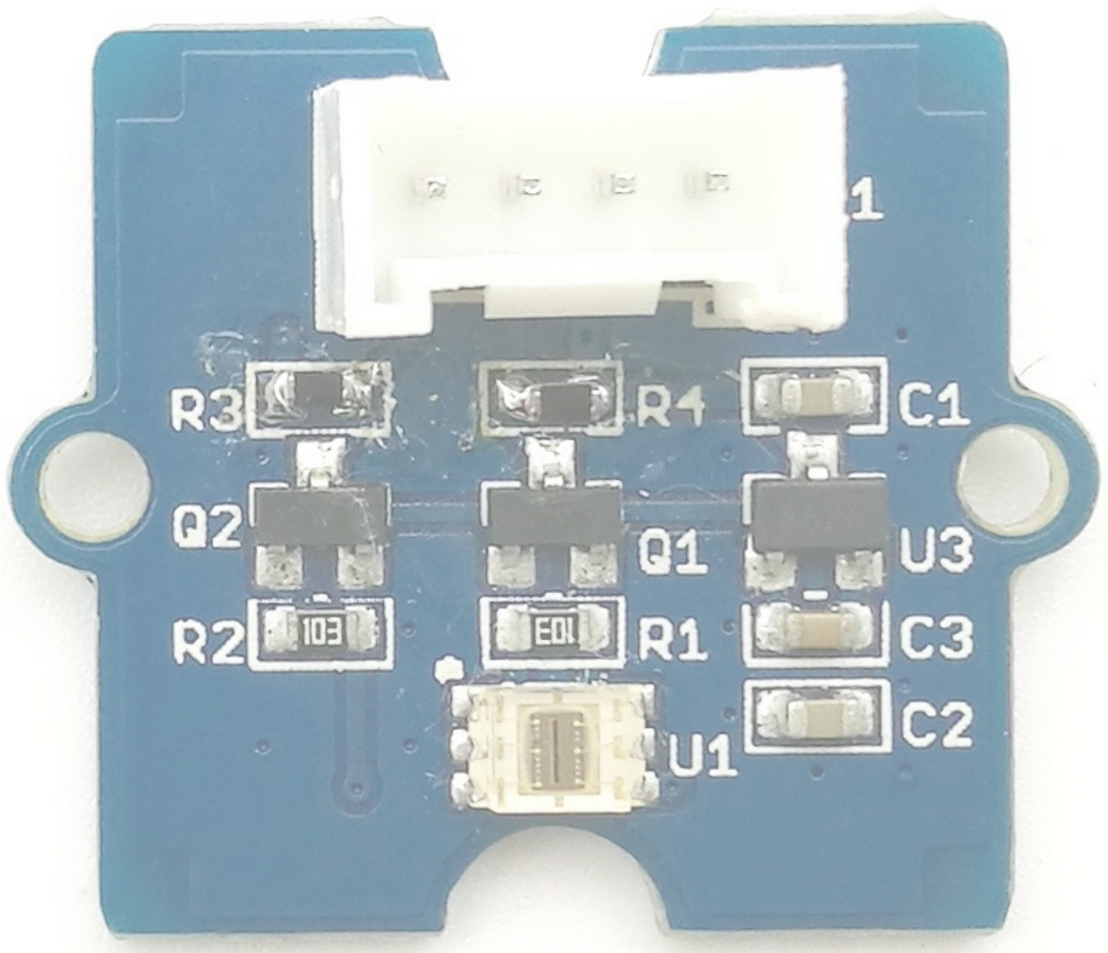
Grove - Digital Light Sensor



This module is based on the I2C light-to-digital converter TSL2561 to transform light intensity to a digital signal. Different from traditional analog light sensor, as Grove - Light Sensor , this digital module features a selectable light spectrum range due to its dual light sensitive diodes: infrared and full spectrum.

We can switch among three detection modes to take your readings. They are infrared mode, full spectrum and human visible mode. When running under the human visible mode, this sensor will give you readings just close to your eye feelings.

Version

Product Version	Changes	Released Date
Grove - Digital Light Sensor V1.1	Initial	Oct 2015

Features

- Selectable detection modes
- High resolution 16-Bit digital output at 400 kHz I2C Fast-Mode

- Wide dynamic range: 0.1 - 40,000 LUX
- Wide operating temperature range: -40°C to 85°C
- Programmable interrupt function with User-Defined Upper and lower threshold settings
- I2C Address 0x29

> Note
> If you want to use multiplue I2C devices, please refer to Software I2C .

> Tip
> More details about Grove modules please refer to Grove System

Specifications

Items	Min	Typical	Max	Unit
Supply voltage, VDD	3.3	5	5.1	V
Operating temperature	-30	\	70	℃
SCL,SDA input low voltage	-0.5	\	0.8	V
SCL,SDA input high voltage	2.3	\	5.1	V

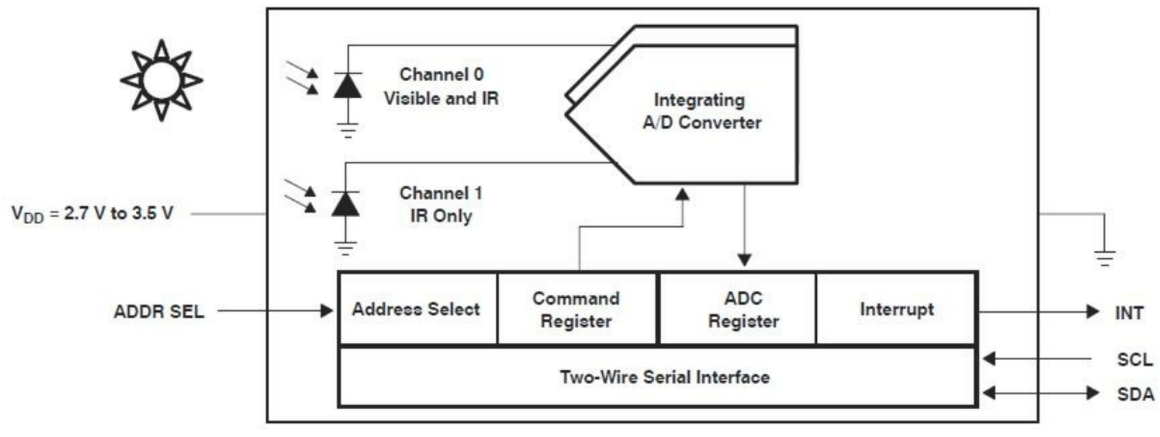
Platforms Supported

Arduino	Raspberry Pi	

> Caution
> The platforms mentioned above as supported is/are an indication of the module's software or theoritical compatibility. We only provide software library or code examples for Arduino platform in most cases. It is not possible to provide software library / demo code for all possible MCU platforms. Hence, users have to write their own software library.

Hardware Overview

U1: TSL2561 IC, Light-To-Digital Converter. Here is the Functional Block Diagram.

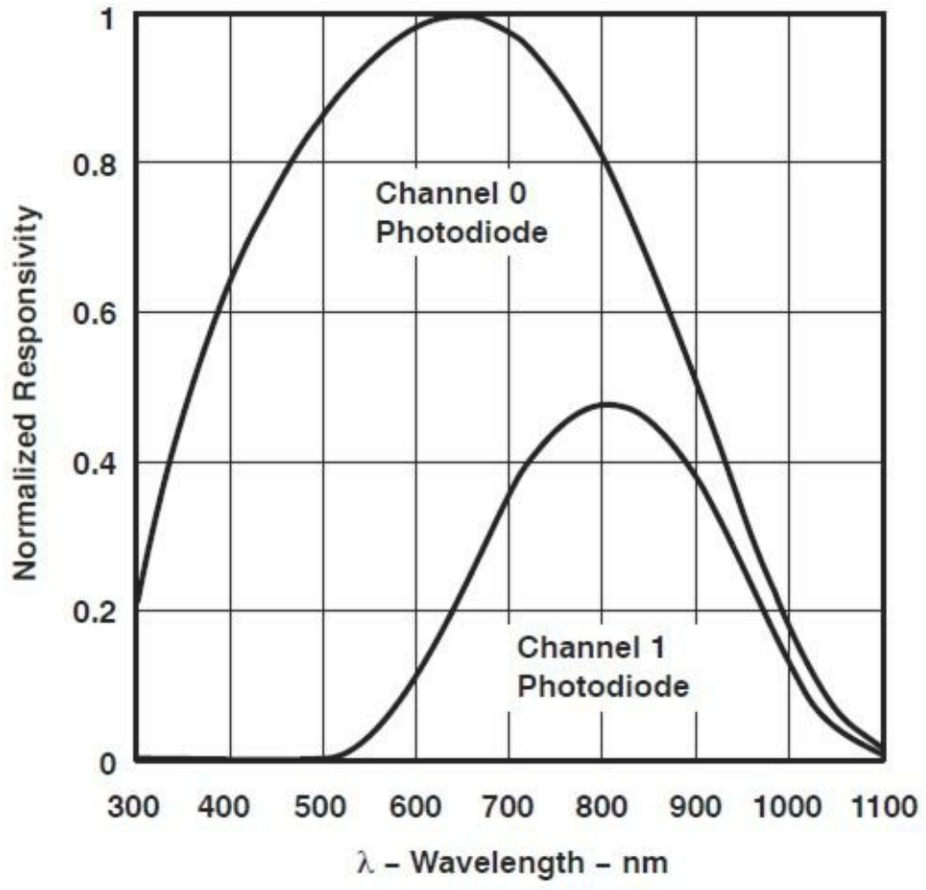


- Register Map

The TSL2561 is controlled and monitored by sixteen registers (three are reserved) and a command register accessed through the serial interface. These registers provide for a variety of control functions and can be read to determine results of the ADC conversions. The register set is summarised as shown below.

ADDRESS	RESISTER NAME	REGISTER FUNCTION
--	COMMAND	Specifies register address
0h	CONTROL	Control of basic functions
1h	TIMING	Integration time/gain control
2h	THRESHLOWLOW	Low byte of low interrupt threshold
3h	THRESHLOWHIGH	High byte of low interrupt threshold
4h	THRESHHIGHLOW	Low byte of high interrupt threshold
5h	THRESHHIGHHIGH	High byte of high interrupt threshold
6h	INTERRUPT	Interrupt control
7h	--	Reserved
8h	CRC	Factory test — not a user register
9h	--	Reserved
Ah	ID	Part number/ Rev ID
Bh	--	Reserved
Ch	DATA0LOW	Low byte of ADC channel 0
Dh	DATA0HIGH	High byte of ADC channel 0
Eh	DATA1LOW	Low byte of ADC channel 1
Fh	DATA1HIGH	High byte of ADC channel 1

- Spectrum Response Curve



Two channels of the digital light sensor have different response characteristic. That's why you can choose its working mode by having both of them on or one of them off.

U3: XC6206MR332 IC, Positive Voltage Regulators.

Q1,Q2: BSN20 IC, N-channel Enhancement Mode Vertical D-MOS Transistor.

SCL,SDA: I2C Signal Interface

Getting Started

> Note
> If this is the first time you work with Arduino, we firmly recommend you to see Getting Started with Arduino before the start.

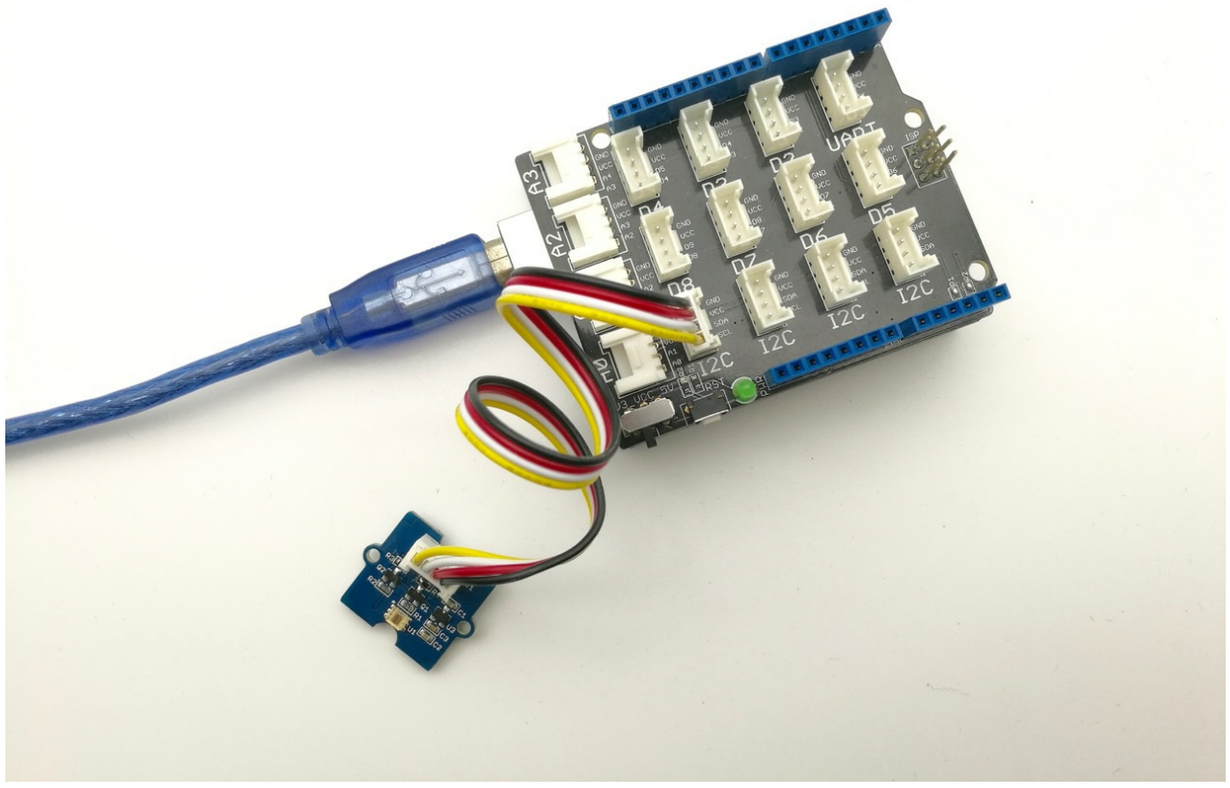
Play With Arduino

Hardware

- Step 1. Prepare the below stuffs:

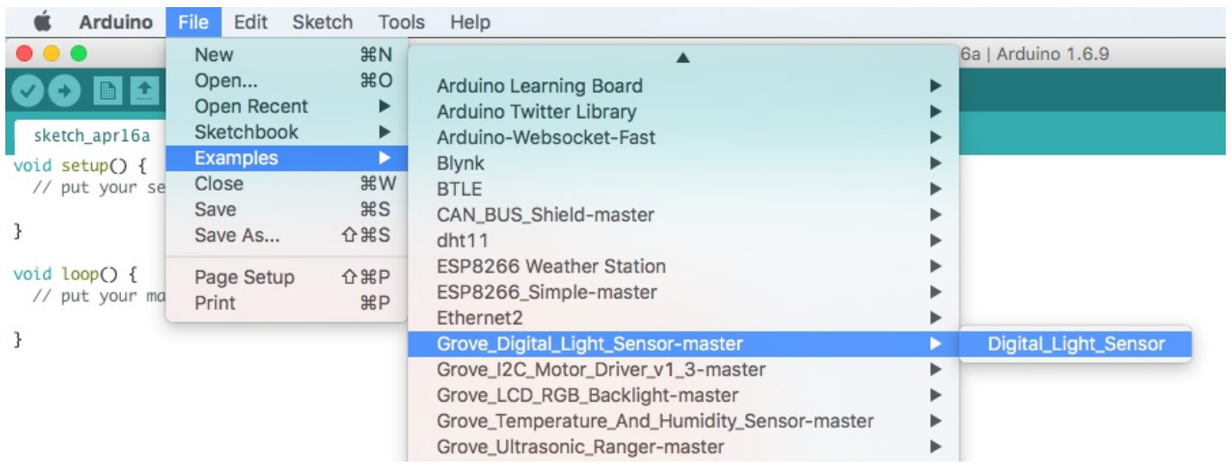
Seeeduino V4	Base Shield	Grove - Digital light sensor
		
Get ONE Now	Get ONE Now	Get ONE Now

- Step 2. Connect Grove - Digital light Sensor to I2C port of base shield.
- Step 3. Plug the base Shield into Arduino.
- Step 4. Connect Arduino to PC by using a USB cable.



Software

- Step 1. Download the library from here Digital Light Sensor Library ;
- Step 2. Please follow how to install an arduino library procedures to install library.
- Step 3. Open the code directly by the path: File -> Example ->Digital_Light_Sensor->Digital_Light_Sensor.



- Or copy below code to IDE and upload to Arduino.

```
/*
    Digital_Light_Sensor.ino
    A library for TSL2561

    Copyright (c) 2012 seeed technology inc.
    Author     : zhangkun
    Create Time:
    Change Log :

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R
    LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING F
ROM,
    OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALING
S IN
    THE SOFTWARE.
*/

#include <Wire.h>
#include <Digital_Light_TSL2561.h>
void setup()
{
  Wire.begin();
  Serial.begin(9600);
  TSL2561.init();
}

void loop()
{
  Serial.print("The Light value is: ");
  Serial.println(TSL2561.readVisibleLux());
  delay(1000);
}
```
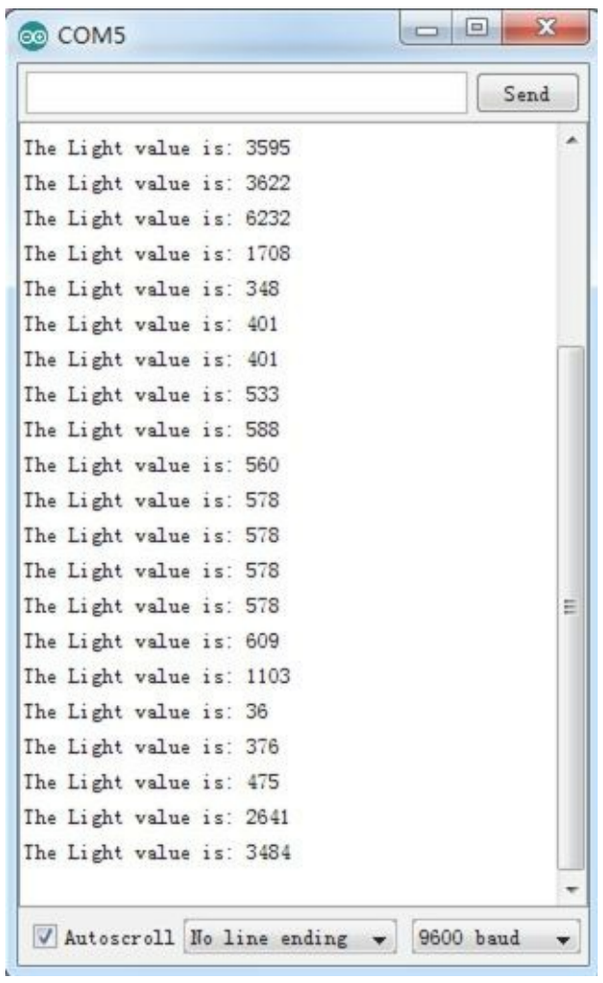

- Step 4. Open the serial monitor to monitor the result.



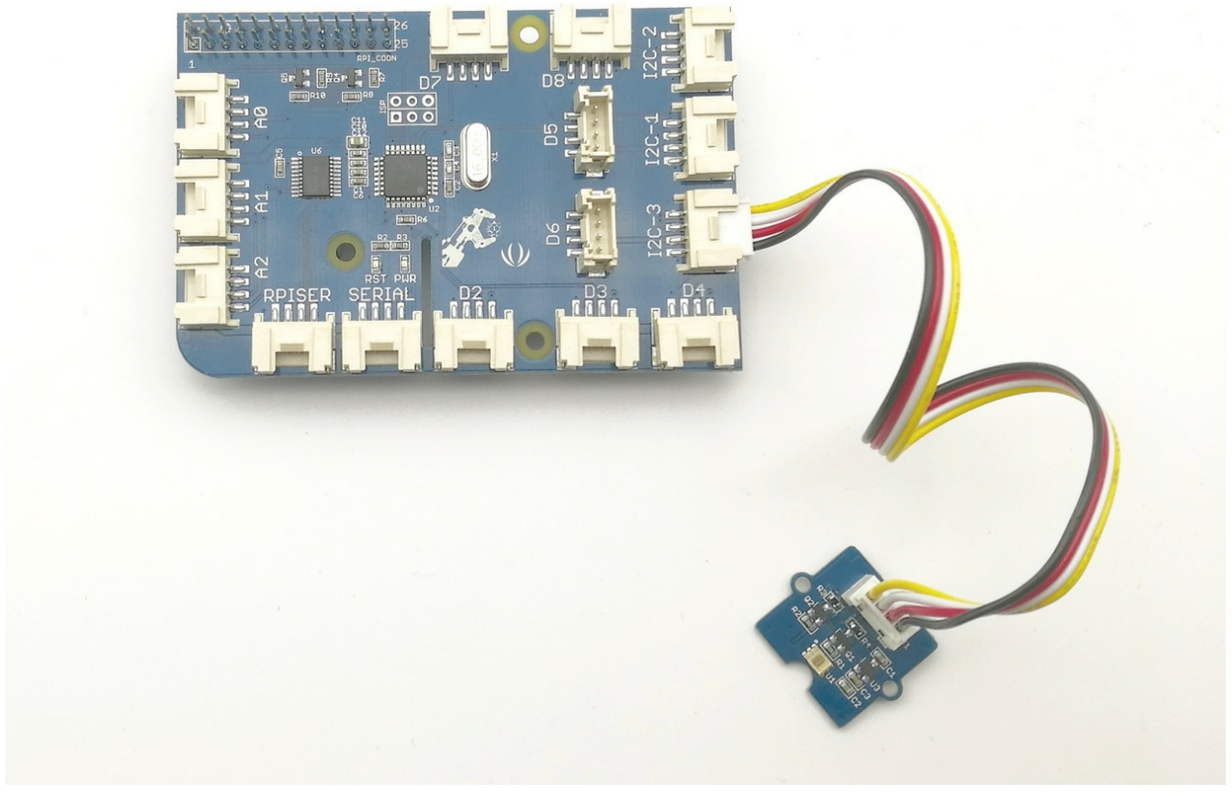
Play With Raspberry Pi

Hardware

- Step 1. Prepare the below stuffs:

Raspberry pi	GrovePi_Plus	Grove - Digital light sensor
		
Get ONE Now	Get ONE Now	Get ONE Now

- Follow instruction to configure the development environment.
- Plug the sensor to grovepi+ socket I2C by using a grove cable.



Software

- Step 1. Follow Setting Software to configure the development environment.
- Step 1. Navigate to the demos' directory:

```
cd yourpath/GrovePi/Software/Python/grove_i2c_digital_light_sensor/
```

- Step 2. To see the code

```
nano grove_i2c_digital_light_sensor.py  # "Ctrl+x" to exit #
```

```
#!/usr/bin/python
# TSL2561 I2C Light-To-Digital converter library for the Raspberry Pi.
# Datasheet: https://www.adafruit.com/datasheets/TSL2561.pdf
#
# This library is based on the work by Cedric Maion https://github.com/cmaion/TSL25
61
#
# Read http://www.dexterindustries.com/topic/greehouse-project/ for the forum discu
ssion about the sensor

from time import sleep
import smbus
from Adafruit_I2C import Adafruit_I2C
import RPi.GPIO as GPIO
from smbus import SMBus

TSL2561_Control = 0x80
TSL2561_Timing = 0x81
TSL2561_Interrupt = 0x86
TSL2561_Channel0L = 0x8C
TSL2561_Channel0H = 0x8D
TSL2561_Channel1L = 0x8E
TSL2561_Channel1H = 0x8F

TSL2561_Address = 0x29 #device address

LUX_SCALE = 14 # scale by 2^14
RATIO_SCALE = 9 # scale ratio by 2^9
CH_SCALE = 10 # scale channel values by 2^10
CHSCALE_TINT0 = 0x7517 # 322/11 * 2^CH_SCALE
CHSCALE_TINT1 = 0x0fe7 # 322/81 * 2^CH_SCALE

K1T = 0x0040 # 0.125 * 2^RATIO_SCALE
B1T = 0x01f2 # 0.0304 * 2^LUX_SCALE
M1T = 0x01be # 0.0272 * 2^LUX_SCALE
K2T = 0x0080 # 0.250 * 2^RATIO_SCA
B2T = 0x0214 # 0.0325 * 2^LUX_SCALE
M2T = 0x02d1 # 0.0440 * 2^LUX_SCALE
K3T = 0x00c0 # 0.375 * 2^RATIO_SCALE
```

```
B3T = 0x023f # 0.0351 * 2^LUX_SCALE
M3T = 0x037b # 0.0544 * 2^LUX_SCALE
K4T = 0x0100 # 0.50 * 2^RATIO_SCALE
B4T = 0x0270 # 0.0381 * 2^LUX_SCALE
M4T = 0x03fe # 0.0624 * 2^LUX_SCALE
K5T = 0x0138 # 0.61 * 2^RATIO_SCALE
B5T = 0x016f # 0.0224 * 2^LUX_SCALE
M5T = 0x01fc # 0.0310 * 2^LUX_SCALE
K6T = 0x019a # 0.80 * 2^RATIO_SCALE
B6T = 0x00d2 # 0.0128 * 2^LUX_SCALE
M6T = 0x00fb # 0.0153 * 2^LUX_SCALE
K7T = 0x029a # 1.3 * 2^RATIO_SCALE
B7T = 0x0018 # 0.00146 * 2^LUX_SCALE
M7T = 0x0012 # 0.00112 * 2^LUX_SCALE
K8T = 0x029a # 1.3 * 2^RATIO_SCALE
B8T = 0x0000 # 0.000 * 2^LUX_SCALE
M8T = 0x0000 # 0.000 * 2^LUX_SCALE



K1C = 0x0043 # 0.130 * 2^RATIO_SCALE
B1C = 0x0204 # 0.0315 * 2^LUX_SCALE
M1C = 0x01ad # 0.0262 * 2^LUX_SCALE
K2C = 0x0085 # 0.260 * 2^RATIO_SCALE
B2C = 0x0228 # 0.0337 * 2^LUX_SCALE
M2C = 0x02c1 # 0.0430 * 2^LUX_SCALE
K3C = 0x00c8 # 0.390 * 2^RATIO_SCALE
B3C = 0x0253 # 0.0363 * 2^LUX_SCALE
M3C = 0x0363 # 0.0529 * 2^LUX_SCALE
K4C = 0x010a # 0.520 * 2^RATIO_SCALE
B4C = 0x0282 # 0.0392 * 2^LUX_SCALE
M4C = 0x03df # 0.0605 * 2^LUX_SCALE
K5C = 0x014d # 0.65 * 2^RATIO_SCALE
B5C = 0x0177 # 0.0229 * 2^LUX_SCALE
M5C = 0x01dd # 0.0291 * 2^LUX_SCALE
K6C = 0x019a # 0.80 * 2^RATIO_SCALE
B6C = 0x0101 # 0.0157 * 2^LUX_SCALE
M6C = 0x0127 # 0.0180 * 2^LUX_SCALE
K7C = 0x029a # 1.3 * 2^RATIO_SCALE
B7C = 0x0037 # 0.00338 * 2^LUX_SCALE
M7C = 0x002b # 0.00260 * 2^LUX_SCALE
K8C = 0x029a # 1.3 * 2^RATIO_SCALE
B8C = 0x0000 # 0.000 * 2^LUX_SCALE
M8C = 0x0000 # 0.000 * 2^LUX_SCALE

# bus parameters
rev = GPIO.RPI_REVISION
if rev == 2 or rev == 3:
   bus = smbus.SMBus(1)
else:
   bus = smbus.SMBus(0)
i2c = Adafruit_I2C(TSL2561_Address)

debug = False
cooldown_time = 0.005 # measured in seconds
packageType = 0 # 0=T package, 1=CS package
gain = 0       # current gain: 0=1x, 1=16x [dynamically selected]
gain_m = 1     # current gain, as multiplier
timing = 2     # current integration time: 0=13.7ms, 1=101ms, 2=402ms [dynamicall
y selected]
timing_ms = 0  # current integration time, in ms
channel0 = 0   # raw current value of visible+ir sensor
channel1 = 0   # raw current value of ir sensor
schannel0 = 0  # normalized current value of visible+ir sensor
schannel1 = 0  # normalized current value of ir sensor


def readRegister(address):
   try:
      byteval = i2c.readU8(address)

      sleep(cooldown_time)
      if (debug):
         print("TSL2561.readRegister: returned 0x%02X from reg 0x%02X" % (byteval,
address))
      return byteval
   except IOError:
      print("TSL2561.readRegister: error reading byte from reg 0x%02X" % address)
      return -1


def writeRegister(address, val):
   try:
      i2c.write8(address, val)

      sleep(cooldown_time)
      if (debug):
         print("TSL2561.writeRegister: wrote 0x%02X to reg 0x%02X" % (val, address))
   except IOError:

      sleep(cooldown_time)
      print("TSL2561.writeRegister: error writing byte to reg 0x%02X" % address)
      return -1

def powerUp():
   writeRegister(TSL2561_Control, 0x03)

def powerDown():
   writeRegister(TSL2561_Control, 0x00)

def setTintAndGain():
   global gain_m, timing_ms

   if gain == 0:
```

```
    if gain == 0:
        gain_m = 1
    else:
        gain_m = 16

    if timing == 0:
        timing_ms = 13.7
    elif timing == 1:
        timing_ms = 101
    else:
        timing_ms = 402
    writeRegister(TSL2561_Timing, timing | gain << 4)

def readLux():
    sleep(float(timing_ms + 1) / 1000)

    ch0_low  = readRegister(TSL2561_Channel0L)
    ch0_high = readRegister(TSL2561_Channel0H)
    ch1_low  = readRegister(TSL2561_Channel1L)
    ch1_high = readRegister(TSL2561_Channel1H)

    global channel0, channel1
    channel0 = (ch0_high<<8) | ch0_low
    channel1 = (ch1_high<<8) | ch1_low

    sleep(cooldown_time)
    if debug:
        print("TSL2561.readVisibleLux: channel 0 = %i, channel 1 = %i [gain=%ix, timing
=%ims]" % (channel0, channel1, gain_m, timing_ms))

def readVisibleLux():
    global timing, gain

    powerUp()
    readLux()

    if channel0 < 500 and timing == 0:
        timing = 1
        sleep(cooldown_time)
        if debug:
            print("TSL2561.readVisibleLux: too dark. Increasing integration time from 13.7
ms to 101ms")
        setTintAndGain()
        readLux()

    if channel0 < 500 and timing == 1:
        timing = 2
        sleep(cooldown_time)
        if debug:
            print("TSL2561.readVisibleLux: too dark. Increasing integration time from 101
ms to 402ms")
        setTintAndGain()
        readLux()

    if channel0 < 500 and timing == 2 and gain == 0:
        gain = 1
        sleep(cooldown_time)
        if debug:
            print("TSL2561.readVisibleLux: too dark. Setting high gain")
        setTintAndGain()
        readLux()

    if (channel0 > 20000 or channel1 > 20000) and timing == 2 and gain == 1:
        gain = 0
        sleep(cooldown_time)
        if debug:
            print("TSL2561.readVisibleLux: enough light. Setting low gain")
        setTintAndGain()
        readLux()

    if (channel0 > 20000 or channel1 > 20000) and timing == 2:
        timing = 1
        sleep(cooldown_time)
        if debug:
            print("TSL2561.readVisibleLux: enough light. Reducing integration time from 4
02ms to 101ms")
        setTintAndGain()
        readLux()

    if (channel0 > 10000 or channel1 > 10000) and timing == 1:
        timing = 0
        sleep(cooldown_time)
        if debug:
            print("TSL2561.readVisibleLux: enough light. Reducing integration time from 1
01ms to 13.7ms")
        setTintAndGain()
        readLux()

    powerDown()

    if (timing == 0 and (channel0 > 5000 or channel1 > 5000)) or (timing == 1 and (ch
annel0 > 37000 or channel1 > 37000)) or (timing == 2 and (channel0 > 65000 or ch
annel1 > 65000)):
        # overflow
        return -1

    return calculateLux(channel0, channel1)

def calculateLux(ch0, ch1):
    chScale = 0
    if timing == 0:   # 13.7 msec
        chScale = CHSCALE_TINT0
    elif timing == 1: # 101 msec
        chScale = CHSCALE_TINT1;
```

```
else:           # assume no scaling
    chScale = (1 << CH_SCALE)

if gain == 0:
    chScale = chScale << 4 # scale 1X to 16X

# scale the channel values
global schannel0, schannel1
schannel0 = (ch0 * chScale) >> CH_SCALE
schannel1 = (ch1 * chScale) >> CH_SCALE

ratio = 0
if schannel0 != 0:
    ratio = (schannel1 << (RATIO_SCALE+1)) / schannel0
ratio = (ratio + 1) >> 1

if packageType == 0:  # T package
    if ((ratio >= 0) and (ratio <= K1T)):
        b=B1T; m=M1T;
    elif (ratio <= K2T):
        b=B2T; m=M2T;
    elif (ratio <= K3T):
        b=B3T; m=M3T;
    elif (ratio <= K4T):
        b=B4T; m=M4T;
    elif (ratio <= K5T):
        b=B5T; m=M5T;
    elif (ratio <= K6T):
        b=B6T; m=M6T;
    elif (ratio <= K7T):
        b=B7T; m=M7T;
    elif (ratio > K8T):
        b=B8T; m=M8T;
elif packageType == 1: # CS package
    if ((ratio >= 0) and (ratio <= K1C)):
        b=B1C; m=M1C;
    elif (ratio <= K2C):
        b=B2C; m=M2C;
    elif (ratio <= K3C):
        b=B3C; m=M3C;
    elif (ratio <= K4C):
        b=B4C; m=M4C;
    elif (ratio <= K5C):
        b=B5C; m=M5C;
    elif (ratio <= K6C):
        b=B6C; m=M6C;
    elif (ratio <= K7C):
        b=B7C; m=M7C;

    temp = ((schannel0*b)-(schannel1*m))
    if temp < 0:
        temp = 0;
    temp += (1<<(LUX_SCALE-1))
    # strip off fractional portion
    lux = temp>>LUX_SCALE
    sleep(cooldown_time)
    if debug:
        print("TSL2561.calculateLux: %i" % lux)

    return lux

def init():
    powerUp()
    setTintAndGain()
    writeRegister(TSL2561_Interrupt, 0x00)
    powerDown()

def main():
    init()
    while (True):
        print("Lux: %i [Vis+IR=%i, IR=%i @ Gain=%ix, Timing=%.1fms]" % (readVisibleLu
x(), channel0, channel1, gain_m, timing_ms))
        sleep(1)

if __name__ == "__main__":
        main()
```

- Step 3. Run the demo.

```
sudo python grove_i2c_digital_light_sensor.py
```

- Step 4. Here is the Result.

```
pi@raspberrypi: ~/software/GrovePi/Software/Python/grove_i2c_digital_light_s...
pi@raspberrypi ~/software/GrovePi/Software/Python/grove_i2c_digital_light_sensor
 $ sudo python grove_i2c_digital_light_sensor.py
Power ON
responce:  80
PartNo =  not TSL2560 or TSL 2561
RevNo =
gain =  0
Setting high gain
I2C: Device 0x29: returned 0x0BBF from reg 0x8C
I2C: Device 0x29: returned 0x0310 from reg 0x8E
IR Result without scaling:  4099
IR Result:  4099
Ambient Result without scaling:  48907
Ambient Result:  48907
ratio:  0.0838121332325
There is light:
ambient = 48907
IR = 4099
_ambient = 48907
_IR = 4099
Light = 1450.40189109 lux.
Power OFF
gain =  0
I2C: Device 0x29: returned 0x0BBC from reg 0x8C
```

Schematic Online Viewer

Resources

- [Eagle] Grove - Digital Light Sensor Schematic
- [PDF] Grove - Digital Light Sensor Sch PDF File
- [PDF] Grove - Digital Light Sensor PCB PDF File
- [Library] Library Github Grove-Digital Light
- [Datasheet] TSL2561 Datasheet