

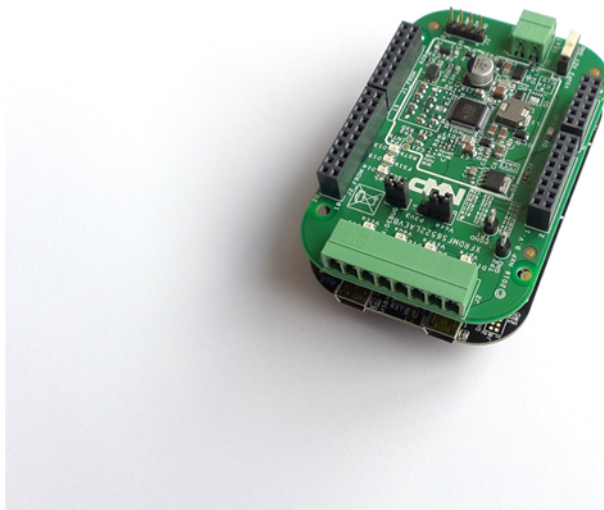
FS4500/FS6500 evaluation boards

KTFRDMFS4500-FS6500EVMUG

Rev. 4.0 — 12 June 2017

User guide

1 FRDMFS4503CAEVM, FRDMFS6523CAEVM and FRDMFS6522LAEVM evaluation boards



aaa-025541

Figure 1. FRDMFS6523CAEVM

2 Important notice

NXP provides the enclosed product(s) under the following conditions:

This evaluation kit is intended for use of ENGINEERING DEVELOPMENT OR EVALUATION PURPOSES ONLY. It is provided as a sample IC pre-soldered to a printed circuit board to make it easier to access inputs, outputs, and supply terminals. This evaluation board may be used with any development system or other source of I/O signals by simply connecting it to the host MCU or computer board via off-the-shelf cables. This evaluation board is not a Reference Design and is not intended to represent a final design recommendation for any particular application. Final device in an application will be heavily dependent on proper printed circuit board layout and heat sinking design as well as attention to supply filtering, transient suppression, and I/O signal quality.

The goods provided may not be complete in terms of required design, marketing, and or manufacturing related protective considerations, including product safety measures typically found in the end product incorporating the goods. Due to the open construction of the product, it is the user's responsibility to take any and all appropriate precautions with regard to electrostatic discharge. In order to minimize risks associated with the customers applications, adequate design and operating safeguards must be provided by the customer to minimize inherent or procedural hazards. For any safety concerns, contact NXP sales and technical support services.

Should this evaluation kit not meet the specifications indicated in the kit, it may be returned within 30 days from the date of delivery and will be replaced by a new kit.

NXP reserves the right to make changes without further notice to any products herein. NXP makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does NXP assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typical", must be validated for each customer application by customer's technical experts.

NXP does not convey any license under its patent rights nor the rights of others. NXP products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the NXP product could create a situation where personal injury or death may occur.

Should the Buyer purchase or use NXP products for any such unintended or unauthorized application, the Buyer shall indemnify and hold NXP and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges NXP was negligent regarding the design or manufacture of the part. NXP and the NXP logo are trademarks of NXP B.V. All other product or service names are the property of their respective owners. © 2017 NXP B.V.

3 Getting started

3.1 Jump start

NXP's analog product development boards provide an easy-to-use platform for evaluating NXP products. The boards support a range of analog, mixed-signal and power solutions. They incorporate monolithic ICs and system-in-package devices that use proven high-volume SMARTMOS technology. NXP products offer longer battery life, a smaller form factor, reduced component counts, lower cost and improved performance in powering state of the art systems.

1. Go to the relevant Tool Summary Page:
<http://www.nxp.com/FRDMFS6522LAEVM>
<http://www.nxp.com/FRDMFS6523CAEVM>
<http://www.nxp.com/FRDMFS4503CAEVM>
2. Review your Tools Summary Page.
3. Locate and click:

Jump Start Your Design

4. Download the documents, software and other information.

Once the files are downloaded, review the user guide in the bundle. The user guide includes setup instructions, BOM and schematics. Jump start bundles are available on each tool summary page with the most relevant and current information. The information includes everything needed for design.

3.2 Kit contents/packing list

The FRDMFS6522LAEVM, FRDMFS6523CAEVM and FRDMFS4503CAEVM contents include:

- Assembled and tested FRDMFS65xx board
- Assembled and test FRDM-KL25Z board
- 3.0 ft. USB-STD A to USB-B-mini cable
- Connector, terminal block plug, 2 pos., str. 3.81 mm
- Connector, terminal block plug, 8 pos., str. 3.81 mm

3.3 Required equipment

The EVM requires the following items:

- Power supply with a range of 8.0 V to 40 V and a current limit set initially to 1.0 A
- Standard A plug to Mini-B plug USB cable M/M
- FlexGUI graphical user interface
- FlexGUI register definition XML file

3.4 EVM overview

The EVM contains two boards:

- **FRDMFS4503CAEVB or FRDMFS6523CAEVB or FRDMFS6522LAEVB:** These are the evaluation boards available for the FS6500 / FS4500 SBC. The hardware is described in [Section 4.5 "Getting to know the hardware"](#). This document refers to these boards as EVBs.
- **FRDM-KL25Z:** This board contains the KL25Z MCU. It is plugged into the EVB by means of the Arduino™ connectors on both boards. The FRDM-KL25Z manages communication between the EVB and a host PC, allowing users to access the EVB's on-board device features and registers. For more information on the FRDM-KL25Z see [Section 11 "References"](#)

4 Board description

4.1 Board overview

The FRDMFS4503CAEVB, FRDMFS6523CAEVB and FRDMFS6522LAEVB are hardware evaluation tools supporting system designs based on NXP's FS4500 and FS6500 product families. The EVM allow testing the devices as an integral part of the overall system being developed. They provide access to all FS45xx and FS65xx functions (SPI, IOs) and support functional modes such as debug, normal, buck and boost.

Table 1. EVMs supporting the FS45xx/FS65xx family

EVM name	Supported silicon	Options
FRDMFS6522LAEVM	MC33FS6522LAE	CAN, LIN, No FS1b, V _{CORE} DC/DC 2.2 A ^[1]
FRDMFS6523CAEVM	MC33FS6523CAE	CAN, FS1b, No LIN, V _{CORE} DC/DC 2.2 A ^[1]
FRDMFS4503CAEVM	MC33FS4503CAE	CAN, FS1b, No LIN, V _{CORE} LDO 500 mA

[1] The FRDM board is limited to 1.5 A

4.2 Board features

The main features of the FRDMFS6522LAEVB, FRDMFS6523CAEVB and FRDMFS4503CAEVB evaluation boards are:

- VBAT power supply connector
- V_{CORE} configuration: 1.3 V
- V_{CCA} configuration: 3.3 V, using internal PMOS
- V_{AUX} configuration: 5.0 V
- Buck or boost setting
- DFS configuration
- Ignition key switch
- CAN bus
- LIN bus (FRDMFS6522LAEVM only)
- FS0B
- FS1B (FRDMFS6523CAEVM or FRDMFS4503CAEVM only)
- IO connector (IO_0 to IO_5)
- Connectivity to KL25Z Freedom board (Access to SPI bus, IOs, LIN digital, RSTB, FS0B, INTB, Debug, MUX_OUT, Regulators)
- LEDs that indicate signal or regulator status

4.3 Block diagram

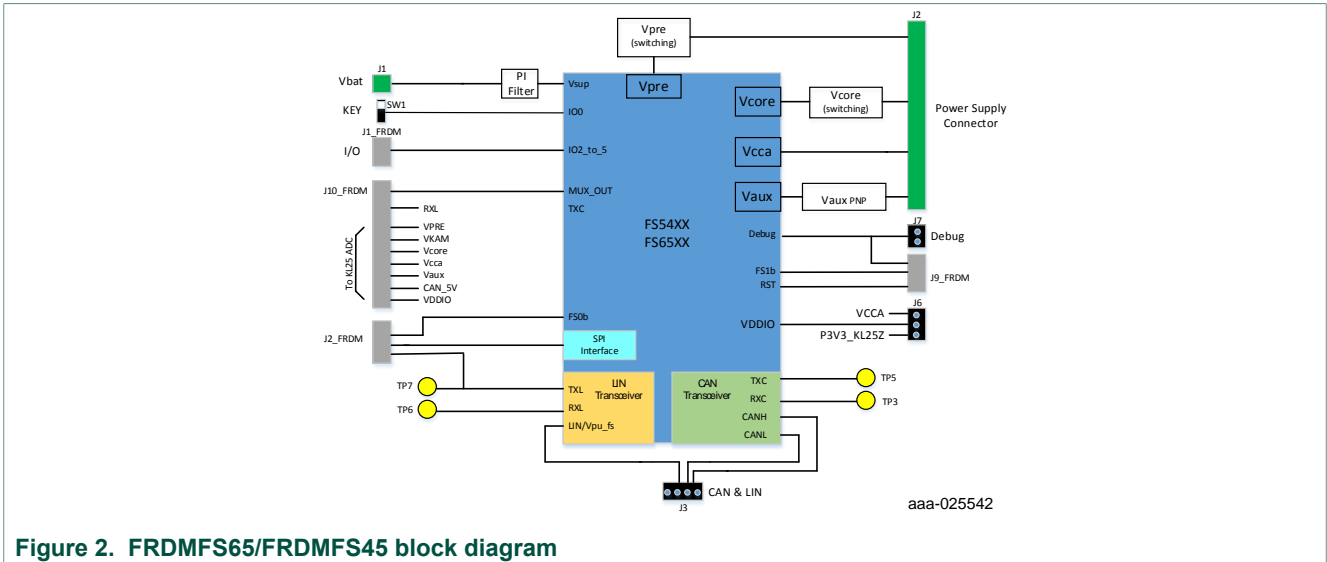


Figure 2. FRDMFS65/FRDMFS45 block diagram

4.4 Device features

The FS65xx/FS45xx are multi-output power-regulating SMARTMOS devices aimed at the automotive market. They include CAN flexible data (FD) and/or LIN transceivers.

Multiple switching and linear voltage regulators—including low-power mode (32 µA) — provide a variety of wake-up capabilities. An advanced power management scheme maintains high efficiency over a wide range of input voltages (down to 2.7 V) and output current ranges (up to 2.2 A).

The FS45xx/FS65xx family includes enhanced safety features with multiple fail-safe outputs. The devices are capable of fully supporting safety-oriented system partitioning with a high integrity safety level (up to ASIL D).

The built-in CAN FD (flexible data-rate) interface meets all ISO11898-2 and -5 standards. The LIN interface is compliant with LIN protocol specifications 2.0, 2.1, 2.2, and SAEJ2602-2.

Table 2. FS45xx/FS65xx features

Device	Description	Features
FS4500/ FS6500	Automotive control devices	<ul style="list-style-type: none"> • Battery voltage sensing and MUX output pin • Highly flexible SMPS pre-regulator, allowing two topologies: non-inverting buck-boost and standard buck • Switching mode power supply (SMPS) dedicated to MCU core supply, from 1.0 V to 5.0 V, delivering up to 2.2 A • Switching mode power supply (SMPS) dedicated to MCU core supply, from 1.0 V to 5.0 V, delivering up to 2.2 A • Linear voltage regulator dedicated to auxiliary functions, or to sensor supply (VCCA tracker or independent), 5.0 V or 3.3 V • Linear voltage regulator dedicated to MCU A/D reference voltage or I/Os supply (VCCA), 5.0 V or 3.3 V • 3.3 V keep alive memory supply available in low-power mode • Long duration timer available in low-power mode (1.0 s resolution) • Multiple wake-up sources in low-power mode: CAN, LIN, I/Os, LDT • Five configurable I/Os

4.5 Getting to know the hardware

The primary component of the evaluation boards is the SBC. The boards include an FS45xx or FS65xx and provide full access to all the device’s features.

This EVB can either be used alone, or connected to the FRDM-KL25Z board included with this EVM. This provides access to all the features and I/Os of FS45xx/FS65xx through a USB connection.

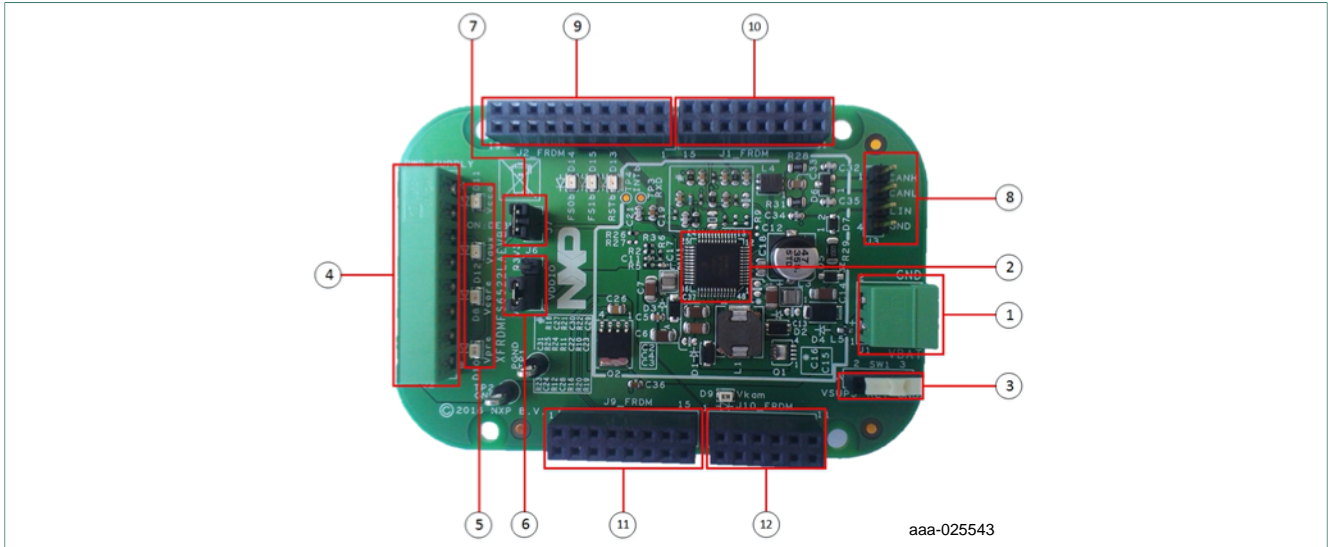


Figure 3. Evaluation board description

Table 3. Board description

Number	Description
1	V _{BAT} connector - Use Phoenix connector to supply board
2	FS45xx / FS65xx
3	Ignition key - Ignition key from car
4	Power supplies - Connector for power supplies (V _{PRE} /V _{CORE} /V _{CCA} /V _{AUX})
5	Power supplies LED - Visualizes regulator state (on or off).
6	V _{DDIO} selection - Selects either V _{CCA} or P3V3_KL25Z (3.3V supply from FRDM-KL25Z board)
7	Enable DBG mode
8	Can & LIN connector - Could be used for debug purpose (CANH, CANL, LIN)
9	I/Os - Input and Output from FS45XX/FS65XX (SPI, V _{PRE} , FS0b, TX LIN)
10	I/Os - Input and Output from FS45XX/FS65XX (IO2, IO3, IO4, IO5, Ignition)
11	I/Os - Input and Output from FS45XX/FS65XX (RSTb, FS1b, DBG, GND, P3V3_KL25Z)
12	I/Os - Input and Output from FS45XX/FS65XX (TX CAN, RX LIN, CAN_5V, V _{CORE} , V _{CCA} , V _{AUX} , V _{KAM} , V _{DDIO})

4.5.2 Jumper definitions

Figure 5 shows the location of jumpers on the evaluation board.

Table 5 describes the function and settings for each jumper. Default jumper settings are shown in bold text.

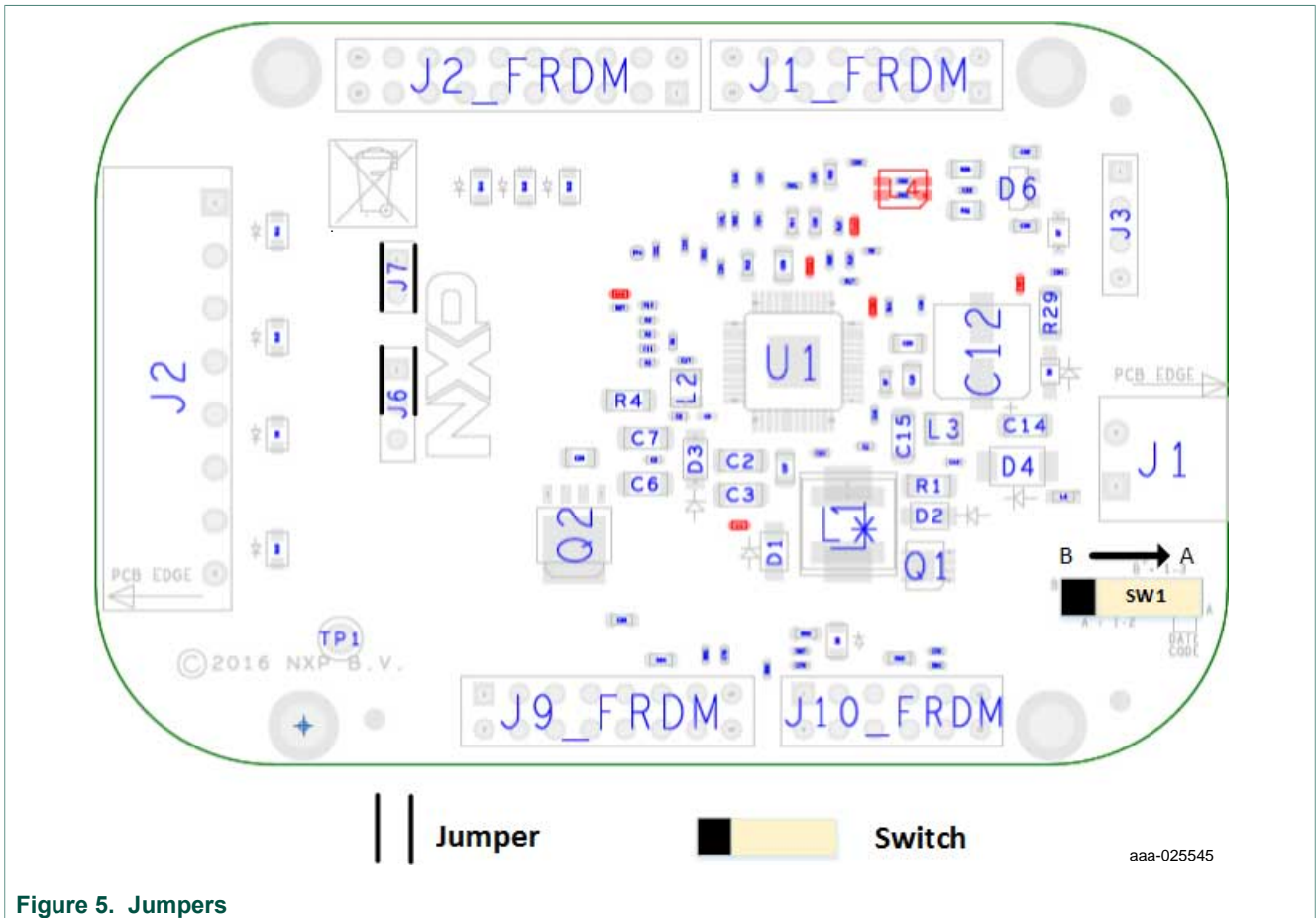


Figure 5. Jumpers

Table 5. Jumper definitions

Jumper	Description	Setting	Connection/Result
J6	VDDIO selection	[1–2]	VDDIO referenced to V _{CORE} or P3V3_KL25Z
		[2–3]	VDDIO referenced to V _{CCA}
J7	Debug mode	[1–2]	ON:Debug mode OFF: normal mode

4.5.3 Test point definitions

The following test points provide access to various signals to and from the board.

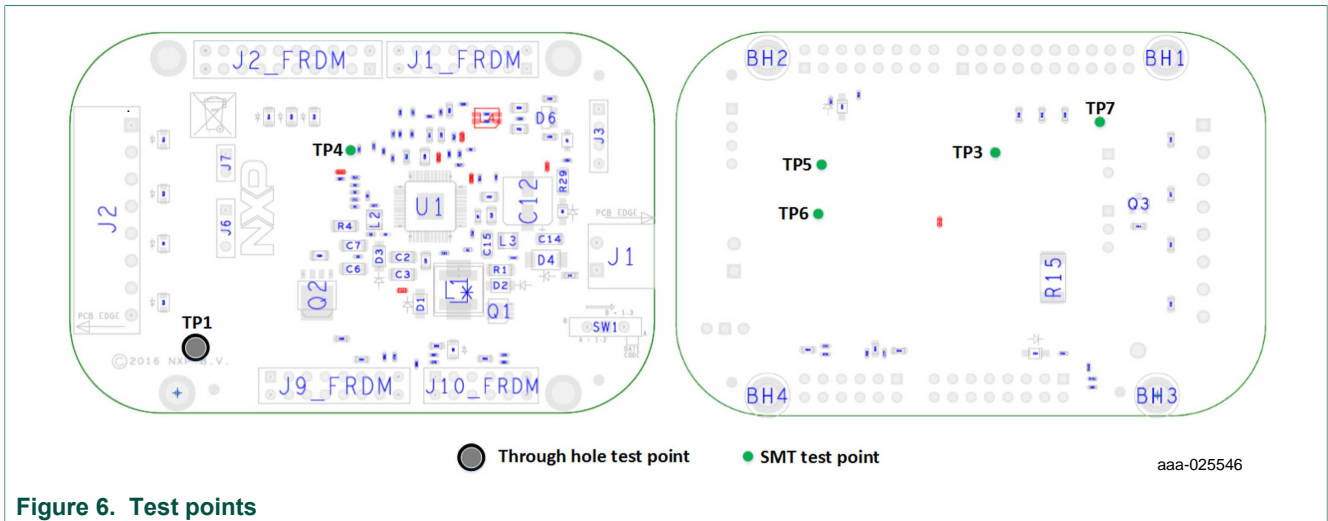


Figure 6. Test points

Table 6. Test point definitions

Test point name	Signal name	Description
TP1	GND	Ground
TP3	RXC	CAN receiver data. Logic level
TP4	INTB	INTB asserted (logic level = 0)
TP5	TXC	CAN transmit data. Logic Level
TP6	RXL	LIN receiver data. Logic level.
TP7	TXL	LIN transmit data. Logic Level

4.5.4 Connectors

Figure 7 shows the location of connectors on the board. The tables below list the pin-outs for each connector.

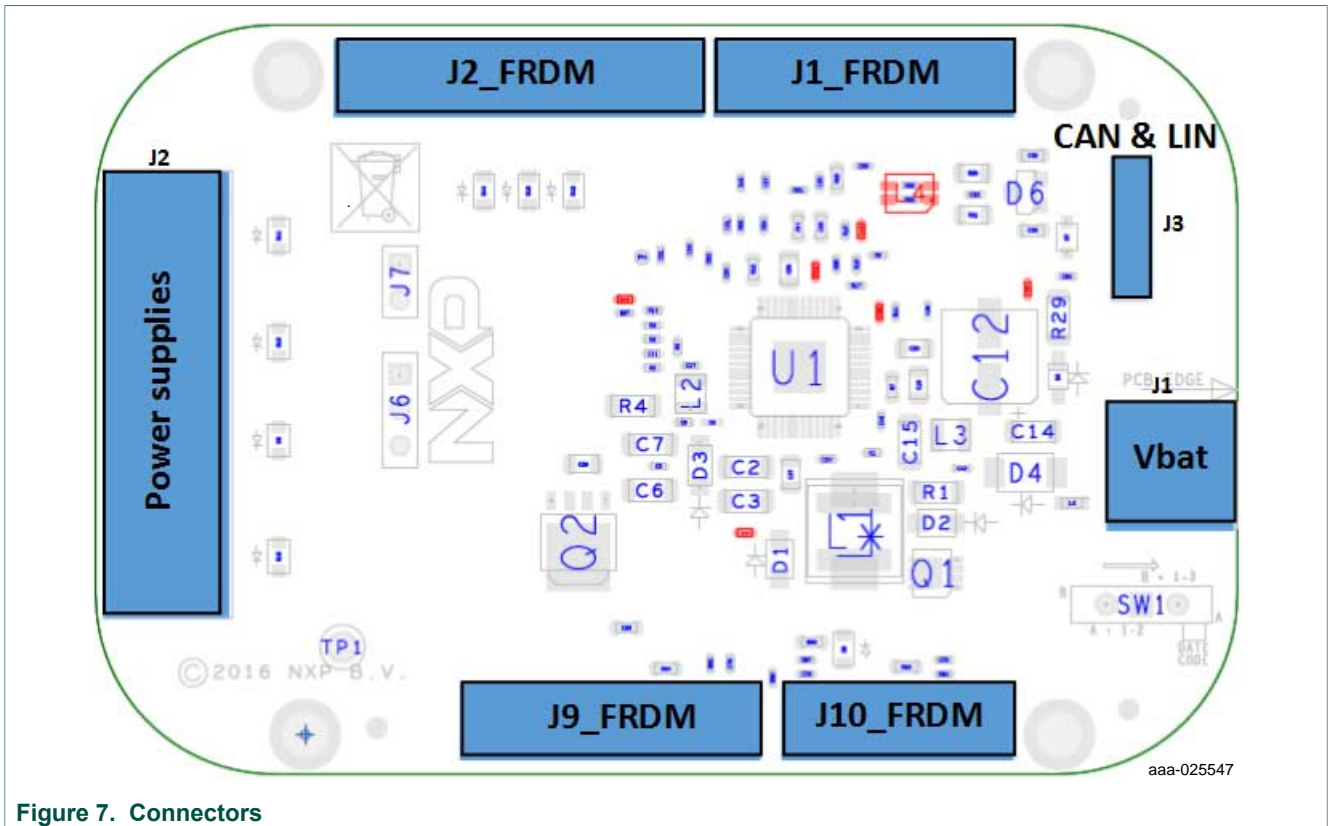


Figure 7. Connectors

4.5.4.1 V_{BAT} connector (J1)

V_{BAT} connects to the board through Phoenix connector (J1).

Table 7. V_{BAT} Phoenix connector (J1)

Pin number	Connection	Description
1	V _{BAT}	Connects to V _{BAT}
2	Ground	Connects to ground

4.5.4.2 SPI connector (J2_FRDM)

The Debug connector(J2_FRDM) gives access to the FS65xx main signal for debug or experimentation purposes.

Table 8. SPI connector (J2_FRDM)

Pin number	Connection	Description
1	Not Connected	
2	Not Connected	
3	Not Connected	
4	Not Connected	
5	Not Connected	
6	CSB	SPI chip select, active low

Pin number	Connection	Description
7	FS0B	Fail-safe 0.
8	MOSI	SPI Master Output Slave Input
9	Not Connected	
10	MISO	SPI Master Input Slave Output
11	Not Connected	
12	SCLK	SPI serial clock
13	Not Connected	
14	GND	Ground
15	Not Connected	
16	Not Connected	
17	Not Connected	
18	Not Connected	
19	TXL	LIN transmit data. Logic level.
20	Not Connected	

4.5.4.3 CAN and LIN connector (J3)

The CAN and LIN connector is mounted on all three boards, but LIN is supported only on the FRDMFS6522LAEVB.

Table 9. CAN & LINconnector (J3)

Pin number	Connection	Description
1	CANH	Connects to the CANH bus line
2	CANL	Connects to CANL bus line
3	LIN	Connects to the LIN bus
4	GND	Connects to ground

4.5.4.4 Debug connector (J9_FRDM)

The debug connector provides access to DBG as well as FS1b and reset.

Table 10. USB connector (J33)

Pin number	Connection	Description
1	Not Connected	
2	Not Connected	
3	FS1b	Fail-safe 1
4	P3V3_KL25Z	3.3V KL25Z supply
5	Not Connected	
6	Not Connected	
7	Not Connected	
8	P3V3_KL25Z	3.3V KL25Z supply

Pin number	Connection	Description
9	Not Connected	
10	Not Connected	
11	Not Connected	
12	GND	Connects to ground
13	DBG	Debug pin selection
14	GND	Connects to ground
15	RSTB	Reset, active low
16	Not Connected	

4.5.4.5 I/O connector (J1_FRDM)

The I/O connector accesses the device under test (DUT) IO and V_{KAM} signals.

Table 11. I/O connector (J1_FRDM)

Pin number	Connection	Description
1	Vkam_IO5	Keep alive memory voltage
2	Not Connected	
3	Not Connected	
4	Not Connected	
5	Key	Ignition signal
6	Not Connected	
7	IO_2	Input/Output 2
8	Not Connected	
9	IO_3	Input/Output 3
10	Not Connected	
11	IO_4	Input/Output 4
12	Not Connected	
13	Not Connected	
14	Not Connected	
15	Not Connected	
16	Not Connected	

4.5.4.6 Power supply connector (J2)

The power supply connector (J2) connects any of the SBC regulators to an external load or board for evaluation purposes.

Table 12. Power supply connector (J2)

Pin number	Connection	Description
1	V_{CCA}	V_{CCA} output voltage
2	GND	Ground

Pin number	Connection	Description
3	V _{AUX}	V _{AUX} auxiliary voltage regulator
4	GND	Ground
5	V _{CORE}	V _{CORE} voltage output
6	GND	Ground
7	V _{PRE}	V _{PRE} regulator output regulator
8	GND	Ground

4.5.4.7 KL25Z ADC inputs (J10_FRDM)

The KL25Z ADC connector (J10_FRDM) connects the FS6500 regulator outputs to the ADCs on the KL25Z. The regulator values can then be measured and displayed in FlexGUI.

Table 13. KL25Z Analog regulator inputs (J10_FRDM)

Pin number	FRDM Signal	Description
1	Vkam_IO5	Keep alive memory voltage, connected to KL25 ADC0_SE0
2	V _{CORE}	V _{CORE} voltage output, connected to KL25 ADC0_SE8
3	RXL	LIN receiver data. Logic level.
4	V _{AUX}	V _{AUX} auxiliary voltage regulator, connected to KL25 ADC0_SE9
5	VDDIO	Reference voltage for IOs, connected to KL25 ADC0_SE3
6	V _{CCA}	V _{CCA} output voltage, connected to KL25 ADC0_SE12
7	Not connected	
8	CAN_5V	CAN voltage regulator, connected to KL25 ADC0_SE13
9	Not connected	
10	MUX_OUT	Multiplexer output
11	TXC	CAN transmit data. Logic level.
12	Not connected	

4.5.5 Switches

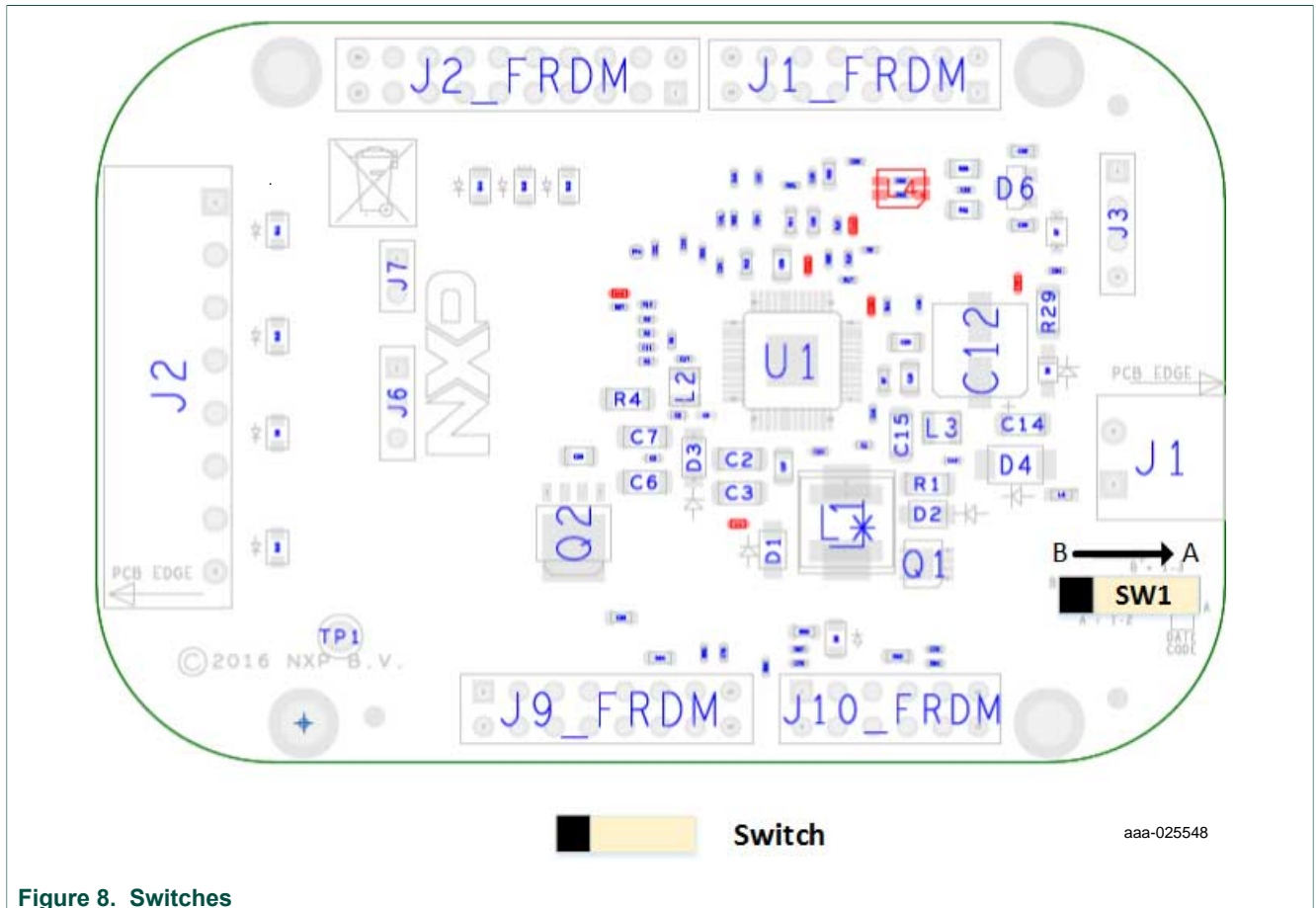


Figure 8. Switches

Table 14. SW1

Position	Function	Description
A	GND	Connection between Key input and ground
B	Vsup3	Connection between Key input and Vsup3

5 Board default settings

5.1 V_{CCA} and V_{AUX} setting

V_{CCA} and V_{AUX} are set by default, respectively to 3.3 V and 5.0 V. It's possible to change that by modifying R26 or R27 (whichever is populated) according to [Figure 9](#).

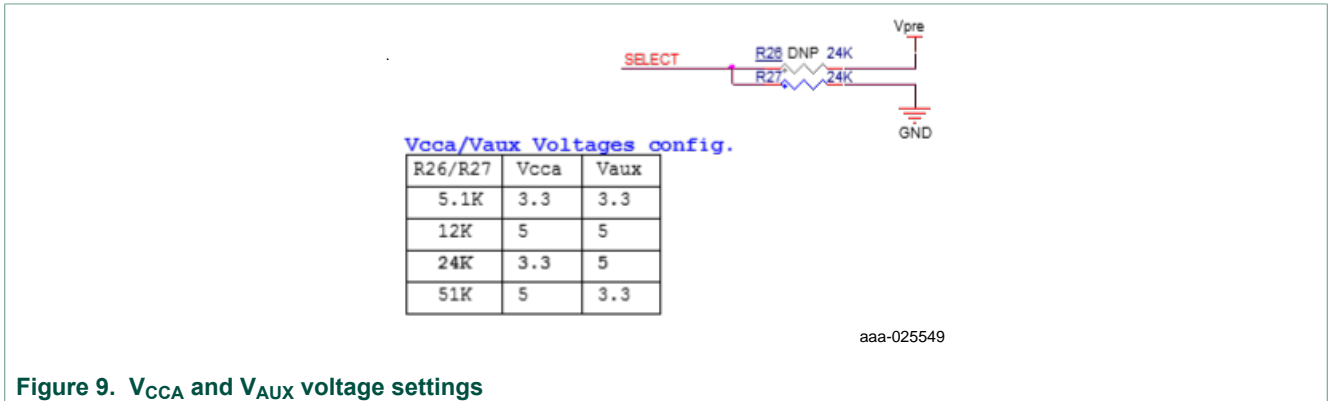


Figure 9. V_{CCA} and V_{AUX} voltage settings

The V_{AUX} regulator is always tied to the external PNP transistor

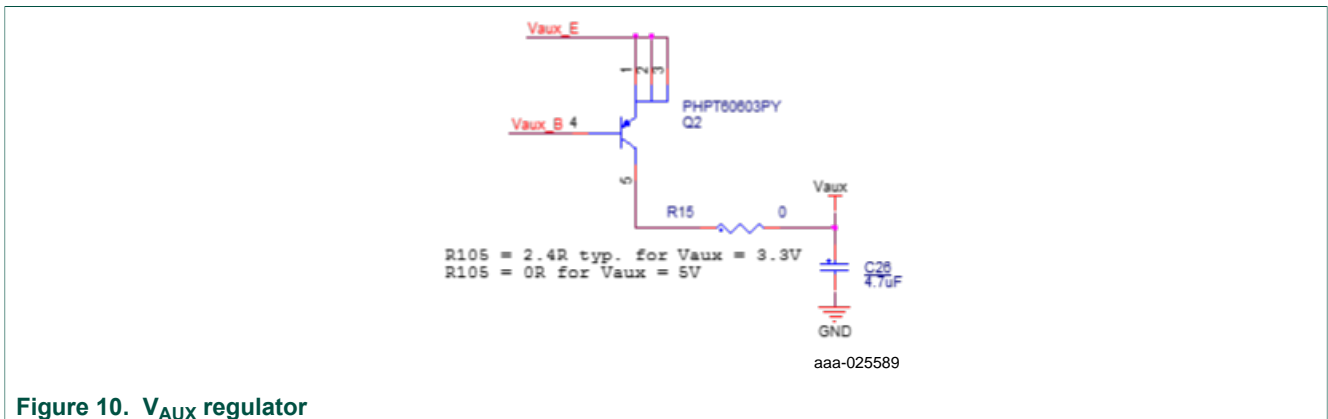


Figure 10. V_{AUX} regulator

5.2 V_{CORE} settings and related configurations

5.2.1 V_{CORE} and F45xx versus FS65xx

The FS45xx family of devices only support V_{CORE} LDO (low dropout) voltage regulators. The FS65xx family only supports V_{CORE} DC/DC voltage regulators. The evaluation board circuitry accommodates this discrepancy by implementing a variation of the BOM for each of the two device families. Populating or not populating resistors with some components depends on which device family is in use and determines which network is enabled.

For the FS45xx family, the following assembly options must be implemented:

- R42: DNP
- C8/C9/R4/D3/L2/C5/C7/R2/C11/R5/C17: populated

For the FS65xx family, it is the opposite:

- R42: populated
- C8/C9/R4/D3/L2/C5/C7/R2/C11/R5/C17: DNP

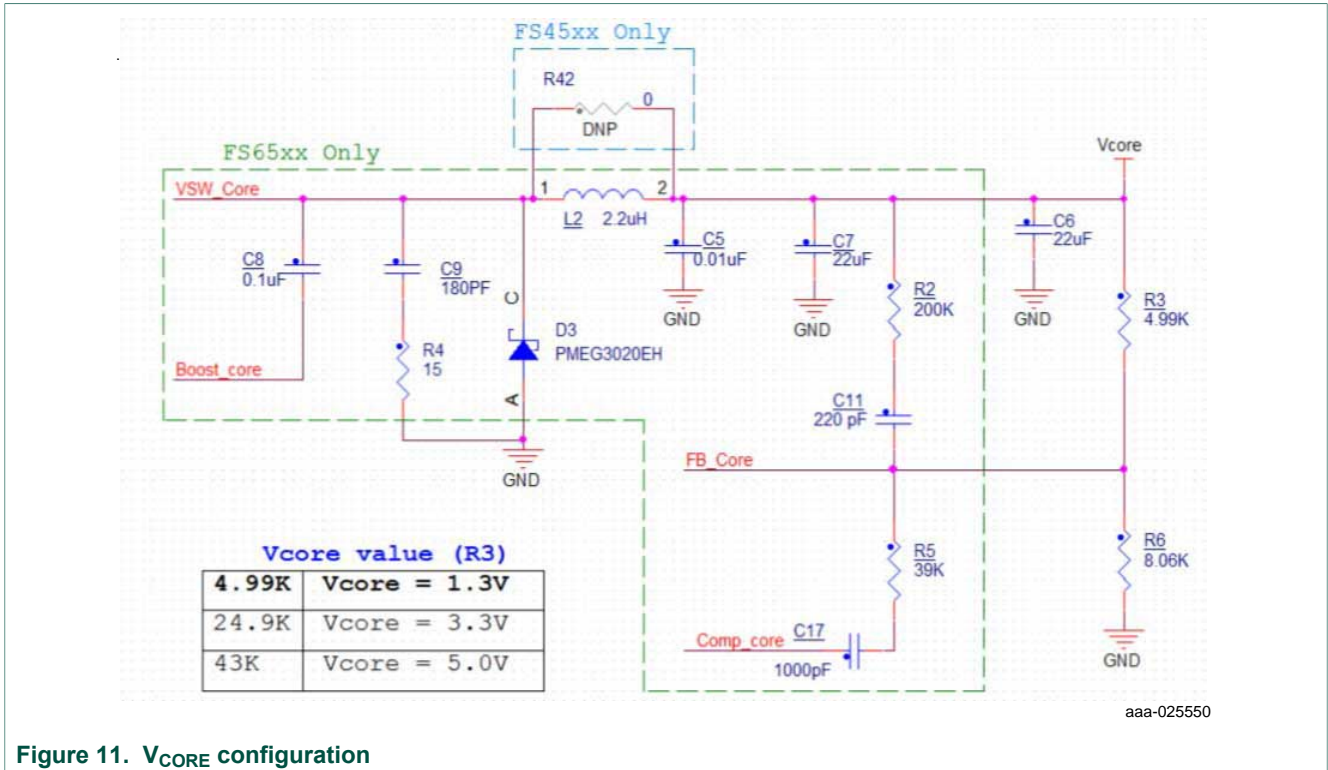


Figure 11. V_{CORE} configuration

5.2.2 Compensation network

Both LDO and DC/DC voltage regulators use V_{CORE} voltage feedback to control the output voltage (see Figure 12).

For FS45xx devices using static (steady-state) LDO regulators, a simple resistor bridge (resistors R3 and R6) determines the feedback voltage. By default, the feedback voltage is 1.3 V.

For FS65xx devices using DC/DC voltage regulators, a pair of RC voltage dividers controls the dynamic behavior of the regulator.

5.2.3 FCRBM Resistor Bridge

The feedback core bridge monitoring (FCRBM) Resistor Bridge is an evaluation board safety feature.

The bridge generates the same voltage as the bridge connected to the FB_core pin. If the difference between the two voltages is greater than the V_{CORE_FB_DRIFT} value, the FS state machine is impacted (refer to data sheet). The drift value is set to 1.3V by default.

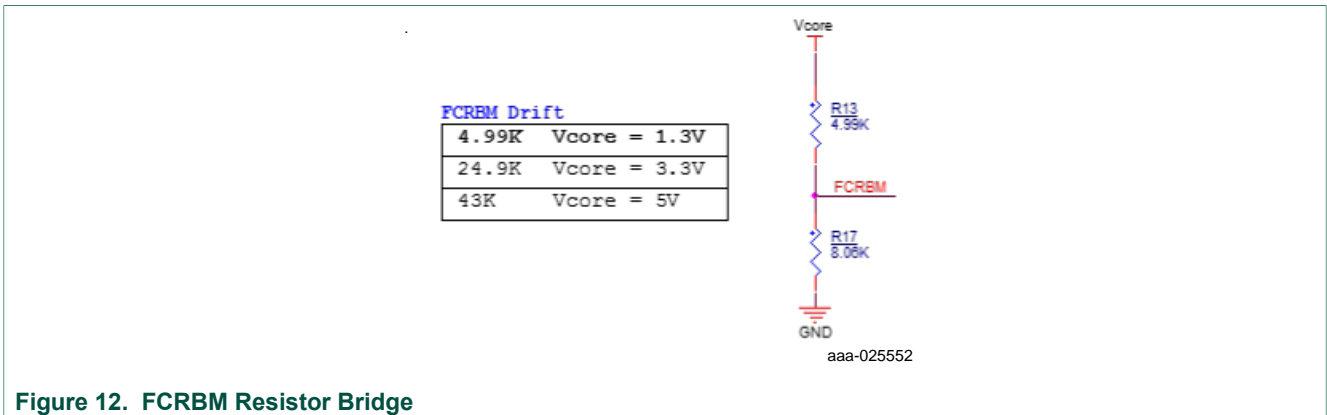


Figure 12. FCRBM Resistor Bridge

5.2.4 MCU analog input

To assure the complete isolation of analog signals connected from an external component to the MCU, remove input resistance as applicable for the following:

- V_{PRE} tied to MCU through R83
- V_{CORE} tied to MCU through R98
- V_{AUX} tied to MCU through R90
- V_{CCA} tied to MCU through R94
- CAN_5V tied to MCU through R80
- MUX_OUT tied to MCU through R18
- V_{KAM} tied to MCU through R96

6 Configuring the EVM

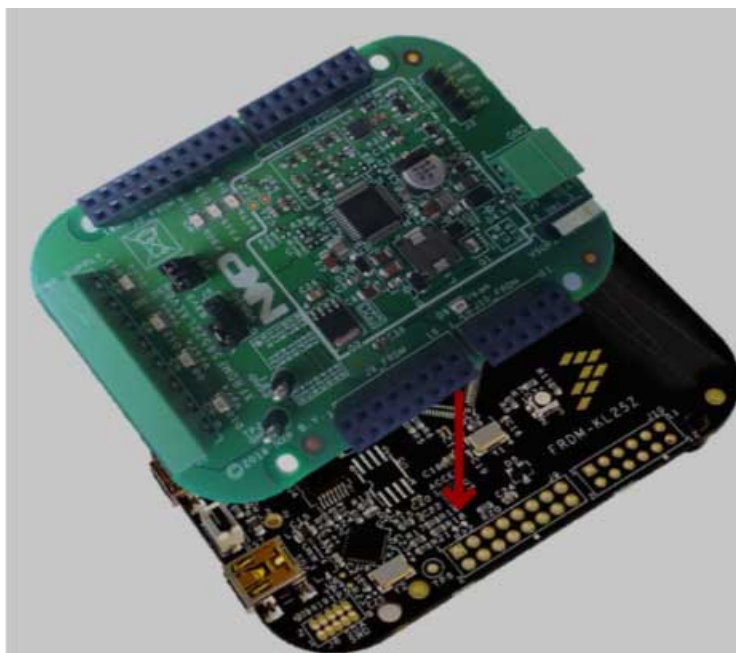
6.1 Connecting the hardware

The EVB can be connected to a PC through the FRDM-KL25Z board included with this EVM or any board with an MCU that supports SPI. A power supply with a typical value of 13.5 V must be connected to J1. Regulators can be loaded using J2 connector.

In order to use the board with an FRDM-KL25Z, these steps must be followed for the hardware setup:

Caution: To avoid damaging the board, the V_{BAT} voltage must not exceed 40 V.

1. With the power switched off, attach the DC power supply to the Phoenix connector (J1) on the evaluation board.
2. A load or an external board can be attached to J2 (not mandatory).
3. Plug the board to an FRDM-KL25Z board.



aaa-025553

4. Connect a USB cable from the USB port labeled **USBKL25Z** on the FRDM-KL25Z board to a USB port on a PC that has the FlexGUI installed.
5. Turn on the DC power supply.

[Figure 13](#) illustrates the hardware configuration.

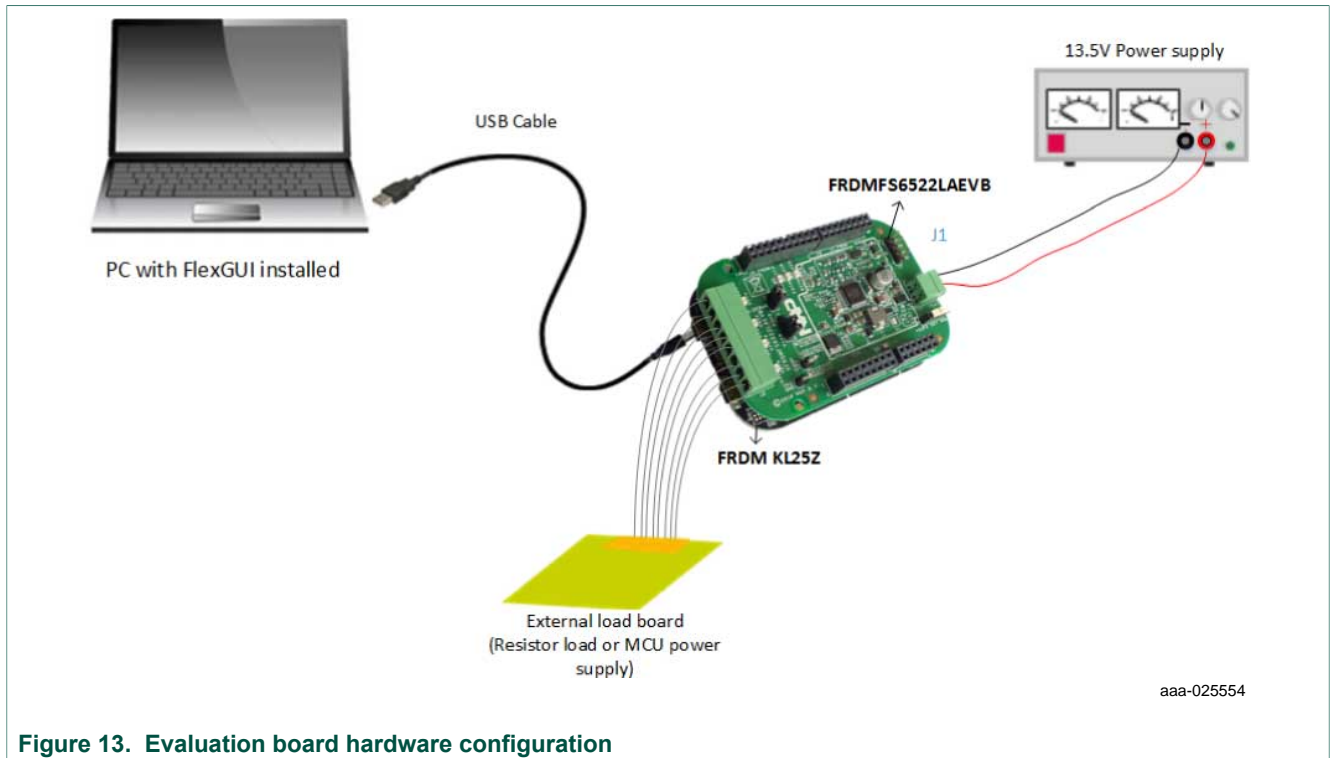


Figure 13. Evaluation board hardware configuration

The software is normally pre-loaded on the KL25Z. For future updates, the procedure for programming the KL25 is described in [Section 8 "Appendix A: FRDM-KL25Z software loading"](#).

7 Software

The FRDMFS4503CAEVB/FRDMFS6523CAEVB/FRDMFS6522LAEVB boards must be plugged into a FRDM-KL25Z. Firmware controlling the communication with the FS45xx/FS65xx must be loaded onto the MCU. The procedure for loading the firmware is described in [Section 8 "Appendix A: FRDM-KL25Z software loading"](#). The FlexGUI graphical user interface that is installed on a PC serves as the user interface to the evaluation board ([Section 9 "Appendix B: Installing the FlexGUI"](#)). When connecting the FRDM-KL25Z board to a PC through a USB cable, the following data exchanges are available:

- SPI access (read and write) to FS45xx/FS65xx
- ADC readout, connected to regulators
 - V_{PRE}
 - V_{CORE}
 - V_{AUX}
 - V_{CCA}
 - CAN_5V
 - MUX_OUT
 - V_{DDIO}
 - V_{KAM}
- I/O readout, connected to IO_2 to IO_5
- FS0B/FS1B readout
- RSTB readout
- CAN generated TX signal
- LIN generated TX signal with loopback checking

The software bundle also includes an XML file containing register descriptions for the FS45xx or FS65XX (depending on the evaluation board). This file must be installed in order for the GUI to work properly. In addition, an optional Excel file can be created to facilitate setting several registers at a click.

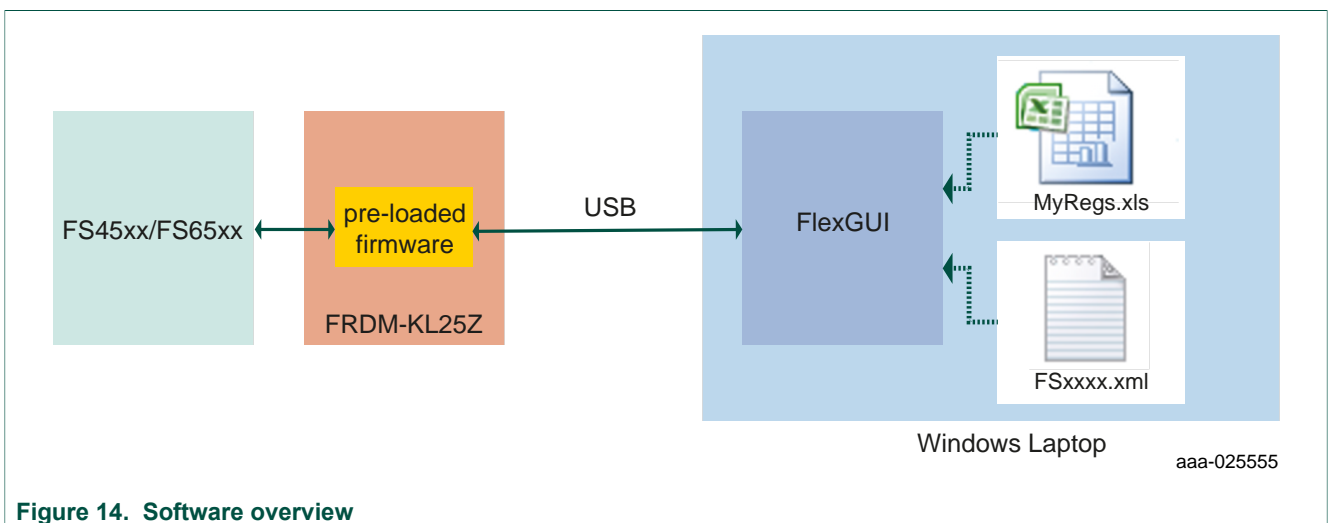


Figure 14. Software overview

7.1 Creating and using a register configuration file

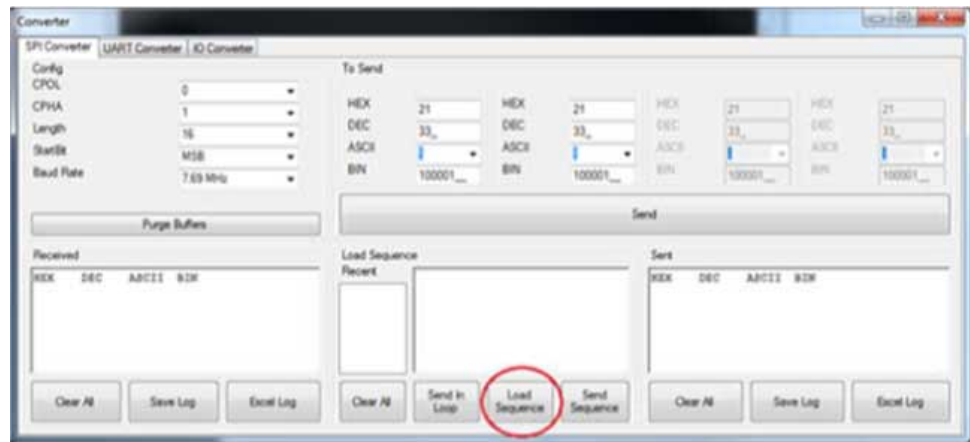
Creating an Excel register configuration file allows the user to initialize the evaluation board MCU with a predefined set of register values. To create a register configuration file, do the following:

1. Open a new Excel spreadsheet file and label the first three columns in row 1 **hex**, **registers** and **comment**. Notice that the first two columns —**hex** and **registers**— are mandatory. The **comment** column is optional.
2. In the **hex** column (column A), enter the data or address to be assigned to each register. The address and data must be contained in two bytes and must be expressed as a hexadecimal value. Enter one row per register.
3. In the **registers** column (column B), enter the register name associated with the value in the **hex** column.
4. In the **comments** column (column C), enter any comments desired. Data in this column is not processed by the FlexGUI. The image below illustrates a typical register configuration file.

	A	B	C
1	Hex	Registers	Comment
2	C424	BIST	ABIST2_VAUX enabled => Start Vaux ABIST
3	CB0C	INIT_FSSM	IO_23_FS Disabled
4	.	.	.
5	.	.	.
6	.	.	.
7			
8			
9			

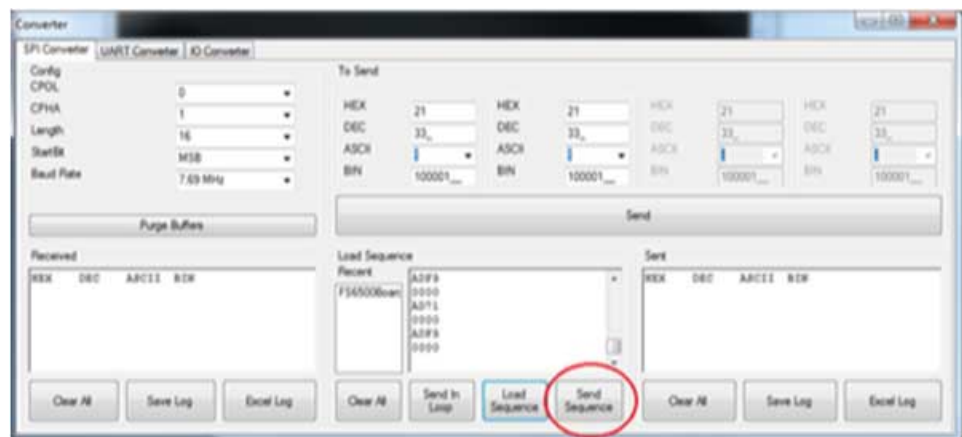
aaa-025557

5. Launch FlexGUI. When FlexGUI opens, click the **Load Sequence** button to load the register configuration file.



aaa-025556

6. Send the register configuration file to the FS45xx/FS65xx by clicking the **Send Sequence** button.



aaa-025645

7.2 Using the FlexGUI

To start the FlexGUI, do the following:

1. Configure the hardware as described in [Section 6.1 "Connecting the hardware"](#).
2. To launch the FlexGUI, execute the .bat file created in [Section 9 "Appendix B: Installing the FlexGUI"](#).

7.3 Use case example

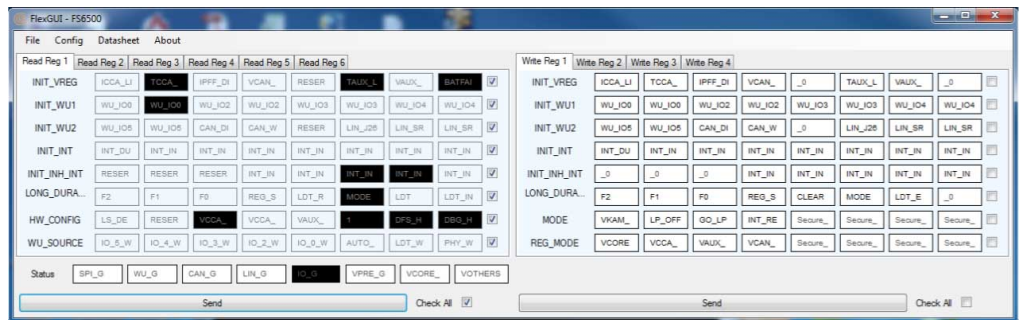
This example assumes the user has configured the hardware as shown in [Figure 13](#) and put the evaluation board into debug mode by placing a connector on jumper J15 (see [Section 6.1](#)). After launching the FlexGUI, the example configures registers to disable IO_23_FS safety mode, disable the watchdog and release the FSx pins.

- Create an Excel file configured as shown in [Table 15](#). For details on creating an Excel register configuration file, see [Section 7.1 "Creating and using a register configuration file"](#)

Table 15. Use case register configuration Excel file example

HEX	Registers	Comment
C465	BIST	Execute ABIST2_VAUX and ABIST2_FS1B
D60C	SF_OUTPUT_REQUEST	Close S1 switch between V _{PRE} and VPU_FS to enable FS1B pull up
CB0C	INIT_FSSM	IO_23_FS Disabled
8900	INIT_INT	Close main machine initialization sequence
D34D	WD_refresh_0	1st Watchdog refresh answer
D29B	WD_refresh_1	2nd Watchdog refresh answer
D237	WD_refresh_2	3rd Watchdog refresh answer
D26E	WD_refresh_3	4th Watchdog refresh answer
D2DC	WD_refresh_4	5th Watchdog refresh answer
D2B9	WD_refresh_5	6th Watchdog refresh answer
D372	WD_refresh_6	7th Watchdog refresh answer
D4A7	RELEASE_FSxB	Release FS0B & FS1B pins

- To use the register configuration file, open FlexGUI, then load the register configuration file and send it to the evaluation board .
- FlexGUI can now be used to read or write any authorized registers. Below is an example of registers contents:



aaa-025558

Get regulators and IO values from IOs tab:



aaa-025559

8 Appendix A: FRDM-KL25Z software loading

The quick start package containing the latest firmware can be downloaded from the Downloads tab of the following webpage:

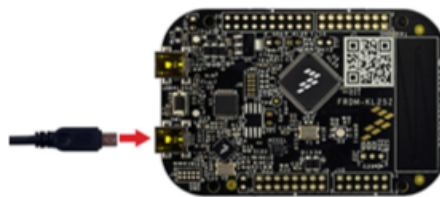
<http://www.nxp.com/FRDM-KL25Z>

Software loading for the FRDM-KL25Z consists of the following:

- Updating the OpenSDA.
- Programming the FRDM-KL25Z

8.1 Updating OpenSDA

1. Press the RST button and connect the USB (the one marked **SDA**) to the PC.



aaa-025593

2. LED D4 will start blinking.
3. Release the RST button.
4. Drag the file **FRDM-KL25Z Quick Start Package\OpenSDA Applications\MSD-DEBUG-FRDM-KL25Z_Pemicro_v105.SDA** and drop it on the KL25Z board icon which appears as a mass storage device on the host PC.



5. Disconnect the board.

8.2 Programming the FRDM-KL25Z

The software bundle for FRDM_FS6500 includes a **USBtest3.hex** file that programs FRDM-KL25Z with the needed firmware. The procedure is as follows:

1. Connect USB (the one marked **SDA**).
2. Drag the file **FRDM_FS6500_Test_Package\FRDM_KL25Z_Flash\USBtest3.hex** and drop it onto the KL25Z board icon that appears as a mass storage device on the host PC.



3. Unplug the mini USB.

9 Appendix B: Installing the FlexGUI

The FlexGUI graphical user interface provides a PC-based interface for accessing the evaluation board and exercising FS45xx/FS65xx functions. The GUI runs on any Windows 8, Windows 7 or Vista operating system.

To install the FlexGUI software:

1. Go to the evaluation board tool summary page
2. Under **Jump Start Your Design**, click on the **Get Started with the FRDMFS65xx** link.
3. From the list of files that appear, click on the **FlexGUI** link. The software downloads to the PC and initiates the installation. An installation wizard guides the user through the process. Upon completion, the GUI executable (FlexGUI.exe), and the relevant register description XML file (in this case, FS65xx.xml) are installed on the system.
4. To simplify launching the FlexGUI, create a .bat file with the following commands:

```
C:\Program Files (x86)\FlexGUI\bin\FlexGUI.exe
```

```
C:\Program Files (x86)\FlexGUI\Sequences&Config\FS65xx.xml
```

10 Schematics, board layout and bill of materials

Board schematics, board layout and bill of materials are available in the download tab of the Tool summary page for the associated board. See [Section 11 "References"](#) for links to the relevant Tool summary pages.

11 References

The following URLs reference related NXP products and application solutions:

NXP.com support pages	Description	URL
FS6500-FS4500	Datasheet	https://www.nxp.com/webapp/Download?colCode=FS6500-FS4500
AN5238 - Hardware design and product guidelines	Application note	https://www.nxp.com/webapp/Download?colCode=AN5238
AN4661 - Designing the VCORE Compensation Network	Application note	http://www.nxp.com/files/analog/doc/app_note/AN4661.pdf
AN4388 - QuadFlat Package (QFP)	Application note	http://www.nxp.com/files/AN4388.pdf
Power dissipation tool (Excel file)	Excel file	http://www.nxp.com/assets/downloads/data/en/calculators/FS6500-FS4500-power-dissipation-calculator.xlsx
VCORE compensation network simulation board (CNC)		Available on demand
FMEDA	FS6500/FS4500FMEDA	Available on demand
FS6500-FS4500SMUG	FS6500-FS4500SMUG safety manual – User Guide	https://www.nxp.com/webapp/Download?colCode=FS6500-%20FS4500SMUG
FRDMFS6522LAEVM	Tool Summary Page	http://www.nxp.com/FRDMFS6522LAEVM
FRDMFS6523CAEVM	Tool Summary Page	http://www.nxp.com/FRDMFS6523CAEVM
FRDMFS4503CAEVM	Tool Summary Page	http://www.nxp.com/FRDMFS4503CAEVM
FRDM-KL25Z	Tool Summary Page	http://www.nxp.com/FRDM-KL25Z
FS6500	Product Summary Page	http://www.nxp.com/FS6500
FS4500	Product Summary Page	http://www.nxp.com/FS4500
Analog home page	NXP website	http://www.nxp.com/analog

12 Contact information

Visit <http://www.nxp.com/support> for a list of phone numbers within your region.

Visit <http://www.nxp.com/warranty> to submit a request for tool warranty.

13 Revision history

Revision	Date	Description of changes
1.0	11/2016	<ul style="list-style-type: none">Initial release
2.0	11/2016	<ul style="list-style-type: none">Removed content, supporting data and external references for FRDMFS6522LAEVM and FRDMFS6522LAEVB in Section 3.1, Section 3.2, Section 3.4, Section 4.1, Table 1, Section 4.2, Section 4.5.4.3, Section 7 and Section 11Updated Section 5.1 to reference Figure 9Updated Section 7.1, item 4 to reference the imageUpdated Section 7.3 referring user to Figure 13, Section 6.1 and Table 15Updated external link found in Section 8Updated URL destinations in Section 11
3.0	6/2017	<ul style="list-style-type: none">Updated content to include FRDMFS6522LAEVM
4.0	6/2017	<ul style="list-style-type: none">Minor correction (replaced FRDM-KL43Z by FRDM-KL25Z) in Section 8

14 Legal information

14.1 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

14.2 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors. In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory. Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification. Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products. NXP Semiconductors does not accept any

liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Suitability for use in automotive applications — This NXP Semiconductors product has been qualified for use in automotive applications. Unless otherwise agreed in writing, the product is not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Evaluation products — This product is provided on an "as is" and "with all faults" basis for evaluation purposes only. NXP Semiconductors, its affiliates and their suppliers expressly disclaim all warranties, whether express, implied or statutory, including but not limited to the implied warranties of non-infringement, merchantability and fitness for a particular purpose. The entire risk as to the quality, or arising out of the use or performance, of this product remains with customer. In no event shall NXP Semiconductors, its affiliates or their suppliers be liable to customer for any special, indirect, consequential, punitive or incidental damages (including without limitation damages for loss of business, business interruption, loss of use, loss of data or information, and the like) arising out of the use of or inability to use the product, whether or not based on tort (including negligence), strict liability, breach of contract, breach of warranty or any other theory, even if advised of the possibility of such damages. Notwithstanding any damages that customer might incur for any reason whatsoever (including without limitation, all damages referenced above and all direct or general damages), the entire liability of NXP Semiconductors, its affiliates and their suppliers and customer's exclusive remedy for all of the foregoing shall be limited to actual damages incurred by customer based on reasonable reliance up to the greater of the amount actually paid by customer for the product or five dollars (US\$5.00). The foregoing limitations, exclusions and disclaimers shall apply to the maximum extent permitted by applicable law, even if any remedy fails of its essential purpose.

Translations — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

14.3 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

NXP — is a trademark of NXP B.V.

Tables

Tab. 1.	EVMs supporting the FS45xx/FS65xx family5	Tab. 9.	CAN & LINconnector (J3) 13
Tab. 2.	FS45xx/FS65xxfeatures 7	Tab. 10.	USB connector (J33) 13
Tab. 3.	Board description 8	Tab. 11.	I/O connector (J1_FRDM) 14
Tab. 4.	LEDs9	Tab. 12.	Power supply connector (J2) 14
Tab. 5.	Jumper definitions 10	Tab. 13.	KL25Z Analog regulator inputs (J10_FRDM)	... 15
Tab. 6.	Test point definitions 11	Tab. 14.	SW1 16
Tab. 7.	VBAT Phoenix connector (J1) 12	Tab. 15.	Use case register configuration Excel file example 25
Tab. 8.	SPI connector (J2_FRDM) 12			

Figures

Fig. 1.	FRDMFS6523CAEVM 1	Fig. 8.	Switches 16
Fig. 2.	FRDMFS65/FRDMFS45 block diagram 6	Fig. 9.	VCCA and VAUX voltage settings 17
Fig. 3.	Evaluation board description 8	Fig. 10.	VAUX regulator 17
Fig. 4.	LEDs9	Fig. 11.	VCORE configuration 18
Fig. 5.	Jumpers 10	Fig. 12.	FCRBM Resistor Bridge 19
Fig. 6.	Test points 11	Fig. 13.	Evaluation board hardware configuration 21
Fig. 7.	Connectors 12	Fig. 14.	Software overview 22

Contents

1	FRDMFS4503CAEVM, FRDMFS6523CAEVM and FRDMFS6522LAEVM evaluation boards	1
2	Important notice	2
3	Getting started	3
3.1	Jump start	3
3.2	Kit contents/packing list	3
3.3	Required equipment	3
3.4	EVM overview	4
4	Board description	5
4.1	Board overview	5
4.2	Board features	5
4.3	Block diagram	6
4.4	Device features	7
4.5	Getting to know the hardware	7
4.5.1	LED display	9
4.5.2	Jumper definitions	10
4.5.3	Test point definitions	10
4.5.4	Connectors	11
4.5.4.1	VBAT connector (J1)	12
4.5.4.2	SPI connector (J2_FRDM)	12
4.5.4.3	CAN and LIN connector (J3)	13
4.5.4.4	Debug connector (J9_FRDM)	13
4.5.4.5	I/O connector (J1_FRDM)	14
4.5.4.6	Power supply connector (J2)	14
4.5.4.7	KL25Z ADC inputs (J10_FRDM)	15
4.5.5	Switches	16
5	Board default settings	17
5.1	VCCA and VAUX setting	17
5.2	VCORE settings and related configurations	17
5.2.1	VCORE and F45xx versus FS65xx	17
5.2.2	Compensation network	18
5.2.3	FCRBM Resistor Bridge	18
5.2.4	MCU analog input	19
6	Configuring the EVM	20
6.1	Connecting the hardware	20
7	Software	22
7.1	Creating and using a register configuration file	23
7.2	Using the FlexGUI	24
7.3	Use case example	24
8	Appendix A: FRDM-KL25Z software loading	26
8.1	Updating OpenSDA	26
8.2	Programming the FRDM-KL25Z	27
9	Appendix B: Installing the FlexGUI	28
10	Schematics, board layout and bill of materials	29
11	References	30
12	Contact information	30
13	Revision history	31
14	Legal information	32

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2017.

All rights reserved.

For more information, please visit: <http://www.nxp.com>
For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 12 June 2017

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

[NXP:](#)

[FRDMFS6522LAEVM](#) [FRDMFS4503CAEVM](#) [FRDMFS6523CAEVM](#)