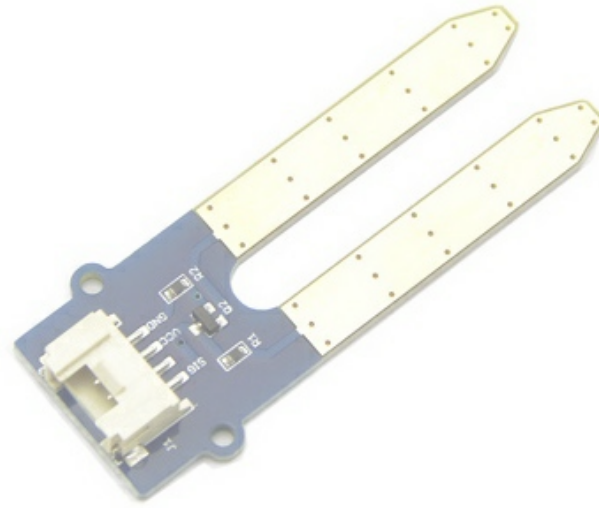


## Grove - Moisture Sensor



This Moisture Sensor can be used for detecting the moisture of soil or judge if there is water around the sensor, let the plant in your garden able to reach out for human's help when they are thirsty. This sensor is very easy to use, you can just simply insert in into the soil and read the data. With this sensor, you can make a small project that can let the plant send a message to you like " I am thirsty now, please feed me some water."

### Version

Product Version	Changes	Released Date
Grove - Moisture Sensor V1.4	Initial	June 2014

### Features


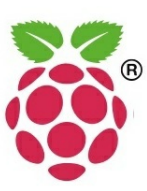
- Soil moisture sensor based on soil resistivity measurement
- Easy to use
- 2.0 cm X 6.0 cm grove module

**Tip**  
More details about Grove modules please refer to [Grove System](#)

### Specification

Item	Condition	Min	Typical	Max	Unit
Voltage	-	3.3	-	5	V
Current	-	0	-	35	mA
Output Value	Sensor in dry soil	0	-	300	-
	Sensor in humid soil	300	-	700	-
	Sensor in water	700	-	950	-

### Platforms Supported

Arduino	Raspberry Pi		
			

**Caution**  
The platforms mentioned above as supported is/are an indication of the module's software or theoretical compatibility. We only provide software library or code examples for Arduino platform in most cases. It is not possible to provide software library / demo code for all possible MCU platforms. Hence, users have to write their own software library.

## Application Ideas

- Botanical Gardening
- Moisture Sensoring
- Consistency Measurement

## Getting Started

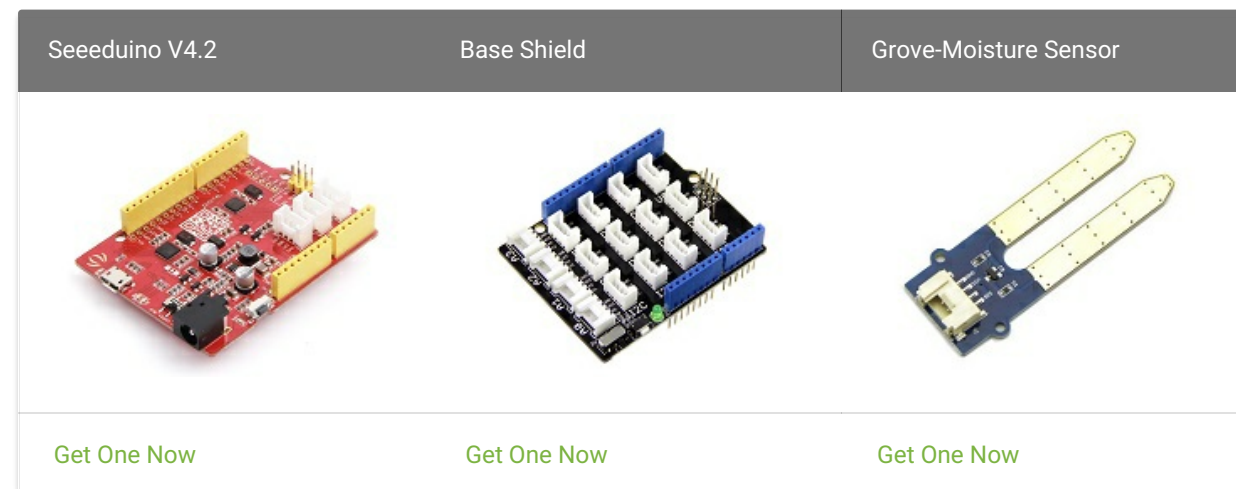
### Note

If this is the first time you work with Arduino, we firmly recommend you to see [Getting Started with Arduino](#) before the start.

## Play With Arduino

### Hardware

- Step 1. Prepare the below stuffs:



- Step 2. Connect Grove-Moisture Sensor to port A0 of Grove-Base Shield.
- Step 3. Plug Grove - Base Shield into Seeeduino.
- Step 4. Connect Seeeduino to PC via a USB cable.



### Note

If we don't have Grove Base Shield, We also can directly connect Grove-Moisture Sensor to Seeeduino as below.

Seeeduino	Grove-Moisture Sensor
5V	Red
GND	Black
Not Conencted	White
A0	Yellow

### Software

- Step 1. Copy the code into Arduino IDE and upload. If you do not know how to upload the code, please check [how to upload code](#).

```
int sensorPin = A0;
int sensorValue = 0;

void setup() {
  Serial.begin(9600);
}
void loop() {
  // read the value from the sensor:
  sensorValue = analogRead(sensorPin);
  Serial.print("Moisture = ");
  Serial.println(sensorValue);
  delay(1000);
}
```

- Step 2. We will see the moisture display on terminal as below.

```
Moisture = 0
Moisture = 31
Moisture = 48
Moisture = 139
Moisture = 155
Moisture = 124
Moisture = 236
Moisture = 218
Moisture = 215
Moisture = 221
```

### Play with Codecraft

#### Hardware

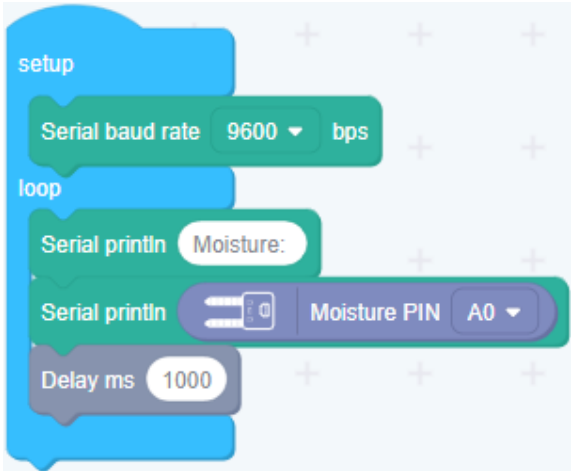
- Step 1. Connect a Grove - Moisture Sensor to port A0 of a Base Shield.
- Step 2. Plug the Base Shield to your Seeeduino/Arduino.
- Step 3. Link Seeeduino/Arduino to your PC via an USB cable.

#### Software

- Step 1. Open [Codecraft](#), add Arduino support, and drag a main procedure to working area.

Note  
If this is your first time using Codecraft, see also [Guide for Codecraft using Arduino](#).

- Step 2. Drag blocks as picture below or open the cdc file which can be downloaded at the end of this page.



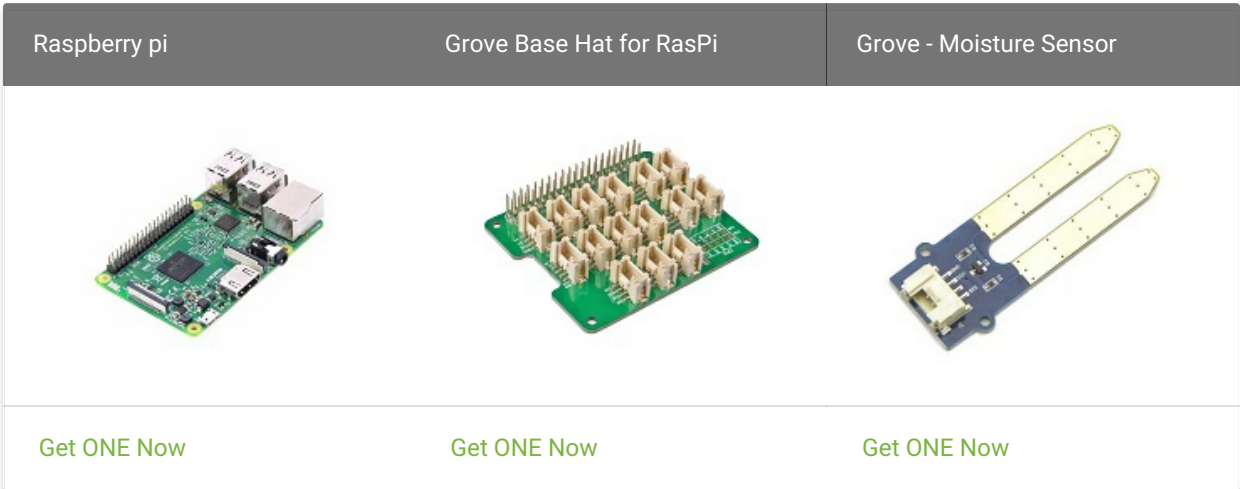
Upload the program to your Arduino/Seeeduino.

Success  
When the code finishes uploaded, you will see the moisture value displayed in the Serial Monitor.

### Play With Raspberry Pi (With Grove Base Hat for Raspberry Pi)

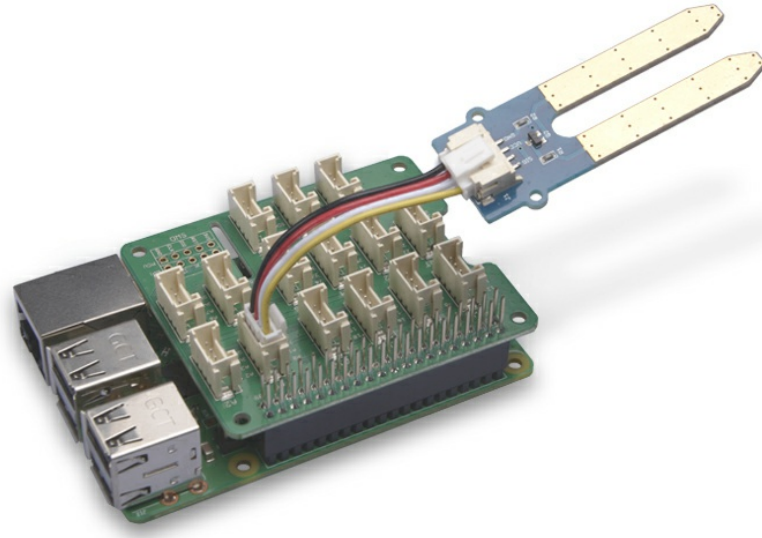
#### Hardware

- Step 1. Things used in this project:



- Step 2. Plug the Grove Base Hat into Raspberry Pi.
- Step 3. Connect the Grove - Moisture Sensor to the A0 port of the Base Hat.

- Step 4. Connect the Raspberry Pi to PC through USB cable.



#### Software

- Step 1. Follow [Setting Software](#) to configure the development environment.
- Step 2. Download the source file by cloning the grove.py library.

```
cd ~  
git clone https://github.com/Seeed-Studio/grove.py
```

- Step 3. Excute below command to run the code.

```
cd grove.py/grove  
python grove_moisture_sensor.py 0
```

Following is the grove\_moisture\_sensor.py code.

```

#!/usr/bin/env python
# -*- coding: utf-8 -*-
#
# The MIT License (MIT)
#
# Grove Base Hat for the Raspberry Pi, used to connect grove sensors.
# Copyright (C) 2018 Seeed Technology Co.,Ltd.
'''
This is the code for
- Grove - Moisture Sensor <https://www.seeedstudio.com/Grove-Moisture-Sensor-p-955.html>`_
'''

Examples:

.. code-block:: python

import time
from grove.grove_moisture_sensor import GroveMoistureSensor

# connect to analog pin 2(slot A2)
PIN = 2

sensor = GroveMoistureSensor(PIN)

print('Detecting moisture...')
while True:
    m = sensor.moisture
    if 0 <= m and m < 300:
        result = 'Dry'
    elif 300 <= m and m < 600:
        result = 'Moist'
    else:
        result = 'Wet'
    print('Moisture value: {0}, {1}'.format(m, result))
    time.sleep(1)
'''

import math
import sys
import time
from grove.adc import ADC

__all__ = ["GroveMoistureSensor"]

class GroveMoistureSensor:
    '''
    Grove Moisture Sensor class

    Args:
        pin(int): number of analog pin/channel the sensor connected.
    '''
    def __init__(self, channel):
        self.channel = channel
        self.adc = ADC()

    @property
    def moisture(self):
        '''
        Get the moisture strength value/voltage

        Returns:
            (int): voltage, in mV
        '''
        value = self.adc.read_voltage(self.channel)
        return value

Grove = GroveMoistureSensor

def main():
    from grove.helper import SlotHelper
    sh = SlotHelper(SlotHelper.ADC)
    pin = sh.argv2pin()

    sensor = GroveMoistureSensor(pin)

    print('Detecting moisture...')
    while True:
        m = sensor.moisture
        if 0 <= m and m < 300:
            result = 'Dry'
        elif 300 <= m and m < 600:
            result = 'Moist'
        else:
            result = 'Wet'
        print('Moisture value: {0}, {1}'.format(m, result))
        time.sleep(1)

if __name__ == '__main__':
    main()

```

Success

If everything goes well, you will be able to see the following result:

```
pi@raspberrypi:~/grove.py/grove $ python grove_moisture_sensor.py 0
Detecting moisture...
Moisture value: 0 Dry
Moisture value: 1 Dry
Moisture value: 25 Dry
Moisture value: 3 Dry
Moisture value: 0 Dry
Moisture value: 0 Dry
Moisture value: 0 Dry
Moisture value: 0 Dry
Moisture value: 0 Dry
Moisture value: 1 Dry
^C
Traceback (most recent call last):
  File "grove_moisture_sensor.py", line 74, in <module>
    main()
  File "grove_moisture_sensor.py", line 71, in main
    time.sleep(1)
KeyboardInterrupt
```

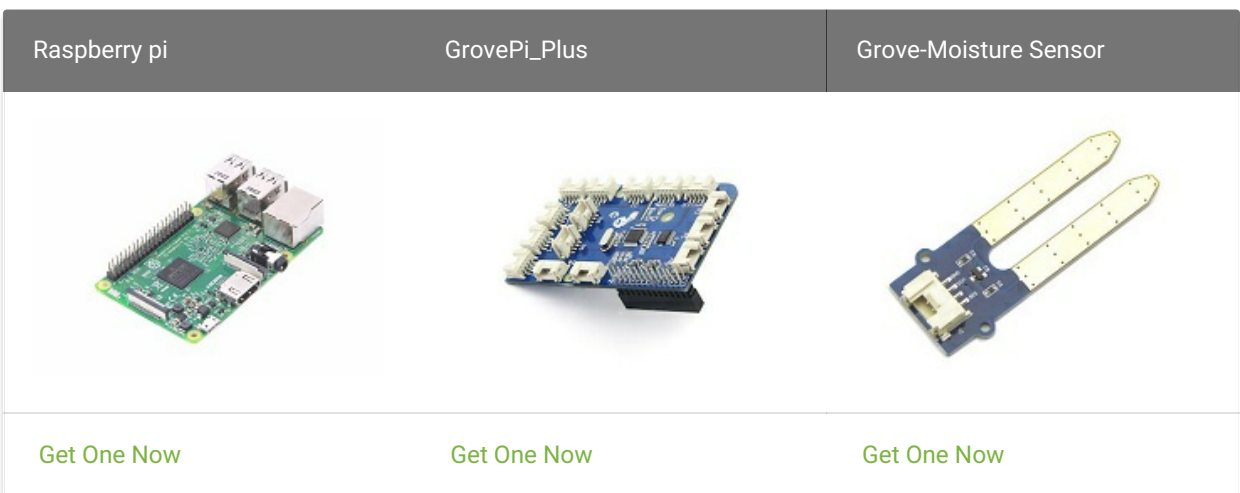
You can use this sensor to detect the air quality. Press `Ctrl+C` to quit.

**Notice**  
You may have noticed that for the analog port, the silkscreen pin number is something like A1, A0, however in the command we use parameter 0 and 1, just the same as the digital port. So please make sure you plug the module into the correct port, otherwise, there may be pin conflicts.

### Play With Raspberry Pi(with GrovePi\_Plus)

#### Hardware

- Step 1. Prepare the below stuffs:



- Step 2. Plug the GrovePi\_Plus into Raspberry.
- Step 3. Connect Grove-Moisture Sensor to A0 port of GrovePi\_Plus.
- Step 4. Connect the Raspberry to PC through USB cable.



#### Software

- Step 1. Follow [Setting Software](#) to configure the development environment.
- Step 2. Git clone the Github repository.

```
cd ~
git clone https://github.com/DexterInd/GrovePi.git
```

- Step 3. Excute below commands to use the Grove-Moisture Sensor to meansure the moisture.

```
cd ~/GrovePi/Software/Python
python grove_moisture_sensor.py
```

Here is the grove\_moisture\_sensor.py code.

```
# Here are suggested sensor values:  
#   Min Typ Max Condition  
#   0   0   0  sensor in open air  
#   0  20 300  sensor in dry soil  
#  300 580 700  sensor in humid soil  
#  700 940 950  sensor in water
```

```
import time  
import grovepi  
  
# Connect the Grove Moisture Sensor to analog port A0  
# SIG,NC,VCC,GND  
sensor = 0  
  
while True:  
    try:  
        print(grovepi.analogRead(sensor))  
        time.sleep(.5)  
  
    except KeyboardInterrupt:  
        break  
    except IOError:  
        print("Error")
```

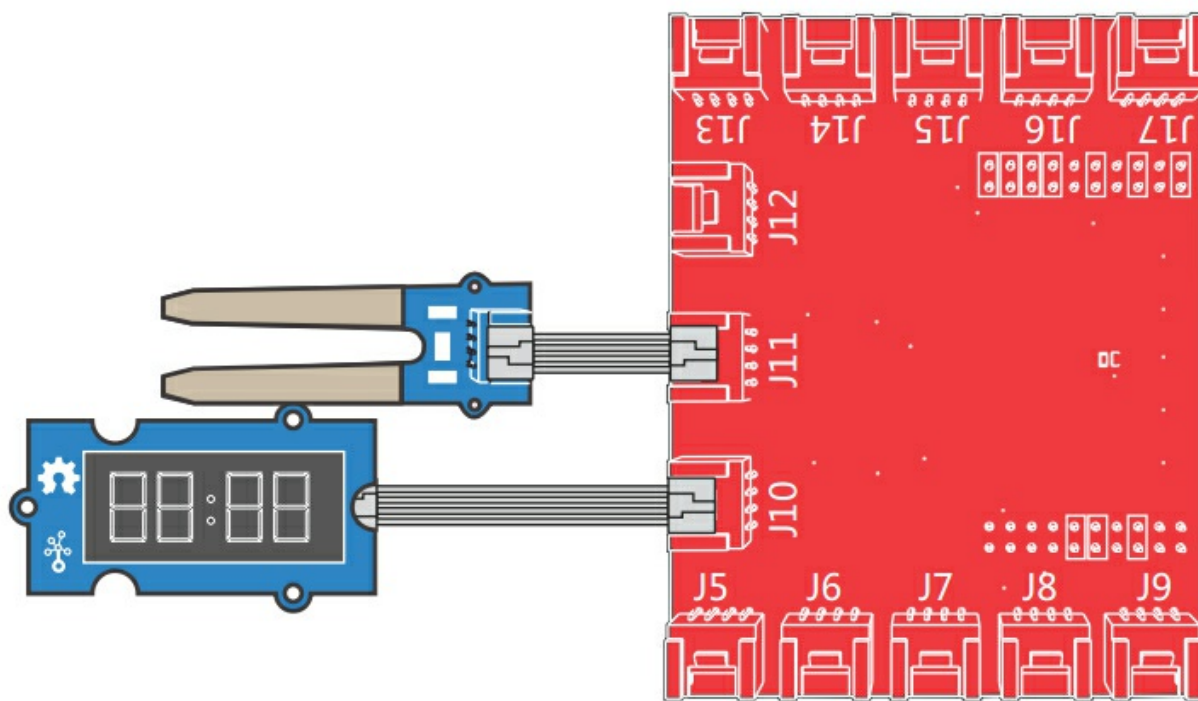
- Step 4. We will see the moisture display on terminal as below.

```
pi@raspberrypi:~/GrovePi/Software/Python $ python grove_moisture_sensor.py  
0  
90  
130  
150  
160  
218  
238
```

## Play With TI LaunchPad

### Hardware

The following sketch demonstrates a simple application of sensing the moisture in soil. With this, you can know whether your plant needs water or not by observing the result from the output of the sensor



### Software

```

/*
Moisture-Sensor
The following sketch demonstrates a simple application of sensing
the moisture of the soil. You can know whether a plant needs water
or not by observing the results that the sensor outputs.
The circuit:
* Moisture-Sensor attached to pin 24 (J6 plug on Grove Base BoosterPack)
* one side pin (either one) to ground
* the other side pin to +VCC
* LED anode (long leg) attached to RED_LED
* LED cathode (short leg) attached to ground
- NOTE:
This example code is in the public domain.
https://www.seeedstudio.com/wiki/Grove_-_Moisture_Sensor
*/
#include "TM1637.h"
/* Macro Define */
#define CLK 39          /* 4-digital display clock pin */
#define DIO 38         /* 4-digital display data pin */
#define BLINK_LED RED_LED /* blink led */
#define MOISTURE_PIN 24 /* pin of moisture sensor */
#define THRESHOLD_VALUE 300 /* threshold for watering the flowers */
#define ON HIGH        /* led on */
#define OFF LOW        /* led off */
#define _handle_led(x) digitalWrite(BLINK_LED, x) /* handle led */

/* Global Variables */
TM1637 tm1637(CLK, DIO); /* 4-digital display object */
int analog_value = 0; /* variable to store the value coming from rotary angle
sensor */
int8_t bits[4] = {0}; /* array to store the single bits of the value */
/* the setup() method runs once, when the sketch starts */
void setup() {
/* Initialize 4-digital display */
tm1637.init();
tm1637.set(BRIGHT_TYPICAL);
/* declare the red_led pin as an OUTPUT */
pinMode(BLINK_LED, OUTPUT);
}
/* the loop() method runs over and over again */
void loop() {
analog_value = analogRead(MOISTURE_PIN); /* read the value from the sensor */
/* if the value is smaller than threshold, turn on led */
if(analog_value < THRESHOLD_VALUE) {
_handle_led(ON);
} else {
_handle_led(OFF);
}
memset(bits, 0, 4); /* reset array when we use it */
for(int i = 3; i >= 0; i--) {
/* get single bits of the analog value */
bits[i] = analog_value % 10;
analog_value = analog_value / 10;
tm1637.display(i, bits[i]); /* display by 4-digital display */
}
delay(200);
}

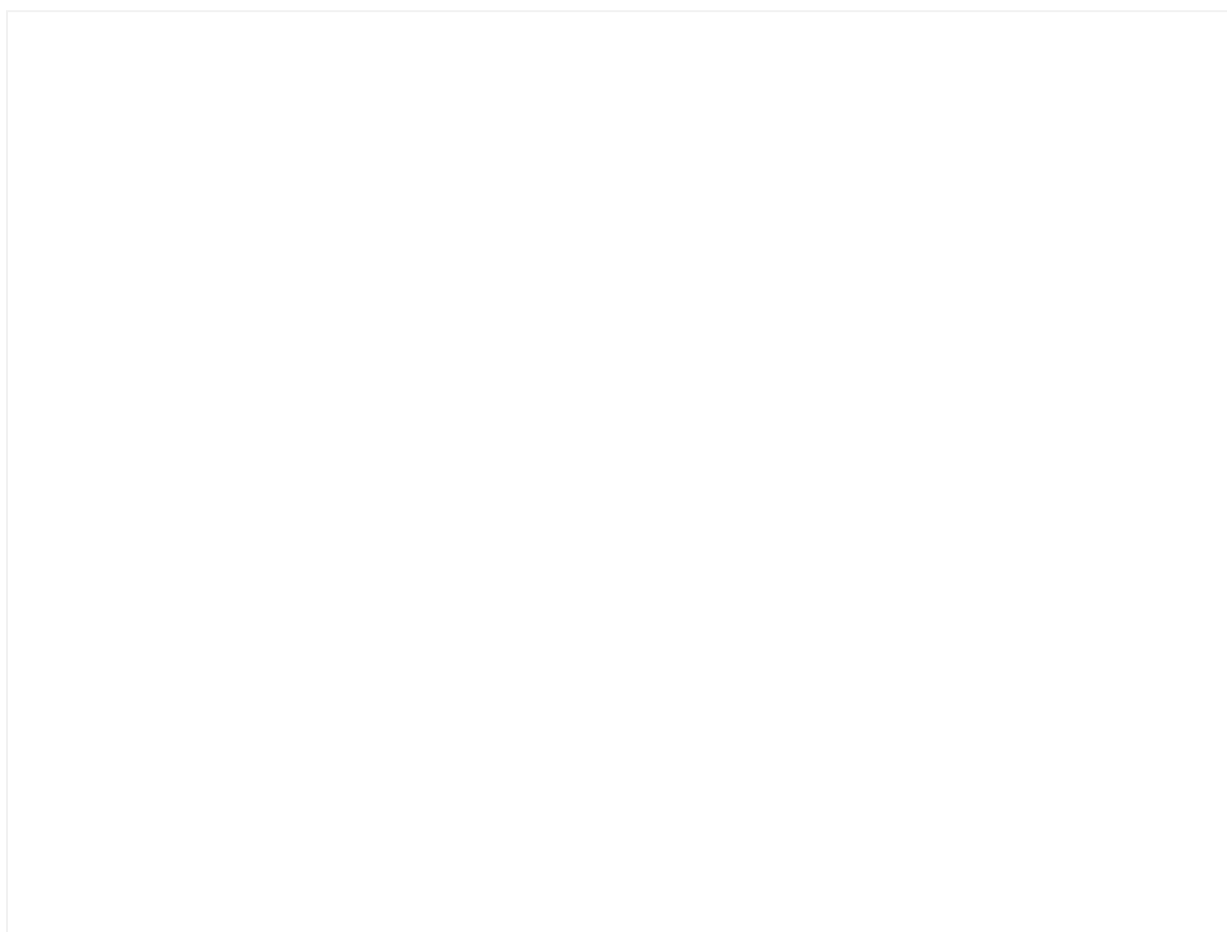
```

## FAQs

Q1: What does the output mean? voltage or counts?

A1: The output is voltage values. When using `analogRead()`, 5V will be divided by 1023. So the output value =  $V_{out} * 1023/5$ . The higher output voltage is, the higher moisture there is.

## Schematic Online Viewer





## Resources

- [\[Eagle&PDF\] Grove - Moisture Sensor v1.4 Schematic](#)
- [\[Codecraft\] CDC File](#)

## Tech Support

Please submit any technical issue into our [forum](#).

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