DEMO CIRCUIT 827 QUICK START GUIDE

LTC2803 and LTC2804

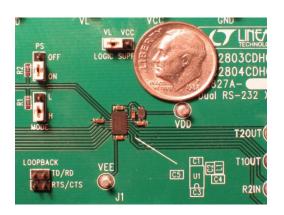
1.8V to 5.5V RS-232 Dual Transceiver

DESCRIPTION

Demonstration circuit 827 is a 1.8V to 5.5V RS-232 Dual Transceiver featuring the LTC2803 and LTC2804.

VERSION	P/N
DC827A-A	LTC2803CDHC
DC827A-B	LTC2804CDHC

Design files for this circuit board are available. Call the LTC factory.



PERFORMANCE SUMMARY

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V _{CC}	Input Supply Voltage		1.8		5.5	V
V_{L}	Logic Supply Voltage		1.8		5.5	V
SR(D)	Driver Slew Rate	$R_L=3k\Omega$, $50pF$				
		LTC2803:	4		30	V/µs
		LTC2804:	4		150	V/µs
	Maximum Data Rate	$R_L = 3k\Omega$, $C_L = 2.5nF$	100			kbps
		$R_L = 3k\Omega$, $C_L = 1.0nF$	250			kbps
		$R_L = 3k\Omega$, $C_L = 250pF$ (LTC2804)	1000			kbps

JUMPERS

SCH	NAME	PURPOSE		
JP1,	MODE,	Mode control, as follows:		
JP2	PS	PS MODE MODE NAME		
		OFF L Shutdown		
		OFF H Receivers Active		
		ON L Drivers Disabled		
		ON H Normal		
JP3	LOGIC	Selects supply for VL pin. Use setting "VL" for a		
	SUPPLY	separate logic supply, or "VCC" to share a single		
		supply.		
JP4,	TD/RD,	Selects Receiver loopback mode, for use with the		
JP5	RTS/CTS	DB9 connector. In this configuration, R10UT is con-		
		nected to T1IN and R2OUT is connected to T2IN.		

SCH	NAME	PURPOSE
		For the UART connected to the DB9, this wraps TD
		back to RD and RTS back to CTS.



QUICK START PROCEDURE

Demonstration circuit 827 is easy to set up for evaluating the LTC2803 and LTC2804. Refer to Figure 1 or Figure 2 for proper setup and follow the procedure below:

1. Place jumpers in the following positions:

JP1 MODE H JP2 PS ON

- 2. With power off, connect the primary power supply to VCC and GND.
- 3. Set JP3 "Logic Supply" to the correct position. If a separate logic supply isn't needed, use the "VCC" setting. If a separate Logic Supply will be used, use the "VL" setting and, with the power off, connect the supply to VL and GND.
- 4. For transmitter loopback mode (Figure 1), connect each driver output to a receiver input. Connect input sources to the driver inputs. (Make sure that input voltages don't exceed 7V.) Omit Loopback jumpers JP4 and JP5 for this mode.
- 5. Alternatively, to operate the part in receiver loopback mode (Figure 2), connect a 9-wire RS-232 cable between DB9 connector J1 and the serial port of a computer. Place jumpers in the two LOOPBACK positions:

JP4 TD/RD JP5 CTS/RTS

Data may be transmitted and monitored using a terminal emulation program such as Terminal, HyperTerminal, Tera Term Pro, or RealTerm.

6. Turn on the input supply/supplies in any order. (Note: Make sure that the voltage doesn't exceed 7V.)

- 7. Check for the proper generated supply voltages: VDD = 6.5V to 7.5V, and VEE = -6.8V to -5.8V.
- 8. Send data!

Notes:

- 1. Inputs PS and MODE may be driven by signals instead of set with jumpers. If done, ensure that the voltage of PS doesn't exceed VL.
- 2. The terminal emulation program RealTerm can lock up when RTS/CTS flow control is used in receiver loopback mode.



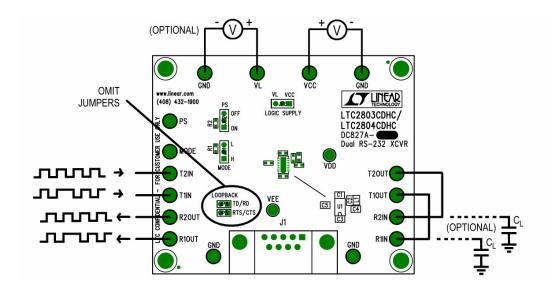


Figure 1. Setup for Transmitter Loopback Mode

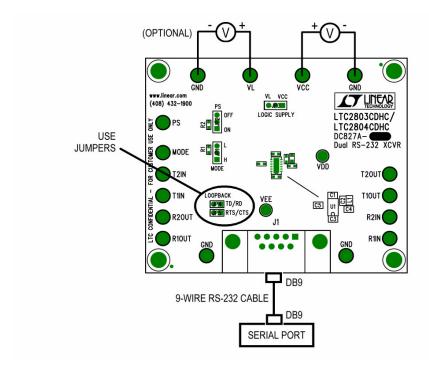
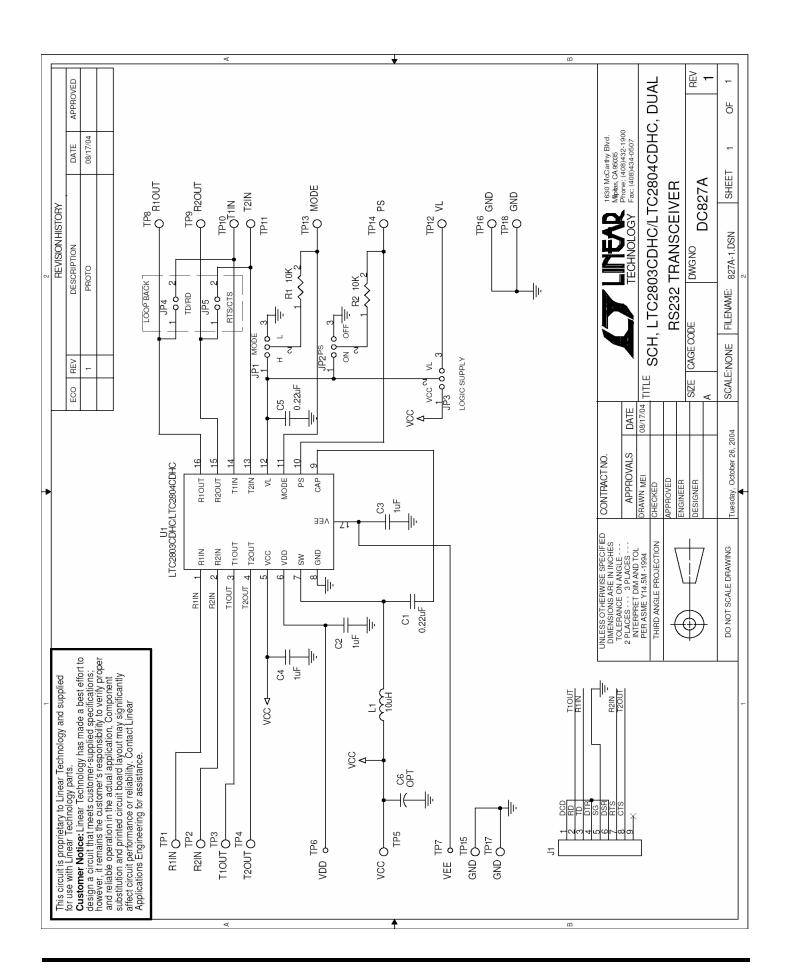


Figure 2. Setup for Receiver Loopback Mode







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