Open746I-C Package B



# Introduction

STM32 development board designed for STM32F746I, features the STM32F746IGT6 MCU, and integrates various standard interfaces, pretty easy for peripheral expansions.

## More

# **Getting Started with modules**

We provide various modules for Open746I-C development board aiming to improve your development efficiency. These modules are not only designed for STM32 but also can be used for many other MCU platforms. Let's begin with the demos.

## **Development Environment**

- KEILMDK Version : 5.12 or above.
- Programmer/Debugger: ST-LINK V2
- Programming/Debugginginterface:JTAG/SWD
- Results of demo which based on serial port are all checked via onboard CP2102; connect the USB cable to the USART1 interface.
- Serial port settings:

Baud rate	115200
Data bits	8
Stop bits	1
Parity bits	None
Flow control	None

Note: All the below Demo results are available when push the reset button after program downloaded.

#### Conventions

• The following table provides the conventions used for the ON and OFF settings in the present document.

Convention	Definition
Jumper JP1 ON	Jumper fitted
Jumper JP1 OFF	Jumper not fitted

#### **Sample Program Description**

#### • LED:

Name	Description	Hardware Connection	Expected result
LED	GPIO output.	LED JMP ON	LED1 to LED4 will be turned on in sequence.

## • KEY:

Name	Description	Hardware Connection	Expected result
VEV	GPIO	LED JMP ON, KEY	The LED status will keep changing when
KE I	input/output.	JMP ON	push the buttons.

## • Interrupt:

Name	Description	Hardware Connection	Expected result
Intomunt	GPIO	LED JMP ON, KEY JMP	LED1 status will be changed by the button
Interrupt	interrupt.	ON	pressed.

#### • TIM:

Name	Description	Hardware Connection	Expected result
TIM	Timer.	LED JMP ON	LED1 flashes.

#### • PWM:

Name	Description	Hardware Connection	Expected result
PWM	Using PWM timer.	LED JMP ON	LED1 status changes gradually.

#### • USART:

Name	Description	Hardware Connection	Expected result
USART_Printf	Retarget the <i>printf</i> function using HAL polling.	Connect the on-board UART1 to a PC with a USB cable. UART1 interface is connected to USART1 by default, which can be changed to other USART interface by setting UART1 JMP.	Download the program and press RESET button. Serial output: UART Printf Example: retarget the C library printf function to the UART welcome to www.waveshare.com !!!
USART_IT	HAL interrupt for UART.	Ditto.	Download the program and press RESET button, then enter 10 characters (e.g. Open7XXI-C) and send them. Serial output: ****UART-Hyperterminal communication based on IT **** Enter 10 characters using keyboard: Open7XXI-C Example Finished
USART_DMA HAL DMA for UART.		Ditto.	Download the program and press RESET button. Serial output: **** UART-Hyperterminal communication based on DMA *** WaveShare Open7XXI-C

_		
		Board
-		

## • ADC+DMA:

Name	Description	Hardware Connection	Expected result
ADC+DMA	AD acquisition demo, DMA transfer.	Connect Analog Test Board to SPI1 (ADC+DAC) connector. Image	Rotate the onboard potentiometer. Serial output: ******* ADC DMA Example ******* AD1 value = 3.298V AD2 value = 1.647V ******* ADC DMA Example ******* AD1 value = 3.298V AD2 value = 1.647V

#### • DAC:

Name	Description	Hardware Connection	Expected result
DAC	DA output demo, output via DMA channel.	Connect the Analog Test Board to the SPI1 (ADC+DAC) connector. Connect the Analog Test Board onboard 5V interface to the board onboard 5V interface via jumper wire. <u>Image</u>	You may hear sound from the Analog Test Board.

## • I2C-AT24C02:

Name	Description	Hardware Connection	Expected result
I2C- AT24C02	Read and write data on E2PROM via I2C protocol.	Connect the AT24/FM24 Board to the board via I2C connector (I2C1or I2C2, depending on the software configuration). Image	Serial output: ************************************

## • SPI-W25QXX:

Name	Description	Hardware Connection	Expected result
SPI- W25QXX	Drive the W25QXX DataFlash Board via SPI interface.	Connect the W25QXX DataFlash Board to SPI1 connector. <u>Image</u>	Serial output: SPI-W25Qxxx Example W25Qxxx ID is : 0xEF 0x17 QSPI Erase Block ok QSPI Write ok QSPI Read ok QSPI Read Data : 0x00 0x01 0x02

	0x03 0x04 0xFF W250128EV 0wodSDI
	Test OK

## • CAN:

Name	Description	Hardware Connection	Expected result
CAN	CAN modules communication.	Connect the two CAN modules to the onboard CAN1 and CAN2 interface. Connect the two CAN modules via jumper wire (CANL <-> CANL, CANH <-> CANH) Image	Serial output: **** This is CAN test program **** StdId : 123 RxMsg : CAN Test StdId : 123 RxMsg : CAN Test Test

## • PWR:

Name	Description	Hardware Connection	Expected result
PWR	STM32 low power mode demo.		Press the WAKEUP button to enter Stop Mode, in this case, LED1 stops flashing. Press the WAKEUP button again or wait 20s to quit Stop Mode, in this case LED1 flashes. (Note: You can modify the macro definition in stm32f7xx_lp_modes.h for choosing different low power modes.) Serial output: ******* STM32F7 LowPower Test ****** Press button to enter LP modes StopMode! Automatic Wake-up using RTC clocked by LSI (after ~20s) StopMode wake up , system running continue Press button to enter LP modes

## • RTC:

Name	Description	Hardware Connection	Expected result
RTC	Real-Time Clock in the STM32 MCU.		You can modify the MX_RTC_Init function in rtc.c to set the time. Serial output: 2015/09/08 18:50:00 2015/09/08 18:50:01

## • MCU TEMPERATURE:

Name	Description	Hardware Connection	Expected result
MCU	STM32 inner temperature		Serial output:

TEMPERATURE	measurement.	MCU Temperature	:
		MCU Temperature	:
		MCU Temperature	:

#### • IWDG:

Name	Description	Hardware Connection	Expected result
IWDG	Independent watchdog program.		Serial output: ***** WaveShare Open7XXI-C Board ***** Refreshes the IWDG !!! Refreshes the IWDG !!! Refreshes the IWDG !!!

### • WWDG:

Name	Description	Hardware Connection	Expected result
WWDG	Window watchdog program.		<pre>If the watch dog is not updated, the program will restart. Serial output: ***** WaveShare Open7XXI-C Board ***** waveshare.net !!! waveshare.net !!! waveshare.net !!!</pre>

## • RNG:

Name	Description	Hardware Connection	Expected result
			Generates a 32-bit random number. Serial
	Random number generator.		output:
			Random 32bit Numbers :
			0x3664130B !!!
RNG			Random 32bit Numbers :
10,00			0xFF7D82B4 !!!
			Random 32bit Numbers :
			0xD1BAFF04 !!!
			Random 32bit Numbers :
			0xAAC48854 !!!

## • CRC:

Name	Description	Hardware Connection	Expected result
CRC	CRC checking.		<b>Serial output:</b> ****** CRC Test Example ***** CRC right value

• SDIO:

Name	Description	Hardware Connection	Expected result
SDIO	Read and write SD card.	Connect the Micro SD Storage Board to the board via SDIO interface. Insert the SD card to the Micro SD Storage Board socket. <u>Image</u>	Warning: This program may erase all the TF card data. Make sure you have backed up. Serial output: Warning: this program may erase all the TF card data. Make sure you have backed up. Press 'y' to continue. Initialize SD card successfully! SD card information! CardCapacity : 8053063680 CardBlockSize : 512 RCA : 2 CardType : 2 Enable wide bus operation successfully! Write block successfully! 00:0x15151515 01:0x15151515 7f:0x15151515 Read block successfully! 00:0x15151515 01:0x1515155 7f:0x15151515 Erase block successfully! Read block successfully! 00:0xfffffff 01:0xffffffff 7f:0xfffffff

## • FATFS:

Name	Description	Hardware Connection	Expected result
FATFS	Read and write SD card, of which file system is FAT.	Connect the Micro SD Storage Board to the board via SDIO interface. Insert the SD card to the Micro SD Storage Board socket. Image	Note: Please first make sure the FATFS file system is exist in your SD card. Serial output: ****** FatFs Example ****** Mounted successfully!!! Opened file successfully!!! Wrote successfully!!! Write Data : This is STM32 working with FatFs Closed successfully!!! Opened file successfully!!! Read successfully!!! Read successfully!!! Read Data : This is STM32 working with FatFs Closed successfully!!! FatFs is working well!!!

## • DCMI-OV2640:

Name	Description	Hardware Connection	Expected result
DCMI- OV2640	The camera snaps pictures.	Connect the OV2640 Camera Board to the onboard DCMI interface. Run the software	Press WAKE UP button to take a picture. <u>Image</u> (Note: You can modify the OV2640_320x240_JPEG parameters

<i>camera test.exe</i> (in the	in ov2640.c for changing the resolution
Software directory). Choose a	of a image.)
COM port and set parameters.	
Image	

#### • I2S-UDA1380:

Name	Description	Hardware Connection	Expected result
I2S- UDA1380	Drive the UDA1380 Board to play music via I2S protocol	Connect the UDA1380 Board to the board via I2S interface. Connect an earphone to the UDA1380 Board via LINEOUT connector. Image	Press RESET button to play music. Serial output: Welcome to use UDA1380 I2S test: WaveDataLength:1003324 UDA1380 Init OK! AudioRemSize:370563 AudioRemSize:305028 AudioRemSize:239493 AudioRemSize:173958 AudioRemSize:108423 AudioRemSize:42888 AudioRemSize:0 The data is completely transmitted.

#### • SAI:

Name	Description	Hardware Connection	Expected result
SAI	Drive the UDA1380 Board to play music via SAI interface.	Connect UDA1380 Board to the board via SAI1 interface. Connect the earphone to the UDA1380 Board via LINEOUT connector. <u>Image</u>	Press RESET button to play music. Serial output: Welcome to use UDA1380 SAI test: UDA1380 Init OK! Data transmission begin AudioRemSize:370485 AudioRemSize:304950 AudioRemSize:239415 AudioRemSize:108345 AudioRemSize:108345 AudioRemSize:0 The data is completely transmitted.

## • FSMC-NANDFLASH:

Name	Description	Hardware Connection	Expected result
FSMC- NANDFLASH	Read and write NAND FLASH via FMC.	Connect the Nand Flash Board to the board via 8BIT FMC interface. Image	Serial output: ***** NandFlash Example ***** Nand Flash ID = 0xEC,0xF1,0x00,0x95 Type = K9F1G08U0B Written to the number of: 0x00 0x01 0x02 0x03 0xFF

	Read several: 0x00 0x01 0x02 0x03
	OxFF NandFlash Read Write Test OK

## • FSMC-SDRAM:

Name	Description	Hardware Connection	Expected result
			Serial output: ****** SDRAM example !!! *****
FSMC- SDRAM	Read and write SDRAM via FMC.		<pre>/* Write data to the SDRAM memory */ 00:0xA244250F 01:0xA2442510 FF:0xA244260E /* Read back data from the SDRAM memory */ 00:0xA244250F 01:0xA2442510 FF:0xA244260E SDRAM Test OK</pre>

## • LDTC:

Name	Description	Hardware Connection	Expected result
LDTC	LCD display demos. These 3 demos, 4.3inch 480x272, 7inch 800x600 and 7inch 1024x600, are used for 3 kinds of LCD separately.	For 4.3inch 480x272 Touch LCD (B) module: Connect it to the LCD interface. For 7inch 800x600 LCD or 7inch 1024x600 LCD, connect it to the FFC LCD interface with a FFC cable. (Note: multiple LCDs are not allowed to connect at the same time.)	Static pictures are shown on the LCD.

## • DMA2D:

Name	Description	Hardware Connection	Expected result
DMA2D	This LCD display demo is compatible with 4.3inch 480x272, 7inch 800x480 and 7inch 1024x600 LCD to show dynamic pictures.	For 4.3inch 480x272 Touch LCD (B) module: Connect it to the LCD interface. For 7inch 800x600 LCD or 7inch 1024x600 LCD, connect it to the FFC LCD interface with a FFC cable. (Note: multiple LCDs are not allowed to connect at the same time.)	LCD shows 2 moving and stacked pictures. • <u>4.3inch</u> <u>480x272</u> <u>Display</u> • <u>7inch 800x480</u> <u>and 7inch</u> <u>1024x600 LCD</u> <u>Display</u>

## • LCD\_DISPLAY:

Name	Description	Hardware Connection	Expected

			result
LCD_DISPLAY	This LCD display demo is compatible with 4.3inch 480x272, 7inch 800x480 and 7inch 1024x600 LCD to show characters.	For 4.3inch 480x272 Touch LCD (B) module: Connect it to the LCD interface. For 7inch 800x600 LCD or 7inch 1024x600 LCD, connect it to the FFC LCD interface with a FFC cable. (Note: multiple LCDs are not allowed to connect at the same time.)	Characters are shown on the LCD. <u>Image</u>

#### • Touch:

This LCD display demo is compatible with 4.3inch 480x272 (Resistive), 7inch 800x480 (Capacitive) and 7inch 1024x600 (Capacitive) LCD.

Name	Description	Hardware Connection	Expected result
Touch 4.3inch 480x272	This demo is used for 4.3inch 480x272 (Resistive) LCD.	Connect a 4.3inch 480x272 Touch LCD (B) module to the LCD interface.	Tap the Adjust area for calibration and then goto a sketchpad interface, on which you can paint with different colors. <u>Image</u>
Touch 7inch 800x480 / Touch 7inch 1024x600	This demo is used for 7inch 800x480 / Touch 7inch 1024x600 (Capacitive) LCD.	Connect the LCD to the FFC LCD interface with a FFC cable.	The LCD shows the tapped locations up to 5. <u>Image</u>

## • STemWin:

Name	Description	Expected result	
	STemWin	This demo is compatible with 4.3 inch	The LCD shows
STemWin	interlayer	480x272, 7inch 800x480 and 7inch	STemWin demo GUI
	migration GUI	1024x600 LCD but you should download	which looks so cool.
	program.	the corresponding project.	<u>Image</u>

## • USB FS:

Name	Description	Hardware Connection	Expected result
		• OTG JMP ON, UART1 JMP	Please unzip and install the driver, stsw.zip, in the
	USB FS	OFF. By	Software directory and
	device CDC	default, you	your PC will recognize
	demo. Your	should connect	the board as a
USB FS Device	PC will	a 7 inch	"STMicroelectronics
(CDC_Standalone)	recognize the	1024x600	Virtual COM Port" which
	board as a	LCD to your	is listed on the Device
	Virtual COM	board, but the	Manager. Information sent
	Port.	program	from PC through COM
		should be	Port will be shown on the
		modified	LCD. For example, what

		<ul> <li>appropriately for other LCD.</li> <li>Connect the core board USB port to your PC using a micro USB cable. <u>Image</u></li> </ul>	you sent: WaveShare Open7XXI-C Board STM32 Virtual COM Port Driver WaveShare Open7XXI-C Board STM32 Virtual COM Port Driver WaveShare Open7XXI-C Board STM32 Virtual COM Port Driver what you get: Image
USB FS Device (HID_Standalone)	USB FS device HID demo. Your PC will recognize the board as a mouse.	Ditto.	A new mouse will be listed on the Device Manger and you can move the onboard joystick to control the cursor on PC. Image
USB FS Device (MSC_Standalone)	USB FS device MSC demo. Your PC will recognize the board as a USB drive.	Ditto. Besides, you shall connect a Micro SD Storage Board, with a Micro SD card inserted, to the SDIO interface.	A "USB Mass storage device" will be listed on the Device Manager and a removable hard drive will appear on "this PC". Image
USB FS Host (HID_STandalone)	USB FS host HID demo. The board can recognize a mouse device.	OTG JMP ON, UART1 JMP OFF. By default, you should connect a 7 inch 1024x600 LCD to your board, but the program should be modified appropriately for other LCD.	Connect a mouse to the core board with a OTG cable (type A to micro USB) and then the green dot on the LCD will move following the mouse. Image
USB FS Host (MSC_STandalone)	USB FS host MSC demo. The board can recognize a USB drive.	Ditto.	Connect a USB flash drive to the core board with a OTG cable (type A to micro USB), then press the User button to get the info of your USB drive and directories. <u>Image</u>
USB FS Host (DynamicSwitch_Standalone)	USB FS host Dynamic Switch demo. Using the same program, the board can recognize a USB drive or a mouse	Ditto.	The board can recognize either a USB drive or a mouse device in use. <u>Image of using USB drive</u>

		device.		
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#### • USB HS:

Name	Description	Hardware Connection	Expected result
USB HS Device (HID_STANdalone)	USB HS Device HID demo. Your PC will recognize the board as a mouse.	<ul> <li>Connect a USB3300 module to the ULPI interface.</li> <li>Connect the OTG port, on the USB3300 module, to your PC with a OTG cable (type A to mini USB).</li> <li>Image</li> </ul>	A new mouse will be listed on the Device Manger and you can move the onboard joystick to control the cursor on PC.
USB HS Device (MSC_Standalone)	USB HS Device MSC demo. Your PC will recognize the board as a USB drive.	Ditto. Besides, you shall connect a Micro SD Storage Board, with a micro SD card inserted, to the SDIO interface.	A "USB Mass storage device" will be listed on the Device Manager and a removable hard drive will appear on "this PC".
USB HS Host (MSC_Standalone)	USB HS Host MSC demo. The board can recognize a USB drive.	Connect a USB3300 module to the ULPI interface.	Connect a USB flash drive to the USB3300 module with a OTG cable (type A to mini USB), then press the User button to list the files of your USB drive.

## • ETH:

Name	Description	Hardware Connection	Expected result
LwIP_TCP_Echo_Client	TCP echo client demo.	<ul> <li>Copy the echotool.exe to the root directory of Drive C:</li> <li>Connect a DP83848 module to the ETH interface.</li> <li>Connect the DP83848 module to a router of a LAN or connect to a PC directly with a cable.</li> </ul>	<ul> <li>Please ensure that the remote PC IP address is the same IP address as the one defined in the mxconstants.h file (192.168.1.189 by default).</li> <li>Run the Command Prompt (Win + R then run the command <i>cmd</i>).</li> <li>At the command prompt, enter:</li> <li>C:\&gt;echotool /p tcp /s</li> </ul>

			<ul> <li>where: <ul> <li>/p tcp is the TCP</li> <li>protocol (TCP</li> <li>protocol)</li> <li>/s is the actual</li> <li>mode of connection</li> <li>(Server mode)</li> </ul> </li> <li>When you press the User button on the board, the client sends a string and the server echoes back the same string to the client.</li> </ul>
			Image
LwIP_TCP_Echo_Server	TCP echo server demo.	Ditto.	<ul> <li>At the command prompt, enter:</li> <li>C:\&gt;echotool IP_address /p tcp /r 7 /n 15 /t 2 /d Testing LwIP TCP echo server where         <ul> <li>IP_address is the actual board's IP address. By default, the following static IP address is used:</li> <li>192.168.1.189             <li>-/p tcp is the protocol (TCP protocol)</li> <li>-/r is the actual remote port on the echo server (echo port)</li> <li>-/n is the number of echo requests (for example, 15)</li> <li>-/t is the connection timeout in seconds (for example, 2)</li> <li>-/d is the message to be sent for echo (for example, "Testing LwIP TCP echo server")</li> </li></ul> </li> </ul>
LwIP_UDP_Echo_Client	UDP echo	Ditto.	• Please ensure that the

	client demo.			remote PC IP address
	enent demo.			is the same IP
				address as the one
				defined in the
				mxconstants.h file
				(192.168.1.189 by
				default).
			•	Run the Command
				Prompt (Win + R
				then open <i>cmd</i> ).
			•	At the command
				prompt, enter:
				C:\>echotool /p
				udp/s
				where: /n udn is the LIDP
				-/p uup is the ODP
				protocol)
				-/s is the actual
				mode of connection
				(Server mode)
			•	When you press the
				User button on the
				board, the client
				sends a string and the
				the same string to the
				client
				chem.
				Image
			•	At the command
				prompt, enter:
				C:\>echotool
				IP_address /p udp
				/r 7 1/ 7 /n 15 /t 2 /d Testing
				LwIP UDP echo
				server
				where
LwIP UDP Echo Server	UDP echo	Ditto.		– IP_address is the
	server demo.			actual board's IP
				address. By default,
				IP address is used:
				192 168 1 189
				-/n udn is the
				protocol (UDP
				protocol)
				-/r is the actual
				remote port on the

LwIP_HTTP_Server_Raw   Name   FreeRTOS   STM32cubeM2   as threads, mutiand so on.	Httpserver demo. Descri ased on the ex X. This demo of exes, queues, a Description	<ul> <li>to the ETH interface.</li> <li>Connect the DP83848 module to a router of a LAN or connect to a PC directly with a cable.</li> <li>Image</li> <li>By default, you should connect a 7 inch 1024x600 LCD to your board, but the program should be modified appropriately for other LCD.</li> </ul> ption amples generated by contains 11 examples suc signals, messages, timers	<ul> <li>LCD sc indicatin or failur DHCP I allocatic example 192.168</li> <li>Image</li> <li>On the roopen a vertice of the H demo</li> <li>You car control LED staboard.</li> <li>Hardware Connection</li> <li>Hardware Connection</li> </ul>	reen ng the success re of the IP address on (for e, 3.1.160). remote PC, web client and board's IP in a web : Home page ITTP server n click <i>LED</i> to change the atus on the <b>Expected</b> result <b>Expected</b> result
	Connect a     DP83848 module     to the ETH     interface.     Connect the     DP83848 module     to a router of a     LAN or connect		echo ser port) -/l is th port for (echo po -/n is th echo rec example -/t is th timeout (for exa -/d is th be sent : example LwIP U server") <u>Image</u> • A messa displaye LCD sc indicatin or failun DHCP I	ever (echo e actual local the client ort) he number of quests (for e, 15) he connection in seconds mple, 2) he message to for echo (for e, "Testing DP echo age is ed on the reen ng the success re of the IP address

uCOS	This demo shows the uCOS III OS which is based on		LED1
III	the HAL libraries generated by STM32cubeMX.	LED JMP ON	flashes.

## Resource

- <u>Core746I Schematic</u>
- <u>Open746I-C Schematic</u>
- <u>Demo</u>

#### STM32 Software

#### IDE

- <u>Keil MDK</u>
- <u>STM32CubeMX</u>

#### Programmers

- Flash Loader for ISP
- <u>STVP</u>
- <u>STM32 ST LINK Utility</u>

#### **USB Driver**

- PL2303 Windows Driver
- <u>ST-Link V2 USB Driver</u>
- <u>Virtual\_COM\_Port\_Driver</u>

#### **Other Software**

- <u>Stlinkupgrade</u>
- TCP UDP Debugger
- IpTool
- <u>EMWToolBox\_Setup</u>
- <u>BonjourSetup</u>
- <u>SecureCRT</u>
- <u>Camera test</u>
- <u>BusHound</u>

#### STM32F7 Datasheets

- <u>STM32F745\_STM32F746-Datasheet</u>
- <u>STM32F7-Reference-EN</u>
- <u>STM32F7xx HAL drivers</u>

#### **STM32 Documents**

#### ST libraries

• <u>STM32\_I2C\_CPAL.7z</u>

#### **UCOS Source**

• <u>UCGUI3.90\_Source.zip</u>

# Support



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Our working time: 09:00-18:00 (UTC+8 Monday to Saturday)