## General-purpose Encoder with <br> External Diameter of 50 mm

- Incremental model
- External diameter of 50 mm .
- Resolution of up to 2,000 ppr.
- IP64 (improved oil-proof construction with sealed bearings)
- Side or back connections are possible. Pre-wired Models with cable connected at an angle.


For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

Ordering Information
Encoders [Refer to Dimensions on page 4.]

| Power supply voltage | Output configuration | Resolution (pulses/rotation) | Model |
| :---: | :---: | :---: | :---: |
| 5 to 24 VDC | Open-collector output (NPN) | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600 | E6C2-CWZ6C (resolution) 2M Example: E6C2-CWZ6C 10P/R 2M |
|  |  | $720,800,1,000,1,024,1,200,1,500,1,800,2,000$ |  |
| 12 to 24 VDC | Open-collector output (PNP) | 100, 200, 360, 500, 600 | E6C2-CWZ5B (resolution) 2M Example: E6C2-CWZ5B 100P/R 2M |
|  |  | 1,000, 2,000 |  |
| 5 to 12 VDC | Voltage output | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600 | E6C2-CWZ3E (resolution) 2M <br> Example: E6C2-CWZ3E 10P/R 2M |
|  |  | 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000 |  |
| 5 VDC | Line-driver output | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600 | E6C2-CWZ1X (resolution) 2M Example: E6C2-CWZ1X 10P/R 2M |
|  |  | 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000 |  |

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

| Name | Model |  |
| :--- | :--- | :--- |
| Couplings | E69-C06B | --- |
|  | E69-C68B | Different end diameter |
|  | E69-C610B | Different end diameter |
|  | E69-C06M | Metal construction |
| Flanges | E69-FCA | --- |
|  | E69-FCA02 | E69-2 Servo Mounting Bracket provided. |
|  | E69-2 | Provided with E69-FCA02 Flange. |
| Refer to Accessories for details |  |  |

Refer to Accessories for details.

## Ratings and Specifications

| Item | Model | E6C2-CWZ6C | E6C2-CWZ5B | E6C2-CWZ3E | E6C2-CWZ1X |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Power supply voltage |  | $\begin{aligned} & 5 \text { VDC -5\% to } 24 \text { VDC +15\%, } \\ & \text { ripple (p-p): } 5 \% \text { max. } \end{aligned}$ | $\begin{aligned} & 12 \text { VDC - } 10 \% \text { to } 24 \text { VDC +15\%, } \\ & \text { ripple (p-p): } 5 \% \text { max. } \end{aligned}$ | $\begin{aligned} & 5 \text { VDC -5\% to } 12 \text { VDC +10\%, } \\ & \text { ripple (p-p): } 5 \% \text { max. } \end{aligned}$ | $5 \mathrm{VDC} \pm 5 \%$, ripple (p-p): $5 \%$ max |
| Current consumption*1 |  | 80 mA max. | 100 mA max. |  | 160 mA max. |
| Resolution (pulses/rotation) |  | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000 | $\begin{aligned} & \text { 100, 200, 360, 500, 600, 1,000, } \\ & 2,000 \end{aligned}$ | $\begin{aligned} & 10,20,30,40,50,60,100,200 \\ & 1,000,1,024,1,200,1,500,1,8 \end{aligned}$ | $\begin{aligned} & 00,360,400,500,600,720,800 \\ & 2,000 \end{aligned}$ |
| Output phases |  | Phases A, B, and Z |  |  | Phases A, $\overline{\mathrm{A}}, \mathrm{B}, \overline{\mathrm{B}}, \mathrm{Z}$, and $\overline{\mathrm{Z}}$ |
| Output configuration |  | NPN open-collector output | PNP open-collector output | Voltage output (NPN output) | Line driver output*2 |
| Output capacity |  | Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA ) | Applied voltage: 30 VDC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA ) | Output resistance: $2 \mathrm{k} \Omega$ <br> Output current: 20 mA max. <br> Residual voltage: 0.4 V max. <br> (at sink current of 20 mA ) | AM26LS31 equivalent Output voltage: <br> High level: lo $=-20 \mathrm{~mA}$ Low level: Is = 20 mA Output voltage: $\mathrm{Vo}=2.5 \mathrm{~V}$ min. $\mathrm{V}=0.5 \mathrm{~V}$ max. |
| Maximum response frequency* ${ }^{*}$ |  | 100 kHz | 50 kHz | 100 kHz |  |
| Phase difference between outputs |  | $90^{\circ} \pm 45^{\circ}$ between A and $\mathrm{B}(1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T})$ |  |  |  |
| Rise and fall times of output |  | 1 us max. (Control output voltage: 5 V , Load resistance: $1 \mathrm{k} \Omega$, Cable length: 2 m ) | 1 us max. (Cable length: 2 m , Sink current: | mA) | $0.1 \mu \mathrm{~s}$ max. <br> (Cable length: $2 \mathrm{~m}, \mathrm{lo}=-20 \mathrm{~mA}$, Is $=20 \mathrm{~mA}$ ) |
| Starting torque |  | $10 \mathrm{mN} \cdot \mathrm{m}$ max. |  |  |  |
| Moment of inertia |  | $1 \times 10^{-6} \mathrm{~kg} \cdot \mathrm{~m}^{2}$ max.; $3 \times 10^{-7} \mathrm{~kg} \cdot \mathrm{~m}^{2} \mathrm{max}$. at $600 \mathrm{P} / \mathrm{R}$ max. |  |  |  |
| Shaft loading | Radial | 50 N |  |  |  |
|  | Thrust | 30 N |  |  |  |
| Maximum permissible speed |  | 6,000 r/min |  |  |  |
| Protection circuits |  | Power supply reverse polarity protection, Load short-circuit protection |  |  | --- |
| Ambient temperature range |  | Operating: -10 to $70^{\circ} \mathrm{C}$ (with no icing), Storage: -25 to $85^{\circ} \mathrm{C}$ (with no icing) |  |  |  |
| Ambient humidity range |  | Operating/Storage: $35 \%$ to $85 \%$ (with no condensation) |  |  |  |
| Insulation resistance |  | $20 \mathrm{M} \Omega$ min. (at 500 VDC ) between current-carrying parts and case |  |  |  |
| Dielectric strength |  | 500 VAC, $50 / 60 \mathrm{~Hz}$ for 1 min between current-carrying parts and case |  |  |  |
| Vibration resistance |  | Destruction: 10 to $500 \mathrm{~Hz}, 150 \mathrm{~m} / \mathrm{s}^{2}$ or 2-mm double amplitude for 11 min 3 times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Shock resistance |  | Destruction: $1,000 \mathrm{~m} / \mathrm{s}^{2} 3$ times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Degree of protection |  | IEC 60529 IP64, in-house standards: oilproof |  |  |  |
| Connection method |  | Pre-wired Models (Standard cable length: 2 m ) |  |  |  |
| Material |  | Case: Zinc alloy, Main unit: Aluminum, Shaft: SUS420J2 |  |  |  |
| Weight (packed state) |  | Approx. 400 g |  |  |  |
| Accessories |  | Instruction manual Note: Coupling, mounting bracket and hex-head spanner are sold separately. |  |  |  |

Note: Origin Indication
The following illustration shows the relationship between phase $Z$ and the origin. Set cut face $D$ to the phase $Z$ origin as shown in the illustration.

*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable.(AM26LS31 equivalent)
*3. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:
Maximum electrical response speed $(\mathrm{rpm})=\frac{\text { Maximum response frequency }}{\text { Resolution }} \times 60$
This means that the E6C2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

## I/O Circuit Diagrams



## E6C2-CWZ3E



## E6C2-CWZ3E Voltage Output Model



Note: Phase A is $1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T} \quad$ Note: Phase A is $1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T}$ faster than phase $B$. slower than phase $B$.
("H" and "L" in the diagrams are the output voltage) levels of phases A, B, and Z.

## E6C2-CWZ1X Line Driver Output Model



| Color | Terminal |
| :---: | :---: |
| Brown | Power supply <br> $(+V c c)$ |
| Black | Output phase A |
| White | Output phase B |
| Orange | Output phase Z |
| Black/red <br> stripes | Output phase $\overline{\mathrm{A}}$ |
| White/red <br> stripes | Output phase $\overline{\mathrm{B}}$ |
| Orange/ <br> red stripes | Output phase $\overline{\mathrm{Z}}$ |
| Blue | O V (common) |

Note: Receiver: AM26LS32 equivalent
3. Normally, connect GND to 0 V or to an external ground.

## Safety Precautions

Refer to Warranty and Limitations of Liability.

| $\lfloor$ WARNING |
| :--- |
| This product is not designed or rated for ensuring |
| safety of persons either directly or indirectly. |
| Do not use it for such purposes. |

## Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

## - Wiring

## Cable Extension Characteristics

- When the cable length is extended, the output waveform startup time is lengthened and it affects the phase difference characteristics of phases $A$ and $B$. Conditions will change according to frequency, noise, and other factors. As a guideline, use a cable length of $10 \mathrm{~m}^{*}$ or less. If the cable must be more than 2 m , use a Model with a Line-driver Output (max. length for linedriver output: 100 m ).
* Recommended Cable

Conductor cross section: $0.2 \mathrm{~mm}^{2}$
Spiral shield
Conductor resistance: $92 \Omega / \mathrm{km}$ max. $\left(20^{\circ} \mathrm{C}\right)$
Insulation resistance: $5 \Omega / \mathrm{km}$ min. $\left(20^{\circ} \mathrm{C}\right)$

- The output waveform startup time changes not only according to the length of the cable, but also according to the load resistance and the cable type.
- Extending the cable length not only changes the startup time, but also increases the output residual voltage.


## - Connection

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.
(Unit: mm)
Dimensions
Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

## Encoder

E6C2-CWZ $\square \square$


## Accessories (Order Separately)

| Couplings | Flanges |
| :--- | :--- |
| E69-C06B | E69-FCA |
| E69-C68B | E69-FCA02 |
| E69-C610B |  |
| E69-C06M |  |

## Servo Mounting Bracket

E69-2 (Three brackets in a set.)
Refer to Accessories for details.

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