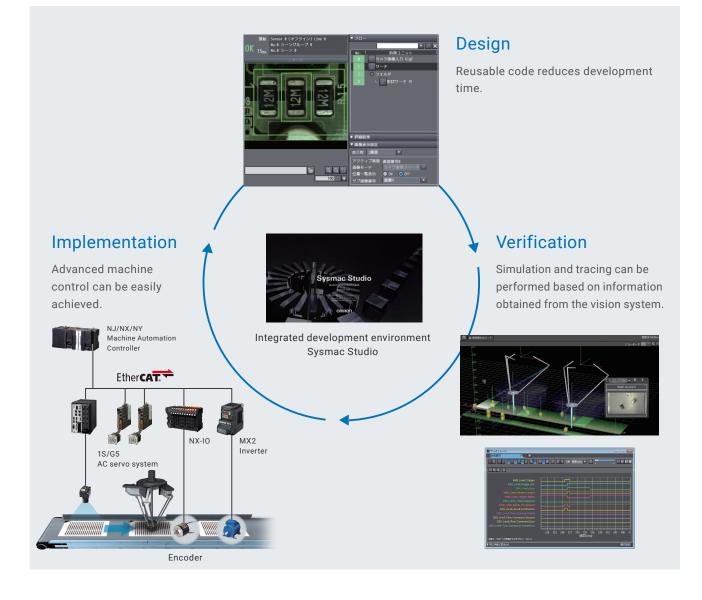
OCR can reliably read characters printed too close to each other or on curved surfaces. Also plus signs can be read.

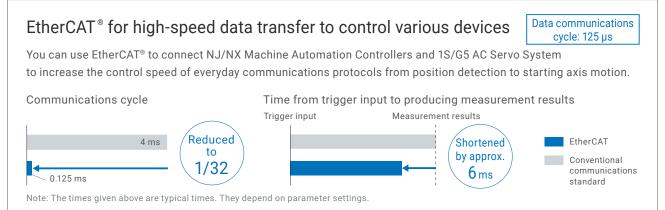


Design interface for quick setup

Integrated development environment Sysmac Studio

Sysmac Studio is a unique environment that integrates logic, motion and drives, robotics, safety, visualization, and information technologies in a single project, thus reducing the learning curve and the intra-operative software costs.





Total Design Management Editor simplifies complex processing design

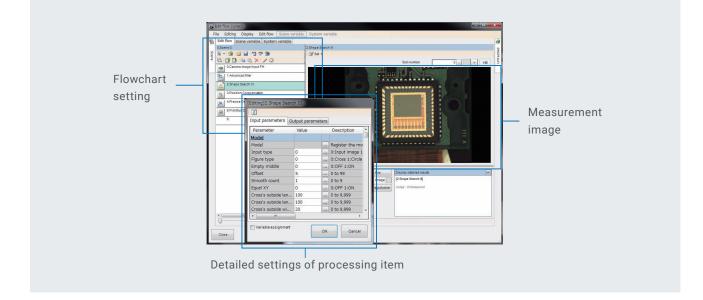
This design interface includes pre-installed screens for all phases, from design through to setting and operation. Just select processing items and determine the order to manage variables. Time-consuming calculations and inputs are no longer required.

Easy setting

All the common settings of multiple scenes can be made at once. Simplified inspection flowcharts reduce setting errors and prevent from forgetting to change settings.

Efficient setting

To inspect aligned parts, the FH Series can repeat the same measurements while shifting the measurement region within the same image. This reduces setting times.



Customizable user interface simplifies operations at production sites

Showing only necessary screens for production makes the interface easier to use. Screen layout can be customized just by selecting and placing objects, without programming.

✓ High-Free. ✓ Radation Angle range: ✓ Multiple output ✓ Court: Soft condition: Soft condition: Contract Re-soft Re-soft Re-soft Sample: Overlay updgement Overlay rejection(%):	Show only parameters you change every day	Enlarge only my you use every of 21ms
Show overlap judg, area Detail settings Test measuring of this item. Measure Judgenent	Count 0.0000 0.0000 Correlate 0.0000 0.0000	Derve disjund on
Count: 0 0 - 32 - Measure X: 0.0000 -99999.9999 - 99999.9999 -	0K Dancel	
Measure Y : 0.0000 -99999.9999 - 99999.9999 - Search angle : 0.0000		
Correlation : 0.0000		

Vision System FH-Series

Al-based automated visual inspection

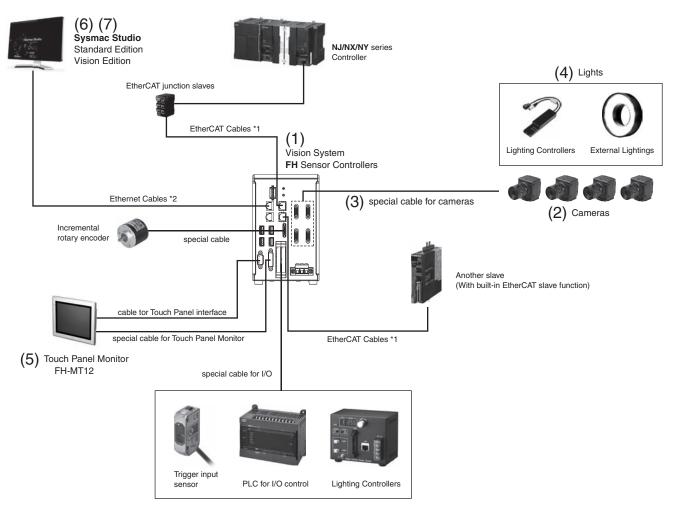
- Al reproduces human sensibility and experience
- Software for flexible automation
- Design interface for quick setup



System configuration

EtherCAT connections for FH series

Example of the FH Sensor Controllers (4-camera type)



*1. To use STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT and RJ45 connector. *2. To use STP (shielded twisted-pair) cable of category 5 or higher for Ethernet and RJ45 connector.

(1) Controllers



Select a controller based on the required processing speed and network.

	Series	CPU	Performance	Memory	No. of connectable cameras	Fieldbus
High-speed, Large-capacity Controller	FH-5550 Series	Intel [®] Core™ i7 processor 4 cores	****	RAM 32 GB, ROM 64 GB	8 max.	PROFINET, EtherNet/IP™, EtherCAT
High-speed Controller	FH-5050 Series	Intel [®] Core™ i7 processor 4 cores	****	RAM 8 GB, ROM 32 GB	8 max.	PROFINET, EtherNet/IP™, EtherCAT
Standard Controller	FH-2050 Series	Intel® Celeron® processor 2 cores	***	RAM 8 GB, ROM 32 GB	8 max.	PROFINET, EtherNet/IP [™] , EtherCAT
Lite Controller	FH-L550 Series	Intel® Atom® processor 2 cores	*	RAM 4 GB, ROM 4 GB	4 max.	PROFINET, EtherNet/IP™
					*:	The more stars, the higher the performance.

Optional product (sold separately) Model
Scratch Detect AI Software Installer* FH-UMAI1

This product can be installed on the FH-5□50-series Controller (version 6.40 or later).

(2) Cameras

Choose the right camera to suit your required number of pixels. Easy-to-use cameras with built-in light are also available.



No. of pixels	High-speed camera	Standard camera	Rolling shutter camera	Camera with built-in light
20.4 Mpix*			FH-S□21R	
12 Mpix	FH-S X12			
5 Mpix	FH-S X05	FZ-S□5M3	FH-S□05R	
2 Mpix	FH-S□02	FZ-S□2M		
0.4 Mpix/0.3 Mpix	FH-S□X	FZ-S		FZ-SQ

* 20.4 Mpix Cameras can be used with the FH-5050/2050-series High-speed, Large-capacity Controllers.

(4) Lights

Omron offers a complete line-up of lights required for image processing. The use of the camera-mount lighting controller allows you to control lighting conditions from the FH Controller, making system configuration simple.

External lighting controller

Description	LED	High-brightness LED
Camera-mount Lighting Controller	FLV-TCC	FL-TCC
Bar Light	FLV-BR	FL-BR
Direct Ring Light	FLV-DR	FL-DR
Low Angle Ring Light	FLV-DL	
Coaxial Light	FLV-CL	
Shadowless Light	FLV-FR/FP/FS/FQ	
Spot Light	FLV-EP	
Direct Back/Edge Type Light	FLV-DB/FB	
Dome Light	FLV-DD	
Photometric Stereo Light *		FL-PS

* The FL-TCC Camera-mount Lighting Controller cannot be used. Use the FL-TCC1PS Lighting Controller for Photometric Stereo Light.

Built-in lighting controller

Description	Model
MDMC Light	FL-MD

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

(5) Touch panel monitor

The touch panel monitor is optimized for the operation of the FH Series.

Description	Model
Touch Panel Monitor 12.1 inches	FH-MT12
DVI-Analog Conversion Cable for Touch Panel Monitor	FH-VMDA
USB Cable for Touch Panel Monitor	FH-VUAB

* RS-232C cables for long-distance connections are also available.

Refer to Ordering Information for details.

(3) Camera cables



The cable line-up includes bend-resistant cables and right-angle cables. Use the FZ-VSJ Cable Extension Unit for cable extensions.

Description	Model
Camera Cable	FZ-VS
Right-angle Camera Cable	FZ-VSL
Bend-resistant Camera Cable	FZ-VSB3
Bend-resistant Right-angle Camera Cable	FZ-VSLB3
Cable Extension Unit	FZ-VSJ

(6) Sysmac Studio

The development environment for the Sysmac platform allows you to configure and simulate the FH Series on your PC.



Description	Model
DVD for installation	SYSMAC-SE200D
Software license (Vision Edition)	SYSMAC-VE001L



(7) Application producer

This development environment enables you to customize FH functions. It includes sample codes and wizards that will help you develop your own interfaces and processing items.

Description	Model
DVD for installation	FH-AP1
Software license	FH-AP1L

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FH-Series

Ordering Information

FH Series Sensor Controllers

			Al function		No. of		
Item		CPU	Al Scratch Detect Filter*	AI FineMatching	cameras	Output	Model
	High-speed,				2	NPN/PNP	FH-5550
	Large-capacity	Intel [®] Core [™] i7 processor 4 cores	Available	Available	4	NPN/PNP	FH-5550-10
CHIER A	Controller				8	NPN/PNP	FH-5550-20
					2	NPN/PNP	FH-5050
	High-speed Controller	Intel [®] Core [™] i7 processor 4 cores	Available	e Available	4	NPN/PNP	FH-5050-10
		processor 4 cores			8	NPN/PNP	FH-5050-20
Standard Controller					2	NPN/PNP	FH-2050
	Intel [®] Celeron [®] processor 2 cores	Not available	ble Available	4	NPN/PNP	FH-2050-10	
		p10000001 2 00100			8	NPN/PNP	FH-2050-20
	Intel [®] Atom [®]	Not available		2	NPN/PNP	FH-L550	
	Box-type controllers	processor 2 cores	INUL AVAIIADIE	Not available	4	NPN/PNP	FH-L550-10

* Optional FH-UMAI1 Scratch Detect AI Software Installer is required.

Optional Products (Sold Separately)

Item	Model
Scratch Detect AI Software Installer *	FH-UMAI1

 * This product can be installed on the FH-5]]50-series Controller (version 6.40 or later).

Cameras

	Item	Lens mount	Descriptions	Color / Monochrome	Image Acquisition Time *1	Model
	Digital CMOS Cameras	0	20.4 million pixels	Color	10.0	FH-SC21R
	(Lens required)	C mount	(Supported controller: FH-5□50(-□)/2050(-□) Series) *2	Monochrome	42.6 ms *3	FH-SM21R
				Color	0.4.0 ±0	FH-SCX12
Comp			12 million pixels *2	Monochrome	24.9 ms *3	FH-SMX12
	High-speed Digital		5 million pixels	Color	10.3 ms *3	FH-SCX05
	CMOS Cameras	C mount	5 million pixels	Monochrome	10.3 1115 - 3	FH-SMX05
0	(Lens required)			Color		FH-SCX
OV			0.4 million pixels	Monochrome	1.9ms	FH-SMX
	High-speed Digital CMOS Cameras	M42 mount	12 million pixels *2	Color	25.7 ms *3	FH-SC12
C A	(Lens required)	M42 mount	12 million pixels 2	Monochrome	20.7 115 3	FH-SM12
			4 million nivele	Color	0 E ma *0	FH-SC04
			4 million pixels	Monochrome	8.5 ms *3	FH-SM04
<u> </u>	High-speed Digital	C mount	2 million pixels	Color	4.6 ms *3	FH-SC02
	CMOS Cameras (Lens required)			Monochrome	4.0 1115 5	FH-SM02
	(Lens required)		0.3 million pixels	Color	– 3.3 ms	FH-SC
			0.3 million pixels	Monochrome	3.3 ms	FH-SM
			5 million pixels	Color	71.7ms	FH-SC05R
	Digital CMOS Cameras		5 million pixels	Monochrome	71.7ms	FH-SM05R
	(Lens required)	C mount		Color		FZ-SC5M3
032			5 million pixels	Monochrome	38.2 ms	FZ-S5M3
				Color		FZ-SC2M
9) e	Digital CCD Cameras	0	2 million pixels	Monochrome	33.3 ms	FZ-S2M
	(Lens required)	C mount	0.0 million minute	Color	10.5	FZ-SC
			0.3 million pixels	Monochrome	12.5 ms	FZ-S
			200,000 pivel flat type	Color	10 E ma	FZ-SFC
and the	Small Digital	Lenses for small	300,000-pixel flat type	Monochrome	12.5 ms	FZ-SF
	- CCD Cameras (Lens required)	camera required	200,000 pixel per ture	Color	10 E ma	FZ-SPC
C. B	,/		300,000-pixel pen type	Monochrome	12.5 ms	FZ-SP

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FH-Series

Item		Lens mount	ens mount Descriptions		Image Acquisition Time *1	Model
-	Intelligent Compact Digital CMOS Camera	Built-in lens	Narrow view	Color		FZ-SQ010F
Ĩ			Standard view	Color	– 16.7 ms	FZ-SQ050F
			Wide View (long-distance)	Color		FZ-SQ100F
			Wide View (short-distance)	Color		FZ-SQ100N

 *1 The image acquisition time does not include the image conversion processing time of the sensor controller. The camera image input time varies depending on the sensor controller model, number of cameras, and camera settings. Check before you use the camera.
 *2 Up to four cameras of this model can be connected to one controller. Up to eight cameras including other models can be connected to an FH-5550-20, 5050-20 or 2050-20

*3 Frame rate in high speed mode when the camera is connected using two camera cables. For other conditions, refer to the table on the next page.

Model		FH- SM02	FH- SC02	FH- SM04	FH- SC04	FH- SM12	FH- SC12	FH- SMX	FH- SCX	FH- SMX05	FH- SCX05	FH- SMX12	FH- SCX12	FH- SM21R	FH- SC21R	
2	2Cables	High Speed Mode *6	4.6	4.6 ms		8.5 ms 25.7 ms				10.3 ms		24.9 ms		42.6	3 ms	
Image Acquisition	*5	Standard Mode	9.7	ms	17.9	ms	51.3	8 ms	-	-	22.1	ms	53.5	i ms	90.1	ms
Time *4 1 Cables	1 Cables	High Speed Mode *6	9.2	ms	17.0) ms	51.3	8 ms	1.9	ms	20.6	6 ms	50.0) ms	83.3	8 ms
	T Cables	Standard Mode	19.3	3 ms	35.8	s ms	102.	0 ms	3.8	ms	44.1	ms	106.4	4 ms	175.4	4 ms

*4 The image acquisition time does not include the image conversion processing time of the sensor controller.
*5 Two Camera ports of the controller are used per one camera.
*6 Up to 5 m Camera Cable length.

Camera Cables

Item	Descriptions	Model *3
$\dot{\mathbb{Q}}$	Camera Cable Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VS3 □M
Ó	Bend resistant Camera Cable Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VSB3 □M
\sim	Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VSL3 □M
Ņ	Bend resistant Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VSLB3 □M
Q.	Long-distance Camera Cable Cable length: 15 m *2	FZ-VS4 15M
, Ô	Long-distance Right-angle Camera Cable *1 Cable length: 15 m *2	FZ-VSL4 15M
	Cable Extension Unit Up to two Extension Units and three Cables can be connected. (Maximum cable length: 45 m *2)	FZ-VSJ

This Cable has an L-shaped connector on the Camera end. The maximum cable length depends on the camera being connected, and the model and length of the cable being used. For further information, refer to the *Cameras / Cables Connection Table and Maximum Extension Length Using Cable Extension Units FZ-VSJ* table. When a High-speed Digital CMOS Camera FH-S_02/-S_04/-S_12/-S_21R is used in the high speed mode of transmission speed, two camera cables are *1 *2

required.

*3 Insert the cables length into \Box in the model number as follows. 2 m = 2, 3 m = 3, 5 m = 5, 10 m = 10

Cameras / Cables Connection Table

					High-sp	eed Digital CMOS	6 cameras			
			300,000-pixel	2 millio	n-pixel	4 millio	on-pixel	12 millio	on-pixel	
Camera Cables	Model	Cable length	FH-SM/SC	FH-SM0	2/SC02	FH-SM0	04/SC04	FH-SM12/SC12		
			length	-	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select
	FZ-VS3 FZ-VSL3	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cables Right-angle		3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	Yes	No	Yes	No	Yes	No	Yes	
Bend resistant		2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cable		10 m	Yes	No	Yes	No	Yes	No	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	No	Yes	

					High-speed Digita	al CMOS cameras			
			400,00	0-pixel	5 millio	on-pixel	12 milli	on-pixel	
Camera Cables	Model	Cable	FH-SM	IX/SCX	FH-SMX	05/SCX05	FH-SMX12/SCX12		
		length	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	
		2 m	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cables Right-angle	FZ-VS3 FZ-VSL3	3 m	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	No	Yes	No	Yes	No	Yes	
Bend resistant	FZ-VSB3	2 m	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables Bend resistant		3 m	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Čable		10 m	No	Yes	No	Yes	No	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	No	Yes	No	Yes	No	Yes	

				Digital CM	OS Camera		Digital CC	D cameras
			5 million-pixel	20.4 mill	ion-pixel	5 million-pixel	300,000-pixel	2 million-pixel
Camera Cables	Model	Cable length	FH-SM05R/ SC05R	FH-SM21	R/SC21R	FZ-S5M3/ SC5M3	FZ-S/SC	FZ-S2M/SC2M
		longin	-	High speed mode of transmission speed select	Standard mode of transmission speed select	-	-	-
	FZ-VS3 FZ-VSL3	2 m	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cables		3 m	Yes	Yes	Yes	Yes	Yes	Yes
Right-angle camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	No	Yes	No	Yes	Yes
Bend resistant		2 m	Yes	Yes	Yes	Yes	Yes	Yes
camera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes	Yes	Yes	Yes	Yes
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cable		10 m	Yes	No	Yes	No	Yes	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	Yes

Camera Cables	Medel	Cable	Small digital CCD cameras Pen type / flat type	Intelligent Compact Digital CMOS Camera
Camera Cables	Model	length	FZ-SF/SFC FZ-SP/SPC	FZ-SQ□
	FZ-VS3 FZ-VSL3	2 m	Yes	Yes
		3 m	Yes	Yes
		5 m	Yes	Yes
		10 m	Yes	Yes
Bend resistant		2 m	Yes	Yes
amera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes
Right-angle	FZ-VSLB3	5 m	Yes	Yes
Camera Čable		10 m	Yes	Yes
	FZ-VS4 FZ-VSL4	15 m	Yes	Yes

Maximum Extension Length Using Cable Extension Units FZ-VSJ

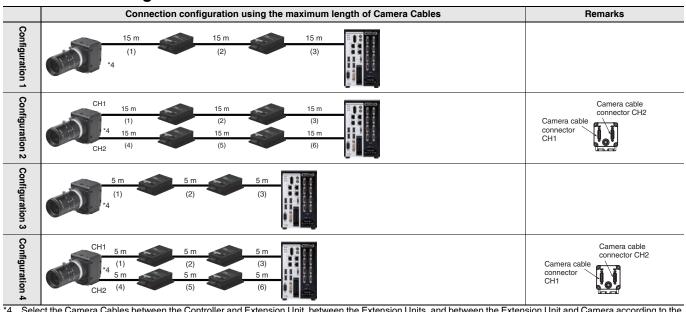
		Transmission	No. of CH used	Maximum cable length	Max. number of	Using Cable Extension Units FZ-VSJ			
Item	Model	speed (*1)	for connection (*2)	using 1 Camera Cable (*1)	connectable Extension Units	Max.cable length	Connection configuration		
	FH-SM/SC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m X 3 Extension Unit: 2		
	FH-SMX/SCX	Standard		15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m X 3 Extension Unit: 2		
		High speed		5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2		
High-speed Digital CMOS Cameras		Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2		
	FH-SM02/SC02 FH-SM04/SC04 FH-SM12/SC12	Standard	2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: $15 \text{ m} \times 6$ Extension Unit: 4		
	FH-SM12/SC12 FH-SMX05/SCX05 FH-SMX12/SCX12	High speed	1	5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2		
			2	5 m (Using FZ-VS⊡/VSL⊡)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m × 6 Extension Unit: 4		
	FH-SM21R/SC21R	Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2		
		Clandard	2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: $15 \text{ m} \times 6$ Extension Unit: 4		
Digital CMOS		L link an and	1	5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2		
Cameras		High speed	2	5 m (Using FZ-VS□/VSL□)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m × 6 Extension Unit: 4		
	FH-SM05R/SC05R			15 m (Using FZ-VS⊟/VSL⊟)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2		
	FZ-S5M3/SC5M3			5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m \times 3 Extension Unit: 2		
Digital CCD Cameras	FZ-S/SC FZ-S2M/SC2M			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2		
Small Digital CCD Cameras Flat type/ Pen type	FZ-SF/SFC FZ-SP/SPC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2		
Intelligent Compact Digital CMOS Camera	FZ-SQ			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2		

*1 The FH-S = enables switching between standard and high speed modes. In high speed mode, images can be transferred approximately two times faster than in standard mode, but the connectable cable length will be shorter.

*2 The FH-SDD has two channels to connect Camera Cables. Connection to two channels makes image transfer two times faster than connection to one channel: high speed mode using two channels can transfer approximately four times as many images as standard mode using one channel.

*3 Each channel can be used to connect up to two Cable Extension Units: up to four extension units, two channels x two units, can be connected by using two channels.

Connection Configuration



Select the Camera Cables between the Controller and Extension Unit, between the Extension Units, and between the Extension Unit and Camera according to the connected Camera. Different types or lengths of Camera Cables can be used for (1), (2), and (3) as well as for (4), (5), and (6). However, the type and length of Camera Cable (1) must be the same as those of Camera Cable (4), (2) must be the same as (5), and (3) must be the same as (6).

Monitor

Item	Descriptions	Model
	Touch Panel Monitor 12.1 inches For FH Sensor Controllers *	FH-MT12
	LCD Monitor 8.4 inches	FZ-M08

* FH Series Sensor Controllers version 5.32 or higher is required.

Monitor Cables

Item	Descriptions	Model
40	DVI-Analog Conversion Cable for Touch Panel Monitor/LCD Monitor Cable length: 2 m, 5 m or 10 m	FH-VMDA □M *1
	RS-232C Cable for Touch Panel Monitor Cable length: 2 m, 5 m or 10 m	XW2Z-□□□PP-1 *2
, O,	USB Cable for Touch Panel Monitor Cable length: 2 m or 5 m	FH-VUAB □M *1

*1 Insert the cables length into \Box in the model number as follows. 2 m = 2, 5 m = 5, 10 m = 10

Insert the cables length into $\square\square$ in the model number as follows. 2 m = 200, 5 m = 500, 10 m = 010. *2

A video signal cable and an operation signal cable are required to connect the Touch Panel Monitor.

Signal	Cable	2 m	5 m	10 m
Video signal	DVI-Analog Conversion Cable	Yes	Yes	Yes
Touch panel operation	USB Cable	Yes	Yes	No
signal	RS-232C Cable	Yes	Yes	Yes

Parallel I/O Cables/Encoder Cable

Item	Descriptions	Model
2	Parallel I/O Cable *1 Cable length: 2m, 5m or 15m	XW2Z-S013- □ *2
	Parallel I/O Cable for Connector-terminal Conversion Unit *1 Cable length: 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m Connector-Terminal Block Conversion Units can be connected (Terminal Blocks Recommended Products: OMRON XW2R-□34G-T)	XW2Z-□□□EE *3
	Connector-Terminal Block Conversion Units, General-purpose devices	XW2R-⊡34GD-T *4
∕ ♀	Encoder Cable for line-driver Cable length: 1.5 m	FH-VR 1.5M

*1 *2 *3 *4

2 Cables are required for all I/O signals. Insert the cables length into \Box in the model number as follows. 2 m = 2, 5 m = 5, 15 m = 15 Insert the cables length into $\Box\Box$ in the model number as follows. 0.5 m = 050, 1 m = 100, 1.5 m = 150, 2 m = 200, 3 m = 300, 5 m = 500 Insert the wiring method into \Box in the model number as follows. Phillips screw = J, Slotted screw (rise up) = E, Push-in spring = P Refer to the XW2R Series catalog (Cat. No. G077) for details.

Parallel Converter Cable

When you change to connect the F series, FZ5 series, or FZ5-L series to FH series Sensor Controller, you can convert by using the appropriate parallel converter cable of FH-VPX series under the usable condition.

Item	Appl	icable Model	Usable Condition	Model	
$\widehat{}$			 Do not use RESET signal. * Use with COMIN and COMUT are same power source. 	FH-VPX-FZ	
$\overline{\mathbf{Q}}$	FZ□-L35x series		Do not use RESET signal. *	FH-VPX-FZL	
	F160 series	F160-C10	Do not use RESET signal. * Use with COMIN and COMOUT are same power source. Do not use DI5 and DI6.	FH-VPX-F160	
	F210 series	F210-C10	Do not use RESET signal. *		
~)	1210 30105	F210-C10-ETN	 Use with COMIN and COMOUT are same power source. 	FH-VPX-F210	
	F500 series	F500-C10	Do not use DI8 and DI9.		

* Even if RESET signal cannot be use by conversion, conversion is possible to convert satisfying other usable condition. **Note:** Cannot be used for the F160-C10CP/-C10CF.

Recommended EtherCAT and EtherNet/IP Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT. Use Straight or cross STP (shielded twisted-pair) cable of category 5 or higher for EtherNet/IP. Cable with Connectors

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6LSZH8SS30CM-Y
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6LSZH8SS50CM-Y
Standard RJ45 plugs type *1 Wire Gauge and Number of Pairs: AWG26, 4-pair Cable		OMBON	1	XS6W-6LSZH8SS100CM-Y
Cable Sheath material: LSZH *2		OMRON	2	XS6W-6LSZH8SS200CM-Y
Cable color: Yellow *3			3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)	and the second s		0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1		OMRON	1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			2	XS5W-T421-DMD-K
Cable color: Light blue			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
		OMRON	0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *4			2	XS5W-T421-DM2-SS
M12/Smartclick Connectors	-0		3	XS5W-T421-EM2-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GM2-SS
Casic color. Black			10	XS5W-T421-JM2-SS
			0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *4			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	23	ONDON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type	-0	OMRON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

*1 Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the Industrial Ethernet Connectors Catalog (Cat. No. G019).

*2 The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

*3 Cables colors are available in yellow, green, and blue.

*4 For details, contact your OMRON representative.

FH-Series

Cables / Connectors

Ite	em	Recommended manufacturer	Model
Products for EtherCAT or EtherNet/IP		Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 x 4P CP *1
(1000BASE-T/100BASE-TX)	Cable	Kuramo Electric Co.	KETH-SB *1
Wire gauge and number of pairs:		SWCC Showa Cable Systems Co.	FAE-5004 *1
AWG24, 4-pair cable	RJ45 Connector	Panduit Corporation	MPS588-C *1
	O-bl-	Kuramo Electric Co.	KETH-PSB-OMR *2
Products for EtherCAT or EtherNet/IP	Cable	JMACS Japan Co., Ltd.	PNET/B *2
(100BASE-TX/10BASE-T) Wire gauge and number of pairs: AWG22, 2-pair cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 *2

*1 We recommend you to use the above Cable and RJ45 Connector together.

*2 We recommend you to use the above Cable and RJ45 Assembly Connector together.

Automation Software Sysmac Studio Please purchase a DVD and licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. The license does not include the DVD.

Item	Creatifications			Model
nem	Specifications	Number of licenses	Media	woder
	The Sysmac Studio is the software that provides an integrated envi- ronment for setting, programming, debugging and maintenance of	(Media only)	Sysmac Studio (32bit) DVD *2	SYSMAC-SE200D
	machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCat Slave, and the HMI.	(Media only)	Sysmac Studio (64bit) DVD *2	SYSMAC-SE200D-64
Sysmac Studio Standard Edition	Sysmac Studio runs on the following OS. Windows 7 (32-bit/64-bit version) / Windows 8 (32-bit/64-bit version) / Windows 8.1 (32-bit/64-bit version) / Windows 10 Pro (32/64bit) or Enterprise (32/64bit) *1 This software provides functions of the Vision Edition. Refer to OMRON website for details such as supported models and functions.	1 license	-	SYSMAC-SE201L
Ver.1.		3 license	-	SYSMAC-SE203L
		10 license	-	SYSMAC-SE210L
		30 license	-	SYSMAC-SE230L
		50 license	-	SYSMAC-SE250L
Sysmac Studio Vision Edition Ver.1. 2 *3 *4	Sysmac Studio Vision Edition is a limited license that provides se- lected functions required for Vision Sensor FH-series/ Smart Camera FHV7-series/FQ-M-series settings.	1 license	_	SYSMAC-VE001L
Sysmac Studio Robot Additional Option *4	Sysmac Studio Robot Additional Option is a license to enable the Vi- sion & Robot integrated simulation.	1 license	-	SYSMAC-RA401L

Note: Site licenses are available for users who will run Sysmac Studio on multiple computers. Ask your OMRON sales representative for details.
 Sysmac Studio version 1.07 or higher supports the FH Series. Sysmac Studio does not support the FH-L550/-L550-10.

*1 *2 *3 *4

Model "SYSMAC-SE200D-64" runs on Windows 10 (64bit). The same media is used for both the Standard Edition and the Vision Edition. With the Vision Edition, you can use only the setup functions for FH-series/FQ-M-series Vision Sensors. This product is a license only. You need the Sysmac Studio Standard Edition DVD media to install it.

Development Environment

Please purchase a CD-ROM and licenses the first time you purchase the Application Producer. CD-ROMs and licenses are available individually. The license does not include the CD-ROM.

Product	Specifications	Number of Model Standards licenses	Media	Model
	Software components that provide a development environment to further customize the standard controller features of the FH Series. System requirements: CPU: Intel Pentium Processor (SSE2 or higher) OS: Windows 7 Professional (32/64bit) or Enterprise(32/64bit) or Ultimate (32/64bit), Windows 8 Pro (32/64bit) or Enterprise (32/64bit),	— (Media only)	CD-ROM	FH-AP1
Application Producer	Windows 8.1 Pro (32/64bit) or Enterprise (32/64bit), Windows 10 Pro (32/64bit) or Enterprise (32/64bit) .NET Framework: .NET Framework 3.5 SP1 or higher Memory: At least 2 GB RAM Available disk space: At least 2 GB Browser: Microsoft® Internet Explorer 6.0 or later Display: XGA (1024 × 768), True Color (32-bit) or higher Optical drive: CD/DVD drive The following software is required to customize the software: Microsoft® Visual Studio® 2008 Professional or Microsoft® Visual Studio® 2012 Professional	1 license	_	FH-AP1L

			Descriptions		Model
	USB Memory		2 GB		FZ-MEM2G
E.			8 GB		FZ-MEM8G
	SD Card		2 GB		HMC-SD291
200			4 GB		HMC-SD491
	Display/USB Switcher				FZ-DU
_	Mouse Recommended Pro Driverless wired mouse (A mouse that requires the		e installed is not supported.)		
	EtherCAT junction slaves	3 port	Power supply voltage:	Current consumption: 0.08 A	GX-JC03
No B B		6 port	20.4 to 28.8 VDC (24 VDC -15 to 20%)	Current consumption: 0.17 A	GX-JC06
Jane	Industrial Switching Hubs	3 port	Failure detection: None	Current consumption: 0.08 A	W4S1-03B
	for EtherNet/IP and Ether- net	5 port	Failure detection: None	Current consumption:	W4S1-05B
a state	net	5 port	Failure detection: Supported	0.12 A	W4S1-05C
_	Calibration Plate	•			FZD-CAL
		DIN rail mounting bracket (For Lite Controllers)			FH-XDM-L
	Common items related to DIN rail (for FH-L550/-L550-10)	DIN 35mm rail	PHOENIX CONTACT	Length: 75.5/95.5/115.5/200 cm Height: 7.5mm Material: Iron Surface: Conductive	NS 35/7,5 PERF
			PHOENIX CONTACT	Length:75.5/95.5/115.5/200 cm Height: 15mm Material: Iron Surface: Conductive	NS 35/15 PERF
Des de la companya de		End plate	PHOENIX CONTACT	Need 2 pieces each Sensor Con- troller	CLIPFIX 35
				LED	FLV Series
			External lighting controller	High-brightness LED	FL-BR/DR Serie
-	External Lights			Photometric Stereo Light	FL-PS Series
			Built-in lighting controller	MDMC Light	FL-MD Series
				Mounting Bracket	FQ-XL
	For Intelligent Compact Dig	gital CMOS Came	ra	Mounting Brackets	FQ-XL2
				Polarizing Filter Attachment	FQ-XF1
	Mounting Bracket for FZ-S	□, FH-S□05R, FZ	-S□X		FZ-S-XLC
	Mounting Bracket for FZ-S				FZ-S2M-XLC
_	Mounting Bracket for FH-S	□, FZ-S□5M□, FI	H-S□X05, FH-S□X12, FH-S□21	R	FH-SM-XLC
_	Mounting Bracket for FH-S	FH-SM12-XLC			

* Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

Lenses

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

			Recommended lens			
Resolution	Camera Model	Size of image element	Standard Lens	Telecentric Lens	Vibrations and Shocks Resistant Lens	
	FZ-SF/SFC					
200.000 nivel	FZ-SP/SPC	1/0" equivalent	FZ-LES Series			
300,000-pixel	FZ-S/SC	1/3" equivalent			VS-MCA Series	
	FH-SM/SC		SV-V Series	NO TOULO		
400,000-pixel	FH-SMX/SCX	1/2.9" equivalent		VS-TCH Series	Non-telecentric Macro VS-MC Series	
0 million aired	FZ-S2M/SC2M	1/1.8" equivalent	SV-H Series			
2 million-pixel	FH-SM02/SC02	2/3" equivalent			VS-MCA Series	
4 million-pixel	FH-SM04/SC04	1" equivalent	VS-H1 Series	VS-TEV Series	VS-MCH1 Series	
	FH-SM05R/SC05R	1/2.5" equivalent			VS-MCA Series	
5 million-pixel	FZ-S5M3/SC5M3	2/3" equivalent	SV-H Series	VS-TCH Series	Non-telecentric Macro	
	FH-SMX05/SCX05	2/3" equivalent	-		VS-MC Series	
10 111 1	FH-SMX12/SCX12	1.1" equivalent	VS-LLD Series	VS-TEV Series		
12 million-pixel	FH-SM12/SC12	1.76" equivalent	VS-L/M42-10 Series		VS-MCL/M42-10 Series	
20.4 million-pixel	FH-SM21R/SC21R	1" equivalent	VS-LLD Series	VS-TEV Series	VS-MCH1 Series	

Ratings and Specifications (FH Sensor Controllers)

High-speed, Large-capacity Controller

Parallel IO	oller Series oller Model		FH-5550/5050	FH-5550/5050 Series FH-5550/5050-10	FH-5550/5050-20	FH-2050	FH-2050 Series FH-2050-10	FH-2050-20	
			NPN/PNP (common)						
Memory, Stora	ige		FH-5550 series : 32G FH-5050 series : 8GE			8GB RAM, 32GB R	NOM		
Number of cor	es		4 cores			2 cores			
		Standard	Yes						
	Operation Mode	Double Speed Multi-input	Yes						
	Mode	Non-stop adjustment mode Multi-line random-trigger mode	Yes Yes (Maximum 8 line	s) *1					
	Parallel Proces		Yes	-, -					
	Number of Cor	nectable Camera	2	4	8	2	4	8	
Main	Supported Camera	FH-S series camera	All of the FH-S series connectable.		All of the FH-S series cameras are connectable. *2	All of the FH-S seri connectable.	es cameras are	All of the FH-S series cameras are connectable. *2	
unctions	0	FZ-S series camera Camera I/F Possible Number of Captured Images		cameras are connectab	ole.				
	Possible Number of Logging Images to Sensor Controller		Refer to page 31. Refer to the Vision St	vstem FH/FZ5 Series Us	ser's Manual (Cat. No. 2	2365).			
	Possible Num		128						
	Operating on UI	USB Mouse Touch Panel		driver is unnecessary ty connection: FH-MT12)	pe)				
	Setup			g flow using Flow editing	j .				
	Language			implified Chinese, Tradi	tional Chinese, Korean	German, French, Sp	oanish, Italian, Vietname	se, Polish	
	Serial Commu		RS-232C × 1						
	Ethernet Communication	Protocol I/F	Non-procedure (TCP) 1000BASE-T × 2	(UDP)					
	EtherNet/IP Co		Yes (Target/Ethernet port)						
	PROFINET Cor	nmunication	 Yes (Slave/Etherne Conformance class 						
	EtherCAT Com	munication		A bage 36 about EtherCA	Communications Spe	cifications.			
			• 12 inputs/31 output	0					
			 Use 1 Line. Operation mode: 	Except Multi-line rando	m-trigger mode				
			 17 inputs/37 outputs 		in higger meder				
External			Use 2 Lines. Operation mode:	Multi-line random-trigge	ar mode				
Interface	Parallel I/O		 14 inputs/29 outputs 	99	er mode.				
			Use 3 to 4 Lines.	Multi line rendem trigge	x mada				
			 Operation mode. 19 inputs/34 outputs 	Multi-line random-trigge s:	er mode.				
			 Use 5 to 8 Lines. 						
			Operation mode: Multi-line random-trigger mode. Input voltage: 5 V ± 5%						
	Encoder Interf	ace	Signal: RS-422A Line Driver Level						
	Monitor Interface		Phase A/B/Z: 1 MHz DVI-I output (Analog RGB & DVI-D single link) × 1						
	USB I/F		USB3.0 host × 2 (BUS Power: Port5 V/0.5 A)						
	SD Card I/F		USB2.0 host × 4 (BUS Power: Port5 V/0.5 A)						
	SD Card I/F		SDHC × 1 POWER: Green						
	Main		ERROR: Red RUN: Green						
			ACCESS: Yellow						
			NET RUN1: Green LINK/ACT1: Yellow						
ndicator	Ethernet		NET RUN2: Green LINK/ACT2: Yellow						
Lamps	SD Card		SD POWER: Green						
	SD Card		SD BUSY: Yellow						
	EtherCAT		ECAT RUN: Green LINK/ACT IN: Green						
	LuieroAT		LINK/ACT OUT: Green ECAT ERR: Red						
	voltage		20.4 VDC to 26.4 VD	С					
Power-supply									
Power-supply	When connecting	an intelligent compact digital camera							
Power-supply	 When connecting When connecting controller with the control of the con	ting the following light or lighting hout an external power supply							
Current	 When connecting When connecting controller wit FLV-TCC1 FLV-TCC1 	ting the following light or lighting hout an external power supply , FLV-TCC4, FLV-TCC3HB EP, FL-TCC1	5.6 A max.	7.7 A max.	12.2 A max.	4.6 A max.	6.6 A max.	11.2 A max.	
Current	 When connecting When connection controller with FLV-TCC1 FLV-TCC1 When connection 	ting the following light or lighting hout an external power supply , FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 zting the following light or light-	5.6 A max.	7.7 A max.	12.2 A max.	4.6 A max.	6.6 A max.	11.2 A max.	
Current	When connecting • When connect controller wit FLV-TCC1 FLV-TCC1 • When connect ing controller FL-TCC1P	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- r S, FL-MD⊡MC							
Current consumption	When connecting • When connect controller wit FLV-TCC1 FLV-TCC1 • When connect ing controlle	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- r S, FL-MD⊡MC	4.5 A max.	7.7 A max. 5.5 A max.	12.2 A max. 7.3 A max.	4.6 A max. 3.5 A max.	6.6 A max.	11.2 A max. 6.3 A max.	
Current consumption	When connecting • When connect controller with FLV-TCC1 • When connect ing controlle FL-TCC1P Other than abc	ting the following light or lighting hout an external power supply , FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- r s, FL-MD⊡MC we	4.5 A max. Yes Operating: 0°C to +45	5.5 A max.	7.3 A max.	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption	When connecting • When connect controller wit FLV-TCC1 FLV-TCC1 • When connect ing controller FL-TCC1P	ting the following light or lighting hout an external power supply , FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- r s, FL-MD⊡MC we	4.5 A max. Yes Operating: 0°C to +48 Storage: -20 to +65°C	5.5 A max. 5°C 2 (with no icing or conde	7.3 A max.	3.5 A max. Operating: 0°C to +	4.3 A max.	6.3 A max.	
Current consumption	When connecting • When connect controller with FLV-TCC1 • When connect ing controlle FL-TCC1P Other than abc	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- r's, FL-MD⊡MC we	4.5 A max. Yes Operating: 0°C to +48 Storage: -20 to +65°C Operating:35 to 85%I	5.5 A max. 5°C 2 (with no icing or conde	7.3 A max.	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption	When connecting • When connect controller with FLV-TCC1 • When connecting ing controller FL-TCC1P Other than abcomposition Ambient tempo	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- rs, FL-MD⊡MC ve erature range	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating:35 to 85%Ri Storage: 35 to 85%Ri No corrosive gases	5.5 A max. 5°C C (with no icing or conde RH H (with no condensation	7.3 A max.	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Power-supply Current consumption Built-in FAN	When connecting • When connecting controller with FLV-TCC1 FLV-TCC1 • When connecting ing controlle FL-TCC1P Other than abc Ambient tempe Ambient humid	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 ting the following light or light- rs, FL-MD⊡MC ve erature range	4.5 A max. Yes Operating: 0°C to +45 Storage: -20 to +65°C Operating:35 to 85%R No corrosive gases Oscillation frequency	5.5 A max. 5°C 2 (with no icing or conde RH H (with no condensation 10 to 150 Hz	7.3 A max.	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption Built-in FAN	When connecting • When connecting controller with FLV-TCC1 FLV-TCC1 • When connecting ing controlle FL-TCC1P Other than abc Ambient tempe Ambient humid	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 sting the following light or light- rs, FL-MD⊡MC vve erature range dity range sphere	4.5 A max. Yes Operating: 0°C to +45 Storage: -20 to +65°C Operating:35 to 85%R No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ²	5.5 A max. 5°C 2 (with no icing or conde RH H (with no condensation 10 to 150 Hz m	7.3 A max.	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption Built-in FAN Jsage	When connecting • When connecting controller wit FLV-TCC1 • When conne- ing controlle FL-TCC1P Other than abc Ambient tempo Ambient humie Ambient atmos	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 sting the following light or light- rs, FL-MD⊡MC vve erature range dity range sphere	4.5 A max. Yes Operating: 0°C to +45 Storage: -20 to +65°C Operating:35 to 85%R No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10	5.5 A max. 5°C 2 (with no icing or conde RH H (with no condensation 10 to 150 Hz m	7.3 A max. ensation)	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption Built-in FAN Jsage	When connecting • When connect controller with FLV-TCC1 • When connec- ing controlle FL-TCC1P Other than above Ambient tempor Ambient humid Ambient atmost Vibration toler	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 EX, FL-MD⊡MC serature range dity range sphere	4.5 A max. Yes Operating: 0°C to +45 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up	5.5 A max. 5°C 2 (with no icing or conder H H H (with no condensation 10 to 150 Hz m b/count o and down/front and be	7.3 A max. ensation)	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption	When connecting • When connecting controller wit FLV-TCC1 • When conne- ing controlle FL-TCC1P Other than abc Ambient tempo Ambient humie Ambient atmos	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 EX, FL-MD⊡MC serature range dity range sphere	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating:35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and	5.5 A max. 5°C 2 (with no icing or conder H H H (with no condensation 10 to 150 Hz m b/count o and down/front and be	7.3 A max. ensation)) hind/left and right	3.5 A max. Operating: 0°C to +	4.3 A max. 50°C	6.3 A max.	
Current consumption Built-in FAN Jsage	When connecting • When connecting controller with FLV-TCC1 FLV-TCC1 • When conne- ing controlle FL-TCC1P Other than abc Ambient tempo Ambient humid Ambient toler Vibration toler Shock resistar	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 sting the following light or light- r's, FL-MDEIMC vve erature range dity range sphere ance	4.5 A max. Yes Operating: 0°C to +48 Storage: -20 to +65°C Operating: 35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up and + DC power	5.5 A max. 5°C 2 (with no icing or conde H (with no condensation 10 to 150 Hz m 5/count 2 and down/front and be 92 1 down/front and behind	7.3 A max.	3.5 A max. Operating: 0°C to + Storage: -20 to +65	4.3 A max. 50°C (with no icing or cond	ensation)	
Current consumption Built-in FAN	When connecting • When connect controller with FLV-TCC1 • When connec- ing controlle FL-TCC1P Other than above Ambient tempor Ambient humid Ambient atmost Vibration toler	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 EX, FL-MD⊡MC serature range dity range sphere	4.5 A max. Yes Operating: 0°C to +45 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up Impact force: 150 m/s ² Test direction: up and • DC power Direct infusion: 2kV	5.5 A max. 5°C 2 (with no icing or conder H (with no condensation 10 to 150 Hz m 2/count 2 and down/front and behind 3 down/front and behind , Pulse rising: 5ns, Puls	7.3 A max. ensation) hind/left and right /left and right e width: 50ns, Burst con	3.5 A max. Operating: 0°C to + Storage: -20 to +65	4.3 A max. 50°C °C (with no icing or cond (with no icing or cond 4.3 A max.	6.3 A max. lensation) , Application time: 1 t	
Current onsumption Built-in FAN	When connecting • When connecting controller with FLV-TCC1 FLV-TCC1 • When conne- ing controlle FL-TCC1P Other than abc Ambient tempo Ambient humin Ambient numin Shock resistar Noise immunity	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 sting the following light or light- r's, FL-MDEIMC vve erature range dity range sphere ance	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct influsion: 1kV	5.5 A max. 5°C 2 (with no icing or conder RH H (with no condensation 10 to 150 Hz m 2/count a and down/front and behind 3 4 down/front and behind , Pulse rising: 5ns, Puls , Pulse rising: 5ns, Puls	7.3 A max. ensation))) hind/left and right /left and right e width: 50ns, Burst cor e width: 50ns, Burst cor	3.5 A max. Operating: 0°C to + Storage: -20 to +65	4.3 A max. 50°C (with no icing or cond	6.3 A max. lensation) , Application time: 1 t	
Current onsumption Built-in FAN	When connecting • When connecting controller with FLV-TCC1 FLV-TCC1 • When conne- ing controlle FL-TCC1P Other than abc Ambient tempo Ambient humin Ambient atmost Vibration toler Shock resistar Noise immunity	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 sting the following light or light- r's, FL-MDEIMC vve erature range dity range sphere ance	4.5 A max. Yes Operating: 0°C to +45 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up and • DC power Direct infusion: 2kV I/D line Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm ×	5.5 A max. 5°C 2 (with no icing or conder H (with no condensation 10 to 150 Hz m 2/count 2 and down/front and behind 9 and down/front and behind 9 pulse rising: 5ns, Puls 9 Ω Ω or less grounding r 182.5 mm	7.3 A max. ensation))) hind/left and right /left and right e width: 50ns, Burst cor e width: 50ns, Burst cor	3.5 A max. Operating: 0°C to + Storage: -20 to +65	4.3 A max. 50°C °C (with no icing or cond (with no icing or cond 4.3 A max.	6.3 A max.	
Surrent onsumption Suilt-in FAN Isage invironment	When connecting • When connecting controller with FLV-TCC1 FLV-TCC1 • When conne- ing controlle FL-TCC1P Other than abc Ambient tempo Ambient humid Ambient atmost Vibration toler Shock resistar Noise immunity Grounding Dimensions	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 sting the following light or light- r's, FL-MDEIMC vve erature range dity range sphere ance	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ⁶ Sweep time: 8 minute Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct infusion: 2kV • V/O line Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm ×	5.5 A max. 5°C 2 (with no icing or conder AH H (with no condensation 10 to 150 Hz m b/count and down/front and behind pulse rising: 5ns, Puls pulse rising: 5ns, Pulse rising: 5ns, Puls pulse rising: 5ns, Pulse ris	7.3 A max. ensation) a) hind/left and right /left and right e width: 50ns, Burst cor e width: 50ns, Burst cor e sistance) *3	3.5 A max. Operating: 0°C to + Storage: -20 to +65 ntinuation time: 15ms ntinuation time: 15ms	4.3 A max. 50°C °C (with no icing or cond °C (with no icing or cond (with	6.3 A max. lensation) Application time: 1 r Application time: 1 r	
urrent onsumption uilt-in FAN sage invironment	When connecting • When connect controller with FLV-TCC1 • When connect ing controlle FLV-TCC1 • When connect • Mbient tempe Ambient tempe Ambient tempe Ambient tempe Ambient tempe Shock resistar Noise immunity Grounding Dimensions	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 both and external power supply for light-following light or light-following lig	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency. Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up Impact force: 150 m/x Test direction: up and • DC power Direct infusion: 2kV U/D line Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm × Note Height: Including Approx. 3.4 kg	5.5 A max. 5°C 2 (with no icing or conder H (with no condensation 10 to 150 Hz m 2/count 2 and down/front and behind 9 and down/front and behind 9 pulse rising: 5ns, Puls 9 Ω Ω or less grounding r 182.5 mm	7.3 A max. ensation))) hind/left and right /left and right e width: 50ns, Burst cor e width: 50ns, Burst cor	3.5 A max. Operating: 0°C to + Storage: -20 to +65	4.3 A max. 50°C °C (with no icing or cond (with no icing or cond 4.3 A max.	6.3 A max.	
urrent onsumption uilt-in FAN sage invironment	When connecting • When connecting • When connecting controller with FLV-TCC1 • When connecting ing controlle FLV-TCC1 • When connecting Other than abore Ambient temper Ambient temper Ambient temper Shock resistar Noise immunity Grounding Dimensions Weight Degree of prot	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 both and external power supply for light-following light or light-following lig	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating: 35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up and birect infusion: 2kV • JO line Direct infusion: 2kV • JO ine Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm × Note Height: Including Approx. 3.4 kg IEC60529 IP20	5.5 A max. 5°C 2 (with no icing or conder RH H (with no condensation 10 to 150 Hz m 2/count and down/front and behind pand down/front and behind pulse rising: 5ns, Puls pulse rising: 5ns, Puls pulse rising: 5ns, Puls 0 Ω or less grounding r 182.5 mm g the feet at the base. Approx. 3.6 kg sel plate	7.3 A max. ensation) a) hind/left and right /left and right e width: 50ns, Burst cor e width: 50ns, Burst cor e sistance) *3	3.5 A max. Operating: 0°C to + Storage: -20 to +65 ntinuation time: 15ms ntinuation time: 15ms	4.3 A max. 50°C °C (with no icing or cond °C (with no icing or cond (with	6.3 A max. lensation) Application time: 1 r Application time: 1 r	
Current onsumption Built-in FAN	When connecting • When connect controller with FLV-TCC1 • When connect ing controlle FLV-TCC1 • When connect • Mbient tempe Ambient tempe Ambient tempe Ambient tempe Ambient tempe Shock resistar Noise immunity Grounding Dimensions	ting the following light or lighting hout an external power supply FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 both and external power supply for light-following light or light-following lig	4.5 A max. Yes Operating: 0°C to +44 Storage: -20 to +65°C Operating:35 to 85%I Storage: 35 to 85%I No corrosive gases Oscillation frequency Half amplitude: 0.1 m Acceleration: 15 m/s ² Sweep time: 8 minute Sweep count: 10 Vibration direction: up Impact force: 150 m/s ² Direct infusion: 2kV I/O line Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm × Note Height: Includin Approx. 3.4 kg IEC60529 IP20 Cover: zinc-plated std Side plate: alluminum	5.5 A max. 5°C 2 (with no icing or conder RH H (with no condensation 10 to 150 Hz m 2/count and down/front and behind pand down/front and behind pulse rising: 5ns, Puls pulse rising: 5ns, Puls pulse rising: 5ns, Puls 0 Ω or less grounding r 182.5 mm g the feet at the base. Approx. 3.6 kg sel plate	7.3 A max. ensation)) hind/left and right /left and right e width: 50ns, Burst cor e width: 50ns, Burst cor esistance) *3 Approx. 3.6 kg	3.5 A max. Operating: 0°C to + Storage: -20 to +65 ntinuation time: 15ms ntinuation time: 15ms Approx. 3.4 kg	4.3 A max. 50°C (with no icing or cond (0.75ms, Period: 300ms) (0.75ms, Period: 300ms) (0.75ms, Period: 300ms)	6.3 A max. lensation) Application time: 1 n Application time: 1 n	

*1 According to the CPU performance, FH-2050 series is recommended to use up to two lines in this mode.
 *2 Up to eight cameras can be connected in total including up to four 12 or 20.4 million-pixel cameras.
 *3 Existing third class grounding

Lite Controllers

Sensor Control				0 Series			
Sensor Control	itroller Model		FH-L550	FH-L550-10			
Parallel IO			NPN/PNP (common)				
Memory, Storag	ge		4GB RAM, 4GB ROM				
		Standard	Yes				
		Double Speed Multi-input	Yes				
	Operation Mode	Non-stop adjustment mode	Yes				
		Multi-line random-trigger					
		mode	No				
	Parallel Processin	ıg	Yes				
	Number of Conne	ctable Camera	2	4			
Main Func-	Supported FH-S series camera		All of the FH-S series cameras except FH-SM21R/SC21R				
ions	Camera	FZ-S series camera	All of the FZ-S series cameras are connectable.				
	Camera I/F		OMRON I/F				
		of Captured Images of Logging Images to	Refer to page 31.				
	Sensor Controller		Refer to the Vision System FH/FZ5 Series User's Manual (Cat. No. Z	365).			
	Possible Number		128				
		USB Mouse	Yes (wired USB driver-less type)				
	UI Operations	Touch Panel	Yes (RS-232C/USB connection: FH-MT12)				
	Setup		Create the processing flow using Flow editing.				
	Language		Japanese, English, Simplified Chinese, Traditional Chinese, Korean,	German, French, Spanish, Italian, Vietnamese, Polish			
	Serial Communica		RS-232C × 1				
	Ethernet	Protocol	Non-procedure (TCP/UDP)				
	Communication	I/F	1000BASE-T × 1				
	EtherNet/IP Comm	nunication	Yes (Target/Ethernet port)				
	PROFINET Comm	unication	Yes (Slave/Ethernet port) Conformance class A				
	EtherCAT Commu	inication	No				
External			High-speed input: 1				
Interface	Parallel I/O		Normal speed: 9				
			High-speed output: 4 Normal speed: 23				
	Encoder Interface		None				
	Monitor Interface		DVI-I output (Analog RGB & DVI-D single link) × 1				
	USB I/F		USB2.0 host × 1: BUS Power: Port 5 V/0.5 A				
			USB3.0 × 1: BUS Power: Port 5 V/0.5 A				
	SD Card I/F		SDHC×1				
			POWER: Green ERROR: Red				
	Main		RUN: Green				
Indicator			ACCESS: Yellow				
Lamps	Ethernet		NET RUN: Green LINK/ACT: Yellow				
			SD POWER: Green				
	SD Card		SD BUSY: Yellow				
	EtherCAT		None				
Power-supply v	voltage		20.4 VDC to 26.4 VDC	-			
		an intelligent compact dig-					
	ital camera	g the following light or					
		er without an external					
Current	power supply		2.7 A max.	4.4 A max.			
consumption	FLV-TCC1, FL	_V-TCC4, FLV-TCC3HB . FL-TCC1					
	 When connecting 	g the following light or					
	lighting controll FL-TCC1PS, I						
	Other than above		1.5 A max.	2.0 A max.			
Built-in FAN			No	1			
	Ambient temperat		Operating: 0°C to 55°C				
	Ambient temperat		Storage: -25 to +70°C				
	Ambient humidity		Operating and Storage: 10 to 90%RH (with no condensation)				
	Ambient atmosph	ere	No corrosive gases	tion (00 / 2			
	Vibration tolerand	e	5 to 8.4 Hz with 3.5 mm amplitude, 8.4 to 150 Hz, accelera 100 min each in X, Y, and Z directions (10 sweeps of 10 min each =				
Usage Envi-			Impact force: 150 m/s ²				
ronment	Shock resistance		Test direction: up and down/front and behind/left and right				
			DC power				
	Noise		Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1 min				
	immunity	Fast Transient Burst	I/O line				
			Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1 min				
	Grounding		Survey Continuation time: 15ms/0.75ms, Period: 300ms, Application to Type D grounding (100 Ω or less grounding resistance) *				
	Dimensions		$200 \text{ mm} \times 80 \text{ mm} \times 130 \text{ mm}$				
External	Weight		Approx. 1.5 kg	Approx. 1.5 kg			
Features	Degree of protect	ion	IEC60529 IP20	PP			
	Case materials		PC				
			Instruction Sheet (Japanese and English): 1, Installation Instruction M				
Accessories	5		General Compliance Information and Instructions for EU:1, Member r	egistration sheet: 1,			
			Power source (FH-XCN-L):1 (male)				

* Existing third class grounding

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Maximum Number of Loading Images during Multi-input

Camera	Model	Max. Number of Loading Images during Multi-input *1
Intelligent Compact Digital CMOS Cameras *2	FZ-SQ010F/-SQ050F/-SQ100F/-SQ100N	256
0.3 million pixels CCD/CMOS Cameras	FZ-S/-SC/-SF/SFC/-SH/-SHC/-SP/-SPC FH-SM/-SC	256
0.4 million pixels CMOS Cameras	FH-SMX/-SCX	256
2 million pixels CCD Cameras	FZ-S2M/-SC2M	64
2 million pixels CMOS Cameras	FH-SM02/-SC02	51
4 million pixels CMOS Cameras	FH-SM04/-SC04	32
5 million pixels CCD/CMOS Cameras	FZ-S5M3/-SC5M3/-S5M2 FH-SMX05/-SCX05/-SM05R/-SC05R	25
12 million pixels CMOS Cameras	FH-SM12/-SC12/-SMX12/-SCX12	10
20.4 million pixels CMOS Cameras	FH-SM21R/-SC21R	6

When using two camera cables for connection, the maximum number of loaded images during multi-input is twice the number given in the table. The multi-input function cannot be used when the built-in light of an intelligent compact digital camera is used. Refer to the *Vision System FH/FZ5 Series User's Manual* (Cat. No. Z340) for details. *1 *2

Ratings and Specifications (Cameras)

High-speed Digital CMOS cameras

Model	FH-SM	FH-SC	FH-SM0	2 FH-SC02	FH-SM04	FH-SC04	FH-SM12	FH-SC12	
Image elements	CMOS image el (1/3-inch equiva		CMOS imag (2/3-inch ec	ge elements quivalent)	CMOS image el (1-inch equivale		CMOS image (1.76-inch equ		
Color/Monochrome	Monochrome	Color	Monochrom	ne Color	Monochrome	Color	Monochrome	Color	
Effective pixels	640 (H) × 480 (V)	2040 (H) ×	(V) 2040 (H) × 2048 (V)			4084 (H) × 30	72 (V)	
Imaging area H x V (opposing corner)	4.8×3.6 (6.0 m	m)	11.26 × 5.9	98 (12.76 mm) 11.26 × 11.26 (15.93 mm)		22.5 × 16.9 (28.14 mm)			
Pixel size	7.4 (μ m) $ imes$ 7.4 (μ	μm)	5.5 (μm) × 5	5.5 (µm)	5.5 (μ m) $ imes$ 5.5 (μ	um)	5.5 (μm) × 5.5	(μm)	
Shutter function	Electronic shutter Shutter speeds 20 µs to 100 ms	can be set from	Electronic s Shutter spe	shutter; eds can be set from 2	25 μs to 100 ms.		Electronic shu Shutter speed 60 µs to 100 n	s can be set from	
Partial function	1 to 480 lines	2 to 480 lines	1 to 1088 lii	nes 2 to 1088 lines	1 to 2048 lines	2 to 2048 lines	4 to 3072 lines (4-line increme		
Frame rate (Image Acquisition Time *1)	308 fps (3.3 ms)	219 fps (4.6	6 ms) *2	118 fps (8.5 ms	*2	38.9 fps (25.7	ms) *2	
Lens mounting	C mount						M42 mount		
Field of vision, installation distance	Ŭ	Ũ		n and installation dista					
Ambient temperature range	Operating: 0 to	40 °C, Storage:	-25 to 65 °C (v	with no icing or conde	nsation)				
Ambient humidity range	Operating and s	storage: 35% to	85% (with no c	condensation)					
Weight	Approx.105 g		Approx.110	g			Approx.320 g		
Accessories	Instruction man	ual							
Model	FH-SMX	FI	I-SCX	FH-SMX05	FH-SCX05	FH-S	FH-SMX12 FH-SCX12		
Image elements	CMOS image ele	ements (1/2.9-ind	h equivalent)	CMOS image elemen	IOS image elements (2/3-inch equivalent)				
Color/Monochrome	Monochrome	Color					Monochrome Color		
Effective pixels	720 (H) × 540 (V)			2448 (H) × 2048 (V) 4092 (H)			H) × 3000 (V)		
	4.97 × 3.73 (6.21 mm)								
(opposing corner)		,		8.45 × 7.07 (11.01 m	m)	14.12 × 10).35 (17.5 mm)		
Imaging area H x V (opposing corner) Pixel size	4.97 × 3.73 (6.2 6.9 (μm) × 6.9 (μ	1 mm) μm)		8.45 × 7.07 (11.01 m 3.45 (μm) × 3.45 (μm			. ,		
(opposing corner) Pixel size	4.97 × 3.73 (6.2	μm) er;		3.45 (μm) × 3.45 (μm		Electronic	shutter;	om 15 μs to 100 m	
(opposing corner)	4.97×3.73 (6.2 6.9 (µm) × 6.9 (µm) × 6.9 (µm)	μm) er; can be set from	1 μs to 100 m	3.45 (μm) × 3.45 (μm)	Electronic Shutter spe	shutter;	om 15 µs to 100 m ements)	
(opposing corner) Pixel size Shutter function	$\begin{array}{c} 4.97 \times 3.73 \ (6.2 \\ 6.9 \ (\mu m) \times 6.9 \ (\mu m) \times 6.9 \ (\mu m) \\ \text{Electronic shutt} \\ \text{Shutter speeds} \end{array}$	u1 mm) μm) er; can be set from I-line increment	1 μs to 100 m s)	3.45 (μm) × 3.45 (μm s.)	Electronic Shutter spe 4 to 3000	shutter; eds can be set fr	•	
(opposing corner) Pixel size Shutter function Partial function Frame rate (Image Acquisition Time *1)	4.97 × 3.73 (6.2 6.9 (μm) × 6.9 (μ Electronic shutter Shutter speeds 4 to 540 lines (4	u1 mm) μm) er; can be set from I-line increment	1 μs to 100 m s)	3.45 (μm) × 3.45 (μm s. 4 to 2048 lines (4-line)	Electronic Shutter spe 4 to 3000	shutter; eeds can be set fr lines (4-line incr	•	
(opposing corner) Pixel size Shutter function Partial function Frame rate (Image Acquisition Time *1)	4.97×3.73 (6.2 6.9 (µm) × 6.9 (j Electronic shutter Shutter speeds 4 to 540 lines (4 523.6 fps (1.9 m C mount	i1 mm) μm) er; can be set from I-line increment ns)	1 μs to 100 m s)	3.45 (μm) × 3.45 (μm s. 4 to 2048 lines (4-line) e increments)	Electronic Shutter spe 4 to 3000	shutter; eeds can be set fr lines (4-line incr	•	
(opposing corner) Pixel size Shutter function Partial function Frame rate (Image Acquisition Time *1) Lens mounting Field of vision,	4.97×3.73 (6.2 6.9 (µm) × 6.9 (j Electronic shutter Shutter speeds 4 to 540 lines (4 523.6 fps (1.9 m C mount	i1 mm) μm) er; can be set from I-line increment hs) according to th 50 °C, 65 °C	1 μs to 100 m s) e field of visior	3.45 (μm) × 3.45 (μm s. 4 to 2048 lines (4-line 97.2 fps (10.3 ms) *2) e increments) ince	Electronic Shutter spe 4 to 3000	shutter; eeds can be set fr lines (4-line incr	•	
(opposing corner) Pixel size Shutter function Partial function Frame rate (Image Acquisition Time *1) Lens mounting Field of vision, installation distance Ambient temperature	4.97×3.73 (6.2 6.9 (µm) × 6.9 (J Electronic shutter Shutter speeds 4 to 540 lines (4 523.6 fps (1.9 m C mount Selecting a lens Operating: 0 to Storage: -25 to	i1 mm) μm) er; can be set from I-line increment: hs) according to th 50 °C, 65 °C condensation)	1 μs to 100 m s) e field of visior	3.45 (μm) × 3.45 (μm s. 4 to 2048 lines (4-line 97.2 fps (10.3 ms) *2 n and installation dista Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or cond) e increments) ince	Electronic Shutter spe 4 to 3000	shutter; eeds can be set fr lines (4-line incr		
(opposing corner) Pixel size Shutter function Partial function Frame rate (Image Acquisition Time *1) Lens mounting Field of vision, installation distance Ambient temperature range	4.97×3.73 (6.2 6.9 (μ m) \times 6.9 (J Electronic shutter Shutter speeds 4 to 540 lines (4 523.6 fps (1.9 m C mount Selecting a lens Operating: 0 to Storage: -25 to (with no icing or	i1 mm) μm) er; can be set from I-line increment: hs) according to th 50 °C, 65 °C condensation)	1 μs to 100 m s) e field of vision 85% (with no c	3.45 (μm) × 3.45 (μm s. 4 to 2048 lines (4-line 97.2 fps (10.3 ms) *2 n and installation dista Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or cond) e increments) ince	Electronic Shutter spe 4 to 3000	shutter; eeds can be set fr lines (4-line incr		
(opposing corner) Pixel size Shutter function Partial function Frame rate (Image Acquisition Time *1) Lens mounting Field of vision, installation distance Ambient temperature range	4.97×3.73 (6.2 6.9 (µm) × 6.9 (J Electronic shutter Shutter speeds 4 to 540 lines (4 523.6 fps (1.9 m C mount Selecting a lens Operating: 0 to Storage: -25 to (with no icing or Operating and s Approx.48 g	(1 mm) μ m) er; can be set from I-line increment: hs) according to th 50 °C, 65 °C condensation) storage: 35% to	1 μs to 100 m s) e field of visior 85% (with no c	3.45 (μm) × 3.45 (μm s. 4 to 2048 lines (4-line 97.2 fps (10.3 ms) *2 n and installation dista Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or cond condensation)) e increments) unce , ensation)	Electronic Shutter spe 4 to 3000	shutter; eeds can be set fr lines (4-line incr		

*1 The image acquisition time does not include the image conversion processing time of the sensor controller.
 *2 Frame rate in high speed mode when the camera is connected using two camera cables.

Digital CMOS Cameras

Model	FH-SM05R	FH-SC05R	FH-SM21R	FH-SC21R	FZ-S5M3	FZ-SC5M3
Image Elements	CMOS image elements	(1/2.5-inch equivalent)	CMOS image elemen	ts (1-inch equivalent)	CMOS image elemen	ts (2/3-inch equivalent)
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color
Effective Pixels	2592 (H) × 1944 (V)		5544 (H) × 3692 (V)		2448 (H) × 2048 (V)	
Imaging area $H \times V$ (opposing corner)	5.70 × 4.28 (7.13 mm)		13.31 × 8.86 (16.00 m	nm)	8.45 × 7.07 (11.01 m	m)
Pixel Size	2.2 (μm) × 2.2 (μm)		2.4 (μm) × 2.4 (μm)		3.45 (μm) × 3.45 (μm)
Scan Type	Progressive					
Shutter Method	Rolling shutter (Globa	I reset mode supported)		Global shutter	
Shutter Function	Electronic shutter; Shutter speeds can be set from 500 to 10000 ms in multiples of 50 μs		Electronic shutter; Shutter speeds can be set from 50 μs to 100 ms.		Electronic shutter; Shutter speeds can be set from 20 μs to 100 ms.	
Partial function	4 to 1944 lines (2-line	increments)	1848 to 3692 lines		4 to 2048 lines	
Frame rate (Image Acquisition Time *)	14 fps (71.7ms)		23.5 fps (42.6ms)		25.6 fps (38.2ms)	
Lens Mounting	C mount				- <u>-</u>	
Field of vision, Installation distance	Selecting a lens acco	rding to the field of visio	on and installation dista	nce		
Ambient temperature range	Operating: 0 to +40°C Storage: -30 to 65°C (with no icing or condensation)		Operating: 0 to +40°C Storage: -20 to 65°C (with no icing or condensation)		Operating: 0 to +40°C Storage: -30 to 65°C (with no icing or condensation)	
Ambient humidity range	Operating: 35 to 85%	RH, Storage: 35 to 85%	RH (with no condensa	tion)		
Weight	Approx. 52 g		Approx. 85 g			
Accessories	Instruction Sheet		Instruction Sheet, General Compliance Inform		mation and Instructions	for EU

* The image acquisition time does not include the image conversion processing time of the sensor controller.

Digital CCD Cameras

Model	FZ-S	FZ-SC	FZ-S2M	FZ-SC2M	
Image elements				ll pixels, .8-inch equivalent)	
Color/Monochrome	Monochrome Color		Monochrome	Color	
Effective pixels	640 (H) × 480 (V)		1600 (H) × 1200 (V)		
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0mm)		7.1 × 5.4 (8.9mm)	7.1 × 5.4 (8.9mm)	
Pixel size	7.4 (µm) \times 7.4 (µm)		4.4 (μ m) $ imes$ 4.4 (μ m)		
Shutter function	Electronic shutter; select shutter speeds from 20 μs to 100 ms				
Partial function	12 to 480 lines		12 to 1200 lines	12 to 1200 lines	
Frame rate (Image Acquisition Time *)	80 fps (12.5 ms)		30 fps (33.3 ms)	30 fps (33.3 ms)	
Lens mounting	C mount				
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance				
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C (with no icing or condensation)		Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)		
Ambient humidity range	Operating and storage: 35% to a	35% (with no condensation)			
Weight	Approx. 55 g		Approx. 76 g		
Accessories	Instruction manual	Instruction manual			

* The image acquisition time does not include the image conversion processing time of the sensor controller.

Small CCD Digital Cameras

Model	FZ-SF	FZ-SFC	FZ-SP	FZ-SPC		
Image elements	Interline transfer reading all pixel	erline transfer reading all pixels, CCD image elements (1/3-inch equivalent)				
Color/Monochrome	Monochrome	Monochrome Color Monochrome Color		Color		
Effective pixels	40 (H) × 480 (V)					
Imaging area H x V (opposing corner)	.8 × 3.6 (6.0mm)					
Pixel size	7.4 (μm) × 7.4 (μm)	7.4 (μm) × 7.4 (μm)				
Shutter function	Electronic shutter; select shutter	lectronic shutter; select shutter speeds from 20 μm to 100 ms				
Partial function	12 to 480 lines	2 to 480 lines				
Frame rate (Image Acquisition Time *)	80 fps (12.5ms)					
Lens mounting	Special mount (M10.5 P0.5)					
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance					
Ambient temperature range	Operating: 0 to 50 °C (camera amp) 0 to 45 °C (camera head) Storage: -25 to 65 °C (with no icing or condensation)					
Ambient humidity range	Operating and storage: 35% to 8	Operating and storage: 35% to 85% (with no condensation)				
Weight	Approx. 150 g					
Accessories	Instruction manual, installation bracket, Four mounting brackets (M2)					

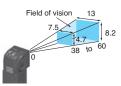
The image acquisition time does not include the image conversion processing time of the sensor controller.

Intelligent Compact Digital CMOS Cameras

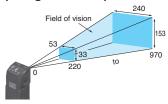
Model	FZ-SQ010F	FZ-SQ050F	FZ-SQ100F	FZ-SQ100N		
Image elements	CMOS color image elements	(1/3-inch equivalent)				
Color/Monochrome	Color					
Effective pixels	752 (H) × 480 (V)	752 (H) × 480 (V)				
Imaging area H x V (opposing corner)	4.51 × 2.88 (5.35mm)					
Pixel size	6.0 (μm) × 6.0 (μm)					
Shutter function	1/250 to 1/32,258	/250 to 1/32,258				
Partial function	8 to 480 lines					
Frame rate (Image Acquisition Time *1)	60 fps (16.7 ms)					
Field of vision	7.5×4.7 to 13×8.2 mm	13×8.2 to 53×33 mm	53×33 to 240×153 mm	29×18 to 300×191 mm		
Installation distance	38 to 60 mm	56 to 215 mm	220 to 970 mm	32 to 380 mm		
LED class *2	Risk Group2					
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C					
Ambient humidity range	Operating and storage: 35%	Operating and storage: 35% to 85% (with no condensation)				
Weight	Approx. 150 g Approx. 140 g					
Accessories	Mounting bracket (FQ-XL), polarizing filter attachment (FQ-XF1), instruction manual and warning label					

The image acquisition time does not include the image conversion processing time of the sensor controller. Applicable standards: IEC62471-2 *1 *2

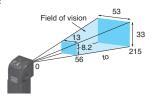
• Narrow View FZ-SQ010F



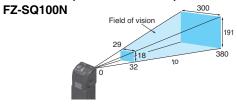
• Wide View (Long-distance) FZ-SQ100F



Standard FZ-SQ050F



• Wide View (Short-distance)



Ratings and Specifications (Cable, Monitor)

Camera Cables

Model	FZ-VS3 (2 m)	FZ-VSB3 (2 m)	FZ-VSL3 (2 m)	FZ-VSLB3 (2 m)
Туре	Standard	Bend resistant	Right-angle	Bend resistant Right-angle
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times			
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)			
Ambient atmosphere	No corrosive gases			
Material	Cable sheath, connector: PVC			
Minimum bending radius	69mm	69mm	69mm	69mm
Weight	Approx. 170 g	Approx. 180 g	Approx. 170 g	Approx. 180 g

Cable Extension Unit

Model	FZ-VSJ
Power supply voltage *1	11.5 to 13.5 VDC
Current consumption *2	1.5 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 240 g
Accessories	Instruction Sheet and 4 mounting screws

*1 A 12-VDC power supply must be provided to the Cable Extension Unit when connecting the Intelligent Compact Camera, or the Lighting Controller.

*2 The current consumption shows when connecting the Cable Extension Unit to an external power supply.

Touch Panel Monitor

Long-distance Camera Cables

Model	FZ-VS4 (15 m)	FZ-VSL4 (15 m)	
Туре	Standard	Right-angle	
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times		
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)		
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)		
Ambient atmosphere	No corrosive gases		
Material	Cable sheath, connector: PVC		
Minimum bending radius	linimum bending radius 78 mm		
Weight	Approx. 1400 g		

Encoder Cable

Model	FH-VR
Vibration resistiveness	10 to 150 Hz single amplitude 0.1 mm 3 directions, 8 strokes, 10 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -10 to 60 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable Jacket: Heat, oil and flame resistant PVC Connector: polycarbonate resin
Minimum bending radius	65 mm
Weight	Approx. 104 g

Model		FH-MT12
	Display area	12.1 inch
	Resolution	1024 (V) × 768 (H)
	Number of color	16,700,000 colors (8 bit/color)
	Brightness	500cd/m ² (Typ)
Major Function	Contrast Ratio	600:1 (Typ)
	Viewing angle	Left and right: each 80°, upward: 80°, downward: 60°
	Backlight Unit	LED, edge-light
	Backlight lifetime	About 100,000hour
	Touch panel	4wire resistive touch screen
	Video input	analog RGB
External interface	Tauch neural simul	USB
	Touch panel signal	RS-232C
	Power supply voltage	24 VDC (21.6 to 26.4 VDC)
Ratings	Current consumption	0.5A
natings	Insulation resistance	Between DC power supply and Touch Panel Monitor FG: 20 M Ω or higher (rated volt age 250 V)
	Ambient temperature range	Operating: 0 to 50°C, Storage: -20 to +65°C (with no icing or condensation)
	Ambient humidity range	Operating and Storage: 20 to 90 %RH (with no icing or condensation)
Operating	Ambient environment	No corrosive gas
environment	Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm (Max. acceleration 15 m/s ²) 10 times for 8 minutes for each three direction
	Degree of protection	Panel mounting: IP65 on the front
Operation		Touch pen
	Mounting	Panel mounting, VESA mounting
Structure	Weight	Approx.2.6 kg
	Material	Front panel: PC/PBT, Front Sheet: PET, Rear case: SUS

Monitor Cables

Model	FH-VMDA (2 m)	FH-VUAB (2 m)	XW2Z-200PP-1 (2 m)	
Cable type	DVI-Analog Conversion Cable	USB Cable	RS-232C Cable	
Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm, 10 times for 8 minutes for each three direction			
Ambient Temperature	Operating Condition: 0 to 50°C, Storage C	Dperating Condition: 0 to 50°C, Storage Condition: -10 to 60°C (with no icing or condensation)		
Ambient Humidity	Operating Condition: 35 to 85%RH, Storage Condition: 35 to 85%RH (with no icing or condensation)			
Ambient environment	No corrosive gases			
Material	Cable outer sheath, Connector: PVC Connector: ABS/Ni Plating			
Minimum bend radius	36 mm	25 mm	59 mm	
Weight	Approx.220 g	Approx.75 g	Approx.162 g	

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LCD Monitor

Model	FZ-M08
Size	8.4 inches
Туре	Liquid crystal color TFT
Resolution	1,024 × 768 dots
Input signal	Analog RGB video input, 1 channel
Power supply voltage	21.6 to 26.4 VDC
Current consumption	Approx. 0.7 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no con- densation)
Weight	Approx. 1.2 kg
Accessories	Instruction Sheet and 4 mounting brackets

EtherCAT Communications Specifications

Item		Specifications
Communications standard		IEC61158 Type 12
Physical layer		100 BASE-TX (IEEE802.3)
Modulation		Base band
Baud rate		100 Mbps
Topology		Depends on the specifications of the EtherCAT master.
Transmission Media		Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)
Transmission Distance		Distance between nodes: 100 m or less
Node address setting		00 to 99
External connection terminals	6	RJ45 \times 2 (shielded) IN: EtherCAT input data, OUT: EtherCAT output data
Orand/marsing DDO data sizes	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *
Send/receive PDO data sizes	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *
Mailhay data aire	Input	512 bytes
Mailbox data size	Output	512 bytes
Mailbox	•	Emergency messages, SDO requests, and SDO information
Refreshing methods		I/O-synchronized refreshing (DC)

* This depends on the upper limit of the master.

Version Information

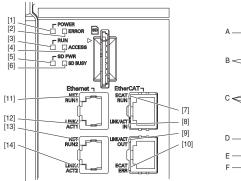
FH Series and Programming Devices Use the latest version of Sysmac Studio Standard Edition/Vision Edition.

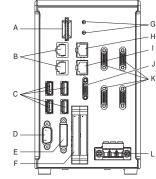
FH Series	Version of FH Series	Corresponding version of Sysmac Studio Standard Edition/Vision Edition
FH-5550 (-□) FH-5050 (-□) FH-2050 (-□)	Version 6.40	Supported by version 1.43* or higher.
	Version 6.31	Supported by version 1.30 or higher.
	Version 6.21	Supported by version 1.26 or higher.
	Version 6.11	Supported by version 1.25 or higher.
	Version 5.72	Supported by version 1.18 or higher.
	Version 5.71	Supported by version 1.18 or higher.
	Version 5.60	Supported by version 1.15 or higher.
	Version 5.50	Supported by version 1.14.89 or higher.
	Version 5.30	Supported by version 1.10.80 or higher.
	Version 5.20	Supported by version 1.10 or higher.
	Version 5.10	Supported by version 1.07.43 or higher.
	Version 5.00	Supported by version 1.07 or higher. Not supported by version 1.06 or lower.

* Sysmac Studio Ver.1.42 will be supported soon.

Components and Functions

Sensor Controllers High-speed, Large-capacity Controller Standard Controller (4-camera type)





	Name	Description
[1]	POWER LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD POWER LED	Blinks while power is supplied to the SD memory card and the card is usable.
[6]	SD BUSY LED	Blinks while the SD memory card is accessed.
[7]	EtherCAT RUN LED	Lit while EtherCAT communications are usable.
[8]	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[9]	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[10]	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.
[11]	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.
[12]	EtherNet LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.
[13]	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.
[14]	EtherNet LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.

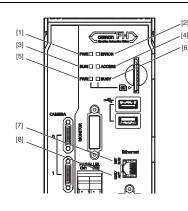
	Name	Description					
А	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.					
		Connect an EtherNet device.					
		FH-2050 Series/FH-5⊟50 Series					
В	EtherNet connector	Upper port: Ethernet port Lower port: Ethernet port, EtherNet/IP port, and PROFINET port are sharing use.					
с	USB connector	Connect a USB device. Do not plug or unplug it during measurement operation. Otherwise measurement time may be affected or data may be destroyed.					
D	RS-232C connector	Connect an external device such as a programmable controller.					
E	DVI-I connector	Connect a monitor.					
F	I/O connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.					
G	EtherCAT address setup volume	Used to set a node address (00 to 99) as an EtherCAT communication device.					
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.					
I	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.					
J	Encoder connector	Connect an encoder.					
К	Camera connector	Connect cameras.					
L	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground line. Be sure to ground the controller alone.					

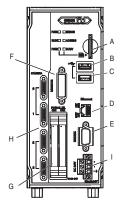
* Use the attachment power terminal connector (male) of FH-XCN series.

For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual (Z366).

Lite Controllers

(4-camera type)





	LED name	Description
[1]	PWR LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD PWR LED	Lit while power is supplied to the SD memory card and the card is usable.
[6]	SD BUSY LED	Lit when access to the SD memory card.
[7]	Ethernet NET RUN LED	Lit while Ethernet communications are usable.
[8]	Ethernet LINK/ACT LED	Blinks when connected with an Ethernet device, and blinks while performing communications.

	Connector name	Description
Α	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.
В	USB 2.0 connector	Connects to USB 2.0. Do not insert or remove during loading or writing of measurement or data. The measurement time can be longer or data can be damaged.
с	USB 3.0 connector	Connects to USB 3.0. Do not insert or remove during loading or writing of measurement or data. The measurement time can be longer or data can be damaged. USB 3.0 has a high ability to supply the bus power. Use the Sensor Controller by combining USB 3.0, faster transport can be realized.
D	Ethernet connector	Connect an Ethernet device. Ethernet port, EtherNet/IP port, and PROFINET port are sharing use.
E	RS-232C connector	Connect an external device such as a programmable controller.
F	DVI-I connector	Connect a monitor.
G	Parallel connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor.
н	Camera connector	Connect a camera.
I	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground line. Be sure to ground the FH Sensor Controller alone.

* Use the attachment power terminal connector (male) of FH-XCN-L series. For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual(Z366).

Processing Items

Group	Icon Processing Item		Corresponding Page in the Group Catalog		lcon		Processing Item	Corresponding Page in the Catalog	
	à	Search	Used to identify the shapes and calculate the position of measurement objects.			1	Glue Bead Inspection	You can inspect coating of a specified col- or for gaps or runoffs along the coating path.	
	dos	Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.		Measurement			Performs learning with "non-defective" prod- uct images and detects the difference be-	
	***	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.			F	AI FineMatching *4	tween the input image and the non-defective image. Allows for variations in non-defective products and detects only defects.	
	-	ECM Search	Used to search the similar part of model form input image. Detect the evaluation value and position.			P	Camera Image Input FH	To input images from cameras. And set up the conditions to input images from camer- as. (For FH Sensor Controllers only)	
	-	EC Circle Search	Extract circles using "round " shape infor- mation and get position, radius and quan- tity in high preciseness.			New York	Camera Image Input HDR	Create high-dynamic range images by ac- quiring several images with different con- ditions.	P10
		Shape Search II	Used to search the similar part of model from input image regardless of environ- mental changes. Detect the evaluation value and position.			Lite	Camera Image Input HDRLite Photometric	HDR function for FZ-SQ Intelligent Com- pact Cameras. Capture images under different illumina-	•
			Robust detection of positions is possible at			HE I	Stereo Image	tion directions using a photometric stereo light.	
	La L	Shape Search III	high-speed and with high precision incor- porating environmental fluctuations, such as differences in individual shapes of the workpieces, pose fluctuations, noise su- perimposition and shielding.	P12	Input Image	M	Camera Switch	To switch the cameras used for measure- ment. Not input images from cameras again.	
-	-	EC Corner	This processing item measures a corner position (corner) of a workpiece.				Measurement Image Switching	To switch the images used for measure- ment. Not input images from camera again.	
		Ec Cross	The center position of a crosshair shape is measured using the lines created by the edge information on each side of the crosshair.			뼺뼺	Multi-trigger Imaging	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measure- ment for each image. Insert the Multi-trig- ger Imaging to the top of the flow.	P10
	<i>b</i>	Classification	Used when various kinds of products on the assembly line need to be sorted and identified. Measure position of measurement ob-				Multi-trigger Imaging Task	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measure- ment for each image. Insert this process-	
		Edge Position	jects according to the color change in measurement area. Detect edges by color change in measure- ment area. Used for calculating number of				Position	ing item to the top of the processing which requires imaging for multiple times. Used when positions are differed. Correct	
		Scan Edge	pins of IC and connectors. Measure peak/bottom edge position of workpieces according to the color change	P12		1	Compensation	measurement is performed by correcting position of input images. Used for processing images input from	
-	#	Position	in separated measurement area. Measure max/min/average width of work-	1.12			Filtering	cameras in order to make them easier to be measured.	
	₫	Scan Edge Width	pieces according to the color change in separated measurement area.				Background Suppression	To enhance contrast of images by extract- ing color in specified brightness. Track brightness change of entire	
	Q	Circular Scan Edge Position	Measure center axis, diameter and radius of circular workpieces.	P12		F	Brightness Correct Filter	screen and remove gradual brightness change such as uneven brightness.	
Measurement	Q	Circular Scan Edge Width	Measure center axis, width and thickness of ring workpieces.				Color Gray Filter	Color image is converted into monochrome images to emphasize specific color.	
		Intersection	Calculate approximate lines from the edge information on two sides of a square work- piece to measure the angle formed at the				Extract Color Filter	Convert color image to color extracted im- age or binary image.	
	8	Color Data	intersection of the two lines. Used for detecting presence and mixed varieties of products by using color aver-		Compensate image	4	Anti Color Shading	To remove the irregular color/pattern by uniformizing max.2 specified colors. Remove the background pattern of	
-			age and deviation. Used to measure area, center of gravity of			R.	Stripes Removal Filter II	vertical, horizontal and diagonal stripes.	
		Gravity and Area	workpices by extracting the color to be measured. Used to measure number, area and gravi-			ABC	Polar Transformation	Rectify the image by polar transformation. Useful for OCR or pattern inspection print- ed on circle.	
	E	Labeling	ty of workpieces by extracting registered color.			4	Trapezoidal Correction	Rectify the trapezoidal deformed image.	
		Label Data	Selecting one region of extracted Label- ing, and get that measurement. Area and Gravity position can be got and judged.				Machine Simulator	How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.	
-	M	Defect	Used for appearance measurement of plain-color measurement objects such as defects, stains and burrs.			1	Image Subtraction	The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.	
	×	Precise Defect	Check the defect on the object. Parame- ters for extraction defect can be set pre- cisely.				Advanced filter	Process the images acquired from camer- as in order to make them easier to mea- sure. This processing item consolidates	
		Fine Matching	Difference can be detected by overlapping and comparing (matching) registered fine images with input images.					existing image conversion filtering into one processing item and adds extra functions. Combine multiple image to create one big	
	AB	Character Inspect	Recognize character according correlation search with model image registered in [Model Dictionary].	P15			Panorama Al Scratch	image. Extracts defects in the set measurement	P4
	Date 08-02-1	Date Verification	Reading character string is verified with in- ternal date.		Support measurement		Detect Filter *5	area. Advanced arithmetic processing can be	
	A	Model Dictionary	Register character pattern as dictionary. The pattern is used in [Character Inspec- tion].				Unit Macro	easily incorporated into workflow as Unit Macro processing items. This function is convenient when the user	
		2DCode II *1	Recognize 2D code and display where the code quality is poor.	P15		- 	Unit Calculation Macro	wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.	
ł		2DCode *2	Recognize 2D code and display where the code quality is poor. Recognize barcode, verify and output de-				Calculation	Used when using the judge results and measured values of ProcItem which are registered in processing units.	
		Barcode *3	coded characters. Recognize and read characters in	D15		+++++++++++++++++++++++++++++++++++++++	Line Regression	Used for calculating regression line from plural measurement coodinate.	
ł		OCR OCR User	images as character information.	P15	-	ţ.	Circle Regression	Used for calculating regression circle from plural measurement coordinate.	
-		Dictionary Circle Angle	Register dictionary data to use for OCR. Used for calculating angle of inclination of				Precise Calibration	Used for calibration corresponding to trape- zoidal distortion and lens distortion.	

Group	lcon				Corresponding Page in the Group Catalog			Processing Item	Corresponding Page in the Catalog
	User	User Data	Used for setting of the data that can be used as common constants and variables in scene group data.				Conditional Branch	Used where more than two kinds of prod- ucts on the production line need to detect- ed separately.	
	4	Set Unit Data	Used to change the ProcItem data (setting parameters, etc.) that has been set up in a scene.			₿ `	End	This ProcItem must be set up as the last processing unit of a branch.	
	B -	Get Unit Data	Used to get one data (measured results, setting parameters, etc.) of ProcItem that has been set up in a scene.		-	100 VG0	DI Branch	Same as ProcItem "Branch". But you can change the targets of conditional branch- ing via external inputs.	
		Set Unit Figure	Used for re-setting the figure data (model, measurement area) registered in an unit.		Branch		Control Flow Normal	Set the measurement flow processing into the wait state in which the specific no-pro- tocol command can be executed.	
	*	Get Unit Figure	Used for get the figure data (model, mea- surement area) registered in an unit.				Control Flow PLC Link	Set the measurement flow processing into the wait state in which the specific PLC Link command can be executed.	
		Trend Monitor	Used for displaying the information about results on the monitor, facilitating to avoid NG and analyze causes.				Control Flow Parallel	Set the measurement flow processing into the wait state in which the specific parallel command can be executed.	
	25	Image Logging	Used for saving the measurement images to the memory and USB memory.				Control Flow Fieldbus	Set the measurement flow processing into the wait state in which the specific Field-	
	ⓐ→	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.					bus command can be executed. Easily branch to multiple destinations.	
	E \$	Data Logging	Used for saving the measurement data to the memory and USB memory.			h	Conditional Execution (If)	The measurement flow is divided accord- ing to the comparison result obtained us-	
	N	Elapsed Time	Used for calculating the elapsed time since the measurement trigger input. Processing is stopped only at the set time. The					ing the set expressions and conditions. Insert between the Conditional Execution (If) processing item and End If processing	
	2	Wait Focus	standby time is set by the unit of [ms]. Focus setting is supported.			5	Conditional Execution (Else)	item. The measurement flow is divided ac- cording to the comparison result obtained using the set expressions and conditions.	
	2	Iris	Focus and aperture setting is supported.			5	Loop	The set processes are repeated until the loop count reaches the specified number,	
	- 000	Parallelize	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed at the top of			Ç 7	Loop Suspension	and then the next process starts. Insert between the Loop processing item and End Loop processing item. Used to stop the loop before the loop count reach- es the specified number.	
	-		processing to be performed in parallel. A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time.			ት	Select Execution (Select)	Used to set conditions. The measurement flow is divided according to the compari- son result obtained using the conditions given by expressions.	
		Parallelize Task	This processing item is placed immediate- ly before processing to be performed in parallel between Parallelize and Paral- lelize End.			ŝ	Select Execution (Case)	Used to make a judgment. The measure- ment flow is divided according to the com- parison result obtained using the conditions given by expressions.	
upport easure- ent		Statistics	Used when you need to calculate an aver- age of multiple measurement results. Calibration data and distortion compensa-		Output result	21 22 33 45 4	Result Output (I/	Output data to the external devices such as a programmable controller or a PC via PLC Link, Parallel interface, Fieldbus in-	
ient	L +	Reference Calib Data	tion data held under other processing items can be referenced.			I	O)	terface (EtherCAT, EtherNet/IP (other than message communication), PROF- INET).	
		Position Data Calculation	The specified position angle is calculated from the measured positions.				Result Output (Message)	Output data to the external devices such as a programmable controller or a PC with	
		Stage Data Robot Data	Sets and stores data related to stages. Sets and stores data related to robots.	P13				non-procedure mode via the serial inter- face or EtherNet/IP (message communi- cation). This processing item allows you to save the logging data as a ".csv" file into	
		Vision Master Calibration	This processing item automatically calcu- lates the entire axis movement amount of the control equipment necessary for cali-				Data Output	the Sensor Controller as well. Used when you need to output data to the external devices such as PLC or PC via	
		PLC Master	bration. Calibration data is created using a com-				Parallel Data	serial ports. Used when you need to output data to the external devices such as PLC or PC via	
	÷⊞ î ĵ	Calibration Convert Position Data	munication command from PLC. The position angle after the specified axis movement is calculated.				Output Parallel	parallel ports. Used when you need to output judgement	
		Movement Single Position	The axis movement that is required to match the measured position angle to the			<u>ek</u>	Judgement Output	results to the external devices such as PLC or PC via parallel ports. Outputs data to an external device, such	
		Movement Multi	reference position angle is calculated. The axis movements that are required to match the measured position angles to the				Fieldbus Data Output	as a Programmable Controller, through a fieldbus interface.	
	14	Points	corresponding reference position angles are calculated. Obtains position/angle information by re-		_	OK	Result Display Display Image	Used for displaying the texts or the figures in the camera image.	
	+	Detection Point	ferring to the coordinate values measured with the Measurement Processing Unit.			NG	File Display Last NG	Display selected image file. Display the last NG images.	
	+4	Manual Position Setting	Used to change the measurement coordi- nates X and Y of the measurement pro- cessing unit.		Display result		Image Conveyor Panorama	Display images of the tracking area as a	
		Camera Calibration	By setting the camera calibration, the measurement result can be converted and output as actual dimensions.				Display Display Image	panoramic image. Processing item to retain images, includ-	
	#)	Data Save	The set data can be saved in the controller main unit or as scene data. The data is held even after the FH/FZ power is turned off.		*2 2D Code *3 Bar Code	es that o es that o es that	can be read : D can be read : J	ing measurement results. ata Matrix (ECC200) ata Matrix (ECC200), QR Code AN/EAN/UPC (including add-on co (including add-on co	
	1	Conveyor Calibration	Conveyor Calibration is used to calibrate camera, conveyor, and robots for convey- or tracking application.		GS1-128 Pharmad	3, GS1 I code	DataBar (ŔSS-	(Interleaved 2 of 5), Code 93, Co 14 / RSS Limited / RSS Expanded	ł),
		Scene	The specified scene is copied to the cur- rent scene.		*5 Available	e on the	FH-5050-seri	es Controller (version 6.40 or later es Controller (version 6.40 or later etect Al Software Installer is requir	ý.
	Q	System Information	Obtain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller.		Οριιοπαι	11-010	In Outlin D	ologi Al Contware installer is lequi	cu.

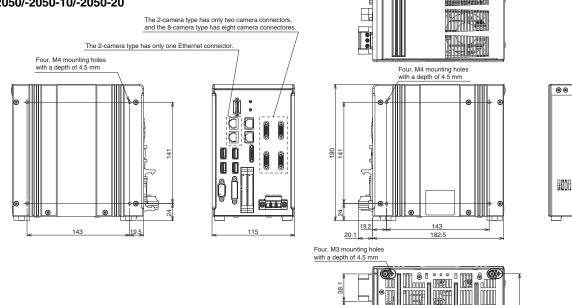
(Unit: mm)

Dimensions

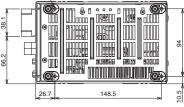
Sensor Controllers

High-speed, Large-capacity Controllers/Standard Controllers

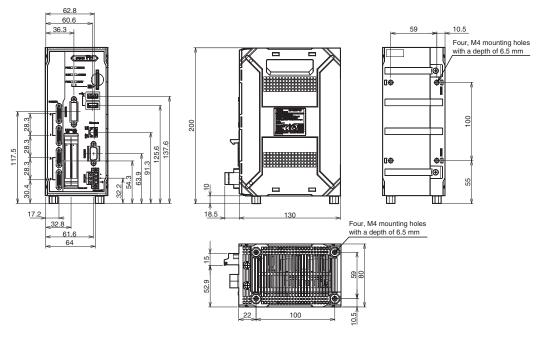
FH-5550/-5550-10/-5550-20 FH-5050/-5050-10/-5050-20 FH-2050/-2050-10/-2050-20





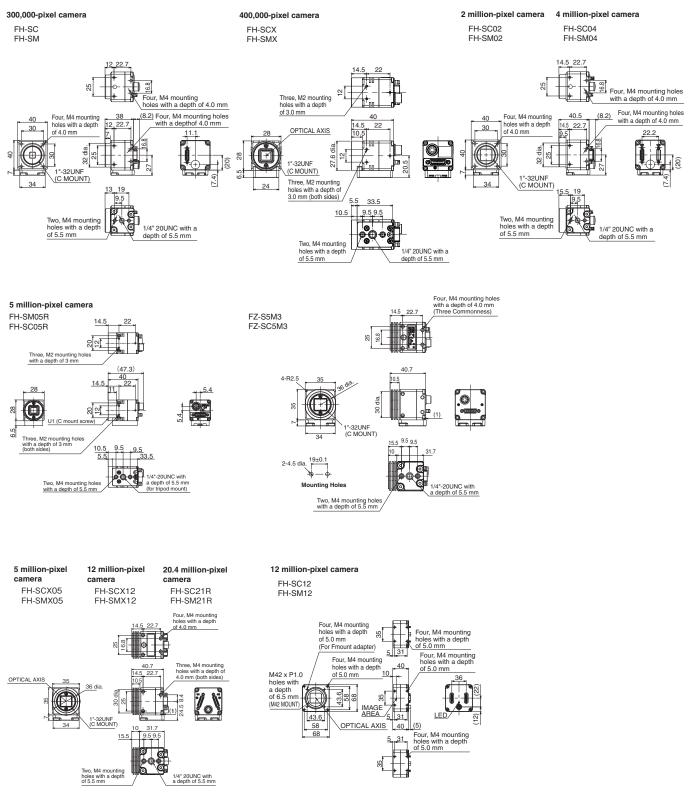


Lite Controllers FH-L550/-L550-10

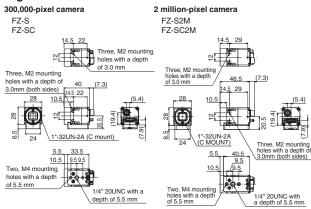


Cameras

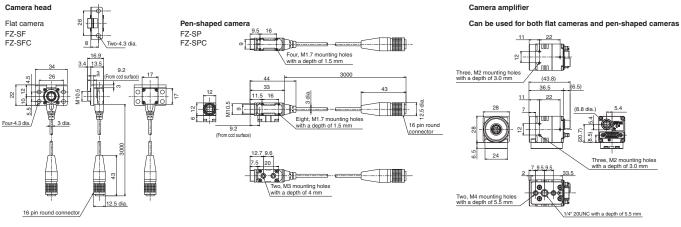
High-speed Digital CMOS Camera/Digital CMOS Camera



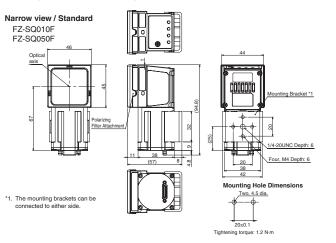
Digital CCD/CMOS Cameras

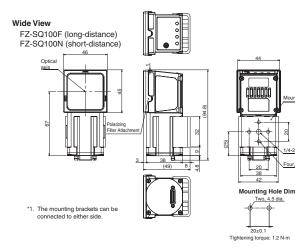


Small digital CCD cameras



Intelligent Compact Digital CMOS Cameras

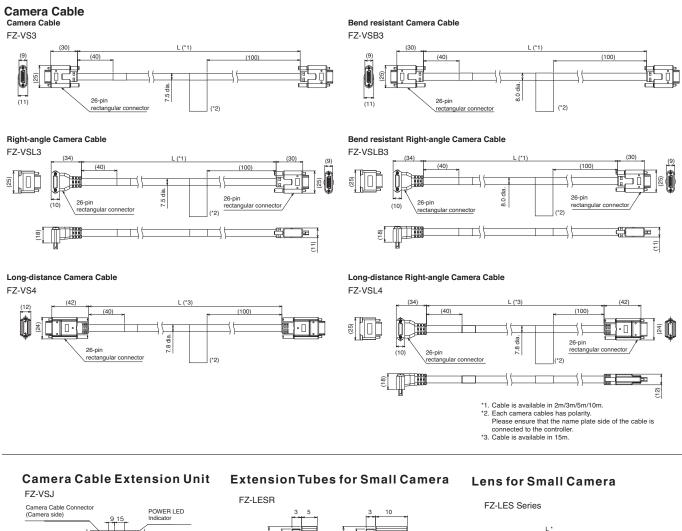


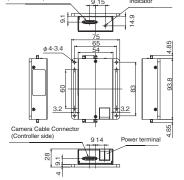


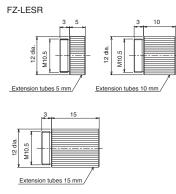
et *1

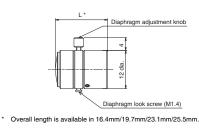
Four, M4 Depth: 6

Cables

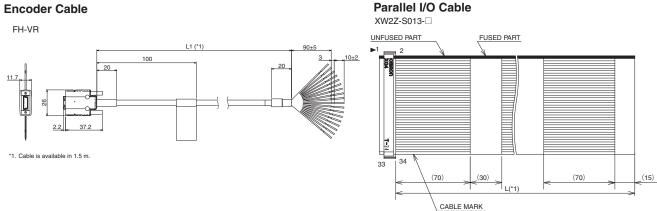








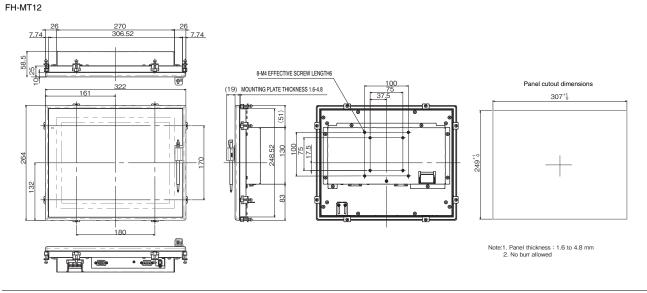
Encoder Cable



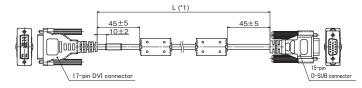
*1. Cable is available in 2m/5m

Touch Panel Monitor

Panel cutout dimensions

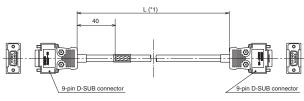


DVI-Analog Conversion Cable for Touch Panel Monitor/LCD Monitor FH-VMDA



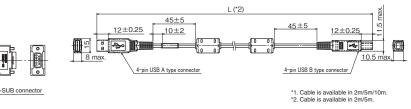
RS-232C Cable for Touch Panel Monitor

XW2Z-DDDP-1



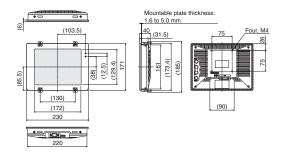
USB Cable for Touch Panel Monitor

FH-VUAB



LCD Monitor

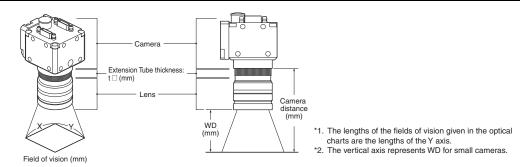
FZ-M08



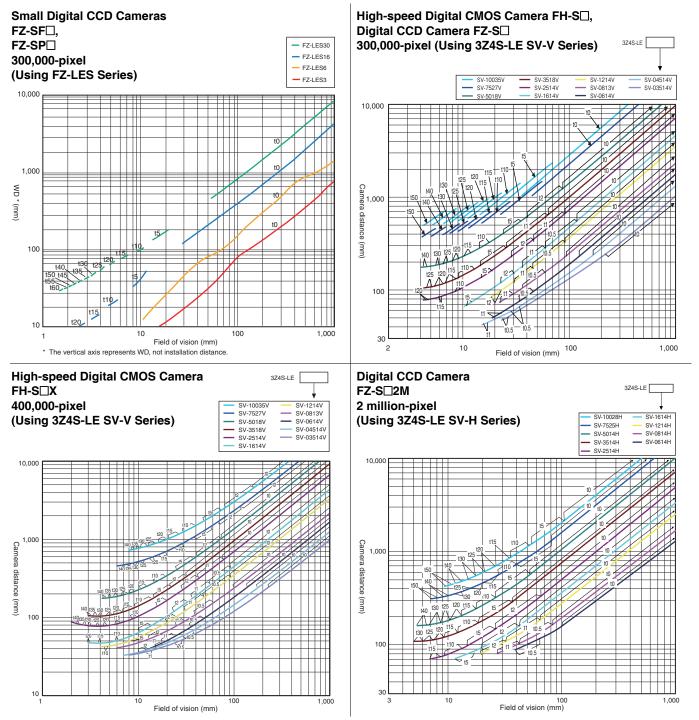
FH-Series Optical Chart

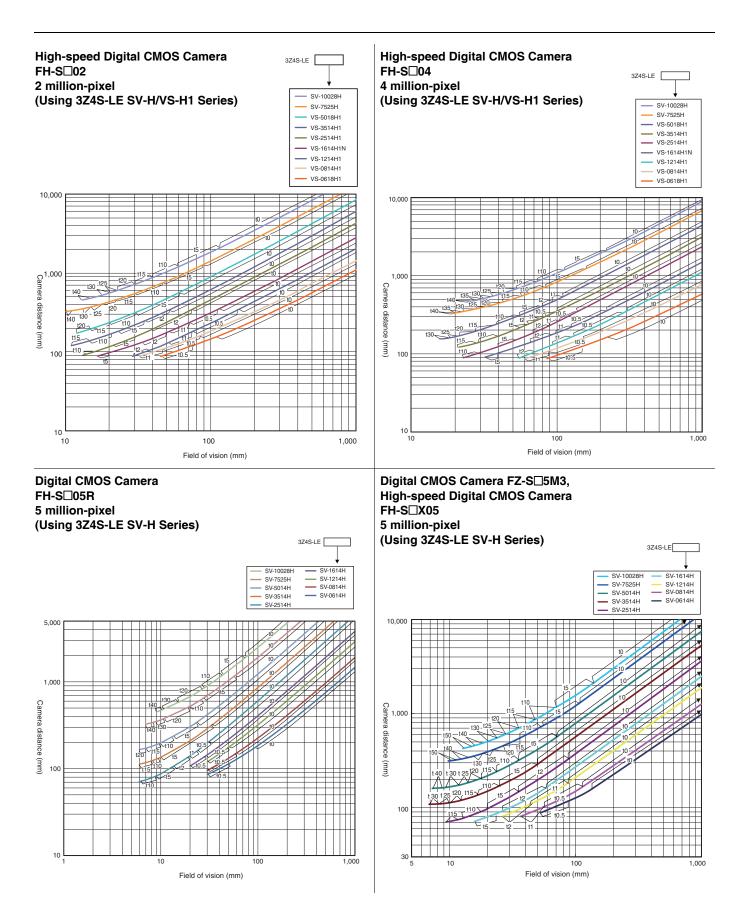
Meaning of Optical Chart

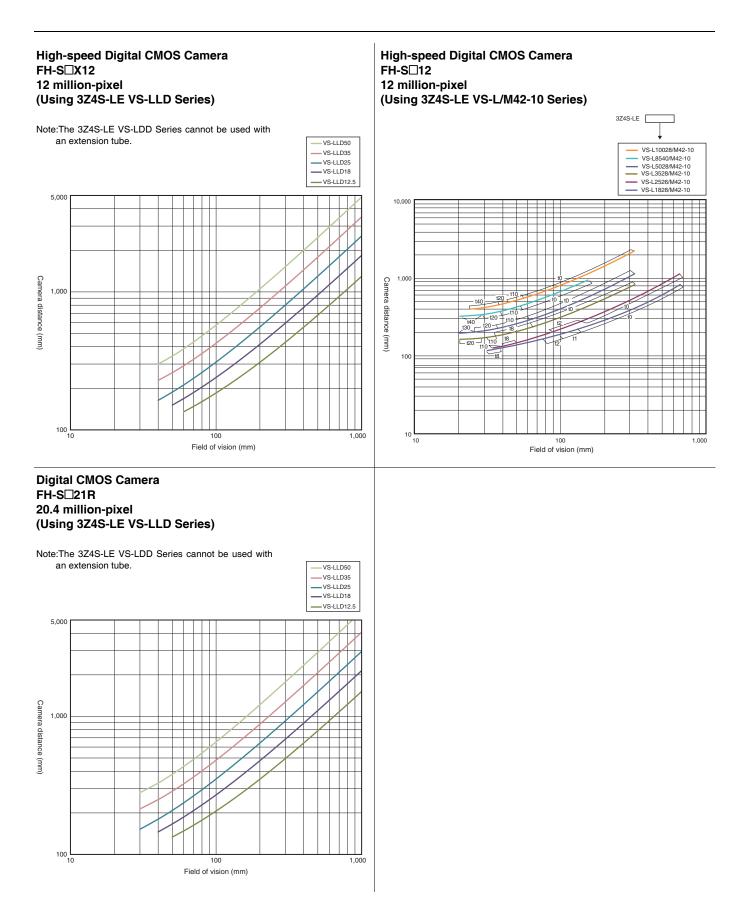
The X axis of the optical chart shows the field of vision (mm) (*1), and the Y axis of the optical chart shows the camera installation distance (mm) (*2).



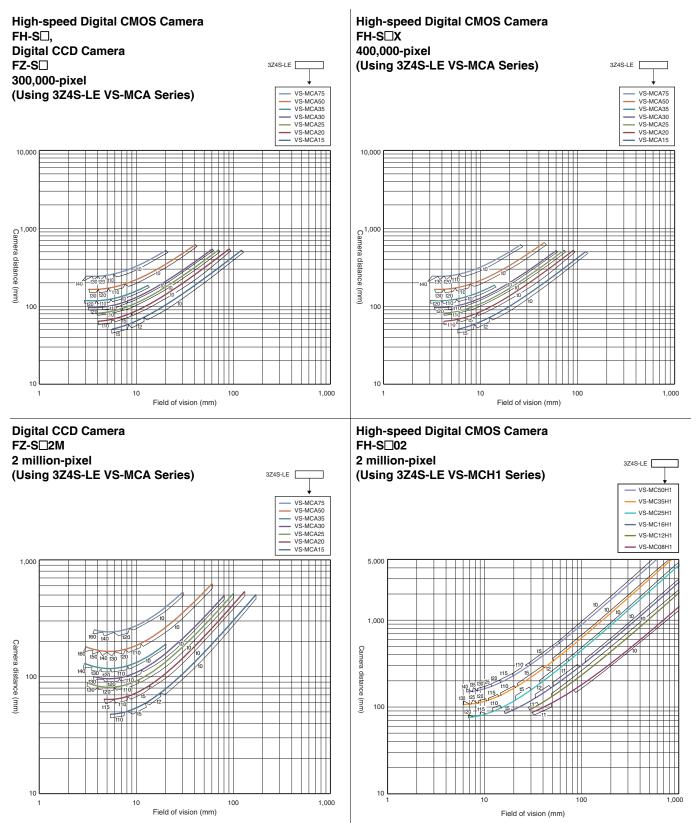
Standard Lenses

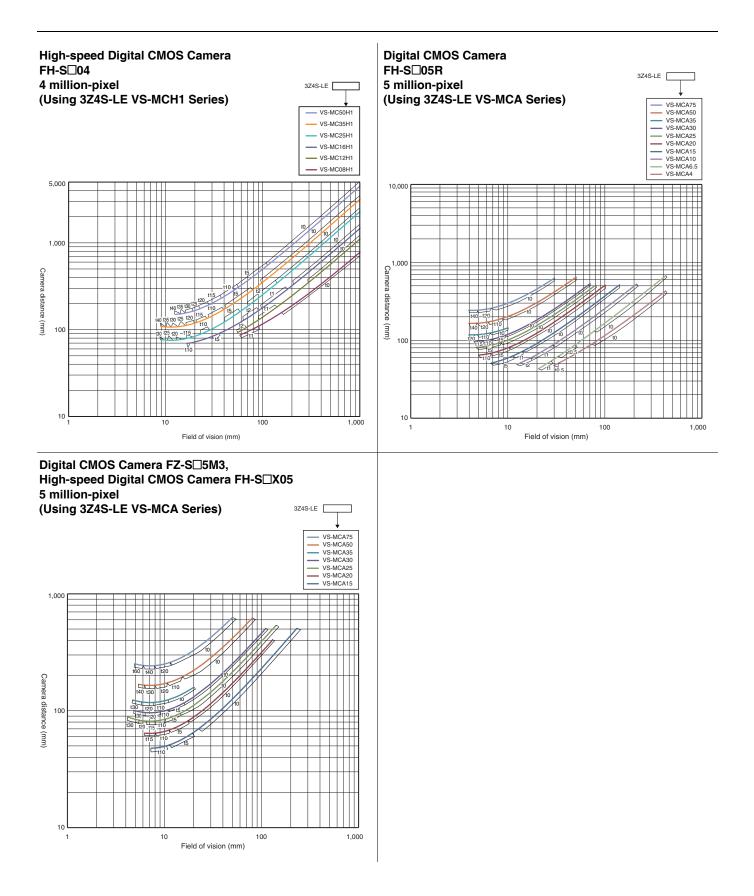




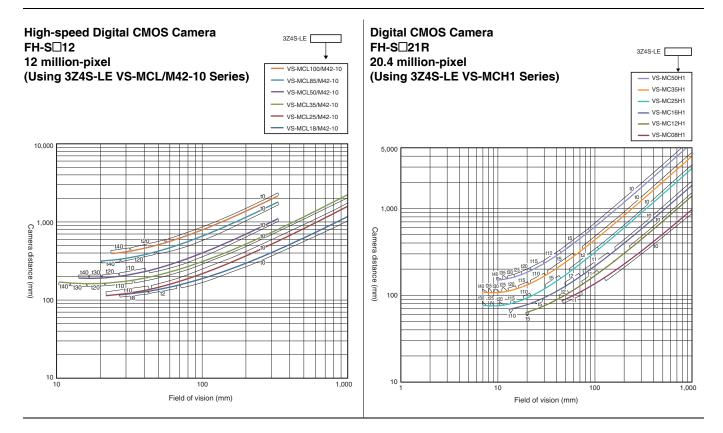


Vibrations and Shocks Resistant Lenses/Telecentric Lenses





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Related Manuals

Man.No.	Model number	Manual
Z365	FH/FHV7	Vision System FH/FHV7 Series User's Manual
Z341	FH/FHV7	Vision System FH/FHV7 series Processing Item Function Reference Manual
Z342	FH/FHV7	Vision System FH/FHV7 Series User's Manual for Communications Settings
Z343	FH/FHV7	Vision System FH/FHV7 Series Operation Manual for Sysmac Studio
Z366	FH	Vision System FH series Hardware Setup Manual
Z367	FH	Vision System FH series Macro Customize Functions Programming Manual
Z437	FH-UMAI	FH Application Software FH-UMAI Processing Item Function Reference Manual
Z438	FH-UMAI	FH Application Software FH-UMAI Version Update Tool Operating Manual

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