# **HEF40106B**

## **Hex inverting Schmitt trigger**

Rev. 10 — 7 October 2022

**Product data sheet** 

## 1. General description

The HEF40106B is a hex inverter with Schmitt-trigger inputs. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of  $V_{DD}$ .

## 2. Features and benefits

- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Schmitt trigger input discrimination
- · Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B
- · ESD protection:
  - HBM JESD22-A114F exceeds 2 kV
  - MM JESD22-A115-B exceeds 200 V

## 3. Applications

- · Wave and pulse shapers
- Astable multivibrators
- · Monostable multivibrators

## 4. Ordering information

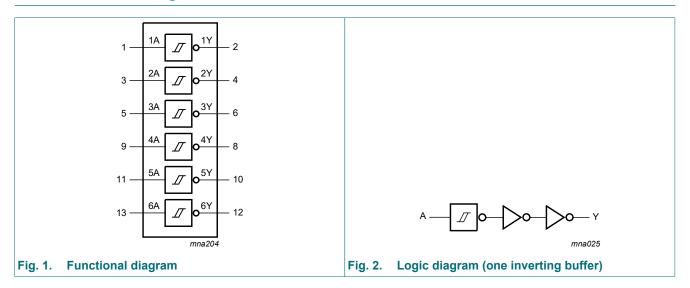
#### **Table 1. Ordering information**

Type number	Package	Package										
	Temperature range	Name	Description	Version								
HEF40106BT	-40 °C to +125 °C	SO14	plastic small outline package; 14 leads; body width 3.9 mm	<u>SOT108-1</u>								
HEF40106BTT	-40 °C to +125 °C	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1								



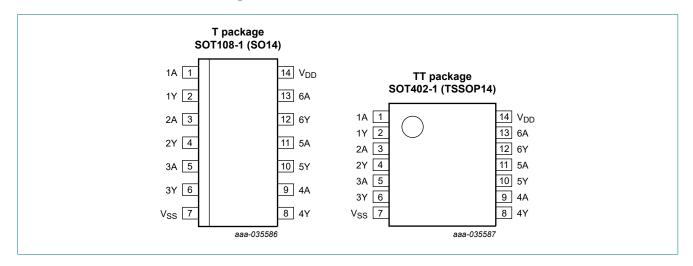
**Hex inverting Schmitt trigger** 

## 5. Functional diagram



## 6. Pinning information

## 6.1. Pinning



## 6.2. Pin description

**Table 2. Pin description** 

Symbol	Pin	Description
1A, 2A, 3A, 4A, 5A, 6A	1, 3, 5, 9, 11, 13	input
1Y, 2Y, 3Y, 4Y, 5Y, 6Y	2, 4, 6, 8, 10, 12	output
$V_{DD}$	14	supply voltage
V <sub>SS</sub>	7	ground (0 V)

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## 7. Functional description

#### Table 3. Function table

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level.$ 

Input	Output
nA	nY
L	Н
Н	L

## 8. Limiting values

#### **Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to  $V_{SS} = 0 \text{ V}$  (ground).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$	-	±10	mΑ
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mΑ
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$ [1]	-	500	mW
Р	power dissipation	per output	-	100	mW

<sup>[1]</sup> For SOT108-1 (SO14) package:  $P_{tot}$  derates linearly with 10.1 mW/K above 100 °C. For SOT402-1 (TSSOP14) package:  $P_{tot}$  derates linearly with 7.3 mW/K above 81 °C.

## 9. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Min	Max	Unit	
$V_{DD}$	supply voltage		3	15	V
VI	input voltage		0	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	+125	°C

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## 10. Static characteristics

#### **Table 6. Static characteristics**

 $V_{SS} = 0 \ V$ ;  $V_{I} = V_{SS} \ or \ V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	-40 °C	T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> =	+85 °C	T <sub>amb</sub> = +125 °C		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>OH</sub>	HIGH-level	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
OL	LOW-level	I <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mΑ
		V <sub>O</sub> = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mΑ
		V <sub>O</sub> = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mΑ
I <sub>OL</sub>	LOW-level	V <sub>O</sub> = 0.4 V	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mΑ
	output current	V <sub>O</sub> = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mΑ
		V <sub>O</sub> = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
l <sub>l</sub>	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μA
I <sub>DD</sub>	supply current	all valid input	5 V	-	0.25	-	0.25	-	7.5	-	7.5	μΑ
		combinations; I <sub>O</sub> = 0 A	10 V	-	0.5	-	0.5	-	15.0	-	15.0	μΑ
		10 - 0 A	15 V	-	1.0	-	1.0	-	30.0	-	30.0	μΑ
C <sub>I</sub>	input capacitance			-	-	-	7.5	-	-	-	-	pF

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## 11. Dynamic characteristics

#### **Table 7. Dynamic characteristics**

 $T_{amb}$  = 25 °C;  $C_L$  = 50 pF;  $t_r$  =  $t_f \le$  20 ns unless otherwise specified.

For waveforms see Fig. 3; for test circuit see Fig. 4;

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula [1]	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	nA to nY	5 V	63 ns + (0.55 ns/pF)C <sub>L</sub>	-	90	180	ns
	propagation delay		10 V	29 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
TLII	LOW to HIGH propagation delay	nA to nY	5 V	58 ns + (0.55 ns/pF)C <sub>L</sub>	-	75	150	ns
			10 V	29 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
t <sub>THL</sub>	HIGH to LOW output	nY to LOW	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
	transition time		10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>TLH</sub>	LOW to HIGH output	nY to HIGH	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
	transition time		10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns

<sup>[1]</sup> Typical value of the propagation delay and output transition time can be calculated with the extrapolation formula ( $C_L$  in pF).

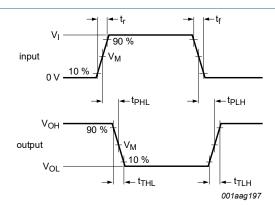
#### **Table 8. Dynamic power dissipation**

 $V_{SS} = 0 \ V; \ t_r = t_f \le 20 \ ns; \ T_{amb} = 25 \ ^{\circ}C.$ 

Symbol	Parameter	$V_{DD}$	Typical formula	where:
$P_D$	dynamic power	5 V	. (0 2) 22 (. )	f <sub>i</sub> = input frequency in MHz;
	dissipation		F D = 30000 ^ 1; T / 11° ^ (7) 1 ^ V DD	f <sub>o</sub> = output frequency in MHz; C <sub>L</sub> = output load capacitance in pF;
		15 V		$\Sigma(f_o \times C_L)$ = sum of the outputs; $V_{DD}$ = supply voltage in V.

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## 11.1. Waveforms and test circuit



Measurement points are given in Table 9.

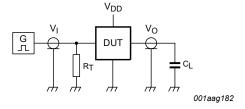
Logic levels:  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

 $t_r$ ,  $t_f$  = input rise and fall times.

Fig. 3. Propagation delay and output transition time

**Table 9. Measurement points** 

Supply voltage	Input	Output
$V_{DD}$	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	$0.5 \times V_{DD}$	0.5 × V <sub>DD</sub>



Test data given in Table 10.

Definitions for test circuit:

C<sub>L</sub> = load capacitance including jig and probe capacitance;

 $R_T$  = termination resistance should be equal to the output impedance  $Z_0$  of the pulse generator.

Fig. 4. Test circuit for measuring switching times

#### Table 10. Test data

Supply voltage	Input	Load	
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF

**Hex inverting Schmitt trigger** 

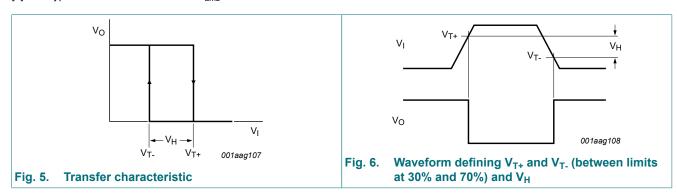
## 12. Transfer characteristics

#### **Table 11. Transfer characteristics**

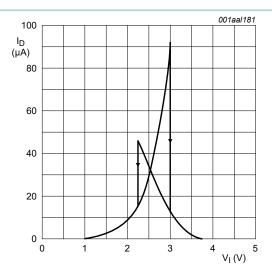
 $V_{SS} = 0 V$ ; see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	-40 °C to	+85 °C	T <sub>amb</sub> = -40 °	Unit	
				Min	Typ [1]	Max	Min	Max	
V <sub>T+</sub> positive-going threshold voltage			5 V	2.0	3.0	3.5	2.0	3.5	V
		10 V	3.7	5.8	7.0	3.7	7.0	V	
			15 V	4.9	8.3	11.0	4.9	11.0	V
V <sub>T-</sub>	negative-going		5 V	1.5	2.2	3.0	1.5	3.0	V
	threshold voltage		10 V	3.0	4.5	6.3	3.0	6.3	V
			15 V	4.0	6.5	10.1	4.0	10.1	V
V <sub>H</sub>	hysteresis voltage		5 V	0.5	0.8	-	0.5	-	V
			10 V	0.7	1.3	-	0.7	-	V
			15 V	0.9	1.8	-	0.9	-	V

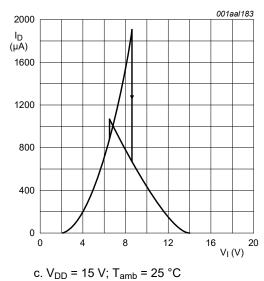
[1] All typical values are measured at  $T_{amb}$  = 25 °C.

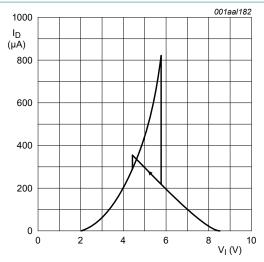


## **Hex inverting Schmitt trigger**

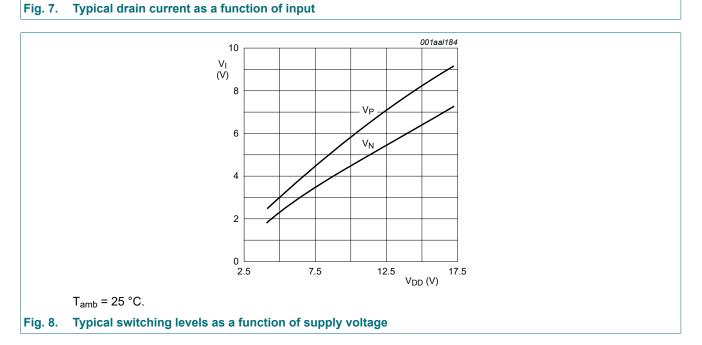


a.  $V_{DD}$  = 5 V;  $T_{amb}$  = 25 °C





b.  $V_{DD}$  = 10 V;  $T_{amb}$  = 25 °C



HEF40106B

**Hex inverting Schmitt trigger** 

## 13. Application information

Some examples of applications for the HEF40106B are:

- · Wave and pulse shapers
- · Astable multivibrators
- · Monostable multivibrators

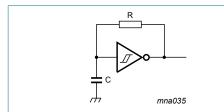


Fig. 9. Astable multivibrator

Fig. 10. Schmitt trigger driven via a high-impedance input

If a Schmitt trigger is driven via a high-impedance (R > 1 k $\Omega$ ), then it is necessary to incorporate a capacitor C with a value of  $\frac{C}{C_P} > \frac{V_{DD} - V_{SS}}{V_H}$ ; otherwise oscillation can occur on the edges of a pulse.

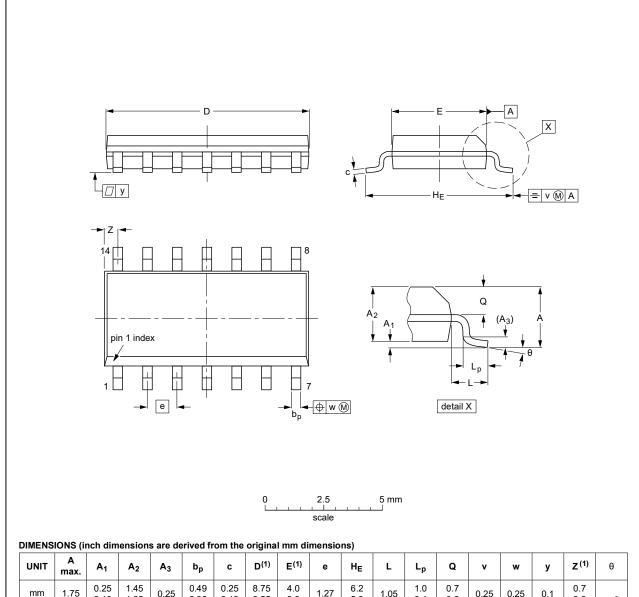
 $C_p$  is the external parasitic capacitance between inputs and output; the value depends on the circuit board layout.

## **Hex inverting Schmitt trigger**

## 14. Package outline

#### SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(1)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	8.75 8.55	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01	I	0.0100 0.0075	0.35 0.34	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	0°

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN	ISSUE DATE
	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT108-1	076E06	MS-012				<del>99-12-27</del> 03-02-19

Fig. 11. Package outline SOT108-1 (SO14)

#### **Hex inverting Schmitt trigger**

TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1

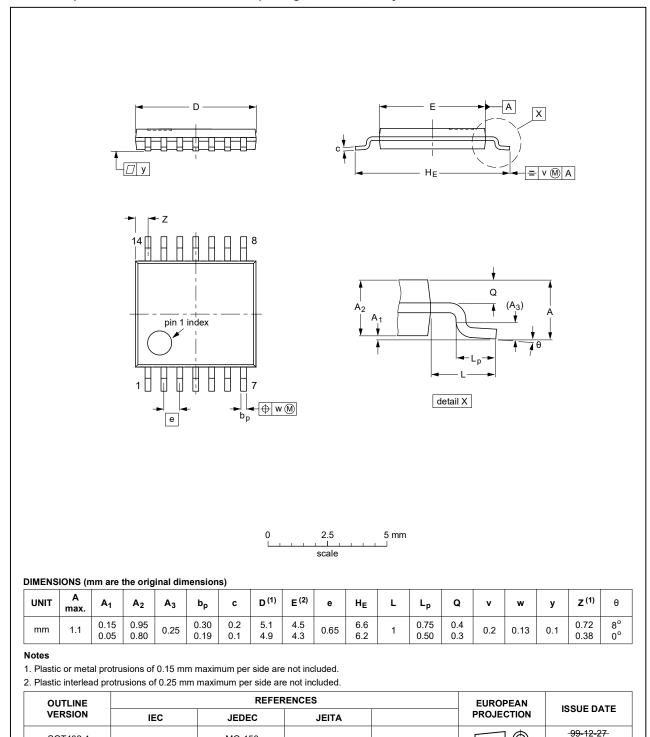


Fig. 12. Package outline SOT402-1 (TSSOP14)

03-02-18

MO-153

SOT402-1

**Hex inverting Schmitt trigger** 

## 15. Abbreviations

#### **Table 12. Abbreviations**

Acronym	Description	
CMOS	Complementary Metal-Oxide Semiconductor	
DUT	Device Under Test	
ESD	ElectroStatic Discharge	
НВМ	Human Body Model	
MM	Machine Model	

## 16. Revision history

## Table 13. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes		
HEF40106B v.10	20221007	Product data sheet	-	HEF40106B v.9		
Modifications:	<u>Table 7</u> : Typo corrected.					
HEF40106B v.9	20211122	Product data sheet	-	HEF40106B v.8		
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Section 1 and Section 2 updated.</li> <li>Table 4: Derating values for P<sub>tot</sub> total power dissipation updated.</li> </ul>					
HEF40106B v.8	20151210	Product data sheet	-	HEF40106B v.7		
Modifications:	Type number HEF40106BP (SOT27-1) removed.					
HEF40106B v.7	20111121	Product data sheet	-	HEF40106B v.6		
Modifications:	<ul><li>Legal pages</li><li>Changes in</li></ul>	updated. Section 1 and Section 2.				
HEF40106B v.6	20110823	Product data sheet	-	HEF40106B v.5		
HEF40106B v.5	20110511	Product data sheet	-	HEF40106B v.4		
HEF40106B v.4	20101115	Product data sheet	-	HEF40106B_CNV v.3		
HEF40106B_CNV v.3	19950101	Product specification	-	HEF40106B_CNV v.2		
HEF40106B_CNV v.2	19950101	Product specification	-	-		

### Hex inverting Schmitt trigger

## 17. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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Product [short] data sheet	Production	This document contains the product specification.

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