user's guide to

mikrome ia board for XMEGA

Compact development system rich with on-board peripherals for all-round multimedia development on ATXMEGA128A1





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Nebojsa Matic General Manager

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Introduction to mikromedia for XMEGA

The mikromedia for XMEGA is a compact development system which provides a convenient platform for development of devices with multimedia contents. The central part of the system is a 16-bit microcontroller ATXMEGA128A1 which is programed with bootloader software. The mikromedia for XMEGA features integrated modules such as audio module, TFT 320x240 touch screen display, USB connector for communication with the microcontroller, accelerometer and microSD card connector.









Package contains



Damage resistant protective box



mikromedia for XMEGA development system



OB CD with documentation and examples



mikromedia for XMEGA user's guide



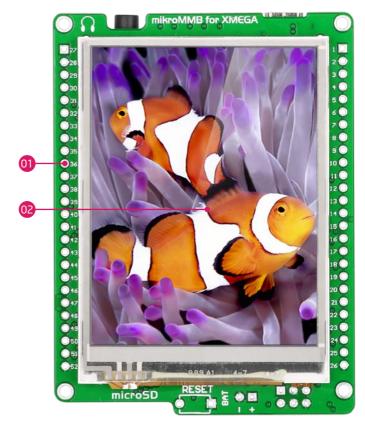
mikromedia for XMEGA schematic

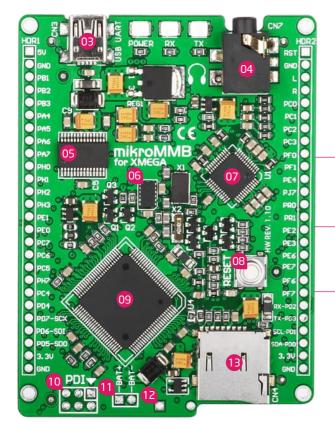


06 USB cable

Key Features

- 01 Pads
- 02 TFT 320x240 display
- USB MINI-B connector
- 04 3.5mm headphone connector
- 05 USB UART module
- 06 Accelerometer
- 07 Audio module
- 08 RESET button
- 09 ATXMEGA128A1
- 10 Pads for external PDI programmer
- 11 LI-Polymer battery connector
- 12 Additional RESET taster pads
- 13 MicroSD Card Slot





System Specification



power supply

Over a USB cable (5V DC)



power consumption

50mA in idle state

(when on-board modules are off)



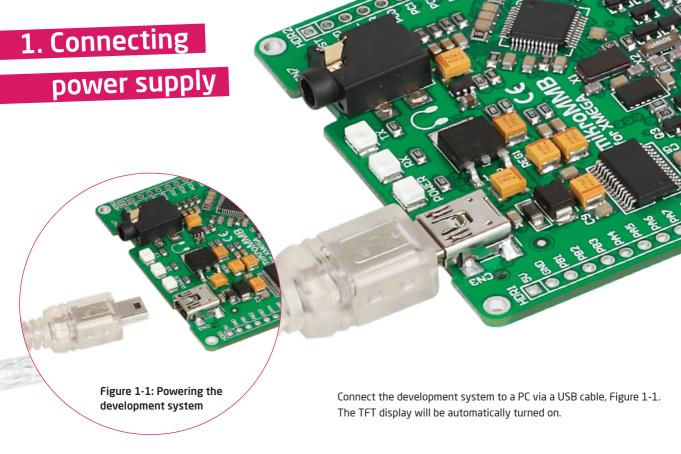
board dimensions

8 x 6cm (3.14 x 2.36 inch)



weight

~50g (0.11 lbs)

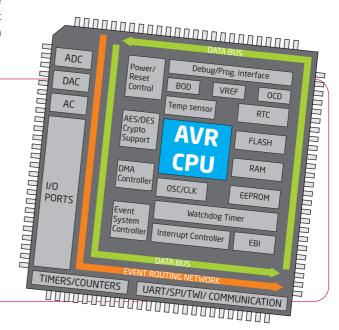


2. ATXMEGA128A Microcontroller

The **mikromedia for XMEGA** development system comes with the **ATXMEGA128A1** microcontroller. This high-performance 8/16-bit microcontroller with its integrated modules and in combination with other on-board modules is ideal for multimedia applications.

Key microcontroller features

- Up to 32 MIPS Operation;
- 8/16-bit architecture:
- 128KB of Flash memory;
- 8KB of SRAM memory;
- 2048Bytes of EEPROM
- 78 I/O pins;
- 32kHz RTC:
- UART, SPI, ADC; etc.



3. Programming with bootloader

For programming, microcontroller use bootloader program which is preinstaled in to MCU memory. To transfer .hex file from a PC to MCU you need bootloader software (mikroBootloader) which can be downloaded from:



After software is downloaded unzip it to desired location and start mikroBootloader software.





Figure 3-1: mikroBootloader software



Connect mikromedia for XMEGA with a PC before starting mikroBootloader software

Identifying device COM port

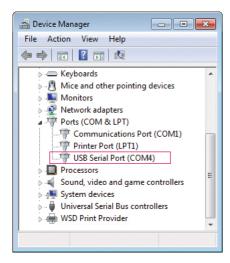


Figure 3-2: Identifying COM port

note

In Device Manager you can see which COM port is assigned to mikromedia (in this case COM4)

step 1 - Choosing COM port

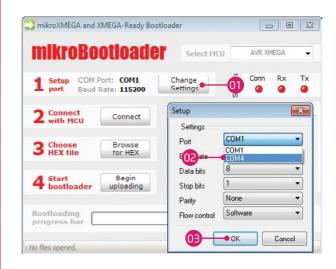


Figure 3-2: Selecting COM port

- 01 Click on Change Settings button
- OP From drop down list select USB COM port which is used for communication with a PC (in this case COM4)
- OB Click OK button

step 2 - Connecting with a PC



Figure 3-3: Connecting mikromedia with mikroBootloader

01 Reset mikromedia board and within 5s click on Connect button

note Baud Rate is set to 115200 by default

step 3 - Browse for .hex file



Figure 3-4: Browsing for .hex file

Olick on Browse for HEX and from pop-up window (figure 3-5) select hex file which will be uploaded to MCU memory

step 4 - Select .hex file

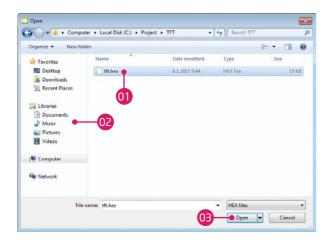


Figure 3-5: Selecting .hex file

- 01 Select desired .hex file
- 02 Folder list
- OB Click on Open button

step 5 - Uploading .hex file



Figure 3-6: Begin uploading

01 Click on Begin uploading button to start .hex file transfer from a PC to microcontroler

step 6 - Progress bar

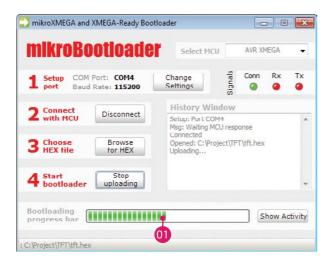


Figure 3-7: Bootloading progress bar

01 Via progress bar you can monitor .hex file uploading process

step 7 - Reset MCU

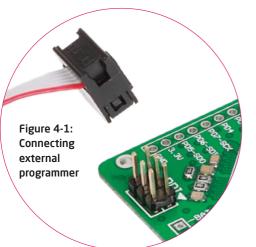


Figure 3-8: Uploading is finished

Olick on OK button after uploading is finished. Reset MCU and you can see product of your work

4. Programing with

external programmer



The microcontroller can be programmed with external programmer (AVRISP mkII, AVR JTAGICE mkII or other supported programer with PDI interface). The external programmer is connected to the development system via pads marked with PDI, Figure 4-1.

In order to connect the external programmer to the development system, it is necessary to provide a 2x3 connector that should be soldered to **PDI** pads. If bootloader program is accidently erased you can upload it again via AVR JTAGICE mkll programmer. Program **xmega_bootloader_firmware.hex** can be found under Firmware folder (page 10).

5. Touch Screen

The development system features a **TFT 320x240 display** covered with a **resistive** touch panel. Together they form a functional unit called a touch screen. It enables data to be entered and displayed at the same time. The way of entering and displaying data depends on the program loaded into the microcontroller. The TFT display is capable of showing data in **262.000** different colors. Figure 5-1: Touch Screen ATXMEGA128A1 Figure 5-2: Touch Screen connection schematic TFT 320x240 display

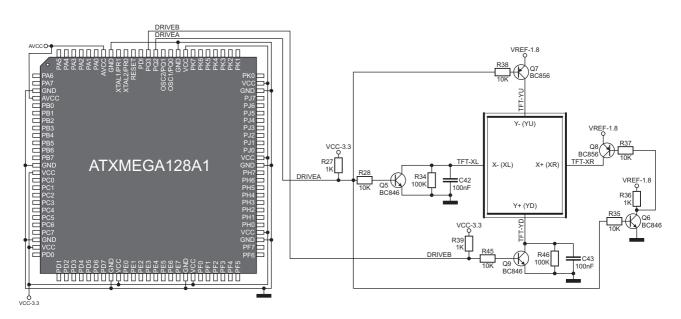


Figure 5-3: Resistive touch panel driver connection schematic

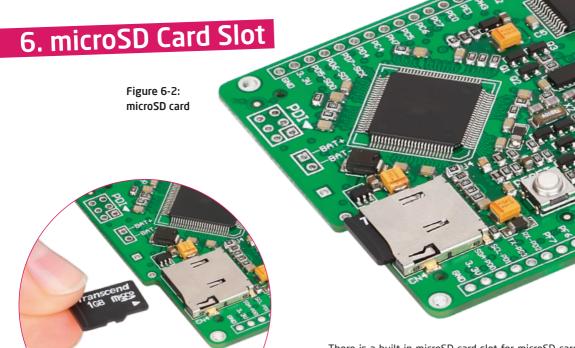


Figure 6-1: Inserting microSD card

There is a built-in microSD card slot for microSD cards provided on the development system. It enables the system to additionally expand available memory space. The Serial Peripheral Interface (**SPI**) is used for communication between the microcontroller and microSD card.

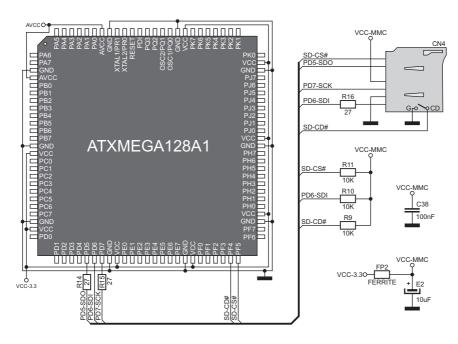


Figure 6-3: microSD card slot connecting schematic

7. Audio Module

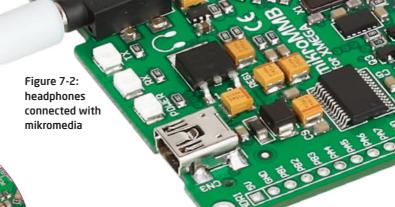


Figure 7-1: Inserting 3.5mm headphones jack

The mikromedia for XMEGA features an audio module providing an interface for stereo headphones. This module enables audio reproduction by using stereo headphones connected to the system via a **3.5mm** connector CN7. Volume as well as other functions of this module are controlled by the microcontroller from within the software using the Serial Peripheral Interface (**SPI**). Communication between the audio module and the microcontroller is performed via the Serial Peripheral Interface (**SPI**).

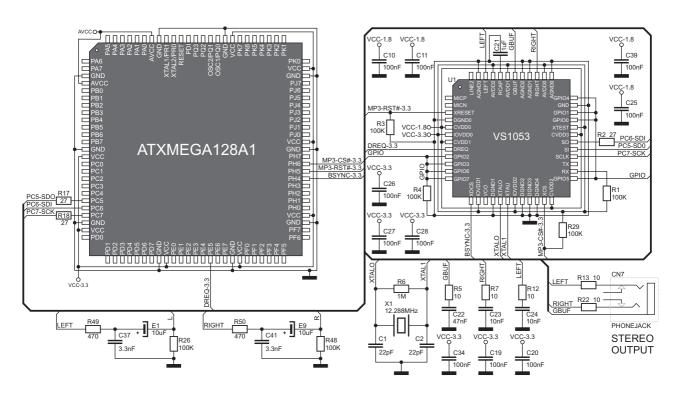


Figure 7-3: Audio module connecting schematic

8. USB UART

Development system can communicate with USB devices via USB UART module. This module comes in form of FT232RL chip which is interface between serial UART on MCU and USB device.

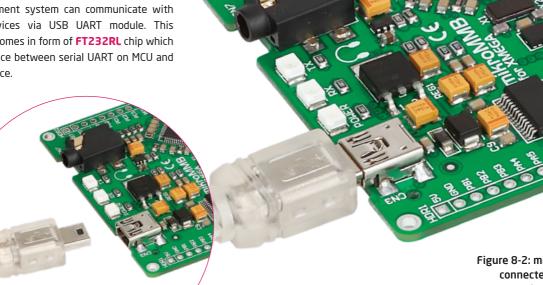


Figure 8-1: Inserting the USB cable

Figure 8-2: mikromedia connected with PC via USB cable

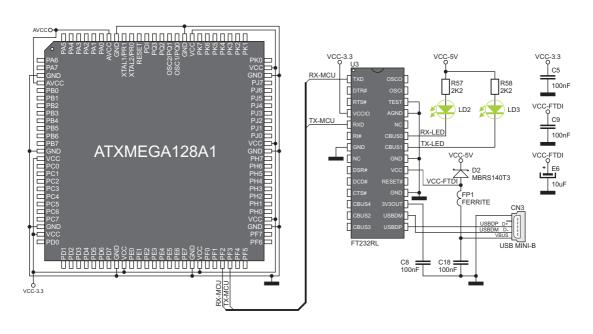


Figure 8-3: USB UART connecting schematic

9. Accelerometer VCC-3.3 PD0-SDA Figure 9-2: ATXMEGA128A1 Accelerometer module The accelerometer is used to measure acceleration. orientation, gravity, etc. The accelerometer's function is defined by the user in the program loaded into the microcontroller. Communication between the accelerometer and the microcontroller is performed via

Figure 9-1: Accelerometer connecting schematic

the I²C interface.

+ 1000mAh 3.74 3 | E384462 110304

10. Battery charger

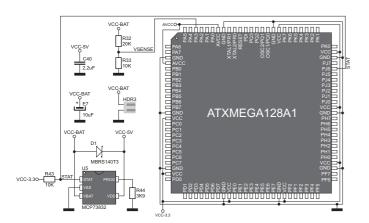
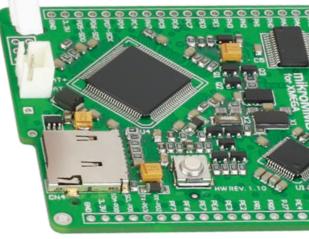


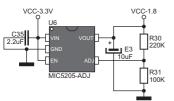
Figure 10-1: Battery charger connecting schematic

Figure 10-2: Li-Polymer battery connected to mikromedia



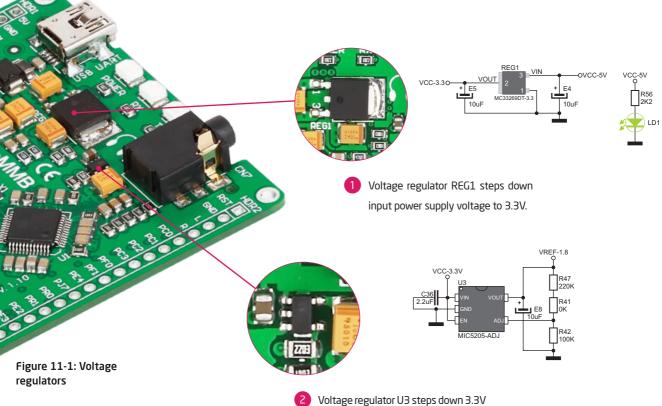
Development system can be supplied with power via **Li-Polymer** battery. To connect battery use connector marked with **BATTERY**. While battery is still connected attach mikromedia with a PC via USB cable. On-board battery charger will start to charge battery. Charging current value is ~250mA and charging voltage is 4.2V DC.

11. Voltage regulators



3 Voltage regulator U6 steps down 3.3V to VCC-1.8 voltage (1.8V).

Input power supply (VCC-5V) is to high for supplying on-board modules. To lower power supply voltage mikromedia board is equipped with voltage regulators. Primary voltage of 5V (3.6V Li-Polymer battery) is stepped down to 3.3V via regulator REG1. 3.3V is distributed to regulators U3 (VREF-1.8) and U6 (VCC-1.8) which step down 3.3V to 1.8V and 1.8V.



to VREF-1.8 voltage (1.8V).

12. Pads 5V power supply I/O pad Pad for reset Ground Ground Left audio out Right audio out Analog I/O **PWM** mmaaaa INTERRUPT I/O pads Dgital I/O SCL SDA I/O pads RX-SCK TX SPI SDI RXSDO TX **UART** RXDigital I/O TX RXTX-PE3 TX-SDO SDA 3.3V power supply I/O pad 3.30 3.3V power supply I/O pad Pad for reset Ground

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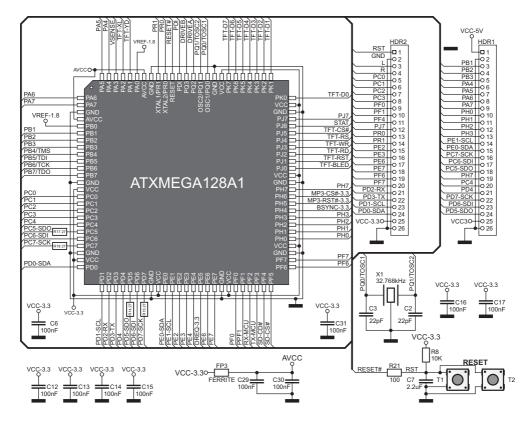
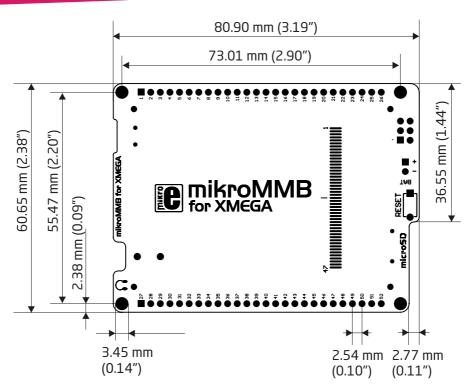


Figure 12-1: Pads connecting schematic

13. Dimensions



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