nRF52810

Product Specification

v1.4



Feature list

Features:

- Bluetooth 5, 2.4 GHz transceiver
 - -96 dBm sensitivity in Bluetooth low energy mode
 - Supported data rates: 1 Mbps, 2 Mbps Bluetooth low energy mode
 - -20 to +4 dBm TX power, configurable in 4 dB steps
 - On-chip balun (single-ended RF)
 - 4.6 mA peak current in TX (0 dBm)
 - 4.6 mA peak current in RX
 - RSSI (1 dB resolution)
- ARM[®] Cortex[®]-M4 32-bit processor, 64 MHz
 - 144 EEMBC CoreMark score running from flash memory
 - 34.4 μA/MHz running CoreMark from flash memory
 - 32.8 μA/MHz running CoreMark from RAM memory
 - Serial wire debug (SWD)
- Flexible power management
 - 1.7 V to 3.6 V supply voltage range
 - Fully automatic LDO and DC/DC regulator system
 - Fast wake-up using 64 MHz internal oscillator
 - 0.3 μA at 3 V in System OFF mode, no RAM retention
 - 0.5 μA at 3 V in System OFF mode with full 24 kB RAM retention
 - 1.5 μA at 3 V in System ON mode, with full 24 kB RAM retention, wake on
 - 1.4 μA at 3 V in System ON mode, no RAM retention, wake on RTC

- 192 kB flash and 24 kB RAM
- Nordic SoftDevice ready
- Support for concurrent multi-protocol
- 12-bit, 200 ksps ADC that has 8 configurable channels with programmable gain
- 64 level comparator
- Temperature sensor
- Up to 32 general purpose I/O pins
- 4-channel pulse width modulator (PWM) unit with EasyDMA
- Digital microphone interface (PDM)
- 3x 32-bit timer with counter mode
- SPI master/slave with EasyDMA
- I²C compatible two-wire master/slave
- UART (CTS/RTS) with EasyDMA
- Programmable peripheral interconnect (PPI)
- Quadrature decoder (QDEC)
- AES HW encryption with EasyDMA
- 2x real-time counter (RTC)
- Single crystal operation
- Package variants
 - QFN48 package, 6 x 6 mm
 - QFN32 package, 5 x 5 mm
 - WLCSP package, 2.482 x 2.464 mm

Applications:

- Computer peripherals and I/O devices
 - Mouse
 - Keyboard
 - Mobile HID
- CE remote controls
- Network processor
 - Wearables
 - Virtual reality headsets

- Health and medical
- Enterprise lighting
 - Industrial
 - Commercial
 - Retail
- Beacons
- Connectivity device in multi-chip solutions



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1 Revision history

Date	Version	Description
November 2021	1.4	The following content has been added or updated: Debug on page 39 - Updated access port protection RADIO - Updated preamble length in packet configuration and RSSI timing UICR - Added NRFMDK registers, removed NRFFW[13] and NRFFW[14] registers, and updated access port protection CLOCK - Updated parameter P _{D_LFXO} POWER - Corrected Erratum-213, by adding missing Wake from System OFF reset source for the WDT in the reset behavior table. Updated minimum valid value for EasyDMA registers MAXCNT and AMOUNT in the following: SPIM SPIS TWIM TWIS UARTE TWIM - Updated t _{TWIM,HD_STA} parameters Mechanical specifications on page 396 - Updated WLCSP mechanical specification Ordering information on page 411 - Build codes Dxx not recommended for new designs
February 2019	1.3	 The following content has been added or updated: Memory on page 17 - Added missing chip variants to memory table Absolute maximum ratings on page 410 - Updated value for Moisture Sensitivity Level for WLCSP package FICR - Added missing WLCSP package to INFO.PACKAGE register UICR - Updated description and PIN size in PSELRESET register EasyDMA on page 36 - Added EasyDMA error handling and updated example code for EasyDMA array list SPIM - Updated the LIST register size SPIS - Added the LIST register and updated the SPI modes table TWIS - Added the LIST register UARTE - Added note about needing an external crystal oscillator for accuracy



Date	Version	Description
		 RADIO - Updated value for parameter C/I_{2M,co-channel} and updated Min. and Max. values for several electrical specification radio timings Added the following serial peripherals: SPI — Serial peripheral interface master on page 256 TWI — I²C compatible two-wire interface on page 300 UART — Universal asynchronous receiver/transmitter on page 353 Editorial
May 2018	1.2	The following content has been added or updated:
		 Added new package variant nRF52810 CAAA WLCSP to the following chapters:
		 Pin assignments on page 389 Mechanical specifications on page 396 Reference circuitry on page 398 Absolute maximum ratings on page 410 Ordering information on page 411 Current consumption on page 46 - Added values for RTC running from LFRC (parameter I_{ON_RAMON_RTC}) Debug on page 39 - Added SWDCLK frequency parameter (f_{SWDCLK}) to the electrical specification NVMC - Updated NVMC write operations description and added partial page erase feature CPU on page 16 - Updated CM_{FLASH/mA} parameter in the electrical specification from 60 to 65 CoreMark/mA TWIM - Added description of suspend short Mechanical specifications on page 396 - Updated mechanical specification drawings for QFN48 and QFN32 Editorial
November 2017	1.1	 RADIO - Added 2 Mbps Bluetooth[®] low energy mode parameters NVMC - Updated electrical specifications TWIM - Added range value for registers TXD.MAXCNT, TXD.AMOUNT, RXD.MAXCNT, and RXD.AMOUNT Ordering information on page 411 - Updated MOQ numbers for nRF52810-QCAA-R7 and nRF52810-QCAA-R Editorial
September 2017	1.0	First release



2

About this document

This document is organized into chapters that are based on the modules and peripherals available in the IC.

2.1 Document status

The document status reflects the level of maturity of the document.

Document name	Description
Objective Product Specification (OPS)	Applies to document versions up to 1.0. This document contains target specifications for product development.
Product Specification (PS)	Applies to document versions 1.0 and higher. This document contains final product specifications. Nordic Semiconductor ASA reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

Table 1: Defined document names

2.2 Peripheral chapters

Every peripheral has a unique capitalized name or an abbreviation of its name, e.g. TIMER, used for identification and reference. This name is used in chapter headings and references, and it will appear in the ARM[®] Cortex[®] Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer to identify the peripheral.

The peripheral instance name, which is different from the peripheral name, is constructed using the peripheral name followed by a numbered postfix, starting with 0, for example, TIMERO. A postfix is normally only used if a peripheral can be instantiated more than once. The peripheral instance name is also used in the CMSIS to identify the peripheral instance.

The chapters describing peripherals may include the following information:

- A detailed functional description of the peripheral
- Register configuration for the peripheral
- Electrical specification tables, containing performance data which apply for the operating conditions described in Recommended operating conditions on page 409.

2.3 Register tables

Individual registers are described using register tables. These tables are built up of two sections. The first three colored rows describe the position and size of the different fields in the register. The following rows describe the fields in more detail.



2.3.1 Fields and values

The **Id (Field Id)** row specifies the bits that belong to the different fields in the register. If a field has enumerated values, then every value will be identified with a unique value id in the **Value Id** column.

A blank space means that the field is reserved and read as undefined, and it also must be written as 0 to secure forward compatibility. If a register is divided into more than one field, a unique field name is specified for each field in the **Field** column. The **Value Id** may be omitted in the single-bit bit fields when values can be substituted with a Boolean type enumerator range, e.g. true/false, disable(d)/enable(d), on/off, and so on.

Values are usually provided as decimal or hexadecimal. Hexadecimal values have a $0 \times$ prefix, decimal values have no prefix.

The Value column can be populated in the following ways:

- Individual enumerated values, for example 1, 3, 9.
- Range of values, e.g. [0..4], indicating all values from and including 0 and 4.
- Implicit values. If no values are indicated in the **Value** column, all bit combinations are supported, or alternatively the field's translation and limitations are described in the text instead.

If two or more fields are closely related, the **Value Id**, **Value**, and **Description** may be omitted for all but the first field. Subsequent fields will indicate inheritance with '..'.

A feature marked **Deprecated** should not be used for new designs.

2.3.2 Permissions

Different fields in a register might have different access permissions enforced by hardware.

The access permission for each register field is documented in the Access column in the following ways:

Access	Description	Hardware behavior
RO	Read-only	Field can only be read. A write will be ignored.
wo	Write-only	Field can only be written. A read will return an undefined value.
RW	Read-write	Field can be read and written multiple times.
W1	Write-once	Field can only be written once per reset. Any subsequent write will be ignored. A read will return an undefined value.
RW1	Read-write-once	Field can be read multiple times, but only written once per reset. Any subsequent write will be ignored.

Table 2: Register field permission schemes

2.4 Registers

Register	Offset	Description
DUMMY	0x514	Example of a register controlling a dummy feature

Table 3: Register overview

2.4.1 DUMMY

Address offset: 0x514

Example of a register controlling a dummy feature



Bit r	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	4 3 2 1 0
ID			DDDI	D C C C B	АА
Rese	et 0x00050002		0 0 0 0 0 0 0	0 0 0 0 0 0 1 0 1 0 0 0 0 0 0 0 0 0 0 0	0 0 0 1 0
ID					
Α	RW FIELD_A			Example of a read-write field with several enumerated	
				values	
		Disabled	0	The example feature is disabled	
		NormalMode	1	The example feature is enabled in normal mode	
		ExtendedMode	2	The example feature is enabled along with extra	
				functionality	
В	RW FIELD_B			Example of a deprecated read-write field	Deprecated
		Disabled	0	The override feature is disabled	
		Enabled	1	The override feature is enabled	
С	RW FIELD_C			Example of a read-write field with a valid range of values	
		ValidRange	[27]	Example of allowed values for this field	
D	RW FIELD_D			Example of a read-write field with no restriction on the	
				values	



3 Block diagram

This block diagram illustrates the overall system. Arrows with white heads indicate signals that share physical pins with other signals.

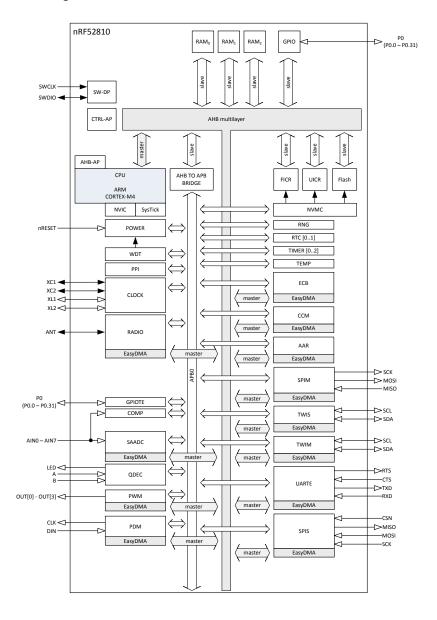


Figure 1: Block diagram

4 Core components

4.1 CPU

The ARM[®] Cortex-M4 processor has a 32-bit instruction set (Thumb[®]-2 technology) that implements a superset of 16- and 32-bit instructions to maximize code density and performance.

This processor implements several features that enable energy-efficient arithmetic and high-performance signal processing including:

- Digital signal processing (DSP) instructions
- Single-cycle multiply and accumulate (MAC) instructions
- Hardware divide
- 8- and 16-bit single instruction multiple data (SIMD) instructions

The ARM Cortex Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer for the ARM Cortex processor series is implemented and available for the M4 CPU.

Real-time execution is highly deterministic in thread mode, to and from sleep modes, and when handling events at configurable priority levels via the nested vectored interrupt controller (NVIC).

Executing code from flash will have a wait state penalty on the nRF52 Series. The section Electrical specification on page 16 shows CPU performance parameters including wait states in different modes, CPU current and efficiency, and processing power and efficiency based on the CoreMark® benchmark.

The ARM System Timer (SysTick) is present on the device. The SysTick's clock will only tick when the CPU is running or when the system is in debug interface mode.

4.1.1 Electrical specification

4.1.1.1 CPU performance

The CPU clock speed is 64 MHz. Current and efficiency data is taken when in System ON and the CPU is executing the CoreMark[®] benchmark. It includes power regulator and clock base currents. All other blocks are IDLE.

Symbol	Description	Min.	Тур.	Max.	Units
W _{FLASH}	CPU wait states, running from flash	0		2	
W_{RAM}	CPU wait states, running from RAM			0	
CM_{FLASH}	CoreMark ¹ , running from flash		144		CoreMark
CM _{FLASH/MHz}	CoreMark per MHz, running from flash		2.25		Corel
					MHz
CM _{FLASH/mA}	CoreMark per mA, running from flash, DCDC 3V		65		CoreMark/
					mA

4.1.2 CPU and support module configuration

The ARM[®] Cortex[®]-M4 processor has a number of CPU options and support modules implemented on the device.

Using IAR v6.50.1.4452 with flags --endian=little --cpu=Cortex-M4 -e --fpu=VFPv4_sp -Ohs -no_size_constraints



Description	Implemented
Nested vector interrupt controller	30 vectors
Priority bits	3
Wakeup interrupt controller	NO
Memory system endianness	Little endian
Bit banded memory	NO
Data watchpoint and trace	NO
System tick timer	YES
Memory protection unit	YES
Floating-point unit	NO
Debug access port	YES
Embedded trace macrocell	NO
Instrumentation trace macrocell	NO
Trace port interface unit	NO
Embedded trace buffer	NO
Flash patch and breakpoint unit	YES
AMBA® AHB trace macrocell	NO
	Nested vector interrupt controller Priority bits Wakeup interrupt controller Memory system endianness Bit banded memory Data watchpoint and trace System tick timer Memory protection unit Floating-point unit Debug access port Embedded trace macrocell Instrumentation trace macrocell Trace port interface unit Embedded trace buffer Flash patch and breakpoint unit

4.2 Memory

The nRF52810 contains flash and RAM that can be used for code and data storage.

The amount of RAM and flash differs depending on variant, see Memory variants on page 17.

Device name	RAM	Flash
nRF52810-QFAA	24 kB	192 kB
nRF52810-QCAA	24 kB	192 kB
nRF52810-CAAA	24 kB	192 kB

Table 4: Memory variants

The CPU and peripherals with EasyDMA can access memory via the AHB multilayer interconnect. The CPU is also able to access peripherals via the AHB multilayer interconnect, as illustrated in Memory layout on page 18.



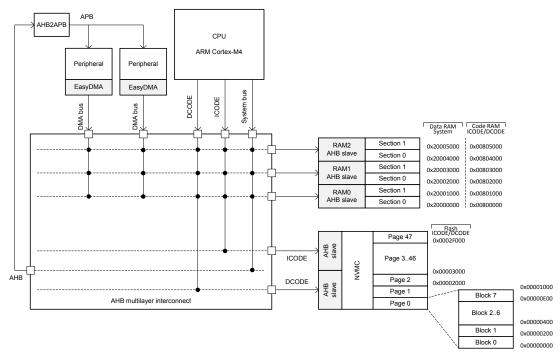


Figure 2: Memory layout

See AHB multilayer on page 39 and EasyDMA on page 36 for more information about the AHB multilayer interconnect and the EasyDMA.

The same physical RAM is mapped to both the Data RAM region and the Code RAM region. It is up to the application to partition the RAM within these regions so that one does not corrupt the other.

4.2.1 RAM - Random access memory

The RAM interface is divided into three RAM AHB slaves.

RAM AHB slaves 0 to 2 are connected to two 4 kB RAM sections each, as shown in Memory layout on page 18.

Each RAM section has separate power control for System ON and System OFF mode operation, which is configured via RAM register (see the POWER — Power supply on page 52).

4.2.2 Flash - Non-volatile memory

The flash can be read an unlimited number of times by the CPU, but it has restrictions on the number of times it can be written and erased, and also on how it can be written.

Writing to flash is managed by the non-volatile memory controller (NVMC), see NVMC — Non-volatile memory controller on page 20.

The flash is divided into multiple 4 kB pages that can be accessed by the CPU via both the ICODE and DCODE buses as shown in, Memory layout on page 18. Each page is divided into 8 blocks.

4.2.3 Memory map

The complete memory map is shown in Memory map on page 19. As described in Memory on page 17, Code RAM and Data RAM are the same physical RAM.



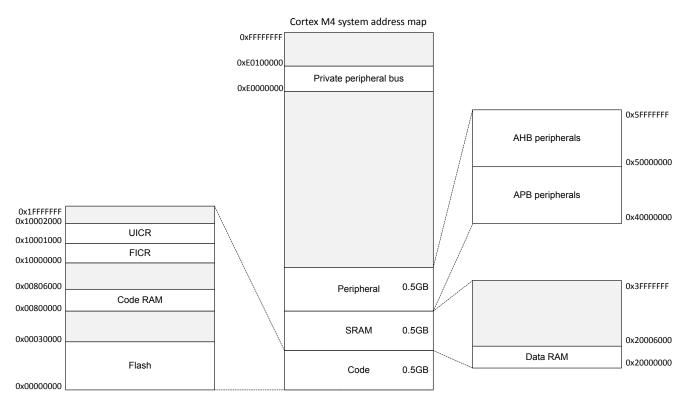


Figure 3: Memory map

4.2.4 Instantiation

ID	Base address	Peripheral	Instance	Description			
0	0x40000000	APPROTECT	APPROTECT	APPROTECT control			
0	0x40000000	BPROT	BPROT	Block protect			
0	0x40000000	CLOCK	CLOCK	Clock control			
0	0x40000000	POWER	POWER	Power control			
0	0x50000000	GPIO	P0	General purpose input and output			
1	0x40001000	RADIO	RADIO	2.4 GHz radio			
2	0x40002000	UART	UART0	Universal asynchronous receiver/transmitter De			
2	0x40002000	UARTE	UARTE0	Universal asynchronous receiver/transmitter with EasyDMA			
3	0x40003000	TWI	TWI0	Two-wire interface master	Deprecated		
3	0x40003000	TWIM	TWIM0	Two-wire interface master			
3	0x40003000	TWIS	TWIS0	Two-wire interface slave			
4	0x40004000	SPI	SPI0	SPI master	Deprecated		
4	0x40004000	SPIM	SPIM0	SPI master			
4	0x40004000	SPIS	SPIS0	SPI slave			
6	0x40006000	GPIOTE	GPIOTE	GPIO tasks and events			
7	0x40007000	SAADC	SAADC	Analog-to-digital converter			
8	0x40008000	TIMER	TIMER0	Timer 0			
9	0x40009000	TIMER	TIMER1	Timer 1			
10	0x4000A000	TIMER	TIMER2	Timer 2			
11	0x4000B000	RTC	RTC0	Real-time counter 0			
12	0x4000C000	TEMP	TEMP	Temperature sensor			
13	0x4000D000	RNG	RNG	Random number generator			
14	0x4000E000	ECB	ECB	AES Electronic Codebook (ECB) mode block encryption			
15	0x4000F000	AAR	AAR	Accelerated address resolver			
15	0x4000F000	ССМ	ССМ	AES CCM mode encryption			
16	0x40010000	WDT	WDT	Watchdog timer			



ID	Base address	Peripheral	Instance	Description
		•		
17	0x40011000	RTC	RTC1	Real-time counter 1
18	0x40012000	QDEC	QDEC	Quadrature decoder
19	0x40013000	COMP	COMP	General purpose comparator
20	0x40014000	EGU	EGU0	Event generator unit 0
20	0x40014000	SWI	SWI0	Software interrupt 0
21	0x40015000	EGU	EGU1	Event generator unit 1
21	0x40015000	SWI	SWI1	Software interrupt 1
22	0x40016000	SWI	SWI2	Software interrupt 2
23	0x40017000	SWI	SWI3	Software interrupt 3
24	0x40018000	SWI	SWI4	Software interrupt 4
25	0x40019000	SWI	SWI5	Software interrupt 5
28	0x4001C000	PWM	PWM0	Pulse-width modulation unit 0
29	0x4001D000	PDM	PDM	Pulse-density modulation (digital microphone interface)
30	0x4001E000	NVMC	NVMC	Non-volatile memory controller
31	0x4001F000	PPI	PPI	Programmable peripheral interconnect
N/A	0x10000000	FICR	FICR	Factory information configuration
N/A	0x10001000	UICR	UICR	User information configuration

Table 5: Instantiation table

4.3 NVMC — Non-volatile memory controller

The non-volatile memory controller (NVMC) is used for writing and erasing of the internal flash memory and the UICR (user information configuration registers).

The CONFIG on page 22 is used to enable the NVMC for writing (CONFIG.WEN) and erasing (CONFIG.EEN). The user must make sure that writing and erasing are not enabled at the same time. Having both enabled at the same time may result in unpredictable behavior.

The CPU must be halted before initiating a NVMC operation from the debug system.

4.3.1 Writing to flash

When writing is enabled, full 32-bit words are written to word-aligned addresses in flash.

As illustrated in Memory on page 17, the flash is divided into multiple pages. The same 32-bit word in the flash can only be written n_{WRITE} number of times before a page erase must be performed.

The NVMC is only able to write 0 to bits in the flash that are erased (set to 1). It cannot rewrite a bit back to 1. Only full 32-bit words can be written to flash using the NVMC interface. To write less than 32 bits, write the data as a full 32-bit word and set all the bits that should remain unchanged in the word to 1. Note that the restriction on the number of writes (n_{WRITE}) still applies in this case.

Only word-aligned writes are allowed. Byte or half-word-aligned writes will result in a hard fault.

The time it takes to write a word to flash is specified by t_{WRITE} . The CPU is halted while the NVMC is writing to the flash.

4.3.2 Erasing a page in flash

When erase is enabled, the flash memory can be erased page by page using the ERASEPAGE on page 22

After erasing a flash page, all bits in the page are set to 1. The time it takes to erase a page is specified by $t_{\text{ERASEPAGE}}$. The CPU is halted if the CPU executes code from the flash while the NVMC is writing to the flash.



See Partial erase of a page in flash on page 21 for information on dividing the page erase time into shorter chunks.

4.3.3 Writing to user information configuration registers (UICR)

User information configuration registers (UICR) are written in the same way as flash. After UICR has been written, the new UICR configuration will take effect after a reset.

UICR can only be written n_{WRITE} number of times before an erase must be performed using ERASEUICR on page 24 or ERASEALL on page 23. The time it takes to write a word to UICR is specified by t_{WRITE} . The CPU is halted while the NVMC is writing to the UICR.

4.3.4 Erasing user information configuration registers (UICR)

When erase is enabled, UICR can be erased using the ERASEUICR on page 24.

After erasing UICR all bits in UICR are set to 1. The time it takes to erase UICR is specified by $t_{\text{ERASEPAGE}}$. The CPU is halted if the CPU executes code from the flash while the NVMC performs the erase operation.

4.3.5 Frase all

When erase is enabled, flash and UICR can be erased completely in one operation by using ERASEALL on page 23. This operation will not erase the factory information configuration registers (FICR).

The time it takes to perform an ERASEALL command is specified by t_{ERASEALL}. The CPU is halted if the CPU executes code from the flash while the NVMC performs the erase operation.

4.3.6 Partial erase of a page in flash

Partial erase is a feature in the NVMC to split a page erase time into shorter chunks, so this can be used to prevent longer CPU stalls in time-critical applications. Partial erase is only applicable to the code area in the flash and does not work with UICR.

When erase is enabled, the partial erase of a flash page can be started by writing to ERASEPAGEPARTIAL on page 24. The duration of a partial erase can be configured in ERASEPAGEPARTIALCFG on page 24. A flash page is erased when its erase time reaches $t_{\text{ERASEPAGE}}$. Use ERASEPAGEPARTIAL N number of times so that N * ERASEPAGEPARTIALCFG \geq $t_{\text{ERASEPAGE}}$, where N * ERASEPAGEPARTIALCFG gives the cumulative (total) erase time. Every time the cumulative erase time reaches $t_{\text{ERASEPAGE}}$, it counts as one erase cycle.

After the erase is done, all bits in the page are set to '1'. The CPU is halted if the CPU executes code from the flash while the NVMC performs the partial erase operation.

The bits in the page are undefined if the flash page erase is incomplete, i.e. if a partial erase has started but the total erase time is less than $t_{\text{ERASEPAGE}}$.

4.3.7 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4001E000	NVMC	NVMC	Non-volatile memory controller	

Table 6: Instances

Register	Offset	Description	
READY	0x400	Ready flag	
CONFIG	0x504	Configuration register	
ERASEPAGE	0x508	Register for erasing a page in code area	
ERASEPCR1	0x508	Register for erasing a page in code area. Equivalent to ERASEPAGE.	Deprecated



Register	Offset	Description	
ERASEALL	0x50C	Register for erasing all non-volatile user memory	
ERASEPCR0	0x510	Register for erasing a page in code area. Equivalent to ERASEPAGE.	Deprecated
ERASEUICR	0x514	Register for erasing user information configuration registers	
ERASEPAGEPARTIAL	0x518	Register for partial erase of a page in code area	
ERASEPAGEPARTIALCFG	0x51C	Register for partial erase configuration	

Table 7: Register overview

4.3.7.1 READY

Address offset: 0x400

Ready flag

Bit number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000001		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R READY			NVMC is ready or busy
	Busy	0	NVMC is busy (ongoing write or erase operation)
	Ready	1	NVMC is ready

4.3.7.2 CONFIG

Address offset: 0x504 Configuration register

Bit r	number		31 30 29 28 2	7 26 25	24	23 22	21 2	20 19	9 18	17	16	15 1	14 :	13 1	12 1	11 1	0 9	8	7	6	5	4	3	2	1 (
ID																									ΑА
Res	et 0x00000000		0 0 0 0 0	0 0	0	0 0	0	0 0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 0
Α	RW WEN					rogra	am r	nem	ory	acc	ess	mo	de	. It	is s	tror	ngly	rec	om	nei	nde	d			
					1	o act	ivate	e era	ise a	and	wri	ite n	no	des	on	ly w	hen	the	еу а	re					
						ctive	ely us	sed.																	
		Ren	0			Read	only	acc	ess																
		Wen	1		,	Vrite	ena	bled	ł																
		Een	2			rase	ena	bled																	

4.3.7.3 ERASEPAGE

Address offset: 0x508

Register for erasing a page in code area

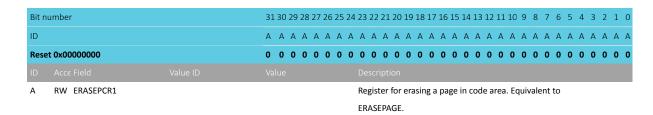


Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A RW ERASEPAGE	Register for starting erase of a page in code area.
	The value is the address to the page to be erased (addresses
	of first word in page). Note that the erase must be enabled
	using CONFIG.WEN before the page can be erased.
	Attempts to erase pages that are outside the code area may
	result in undesirable behavior, e.g. the wrong page may be
	erased.

4.3.7.4 ERASEPCR1 (Deprecated)

Address offset: 0x508

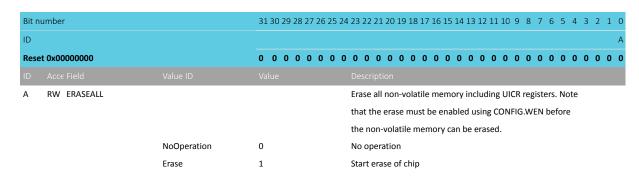
Register for erasing a page in code area. Equivalent to ERASEPAGE.



4.3.7.5 ERASEALL

Address offset: 0x50C

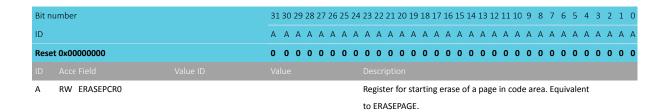
Register for erasing all non-volatile user memory



4.3.7.6 ERASEPCRO (Deprecated)

Address offset: 0x510

Register for erasing a page in code area. Equivalent to ERASEPAGE.

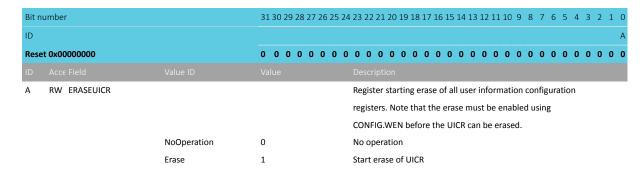




4.3.7.7 ERASEUICR

Address offset: 0x514

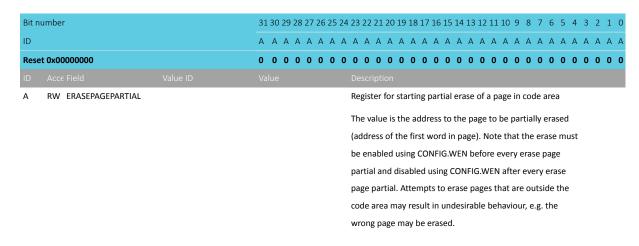
Register for erasing user information configuration registers



4.3.7.8 ERASEPAGEPARTIAL

Address offset: 0x518

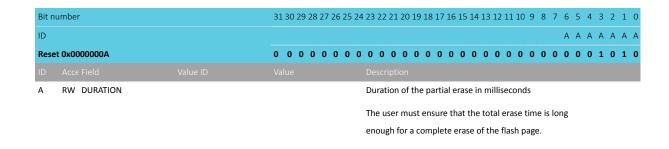
Register for partial erase of a page in code area



4.3.7.9 ERASEPAGEPARTIALCFG

Address offset: 0x51C

Register for partial erase configuration





4.3.8 Electrical specification

4.3.8.1 Flash programming

Symbol	Description	Min.	Тур.	Max.	Units
n _{WRITE}	Number of times a 32-bit word can be written before erase			2	
n _{endurance}	Erase cycles per page	10000			
t _{WRITE}	Time to write one 32-bit word			41 ²	μs
t _{ERASEPAGE}	Time to erase one page			85 ²	ms
t _{ERASEALL}	Time to erase all flash			169 ²	ms
$t_{ERASEPAGEPARTIAL,acc}$	Accuracy of the partial page erase duration. Total			1.05 ²	
	execution time for one partial page erase is defined as				
	ERASEPAGEPARTIALCFG * t _{erasepagepartial,acc}				

4.4 FICR — Factory information configuration registers

Factory information configuration registers (FICR) are pre-programmed in factory and cannot be erased by the user. These registers contain chip-specific information and configuration.

4.4.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x10000000	FICR	FICR	Factory information configuration	

Table 8: Instances

Register	Offset	Description	
CODEPAGESIZE	0x010	Code memory page size	
CODESIZE	0x014	Code memory size	
DEVICEID[0]	0x060	Device identifier	
DEVICEID[1]	0x064	Device identifier	
ER[0]	0x080	Encryption root, word 0	
ER[1]	0x084	Encryption root, word 1	
ER[2]	0x088	Encryption root, word 2	
ER[3]	0x08C	Encryption root, word 3	
IR[0]	0x090	Identity root, word 0	
IR[1]	0x094	Identity root, word 1	
IR[2]	0x098	Identity root, word 2	
IR[3]	0x09C	Identity root, word 3	
DEVICEADDRTYPE	0x0A0	Device address type	
DEVICEADDR[0]	0x0A4	Device address 0	
DEVICEADDR[1]	0x0A8	Device address 1	
INFO.PART	0x100	Part code	
INFO.VARIANT	0x104	Part variant, hardware version and production configuration	
INFO.PACKAGE	0x108	Package option	
INFO.RAM	0x10C	RAM variant	
INFO.FLASH	0x110	Flash variant	
INFO.UNUSED8[0]	0x114		Reserved

² HFXO is used here



Register	Offset	Description	
NFO.UNUSED8[1]	0x118		Reserved
NFO.UNUSED8[2]	0x11C		Reserved
EMP.A0	0x404	Slope definition A0	Nesei veu
EMP.A1	0x404	Slope definition A1	
		·	
EMP.A2	0x40C	Slope definition A2	
EMP.A3	0x410	Slope definition A3	
EMP.A4	0x414	Slope definition A4	
EMP.A5	0x418	Slope definition A5	
EMP.B0	0x41C	Y-intercept B0	
EMP.B1	0x420	Y-intercept B1	
EMP.B2	0x424	Y-intercept B2	
EMP.B3	0x428	Y-intercept B3	
EMP.B4	0x42C	Y-intercept B4	
EMP.B5	0x430	Y-intercept B5	
EMP.TO	0x434	Segment end T0	
EMP.T1	0x438	Segment end T1	
EMP.T2	0x43C	Segment end T2	
EMP.T3	0x440	Segment end T3	
EMP.T4	0x444	Segment end T4	

Table 9: Register overview

4.4.1.1 CODEPAGESIZE

Address offset: 0x010 Code memory page size

Α	R	CODEPAGESIZE								С	ode	me	emo	ry p	age	siz	ze.														
ID																															
Res	et 0x0	0001000	0	0	0	0	0 () (0 (0	0	0	0	0	0	0	0	0 (0	1	0	0	0	0	0	0	0	0 0	0	0	0
ID			А	Α	Α	Α	A A	A A	4 Α	Α Α	A	Α	Α	Α	A	A ,	A ,	A A	A A	A	Α	Α	Α	Α	Α	Α	Α.	ДД	Α	Α	Α
Bit r	numbe	er	31	30	29 2	28 2	27 2	6 2	5 2	4 2:	3 22	2 2 1	. 20	19	18 1	17 1	L6 1	L5 1	4 1	3 12	2 11	. 10	9	8	7	6	5	4 3	2	1	0

4.4.1.2 CODESIZE

Address offset: 0x014 Code memory size

Α	R CODESIZE	Cod	ode memory size in number of pages
ID			
Res	et 0x00000030	0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0
ID		A A A A A A A A	
Bit r	umber	31 30 29 28 27 26 25 24 23	3 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

Code memory size in number of pages

Total code space is: CODEPAGESIZE * CODESIZE

4.4.1.3 DEVICEID[n] (n=0..1)

Address offset: $0x060 + (n \times 0x4)$

Device identifier



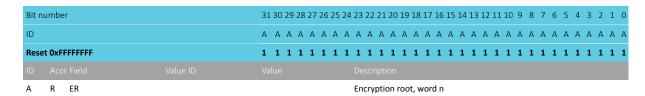
ID Acce Field	
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID	A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

DEVICEID[0] contains the least significant bits of the device identifier. DEVICEID[1] contains the most significant bits of the device identifier.

4.4.1.4 ER[n] (n=0..3)

Address offset: $0x080 + (n \times 0x4)$

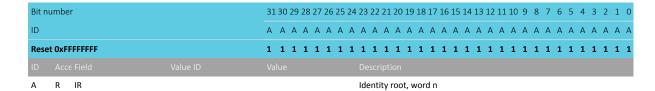
Encryption root, word n



4.4.1.5 IR[n] (n=0..3)

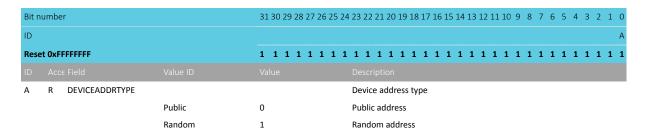
Address offset: $0x090 + (n \times 0x4)$

Identity root, word n



4.4.1.6 DEVICEADDRTYPE

Address offset: 0x0A0 Device address type

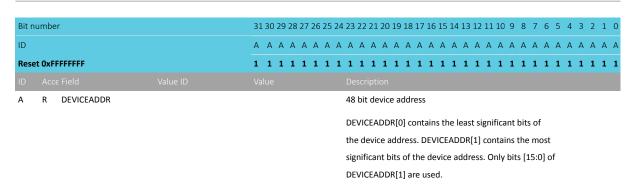


4.4.1.7 DEVICEADDR[n] (n=0..1)

Address offset: $0x0A4 + (n \times 0x4)$

Device address n





4.4.1.8 INFO.PART

Address offset: 0x100

Part code

Bit number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0x00052810	0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 1 0 1 0 1 0 0 0 0 0 0
ID Acce Field Value ID		Description
A R PART		Part code
N52810	0x52810	nRF52810
N52811	0x52811	nRF52811
N52832	0x52832	nRF52832
Unspecified	0xFFFFFFF	Unspecified

4.4.1.9 INFO.VARIANT

Address offset: 0x104

Part variant, hardware version and production configuration

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	et OxFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	R VARIANT			Part variant, hardware version and production
				configuration, encoded as ASCII
		AAAA	0x41414141	AAAA
		AAA0	0x41414130	AAA0
		AABA	0x41414241	AABA
		AABB	0x41414242	AABB
		AAB0	0x41414230	AAB0
		AACA	0x41414341	AACA
		AACB	0x41414342	AACB
		AAC0	0x41414330	AAC0
		AAE0	0x41414530	AAE0
		AAE1	0x41414531	AAE1
		Unspecified	0xFFFFFFF	Unspecified

4.4.1.10 INFO.PACKAGE

Address offset: 0x108

Package option



Bit n	umbe	r		31	30 2	29 2	28	27	26	25	24	23	22	21	20 :	19 :	18 :	17 :	16	15	14	13	12 :	11 :	10	9	8	7	6	5	4	3	2	1 0
ID				Α	A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A .	4 A
Rese	t OxF	FFFFFF		1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1 1
ID																																		
Α	R	PACKAGE										Pac	cka	ge c	pti	on																		
			QF	0x2	2000)						QF	xx -	48	-pir	ı Q	FN																	
			QC	0x2	2003	3						QC	xx -	- 32	iq-	n Q	FN																	
			CA	0x2	2004	ļ						CA	xx -	WI	.CS	Р																		
			Unspecified	0xI	FFFF	FFI	FF					Un	spe	cifi	ed																			

4.4.1.11 INFO.RAM

Address offset: 0x10C

RAM variant

Bit nu	mber		31	30	29	28 2	27 2	6 2	5 24	4 23	3 22	2 21	L 20	19	18	17	16	15	14	13	12 :	11 1	10 9	9 8	7	6	5	4	3	2	1 0
ID			Α	Α	Α	Α	ΑА	. Δ	A	Α	Δ	A	Α	. A	Α	Α	Α	Α	Α	Α	Α	Α	A A	Α Α	Α	Α	Α	Α	Α	A	ΔА
Reset	0x0000018		0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	1	1	0	0 0
ID																															
Α	R RAM									R	ΑM	l vai	rian	nt																	
		K24	0x1	18						2	4 kl	Byte	e RA	ΑM																	
		Unspecified	0xF	FFF	FFF	FF				U	nsp	eci	fiec	d																	

4.4.1.12 INFO.FLASH

Address offset: 0x110

Flash variant

Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0x000000C0		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0
ID Acce Field			
A R FLASH			Flash variant
	K192	0xC0	192 kByte flash
	Unspecified	0xFFFFFFF	Unspecified

4.4.1.13 TEMP.A0

Address offset: 0x404 Slope definition A0

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18	3 17 16 15 14 1	3 12 11 10	9 8	7	6 !	5 4	3	2 1
ID					АА	4 Α	Α	Α ,	4 A	Α.	А А
Reset 0xFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1	1 1 1 1 1	1 1 1	1 1	1	1 :	1 1	1	1 1
ID Acce Field	Value ID	Value	Description								

A R A A (slope definition) register

4.4.1.14 TEMP.A1

Address offset: 0x408 Slope definition A1



Reset 0xFFFFFFFF 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Description
Reset OxFFFFFFF 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID	A A A A A A A A A A A A A A A A A A A
Bit number 31 30 29 28 2	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

4.4.1.15 TEMP.A2

Address offset: 0x40C Slope definition A2

		A (slope definition) register
ID Acce Field		
Reset 0xFFFFFFF	1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID		A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

4.4.1.16 TEMP.A3

Address offset: 0x410 Slope definition A3

A R A		A (slope definition) registe	r		
ID Acce Field					
Reset 0xFFFFFFF	1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1	11111	11111
ID			ААА	A A A A A	A A A A A
Bit number	31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15	14 13 12 11 10 9	8 7 6 5 4	4 3 2 1 0

4.4.1.17 TEMP.A4

Address offset: 0x414 Slope definition A4

Bit number	31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field		Description
A R A		A (slope definition) register

4.4.1.18 TEMP.A5

Address offset: 0x418 Slope definition A5

A R A	1218212	12122	A (slope definition) register			
ID Acce Field	Value ID		Description			
Reset 0xFFFFFFF		1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1	1111	1 1 1 1
ID				A A A A	. A A A A	A A A A
Bit number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14	13 12 11 10 9 8	7 6 5 4	3 2 1 0

4430_161 v1.4 30



Downloaded from Arrow.com.

4.4.1.19 TEMP.B0

Address offset: 0x41C

Y-intercept B0

Bit number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field		
A R B		B (y-intercept)

4.4.1.20 TEMP.B1

Address offset: 0x420

Y-intercept B1

Λ	D B		B /s	v-inte	rcon	+1														
ID A																				
Reset 0	xFFFFFFF	1 1 1 1 1 1 1	1 1	1 1	1	1 1	1 1	. 1	1 1	. 1	1	1	1	1 1	1	1	1	1	1 1	. 1
ID									A	A	Α	Α	Α	A A	. A	Α	Α	Α	A A	A A
Bit num	nber	31 30 29 28 27 26 25 2	24 23 :	22 21	1 20 1	19 18	17 1	6 15	14 1	3 12	11	10	9	8 7	6	5	4	3	2 1	. 0

4.4.1.21 TEMP.B2

Address offset: 0x424

Y-intercept B2

Bit number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14	4 13 12 11 10 9 8	7 6 5 4 3 2 1 0
ID			A A A A A	A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1	111111	. 1 1 1 1 1 1 1 1
ID Acce Field				
A R B		B (y-intercept)		

4.4.1.22 TEMP.B3

Address offset: 0x428

Y-intercept B3

Bit number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field		
A R B		B (y-intercept)

4.4.1.23 TEMP.B4

Address offset: 0x42C

Y-intercept B4



Bit number	31 30 29 28 27 26 25 24 23 22 21 2	20 19 18 17 16 15 14 13 12 11 10	9 8 7 6 5 4 3 2 1 0
ID		АААА	. A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1
ID Acce Field Value ID			

4.4.1.24 TEMP.B5

Address offset: 0x430

Y-intercept B5

A R B		B (y-intercept)			
ID Acce Field					
Reset 0xFFFFFFF	1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1	1 1 1 1 1	1 1 1 1 1
ID			АААА	AAAAA	A A A A A
Bit number	31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 1	5 14 13 12 11 10	9 8 7 6 5	4 3 2 1 0

4.4.1.25 TEMP.TO

Address offset: 0x434

Segment end TO

Reset 0xFFFFFFFF		
Reset 0xFFFFFFFF 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
IU .	111111	1 1 1 1
	АААА	A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10	987654	3 2 1 0

4.4.1.26 TEMP.T1

Address offset: 0x438

Segment end T1

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field Value ID	Value Description
A R T	T (segment end) register

4.4.1.27 TEMP.T2

Address offset: 0x43C

Segment end T2

A R T		T (segme	nt end) r	egiste	r										
ID Acce Field															
Reset 0xFFFFFFF	1 1 1 1 1 1	1 1 1 1 1	1 1 1	1 1	1 1	1 1	. 1	1 1	1	1	1 1	. 1	1	1 1	1
ID										Α	A A	A	Α	A A	A A
Bit number	31 30 29 28 27 26	5 25 24 23 22 21 :	20 19 18	17 16	15 14	1 13 1	2 11 1	10 9	8	7	6 5	4	3	2 2	0

4430_161 v1.4 32



Downloaded from Arrow.com.

4.4.1.28 TEMP.T3

Address offset: 0x440

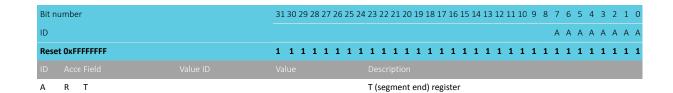
Segment end T3



4.4.1.29 TEMP.T4

Address offset: 0x444

Segment end T4



4.5 UICR — User information configuration registers

The user information configuration registers (UICRs) are non-volatile memory (NVM) registers for configuring user-specific settings.

For information on writing UICR registers, see the NVMC — Non-volatile memory controller on page 20 and Memory on page 17 chapters.

4.5.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x10001000	UICR	UICR	User information configuration	

Table 10: Instances

Register	Offset	Description	
UNUSED0	0x000		Reserved
UNUSED1	0x004		Reserved
UNUSED2	0x008		Reserved
UNUSED3	0x010		Reserved
NRFFW[0]	0x014	Reserved for Nordic firmware design	
NRFFW[1]	0x018	Reserved for Nordic firmware design	
NRFFW[2]	0x01C	Reserved for Nordic firmware design	
NRFFW[3]	0x020	Reserved for Nordic firmware design	
NRFFW[4]	0x024	Reserved for Nordic firmware design	
NRFFW[5]	0x028	Reserved for Nordic firmware design	
NRFFW[6]	0x02C	Reserved for Nordic firmware design	
NRFFW[7]	0x030	Reserved for Nordic firmware design	



Register	Offset	Description
NRFFW[8]	0x034	Reserved for Nordic firmware design
NRFFW[9]	0x038	Reserved for Nordic firmware design
NRFFW[10]	0x03C	Reserved for Nordic firmware design
NRFFW[11]	0x040	Reserved for Nordic firmware design
NRFFW[12]	0x044	Reserved for Nordic firmware design
NRFHW[0]	0x050	Reserved for Nordic hardware design
NRFHW[1]	0x054	Reserved for Nordic hardware design
NRFHW[2]	0x058	Reserved for Nordic hardware design
NRFHW[3]	0x05C	Reserved for Nordic hardware design
NRFHW[4]	0x060	Reserved for Nordic hardware design
NRFHW[5]	0x064	Reserved for Nordic hardware design
NRFHW[6]	0x068	Reserved for Nordic hardware design
NRFHW[7]	0x06C	Reserved for Nordic hardware design
NRFHW[8]	0x070	Reserved for Nordic hardware design
NRFHW[9]	0x074	Reserved for Nordic hardware design
NRFHW[10]	0x078	Reserved for Nordic hardware design
NRFHW[11]	0x07C	Reserved for Nordic hardware design
CUSTOMER[0]	0x080	Reserved for customer
CUSTOMER[1]	0x084	Reserved for customer
CUSTOMER[2]	0x088	Reserved for customer
CUSTOMER[3]	0x08C	Reserved for customer
CUSTOMER[4]	0x090	Reserved for customer
CUSTOMER[5]	0x094	Reserved for customer
CUSTOMER[6]	0x098	Reserved for customer
CUSTOMER[7]	0x09C	Reserved for customer
CUSTOMER[8]	0x0A0	Reserved for customer
CUSTOMER[9]	0x0A4	Reserved for customer
CUSTOMER[10]	0x0A8	Reserved for customer
CUSTOMER[11]	0x0AC	Reserved for customer
CUSTOMER[12]	0x0B0	Reserved for customer
CUSTOMER[13]	0x0B4	Reserved for customer
CUSTOMER[14]	0x0B8	Reserved for customer
CUSTOMER[15]	0x0BC	Reserved for customer
CUSTOMER[16]	0x0C0	Reserved for customer
CUSTOMER[17]	0x0C4	Reserved for customer
CUSTOMER[18]	0x0C8	Reserved for customer
CUSTOMER[19]	0x0CC	Reserved for customer
CUSTOMER[20]	0x0D0	Reserved for customer
CUSTOMER[21]	0x0D4	Reserved for customer
CUSTOMER[22]	0x0D8	Reserved for customer
CUSTOMER[23]	0x0DC	Reserved for customer
CUSTOMER[24]	0x0E0	Reserved for customer
CUSTOMER[25]	0x0E4	Reserved for customer
CUSTOMER[26]	0x0E8	Reserved for customer
CUSTOMER[27]	0x0EC	Reserved for customer
CUSTOMER[28]	0x0F0	Reserved for customer
CUSTOMER[29]	0x0F4	Reserved for customer
CUSTOMER[30]	0x0F8	Reserved for customer
CUSTOMER[31]	0x0FC	Reserved for customer
NRFMDK[0]	0x100	Reserved for Nordic MDK
NRFMDK[1]	0x104	Reserved for Nordic MDK
NRFMDK[2]	0x104	Reserved for Nordic MDK
NRFMDK[3]	0x106	Reserved for Nordic MDK
וכןאטואו ווואי	OVIOC	NESCI VEG TOL MOTULE IVIDIO



Register	Offset	Description
NRFMDK[4]	0x110	Reserved for Nordic MDK
NRFMDK[5]	0x114	Reserved for Nordic MDK
NRFMDK[6]	0x118	Reserved for Nordic MDK
NRFMDK[7]	0x11C	Reserved for Nordic MDK
PSELRESET[0]	0x200	Mapping of the nRESET function (see POWER chapter for details)
PSELRESET[1]	0x204	Mapping of the nRESET function (see POWER chapter for details)
APPROTECT	0x208	Access port protection

Table 11: Register overview

4.5.1.1 NRFFW[n] (n=0..12)

Address offset: $0x014 + (n \times 0x4)$ Reserved for Nordic firmware design

Α	RW NRFFW		Reserved for Nordic firmware design
ID			
Res	et OxFFFFFFF	1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID		A A A A A A A	A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

4.5.1.2 NRFHW[n] (n=0..11)

Address offset: $0x050 + (n \times 0x4)$

Reserved for Nordic hardware design

Α	RW NRFHW								Re	ser	ved	for	No	rdic	har	dwa	re d	esig	n									
ID																												
Rese	t OxFFFFFFF	1	1	1	1 :	1 1	. 1	1	1	1	1	1	1 1	۱ 1	1	1	1 1	. 1	1	1	1	1	1	1 1	. 1	1	1	1 1
ID		Α	Α	Α.	A A	4 A	A	Α	Α	Α	Α	Α.	A A	A A	Α	Α	A A	A	Α	Α	Α	A	۸ ,	Δ Δ	A	Α	Α	A A
Bit n	umber	31	30 2	29 2	28 2	7 26	5 25	5 24	23	22	21	20 1	19 1	8 17	16	15	14 1	3 12	11	10	9	8	7	5 5	4	3	2	1 0

4.5.1.3 CUSTOMER[n] (n=0..31)

Address offset: $0x080 + (n \times 0x4)$

Reserved for customer

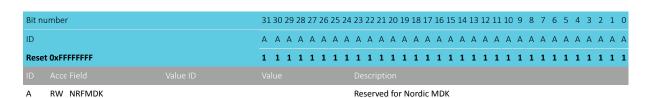
Bit r	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID		A A A A A A A A A A A A A A A A A A A
Rese	t OxFFFFFFF	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID		
Α	RW CUSTOMER	Reserved for customer

4.5.1.4 NRFMDK[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

Reserved for Nordic MDK





4.5.1.5 PSELRESET[n] (n=0..1)

Address offset: $0x200 + (n \times 0x4)$

Mapping of the nRESET function (see POWER chapter for details)

All PSELRESET registers have to contain the same value for a pin mapping to be valid. If values are not the same, there will be no nRESET function exposed on a GPIO. As a result, the device will always start independently of the levels present on any of the GPIOs.

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	ААААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		21	GPIO pin number onto which nRESET is exposed
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

4.5.1.6 APPROTECT

Address offset: 0x208
Access port protection

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0										
ID			A A A A A A A										
Reset 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1										
ID Acce Field			Description										
A RW PALL			Enable or disable access port protection.										
			See Debug on page 39 for more information.										
	Disabled	0xFF	Hardware disable of access port protection for devices										
			where access port protection is controlled by hardware										
	HwDisabled	0x5A	Hardware disable of access port protection for devices										
			where access port protection is controlled by hardware and										
			software										
	Enabled	0x00	Enable										

4.6 EasyDMA

EasyDMA is a module implemented by some peripherals to gain direct access to Data RAM.

EasyDMA is an AHB bus master similar to CPU and is connected to the AHB multilayer interconnect for direct access to Data RAM. EasyDMA is not able to access flash.

A peripheral can implement multiple EasyDMA instances to provide dedicated channels. For example, for reading and writing of data between the peripheral and RAM. This concept is illustrated in EasyDMA example on page 37.



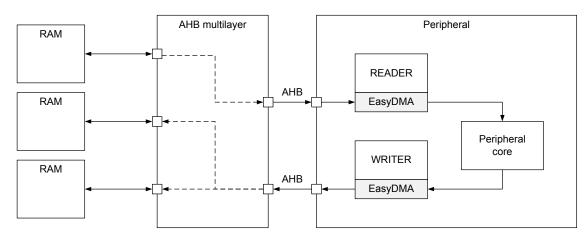


Figure 4: EasyDMA example

An EasyDMA channel is implemented in the following way, but some variations may occur:

```
READERBUFFER_SIZE 5
WRITERBUFFER_SIZE 6

uint8_t readerBuffer[READERBUFFER_SIZE] __at__ 0x20000000;
uint8_t writerBuffer[WRITERBUFFER_SIZE] __at__ 0x200000005;

// Configuring the READER channel
MYPERIPHERAL->READER.MAXCNT = READERBUFFER_SIZE;
MYPERIPHERAL->READER.PTR = &readerBuffer;

// Configure the WRITER channel
MYPERIPHERAL->WRITER.MAXCNT = WRITEERBUFFER_SIZE;
MYPERIPHERAL->WRITER.MAXCNT = &writerBuffer;
```

This example shows a peripheral called MYPERIPHERAL that implements two EasyDMA channels - one for reading called READER, and one for writing called WRITER. When the peripheral is started, it is assumed that the peripheral will:

- Read 5 bytes from the readerBuffer located in RAM at address 0x20000000.
- Process the data.
- Write no more than 6 bytes back to the writerBuffer located in RAM at address 0x20000005.

The memory layout of these buffers is illustrated in EasyDMA memory layout on page 37.

0x20000000	readerBuffer[0]	readerBuffer[1]	readerBuffer[2]	readerBuffer[3]
0x20000004	readerBuffer[4]	writerBuffer[0]	writerBuffer[1]	writerBuffer[2]
0x20000008	writerBuffer[3]	writerBuffer[4]	writerBuffer[5]	

Figure 5: EasyDMA memory layout

The WRITER.MAXCNT register should not be specified larger than the actual size of the buffer (writerBuffer). Otherwise, the channel would overflow the writerBuffer.



Once an EasyDMA transfer is completed, the AMOUNT register can be read by the CPU to see how many bytes were transferred. For example, CPU can read MYPERIPHERAL->WRITER.AMOUNT register to see how many bytes WRITER wrote to RAM.

Note: The PTR register of a READER or WRITER must point to a valid memory region before use. The reset value of a PTR register is not guaranteed to point to valid memory. See Memory on page 17 for more information about the different memory regions and EasyDMA connectivity.

4.6.1 EasyDMA error handling

Some errors may occur during DMA handling.

If READER.PTR or WRITER.PTR is not pointing to a valid memory region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

If several AHB bus masters try to access the same AHB slave at the same time, AHB bus congestion might occur. An EasyDMA channel is an AHB master. Depending on the peripheral, the peripheral may either stall and wait for access to be granted, or lose data.

4.6.2 EasyDMA array list

EasyDMA is able to operate in Array List mode.

The Array List mode is implemented in channels where the LIST register is available.

The array list does not provide a mechanism to explicitly specify where the next item in the list is located. Instead, it assumes that the list is organized as a linear array where items are located one after the other in RAM.

The EasyDMA Array List can be implemented by using the data structure ArrayList_type as illustrated in the code example below using a READER EasyDMA channel as an example:

```
#define BUFFER_SIZE 4

typedef struct ArrayList
{
   uint8_t buffer[BUFFER_SIZE];
} ArrayList_type;

ArrayList_type ReaderList[3] __at__ 0x20000000;

MYPERIPHERAL->READER.MAXCNT = BUFFER_SIZE;
MYPERIPHERAL->READER.PTR = &ReaderList;
MYPERIPHERAL->READER.LIST = MYPERIPHERAL_READER_LIST_ArrayList;
```

The data structure only includes a buffer with size equal to the size of READER.MAXCNT register. EasyDMA uses the READER.MAXCNT register to determine when the buffer is full.



READER.PTR = &ReaderList

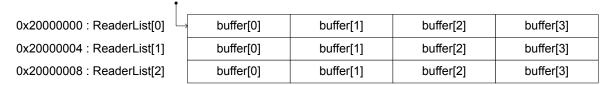


Figure 6: EasyDMA array list

4.7 AHB multilayer

AHB multilayer enables parallel access paths between multiple masters and slaves in a system. Access is resolved using priorities.

Each bus master is connected to the slave devices using an interconnection matrix. The bus masters are assigned priorities. Priorities are used to resolve access when two (or more) bus masters request access to the same slave device. The following applies:

- If two (or more) bus masters request access to the same slave device, the master with the highest priority is granted the access first.
- Bus masters with lower priority are stalled until the higher priority master has completed its transaction.
- If the higher priority master pauses at any point during its transaction, the lower priority master in queue is temporarily granted access to the slave device until the higher priority master resumes its activity.
- Bus masters that have the same priority are mutually exclusive, thus cannot be used concurrently. Below is a list of bus masters in the system and their priorities.

Bus master name	Description
CPU	
SPIMO/SPISO	Same priority and mutually exclusive
RADIO	
CCM/ECB/AAR	Same priority and mutually exclusive
SAADC	
UARTEO	
TWIM0/TWIS0	Same priority and mutually exclusive
PDM	
PWM	

Table 12: AHB bus masters (listed in priority order, highest to lowest)

Defined bus masters are the CPU and the peripherals with implemented EasyDMA, and the available slaves are RAM AHB slaves. How the bus masters and slaves are connected using the interconnection matrix is illustrated in Memory on page 17.

4.8 Debug

The debug system offers a flexible and powerful mechanism for non-intrusive debugging.



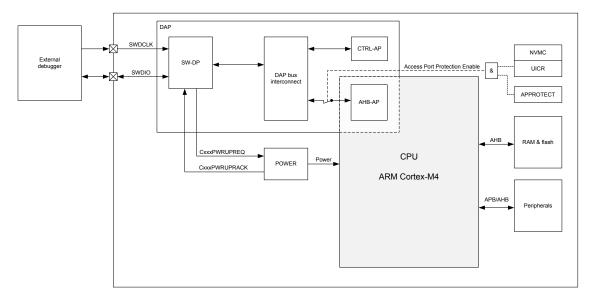


Figure 7: Debug overview

The main features of the debug system are the following:

- Two-pin serial wire debug (SWD) interface
- Flash patch and breakpoint (FPB) unit that supports the following comparators:
 - Two literal comparators
 - Six instruction comparators

4.8.1 DAP - Debug access port

An external debugger can access the device via the DAP.

The debug access port (DAP) implements a standard ARM[®] CoreSight[™] serial wire debug port (SW-DP), which implements the serial wire debug protocol (SWD). SWD is a two-pin serial interface, see SWDCLK and SWDIO in Debug overview on page 40.

In addition to the default access port in CPU (AHB-AP), the DAP includes a custom control access port (CTRL-AP). The CTRL-AP is described in more detail in CTRL-AP - Control access port on page 43.

Note:

- The SWDIO line has an internal pull-up resistor.
- The SWDCLK line has an internal pull-down resistor.

4.8.2 Access port protection

Access port protection blocks the debugger from read and write access to all CPU registers and memory-mapped addresses when enabled.

Access port protection is enabled and disabled differently depending on the build code of the device.

Access port protection controlled by hardware

This information refers to build codes Dxx and earlier.

By default, access port protection is disabled.

Access port protection is enabled by writing UICR.APPROTECT to Enabled and performing any reset. See Reset on page 56 for more information.



Access port protection is disabled by issuing an ERASEALL command via CTRL-AP. This command will erase the flash, UICR, and RAM, including UICR.APPROTECT. Erasing UICR will set UICR.APPROTECT value to Disabled. CTRL-AP is described in more detail in CTRL-AP - Control access port on page 43.

Access port protection controlled by hardware and software

This information refers to build codes Exx and later.

By default, access port protection is enabled.

Access port protection is disabled by issuing an ERASEALL command via CTRL-AP. Read CTRL-AP.AP.APPROTECTSTATUS to ensure that access port protection is disabled, and repeat the ERASEALL command if needed. This command will erase the flash, UICR, and RAM. CTRL-AP is described in more detail in CTRL-AP - Control access port on page 43. Access port protection will remain disabled until one of the following occurs:

- Pin reset
- Power or brownout reset
- Watchdog reset if not in Debug Interface Mode, see Debug Interface mode on page 45
- · Wake from System OFF if not in Emulated System OFF

To keep access port protection disabled, the following actions must be performed:

- Program UICR.APPROTECT to HwDisabled. This disables the hardware part of the access port protection scheme after the first reset of any type. The hardware part of the access port protection will stay disabled as long as UICR.APPROTECT is not overwritten.
- Firmware must write APPROTECT.DISABLE to SwDisable. This disables the software part of the access port protection scheme.

Note: Register APPROTECT.DISABLE is reset after pin reset, power or brownout reset, watchdog reset, or wake from System OFF as mentioned above.

The following figure is an example on how a device with access port protection enabled can be erased, programmed, and configured to allow debugging. Operations sent from debugger as well as registers written by firmware will affect the access port state.

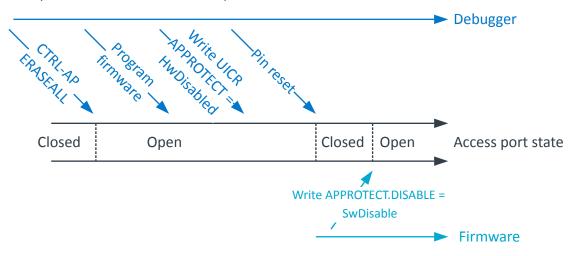


Figure 8: Access port unlocking

Access port protection is enabled when the disabling conditions are not present. For additional security, it is recommended to write <code>Enabled</code> to <code>UICR.APPROTECT</code>, and have firmware write <code>Force</code> to <code>APPROTECT.FORCEPROTECT</code>. This is illustrated in the following figure.

Note: Register APPROTECT.FORCEPROTECT is reset after any reset.



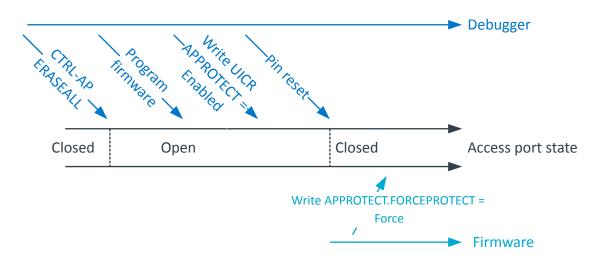


Figure 9: Force access port protection

4.8.2.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40000000	APPROTECT	APPROTECT	APPROTECT control	

Table 13: Instances

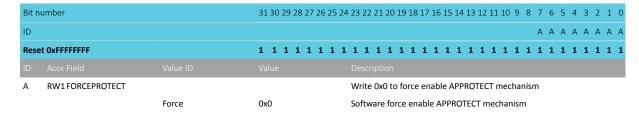
Register	Offset	Description
FORCEPROTECT	0x550	Software force enable APPROTECT mechanism until next reset.
DISABLE	0x558	Software disable APPROTECT mechanism

Table 14: Register overview

4.8.2.1.1 FORCEPROTECT

Address offset: 0x550

Software force enable APPROTECT mechanism until next reset.

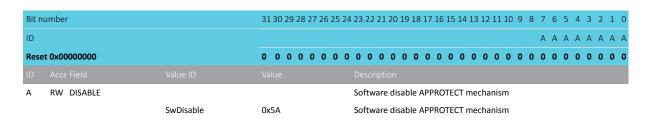


4.8.2.1.2 DISABLE

Address offset: 0x558

Software disable APPROTECT mechanism





4.8.3 CTRL-AP - Control access port

The control access port (CTRL-AP) is a custom access port that enables control of the device when other access ports in the DAP are disabled by the access port protection.

Access port protection is described in more detail in Access port protection on page 40.

Control access port has the following features:

- Soft reset see Reset on page 56 for more information
- Disabling of access port protection device control is allowed through CTRL-AP even when all other access ports in DAP are disabled by access port protection

4.8.3.1 Registers

Register	Offset	Description
RESET	0x000	Soft reset triggered through CTRL-AP
ERASEALL	0x004	Erase all
ERASEALLSTATUS	0x008	Status register for the ERASEALL operation
APPROTECTSTATUS	0x00C	Status register for access port protection
IDR	0x0FC	CTRL-AP identification register, IDR

Table 15: Register overview

4.8.3.1.1 RESET

Address offset: 0x000

Soft reset triggered through CTRL-AP

Bit n	umber		31	130	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8 :	7	6 5	5 4	3	2	1 (
ID																																A
Rese	t 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0 (0	0	0	0 0
ID																																
Α	RW RESET										So	ft r	ese	t tr	igg	ere	d tl	hro	ug	h C	TRI	-AF	P. Se	ee R	ese	t be	eha	vio	r in			
											РО	W	ER c	ha	pte	r fo	or n	nor	e d	eta	ils.											
		NoReset	0								Re	set	is r	ot	act	tive																
		Reset	1								Re	set	is a	cti	ve.	De	vic	e is	he	ld i	in r	ese	t.									

4.8.3.1.2 ERASEALL

Address offset: 0x004

Erase all



Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A W ERASEALL			Erase all flash and RAM
	NoOperation	0	No operation
	Erase	1	Erase all flash and RAM

4.8.3.1.3 ERASEALLSTATUS

Address offset: 0x008

Status register for the ERASEALL operation

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	R ERASEALLSTATUS			Status register for the ERASEALL operation
		Ready	0	ERASEALL is ready
		Busy	1	ERASEALL is busy (on-going)

4.8.3.1.4 APPROTECTSTATUS

Address offset: 0x00C

Status register for access port protection

Bit number	31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A R APPROTECTSTATUS		Status register for access port protection
Enabled	0	Access port protection enabled
Disabled	1	Access port protection not enabled

4.8.3.1.5 IDR

Address offset: 0x0FC

CTRL-AP identification register, IDR

Bit n	iumbe	r		31	30 2	9 28	27	26 2	5 24	23	22	21 2	20 19	18	17 :	16 1	5 14	113	12	11 1	9	8	7	6 5	4	3	2	1 0
ID				Ε	E E	Е	D	D C	D	С	С	С	СС	С	С	ВЕ	3 B	В				,	۱ ،	А А	A	Α	Α	АА
Rese	et OxO	2880000		0	0 0	0	0	0 1	0	1	0	0	0 1	0	0	0 (0	0	0	0 0	0	0) ו	0 0	0	0	0	0 0
ID																												
Α	R	APID								AP	ide	entif	icati	on														
В	R	CLASS								Ac	ces	s po	rt (A	P) c	lass													
			NotDefined	0x	0					No	de	fine	d cla	ISS														
			MEMAP	0x	8					Me	emo	ory a	cces	ss po	ort													
С	R	JEP106ID								JE	DEC	JEP	106	iden	tity	coc	le											
D	R	JEP106CONT								JE	DEC	JEP	106	cont	tinu	atio	n cc	de										
E	R	REVISION								Re	visi	on																



4.8.3.2 Electrical specification

4.8.3.2.1 Control access port

Symbol	Description	Min.	Тур.	Max.	Units
R _{pull}	Internal SWDIO and SWDCLK pull up/down resistance		13		kΩ
f _{SWDCLK}	SWDCLK frequency	0.125		8	MHz

4.8.4 Debug Interface mode

Before an external debugger can access either CPU's access port (AHB-AP) or the control access port (CTRL-AP), the debugger must first request the device to power up via CxxxPWRUPREQ in the SWJ-DP.

If the device is in System OFF when power is requested via CxxxPWRUPREQ, the system will wake up and the DIF flag in RESETREAS on page 61 will be set. The device is in the Debug Interface mode as long as the debugger is requesting power via CxxxPWRUPREQ. Once the debugger stops requesting power via CxxxPWRUPREQ, the device is back in normal mode. Some peripherals behave differently in Debug Interface mode compared to normal mode. These differences are described in more detail in the chapters of the peripherals that are affected.

When a debug session is over, the external debugger must make sure to put the device back into normal mode since the overall power consumption is higher in Debug Interface mode than in normal mode.

For details on how to use the debug capabilities, read the debug documentation of your IDE.

4.8.5 Real-time debug

The nRF52810 supports real-time debugging.

Real-time debugging allows interrupts to execute to completion in real time when breakpoints are set in Thread mode or lower priority interrupts. This enables developers to set breakpoints and single-step through the code without the risk of real-time event-driven threads running at higher priority failing. For example, this enables the device to continue to service the high-priority interrupts of an external controller or sensor without failure or loss of state synchronization while the developer steps through code in a low-priority thread.



5

Power and clock management

5.1 Power management unit (PMU)

Power and clock management in nRF52810 is designed to automatically ensure maximum power efficiency.

The core of the power and clock management system is the power management unit (PMU) illustrated in Power management unit on page 46.

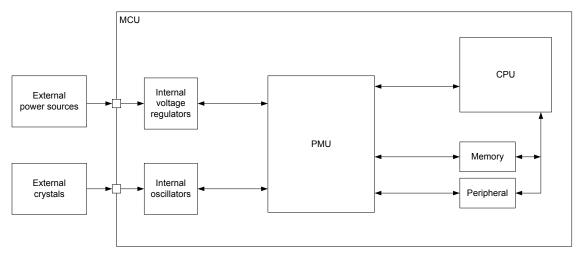


Figure 10: Power management unit

The PMU automatically detects which power and clock resources are required by the different components in the system at any given time. It will then start/stop and choose operation modes in supply regulators and clock sources, without user interaction, to achieve the lowest power consumption possible.

5.2 Current consumption

As the system is being constantly tuned by the Power management unit (PMU) on page 46, estimating the current consumption of an application can be challenging if the designer is not able to perform measurements directly on the hardware. To facilitate the estimation process, a set of current consumption scenarios are provided to show the typical current drawn from the VDD supply.

Each scenario specifies a set of operations and conditions applying to the given scenario. Current consumption scenarios, common conditions on page 47 shows a set of common conditions used in all scenarios, unless otherwise stated in the description of a given scenario. All scenarios are listed in Electrical specification on page 47.



Condition	Value
VDD	3 V
Temperature	25°C
CPU	WFI (wait for interrupt)/WFE (wait for event) sleep
Peripherals	All idle
Clock	Not running
Regulator	LDO
RAM	Full 24 kB retention
Compiler ³	GCC v4.9.3 20150529 (arm-none-eabi-gcc). Compiler flags: -O0 -falign-functions=16 -fno-strict-aliasing -mcpu=cortex-m4 -mfloat-abi=soft -msoft-float -mthumb.
32 MHz crystal ⁴	SMD 2520, 32 MHz, 10 pF +/- 10 ppm

Table 16: Current consumption scenarios, common conditions

5.2.1 Electrical specification

5.2.1.1 CPU running

Symbol	Description	Min.	Тур.	Max.	Units
I _{CPU0}	CPU running CoreMark @64 MHz from flash, Clock = HFXO,		2.2		mA
	Regulator = DCDC				
I _{CPU1}	CPU running CoreMark @64 MHz from flash, Clock = HFXO		4.2		mA
I _{CPU2}	CPU running CoreMark @64 MHz from RAM, Clock = HFXO,		2.1		mA
	Regulator = DCDC				
I _{CPU3}	CPU running CoreMark @64 MHz from RAM, Clock = HFXO		4		mA
I _{CPU4}	CPU running CoreMark @64 MHz from flash, Clock = HFINT,		2		mA
	Regulator = DCDC				



Applying only when CPU is running
 Applying only when HFXO is running

5.2.1.2 Radio transmitting/receiving

Symbol	Description	Min.	Тур.	Max.	Units
I _{RADIO_TX0}	Radio transmitting @ 4 dBm output power, 1 Mbps		8		mA
	Bluetooth low energy mode, Clock = HFXO, Regulator =				
	DCDC				
I _{RADIO_TX1}	Radio transmitting @ 0 dBm output power, 1 Mbps		5.8		mA
	Bluetooth low energy mode, Clock = HFXO, Regulator =				
	DCDC				
I _{RADIO_TX2}	Radio transmitting @ -40 dBm output power, 1 Mbps		3.4		mA
	Bluetooth low energy mode, Clock = HFXO, Regulator =				
	DCDC				
I _{RADIO_RX0}	Radio receiving @ 1 Mbps Bluetooth low energy mode,		6.1		mA
	Clock = HFXO, Regulator = DCDC				
I _{RADIO_TX3}	Radio transmitting @ 0 dBm output power, 1 Mbps		10.5		mA
	Bluetooth low energy mode, Clock = HFXO				
I _{RADIO_TX4}	Radio transmitting @ -40 dBm output power, 1 Mbps		5.1		mA
	Bluetooth low energy mode, Clock = HFXO				
I _{RADIO_RX1}	Radio receiving @ 1 Mbps Bluetooth low energy mode,		10.8		mA
	Clock = HFXO				

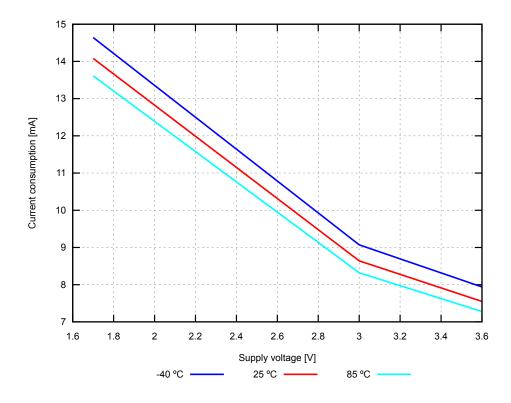


Figure 11: Radio transmitting @ 4 dBm output power, 1 Mbps Bluetooth low energy mode, Clock = HFXO, Regulator = DCDC (typical values)



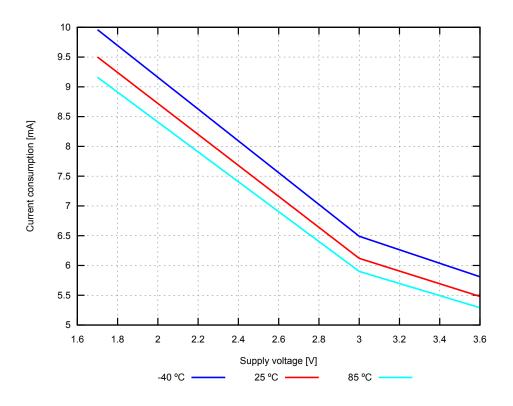


Figure 12: Radio transmitting @ 0 dBm output power, 1 Mbps Bluetooth low energy mode, Clock = HFXO, Regulator = DCDC (typical values)

5.2.1.3 Sleep

Symbol	Description	Min.	Тур.	Max.	Units
I _{ON_RAMOFF_EVENT}	System ON, No RAM retention, Wake on any event		0.6		μΑ
I _{ON_RAMON_EVENT}	System ON, Full 24 kB RAM retention, Wake on any event		0.8		μΑ
I _{ON_RAMON_POF}	System ON, Full 24 kB RAM retention, Wake on any event,		0.8		μΑ
	Power fail comparator enabled				
I _{ON_RAMON_GPIOTE}	System ON, Full 24 kB RAM retention, Wake on GPIOTE input		3.3		μΑ
	(Event mode)				
I _{ON_RAMON_GPIOTEPOR}	_T System ON, Full 24 kB RAM retention, Wake on GPIOTE		0.8		μΑ
	PORT event				
I _{ON_RAMON_RTC}	System ON, Full 24 kB RAM retention, Wake on RTC (running		1.5		μΑ
	from LFRC clock)				
I _{ON_RAMOFF_RTC}	System ON, No RAM retention, Wake on RTC (running from		1.4		μΑ
	LFRC clock)				
I _{ON_RAMON_RTC_LFXO}	System ON, Full 24 kB RAM retention, Wake on RTC (running		1.1		μΑ
	from LFXO clock)				
I _{ON_RAMOFF_RTC_LFXO}	System ON, No RAM retention, Wake on RTC (running from		1.0		μΑ
	LFXO clock)				
I _{OFF_RAMOFF_RESET}	System OFF, No RAM retention, Wake on reset		0.3		μΑ
I _{OFF_RAMON_RESET}	System OFF, Full 24 kB RAM retention, Wake on reset		0.5		μΑ



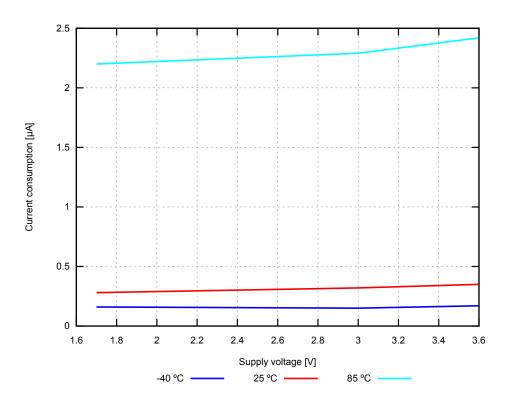


Figure 13: System OFF, No RAM retention, Wake on reset (typical values)

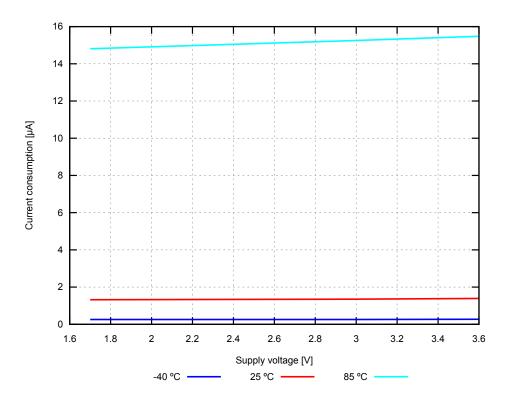


Figure 14: System ON, Full 24 kB RAM retention, Wake on any event (typical values)



5.2.1.4 Compounded

Symbol	Description	Min.	Тур.	Max.	Units
I _{SO}	CPU running CoreMark from flash, Radio transmitting @ 0		7.4		mA
	dBm output power, 1 Mbps Bluetooth low energy mode,				
	Clock = HFXO, Regulator = DCDC				
I _{S1}	CPU running CoreMark from flash, Radio receiving @ 1		7.6		mA
	Mbps Bluetooth low energy mode, Clock = HFXO, Regulator				
	= DCDC				
I _{S2}	CPU running CoreMark from flash, Radio transmitting @ 0		13.8		mA
	dBm output power, 1 Mbps Bluetooth low energy mode,				
	Clock = HFXO				
I _{S3}	CPU running CoreMark from flash, Radio receiving @ 1		14.2		mA
	Mbps Bluetooth low energy mode, Clock = HFXO				

5.2.1.5 TIMER running

Symbol	Description	Min.	Тур.	Max.	Units
I _{TIMERO}	One TIMER instance running @ 1 MHz, Clock = HFINT		432		μΑ
I _{TIMER1}	Two TIMER instances running @ 1 MHz, Clock = HFINT		432		μΑ
I _{TIMER2}	One TIMER instance running @ 1 MHz, Clock = HFXO		730		μΑ
I _{TIMER3}	One TIMER instance running @ 16 MHz, Clock = HFINT		495		μΑ
I _{TIMER4}	One TIMER instance running @ 16 MHz, Clock = HFXO		792		μΑ

5.2.1.6 RNG active

Symbol	Description	Min.	Тур.	Max.	Units
I _{RNG0}	RNG running		539		μΑ

5.2.1.7 TEMP active

Symbol	Description	Min.	Тур.	Max.	Units
I _{TEMP0}	TEMP started		998		μΑ

5.2.1.8 SAADC active

Symbol	Description	Min.	Тур.	Max.	Units
I _{SAADC,RUN}	SAADC sampling @ 16 ksps, Acquisition time = 20 μ s, Clock =		1.1		mA
	HFXO, Regulator = DCDC				

5.2.1.9 COMP active

Symbol	Description	Min.	Тур.	Max.	Units
I _{COMP,LP}	COMP enabled, low power mode		17.2		μΑ
I _{COMP,NORM}	COMP enabled, normal mode		21		μΑ
I _{COMP,HS}	COMP enabled, high-speed mode		28.7		μΑ



5.2.1.10 WDT active

Symbol	Description	Min.	Тур.	Max.	Units	
I _{WDT,STARTED}	WDT started		1.3		μΑ	

5.3 POWER — Power supply

This device has the following power supply features:

- On-chip LDO and DC/DC regulators
- Global System ON/OFF modes with individual RAM section power control
- Analog or digital pin wakeup from System OFF
- Supervisor HW to manage power on reset, brownout, and power fail
- Auto-controlled refresh modes for LDO and DC/DC regulators to maximize efficiency
- Automatic switching between LDO and DC/DC regulator based on load to maximize efficiency

Note: Two additional external passive components are required to use the DC/DC regulator.

5.3.1 Regulators

The following internal power regulator alternatives are supported:

- Internal LDO regulator
- Internal DC/DC regulator

The LDO is the default regulator.

The DC/DC regulator can be used as an alternative to the LDO regulator and is enabled through the DCDCEN on page 63 register. Using the DC/DC regulator will reduce current consumption compared to when using the LDO regulator, but the DC/DC regulator requires an external LC filter to be connected, as shown in DC/DC regulator setup on page 53.

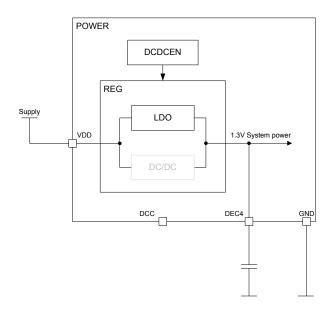


Figure 15: LDO regulator setup



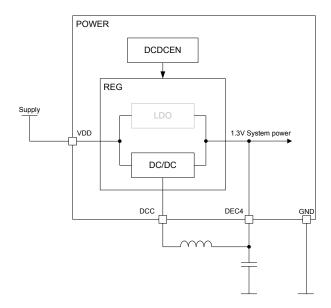


Figure 16: DC/DC regulator setup

5.3.2 System OFF mode

System OFF is the deepest power saving mode the system can enter. In this mode, the system's core functionality is powered down and all ongoing tasks are terminated.

The device can be put into System OFF mode using the register SYSTEMOFF on page 61. When in System OFF mode, the device can be woken up through one of the following signals:

- The DETECT signal, optionally generated by the GPIO peripheral
- A reset

When the system wakes up from System OFF mode, it gets reset. For more details, see Reset behavior on page 57.

One or more RAM sections can be retained in System OFF mode, depending on the settings in the RAM[n].POWER registers.

RAM[n].POWER are retained registers, see Reset behavior. These registers are usually overwritten by the startup code provided with the nRF application examples.

Before entering System OFF mode, the user must make sure that all on-going EasyDMA transactions have been completed. This is usually accomplished by making sure that the EasyDMA enabled peripheral is not active when entering System OFF.

5.3.2.1 Emulated System OFF mode

If the device is in debug interface mode, System OFF will be emulated to secure that all required resources needed for debugging are available during System OFF.

See Debug on page 39 for more information. Required resources needed for debugging include the following key components:

- Debug on page 39
- CLOCK Clock control on page 65
- POWER Power supply on page 52
- NVMC Non-volatile memory controller on page 20
- CPU
- Flash



RAM

Since the CPU is kept on in an emulated System OFF mode, it is recommended to add an infinite loop directly after entering System OFF, to prevent the CPU from executing code that normally should not be executed.

5.3.3 System ON mode

System ON is the default state after power-on reset. In System ON, all functional blocks such as the CPU or peripherals can be in IDLE or RUN mode, depending on the configuration set by the software and the state of the application executing.

Register RESETREAS on page 61 provides information about the source causing the wakeup or reset.

The system can switch the appropriate internal power sources on and off, depending on how much power is needed at any given time. The power requirement of a peripheral is directly related to its activity level, and the activity level of a peripheral is usually raised and lowered when specific tasks are triggered or events are generated.

5.3.3.1 Sub power modes

In System ON mode, when both the CPU and all the peripherals are in IDLE mode, the system can reside in one of the two sub power modes.

The sub power modes are:

- Constant Latency
- · Low-power

In Constant Latency mode, the CPU wakeup latency and the PPI task response are constant and kept at a minimum. This is secured by forcing a set of basic resources to be turned on while in sleep. Having a constant and predictable latency is at the cost of having increased power consumption. The Constant Latency mode is selected by triggering the CONSTLAT task.

In Low-power mode, the automatic power management system described in System ON mode on page 54 ensures that the most efficient supply option is chosen to save most power. Having the lowest power possible is at the cost of having a varying CPU wakeup latency and PPI task response. The Low-power mode is selected by triggering the LOWPWR task.

When the system enters System ON mode, it is by default in Low-power sub power mode.

5.3.4 Power supply supervisor

The power supply supervisor initializes the system at power-on and provides an early warning of impending power failure.

In addition, the power supply supervisor puts the system in a reset state if the supply voltage is too low for safe operation (brownout). The power supply supervisor is illustrated in Power supply supervisor on page 55.



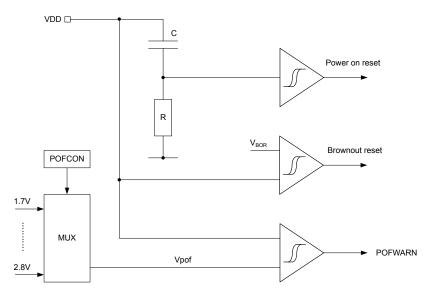


Figure 17: Power supply supervisor

5.3.4.1 Power-fail comparator

The power-fail comparator (POF) can provide the CPU with an early warning of impending power failure. It will not reset the system, but give the CPU time to prepare for an orderly power-down.

The comparator features a hysteresis of V_{HYST} , as illustrated in Power-fail comparator (BOR = Brownout reset) on page 55. The threshold V_{POF} is set in register POFCON on page 62. If the POF is enabled and the supply voltage falls below V_{POF} , the POFWARN event will be generated. This event will also be generated if the supply voltage is already below V_{POF} at the time the POF is enabled, or if V_{POF} is reconfigured to a level above the supply voltage.

If power-fail warning is enabled and the supply voltage is below V_{POF} the power-fail comparator will prevent the NVMC from performing write operations to the NVM. See NVMC — Non-volatile memory controller on page 20 for more information about the NVMC.

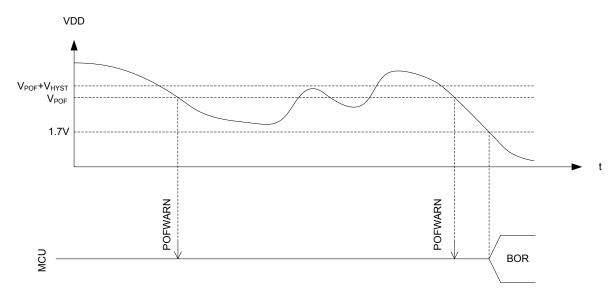


Figure 18: Power-fail comparator (BOR = Brownout reset)

To save power, the power-fail comparator is not active in System OFF or in System ON when HFCLK is not running.



5.3.5 RAM power control

The RAM power control registers are used for configuring the following:

- The RAM sections to be retained during System OFF
- The RAM sections to be retained and accessible during System ON

In System OFF, retention of a RAM section is configured in the RETENTION field of the corresponding RAM[n] register.

In System ON, retention and accessibility for a RAM section is configured in the RETENTION and POWER fields of the corresponding RAM[n] register.

The following table summarizes the behavior of these registers.

Configuration		RAM section status			
System on/off	RAM[n].POWER.POWER	RAM[n].POWER.RETENTION	Accessible	Retained	
Off	х	Off	No	No	
Off	х	On	No	Yes	
On	Off	Off	No	No	
On	Off ¹	On	No	Yes	
On	On	X	Yes	Yes	

Table 17: RAM section configuration

The advantage of not retaining RAM contents is that the overall current consumption is reduced.

See chapter Memory on page 17 for more information on RAM sections.

5.3.6 Reset

There are multiple sources that may trigger a reset.

After a reset has occurred, register RESETREAS can be read to determine which source generated the reset.

5.3.6.1 Power-on reset

The power-on reset generator initializes the system at power-on.

The system is held in reset state until the supply has reached the minimum operating voltage and the internal voltage regulators have started.

A step increase in supply voltage of 300 mV or more, with rise time of 300 ms or less, within the valid supply range, may result in a system reset.

5.3.6.2 Pin reset

A pin reset is generated when the physical reset pin on the device is asserted.

Pin reset is configured via the PSELRESET[n] registers.

Note: Pin reset is not available on all pins.

5.3.6.3 Wakeup from System OFF mode reset

The device is reset when it wakes up from System OFF mode.

¹ Not useful setting. RAM section power off gives negligible reduction in current consumption when retention is on.



The debug access port (DAP) is not reset following a wake up from System OFF mode if the device is in Debug Interface mode. See chapter Debug on page 39 for more information.

5.3.6.4 Soft reset

A soft reset is generated when the SYSRESETREQ bit of the Application Interrupt and Reset Control Register (AIRCR register) in the ARM® core is set.

Refer to ARM documentation for more details.

A soft reset can also be generated via the RESET on page 43 register in the CTRL-AP.

5.3.6.5 Watchdog reset

A Watchdog reset is generated when the watchdog times out.

See chapter WDT — Watchdog timer on page 383 for more information.

5.3.6.6 Brown-out reset

The brown-out reset generator puts the system in reset state if the supply voltage drops below the brownout reset (BOR) threshold.

Refer to section Power fail comparator on page 65 for more information.

5.3.7 Retained registers

A retained register is a register that will retain its value in System OFF mode and through a reset, depending on reset source. See individual peripheral chapters for information of which registers are retained for the various peripherals.

5.3.8 Reset behavior

Reset source	Reset targe	t							
	СРИ	Peripherals	GPIO	Debug ^a	SWJ-DP	RAM	WDT	Retained	RESETREAS
								registers	
CPU lockup ⁵	x	x	x						
Soft reset	х	x	x						
Wakeup from System OFF	х	x		x ⁶		x ⁷	х		
mode reset									
Watchdog reset ⁸	х	x	x	х		х	х	х	
Pin reset	x	x	x	х		х	х	х	
Brownout reset	x	x	x	х	х	х	х	х	x
Power on reset	x	x	x	x	x	x	x	х	x

Note: The RAM is never reset, but depending on reset source, RAM content may be corrupted.



^a All debug components excluding SWJ-DP. See Debug on page 39 for more information about the different debug components in the system.

⁵ Reset from CPU lockup is disabled if the device is in debug interface mode. CPU lockup is not possible in System OFF.

⁶ The Debug components will not be reset if the device is in debug interface mode.

⁷ RAM is not reset on wakeup from System OFF mode, but depending on settings in the RAM registers, parts, or the whole RAM may not be retained after the device has entered System OFF mode.

Watchdog reset is not available in System OFF.

5.3.9 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40000000	POWER	POWER	Power control	For 24 kB RAM variant, only RAM[0].x to
				RAM[2].x registers are in use.

Table 18: Instances

Register	Offset	Description
TASKS_CONSTLAT	0x078	Enable Constant Latency mode
TASKS_LOWPWR	0x07C	Enable Low-power mode (variable latency)
EVENTS_POFWARN	0x108	Power failure warning
EVENTS_SLEEPENTER	0x114	CPU entered WFI/WFE sleep
EVENTS_SLEEPEXIT	0x118	CPU exited WFI/WFE sleep
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
RESETREAS	0x400	Reset reason
SYSTEMOFF	0x500	System OFF register
POFCON	0x510	Power failure comparator configuration
GPREGRET	0x51C	General purpose retention register
GPREGRET2	0x520	General purpose retention register
DCDCEN	0x578	DC/DC enable register
RAM[0].POWER	0x900	RAM0 power control register. The RAM size will vary depending on product variant, and the
		RAMO register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[0].POWERSET	0x904	RAM0 power control set register
RAM[0].POWERCLR	0x908	RAM0 power control clear register
RAM[1].POWER	0x910	RAM1 power control register. The RAM size will vary depending on product variant, and the
		RAM1 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[1].POWERSET	0x914	RAM1 power control set register
RAM[1].POWERCLR	0x918	RAM1 power control clear register
RAM[2].POWER	0x920	RAM2 power control register. The RAM size will vary depending on product variant, and the
		RAM2 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[2].POWERSET	0x924	RAM2 power control set register
RAM[2].POWERCLR	0x928	RAM2 power control clear register
RAM[3].POWER	0x930	RAM3 power control register. The RAM size will vary depending on product variant, and the
		RAM3 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[3].POWERSET	0x934	RAM3 power control set register
RAM[3].POWERCLR	0x938	RAM3 power control clear register
RAM[4].POWER	0x940	RAM4 power control register. The RAM size will vary depending on product variant, and the
		RAM4 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[4].POWERSET	0x944	RAM4 power control set register
RAM[4].POWERCLR	0x948	RAM4 power control clear register
RAM[5].POWER	0x950	RAM5 power control register. The RAM size will vary depending on product variant, and the
		RAM5 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[5].POWERSET	0x954	RAM5 power control set register
RAM[5].POWERCLR	0x958	RAM5 power control clear register



Register	Offset	Description
RAM[6].POWER	0x960	RAM6 power control register. The RAM size will vary depending on product variant, and the
		RAM6 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[6].POWERSET	0x964	RAM6 power control set register
RAM[6].POWERCLR	0x968	RAM6 power control clear register
RAM[7].POWER	0x970	RAM7 power control register. The RAM size will vary depending on product variant, and the
		RAM7 register will only be present if the corresponding RAM AHB slave is present on the
		device.
RAM[7].POWERSET	0x974	RAM7 power control set register
RAM[7].POWERCLR	0x978	RAM7 power control clear register

Table 19: Register overview

5.3.9.1 TASKS_CONSTLAT

Address offset: 0x078

Enable Constant Latency mode

Bit n	umbe	r		313	30 2	9 28	3 27 2	26 2	5 24	23	22	21	20 1	19 1	8 17	16	15	14 1	3 12	2 11	10 9	8	7	6	5 .	4 3	2	1 0
ID																												Α
Rese	t 0x00	0000000		0	0 (0 0	0	0 (0 0	0	0	0	0	0 0	0	0	0	0 (0	0	0 0	0	0	0	0	0 0	0	0 0
ID																												
Α	W	TASKS_CONSTLAT								Er	nable	e Co	onst	ant	Late	ncy	m	ode										
			Trigger	1						Tr	igge	r ta	ask															

5.3.9.2 TASKS_LOWPWR

Address offset: 0x07C

Enable Low-power mode (variable latency)

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_LOWPWR			Enable Low-power mode (variable latency)
		Trigger	1	Trigger task

5.3.9.3 EVENTS_POFWARN

Address offset: 0x108

Power failure warning

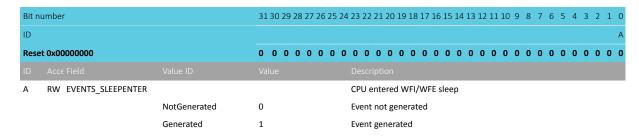
Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW EVENTS_POFWARN			Power failure warning
	NotGenerated	0	Event not generated
	Generated	1	Event generated



5.3.9.4 EVENTS_SLEEPENTER

Address offset: 0x114

CPU entered WFI/WFE sleep



5.3.9.5 EVENTS_SLEEPEXIT

Address offset: 0x118

CPU exited WFI/WFE sleep

Bit number		31 30 29 28	27 26 25	24 23 2	2 21 20	19 18	17 16	15 14	4 13 1	.2 11	10 9	8	7 6	5 5	4	3	2 1	0
ID																		Α
Reset 0x00000000		0 0 0 0	0 0 0	0 0 0	0 0	0 0	0 0	0 0	0	0 0	0 0	0	0 (0	0	0	0 0	0
ID Acce Field																		
A RW EVENTS_SLEEPE	XIT			CPU	exited	WFI/W	/FE sle	еер										
	NotGenerated	0		Even	t not g	enerate	ed											
	Generated	1		Even	t gener	rated												

5.3.9.6 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВ А
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
Α	RW POFWARN			Write '1' to enable interrupt for event POFWARN
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW SLEEPENTER			Write '1' to enable interrupt for event SLEEPENTER
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW SLEEPEXIT			Write '1' to enable interrupt for event SLEEPEXIT
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

5.3.9.7 INTENCLR

Address offset: 0x308

Disable interrupt

NORDIC*

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				C B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW POFWARN			Write '1' to disable interrupt for event POFWARN
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW SLEEPENTER			Write '1' to disable interrupt for event SLEEPENTER
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW SLEEPEXIT			Write '1' to disable interrupt for event SLEEPEXIT
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

5.3.9.8 RESETREAS

Address offset: 0x400

Reset reason

Unless cleared, the RESETREAS register will be cumulative. A field is cleared by writing '1' to it. If none of the reset sources are flagged, this indicates that the chip was reset from the on-chip reset generator, which will indicate a power-on-reset or a brownout reset.

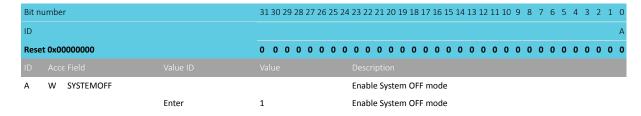
Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Va			Description
A RW RESETPIN			Reset from pin-reset detected
No	otDetected	0	Not detected
De	etected	1	Detected
B RW DOG			Reset from watchdog detected
No	otDetected	0	Not detected
De	etected	1	Detected
C RW SREQ			Reset from soft reset detected
No	otDetected	0	Not detected
De	etected	1	Detected
D RW LOCKUP			Reset from CPU lock-up detected
No	otDetected	0	Not detected
De	etected	1	Detected
E RW OFF			Reset due to wake up from System OFF mode when wakeup
			is triggered from DETECT signal from GPIO
No	otDetected	0	Not detected
De	etected	1	Detected
F RW DIF			Reset due to wake up from System OFF mode when wakeup
			is triggered from entering into debug interface mode
No	otDetected	0	Not detected
De	etected	1	Detected

5.3.9.9 SYSTEMOFF

Address offset: 0x500



System OFF register



5.3.9.10 POFCON

Address offset: 0x510

Power failure comparator configuration

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				вввва
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW POF			Enable or disable power failure comparator
		Disabled	0	Disable
		Enabled	1	Enable
В	RW THRESHOLD			Power failure comparator threshold setting
		V17	4	Set threshold to 1.7 V
		V18	5	Set threshold to 1.8 V
		V19	6	Set threshold to 1.9 V
		V20	7	Set threshold to 2.0 V
		V21	8	Set threshold to 2.1 V
		V22	9	Set threshold to 2.2 V
		V23	10	Set threshold to 2.3 V
		V24	11	Set threshold to 2.4 V
		V25	12	Set threshold to 2.5 V
		V26	13	Set threshold to 2.6 V
		V27	14	Set threshold to 2.7 V
		V28	15	Set threshold to 2.8 V

5.3.9.11 GPREGRET

Address offset: 0x51C

General purpose retention register

Bit r	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		
Α	RW GPREGRET	General purpose retention register

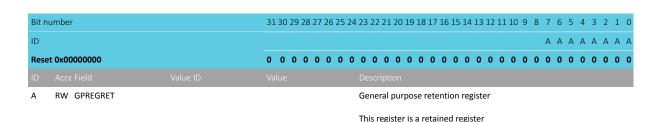
This register is a retained register

5.3.9.12 GPREGRET2

Address offset: 0x520

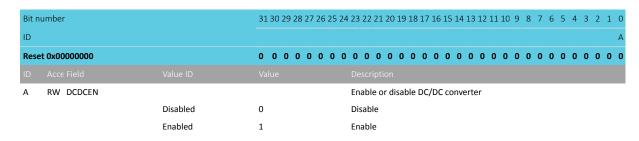
General purpose retention register





5.3.9.13 DCDCEN

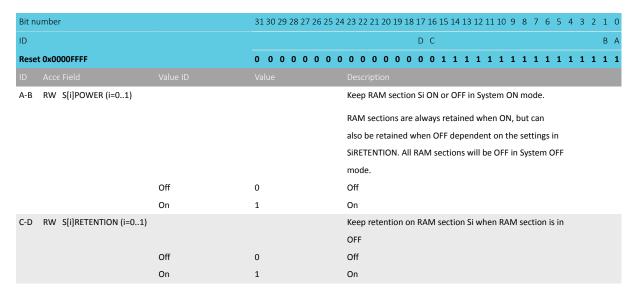
Address offset: 0x578 DC/DC enable register



5.3.9.14 RAM[n].POWER (n=0..7)

Address offset: $0x900 + (n \times 0x10)$

RAMn power control register. The RAM size will vary depending on product variant, and the RAMn register will only be present if the corresponding RAM AHB slave is present on the device.



5.3.9.15 RAM[n].POWERSET (n=0..7)

Address offset: $0x904 + (n \times 0x10)$ RAMn power control set register

When read, this register will return the value of the POWER register.



Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18	8 17 16	5 15 14	4 13 12	11 10	9 8	7 6	5	4 3	2	1 0
ID	ID					D C							В		
Rese	t 0x0000FFFF			0 0 0 0 0 0 0 0	0 0 0 0 0 0	0 0	1 1	1 1	1 1	1 1	1 1	1	1 1	1	1 1
ID															
A-B	W S[i]PO\	VER (i=01)			Keep RAM sectio	n Si of	RAMr	n on or	off in	Syster	n ON	mode	e		
		O	On	1	On										
C-D	W S[i]RET	ENTION (i=01)			Keep retention or	n RAM	l section	on Si w	hen R	AM se	ction	is			
					switched off										
		0)n	1	On										

5.3.9.16 RAM[n].POWERCLR (n=0..7)

Address offset: $0x908 + (n \times 0x10)$

RAMn power control clear register

When read, this register will return the value of the POWER register.

Bit n	umbe	er		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID					D C	ВА
Rese	t 0x0	000FFFF		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1
ID						
A-B	W	S[i]POWER (i=01)			Keep RAM section Si of RAMn on or off in System ON mode	
			Off	1	Off	
C-D	W	S[i]RETENTION (i=01)			Keep retention on RAM section Si when RAM section is	
					switched off	
			Off	1	Off	

5.3.10 Electrical specification

5.3.10.1 Device startup times

Symbol	Description	Min.	Тур.	Max.	Units
t _{POR}	Time in Power on Reset after VDD reaches 1.7 V for all				
	supply voltages and temperatures. Dependent on supply rise				
	time. ⁹				
t _{POR,10us}	VDD rise time 10 µs		1		ms
t _{POR,10ms}	VDD rise time 10 ms		9		ms
t _{POR,60ms}	VDD rise time 60 ms		23		ms
t _{PINR}	If a GPIO pin is configured as reset, the maximum time taken				
	to pull up the pin and release reset after power on reset.				
	Dependent on the pin capacitive load (C) 10 : t=5RC, R = 13 k Ω				
t _{PINR,500nF}	C = 500 nF			32.5	ms
t _{PINR,10uF}	$C = 10 \mu F$			650	ms
t _{R2ON}	Time from reset to ON (CPU execute)				
t _{R2ON,NOTCONF}	If reset pin not configured	tPOR			ms
t _{R2ON,CONF}	If reset pin configured	tPOR+			ms
		tPINR			
t _{OFF2ON}	Time from OFF to CPU execute		16.5		μs

⁹ A step increase in supply voltage of 300 mV or more, with rise time of 300 ms or less, within the valid supply range, may result in a system reset.

NORDIC SEMICONDUCTOR

To decrease maximum time a device could hold in reset, a strong external pullup resistor can be used.

Symbol	Description	Min.	Тур.	Max.	Units
t _{IDLE2CPU}	Time from IDLE to CPU execute		3.0		μs
t _{EVTSET,CL1}	Time from HW event to PPI event in Constant Latency		0.0625		μs
	System ON mode				
t _{EVTSET,CLO}	Time from HW event to PPI event in Low Power System ON		0.0625		μs
	mode				

5.3.10.2 Power fail comparator

Symbol	Description	Min.	Тур.	Max.	Units
V_{POF}	Nominal power level warning thresholds (falling supply	1.7		2.8	V
	voltage). Levels are configurable between Min. and Max. in				
	100 mV increments.				
V _{POFTOL}	Threshold voltage tolerance		±1	±5	%
V _{POFHYST}	Threshold voltage hysteresis		50		mV
$V_{BOR,OFF}$	Brown out reset voltage range SYSTEM OFF mode	1.2		1.7	V
V _{BOR,ON}	Brown out reset voltage range SYSTEM ON mode	1.48		1.7	V

5.4 CLOCK — Clock control

The clock control system can source the system clocks from a range of internal or external high and low frequency oscillators and distribute them to modules based upon a module's individual requirements. Clock distribution is automated and grouped independently by module to limit current consumption in unused branches of the clock tree.

Listed here are the main features for CLOCK:

- 64 MHz on-chip oscillator
- 64 MHz crystal oscillator, using external 32 MHz crystal
- 32.768 kHz +/-500 ppm RC oscillator
- 32.768 kHz crystal oscillator, using external 32.768 kHz crystal
- 32.768 kHz oscillator synthesized from 64 MHz oscillator
- Firmware (FW) override control of oscillator activity for low latency start up
- Automatic oscillator and clock control, and distribution for ultra-low power



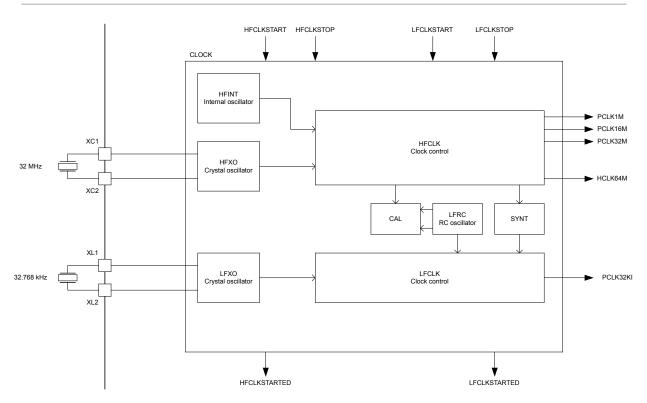


Figure 19: Clock control

5.4.1 HFCI K clock controller

The HFCLK clock controller provides the following clocks to the system.

- HCLK64M: 64 MHz CPU clock
- PCLK1M: 1 MHz peripheral clock
- PCLK16M: 16 MHz peripheral clock
- PCLK32M: 32 MHz peripheral clock

The HFCLK controller supports the following high frequency clock (HFCLK) sources:

- 64 MHz internal oscillator (HFINT)
- 64 MHz crystal oscillator (HFXO)

For illustration, see Clock control on page 66.

When the system requests one or more clocks from the HFCLK controller, the HFCLK controller will automatically provide them. If the system does not request any clocks provided by the HFCLK controller, the controller will enter a power saving mode.

These clocks are only available when the system is in ON mode. When the system enters ON mode, the internal oscillator (HFINT) clock source will automatically start to be able to provide the required HFCLK clock(s) for the system.

The HFINT will be used when HFCLK is requested and HFXO has not been started. The HFXO is started by triggering the HFCLKSTART task and stopped using the HFCLKSTOP task. A HFCLKSTARTED event will be generated when the HFXO has started and its frequency is stable.

The HFXO must be running to use the RADIO or the calibration mechanism associated with the 32.768 kHz RC oscillator.

5.4.1.1 64 MHz crystal oscillator (HFXO)

The 64 MHz crystal oscillator (HFXO) is controlled by a 32 MHz external crystal



The crystal oscillator is designed for use with an AT-cut quartz crystal in parallel resonant mode. To achieve correct oscillation frequency, the load capacitance must match the specification in the crystal data sheet.

Circuit diagram of the 64 MHz crystal oscillator on page 67 shows how the 32 MHz crystal is connected to the 64 MHz crystal oscillator.

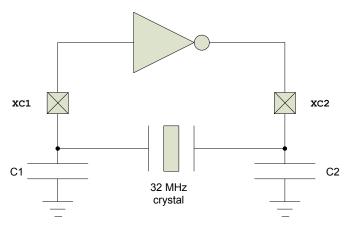


Figure 20: Circuit diagram of the 64 MHz crystal oscillator

The load capacitance (CL) is the total capacitance seen by the crystal across its terminals and is given by:

$$CL = \frac{\left(C1' \cdot C2'\right)}{\left(C1' + C2'\right)}$$

$$C1' = C1 + C_{pcb1} + C_{pin}$$

 $C2' = C2 + C_{pcb2} + C_{pin}$

C1 and C2 are ceramic SMD capacitors connected between each crystal terminal and ground. For more information, see Reference circuitry on page 398. C_{pcb1} and C_{pcb2} are stray capacitances on the PCB. C_{pin} is the pin input capacitance on the XC1 and XC2 pins. See table 64 MHz crystal oscillator (HFXO) on page 76. The load capacitors C1 and C2 should have the same value.

For reliable operation, the crystal load capacitance, shunt capacitance, equivalent series resistance, and drive level must comply with the specifications in table 64 MHz crystal oscillator (HFXO) on page 76. It is recommended to use a crystal with lower than maximum load capacitance and/or shunt capacitance. A low load capacitance will reduce both start up time and current consumption.

5.4.2 LFCLK clock controller

The system supports several low frequency clock sources.

As illustrated in Clock control on page 66, the system supports the following low frequency clock sources:

- 32.768 kHz RC oscillator (LFRC)
- 32.768 kHz crystal oscillator (LFXO)
- 32.768 kHz synthesized from HFCLK (LFSYNT)

The LFCLK clock is started by first selecting the preferred clock source in register LFCLKSRC on page 75 and then triggering the LFCLKSTART task. If the LFXO is selected as the clock source, the LFCLK will initially start running from the 32.768 kHz LFRC while the LFXO is starting up and automatically switch to using the LFXO once this oscillator is running. The LFCLKSTARTED event will be generated when the LFXO has been started.



The LFCLK clock is stopped by triggering the LFCLKSTOP task.

It is not allowed to write to register LFCLKSRC on page 75 when the LFCLK is running.

A LFCLKSTOP task will stop the LFCLK oscillator. However, the LFCLKSTOP task can only be triggered after the STATE field in register LFCLKSTAT on page 75 indicates a 'LFCLK running' state.

The LFCLK clock controller and all of the LFCLK clock sources are always switched off when in OFF mode.

5.4.2.1 32.768 kHz RC oscillator (LFRC)

The default source of the low frequency clock (LFCLK) is the 32.768 kHz RC oscillator (LFRC).

The LFRC frequency will be affected by variation in temperature. The LFRC oscillator can be calibrated to improve accuracy by using the HFXO as a reference oscillator during calibration. See Table 32.768 kHz RC oscillator (LFRC) on page 77 for details on the default and calibrated accuracy of the LFRC oscillator. The LFRC oscillator does not require additional external components.

5.4.2.2 Calibrating the 32.768 kHz RC oscillator

After the 32.768 kHz RC oscillator is started and running, it can be calibrated by triggering the CAL task. In this case, the HFCLK will be temporarily switched on and used as a reference.

A DONE event will be generated when calibration has finished. The calibration mechanism will only work as long as HFCLK is generated from the HFCLK crystal oscillator, it is therefore necessary to explicitly start this crystal oscillator before calibration can be started, see HFCLKSTART task.

It is not allowed to stop the LFRC during an ongoing calibration.

5.4.2.3 Calibration timer

The calibration timer can be used to time the calibration interval of the 32.768 kHz RC oscillator.

The calibration timer is started by triggering the CTSTART task and stopped by triggering the CTSTOP task. The calibration timer will always start counting down from the value specified in CTIV and generate a CTTO timeout event when it reaches 0. The Calibration timer will stop by itself when it reaches 0.

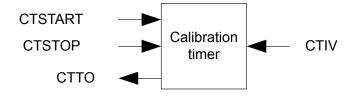


Figure 21: Calibration timer

Due to limitations in the calibration timer, only one task related to calibration, that is, CAL, CTSTART and CTSTOP, can be triggered for every period of LFCLK.

5.4.2.4 32.768 kHz crystal oscillator (LFXO)

For higher LFCLK accuracy the low frequency crystal oscillator (LFXO) must be used.

The following external clock sources are supported:

- Low swing clock signal applied to the XL1 pin. The XL2 pin shall then be grounded.
- Rail-to-rail clock signal applied to the XL1 pin. The XL2 pin shall then be grounded or left unconnected.

The LFCLKSRC on page 75 register controls the clock source, and its allowed swing. The truth table for various situations is as follows:



SRC	EXTERNAL	BYPASS	Comment
0	0	0	Normal operation, RC is source
0	0	1	DO NOT USE
0	1	Χ	DO NOT USE
1	0	0	Normal XTAL operation
1	1	0	Apply external low swing signal to XL1, ground XL2
1	1	1	Apply external full swing signal to XL1, leave XL2 grounded or unconnected
1	0	1	DO NOT USE
2	0	0	Normal operation, synth is source
2	0	1	DO NOT USE
2	1	Χ	DO NOT USE

Table 20: LFCLKSRC configuration depending on clock source

To achieve correct oscillation frequency, the load capacitance must match the specification in the crystal data sheet. Circuit diagram of the 32.768 kHz crystal oscillator on page 69 shows the LFXO circuitry.

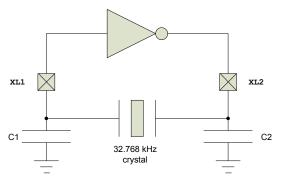


Figure 22: Circuit diagram of the 32.768 kHz crystal oscillator

The load capacitance (CL) is the total capacitance seen by the crystal across its terminals and is given by:

$$CL = \frac{\left(C1' \cdot C2'\right)}{\left(C1' + C2'\right)}$$

$$C1' = C1 + C_{pcb1} + C_{pin}$$

$$C2' = C2 + C_{pcb2} + C_{pin}$$

C1 and C2 are ceramic SMD capacitors connected between each crystal terminal and ground. C_{pcb1} and C_{pcb2} are stray capacitances on the PCB. C_{pin} is the pin input capacitance on the XC1 and XC2 pins (see 32.768 kHz crystal oscillator (LFXO) on page 77). The load capacitors C1 and C2 should have the same value.

For more information, see Reference circuitry on page 398.

5.4.2.5 32.768 kHz synthesized from HFCLK (LFSYNT)

LFCLK can also be synthesized from the HFCLK clock source. The accuracy of LFCLK will then be the accuracy of the HFCLK.

Using the LFSYNT clock avoids the requirement for a 32.768 kHz crystal, but increases average power consumption as the HFCLK will need to be requested in the system.



5.4.3 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40000000	CLOCK	CLOCK	Clock control	

Table 21: Instances

Register	Offset	Description	
TASKS_HFCLKSTART	0x000	Start HFCLK crystal oscillator	
TASKS_HFCLKSTOP	0x004	Stop HFCLK crystal oscillator	
TASKS_LFCLKSTART	0x008	Start LFCLK source	
TASKS_LFCLKSTOP	0x00C	Stop LFCLK source	
TASKS_CAL	0x010	Start calibration of LFRC oscillator	
TASKS_CTSTART	0x014	Start calibration timer	
TASKS_CTSTOP	0x018	Stop calibration timer	
EVENTS_HFCLKSTARTED	0x100	HFCLK oscillator started	
EVENTS_LFCLKSTARTED	0x104	LFCLK started	
EVENTS_DONE	0x10C	Calibration of LFCLK RC oscillator complete event	
EVENTS_CTTO	0x110	Calibration timer timeout	
INTENSET	0x304	Enable interrupt	
INTENCLR	0x308	Disable interrupt	
HFCLKRUN	0x408	Status indicating that HFCLKSTART task has been triggered	
HFCLKSTAT	0x40C	HFCLK status	
LFCLKRUN	0x414	Status indicating that LFCLKSTART task has been triggered	
LFCLKSTAT	0x418	LFCLK status	
LFCLKSRCCOPY	0x41C	Copy of LFCLKSRC register, set when LFCLKSTART task was triggered	
LFCLKSRC	0x518	Clock source for the LFCLK	
CTIV	0x538	Calibration timer interval	Retained

Table 22: Register overview

5.4.3.1 TASKS_HFCLKSTART

Address offset: 0x000

Start HFCLK crystal oscillator

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_HFCLKSTART			Start HFCLK crystal oscillator
		Trigger	1	Trigger task

5.4.3.2 TASKS_HFCLKSTOP

Address offset: 0x004

Stop HFCLK crystal oscillator



Bit n	umb	per		31 30 29 28 27 26 2	5 24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																												А
Rese	t Ox	00000000		0 0 0 0 0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																												
Α	W	TASKS_HFCLKSTOP				Sto	рΕ	HFC	LK (cry	stal	os	cilla	ato	r													
			Trigger	1		Trig	gge	er ta	ask																			

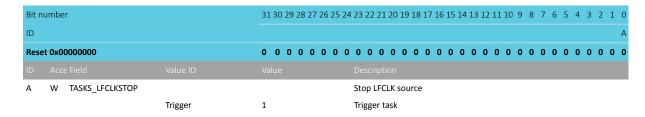
5.4.3.3 TASKS_LFCLKSTART

Address offset: 0x008 Start LFCLK source

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_LFCLKSTART			Start LFCLK source
		Trigger	1	Trigger task

5.4.3.4 TASKS_LFCLKSTOP

Address offset: 0x00C Stop LFCLK source



5.4.3.5 TASKS_CAL

Address offset: 0x010

Start calibration of LFRC oscillator

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x0000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_CAL			Start calibration of LFRC oscillator
		Trigger	1	Trigger task

5.4.3.6 TASKS_CTSTART

Address offset: 0x014 Start calibration timer



Bit number					0 29	28	27 2	6 2	:5 24	1 23	22	21	. 20	19	18 1	17 1	.6 1	5 1	4 13	3 12	2 11	10	9	8	7	6	5	4	3 :	2 1	1 0
ID																															Α
Rese	Reset 0x00000000					0	0 () (0 0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0	0	0	0	0	0 (0	0 0
ID																															
A W TASKS_CTSTART										Start calibration timer																					
			Trigger	1						Tr	igge	er t	ask																		

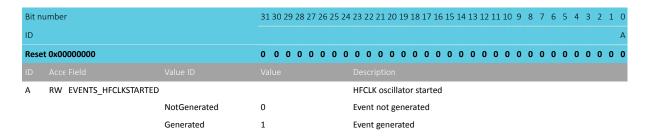
5.4.3.7 TASKS_CTSTOP

Address offset: 0x018 Stop calibration timer

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_CTSTOP			Stop calibration timer
		Trigger	1	Trigger task

5.4.3.8 EVENTS_HFCLKSTARTED

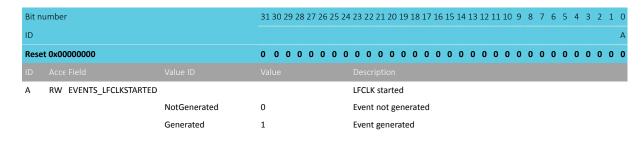
Address offset: 0x100 HFCLK oscillator started



5.4.3.9 EVENTS_LFCLKSTARTED

Address offset: 0x104

LFCLK started



5.4.3.10 EVENTS DONE

Address offset: 0x10C

Calibration of LFCLK RC oscillator complete event



Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_DONE			Calibration of LFCLK RC oscillator complete event
	NotGenerated	0	Event not generated
	Generated	1	Event generated

5.4.3.11 EVENTS_CTTO

Address offset: 0x110

Calibration timer timeout

Bit no	umber		31	30	29 2	28 2	7 26	25	24	23 :	22 2	21 2	20 1	.9 18	3 17	' 16	15	14	13 :	2 1	1 10	9	8	7	6	5	4	3	2 1	. 0
ID																														Α
Rese	t 0x00000000		0	0	0	0 0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0 (0
ID										Des																				
Α	RW EVENTS_CTTO									Cali	ibra	itio	n ti	mer	tim	ieoi	ut													
		NotGenerated	0							Eve	ent i	not	ger	nera	ted															
		Generated	1							Eve	ent g	gen	era	ted																

5.4.3.12 INTENSET

Address offset: 0x304 Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW HFCLKSTARTED			Write '1' to enable interrupt for event HFCLKSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW LFCLKSTARTED			Write '1' to enable interrupt for event LFCLKSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW DONE			Write '1' to enable interrupt for event DONE
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW CTTO			Write '1' to enable interrupt for event CTTO
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

5.4.3.13 INTENCLR

Address offset: 0x308

Disable interrupt



Bit r	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW HFCLKSTARTED			Write '1' to disable interrupt for event HFCLKSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW LFCLKSTARTED			Write '1' to disable interrupt for event LFCLKSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW DONE			Write '1' to disable interrupt for event DONE
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW CTTO			Write '1' to disable interrupt for event CTTO
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

5.4.3.14 HFCLKRUN

Address offset: 0x408

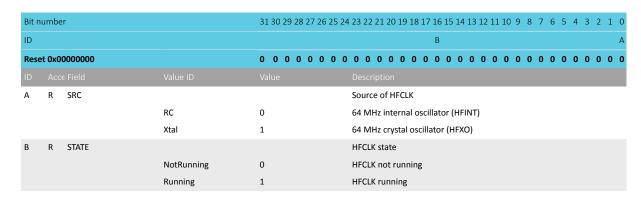
Status indicating that HFCLKSTART task has been triggered

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R STATUS			HFCLKSTART task triggered or not
	NotTriggered	0	Task not triggered
	Triggered	1	Task triggered

5.4.3.15 HFCLKSTAT

Address offset: 0x40C

HFCLK status

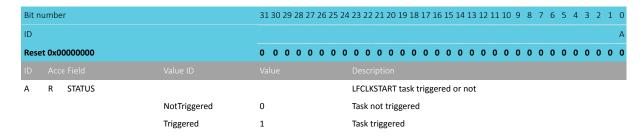


5.4.3.16 LFCLKRUN

Address offset: 0x414



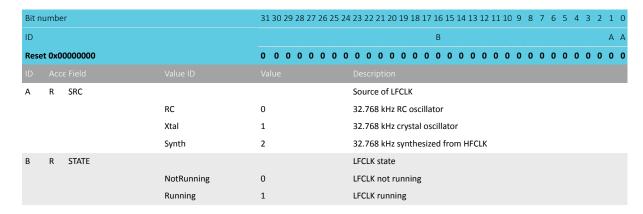
Status indicating that LFCLKSTART task has been triggered



5.4.3.17 LFCLKSTAT

Address offset: 0x418

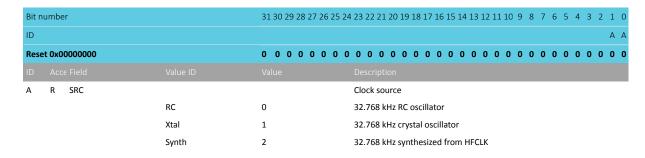
LFCLK status



5.4.3.18 LFCLKSRCCOPY

Address offset: 0x41C

Copy of LFCLKSRC register, set when LFCLKSTART task was triggered



5.4.3.19 LFCLKSRC

Address offset: 0x518

Clock source for the LFCLK



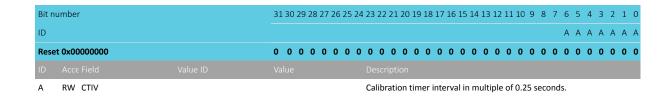
Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВАА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW SRC			Clock source
		RC	0	32.768 kHz RC oscillator
		Xtal	1	32.768 kHz crystal oscillator
		Synth	2	32.768 kHz synthesized from HFCLK
В	RW BYPASS			Enable or disable bypass of LFCLK crystal oscillator with
				external clock source
		Disabled	0	Disable (use with Xtal or low-swing external source)
		Enabled	1	Enable (use with rail-to-rail external source)
С	RW EXTERNAL			Enable or disable external source for LFCLK
		Disabled	0	Disable external source (use with Xtal)
		Enabled	1	Enable use of external source instead of Xtal (SRC needs to
				be set to Xtal)

5.4.3.20 CTIV (Retained)

Address offset: 0x538

This register is a retained register

Calibration timer interval



Range: 0.25 seconds to 31.75 seconds.

5.4.4 Electrical specification

5.4.4.1 64 MHz internal oscillator (HFINT)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFINT}	Nominal output frequency		64		MHz
f _{TOL_HFINT}	Frequency tolerance		<±1.5	<±8	%
t _{START_HFINT}	Startup time		3		us

5.4.4.2 64 MHz crystal oscillator (HFXO)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFXO}	Nominal output frequency		64		MHz
f _{XTAL_HFXO}	External crystal frequency		32		MHz
f_{TOL_HFXO}	Frequency tolerance requirement for 2.4 GHz proprietary			±60	ppm
	radio applications				
f _{TOL_HFXO_BLE}	Frequency tolerance requirement, Bluetooth low energy			±40	ppm
	applications				
C _{L_HFXO}	Load capacitance			12	pF
C _{0_HFXO}	Shunt capacitance			7	pF



Symbol	Description	Min.	Тур.	Max.	Units
R _{S_HFXO_7PF}	Equivalent series resistance C0 = 7 pF			60	ohm
R _{S_HFXO_5PF}	Equivalent series resistance C0 = 5 pF			60	ohm
R _{S_HFXO_3PF}	Equivalent series resistance C0 = 3 pF			100	ohm
P _{D_HFXO}	Drive level			100	uW
C _{PIN_HFXO}	Input capacitance XC1 and XC2		4		pF
t _{START_HFXO}	Startup time		0.36		ms

5.4.4.3 32.768 kHz RC oscillator (LFRC)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_LFRC}	Nominal frequency		32.768		kHz
f_{TOL_LFRC}	Frequency tolerance			±2	%
$f_{TOL_CAL_LFRC}$	Frequency tolerance for LFRC after calibration 11			±500	ppm
t _{START_LFRC}	Startup time for 32.768 kHz RC oscillator		600		us

5.4.4.4 32.768 kHz crystal oscillator (LFXO)

Symbol	Description	Min.	Тур.	Max.	Units
f_{NOM_LFXO}	Crystal frequency		32.768		kHz
f _{TOL_LFXO_BLE}	Frequency tolerance requirement for BLE stack			±250	ppm
$f_{TOL_LFXO_ANT}$	Frequency tolerance requirement for ANT stack			±50	ppm
C _{L_LFXO}	Load capacitance			12.5	pF
C_{0_LFXO}	Shunt capacitance			2	pF
R _{S_LFXO}	Equivalent series resistance			100	kohm
P_{D_LFXO}	Drive level			0.5	uW
C _{pin}	Input capacitance on XL1 and XL2 pads		4		pF
t _{START_LFXO}	Startup time for 32.768 kHz crystal oscillator		0.25		S
$V_{AMP_IN_XO_LOW}$	Peak to peak amplitude for external low swing clock. Input	200		1000	mV
	signal must not swing outside supply rails.				

5.4.4.5 32.768 kHz synthesized from HFCLK (LFSYNT)

Symbol	Description	Min.	Тур.	Max.	Units
f_{NOM_LFSYNT}	Nominal frequency		32.768		kHz
f _{TOL_LFSYNT}	Frequency tolerance in addition to HFLCK tolerance 12		8		ppm
t _{START_LFSYNT}	Startup time for synthesized 32.768 kHz		100		us

Constant temperature within ± 0.5 °C and calibration performed at least every 8 seconds, defined as 3 12 Frequency tolerance will be derived from the HFCLK source clock plus the LFSYNT tolerance

6 Peripherals

6.1 Peripheral interface

Peripherals are controlled by the CPU by writing to configuration registers and task registers. Peripheral events are indicated to the CPU by event registers and interrupts if they are configured for a given event.

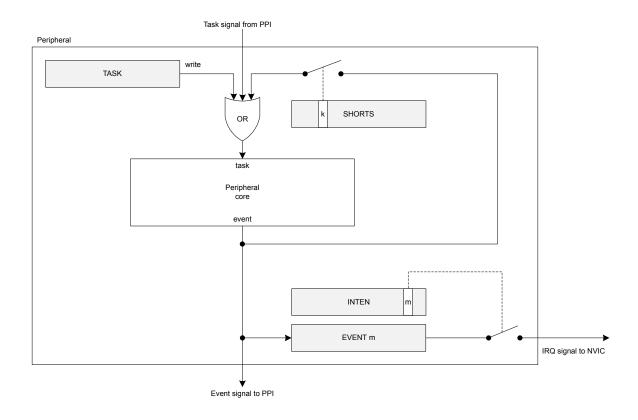


Figure 23: Tasks, events, shortcuts, and interrupts

6.1.1 Peripheral ID

Every peripheral is assigned a fixed block of 0x1000 bytes of address space, which is equal to 1024 x 32 bit registers.

See Instantiation on page 19 for more information about which peripherals are available and where they are located in the address map.

There is a direct relationship between peripheral ID and base address. For example, a peripheral with base address 0x40000000 is assigned ID=0, a peripheral with base address 0x40001000 is assigned ID=1, and a peripheral with base address 0x4001F000 is assigned ID=31.

Peripherals may share the same ID, which may impose one or more of the following limitations:

- Some peripherals share some registers or other common resources.
- Operation is mutually exclusive. Only one of the peripherals can be used at a time.
- Switching from one peripheral to another must follow a specific pattern (disable the first, then enable the second peripheral).



6.1.2 Peripherals with shared ID

In general (with the exception of ID 0), peripherals sharing an ID and base address may not be used simultaneously. The user can only enable one peripheral at the time on this specific ID.

When switching between two peripherals sharing an ID, the user should do the following to prevent unwanted behavior:

- Disable the previously used peripheral.
- Remove any programmable peripheral interconnect (PPI) connections set up for the peripheral that is being disabled.
- Clear all bits in the INTEN register, i.e. INTENCLR = 0xFFFFFFFF.
- Explicitly configure the peripheral that you are about to enable and do not rely on configuration values that may be inherited from the peripheral that was disabled.
- Enable the now configured peripheral.

See which peripherals are sharing ID in Instantiation on page 19.

6.1.3 Peripheral registers

Most peripherals feature an ENABLE register. Unless otherwise specified in the relevant chapter, the peripheral registers (in particular the PSEL registers) must be configured before enabling the peripheral.

Note that the peripheral must be enabled before tasks and events can be used.

6.1.4 Bit set and clear

Registers with multiple single-bit bit fields may implement the set-and-clear pattern. This pattern enables firmware to set and clear individual bits in a register without having to perform a read-modify-write operation on the main register.

This pattern is implemented using three consecutive addresses in the register map, where the main register is followed by dedicated SET and CLR registers (in that exact order).

The SET register is used to set individual bits in the main register while the CLR register is used to clear individual bits in the main register. Writing $\mathbb 1$ to a bit in SET or CLR register will set or clear the same bit in the main register respectively. Writing $\mathbb 0$ to a bit in SET or CLR register has no effect. Reading the SET or CLR register returns the value of the main register.

Note: The main register may not be visible and hence not directly accessible in all cases.

6.1.5 Tasks

Tasks are used to trigger actions in a peripheral, for example to start a particular behavior. A peripheral can implement multiple tasks with each task having a separate register in that peripheral's task register group.

A task is triggered when firmware writes 1 to the task register, or when the peripheral itself or another peripheral toggles the corresponding task signal. See Tasks, events, shortcuts, and interrupts on page 78.

6.1.6 Events

Events are used to notify peripherals and the CPU about events that have happened, for example a state change in a peripheral. A peripheral may generate multiple events with each event having a separate register in that peripheral's event register group.

An event is generated when the peripheral itself toggles the corresponding event signal, and the event register is updated to reflect that the event has been generated. See Tasks, events, shortcuts, and interrupts on page 78. An event register is only cleared when firmware writes 0 to it.



Events can be generated by the peripheral even when the event register is set to 1.

6.1.7 Shortcuts

A shortcut is a direct connection between an event and a task within the same peripheral. If a shortcut is enabled, the associated task is automatically triggered when its associated event is generated.

Using a shortcut is the equivalent to making the same connection outside the peripheral and through the PPI. However, the propagation delay through the shortcut is usually shorter than the propagation delay through the PPI.

Shortcuts are predefined, which means their connections cannot be configured by firmware. Each shortcut can be individually enabled or disabled through the shortcut register, one bit per shortcut, giving a maximum of 32 shortcuts for each peripheral.

6.1.8 Interrupts

All peripherals support interrupts. Interrupts are generated by events.

A peripheral only occupies one interrupt, and the interrupt number follows the peripheral ID. For example, the peripheral with ID=4 is connected to interrupt number 4 in the nested vectored interrupt controller (NVIC).

Using the INTEN, INTENSET and INTENCLR registers, every event generated by a peripheral can be configured to generate that peripheral's interrupt. Multiple events can be enabled to generate interrupts simultaneously. To resolve the correct interrupt source, the event registers in the event group of peripheral registers will indicate the source.

Some peripherals implement only INTENSET and INTENCLR registers, and the INTEN register is not available on those peripherals. See the individual peripheral chapters for details. In all cases, reading back the INTENSET or INTENCLR register returns the same information as in INTEN.

Each event implemented in the peripheral is associated with a specific bit position in the INTEN, INTENSET and INTENCLR registers.

The relationship between tasks, events, shortcuts, and interrupts is shown in Tasks, events, shortcuts, and interrupts on page 78.

Interrupt clearing

Clearing an interrupt by writing 0 to an event register, or disabling an interrupt using the INTENCLR register, can take up to four CPU clock cycles to take effect. This means that an interrupt may reoccur immediatelly, even if a new event has not come, if the program exits an interrupt handler after the interrupt is cleared or disabled but before four clock cycles have passed.

Note: To avoid an interrupt reoccurring before a new event has come, the program should perform a read from one of the peripheral registers. For example, the event register that has been cleared, or the INTENCLR register that has been used to disable the interrupt. This will cause a one to three-cycle delay and ensure the interrupt is cleared before exiting the interrupt handler.

Care should be taken to ensure the compiler does not remove the read operation as an optimization. If the program can guarantee a four-cycle delay after event being cleared or interrupt disabled in any other way, then a read of a register is not required.



6.2 AAR — Accelerated address resolver

Accelerated address resolver is a cryptographic support function for implementing the Resolvable Private Address Resolution Procedure described in the *Bluetooth Core specification* v4.0. Resolvable Private Address generation should be achieved using ECB and is not supported by AAR.

The procedure allows two devices that share a secret key to generate and resolve a hash based on their device address. The AAR block enables real-time address resolution on incoming packets when configured as described in this chapter. This allows real-time packet filtering (whitelisting) using a list of known shared keys (Identity Resolving Keys (IRK) in *Bluetooth*).

6.2.1 EasyDMA

The AAR implements EasyDMA for reading and writing to the RAM. The EasyDMA will have finished accessing the RAM when the END, RESOLVED, and NOTRESOLVED events are generated.

If the IRKPTR on page 86, ADDRPTR on page 86, and the SCRATCHPTR on page 86 is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

6.2.2 Resolving a resolvable address

As per Bluetooth specification, a private resolvable address is composed of six bytes.

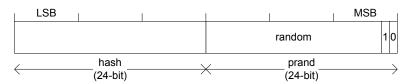


Figure 24: Resolvable address

To resolve an address the register ADDRPTR on page 86 must point to the start of the packet. The resolver is started by triggering the START task. A RESOLVED event is generated when the AAR manages to resolve the address using one of the Identity Resolving Keys (IRK) found in the IRK data structure. The AAR will use the IRK specified in the register IRKO to IRK15 starting from IRKO. The register NIRK on page 85 specifies how many IRKs should be used. The AAR module will generate a NOTRESOLVED event if it is not able to resolve the address using the specified list of IRKs.

The AAR will go through the list of available IRKs in the IRK data structure and for each IRK try to resolve the address according to the Resolvable Private Address Resolution Procedure described in the *Bluetooth Core specification* v4.0 [Vol 3] chapter 10.8.2.3. The time it takes to resolve an address varies due to the location in the list of the resolvable address. The resolution time will also be affected by RAM accesses performed by other peripherals and the CPU. See the Electrical specifications for more information about resolution time.

The AAR only compares the received address to those programmed in the module without checking the address type.

The AAR will stop as soon as it has managed to resolve the address, or after trying to resolve the address using NIRK number of IRKs from the IRK data structure. The AAR will generate an END event after it has stopped.



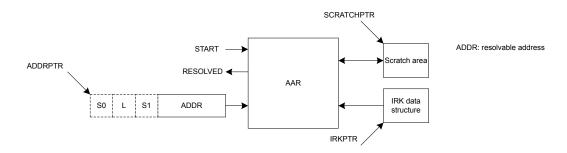


Figure 25: Address resolution with packet preloaded into RAM

6.2.3 Use case example for chaining RADIO packet reception with address resolution using AAR

The AAR may be started as soon as the 6 bytes required by the AAR have been received by the RADIO and stored in RAM. The ADDRPTR pointer must point to the start of packet.

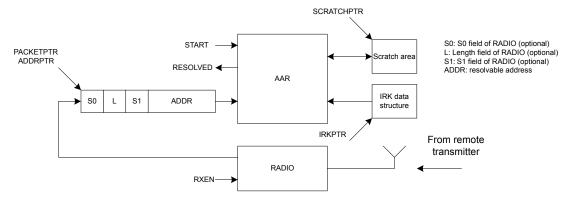


Figure 26: Address resolution with packet loaded into RAM by the RADIO

6.2.4 IRK data structure

The IRK data structure is located in RAM at the memory location specified by the IRKPTR register.

Property	Address offset	Description
IRK0	0	IRK number 0 (16 - byte)
IRK1	16	IRK number 1 (16 - byte)
IRK15	240	IRK number 15 (16 - byte)

Table 23: IRK data structure overview

6.2.5 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4000F000	AAR	AAR	Accelerated address resolver	

Table 24: Instances

Register	Offset	Description
TASKS_START	0x000	Start resolving addresses based on IRKs specified in the IRK data structure
TASKS_STOP	0x008	Stop resolving addresses
EVENTS END	0×100	Address resolution procedure complete



Register	Offset	Description
EVENTS_RESOLVED	0x104	Address resolved
EVENTS_NOTRESOLVED	0x108	Address not resolved
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
STATUS	0x400	Resolution status
ENABLE	0x500	Enable AAR
NIRK	0x504	Number of IRKs
IRKPTR	0x508	Pointer to IRK data structure
ADDRPTR	0x510	Pointer to the resolvable address
SCRATCHPTR	0x514	Pointer to data area used for temporary storage

Table 25: Register overview

6.2.5.1 TASKS_START

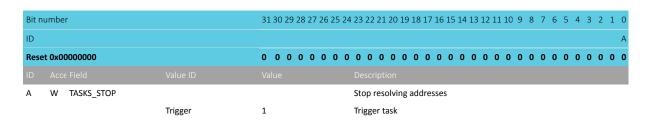
Address offset: 0x000

Start resolving addresses based on IRKs specified in the IRK data structure

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A W TASKS_START			Start resolving addresses based on IRKs specified in the IRK
			data structure
	Trigger	1	Trigger task

6.2.5.2 TASKS_STOP

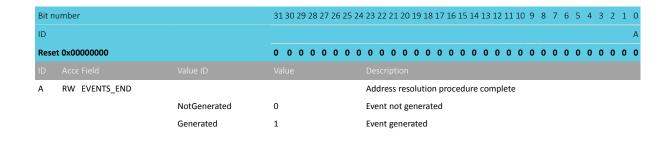
Address offset: 0x008 Stop resolving addresses



6.2.5.3 EVENTS_END

Address offset: 0x100

Address resolution procedure complete

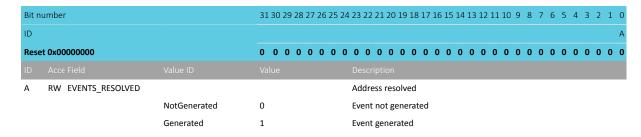




6.2.5.4 EVENTS_RESOLVED

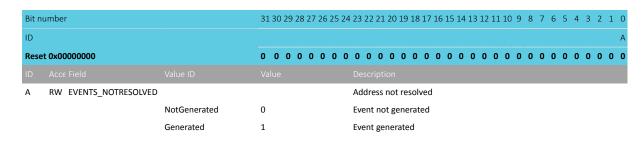
Address offset: 0x104

Address resolved



6.2.5.5 EVENTS_NOTRESOLVED

Address offset: 0x108 Address not resolved



6.2.5.6 INTENSET

Address offset: 0x304 Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	Reset 0x00000000 0 0 0 0 0 0 0 0			0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW END			Write '1' to enable interrupt for event END
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW RESOLVED			Write '1' to enable interrupt for event RESOLVED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW NOTRESOLVED			Write '1' to enable interrupt for event NOTRESOLVED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.2.5.7 INTENCLR

Address offset: 0x308

Disable interrupt



Bit r	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW END			Write '1' to disable interrupt for event END
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW RESOLVED			Write '1' to disable interrupt for event RESOLVED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW NOTRESOLVED			Write '1' to disable interrupt for event NOTRESOLVED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.2.5.8 STATUS

Address offset: 0x400 Resolution status

A R STATUS	[015]	The IRK that was used last time an address was resolved
ID Acce Field		Description
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		АААА
Bit number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.2.5.9 ENABLE

Address offset: 0x500

Enable AAR

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АА
Reset 0x00000000		0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field			
A RW ENABLE			Enable or disable AAR
	Disabled	0	Disable
	Enabled	3	Enable

6.2.5.10 NIRK

Address offset: 0x504

Number of IRKs

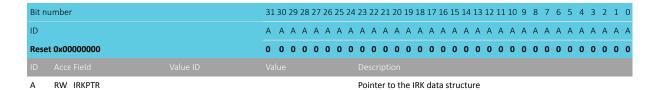
			structure
Α	RW NIRK	[116]	Number of Identity root keys available in the IRK data
ID			
Res	et 0x00000001	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A
Bit r	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



6.2.5.11 IRKPTR

Address offset: 0x508

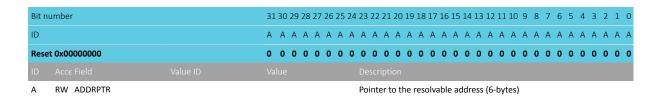
Pointer to IRK data structure



6.2.5.12 ADDRPTR

Address offset: 0x510

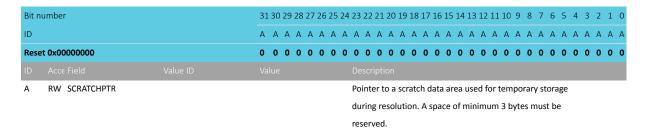
Pointer to the resolvable address



6.2.5.13 SCRATCHPTR

Address offset: 0x514

Pointer to data area used for temporary storage



6.2.6 Electrical specification

6.2.6.1 AAR Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{AAR}	Address resolution time per IRK. Total time for several IRKs				μs
	is given as (1 μ s + n * t_AAR), where n is the number of IRKs.				
	(Given priority to the actual destination RAM block).				
t _{AAR,8}	Time for address resolution of 8 IRKs. (Given priority to the		48		μs
	actual destination RAM block).				

6.3 BPROT — Block protection

The mechanism for protecting non-volatile memory can be used to prevent erroneous application code from erasing or writing to protected blocks.



Non-volatile memory can be protected from erases and writes depending on the settings in the CONFIG registers. One bit in a CONFIG register represents one protected block of 4 kB. There are multiple CONFIG registers to cover the whole range of the flash. Protected regions of program memory on page 87 illustrates how the CONFIG bits map to the program memory space.

Important: If an erase or write to a protected block is detected, the CPU will hard fault. If an ERASEALL operation is attempted from the CPU while any block is protected, it will be blocked and the CPU will hard fault.

On reset, all the protection bits are cleared. To ensure safe operation, the first task after reset must be to set the protection bits. The only way of clearing protection bits is by resetting the device from any reset source.

The protection mechanism is turned off when in debug mode (when a debugger is connected) and the DISABLEINDEBUG register is set to disabled.

Program memory n*32 + 31 n*32 + 1 n*32 + 0 ... 2 1 0 0x00000000

Figure 27: Protected regions of program memory



6.3.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40000000	BPROT	BPROT	Block protect	

Table 26: Instances

Register	Offset	Description
CONFIG0	0x600	Block protect configuration register 0
CONFIG1	0x604	Block protect configuration register 1
DISABLEINDEBUG	0x608	Disable protection mechanism in debug mode
UNUSED0	0x60C	Reserved

Table 27: Register overview

6.3.1.1 CONFIGO

Address offset: 0x600

Block protect configuration register 0

Bit n	umber		31	30	29	28	27	26	25	24	23	22	21	20	19 1	18 1	7 1	6 15	5 14	13	12	11	10 !	9 8	3 7	΄ ε	5	4	3	2	1 0
ID			f	е	d	С	b	а	Z	Υ	Χ	W	٧	U	Т	S I	R C	Q P	0	N	М	L	K	J	Н	I	i F	Ε	D	С	ВА
Rese	t 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 0
ID																															
A-f	RW REGION[i] (i=031)										Ena	able	e pr	ote	ectio	n f	or r	egio	on i	. W	rite	'0' l	nas	no e	effe	ct.					
		Disabled	0								Pro	otec	ctio	n d	isak	led															
		Enabled	1								Pro	otec	ctio	n e	nab	led															

6.3.1.2 CONFIG1

Address offset: 0x604

Block protect configuration register 1

Bit number	31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		PONMLKJIHGFEDCBA
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A-P RW REGION[i+32] (i=015)		Enable protection for region i+32. Write '0' has no effect.
Disabled	0	Protection disabled
Enabled	1	Protection enabled

6.3.1.3 DISABLEINDEBUG

Address offset: 0x608

Disable protection mechanism in debug mode



Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000001		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW DISABLEINDEBUG			Disable the protection mechanism for NVM regions while in
				debug mode. This register will only disable the protection
				mechanism if the device is in debug mode.
		Disabled	1	Disabled in debug
		Enabled	0	Enabled in debug

6.4 CCM — AES CCM mode encryption

Cipher block chaining - message authentication code (CCM) mode is an authenticated encryption algorithm designed to provide both authentication and confidentiality during data transfer. CCM combines counter mode encryption and CBC-MAC authentication. The CCM terminology "Message authentication code (MAC)" is called the "Message integrity check (MIC)" in *Bluetooth* terminology and also in this document.

The CCM block generates an encrypted keystream that is applied to input data using the XOR operation and generates the 4 byte MIC field in one operation. The CCM and radio can be configured to work synchronously. The CCM will encrypt in time for transmission and decrypt after receiving bytes into memory from the radio. All operations can complete within the packet RX or TX time. CCM on this device is implemented according to *Bluetooth* requirements and the algorithm as defined in IETF RFC3610, and depends on the AES-128 block cipher. A description of the CCM algorithm can also be found in NIST Special Publication 800-38C. The *Bluetooth* specification describes the configuration of counter mode blocks and encryption blocks to implement compliant encryption for BLE.

The CCM block uses EasyDMA to load key, counter mode blocks (including the nonce required), and to read/write plain text and cipher text.

The AES CCM supports three operations: key-stream generation, packet encryption, and packet decryption. All these operations are done in compliance with the *Bluetooth* specification. ¹³

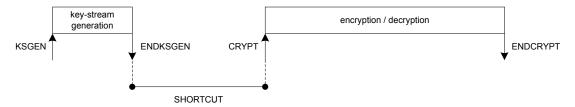


Figure 28: Key-stream generation followed by encryption or decryption. The shortcut is optional.

6.4.1 Key-steam generation

A new key-stream needs to be generated before a new packet encryption or packet decryption operation can be started.

A key-stream is generated by triggering the KSGEN task and an ENDKSGEN event will be generated when the key-stream has been generated.

Key-stream generation, packet encryption, and packet decryption operations utilize the configuration specified in the data structure pointed to by CNFPTR on page 99. It is necessary to configure this pointer and its underlying data structure, and the MODE on page 98 register before the KSGEN task is triggered.

¹³ Bluetooth AES CCM 128 bit block encryption, see Bluetooth Core specification Version 4.0.



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The key-stream will be stored in the AES CCM's temporary memory area, specified by the SCRATCHPTR on page 99, where it will be used in subsequent encryption and decryption operations.

For default length packets (MODE.LENGTH = Default) the size of the generated key-stream is 27 bytes. When using extended length packets (MODE.LENGTH = Extended) the MAXPACKETSIZE on page 100 register specifies the length of the key-stream to be generated. The length of the generated key-stream must be greater or equal to the length of the subsequent packet payload to be encrypted or decrypted. The maximum length of the key-stream in extended mode is 251 bytes, which means that the maximum packet payload size is 251.

If a shortcut is used between ENDKSGEN event and CRYPT task, the INPTR on page 99 pointer and the OUTPTR on page 99 pointers must also be configured before the KSGEN task is triggered.

6.4.2 Encryption

During packet encryption, the AES CCM will read the unencrypted packet located in RAM at the address specified in the INPTR pointer, encrypt the packet and append a four byte long Message Integrity Check (MIC) field to the packet.

Encryption is started by triggering the CRYPT task with the MODE on page 98 register set to ENCRYPTION. An ENDCRYPT event will be generated when packet encryption is completed

The AES CCM will also modify the length field of the packet to adjust for the appended MIC field, that is, add four bytes to the length, and store the resulting packet back into RAM at the address specified in the OUTPTR on page 99 pointer, see Encryption on page 90.

Empty packets (length field is set to 0) will not be encrypted but instead moved unmodified through the AES CCM.

The CCM supports different widths of the LENGTH field in the data structure for encrypted packets. This is configured in the MODE on page 98 register.

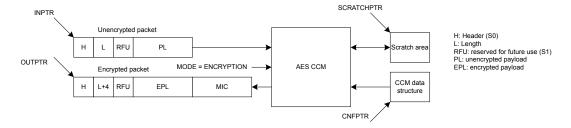


Figure 29: Encryption

6.4.3 Decryption

During packet decryption, the AES CCM will read the encrypted packet located in RAM at the address specified in the INPTR pointer, decrypt the packet, authenticate the packet's MIC field and generate the appropriate MIC status.

Decryption is started by triggering the CRYPT task with the MODE on page 98 register set to DECRYPTION. An ENDCRYPT event will be generated when packet decryption is completed

The AES CCM will also modify the length field of the packet to adjust for the MIC field, that is, subtract four bytes from the length, and then store the decrypted packet into RAM at the address pointed to by the OUTPTR pointer, see Decryption on page 91.

The CCM is only able to decrypt packet payloads that are at least 5 bytes long, that is, 1 byte or more encrypted payload (EPL) and 4 bytes of MIC. The CCM will therefore generate a MIC error for packets where the length field is set to 1, 2, 3 or 4.

Empty packets (length field is set to 0) will not be decrypted but instead moved unmodified through the AES CCM, these packets will always pass the MIC check.



The CCM supports different widths of the LENGTH field in the data structure for decrypted packets. This is configured in the MODE on page 98 register.

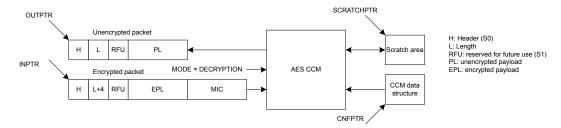


Figure 30: Decryption

6.4.4 AES CCM and RADIO concurrent operation

The CCM module is able to encrypt/decrypt data synchronously to data being transmitted or received on the radio.

In order for the CCM module to run synchronously with the radio, the data rate setting in the MODE on page 98 register needs to match the radio data rate. The settings in this register apply whenever either the KSGEN or CRYPT tasks are triggered.

The data rate setting of the MODE on page 98 register can also be overridden on-the-fly during an ongoing encrypt/decrypt operation by the contents of the RATEOVERRIDE on page 100 register. The data rate setting in this register applies whenever the RATEOVERRIDE task is triggered. This feature can be useful in cases where the radio data rate is changed during an ongoing packet transaction.

6.4.5 Encrypting packets on-the-fly in radio transmit mode

When the AES CCM is encrypting a packet on-the-fly at the same time as the radio is transmitting it, the radio must read the encrypted packet from the same memory location as the AES CCM is writing to.

The OUTPTR on page 99 pointer in the AES CCM must therefore point to the same memory location as the PACKETPTR pointer in the radio, see Configuration of on-the-fly encryption on page 91.

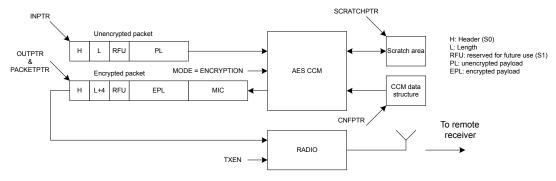


Figure 31: Configuration of on-the-fly encryption

In order to match the RADIO's timing, the KSGEN task must be triggered early enough to allow the keystream generation to complete before the encryption of the packet shall start.

For short packets (MODE.LENGTH = Default) the KSGEN task must be triggered no later than when the START task in the RADIO is triggered. In addition the shortcut between the ENDKSGEN event and the CRYPT task must be enabled. This use-case is illustrated in On-the-fly encryption of short packets (MODE.LENGTH = Default) using a PPI connection on page 92 using a PPI connection between the READY event in the RADIO and the KSGEN task in the AES CCM.

For long packets (MODE.LENGTH = Extended) the key-stream generation will need to be started even earlier, for example at the time when the TXEN task in the RADIO is triggered.



Important: Refer to Timing specification on page 101 for information about the time needed for generating a key-stream.

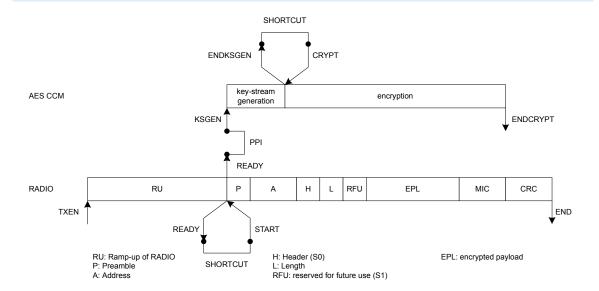


Figure 32: On-the-fly encryption of short packets (MODE.LENGTH = Default) using a PPI connection

6.4.6 Decrypting packets on-the-fly in radio receive mode

When the AES CCM is decrypting a packet on-the-fly at the same time as the RADIO is receiving it, the AES CCM must read the encrypted packet from the same memory location as the RADIO is writing to.

The INPTR on page 99 pointer in the AES CCM must therefore point to the same memory location as the PACKETPTR pointer in the RADIO, see Configuration of on-the-fly decryption on page 92.

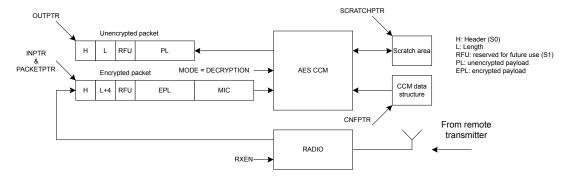


Figure 33: Configuration of on-the-fly decryption

In order to match the RADIO's timing, the KSGEN task must be triggered early enough to allow the keystream generation to complete before the decryption of the packet shall start.

For short packets (MODE.LENGTH = Default) the KSGEN task must be triggered no later than when the START task in the RADIO is triggered. In addition, the CRYPT task must be triggered no earlier than when the ADDRESS event is generated by the RADIO.

If the CRYPT task is triggered exactly at the same time as the ADDRESS event is generated by the RADIO, the AES CCM will guarantee that the decryption is completed no later than when the END event in the RADIO is generated.

This use-case is illustrated in On-the-fly decryption of short packets (MODE.LENGTH = Default) using a PPI connection on page 93 using a PPI connection between the ADDRESS event in the RADIO and the CRYPT task in the AES CCM. The KSGEN task is triggered from the READY event in the RADIO through a PPI connection.



For long packets (MODE.LENGTH = Extended) the key-stream generation will need to be started even earlier, for example at the time when the RXEN task in the RADIO is triggered.

Important: Refer to Timing specification on page 101 for information about the time needed for generating a key-stream.

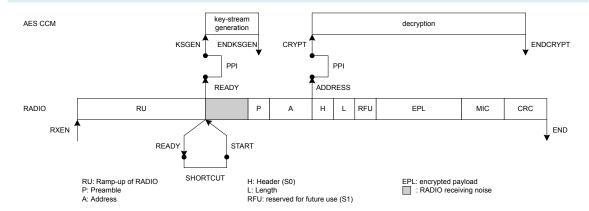


Figure 34: On-the-fly decryption of short packets (MODE.LENGTH = Default) using a PPI connection

6.4.7 CCM data structure

The CCM data structure is located in Data RAM at the memory location specified by the CNFPTR pointer register.

Property	Address offset	Description
KEY	0	16 byte AES key
PKTCTR	16	Octet0 (LSO) of packet counter
	17	Octet1 of packet counter
	18	Octet2 of packet counter
	19	Octet3 of packet counter
	20	Bit 6 – Bit 0: Octet4 (7 most significant bits of packet counter, with Bit 6 being the most
		significant bit) Bit7: Ignored
	21	Ignored
	22	Ignored
	23	Ignored
	24	Bit 0: Direction bit Bit 7 – Bit 1: Zero padded
IV	25	8 byte initialization vector (IV) Octet0 (LSO) of IV, Octet1 of IV, \dots , Octet7 (MSO) of IV

Table 28: CCM data structure overview

The NONCE vector (as specified by the *Bluetooth* Core Specification) will be generated by hardware based on the information specified in the CCM data structure from CCM data structure overview on page 93.

Property	Address offset	Description
HEADER	0	Packet Header
LENGTH	1	Number of bytes in unencrypted payload
RFU	2	Reserved Future Use
PAYLOAD	3	Unencrypted payload

Table 29: Data structure for unencrypted packet



Property	Address offset	Description
HEADER	0	Packet Header
LENGTH	1	Number of bytes in encrypted payload including length of MIC
		Important: LENGTH will be 0 for empty packets since the MIC is not added to empty packets
RFU	2	Reserved Future Use
PAYLOAD	3	Encrypted payload
MIC	3 + payload length	ENCRYPT: 4 bytes encrypted MIC
		Important: MIC is not added to empty packets

Table 30: Data structure for encrypted packet

6.4.8 EasyDMA and ERROR event

The CCM implements an EasyDMA mechanism for reading and writing to the RAM.

In cases where the CPU and other EasyDMA enabled peripherals are accessing the same RAM block at the same time, a high level of bus collisions may cause too slow operation for correct on the fly encryption. In this case the ERROR event will be generated.

The EasyDMA will have finished accessing the RAM when the ENDKSGEN and ENDCRYPT events are generated.

If the CNFPTR, SCRATCHPTR, INPTR and the OUTPTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

6.4.9 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4000F000	CCM	CCM	AES CCM mode encryption	

Table 31: Instances

Register	Offset	Description	
TASKS_KSGEN	0x000	Start generation of key-stream. This operation will stop by itself when completed.	
TASKS_CRYPT	0x004	Start encryption/decryption. This operation will stop by itself when completed.	
TASKS_STOP	0x008	Stop encryption/decryption	
TASKS_RATEOVERRIDE	0x00C	Override DATARATE setting in MODE register with the contents of the RATEOVERRIDE register	
		for any ongoing encryption/decryption	
EVENTS_ENDKSGEN	0x100	Key-stream generation complete	
EVENTS_ENDCRYPT	0x104	Encrypt/decrypt complete	
EVENTS_ERROR	0x108	CCM error event	Deprecated
SHORTS	0x200	Shortcuts between local events and tasks	
INTENSET	0x304	Enable interrupt	
INTENCLR	0x308	Disable interrupt	
MICSTATUS	0x400	MIC check result	
ENABLE	0x500	Enable	
MODE	0x504	Operation mode	
CNFPTR	0x508	Pointer to data structure holding AES key and NONCE vector	
INPTR	0x50C	Input pointer	
OUTPTR	0x510	Output pointer	
SCRATCHPTR	0x514	Pointer to data area used for temporary storage	



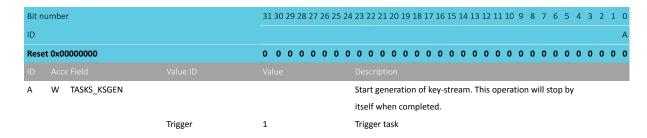
Register	Offset	Description
MAXPACKETSIZE	0x518	Length of key-stream generated when MODE.LENGTH = Extended.
RATEOVERRIDE	0x51C	Data rate override setting.

Table 32: Register overview

6.4.9.1 TASKS KSGEN

Address offset: 0x000

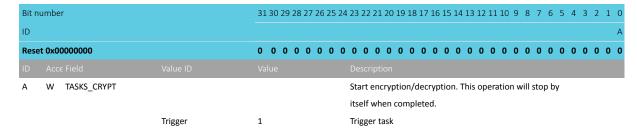
Start generation of key-stream. This operation will stop by itself when completed.



6.4.9.2 TASKS_CRYPT

Address offset: 0x004

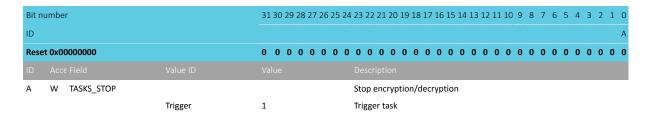
Start encryption/decryption. This operation will stop by itself when completed.



6.4.9.3 TASKS STOP

Address offset: 0x008

Stop encryption/decryption



6.4.9.4 TASKS RATEOVERRIDE

Address offset: 0x00C

Override DATARATE setting in MODE register with the contents of the RATEOVERRIDE register for any ongoing encryption/decryption



Bit nu	ımber		31	30 2	29 2	8 27	7 26	25 :	24 2	23 2	2 2:	1 20) 19	18	17 1	l6 1	5 14	4 13	12	11 :	10 9	8 (7	6	5	4	3	2 1	1 0
ID																													Α
Rese	t 0x00000000		0	0	0 (0 0	0	0	0	0 0	0 0	0	0	0	0	0 (0	0	0	0	0 (0	0	0	0	0	0	0 (0 0
ID																													
Α	W TASKS_RATEOVERRIDE								(Over	rrid	e D	ATA	RAT	E se	ttin	g in	MC	DDE	reg	iste	r wi	th t	he					
									C	ont	ent	s of	f the	e RA	TEC	VEF	RRIE	DE re	egis	ter f	for a	ny	ong	oin	g				
									e	encr	ypt	ion,	/de	cryp	tior	1													
		Trigger	1						1	rigg	ger 1	task	(

6.4.9.5 EVENTS_ENDKSGEN

Address offset: 0x100

Key-stream generation complete

Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_ENDKSGEN			Key-stream generation complete
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.4.9.6 EVENTS_ENDCRYPT

Address offset: 0x104

Encrypt/decrypt complete

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				Α
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_ENDCRYPT			Encrypt/decrypt complete
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.4.9.7 EVENTS_ERROR (Deprecated)

Address offset: 0x108

CCM error event

Bit n	umber		313	0 2	9 28	27	26	25	24	23 :	22	21	20	19 :	18 1	17 1	.6 1	5 1	4 1	3 1	2 1:	1 10	9	8	7	6	5	4	3 2	2 1	. 0
ID																															Α
Rese	t 0x00000000		0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 () (0	0	0	0	0	0	0	0	0	0 () (0
ID																															
Α	RW EVENTS_ERROR									CCI	Mε	erro	r e	ven	t													-	Dep	rec	ated
		NotGenerated	0							Eve	nt	not	ge	ner	ate	d															
		Generated	1							Eve	nt	gen	era	ateo	i																

6.4.9.8 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks



Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW ENDKSGEN_CRYPT			Shortcut between event ENDKSGEN and task CRYPT
ļ	Disabled	0	Disable shortcut
1	Enabled	1	Enable shortcut

6.4.9.9 INTENSET

Address offset: 0x304 Enable interrupt

Bit number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	1 0
ID			C [ВА
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID Acce Field				
A RW ENDKSGEN			Write '1' to enable interrupt for event ENDKSGEN	
	Set	1	Enable	
	Disabled	0	Read: Disabled	
	Enabled	1	Read: Enabled	
B RW ENDCRYPT			Write '1' to enable interrupt for event ENDCRYPT	
	Set	1	Enable	
	Disabled	0	Read: Disabled	
	Enabled	1	Read: Enabled	
C RW ERROR			Write '1' to enable interrupt for event ERROR Deprec	ated
	Set	1	Enable	
	Disabled	0	Read: Disabled	
	Enabled	1	Read: Enabled	

6.4.9.10 INTENCLR

Address offset: 0x308

Disable interrupt

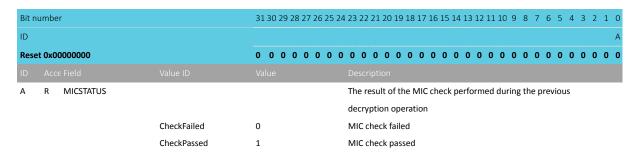
		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID			c	ВА
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
A RW ENDKSGEN			Write '1' to disable interrupt for event ENDKSGEN	
	Clear	1	Disable	
	Disabled	0	Read: Disabled	
	Enabled	1	Read: Enabled	
B RW ENDCRYPT			Write '1' to disable interrupt for event ENDCRYPT	
	Clear	1	Disable	
	Disabled	0	Read: Disabled	
	Enabled	1	Read: Enabled	
C RW ERROR			Write '1' to disable interrupt for event ERROR Depre	ecated
	Clear	1	Disable	
	Disabled	0	Read: Disabled	
	Enabled	1	Read: Enabled	



6.4.9.11 MICSTATUS

Address offset: 0x400

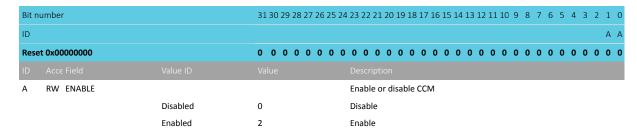
MIC check result



6.4.9.12 ENABLE

Address offset: 0x500

Enable



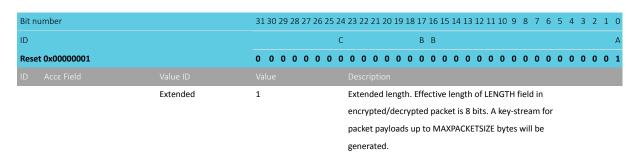
6.4.9.13 MODE

Address offset: 0x504

Operation mode

31 30	0 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0			
	С	В В А			
0 0	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			
		Description			
		The mode of operation to be used. The settings in this			
		register apply whenever either the KSGEN or CRYPT tasks			
		are triggered.			
ryption 0		AES CCM packet encryption mode			
ryption 1		AES CCM packet decryption mode			
		Radio data rate that the CCM shall run synchronous with			
oit 0		1 Mbps			
oit 1		2 Mbps			
Kbps 2		125 Kbps			
Kbps 3		500 Kbps			
		Packet length configuration			
ault 0		Default length. Effective length of LENGTH field in			
		encrypted/decrypted packet is 5 bits. A key-stream for			
		packet payloads up to 27 bytes will be generated.			
	ryption 0 ryption 1 oit 0 rit 1 Kbps 2 Kbps 3	yption 0 control of the state o			





6.4.9.14 CNFPTR

Address offset: 0x508

Pointer to data structure holding AES key and NONCE vector

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Rese	t 0x0000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		Value Description
Α	RW CNFPTR	Pointer to the data structure holding the AES key and
		the CCM NONCE vector (see Table 1 CCM data structure
		overview)

6.4.9.15 INPTR

Address offset: 0x50C

Input pointer

Bit n	ımber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Rese	t 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		Value Description
Α	RW INPTR	Input pointer

6.4.9.16 OUTPTR

Address offset: 0x510

Output pointer

ID Acce Field	Value ID	
Reset 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A
Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.4.9.17 SCRATCHPTR

Address offset: 0x514

Pointer to data area used for temporary storage

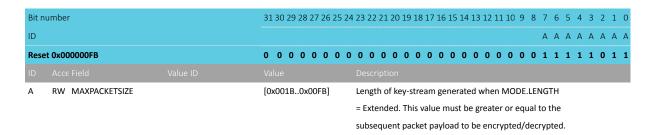


Bit r	umber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0				
ID							
Rese	et 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				
Α	RW SCRATCHPTR Pointer to a scratch data area used for temporary storage						
	during key-stream generation, MIC generation and						
			encryption/decryption.				
			The scratch area is used for temporary storage of data				
			, , ,				
			during key-stream generation and encryption.				
			When MODE.LENGTH = Default, a space of 43 bytes				
			is required for this temporary storage. MODE.LENGTH				
			= Extended (16 + MAXPACKETSIZE) bytes of storage is				
			required.				

6.4.9.18 MAXPACKETSIZE

Address offset: 0x518

Length of key-stream generated when MODE.LENGTH = Extended.



6.4.9.19 RATEOVERRIDE

Address offset: 0x51C

Data rate override setting.

Override value to be used instead of the setting of MODE.DATARATE. This override value applies when the RATEOVERRIDE task is triggered.

Bit r	Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW RATEOVERRIDE			Data rate override setting.
		1Mbit	0	1 Mbps
		2Mbit	1	2 Mbps
		125Kbps	2	125 Kbps
		500Kbps	3	500 Kbps



6.4.10 Electrical specification

6.4.10.1 Timing specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{kgen}	Time needed for key-stream generation (given priority				μs
	access to destination RAM block).				

6.5 COMP — Comparator

The comparator (COMP) compares an input voltage (VIN+) against a second input voltage (VIN-). VIN+ can be derived either from an analog input pin (AIN0-AIN6) or VDD/2. VIN- can be derived from multiple sources depending on the operation mode of the comparator.

Main features of the comparator are:

- Input range from 0 V to VDD
- Single-ended mode
 - Fully flexible hysteresis using a 64-level reference ladder
- Differential mode
 - Configurable hysteresis
- Reference inputs (VREF):
 - VDF
 - External reference from AINO to AIN7 (between 0 V and VDD)
 - Internal references 1.2 V, 1.8 V and 2.4 V
- Three speed/power consumption modes: low-power, normal and high-speed
- · Event generation on output changes
 - UP event on VIN- > VIN+
 - DOWN event on VIN- < VIN+
 - CROSS event on VIN+ and VIN- crossing
 - · READY event on core and internal reference (if used) ready



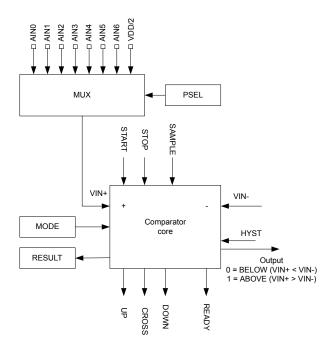


Figure 35: Comparator overview

Once enabled (using the ENABLE register), the comparator is started by triggering the START task and stopped by triggering the STOP task. After a start-up time of $t_{COMP,START}$, the comparator will generate a READY event to indicate that it is ready for use and that its output is correct. When the COMP module is started, events will be generated every time VIN+ crosses VIN-.

Operation modes

The comparator can be configured to operate in two main operation modes, differential mode and single-ended mode. See the MODE register for more information. In both operation modes, the comparator can operate in different speed and power consumption modes (low-power, normal and high-speed). High-speed mode will consume more power compared to low-power mode, and low-power mode will result in slower response time compared to high-speed mode.

Use the PSEL register to select any of the AINO-AIN6 pins (or VDD/2) as VIN+ input, irregardless of the operation mode selected for the comparator. The source of VIN- depends on which operation mode is used:

- Differential mode: Derived directly from AINO to AIN7
- Single-ended mode: Derived from VREF. VREF can be derived from VDD, AINO-AIN7 or internal 1.2 V,
 1.8 V and 2.4 V references.

The selected analog pins will be acquired by the comparator once it is enabled.

An optional hysteresis on VIN+ and VIN- can be enabled when the module is used in differential mode through the HYST register. In single-ended mode, VUP and VDOWN thresholds can be set to implement a hysteresis using the reference ladder (see Comparator in single-ended mode on page 104). This hysteresis is in the order of magnitude of 30 mV, and shall prevent noise on the signal to create unwanted events. See Hysteresis example where VIN+ starts below VUP on page 105 for illustration of the effect of an active hysteresis on a noisy input signal.

An upward crossing will generate an UP event and a downward crossing will generate a DOWN event. The CROSS event will be generated every time there is a crossing, independent of direction.

The immediate value of the comparator can be sampled to RESULT register by triggering the SAMPLE task.



6.5.1 Differential mode

In differential mode, the reference input VIN- is derived directly from one of the AINx pins.

Before enabling the comparator via the ENABLE register, the following registers must be configured for the differential mode:

- PSEL
- MODE
- EXTREFSEL

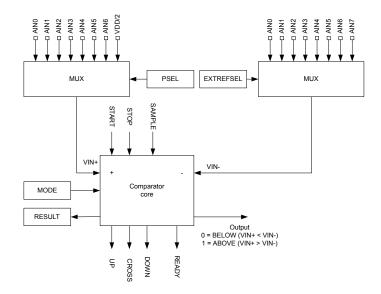


Figure 36: Comparator in differential mode

Restriction: Depending on the device, not all the analog inputs may be available for each MUX. See definitions for PSEL and EXTREFSEL for more information about which analog pins are available on a particular device.

When HYST register is turned on while in this mode, the output of the comparator (and associated events) will change from ABOVE to BELOW whenever VIN+ becomes lower than VIN- - ($V_{DIFFHYST}$ / 2). It will also change from BELOW to ABOVE whenever VIN+ becomes higher than VIN- + ($V_{DIFFHYST}$ / 2). This behavior is illustrated in Hysteresis enabled in differential mode on page 103.

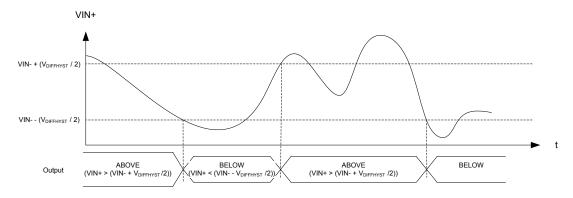


Figure 37: Hysteresis enabled in differential mode

6.5.2 Single-ended mode

In single-ended mode, VIN- is derived from the reference ladder.



Before enabling the comparator via the ENABLE register, the following registers must be configured for the single-ended mode:

- PSEL
- MODE
- REFSEL
- EXTREFSEL
- TH

The reference ladder uses the reference voltage (VREF) to derive two new voltage references, VUP and VDOWN. VUP and VDOWN are configured using THUP and THDOWN respectively in the TH register. VREF can be derived from any of the available reference sources, configured using the EXTREFSEL and REFSEL registers as illustrated in Comparator in single-ended mode on page 104. When AREF is selected in the REFSEL register, the EXTREFSEL register is used to select one of the AINO-AIN7 analog input pins as reference input. The selected analog pins will be acquired by the comparator once it is enabled.

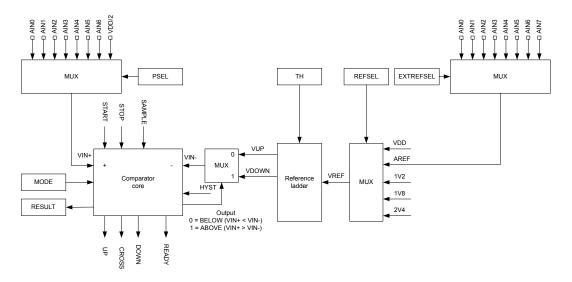


Figure 38: Comparator in single-ended mode

Restriction: Depending on the device, not all the analog inputs may be available for each MUX. See definitions for PSEL and EXTREFSEL for more information about which analog pins are available on a particular device.

When the comparator core detects that VIN+ > VIN-, i.e. ABOVE as per the RESULT register, VIN- will switch to VDOWN. When VIN+ falls below VIN- again, VIN- will be switched back to VUP. By specifying VUP larger than VDOWN, a hysteresis can be generated as illustrated in Hysteresis example where VIN+ starts below VUP on page 105 and Hysteresis example where VIN+ starts above VUP on page 105.

Writing to HYST has no effect in single-ended mode, and the content of this register is ignored.



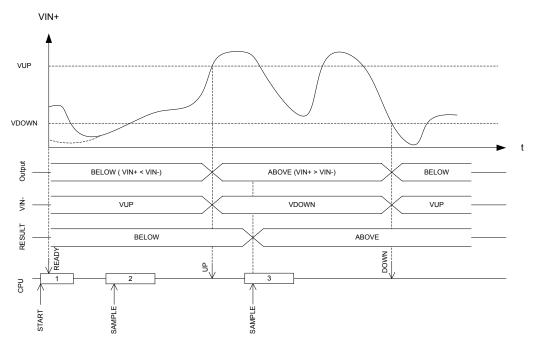


Figure 39: Hysteresis example where VIN+ starts below VUP

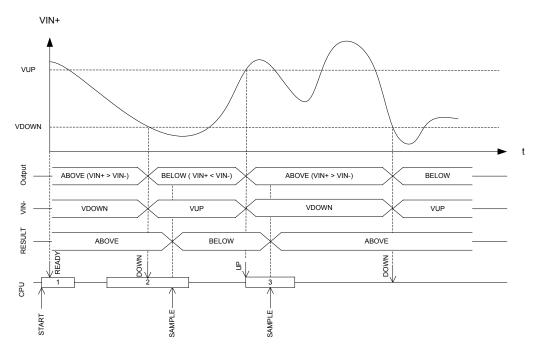


Figure 40: Hysteresis example where VIN+ starts above VUP

6.5.3 Registers

Base address	Peripheral	Instance	Description	Configuration	
0x40013000	COMP	COMP	General purpose comparator		

Table 33: Instances

Register	Offset	Description
TASKS_START	0x000	Start comparator

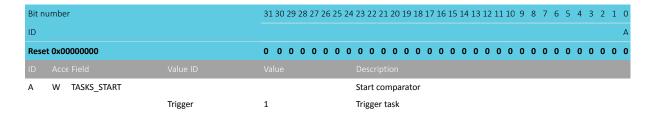


Register	Offset	Description
TASKS_STOP	0x004	Stop comparator
TASKS_SAMPLE	0x008	Sample comparator value
EVENTS_READY	0x100	COMP is ready and output is valid
EVENTS_DOWN	0x104	Downward crossing
EVENTS_UP	0x108	Upward crossing
EVENTS_CROSS	0x10C	Downward or upward crossing
SHORTS	0x200	Shortcuts between local events and tasks
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
RESULT	0x400	Compare result
ENABLE	0x500	COMP enable
PSEL	0x504	Pin select
REFSEL	0x508	Reference source select for single-ended mode
EXTREFSEL	0x50C	External reference select
TH	0x530	Threshold configuration for hysteresis unit
MODE	0x534	Mode configuration
HYST	0x538	Comparator hysteresis enable

Table 34: Register overview

6.5.3.1 TASKS_START

Address offset: 0x000 Start comparator



6.5.3.2 TASKS_STOP

Address offset: 0x004 Stop comparator

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_STOP			Stop comparator
		Trigger	1	Trigger task

6.5.3.3 TASKS_SAMPLE

Address offset: 0x008

Sample comparator value



Bit no	uml	ber			313	30 29	9 2	8 2	7 2	6 2	25	24	23	22	21	L 21	0 1:	9 1	8 1	7 :	16 1	.5	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																																				А
Rese	t Ox	(00	000000		0	0 0	() (0 (כ	0	0	0	0	0	0	0) (0 (כ	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																				
Α	W	,	TASKS_SAMPLE										Sa	mp	le	COI	np	ara	itoi	va	lue	:														
				Trigger	1								Tri	gge	er t	as	k																			

6.5.3.4 EVENTS_READY

Address offset: 0x100

COMP is ready and output is valid

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_READY			COMP is ready and output is valid
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.5.3.5 EVENTS_DOWN

Address offset: 0x104

Downward crossing

Bit n	umber		31 30 29	28 27 2	26 25	24 2	3 22	21 2	0 19	18 1	7 16	15 1	.4 13	12 1	11 10	9	8	7 6	5	4	3	2	1 0
ID																							Α
Rese	et 0x00000000		0 0 0	0 0	0 0	0 (0 0	0 0	0	0 0	0	0	0 0	0	0 0	0	0	0 0	0	0	0	0	0 0
ID																							
Α	RW EVENTS_DOWN					C	own	ward	l cro	ssing													
		NotGenerated	0			Е	vent	not (gene	rated	t												
		Generated	1			Е	vent	gene	erate	d													

6.5.3.6 EVENTS_UP

Address offset: 0x108

Upward crossing

Bit n	umber		31	30	29	28 2	27 2	6 25	5 24	1 23	22	2 2 1	20	19 1	.8 1	7 1	6 15	5 14	13	12 1	111	.0 9	8	7	6	5	4	3	2	1 0
ID																														Α
Rese	et 0x00000000		0	0	0	0	0 (0 0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0 0
ID																														
Α	RW EVENTS_UP									Up	owa	ard o	ros	ssin	3															
		NotGenerated	0							Ev	ent	t no	t ge	ner	ate	d														
		Generated	1							Ev	ent	t ger	nera	ated																

6.5.3.7 EVENTS_CROSS

Address offset: 0x10C

Downward or upward crossing



Bit number		31 30 29 28 27 26 29	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW EVENTS_CROSS			Downward or upward crossing
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.5.3.8 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			EDCBA
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW READY_SAMPLE			Shortcut between event READY and task SAMPLE
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut
B RW READY_STOP			Shortcut between event READY and task STOP
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut
C RW DOWN_STOP			Shortcut between event DOWN and task STOP
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut
D RW UP_STOP			Shortcut between event UP and task STOP
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut
E RW CROSS_STOP			Shortcut between event CROSS and task STOP
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut

6.5.3.9 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW READY			Enable or disable interrupt for event READY
		Disabled	0	Disable
		Enabled	1	Enable
В	RW DOWN			Enable or disable interrupt for event DOWN
		Disabled	0	Disable
		Enabled	1	Enable
С	RW UP			Enable or disable interrupt for event UP
		Disabled	0	Disable
		Enabled	1	Enable
D	RW CROSS			Enable or disable interrupt for event CROSS
		Disabled	0	Disable



D Reset 0x000000000	0 0 0 0 0 0 0
Reset 0x000000000 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0
ID	
	DCBA
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7	6 5 4 3 2 1 0

6.5.3.10 INTENSET

Address offset: 0x304 Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW READY			Write '1' to enable interrupt for event READY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW DOWN			Write '1' to enable interrupt for event DOWN
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW UP			Write '1' to enable interrupt for event UP
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW CROSS			Write '1' to enable interrupt for event CROSS
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.5.3.11 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 (
ID				D C	В А
Res	et 0x00000000 0 0 0 0 0 0 0 0 0 0 0 0 0 0			0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 (
Α	RW READY			Write '1' to disable interrupt for event READY	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
В	RW DOWN			Write '1' to disable interrupt for event DOWN	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
С	RW UP			Write '1' to disable interrupt for event UP	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	



Bit number	3	31 30 29 28 27	26 25 24	4 23 2	22 21	20 1	19 18	3 17	16 1	.5 14	4 13	12 1	1 10	9	8 7	6	5	4	3 2	1	0
ID																			D C	В	Α
Reset 0x00000000	0	0 0 0 0	0 0 0	0	0 0	0	0 0	0	0 (0 0	0	0 (0	0	0 0	0	0	0	0 0	0	0
ID Acce Field Va																					
D RW CROSS				Wri	te '1'	to d	isab	le in	terrı	upt	for e	vent	CRC	OSS							
Cle	ear 1	L		Disa	ble																
Di	sabled 0)		Rea	d: Di	sable	ed														
En	abled 1			Rea	d: En	able	d														

6.5.3.12 RESULT

Address offset: 0x400

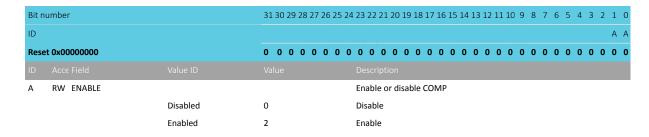
Compare result

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	R RESULT			Result of last compare. Decision point SAMPLE task.
		Below	0	Input voltage is below the threshold (VIN+ < VIN-)
		Above	1	Input voltage is above the threshold (VIN+ > VIN-)

6.5.3.13 ENABLE

Address offset: 0x500

COMP enable

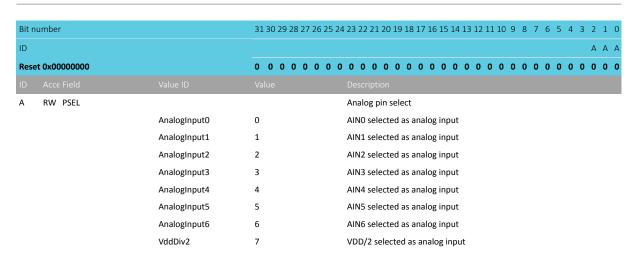


6.5.3.14 PSEL

Address offset: 0x504

Pin select





6.5.3.15 REFSEL

Address offset: 0x508

Reference source select for single-ended mode

Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2			
ID			A A A		
Reset 0x00000004		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID Acce Field					
A RW REFSEL			Reference select		
	Int1V2	0	VREF = internal 1.2 V reference (VDD >= 1.7 V)		
	Int1V8	1	VREF = internal 1.8 V reference (VDD >= VREF + 0.2 V)		
	Int2V4	2	VREF = internal 2.4 V reference (VDD >= VREF + 0.2 V)		
	VDD	4	VREF = VDD		
	ARef	5	VREF = AREF (VDD >= VREF >= AREFMIN)		

6.5.3.16 EXTREFSEL

Address offset: 0x50C
External reference select

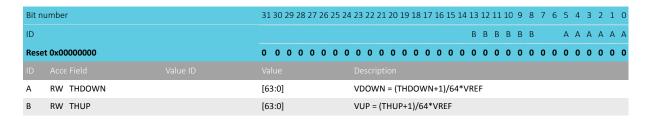
Bit n	umber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3			
ID				ААА		
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID						
Α	RW EXTREFSEL			External analog reference select		
		AnalogReference0	0	Use AINO as external analog reference		
		AnalogReference1	1	Use AIN1 as external analog reference		
		AnalogReference2	2	Use AIN2 as external analog reference		
		AnalogReference3	3	Use AIN3 as external analog reference		
		AnalogReference4	4	Use AIN4 as external analog reference		
		AnalogReference5	5	Use AIN5 as external analog reference		
		AnalogReference6	6 Use AIN6 as external analog reference			
		AnalogReference7	7	Use AIN7 as external analog reference		

6.5.3.17 TH

Address offset: 0x530



Threshold configuration for hysteresis unit



6.5.3.18 MODE

Address offset: 0x534 Mode configuration

Bit n	umber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	
ID			В	
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW SP			Speed and power modes
		Low	0	Low-power mode
		Normal	1	Normal mode
		High	2	High-speed mode
В	RW MAIN			Main operation modes
		SE	0	Single-ended mode
		Diff	1	Differential mode

6.5.3.19 HYST

Address offset: 0x538

Comparator hysteresis enable

Bit number	31 30	29 28 27 26 25 24 23	22 21 20 19 18	17 16 15 14	13 12 11	109	8 7	6 5	4 3	2	1 0
ID											Α
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0	0 0 0 0	0 0 0	0 0	0 0	0 0	0 0	0	0 0
ID Acce Field Va											
A RW HYST		Co	omparator hyste	resis							
No	oHyst 0	Co	Comparator hysteresis disabled								
ну	vst50mV 1	1 Comparator hysteresis enabled									

6.5.4 Electrical specification

6.5.4.1 COMP Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{PROPDLY,LP}	Propagation delay, low-power mode ^a		0.6		μS
t _{PROPDLY,N}	Propagation delay, normal mode ^a		0.2		μS
t _{PROPDLY,HS}	Propagation delay, high-speed mode ^a		0.1		μS
$V_{DIFFHYST}$	Optional hysteresis applied to differential input		30		mV

^a Propagation delay is with 10 mV overdrive.



Symbol	Description	Min.	Тур.	Max.	Units
V _{VDD-VREF}	Required difference between VDD and a selected VREF, VDD	0.3			V
	> VREF				
t _{INT_REF,START}	Startup time for the internal bandgap reference		50	80	μS
E _{INT_REF}	Internal bandgap reference error	-3		3	%
V _{INPUTOFFSET}	Input offset	-10		10	mV
t _{COMP,START}	Startup time for the comparator core		3		μS

6.6 ECB — AES electronic codebook mode encryption

The AES electronic codebook mode encryption (ECB) can be used for a range of cryptographic functions like hash generation, digital signatures, and keystream generation for data encryption/decryption. The ECB encryption block supports 128 bit AES encryption (encryption only, not decryption).

AES ECB operates with EasyDMA access to system Data RAM for in-place operations on cleartext and ciphertext during encryption. ECB uses the same AES core as the CCM and AAR blocks and is an asynchronous operation which may not complete if the AES core is busy.

AES ECB features:

- 128 bit AES encryption
- Supports standard AES ECB block encryption
- Memory pointer support
- DMA data transfer

AES ECB performs a 128 bit AES block encrypt. At the STARTECB task, data and key is loaded into the algorithm by EasyDMA. When output data has been written back to memory, the ENDECB event is triggered.

AES ECB can be stopped by triggering the STOPECB task.

6.6.1 Shared resources

The ECB, CCM, and AAR share the same AES module. The ECB will always have lowest priority and if there is a sharing conflict during encryption, the ECB operation will be aborted and an ERRORECB event will be generated.

6.6.2 EasyDMA

The ECB implements an EasyDMA mechanism for reading and writing to the Data RAM. This DMA cannot access the program memory or any other parts of the memory area except RAM.

If the ECBDATAPTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

The EasyDMA will have finished accessing the Data RAM when the ENDECB or ERRORECB is generated.

6.6.3 ECB data structure

Input to the block encrypt and output from the block encrypt are stored in the same data structure. ECBDATAPTR should point to this data structure before STARTECB is initiated.

Property	Address offset	Description
KEY	0	16 byte AES key
CLEARTEXT	16	16 byte AES cleartext input block
CIPHERTEXT	32	16 byte AES ciphertext output block

Table 35: ECB data structure overview



6.6.4 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4000E000	ECB	ECB	AES Electronic Codebook (ECB) mode	
			block encryption	

Table 36: Instances

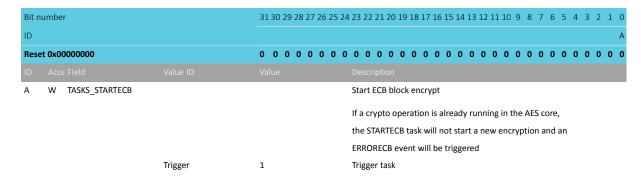
Register	Offset	Description
TASKS_STARTECB	0x000	Start ECB block encrypt
TASKS_STOPECB	0x004	Abort a possible executing ECB operation
EVENTS_ENDECB	0x100	ECB block encrypt complete
EVENTS_ERRORECB	0x104	ECB block encrypt aborted because of a STOPECB task or due to an error
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ECBDATAPTR	0x504	ECB block encrypt memory pointers

Table 37: Register overview

6.6.4.1 TASKS_STARTECB

Address offset: 0x000 Start ECB block encrypt

If a crypto operation is already running in the AES core, the STARTECB task will not start a new encryption and an ERRORECB event will be triggered

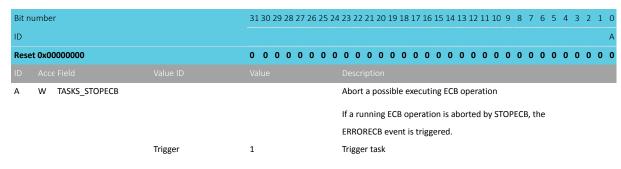


6.6.4.2 TASKS_STOPECB

Address offset: 0x004

Abort a possible executing ECB operation

If a running ECB operation is aborted by STOPECB, the ERRORECB event is triggered.

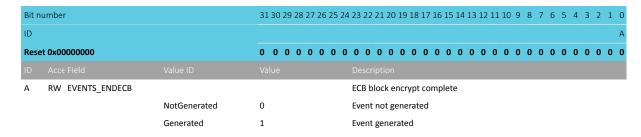




6.6.4.3 EVENTS_ENDECB

Address offset: 0x100

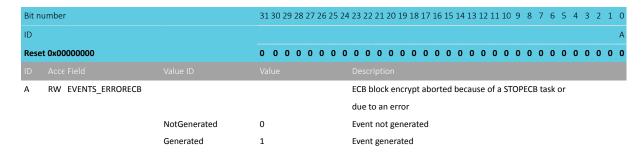
ECB block encrypt complete



6.6.4.4 EVENTS ERRORECB

Address offset: 0x104

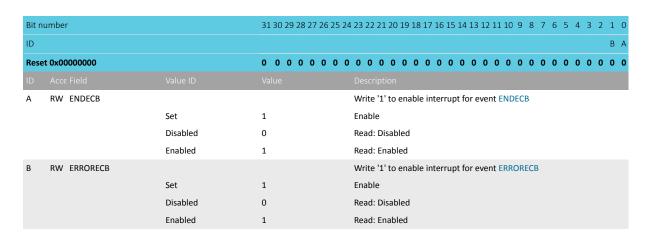
ECB block encrypt aborted because of a STOPECB task or due to an error



6.6.4.5 INTENSET

Address offset: 0x304

Enable interrupt

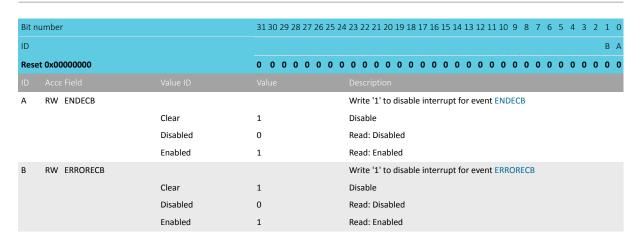


6.6.4.6 INTENCLR

Address offset: 0x308

Disable interrupt





6.6.4.7 ECBDATAPTR

Address offset: 0x504

ECB block encrypt memory pointers

Bit r	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		
Α	RW ECBDATAPTR	Pointer to the ECB data structure (see Table 1 ECB data
		structure overview)

6.6.5 Electrical specification

6.6.5.1 ECB Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{ECB}	Run time per 16 byte block in all modes		6		μs

6.7 EGU — Event generator unit

Event generator unit (EGU) provides support for interlayer signaling. This means providing support for atomic triggering of both CPU execution and hardware tasks, from both firmware (by CPU) and hardware (by PPI). This feature can, for instance, be used for triggering CPU execution at a lower priority execution from a higher priority execution, or to handle a peripheral's interrupt service routine (ISR) execution at a lower priority for some of its events. However, triggering any priority from any priority is possible.

Listed here are the main EGU features:

- · Software-enabled interrupt triggering
- Separate interrupt vectors for every EGU instance
- Up to 16 separate event flags per interrupt for multiplexing

Each instance of EGU implements a set of tasks which can individually be triggered to generate the corresponding event, for example, the corresponding event for TASKS_TRIGGER[n] is EVENTS_TRIGGERED[n]. See Instances on page 117 for a list of EGU instances.



6.7.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40014000	EGU	EGU0	Event generator unit 0	
0x40015000	EGU	EGU1	Event generator unit 1	

Table 38: Instances

Register	Offset	Description
TASKS_TRIGGER[0]	0x000	Trigger 0 for triggering the corresponding TRIGGERED[0] event
TASKS_TRIGGER[1]	0x004	Trigger 1 for triggering the corresponding TRIGGERED[1] event
TASKS_TRIGGER[2]	0x008	Trigger 2 for triggering the corresponding TRIGGERED[2] event
TASKS_TRIGGER[3]	0x00C	Trigger 3 for triggering the corresponding TRIGGERED[3] event
TASKS_TRIGGER[4]	0x010	Trigger 4 for triggering the corresponding TRIGGERED[4] event
TASKS_TRIGGER[5]	0x014	Trigger 5 for triggering the corresponding TRIGGERED[5] event
TASKS_TRIGGER[6]	0x018	Trigger 6 for triggering the corresponding TRIGGERED[6] event
TASKS_TRIGGER[7]	0x01C	Trigger 7 for triggering the corresponding TRIGGERED[7] event
TASKS_TRIGGER[8]	0x020	Trigger 8 for triggering the corresponding TRIGGERED[8] event
TASKS_TRIGGER[9]	0x024	Trigger 9 for triggering the corresponding TRIGGERED[9] event
TASKS_TRIGGER[10]	0x028	Trigger 10 for triggering the corresponding TRIGGERED[10] event
TASKS_TRIGGER[11]	0x02C	Trigger 11 for triggering the corresponding TRIGGERED[11] event
TASKS_TRIGGER[12]	0x030	Trigger 12 for triggering the corresponding TRIGGERED[12] event
TASKS_TRIGGER[13]	0x034	Trigger 13 for triggering the corresponding TRIGGERED[13] event
TASKS_TRIGGER[14]	0x038	Trigger 14 for triggering the corresponding TRIGGERED[14] event
TASKS_TRIGGER[15]	0x03C	Trigger 15 for triggering the corresponding TRIGGERED[15] event
EVENTS_TRIGGERED[0]	0x100	Event number 0 generated by triggering the corresponding TRIGGER[0] task
EVENTS_TRIGGERED[1]	0x104	Event number 1 generated by triggering the corresponding TRIGGER[1] task
EVENTS_TRIGGERED[2]	0x108	Event number 2 generated by triggering the corresponding TRIGGER[2] task
EVENTS_TRIGGERED[3]	0x10C	Event number 3 generated by triggering the corresponding TRIGGER[3] task
EVENTS_TRIGGERED[4]	0x110	Event number 4 generated by triggering the corresponding TRIGGER[4] task
EVENTS_TRIGGERED[5]	0x114	Event number 5 generated by triggering the corresponding TRIGGER[5] task
EVENTS_TRIGGERED[6]	0x118	Event number 6 generated by triggering the corresponding TRIGGER[6] task
EVENTS_TRIGGERED[7]	0x11C	Event number 7 generated by triggering the corresponding TRIGGER[7] task
EVENTS_TRIGGERED[8]	0x120	Event number 8 generated by triggering the corresponding TRIGGER[8] task
EVENTS_TRIGGERED[9]	0x124	Event number 9 generated by triggering the corresponding TRIGGER[9] task
EVENTS_TRIGGERED[10]	0x128	Event number 10 generated by triggering the corresponding TRIGGER[10] task
EVENTS_TRIGGERED[11]	0x12C	Event number 11 generated by triggering the corresponding TRIGGER[11] task
EVENTS_TRIGGERED[12]	0x130	Event number 12 generated by triggering the corresponding TRIGGER[12] task
EVENTS_TRIGGERED[13]	0x134	Event number 13 generated by triggering the corresponding TRIGGER[13] task
EVENTS_TRIGGERED[14]	0x138	Event number 14 generated by triggering the corresponding TRIGGER[14] task
EVENTS_TRIGGERED[15]	0x13C	Event number 15 generated by triggering the corresponding TRIGGER[15] task
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt

Table 39: Register overview

6.7.1.1 TASKS_TRIGGER[n] (n=0..15)

Address offset: $0x000 + (n \times 0x4)$

Trigger n for triggering the corresponding TRIGGERED[n] event



Bit number	31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field		Description
A W TASKS_TRIGGER		Trigger n for triggering the corresponding TRIGGERED[n]
		event
		eveni

6.7.1.2 EVENTS_TRIGGERED[n] (n=0..15)

Address offset: $0x100 + (n \times 0x4)$

Event number n generated by triggering the corresponding TRIGGER[n] task

Bit n	umber		31 30 29 28 27 26	25 24	23 :	22 2	21 20) 19	18	17	16	15	14 1	13 1	2 11	10	9	8	7	6	5	4	3 2	1	0
ID																									Α
Rese	t 0x00000000		0 0 0 0 0 0	0 0	0	0 (0 0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0	0
ID																									
Α	RW EVENTS_TRIGGERED				Eve	ent n	numl	ber	n g	ene	rat	ed l	by t	rigg	erin	g th	e co	orre	sp	ond	ling				
					TRI	GGE	R[n] ta	sk																
		NotGenerated	0		Eve	ent n	not g	gene	erat	ed															
		Generated	1		Eve	ent g	gene	rate	ed																

6.7.1.3 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	ımber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16	15 14	13 12	11 10	9	8 7	6	5	4 3	2	1 0
ID					РО	N M	L K	J	T F	I G	F	E D	С	ВА
Rese	0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0	0 0	0 0	0 0	0	0 0	0	0	0 0	0	0 0
ID														
A-P	RW TRIGGERED[i] (i=015)			Enable or disable interre	upt for	event	TRIG	GER	ED[i]					
		Disabled	0	Disable										
		Enabled	1	Enable										

6.7.1.4 INTENSET

Address offset: 0x304

Enable interrupt

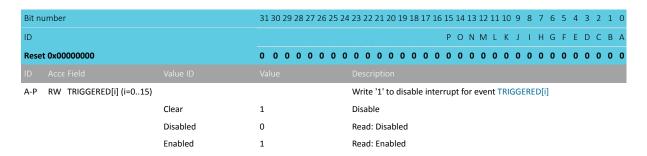
Bit number		31 30 29	28 27	7 26	25	24 2	23 2	2 2	1 20	0 19	18	17	16	15	14	13	12	11 :	10	9	8 7	7 (5 5	4	3	2	1 ()
ID														Р	0	N	М	L	K	J	I F	1 (3 F	Е	D	С	В	
Reset 0x00000000		0 0 0	0 0	0	0	0	0 0) (0	0	0	0	0	0	0	0	0	0	0	0	0 () () (0	0	0	0 ()
ID Acce Field							Desc																					ı
A-P RW TRIGGERED[i] (i=015)						١	Writ	e '1	l' to	en	abl	e ir	iter	rup	t fo	or e	ven	t TF	RIG	GEF	RED	[i]						
	Set	1				-	Enat	ole																				
	Disabled	0				-	Read	d: D	isal	ble	t																	
	Enabled	4					Read																					

6.7.1.5 INTENCLR

Address offset: 0x308



Disable interrupt



6.7.2 Electrical specification

6.7.2.1 EGU Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{EGU,EVT}	Latency between setting an EGU event flag and the system		1		cycles
	setting an interrupt				

6.8 GPIO — General purpose input/output

The general purpose input/output pins (GPIOs) are grouped as one or more ports, with each port having up to 32 GPIOs.

The number of ports and GPIOs per port might vary with product variant and package. Refer to Registers on page 121 and Pin assignments on page 389 for more information about the number of GPIOs that are supported.

GPIO has the following user-configurable features:

- Up to 32 GPIO pins per GPIO port
- · Configurable output drive strength
- Internal pull-up and pull-down resistors
- Wake-up from high or low level triggers on all pins
- Trigger interrupt on state changes on any pin
- All pins can be used by the PPI task/event system
- One or more GPIO outputs can be controlled through the PPI and GPIOTE channels
- Any pin can be mapped to a peripheral for layout flexibility
- GPIO state changes captured on the SENSE signal can be stored by the LATCH register

The GPIO port peripheral implements up to 32 pins, PIN0 through PIN31. Each of these pins can be individually configured in the PIN_CNF[n] registers (n=0..31).

The following parameters can be configured through these registers:

- Direction
- Drive strength
- Enabling of pull-up and pull-down resistors
- Pin sensing
- · Input buffer disconnect
- · Analog input (for selected pins)

The PIN_CNF registers are retained registers. See POWER — Power supply on page 52 chapter for more information about retained registers.



6.8.1 Pin configuration

Pins can be individually configured through the SENSE field in the PIN_CNF[n] register to detect either a high or low level input.

When the correct level is detected on a configured pin, the sense mechanism will set the DETECT signal high. Each pin has a separate DETECT signal. Default behavior, defined by the DETECTMODE register, combines all DETECT signals from the pins in the GPIO port into one common DETECT signal and routes it through the system to be utilized by other peripherals. This mechanism is functional in both System ON and System OFF mode. See GPIO port and the GPIO pin details on page 120.

The following figure illustrates the GPIO port containing 32 individual pins, where PINO is shown in more detail for reference. All signals on the left side of the illustration are used by other peripherals in the system and therefore not directly available to the CPU.

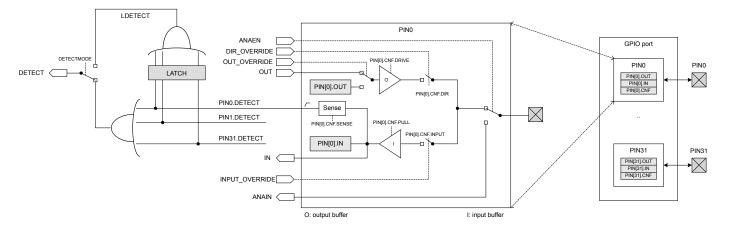


Figure 41: GPIO port and the GPIO pin details

Pins should be in a level that cannot trigger the sense mechanism before being enabled. If the SENSE condition configured in the PIN_CNF registers is met when the sense mechanism is enabled, the DETECT signal will immediately go high. A PORT event is triggered if the DETECT signal was low before enabling the sense mechanism. See GPIOTE — GPIO tasks and events on page 127.

See the following peripherals for more information about how the DETECT signal is used:

- POWER Power supply on page 52 uses the DETECT signal to exit from System OFF mode.
- GPIOTE GPIO tasks and events on page 127 uses the DETECT signal to generate the PORT event.

When a pin's PINx.DETECT signal goes high, a flag is set in the LATCH register. For example, when the PIN0.DETECT signal goes high, bit 0 in the LATCH register is set to '1'. If the CPU performs a clear operation on a bit in the LATCH register when the associated PINx.DETECT signal is high, the bit in the LATCH register will not be cleared. The LATCH register will only be cleared if the CPU explicitly clears it by writing a '1' to the bit that shall be cleared, i.e. the LATCH register will not be affected by a PINx.DETECT signal being set low

The LDETECT signal will be set high when one or more bits in the LATCH register are '1'. The LDETECT signal will be set low when all bits in the LATCH register are successfully cleared to '0'.

If one or more bits in the LATCH register are '1' after the CPU has performed a clear operation on the LATCH register, a rising edge will be generated on the LDETECT signal. This is illustrated in DETECT signal behavior on page 121.

Note: The CPU can read the LATCH register at any time to check if a SENSE condition has been met on one or more of the the GPIO pins, even if that condition is no longer met at the time the CPU queries the LATCH register. This mechanism will work even if the LDETECT signal is not used as the DETECT signal.



The LDETECT signal is by default not connected to the GPIO port's DETECT signal, but via the DETECTMODE register. It is possible to change from default behavior to the DETECT signal that is derived directly from the LDETECT signal. See GPIO port and the GPIO pin details on page 120. The following figure illustrates the DETECT signal behavior for these two alternatives.

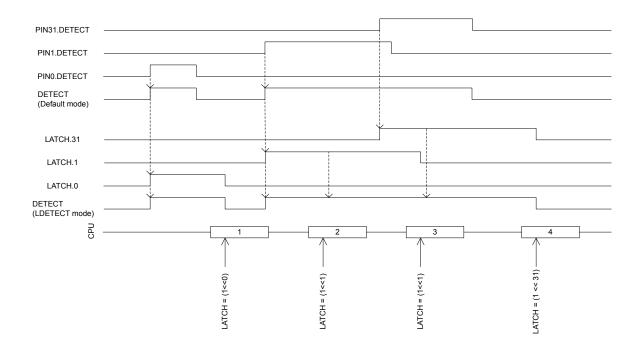


Figure 42: DETECT signal behavior

The input buffer of a GPIO pin can be disconnected from the pin to enable power savings when the pin is not used as an input, see GPIO port and the GPIO pin details on page 120. Input buffers must be connected to get a valid input value in the IN register, and for the sense mechanism to get access to the pin.

Other peripherals in the system can connect to GPIO pins and override their output value and configuration, or read their analog or digital input value. See GPIO port and the GPIO pin details on page 120.

Selected pins also support analog input signals, see ANAIN in GPIO port and the GPIO pin details on page 120. The assignment of the analog pins can be found in Pin assignments on page 389.

Note: When a pin is configured as digital input, increased current consumption occurs when the input voltage is between V_{IL} and V_{IH} . It is good practice to ensure that the external circuitry does not drive that pin to levels between V_{IL} and V_{IH} for a long period of time.

6.8.2 Registers

Base address	Peripheral	Instance	Description	Configuration
0x50000000	GPIO	P0	General purpose input and output	

Table 40: Instances

Register	Offset	Description
OUT	0x504	Write GPIO port



Register	Offset	Description
OUTSET	0x508	Set individual bits in GPIO port
OUTCLR	0x50C	Clear individual bits in GPIO port
IN	0x510	Read GPIO port
DIR	0x514	Direction of GPIO pins
DIRSET	0x518	DIR set register
DIRCLR	0x51C	DIR clear register
LATCH	0x520	Latch register indicating what GPIO pins that have met the criteria set in the PIN_CNF[n].SENSE
		registers
DETECTMODE	0x524	Select between default DETECT signal behaviour and LDETECT mode
PIN_CNF[0]	0x700	Configuration of GPIO pins
PIN_CNF[1]	0x704	Configuration of GPIO pins
PIN_CNF[2]	0x708	Configuration of GPIO pins
PIN_CNF[3]	0x70C	Configuration of GPIO pins
PIN_CNF[4]	0x710	Configuration of GPIO pins
PIN_CNF[5]	0x714	Configuration of GPIO pins
PIN_CNF[6]	0x718	Configuration of GPIO pins
PIN_CNF[7]	0x71C	Configuration of GPIO pins
PIN_CNF[8]	0x720	Configuration of GPIO pins
PIN_CNF[9]	0x724	Configuration of GPIO pins
PIN_CNF[10]	0x728	Configuration of GPIO pins
PIN_CNF[11]	0x72C	Configuration of GPIO pins
PIN_CNF[12]	0x730	Configuration of GPIO pins
PIN_CNF[13]	0x734	Configuration of GPIO pins
PIN_CNF[14]	0x738	Configuration of GPIO pins
PIN_CNF[15]	0x73C	Configuration of GPIO pins
PIN_CNF[16]	0x740	Configuration of GPIO pins
PIN_CNF[17]	0x744	Configuration of GPIO pins
PIN_CNF[18]	0x748	Configuration of GPIO pins
PIN_CNF[19]	0x74C	Configuration of GPIO pins
PIN_CNF[20]	0x750	Configuration of GPIO pins
PIN_CNF[21]	0x754	Configuration of GPIO pins
PIN_CNF[22]	0x758	Configuration of GPIO pins
PIN_CNF[23]	0x75C	Configuration of GPIO pins
PIN_CNF[24]	0x760	Configuration of GPIO pins
PIN_CNF[25]	0x764	Configuration of GPIO pins
PIN_CNF[26]	0x768	Configuration of GPIO pins
PIN_CNF[27]	0x76C	Configuration of GPIO pins
PIN_CNF[28]	0x770	Configuration of GPIO pins
PIN_CNF[29]	0x774	Configuration of GPIO pins
PIN_CNF[30]	0x778	Configuration of GPIO pins
PIN_CNF[31]	0x77C	Configuration of GPIO pins

Table 41: Register overview

6.8.2.1 OUT

Address offset: 0x504

Write GPIO port



Bit number		31 30 29 28 27 2	5 25 24	23 22 21	20 19	18 17	16 19	5 14 1	3 12 1	11 10	9	8 7	' 6	5	4	3 2	1 0
ID		fedcba	ΖY	x w v	U T	S R	Q P	1 0	I M	L K	J	I F	l G	F	Ε	D (ВА
Reset 0x00000000		0 0 0 0 0	0 0	0 0 0	0 0	0 0	0 0	0 (0	0 0	0	0 (0	0	0	0 (0 0
ID Acce Field																	
A-f RW PIN[i] (i=031)				Pin i													
	Low	0		Pin drive	er is lov	v											

6.8.2.2 OUTSET

Address offset: 0x508

Set individual bits in GPIO port

Read: reads value of OUT register.

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			f edcbaZ	Y X W V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
A-f	RW PIN[i] (i=031)			Pin i
		Low	0	Read: pin driver is low
		High	1	Read: pin driver is high
		Set	1	Write: writing a '1' sets the pin high; writing a '0' has no
				effect

6.8.2.3 **OUTCLR**

Address offset: 0x50C

Clear individual bits in GPIO port

Read: reads value of OUT register.

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			fedcbaZ'	Y X W V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
A-f	RW PIN[i] (i=031)			Pin i
		Low	0	Read: pin driver is low
		High	1	Read: pin driver is high
		Clear	1	Write: writing a '1' sets the pin low; writing a '0' has no
				effect

6.8.2.4 IN

Address offset: 0x510

Read GPIO port



Bit number		31 30	29	28 2	27 2	6 25	5 24	23	22 2	1 20	19 :	18 17	7 16	15	14 1	3 12	11 10	9	8	7	6	5	4	3 2	1 0
ID		f e	d	С	b a	a Z	Υ	Χ	w v	/ U	Т	S R	Q	Р	0 N	М	L K	J	1	Н	G	F	Ε	D C	ВА
Reset 0x00000000		0 0	0	0	0 (0	0	0	0 0	0 0	0	0 0	0	0	0 0	0	0 0	0	0	0	0	0	0	0 0	0 0
ID Acce Field																									
A-f R PIN[i] (i=031)								Pin	i				Т	Т		Т		Т	Т				Т		
A-f R PIN[i] (i=031)	Low	0								ut is l	low				Π			Π		Ī	Ī	Ī			Π

6.8.2.5 DIR

Address offset: 0x514 Direction of GPIO pins

Bit number		313	30 2	9 2	28 2	7 2	6 25	5 24	4 2	3 2:	2 2	1 20	19	18	17	16	15	14 :	13 1	2 1	1 10	9	8	7	6	5	4	3	2 :	1 0
ID		f	e d	d (c b	а	Z	. Y	′ >	< V	/ V	/ U	Т	S	R	Q	Р	О	N N	ИL	K	J	1	Н	G	F	Ε	D	C I	ВА
Reset 0x00000000		0	0 () (0 0	0	0	0) (0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0 (0 0
ID Acce Field																														
A-f RW PIN[i] (i=031)									Р	in i																				
	Input	0							P	in s	et a	as ir	npu	t																
	Output	1							Р	in s	et a	as o	utp	ut																

6.8.2.6 DIRSET

Address offset: 0x518

DIR set register

Read: reads value of DIR register.

Bit n	umber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			fedcbaZYXWVUTSRQPONMLKJIHGFEDCB
Rese	et 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			
A-f	RW PIN[i] (i=031)		Set as output pin i
		Input	0 Read: pin set as input
		Output	1 Read: pin set as output
		Set	1 Write: writing a '1' sets pin to output; writing a '0' has no
			effect

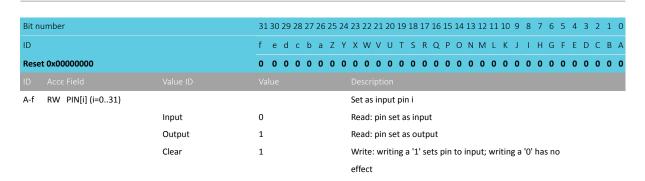
6.8.2.7 DIRCLR

Address offset: 0x51C

DIR clear register

Read: reads value of DIR register.

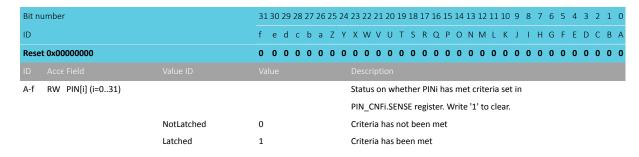




6.8.2.8 LATCH

Address offset: 0x520

Latch register indicating what GPIO pins that have met the criteria set in the PIN_CNF[n].SENSE registers



6.8.2.9 DETECTMODE

Address offset: 0x524

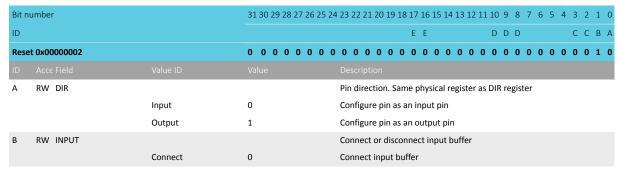
Select between default DETECT signal behaviour and LDETECT mode

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW DETECTMODE			Select between default DETECT signal behaviour and
				LDETECT mode
		Default	0	DETECT directly connected to PIN DETECT signals
		LDETECT	1	Use the latched LDETECT behaviour

6.8.2.10 PIN_CNF[n] (n=0..31)

Address offset: $0x700 + (n \times 0x4)$

Configuration of GPIO pins





Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			E E D D D C C B A
Reset 0x00000002		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	Disconnect	1	Disconnect input buffer
C RW PULL			Pull configuration
	Disabled	0	No pull
	Pulldown	1	Pull down on pin
	Pullup	3	Pull up on pin
D RW DRIVE			Drive configuration
	S0S1	0	Standard '0', standard '1'
	H0S1	1	High drive '0', standard '1'
	S0H1	2	Standard '0', high drive '1'
	H0H1	3	High drive '0', high 'drive '1"
	DOS1	4	Disconnect '0' standard '1' (normally used for wired-or
			connections)
	D0H1	5	Disconnect '0', high drive '1' (normally used for wired-or
			connections)
	SOD1	6	Standard '0'. disconnect '1' (normally used for wired-and
			connections)
	H0D1	7	High drive '0', disconnect '1' (normally used for wired-and
			connections)
E RW SENSE			Pin sensing mechanism
	Disabled	0	Disabled
	High	2	Sense for high level
	Low	3	Sense for low level

6.8.3 Electrical specification

6.8.3.1 GPIO Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
V _{IH}	Input high voltage	0.7 x		VDD	V
		VDD			
V_{IL}	Input low voltage	VSS		0.3 x	V
				VDD	
$V_{\text{OH,SD}}$	Output high voltage, standard drive, 0.5 mA, VDD \geq 1.7	VDD-0	.4	VDD	V
V _{OH,HDH}	Output high voltage, high drive, 5 mA, VDD \geq 2.7 V	VDD-0	.4	VDD	V
$V_{OH,HDL}$	Output high voltage, high drive, 3 mA, VDD \geq 1.7 V	VDD-0	.4	VDD	V
$V_{OL,SD}$	Output low voltage, standard drive, 0.5 mA, VDD ≥ 1.7	VSS		VSS+0.4	V
$V_{OL,HDH}$	Output low voltage, high drive, 5 mA, VDD ≥ 2.7 V	VSS		VSS+0.4	V
$V_{OL,HDL}$	Output low voltage, high drive, 3 mA, VDD ≥ 1.7 V	VSS		VSS+0.4	V
$I_{OL,SD}$	Current at VSS+0.4 V, output set low, standard drive, VDD ≥	1	2	4	mA
	1.7				
I _{OL,HDH}	Current at VSS+0.4 V, output set low, high drive, VDD \geq 2.7 V	6	10	15	mA
$I_{OL,HDL}$	Current at VSS+0.4 V, output set low, high drive, VDD \geq 1.7 V	3			mA
I _{OH,SD}	Current at VDD-0.4 V, output set high, standard drive, VDD	1	2	4	mA
	≥ 1.7				
I _{OH,HDH}	Current at VDD-0.4 V, output set high, high drive, VDD ≥ 2.7	6	9	14	mA
	V				
I _{OH,HDL}	Current at VDD-0.4 V, output set high, high drive, VDD ≥ 1.7	3			mA
	V				



Symbol	Description	Min.	Тур.	Max.	Units
t _{RF,15pF}	Rise/fall time, standard drive mode, 10-90%, 15 pF load 1		9		ns
t _{RF,25pF}	Rise/fall time, standard drive mode, 10-90%, 25 pF load ¹		13		ns
t _{RF,50pF}	Rise/fall time, standard drive mode, 10-90%, 50 pF load ¹		25		ns
t _{HRF,15pF}	Rise/Fall time, high drive mode, 10-90%, 15 pF load ¹		4		ns
t _{HRF,25pF}	Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹		5		ns
t _{HRF,50pF}	Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹		8		ns
R _{PU}	Pull-up resistance	11	13	16	kΩ
R_{PD}	Pull-down resistance	11	13	16	kΩ
C _{PAD}	Pad capacitance		3		pF

6.9 GPIOTE — GPIO tasks and events

The GPIO tasks and events (GPIOTE) module provides functionality for accessing GPIO pins using tasks and events. Each GPIOTE channel can be assigned to one pin.

A GPIOTE block enables GPIOs to generate events on pin state change which can be used to carry out tasks through the PPI system. A GPIO can also be driven to change state on system events using the PPI system. Low power detection of pin state changes is possible when in System ON or System OFF.

Instance	Number of GPIOTE channels
GPIOTE	8

Table 42: GPIOTE properties

Up to three tasks can be used in each GPIOTE channel for performing write operations to a pin. Two tasks are fixed (SET and CLR), and one (OUT) is configurable to perform following operations:

- Set
- Clear
- Toggle

An event can be generated in each GPIOTE channel from one of the following input conditions:

- · Rising edge
- · Falling edge
- Any change

6.9.1 Pin events and tasks

The GPIOTE module has a number of tasks and events that can be configured to operate on individual GPIO pins.

The tasks (SET[n], CLR[n] and OUT[n]) can be used for writing to individual pins, and the events (IN[n]) can be generated from changes occurring at the inputs of individual pins.

The SET task will set the pin selected in CONFIG[n]. PSEL to high.

The CLR task will set the pin low.

The effect of the OUT task on the pin is configurable in CONFIG[n].POLARITY, and can either set the pin high, set it low, or toggle it.

The tasks and events are configured using the CONFIG[n] registers. Every set of SET, CLR and OUT[n] tasks and IN[n] events has one CONFIG[n] register associated with it.



¹ Rise and fall times based on simulations

As long as a SET[n], CLR[n] and OUT[n] task or an IN[n] event is configured to control a pin **n**, the pin's output value will only be updated by the GPIOTE module. The pin's output value as specified in the GPIO will therefore be ignored as long as the pin is controlled by GPIOTE. Attempting to write a pin as a normal GPIO pin will have no effect. When the GPIOTE is disconnected from a pin, see MODE field in CONFIG[n] register, the associated pin will get the output and configuration values specified in the GPIO module.

When conflicting tasks are triggered simultaneously (i.e. during the same clock cycle) in one channel, the precedence of the tasks will be as described in Task priorities on page 128.

Priority	Task
1	OUT
2	CLR
3	SET

Table 43: Task priorities

When setting the CONFIG[n] registers, MODE=Disabled does not have the same effect as MODE=Task and POLARITY=None. In the latter case, a CLR or SET task occurring at the exact same time as OUT will end up with no change on the pin, according to the priorities described in the table above.

When a GPIOTE channel is configured to operate on a pin as a task, the initial value of that pin is configured in the OUTINIT field of CONFIG[n].

6.9.2 Port event

PORT is an event that can be generated from multiple input pins using the GPIO DETECT signal.

The event will be generated on the rising edge of the DETECT signal. See GPIO — General purpose input/output on page 119 for more information about the DETECT signal.

Putting the system into System ON IDLE while DETECT is high will not cause DETECT to wake the system up again. Make sure to clear all DETECT sources before entering sleep. If the LATCH register is used as a source, if any bit in LATCH is still high after clearing all or part of the register (for instance due to one of the PINx.DETECT signal still high), a new rising edge will be generated on DETECT, see Pin configuration on page 120.

Trying to put the system to System OFF while DETECT is high will cause a wakeup from System OFF reset.

This feature is always enabled although the peripheral itself appears to be IDLE, that is, no clocks or other power intensive infrastructure have to be requested to keep this feature enabled. This feature can therefore be used to wake up the CPU from a WFI or WFE type sleep in System ON with all peripherals and the CPU idle, that is, lowest power consumption in System ON mode.

In order to prevent spurious interrupts from the PORT event while configuring the sources, the user shall first disable interrupts on the PORT event (through INTENCLR.PORT), then configure the sources (PIN_CNF[n].SENSE), clear any potential event that could have occurred during configuration (write '0' to EVENTS_PORT), and finally enable interrupts (through INTENSET.PORT).

6.9.3 Tasks and events pin configuration

Each GPIOTE channel is associated with one physical GPIO pin through the CONFIG.PSEL field.

When Event mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an input, overriding the DIR setting in GPIO. Similarly, when Task mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an output overriding the DIR setting and OUT value in GPIO. When Disabled is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will use its configuration from the PIN[n].CNF registers in GPIO.

Only one GPIOTE channel can be assigned to one physical pin. Failing to do so may result in unpredictable behavior.



6.9.4 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40006000	GPIOTE	GPIOTE	GPIO tasks and events	

Table 44: Instances

Register	Offset	Description
TASKS_OUT[0]	0x000	Task for writing to pin specified in CONFIG[0].PSEL. Action on pin is configured in
		CONFIG[0].POLARITY.
TASKS_OUT[1]	0x004	Task for writing to pin specified in CONFIG[1].PSEL. Action on pin is configured in
		CONFIG[1].POLARITY.
TASKS_OUT[2]	0x008	Task for writing to pin specified in CONFIG[2].PSEL. Action on pin is configured in
		CONFIG[2].POLARITY.
TASKS_OUT[3]	0x00C	Task for writing to pin specified in CONFIG[3].PSEL. Action on pin is configured in
		CONFIG[3].POLARITY.
TASKS_OUT[4]	0x010	Task for writing to pin specified in CONFIG[4].PSEL. Action on pin is configured in
		CONFIG[4].POLARITY.
TASKS_OUT[5]	0x014	Task for writing to pin specified in CONFIG[5].PSEL. Action on pin is configured in
		CONFIG[5].POLARITY.
TASKS_OUT[6]	0x018	Task for writing to pin specified in CONFIG[6].PSEL. Action on pin is configured in
		CONFIG[6].POLARITY.
TASKS_OUT[7]	0x01C	Task for writing to pin specified in CONFIG[7].PSEL. Action on pin is configured in
		CONFIG[7].POLARITY.
TASKS_SET[0]	0x030	Task for writing to pin specified in CONFIG[0].PSEL. Action on pin is to set it high.
TASKS_SET[1]	0x034	Task for writing to pin specified in CONFIG[1].PSEL. Action on pin is to set it high.
TASKS_SET[2]	0x038	Task for writing to pin specified in CONFIG[2].PSEL. Action on pin is to set it high.
TASKS_SET[3]	0x03C	Task for writing to pin specified in CONFIG[3].PSEL. Action on pin is to set it high.
TASKS_SET[4]	0x040	Task for writing to pin specified in CONFIG[4].PSEL. Action on pin is to set it high.
TASKS_SET[5]	0x044	Task for writing to pin specified in CONFIG[5].PSEL. Action on pin is to set it high.
TASKS_SET[6]	0x048	Task for writing to pin specified in CONFIG[6].PSEL. Action on pin is to set it high.
TASKS_SET[7]	0x04C	Task for writing to pin specified in CONFIG[7].PSEL. Action on pin is to set it high.
TASKS_CLR[0]	0x060	Task for writing to pin specified in CONFIG[0].PSEL. Action on pin is to set it low.
TASKS_CLR[1]	0x064	Task for writing to pin specified in CONFIG[1].PSEL. Action on pin is to set it low.
TASKS_CLR[2]	0x068	Task for writing to pin specified in CONFIG[2].PSEL. Action on pin is to set it low.
TASKS_CLR[3]	0x06C	Task for writing to pin specified in CONFIG[3].PSEL. Action on pin is to set it low.
TASKS_CLR[4]	0x070	Task for writing to pin specified in CONFIG[4].PSEL. Action on pin is to set it low.
TASKS_CLR[5]	0x074	Task for writing to pin specified in CONFIG[5].PSEL. Action on pin is to set it low.
TASKS_CLR[6]	0x078	Task for writing to pin specified in CONFIG[6].PSEL. Action on pin is to set it low.
TASKS_CLR[7]	0x07C	Task for writing to pin specified in CONFIG[7].PSEL. Action on pin is to set it low.
EVENTS_IN[0]	0x100	Event generated from pin specified in CONFIG[0].PSEL
EVENTS_IN[1]	0x104	Event generated from pin specified in CONFIG[1].PSEL
EVENTS_IN[2]	0x108	Event generated from pin specified in CONFIG[2].PSEL
EVENTS_IN[3]	0x10C	Event generated from pin specified in CONFIG[3].PSEL
EVENTS_IN[4]	0x110	Event generated from pin specified in CONFIG[4].PSEL
EVENTS_IN[5]	0x114	Event generated from pin specified in CONFIG[5].PSEL
EVENTS_IN[6]	0x118	Event generated from pin specified in CONFIG[6].PSEL
EVENTS_IN[7]	0x11C	Event generated from pin specified in CONFIG[7].PSEL
EVENTS_PORT	0x17C	Event generated from multiple input GPIO pins with SENSE mechanism enabled
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
CONFIG[0]	0x510	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[1]	0x514	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event



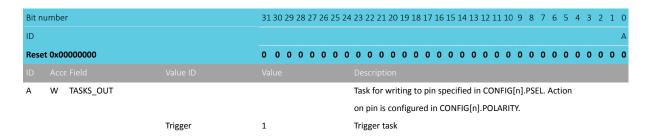
Register	Offset	Description
CONFIG[2]	0x518	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[3]	0x51C	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[4]	0x520	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[5]	0x524	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[6]	0x528	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[7]	0x52C	Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event

Table 45: Register overview

6.9.4.1 TASKS_OUT[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

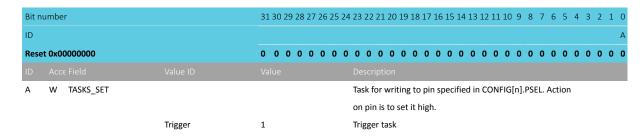
Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is configured in CONFIG[n].POLARITY.



6.9.4.2 TASKS_SET[n] (n=0..7)

Address offset: $0x030 + (n \times 0x4)$

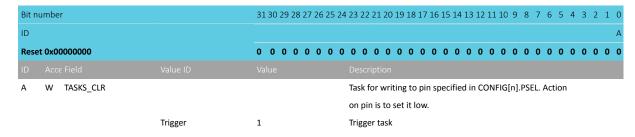
Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it high.



6.9.4.3 TASKS CLR[n] (n=0..7)

Address offset: $0x060 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it low.

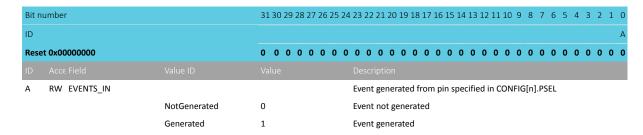


6.9.4.4 EVENTS IN[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$



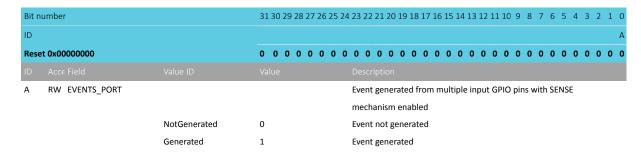
Event generated from pin specified in CONFIG[n].PSEL



6.9.4.5 EVENTS PORT

Address offset: 0x17C

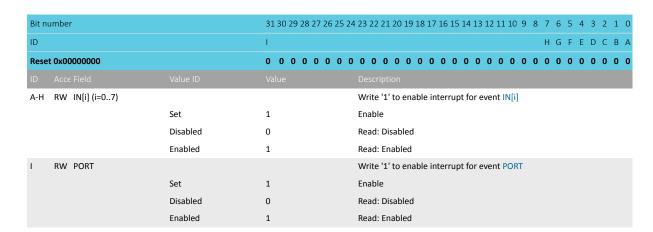
Event generated from multiple input GPIO pins with SENSE mechanism enabled



6.9.4.6 INTENSET

Address offset: 0x304

Enable interrupt



6.9.4.7 INTENCLR

Address offset: 0x308

Disable interrupt



Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		I	HGFEDCBA
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A-H RW IN[i] (i=07)			Write '1' to disable interrupt for event IN[i]
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
I RW PORT			Write '1' to disable interrupt for event PORT
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

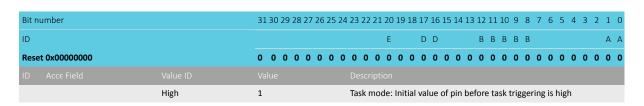
6.9.4.8 CONFIG[n] (n=0..7)

Address offset: $0x510 + (n \times 0x4)$

Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E DD BBBB AA
Rese	et 0x00000000		0 0 0 0 0 0 0 0	000000000000000000000000000000000000000
ID				
Α	RW MODE			Mode
		Disabled	0	Disabled. Pin specified by PSEL will not be acquired by the
				GPIOTE module.
		Event	1	Event mode
				The pin specified by PSEL will be configured as an input and
				the IN[n] event will be generated if operation specified in
				POLARITY occurs on the pin.
		Task	3	Task mode
				The GPIO specified by PSEL will be configured as an output
				and triggering the SET[n], CLR[n] or OUT[n] task will
				perform the operation specified by POLARITY on the pin.
				When enabled as a task the GPIOTE module will acquire the
				pin and the pin can no longer be written as a regular output
				pin from the GPIO module.
В	RW PSEL		[031]	GPIO number associated with SET[n], CLR[n] and OUT[n]
				tasks and IN[n] event
D	RW POLARITY			When In task mode: Operation to be performed on output
				when OUT[n] task is triggered. When In event mode:
				Operation on input that shall trigger IN[n] event.
		None	0	Task mode: No effect on pin from OUT[n] task. Event mode:
				no IN[n] event generated on pin activity.
		LoToHi	1	Task mode: Set pin from OUT[n] task. Event mode: Generate
				IN[n] event when rising edge on pin.
		HiToLo	2	Task mode: Clear pin from OUT[n] task. Event mode:
				Generate IN[n] event when falling edge on pin.
		Toggle	3	Task mode: Toggle pin from OUT[n]. Event mode: Generate
				IN[n] when any change on pin.
E	RW OUTINIT			When in task mode: Initial value of the output when the
				GPIOTE channel is configured. When in event mode: No
			_	effect.
		Low	0	Task mode: Initial value of pin before task triggering is low





6.9.5 Electrical specification

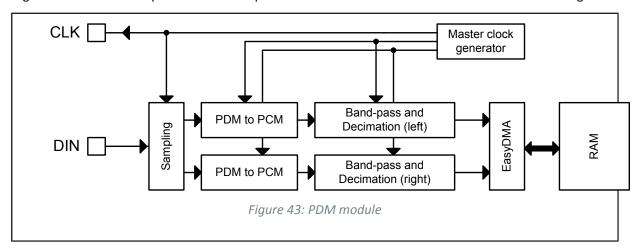
6.10 PDM — Pulse density modulation interface

The pulse density modulation (PDM) module enables input of pulse density modulated signals from external audio frontends, for example, digital microphones. The PDM module generates the PDM clock and supports single-channel or dual-channel (Left and Right) data input. Data is transferred directly to RAM buffers using EasyDMA.

Listed here are the main features for PDM:

- Up to two PDM microphones configured as a Left/Right pair using the same data input
- 16 kHz output sample rate, 16-bit samples
- EasyDMA support for sample buffering
- · HW decimation filters

The PDM module illustrated in PDM module on page 133 is interfacing up to two digital microphones with the PDM interface. It implements EasyDMA, which relieves real-time requirements associated with controlling the PDM slave from a low priority CPU execution context. It also includes all the necessary digital filter elements to produce PCM samples. The PDM module allows continuous audio streaming.



6.10.1 Master clock generator

The FREQ field in the master clock's PDMCLKCTRL register allows adjusting the PDM clock's frequency.

The master clock generator does not add any jitter to the HFCLK source chosen. It is recommended (but not mandatory) to use the Xtal as HFCLK source.

6.10.2 Module operation

By default, bits from the left PDM microphone are sampled on PDM_CLK falling edge, bits for the right are sampled on the rising edge of PDM_CLK, resulting in two bitstreams. Each bitstream is fed into a digital filter which converts the PDM stream into 16-bit PCM samples, and filters and down-samples them to reach the appropriate sample rate.



The EDGE field in the MODE register allows swapping Left and Right, so that Left will be sampled on rising edge, and Right on falling.

The PDM module uses EasyDMA to store the samples coming out from the filters into one buffer in RAM.

Depending on the mode chosen in the OPERATION field in the MODE register, memory either contains alternating left and right 16-bit samples (Stereo), or only left 16-bit samples (Mono).

To ensure continuous PDM sampling, it is up to the application to update the EasyDMA destination address pointer as the previous buffer is filled.

The continuous transfer can be started or stopped by sending the START and STOP tasks. STOP becomes effective after the current frame has finished transferring, which will generate the STOPPED event. The STOPPED event indicates that all activity in the module are finished, and that the data is available in RAM (EasyDMA has finished transferring as well). Attempting to restart before receiving the STOPPED event may result in unpredictable behaviour.

6.10.3 Decimation filter

In order to convert the incoming data stream into PCM audio samples, a decimation filter is included in the PDM interface module.

The input of the filter is the two-channel PDM serial stream (with left channel on clock high, right channel on clock low), its output is 2×16 -bit PCM samples at a sample rate 64 times lower than the PDM clock rate.

The filter stage of each channel is followed by a digital volume control, to attenuate or amplify the output samples in a range of -20 dB to +20 dB around the default (reset) setting, defined by G_{PDM,default}. The gain is controlled by the GAINL and GAINR registers.

As an example, if the goal is to achieve 2500 RMS output samples (16 bit) with a 1 kHz 90 dBA signal into a -26 dBFS sensitivity PDM microphone, the user will have to sum the PDM module's default gain ($G_{PDM,default}$) and the gain introduced by the microphone and acoustic path of his implementation (an attenuation would translate into a negative gain), and adjust GAINL and GAINR by this amount. Assuming that only the PDM module influences the gain, GAINL and GAINR must be set to - $G_{PDM,default}$ dB to achieve the requirement.

With G_{PDM,default}=3.2 dB, and as GAINL and GAINR are expressed in 0.5 dB steps, the closest value to program would be 3.0 dB, which can be calculated as:

```
GAINL = GAINR = (DefaultGain - (2 * 3))
```

Remember to check that the resulting values programmed into GAINL and GAINR fall within MinGain and MaxGain.

6.10.4 EasyDMA

Samples will be written directly to RAM, and EasyDMA must be configured accordingly.

The address pointer for the EasyDMA channel is set in SAMPLE.PTR register. If the destination address set in SAMPLE.PTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

DMA supports Stereo (Left+Right 16-bit samples) and Mono (Left only) data transfer, depending on setting in the OPERATION field in the MODE register. The samples are stored little endian.



MODE.OPERATION	Bits per sample	Result stored per RAM	Physical RAM allocated	M allocated Result boundary indexes Note	
		word	(32 bit words)	in RAM	
Stereo	32 (2x16)	L+R	ceil(SAMPLE.MAXCNT/2)	R0=[31:16]; L0=[15:0] Defa	ult
Mono	16	2xL	ceil(SAMPLE.MAXCNT/2)	L1=[31:16]; L0=[15:0]	

Table 46: DMA sample storage

The destination buffer in RAM consists of one block, the size of which is set in SAMPLE.MAXCNT register. Format is number of 16-bit samples. The physical RAM allocated is always:

```
(RAM allocation, in bytes) = SAMPLE.MAXCNT * 2;
```

(but the mapping of the samples depends on MODE.OPERATION.

If OPERATION=Stereo, RAM will contain a succession of Left and Right samples.

If OPERATION=Mono, RAM will contain a succession of mono samples.

For a given value of SAMPLE.MAXCNT, the buffer in RAM can contain half the stereo sampling time as compared to the mono sampling time.

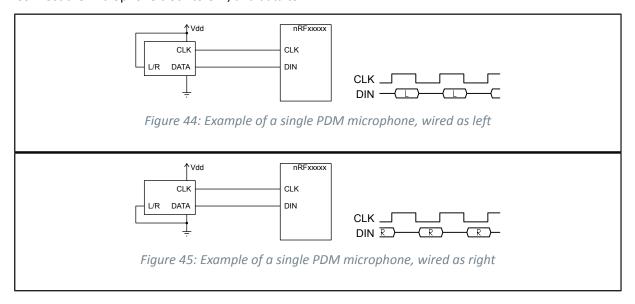
The PDM acquisition can be started by the START task, after the SAMPLE.PTR and SAMPLE.MAXCNT registers have been written. When starting the module, it will take some time for the filters to start outputting valid data. Transients from the PDM microphone itself may also occur. The first few samples (typically around 50) might hence contain invalid values or transients. It is therefore advised to discard the first few samples after a PDM start.

As soon as the STARTED event is received, the firmware can write the next SAMPLE.PTR value (this register is double-buffered), to ensure continuous operation.

When the buffer in RAM is filled with samples, an END event is triggered. The firmware can start processing the data in the buffer. Meanwhile, the PDM module starts acquiring data into the new buffer pointed to by SAMPLE.PTR, and sends a new STARTED event, so that the firmware can update SAMPLE.PTR to the next buffer address.

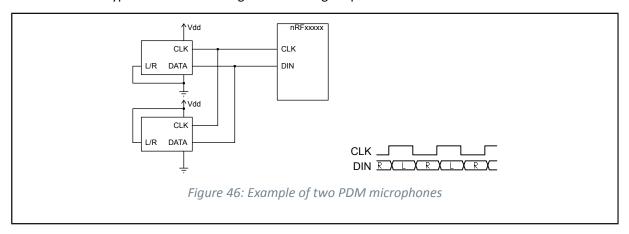
6.10.5 Hardware example

Connect the microphone clock to CLK, and data to DIN.





Note that in a single-microphone (mono) configuration, depending on the microphone's implementation, either the left or the right channel (sampled at falling or rising CLK edge respectively) will contain reliable data. If two microphones are used, one of them has to be set as left, the other as right (L/R pin tied high or to GND on the respective microphone). It is strongly recommended to use two microphones of exactly the same brand and type so that their timings in left and right operation match.



6.10.6 Pin configuration

The CLK and DIN signals associated to the PDM module are mapped to physical pins according to the configuration specified in the PSEL.CLK and PSEL.DIN registers respectively. If the CONNECT field in any PSEL register is set to Disconnected, the associated PDM module signal will not be connected to the required physical pins, and will not operate properly.

The PSEL.CLK and PSEL.DIN registers and their configurations are only used as long as the PDM module is enabled, and retained only as long as the device is in System ON mode. See POWER — Power supply on page 52 for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN CNF[n] register.

To ensure correct behaviour in the PDM module, the pins used by the PDM module must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 136 before enabling the PDM module. This is to ensure that the pins used by the PDM module are driven correctly if the PDM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the PDM module is supposed to be connected to an external PDM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behaviour.

PDM signal	PDM pin	Direction	Output value	Comment
CLK	As specified in PSEL.CLK	Output	0	
DIN	As specified in PSEL.DIN	Input	Not applicable	

Table 47: GPIO configuration before enabling peripheral

6.10.7 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4001D000	PDM	PDM	Pulse-density modulation (digital	
			microphone interface)	

Table 48: Instances



Register	Offset	Description	
TASKS_START	0x000	Starts continuous PDM transfer	
TASKS_STOP	0x004	Stops PDM transfer	
EVENTS_STARTED	0x100	PDM transfer has started	
EVENTS_STOPPED	0x104	PDM transfer has finished	
EVENTS_END	0x108	The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after a	
		STOP task has been received) to Data RAM	
INTEN	0x300	Enable or disable interrupt	
INTENSET	0x304	Enable interrupt	
INTENCLR	0x308	Disable interrupt	
ENABLE	0x500	PDM module enable register	
PDMCLKCTRL	0x504	PDM clock generator control	
MODE	0x508	Defines the routing of the connected PDM microphones' signals	
GAINL	0x518	Left output gain adjustment	
GAINR	0x51C	Right output gain adjustment	
PSEL.CLK	0x540	Pin number configuration for PDM CLK signal	
PSEL.DIN	0x544	Pin number configuration for PDM DIN signal	
SAMPLE.PTR	0x560	RAM address pointer to write samples to with EasyDMA	
SAMPLE.MAXCNT	0x564	Number of samples to allocate memory for in EasyDMA mode	

Table 49: Register overview

6.10.7.1 TASKS_START

Address offset: 0x000

Starts continuous PDM transfer

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				Description
Α	W TASKS_START			Starts continuous PDM transfer
		Trigger	1	Trigger task

6.10.7.2 TASKS_STOP

Address offset: 0x004 Stops PDM transfer

		Trigger	1	Trigger task
Α	W TASKS_STOP			Stops PDM transfer
ID				
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A
Bit n	umber		31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.10.7.3 EVENTS_STARTED

Address offset: 0x100 PDM transfer has started



Bit number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW EVENTS_STARTED		PDM transfer has started
NotGenerated	i 0	Event not generated
Generated	1	Event generated

6.10.7.4 EVENTS_STOPPED

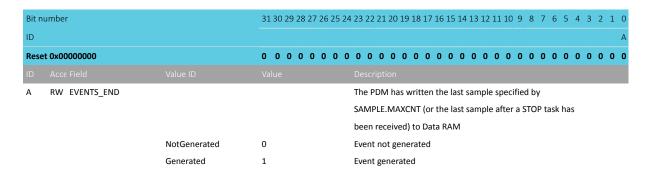
Address offset: 0x104
PDM transfer has finished

Bit number	31 30) 29 28 27 26 25	24 23 22 21 20	19 18 17 16	15 14 13 12	11 10 9	8 7	6 5	4 3	2 1 0
ID										А
Reset 0x00000000	0 0	0 0 0 0 0	0 0 0 0 0	0 0 0 0	0 0 0 0	0 0 0	0 0	0 0	0 0	0 0 0
ID Acce Field Value										
A RW EVENTS_STOPPED			PDM transfe	er has finishe	d					
NotGe	enerated 0		Event not ge	enerated						
Gener	ated 1		Event genera	ated						

6.10.7.5 EVENTS_END

Address offset: 0x108

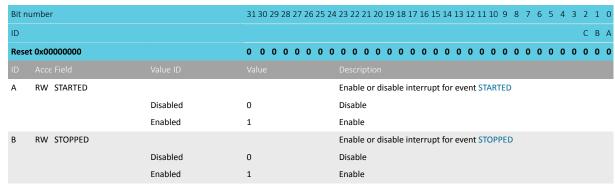
The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after a STOP task has been received) to Data RAM



6.10.7.6 INTEN

Address offset: 0x300

Enable or disable interrupt





Bit number	31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		СВА
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
C RW END		Enable or disable interrupt for event END
Disabled	0	Disable
Enabled	1	Enable

6.10.7.7 INTENSET

Address offset: 0x304

Enable interrupt

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			СВА
Reset 0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field			Description
A RW STARTED)		Write '1' to enable interrupt for event STARTED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
B RW STOPPE)		Write '1' to enable interrupt for event STOPPED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
C RW END			Write '1' to enable interrupt for event END
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.10.7.8 INTENCLR

Address offset: 0x308

Disable interrupt

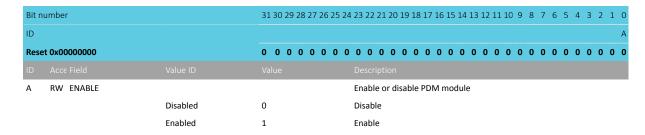
Bit number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			СВА
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A RW STARTED			Write '1' to disable interrupt for event STARTED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
B RW STOPPED			Write '1' to disable interrupt for event STOPPED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
C RW END			Write '1' to disable interrupt for event END
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled



6.10.7.9 ENABLE

Address offset: 0x500

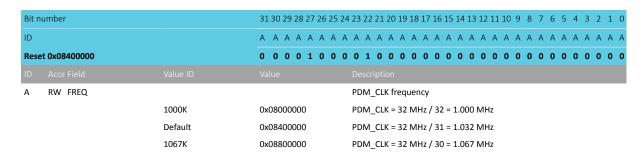
PDM module enable register



6.10.7.10 PDMCLKCTRL

Address offset: 0x504

PDM clock generator control



6.10.7.11 MODE

Address offset: 0x508

Defines the routing of the connected PDM microphones' signals

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID				B A	
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID					
Α	RW OPERATION			Mono or stereo operation	
		Stereo	0	Sample and store one pair (Left + Right) of 16bit samples	
				per RAM word R=[31:16]; L=[15:0]	
		Mono	1	Sample and store two successive Left samples (16 bit each)	
				per RAM word L1=[31:16]; L0=[15:0]	
В	RW EDGE			Defines on which PDM_CLK edge Left (or mono) is sampled	
		LeftFalling	0 Left (or mono) is sampled on falling edge of PDM_CLK		
		LeftRising	1	Left (or mono) is sampled on rising edge of PDM_CLK	

6.10.7.12 GAINL

Address offset: 0x518

Left output gain adjustment

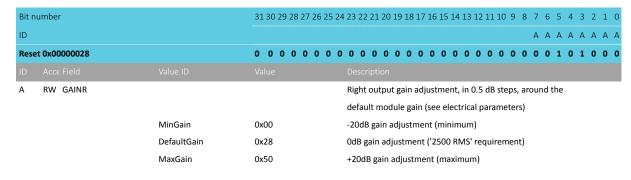


Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID		A A A A A A	
Reset 0x00000028		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID Acce Field			
A RW GAINL		Left output gain adjustment, in 0.5 dB steps, around the	
		default module gain (see electrical parameters)	
		0x00 -20 dB gain adjust	
		0x01 -19.5 dB gain adjust	
		()	
		0x27 -0.5 dB gain adjust	
		0x28 0 dB gain adjust	
		0x29 +0.5 dB gain adjust	
		()	
		0x4F +19.5 dB gain adjust	
		0x50 +20 dB gain adjust	
	MinGain	0x00 -20dB gain adjustment (minimum)	
	DefaultGain	0x28 OdB gain adjustment ('2500 RMS' requirement)	
	MaxGain	0x50 +20dB gain adjustment (maximum)	

6.10.7.13 GAINR

Address offset: 0x51C

Right output gain adjustment



6.10.7.14 PSEL.CLK

Address offset: 0x540

Pin number configuration for PDM CLK signal

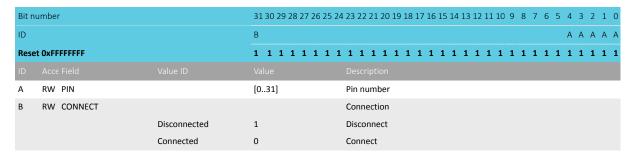
Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
A B	RW PIN RW CONNECT		[031]	Pin number Connection
		Disconnected	[031]	



6.10.7.15 PSEL.DIN

Address offset: 0x544

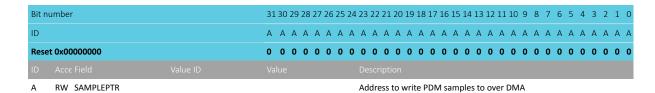
Pin number configuration for PDM DIN signal



6.10.7.16 SAMPLE.PTR

Address offset: 0x560

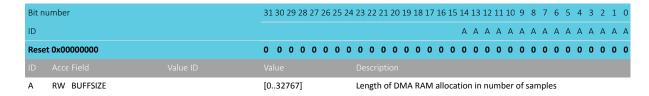
RAM address pointer to write samples to with EasyDMA



6.10.7.17 SAMPLE.MAXCNT

Address offset: 0x564

Number of samples to allocate memory for in EasyDMA mode



6.10.8 Electrical specification

6.10.8.1 PDM Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{PDM,CLK}	PDM clock speed		1.032		MHz
t _{PDM,JITTER}	Jitter in PDM clock output			20	ns
$T_{dPDM,CLK}$	PDM clock duty cycle	40	50	60	%
t _{PDM,DATA}	Decimation filter delay			5	ms
t _{PDM,cv}	Allowed clock edge to data valid			125	ns
t _{PDM,ci}	Allowed (other) clock edge to data invalid	0			ns
t _{PDM,s}	Data setup time at f _{PDM,CLK} =1.024 MHz	65			ns
t _{PDM,h}	Data hold time at f _{PDM,CLK} =1.024 MHz	0			ns
G _{PDM,default}	Default (reset) absolute gain of the PDM module		3.2		dB



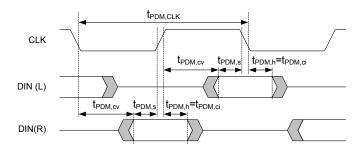


Figure 47: PDM timing diagram

6.11 PPI — Programmable peripheral interconnect

The programmable peripheral interconnect (PPI) enables peripherals to interact autonomously with each other using tasks and events independent of the CPU. The PPI allows precise synchronization between peripherals when real-time application constraints exist and eliminates the need for CPU activity to implement behavior which can be predefined using PPI.

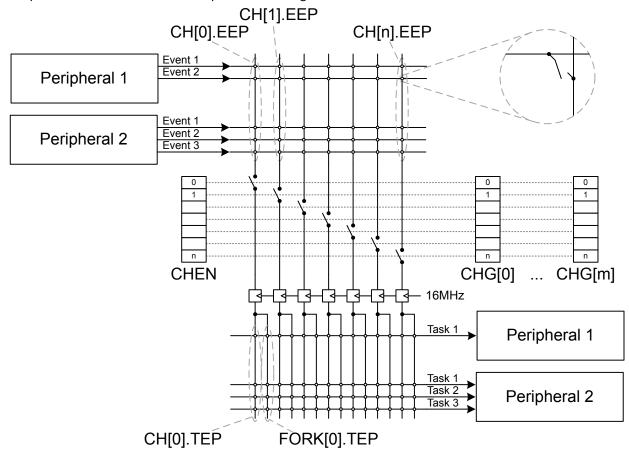


Figure 48: PPI block diagram

The PPI system has, in addition to the fully programmable peripheral interconnections, a set of channels where the event end point (EEP) and task end points (TEP) are fixed in hardware. These fixed channels can be individually enabled, disabled, or added to PPI channel groups (see CHG[n] registers), in the same way as ordinary PPI channels.



Instance	Channel	Number of channels
PPI	0-19	20
PPI (fixed)	20-31	12

Table 50: Configurable and fixed PPI channels

The PPI provides a mechanism to automatically trigger a task in one peripheral as a result of an event occurring in another peripheral. A task is connected to an event through a PPI channel. The PPI channel is composed of three end point registers, one EEP, and two TEPs. A peripheral task is connected to a TEP using the address of the task register associated with the task. Similarly, a peripheral event is connected to an EEP using the address of the event register associated with the event.

On each PPI channel, the signals are synchronized to the 16 MHz clock to avoid any internal violation of setup and hold timings. As a consequence, events that are synchronous to the 16 MHz clock will be delayed by one clock period, while other asynchronous events will be delayed by up to one 16 MHz clock period.

Note: Shortcuts (as defined in the SHORTS register in each peripheral) are not affected by this 16 MHz synchronization, and are therefore not delayed.

Each TEP implements a fork mechanism that enables a second task to be triggered at the same time as the task specified in the TEP is triggered. This second task is configured in the task end point register in the FORK registers groups, e.g. FORK.TEP[0] is associated with PPI channel CH[0].

There are two ways of enabling and disabling PPI channels:

- Enable or disable PPI channels individually using the CHEN, CHENSET, and CHENCLR registers.
- Enable or disable PPI channels in PPI channel groups through the groups' ENABLE and DISABLE tasks. Prior to these tasks being triggered, the PPI channel group must be configured to define which PPI channels belong to which groups.

Note: When a channel belongs to two groups m and n, and the tasks CHG[m].EN and CHG[n].DIS occur simultaneously (m and n can be equal or different), the CHG[m].EN on that channel has priority.

PPI tasks (for example, CHG[0].EN) can be triggered through the PPI like any other task, which means they can be hooked to a PPI channel as a TEP. One event can trigger multiple tasks by using multiple channels and one task can be triggered by multiple events in the same way.

6.11.1 Pre-programmed channels

Some of the PPI channels are pre-programmed. These channels cannot be configured by the CPU, but can be added to groups and enabled and disabled like the general purpose PPI channels. The FORK TEP for these channels are still programmable and can be used by the application.

For a list of pre-programmed PPI channels, see the following table.



Channel	EEP	TEP
20	TIMERO->EVENTS_COMPARE[0]	RADIO->TASKS_TXEN
21	TIMERO->EVENTS_COMPARE[0]	RADIO->TASKS_RXEN
22	TIMERO->EVENTS_COMPARE[1]	RADIO->TASKS_DISABLE
23	RADIO->EVENTS_BCMATCH	AAR->TASKS_START
24	RADIO->EVENTS_READY	CCM->TASKS_KSGEN
25	RADIO->EVENTS_ADDRESS	CCM->TASKS_CRYPT
26	RADIO->EVENTS_ADDRESS	TIMERO->TASKS_CAPTURE[1]
27	RADIO->EVENTS_END	TIMERO->TASKS_CAPTURE[2]
28	RTCO->EVENTS_COMPARE[0]	RADIO->TASKS_TXEN
29	RTCO->EVENTS_COMPARE[0]	RADIO->TASKS_RXEN
30	RTCO->EVENTS_COMPARE[0]	TIMERO->TASKS_CLEAR
31	RTC0->EVENTS_COMPARE[0]	TIMERO->TASKS_START

Table 51: Pre-programmed channels

6.11.2 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4001F000	PPI	PPI	Programmable peripheral interconnect	

Table 52: Instances

Register	Offset	Description
TASKS_CHG[0].EN	0x000	Enable channel group 0
TASKS_CHG[0].DIS	0x004	Disable channel group 0
TASKS_CHG[1].EN	0x008	Enable channel group 1
TASKS_CHG[1].DIS	0x00C	Disable channel group 1
TASKS_CHG[2].EN	0x010	Enable channel group 2
TASKS_CHG[2].DIS	0x014	Disable channel group 2
TASKS_CHG[3].EN	0x018	Enable channel group 3
TASKS_CHG[3].DIS	0x01C	Disable channel group 3
TASKS_CHG[4].EN	0x020	Enable channel group 4
TASKS_CHG[4].DIS	0x024	Disable channel group 4
TASKS_CHG[5].EN	0x028	Enable channel group 5
TASKS_CHG[5].DIS	0x02C	Disable channel group 5
CHEN	0x500	Channel enable register
CHENSET	0x504	Channel enable set register
CHENCLR	0x508	Channel enable clear register
CH[0].EEP	0x510	Channel 0 event endpoint
CH[0].TEP	0x514	Channel 0 task endpoint
CH[1].EEP	0x518	Channel 1 event endpoint
CH[1].TEP	0x51C	Channel 1 task endpoint
CH[2].EEP	0x520	Channel 2 event endpoint
CH[2].TEP	0x524	Channel 2 task endpoint
CH[3].EEP	0x528	Channel 3 event endpoint
CH[3].TEP	0x52C	Channel 3 task endpoint
CH[4].EEP	0x530	Channel 4 event endpoint
CH[4].TEP	0x534	Channel 4 task endpoint
CH[5].EEP	0x538	Channel 5 event endpoint
CH[5].TEP	0x53C	Channel 5 task endpoint
CH[6].EEP	0x540	Channel 6 event endpoint
CH[6].TEP	0x544	Channel 6 task endpoint



Register	Offset	Description
CH[7].EEP	0x548	Channel 7 event endpoint
CH[7].TEP	0x54C	Channel 7 task endpoint
CH[8].EEP	0x550	Channel 8 event endpoint
CH[8].TEP	0x554	Channel 8 task endpoint
CH[9].EEP	0x558	Channel 9 event endpoint
CH[9].TEP	0x55C	Channel 9 task endpoint
CH[10].EEP	0x560	Channel 10 event endpoint
CH[10].TEP	0x564	Channel 10 task endpoint
CH[11].EEP	0x568	Channel 11 event endpoint
CH[11].TEP	0x56C	Channel 11 task endpoint
CH[12].EEP	0x570	Channel 12 event endpoint
CH[12].TEP	0x574	Channel 12 task endpoint
CH[13].EEP	0x578	Channel 13 event endpoint
CH[13].TEP	0x57C	Channel 13 task endpoint
CH[14].EEP	0x580	Channel 14 event endpoint
CH[14].TEP	0x584	Channel 14 task endpoint
CH[14].TEP	0x588	Channel 15 event endpoint
CH[15].TEP	0x58C	Channel 15 task endpoint
CH[16].EEP	0x590	
	0x590	Channel 16 event endpoint Channel 16 task endpoint
CH[16].TEP		·
CH[17].EEP	0x598	Channel 17 event endpoint
CH[17].TEP	0x59C	Channel 17 task endpoint
CH[18].EEP	0x5A0	Channel 18 event endpoint
CH[18].TEP	0x5A4	Channel 18 task endpoint
CH[19].EEP	0x5A8	Channel 19 event endpoint
CH[19].TEP	0x5AC	Channel 19 task endpoint
CHG[0]	0x800	Channel group 0
CHG[1]	0x804	Channel group 1
CHG[2]	0x808	Channel group 2
CHG[3]	0x80C	Channel group 3
CHG[4]	0x810	Channel group 4
CHG[5]	0x814	Channel group 5
FORK[0].TEP	0x910	Channel 0 task endpoint
FORK[1].TEP	0x914	Channel 1 task endpoint
FORK[2].TEP	0x918	Channel 2 task endpoint
FORK[3].TEP	0x91C	Channel 3 task endpoint
FORK[4].TEP	0x920	Channel 4 task endpoint
FORK[5].TEP	0x924	Channel 5 task endpoint
FORK[6].TEP	0x928	Channel 6 task endpoint
FORK[7].TEP	0x92C	Channel 7 task endpoint
FORK[8].TEP	0x930	Channel 8 task endpoint
FORK[9].TEP	0x934	Channel 9 task endpoint
FORK[10].TEP	0x938	Channel 10 task endpoint
FORK[11].TEP	0x93C	Channel 11 task endpoint
FORK[12].TEP	0x940	Channel 12 task endpoint
FORK[13].TEP	0x944	Channel 13 task endpoint
FORK[14].TEP	0x948	Channel 14 task endpoint
FORK[15].TEP	0x94C	Channel 15 task endpoint
FORK[16].TEP	0x950	Channel 16 task endpoint
FORK[17].TEP	0x954	Channel 17 task endpoint
FORK[18].TEP	0x958	Channel 18 task endpoint
FORK[19].TEP	0x95C	Channel 19 task endpoint
FORK[20].TEP	0x960	Channel 20 task endpoint



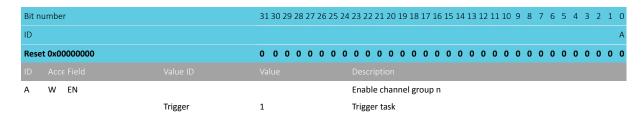
	۰	
Register	Offset	Description
FORK[21].TEP	0x964	Channel 21 task endpoint
FORK[22].TEP	0x968	Channel 22 task endpoint
FORK[23].TEP	0x96C	Channel 23 task endpoint
FORK[24].TEP	0x970	Channel 24 task endpoint
FORK[25].TEP	0x974	Channel 25 task endpoint
FORK[26].TEP	0x978	Channel 26 task endpoint
FORK[27].TEP	0x97C	Channel 27 task endpoint
FORK[28].TEP	0x980	Channel 28 task endpoint
FORK[29].TEP	0x984	Channel 29 task endpoint
FORK[30].TEP	0x988	Channel 30 task endpoint
FORK[31].TEP	0x98C	Channel 31 task endpoint

Table 53: Register overview

6.11.2.1 TASKS_CHG[n].EN (n=0..5)

Address offset: $0x000 + (n \times 0x8)$

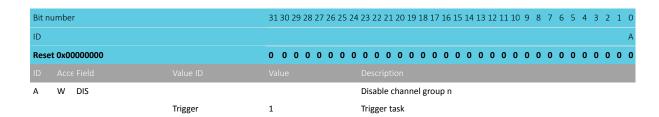
Enable channel group n



6.11.2.2 TASKS_CHG[n].DIS (n=0..5)

Address offset: $0x004 + (n \times 0x8)$

Disable channel group n



6.11.2.3 CHEN

Address offset: 0x500 Channel enable register



Bit number		31	30 2	9 2	8 2	7 26	25	24	23	22	21 2	0 19	18	17	16	15	14	13 1	2 1	1 10	9	8	7	6	5	4	3	2 1	. 0
ID		f	e d	d d	e b	а	Z	Υ	Х	W	νι	J T	S	R	Q	Р	О	N I	M L	. K	J	1	Н	G	F	Ε	D	СВ	A
Reset 0x00000000		0	0 () (0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0 0	0
ID Acce Field																													
A-T RW CH[i] (i=019)									Ena	able	or	disa	ble	cha	nne	el i													
	Disabled	0							Dis	abl	e ch	ann	el																
E	Enabled	1							Ena	able	cha	nne	el																
U-f RW CH[i] (i=2031)									Ena	able	or	disa	ble	cha	nne	el i													
	Disabled	0							Dis	abl	e ch	ann	el																
E	Enabled	1							Ena	able	e cha	nne	el																

6.11.2.4 CHENSET

Address offset: 0x504

Channel enable set register

Read: reads value of CH{i} field in CHEN register.

Bit number		31	30 2	9 2	8 2	7 2	6 25	5 24	4 23	3 22	21	20 :	19 1	.8 1	7 16	15	14	13 1	2 11	. 10	9	8	7	6	5 4	4 3	2	1 0
ID		f	e d	t	c l	b a	a Z	Υ	X	W	٧	U	Т :	S F	Q	Р	0	N N	1 L	K	J	1	Н	G	FI	E D	С	ВА
Reset 0x00000000		0	0 () (0 (0 (0	0	0	0	0	0	0	0 0	0	0	0	0 (0	0	0	0	0	0	0 (0 0	0	0 0
ID Acce Field Va																												
A-T RW CH[i] (i=019)									Cł	nanı	nel i	en	able	e se	t reg	iste	r. V	/ritii	ng 'C)' ha	s n	o ef	fec	t.				
Di	isabled	0							Re	ead:	cha	ann	el d	isab	led													
En	nabled	1							Re	ead:	cha	ann	el e	nab	led													
Se	et	1							W	rite	: En	abl	e ch	anr	iel													
U-f RW CH[i] (i=2031)									Cł	nanı	nel i	en	able	e se	t reg	iste	r. V	/ritii	ng 'C)' ha	s n	o ef	fec	t.				
Di	isabled	0							Re	ead:	cha	ann	el d	isab	led													
En	nabled	1							Re	ead:	cha	ann	el e	nab	led													
Se	et	1							W	rite	: En	abl	e ch	anr	iel													

6.11.2.5 CHENCLR

Address offset: 0x508

Channel enable clear register

Read: reads value of CH{i} field in CHEN register.

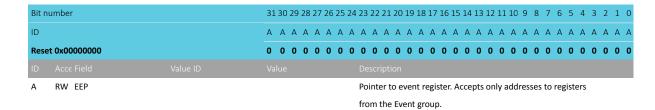
Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	f e d c b a Z Y	/XWVUTSRQPONMLKJIHGFEDCBA
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A-T RW CH[i] (i=019)		Channel i enable clear register. Writing '0' has no effect.
Disabled	0	Read: channel disabled
Enabled	1	Read: channel enabled
Clear	1	Write: disable channel
U-f RW CH[i] (i=2031)		Channel i enable clear register. Writing '0' has no effect.
Disabled	0	Read: channel disabled
Enabled	1	Read: channel enabled
Clear	1	Write: disable channel

6.11.2.6 CH[n].EEP (n=0..19)

Address offset: $0x510 + (n \times 0x8)$



Channel n event endpoint



6.11.2.7 CH[n].TEP (n=0..19)

Address offset: $0x514 + (n \times 0x8)$

Channel n task endpoint

Α	RW TEP	Pointer to task register. Accepts only ad-	dresses to registers
ID			
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A	A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11	10 9 8 7 6 5 4 3 2 1 0

from the Task group.

6.11.2.8 CHG[n] (n=0..5)

Address offset: $0x800 + (n \times 0x4)$

Channel group n

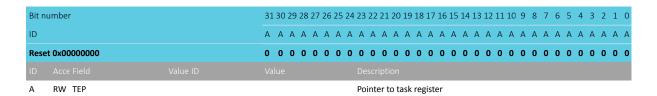
Bit number		31 30 29 28 27 2	26 25 24	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		f e d c b	a Z Y	Y X W V U T S R Q P O N M L K J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0	0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field				
A-T RW CH[i] (i=019)				Include or exclude channel i
	Excluded	0		Exclude
	Included	1		Include
U-f RW CH[i] (i=2031)				Include or exclude channel i
	Excluded	0		Exclude
	Included	1		Include

6.11.2.9 FORK[n].TEP (n=0..19, 20..31)

Address offset: $0x910 + (n \times 0x4)$

Channel n task endpoint

Downloaded from **Arrow.com**.







6.12 PWM — Pulse width modulation

The pulse with modulation (PWM) module enables the generation of pulse width modulated signals on GPIO. The module implements an up or up-and-down counter with four PWM channels that drive assigned GPIOs.

The following are the main features of a PWM module:

- Programmable PWM frequency
- Up to four PWM channels with individual polarity and duty cycle values
- Edge or center-aligned pulses across PWM channels
- Multiple duty cycle arrays (sequences) defined in RAM
- Autonomous and glitch-free update of duty cycle values directly from memory through EasyDMA (no CPU involvement)
- Change of polarity, duty cycle, and base frequency possibly on every PWM period
- RAM sequences can be repeated or connected into loops

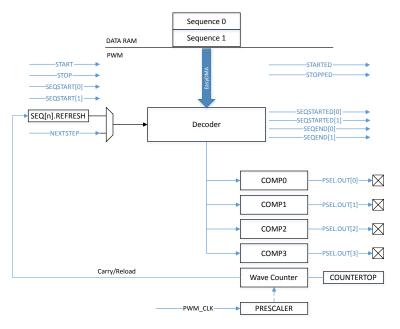


Figure 49: PWM module

6.12.1 Wave counter

The wave counter is responsible for generating the pulses at a duty cycle that depends on the compare values, and at a frequency that depends on COUNTERTOP.

There is one common 15-bit counter with four compare channels. Thus, all four channels will share the same period (PWM frequency), but can have individual duty cycle and polarity. The polarity is set by a value read from RAM (see figure Decoder memory access modes on page 154). Whether the counter counts up, or up and down, is controlled by the MODE register.

The timer top value is controlled by the COUNTERTOP register. This register value, in conjunction with the selected PRESCALER of the PWM_CLK, will result in a given PWM period. A COUNTERTOP value smaller than the compare setting will result in a state where no PWM edges are generated. OUT[n] is held high, given that the polarity is set to FallingEdge. All compare registers are internal and can only be configured through decoder presented later. COUNTERTOP can be safely written at any time.

Sampling follows the START task. If DECODER.LOAD=WaveForm, the register value is ignored and taken from RAM instead (see section Decoder with EasyDMA on page 153 for more details). If DECODER.LOAD



is anything else than the WaveForm, it is sampled following a STARTSEQ[n] task and when loading a new value from RAM during a sequence playback.

The following figure shows the counter operating in up mode (MODE=PWM_MODE_Up), with three PWM channels with the same frequency but different duty cycle:

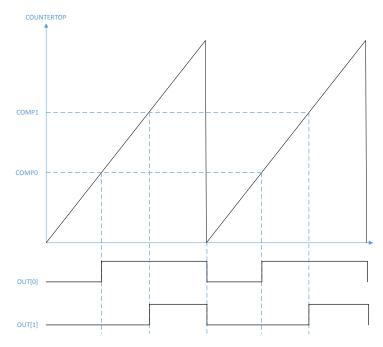


Figure 50: PWM counter in up mode example - FallingEdge polarity

The counter is automatically reset to zero when COUNTERTOP is reached and OUT[n] will invert. OUT[n] is held low if the compare value is 0 and held high if set to COUNTERTOP, given that the polarity is set to FallingEdge. Counter running in up mode results in pulse widths that are edge-aligned. The following is the code for the counter in up mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                       (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->PSEL.OUT[1] = (second pin << PWM PSEL OUT PIN Pos) |
                       (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                   = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
NRF PWM0->MODE = (PWM MODE UPDOWN Up << PWM MODE UPDOWN Pos);
NRF_PWM0->PRESCALER = (PWM_PRESCALER_PRESCALER DIV 1 <<
                                                PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF PWM0->LOOP = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Individual << PWM_DECODER_LOAD_Pos) |
                     (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t)(pwm seq) << PWM SEQ PTR PTR Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(pwm seq) / sizeof(uint16 t)) <<
                                                PWM SEQ CNT CNT Pos);
NRF_PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```



When the counter is running in up mode, the following formula can be used to compute the PWM period and the step size:

PWM period: $T_{PWM (Up)} = T_{PWM CLK} * COUNTERTOP$

Step width/Resolution: $T_{\text{steps}} = T_{\text{PWM CLK}}$

The following figure shows the counter operating in up-and-down mode (MODE=PWM_MODE_UpAndDown), with two PWM channels with the same frequency but different duty cycle and output polarity:

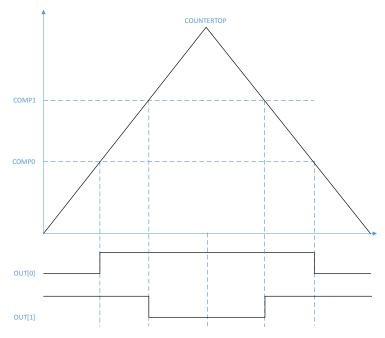


Figure 51: PWM counter in up-and-down mode example



The counter starts decrementing to zero when COUNTERTOP is reached and will invert the OUT[n] when compare value is hit for the second time. This results in a set of pulses that are center-aligned. The following is the code for the counter in up-and-down mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF_PWM0->PSEL.OUT[0] = (first_pin << PWM_PSEL_OUT_PIN_Pos) |</pre>
                         (PWM PSEL OUT CONNECT Connected <<
                                                    PWM_PSEL_OUT_CONNECT_Pos);
NRF PWM0->PSEL.OUT[1] = (second pin << PWM PSEL OUT PIN Pos) |
                        (PWM_PSEL_OUT_CONNECT_Connected <<
                                                    PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_UpAndDown << PWM_MODE_UPDOWN_Pos);</pre>
NRF_PWM0->PRESCALER = (PWM_PRESCALER_PRESCALER_DIV_1 <<
                                                    PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF_PWM0->LOOP = (PWM_LOOP_CNT_Disabled << PWM_LOOP_CNT_Pos);
NRF PWM0->DECODER = (PWM DECODER LOAD Individual << PWM DECODER LOAD Pos) |
                      (PWM_DECODER_MODE_RefreshCount << PWM_DECODER_MODE_Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(pwm_seq) << PWM_SEQ_PTR_PTR_Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(pwm seq) / sizeof(uint16 t)) <<
                                                   PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

When the counter is running in up-and-down mode, the following formula can be used to compute the PWM period and the step size:

```
\begin{split} &T_{\text{PWM}\,(\text{Up And Down})} \ = \ T_{\text{PWM\_CLK}} \ * \ 2 \ * \ \text{COUNTERTOP} \\ &\text{Step width/Resolution:} \quad &T_{\text{steps}} \ = \ &T_{\text{PWM\_CLK}} \ * \ 2 \end{split}
```

6.12.2 Decoder with EasyDMA

The decoder uses EasyDMA to take PWM parameters stored in RAM and update the internal compare registers of the wave counter, based on the mode of operation.

PWM parameters are organized into a sequence containing at least one half word (16 bit). Its most significant bit[15] denotes the polarity of the OUT[n] while bit[14:0] is the 15-bit compare value.

Bit n	umb	er		31 30 29 28 23	7 26 2	5 24	23 2	22 2	21 20	0 19	18	17	16 :	15 1	4 13	3 12	11	10 9	9 8	3 7	6	5	4	3	2	1 0
Id														В	ДД	A	Α	Α /	4 <i>A</i>	, Δ	A	. A	Α	Α	Α	А А
Rese	et Ox	0000000		0 0 0 0 0	0 (0 0	0	0 (0 0	0	0	0	0	0	0 0	0	0	0 (0 (0	0	0	0	0	0	0 0
Id																										
Α	RW	COMPARE					Dut	у су	/cle	sett	ing	- Va	llue	loa	ded	to i	nter	nal	con	npa	re					
							regi	iste	r																	
В	RW	POLARITY					Edg	e p	olar	ity c	f G	PIO														
			RisingEdge	0			Firs	t ed	lge v	with	in t	he I	PWI	Мρ	erio	d is	risir	ng								
			FallingEdge	1			Firs	t ed	lge v	with	in t	he	PWI	Мр	erio	d is	falli	ng								

The DECODER register controls how the RAM content is interpreted and loaded into the internal compare registers. The LOAD field controls if the RAM values are loaded to all compare channels, or to update a



group or all channels with individual values. The following figure illustrates how parameters stored in RAM are organized and routed to various compare channels in different modes:

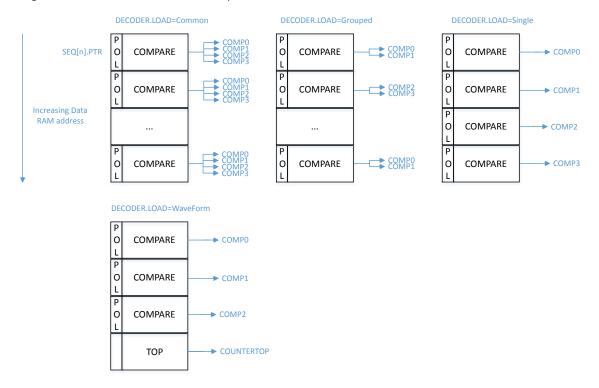


Figure 52: Decoder memory access modes

A special mode of operation is available when DECODER.LOAD is set to WaveForm. In this mode, up to three PWM channels can be enabled - OUT[0] to OUT[2]. In RAM, four values are loaded at a time: the first, second and third location are used to load the values, and the fourth RAM location is used to load the COUNTERTOP register. This way one can have up to three PWM channels with a frequency base that changes on a per PWM period basis. This mode of operation is useful for arbitrary wave form generation in applications, such as LED lighting.

The register SEQ[n].REFRESH=N (one per sequence n=0 or 1) will instruct a new RAM stored pulse width value on every (N+1)th PWM period. Setting the register to zero will result in a new duty cycle update every PWM period, as long as the minimum PWM period is observed.

Note that registers SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored when DECODER.MODE=NextStep. The next value is loaded upon every received NEXTSTEP task.

SEQ[n].PTR is the pointer used to fetch COMPARE values from RAM. If the SEQ[n].PTR is not pointing to a RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions. After the SEQ[n].PTR is set to the desired RAM location, the SEQ[n].CNT register must be set to number of 16-bit half words in the sequence. It is important to observe that the Grouped mode requires one half word per group, while the Single mode requires one half word per channel, thus increasing the RAM size occupation. If PWM generation is not running when the SEQSTART[n] task is triggered, the task will load the first value from RAM and then start the PWM generation. A SEQSTARTED[n] event is generated as soon as the EasyDMA has read the first PWM parameter from RAM and the wave counter has started executing it. When LOOP.CNT=0, sequence n=0 or 1 is played back once. After the last value in the sequence has been loaded and started executing, a SEQEND[n] event is generated. The PWM generation will then continue with the last loaded value. The following figure illustrates an example of such simple playback:



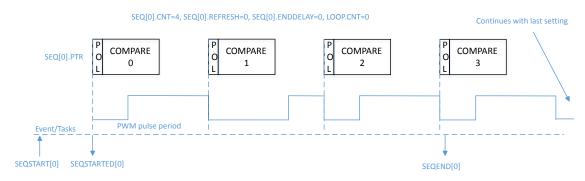


Figure 53: Simple sequence example

Figure depicts the source code used for configuration and timing details in a sequence where only sequence 0 is used and only run once with a new PWM duty cycle for each period.

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                     = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE
                     = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF PWM0->LOOP = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                     (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t)(seq0 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[0].CNT = ((sizeof(seq0_ram) / sizeof(uint16_t)) <</pre>
                                                PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

To completely stop the PWM generation and force the associated pins to a defined state, a STOP task can be triggered at any time. A STOPPED event is generated when the PWM generation has stopped at the end of currently running PWM period, and the pins go into their idle state as defined in GPIO OUT register. PWM generation can then only be restarted through a SEQSTART[n] task. SEQSTART[n] will resume PWM generation after having loaded the first value from the RAM buffer defined in the SEQ[n].PTR register.

The table below indicates when specific registers get sampled by the hardware. Care should be taken when updating these registers to avoid that values are applied earlier than expected.



Taken into account by hardware	Recommended (safe) update
When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
Every time a new value from sequence [0] has been loaded from	When no more value from sequence [0] gets loaded from RAM
RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[0] event)
PWMPERIODEND event)	At any time during sequence [1] (which starts when the
	SEQSTARTED[1] event is generated)
When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
Every time a new value from sequence [1] has been loaded from	When no more value from sequence [1] gets loaded from RAM
RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[1] event)
PWMPERIODEND event)	At any time during sequence [0] (which starts when the
	SEQSTARTED[0] event is generated)
When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
Every time a new value from sequence [0] has been loaded from	At any time during sequence [1] (which starts when the
RAM and gets applied to the Wave Counter (indicated by the	SEQSTARTED[1] event is generated)
PWMPERIODEND event)	
When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
Every time a new value from sequence [1] has been loaded from	At any time during sequence [0] (which starts when the
RAM and gets applied to the Wave Counter (indicated by the	SEQSTARTED[0] event is generated)
PWMPERIODEND event)	
In DECODER.LOAD=WaveForm: this register is ignored.	Before starting PWM generation through a SEQSTART[n] task
In all other LOAD modes: at the end of current PWM period	After a STOP task has been triggered, and the STOPPED event has
(indicated by the PWMPERIODEND event)	been received.
Immediately	Before starting PWM generation through a SEQSTART[n] task
	After a STOP task has been triggered, and the STOPPED event has
	been received.
Immediately	Before starting PWM generation through a SEQSTART[n] task
	After a STOP task has been triggered, and the STOPPED event has
	been received.
Immediately	Before starting PWM generation through a SEQSTART[n] task
	After a STOP task has been triggered, and the STOPPED event has
	been received.
Immediately	Before starting PWM generation through a SEQSTART[n] task
	After a CTOD took has been tries and and the CTODDED asset has
	After a STOP task has been triggered, and the STOPPED event has
	been received.
	When sending the SEQSTART[n] task When sending the SEQSTART[n] task When sending the SEQSTART[n] task Every time a new value from sequence [0] has been loaded from RAM and gets applied to the Wave Counter (indicated by the PWMPERIODEND event) When sending the SEQSTART[1] task Every time a new value from sequence [1] has been loaded from RAM and gets applied to the Wave Counter (indicated by the PWMPERIODEND event) When sending the SEQSTART[0] task Every time a new value from sequence [0] has been loaded from RAM and gets applied to the Wave Counter (indicated by the PWMPERIODEND event) When sending the SEQSTART[1] task Every time a new value from sequence [1] has been loaded from RAM and gets applied to the Wave Counter (indicated by the PWMPERIODEND event) In DECODER.LOAD=WaveForm: this register is ignored. In all other LOAD modes: at the end of current PWM period (indicated by the PWMPERIODEND event) Immediately Immediately Immediately

Table 54: When to safely update PWM registers

Note: SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored at the end of a complex sequence, indicated by a LOOPSDONE event. The reason for this is that the last value loaded from RAM is maintained until further action from software (restarting a new sequence, or stopping PWM generation).

A more complex example, where LOOP.CNT>0, is shown in the following figure:



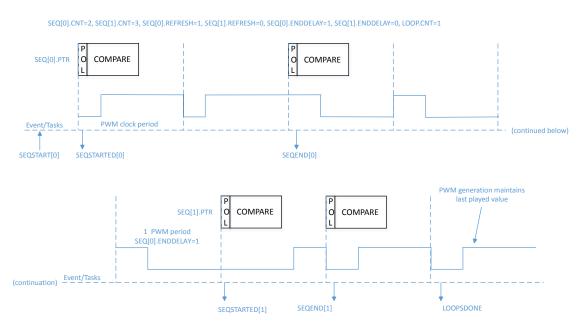


Figure 54: Example using two sequences

In this case, an automated playback takes place, consisting of SEQ[0], delay 0, SEQ[1], delay 1, then again SEQ[0], etc. The user can choose to start a complex playback with SEQ[0] or SEQ[1] through sending the SEQSTART[0] or SEQSTART[1] task. The complex playback always ends with delay 1.

The two sequences 0 and 1 are defined by the addresses of value tables in RAM (pointed to by SEQ[n].PTR) and the buffer size (SEQ[n].CNT). The rate at which a new value is loaded is defined individually for each sequence by SEQ[n].REFRESH. The chaining of sequence 1 following the sequence 0 is implicit, the LOOP.CNT register allows the chaining of sequence 1 to sequence 0 for a determined number of times. In other words, it allows to repeat a complex sequence a number of times in a fully automated way.

In the following code example, sequence 0 is defined with SEQ[0].REFRESH set to 1, meaning that a new PWM duty cycle is pushed every second PWM period. This complex sequence is started with the SEQSTART[0] task, so SEQ[0] is played first. Since SEQ[0].ENDDELAY=1 there will be one PWM period delay between last period on sequence 0 and the first period on sequence 1. Since SEQ[1].ENDDELAY=0 there is no delay 1, so SEQ[0] would be started immediately after the end of SEQ[1]. However, as LOOP.CNT is



1, the playback stops after having played SEQ[1] only once, and both SEQEND[1] and LOOPSDONE are generated (their order is not guaranteed in this case).

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF_PWM0->PRESCALER = (PWM_PRESCALER_PRESCALER DIV 1 <<
                                                    PWM PRESCALER PRESCALER Pos);
NRF_PWM0->COUNTERTOP = (16000 << PWM_COUNTERTOP_COUNTERTOP_Pos); //1 msec
NRF_PWM0->LOOP = (1 << PWM_LOOP_CNT_Pos);</pre>
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(seq0_ram) << PWM_SEQ_PTR_PTR_Pos);</pre>
NRF_PWM0->SEQ[0].CNT = ((sizeof(seq0_ram) / sizeof(uint16_t)) <<
                                                    PWM SEQ CNT CNT Pos);
NRF_PWM0->SEQ[0].REFRESH = 1;
NRF PWM0->SEQ[0].ENDDELAY = 1;
NRF PWM0->SEQ[1].PTR = ((uint32 t)(seq1 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[1].CNT = ((sizeof(seq1_ram) / sizeof(uint16_t)) <<
                                                  PWM SEQ CNT CNT Pos);
NRF_PWM0->SEQ[1].REFRESH = 0;
NRF_PWM0->SEQ[1].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

The decoder can also be configured to asynchronously load new PWM duty cycle. If the DECODER.MODE register is set to NextStep, then the NEXTSTEP task will cause an update of internal compare registers on the next PWM period.

The following figures provide an overview of each part of an arbitrary sequence, in various modes (LOOP.CNT=0 and LOOP.CNT>0). In particular, the following are represented:

- Initial and final duty cycle on the PWM output(s)
- Chaining of SEQ[0] and SEQ[1] if LOOP.CNT>0
- Influence of registers on the sequence
- Events generated during a sequence
- DMA activity (loading of next value and applying it to the output(s))



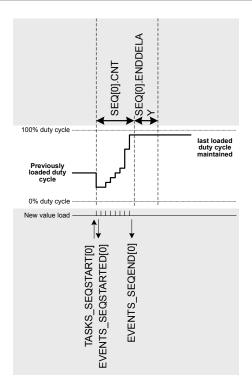


Figure 55: Single shot (LOOP.CNT=0)

Note: The single-shot example also applies to SEQ[1]. Only SEQ[0] is represented for simplicity.

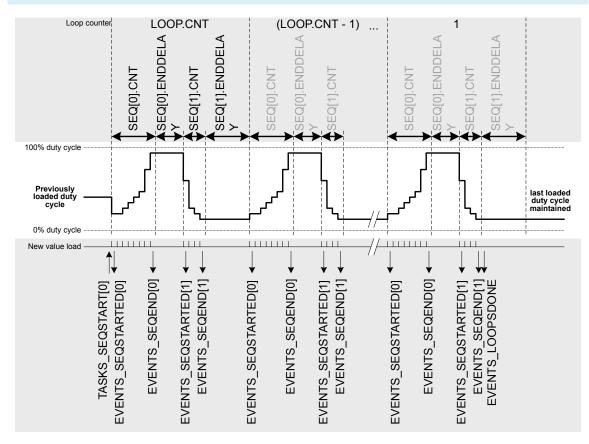


Figure 56: Complex sequence (LOOP.CNT>0) starting with SEQ[0]



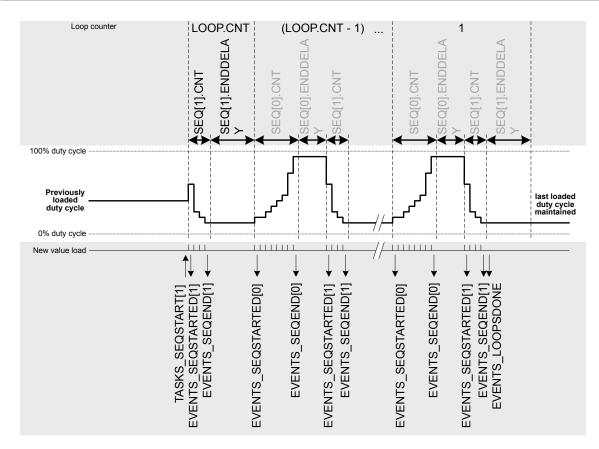


Figure 57: Complex sequence (LOOP.CNT>0) starting with SEQ[1]

Note: If a sequence is in use in a simple or complex sequence, it must have a length of SEQ[n].CNT > 0.

6.12.3 Limitations

Previous compare value is repeated if the PWM period is shorter than the time it takes for the EasyDMA to retrieve from RAM and update the internal compare registers. This is to ensure a glitch-free operation even for very short PWM periods.

6.12.4 Pin configuration

The OUT[n] (n=0..3) signals associated with each PWM channel are mapped to physical pins according to the configuration of PSEL.OUT[n] registers. If PSEL.OUT[n].CONNECT is set to Disconnected, the associated PWM module signal will not be connected to any physical pins.

The PSEL.OUT[n] registers and their configurations are used as long as the PWM module is enabled and the PWM generation active (wave counter started). They are retained only as long as the device is in System ON mode (see section POWER for more information about power modes).

To ensure correct behavior in the PWM module, the pins that are used must be configured in the GPIO peripheral in the following way before the PWM module is enabled:

PWM signal	PWM pin	Direction	Output value	Comment
OUT[n]	As specified in PSEL.OUT[n]	Output	0	Idle state defined in GPIO OUT
	(n=03)			register

Table 55: Recommended GPIO configuration before starting PWM generation



The idle state of a pin is defined by the OUT register in the GPIO module, to ensure that the pins used by the PWM module are driven correctly. If PWM generation is stopped by triggering a STOP task, the PWM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected pins (I/Os) for as long as the PWM module is supposed to be connected to an external PWM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

6.12.5 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4001C000	PWM	PWM0	Pulse-width modulation unit 0	

Table 56: Instances

Register	Offset	Description
TASKS_STOP	0x004	Stops PWM pulse generation on all channels at the end of current PWM period, and stops
		sequence playback
TASKS_SEQSTART[0]	0x008	Loads the first PWM value on all enabled channels from sequence 0, and starts playing
		that sequence at the rate defined in SEQ[0]REFRESH and/or DECODER.MODE. Causes PWM
		generation to start if not running.
TASKS_SEQSTART[1]	0x00C	Loads the first PWM value on all enabled channels from sequence 1, and starts playing
		that sequence at the rate defined in SEQ[1]REFRESH and/or DECODER.MODE. Causes PWM
		generation to start if not running.
TASKS_NEXTSTEP	0x010	Steps by one value in the current sequence on all enabled channels if
		DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.
EVENTS_STOPPED	0x104	Response to STOP task, emitted when PWM pulses are no longer generated
EVENTS_SEQSTARTED[0]	0x108	First PWM period started on sequence 0
EVENTS_SEQSTARTED[1]	0x10C	First PWM period started on sequence 1
EVENTS_SEQEND[0]	0x110	Emitted at end of every sequence 0, when last value from RAM has been applied to wave
		counter
EVENTS_SEQEND[1]	0x114	Emitted at end of every sequence 1, when last value from RAM has been applied to wave
		counter
EVENTS_PWMPERIODEND	0x118	Emitted at the end of each PWM period
EVENTS_LOOPSDONE	0x11C	Concatenated sequences have been played the amount of times defined in LOOP.CNT
SHORTS	0x200	Shortcuts between local events and tasks
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ENABLE	0x500	PWM module enable register
MODE	0x504	Selects operating mode of the wave counter
COUNTERTOP	0x508	Value up to which the pulse generator counter counts
PRESCALER	0x50C	Configuration for PWM_CLK
DECODER	0x510	Configuration of the decoder
LOOP	0x514	Number of playbacks of a loop
SEQ[0].PTR	0x520	Beginning address in RAM of this sequence
SEQ[0].CNT	0x524	Number of values (duty cycles) in this sequence
SEQ[0].REFRESH	0x528	Number of additional PWM periods between samples loaded into compare register
SEQ[0].ENDDELAY	0x52C	Time added after the sequence
SEQ[1].PTR	0x540	Beginning address in RAM of this sequence
SEQ[1].CNT	0x544	Number of values (duty cycles) in this sequence
SEQ[1].REFRESH	0x548	Number of additional PWM periods between samples loaded into compare register
SEQ[1].ENDDELAY	0x54C	Time added after the sequence



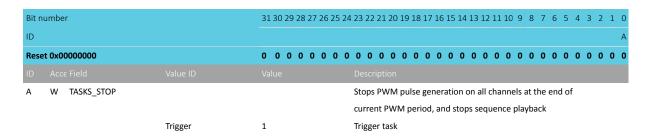
Register	Offset	Description
PSEL.OUT[0]	0x560	Output pin select for PWM channel 0
PSEL.OUT[1]	0x564	Output pin select for PWM channel 1
PSEL.OUT[2]	0x568	Output pin select for PWM channel 2
PSEL.OUT[3]	0x56C	Output pin select for PWM channel 3

Table 57: Register overview

6.12.5.1 TASKS_STOP

Address offset: 0x004

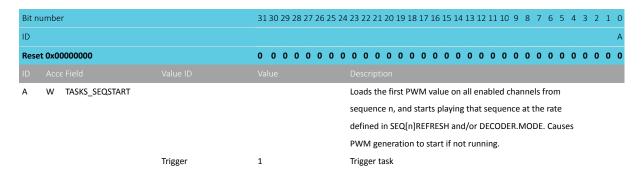
Stops PWM pulse generation on all channels at the end of current PWM period, and stops sequence playback



6.12.5.2 TASKS_SEQSTART[n] (n=0..1)

Address offset: $0x008 + (n \times 0x4)$

Loads the first PWM value on all enabled channels from sequence n, and starts playing that sequence at the rate defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes PWM generation to start if not running.

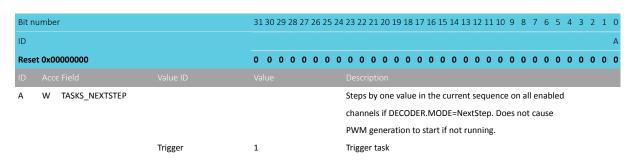


6.12.5.3 TASKS NEXTSTEP

Address offset: 0x010

Steps by one value in the current sequence on all enabled channels if DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.

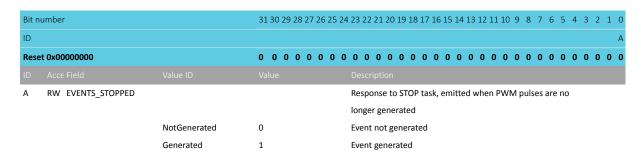




6.12.5.4 EVENTS STOPPED

Address offset: 0x104

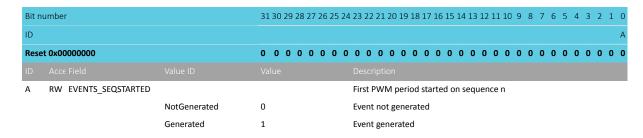
Response to STOP task, emitted when PWM pulses are no longer generated



6.12.5.5 EVENTS SEQSTARTED[n] (n=0..1)

Address offset: $0x108 + (n \times 0x4)$

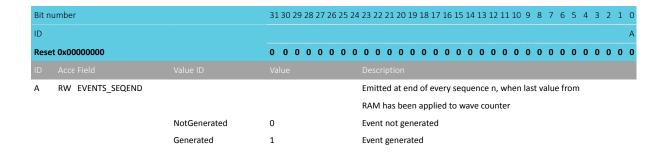
First PWM period started on sequence n



6.12.5.6 EVENTS_SEQEND[n] (n=0..1)

Address offset: $0x110 + (n \times 0x4)$

Emitted at end of every sequence n, when last value from RAM has been applied to wave counter

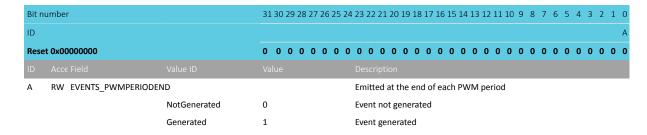




6.12.5.7 EVENTS_PWMPERIODEND

Address offset: 0x118

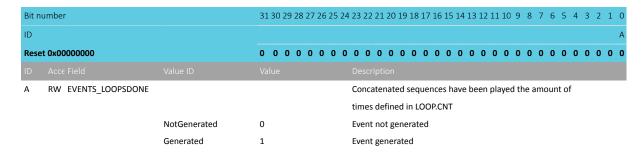
Emitted at the end of each PWM period



6.12.5.8 EVENTS LOOPSDONE

Address offset: 0x11C

Concatenated sequences have been played the amount of times defined in LOOP.CNT



6.12.5.9 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E D C B A
Reset 0x00000000			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW SEQENDO_STOP			Shortcut between event SEQEND[0] and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
В	RW SEQEND1_STOP			Shortcut between event SEQEND[1] and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
С	RW LOOPSDONE_SEQSTART	ГО		Shortcut between event LOOPSDONE and task SEQSTART[0]
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
D	RW LOOPSDONE_SEQSTART	T1		Shortcut between event LOOPSDONE and task SEQSTART[1]
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
Е	RW LOOPSDONE_STOP			Shortcut between event LOOPSDONE and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut



6.12.5.10 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				HGFEDCB
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	Acce Field	Value ID	Value	Description
В	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
C-D	RW SEQSTARTED[i] (i=01)			Enable or disable interrupt for event SEQSTARTED[i]
		Disabled	0	Disable
		Enabled	1	Enable
E-F	RW SEQEND[i] (i=01)			Enable or disable interrupt for event SEQEND[i]
		Disabled	0	Disable
		Enabled	1	Enable
G	RW PWMPERIODEND			Enable or disable interrupt for event PWMPERIODEND
		Disabled	0	Disable
		Enabled	1	Enable
Н	RW LOOPSDONE			Enable or disable interrupt for event LOOPSDONE
		Disabled	0	Disable
		Enabled	1	Enable
		Enabled Disabled	0	Disable Enable Enable or disable interrupt for event LOOPSDONE Disable

6.12.5.11 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				HGFEDCB
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
В	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
C-D	RW SEQSTARTED[i] (i=01)			Write '1' to enable interrupt for event SEQSTARTED[i]
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E-F	RW SEQEND[i] (i=01)			Write '1' to enable interrupt for event SEQEND[i]
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW PWMPERIODEND			Write '1' to enable interrupt for event PWMPERIODEND
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW LOOPSDONE			Write '1' to enable interrupt for event LOOPSDONE
		Set	1	Enable
		Disabled	0	Read: Disabled



Reset 0x000000000 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Reset 0x000000000 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	HGFEDCB
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14	13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.12.5.12 INTENCLR

Address offset: 0x308

Disable interrupt

Rit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			0100101010101010101010101010101010101010	H G F E D C B
	t 0x00000000		0 0 0 0 0 0 0 0	000000000000000000000000000000000000000
ID	Acce Field		Value	Description
В	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
C-D	RW SEQSTARTED[i] (i=01)			Write '1' to disable interrupt for event SEQSTARTED[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E-F	RW SEQEND[i] (i=01)			Write '1' to disable interrupt for event SEQEND[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW PWMPERIODEND			Write '1' to disable interrupt for event PWMPERIODEND
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW LOOPSDONE			Write '1' to disable interrupt for event LOOPSDONE
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.12.5.13 ENABLE

Address offset: 0x500

PWM module enable register

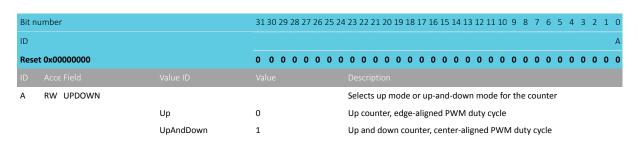
Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW ENABLE			Enable or disable PWM module
		Disabled	0	Disabled
		Enabled	1	Enable

6.12.5.14 MODE

Address offset: 0x504

Selects operating mode of the wave counter





6.12.5.15 COUNTERTOP

Address offset: 0x508

Value up to which the pulse generator counter counts

Bit r	umber	31	30 2	9 28	27	26 2	25 2	4 2	3 2:	2 2	1 20	19	18	17	16 1	15 1	4 13	3 12	11	10 !	9 8	3 7	6	5	4	3	2	1 0
ID																,	4 Α	Α	Α	A	A A	۱ A	Α	Α	Α	Α	A	А А
Res	et 0x000003FF	0	0 0	0	0	0 (0 () (0) (0	0	0	0	0	0 (0	0	0	0	L 1	. 1	1	1	1	1	1 :	1 1
ID																												
Α	RW COUNTERTOP	[3	3276	67]				٧	alu	e u	p to	wh	nich	the	pu	lse	gen	erat	or c	oun	ter	cou	nts.	Th	is			
								r	egis	ter	r is i	gno	red	wh	en l	DEC	ODI	ER.N	100	E=V	Vav	eFo	rm	and	t			
								0	nly	val	lues	fro	m F	RAN	1 ar	e us	ed.											

6.12.5.16 PRESCALER

Address offset: 0x50C

Configuration for PWM_CLK

Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			ААА
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW PRESCALER			Prescaler of PWM_CLK
	DIV_1	0	Divide by 1 (16 MHz)
	DIV_2	1	Divide by 2 (8 MHz)
	DIV_4	2	Divide by 4 (4 MHz)
	DIV_8	3	Divide by 8 (2 MHz)
	DIV_16	4	Divide by 16 (1 MHz)
	DIV_32	5	Divide by 32 (500 kHz)
	DIV_64	6	Divide by 64 (250 kHz)
	DIV_128	7	Divide by 128 (125 kHz)

6.12.5.17 DECODER

Address offset: 0x510

Configuration of the decoder



Bit number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			B A A
Reset 0x0000	0000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Fie			Description
A RW LO	AD		How a sequence is read from RAM and spread to the
			compare register
	Common	0	1st half word (16-bit) used in all PWM channels 03
	Grouped	1	1st half word (16-bit) used in channel 01; 2nd word in
			channel 23
	Individual	2	1st half word (16-bit) in ch.0; 2nd in ch.1;; 4th in ch.3
	WaveForm	3	1st half word (16-bit) in ch.0; 2nd in ch.1;; 4th in
			COUNTERTOP
B RW M	ODE		Selects source for advancing the active sequence
	RefreshCount	0	SEQ[n].REFRESH is used to determine loading internal
			compare registers
	NextStep	1	NEXTSTEP task causes a new value to be loaded to internal
			compare registers

6.12.5.18 LOOP

Address offset: 0x514

Number of playbacks of a loop

Reset 0x00000000	0 0 0 0 0 0		0 0	0	0 0	0 (0	0	0 0	0	0	0 (0	0

6.12.5.19 SEQ[n].PTR (n=0..1)

Address offset: $0x520 + (n \times 0x20)$

Beginning address in RAM of this sequence



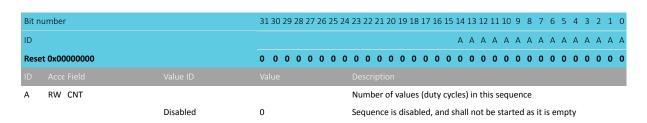
Note: See the memory chapter for details about which memories are available for EasyDMA.

6.12.5.20 SEQ[n].CNT (n=0..1)

Address offset: $0x524 + (n \times 0x20)$

Number of values (duty cycles) in this sequence





6.12.5.21 SEQ[n].REFRESH (n=0..1)

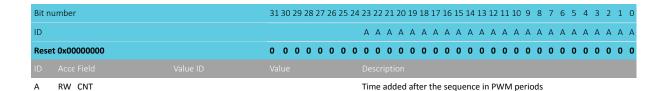
Address offset: $0x528 + (n \times 0x20)$

Number of additional PWM periods between samples loaded into compare register

Bit n	umber		31 30 29 28 27 26	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				A A A A A A A A A A A A A A A A A A A
Rese	t 0x00000001		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CNT			Number of additional PWM periods between samples
				loaded into compare register (load every REFRESH.CNT+1
				PWM periods)
		Continuous	0	Update every PWM period

6.12.5.22 SEQ[n].ENDDELAY (n=0..1)

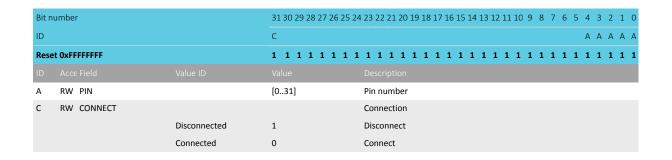
Address offset: $0x52C + (n \times 0x20)$ Time added after the sequence



6.12.5.23 PSEL.OUT[n] (n=0..3)

Address offset: $0x560 + (n \times 0x4)$

Output pin select for PWM channel n



6.13 QDEC — Quadrature decoder

The Quadrature decoder (QDEC) provides buffered decoding of quadrature-encoded sensor signals. It is suitable for mechanical and optical sensors.



The sample period and accumulation are configurable to match application requirements. The QDEC provides the following:

- Decoding of digital waveform from off-chip quadrature encoder.
- Sample accumulation eliminating hard real-time requirements to be enforced on application.
- Optional input de-bounce filters.
- Optional LED output signal for optical encoders.

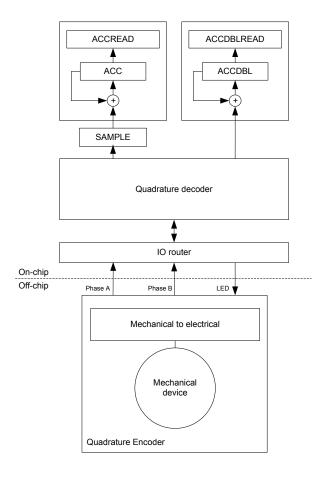


Figure 58: Quadrature decoder configuration

6.13.1 Sampling and decoding

The QDEC decodes the output from an incremental motion encoder by sampling the QDEC phase input pins (A and B).

The off-chip quadrature encoder is an incremental motion encoder outputting two waveforms, phase A and phase B. The two output waveforms are always 90 degrees out of phase, meaning that one always changes level before the other. The direction of movement is indicated by which of these two waveforms that changes level first. Invalid transitions may occur, that is when the two waveforms switch simultaneously. This may occur if the wheel rotates too fast relative to the sample rate set for the decoder.

The QDEC decodes the output from the off-chip encoder by sampling the QDEC phase input pins (A and B) at a fixed rate as specified in the SAMPLEPER register.

If the SAMPLEPER value needs to be changed, the QDEC shall be stopped using the STOP task. SAMPLEPER can be then changed upon receiving the STOPPED event, and QDEC can be restarted using the START task. Failing to do so may result in unpredictable behaviour.



It is good practice to change other registers (LEDPOL, REPORTPER, DBFEN and LEDPRE) only when the QDEC is stopped.

When started, the decoder continuously samples the two input waveforms and decodes these by comparing the current sample pair (n) with the previous sample pair (n-1).

The decoding of the sample pairs is described in the table below.

Previo	ous le pair(n	Curre		SAMPLE register	ACC operation	ACCDBL operation	Description
- 1)	.с ра (pair(n		. eg.ste.		operation.	
Α	В	Α	В				
0	0	0	0	0	No change	No change	No movement
0	0	0	1	1	Increment	No change	Movement in positive direction
0	0	1	0	-1	Decrement	No change	Movement in negative direction
0	0	1	1	2	No change	Increment	Error: Double transition
0	1	0	0	-1	Decrement	No change	Movement in negative direction
0	1	0	1	0	No change	No change	No movement
0	1	1	0	2	No change	Increment	Error: Double transition
0	1	1	1	1	Increment	No change	Movement in positive direction
1	0	0	0	1	Increment	No change	Movement in positive direction
1	0	0	1	2	No change	Increment	Error: Double transition
1	0	1	0	0	No change	No change	No movement
1	0	1	1	-1	Decrement	No change	Movement in negative direction
1	1	0	0	2	No change	Increment	Error: Double transition
1	1	0	1	-1	Decrement	No change	Movement in negative direction
1	1	1	0	1	Increment	No change	Movement in positive direction
1	1	1	1	0	No change	No change	No movement

Table 58: Sampled value encoding

6.13.2 LED output

The LED output follows the sample period, and the LED is switched on a given period before sampling and switched off immediately after the inputs are sampled. The period the LED is switched on before sampling is given in the LEDPRE register.

The LED output pin polarity is specified in the LEDPOL register.

For using off-chip mechanical encoders not requiring a LED, the LED output can be disabled by writing value 'Disconnected' to the CONNECT field of the PSEL.LED register. In this case the QDEC will not acquire access to a LED output pin and the pin can be used for other purposes by the CPU.

6.13.3 Debounce filters

Each of the two-phase inputs have digital debounce filters.

When enabled through the DBFEN register, the filter inputs are sampled at a fixed 1 MHz frequency during the entire sample period (which is specified in the SAMPLEPER register), and the filters require all of the samples within this sample period to equal before the input signal is accepted and transferred to the output of the filter.

As a result, only input signal with a steady state longer than twice the period specified in SAMPLEPER are guaranteed to pass through the filter, and any signal with a steady state shorter than SAMPLEPER will always be suppressed by the filter. (This is assumed that the frequency during the debounce period never exceeds 500 kHz (as required by the Nyquist theorem when using a 1 MHz sample frequency).

The LED will always be ON when the debounce filters are enabled, as the inputs in this case will be sampled continuously.



Note that when when the debounce filters are enabled, displacements reported by the QDEC peripheral are delayed by one SAMPLEPER period.

6.13.4 Accumulators

The quadrature decoder contains two accumulator registers, ACC and ACCDBL, that accumulate respectively valid motion sample values and the number of detected invalid samples (double transitions).

The ACC register will accumulate all valid values (1/-1) written to the SAMPLE register. This can be useful for preventing hard real-time requirements from being enforced on the application. When using the ACC register the application does not need to read every single sample from the SAMPLE register, but can instead fetch the ACC register whenever it fits the application. The ACC register will always hold the relative movement of the external mechanical device since the previous clearing of the ACC register. Sample values indicating a double transition (2) will not be accumulated in the ACC register.

An ACCOF event will be generated if the ACC receives a SAMPLE value that would cause the register to overflow or underflow. Any SAMPLE value that would cause an ACC overflow or underflow will be discarded, but any samples not causing the ACC to overflow or underflow will still be accepted.

The accumulator ACCDBL accumulates the number of detected double transitions since the previous clearing of the ACCDBL register.

The ACC and ACCDBL registers can be cleared by the READCLRACC and subsequently read using the ACCREAD and ACCDBLREAD registers.

The ACC register can be separately cleared by the RDCLRACC and subsequently read using the ACCREAD registers.

The ACCDBL register can be separately cleared by the RDCLRDBL and subsequently read using the ACCDBLREAD registers.

The REPORTPER register allows automating the capture of several samples before it can send out a REPORTRDY event in case a non-null displacement has been captured and accumulated, and a DBLRDY event in case one or more double-displacements have been captured and accumulated. The REPORTPER field in this register selects after how many samples the accumulators contents are evaluated to send (or not) REPORTRDY and DBLRDY events.

Using the RDCLRACC task (manually sent upon receiving the event, or using the DBLRDY_RDCLRACC shortcut), ACCREAD can then be read.

In case at least one double transition has been captured and accumulated, a DBLRDY event is sent. Using the RDCLRDBL task (manually sent upon receiving the event, or using the DBLRDY_RDCLRDBL shortcut), ACCDBLREAD can then be read.

6.13.5 Output/input pins

The QDEC uses a three-pin interface to the off-chip quadrature encoder.

These pins will be acquired when the QDEC is enabled in the ENABLE register. The pins acquired by the QDEC cannot be written by the CPU, but they can still be read by the CPU.

The pin numbers to be used for the QDEC are selected using the PSEL.n registers.

6.13.6 Pin configuration

The Phase A, Phase B, and LED signals are mapped to physical pins according to the configuration specified in the PSEL.A, PSEL.B, and PSEL.LED registers respectively.

If the CONNECT field value 'Disconnected' is specified in any of these registers, the associated signal will not be connected to any physical pin. The PSEL.A, PSEL.B, and PSEL.LED registers and their configurations are only used as long as the QDEC is enabled, and retained only as long as the device is in ON mode.



When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register.

To secure correct behavior in the QDEC, the pins used by the QDEC must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 173 before enabling the QDEC. This configuration must be retained in the GPIO for the selected IOs as long as the QDEC is enabled.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

QDEC signal	QDEC pin	Direction	Output value	Comment
Phase A	As specified in PSEL.A	Input	Not applicable	
Phase B	As specified in PSEL.B	Input	Not applicable	
LED	As specified in PSEL.LED	Input	Not applicable	

Table 59: GPIO configuration before enabling peripheral

6.13.7 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40012000	QDEC	QDEC	Quadrature decoder	

Table 60: Instances

Register	Offset	Description
TASKS_START	0x000	Task starting the quadrature decoder
TASKS_STOP	0x004	Task stopping the quadrature decoder
TASKS_READCLRACC	0x008	Read and clear ACC and ACCDBL
TASKS_RDCLRACC	0x00C	Read and clear ACC
TASKS_RDCLRDBL	0x010	Read and clear ACCDBL
EVENTS_SAMPLERDY	0x100	Event being generated for every new sample value written to the SAMPLE register
EVENTS_REPORTRDY	0x104	Non-null report ready
EVENTS_ACCOF	0x108	ACC or ACCDBL register overflow
EVENTS_DBLRDY	0x10C	Double displacement(s) detected
EVENTS_STOPPED	0x110	QDEC has been stopped
SHORTS	0x200	Shortcuts between local events and tasks
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ENABLE	0x500	Enable the quadrature decoder
LEDPOL	0x504	LED output pin polarity
SAMPLEPER	0x508	Sample period
SAMPLE	0x50C	Motion sample value
REPORTPER	0x510	Number of samples to be taken before REPORTRDY and DBLRDY events can be generated
ACC	0x514	Register accumulating the valid transitions
ACCREAD	0x518	Snapshot of the ACC register, updated by the READCLRACC or RDCLRACC task
PSEL.LED	0x51C	Pin select for LED signal
PSEL.A	0x520	Pin select for A signal
PSEL.B	0x524	Pin select for B signal
DBFEN	0x528	Enable input debounce filters
LEDPRE	0x540	Time period the LED is switched ON prior to sampling
ACCDBL	0x544	Register accumulating the number of detected double transitions



Register	Offset	Description
ACCDBLREAD	0x548	Snapshot of the ACCDBL, updated by the READCLRACC or RDCLRDBL task

Table 61: Register overview

6.13.7.1 TASKS_START

Address offset: 0x000

Task starting the quadrature decoder

When started, the SAMPLE register will be continuously updated at the rate given in the SAMPLEPER register.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_START			Task starting the quadrature decoder
				When started, the SAMPLE register will be continuously
				updated at the rate given in the SAMPLEPER register.
		Trigger	1	Trigger task

6.13.7.2 TASKS STOP

Address offset: 0x004

Task stopping the quadrature decoder

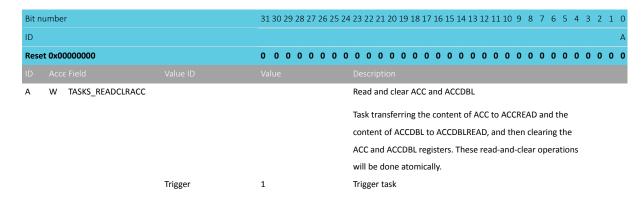
Bit n	umber		31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOP			Task stopping the quadrature decoder
		Trigger	1	Trigger task

6.13.7.3 TASKS READCLRACC

Address offset: 0x008

Read and clear ACC and ACCDBL

Task transferring the content of ACC to ACCREAD and the content of ACCDBL to ACCDBLREAD, and then clearing the ACC and ACCDBL registers. These read-and-clear operations will be done atomically.



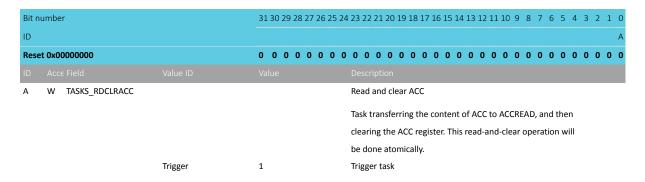


6.13.7.4 TASKS_RDCLRACC

Address offset: 0x00C

Read and clear ACC

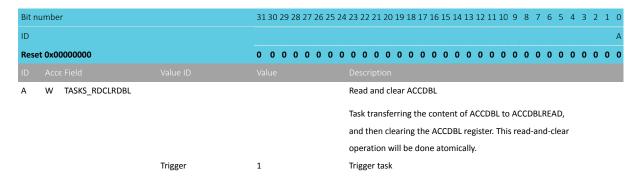
Task transferring the content of ACC to ACCREAD, and then clearing the ACC register. This read-and-clear operation will be done atomically.



6.13.7.5 TASKS_RDCLRDBL

Address offset: 0x010
Read and clear ACCDBL

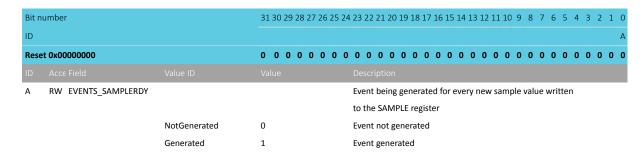
Task transferring the content of ACCDBL to ACCDBLREAD, and then clearing the ACCDBL register. This readand-clear operation will be done atomically.



6.13.7.6 EVENTS SAMPLERDY

Address offset: 0x100

Event being generated for every new sample value written to the SAMPLE register



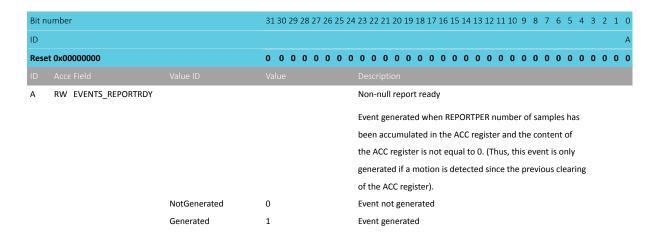
6.13.7.7 EVENTS_REPORTRDY

Address offset: 0x104



Non-null report ready

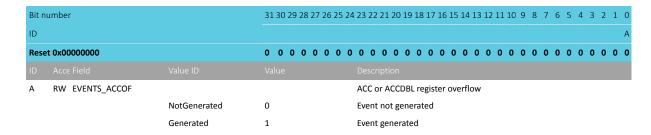
Event generated when REPORTPER number of samples has been accumulated in the ACC register and the content of the ACC register is not equal to 0. (Thus, this event is only generated if a motion is detected since the previous clearing of the ACC register).



6.13.7.8 EVENTS_ACCOF

Address offset: 0x108

ACC or ACCDBL register overflow



6.13.7.9 EVENTS_DBLRDY

Address offset: 0x10C

Double displacement(s) detected

Event generated when REPORTPER number of samples has been accumulated and the content of the ACCDBL register is not equal to 0. (Thus, this event is only generated if a double transition is detected since the previous clearing of the ACCDBL register).

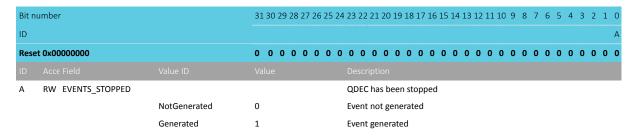


Bit number		31 30 29 28 27 26	$25\; 24\; 23\; 22\; 21\; 20\; 19\; 18\; 17\; 16\; 15\; 14\; 13\; 12\; 11\; 10\; 9\; 8\; 7\; 6\; 5\; 4\; 3\; 2\; 1\; 0$
ID			A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_DBLRDY			Double displacement(s) detected
			Event generated when REPORTPER number of samples has
			been accumulated and the content of the ACCDBL register
			is not equal to 0. (Thus, this event is only generated if a
			double transition is detected since the previous clearing of
			the ACCDBL register).
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.13.7.10 EVENTS_STOPPED

Address offset: 0x110

QDEC has been stopped



6.13.7.11 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit number			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW REPORTRDY_READCLR	ACC		Shortcut between event REPORTRDY and task READCLRACC
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
В	RW SAMPLERDY_STOP			Shortcut between event SAMPLERDY and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
С	RW REPORTRDY_RDCLRAC	cc		Shortcut between event REPORTRDY and task RDCLRACC
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
D	RW REPORTRDY_STOP			Shortcut between event REPORTRDY and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
Е	RW DBLRDY_RDCLRDBL			Shortcut between event DBLRDY and task RDCLRDBL
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
F	RW DBLRDY_STOP			Shortcut between event DBLRDY and task STOP
		Disabled	0	Disable shortcut



Bit n	umber		31 30	29 :	28 2	7 26	5 25	24	23 2	22 2	21 20) 19	18	17	16 1	.5 1	4 13	12	11 10	9	8	7	6	5	4	3 2	2 1	0
ID																							G	F	Ε	D (В	Α
Rese	t 0x00000000		0 0	0	0 0	0	0	0	0	0	0 0	0	0	0	0	0 0	0	0	0 0	0	0	0	0	0	0	0 (0	0
ID																												
		Enabled	1						Ena	ble	sho	rtcu	it															
G	RW SAMPLERDY_READCLR.	ACC							Sho	rtcı	ut be	etwe	een	eve	nt S	SAN	PLE	RDY	and	task	RE	AD	CLF	RAC	C			
		Disabled	0						Disa	able	sho	ortcı	ut															
		Enabled	1						Ena	ble	sho	rtcu	it															

6.13.7.12 INTENSET

Address offset: 0x304

Enable interrupt

ID Rese					4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (
Rese					E D C B A
	et 0x00000000		0 0 0 0 0	0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW SAMPLERDY				Write '1' to enable interrupt for event SAMPLERDY
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
В	RW REPORTRDY				Write '1' to enable interrupt for event REPORTRDY
					Event generated when REPORTPER number of samples has
					been accumulated in the ACC register and the content of
					the ACC register is not equal to 0. (Thus, this event is only
					generated if a motion is detected since the previous clearing
					of the ACC register).
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
С	RW ACCOF				Write '1' to enable interrupt for event ACCOF
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
D	RW DBLRDY				Write '1' to enable interrupt for event DBLRDY
					Event generated when REPORTPER number of samples has
					been accumulated and the content of the ACCDBL register
					is not equal to 0. (Thus, this event is only generated if a
					double transition is detected since the previous clearing of
					the ACCDBL register).
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
E	RW STOPPED				Write '1' to enable interrupt for event STOPPED
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled

6.13.7.13 INTENCLR

Address offset: 0x308

Disable interrupt



Reset 0x00000000	2 1	2	3		4	5	5	6	7	7	8	8	9	9	9	!) !) !	9	9	9	9	9)		1	8	8	3		1	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7		3	8	8))	Э	9	9	Э	Э))))))))))))))))))	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9
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Disabled 0 Read: Disabled																																																																																																																
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6.13.7.14 ENABLE

Address offset: 0x500

Enable the quadrature decoder

Bit number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW ENABLE		Enable or disable the quadrature decoder
		When enabled the decoder pins will be active. When
		disabled the quadrature decoder pins are not active and can
		be used as GPIO .
Disabled	0	Disable
Enabled	1	Enable



6.13.7.15 LEDPOL

Address offset: 0x504 LED output pin polarity

Bit number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW LEDPOL			LED output pin polarity
	ActiveLow	0	Led active on output pin low
	ActiveHigh	1	Led active on output pin high

6.13.7.16 SAMPLEPER

Address offset: 0x508

Sample period

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW SAMPLEPER			Sample period. The SAMPLE register will be updated for
				every new sample
		128us	0	128 us
		256us	1	256 us
		512us	2	512 us
		1024us	3	1024 us
		2048us	4	2048 us
		4096us	5	4096 us
		8192us	6	8192 us
		16384us	7	16384 us
		32ms	8	32768 us
		65ms	9	65536 us
		131ms	10	131072 us

6.13.7.17 SAMPLE

Address offset: 0x50C Motion sample value

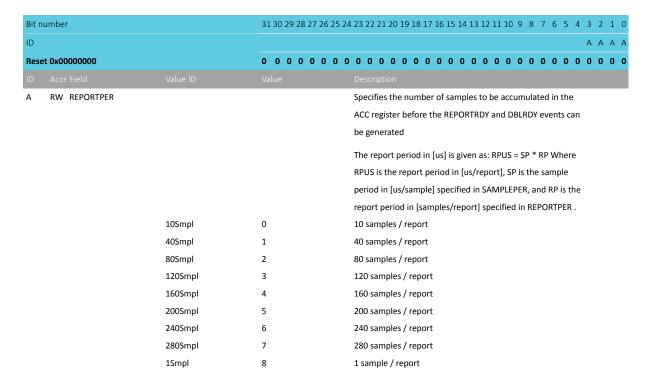
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 1	.5 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A A A A A A A A A A A A A	A A A A A A A A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		
A R SAMPLE	[-12] Last motion sample	
	·	ment value, and the sign gives the
	transition.	The value 2 indicates a double



6.13.7.18 REPORTPER

Address offset: 0x510

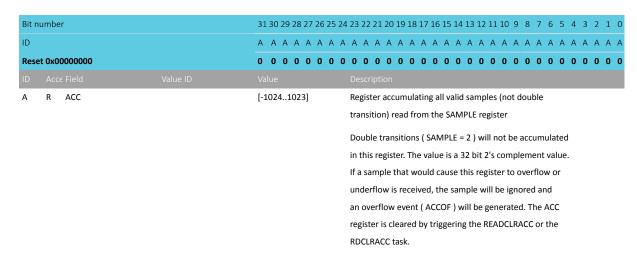
Number of samples to be taken before REPORTRDY and DBLRDY events can be generated



6.13.7.19 ACC

Address offset: 0x514

Register accumulating the valid transitions



6.13.7.20 ACCREAD

Address offset: 0x518

Snapshot of the ACC register, updated by the READCLRACC or RDCLRACC task



ID	
<u> </u>	
A A A A A A A A A A A A A A A A A A A	AAAA
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5	4 3 2 1 0

The ACCREAD register is updated when the READCLRACC or RDCLRACC task is triggered

6.13.7.21 PSEL.LED

Address offset: 0x51C Pin select for LED signal

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 :	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect

6.13.7.22 PSEL.A

Address offset: 0x520 Pin select for A signal

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.13.7.23 PSEL.B

Address offset: 0x524 Pin select for B signal

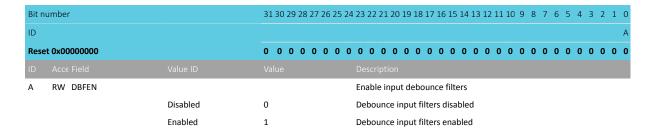
Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
С	RW CONNECT	Disconnected	1	Connection Disconnect



6.13.7.24 DBFEN

Address offset: 0x528

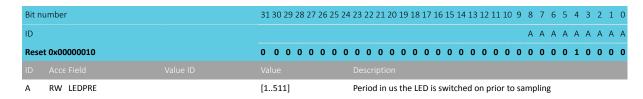
Enable input debounce filters



6.13.7.25 LEDPRE

Address offset: 0x540

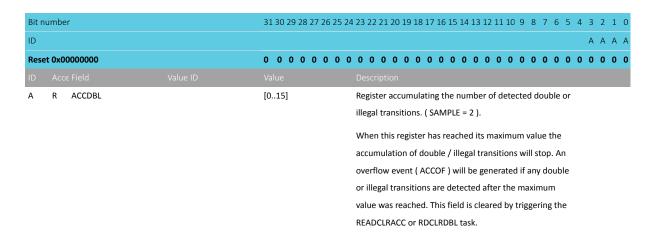
Time period the LED is switched ON prior to sampling



6.13.7.26 ACCDBL

Address offset: 0x544

Register accumulating the number of detected double transitions

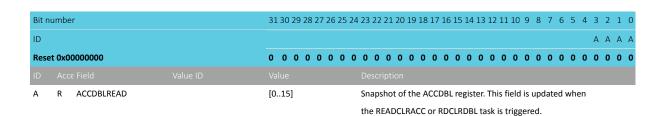


6.13.7.27 ACCDBLREAD

Address offset: 0x548

Snapshot of the ACCDBL, updated by the READCLRACC or RDCLRDBL task





6.13.8 Electrical specification

6.13.8.1 QDEC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{SAMPLE}	Time between sampling signals from quadrature decoder	128		131072	μs
t _{LED}	Time from LED is turned on to signals are sampled	0		511	μs

6.14 RADIO — 2.4 GHz radio

The 2.4 GHz radio transceiver is compatible with multiple radio standards, such as 1 Mbps and 2 Mbps $Bluetooth^{@}$ low energy, as well as Nordic's proprietary 1 Mbps and 2 Mbps modes of operation.

EasyDMA in combination with an automated packet assembler and packet disassembler, and an automated CRC generator and CRC checker, makes it very easy to configure and use the RADIO. See RADIO block diagram on page 184 for details.

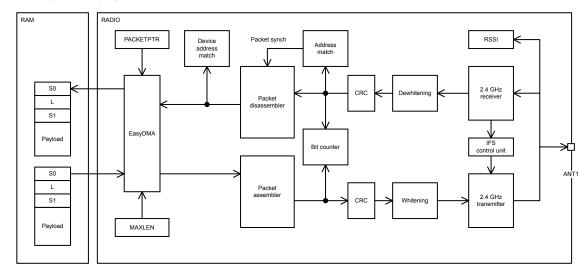


Figure 59: RADIO block diagram

The RADIO includes a device address match unit and an interframe spacing control unit that can be utilized to simplify address white listing and interframe spacing respectively, in *Bluetooth*[®] Smart and similar applications.

The RADIO also includes a received signal strength indicator (RSSI) and a bit counter. The bit counter generates events when a preconfigured number of bits have been sent or received by the RADIO.

6.14.1 EasyDMA

The RADIO peripheral uses EasyDMA for reading of data packets from and writing to RAM, without CPU involvement.



As illustrated in RADIO block diagram on page 184, the RADIO's EasyDMA utilizes the same PACKETPTR on page 204 for receiving and transmitting packets, and this pointer can only point to the Data RAM region. See Memory on page 17 for more information about the different memoryregions.

The DISABLED event indicates that the EasyDMA has finished accessing the RAM.

The structure of a radio packet is described in detail in Packet configuration on page 185. The data that is stored in Data RAM and transported by EasyDMA consists of the following fields:

- S0
- LENGTH
- S1
- PAYLOAD

In addition, a static add-on is sent immediately after the payload.

The size of each of the above fields in the frame is configurable, and the space occupied in RAM depends on these settings. A size of zero is possible for any of the fields, it is up to the user to make sure that the resulting frame complies with the RF protocol chosen. For the field sizes defined in bits, the occupation in RAM will always be rounded up to the next full byte size (for instance 3 bit length will allocate 1 byte in RAM, 9 bit length will allocate 2 bytes, etc.).

The sizes of the fields SO, LENGTH and S1 can be individually configured by the SOLEN, LFLEN and S1LEN fields of the PCNFO register respectively. The size of the payload is configured through the value in RAM corresponding to the LENGTH field. The size of the static add-on to the payload is configured through the STATLEN field in PCNF1 register.

The MAXLEN field in the PCNF1 register configures the maximum packet payload plus add-on size in number of bytes that can be transmitted or received by the RADIO. This feature can be used to ensure that the RADIO does not overwrite, or read beyond, the RAM assigned to the packet payload. This means that if the packet payload length defined by the PCNF1.STATLEN and the LENGTH field in the packet specify a packet larger than MAXLEN, the payload will be truncated at MAXLEN. The packet's LENGTH field will not be altered when the payload is truncated. The RADIO will calculate CRC as if the packet length is equal to MAXLEN.

Important: Note that MAXLEN includes the size of the payload and the add-on, but excludes the size occupied by the fields SO, LENGTH and S1. This has to be taken into account when allocating RAM.

6.14.2 Packet configuration

RADIO packet contains the following fields: PREAMBLE, ADDRESS, SO, LENGTH, S1, PAYLOAD and CRC.

The content of a RADIO packet is illustrated in On-air packet layout on page 185. The RADIO sends the different fields in the packet in the order they are illustrated below, from left to right:



Figure 60: On-air packet layout

PREAMBLE is sent with least significant bit first on-air. The size of the PREAMBLE depends on the mode selected in the MODE register:

• The PREAMBLE is one byte for MODE = Ble_1Mbit as well as all Nordic proprietary operating modes (MODE = Nrf_1Mbit and MODE = Nrf_2Mbit), and the PLEN field in the PCNFO register has to be set accordingly. If the first bit of the ADDRESS is 0 the preamble will be set to 0xAA otherwise the PREAMBLE will be set to 0x55.



• For MODE = Ble_2Mbit the PREAMBLE has to be set to 2 byte long through the PLEN field in the PCNFO register. If the first bit of the ADDRESS is 0 the preamble will be set to 0xAAAA otherwise the PREAMBLE will be set to 0x5555.

Not shown in the figure above is the static payload add-on (the length of which is defined in PCNF1.STATLEN, and which is 0 bytes long in a standard BLE packet). The static payload add-on is sent between the PAYLOAD and CRC fields.

The RADIO packets are stored in memory, inside instances of a radio packet data structure as illustrated in In-RAM representation of radio packet - SO, LENGTH and S1 are optional on page 186. The PREAMBLE, ADDRESS and CRC fields are omitted in this data structure.



Figure 61: In-RAM representation of radio packet - SO, LENGTH and S1 are optional

The byte ordering on the air is always:

- Least significant byte first for the fields ADDRESS and PAYLOAD. The ADDRESS fields are also always transmitted and received least significant bit first on-air.
- Most significant byte first for the CRC field. The CRC field is also always transmitted and received most significant bit first.

The bit endianness, i.e. the order in which the bits are sent and received, is configured in PCNF1.ENDIAN for the fields S0, LENGTH, S1 and PAYLOAD.

The sizes of the fields SO, LENGTH and S1 can be individually configured in the SOLEN, LFLEN and S1LEN fields of the PCNFO register respectively. If any of these fields are configured to be less than 8 bit long, the least significant bits of the fields are used, as seen from the RAM representation.

If S0, LENGTH or S1 are specified with zero length, their fields will be omitted in memory. Otherwise each field will be represented as a separate byte, regardless of the number of bits in their on-air counterpart.

6.14.3 Maximum packet length

Independent of the configuration of MAXLEN, the combined length of SO, LENGTH, S1 and PAYLOAD cannot exceed 258 bytes.

6.14.4 Address configuration

The on-air radio ADDRESS field is composed of two parts, the base address field and the address prefix field.

The size of the base address field is configurable via BALEN in PCNF1. The base address is truncated from LSByte if the BALEN is less than 4. See Definition of logical addresses on page 187.

The on-air addresses are defined in the BASEn and PREFIXn registers, and it is only when writing these registers the user will have to relate to actual on-air addresses. For other radio address registers such as the TXADDRESS, RXADDRESSES and RXMATCH registers, logical radio addresses ranging from 0 to 7 are being used. The relationship between the on-air radio addresses and the logical addresses is described in Definition of logical addresses on page 187.



Logical address	Base address	Prefix byte
0	BASE0	PREFIXO.APO
1	BASE1	PREFIXO.AP1
2	BASE1	PREFIXO.AP2
3	BASE1	PREFIXO.AP3
4	BASE1	PREFIX1.AP4
5	BASE1	PREFIX1.AP5
6	BASE1	PREFIX1.AP6
7	BASE1	PREFIX1.AP7

Table 62: Definition of logical addresses

6.14.5 Data whitening

The RADIO is able to do packet whitening and de-whitening.

See WHITEEN in PCNF1 register for how to enable whitening. When enabled, whitening and de-whitening will be handled by the RADIO automatically as packets are sent and received.

The whitening word is generated using polynomial $g(D) = D^7 + D^4 + 1$, which then is XORed with the data packet that is to be whitened, or de-whitened. See the figure below.

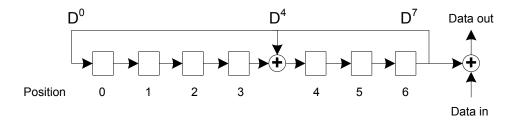


Figure 62: Data whitening and de-whitening

Whitening and de-whitening will be performed over the whole packet (except for the preamble and the address field).

The linear feedback shift register, illustrated in Data whitening and de-whitening on page 187 can be initialised via the DATAWHITEIV register.

6.14.6 CRC

The CRC generator in the RADIO calculates the CRC over the whole packet excluding the preamble. If desirable, the address field can be excluded from the CRC calculation as well

See CRCCNF register for more information.

The CRC polynomial is configurable as illustrated in CRC generation of an n bit CRC on page 188 where bit 0 in the CRCPOLY register corresponds to X^0 and bit 1 corresponds to X^1 etc. See CRCPOLY for more information.



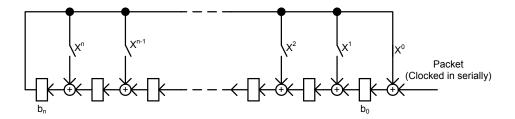


Figure 63: CRC generation of an n bit CRC

As illustrated in CRC generation of an n bit CRC on page 188, the CRC is calculated by feeding the packet serially through the CRC generator. Before the packet is clocked through the CRC generator, the CRC generator's latches b_0 through b_n will be initialized with a predefined value specified in the CRCINIT register. When the whole packet is clocked through the CRC generator, latches b_0 through b_n will hold the resulting CRC. This value will be used by the RADIO during both transmission and reception but it is not available to be read by the CPU at any time. A received CRC can however be read by the CPU via the RXCRC register independent of whether or not it has passed the CRC check.

The length (n) of the CRC is configurable, see CRCCNF for more information.

After the whole packet including the CRC has been received, the RADIO will generate a CRCOK event if no CRC errors were detected, or alternatively generate a CRCERROR event if CRC errors were detected.

The status of the CRC check can be read from the CRCSTATUS register after a packet has been received.

6.14.7 Radio states

The RADIO can enter a number of states.

The RADIO can enter the states described the table below. An overview state diagram for the RADIO is illustrated in Radio states on page 189. This figure shows how the tasks and events relate to the RADIO's operation. The RADIO does not prevent a task from being triggered from the wrong state. If a task is triggered from the wrong state, for example if the RXEN task is triggered from the RXDISABLE state, this may lead to incorrect behaviour. As illustrated in Radio states on page 189, the PAYLOAD event is always generated even if the payload is zero.

State	Description
DISABLED	No operations are going on inside the radio and the power consumption is at a minimum
RXRU	The radio is ramping up and preparing for reception
RXIDLE	The radio is ready for reception to start
RX	Reception has been started and the addresses enabled in the RXADDRESSES register are being monitored
TXRU	The radio is ramping up and preparing for transmission
TXIDLE	The radio is ready for transmission to start
TX	The radio is transmitting a packet
RXDISABLE	The radio is disabling the receiver
TXDISABLE	The radio is disabling the transmitter

Table 63: RADIO state diagram



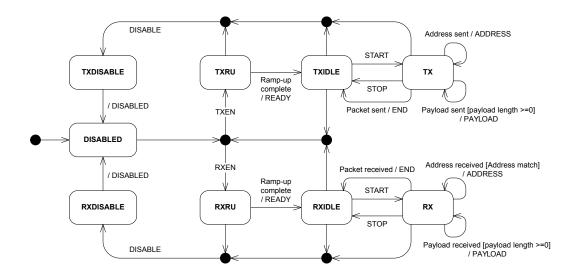


Figure 64: Radio states

6.14.8 Transmit sequence

Before the RADIO is able to transmit a packet, it must first ramp-up in TX mode.

See TXRU in Radio states on page 189 and Transmit sequence on page 189. A TXRU ramp-up sequence is initiated when the TXEN task is triggered. After the radio has successfully ramped up it will generate the READY event indicating that a packet transmission can be initiate. A packet transmission is initiated by triggering the START task. As illustrated in Radio states on page 189 the START task can first be triggered after the RADIO has entered into the TXIDLE state.

Transmit sequence on page 189 illustrates a single packet transmission where the CPU manually triggers the different tasks needed to control the flow of the RADIO, i.e. no shortcuts are used. If shortcuts are not used, a certain amount of delay caused by CPU execution is expected between READY and START, and between END and DISABLE. As illustrated in Transmit sequence on page 189 the RADIO will by default transmit '1's between READY and START, and between END and DISABLED. What is transmitted can be programmed through the DTX field in the MODECNFO register.

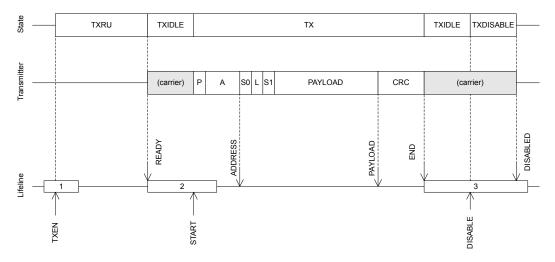


Figure 65: Transmit sequence

A slightly modified version of the transmit sequence from Transmit sequence on page 189 is illustrated in Transmit sequence using shortcuts to avoid delays on page 190 where the RADIO is configured to



use shortcuts between READY and START, and between END and DISABLE, which means that no delay is introduced.

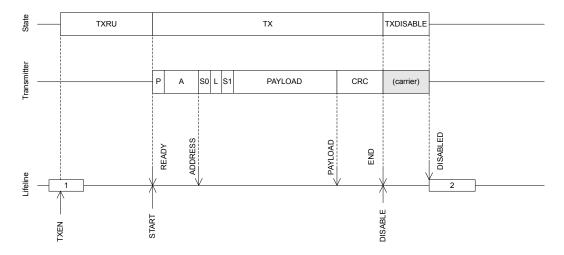


Figure 66: Transmit sequence using shortcuts to avoid delays

The RADIO is able to send multiple packets one after the other without having to disable and re-enable the RADIO between packets, this is illustrated in Transmission of multiple packets on page 190.

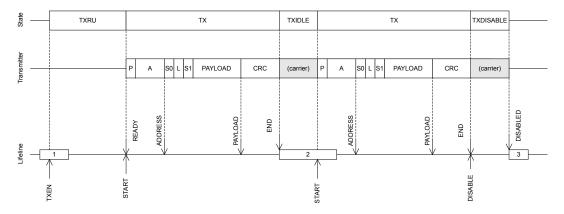


Figure 67: Transmission of multiple packets

6.14.9 Receive sequence

Before the RADIO is able to receive a packet, it must first ramp up in RX mode

See RXRU in Radio states on page 189 and Receive sequence on page 191. An RXRU ramp-up sequence is initiated when the RXEN task is triggered. After the radio has successfully ramped up it will generate the READY event indicating that a packet reception can be initiated. A packet reception is initiated by triggering the START task. As illustrated in Radio states on page 189 the START task can, first be triggered after the RADIO has entered into the RXIDLE state.

Receive sequence on page 191 illustrates a single packet reception where the CPU manually triggers the different tasks needed to control the flow of the RADIO, i.e. no shortcuts are used. If shortcuts are not used, a certain amount of delay, caused by CPU execution, is expected between READY and START, and between END and DISABLE. As illustrated Receive sequence on page 191 the RADIO will be listening and possibly receiving undefined data, illustrated with an 'X', from START and until a packet with valid preamble (P) is received.



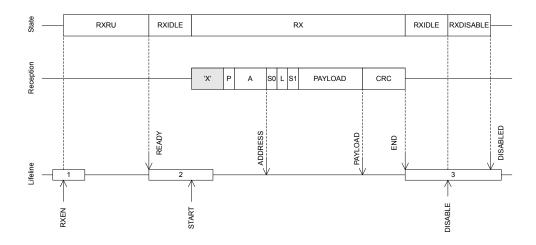


Figure 68: Receive sequence

A slightly modified version of the receive sequence from Receive sequence on page 191 is illustrated in Receive sequence using shortcuts to avoid delays on page 191 where the the RADIO is configured to use shortcuts between READY and START, and between END and DISABLE, which means that no delay is introduced.

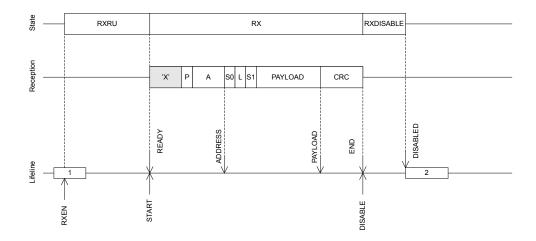


Figure 69: Receive sequence using shortcuts to avoid delays

The RADIO is able to receive multiple packets one after the other without having to disable and re-enable the RADIO between packets, this is illustrated Reception of multiple packets on page 192.



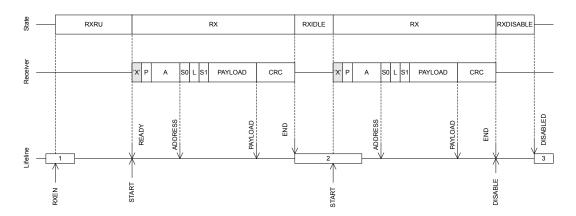


Figure 70: Reception of multiple packets

6.14.10 Received signal strength indicator (RSSI)

The RADIO implements a mechanism for measuring the power in the received signal. This feature is called received signal strength indicator (RSSI).

The RSSI is measured continuously and the value filtered using a single-pole IIR filter. After a signal level change, the RSSI will settle after approximately RSSI_{SETTLE}.

Sampling of the received signal strength is started by using the RSSISTART task. The sample can be read from the RSSISAMPLE register.

The sample period of the RSSI is defined by RSSI_{PERIOD}. The RSSISAMPLE will hold the filtered received signal strength after this sample period.

For the RSSI sample to be valid, the RADIO has to be enabled in receive mode (RXEN task) and the reception has to be started (READY event followed by START task).

6.14.11 Interframe spacing

Interframe spacing is the time interval between two consecutive packets.

It is defined as the time (in microseconds) from the end of the last bit of the previous packet received and to the start of the first bit of the subsequent packet that is transmitted. The radio is able to enforce this interval as specified in the TIFS register as long as TIFS is not specified to be shorter than the radio's turnaround time, i.e. the time needed to switch off the receiver, and switch back on the transmitter.

TIFS is only enforced if END_DISABLE and DISABLED_TXEN or END_DISABLE and DISABLED_RXEN shortcuts are enabled. TIFS is only qualified for use in BLE_1MBIT mode, and default ramp-up mode. The use of shortcuts and timing is illustrated in Ramp up and TIFS Timing Details on page 192.

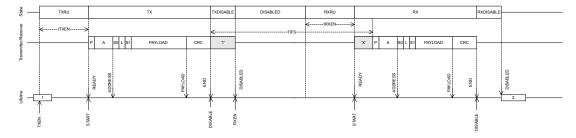


Figure 71: Ramp up and TIFS Timing Details

6.14.12 Device address match

The device address match feature is tailored for address white listing in a *Bluetooth*[®] Smart and similar implementations.



This feature enables on-the-fly device address matching while receiving a packet on air. This feature only works in receive mode and as long as the radio is configured for little endian, see PCNF1.ENDIAN.

The device address match unit assumes that the 48 first bits of the payload is the device address and that bit number 6 in S0 is the TxAdd bit. See the *Bluetooth*[®] Core Specification for more information about device addresses, TxAdd and whitelisting.

The radio is able to listen for eight different device addresses at the same time. These addresses are specified in a DAB/DAP register pair, one pair per address, in addition to a TxAdd bit configured in the DACNF register. The DAB register specifies the 32 least significant bits of the device address, while the DAP register specifies the 16 most significant bits of the device address.

Each of the device addresses can be individually included or excluded from the matching mechanism. This is configured in the DACNF register.

6.14.13 Bit counter

Radio implements a simple counter that can be configured to generate an event after a specific number of bits have been transmitted or received.

By using shortcuts, this counter can be started from different events generated by the radio and hence count relative to these.

The bit counter is started by triggering the BCSTART task, and stopped by triggering the BCSTOP task. A BCMATCH event will be generated when the bit counter has counted the number of bits specified in the BCC register. The bit counter will continue to count bits until the DISABLED event is generated or until the BCSTOP task is triggered. The CPU can therefore, after a BCMATCH event, reconfigure the BCC value for new BCMATCH events within the same packet.

The bit counter can only be started after the radio has received the ADDRESS event.

The bit counter will stop and reset on BCSTOP, STOP, END and DISABLE tasks.

The figure below illustrates how the bit counter can be used to generate a BCMATCH event in the beginning of the packet payload, and again generate a second BCMATCH event after sending 2 bytes (16 bits) of the payload.

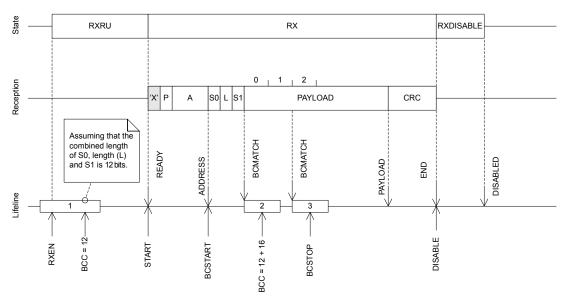


Figure 72: Bit counter example



6.14.14 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40001000	RADIO	RADIO	2.4 GHz radio	

Table 64: Instances

Register	Offset	Description	
TASKS_TXEN	0x000	Enable RADIO in TX mode	
TASKS_RXEN	0x004	Enable RADIO in RX mode	
TASKS_START	0x008	Start RADIO	
TASKS_STOP	0x00C	Stop RADIO	
TASKS_DISABLE	0x010	Disable RADIO	
TASKS_RSSISTART	0x014	Start the RSSI and take one single sample of the receive signal strength.	
TASKS_RSSISTOP	0x018	Stop the RSSI measurement	
TASKS_BCSTART	0x01C	Start the bit counter	
TASKS_BCSTOP	0x020	Stop the bit counter	
EVENTS_READY	0x100	RADIO has ramped up and is ready to be started	
EVENTS_ADDRESS	0x104	Address sent or received	
EVENTS_PAYLOAD	0x108	Packet payload sent or received	
EVENTS_END	0x10C	Packet sent or received	
EVENTS_DISABLED	0x110	RADIO has been disabled	
EVENTS_DEVMATCH	0x114	A device address match occurred on the last received packet	
EVENTS_DEVMISS	0x118	No device address match occurred on the last received packet	
EVENTS_RSSIEND	0x11C	Sampling of receive signal strength complete.	
EVENTS_BCMATCH	0x128	Bit counter reached bit count value.	
EVENTS_CRCOK	0x130	Packet received with CRC ok	
EVENTS_CRCERROR	0x134	Packet received with CRC error	
SHORTS	0x200	Shortcuts between local events and tasks	
INTENSET	0x304	Enable interrupt	
INTENCLR	0x308	Disable interrupt	
CRCSTATUS	0x400	CRC status	
RXMATCH	0x408	Received address	
RXCRC	0x40C	CRC field of previously received packet	
DAI	0x410	Device address match index	
PACKETPTR	0x504	Packet pointer	
FREQUENCY	0x508	Frequency	
TXPOWER	0x50C	Output power	
MODE	0x510	Data rate and modulation	
PCNF0	0x514	Packet configuration register 0	
PCNF1	0x518	Packet configuration register 1	
BASE0	0x51C	Base address 0	
BASE1	0x520	Base address 1	
PREFIXO	0x524	Prefixes bytes for logical addresses 0-3	
PREFIX1	0x528	Prefixes bytes for logical addresses 4-7	
TXADDRESS	0x52C	Transmit address select	
RXADDRESSES	0x530	Receive address select	
CRCCNF	0x534	CRC configuration	
CRCPOLY	0x538	CRC polynomial	
CRCINIT	0x53C	CRC initial value	
UNUSED0	0x540		Reserved
TIFS	0x544	Inter Frame Spacing in us	
RSSISAMPLE	0x548	RSSI sample	



Register	Offset	Description
STATE	0x550	Current radio state
DATAWHITEIV	0x554	Data whitening initial value
BCC	0x560	Bit counter compare
DAB[0]	0x600	Device address base segment 0
DAB[1]	0x604	Device address base segment 1
DAB[2]	0x608	Device address base segment 2
DAB[3]	0x60C	Device address base segment 3
DAB[4]	0x610	Device address base segment 4
DAB[5]	0x614	Device address base segment 5
DAB[6]	0x618	Device address base segment 6
DAB[7]	0x61C	Device address base segment 7
DAP[0]	0x620	Device address prefix 0
DAP[1]	0x624	Device address prefix 1
DAP[2]	0x628	Device address prefix 2
DAP[3]	0x62C	Device address prefix 3
DAP[4]	0x630	Device address prefix 4
DAP[5]	0x634	Device address prefix 5
DAP[6]	0x638	Device address prefix 6
DAP[7]	0x63C	Device address prefix 7
DACNF	0x640	Device address match configuration
MODECNF0	0x650	Radio mode configuration register 0
POWER	0xFFC	Peripheral power control

Table 65: Register overview

6.14.14.1 TASKS_TXEN

Address offset: 0x000 Enable RADIO in TX mode

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_TXEN			Enable RADIO in TX mode
		Trigger	1	Trigger task

6.14.14.2 TASKS_RXEN

Address offset: 0x004
Enable RADIO in RX mode

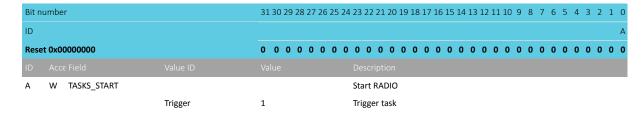
Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_RXEN			Enable RADIO in RX mode
		Trigger	1	Trigger task

6.14.14.3 TASKS_START

Address offset: 0x008



Start RADIO



6.14.14.4 TASKS_STOP

Address offset: 0x00C

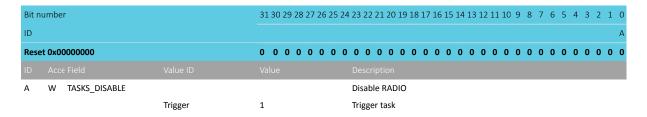
Stop RADIO

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_STOP			Stop RADIO
		Trigger	1	Trigger task

6.14.14.5 TASKS_DISABLE

Address offset: 0x010

Disable RADIO



6.14.14.6 TASKS_RSSISTART

Address offset: 0x014

Start the RSSI and take one single sample of the receive signal strength.

Bit number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A W TASKS_RSSISTART			Start the RSSI and take one single sample of the receive
			signal strength.
	Trigger	1	Trigger task

6.14.14.7 TASKS_RSSISTOP

Address offset: 0x018

Stop the RSSI measurement



Bit n	umb	per		31 30 29	9 28 2	7 26	25 2	4 2	3 22	2 21	L 20	19	18 1	17 :	L6 1	.5 1	.4 1	3 1	2 11	. 10	9	8	7	6	5	4	3	2 1	1 0
ID																													Α
Rese	t Ox	00000000		0 0 0	0	0 0	0 () (0	0	0	0	0	0	0 (0	0 () (0	0	0	0	0	0	0	0	0 (0	D O
ID																													
Α	W	TASKS_RSSISTOP						S	top	the	RSS	SIn	ieas	ure	eme	nt													
			Trigger	1				Ti	rigg	er t	ask																		

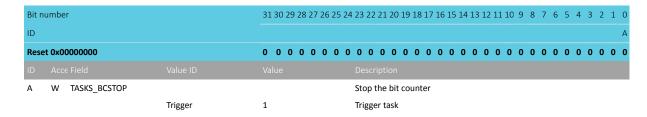
6.14.14.8 TASKS_BCSTART

Address offset: 0x01C Start the bit counter

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_BCSTART			Start the bit counter
		Trigger	1	Trigger task

6.14.14.9 TASKS_BCSTOP

Address offset: 0x020 Stop the bit counter



6.14.14.10 EVENTS_READY

Address offset: 0x100

RADIO has ramped up and is ready to be started

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_READY			RADIO has ramped up and is ready to be started
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.14.14.11 EVENTS_ADDRESS

Address offset: 0x104
Address sent or received



Bit number	31 30 29 28 27	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW EVENTS_ADDRESS		Address sent or received
NotGenerated	0	Event not generated
Generated	1	Event generated

6.14.14.12 EVENTS_PAYLOAD

Address offset: 0x108

Packet payload sent or received

Bit number		31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field			Description
A RW EVENTS_	_PAYLOAD		Packet payload sent or received
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.14.14.13 EVENTS_END

Address offset: 0x10C Packet sent or received

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_END			Packet sent or received
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.14.14.14 EVENTS_DISABLED

Address offset: 0x110 RADIO has been disabled

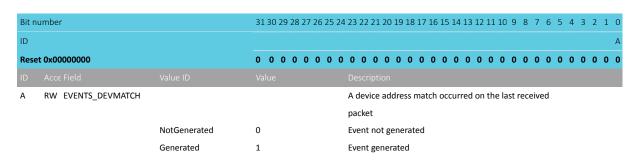
Bit nu	umber		31	30	29	28 2	27 2	6 25	5 24	4 23	3 22	2 21	. 20	19	18	17 :	16 1	.5 1	4 13	3 12	11	10	9 8	7	6	5	4	3	2	1 0
ID																														Α
Rese	t 0x00000000		0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0 (0 (0	0	0	0	0	0	0	0	0	0	0	0 0
ID																														
Α	RW EVENTS_DISABLED									R	٩DI	0 h	as l	oee	n di	sab	led													
		NotGenerated	0							E١	/en	t no	ot ge	ene	rate	ed														
		Generated	1							E۱	/en	t ge	ner	ate	d															

6.14.14.15 EVENTS_DEVMATCH

Address offset: 0x114

A device address match occurred on the last received packet

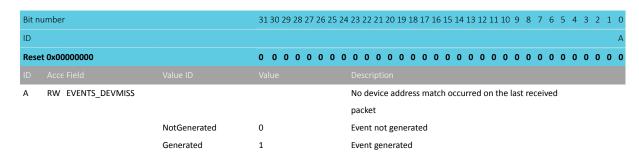




6.14.14.16 EVENTS DEVMISS

Address offset: 0x118

No device address match occurred on the last received packet

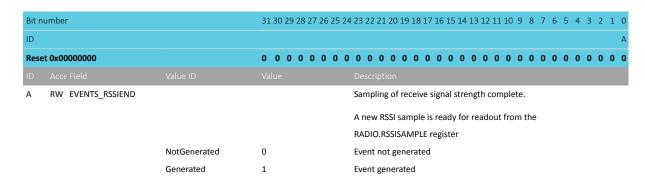


6.14.14.17 EVENTS RSSIEND

Address offset: 0x11C

Sampling of receive signal strength complete.

A new RSSI sample is ready for readout from the RADIO.RSSISAMPLE register



6.14.14.18 EVENTS BCMATCH

Address offset: 0x128

Bit counter reached bit count value.

Bit counter value is specified in the RADIO.BCC register



Bit n	umber		31 30 2	9 28 :	27 2	26 25	5 24	23	22	21 2	0 19	9 18	17	16 1	.5 1	4 13	12	11 1	0 9	8	7	6	5	4	3 2	1	0
ID																											Α
Rese	t 0x00000000		0 0 0	0	0	0 0	0	0	0	0 (0	0	0	0	0 0	0	0	0 (0	0	0	0	0	0	0 0	0	0
ID																											
Α	RW EVENTS_BCMATCH							Bit	co	unte	r re	ache	ed b	it co	ount	val	ue.										
								Bit	co	unte	r va	lue	is sp	ecit	fied	in t	he R	ADI	O.BC	C re	egis	ter					
		NotGenerated	0					Eve	ent	not	gen	erat	ed														
		Generated	1					Eve	ent	gen	erat	ed															

6.14.14.19 EVENTS_CRCOK

Address offset: 0x130

Packet received with CRC ok

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_CRCOK			Packet received with CRC ok
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.14.14.20 EVENTS_CRCERROR

Address offset: 0x134

Packet received with CRC error

Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_CRCERROR			Packet received with CRC error
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.14.14.21 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit r	number		31 30 29 28 27 2	26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					H G F E D C B A
Res	et 0x00000000		0 0 0 0 0	0 0 (0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW READY_START				Shortcut between event READY and task START
		Disabled	0		Disable shortcut
		Enabled	1		Enable shortcut
В	RW END_DISABLE				Shortcut between event END and task DISABLE
		Disabled	0		Disable shortcut
		Enabled	1		Enable shortcut
С	RW DISABLED TXEN				Shortcut between event DISABLED and task TXEN



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				H GFEDCBA
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
D	RW DISABLED_RXEN			Shortcut between event DISABLED and task RXEN
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
E	RW ADDRESS_RSSISTART			Shortcut between event ADDRESS and task RSSISTART
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
F	RW END_START			Shortcut between event END and task START
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
G	RW ADDRESS_BCSTART			Shortcut between event ADDRESS and task BCSTART
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
Н	RW DISABLED_RSSISTOP			Shortcut between event DISABLED and task RSSISTOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.14.14.22 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				K J I H G F E D C B A
Reset	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW READY			Write '1' to enable interrupt for event READY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW ADDRESS			Write '1' to enable interrupt for event ADDRESS
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW PAYLOAD			Write '1' to enable interrupt for event PAYLOAD
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW END			Write '1' to enable interrupt for event END
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW DISABLED			Write '1' to enable interrupt for event DISABLED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW DEVMATCH			Write '1' to enable interrupt for event DEVMATCH
		Set	1	Enable



D:+			21 20 20 20 27 27		4 22 22 24 20 40 40 47 46 4F 44 42 42 44 40 0 0 7 C F A 2 2 2 4 6
	umber		31 30 29 28 27 26	5 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0	
ID	Acce Field	Value ID	Value		Description
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
G	RW DEVMISS				Write '1' to enable interrupt for event DEVMISS
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
Н	RW RSSIEND				Write '1' to enable interrupt for event RSSIEND
					A new RSSI sample is ready for readout from the
					RADIO.RSSISAMPLE register
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
I	RW BCMATCH				Write '1' to enable interrupt for event BCMATCH
					Bit counter value is specified in the RADIO.BCC register
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
J	RW CRCOK				Write '1' to enable interrupt for event CRCOK
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
K	RW CRCERROR				Write '1' to enable interrupt for event CRCERROR
		Set	1		Enable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled

6.14.14.23 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				K J I H G F E D C B A
Res	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW READY			Write '1' to disable interrupt for event READY
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW ADDRESS			Write '1' to disable interrupt for event ADDRESS
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW PAYLOAD			Write '1' to disable interrupt for event PAYLOAD
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW END			Write '1' to disable interrupt for event END
		Clear	1	Disable



Bit r	umber		31 30 29 28 2	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				K J I H G F E D C B A
Res	et 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW DISABLED			Write '1' to disable interrupt for event DISABLED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW DEVMATCH			Write '1' to disable interrupt for event DEVMATCH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW DEVMISS			Write '1' to disable interrupt for event DEVMISS
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW RSSIEND			Write '1' to disable interrupt for event RSSIEND
				A new RSSI sample is ready for readout from the
				RADIO.RSSISAMPLE register
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
I	RW BCMATCH			Write '1' to disable interrupt for event BCMATCH
				Bit counter value is specified in the RADIO.BCC register
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW CRCOK			Write '1' to disable interrupt for event CRCOK
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
K	RW CRCERROR			Write '1' to disable interrupt for event CRCERROR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.14.14.24 CRCSTATUS

Address offset: 0x400

CRC status

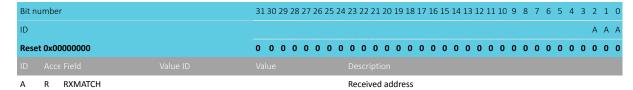
Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R CRCSTATUS			CRC status of packet received
	CRCError	0	Packet received with CRC error
	CRCOk	1	Packet received with CRC ok



6.14.14.25 RXMATCH

Address offset: 0x408

Received address

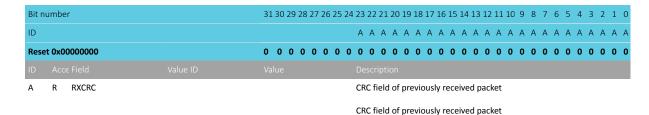


Logical address of which previous packet was received

6.14.14.26 RXCRC

Address offset: 0x40C

CRC field of previously received packet

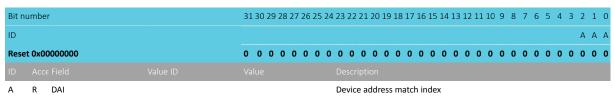


_ _ _ _ . .

6.14.14.27 DAI

Address offset: 0x410

Device address match index



Index (n) of device address, see DAB[n] and DAP[n], that got an address match.

6.14.14.28 PACKETPTR

Address offset: 0x504

Packet pointer



Bit r	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		
Α	RW PACKETPTR	Packet pointer
		Packet address to be used for the next transmission or
		reception. When transmitting, the packet pointed to by
		this address will be transmitted and when receiving, the
		received packet will be written to this address. This address
		is a byte aligned ram address.

6.14.14.29 FREQUENCY

Address offset: 0x508

Frequency

Bit n	umber		31	30 :	29 2	28 2	7 26	25	24	23	3 22	21	20 :	19 1	18 1	7 16	5 15	14	13	12 :	11 1	0 9	8	7	6	5	4	3 2	2 1	1 0
ID																							В		Α	Α	Α	A A	Δ ,	ΔА
Rese	t 0x00000002		0	0	0	0 0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0 (0	0	0	0	0	0	0 (0 1	1 0
ID																														
Α	RW FREQUENCY		[0	.100	0]					Ra	dio	cha	ann	el fr	equ	ien	у													
										Fre	equ	enc	:y =	240	00 +	FRI	QU	EN	CY (МН	lz).									
В	RW MAP									Ch	nanı	nel	map	se	lect	ion														
		Default	0							Ch	nanı	nel	map	be	twe	een	240	0 N	1HZ	2	500	МН	Z							
										Fre	equ	enc	:y =	240	00 +	FRI	QU	EN	CY (МН	lz)									
		Low	1							Ch	nanı	nel	map	be	twe	een	236	0 N	1HZ	2	460	МН	Z							
										Fre	equ	enc	:y =	236	50 +	FRI	QU	EN	CY (МН	lz)									

6.14.14.30 TXPOWER

Address offset: 0x50C

Output power

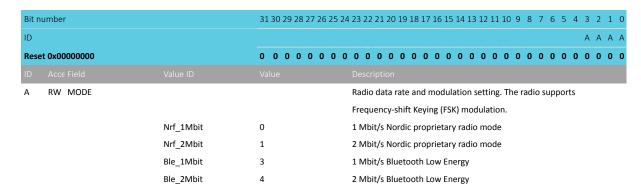
Bit number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW TXPOWER		RADIO output power.
		Output power in number of dBm, i.e. if the value -20 is
		specified the output power will be set to -20dBm.
Pos4dBm	0x04	+4 dBm
Pos3dBm	0x03	+3 dBm
0dBm	0x00	0 dBm
Neg4dBm	0xFC	-4 dBm
Neg8dBm	0xF8	-8 dBm
Neg12dBm	0xF4	-12 dBm
Neg16dBm	0xF0	-16 dBm
Neg20dBm	0xEC	-20 dBm
Neg30dBm	0xE2	-40 dBm Deprecated
Neg40dBm	0xD8	-40 dBm



6.14.14.31 MODE

Address offset: 0x510

Data rate and modulation



6.14.14.32 PCNF0

Address offset: 0x514

Packet configuration register 0

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			(G FEEEE C AAAA
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW LFLEN			Length on air of LENGTH field in number of bits.
С	RW SOLEN			Length on air of SO field in number of bytes.
Е	RW S1LEN			Length on air of S1 field in number of bits.
F	RW S1INCL			Include or exclude S1 field in RAM
		Automatic	0	Include S1 field in RAM only if S1LEN > 0
		Include	1	Always include S1 field in RAM independent of S1LEN
G	RW PLEN			Length of preamble on air. Decision point: TASKS_START task
		8bit	0	8-bit preamble
		16bit	1	16-bit preamble

6.14.14.33 PCNF1

Address offset: 0x518

Packet configuration register 1



Bit r	number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0						
ID			E D	C C C B B B B B B B A A A A A A A						
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0						
Α	RW MAXLEN		[0255]	Maximum length of packet payload. If the packet payload is						
				larger than MAXLEN, the radio will truncate the payload to						
				MAXLEN.						
В	RW STATLEN		[0255]	Static length in number of bytes						
				The static length parameter is added to the total length						
				of the payload when sending and receiving packets, e.g. if						
				the static length is set to N the radio will receive or send N						
				bytes more than what is defined in the LENGTH field of the						
				packet.						
С	RW BALEN		[24]	Base address length in number of bytes						
				The address field is composed of the base address and the						
				one byte long address prefix, e.g. set BALEN=2 to get a total						
				address of 3 bytes.						
D	RW ENDIAN			On air endianness of packet, this applies to the SO, LENGTH,						
	NW ENDIAN			S1 and the PAYLOAD fields.						
		Little	0	Least Significant bit on air first						
		Big	1	Most significant bit on air first						
E	RW WHITEEN	0	-	Enable or disable packet whitening						
-		Disabled	0	Disable						
		Enabled	1	Enable						
			=							

6.14.14.34 BASE0

Address offset: 0x51C

Base address 0

Bit n	umber	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	t 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			Description
Α	RW BASE0		Base address 0

Radio base address 0.

6.14.14.35 BASE1

Address offset: 0x520

Base address 1

Α	RW BASE1	Base address 1
ID		Value Description
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		
Bit r	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

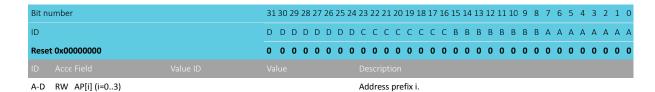
Radio base address 1.

6.14.14.36 PREFIXO

Address offset: 0x524



Prefixes bytes for logical addresses 0-3



6.14.14.37 PREFIX1

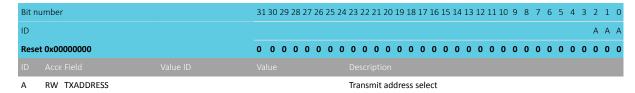
Address offset: 0x528

Prefixes bytes for logical addresses 4-7

A-D	RW AP[i] (i=47)		Address prefix i.
ID			
Rese	t 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		D D D D D D D	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
Bit n	umber	31 30 29 28 27 26 25 2	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.14.14.38 TXADDRESS

Address offset: 0x52C
Transmit address select



Logical address to be used when transmitting a packet.

6.14.14.39 RXADDRESSES

Address offset: 0x530 Receive address select

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			HGFEDCBA
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A-H RW ADDR[i] (i=07)			Enable or disable reception on logical address i.
	Disabled	0	Disable
	Enabled	1	Enable

6.14.14.40 CRCCNF

Address offset: 0x534 CRC configuration



Rit n	umber		31 30 29 28 27 26	25.2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			0100 25 20 27 20	202	В АА
Rese	et 0x00000000		0 0 0 0 0 0	0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW LEN		[13]		CRC length in number of bytes.
		Disabled	0		CRC length is zero and CRC calculation is disabled
		One	1		CRC length is one byte and CRC calculation is enabled
		Two	2		CRC length is two bytes and CRC calculation is enabled
		Three	3		CRC length is three bytes and CRC calculation is enabled
В	RW SKIPADDR				Include or exclude packet address field out of CRC
					calculation.
		Include	0		CRC calculation includes address field
		Skip	1		CRC calculation does not include address field. The CRC
					calculation will start at the first byte after the address.

6.14.14.41 CRCPOLY

Address offset: 0x538

CRC polynomial

Bit nu	ımber	31 30 2	9 28 2	7 26	25 24	1 23	22 2	1 20	19	18 1	17 1	6 15	14 1	.3 12	11	10 9	8	7	6	5	4 3	2	1 0
ID						Α	A A	4 A	Α	Α.	A A	A	Α ,	А А	Α	ΑА	A	Α	Α	Α	А А	Α	A A
Rese	0x00000000	0 0 0	0 0	0 0	0 0	0	0 0	0	0	0	0 0	0	0	0 0	0	0 0	0	0	0	0	0 0	0	0 0
ID																							
Α	RW CRCPOLY					CR	C pol	lync	mia	I													
						Eac	h te	rm i	n th	e CF	RC p	olyn	omia	al is r	nap	ped	to a	bit	in t	his			
						reg	ister	r wh	ich i	nde	х со	rres	oon	ds to	the	tern	n's e	хрс	ner	nt.			
						The	e lea	st si	gnifi	ican	t tei	rm/b	it is	hard	-wir	ed ir	iteri	nall	y to	,			
						1, a	and b	oit n	umb	oer (0 of	the	egis	ter c	onte	ent is	ign	ore	d b	У			
						the	han	dwa	re. 7	Γhe	follo	win	g exa	ampl	e is	for a	n 8	bit	CRC	:			
						pol	lynor	mial	: x8	+ x7	7 + x	3 + >	2 +	1 = 1	100	0 11	01.						

6.14.14.42 CRCINIT

Address offset: 0x53C

CRC initial value

A RW CRCINIT		CRC initial value	
ID Acce Field			
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	000000
ID		A A A A A A A A A A A A A A A A A A A	
Bit number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6	5 4 3 2 1 0

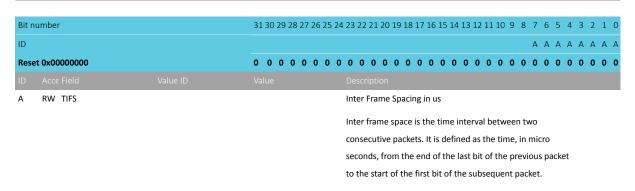
Initial value for CRC calculation.

6.14.14.43 TIFS

Address offset: 0x544

Inter Frame Spacing in us





6.14.14.44 RSSISAMPLE

Address offset: 0x548

RSSI sample

Bit n	umbe	er	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A
Rese	et OxO	0000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	R	RSSISAMPLE	[0127]	RSSI sample
				RSSI sample result. The value of this register is read as a
				positive value while the actual received signal strength is a
				negative value. Actual received signal strength is therefore
				as follows: received signal strength = -A dBm

6.14.14.45 STATE

Address offset: 0x550 Current radio state

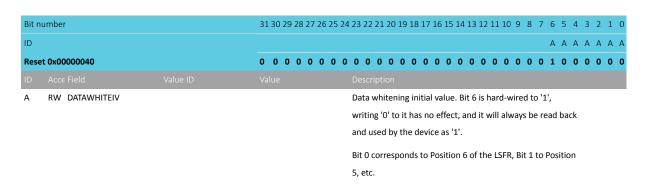
Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АААА
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
			Description
A R STATE			Current radio state
	Disabled	0	RADIO is in the Disabled state
F	RxRu	1	RADIO is in the RXRU state
F	RxIdle	2	RADIO is in the RXIDLE state
F	₹x	3	RADIO is in the RX state
F	RxDisable	4	RADIO is in the RXDISABLED state
T	TxRu	9	RADIO is in the TXRU state
T	TxIdle	10	RADIO is in the TXIDLE state
T	Γx	11	RADIO is in the TX state
Т	TxDisable	12	RADIO is in the TXDISABLED state

6.14.14.46 DATAWHITEIV

Address offset: 0x554

Data whitening initial value





6.14.14.47 BCC

Address offset: 0x560 Bit counter compare

Δ	RW BCC									Rit	co	unt	ero	ron	npa	re																_
ID																																
Res	et 0x00000000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0
ID		Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α.	Д	A A	A A	Α	Α	Α	Α
Bit r	number	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6 5	5 4	3	2	1	0

Bit counter compare register

6.14.14.48 DAB[n] (n=0..7)

Address offset: $0x600 + (n \times 0x4)$ Device address base segment n

-	4	RW DAB								D	evi	ce a	ıddr	ess	bas	e s	egn	nen'	t n											
1																														
F	Rese	t 0x00000000	0	0 ()	0	0 0) (0	0	0	0	0	0	0	0	0 (0	0	0	0	0 0	0	0	0	0	0	0 (0	0
1	D		Α	A A	۸ ,	A .	A A	\ <i>A</i>	Δ Δ	Α	A	Α	Α	Α	Α	A ,	A A	Δ Α	A	Α	Α	A A	A	Α	Α	Α	Α	Α /	A A	Α
E	Bit nı	umber	31	30 2	9 2	28 2	7 2	6 2	5 2	4 23	3 22	2 2 1	. 20	19	18 :	17 1	l6 1	5 1	4 13	12	11 1	10 9	8	7	6	5	4	3 2	2 1	0

6.14.14.49 DAP[n] (n=0..7)

Address offset: $0x620 + (n \times 0x4)$

Device address prefix n

ID Acce Field Value ID	
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

6.14.14.50 DACNF

Address offset: 0x640

Device address match configuration



Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			P O N M L K J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A-H RW ENA[i] (i=07)			Enable or disable device address matching using device
			address i
	Disabled	0	Disabled
	Enabled	1	Enabled
I-P RW TXADD[i] (i=07)			TxAdd for device address i

6.14.14.51 MODECNFO

Address offset: 0x650

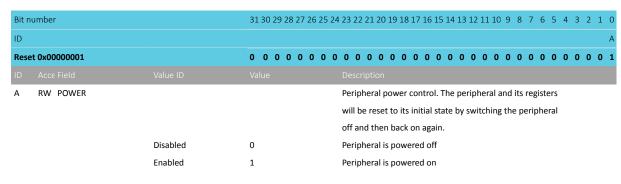
Radio mode configuration register 0

Bit number		31 30 29 28 27 26 25 24 23 22 21	20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			СС
Reset 0x00000200		0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0
ID Acce Field			
A RW RU		Radio ran	mp-up time
	Default	0 Default ra	amp-up time (tRXEN), compatible with firmware
		written fo	or nRF51
	Fast	1 Fast ramp	p-up (tRXEN,FAST), see electrical specification for
		more info	ormation
C RW DTX		Default T	'X value
		Specifies	what the RADIO will transmit when it is not
		started, i.	.e. between:
		RADIO.E\	VENTS_READY and RADIO.TASKS_START
		RADIO.E\	VENTS_END and RADIO.TASKS_START
		RADIO.E\	VENTS_END and RADIO.EVENTS_DISABLED
	B1	0 Transmit	'1'
	ВО	1 Transmit	'0'
	Center	2 Transmit	center frequency
		When tu	ning the crystal for centre frequency, the RADIO
		must be s	set in DTX = Center mode to be able to achieve the
		expected	d accuracy.

6.14.14.52 POWER

Address offset: 0xFFC

Peripheral power control





6.14.15 Electrical specification

6.14.15.1 General radio characteristics

Symbol	Description	Min.	Тур.	Max.	Units
f_{OP}	Operating frequencies	2360		2500	MHz
$f_{PLL,PROG,RES}$	PLL programming resolution		2		kHz
f _{PLL,CH,SP}	PLL channel spacing		1		MHz
f _{DELTA,1M}	Frequency deviation @ 1 Mbps		±170		kHz
f _{DELTA,BLE,1M}	Frequency deviation @ BLE 1 Mbps		±250		kHz
f _{DELTA,2M}	Frequency deviation @ 2 Mbps		±320		kHz
f _{DELTA,BLE,2M}	Frequency deviation @ BLE 2 Mbps		±500		kHz
fsk _{SPS}	On-the-air data rate	1		2	Mbps

6.14.15.2 Radio current consumption (transmitter)

Symbol	Description	Min.	Тур.	Max.	Units
I _{TX,PLUS4dBM,DCDC}	TX only run current (DCDC, 3V) P _{RF} =+4 dBm		7.0		mA
I _{TX,PLUS4dBM}	TX only run current P _{RF} = +4 dBm		15.4		mA
I _{TX,0dBM,DCDC}	TX only run current (DCDC, 3V)P _{RF} = 0dBm		4.6		mA
I _{TX,0dBM}	TX only run current P _{RF} = 0dBm		10.1		mA
I _{TX,MINUS4dBM,DCDC}	TX only run current DCDC, 3V P _{RF} = -4dBm		3.6		mA
I _{TX,MINUS4dBM}	TX only run current P _{RF} = -4 dBm		7.8		mA
I _{TX,MINUS8dBM,DCDC}	TX only run current DCDC, 3V P _{RF} = -8 dBm		3.2		mA
I _{TX,MINUS8dBM}	TX only run current P _{RF} = -8 dBm		6.8		mA
I _{TX,MINUS12dBM,DCDC}	TX only run current DCDC, 3V P _{RF} = -12 dBm		2.9		mA
I _{TX,MINUS12dBM}	TX only run current P _{RF} = -12 dBm		6.2		mA
$I_{TX,MINUS16dBM,DCDC}$	TX only run current DCDC, 3V P _{RF} = -16 dBm		2.7		mA
I _{TX,MINUS16dBM}	TX only run current P _{RF} = -16 dBm		5.7		mA
I _{TX,MINUS20dBM,DCDC}	TX only run current DCDC, 3V P _{RF} = -20 dBm		2.5		mA
I _{TX,MINUS20dBM}	TX only run current P _{RF} = -20 dBm		5.4		mA
I _{TX,MINUS40dBM,DCDC}	TX only run current DCDC, 3V P _{RF} = -40 dBm		2.1		mA
I _{TX,MINUS40dBM}	TX only run current P _{RF} = -40 dBm		4.3		mA

6.14.15.3 Radio current consumption (receiver)

Symbol	Description	Min.	Тур.	Max.	Units
I _{RX,1M,DCDC}	RX only run current (DCDC, 3V) 1 Mbps / 1 Mbps BLE		4.6		mA
I _{RX,1M}	RX only run current 1 Mbps / 1 Mbps BLE		10.0		mA
I _{RX,2M,DCDC}	RX only run current (DCDC, 3V) 2 Mbps / 2 Mbps BLE		5.2		mA
I _{RX,2M}	RX only run current 2 Mbps / 2 Mbps BLE		11.2		mA
I _{START,RX,1M,DCDC}	RX start-up current (DCDC, 3 V) 1 Mbps / 1 Mbps BLE		3.5		mA
I _{START,RX,1M}	RX start-up current 1 Mbps / 1 Mbps BLE		6.7		mA

6.14.15.4 Transmitter specification

Symbol	Description	Min.	Тур.	Max.	Units
P_{RF}	Maximum output power		4	8	dBm
P _{RFC}	RF power control range		24		dB
P _{RFCR}	RF power accuracy			±4	dB
P _{RF1,1}	1st Adjacent Channel Transmit Power 1 MHz (1 Mbps)		-25		dBc



Symbol	Description	Min.	Тур.	Max.	Units
P _{RF2,1}	2nd Adjacent Channel Transmit Power 2 MHz (1 Mbps)		-50		dBc
P _{RF1,2}	1st Adjacent Channel Transmit Power 2 MHz (2 Mbps)		-25		dBc
P _{RE2 2}	2nd Adjacent Channel Transmit Power 4 MHz (2 Mbps)		-50		dBc

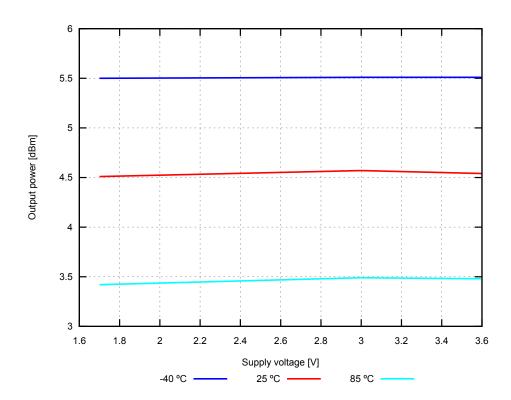


Figure 73: Output power, 1 Mbps Bluetooth low energy mode, 4 dBm TXPOWER setting (typical values)

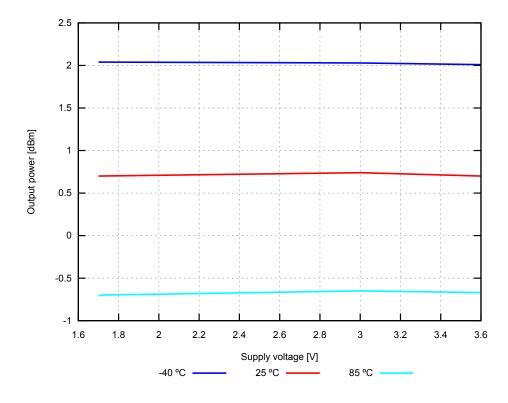


Figure 74: Output power, 1 Mbps Bluetooth low energy mode, 0 dBm TXPOWER setting (typical values)



6.14.15.5 Receiver operation

Symbol	Description	Min.	Тур.	Max.	Units
P _{RX,MAX}	Maximum received signal strength at < 0.1% BER		0		dBm
P _{SENS,IT,1M}	Sensitivity, 1 Mbps nRF mode ideal transmitter ¹⁴		-93		dBm
P _{SENS,IT,2M}	Sensitivity, 2 Mbps nRF mode ideal transmitter ¹⁵		-89		dBm
P _{SENS,IT,SP,1M,BLE}	Sensitivity, 1 Mbps BLE ideal transmitter, <=37 bytes		-96		dBm
	BER=1E-3 ¹⁶				
P _{SENS,IT,LP,1M,BLE}	Sensitivity, 1 Mbps BLE ideal transmitter >=128 bytes		-95		dBm
	BER=1E-4 ¹⁷				
P _{SENS,IT,SP,2M,BLE}	Sensitivity, 2 Mbps BLE ideal transmitter, Packet length		-93		dBm
	<=37bytes				

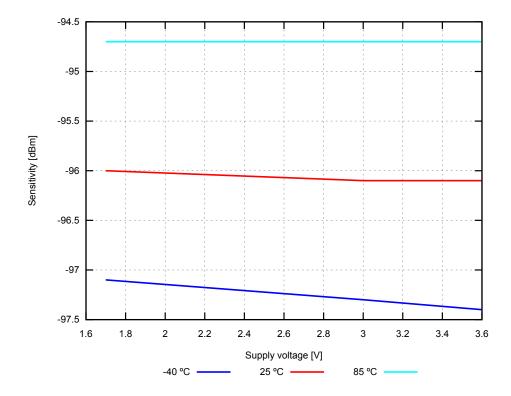


Figure 75: Sensitivity, 1 Mbps Bluetooth low energy mode, Regulator = LDO (typical values)

6.14.15.6 RX selectivity

RX selectivity with equal modulation on interfering signal ¹⁸

NORDIC SEMICONDUCTOR

¹⁴ Typical sensitivity applies when ADDR0 is used for receiver address correlation. When ADDR[1...7] are used for receiver address correlation, the typical sensitivity for this mode is degraded by 3dB.

Typical sensitivity applies when ADDR0 is used for receiver address correlation. When ADDR[1...7] are used for receiver address correlation, the typical sensitivity for this mode is degraded by 3dB.

As defined in the Bluetooth Core Specification v4.0 Volume 6: Core System Package (Low Energy Controller Volume)

¹⁷ Equivalent BER limit < 10E-04

Wanted signal level at PIN = -67 dBm. One interferer is used, having equal modulation as the wanted signal. The input power of the interferer where the sensitivity equals BER = 0.1% is presented

Symbol	Description	Min.	Тур.	Max.	Units
C/I _{1M,co-channel}	1 Mbps mode, Co-Channel interference		9		dB
C/I _{1M,-1MHz}	1 Mbps mode, Adjacent (-1 MHz) interference		-2		dB
C/I _{1M,+1MHz}	1 Mbps mode, Adjacent (+1 MHz) interference		-10		dB
C/I _{1M,-2MHz}	1 Mbps mode, Adjacent (-2 MHz) interference		-19		dB
C/I _{1M,+2MHz}	1 Mbps mode, Adjacent (+2 MHz) interference		-42		dB
C/I _{1M,-3MHz}	1 Mbps mode, Adjacent (-3 MHz) interference		-38		dB
C/I _{1M,+3MHz}	1 Mbps mode, Adjacent (+3 MHz) interference		-48		dB
C/I _{1M,±6MHz}	1 Mbps mode, Adjacent (≥6 MHz) interference		-50		dB
C/I _{1MBLE,co-channel}	1 Mbps BLE mode, Co-Channel interference		6		dB
C/I _{1MBLE,-1MHz}	1 Mbps BLE mode, Adjacent (-1 MHz) interference		-2		dB
C/I _{1MBLE,+1MHz}	1 Mbps BLE mode, Adjacent (+1 MHz) interference		-9		dB
C/I _{1MBLE,-2MHz}	1 Mbps BLE mode, Adjacent (-2 MHz) interference		-22		dB
C/I _{1MBLE,+2MHz}	1 Mbps BLE mode, Adjacent (+2 MHz) interference		-46		dB
C/I _{1MBLE,>3MHz}	1 Mbps BLE mode, Adjacent (≥3 MHz) interference		-50		dB
C/I _{1MBLE,image}	Image frequency Interference		-22		dB
C/I _{1MBLE,image,1MHz}	Adjacent (1 MHz) interference to in-band image frequency		-35		dB
C/I _{2M,co-channel}	2 Mbps mode, Co-Channel interference		10		dB
C/I _{2M,-2MHz}	2 Mbps mode, Adjacent (-2 MHz) interference		6		dB
C/I _{2M,+2MHz}	2 Mbps mode, Adjacent (+2 MHz) interference		-14		dB
C/I _{2M,-4MHz}	2 Mbps mode, Adjacent (-4 MHz) interference		-20		dB
C/I _{2M,+4MHz}	2 Mbps mode, Adjacent (+4 MHz) interference		-44		dB
C/I _{2M,-6MHz}	2 Mbps mode, Adjacent (-6 MHz) interference		-42		dB
C/I _{2M,+6MHz}	2 Mbps mode, Adjacent (+6 MHz) interference		-47		dB
C/I _{2M,≥12MHz}	2 Mbps mode, Adjacent (≥12 MHz) interference		-52		dB

6.14.15.7 RX intermodulation

RX intermodulation¹⁹

Description	Min.	Тур.	Max.	Units
IMD performance, 1 Msps, 5th offset channel, Packet length		-33		dBm
<= 37 bytes				
IMD performance, BLE 1 Msps, 5th offset channel, Packet		-30		dBm
length <= 37 bytes				
IMD performance, 2 Msps, 5th offset channel, Packet length		-33		dBm
<= 37 bytes				
IMD performance, BLE 2 Msps, 5th offset channel, Packet		-31		dBm
length <= 37 bytes				
	IMD performance, 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, BLE 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, 2 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, BLE 2 Msps, 5th offset channel, Packet	IMD performance, 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, BLE 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, 2 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, BLE 2 Msps, 5th offset channel, Packet	IMD performance, 1 Msps, 5th offset channel, Packet length = 33 <= 37 bytes IMD performance, BLE 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, 2 Msps, 5th offset channel, Packet length <p>= 33 <= 37 bytes IMD performance, BLE 2 Msps, 5th offset channel, Packet <p>= 31</p></p>	IMD performance, 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, BLE 1 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, 2 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, 2 Msps, 5th offset channel, Packet length <= 37 bytes IMD performance, BLE 2 Msps, 5th offset channel, Packet IMD performance, BLE 2 Msps, 5th offset channel, Packet -31

6.14.15.8 Radio timing

Symbol	Description	Min.	Тур.	Max.	Units
t _{TXEN}	Time between TXEN task and READY event after channel	140		140	μs
	FREQUENCY configured. Compatible with old devices.				
t _{TXEN,FAST}	Time between TXEN task and READY event after channel	40		40	μs
	FREQUENCY configured (Fast Mode)				

NORDIC SEMICONDUCTOR

Wanted signal level at PIN = -64 dBm. Two interferers with equal input power are used. The interferer closest in frequency is not modulated, the other interferer is modulated equal with the wanted signal. The input power of the interferers where the sensitivity equals BER = 0.1% is presented.

Symbol	Description	Min.	Tun	Max.	Units
Symbol			Тур.		
t _{TXDISABLE,1M}	Time between DISABLE task and DISABLED event when	6		6	μs
	the radio was in TX for MODE = Nrf_1Mbit and MODE =				
	Ble_1Mbit				
t _{TXDISABLE,2M}	Time between DISABLE task and DISABLED event when the	4		4	μs
	radio was in TX and mode is set to 2 Mbps				
t _{RXEN}	Time between the RXEN task and READY event after channel	140		140	μs
	FREQUENCY configured in default mode. Compatible with				
	old devices.				
t _{rxen,fast}	Time between the RXEN task and READY event after channel	40		40	μs
	FREQUENCY configured in fast mode				
t _{SWITCH}	The minimum time taken to switch from RX to TX or TX to RX		20		μs
	when channel FREQUENCY unchanged				
t _{RXDISABLE}	Time between DISABLE task and DISABLED event when the	0		0	μs
	radio was in RX				
t _{TXCHAIN}	Digital propagation delay (in radio only) when transmitting.		0.6		μs
	Does not include EasyDMA access time.				
t _{RXCHAIN}	Digital propagation delay (in radio only) when receiving.		9.4		μs
	Does not include EasyDMA access time.				
t _{RXCHAIN,2M}	Digital propagation delay in 2 Mbps mode (radio only) when		5		μs
	receiving. Does not include EasyDMA access time.				

6.14.15.9 Received signal strength indicator (RSSI) specifications

Symbol	Description	Min.	Тур.	Max.	Units
RSSI _{ACC}	RSSI accuracy valid range -90 to -20 dBm		±2		dB
RSSI _{RESOLUTION}	RSSI resolution		1		dB
RSSI _{PERIOD}	RSSI sampling time from RSSI_START task		0.25		μs
RSSI _{SETTLE}	RSSI settling time after signal level change		15		μs

6.14.15.10 Jitter

Symbol	Description	Min.	Тур.	Max.	Units
t _{DISABLEDJITTER}	Jitter on DISABLED event relative to END event when		0.25		μs
	shortcut between END and DISABLE is enabled.				
t _{READYJITTER}	Jitter on READY event relative to TXEN and RXEN task.		0.25		μs

6.15 RNG — Random number generator

The Random number generator (RNG) generates true non-deterministic random numbers based on internal thermal noise that are suitable for cryptographic purposes. The RNG does not require a seed value.

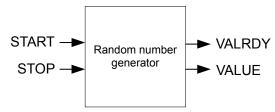


Figure 76: Random number generator

The RNG is started by triggering the START task and stopped by triggering the STOP task. When started, new random numbers are generated continuously and written to the VALUE register when ready. A



VALRDY event is generated for every new random number that is written to the VALUE register. This means that after a VALRDY event is generated the CPU has the time until the next VALRDY event to read out the random number from the VALUE register before it is overwritten by a new random number.

6.15.1 Bias correction

A bias correction algorithm is employed on the internal bit stream to remove any bias toward '1' or '0'. The bits are then queued into an eight-bit register for parallel readout from the VALUE register.

It is possible to enable bias correction in the CONFIG register. This will result in slower value generation, but will ensure a statistically uniform distribution of the random values.

6.15.2 Speed

The time needed to generate one random byte of data is unpredictable, and may vary from one byte to the next. This is especially true when bias correction is enabled.

6.15.3 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4000D000	RNG	RNG	Random number generator	

Table 66: Instances

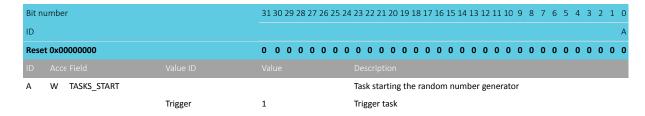
Register	Offset	Description
TASKS_START	0x000	Task starting the random number generator
TASKS_STOP	0x004	Task stopping the random number generator
EVENTS_VALRDY	0x100	Event being generated for every new random number written to the VALUE register
SHORTS	0x200	Shortcuts between local events and tasks
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
CONFIG	0x504	Configuration register
VALUE	0x508	Output random number

Table 67: Register overview

6.15.3.1 TASKS_START

Address offset: 0x000

Task starting the random number generator

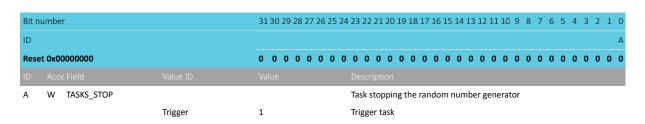


6.15.3.2 TASKS STOP

Address offset: 0x004

Task stopping the random number generator





6.15.3.3 EVENTS_VALRDY

Address offset: 0x100

Event being generated for every new random number written to the VALUE register

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_VALRDY			Event being generated for every new random number
				written to the VALUE register
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.15.3.4 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW VALRDY_STOP			Shortcut between event VALRDY and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.15.3.5 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW VALRDY			Write '1' to enable interrupt for event VALRDY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.15.3.6 INTENCLR

Address offset: 0x308

Disable interrupt



Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW VALRDY			Write '1' to disable interrupt for event VALRDY
	Clear	1	Disable
I	Disabled	0	Read: Disabled
I	Enabled	1	Read: Enabled

6.15.3.7 CONFIG

Address offset: 0x504 Configuration register

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW DERCEN			Bias correction
		Disabled	0	Disabled
		Enabled	1	Enabled

6.15.3.8 VALUE

Address offset: 0x508

Output random number

Bit number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A R VALUE	[0255]	Generated random number

6.15.4 Electrical specification

6.15.4.1 RNG Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{RNG,START}	Time from setting the START task to generation begins.		128		μs
	This is a one-time delay on START signal and does not apply				
	between samples.				
t _{RNG,RAW}	Run time per byte without bias correction. Uniform		30		μs
	distribution of 0 and 1 is not guaranteed.				
t _{RNG,BC}	Run time per byte with bias correction. Uniform distribution		120		μs
	of 0 and 1 is guaranteed. Time to generate a byte cannot be				
	guaranteed.				



6.16 RTC — Real-time counter

The Real-time counter (RTC) module provides a generic, low power timer on the low-frequency clock source (LFCLK).

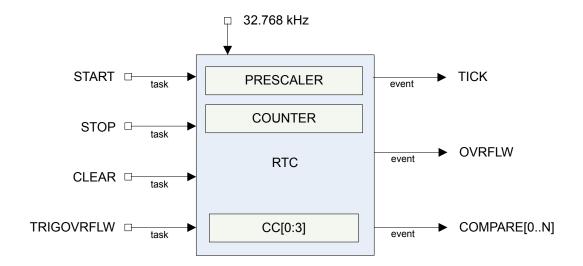


Figure 77: RTC block schematic

The RTC module features a 24-bit COUNTER, a 12-bit (1/X) prescaler, capture/compare registers, and a tick event generator for low power, tickless RTOS implementation.

6.16.1 Clock source

The RTC will run off the LFCLK.

The COUNTER resolution will therefore be 30.517 μ s. Depending on the source, the RTC is able to run while the HFCLK is OFF and PCLK16M is not available.

The software has to explicitely start LFCLK before using the RTC.

See CLOCK — Clock control on page 65 for more information about clock sources.

6.16.2 Resolution versus overflow and the PRESCALER

Counter increment frequency:

```
f<sub>RTC</sub> [kHz] = 32.768 / (PRESCALER + 1 )
```

The PRESCALER register is read/write when the RTC is stopped. The PRESCALER register is read-only once the RTC is STARTed. Writing to the PRESCALER register when the RTC is started has no effect.

The PRESCALER is restarted on START, CLEAR and TRIGOVRFLW, that is, the prescaler value is latched to an internal register (<<PRESC>>) on these tasks.

Examples:

1. Desired COUNTER frequency 100 Hz (10 ms counter period)

```
PRESCALER = round(32.768 kHz / 100 Hz) - 1 = 327 f_{RTC} = 99.9 Hz
```



10009.576 μs counter period

2. Desired COUNTER frequency 8 Hz (125 ms counter period)

PRESCALER = round(32.768 kHz / 8 Hz) - 1 = 4095

 $f_{RTC} = 8 Hz$

125 ms counter period

Prescaler	Counter resolution	Overflow
0	30.517 μs	512 seconds
2 ⁸ -1	7812.5 μs	131072 seconds
2 ¹² -1	125 ms	582.542 hours

Table 68: RTC resolution versus overflow

6.16.3 COUNTER register

The COUNTER increments on LFCLK when the internal PRESCALER register (<<PRESC>>) is 0x00. <<PRESC>> is reloaded from the PRESCALER register. If enabled, the TICK event occurs on each increment of the COUNTER. The TICK event is disabled by default.

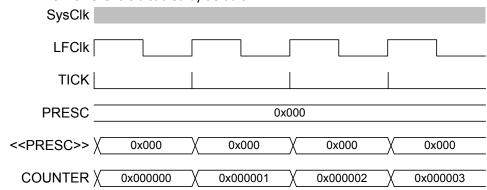


Figure 78: Timing diagram - COUNTER_PRESCALER_0

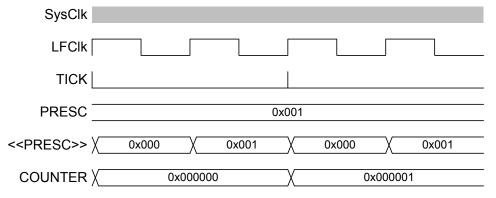


Figure 79: Timing diagram - COUNTER_PRESCALER 1

6.16.4 Overflow features

The TRIGOVRFLW task sets the COUNTER value to 0xFFFFF0 to allow SW test of the overflow condition.

OVRFLW occurs when COUNTER overflows from 0xFFFFFF to 0.

Important: The OVRFLW event is disabled by default.



6.16.5 TICK event

The TICK event enables low power "tick-less" RTOS implementation as it optionally provides a regular interrupt source for a RTOS without the need to use the $ARM^{\$}$ SysTick feature.

Using the RTC TICK event rather than the SysTick allows the CPU to be powered down while still keeping RTOS scheduling active.

Important: The TICK event is disabled by default.

6.16.6 Event control feature

To optimize RTC power consumption, events in the RTC can be individually disabled to prevent PCLK16M and HFCLK being requested when those events are triggered. This is managed using the EVTEN register.

For example, if the TICK event is not required for an application, this event should be disabled as it is frequently occurring and may increase power consumption if HFCLK otherwise could be powered down for long durations.

This means that the RTC implements a slightly different task and event system compared to the standard system described in Peripheral interface on page 78. The RTC task and event system is illustrated in Tasks, events and interrupts in the RTC on page 223.

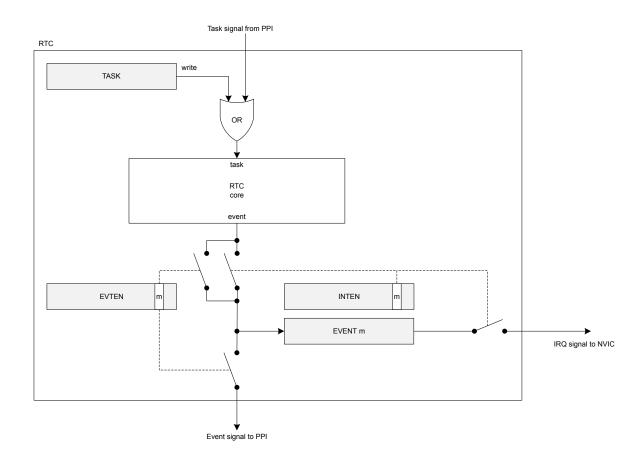


Figure 80: Tasks, events and interrupts in the RTC

6.16.7 Compare feature

There are a number of Compare registers.

For more information, see Registers on page 228.



When setting a compare register, the following behavior of the RTC compare event should be noted:

• If a CC register value is 0 when a CLEAR task is set, this will not trigger a COMPARE event.

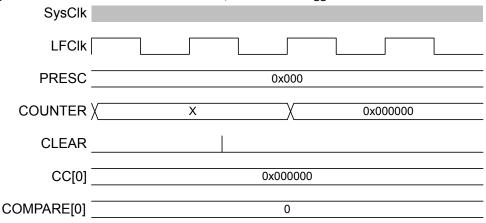


Figure 81: Timing diagram - COMPARE_CLEAR

• If a CC register is N and the COUNTER value is N when the START task is set, this will not trigger a COMPARE event.

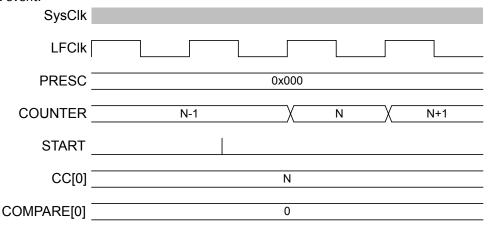


Figure 82: Timing diagram - COMPARE START

• COMPARE occurs when a CC register is N and the COUNTER value transitions from N-1 to N.

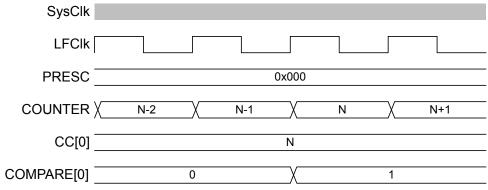


Figure 83: Timing diagram - COMPARE

• If the COUNTER is N, writing N+2 to a CC register is guaranteed to trigger a COMPARE event at N+2.



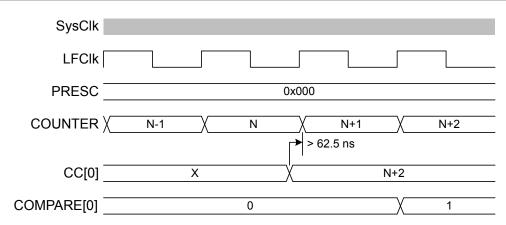


Figure 84: Timing diagram - COMPARE_N+2

• If the COUNTER is N, writing N or N+1 to a CC register may not trigger a COMPARE event.

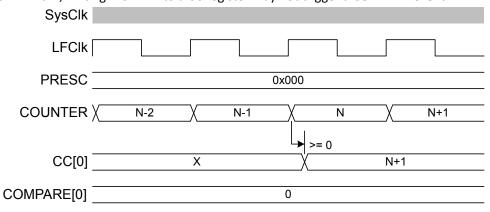


Figure 85: Timing diagram - COMPARE N+1

• If the COUNTER is N and the current CC register value is N+1 or N+2 when a new CC value is written, a match may trigger on the previous CC value before the new value takes effect. If the current CC value greater than N+2 when the new value is written, there will be no event due to the old value.

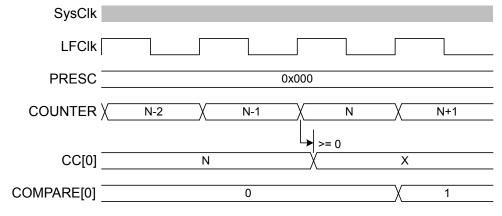


Figure 86: Timing diagram - COMPARE_N-1

6.16.8 TASK and EVENT jitter/delay

Jitter or delay in the RTC is due to the peripheral clock being a low frequency clock (LFCLK) which is not synchronous to the faster PCLK16M.

Registers in the peripheral interface, part of the PCLK16M domain, have a set of mirrored registers in the LFCLK domain. For example, the COUNTER value accessible from the CPU is in the PCLK16M domain and is latched on read from an internal register called COUNTER in the LFCLK domain. COUNTER is the register which is actually modified each time the RTC ticks. These registers must be synchronised between clock domains (PCLK16M and LFCLK).



The following is a summary of the jitter introduced on tasks and events. Figures illustrating jitter follow.

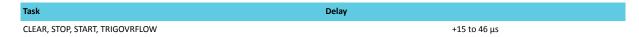


Table 69: RTC jitter magnitudes on tasks

Operation/Function	Jitter
START to COUNTER increment	+/- 15 μs
COMPARE to COMPARE ²⁰	+/- 62.5 ns

Table 70: RTC jitter magnitudes on events

1. CLEAR and STOP (and TRIGOVRFLW; not shown) will be delayed as long as it takes for the peripheral to clock a falling edge and rising of the LFCLK. This is between 15.2585 μs and 45.7755 μs – rounded to 15 μs and 46 μs for the remainder of the section.

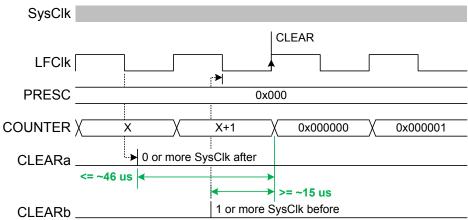


Figure 87: Timing diagram - DELAY_CLEAR

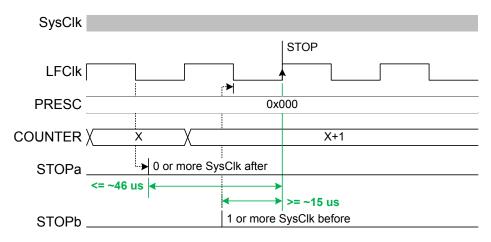


Figure 88: Timing diagram - DELAY_STOP

2. The START task will start the RTC. Assuming that the LFCLK was previously running and stable, the first increment of COUNTER (and instance of TICK event) will be typically after 30.5 μs +/-15 μs. In some cases, in particular if the RTC is STARTed before the LFCLK is running, that timing can be up to ~250 μs. The software should therefore wait for the first TICK if it has to make sure the RTC is running.

Note: 32.768 kHz clock jitter is additional to the numbers provided above.



Downloaded from Arrow.com.

Assumes RTC runs continuously between these events.

Sending a TRIGOVRFLW task sets the COUNTER to a value close to overflow. However, since the update of COUNTER relies on a stable LFCLK, sending this task while LFCLK is not running will start LFCLK, but the update will then be delayed by the same amount of time of up to ~250 us. The figures show the smallest and largest delays to on the START task which appears as a +/-15 μ s jitter on the first COUNTER increment.

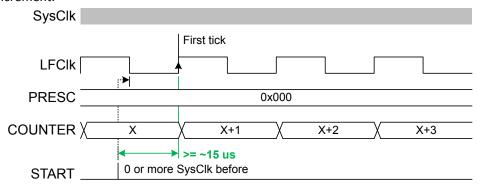


Figure 89: Timing diagram - JITTER START-

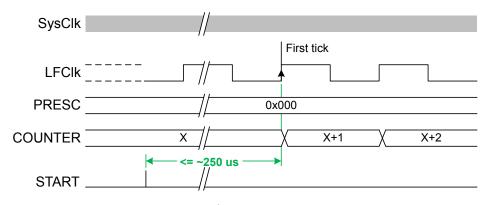


Figure 90: Timing diagram - JITTER_START+

6.16.9 Reading the COUNTER register

To read the COUNTER register, the internal <<COUNTER>> value is sampled.

To ensure that the <<COUNTER>> is safely sampled (considering an LFCLK transition may occur during a read), the CPU and core memory bus are halted for three cycles by lowering the core PREADY signal. The Read takes the CPU 2 cycles in addition resulting in the COUNTER register read taking a fixed five PCLK16M clock cycles.

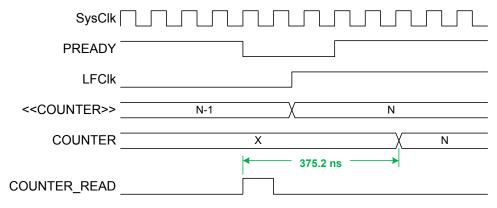


Figure 91: Timing diagram - COUNTER_READ



6.16.10 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4000B000	RTC	RTC0	Real-time counter 0	CC[02] implemented, CC[3] not
				implemented
0x40011000	RTC	RTC1	Real-time counter 1	CC[03] implemented

Table 71: Instances

Register	Offset	Description
TASKS_START	0x000	Start RTC COUNTER
TASKS_STOP	0x004	Stop RTC COUNTER
TASKS_CLEAR	0x008	Clear RTC COUNTER
TASKS_TRIGOVRFLW	0x00C	Set COUNTER to 0xFFFFF0
EVENTS_TICK	0x100	Event on COUNTER increment
EVENTS_OVRFLW	0x104	Event on COUNTER overflow
EVENTS_COMPARE[0]	0x140	Compare event on CC[0] match
EVENTS_COMPARE[1]	0x144	Compare event on CC[1] match
EVENTS_COMPARE[2]	0x148	Compare event on CC[2] match
EVENTS_COMPARE[3]	0x14C	Compare event on CC[3] match
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
EVTEN	0x340	Enable or disable event routing
EVTENSET	0x344	Enable event routing
EVTENCLR	0x348	Disable event routing
COUNTER	0x504	Current COUNTER value
PRESCALER	0x508	12 bit prescaler for COUNTER frequency (32768/(PRESCALER+1)). Must be written when RTC is
		stopped
CC[0]	0x540	Compare register 0
CC[1]	0x544	Compare register 1
CC[2]	0x548	Compare register 2
CC[3]	0x54C	Compare register 3

Table 72: Register overview

6.16.10.1 TASKS_START

Address offset: 0x000
Start RTC COUNTER

Bit n	number		31 30 29 28 27 26	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
ID					Α
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0
ID					
Α	W TASKS_START			Start RTC COUNTER	
		Trigger	1	Trigger task	

6.16.10.2 TASKS_STOP

Address offset: 0x004 Stop RTC COUNTER



Bit n	uml	per		31 30 29 28 27 26 25	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t Ox	00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_STOP			Stop RTC COUNTER
			Trigger	1	Trigger task

6.16.10.3 TASKS_CLEAR

Address offset: 0x008 Clear RTC COUNTER

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_CLEAR			Clear RTC COUNTER
		Trigger	1	Trigger task

6.16.10.4 TASKS_TRIGOVRFLW

Address offset: 0x00C

Set COUNTER to 0xFFFFF0

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_TRIGOVRFLW			Set COUNTER to 0xFFFFF0
		Trigger	1	Trigger task

6.16.10.5 EVENTS_TICK

Address offset: 0x100

Event on COUNTER increment

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_TICK			Event on COUNTER increment
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.16.10.6 EVENTS_OVRFLW

Address offset: 0x104

Event on COUNTER overflow



Bit number	31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW EVENTS_OVRFLW		Event on COUNTER overflow
NotGenerated	0	Event not generated
Generated	1	Event generated

6.16.10.7 EVENTS_COMPARE[n] (n=0..3)

Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_COMPARE			Compare event on CC[n] match
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.16.10.8 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW TICK			Write '1' to enable interrupt for event TICK
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW OVRFLW			Write '1' to enable interrupt for event OVRFLW
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
C-F	RW COMPARE[i] (i=03)			Write '1' to enable interrupt for event COMPARE[i]
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.16.10.9 INTENCLR

Address offset: 0x308

Disable interrupt



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW TICK			Write '1' to disable interrupt for event TICK
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW OVRFLW			Write '1' to disable interrupt for event OVRFLW
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
C-F	RW COMPARE[i] (i=03)			Write '1' to disable interrupt for event COMPARE[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.16.10.10 EVTEN

Address offset: 0x340

Enable or disable event routing

Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW TICK			Enable or disable event routing for event TICK
	Disabled	0	Disable
	Enabled	1	Disable
B RW OVRFLW			Enable or disable event routing for event OVRFLW
	Disabled	0	Disable
	Enabled	1	Disable
C-F RW COMPARE[i] (i=03)			Enable or disable event routing for event COMPARE[i]
	Disabled	0	Disable
	Enabled	1	Disable

6.16.10.11 EVTENSET

Address offset: 0x344 Enable event routing

Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW TICK			Write '1' to enable event routing for event TICK
1	Disabled	0	Read: Disabled
Į.	Enabled	1	Read: Enabled
9	Set	1	Enable
B RW OVRFLW			Write '1' to enable event routing for event OVRFLW
ı	Disabled	0	Read: Disabled
I	Enabled	1	Read: Enabled
9	Set	1	Enable



Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		F E D C B A
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
C-F RW COMPARE[i] (i=03)		Write '1' to enable event routing for event COMPARE[i]
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled
Set	1	Enable

6.16.10.12 EVTENCLR

Address offset: 0x348 Disable event routing

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
			Description
A RW TICK			Write '1' to disable event routing for event TICK
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
	Clear	1	Disable
B RW OVRFLW			Write '1' to disable event routing for event OVRFLW
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
	Clear	1	Disable
C-F RW COMPARE[i] (i=03)			Write '1' to disable event routing for event COMPARE[i]
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
	Clear	1	Disable

6.16.10.13 COUNTER

Address offset: 0x504 Current COUNTER value

Α	R COUNTER		Counter value
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.16.10.14 PRESCALER

Address offset: 0x508

12 bit prescaler for COUNTER frequency (32768/(PRESCALER+1)). Must be written when RTC is stopped

Bit n	umber		31 30	29 28	27 2	6 25	24 2	3 22	21 2	20 19	9 18	17 1	6 15	14	13 1	2 11	10	9	8	7	6 5	4	3	2	1 0
ID																Α	Α	Α	Α /	۱ ،	A A	\ A	Α	Α	А А
Rese	Reset 0x00000000		0 0	0 0	0 0	0 0	0 (0	0	0 0	0	0 (0	0	0	0 0	0	0	0 () ו	0 0	0	0	0	0 0
ID																									

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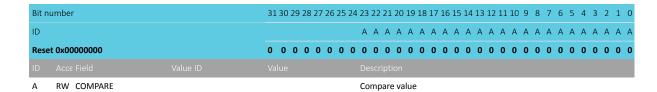


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6.16.10.15 CC[n] (n=0..3)

Address offset: $0x540 + (n \times 0x4)$

Compare register n



6.16.11 Electrical specification

6.17 SAADC — Successive approximation analog-to-digital converter

The ADC is a differential successive approximation register (SAR) analog-to-digital converter.

Listed here are the main features of SAADC:

- 8/10/12-bit resolution, 14-bit resolution with oversampling
- Up to eight input channels
 - One channel per single-ended input and two channels per differential input
 - Scan mode can be configured with both single-ended channels and differential channels.
- Full scale input range (0 to VDD)
- Sampling triggered via a task from software or a PPI channel for full flexibility on sample frequency source from low power 32.768kHz RTC or more accurate 1/16MHz Timers
- One-shot conversion mode to sample a single channel
- Scan mode to sample a series of channels in sequence. Sample delay between channels is t_{ack} + t_{conv} which may vary between channels according to user configuration of t_{ack}.
- Support for direct sample transfer to RAM using EasyDMA
- Interrupts on single sample and full buffer events
- Samples stored as 16-bit 2's complement values for differential and single-ended sampling
- Continuous sampling without the need of an external timer
- Internal resistor string
- · Limit checking on the fly

6.17.1 Shared resources

The ADC can coexist with COMP and other peripherals using one of AIN0-AIN7, provided these are assigned to different pins.

It is not recommended to select the same analog input pin for both modules.

6.17.2 Overview

The ADC supports up to eight external analog input channels, depending on package variant. It can be operated in a one-shot mode with sampling under software control, or a continuous conversion mode with a programmable sampling rate.

The analog inputs can be configured as eight single-ended inputs, four differential inputs or a combination of these. Each channel can be configured to select AINO to AIN7 pins, or the VDD pin. Channels can be



sampled individually in one-shot or continuous sampling modes, or, using scan mode, multiple channels can be sampled in sequence. Channels can also be oversampled to improve noise performance.

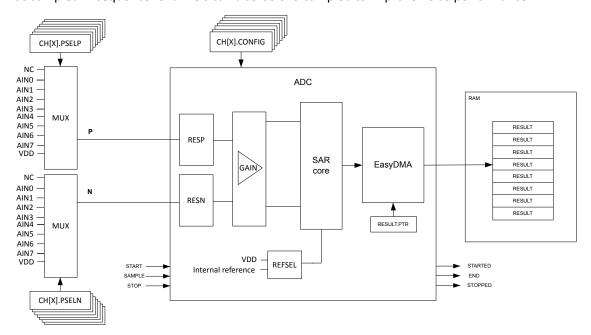


Figure 92: Simplified ADC block diagram

Internally, the ADC is always a differential analog-to-digital converter, but by default it is configured with single-ended input in the MODE field of the CH[n].CONFIG register. In single-ended mode, the negative input will be shorted to ground internally.

The assumption in single-ended mode is that the internal ground of the ADC is the same as the external ground that the measured voltage is referred to. The ADC is thus sensitive to ground bounce on the PCB in single-ended mode. If this is a concern we recommend using differential measurement.

6.17.3 Digital output

The output result of the ADC depends on the settings in the CH[n].CONFIG and RESOLUTION registers as follows:

```
RESULT = [V(P) - V(N)] * GAIN/REFERENCE * 2 (RESOLUTION - m)
```

where

V(P)

is the voltage at input P

V(N)

is the voltage at input N

GAIN

is the selected gain setting

REFERENCE

is the selected reference voltage

and m=0 if CONFIG.MODE=SE, or m=1 if CONFIG.MODE=Diff.

The result generated by the ADC will deviate from the expected due DC errors like offset, gain, differential non-linearity (DNL), and integral non-linearity (INL). See Electrical specification for details on these parameters. The result can also vary due to AC errors like non-linearities in the GAIN block, settling errors



due to high source impedance and sampling jitter. For battery measurement the DC errors are most noticeable.

The ADC has a wide selection of gains controlled in the GAIN field of the CH[n].CONFIG register. If CH[n].CONFIG.REFSEL=0, the input range of the ADC core is nominally ± 0.6 V differential and the input must be scaled accordingly.

The ADC has a temperature dependent offset. If the ADC is to operate over a large temperature range, we recommend running CALIBRATEOFFSET at regular intervals, a CALIBRATEDONE event will be fired when the calibration is complete

6.17.4 Analog inputs and channels

Up to eight analog input channels, CH[n](n=0..7), can be configured.

See Shared resources on page 233 for shared input with comparators.

Any one of the available channels can be enabled for the ADC to operate in one-shot mode. If more than one CH[n] is configured, the ADC enters scan mode.

An analog input is selected as a positive converter input if CH[n].PSELP is set, setting CH[n].PSELP also enables the particular channel.

An analog input is selected as a negative converter input if CH[n].PSELN is set. The CH[n].PSELN register will have no effect unless differential mode is enabled, see MODE field in CH[n].CONFIG register.

If more than one of the CH[n].PSELP registers is set, the device enters scan mode. Input selections in scan mode are controlled by the CH[n].PSELP and CH[n].PSELN registers, where CH[n].PSELN is only used if the particular scan channel is specified as differential, see MODE field in CH[n].CONFIG register.

Important: Channels selected for COMP cannot be used at the same time for ADC sampling, though channels not selected for use by these blocks can be used by the ADC.

Channel input	Source	Connectivity
CH[n].PSELP	AINOAIN7	Yes(any)
CH[n].PSELP	VDD	Yes
CH[n].PSELN	AINOAIN7	Yes(any)
CH[n].PSELN	VDD	Yes

Table 73: Legal connectivity CH[n] vs. analog input

6.17.5 Operation modes

The ADC input configuration supports one-shot mode, continuous mode and scan mode.

Scan mode and oversampling cannot be combined.

6.17.5.1 One-shot mode

One-shot operation is configured by enabling only one of the available channels defined by CH[n].PSELP, CH[n].PSELN, and CH[n].CONFIG registers.

Upon a SAMPLE task, the ADC starts to sample the input voltage. The CH[n].CONFIG.TACQ controls the acquisition time.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA. For more information, see EasyDMA on page 237.



6.17.5.2 Continuous mode

Continuous sampling can be achieved by using the internal timer in the ADC, or triggering the SAMPLE task from one of the general purpose timers through the PPI.

Care shall be taken to ensure that the sample rate fulfils the following criteria, depending on how many channels are active:

```
f_{SAMPLE} < 1/[t_{ACO} + t_{conv}]
```

The SAMPLERATE register can be used as a local timer instead of triggering individual SAMPLE tasks. When SAMPLERATE.MODE is set to Timers, it is sufficient to trigger SAMPLE task only once in order to start the SAADC and triggering the STOP task will stop sampling. The SAMPLERATE.CC field controls the sample rate.

The SAMPLERATE timer mode cannot be combined with SCAN mode, and only one channel can be enabled in this mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.17.5.3 Oversampling

An accumulator in the ADC can be used to average noise on the analog input. In general, oversampling improves the signal-to-noise ratio (SNR). Oversampling, however, does not improve the integral non-linearity (INL), or differential non-linearity (DNL).

Oversampling and scan should not be combined, since oversampling and scan will average over input channels.

The accumulator is controlled in the OVERSAMPLE register. The SAMPLE task must be set 2^{OVERSAMPLE} number of times before the result is written to RAM. This can be achieved by:

- Configuring a fixed sampling rate using the local timer or a general purpose timer and PPI to trigger a SAMPLE task
- Triggering SAMPLE 2^{OVERSAMPLE} times from software
- Enabling BURST mode

CH[n].CONFIG.BURST can be enabled to avoid setting SAMPLE task $2^{\text{OVERSAMPLE}}$ times. With BURST = 1 the ADC will sample the input $2^{\text{OVERSAMPLE}}$ times as fast as it can (actual timing: $<(t_{ACQ}+t_{CONV})\times 2^{\text{OVERSAMPLE}}$). Thus, for the user it will just appear like the conversion took a bit longer time, but other than that, it is similar to one-shot mode. Scan mode can be combined with BURST=1, if burst is enabled on all channels.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event signals that enough conversions have taken place for an oversampled result to get transferred into RAM. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.17.5.4 Scan mode

A channel is considered enabled if CH[n].PSELP is set. If more than one channel, CH[n], is enabled, the ADC enters scan mode.

In scan mode, one SAMPLE task will trigger one conversion per enabled channel. The time it takes to sample all channels is:

```
Total time < Sum(CH[x].t_{ACQ}+t_{CONV}), x=0..enabled channels
```

A DONE event signals that one sample has been taken.



In this mode, the RESULTDONE event signals has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual values have been transferred into RAM by EasyDMA.

Example of RAM placement (even RESULT.MAXCNT), channels 1, 2 and 5 enabled on page 237 provides an example of results placement in Data RAM, with an even RESULT.MAXCNT. In this example, channels 1, 2 and 5 are enabled, all others are disabled.

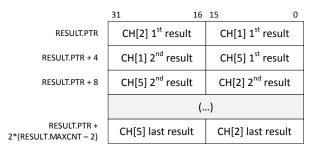


Figure 93: Example of RAM placement (even RESULT.MAXCNT), channels 1, 2 and 5 enabled

Example of RAM placement (odd RESULT.MAXCNT), channels 1, 2 and 5 enabled on page 237 provides an example of results placement in Data RAM, with an odd RESULT.MAXCNT. In this example, channels 1, 2 and 5 are enabled, all others are disabled. The last 32-bit word is populated only with one 16-bit result.

	31 16	15 0
RESULT.PTR	CH[2] 1 st result	CH[1] 1 st result
RESULT.PTR + 4	CH[1] 2 nd result	CH[5] 1 st result
RESULT.PTR + 8	CH[5] 2 nd result	CH[2] 2 nd result
	()
RESULT.PTR + 2*(RESULT.MAXCNT – 1)		CH[5] last result

Figure 94: Example of RAM placement (odd RESULT.MAXCNT), channels 1, 2 and 5 enabled

6.17.6 EasyDMA

After configuring RESULT.PTR and RESULT.MAXCNT, the ADC resources are started by triggering the START task. The ADC is using EasyDMA to store results in a Result buffer in RAM.

The Result buffer is located at the address specified in the RESULT.PTR register. The RESULT.PTR register is double-buffered and it can be updated and prepared for the next START task immediately after the STARTED event is generated. The size of the Result buffer is specified in the RESULT.MAXCNT register and the ADC will generate an END event when it has filled up the Result buffer, see ADC on page 238. Results are stored in little-endian byte order in Data RAM. Every sample will be sign extended to 16 bit before stored in the Result buffer.

The ADC is stopped by triggering the STOP task. The STOP task will terminate an ongoing sampling. The ADC will generate a STOPPED event when it has stopped. If the ADC is already stopped when the STOP task is triggered, the STOPPED event will still be generated.



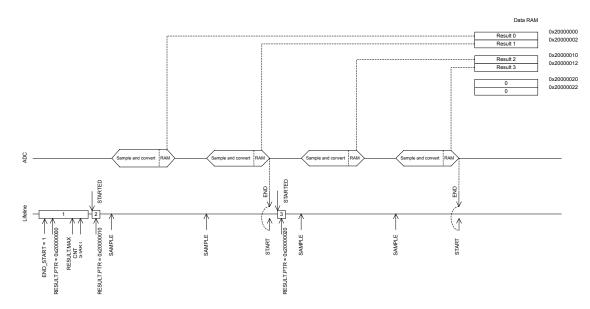


Figure 95: ADC

If the RESULT.PTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

The EasyDMA will have finished accessing the RAM when the END or STOPPED event has been generated.

The RESULT.AMOUNT register can be read following an END event or a STOPPED event to see how many results have been transferred to the Result buffer in RAM since the START task was triggered.

In scan mode, SAMPLE tasks can be triggered once the START task is triggered. The END event is generated when the number of samples transferred to memory reaches the value specified by RESULT.MAXCNT.

After an END event, the START task needs to be triggered again before new samples can be taken. Also make sure that the size of the Result buffer is large enough to have space for minimum one result from each of the enabled channels, by specifying RESULT.MAXCNT >= number of channels enabled. For more information about the scan mode, see Scan mode on page 236.

6.17.7 Resistor ladder

The ADC has an internal resistor string for positive and negative input.

See Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP) on page 239. The resistors are controlled in the CH[n].CONFIG.RESP and CH[n].CONFIG.RESN registers.



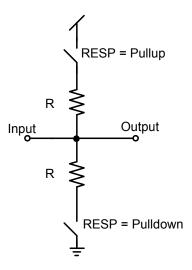


Figure 96: Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP)

6.17.8 Reference

The ADC can use two different references, controlled in the REFSEL field of the CH[n].CONFIG register.

These are:

- Internal reference
- VDD as reference

The internal reference results in an input range of ± 0.6 V on the ADC core. VDD as reference results in an input range of $\pm VDD/4$ on the ADC core. The gain block can be used to change the effective input range of the ADC.

```
Input range = (+- 0.6 \text{ V or } +-\text{VDD}/4)/\text{Gain}
```

For example, choosing VDD as reference, single ended input (grounded negative input), and a gain of 1/4 the input range will be:

```
Input range = (VDD/4)/(1/4) = VDD
```

With internal reference, single ended input (grounded negative input), and a gain of 1/6 the input range will be:

```
Input range = (0.6 \text{ V})/(1/6) = 3.6 \text{ V}
```

The AINO-AIN7 inputs cannot exceed VDD, or be lower than VSS.

6.17.9 Acquisition time

To sample the input voltage, the ADC connects a capacitor to the input.

For illustration, see Simplified ADC sample network on page 240. The acquisition time indicates how long the capacitor is connected, see TACQ field in CH[n].CONFIG register. The required acquisition time depends on the source (R_{source}) resistance. For high source resistance the acquisition time should be increased, see Acquisition time on page 240.



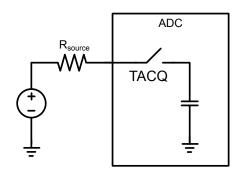


Figure 97: Simplified ADC sample network

TACQ [µs]	Maximum source resistance [kOhm]
3	10
5	40
10	100
15	200
20	400
40	800

Table 74: Acquisition time

6.17.10 Limits event monitoring

A channel can be event monitored by configuring limit register CH[n].LIMIT.

If the conversion result is higher than the defined high limit, or lower than the defined low limit, the appropriate event will get fired.

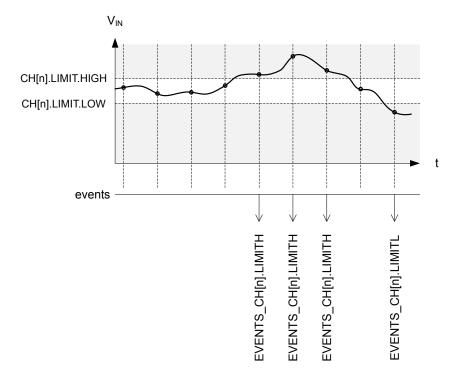


Figure 98: Example of limits monitoring on channel 'n'



Note that when setting the limits, CH[n].LIMIT.HIGH shall always be higher than or equal to CH[n].LIMIT.LOW . In other words, an event can be fired only when the input signal has been sampled outside of the defined limits. It is not possible to fire an event when the input signal is inside a defined range by swapping high and low limits.

The comparison to limits always takes place, there is no need to enable it. If comparison is not required on a channel, the software shall simply ignore the related events. In that situation, the value of the limits registers is irrelevant, so it does not matter if CH[n].LIMIT.LOW is lower than CH[n].LIMIT.HIGH or not.

6.17.11 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40007000	SAADC	SAADC	Analog-to-digital converter	

Table 75: Instances

Register	Offset	Description
TASKS_START	0x000	Start the ADC and prepare the result buffer in RAM
TASKS_SAMPLE	0x004	Take one ADC sample, if scan is enabled all channels are sampled
TASKS_STOP	0x008	Stop the ADC and terminate any on-going conversion
TASKS_CALIBRATEOFFSET	0x00C	Starts offset auto-calibration
EVENTS_STARTED	0x100	The ADC has started
EVENTS_END	0x104	The ADC has filled up the Result buffer
EVENTS_DONE	0x108	A conversion task has been completed. Depending on the mode, multiple conversions might be
		needed for a result to be transferred to RAM.
EVENTS_RESULTDONE	0x10C	A result is ready to get transferred to RAM.
EVENTS_CALIBRATEDONE	0x110	Calibration is complete
EVENTS_STOPPED	0x114	The ADC has stopped
EVENTS_CH[0].LIMITH	0x118	Last results is equal or above CH[0].LIMIT.HIGH
EVENTS_CH[0].LIMITL	0x11C	Last results is equal or below CH[0].LIMIT.LOW
EVENTS_CH[1].LIMITH	0x120	Last results is equal or above CH[1].LIMIT.HIGH
EVENTS_CH[1].LIMITL	0x124	Last results is equal or below CH[1].LIMIT.LOW
EVENTS_CH[2].LIMITH	0x128	Last results is equal or above CH[2].LIMIT.HIGH
EVENTS_CH[2].LIMITL	0x12C	Last results is equal or below CH[2].LIMIT.LOW
EVENTS_CH[3].LIMITH	0x130	Last results is equal or above CH[3].LIMIT.HIGH
EVENTS_CH[3].LIMITL	0x134	Last results is equal or below CH[3].LIMIT.LOW
EVENTS_CH[4].LIMITH	0x138	Last results is equal or above CH[4].LIMIT.HIGH
EVENTS_CH[4].LIMITL	0x13C	Last results is equal or below CH[4].LIMIT.LOW
EVENTS_CH[5].LIMITH	0x140	Last results is equal or above CH[5].LIMIT.HIGH
EVENTS_CH[5].LIMITL	0x144	Last results is equal or below CH[5].LIMIT.LOW
EVENTS_CH[6].LIMITH	0x148	Last results is equal or above CH[6].LIMIT.HIGH
EVENTS_CH[6].LIMITL	0x14C	Last results is equal or below CH[6].LIMIT.LOW
EVENTS_CH[7].LIMITH	0x150	Last results is equal or above CH[7].LIMIT.HIGH
EVENTS_CH[7].LIMITL	0x154	Last results is equal or below CH[7].LIMIT.LOW
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
STATUS	0x400	Status
ENABLE	0x500	Enable or disable ADC
CH[0].PSELP	0x510	Input positive pin selection for CH[0]
CH[0].PSELN	0x514	Input negative pin selection for CH[0]
CH[0].CONFIG	0x518	Input configuration for CH[0]
CH[0].LIMIT	0x51C	High/low limits for event monitoring a channel
CH[1].PSELP	0x520	Input positive pin selection for CH[1]

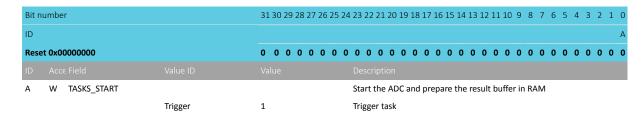
Register	Offset	Description
CH[1].PSELN	0x524	Input negative pin selection for CH[1]
CH[1].CONFIG	0x528	Input configuration for CH[1]
CH[1].LIMIT	0x52C	High/low limits for event monitoring a channel
CH[2].PSELP	0x530	Input positive pin selection for CH[2]
CH[2].PSELN	0x534	Input negative pin selection for CH[2]
CH[2].CONFIG	0x538	Input configuration for CH[2]
CH[2].LIMIT	0x53C	High/low limits for event monitoring a channel
CH[3].PSELP	0x540	Input positive pin selection for CH[3]
CH[3].PSELN	0x544	Input negative pin selection for CH[3]
CH[3].CONFIG	0x548	Input configuration for CH[3]
CH[3].LIMIT	0x54C	High/low limits for event monitoring a channel
CH[4].PSELP	0x550	Input positive pin selection for CH[4]
CH[4].PSELN	0x554	Input negative pin selection for CH[4]
CH[4].CONFIG	0x558	Input configuration for CH[4]
CH[4].LIMIT	0x55C	High/low limits for event monitoring a channel
CH[5].PSELP	0x560	Input positive pin selection for CH[5]
CH[5].PSELN	0x564	Input negative pin selection for CH[5]
CH[5].CONFIG	0x568	Input configuration for CH[5]
CH[5].LIMIT	0x56C	High/low limits for event monitoring a channel
CH[6].PSELP	0x570	Input positive pin selection for CH[6]
CH[6].PSELN	0x574	Input negative pin selection for CH[6]
CH[6].CONFIG	0x578	Input configuration for CH[6]
CH[6].LIMIT	0x57C	High/low limits for event monitoring a channel
CH[7].PSELP	0x580	Input positive pin selection for CH[7]
CH[7].PSELN	0x584	Input negative pin selection for CH[7]
CH[7].CONFIG	0x588	Input configuration for CH[7]
CH[7].LIMIT	0x58C	High/low limits for event monitoring a channel
RESOLUTION	0x5F0	Resolution configuration
OVERSAMPLE	0x5F4	Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The
		RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION
		should be used.
SAMPLERATE	0x5F8	Controls normal or continuous sample rate
RESULT.PTR	0x62C	Data pointer
RESULT.MAXCNT	0x630	Maximum number of buffer words to transfer
RESULT.AMOUNT	0x634	Number of buffer words transferred since last START

Table 76: Register overview

6.17.11.1 TASKS_START

Address offset: 0x000

Start the ADC and prepare the result buffer in RAM

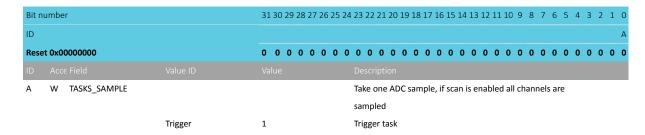


6.17.11.2 TASKS_SAMPLE

Address offset: 0x004



Take one ADC sample, if scan is enabled all channels are sampled



6.17.11.3 TASKS STOP

Address offset: 0x008

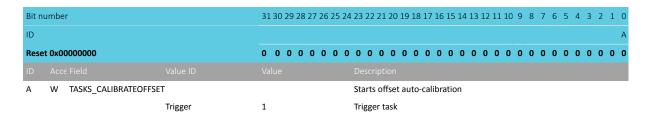
Stop the ADC and terminate any on-going conversion

Bit n	umber		31 30 29 28 27 26	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOP			Stop the ADC and terminate any on-going conversion
		Trigger	1	Trigger task

6.17.11.4 TASKS_CALIBRATEOFFSET

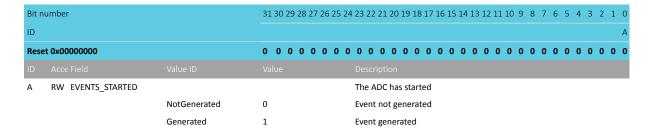
Address offset: 0x00C

Starts offset auto-calibration



6.17.11.5 EVENTS_STARTED

Address offset: 0x100
The ADC has started

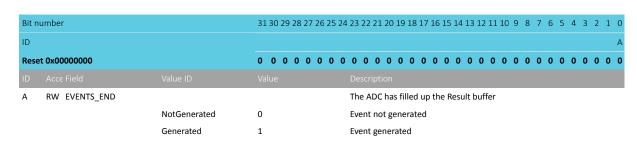


6.17.11.6 EVENTS END

Address offset: 0x104

The ADC has filled up the Result buffer

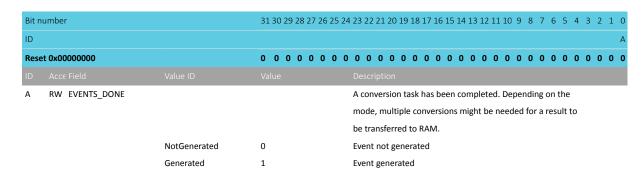




6.17.11.7 EVENTS DONE

Address offset: 0x108

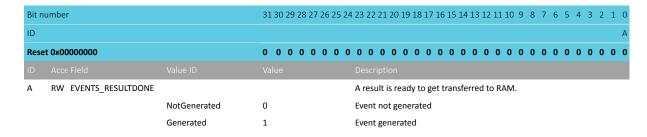
A conversion task has been completed. Depending on the mode, multiple conversions might be needed for a result to be transferred to RAM.



6.17.11.8 EVENTS RESULTDONE

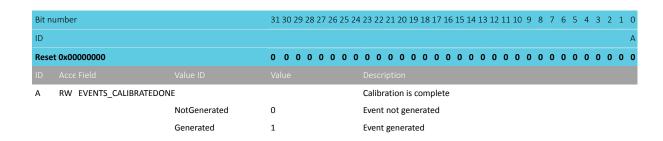
Address offset: 0x10C

A result is ready to get transferred to RAM.



6.17.11.9 EVENTS CALIBRATEDONE

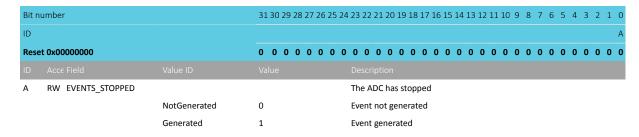
Address offset: 0x110
Calibration is complete





6.17.11.10 EVENTS_STOPPED

Address offset: 0x114
The ADC has stopped



6.17.11.11 EVENTS_CH[n].LIMITH (n=0..7)

Address offset: 0x118 + (n × 0x8)

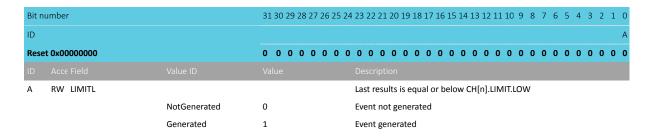
Last results is equal or above CH[n].LIMIT.HIGH

Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW LIMITH			Last results is equal or above CH[n].LIMIT.HIGH
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.17.11.12 EVENTS_CH[n].LIMITL (n=0..7)

Address offset: 0x11C + (n × 0x8)

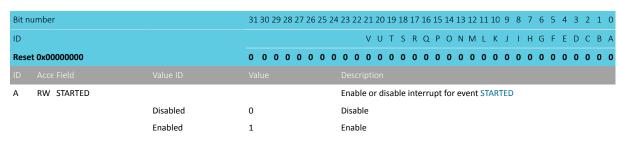
Last results is equal or below CH[n].LIMIT.LOW



6.17.11.13 INTEN

Address offset: 0x300

Enable or disable interrupt





Bit r	number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
В	RW END			Enable or disable interrupt for event END
		Disabled	0	Disable
		Enabled	1	Enable
С	RW DONE			Enable or disable interrupt for event DONE
		Disabled	0	Disable
		Enabled	1	Enable
D	RW RESULTD	ONE		Enable or disable interrupt for event RESULTDONE
		Disabled	0	Disable
		Enabled	1	Enable
E	RW CALIBRA	ΓEDONE		Enable or disable interrupt for event CALIBRATEDONE
		Disabled	0	Disable
		Enabled	1	Enable
F	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
G	RW CHOLIMI	ГН		Enable or disable interrupt for event CHOLIMITH
		Disabled	0	Disable
		Enabled	1	Enable
Н	RW CHOLIMI	ΓL		Enable or disable interrupt for event CHOLIMITL
		Disabled	0	Disable
		Enabled	1	Enable
ı	RW CH1LIMI	гн		Enable or disable interrupt for event CH1LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
J	RW CH1LIMI	ГL		Enable or disable interrupt for event CH1LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
K	RW CH2LIMI	гн		Enable or disable interrupt for event CH2LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
L	RW CH2LIMI	ГL		Enable or disable interrupt for event CH2LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
М	RW CH3LIMI	гн		Enable or disable interrupt for event CH3LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
N	RW CH3LIMI	ΓL		Enable or disable interrupt for event CH3LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
0	RW CH4LIMI	гн		Enable or disable interrupt for event CH4LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
Р	RW CH4LIMI	TL		Enable or disable interrupt for event CH4LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
Q	RW CH5LIMI	гн		Enable or disable interrupt for event CH5LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
R	RW CH5LIMI	TL		Enable or disable interrupt for event CH5LIMITL
		Disabled	0	Disable



Bit n	umber		31 30 29 28	8 27 26	25 24	23 22 2	21 20	19	18 1	7 16	15	14 :	L3 12	11	10	9	8	6	5	4	3 2	1	0
ID						,	V U	Т	S F	R Q	Р	О	N M	L	K	J	I F	ł G	F	Ε	D (В	Α
Rese	t 0x00000000		0 0 0 0	0 0	0 0	0 0	0 0	0	0 (0	0	0	0 0	0	0	0	0 (0	0	0	0 (0	0
ID																							
		Enabled	1			Enable																	
S	RW CH6LIMITH					Enable	or d	isab	le in	terr	upt	for	even	t CH	6LII	MIT	Ή						
		Disabled	0			Disable	e																
		Enabled	1			Enable																	
Т	RW CH6LIMITL					Enable	or d	isab	le in	terr	upt	for	even	t CH	6LII	MIT	L						
		Disabled	0			Disable	9																
		Enabled	1			Enable																	
U	RW CH7LIMITH					Enable	or d	isab	le in	terr	upt	for	even	CH	7LII	MIT	Ή						
		Disabled	0			Disable	9																
		Enabled	1			Enable																	
٧	RW CH7LIMITL					Enable	or d	isab	le in	terr	upt	for	even	t CH	7LII	MIT	L						
		Disabled	0			Disable	9																
		Enabled	1			Enable																	

6.17.11.14 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STARTED			Write '1' to enable interrupt for event STARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW END			Write '1' to enable interrupt for event END
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW DONE			Write '1' to enable interrupt for event DONE
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW RESULTDONE			Write '1' to enable interrupt for event RESULTDONE
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Ε	RW CALIBRATEDONE			Write '1' to enable interrupt for event CALIBRATEDONE
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW CHOLIMITH			Write '1' to enable interrupt for event CHOLIMITH
		Set	1	Enable



Note	Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
	ID				V U T S R Q P O N M L K J I H G F E D C B A
	Rese	et 0x00000000		0 0 0 0 0 0 0 0	000000000000000000000000000000000000000
Empile E	ID				
No. Chount Set 1 Cambide			Disabled	0	Read: Disabled
Set			Enabled	1	Read: Enabled
No. Chillimith Procession	Н	RW CHOLIMITL			Write '1' to enable interrupt for event CHOLIMITL
RW CHILIMITH			Set	1	Enable
RW CHILIMITH			Disabled	0	Read: Disabled
Set			Enabled	1	Read: Enabled
	I	RW CH1LIMITH			Write '1' to enable interrupt for event CH1LIMITH
RW CHILIMIT Set 1 Enable 1 Read: Enable 1			Set	1	Enable
RW CHILIMITL			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
	J	RW CH1LIMITL			Write '1' to enable interrupt for event CH1LIMITL
Enable Final Fin			Set	1	Enable
RW CH2LIMITH			Disabled	0	Read: Disabled
Set			Enabled	1	Read: Enabled
Disabled Disabled Disabled Read: Disabled Read: Disabled Read: Enabled Read: Enabled Read: Enabled Read: Enabled Read: Disabled Read: Dis	K	RW CH2LIMITH			Write '1' to enable interrupt for event CH2LIMITH
Enabled 1 Read: Disabled 1 Read: Disabled 1 Read: Disabled 1 Read: Enabled 1 Read: E			Set	1	Enable
Note			Disabled	0	Read: Disabled
Set			Enabled	1	Read: Enabled
	L	RW CH2LIMITL			Write '1' to enable interrupt for event CH2LIMITL
Read: Enabled 1 Read: Enabled 1 Write '1' to enable interrupt for event CH3LIMITH Set 1 Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Enabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Enabled Read: Disabled Disabled					
Mart					
Set			Enabled	1	
RANGE CHALIMITH For abled Disabled Disabled	M	RW CH3LIMITH	6.1		
RW CHALIMITL Set 1 Enable P RW CHALIMITL Set 1 Enable O RW CHALIMITH Set 1 Enable Set 1 Enable O RW CHALIMITH Set 1 Enable Disabled 0 Read: Enabled O Read: Enabled P RW CHALIMITH Set 1 Enable Disabled 0 Read: Enabled P RW CHALIMITH Set 1 Enable Disabled 0 Read: Enabled O Read: Disabled O Read: Enabled O Read: Enabled O Read: Enabled Read: Enabled O Read: Disabled O Read: Enabled O Read: Enabled O Read: Disabled O Read: Enabled Read: Enabled Read: Enabled Read: Enabled Read: Enabled Read: Enabled Finable O Read: Enabled Read: Enabled O Read: Disabled					
N RW CH3LIMITL Set 1 Enable Disabled 0 Read: Disabled Enabled 1 Read: Enabled O RW CH4LIMITH Set 1 Enable Disabled 0 Read: Disabled Enabled 1 Read: Enabled O Read: Disabled Disabled 0 Read: Disabled Enabled 1 Read: Enabled O Read: Disabled Enabled 1 Read: Enabled Frame of the second of the s					
Set	N	DW/ CHOLIMITI	Eliablea	1	
Disabled Disabled Read: Disabled Read: Disabled Read: Enabled	IN	KW CHISLIVIIIL	Sat	1	·
Read: Enabled 1					
No RW CHALIMITH Set 1 Enable Disabled 0 Read: Disabled Enabled 1 Read: Enabled PROFITE TO Enable 1 Enable 1 Read: Enabled PROFITE TO Enable 1 Enable 1 Read: Enabled PROFITE TO Enable 1 Enable 1 Read: Enabled PROFITE TO Enable 1 Enable 1 Read: Enabled 1					
Finable Set Disabled	0	RW CH4IIMITH	Endored	-	
P RW CHALIMITL Set 1 Enabled 0 Read: Disabled P RW CHALIMITL Set 1 Enabled C Read: Enabled C Read: Disabled C Read: Enabled C Read: Disabled			Set	1	
P RW CHALIMITL Set 1 Enable Q Read: Enabled P RW CHALIMITL Set 1 Enable CO Read: Disabled CO Read: Disabled CO Read: Enabled CO Read: Disabled					
Set 1 Enable Q RW CHSLIMITH Set 1 Enable Read: Disabled Disable					
Read: Disabled Q RW CHSLIMITH Set Disabled O Read: Enabled Write '1' to enable interrupt for event CHSLIMITH Finable Read: Enabled Write '1' to enable interrupt for event CHSLIMITH Read: Disabled Read: Disabled Read: Disabled Read: Enabled Read: Enabled Write '1' to enable interrupt for event CHSLIMITL Set Disabled O Read: Disabled Read: Enabled Read: Enabled Write '1' to enable interrupt for event CHSLIMITL Read: Enabled Write '1' to enable interrupt for event CHSLIMITL Finable Set Disabled Write '1' to enable interrupt for event CH6LIMITH Read: Enabled Read: Enabled Read: Enabled Read: Disabled Read: Disabled Read: Disabled	Р	RW CH4LIMITL			Write '1' to enable interrupt for event CH4LIMITL
RW CHSLIMITH Set 1 Enabled 1 Read: Enabled R RW CHSLIMITH Set 1 Enable Disabled 0 Read: Disabled Enabled R RW CHSLIMITL Set 1 Read: Enabled R RW CHSLIMITL Set 1 Enable Set 1 Enable Set 1 Enable Inable Read: Enabled Read: Enabled Read: Enabled Set 1 Enable Disabled 0 Read: Disabled Read: Enabled Set 1 Enable Disabled 1 Read: Enabled Set 1 Enable Enable Enable Set 1 Enabled Read: Disabled Read: Enabled Read: Enabled Read: Enabled Set 1 Enabled Read: Enabled Read: Enabled			Set	1	Enable
Q RW CH5LIMITH Set 1 Enable Disabled 0 Read: Disabled Read: Enabled Read: Enabled Read: Enabled Read: Enabled Read: Enabled Read: Disabled Read: Enabled Read: Enabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Disabled Read: Enabled Read: Disabled Read: Disabled Read: Disabled			Disabled	0	Read: Disabled
Set 1 Enable Disabled 0 Read: Disabled Read: Enabled Write '1' to enable interrupt for event CH5LIMITL Set 1 Enable Disabled 0 Read: Disabled Enable Disabled 0 Read: Disabled Read: Enabled Set 1 Enable Disabled 1 Read: Enabled Write '1' to enable interrupt for event CH5LIMITL Enable Enable Set 1 Read: Enabled Set 1 Enabled Disabled 0 Read: Disabled			Enabled	1	Read: Enabled
Disabled 0 Read: Disabled R RW CH5LIMITL Set 1 Enabled Set 1 Enabled Disabled 0 Read: Enabled Read: Enablee Disabled 0 Read: Disabled Disabled 0 Read: Disabled Enabled 1 Read: Enabled Set 1 Read: Enabled Set 1 Read: Enabled Finabled 1 Read: Enabled Set 1 Read: Enabled Read: Enabled Set 1 Read: Enabled Read: Disabled 0 Read: Disabled	Q	RW CH5LIMITH			Write '1' to enable interrupt for event CH5LIMITH
R RW CH5LIMITL Set Inabled 1 Read: Enabled Enable interrupt for event CH5LIMITL Set Inable Disabled Inable Enable Enable Read: Disabled Read: Disabled Read: Enabled SRW CH6LIMITH Set Inable Inable Inable Enable Enable Read: Enable Read: Enable Read: Enable Read: Enable Read: Enable Read: Disabled Read: Disabled			Set	1	Enable
R RW CH5LIMITL Set 1 Enable Disabled 0 Read: Disabled Enabled 1 Read: Enabled S RW CH6LIMITH Set 1 Enable Enabled 1 Read: Enabled S RW CH6LIMITH Set 1 Enable Disabled 0 Read: Disabled Read: Disabled Mrite '1' to enable interrupt for event CH6LIMITH Enable Disabled 0 Read: Disabled			Disabled	0	Read: Disabled
Set 1 Enable Disabled 0 Read: Disabled Enabled 1 Read: Enabled S RW CH6LIMITH Set 1 Enable Disabled 0 Read: Disabled Read: Enabled Write '1' to enable interrupt for event CH6LIMITH Set 1 Enable Disabled 0 Read: Disabled			Enabled	1	Read: Enabled
Disabled 0 Read: Disabled Enabled 1 Read: Enabled S RW CH6LIMITH Set 1 Enable Disabled 0 Read: Disabled	R	RW CH5LIMITL			Write '1' to enable interrupt for event CH5LIMITL
Enabled 1 Read: Enabled S RW CH6LIMITH Set 1 Enable Disabled 0 Read: Enabled Read: Enabled Write '1' to enable interrupt for event CH6LIMITH Enable Disabled 0 Read: Disabled			Set	1	Enable
S RW CH6LIMITH Set 1 Enable Disabled 0 Read: Disabled			Disabled	0	Read: Disabled
Set 1 Enable Disabled 0 Read: Disabled			Enabled	1	Read: Enabled
Disabled 0 Read: Disabled	S	RW CH6LIMITH			Write '1' to enable interrupt for event CH6LIMITH
			Set	1	Enable
Enabled 1 Read: Enabled			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled



Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID	V U T S R Q P O N M L K J I H G F E D C B
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	
T RW CH6LIMITL	Write '1' to enable interrupt for event CH6LIMITL
Set	1 Enable
Disabled	0 Read: Disabled
Enabled	1 Read: Enabled
U RW CH7LIMITH	Write '1' to enable interrupt for event CH7LIMITH
Set	1 Enable
Disabled	0 Read: Disabled
Enabled	1 Read: Enabled
V RW CH7LIMITL	Write '1' to enable interrupt for event CH7LIMITL
Set	1 Enable
Disabled	0 Read: Disabled
Enabled	1 Read: Enabled

6.17.11.15 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		31 30 29 28 27 2	6 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW STARTED				Write '1' to disable interrupt for event STARTED
		Clear	1		Disable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
В	RW END				Write '1' to disable interrupt for event END
		Clear	1		Disable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
С	RW DONE				Write '1' to disable interrupt for event DONE
		Clear	1		Disable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
D	RW RESULTDONE				Write '1' to disable interrupt for event RESULTDONE
		Clear	1		Disable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
E	RW CALIBRATEDONE				Write '1' to disable interrupt for event CALIBRATEDONE
		Clear	1		Disable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
F	RW STOPPED				Write '1' to disable interrupt for event STOPPED
		Clear	1		Disable
		Disabled	0		Read: Disabled
		Enabled	1		Read: Enabled
G	RW CHOLIMITH				Write '1' to disable interrupt for event CHOLIMITH
		Clear	1		Disable
		Disabled	0		Read: Disabled



Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Reset	t 0x000000	000		0 0 0 0 0 0 0 0	000000000000000000000000000000000000000
			Enabled	1	Read: Enabled
Н	RW CHO	DLIMITL			Write '1' to disable interrupt for event CHOLIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
I	RW CH1	LLIMITH			Write '1' to disable interrupt for event CH1LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
J	RW CH1	LLIMITL			Write '1' to disable interrupt for event CH1LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
K	RW CH2	LIMITH			Write '1' to disable interrupt for event CH2LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
L	RW CH2	LIMITL			Write '1' to disable interrupt for event CH2LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
М	RW CH3	BLIMITH			Write '1' to disable interrupt for event CH3LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
N	RW CH3	BLIMITL			Write '1' to disable interrupt for event CH3LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
0	RW CH4	ILIMITH			Write '1' to disable interrupt for event CH4LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Р	RW CH4	ILIMITL			Write '1' to disable interrupt for event CH4LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Q	RW CH5	SLIMITH			Write '1' to disable interrupt for event CH5LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
R	RW CH5				Write '1' to disable interrupt for event CH5LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
S	RW CH6				Write '1' to disable interrupt for event CH6LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Т	RW CH6	SLIMITL			Write '1' to disable interrupt for event CH6LIMITL



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
U	RW CH7LIMITH			Write '1' to disable interrupt for event CH7LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
٧	RW CH7LIMITL			Write '1' to disable interrupt for event CH7LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.17.11.16 STATUS

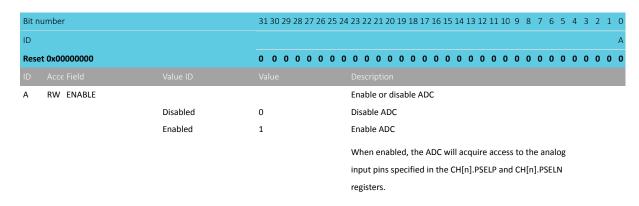
Address offset: 0x400

Status

Bit number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A R STATUS		Status
Ready	0	ADC is ready. No on-going conversion.
Busy	1	ADC is busy. Conversion in progress.

6.17.11.17 ENABLE

Address offset: 0x500 Enable or disable ADC



6.17.11.18 CH[n].PSELP (n=0..7)

Address offset: $0x510 + (n \times 0x10)$

Input positive pin selection for CH[n]



Bit number		31	30 2	9 2	28 27	7 26	6 25	5 24	4 23	3 22	21	20	19 1	18 1	L7 1	16	15 1	L4 1	3 1	2 11	10	9	8	7	6 !	5 4	4 3	2	1	0
ID																										A	Α Α	Α	Α	Α
Reset 0x00000000		0	0 ()	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 () (0	0	0	0
ID Acce Field																														
A RW PSELP									Aı	nalo	g po	sit	ive	inp	ut	cha	nne	el												
	NC	0							N	ot c	onn	ect	ed																	
	AnalogInput0	1							ΑI	N0																				
	AnalogInput1	2							ΑI	N1																				
	AnalogInput2	3							ΑI	N2																				
	AnalogInput3	4							ΑI	N3																				
	AnalogInput4	5							ΑI	N4																				
	AnalogInput5	6							ΑI	N5																				
	AnalogInput6	7							Αl	N6																				
	AnalogInput7	8							Αl	N7																				
	VDD	9							VI	DD																				

6.17.11.19 CH[n].PSELN (n=0..7)

Address offset: $0x514 + (n \times 0x10)$ Input negative pin selection for CH[n]

Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW PSELN			Analog negative input, enables differential channel
		NC	0	Not connected
		AnalogInput0	1	AIN0
		AnalogInput1	2	AIN1
		AnalogInput2	3	AIN2
		AnalogInput3	4	AIN3
		AnalogInput4	5	AIN4
		AnalogInput5	6	AIN5
		AnalogInput6	7	AIN6
		AnalogInput7	8	AIN7
		VDD	9	VDD

6.17.11.20 CH[n].CONFIG (n=0..7)

Address offset: $0x518 + (n \times 0x10)$ Input configuration for CH[n]

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		G	G FEEE D CCC BB AA
Reset 0x00020000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW RESP			Positive channel resistor control
	Bypass	0	Bypass resistor ladder
	Pulldown	1	Pull-down to GND
	Pullup	2	Pull-up to VDD
	VDD1_2	3	Set input at VDD/2
B RW RESN			Negative channel resistor control
	Bypass	0	Bypass resistor ladder



Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		01302320272023	G F E E E D C C C B B A A
Reset 0x00020000		0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field		Value	Description
7,65c Freid	Pulldown	1	Pull-down to GND
	Pullup	2	Pull-up to VDD
	VDD1 2	3	Set input at VDD/2
C RW GAIN	_		Gain control
	Gain1_6	0	1/6
	Gain1_5	1	1/5
	Gain1_4	2	1/4
	Gain1_3	3	1/3
	Gain1_2	4	1/2
	Gain1	5	1
	Gain2	6	2
	Gain4	7	4
D RW REFSEL			Reference control
	Internal	0	Internal reference (0.6 V)
	VDD1_4	1	VDD/4 as reference
E RW TACQ			Acquisition time, the time the ADC uses to sample the input
			voltage
	3us	0	3 us
	5us	1	5 us
	10us	2	10 us
	15us	3	15 us
	20us	4	20 us
	40us	5	40 us
F RW MODE			Enable differential mode
	SE	0	Single ended, PSELN will be ignored, negative input to ADC
			shorted to GND
	Diff	1	Differential
G RW BURST			Enable burst mode
	Disabled	0	Burst mode is disabled (normal operation)
	Enabled	1	Burst mode is enabled. SAADC takes 2^OVERSAMPLE
			number of samples as fast as it can, and sends the average
			to Data RAM.

6.17.11.21 CH[n].LIMIT (n=0..7)

Address offset: $0x51C + (n \times 0x10)$

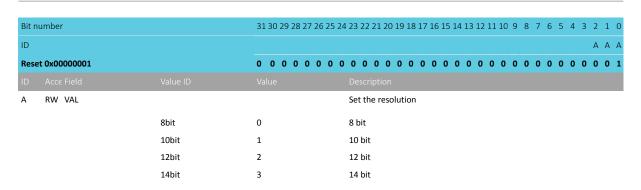
High/low limits for event monitoring a channel

Bit n	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	. 0
ID		B B B B B B B B B B B B B B B B A A A A	A
Rese	et 0x7FFF8000	0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0	0
ID			
Α	RW LOW	[-32768 to +32767] Low level limit	
В	RW HIGH	[-32768 to +32767] High level limit	

6.17.11.22 RESOLUTION

Address offset: 0x5F0
Resolution configuration

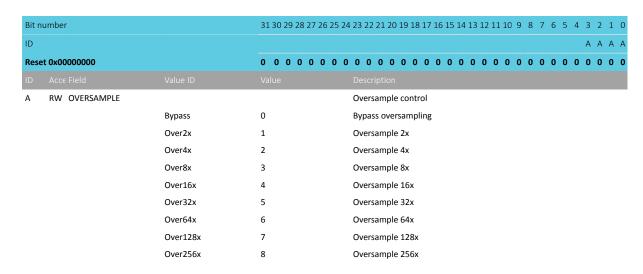




6.17.11.23 OVERSAMPLE

Address offset: 0x5F4

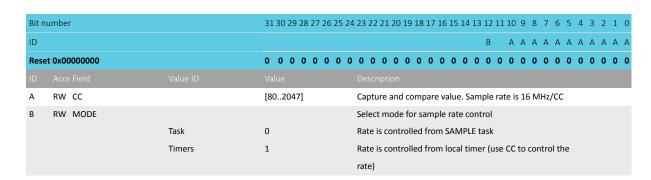
Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION should be used.



6.17.11.24 SAMPLERATE

Address offset: 0x5F8

Controls normal or continuous sample rate

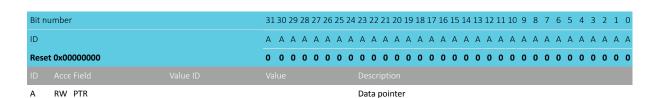


6.17.11.25 RESULT.PTR

Address offset: 0x62C

Data pointer





6.17.11.26 RESULT.MAXCNT

Address offset: 0x630

Maximum number of buffer words to transfer

Α	RW MAXCNT		Maximum number of buf	ffer words to t	ransfer						
ID											
Rese	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0	0 0 0 0	0 0 0	0	0	0 0	0	0 0	0
ID				AAAA	AAA	A A	A	А А	Α .	А А	Α
Bit r	umber	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 1	15 14 13 12 11	. 10 9 8	3 7	6	5 4	3	2 1	0

6.17.11.27 RESULT.AMOUNT

Address offset: 0x634

Number of buffer words transferred since last START

A R AMOUNT		Number of	huffer wa	rds tra	ncfor	rad c	ince l	act S	TΔR	T Th	nic			
ID Acce Field														
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0	0 0 0	0 0	0 0	0 (0 0	0 0	0	0	0 0	0	0	0 0
ID					A A	Α /	A A	A A	Α	Α	ΑА	Α	Α	А А
Bit number	31 30 29 28 27 26 25	24 23 22 21 20	19 18 17	16 15	14 13	12 1	1 10	9 8	7	6	5 4	3	2	1 0

register can be read after an END or STOPPED event.

6.17.12 Electrical specification

6.17.12.1 SAADC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
DNL ₁₀	Differential non-linearity, 10-bit resolution	-0.95	<1		LSB10b
INL ₁₀	Integral non-linearity, 10-bit resolution		1		LSB1(
V _{OS}	Differential offset error (calibrated), 10-bit resolution ^a		+-2		LSB10b
DNL ₁₂	Differential non-linearity, 12-bit resolution	-0.95	1.3		LSB12
INL ₁₂	Integral non-linearity, 12-bit resolution		4.7		LSB12b
C_{EG}	Gain error temperature coefficient		0.02		%/°C
f _{SAMPLE}	Maximum sampling rate			200	kHz
t _{ACQ,10k}	Acquisition time (configurable), source Resistance <= 10kOhm		3		μs
t _{ACQ,40k}	Acquisition time (configurable), source Resistance <= 40kOhm		5		μs
t _{ACQ,100k}	Acquisition time (configurable), source Resistance <= 100kOhm		10		μs
t _{ACQ,200k}	Acquisition time (configurable), source Resistance <= 200kOhm		15		μs

^a Digital output code at zero volt differential input.



Symbol	Description	Min.	Тур.	Max.	Units
t _{ACQ,400k}	Acquisition time (configurable), source Resistance <=		20		μs
	400kOhm				
t _{ACQ,800k}	Acquisition time (configurable), source Resistance <=		40		μs
	800kOhm				
t _{CONV}	Conversion time		<2		μs
E _{G1/6}	Error ^b for Gain = 1/6	-3		3	%
E _{G1/4}	Error ^b for Gain = 1/4	-3		3	%
E _{G1/2}	Error ^b for Gain = 1/2	-3		4	%
E _{G1}	Error ^b for Gain = 1	-3		4	%
C _{SAMPLE}	Sample and hold capacitance at maximum gain ²¹		2.5		pF
R _{INPUT}	Input resistance		>1		ΜΩ
E _{NOB}	Effective number of bits, differential mode, 12-bit		9		Bit
	resolution, 1/1 gain, 3 μs acquisition time, crystal HFCLK,				
	200 ksps				
S _{NDR}	Peak signal to noise and distortion ratio, differential mode,		56		dB
	12-bit resolution, 1/1 gain, 3 μs acquisition time, crystal				
	HFCLK, 200 ksps				
S _{FDR}	Spurious free dynamic range, differential mode, 12-bit		70		dBc
	resolution, 1/1 gain, 3 μs acquisition time, crystal HFCLK,				
	200 ksps				
R _{LADDER}	Ladder resistance		160		kΩ

6.17.13 Performance factors

Clock jitter, affecting sample timing accuracy, and circuit noise can affect ADC performance.

Jitter can be between START tasks or from START task to acquisition. START timer accuracy and startup times of regulators and references will contribute to variability. Sources of circuit noise may include CPU activity and the DC/DC regulator. Best ADC performance is achieved using START timing based on the TIMER module, HFXO clock source, and Constant Latency mode.

6.18 SPI — Serial peripheral interface master

The SPI master provides a simple CPU interface which includes a TXD register for sending data and an RXD register for receiving data. This section is added for legacy support for now.



^b Does not include temperature drift

²¹ Maximum gain corresponds to highest capacitance.

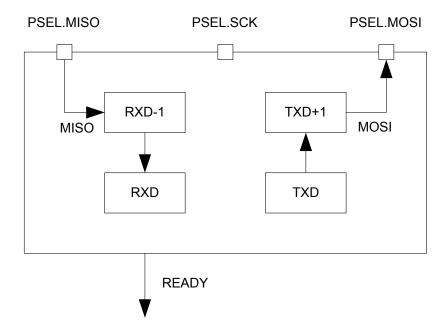


Figure 99: SPI master

RXD-1 and TXD+1 illustrate the double buffered version of RXD and TXD respectively.

6.18.1 Functional description

The TXD and RXD registers are double-buffered to enable some degree of uninterrupted data flow in and out of the SPI master.

The SPI master does not implement support for chip select directly. Therefore, the CPU must use available GPIOs to select the correct slave and control this independently of the SPI master. The SPI master supports SPI modes 0 through 3.

Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Leading)	0 (Active high)
SPI_MODE1	0 (Leading)	1 (Active low)
SPI_MODE2	1 (Trailing)	0 (Active high)
SPI_MODE3	1 (Trailing)	1 (Active low)

Table 77: SPI modes

6.18.1.1 SPI master mode pin configuration

The different signals SCK, MOSI, and MISO associated with the SPI master are mapped to physical pins.

This mapping is according to the configuration specified in the PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively. If the CONNECT field of a PSEL.xxx register is set to Disconnected, the associated SPI master signal is not connected to any physical pin. The PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI master is enabled, and retained only as long as the device is in ON mode. PSEL.SCK, PSEL.MOSI, and PSEL.MISO must only be configured when the SPI master is disabled.

To secure correct behavior in the SPI, the pins used by the SPI must be configured in the GPIO peripheral as described in GPIO configuration on page 258 prior to enabling the SPI. The SCK must always be connected to a pin, and that pin's input buffer must always be connected for the SPI to work. This configuration must be retained in the GPIO for the selected IOs as long as the SPI is enabled.



Only one peripheral can be assigned to drive a particular GPIO pin at a time, failing to do so may result in unpredictable behavior.

SPI master signal	SPI master pin	Direction	Output value
SCK	As specified in PSEL.SCK	Output	Same as CONFIG.CPOL
MOSI	As specified in PSEL.MOSI	Output	0
MISO	As specified in PSEL.MISO	Input	Not applicable

Table 78: GPIO configuration

6.18.1.2 Shared resources

The SPI shares registers and other resources with other peripherals that have the same ID as the SPI. Therefore, the user must disable all peripherals that have the same ID as the SPI before the SPI can be configured and used.

Disabling a peripheral that has the same ID as the SPI will not reset any of the registers that are shared with the SPI. It is therefore important to configure all relevant SPI registers explicitly to secure that it operates correctly.

See the Instantiation table in Instantiation on page 19 for details on peripherals and their IDs.

6.18.1.3 SPI master transaction sequence

An SPI master transaction is started by writing the first byte, which is to be transmitted by the SPI master, to the TXD register.

Since the transmitter is double buffered, the second byte can be written to the TXD register immediately after the first one. The SPI master will then send these bytes in the order they are written to the TXD register.

The SPI master is a synchronous interface, and for every byte that is sent, a different byte will be received at the same time; this is illustrated in SPI master transaction on page 259. Bytes that are received will be moved to the RXD register where the CPU can extract them by reading the register. The RXD register is double buffered in the same way as the TXD register, and a second byte can therefore be received at the same time as the first byte is being extracted from RXD by the CPU. The SPI master will generate a READY event every time a new byte is moved to the RXD register. The double buffered byte will be moved from RXD-1 to RXD as soon as the first byte is extracted from RXD. The SPI master will stop when there are no more bytes to send in TXD and TXD+1.



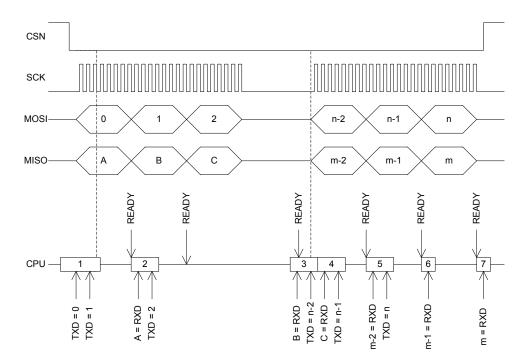


Figure 100: SPI master transaction

The READY event of the third byte transaction is delayed until B is extracted from RXD in occurrence number 3 on the horizontal lifeline. The reason for this is that the third event is generated first when C is moved from RXD-1 to RXD after B is read.

The SPI master will move the incoming byte to the RXD register after a short delay following the SCK clock period of the last bit in the byte. This also means that the READY event will be delayed accordingly, see SPI master transaction on page 259. Therefore, it is important that you always clear the READY event, even if the RXD register and the data that is being received is not used.

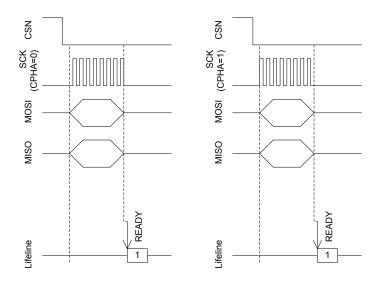


Figure 101: SPI master transaction



6.18.2 Registers

Base address	Peripheral	Instance	Description	Configuration	
0x40004000	SPI	SPI0	SPI master		Deprecated

Table 79: Instances

Register	Offset	Description
EVENTS_READY	0x108	TXD byte sent and RXD byte received
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ENABLE	0x500	Enable SPI
PSEL.SCK	0x508	Pin select for SCK
PSEL.MOSI	0x50C	Pin select for MOSI signal
PSEL.MISO	0x510	Pin select for MISO signal
RXD	0x518	RXD register
TXD	0x51C	TXD register
FREQUENCY	0x524	SPI frequency. Accuracy depends on the HFCLK source selected.
CONFIG	0x554	Configuration register

Table 80: Register overview

6.18.2.1 EVENTS_READY

Address offset: 0x108

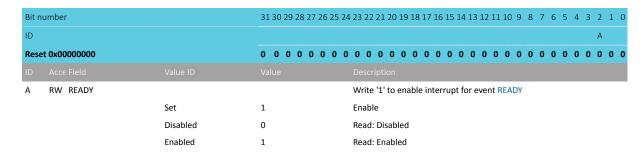
TXD byte sent and RXD byte received

Bit r	number		31 30 29 28 27 26 25	$24\ 23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID				А
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_READY			TXD byte sent and RXD byte received
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.18.2.2 INTENSET

Address offset: 0x304

Enable interrupt

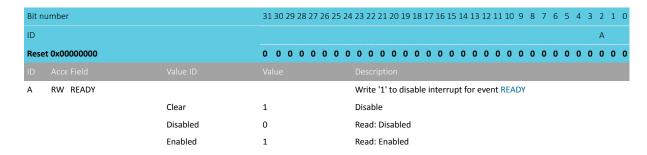


6.18.2.3 INTENCLR

Address offset: 0x308



Disable interrupt



6.18.2.4 ENABLE

Address offset: 0x500

Enable SPI

Bit number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			ААА
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW ENABLE			Enable or disable SPI
	Disabled	0	Disable SPI
	Enabled	1	Enable SPI

6.18.2.5 PSEL.SCK

Address offset: 0x508

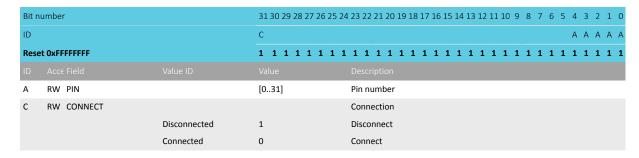
Pin select for SCK

Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.18.2.6 PSEL.MOSI

Address offset: 0x50C

Pin select for MOSI signal

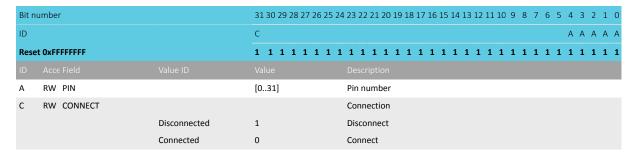




6.18.2.7 PSEL.MISO

Address offset: 0x510

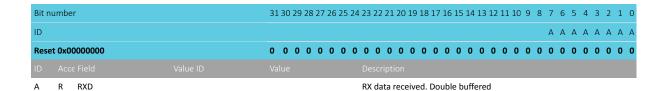
Pin select for MISO signal



6.18.2.8 RXD

Address offset: 0x518

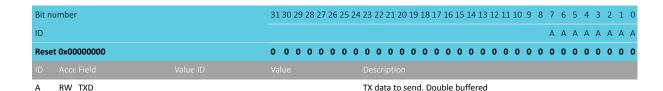
RXD register



6.18.2.9 TXD

Address offset: 0x51C

TXD register



6.18.2.10 FREQUENCY

Address offset: 0x524

SPI frequency. Accuracy depends on the HFCLK source selected.



Bit number		31	30 29	9 2	8 27	7 26	25	24	23 2	2 2:	1 20	19	18	17 :	16 1	15 1	4 13	3 12	11	10	9	8	7	6 5	5 4	4 3	2	1 0
ID		Α	А А	\ <i>A</i>	A А	Α	Α	Α	Α	Д Д	A	Α	Α	Α	Α	Α ,	4 Α	A	Α	Α	Α	A A	Δ.	Δ /	A A	A A	Α	A A
Reset 0x04000000		0	0 0) (0	1	0	0	0	0 0	0	0	0	0	0	0 (0 0	0	0	0	0	0 ()	0 () (0	0	0 0
ID Acce Field Va																												
A RW FREQUENCY									SPI	mas	ter	data	a ra	te														
K	125	0x0	200	000	00				125	kbp	S																	
KZ	250	0x0	0400	000	00				250	kbp	S																	
K	500	0x0	0800	000	00				500	kbp	S																	
M	11	0x1	1000	000	00				1 M	bps																		
M	12	0x2	2000	000	00				2 M	bps																		
M	14	0x4	1000	000	00				4 M	bps																		
M	18	0x8	3000	000	00				8 M	bps																		

6.18.2.11 CONFIG

Address offset: 0x554 Configuration register

Bit number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			СВА
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A RW ORDER			Bit order
	MsbFirst	0	Most significant bit shifted out first
	LsbFirst	1	Least significant bit shifted out first
B RW CPHA			Serial clock (SCK) phase
	Leading	0	Sample on leading edge of clock, shift serial data on trailing
			edge
	Trailing	1	Sample on trailing edge of clock, shift serial data on leading
			edge
C RW CPOL			Serial clock (SCK) polarity
	ActiveHigh	0	Active high
	ActiveLow	1	Active low

6.18.3 Electrical specification

6.18.3.1 SPI master interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPI}	Bit rates for SPI ²²			8 ²³	Mbps
t _{SPI,START}	Time from writing TXD register to transmission started		1		μs

6.18.3.2 Serial Peripheral Interface (SPI) Master timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPI,CSCK}	SCK period	125			ns
$t_{SPI,RSCK,LD}$	SCK rise time, standard drive ^a			t _{RF,25pF}	

High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

NORDIC*

The actual maximum data rate depends on the slave's CLK to MISO and MOSI setup and hold timings.

^a At 25pF load, including GPIO capacitance, see GPIO spec.

Symbol	Description	Min.	Тур.	Max.	Units
$t_{SPI,RSCK,HD}$	SCK rise time, high drive ^a			t _{HRF,25pF}	
t _{SPI,FSCK,LD}	SCK fall time, standard drive ^a			t _{RF,25pF}	
t _{SPI,FSCK,HD}	SCK fall time, high drive ^a			t _{HRF,25pF}	
t _{SPI,WHSCK}	SCK high time ^a	(t _{CSCK}	′ 2)		
		- t _{RSC}	(
t _{SPI,WLSCK}	SCK low time ^a	(t _{CSCK}	′ 2)		
		- t _{FSCI}	(
t _{SPI,SUMI}	MISO to CLK edge setup time	19			ns
t _{SPI,HMI}	CLK edge to MISO hold time	18			ns
t _{SPI,VMO}	CLK edge to MOSI valid			59	ns
t _{SPI,HMO}	MOSI hold time after CLK edge	20			ns

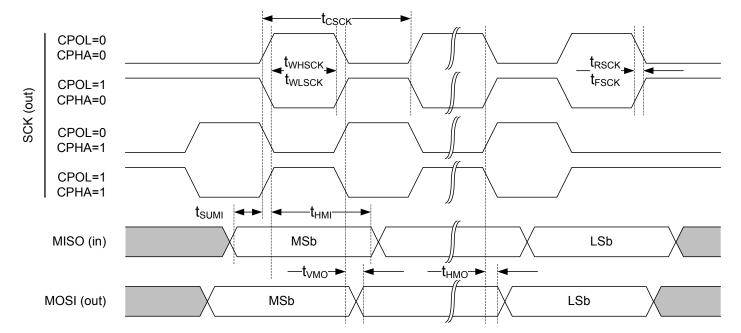


Figure 102: SPI master timing diagram

6.19 SPIM — Serial peripheral interface master with EasyDMA

The SPI master can communicate with multiple slaves using individual chip select signals for each of the slave devices attached to a bus.

Listed here are the main features for the SPIM

- SPI mode 0-3
- EasyDMA direct transfer to/from RAM for both SPI Slave and SPI Master
- Individual selection of IO pin for each SPI signal



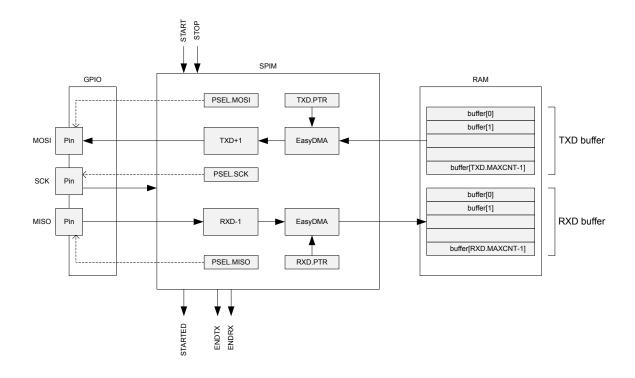


Figure 103: SPIM — SPI master with EasyDMA

The SPIM does not implement support for chip select directly. Therefore, the CPU must use available GPIOs to select the correct slave and control this independently of the SPI master. The SPIM supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.

Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Leading)
SPI_MODE1	0 (Active High)	1 (Trailing)
SPI_MODE2	1 (Active Low)	0 (Leading)
SPI_MODE3	1 (Active Low)	1 (Trailing)

Table 81: SPI modes

6.19.1 SPI master transaction sequence

An SPI master transaction consists of a sequence started by the START task followed by a number of events, and finally the STOP task.

An SPI master transaction is started by triggering the START task. The ENDTX event will be generated when the transmitter has transmitted all bytes in the TXD buffer as specified in the TXD.MAXCNT register. The ENDRX event will be generated when the receiver has filled the RXD buffer, i.e. received the last possible byte as specified in the RXD.MAXCNT register.

Following a START task, the SPI master will generate an END event when both ENDRX and ENDTX have been generated.

The SPI master is stopped by triggering the STOP task. A STOPPED event is generated when the SPI master has stopped.

If the ENDRX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDRX event explicitly even though the RX buffer is not full.



If the ENDTX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

The SPI master is a synchronous interface, and for every byte that is sent, a different byte will be received at the same time; this is illustrated in SPI master transaction on page 266.

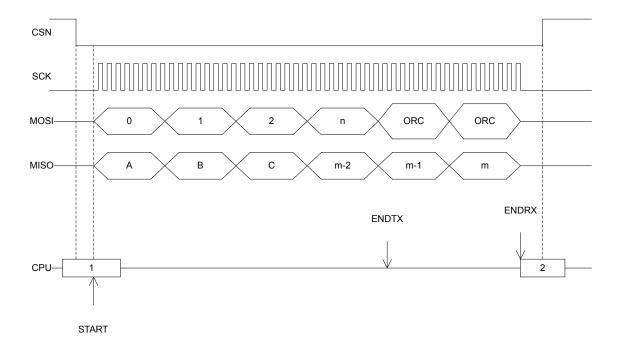


Figure 104: SPI master transaction

6.19.2 Master mode pin configuration

The SCK, MOSI, and MISO signals associated with the SPI master are mapped to physical pins according to the configuration specified in the PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively.

The PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI master is enabled, and retained only as long as the device is in ON mode. PSEL.SCK, PSEL.MOSI and PSEL.MISO must only be configured when the SPI master is disabled.

To secure correct behavior in the SPI, the pins used by the SPI must be configured in the GPIO peripheral as described in GPIO configuration on page 266 prior to enabling the SPI. This configuration must be retained in the GPIO for the selected IOs as long as the SPI is enabled.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI master signal	SPI master pin	Direction	Output value
SCK	As specified in PSEL.SCK	Output	Same as CONFIG.CPOL
MOSI	As specified in PSEL.MOSI	Output	0
MISO	As specified in PSEL.MISO	Input	Not applicable

Table 82: GPIO configuration



6.19.3 EasyDMA

The SPIM implements EasyDMA for accessing RAM without CPU involvement.

The SPIM peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 83: SPIM EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 36.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next transmission immediately after having received the STARTED event.

The SPI master will automatically stop transmitting after TXD.MAXCNT bytes have been transmitted and RXD.MAXCNT bytes have been received. If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register. If TXD.MAXCNT is larger than RXD.MAXCNT, the superfluous received bytes will be discarded.

The ENDRX/ENDTX event indicate that EasyDMA has finished accessing respectively the RX/TX buffer in RAM. The END event gets generated when both RX and TX are finished accessing the buffers in RAM.

In the case of bus congestion as described in , data loss may occur.

6.19.4 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.19.5 Registers

Base address	Peripheral	Instance	Description	Configuration	
0x40004000	SPIM	SPIM0	SPI master		

Table 84: Instances

Register	Offset	Description
TASKS_START	0x010	Start SPI transaction
TASKS_STOP	0x014	Stop SPI transaction
TASKS_SUSPEND	0x01C	Suspend SPI transaction
TASKS_RESUME	0x020	Resume SPI transaction
EVENTS_STOPPED	0x104	SPI transaction has stopped
EVENTS_ENDRX	0x110	End of RXD buffer reached
EVENTS_END	0x118	End of RXD buffer and TXD buffer reached
EVENTS_ENDTX	0x120	End of TXD buffer reached
EVENTS_STARTED	0x14C	Transaction started
SHORTS	0x200	Shortcuts between local events and tasks
INTENSET	0x304	Enable interrupt

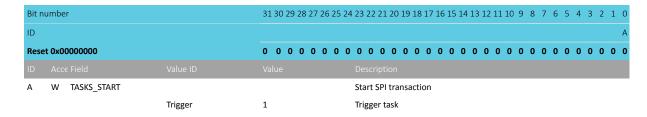


Register	Offset	Description
INTENCLR	0x308	Disable interrupt
ENABLE	0x500	Enable SPIM
PSEL.SCK	0x508	Pin select for SCK
PSEL.MOSI	0x50C	Pin select for MOSI signal
PSEL.MISO	0x510	Pin select for MISO signal
FREQUENCY	0x524	SPI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534	Data pointer
RXD.MAXCNT	0x538	Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C	Number of bytes transferred in the last transaction
RXD.LIST	0x540	EasyDMA list type
TXD.PTR	0x544	Data pointer
TXD.MAXCNT	0x548	Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C	Number of bytes transferred in the last transaction
TXD.LIST	0x550	EasyDMA list type
CONFIG	0x554	Configuration register
ORC	0x5C0	Over-read character. Character clocked out in case and over-read of the TXD buffer.

Table 85: Register overview

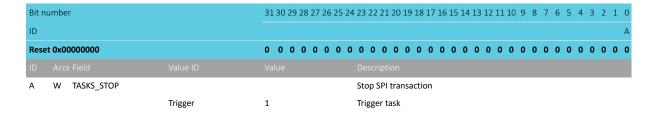
6.19.5.1 TASKS_START

Address offset: 0x010 Start SPI transaction



6.19.5.2 TASKS_STOP

Address offset: 0x014 Stop SPI transaction



6.19.5.3 TASKS_SUSPEND

Address offset: 0x01C Suspend SPI transaction



Bit n	uml	ber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t Ox	c00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_SUSPEND			Suspend SPI transaction
			Trigger	1	Trigger task

6.19.5.4 TASKS_RESUME

Address offset: 0x020 Resume SPI transaction

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_RESUME			Resume SPI transaction
		Trigger	1	Trigger task

6.19.5.5 EVENTS_STOPPED

Address offset: 0x104

SPI transaction has stopped

В	it nı	umber		31	30	29	28	27	26	25	24	23	22	21	L 21	0 1	9 1	8 1	7 1	6	15	14	13	12	11	10	9	8	7	6 !	5 4	4 3	2	1	0
11)																																		Α
F	ese	t 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0) () ()	0	0	0	0	0	0	0	0	0 (0 (0 (0 (0	0	0	0
П																																			
A		RW EVENTS_STOPPED										SP	l tr	ans	sac	tio	n h	as	stc	pp	ed														
			NotGenerated	0								Ev	ent	t no	ot g	gen	era	ite	b																
			Generated	1								Ev	ent	t ge	ene	erat	ed																		

6.19.5.6 EVENTS_ENDRX

Address offset: 0x110

End of RXD buffer reached

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_ENDRX			End of RXD buffer reached
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.19.5.7 EVENTS_END

Address offset: 0x118

End of RXD buffer and TXD buffer reached



Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_END			End of RXD buffer and TXD buffer reached
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.19.5.8 EVENTS_ENDTX

Address offset: 0x120 End of TXD buffer reached

Bit n	umber		31	30 2	29 2	28 2	7 26	25	24 2	23 2	22 2	1 20	19	18	17 1	6 1	5 14	13	12 1	1 10	9	8	7	6	5	4 3	3 2	1	0
ID																													Α
Rese	et 0x00000000		0	0	0	0 0	0	0	0	0 (0 0	0	0	0	0 (0 0	0	0	0 (0	0	0	0	0	0	0 (0	0	0
ID																													
Α	RW EVENTS_ENDTX								-	End	of ⁻	TXD	buf	fer	reac	hec	ı												
		NotGenerated	0						-	ever	nt n	ot g	ene	rate	ed														
		Generated	1						-	ever	nt g	ene	rate	d															

6.19.5.9 EVENTS_STARTED

Address offset: 0x14C
Transaction started

Bit n	umber		313	0 29	28	27 2	6 25	24	23	22 2	21 20	0 19	18	17 1	6 15	5 14	13	L2 1:	1 10	9	8 7	' 6	5	4	3	2	1 0
ID																											А
Rese	t 0x00000000		0 (0 0	0	0 (0	0	0	0	0 0	0	0	0 (0	0	0	0 0	0	0	0 0	0	0	0	0	0	0 0
ID																											
Α	RW EVENTS_STARTED								Tra	nsa	ctio	n sta	artec	i													
		NotGenerated	0						Eve	nt r	not g	gene	erate	d													
		Generated	1						Eve	nt g	gene	erate	ed														

6.19.5.10 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW END_START			Shortcut between event END and task START
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.19.5.11 INTENSET

Address offset: 0x304

Enable interrupt



Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			E D C B A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW STOPPED			Write '1' to enable interrupt for event STOPPED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
B RW ENDRX			Write '1' to enable interrupt for event ENDRX
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
C RW END			Write '1' to enable interrupt for event END
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
D RW ENDTX			Write '1' to enable interrupt for event ENDTX
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
E RW STARTED			Write '1' to enable interrupt for event STARTED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.19.5.12 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW ENDRX			Write '1' to disable interrupt for event ENDRX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW END			Write '1' to disable interrupt for event END
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ENDTX			Write '1' to disable interrupt for event ENDTX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Ε	RW STARTED			Write '1' to disable interrupt for event STARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled



Reset 0x000000000	0 0 0 0 0 0 0 0 0 0
Reset 0x000000000 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0
ID F	D C B A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11	10 9 8 7 6 5 4 3 2 1

6.19.5.13 ENABLE

Address offset: 0x500

Enable SPIM

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW ENABLE			Enable or disable SPIM
		Disabled	0	Disable SPIM
		Enabled	7	Enable SPIM

6.19.5.14 PSEL.SCK

Address offset: 0x508

Pin select for SCK

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0					
ID			C A A A						
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1					
ID				Description					
Α	RW PIN		[031]	Pin number					
C	RW CONNECT		[031]	Pin number Connection					
С		Disconnected	[031]						

6.19.5.15 PSEL.MOSI

Address offset: 0x50C

Pin select for MOSI signal

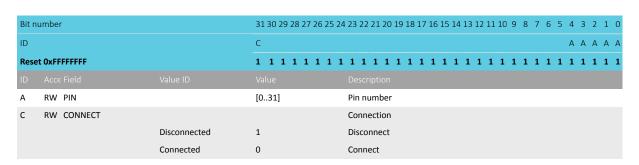
Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.19.5.16 PSEL.MISO

Address offset: 0x510

Pin select for MISO signal





6.19.5.17 FREQUENCY

Address offset: 0x524

SPI frequency. Accuracy depends on the HFCLK source selected.

Bit nu	mber		31	. 30 2	29 2	28 2	7 2	6 25	5 24	23	3 22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4 3	2	1	. 0
ID			Α	Α	Α /	Δ Δ	Δ Δ	A A	A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α.	Α	A	Α.	A A	. A	ιA	A
Reset	0x0400000		0	0	0 (0 0) 1	. 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0	0
ID																																
Α	RW FREQUENCY									SF	Pl m	nast	er c	lata	rat	te																
		K125	0x	0200	000	00				12	25 k	bps	5																			
		K250	0x	0400	000	00				25	50 k	bps	5																			
		K500	0x	080	000	00				50	00 k	bps	5																			
		M1	0x	1000	000	00				1	Mb	ps																				
		M2	0x	2000	000	00				2	Mb	ps																				
		M4	0x	4000	000	00				4	Mb	ps																				
		M8	0x	8000	000	00				8	Mb	ps																				

6.19.5.18 RXD.PTR

Address offset: 0x534

Data pointer

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Rese	t 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		Value Description
Α	RW PTR	Data pointer

Note: See the memory chapter for details about which memories are available for EasyDMA.

6.19.5.19 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer

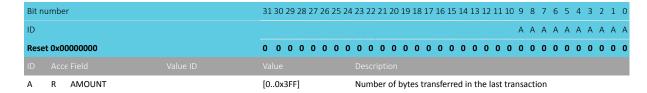
Α	RW MAXCNT	[00x3FF]	Maximum number of bytes in receive buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



6.19.5.20 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last transaction



6.19.5.21 RXD.LIST

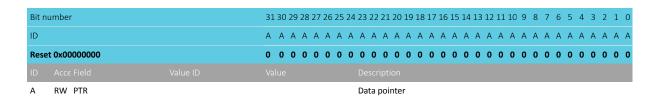
Address offset: 0x540 EasyDMA list type

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АА
Reset 0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field			
A RW LIST			List type
	Disabled	0	Disable EasyDMA list
	ArrayList	1	Use array list

6.19.5.22 TXD.PTR

Address offset: 0x544

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.19.5.23 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer

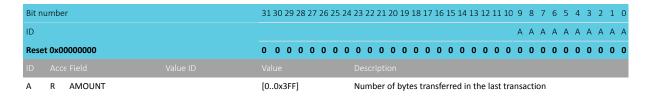
ID			
Rese	et 0x00000000	0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



6.19.5.24 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last transaction



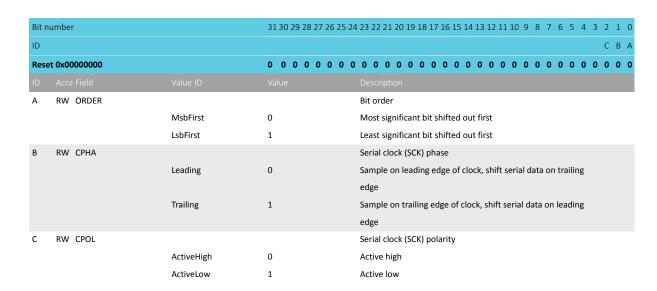
6.19.5.25 TXD.LIST

Address offset: 0x550 EasyDMA list type

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW LIST			List type
		Disabled	0	Disable EasyDMA list
		ArrayList	1	Use array list

6.19.5.26 CONFIG

Address offset: 0x554 Configuration register

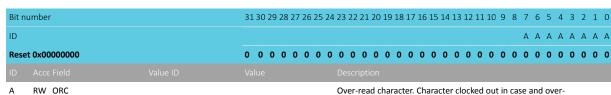


6.19.5.27 ORC

Address offset: 0x5C0

Over-read character. Character clocked out in case and over-read of the TXD buffer.





Over-read character. Character clocked out in case and over read of the TXD buffer.

6.19.6 Electrical specification

6.19.6.1 SPIM master interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIM}	Bit rates for SPIM ²⁴			8 ²⁵	Mbps
t _{SPIM,START}	Time from START task to transmission started	***			μs

6.19.6.2 Serial Peripheral Interface Master (SPIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPIM,CSCK}	SCK period				ns
t _{SPIM,RSCK,LD}	SCK rise time, standard drive ^a			t _{RF,25pF}	
$t_{SPIM,RSCK,HD}$	SCK rise time, high drive ^a			t _{HRF,25pF}	
t _{SPIM,FSCK,LD}	SCK fall time, standard drive ^a			t _{RF,25pF}	
$t_{\text{SPIM,FSCK,HD}}$	SCK fall time, high drive ^a			t _{HRF,25pF}	
t _{SPIM,WHSCK}	SCK high time ^a	(0.5*t _{CSC}	СК		
		- t _{RSCK}			
t _{SPIM,WLSCK}	SCK low time ^a	(0.5*t _{CSC}	ck)		
		- t _{FSCK}			
t _{SPIM,SUMI}	MISO to CLK edge setup time	19			ns
t _{SPIM,HMI}	CLK edge to MISO hold time	18			ns
t _{SPIM,VMO}	CLK edge to MOSI valid			59	ns
t _{SPIM,HMO}	MOSI hold time after CLK edge	20			ns

NORDIC*
SEMICONDUCTOR

High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

The actual maximum data rate depends on the slave's CLK to MISO and MOSI setup and hold timings.

^a At 25pF load, including GPIO pin capacitance, see GPIO spec.

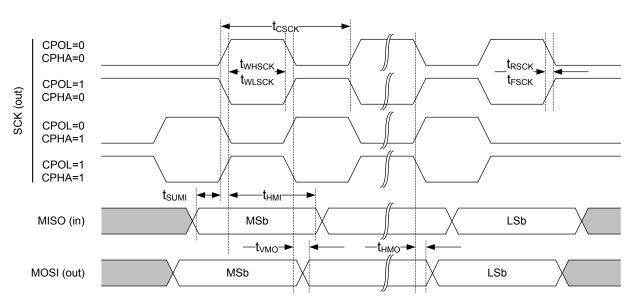


Figure 105: SPIM timing diagram

6.20 SPIS — Serial peripheral interface slave with EasyDMA

SPI slave (SPIS) is implemented with EasyDMA support for ultra-low power serial communication from an external SPI master. EasyDMA, in conjunction with hardware-based semaphore mechanisms, removes all real-time requirements associated with controlling the SPI slave from a low priority CPU execution context.

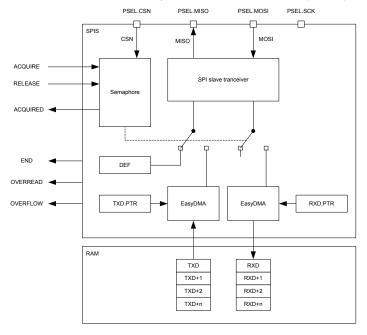


Figure 106: SPI slave

The SPIS supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.



Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Trailing Edge)
SPI_MODE1	0 (Active High)	1 (Leading Edge)
SPI_MODE2	1 (Active Low)	0 (Trailing Edge)
SPI_MODE3	1 (Active Low)	1 (Leading Edge)

Table 86: SPI modes

6.20.1 Shared resources

The SPI slave shares registers and other resources with other peripherals that have the same ID as the SPI slave. Therefore, you must disable all peripherals that have the same ID as the SPI slave before the SPI slave can be configured and used.

Disabling a peripheral that has the same ID as the SPI slave will not reset any of the registers that are shared with the SPI slave. It is important to configure all relevant SPI slave registers explicitly to secure that it operates correctly.

The Instantiation table in Instantiation on page 19 shows which peripherals have the same ID as the SPI slave.

6.20.2 EasyDMA

The SPIS implements EasyDMA for accessing RAM without CPU involvement.

The SPIS peripheral implements the following EasyDMA channels.

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 87: SPIS EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 36.

If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register.

The END event indicates that EasyDMA has finished accessing the buffer in RAM.

6.20.3 SPI slave operation

SPI slave uses two memory pointers, RXD.PTR and TXD.PTR, that point to the RXD buffer (receive buffer) and TXD buffer (transmit buffer) respectively. Since these buffers are located in RAM, which can be accessed by both the SPI slave and the CPU, a hardware based semaphore mechanism is implemented to enable safe sharing.

See SPI transaction when shortcut between END and ACQUIRE is enabled on page 280.

Before the CPU can safely update the RXD.PTR and TXD.PTR pointers, it must first acquire the SPI semaphore. The CPU can acquire the semaphore by triggering the ACQUIRE task and then receiving the ACQUIRED event. When the CPU has updated the RXD.PTR and TXD.PTR pointers the CPU must release the semaphore before the SPI slave will be able to acquire it. The CPU releases the semaphore by triggering the RELEASE task. This is illustrated in SPI transaction when shortcut between END and ACQUIRE is enabled on page 280. Triggering the RELEASE task when the semaphore is not granted to the CPU will have no effect.



The semaphore mechanism does not, at any time, prevent the CPU from performing read or write access to the RXD.PTR register, the TXD.PTR registers, or the RAM that these pointers are pointing to. The semaphore is only telling when these can be updated by the CPU so that safe sharing is achieved.

The semaphore is by default assigned to the CPU after the SPI slave is enabled. No ACQUIRED event will be generated for this initial semaphore handover. An ACQUIRED event will be generated immediately if the ACQUIRE task is triggered while the semaphore is assigned to the CPU.

The SPI slave will try to acquire the semaphore when CSN goes low. If the SPI slave does not manage to acquire the semaphore at this point, the transaction will be ignored. This means that all incoming data on MOSI will be discarded, and the DEF (default) character will be clocked out on the MISO line throughout the whole transaction. This will also be the case even if the semaphore is released by the CPU during the transaction. In case of a race condition where the CPU and the SPI slave try to acquire the semaphore at the same time, as illustrated in lifeline item 2 in SPI transaction when shortcut between END and ACQUIRE is enabled on page 280, the semaphore will be granted to the CPU.

If the SPI slave acquires the semaphore, the transaction will be granted. The incoming data on MOSI will be stored in the RXD buffer and the data in the TXD buffer will be clocked out on MISO.

When a granted transaction is completed and CSN goes high, the SPI slave will automatically release the semaphore and generate the END event.

As long as the semaphore is available, the SPI slave can be granted multiple transactions one after the other. If the CPU is not able to reconfigure the TXD.PTR and RXD.PTR between granted transactions, the same TX data will be clocked out and the RX buffers will be overwritten. To prevent this from happening, the END_ACQUIRE shortcut can be used. With this shortcut enabled, the semaphore will be handed over to the CPU automatically after the granted transaction has completed. This enables the CPU to update the TXPTR and RXPTR between every granted transaction.

If the CPU tries to acquire the semaphore while it is assigned to the SPI slave, an immediate handover will not be granted. However, the semaphore will be handed over to the CPU as soon as the SPI slave has released the semaphore after the granted transaction is completed. If the END_ACQUIRE shortcut is enabled and the CPU has triggered the ACQUIRE task during a granted transaction, only one ACQUIRE request will be served following the END event.

The MAXRX register specifies the maximum number of bytes the SPI slave can receive in one granted transaction. If the SPI slave receives more than MAXRX number of bytes, an OVERFLOW will be indicated in the STATUS register and the incoming bytes will be discarded.

The MAXTX parameter specifies the maximum number of bytes the SPI slave can transmit in one granted transaction. If the SPI slave is forced to transmit more than MAXTX number of bytes, an OVERREAD will be indicated in the STATUS register and the ORC character will be clocked out.

The RXD.AMOUNT and TXD.AMOUNT registers are updated when a granted transaction is completed. The TXD.AMOUNT register indicates how many bytes were read from the TX buffer in the last transaction. This does not include the ORC (over-read) characters. Similarly, the RXD.AMOUNT register indicates how many bytes were written into the RX buffer in the last transaction.

The ENDRX event is generated when the RX buffer has been filled.



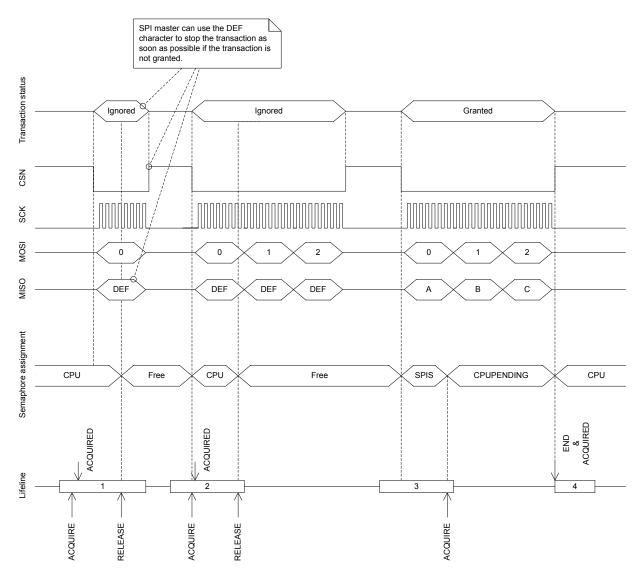


Figure 107: SPI transaction when shortcut between END and ACQUIRE is enabled

6.20.4 Pin configuration

The CSN, SCK, MOSI, and MISO signals associated with the SPI slave are mapped to physical pins according to the configuration specified in the PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively. If the CONNECT field of any of these registers is set to Disconnected, the associated SPI slave signal will not be connected to any physical pins.

The PSEL.CSN, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI slave is enabled, and retained only as long as the device is in System ON mode. See POWER — Power supply on page 52 chapter for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO must only be configured when the SPI slave is disabled.

To secure correct behavior in the SPI slave, the pins used by the SPI slave must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 281 before enabling the SPI slave. This is to secure that the pins used by the SPI slave are driven correctly if the SPI slave itself is temporarily disabled, or if the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the SPI slave is to be recognized by an external SPI master.

The MISO line is set in high impedance as long as the SPI slave is not selected with CSN.



Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI signal	SPI pin	Direction	Output value Comment
CSN	As specified in PSEL.CSN	Input	Not applicable
SCK	As specified in PSEL.SCK	Input	Not applicable
MOSI	As specified in PSEL.MOSI	Input	Not applicable
MISO	As specified in PSEL.MISO	Input	Not applicable Emulates that the SPI slave is not selected.

Table 88: GPIO configuration before enabling peripheral

6.20.5 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40004000	SPIS	SPIS0	SPI slave	

Table 89: Instances

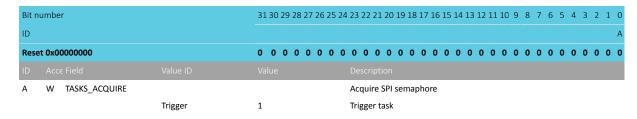
Register	Offset	Description	
TASKS_ACQUIRE	0x024	Acquire SPI semaphore	
TASKS_RELEASE	0x028	Release SPI semaphore, enabling the SPI slave to acquire it	
EVENTS_END	0x104	Granted transaction completed	
EVENTS_ENDRX	0x110	End of RXD buffer reached	
EVENTS_ACQUIRED	0x128	Semaphore acquired	
SHORTS	0x200	Shortcuts between local events and tasks	
INTENSET	0x304	Enable interrupt	
INTENCLR	0x308	Disable interrupt	
SEMSTAT	0x400	Semaphore status register	
STATUS	0x440	Status from last transaction	
ENABLE	0x500	Enable SPI slave	
PSEL.SCK	0x508	Pin select for SCK	
PSEL.MISO	0x50C	Pin select for MISO signal	
PSEL.MOSI	0x510	Pin select for MOSI signal	
PSEL.CSN	0x514	Pin select for CSN signal	
PSELSCK	0x508	Pin select for SCK	Deprecated
PSELMISO	0x50C	Pin select for MISO	Deprecated
PSELMOSI	0x510	Pin select for MOSI	Deprecated
PSELCSN	0x514	Pin select for CSN	Deprecated
RXDPTR	0x534	RXD data pointer	Deprecated
MAXRX	0x538	Maximum number of bytes in receive buffer	Deprecated
AMOUNTRX	0x53C	Number of bytes received in last granted transaction	Deprecated
RXD.PTR	0x534	RXD data pointer	
RXD.MAXCNT	0x538	Maximum number of bytes in receive buffer	
RXD.AMOUNT	0x53C	Number of bytes received in last granted transaction	
RXD.LIST	0x540	EasyDMA list type	
TXDPTR	0x544	TXD data pointer	Deprecated
MAXTX	0x548	Maximum number of bytes in transmit buffer	Deprecated
AMOUNTTX	0x54C	Number of bytes transmitted in last granted transaction	Deprecated
TXD.PTR	0x544	TXD data pointer	
TXD.MAXCNT	0x548	Maximum number of bytes in transmit buffer	
TXD.AMOUNT	0x54C	Number of bytes transmitted in last granted transaction	
TXD.LIST	0x550	EasyDMA list type	
TAD.LIST			

Register	Offset	Description
DEF	0x55C	Default character. Character clocked out in case of an ignored transaction.
ORC	0x5C0	Over-read character

Table 90: Register overview

6.20.5.1 TASKS_ACQUIRE

Address offset: 0x024 Acquire SPI semaphore



6.20.5.2 TASKS_RELEASE

Address offset: 0x028

Release SPI semaphore, enabling the SPI slave to acquire it

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_RELEASE			Release SPI semaphore, enabling the SPI slave to acquire it
		Trigger	1	Trigger task

6.20.5.3 EVENTS_END

Address offset: 0x104

Granted transaction completed

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_END			Granted transaction completed
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.20.5.4 EVENTS ENDRX

Address offset: 0x110

End of RXD buffer reached



Bit number	31 30 29 28 27	27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW EVENTS_ENDRX		End of RXD buffer reached
NotGene	erated 0	Event not generated
Generat	ed 1	Event generated

6.20.5.5 EVENTS_ACQUIRED

Address offset: 0x128 Semaphore acquired

Bit n	umber		31 30	29 28	27 2	6 25	24	23 :	22 2	21 2	0 19	18	17	16 1	l5 1	4 13	12	11 1	0 9	8	7	6	5 4	1 3	2	1 0
ID																										А
Rese	t 0x00000000		0 0	0 0	0 0	0	0	0	0	0 (0	0	0	0	0 (0	0	0 (0	0	0	0	0 (0	0	0 0
ID																										
Α	RW EVENTS_ACQUIRED							Sen	nap	hor	e ac	qui	red													
		NotGenerated	0					Eve	nt i	not	gene	erat	ed													
		Generated	1					Eve	nt g	gene	erate	ed														

6.20.5.6 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW END_ACQUIRE			Shortcut between event END and task ACQUIRE
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.20.5.7 INTENSET

Address offset: 0x304 Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW END			Write '1' to enable interrupt for event END
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW ENDRX			Write '1' to enable interrupt for event ENDRX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW ACQUIRED			Write '1' to enable interrupt for event ACQUIRED



Bit number		31 30 29 28 27 26 25 24	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C B A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
	Set	1	Enable
		=	Litable
	Disabled	0	Read: Disabled

6.20.5.8 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	umber		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				C B A
Res	et 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW END			Write '1' to disable interrupt for event END
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW ENDRX			Write '1' to disable interrupt for event ENDRX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW ACQUIRED			Write '1' to disable interrupt for event ACQUIRED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.20.5.9 SEMSTAT

Address offset: 0x400

Semaphore status register

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A
Rese	et 0x00000001		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	R SEMSTAT			Semaphore status
		Free	0	Semaphore is free
		CPU	1	Semaphore is assigned to CPU
		SPIS	2	Semaphore is assigned to SPI slave
		CPUPending	3	Semaphore is assigned to SPI but a handover to the CPU is
				pending

6.20.5.10 STATUS

Address offset: 0x440

Status from last transaction

Individual bits are cleared by writing a $\ensuremath{\mathtt{1}}$ to the bits that shall be cleared



Bit number		31 30 29 28 27	27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			B A
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW OVERREAD			TX buffer over-read detected, and prevented
	NotPresent	0	Read: error not present
	Present	1	Read: error present
	Clear	1	Write: clear error on writing '1'
B RW OVERFLOW			RX buffer overflow detected, and prevented
	NotPresent	0	Read: error not present
	Present	1	Read: error present
	Clear	1	Write: clear error on writing '1'

6.20.5.11 ENABLE

Address offset: 0x500

Enable SPI slave

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW ENABLE			Enable or disable SPI slave
		Disabled	0	Disable SPI slave
		Enabled	2	Enable SPI slave

6.20.5.12 PSEL.SCK

Address offset: 0x508

Pin select for SCK

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.20.5.13 PSEL.MISO

Address offset: 0x50C

Pin select for MISO signal



Bit nu	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.20.5.14 PSEL.MOSI

Address offset: 0x510

Pin select for MOSI signal

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

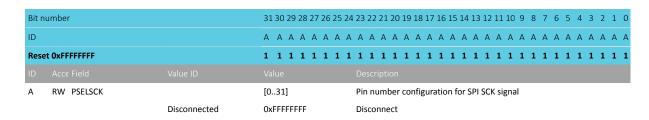
6.20.5.15 PSEL.CSN

Address offset: 0x514 Pin select for CSN signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.20.5.16 PSELSCK (Deprecated)

Address offset: 0x508 Pin select for SCK

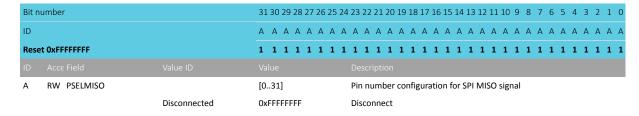


6.20.5.17 PSELMISO (Deprecated)

Address offset: 0x50C



Pin select for MISO



6.20.5.18 PSELMOSI (Deprecated)

Address offset: 0x510
Pin select for MOSI

		Disconnected	0xFFFFFFF	Disconnect
Α	RW PSELMOSI		[031]	Pin number configuration for SPI MOSI signal
ID				Description
Rese	et OxFFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID			A A A A A A	A A A A A A A A A A A A A A A A A A A
Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.20.5.19 PSELCSN (Deprecated)

Address offset: 0x514
Pin select for CSN

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A	
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PSELCSN		[031]	Pin number configuration for SPI CSN signal
		Disconnected	0xFFFFFFF	Disconnect

6.20.5.20 RXDPTR (Deprecated)

Address offset: 0x534 RXD data pointer

Bit n	umber	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11 :	10	9	8	7	6	5	4	3	2 1	. 0
ID		Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A	Δ Α	A
Rese	t 0x00000000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0
ID																																
Α	RW RXDPTR									RX	D c	lata	рс	int	er																	

See the memory chapter for details about which memories are available for EasyDMA.

6.20.5.21 MAXRX (Deprecated)

Address offset: 0x538

Maximum number of bytes in receive buffer



Α	RW MAXRX	[00x3FF	1		N	laxim	num r	numb	er of	byte	s in	rece	ve b	uffer							
ID																					
Res	et 0x00000000	0 0 0	0 0	0 0	0 0	0	0 0	0	0 0	0 0	0	0 (0	0 (0	0	0	0	0 0	0	0 0
ID														,	Δ Δ	Α	Α	Α	ДД	Α	A A
Bit r	umber	31 30 29	28 27 2	26 25	24 23	3 22 2	21 20	19 1	.8 17	16 1	5 14	13 1	2 11	10 9	8 6	7	6	5	4 3	2	1 0

6.20.5.22 AMOUNTRX (Deprecated)

Address offset: 0x53C

Number of bytes received in last granted transaction

Α	R AMOUNTRX	[00x3FF]	Numl	ber of	f byte	es rec	eive	ed in	the	last	grant	ted 1	tran	ısar	ctio	n			
ID																			
Res	et 0x00000000	0 0 0 0 0 0	0 0	0 0	0 (0 0	0	0	0 0	0	0 0	0	0	0	0	0 (0	0	0 (
ID												Α	Α	Α	Α	A A	Δ Α	Α	A A
Bit	number	31 30 29 28 27 26 25 2	4 23 22	212	0 19	18 17	16	15 1	4 13	12	11 10	9	8	7	6	5 4	4 3	2	1 (

6.20.5.23 RXD.PTR

Address offset: 0x534

RXD data pointer

Bit n	umber		31	30	29	28	27 :	26	25 :	24	23	22	21	20	19 :	18 1	7 1	.6 1	5 1	4 13	3 12	11	10	9	8	7	6	5	4	3	2	1 0
ID			Α	Α	Α	Α	Α	Α	Α	A	Α	Α	Α	Α	Α	Α /	Δ,	Α /	۱ ۸	A A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	АА
Rese	t 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0 () (0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID	Acce Field	Value ID	Va	lue							Des	scri	ptio	on																		
Α	RW PTR										RXI	D d	ata	ро	inte	er																

See the memory chapter for details about which memories are available for EasyDMA.

6.20.5.24 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer

^	RW MAXCNT	[00x3FF]	Maximum number of bytes in receive buffer						
ID									
Rese	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0						
ID			A A A A A A A A A A A A A A A A A A A						
Bit n	umber	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0						

6.20.5.25 RXD.AMOUNT

Address offset: 0x53C

Number of bytes received in last granted transaction

Reset 0x000000000 Value Description	
ID A A A A A A A A A	0 0
	А А
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0

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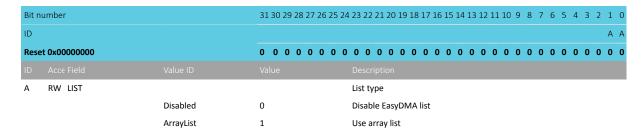


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6.20.5.26 RXD.LIST

Address offset: 0x540

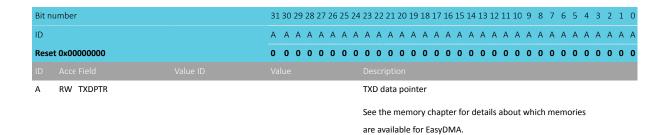
EasyDMA list type



6.20.5.27 TXDPTR (Deprecated)

Address offset: 0x544

TXD data pointer



6.20.5.28 MAXTX (Deprecated)

Address offset: 0x548

Maximum number of bytes in transmit buffer

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	
Rese	t 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID			

6.20.5.29 AMOUNTTX (Deprecated)

Address offset: 0x54C

Number of bytes transmitted in last granted transaction

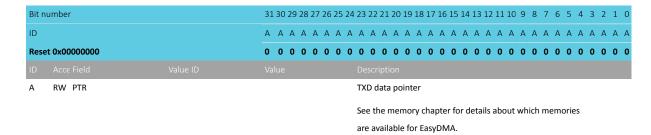
Bit r	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		Value Description
Α	R AMOUNTTX	[00x3FF] Number of bytes transmitted in last granted transaction

6.20.5.30 TXD.PTR

Address offset: 0x544



TXD data pointer



6.20.5.31 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer

A	RW MAXCNT	[00x3FF]	Maximum number of bytes in transmit buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.20.5.32 TXD.AMOUNT

Address offset: 0x54C

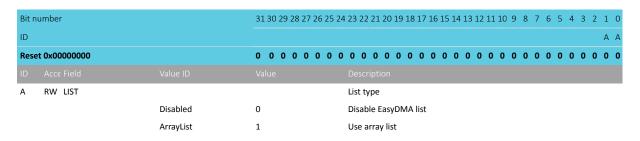
Number of bytes transmitted in last granted transaction

A R AMOUNT	[00x3FF]	Number of bytes transmitted in last granted transaction
ID Acce Field		Description
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.20.5.33 TXD.LIST

Address offset: 0x550

EasyDMA list type



6.20.5.34 CONFIG

Address offset: 0x554 Configuration register



Bit number		31 30 29 28 27	26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID		СВА			
Rese	et 0x00000000		0 0 0 0 0	0 0 (0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW ORDER				Bit order
		MsbFirst	0		Most significant bit shifted out first
		LsbFirst	1		Least significant bit shifted out first
В	RW CPHA				Serial clock (SCK) phase
		Leading	0		Sample on leading edge of clock, shift serial data on trailing
					edge
		Trailing	1		Sample on trailing edge of clock, shift serial data on leading
					edge
С	RW CPOL				Serial clock (SCK) polarity
		ActiveHigh	0		Active high
		ActiveLow	1		Active low

6.20.5.35 DEF

Address offset: 0x55C

Default character. Character clocked out in case of an ignored transaction.

Bit r	number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A
Res	et 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			Description
Α	RW DEF		Default character. Character clocked out in case of an
			ignored transaction.

6.20.5.36 ORC

Address offset: 0x5C0

Over-read character

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field	Value Description
A RW ORC	Over-read character. Character clocked out after an over-
	read of the transmit buffer.

6.20.6 Electrical specification

6.20.6.1 SPIS slave interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIS}	Bit rates for SPIS ²⁶			8 ²⁷	Mbps
t _{SPIS,START}	Time from RELEASE task to receive/transmit (CSN active)		**	**	μs

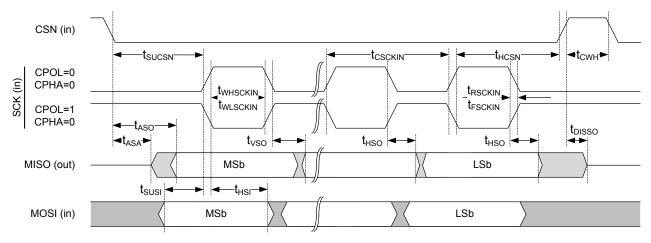
High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

The actual maximum data rate depends on the master's CLK to MISO and MOSI setup and hold timings.



6.20.6.2 Serial Peripheral Interface Slave (SPIS) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPIS,CSCKIN}	SCK input period				ns
t _{SPIS,RFSCKIN}	SCK input rise/fall time			30	ns
t _{SPIS,WHSCKIN}	SCK input high time	30			ns
t _{SPIS,WLSCKIN}	SCK input low time	30			ns
t _{SPIS,SUCSN}	CSN to CLK setup time				ns
t _{SPIS,HCSN}	CLK to CSN hold time	2000			ns
t _{SPIS,ASA}	CSN to MISO driven				ns
t _{SPIS,ASO}	CSN to MISO valid ²⁸			1000	ns
t _{SPIS,DISSO}	CSN to MISO disabled ²⁸			68	ns
t _{SPIS,CWH}	CSN inactive time	300			ns
t _{SPIS,VSO}	CLK edge to MISO valid			19	ns
t _{SPIS,HSO}	MISO hold time after CLK edge	18 ²⁹			ns
t _{SPIS,SUSI}	MOSI to CLK edge setup time	59			ns
t _{SPIS,HSI}	CLK edge to MOSI hold time	20			ns



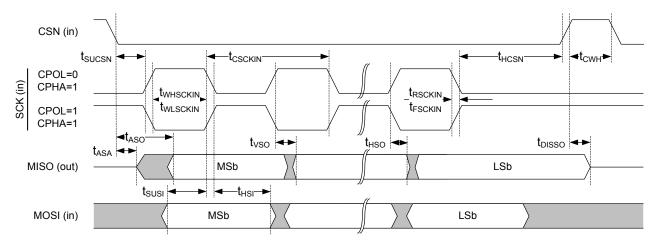


Figure 108: SPIS timing diagram

NORDIC

²⁸ At 25 pF load, including GPIO capacitance, see GPIO electrical specification.

This is to ensure compatibility to SPI masters sampling MISO on the same edge as MOSI is output

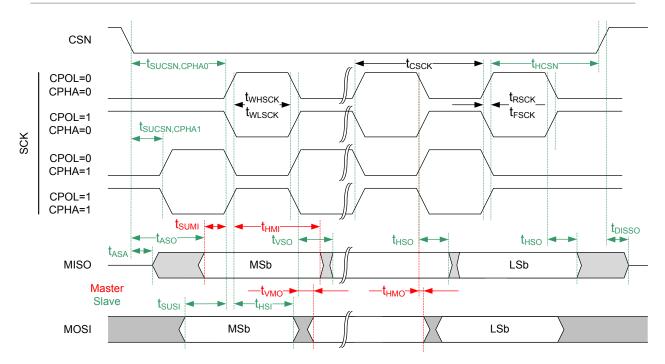


Figure 109: Common SPIM and SPIS timing diagram

6.21 SWI — Software interrupts

A set of interrupts have been reserved for use as software interrupts.

6.21.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40014000	SWI	SWI0	Software interrupt 0	
0x40015000	SWI	SWI1	Software interrupt 1	
0x40016000	SWI	SWI2	Software interrupt 2	
0x40017000	SWI	SWI3	Software interrupt 3	
0x40018000	SWI	SWI4	Software interrupt 4	
0x40019000	SWI	SWI5	Software interrupt 5	

Table 91: Instances

6.22 TEMP — Temperature sensor

The temperature sensor measures die temperature over the temperature range of the device. Linearity compensation can be implemented if required by the application.

Listed here are the main features for TEMP:

- Temperature range is greater than or equal to operating temperature of the device
- Resolution is 0.25 degrees

TEMP is started by triggering the START task.

When the temperature measurement is completed, a DATARDY event will be generated and the result of the measurement can be read from the TEMP register.



To achieve the measurement accuracy stated in the electrical specification, the crystal oscillator must be selected as the HFCLK source, see CLOCK — Clock control on page 65 for more information.

When the temperature measurement is completed, TEMP analog electronics power down to save power.

TEMP only supports one-shot operation, meaning that every TEMP measurement has to be explicitly started using the START task.

6.22.1 Registers

Base address	Peripheral	Instance	Description	Configuration
0x4000C000	TEMP	TEMP	Temperature sensor	

Table 92: Instances

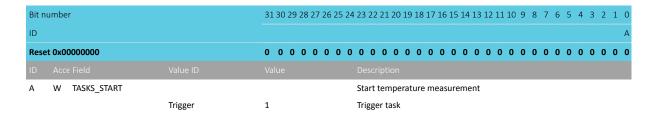
Register	Offset	Description
TASKS_START	0x000	Start temperature measurement
TASKS_STOP	0x004	Stop temperature measurement
EVENTS_DATARDY	0x100	Temperature measurement complete, data ready
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
TEMP	0x508	Temperature in °C (0.25° steps)
A0	0x520	Slope of 1st piece wise linear function
A1	0x524	Slope of 2nd piece wise linear function
A2	0x528	Slope of 3rd piece wise linear function
A3	0x52C	Slope of 4th piece wise linear function
A4	0x530	Slope of 5th piece wise linear function
A5	0x534	Slope of 6th piece wise linear function
В0	0x540	y-intercept of 1st piece wise linear function
B1	0x544	y-intercept of 2nd piece wise linear function
B2	0x548	y-intercept of 3rd piece wise linear function
В3	0x54C	y-intercept of 4th piece wise linear function
B4	0x550	y-intercept of 5th piece wise linear function
B5	0x554	y-intercept of 6th piece wise linear function
то	0x560	End point of 1st piece wise linear function
T1	0x564	End point of 2nd piece wise linear function
T2	0x568	End point of 3rd piece wise linear function
Т3	0x56C	End point of 4th piece wise linear function
T4	0x570	End point of 5th piece wise linear function

Table 93: Register overview

6.22.1.1 TASKS_START

Address offset: 0x000

Start temperature measurement

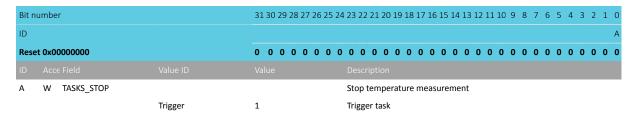




6.22.1.2 TASKS_STOP

Address offset: 0x004

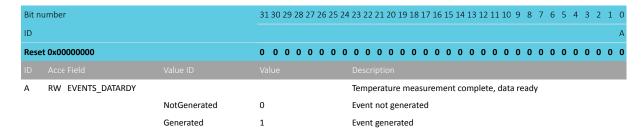
Stop temperature measurement



6.22.1.3 EVENTS DATARDY

Address offset: 0x100

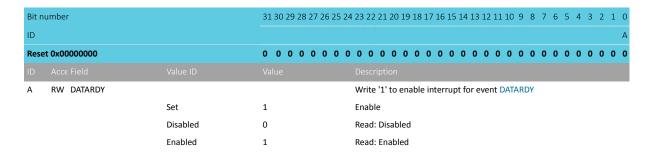
Temperature measurement complete, data ready



6.22.1.4 INTENSET

Address offset: 0x304

Enable interrupt

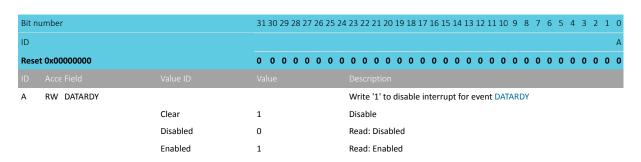


6.22.1.5 INTENCLR

Address offset: 0x308

Disable interrupt





6.22.1.6 TEMP

Address offset: 0x508

Temperature in °C (0.25° steps)

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A A A A A A A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field	
A R TEMP	Temperature in °C (0.25° steps)
	Result of temperature measurement. Die temperature in °C,
	2's complement format, 0.25 °C steps
	Decision point: DATARDY

6.22.1.7 A0

Address offset: 0x520

Slope of 1st piece wise linear function

A RW A0			Slop	e of 1	st pie	ece w	ise I	inea	r fur	ction									
ID Acce Field																			
Reset 0x000003	26	0 0 0 0 0 0	0 0 0	0 0	0 0	0 (0 0	0	0 0	0 (0	1	1	0	0	1 0	0	1	1 0
ID										,	A A	Α	Α	Α	A	4 A	Α	Α	A A
Bit number		31 30 29 28 27 26 25	24 23 2	2 21 2	20 19	18 1	7 16	15 1	14 13	3 12 1	1 10	9	8	7	6	5 4	3	2	1 0

6.22.1.8 A1

Address offset: 0x524

Slope of 2nd piece wise linear function

Α		RW A1	Slope of 2nd piece wise linear function
IC			
R	eset	t 0x00000348	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
IC)		A A A A A A A A A A A A A A A A A A A
Bi	it nu	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.22.1.9 A2

Address offset: 0x528

Slope of 3rd piece wise linear function



Reset 0x0000003AA	0 0 0 1 1 1 0 1 0 1 0 1 0
Reset 0x000003AA 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 1 1 1 0 1 0 1 0 1 0
ID	A A A A A A A A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 15	3 12 11 10 9 8 7 6 5 4 3 2 1 0

6.22.1.10 A3

Address offset: 0x52C

Slope of 4th piece wise linear function

Α	RW A3							Slo	ре	of 4	th p	iece	wis	e lir	near	fun	ctio	n									
ID																											
Rese	et 0x0000040E	0 (0 0	0	0 0	0	0	0	0	0	0 0	0	0	0 (0 0	0	0	0 1	L O	0	0	0	0	0 1	. 1	1	0
ID																		A A	A	Α	Α	Α	Α	A A	A	A	Α
Bit r	umber	313	0 29	9 28 :	27 2	6 25	24	23	22	21 2	20 1	9 18	17	16 1	.5 14	113	12 1	11 1	0 9	8	7	6	5	4 3	2	1	0

6.22.1.11 A4

Address offset: 0x530

Slope of 5th piece wise linear function

Α	RW A4							SI	оре	e of	5th	pied	e w	ise l	ine	ar f	unc	tion										
ID																												
Rese	t 0x000004BD	0 (0 0	0	0	0	0 (0	0	0	0	0 (0	0	0	0	0	0	1	0	0	1	0	1	1	1 1	1 0	1
ID																		Δ	A	Α	Α	Α	Α	Α	Α.	4 4	4 Δ	A
Bit n	umber	313	0 2	9 28	3 27	26 2	25 2	4 23	3 22	21	20	19 1	8 17	16	15	14	13 1	2 1	1 10	9	8	7	6	5	4	3 2	2 1	0

6.22.1.12 A5

Address offset: 0x534

Slope of 6th piece wise linear function

Bit no	umber	31 30 2	9 28 2	7 26 2	5 24	23 2:	2 21 2	20 19	18 1	17 16	5 15	14 13	3 12 1	1 10	9	8	7	6	5 -	4 3	2	1	0
ID														4 A	Α	Α	Α	Α	A	4 A	Α	Α	Α
Rese	t 0x000005A3	0 0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0 0	0) 1	0	1	1	0	1	0 0	0	1	1
ID																							
Α	RW A5					Slop	e of 6	th pi	ece	wise	line	ar fu	nctio	1									_

6.22.1.13 BO

Address offset: 0x540

y-intercept of 1st piece wise linear function

^	RW B0		v-intercept	of 1ct n	ioco w	ico li	noar	func	tion								
ID																	
Rese	et 0x00003FEF	0 0 0 0 0 0	0 0 0 0	0 0	0 0	0 0	1 1	l 1	1 1	l 1	1	1	1 () 1	1	1	1
ID							A A	AA	A A	AA	Α	Α	A A	Α Α	. A	Α	Α
Bit r	umber	31 30 29 28 27 26 25	4 23 22 21 20	19 18 1	17 16 1	15 14	13 1	2 11	10 9	8	7	6	5 4	4 3	2	1	0

4430_161 v1.4 297

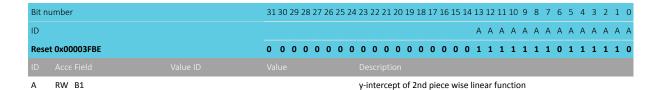


Downloaded from Arrow.com.

6.22.1.14 B1

Address offset: 0x544

y-intercept of 2nd piece wise linear function



6.22.1.15 B2

Address offset: 0x548

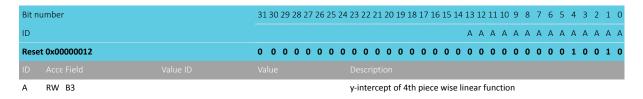
y-intercept of 3rd piece wise linear function

Α	RW B2		y-intercept of 3rd piece wise	linear function	
ID					
Rese	t 0x00003FBE	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0	1 1 1 1 1 1 1 0 1	1111
ID				A A A A A A A A A	A A A A
Bit r	umber	31 30 29 28 27 26 25 2	23 22 21 20 19 18 17 16 15 14	1 13 12 11 10 9 8 7 6 5 4	3 2 1 (

6.22.1.16 B3

Address offset: 0x54C

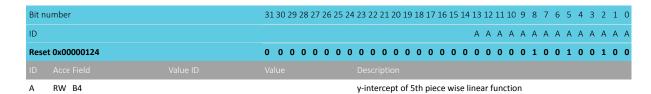
y-intercept of 4th piece wise linear function



6.22.1.17 B4

Address offset: 0x550

y-intercept of 5th piece wise linear function



6.22.1.18 B5

Address offset: 0x554

y-intercept of 6th piece wise linear function



A RW B5			ercept				111										
ID Acce Field																	
Reset 0x0000027C	0 0 0 0 0 0	0 0 0 0	0 0	0 0	0 (0 0	0 0	0	0	0 1	. 0	0	1	1 1	l 1	1	0 0
ID							А	Α	Α	A A	A	Α	Α	A /	A A	Α	A A
Bit number	31 30 29 28 27 26	25 24 23 2	2 21 20	19 18	17 1	.6 15	14 13	3 12	11 :	10 9	8	7	6	5 4	1 3	2	1 0

y-intercept of 6th piece wise linear function

6.22.1.19 TO

Address offset: 0x560

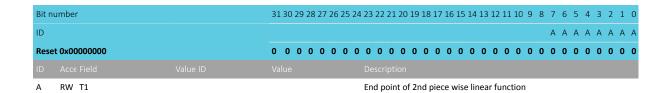
End point of 1st piece wise linear function

Α	RW TO							En	d p	oin	t of	1st p	oiec	e w	ise I	inea	ar fu	ıncti	on								
ID																											
Res	et 0x000000E2	0 0	0	0	0 (0 0	0	0	0	0	0	0 0	0	0	0	0 (0 0	0	0 (0	1	1	1	0	0	0 :	1 0
ID																					Α	Α	Α	Α	Α	A A	ΔА
Bit r	number	31 30	0 29	28 2	27 2	6 25	5 24	23	22	21	20 1	.9 18	3 17	16	15 1	L4 1	3 12	2 11	10 9	8 9	7	6	5	4	3	2 :	1 0

6.22.1.20 T1

Address offset: 0x564

End point of 2nd piece wise linear function



6.22.1.21 T2

Address offset: 0x568

End point of 3rd piece wise linear function

Bit n	umber	31 30	29 2	28 27	26 2	25 24	4 23	22	21 2	0 19	18	17 10	5 15	14	13 1	2 11	10	9 8	3 7	6	5	4	3	2 :	١ ٥
ID																			Α	Α	Α	Α	Α	A A	A A
Rese	t 0x00000019	0 0	0	0 0	0	0 0	0	0	0 0	0	0	0 0	0	0	0 (0 0	0	0 (0 0	0	0	1	1	0 () 1
ID																									
Α	RW T2						En	d po	oint o	of 3r	d pi	ece	wise	lin	ear f	unct	tion								_

6.22.1.22 T3

Address offset: 0x56C

End point of 4th piece wise linear function

Bit number	31 30 29 2	28 27 26 25 24 23 22 2	21 20 19 18 17 :	16 15 14 13 12	11 10 9 8	7 6	5 4	1 3	2 1	0
ID						A A	. A A	A A	А А	Α
Reset 0x0000003C	0 0 0	0 0 0 0 0 0 0	0 0 0 0 0	0 0 0 0 0	0 0 0 0	0 0	1 1	1	1 0	0
ID Acce Field Va	lue ID Value	Descri _l	ption							

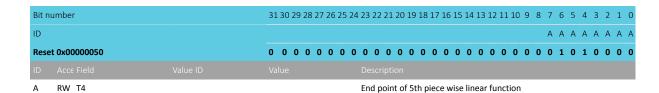
RW T3 End point of 4th piece wise linear function



6.22.1.23 T4

Address offset: 0x570

End point of 5th piece wise linear function



6.22.2 Electrical specification

6.22.2.1 Temperature Sensor Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{TEMP}	Time required for temperature measurement		36		μs
T _{TEMP,RANGE}	Temperature sensor range	-40		85	°C
T _{TEMP,ACC}	Temperature sensor accuracy	-5		5	°C
T _{TEMP,RES}	Temperature sensor resolution		0.25		°C
T _{TEMP,STB}	Sample to sample stability at constant device temperature		+/-0.25		°C
T _{TEMP,OFFST}	Sample offset at 25°C	-2.5		2.5	°C

$6.23 \text{ TWI} - I^2 \text{C}$ compatible two-wire interface

The TWI master is compatible with I²C operating at 100 kHz and 400 kHz.

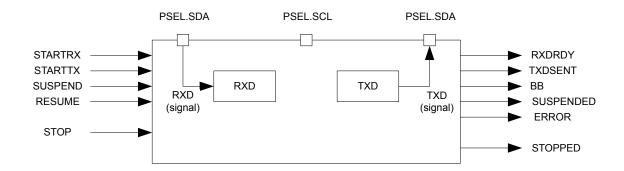


Figure 110: TWI master's main features

6.23.1 Functional description

This TWI master is not compatible with CBUS. The TWI transmitter and receiver are single buffered.

See, TWI master's main features on page 300.

A TWI setup comprising one master and three slaves is illustrated in A typical TWI setup comprising one master and three slaves on page 301. This TWI master is only able to operate as the only master on the TWI bus.



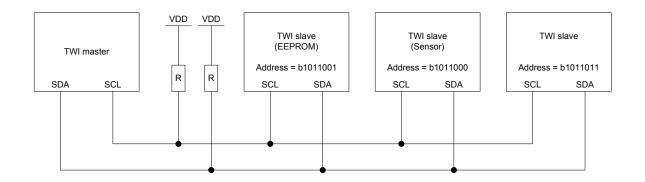


Figure 111: A typical TWI setup comprising one master and three slaves

This TWI master supports clock stretching performed by the slaves. The TWI master is started by triggering the STARTTX or STARTRX tasks, and stopped by triggering the STOP task.

If a NACK is clocked in from the slave, the TWI master will generate an ERROR event.

6.23.2 Master mode pin configuration

The different signals SCL and SDA associated with the TWI master are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

If the CONNECT field of a PSEL.xxx register is set to Disconnected, the associated TWI signal is not connected to any physical pin. The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI master is enabled, and retained only as long as the device is in ON mode. PSEL.SCL and PSEL.SDA must only be configured when the TWI is disabled.

To secure correct signal levels on the pins used by the TWI master when the system is in OFF mode, and when the TWI master is disabled, these pins must be configured in the GPIO peripheral as described in GPIO configuration on page 301.

Only one peripheral can be assigned to drive a particular GPIO pin at a time, failing to do so may result in unpredictable behavior.

TWI master signal	TWI master pin	Direction	Drive strength	Output value
SCL	As specified in PSEL.SCL	Input	SOD1	Not applicable
SDA	As specified in PSEL.SDA	Input	SOD1	Not applicable

Table 94: GPIO configuration

6.23.3 Shared resources

The TWI shares registers and other resources with other peripherals that have the same ID as the TWI.

Therefore, you must disable all peripherals that have the same ID as the TWI before the TWI can be configured and used. Disabling a peripheral that has the same ID as the TWI will not reset any of the registers that are shared with the TWI. It is therefore important to configure all relevant TWI registers explicitly to secure that it operates correctly.

The Instantiation table in Instantiation on page 19 shows which peripherals have the same ID as the TWI.



6.23.4 Master write sequence

A TWI master write sequence is started by triggering the STARTTX task. After the STARTTX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1).

The address must match the address of the slave device that the master wants to write to. The READ/ WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) generated by the slave.

After receiving the ACK bit, the TWI master will clock out the data bytes that are written to the TXD register. Each byte clocked out from the master will be followed by an ACK/NACK bit clocked in from the slave. A TXDSENT event will be generated each time the TWI master has clocked out a TXD byte, and the associated ACK/NACK bit has been clocked in from the slave.

The TWI master transmitter is single buffered, and a second byte can only be written to the TXD register after the previous byte has been clocked out and the ACK/NACK bit clocked in, that is, after the TXDSENT event has been generated.

If the CPU is prevented from writing to TXD when the TWI master is ready to clock out a byte, the TWI master will stretch the clock until the CPU has written a byte to the TXD register.

A typical TWI master write sequence is illustrated in The TWI master writing data to a slave on page 302. Occurrence 3 in the figure illustrates delayed processing of the TXDSENT event associated with TXD byte 1. In this scenario the TWI master will stretch the clock to prevent writing erroneous data to the slave.

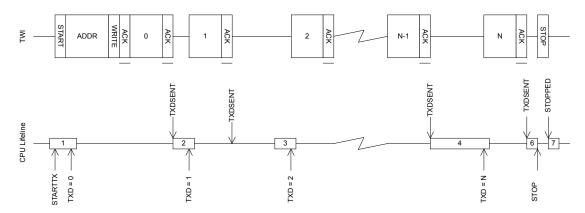


Figure 112: The TWI master writing data to a slave

The TWI master write sequence is stopped when the STOP task is triggered whereupon the TWI master will generate a stop condition on the TWI bus.

6.23.5 Master read sequence

A TWI master read sequence is started by triggering the STARTRX task. After the STARTRX task has been triggered the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE = 0, READ = 1).

The address must match the address of the slave device that the master wants to read from. The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK = 1) generated by the slave.

After having sent the ACK bit the TWI slave will send data to the master using the clock generated by the master.

The TWI master will generate a RXDRDY event every time a new byte is received in the RXD register.

After receiving a byte, the TWI master will delay sending the ACK/NACK bit by stretching the clock until the CPU has extracted the received byte, that is, by reading the RXD register.



The TWI master read sequence is stopped by triggering the STOP task. This task must be triggered before the last byte is extracted from RXD to ensure that the TWI master sends a NACK back to the slave before generating the stop condition.

A typical TWI master read sequence is illustrated in The TWI master reading data from a slave on page 303. Occurrence 3 in this figure illustrates delayed processing of the RXDRDY event associated with RXD byte B. In this scenario the TWI master will stretch the clock to prevent the slave from overwriting the contents of the RXD register.

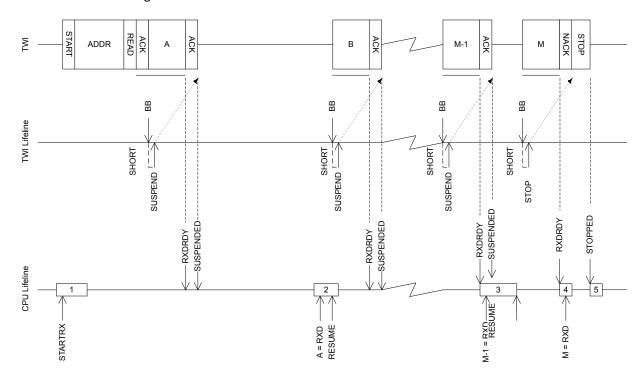


Figure 113: The TWI master reading data from a slave

6.23.6 Master repeated start sequence

A typical repeated start sequence is one in which the TWI master writes one byte to the slave followed by reading M bytes from the slave. Any combination and number of transmit and receive sequences can be combined in this fashion. Only one shortcut to STOP can be enabled at any given time.

The figure below illustrates a repeated start sequence where the TWI master writes one byte, followed by reading M bytes from the slave without performing a stop in-between.



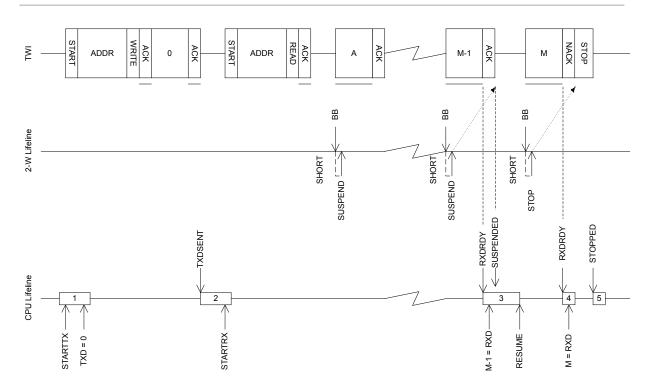


Figure 114: A repeated start sequence, where the TWI master writes one byte, followed by reading M bytes from the slave without performing a stop in-between

To generate a repeated start after a read sequence, a second start task must be triggered instead of the STOP task, that is, STARTRX or STARTTX. This start task must be triggered before the last byte is extracted from RXD to ensure that the TWI master sends a NACK back to the slave before generating the repeated start condition.

6.23.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.23.8 Registers

Base address	Peripheral	Instance	Description	Configuration	
0x40003000	TWI	TWI0	Two-wire interface master		Deprecated

Table 95: Instances

Register	Offset	Description
TASKS_STARTRX	0x000	Start TWI receive sequence
TASKS_STARTTX	0x008	Start TWI transmit sequence
TASKS_STOP	0x014	Stop TWI transaction
TASKS_SUSPEND	0x01C	Suspend TWI transaction
TASKS_RESUME	0x020	Resume TWI transaction
EVENTS_STOPPED	0x104	TWI stopped
EVENTS_RXDREADY	0x108	TWI RXD byte received
EVENTS_TXDSENT	0x11C	TWI TXD byte sent



Register	Offset	Description
EVENTS_ERROR	0x124	TWI error
EVENTS_BB	0x138	TWI byte boundary, generated before each byte that is sent or received
EVENTS_SUSPENDED	0x148	TWI entered the suspended state
SHORTS	0x200	Shortcuts between local events and tasks
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ERRORSRC	0x4C4	Error source
ENABLE	0x500	Enable TWI
PSEL.SCL	0x508	Pin select for SCL
PSEL.SDA	0x50C	Pin select for SDA
RXD	0x518	RXD register
TXD	0x51C	TXD register
FREQUENCY	0x524	TWI frequency. Accuracy depends on the HFCLK source selected.
ADDRESS	0x588	Address used in the TWI transfer

Table 96: Register overview

6.23.8.1 TASKS_STARTRX

Address offset: 0x000

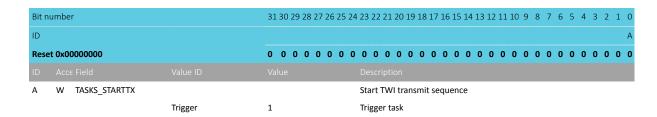
Start TWI receive sequence

Bit n	number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STARTRX			Start TWI receive sequence
		Trigger	1	Trigger task

6.23.8.2 TASKS_STARTTX

Address offset: 0x008

Start TWI transmit sequence



6.23.8.3 TASKS_STOP

Address offset: 0x014 Stop TWI transaction



Bit nu	ımber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Reset	0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				Description
Α	W TASKS_STOP			Stop TWI transaction
		Trigger	1	Trigger task

6.23.8.4 TASKS_SUSPEND

Address offset: 0x01C
Suspend TWI transaction

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_SUSPEND			Suspend TWI transaction
		Trigger	1	Trigger task

6.23.8.5 TASKS_RESUME

Address offset: 0x020 Resume TWI transaction

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_RESUME			Resume TWI transaction
		Trigger	1	Trigger task

6.23.8.6 EVENTS_STOPPED

Address offset: 0x104

TWI stopped

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_STOPPED			TWI stopped
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.23.8.7 EVENTS_RXDREADY

Address offset: 0x108

TWI RXD byte received



Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_RXDREADY			TWI RXD byte received
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.23.8.8 EVENTS_TXDSENT

Address offset: 0x11C TWI TXD byte sent

Bit num	nber		313	30 29	9 28	27 2	6 25	24	23 2	22 2:	1 20	19	18 1	7 16	15	14 1	3 12	11 1	.0 9	8	7	6	5	4	3 2	1	0
ID																											Α
Reset 0	x00000000		0	0 0	0	0 0	0 0	0	0 (0 0	0	0	0 (0	0	0 0	0	0	0	0	0	0	0	0	0 0	0	0
ID A									Des																		
A F	RW EVENTS_TXDSENT								TWI	TXI	D by	te s	ent														
		NotGenerated	0						Ever	nt n	ot g	enei	ate	b													
		Generated	1						Ever	nt ge	ener	rate	t														

6.23.8.9 EVENTS_ERROR

Address offset: 0x124

TWI error

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_ERROR			TWI error
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.23.8.10 EVENTS_BB

Address offset: 0x138

TWI byte boundary, generated before each byte that is sent or received

Bit n	it number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_BB			TWI byte boundary, generated before each byte that is sent
				or received
		NotGenerated	0	Event not generated
		Generated	1	Event generated

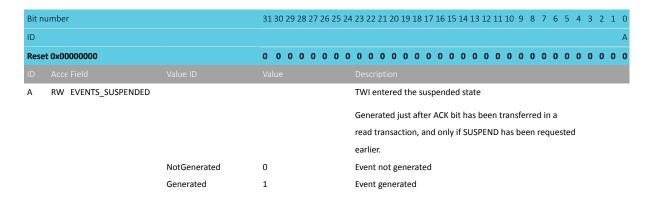
6.23.8.11 EVENTS_SUSPENDED

Address offset: 0x148

TWI entered the suspended state



Generated just after ACK bit has been transferred in a read transaction, and only if SUSPEND has been requested earlier.



6.23.8.12 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27	26 25 2	4 23 22	21 2	0 19	18	17	16	15	14	13	12	11 1	10 9	9 8	8 7	7 (5 5	5 4	4 3	2	1	0
ID																								В	Α
Rese	et 0x00000000		0 0 0 0 0	0 0 0	0 0	0 (0	0	0	0	0	0	0	0	0	0 (0 (0 () (0 () (0	0	0	0
ID																									
Α	RW BB_SUSPEND				Short	cut b	etw	een	eve	ent	ВВ	an	d ta	sk	SUS	PEI	ND								
		Disabled	0		Disab	le sh	ortc	ut																	
		Enabled	1		Enabl	e sho	rtcu	ıt																	
В	RW BB_STOP				Short	cut b	etw	een	eve	ent	ВВ	an	d ta	sk	STC	P									
		Disabled	0		Disab	le sh	ortc	ut																	
		Enabled	1		Enabl	e sho	rtcu	ıt																	

6.23.8.13 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW RXDREADY			Write '1' to enable interrupt for event RXDREADY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW TXDSENT			Write '1' to enable interrupt for event TXDSENT
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ERROR			Write '1' to enable interrupt for event ERROR



Bit n	umber		31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW BB			Write '1' to enable interrupt for event BB
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW SUSPENDED			Write '1' to enable interrupt for event SUSPENDED
				Generated just after ACK bit has been transferred in a
				read transaction, and only if SUSPEND has been requested
				earlier.
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.23.8.14 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID				F E D C B	Α
Res	et 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
Α	RW STOPPED			Write '1' to disable interrupt for event STOPPED	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
В	RW RXDREADY			Write '1' to disable interrupt for event RXDREADY	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
С	RW TXDSENT			Write '1' to disable interrupt for event TXDSENT	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
D	RW ERROR			Write '1' to disable interrupt for event ERROR	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
E	RW BB			Write '1' to disable interrupt for event BB	
		Clear	1	Disable	
		Disabled	0	Read: Disabled	
		Enabled	1	Read: Enabled	
F	RW SUSPENDED			Write '1' to disable interrupt for event SUSPENDED	
				Generated just after ACK bit has been transferred in a	
				read transaction, and only if SUSPEND has been requested	
				earlier.	
		Clear	1	Disable	



Bit number	31 30 29 2	28 27 26 25 24	23 22 21 2	0 19 18 1	7 16 1	5 14 1	13 12 1	1 10	9 8	7	6	5 4	3	2	1 0
ID				F		Е)	С				В	Α
Reset 0x00000000	0 0 0	0 0 0 0	0 0 0 0	0 0 0	0 0 0	0	0 0 0	0	0 0	0	0	0 0	0	0	0 0
ID Acce Field Value ID															
Disabled	0		Read: Disa	bled											
Enabled	1		Read: Enal	bled											

6.23.8.15 ERRORSRC

Address offset: 0x4C4

Error source

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				Description
Α	RW OVERRUN			Overrun error
				A new byte was received before previous byte got read by
				software from the RXD register. (Previous data is lost)
		NotPresent	0	Read: no overrun occured
		Present	1	Read: overrun occured
В	RW ANACK			NACK received after sending the address (write '1' to clear)
		NotPresent	0	Read: error not present
		Present	1	Read: error present
С	RW DNACK			NACK received after sending a data byte (write '1' to clear)
		NotPresent	0	Read: error not present
		Present	1	Read: error present

6.23.8.16 ENABLE

Address offset: 0x500

Enable TWI

Bit	number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Res	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW ENABLE			Enable or disable TWI
		Disabled	0	Disable TWI
		Enabled	5	Enable TWI

6.23.8.17 PSEL.SCL

Address offset: 0x508

Pin select for SCL



Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C	A A A A A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.23.8.18 PSEL.SDA

Address offset: 0x50C
Pin select for SDA

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.23.8.19 RXD

Address offset: 0x518

RXD register

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	Value Description
A R RXD	RXD register

6.23.8.20 TXD

Address offset: 0x51C

TXD register

A RW TXD		TXD res	gister												
ID Acce Field															
Reset 0x00000000	0 0 0 0 0 0	00000	0 0 0	0 0	0	0 0	0 0	0 0	0	0	0 (0	0	0	0 0
ID										Α	Α /	A A	Α	Α .	A A
Bit number	31 30 29 28 27 26	5 25 24 23 22 2	21 20 19 1	.8 17 1	6 15 1	4 13	12 11	10 9	8	7	6 !	5 4	3	2	1 0

6.23.8.21 FREQUENCY

Address offset: 0x524

TWI frequency. Accuracy depends on the HFCLK source selected.

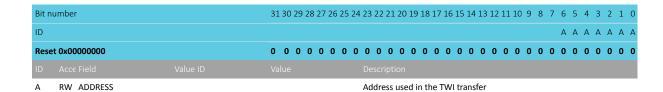


Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Reset 0x04000000		0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field		
A RW FREQUENCY		TWI master clock frequency
	K100	0x01980000 100 kbps
	K250	0x04000000 250 kbps
	K400	0x06680000 400 kbps (actual rate 410.256 kbps)

6.23.8.22 ADDRESS

Address offset: 0x588

Address used in the TWI transfer



6.23.9 Electrical specification

6.23.9.1 TWI interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWI,SCL}	Bit rates for TWI ³⁰	100		400	kbps
t _{TWI,START}	Time from STARTRX/STARTTX task to transmission started		1.5		μs

6.23.9.2 Two Wire Interface (TWI) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{TWI,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWI,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
t _{TWI,HD_STA,100kbps}	TWI master hold time for START and repeated START	10000			ns
	condition, 100 kbps				
t _{TWI,HD_STA,250kbps}	TWI master hold time for START and repeated START	4000			ns
	condition, 250kbps				
t _{TWI,HD_STA,400kbps}	TWI master hold time for START and repeated START	2500			ns
	condition, 400 kbps				
t _{TWI,SU_STO,100kbps}	TWI master setup time from SCL high to STOP condition, 100	5000			ns
	kbps				
t _{TWI,SU_STO,250kbps}	TWI master setup time from SCL high to STOP condition, 250	2000			ns
	kbps				
t _{TWI,SU_STO,400kbps}	TWI master setup time from SCL high to STOP condition, 400	1250			ns
	kbps				
t _{TWI,BUF,100kbps}	TWI master bus free time between STOP and START	5800			ns
	conditions, 100 kbps				

³⁰ High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

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Symbol	Description	Min. Typ.	Max. Units	
t _{TWI,BUF,250kbps}	TWI master bus free time between STOP and START	2700	ns	
	conditions, 250 kbps			
t _{TWI,BUF,400kbps}	TWI master bus free time between STOP and START	2100	ns	
	conditions, 400 kbps			

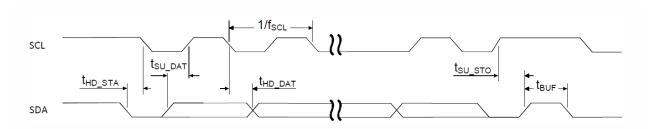


Figure 115: TWI timing diagram, 1 byte transaction

6.24 TIMER — Timer/counter

The TIMER can operate in two modes: timer and counter.

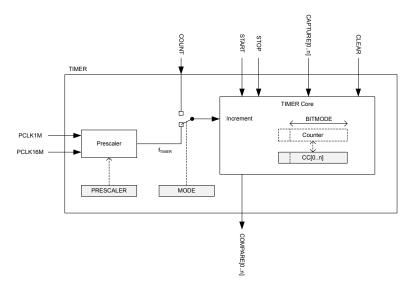


Figure 116: Block schematic for timer/counter

The timer/counter runs on the high-frequency clock source (HFCLK) and includes a four-bit (1/2X) prescaler that can divide the timer input clock from the HFCLK controller. Clock source selection between PCLK16M and PCLK1M is automatic according to TIMER base frequency set by the prescaler. The TIMER base frequency is always given as 16 MHz divided by the prescaler value.

The PPI system allows a TIMER event to trigger a task of any other system peripheral of the device. The PPI system also enables the TIMER task/event features to generate periodic output and PWM signals to any GPIO. The number of input/outputs used at the same time is limited by the number of GPIOTE channels.

The TIMER can operate in two modes, Timer mode and Counter mode. In both modes, the TIMER is started by triggering the START task, and stopped by triggering the STOP task. After the timer is stopped the timer can resume timing/counting by triggering the START task again. When timing/counting is resumed, the timer will continue from the value it had prior to being stopped.



In Timer mode, the TIMER's internal Counter register is incremented by one for every tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 313. The timer frequency is derived from PCLK16M as shown below, using the values specified in the PRESCALER register:

```
f_{\text{TIMER}} = 16 \text{ MHz} / (2^{\text{PRESCALER}})
```

When $f_{TIMER} \ll 1$ MHz the TIMER will use PCLK1M instead of PCLK16M for reduced power consumption.

In counter mode, the TIMER's internal Counter register is incremented by one each time the COUNT task is triggered, that is, the timer frequency and the prescaler are not utilized in counter mode. Similarly, the COUNT task has no effect in Timer mode.

The TIMER's maximum value is configured by changing the bit-width of the timer in the BITMODE on page 318 register.

PRESCALER on page 319 and the BITMODE on page 318 must only be updated when the timer is stopped. If these registers are updated while the TIMER is started then this may result in unpredictable behavior.

When the timer is incremented beyond its maximum value the Counter register will overflow and the TIMER will automatically start over from zero.

The Counter register can be cleared, that is, its internal value set to zero explicitly, by triggering the CLEAR task.

The TIMER implements multiple capture/compare registers.

Independent of prescaler setting the accuracy of the TIMER is equivalent to one tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 313.

6.24.1 Capture

The TIMER implements one capture task for every available capture/compare register.

Every time the CAPTURE[n] task is triggered, the Counter value is copied to the CC[n] register.

6.24.2 Compare

The TIMER implements one COMPARE event for every available capture/compare register.

A COMPARE event is generated when the Counter is incremented and then becomes equal to the value specified in one of the capture compare registers. When the Counter value becomes equal to the value specified in a capture compare register CC[n], the corresponding compare event COMPARE[n] is generated.

BITMODE on page 318 specifies how many bits of the Counter register and the capture/compare register that are used when the comparison is performed. Other bits will be ignored.

6.24.3 Task delays

After the TIMER is started, the CLEAR task, COUNT task and the STOP task will guarantee to take effect within one clock cycle of the PCLK16M.

6.24.4 Task priority

If the START task and the STOP task are triggered at the same time, that is, within the same period of PCLK16M, the STOP task will be prioritized.



6.24.5 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40008000	TIMER	TIMER0	Timer 0	This timer instance has 4 CC registers
				(CC[03])
0x40009000	TIMER	TIMER1	Timer 1	This timer instance has 4 CC registers
				(CC[03])
0x4000A000	TIMER	TIMER2	Timer 2	This timer instance has 4 CC registers
				(CC[03])

Table 97: Instances

Register	Offset	Description	
TASKS_START	0x000	Start Timer	
TASKS_STOP	0x004	Stop Timer	
TASKS_COUNT	0x008	Increment Timer (Counter mode only)	
TASKS_CLEAR	0x00C	Clear time	
TASKS_SHUTDOWN	0x010	Shut down timer	Deprecated
TASKS_CAPTURE[0]	0x040	Capture Timer value to CC[0] register	
TASKS_CAPTURE[1]	0x044	Capture Timer value to CC[1] register	
TASKS_CAPTURE[2]	0x048	Capture Timer value to CC[2] register	
TASKS_CAPTURE[3]	0x04C	Capture Timer value to CC[3] register	
TASKS_CAPTURE[4]	0x050	Capture Timer value to CC[4] register	
TASKS_CAPTURE[5]	0x054	Capture Timer value to CC[5] register	
EVENTS_COMPARE[0]	0x140	Compare event on CC[0] match	
EVENTS_COMPARE[1]	0x144	Compare event on CC[1] match	
EVENTS_COMPARE[2]	0x148	Compare event on CC[2] match	
EVENTS_COMPARE[3]	0x14C	Compare event on CC[3] match	
EVENTS_COMPARE[4]	0x150	Compare event on CC[4] match	
EVENTS_COMPARE[5]	0x154	Compare event on CC[5] match	
SHORTS	0x200	Shortcuts between local events and tasks	
INTENSET	0x304	Enable interrupt	
INTENCLR	0x308	Disable interrupt	
MODE	0x504	Timer mode selection	
BITMODE	0x508	Configure the number of bits used by the TIMER	
PRESCALER	0x510	Timer prescaler register	
CC[0]	0x540	Capture/Compare register 0	
CC[1]	0x544	Capture/Compare register 1	
CC[2]	0x548	Capture/Compare register 2	
CC[3]	0x54C	Capture/Compare register 3	
CC[4]	0x550	Capture/Compare register 4	
CC[5]	0x554	Capture/Compare register 5	

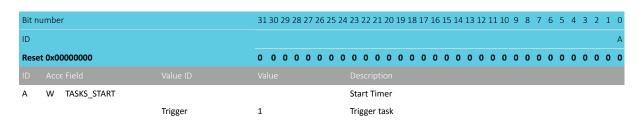
Table 98: Register overview

6.24.5.1 TASKS_START

Address offset: 0x000

Start Timer

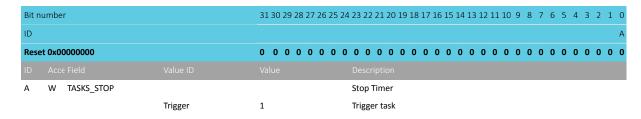




6.24.5.2 TASKS STOP

Address offset: 0x004

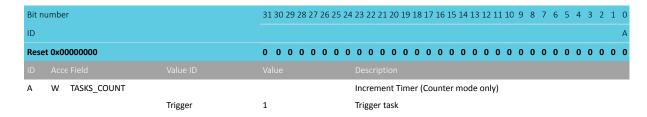
Stop Timer



6.24.5.3 TASKS_COUNT

Address offset: 0x008

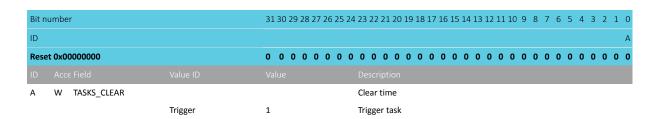
Increment Timer (Counter mode only)



6.24.5.4 TASKS CLEAR

Address offset: 0x00C

Clear time



6.24.5.5 TASKS_SHUTDOWN (Deprecated)

Address offset: 0x010

Shut down timer



Bit n	umber			31 3	0 29	28	27 26	5 25	5 24	23	22	21	20 1	9 1	8 17	16	15	14 :	13 1	2 11	10	9	8	7 (6 5	4	3	2	1 0
ID																													Α
Rese	t 0x000	00000		0 0	0	0	0 0	0	0	0	0	0	0 () (0	0	0	0	0 (0	0	0	0	0 (0 0	0	0	0	0 0
ID																													
Α	W T	ASKS_SHUTDOWN								Sh	ut c	low	n tir	ner													De	pre	cated
			Trigger	1						Tri	gge	r ta	sk																

6.24.5.6 TASKS_CAPTURE[n] (n=0..5)

Address offset: $0x040 + (n \times 0x4)$ Capture Timer value to CC[n] register

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_CAPTURE			Capture Timer value to CC[n] register
		Trigger	1	Trigger task

6.24.5.7 EVENTS_COMPARE[n] (n=0..5)

Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match

Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Res	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_COMPARE			Compare event on CC[n] match
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.24.5.8 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
A-F	RW COMPARE[i]_CLEAR			Shortcut between event COMPARE[i] and task CLEAR
	(i=05)			
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
G-L	RW COMPARE[i]_STOP			Shortcut between event COMPARE[i] and task STOP
	(i=05)			
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut



6.24.5.9 INTENSET

Address offset: 0x304

Enable interrupt

Bit number 31 30 29 28 27 26 25			4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			FEDCBA
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-F RW COMPARE[i] (i=05)			Write '1' to enable interrupt for event COMPARE[i]
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1 Read: Enabled	

6.24.5.10 INTENCLR

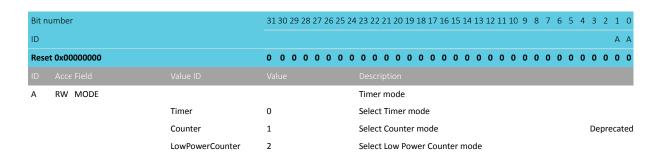
Address offset: 0x308

Disable interrupt

Bit n	umber		31	30	29	28 2	27 2	6 2	5 2	1 2	3 22	2 2:	1 20	0 1	9 18	3 17	16	15	14	13	12	11 1	10 9	8 (7	6	5	4	3	2 :	1 0
ID												F	Ε) C	В	Α														
Rese	t 0x00000000		0	0	0	0	0 () (0	C	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0 (0 0
ID																															
A-F	RW COMPARE[i] (i=05)									٧	Vrit	e '1	' to	di	sab	le ir	nter	rup	ot fo	or e	ven	t C	OME	PAR	E[i]						
		Clear	1							D	isal	ble																			
		Disabled	0							R	ead	l: D	isak	ble	d																
		Enabled	1							R	ead	l: Ei	nab	lec	d																

6.24.5.11 MODE

Address offset: 0x504
Timer mode selection

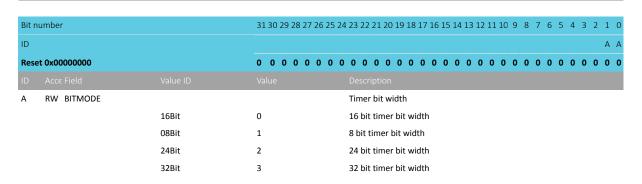


6.24.5.12 BITMODE

Address offset: 0x508

Configure the number of bits used by the TIMER





6.24.5.13 PRESCALER

Address offset: 0x510

Timer prescaler register

Α	RW PRESCALER	[09]	Prescaler value
ID			
Res	et 0x00000004	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			АААА
Bit r	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.24.5.14 CC[n] (n=0..5)

Address offset: $0x540 + (n \times 0x4)$

Capture/Compare register n

			Only the number of bits indicated by BITMODE will be used			
Α	RW CC		Capture/Compare value			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			
ID		A A A A A A A				
Bit r	umber	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0			

 $6.25 \text{ TWIM} - I^2 \text{C}$ compatible two-wire interface master with EasyDMA

by the TIMER.

TWI master with EasyDMA (TWIM) is a two-wire half-duplex master which can communicate with multiple slave devices connected to the same bus

Listed here are the main features for TWIM:

- I²C compatible
- Supported baud rates: 100, 250, 400 kbps
- Support for clock stretching (non I²C compliant)
- EasyDMA

The two-wire interface can communicate with a bi-directional wired-AND bus with two lines (SCL, SDA). The protocol makes it possible to interconnect up to 127 individually addressable devices. TWIM is not compatible with CBUS.



The GPIOs used for each two-wire interface line can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

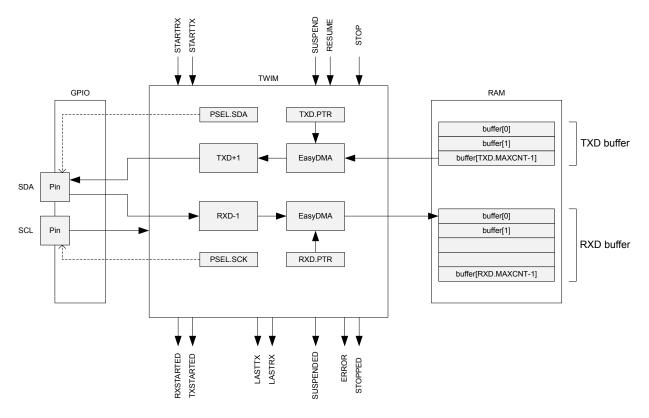


Figure 117: TWI master with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see A typical TWI setup comprising one master and three slaves on page 320. This TWIM is only able to operate as a single master on the TWI bus. Multi-master bus configuration is not supported.

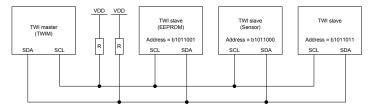


Figure 118: A typical TWI setup comprising one master and three slaves

This TWI master supports clock stretching performed by the slaves. Note that the SCK pulse following a stretched clock cycle may be shorter than specified by the I2C specification.

The TWI master is started by triggering the STARTTX or STARTRX tasks, and stopped by triggering the STOP task. The TWI master will generate a STOPPED event when it has stopped following a STOP task. The TWI master cannot get stopped while it is suspended, so the STOP task has to be issued after the TWI master has been resumed.

After the TWI master is started, the STARTTX task or the STARTRX task should not be triggered again before the TWI master has stopped, i.e. following a LASTRX, LASTTX or STOPPED event.

If a NACK is clocked in from the slave, the TWI master will generate an ERROR event.

6.25.1 EasyDMA

The TWIM implements EasyDMA for accessing RAM without CPU involvement.



The TWIM peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 99: TWIM EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 36.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.

6.25.2 Master write sequence

A TWI master write sequence is started by triggering the STARTTX task. After the STARTTX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1).

The address must match the address of the slave device that the master wants to write to. The READ/ WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) generated by the slave.

After receiving the ACK bit, the TWI master will clock out the data bytes found in the transmit buffer located in RAM at the address specified in the TXD.PTR register. Each byte clocked out from the master will be followed by an ACK/NACK bit clocked in from the slave.

A typical TWI master write sequence is illustrated in TWI master writing data to a slave on page 321. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect; this event can be used to synchronize the software.

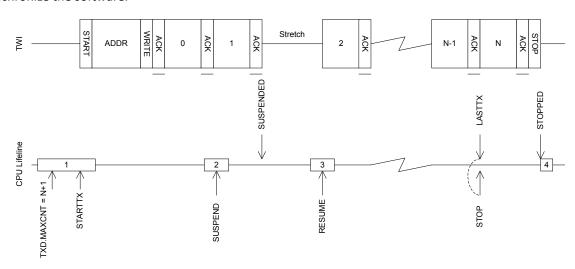


Figure 119: TWI master writing data to a slave

The TWI master will generate a LASTTX event when it starts to transmit the last byte, this is illustrated in TWI master writing data to a slave on page 321

The TWI master is stopped by triggering the STOP task, this task should be triggered during the transmission of the last byte to secure that the TWI will stop as fast as possible after sending the last byte. It is safe to use the shortcut between LASTTX and STOP to accomplish this.



Note that the TWI master does not stop by itself when the whole RAM buffer has been sent, or when an error occurs. The STOP task must be issued, through the use of a local or PPI shortcut, or in software as part of the error handler.

The TWI master cannot get stopped while it is suspended, so the STOP task has to be issued after the TWI master has been resumed.

6.25.3 Master read sequence

A TWI master read sequence is started by triggering the STARTRX task. After the STARTRX task has been triggered the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE = 0, READ = 1). The address must match the address of the slave device that the master wants to read from. The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK = 1) generated by the slave.

After having sent the ACK bit the TWI slave will send data to the master using the clock generated by the master.

Data received will be stored in RAM at the address specified in the RXD.PTR register. The TWI master will generate an ACK after all but the last byte received from the slave. The TWI master will generate a NACK after the last byte received to indicate that the read sequence shall stop.

A typical TWI master read sequence is illustrated in The TWI master reading data from a slave on page 323. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect; this event can be used to synchronize the software.

The TWI master will generate a LASTRX event when it is ready to receive the last byte, this is illustrated in The TWI master reading data from a slave on page 323. If RXD.MAXCNT > 1 the LASTRX event is generated after sending the ACK of the previously received byte. If RXD.MAXCNT = 1 the LASTRX event is generated after receiving the ACK following the address and READ bit.

The TWI master is stopped by triggering the STOP task, this task must be triggered before the NACK bit is supposed to be transmitted. The STOP task can be triggered at any time during the reception of the last byte. It is safe to use the shortcut between LASTRX and STOP to accomplish this.

Note that the TWI master does not stop by itself when the RAM buffer is full, or when an error occurs. The STOP task must be issued, through the use of a local or PPI shortcut, or in software as part of the error handler.

The TWI master cannot get stopped while it is suspended, so the STOP task has to be issued after the TWI master has been resumed.



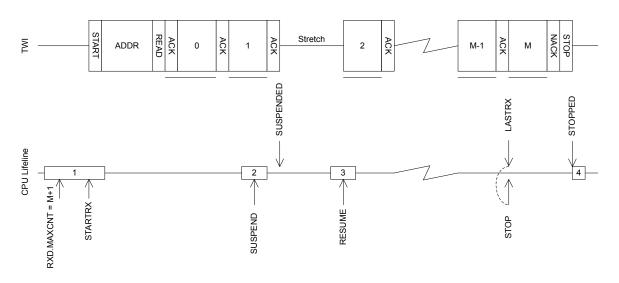


Figure 120: The TWI master reading data from a slave

6.25.4 Master repeated start sequence

A typical repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave. This example uses shortcuts to perform the simplest type of repeated start sequence, i.e. one write followed by one read. The same approach can be used to perform a repeated start sequence where the sequence is read followed by write.

The figure A repeated start sequence, where the TWI master writes two bytes followed by reading 4 bytes from the slave on page 323 illustrates this:

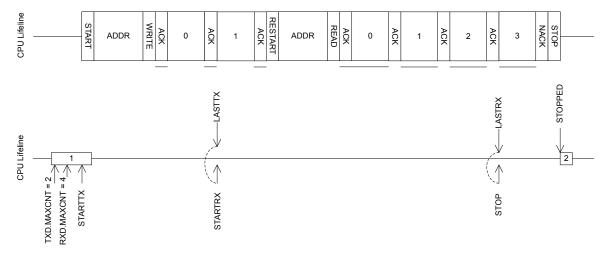


Figure 121: A repeated start sequence, where the TWI master writes two bytes followed by reading 4 bytes from the slave

If a more complex repeated start sequence is needed and the TWI firmware drive is serviced in a low priority interrupt it may be necessary to use the SUSPEND task and SUSPENDED event to guarantee that the correct tasks are generated at the correct time. This is illustrated in A double repeated start sequence using the SUSPEND task to secure safe operation in low priority interrupts on page 324.



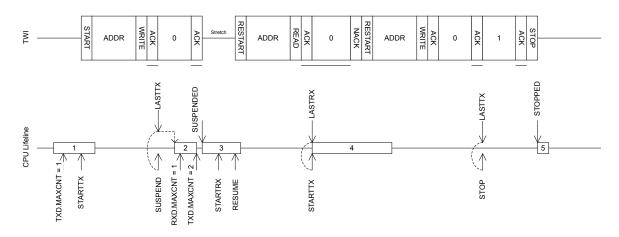


Figure 122: A double repeated start sequence using the SUSPEND task to secure safe operation in low priority interrupts

6.25.5 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.25.6 Master mode pin configuration

The SCL and SDA signals associated with the TWI master are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI master is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL, PSEL.SDA must only be configured when the TWI master is disabled.

To secure correct signal levels on the pins used by the TWI master when the system is in OFF mode, and when the TWI master is disabled, these pins must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 324.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI master signal	TWI master pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 100: GPIO configuration before enabling peripheral

6.25.7 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40003000	TWIM	TWIM0	Two-wire interface master	

Table 101: Instances



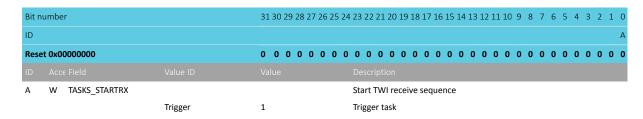
Register	Offset	Description
TASKS_STARTRX	0x000	Start TWI receive sequence
TASKS_STARTTX	0x008	Start TWI transmit sequence
TASKS_STOP	0x014	Stop TWI transaction. Must be issued while the TWI master is not suspended.
TASKS_SUSPEND	0x01C	Suspend TWI transaction
TASKS_RESUME	0x020	Resume TWI transaction
EVENTS_STOPPED	0x104	TWI stopped
EVENTS_ERROR	0x124	TWI error
EVENTS_SUSPENDED	0x148	Last byte has been sent out after the SUSPEND task has been issued, TWI traffic is now
		suspended.
EVENTS_RXSTARTED	0x14C	Receive sequence started
EVENTS_TXSTARTED	0x150	Transmit sequence started
EVENTS_LASTRX	0x15C	Byte boundary, starting to receive the last byte
EVENTS_LASTTX	0x160	Byte boundary, starting to transmit the last byte
SHORTS	0x200	Shortcuts between local events and tasks
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ERRORSRC	0x4C4	Error source
ENABLE	0x500	Enable TWIM
PSEL.SCL	0x508	Pin select for SCL signal
PSEL.SDA	0x50C	Pin select for SDA signal
FREQUENCY	0x524	TWI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534	Data pointer
RXD.MAXCNT	0x538	Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C	Number of bytes transferred in the last transaction
RXD.LIST	0x540	EasyDMA list type
TXD.PTR	0x544	Data pointer
TXD.MAXCNT	0x548	Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C	Number of bytes transferred in the last transaction
TXD.LIST	0x550	EasyDMA list type
ADDRESS	0x588	Address used in the TWI transfer

Table 102: Register overview

6.25.7.1 TASKS_STARTRX

Address offset: 0x000

Start TWI receive sequence

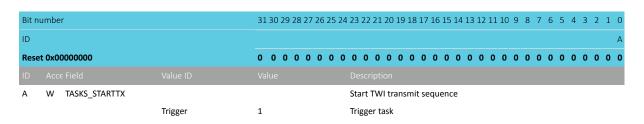


6.25.7.2 TASKS_STARTTX

Address offset: 0x008

Start TWI transmit sequence





6.25.7.3 TASKS_STOP

Address offset: 0x014

Stop TWI transaction. Must be issued while the TWI master is not suspended.

Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A W TASKS_STOP			Stop TWI transaction. Must be issued while the TWI master
			is not suspended.
	Trigger	1	Trigger task

6.25.7.4 TASKS_SUSPEND

Address offset: 0x01C
Suspend TWI transaction

Bit n	uml	ber		31	30	29 :	28 2	7 26	5 25	24	23	22	21	20	19	18 1	.7 1	6 1	5 1	4 13	12	11	10 9	9 8	7	6	5	4	3 2	2 1	. 0
ID																															Α
Rese	et Ox	<00000000		0	0	0	0 (0 0	0	0	0	0	0	0	0	0 (0 (0 0) (0	0	0	0 (0	0	0	0	0	0 (0	0
ID																															
Α	W	/ TASKS_SUSPEND									Su	ıspe	nd	TW	/I tr	ansa	acti	on													
			Trigger	1							Tri	igge	er ta	ask																	

6.25.7.5 TASKS_RESUME

Address offset: 0x020
Resume TWI transaction

Bit n	umber	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0				
ID			A				
Rese	t 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				
ID			Description				
_	MY TACKS DESIDAS	Resume TWI transaction					
А	W TASKS_RESUME		Resume I WI transaction				

6.25.7.6 EVENTS_STOPPED

Address offset: 0x104

TWI stopped



Bit number		31 30 29 28 27 26 25 24	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Va			Description
A RW EVENTS_STOPPED			TWI stopped
N	lotGenerated	0	Event not generated
G	Generated	1	Event generated

6.25.7.7 EVENTS_ERROR

Address offset: 0x124

TWI error

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_ERROR			TWI error
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.25.7.8 EVENTS_SUSPENDED

Address offset: 0x148

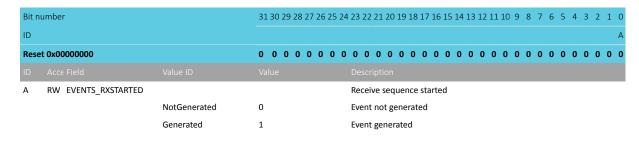
Last byte has been sent out after the SUSPEND task has been issued, TWI traffic is now suspended.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_SUSPENDED			Last byte has been sent out after the SUSPEND task has
				been issued, TWI traffic is now suspended.
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.25.7.9 EVENTS_RXSTARTED

Address offset: 0x14C

Receive sequence started



6.25.7.10 EVENTS_TXSTARTED

Address offset: 0x150

Transmit sequence started



Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_TXSTARTED			Transmit sequence started
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.25.7.11 EVENTS_LASTRX

Address offset: 0x15C

Byte boundary, starting to receive the last byte

Bit n	umber		31	30	29	28 2	27 2	6 25	5 2	4 23	3 22	2 2:	1 20	19	18	17	16	15	14	13	12 1	111	0 9	8	7	6	5	4	3	2	1 0
ID																															Α
Rese	t 0x00000000		0	0	0	0	0 (0 0) (0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 0
ID																															
Α	RW EVENTS_LASTRX									В	yte	bo	unc	dary	, st	arti	ng	to r	ece	eive	the	las	t by	te							
		NotGenerated	0							E۱	ven	nt no	ot g	gen	erat	ed															
		Generated	1							E۱	ven	nt ge	ene	rat	ed																

6.25.7.12 EVENTS_LASTTX

Address offset: 0x160

Byte boundary, starting to transmit the last byte

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_LASTTX			Byte boundary, starting to transmit the last byte
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.25.7.13 SHORTS

Address offset: 0x200

Downloaded from Arrow.com.

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW LASTTX_STARTRX			Shortcut between event LASTTX and task STARTRX
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
В	RW LASTTX_SUSPEND			Shortcut between event LASTTX and task SUSPEND
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
С	RW LASTTX_STOP			Shortcut between event LASTTX and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut





Bit number		31 30 29 28 27	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			FEDCBA
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
D RW LASTRX_STARTTX			Shortcut between event LASTRX and task STARTTX
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut
E RW LASTRX_SUSPEND			Shortcut between event LASTRX and task SUSPEND
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut
F RW LASTRX_STOP			Shortcut between event LASTRX and task STOP
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut

6.25.7.14 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				J I H G F D A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
D	RW ERROR			Enable or disable interrupt for event ERROR
		Disabled	0	Disable
		Enabled	1	Enable
F	F RW SUSPENDED			Enable or disable interrupt for event SUSPENDED
		Disabled	0	Disable
		Enabled	1	Enable
G	RW RXSTARTED			Enable or disable interrupt for event RXSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
Н	RW TXSTARTED			Enable or disable interrupt for event TXSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
I	RW LASTRX			Enable or disable interrupt for event LASTRX
		Disabled	0	Disable
		Enabled	1	Enable
J	RW LASTTX			Enable or disable interrupt for event LASTTX
		Disabled	0	Disable
		Enabled	1	Enable

6.25.7.15 INTENSET

Address offset: 0x304

Enable interrupt



Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				J I H G F D A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ERROR			Write '1' to enable interrupt for event ERROR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW SUSPENDED			Write '1' to enable interrupt for event SUSPENDED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW RXSTARTED			Write '1' to enable interrupt for event RXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW TXSTARTED			Write '1' to enable interrupt for event TXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
ı	RW LASTRX			Write '1' to enable interrupt for event LASTRX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW LASTTX			Write '1' to enable interrupt for event LASTTX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.25.7.16 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			J	II HGF D A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ERROR			Write '1' to disable interrupt for event ERROR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW SUSPENDED			Write '1' to disable interrupt for event SUSPENDED
		Clear	1	Disable
		Disabled	0	Read: Disabled



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		J	I HGF D A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
	Enabled	1	Read: Enabled
G RW RXSTARTED			Write '1' to disable interrupt for event RXSTARTED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
H RW TXSTARTED			Write '1' to disable interrupt for event TXSTARTED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
I RW LASTRX			Write '1' to disable interrupt for event LASTRX
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
J RW LASTTX			Write '1' to disable interrupt for event LASTTX
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.25.7.17 ERRORSRC

Address offset: 0x4C4

Error source

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW OVERRUN			Overrun error
				A new byte was received before previous byte got
				transferred into RXD buffer. (Previous data is lost)
		NotReceived	0	Error did not occur
		Received	1	Error occurred
В	RW ANACK			NACK received after sending the address (write '1' to clear)
		NotReceived	0	Error did not occur
		Received	1	Error occurred
С	RW DNACK			NACK received after sending a data byte (write '1' to clear)
		NotReceived	0	Error did not occur
		Received	1	Error occurred

6.25.7.18 ENABLE

Address offset: 0x500

Enable TWIM



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АААА
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW ENABLE			Enable or disable TWIM
	Disabled	0	Disable TWIM
	Enabled	6	Enable TWIM

6.25.7.19 PSEL.SCL

Address offset: 0x508

Pin select for SCL signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.25.7.20 PSEL.SDA

Address offset: 0x50C

Pin select for SDA signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	ААААА
Rese	t 0xFFFFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.25.7.21 FREQUENCY

Address offset: 0x524

TWI frequency. Accuracy depends on the HFCLK source selected.

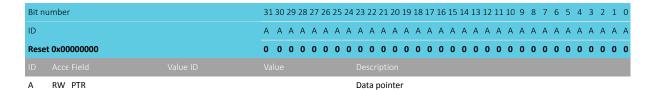
Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A	. A A A A A A A A A A A A A A A A A A A
Res	et 0x04000000		0 0 0 0 0 1 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW FREQUENCY			TWI master clock frequency
		K100	0x01980000	100 kbps
		K250	0x04000000	250 kbps



6.25.7.22 RXD.PTR

Address offset: 0x534

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.25.7.23 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer



6.25.7.24 RXD.AMOUNT

Address offset: 0x53C

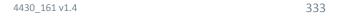
Number of bytes transferred in the last transaction

	of NACK error, includes the NACK'ed byte.
A R AMOUNT	[00x3FF] Number of bytes transferred in the last transaction. In case
ID Acce Field	
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	A A A A A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

6.25.7.25 RXD.LIST

Address offset: 0x540 EasyDMA list type

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		ААА
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW LIST		List type
Disabled	0	Disable EasyDMA list
ArrayList	1	Use array list

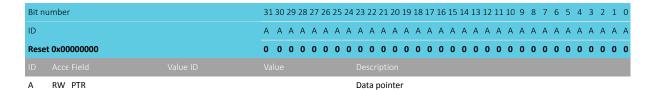




6.25.7.26 TXD.PTR

Address offset: 0x544

Data pointer

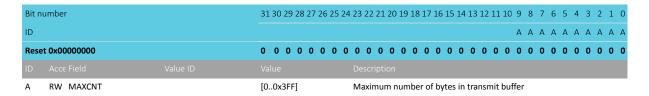


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.25.7.27 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



6.25.7.28 TXD.AMOUNT

Address offset: 0x54C

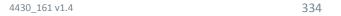
Number of bytes transferred in the last transaction

	of NACK error, includes the NACK'ed byte.
A R AMOUNT	[00x3FF] Number of bytes transferred in the last transaction. In case
ID Acce Field	
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	A A A A A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

6.25.7.29 TXD.LIST

Address offset: 0x550 EasyDMA list type

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		ААА
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW LIST		List type
Disabled	0	Disable EasyDMA list
ArrayList	1	Use array list

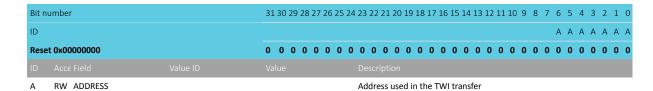




6.25.7.30 ADDRESS

Address offset: 0x588

Address used in the TWI transfer



6.25.8 Electrical specification

6.25.8.1 TWIM interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIM,SCL}	Bit rates for TWIM ³¹	100		400	kbps
t _{TWIM,START}	Time from STARTRX/STARTTX task to transmission started				μs

6.25.8.2 Two Wire Interface Master (TWIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{TWIM,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIM,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
$t_{TWIM,HD_STA,100kbps}$	TWIM master hold time for START and repeated START	9937.5			ns
	condition, 100 kbps				
$t_{TWIM,HD_STA,250kbps}$	TWIM master hold time for START and repeated START	3937.5			ns
	condition, 250kbps				
$t_{\text{TWIM},\text{HD_STA},400\text{kbps}}$	TWIM master hold time for START and repeated START	2437.5			ns
	condition, 400 kbps				
$t_{TWIM,SU_STO,100kbps}$	TWIM master setup time from SCL high to STOP condition,	5000			ns
	100 kbps				
$t_{TWIM,SU_STO,250kbps}$	TWIM master setup time from SCL high to STOP condition,	2000			ns
	250 kbps				
$t_{TWIM,SU_STO,400kbps}$	TWIM master setup time from SCL high to STOP condition,	1250			ns
	400 kbps				
t _{TWIM,BUF,100kbps}	TWIM master bus free time between STOP and START	5800			ns
	conditions, 100 kbps				
t _{TWIM,BUF,250kbps}	TWIM master bus free time between STOP and START	2700			ns
	conditions, 250 kbps				
t _{TWIM,BUF,400kbps}	TWIM master bus free time between STOP and START	2100			ns
	conditions, 400 kbps				

High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

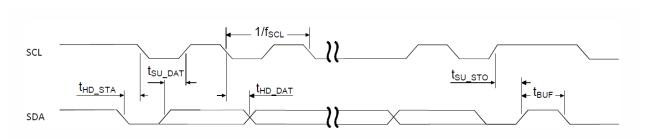


Figure 123: TWIM timing diagram, 1 byte transaction

6.25.9 Pullup resistor

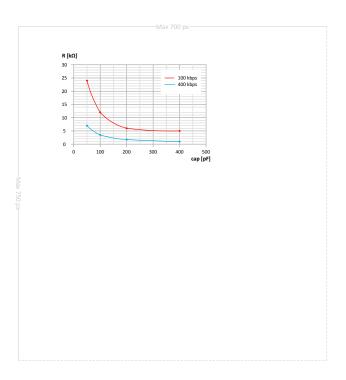


Figure 124: Recommended TWIM pullup value vs. line capacitance

- The I2C specification allows a line capacitance of 400 pF at most.
- The value of internal pullup resistor (R_{PU}) for nRF52810 can be found in GPIO General purpose input/output on page 119.

$6.26 \text{ TWIS} - I^2 \text{C}$ compatible two-wire interface slave with EasyDMA

TWI slave with EasyDMA (TWIS) is compatible with I²C operating at 100 kHz and 400 kHz. The TWI transmitter and receiver implement EasyDMA.

NORDIC

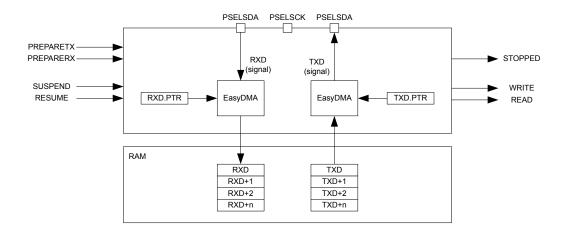


Figure 125: TWI slave with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see A typical TWI setup comprising one master and three slaves on page 337. TWIS is only able to operate with a single master on the TWI bus.



Figure 126: A typical TWI setup comprising one master and three slaves

The TWI slave state machine is illustrated in TWI slave state machine on page 338 and TWI slave state machine symbols on page 338 is explaining the different symbols used in the state machine.



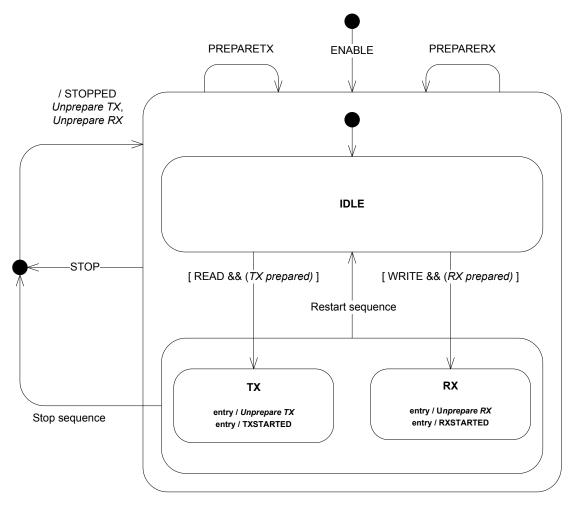


Figure 127: TWI slave state machine

Symbol	Туре	Description
ENABLE	Register	The TWI slave has been enabled via the ENABLE register
PREPARETX	Task	The TASKS_PREPARETX task has been triggered
STOP	Task	The TASKS_STOP task has been triggered
PREPARERX	Task	The TASKS_PREPARERX task has been triggered
STOPPED	Event	The EVENTS_STOPPED event was generated
RXSTARTED	Event	The EVENTS_RXSTARTED event was generated
TXSTARTED	Event	The EVENTS_TXSTARTED event was generated
TX prepared	Internal	Internal flag indicating that a TASKS_PREPARETX task has been triggered. This flag is not visible to the
		user.
RX prepared	Internal	Internal flag indicating that a TASKS_PREPARERX task has been triggered. This flag is not visible to the
		user.
Unprepare TX	Internal	Clears the internal 'TX prepared' flag until next TASKS_PREPARETX task.
Unprepare RX	Internal	Clears the internal 'RX prepared' flag until next TASKS_PREPARERX task.
Stop sequence	TWI protocol	A TWI stop sequence was detected
Restart sequence	TWI protocol	A TWI restart sequence was detected

Table 103: TWI slave state machine symbols

The TWI slave supports clock stretching performed by the master.

The TWI slave operates in a low power mode while waiting for a TWI master to initiate a transfer. As long as the TWI slave is not addressed, it will remain in this low power mode.



To secure correct behaviour of the TWI slave, PSEL.SCL, PSEL.SDA, CONFIG and the ADDRESS[n] registers, must be configured prior to enabling the TWI slave through the ENABLE register. Similarly, changing these settings must be performed while the TWI slave is disabled. Failing to do so may result in unpredictable behaviour.

6.26.1 EasyDMA

The TWIS implements EasyDMA for accessing RAM without CPU involvement.

The TWIS peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 104: TWIS EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 36.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.

6.26.2 TWI slave responding to a read command

Before the TWI slave can respond to a read command the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled the TWI slave will be in its IDLE state where it will consume $I_{\rm IDLE}$.

A read command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the TWI slave.

The TWI slave is able to listen for up to two addresses at the same time. Which addresses to listen for is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the read command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a READ event when it acknowledges the read command.

The TWI slave is only able to detect a read command from the IDLE state.

The TWI slave will set an internal 'TX prepared' flag when the PREPARETX task is triggered.

When the read command is received the TWI slave will enter the TX state if the internal 'TX prepared' flag is set.

If the internal 'TX prepared' flag is not set when the read command is received, the TWI slave will stretch the master's clock until the PREPARETX task is triggered and the internal 'TX prepared' flag is set.

The TWI slave will generate the TXSTARTED event and clear the 'TX prepared' flag ('unprepare TX') when it enters the TX state. In this state the TWI slave will send the data bytes found in the transmit buffer to the master using the master's clock. The TWI slave will consume I_{TX} in this mode.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the TX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the 'TX prepared' flag ('unprepare TX') and go back to the IDLE state when it has stopped.



The transmit buffer is located in RAM at the address specified in the TXD.PTR register. The TWI slave will only be able to send TXD.MAXCNT bytes from the transmit buffer for each transaction. If the TWI master forces the slave to send more than TXD.MAXCNT bytes, the slave will send the byte specified in the ORC register to the master instead. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see TXD.PTR etc., are latched when the TXSTARTED event is generated.

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the 'TX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 342.

Each byte sent from the slave will be followed by an ACK/NACK bit sent from the master. The TWI master will generate a NACK following the last byte that it wants to receive to tell the slave to release the bus so that the TWI master can generate the stop condition. The TXD.AMOUNT register can be queried after a transaction to see how many bytes were sent.

A typical TWI slave read command response is illustrated in The TWI slave responding to a read command on page 340. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.

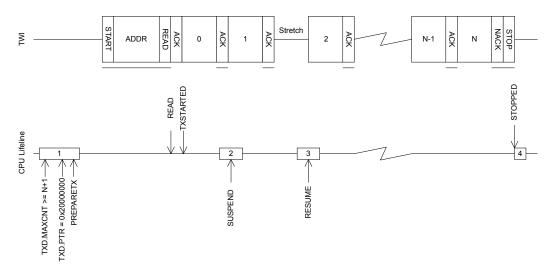


Figure 128: The TWI slave responding to a read command

6.26.3 TWI slave responding to a write command

Before the TWI slave can respond to a write command the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled the TWI slave will be in its IDLE state where it will consume $I_{\rm IDLE}$.

A write command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the slave.

The TWI slave is able to listen for up to two addresses at the same time. Which addresses to listen for is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the write command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a WRITE event if it acknowledges the write command.

The TWI slave is only able to detect a write command from the IDLE state.

The TWI slave will set an internal 'RX prepared' flag when the PREPARERX task is triggered.



When the write command is received the TWI slave will enter the RX state if the internal 'RX prepared' flag is set.

If the internal 'RX prepared' flag is not set when the write command is received, the TWI slave will stretch the master's clock until the PREPARERX task is triggered and the internal 'RX prepared' flag is set.

The TWI slave will generate the RXSTARTED event and clear the internal 'RX prepared' flag ('unprepare RX') when it enters the RX state. In this state the TWI slave will be able to receive the bytes sent by the TWI master. The TWI slave will consume I_{RX} in this mode.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the RX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the internal 'RX prepared' flag ('unprepare RX') and go back to the IDLE state when it has stopped.

The receive buffer is located in RAM at the address specified in the TXD.PTR register. The TWI slave will only be able to receive as many bytes as specified in the RXD.MAXCNT register. If the TWI master tries to send more bytes to the slave than the slave is able to receive, these bytes will be discarded and the bytes will be NACKed by the slave. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see RXD.PTR etc., are latched when the RXSTARTED event is generated.

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the internal 'RX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 342.

The TWI slave will generate an ACK after every byte received from the master. The RXD.AMOUNT register can be queried after a transaction to see how many bytes were received.

A typical TWI slave write command response is illustrated in The TWI slave responding to a write command on page 341. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.

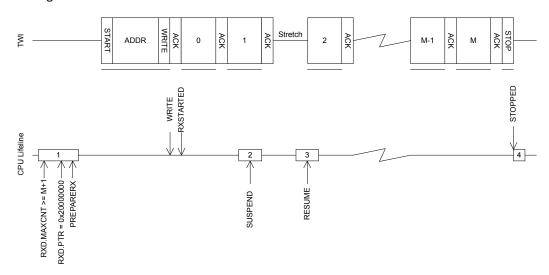


Figure 129: The TWI slave responding to a write command

6.26.4 Master repeated start sequence

An example of a repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave.

This is illustrated in A repeated start sequence, where the TWI master writes two bytes followed by reading four bytes from the slave on page 342.



It is here assumed that the receiver does not know in advance what the master wants to read, and that this information is provided in the first two bytes received in the write part of the repeated start sequence. To guarantee that the CPU is able to process the received data before the TWI slave starts to reply to the read command, the SUSPEND task is triggered via a shortcut from the READ event generated when the read command is received. When the CPU has processed the incoming data and prepared the correct data response, the CPU will resume the transaction by triggering the RESUME task.

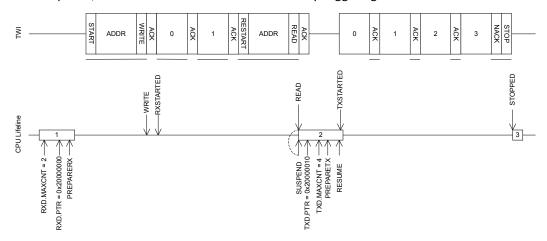


Figure 130: A repeated start sequence, where the TWI master writes two bytes followed by reading four bytes from the slave

6.26.5 Terminating an ongoing TWI transaction

In some situations, e.g. if the external TWI master is not responding correctly, it may be required to terminate an ongoing transaction.

This can be achieved by triggering the STOP task. In this situation a STOPPED event will be generated when the TWI has stopped independent of whether or not a STOP condition has been generated on the TWI bus. The TWI slave will release the bus when it has stopped and go back to its IDLE state.

6.26.6 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.26.7 Slave mode pin configuration

The SCL and SDA signals associated with the TWI slave are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI slave is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL and PSEL.SDA must only be configured when the TWI slave is disabled.

To secure correct signal levels on the pins used by the TWI slave when the system is in OFF mode, and when the TWI slave is disabled, these pins must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 343.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.



TWI slave signal	TWI slave pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 105: GPIO configuration before enabling peripheral

6.26.8 Registers

Base address	Peripheral	Instance	Description	Configuration	
0x40003000	TWIS	TWIS0	Two-wire interface slave		

Table 106: Instances

Register	Offset	Description
TASKS_STOP	0x014	Stop TWI transaction
TASKS_SUSPEND	0x01C	Suspend TWI transaction
TASKS_RESUME	0x020	Resume TWI transaction
TASKS_PREPARERX	0x030	Prepare the TWI slave to respond to a write command
TASKS_PREPARETX	0x034	Prepare the TWI slave to respond to a read command
EVENTS_STOPPED	0x104	TWI stopped
EVENTS_ERROR	0x124	TWI error
EVENTS_RXSTARTED	0x14C	Receive sequence started
EVENTS_TXSTARTED	0x150	Transmit sequence started
EVENTS_WRITE	0x164	Write command received
EVENTS_READ	0x168	Read command received
SHORTS	0x200	Shortcuts between local events and tasks
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ERRORSRC	0x4D0	Error source
MATCH	0x4D4	Status register indicating which address had a match
ENABLE	0x500	Enable TWIS
PSEL.SCL	0x508	Pin select for SCL signal
PSEL.SDA	0x50C	Pin select for SDA signal
RXD.PTR	0x534	RXD Data pointer
RXD.MAXCNT	0x538	Maximum number of bytes in RXD buffer
RXD.AMOUNT	0x53C	Number of bytes transferred in the last RXD transaction
RXD.LIST	0x540	EasyDMA list type
TXD.PTR	0x544	TXD Data pointer
TXD.MAXCNT	0x548	Maximum number of bytes in TXD buffer
TXD.AMOUNT	0x54C	Number of bytes transferred in the last TXD transaction
TXD.LIST	0x550	EasyDMA list type
ADDRESS[0]	0x588	TWI slave address 0
ADDRESS[1]	0x58C	TWI slave address 1
CONFIG	0x594	Configuration register for the address match mechanism
ORC	0x5C0	Over-read character. Character sent out in case of an over-read of the transmit buffer.

Table 107: Register overview

6.26.8.1 TASKS_STOP

Address offset: 0x014 Stop TWI transaction



Bit nu	ımber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Reset	0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				Description
Α	W TASKS_STOP			Stop TWI transaction
		Trigger	1	Trigger task

6.26.8.2 TASKS_SUSPEND

Address offset: 0x01C
Suspend TWI transaction

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_SUSPEND			Suspend TWI transaction
		Trigger	1	Trigger task

6.26.8.3 TASKS_RESUME

Address offset: 0x020 Resume TWI transaction

Bit n	number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				Description
Α	W TASKS_RESUME			Resume TWI transaction
		Trigger	1	Trigger task

6.26.8.4 TASKS_PREPARERX

Address offset: 0x030

Prepare the TWI slave to respond to a write command

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_PREPARERX			Prepare the TWI slave to respond to a write command
		Trigger	1	Trigger task

6.26.8.5 TASKS_PREPARETX

Address offset: 0x034

Prepare the TWI slave to respond to a read command



Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_PREPARETX			Prepare the TWI slave to respond to a read command
		Trigger	1	Trigger task

6.26.8.6 EVENTS_STOPPED

Address offset: 0x104

TWI stopped

Bit n	umber		31 30 29 28 27 26 25 24	$23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_STOPPED			TWI stopped
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.26.8.7 EVENTS_ERROR

Address offset: 0x124

TWI error

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_ERROR			TWI error
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.26.8.8 EVENTS_RXSTARTED

Address offset: 0x14C

Receive sequence started

Bit n	umber		31	30	29	28 2	27 2	6 25	24	23	22	21	20	19 1	8 1	7 1	5 15	5 14	13	12 1	111	.0 9	8	7	6	5	4	3	2	1 0
ID																														Α
Rese	t 0x00000000		0	0	0	0 (0 (0	0	0	0	0	0	0	0 () (0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																														
Α	RW EVENTS_RXSTARTED									Re	cei	ve s	equ	uend	e s	tart	ed													
		NotGenerated	0							Ev	ent	not	ge	ner	ate	b														
		Generated	1							Ev	ent	gen	era	ated																

6.26.8.9 EVENTS_TXSTARTED

Address offset: 0x150

Transmit sequence started



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_TXSTARTED			Transmit sequence started
	NotGenerated	0	Event not generated
	Generated	1	Event generated

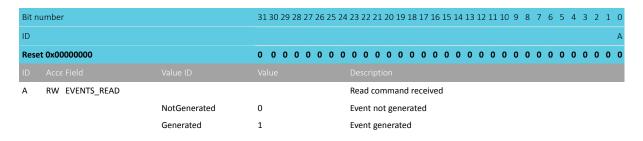
6.26.8.10 EVENTS_WRITE

Address offset: 0x164
Write command received

Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_WRITE			Write command received
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.26.8.11 EVENTS_READ

Address offset: 0x168
Read command received



6.26.8.12 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (
ID				B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW WRITE_SUSPEND			Shortcut between event WRITE and task SUSPEND
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
В	RW READ_SUSPEND			Shortcut between event READ and task SUSPEND
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut



6.26.8.13 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number		31 30 29 28 27 26	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			Н	HG FE B A
Res	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
В	RW ERROR			Enable or disable interrupt for event ERROR
		Disabled	0	Disable
		Enabled	1	Enable
E	RW RXSTARTED			Enable or disable interrupt for event RXSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
F	RW TXSTARTED			Enable or disable interrupt for event TXSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
G	RW WRITE			Enable or disable interrupt for event WRITE
		Disabled	0	Disable
		Enabled	1	Enable
Н	RW READ			Enable or disable interrupt for event READ
		Disabled	0	Disable
		Enabled	1	Enable

6.26.8.14 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	umber		31 30	29 28	27 2	6 25	24 2	23 22	2 21 2	20 19	9 18	17 1	6 1	5 14	13 3	12 1	1 10	9	8 7	7 6	5	4	3 2	1 (
ID					ŀ	H G				F E								В						Α
Rese	et 0x00000000		0 0	0 0	0 (0 0	0	0 0	0	0 0	0	0 0	0	0	0	0 (0 0	0	0 (0	0	0	0 0	0 0
ID								Desc																
Α	RW STOPPED						١	Write	e '1' t	to en	able	inte	rru	pt fo	or ev	ent/	STO	PPE	D					
		Set	1				E	Enab	le															
		Disabled	0				F	Read	l: Dis	abled	d													
		Enabled	1				F	Read	l: Ena	abled	I													
В	RW ERROR						١	Write	e '1' t	to en	able	inte	rru	pt fo	or ev	ent/	ERR	OR						
		Set	1				E	Enab	le															
		Disabled	0				F	Read	l: Dis	abled	d													
		Enabled	1				F	Read	l: Ena	abled	ı													
Ε	RW RXSTARTED						١	Write	e '1' t	to en	able	inte	rru	pt fo	or ev	ent/	RXS	TAR	TED					
		Set	1				E	Enab	le															
		Disabled	0				F	Read	l: Dis	abled	d													
		Enabled	1				F	Read	l: Ena	abled	I													
F	RW TXSTARTED						١	Write	e '1' t	to en	able	inte	rru	pt fo	or ev	ent/	TXS	ΓAR	ΓED					
		Set	1				E	Enab	le															
		Disabled	0				F	Read	l: Dis	abled	d													
		Enabled	1				F	Read	l: Ena	bled														
																								_



D.:																					_		_				
Bit n	umber		31 30	29 28	3 27	26 2	25 2	4 2	13 22 2	21 2	0 19	9 18	3 17	16	15 1	4 13	12	11 1	10 9	8	7	6	5	4	3 2	2 1	. 0
ID						Н	G			F	E								E	3						A	A
Rese	t 0x00000000		0 0	0 0	0	0	0 0	0	0 0	0 (0	0	0	0	0 (0	0	0	0 0	0	0	0	0	0	0 (0	0
ID																											
G	RW WRITE							٧	Vrite '	'1' to	o en	nabl	e in	terr	upt	for e	even	nt W	RITI								
		Set	1					Ε	nable	9																	
		Disabled	0					R	Read:	Disa	ble	d															
		Enabled	1					R	Read:	Enal	bled	t															
Н	RW READ							٧	Vrite '	'1' to	o en	nabl	e in	terr	upt	for e	even	nt RE	AD								
		Set	1					Ε	nable	<u>;</u>																	
		Disabled	0					R	Read:	Disa	ble	d															
		Enabled	1					R	Read:	Enal	bled	t															

6.26.8.15 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		313	30 2	9 28 2	27 26	5 25	24	23	3 22 2	21	20	19 1	.8 1	7 1	5 15	14	13	12	11 1	10 !	9 8	3 7	6	5	4	3 2	1	0
ID						Н	G					F	Е									В						Α	ı
Rese	et 0x00000000		0	0 0	0 0	0 0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0	0 (0	0	0	0	0 0	0	0
ID																													
Α	RW STOPPED								W	rite '	'1'	to c	disal	ble	inte	rru	pt f	or e	ver	nt S1	ГОР	PEC)						
		Clear	1						Di	sable	e																		
		Disabled	0						Re	ead:	Dis	sabl	ed																
		Enabled	1						Re	ead:	En	able	ed																
В	RW ERROR								W	rite '	'1'	to c	disal	ble	inte	rru	pt f	or e	ver	nt El	RRC	R							
		Clear	1						Di	sable	e																		
		Disabled	0						Re	ead:	Dis	sabl	ed																
		Enabled	1						Re	ead:	En	able	ed																
Ε	RW RXSTARTED								W	rite '	'1'	to c	disal	ble	inte	rru	pt f	or e	ver	nt R	XST.	ART	ED						
		Clear	1						Di	sable	e																		
		Disabled	0						Re	ead:	Dis	sabl	ed																
		Enabled	1						Re	ead:	En	able	ed																
F	RW TXSTARTED								W	rite '	'1'	to c	disal	ble	inte	rru	pt f	or e	ver	nt T	KST/	ART	ED						
		Clear	1						Di	sable	e																		
		Disabled	0						Re	ead:	Dis	sabl	ed																
		Enabled	1						Re	ead:	En	able	ed																
G	RW WRITE								W	rite '	'1'	to c	disal	ble	inte	rru	pt f	or e	ver	nt W	/RIT	Έ							
		Clear	1						Di	sable	e																		
		Disabled	0						Re	ead:	Dis	sabl	ed																
		Enabled	1						Re	ead:	En	able	ed																
Н	RW READ								W	rite '	'1'	to c	disal	ble	inte	rru	pt f	or e	ver	nt RI	EAD)							
		Clear	1						Di	sable	e																		
		Disabled	0						Re	ead:	Dis	sabl	ed																
		Enabled	1						Re	ead:	En	able	ed																

6.26.8.16 ERRORSRC

Address offset: 0x4D0

Error source



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field V			Description
A RW OVERFLOW			RX buffer overflow detected, and prevented
N	lotDetected	0	Error did not occur
D	etected	1	Error occurred
B RW DNACK			NACK sent after receiving a data byte
N	lotReceived	0	Error did not occur
R	eceived	1	Error occurred
C RW OVERREAD			TX buffer over-read detected, and prevented
N	lotDetected	0	Error did not occur
D	etected	1	Error occurred

6.26.8.17 MATCH

Address offset: 0x4D4

Status register indicating which address had a match

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3	2 1 0
ID			А
Rese	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0
ID			
Α	R MATCH	[01] Which of the addresses in {ADDRESS} matched the incoming	
		address	

6.26.8.18 ENABLE

Address offset: 0x500

Enable TWIS

Bit number	31 30 29 28 2	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		АААА
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value		Description
A RW ENABLE		Enable or disable TWIS
Disabl	ed 0	Disable TWIS
Enable	ed 9	Enable TWIS

6.26.8.19 PSEL.SCL

Address offset: 0x508

Pin select for SCL signal

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	ААААА
Rese	t 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect



6.26.8.20 PSEL.SDA

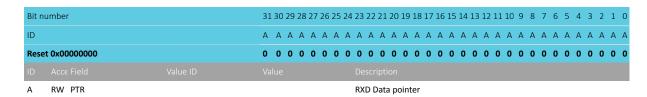
Address offset: 0x50C Pin select for SDA signal

Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.26.8.21 RXD.PTR

Address offset: 0x534

RXD Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.26.8.22 RXD.MAXCNT

Address offset: 0x538

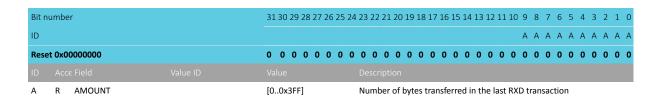
Maximum number of bytes in RXD buffer

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID		A A A A A A A	А А
Rese	t 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID			
Α	RW MAXCNT	[00x3FF] Maximum number of bytes in RXD buffer	

6.26.8.23 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last RXD transaction







6.26.8.24 RXD.LIST

Address offset: 0x540

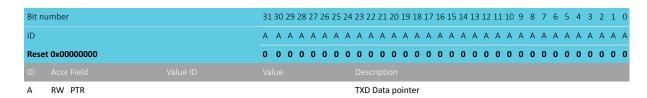
EasyDMA list type

Bit nu	umber		31	30	29 2	28 2	7 2	6 25	5 2	4 23	3 2	2 2	1 2	0 1	9 1	8 1	7 1	6 1	15 1	14 :	13 :	12 1	11	10 9	9 8	8 7	7 6	6 5	5 4	1 3	2	1	0
ID																																А	Α
Rese	t 0x00000000		0	0	0	0 0	0	0	(0	(0 (0) (0 () () (י כ	0	0	0	0	0	0 (0 (0 () (0 (0 (0	0	0	0
Α	RW LIST									Li	st 1	typ	e																				
		Disabled	0							D	isa	ble	Eas	syE	M	A lis	st																
		ArrayList	1							U	se	arr	ay I	ist																			

6.26.8.25 TXD.PTR

Address offset: 0x544

TXD Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.26.8.26 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in TXD buffer

Α	RW MAXCNT	[00x3FF]	Maximum number of bytes in TXD buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A
Bit	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.26.8.27 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last TXD transaction

Reset 0x000000000 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Reset 0x000000000 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	A A A A A A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15	5 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

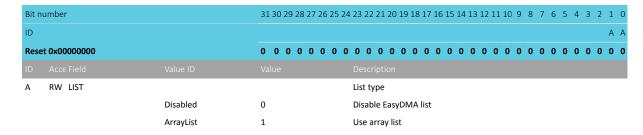




6.26.8.28 TXD.LIST

Address offset: 0x550

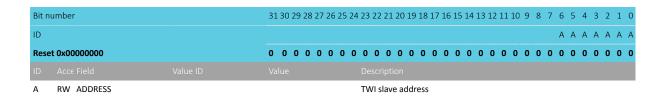
EasyDMA list type



6.26.8.29 ADDRESS[n] (n=0..1)

Address offset: $0x588 + (n \times 0x4)$

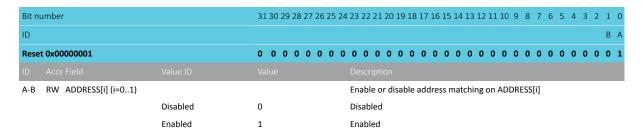
TWI slave address n



6.26.8.30 CONFIG

Address offset: 0x594

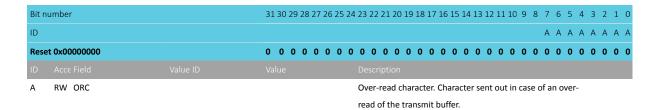
Configuration register for the address match mechanism



6.26.8.31 ORC

Address offset: 0x5C0

Over-read character. Character sent out in case of an over-read of the transmit buffer.





6.26.9 Electrical specification

6.26.9.1 TWIS slave timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIS,SCL}	Bit rates for TWIS ³²	100		400	kbps
t _{TWIS,START}	Time from PREPARERX/PREPARETX task to ready to receive/		1.5		μs
	transmit				
t _{TWIS,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIS,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
$t_{\text{TWIS},\text{HD_STA},\text{100kbps}}$	TWI slave hold time from for START condition (SDA low to	5200			ns
	SCL low), 100 kbps				
$t_{\text{TWIS},\text{HD_STA},400\text{kbps}}$	TWI slave hold time from for START condition (SDA low to	1300			ns
	SCL low), 400 kbps				
$t_{TWIS,SU_STO,100kbps}$	TWI slave setup time from SCL high to STOP condition, 100	5200			ns
	kbps				
$t_{TWIS,SU_STO,400kbps}$	TWI slave setup time from SCL high to STOP condition, 400	1300			ns
	kbps				
t _{TWIS,BUF,100kbps}	TWI slave bus free time between STOP and START		4700		ns
	conditions, 100 kbps				
t _{TWIS,BUF,400kbps}	TWI slave bus free time between STOP and START		1300		ns
	conditions, 400 kbps				

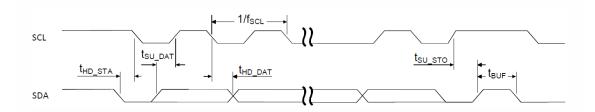


Figure 131: TWIS timing diagram, 1 byte transaction

6.27 UART — Universal asynchronous receiver/transmitter

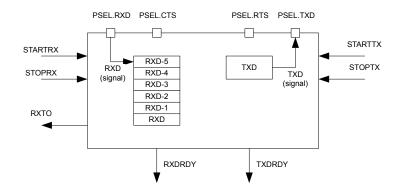


Figure 132: UART configuration

NORDIC SEMICONDUCTOR

High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

6.27.1 Functional description

Listed here are the main features of UART.

The UART implements support for the following features:

- Full-duplex operation
- Automatic flow control
- Parity checking and generation for the 9th data bit

As illustrated in UART configuration on page 353, the UART uses the TXD and RXD registers directly to transmit and receive data. The UART uses one stop bit.

Note: External crystal oscillator must be enabled to obtain sufficient clock accuracy for stable communication. See CLOCK — Clock control on page 65 for more information.

6.27.2 Pin configuration

The different signals RXD, CTS (Clear To Send, active low), RTS (Request To Send, active low), and TXD associated with the UART are mapped to physical pins according to the configuration specified in the PSEL.RXD, PSEL.CTS, PSEL.RTS, and PSEL.TXD registers respectively.

If the CONNECT field of a PSEL.xxx register is set to Disconnected, the associated UART signal will not be connected to any physical pin. The PSEL.RXD, PSEL.CTS, PSEL.RTS, and PSEL.TXD registers and their configurations are only used as long as the UART is enabled, and retained only for the duration the device is in ON mode. PSEL.RXD, PSEL.CTS, PSEL.RTS and PSEL.TXD must only be configured when the UART is disabled.

To secure correct signal levels on the pins by the UART when the system is in OFF mode, the pins must be configured in the GPIO peripheral as described in Pin configuration on page 354.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

UART pin	Direction	Output value
RXD	Input	Not applicable
CTS	Input	Not applicable
RTS	Output	1
TXD	Output	1

Table 108: GPIO configuration

6 27 3 Shared resources

The UART shares registers and other resources with other peripherals that have the same ID as the UART.

Therefore, you must disable all peripherals that have the same ID as the UART before the UART can be configured and used. Disabling a peripheral that has the same ID as the UART will not reset any of the registers that are shared with the UART. It is therefore important to configure all relevant UART registers explicitly to ensure that it operates correctly.

See the Instantiation table in Instantiation on page 19 for details on peripherals and their IDs.

6.27.4 Transmission

A UART transmission sequence is started by triggering the STARTTX task.

Bytes are transmitted by writing to the TXD register. When a byte has been successfully transmitted the UART will generate a TXDRDY event after which a new byte can be written to the TXD register. A UART transmission sequence is stopped immediately by triggering the STOPTX task.



If flow control is enabled a transmission will be automatically suspended when CTS is deactivated and resumed when CTS is activated again, as illustrated in UART transmission on page 355. A byte that is in transmission when CTS is deactivated will be fully transmitted before the transmission is suspended. For more information, see Suspending the UART on page 356.

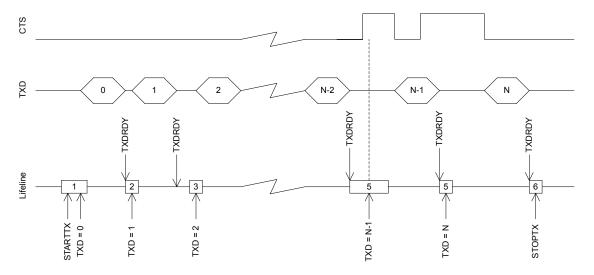


Figure 133: UART transmission

6.27.5 Reception

A UART reception sequence is started by triggering the STARTRX task.

The UART receiver chain implements a FIFO capable of storing six incoming RXD bytes before data is overwritten. Bytes are extracted from this FIFO by reading the RXD register. When a byte is extracted from the FIFO a new byte pending in the FIFO will be moved to the RXD register. The UART will generate an RXDRDY event every time a new byte is moved to the RXD register.

When flow control is enabled, the UART will deactivate the RTS signal when there is only space for four more bytes in the receiver FIFO. The counterpart transmitter is therefore able to send up to four bytes after the RTS signal is deactivated before data is being overwritten. To prevent overwriting data in the FIFO, the counterpart UART transmitter must therefore make sure to stop transmitting data within four bytes after the RTS line is deactivated.

The RTS signal will first be activated again when the FIFO has been emptied, that is, when all bytes in the FIFO have been read by the CPU, see UART reception on page 356.

The RTS signal will also be deactivated when the receiver is stopped through the STOPRX task as illustrated in UART reception on page 356. The UART is able to receive four to five additional bytes if they are sent in succession immediately after the RTS signal has been deactivated. This is possible because the UART is, even after the STOPRX task is triggered, able to receive bytes for an extended period of time dependent on the configured baud rate. The UART will generate a receiver timeout event (RXTO) when this period has elapsed.

To prevent loss of incoming data the RXD register must only be read one time following every RXDRDY event.

To secure that the CPU can detect all incoming RXDRDY events through the RXDRDY event register, the RXDRDY event register must be cleared before the RXD register is read. The reason for this is that the UART is allowed to write a new byte to the RXD register, and therefore can also generate a new event, immediately after the RXD register is read (emptied) by the CPU.



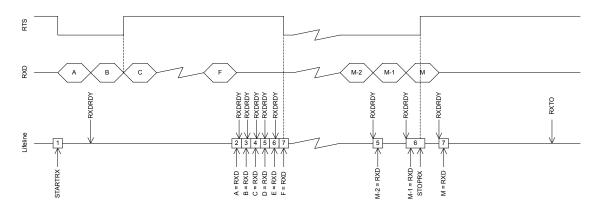


Figure 134: UART reception

As indicated in occurrence 2 in the figure, the RXDRDY event associated with byte B is generated first after byte A has been extracted from RXD.

6.27.6 Suspending the UART

The UART can be suspended by triggering the SUSPEND task.

SUSPEND will affect both the UART receiver and the UART transmitter, i.e. the transmitter will stop transmitting and the receiver will stop receiving. UART transmission and reception can be resumed, after being suspended, by triggering STARTTX and STARTRX respectively.

Following a SUSPEND task, an ongoing TXD byte transmission will be completed before the UART is suspended.

When the SUSPEND task is triggered, the UART receiver will behave in the same way as it does when the STOPRX task is triggered.

6.27.7 Frror conditions

An ERROR event, in the form of a framing error, will be generated if a valid stop bit is not detected in a frame. Another ERROR event, in the form of a break condition, will be generated if the RXD line is held active low for longer than the length of a data frame. Effectively, a framing error is always generated before a break condition occurs.

6.27.8 Using the UART without flow control

If flow control is not enabled, the interface will behave as if the CTS and RTS lines are kept active all the time.

6.27.9 Parity and stop bit configuration

Automatic even parity generation for both transmission and reception can be configured using the register CONFIG on page 365. See the register description for details.

The amount of stop bits can also be configurated through the register CONFIG on page 365.

6.27.10 Registers

Base address	Peripheral	Instance	Description	Configuration	
0x40002000	UART	UART0	Universal asynchronous receiver/		Deprecated
			transmitter		

Table 109: Instances



Register	Offset	Description
TASKS_STARTRX	0x000	Start UART receiver
TASKS_STOPRX	0x004	Stop UART receiver
TASKS_STARTTX	0x008	Start UART transmitter
TASKS_STOPTX	0x00C	Stop UART transmitter
TASKS_SUSPEND	0x01C	Suspend UART
EVENTS_CTS	0x100	CTS is activated (set low). Clear To Send.
EVENTS_NCTS	0x104	CTS is deactivated (set high). Not Clear To Send.
EVENTS_RXDRDY	0x108	Data received in RXD
EVENTS_TXDRDY	0x11C	Data sent from TXD
EVENTS_ERROR	0x124	Error detected
EVENTS_RXTO	0x144	Receiver timeout
SHORTS	0x200	Shortcuts between local events and tasks
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt
ERRORSRC	0x480	Error source
ENABLE	0x500	Enable UART
PSEL.RTS	0x508	Pin select for RTS
PSEL.TXD	0x50C	Pin select for TXD
PSEL.CTS	0x510	Pin select for CTS
PSEL.RXD	0x514	Pin select for RXD
RXD	0x518	RXD register
TXD	0x51C	TXD register
BAUDRATE	0x524	Baud rate. Accuracy depends on the HFCLK source selected.
CONFIG	0x56C	Configuration of parity and hardware flow control

Table 110: Register overview

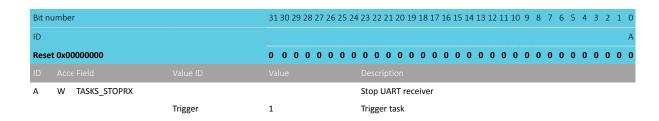
6.27.10.1 TASKS_STARTRX

Address offset: 0x000 Start UART receiver

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_STARTRX			Start UART receiver
		Trigger	1	Trigger task

6.27.10.2 TASKS_STOPRX

Address offset: 0x004 Stop UART receiver





6.27.10.3 TASKS_STARTTX

Address offset: 0x008 Start UART transmitter

Bit n	umb	er			31 30 29 28 27	26 2	25 24	23 :	22	21	20 :	19	18 1	17 :	16 1	.5 :	l4 1	3 1	.2 1	11	.0 9	9	8	7	6	5	4	3	2	1 0
ID																														Α
Rese	t Ox	000	00000		0 0 0 0 0	0	0 0	0	0	0	0	0	0	0	0	0	0 () (0 () (0 (0	0	0	0	0	0	0	0	0 0
ID																														
Α	W	Т	ASKS_STARTTX					Sta	tι	JAR	T tı	ran	smi	itte	r															
				Trigger	1			Trig	ge	r ta	sk																			

6.27.10.4 TASKS_STOPTX

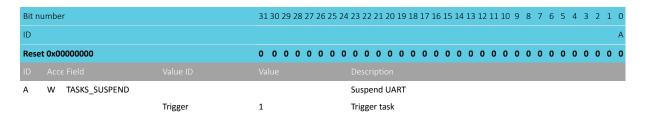
Address offset: 0x00C Stop UART transmitter

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOPTX			Stop UART transmitter
		Trigger	1	Trigger task

6.27.10.5 TASKS_SUSPEND

Address offset: 0x01C

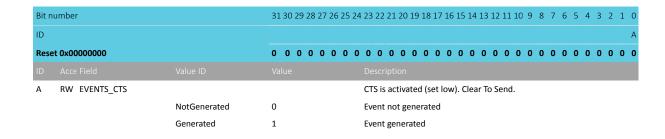
Suspend UART



6.27.10.6 EVENTS_CTS

Address offset: 0x100

CTS is activated (set low). Clear To Send.





6.27.10.7 EVENTS_NCTS

Address offset: 0x104

CTS is deactivated (set high). Not Clear To Send.

Bit number		31 30 29 28 27 26	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_N	NCTS		CTS is deactivated (set high). Not Clear To Send.
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.27.10.8 EVENTS_RXDRDY

Address offset: 0x108

Data received in RXD

Bit n	umber		31	30 2	29 28	8 27	26	25 2	4 2	3 22	21	20 :	19 1	8 17	16	15 1	14 1	3 12	11 1	LO 9	8	7	6	5	4	3 2	2 1	0
ID																												Α
Rese	t 0x00000000		0	0 (0 0	0	0	0 () (0	0	0	0 (0	0	0	0 (0	0	0 0	0	0	0	0	0	0 (0	0
ID																												
Α	RW EVENTS_RXDRDY								D	ata	rec	eive	d in	RXD)													
		NotGenerated	0						E	vent	t no	t ge	nera	ited														
		Generated	1						E	vent	t ge	nera	ited															

6.27.10.9 EVENTS_TXDRDY

Address offset: 0x11C

Data sent from TXD

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_TXDRDY			Data sent from TXD
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.27.10.10 EVENTS_ERROR

Address offset: 0x124

Error detected

Bit number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A RW EVENTS_ERROR		Error detected
NotGenerated	0	Event not generated
Generated	1	Event generated

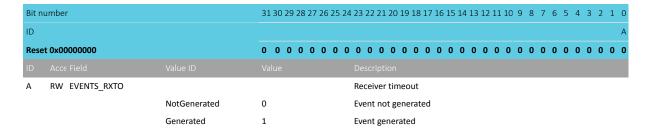




6.27.10.11 EVENTS_RXTO

Address offset: 0x144

Receiver timeout



6.27.10.12 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit r	number		31 30 29 28 27 26	25 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID					ВА	
Rese	et 0x00000000		0 0 0 0 0 0	0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID						ı
Α	RW CTS_STARTRX				Shortcut between event CTS and task STARTRX	
		Disabled	0		Disable shortcut	
		Enabled	1		Enable shortcut	
В	RW NCTS_STOPRX				Shortcut between event NCTS and task STOPRX	
		Disabled	0		Disable shortcut	
		Enabled	1		Enable shortcut	

6.27.10.13 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	mber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Reset	0x0000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CTS			Write '1' to enable interrupt for event CTS
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW NCTS			Write '1' to enable interrupt for event NCTS
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW RXDRDY			Write '1' to enable interrupt for event RXDRDY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW TXDRDY			Write '1' to enable interrupt for event TXDRDY
		Set	1	Enable



Bit number		31 30 29 28 27	7 26 25 2	4 23 22 21 20 19 18 17	' 16 15 14	13 12 11	10 9	8 7	6 5	5 4	3 2	1 0
ID				F			Е	D			C	ВА
Reset 0x00000000		0 0 0 0 0	0 0 0	00000000	0 0 0	0 0 0	0 0	0 0	0 (0	0 0	0 0
ID Acce Field												
	Disabled	0		Read: Disabled								
	Enabled	1		Read: Enabled								
E RW ERROR				Write '1' to enable in	nterrupt fo	or event E	RROR					
	Set	1		Enable								
	Disabled	0		Read: Disabled								
	Enabled	1		Read: Enabled								
F RW RXTO				Write '1' to enable in	nterrupt fo	or event R	хто					
	Set	1		Enable								
	Disabled	0		Read: Disabled								
	Enabled	1		Read: Enabled								

6.27.10.14 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
Α	RW CTS			Write '1' to disable interrupt for event CTS
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW NCTS			Write '1' to disable interrupt for event NCTS
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW RXDRDY			Write '1' to disable interrupt for event RXDRDY
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW TXDRDY			Write '1' to disable interrupt for event TXDRDY
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW ERROR			Write '1' to disable interrupt for event ERROR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW RXTO			Write '1' to disable interrupt for event RXTO
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.27.10.15 ERRORSRC

Address offset: 0x480

Error source



Bit r	number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0					
ID				D C B A					
Reset 0x00000000			0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0						
ID				Description					
Α	RW OVERRUN			Overrun error					
				A start bit is received while the previous data still lies in					
				RXD. (Previous data is lost.)					
		NotPresent	0	Read: error not present					
		Present	1	Read: error present					
В	RW PARITY			Parity error					
				A character with bad parity is received, if HW parity check is					
				enabled.					
		NotPresent	0	Read: error not present					
		Present	1	Read: error present					
С	RW FRAMING			Framing error occurred					
				A valid stop bit is not detected on the serial data input after					
				all bits in a character have been received.					
		NotPresent	0	Read: error not present					
		Present	1	Read: error present					
D	RW BREAK			Break condition					
				The serial data input is '0' for longer than the length of a					
				data frame. (The data frame length is 10 bits without parity					
				bit, and 11 bits with parity bit.).					
		NotPresent	0	Read: error not present					
		Present	1	Read: error present					

6.27.10.16 ENABLE

Address offset: 0x500

Enable UART

Bit number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		АААА
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW ENABLE		Enable or disable UART
Disabled	0	Disable UART
Enabled	4	Enable UART

6.27.10.17 PSEL.RTS

Address offset: 0x508

Pin select for RTS



Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C	A A A A A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.27.10.18 PSEL.TXD

Address offset: 0x50C
Pin select for TXD

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.27.10.19 PSEL.CTS

Address offset: 0x510 Pin select for CTS

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.27.10.20 PSEL.RXD

Address offset: 0x514
Pin select for RXD

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

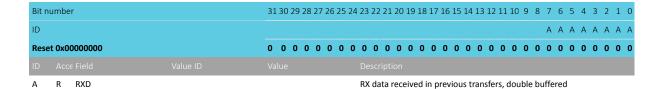




6.27.10.21 RXD

Address offset: 0x518

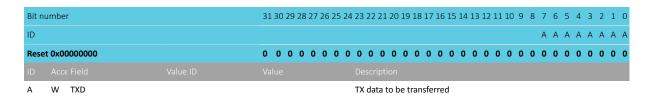
RXD register



6.27.10.22 TXD

Address offset: 0x51C

TXD register



6.27.10.23 BAUDRATE

Address offset: 0x524

Baud rate. Accuracy depends on the HFCLK source selected.

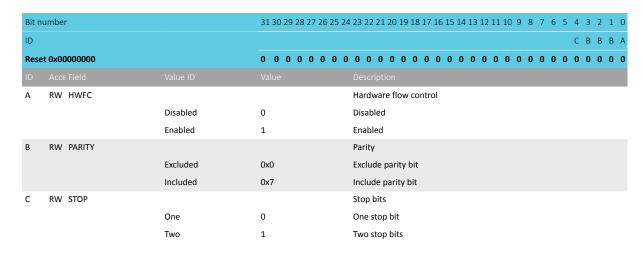
Bit	number		31	30	29	28 2	7 26	25	24	23 2	22 2	1 2	0 19	18	17	16	15	14	13	12 1	11 1	10 9	8	7	6	5	4 3	2	1	0
ID			Α	Α	Α	A	4 А	Α	Α	Α	A A	4 Α	A A	Α	Α	Α	Α	Α	Α	A	A	A A	Α	Α	Α	Α	ДД	Α	Α	Α
Res	et 0x04000000		0	0	0	0 (0 1	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0 0	0	0	0
ID																														
Α	RW BAUDRATE									Bau	d ra	ate																		
		Baud1200	0x0	000)4F0	00				120	0 ba	aud	(act	tua	l ra	te:	120)5)												
		Baud2400	0x(000)9D0	000				240	0 ba	aud	(act	tua	l ra	te:	239	6)												
		Baud4800	0x(001	13B0	000				480	0 ba	aud	(act	tua	l ra	te:	480	8)												
		Baud9600	0x(002	2750	000				960	0 ba	aud	(act	tua	l ra	te:	959	8)												
		Baud14400	0x(003	3B00	000				144	00 l	bau	d (a	ctu	al r	ate	: 14	414	4)											
		Baud19200	0x(004	1EAC	000				192	00 l	bau	d (a	ctu	al r	ate	: 19	208	3)											
		Baud28800	0x0	007	75F0	00				288	00 l	bau	d (a	ctu	al r	ate	: 28	829	9)											
		Baud31250	0x(300	3000	000				312	50 l	bau	d																	
		Baud38400	0x0	009	9D50	000				384	00 l	bau	d (a	ctu	al r	ate	: 38	3462	2)											
		Baud56000	0x(00E	500	00				560	00 l	bau	d (a	ctu	al r	ate	: 55	944	4)											
		Baud57600	0x(00E	BFO	00				576	00 l	bau	d (a	ctu	al r	ate	: 57	762	2)											
		Baud76800	0x(013	3A90	000				768	00 l	bau	d (a	ctu	al r	ate	: 76	923	3)											
		Baud115200	0x(010)7E(000				115	200) ba	ud (act	ual	rat	e: 1	.159	942)										
		Baud230400	0x(03/	AFBC	000				230	400) ba	ud (act	ual	rat	e: 2	318	384)										
		Baud250000	0x(040	0000	000				250	000) ba	ud																	
		Baud460800	0x(075	5F70	00				460	800) ba	ud (act	ual	rat	e: 4	705	588)										
		Baud921600	0x(0EE	BEDO	000				921	600) ba	ud (act	ual	rat	e: 9	41:	176)										
		Baud1M	0x	100	0000	000				1M	ega	baı	ud																	



6.27.10.24 CONFIG

Address offset: 0x56C

Configuration of parity and hardware flow control



6.27.11 Electrical specification

6.27.11.1 UART electrical specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{UART}	Baud rate for UART ³³ .			1000	kbps
t _{UART,CTSH}	CTS high time	1			μs
t _{UART,START}	Time from STARTRX/STARTTX task to transmission started		1		μs

6.28 UARTE — Universal asynchronous receiver/transmitter with EasyDMA

The Universal asynchronous receiver/transmitter with EasyDMA (UARTE) offers fast, full-duplex, asynchronous serial communication with built-in flow control (CTS, RTS) support in hardware at a rate up to 1 Mbps, and EasyDMA data transfer from/to RAM.

Listed here are the main features for UARTE:

- Full-duplex operation
- Automatic hardware flow control
- Optional even parity bit checking and generation
- EasyDMA
- Up to 1 Mbps baudrate
- · Return to IDLE between transactions supported (when using HW flow control)
- One or two stop bit
- Least significant bit (LSB) first

High baud rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.



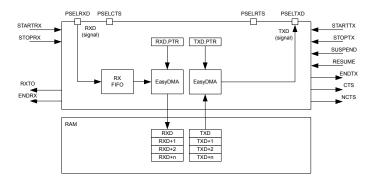


Figure 135: UARTE configuration

The GPIOs used for each UART interface can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

Note: External crystal oscillator must be enabled to obtain sufficient clock accuracy for stable communication. See CLOCK — Clock control on page 65 for more information.

6.28.1 EasyDMA

The UARTE implements EasyDMA for reading and writing to and from the RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 17 for more information about the different memory regions.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The ENDRX/ENDTX event indicates that EasyDMA has finished accessing respectively the RX/TX buffer in RAM.

6.28.2 Transmission

The first step of a DMA transmission is storing bytes in the transmit buffer and configuring EasyDMA. This is achieved by writing the initial address pointer to TXD.PTR, and the number of bytes in the RAM buffer to TXD.MAXCNT. The UARTE transmission is started by triggering the STARTTX task.

After each byte has been sent over the TXD line, a TXDRDY event will be generated.

When all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have been transmitted, the UARTE transmission will end automatically and an ENDTX event will be generated.

A UARTE transmission sequence is stopped by triggering the STOPTX task, a TXSTOPPED event will be generated when the UARTE transmitter has stopped.

If the ENDTX event has not already been generated when the UARTE transmitter has come to a stop, the UARTE will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

If flow control is enabled through the HWFC field in the CONFIG register, a transmission will be automatically suspended when CTS is deactivated and resumed when CTS is activated again, as illustrated in UARTE transmission on page 367. A byte that is in transmission when CTS is deactivated will be fully transmitted before the transmission is suspended.



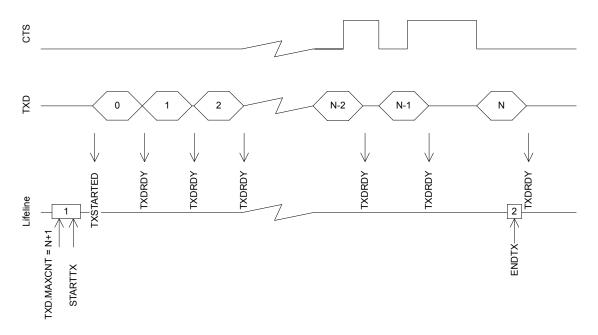


Figure 136: UARTE transmission

The UARTE transmitter will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTTX or after it has been stopped via STOPTX and the TXSTOPPED event has been generated. See POWER — Power supply on page 52 for more information about power modes.

6.28.3 Reception

The UARTE receiver is started by triggering the STARTRX task. The UARTE receiver is using EasyDMA to store incoming data in an RX buffer in RAM.

The RX buffer is located at the address specified in the RXD.PTR register. The RXD.PTR register is double-buffered and it can be updated and prepared for the next STARTRX task immediately after the RXSTARTED event is generated. The size of the RX buffer is specified in the RXD.MAXCNT register and the UARTE will generate an ENDRX event when it has filled up the RX buffer, see UARTE reception on page 368.

For each byte received over the RXD line, an RXDRDY event will be generated. This event is likely to occur before the corresponding data has been transferred to Data RAM.

The RXD.AMOUNT register can be queried following an ENDRX event to see how many new bytes have been transferred to the RX buffer in RAM since the previous ENDRX event.



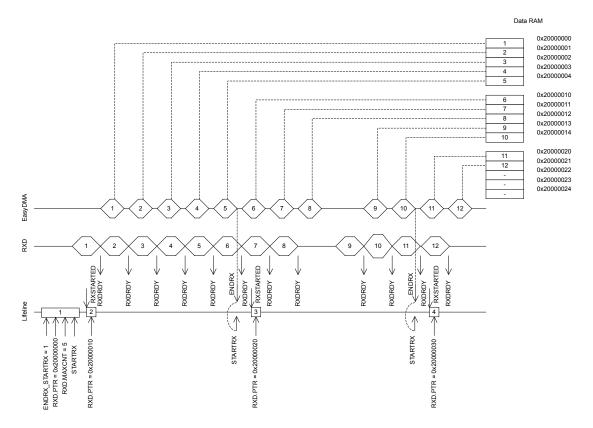


Figure 137: UARTE reception

The UARTE receiver is stopped by triggering the STOPRX task. An RXTO event is generated when the UARTE has stopped. The UARTE will make sure that an impending ENDRX event will be generated before the RXTO event is generated. This means that the UARTE will guarantee that no ENDRX event will be generated after RXTO, unless the UARTE is restarted or a FLUSHRX command is issued after the RXTO event is generated.

Important: If the ENDRX event has not already been generated when the UARTE receiver has come to a stop, which implies that all pending content in the RX FIFO has been moved to the RX buffer, the UARTE will generate the ENDRX event explicitly even though the RX buffer is not full. In this scenario the ENDRX event will be generated before the RXTO event is generated.

To be able to know how many bytes have actually been received into the RX buffer, the CPU can read the RXD.AMOUNT register following the ENDRX event or the RXTO event.

The UARTE is able to receive up to four bytes after the STOPRX task has been triggered as long as these are sent in succession immediately after the RTS signal is deactivated. This is possible because after the RTS is deactivated the UARTE is able to receive bytes for an extended period equal to the time it takes to send 4 bytes on the configured baud rate.

After the RXTO event is generated the internal RX FIFO may still contain data, and to move this data to RAM the FLUSHRX task must be triggered. To make sure that this data does not overwrite data in the RX buffer, the RX buffer should be emptied or the RXD.PTR should be updated before the FLUSHRX task is triggered. To make sure that all data in the RX FIFO is moved to the RX buffer, the RXD.MAXCNT register must be set to RXD.MAXCNT > 4, see UARTE reception with forced stop via STOPRX on page 369. The UARTE will generate the ENDRX event after completing the FLUSHRX task even if the RX FIFO was empty or if the RX buffer does not get filled up. To be able to know how many bytes have actually been received into the RX buffer in this case, the CPU can read the RXD.AMOUNT register following the ENDRX event.



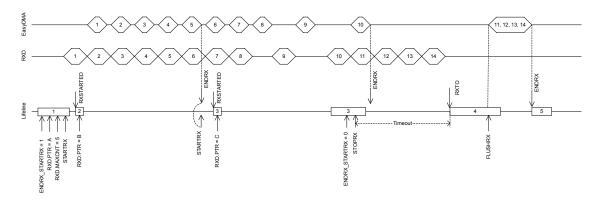


Figure 138: UARTE reception with forced stop via STOPRX

If HW flow control is enabled through the HWFC field in the CONFIG register, the RTS signal will be deactivated when the receiver is stopped via the STOPRX task or when the UARTE is only able to receive four more bytes in its internal RX FIFO.

With flow control disabled, the UARTE will function in the same way as when the flow control is enabled except that the RTS line will not be used. This means that no signal will be generated when the UARTE has reached the point where it is only able to receive four more bytes in its internal RX FIFO. Data received when the internal RX FIFO is filled up, will be lost.

The UARTE receiver will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTRX or after it has been stopped via STOPRX and the RXTO event has been generated. See POWER — Power supply on page 52 for more information about power modes.

6.28.4 Error conditions

An ERROR event, in the form of a framing error, will be generated if a valid stop bit is not detected in a frame. Another ERROR event, in the form of a break condition, will be generated if the RXD line is held active low for longer than the length of a data frame. Effectively, a framing error is always generated before a break condition occurs.

An ERROR event will not stop reception. If the error was a parity error, the received byte will still be transferred into Data RAM, and so will following incoming bytes. If there was a framing error (wrong stop bit), that specific byte will NOT be stored into Data RAM, but following incoming bytes will.

6.28.5 Using the UARTE without flow control

If flow control is not enabled, the interface will behave as if the CTS and RTS lines are kept active all the time.

6.28.6 Parity and stop bit configuration

Automatic even parity generation for both transmission and reception can be configured using the register CONFIG on page 383. See the register description for details.

The amount of stop bits can also be configured through the register CONFIG on page 383.

6.28.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOPTX and STOPRX tasks may not be always needed (the peripheral might already be stopped), but if STOPTX and/or STOPRX is sent, software shall wait until the TXSTOPPED and/or RXTO event is received in response, before disabling the peripheral through the ENABLE register.



6.28.8 Pin configuration

The different signals RXD, CTS (Clear To Send, active low), RTS (Request To Send, active low), and TXD associated with the UARTE are mapped to physical pins according to the configuration specified in the PSEL.RXD, PSEL.RTS, and PSEL.TXD registers respectively.

The PSEL.RXD, PSEL.CTS, PSEL.RTS, and PSEL.TXD registers and their configurations are only used as long as the UARTE is enabled, and retained only for the duration the device is in ON mode. PSEL.RXD, PSEL.RTS, PSEL.RTS and PSEL.TXD must only be configured when the UARTE is disabled.

To secure correct signal levels on the pins by the UARTE when the system is in OFF mode, the pins must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 370.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

UARTE signal	UARTE pin	Direction	Output value
RXD	As specified in PSEL.RXD	Input	Not applicable
CTS	As specified in PSEL.CTS	Input	Not applicable
RTS	As specified in PSEL.RTS	Output	1
TXD	As specified in PSEL.TXD	Output	1

Table 111: GPIO configuration before enabling peripheral

6.28.9 Registers

Base add	ress	Peripheral	Instance	Description	Configuration
0x40002	000	UARTE	UARTE0	Universal asynchronous receiver/	
				transmitter with EasyDMA	

Table 112: Instances

Register	Offset	Description
TASKS_STARTRX	0x000	Start UART receiver
TASKS_STOPRX	0x004	Stop UART receiver
TASKS_STARTTX	0x008	Start UART transmitter
TASKS_STOPTX	0x00C	Stop UART transmitter
TASKS_FLUSHRX	0x02C	Flush RX FIFO into RX buffer
EVENTS_CTS	0x100	CTS is activated (set low). Clear To Send.
EVENTS_NCTS	0x104	CTS is deactivated (set high). Not Clear To Send.
EVENTS_RXDRDY	0x108	Data received in RXD (but potentially not yet transferred to Data RAM)
EVENTS_ENDRX	0x110	Receive buffer is filled up
EVENTS_TXDRDY	0x11C	Data sent from TXD
EVENTS_ENDTX	0x120	Last TX byte transmitted
EVENTS_ERROR	0x124	Error detected
EVENTS_RXTO	0x144	Receiver timeout
EVENTS_RXSTARTED	0x14C	UART receiver has started
EVENTS_TXSTARTED	0x150	UART transmitter has started
EVENTS_TXSTOPPED	0x158	Transmitter stopped
SHORTS	0x200	Shortcuts between local events and tasks
INTEN	0x300	Enable or disable interrupt
INTENSET	0x304	Enable interrupt
INTENCLR	0x308	Disable interrupt

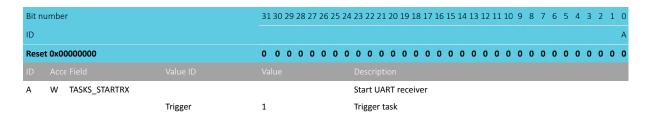


Register	Offset	Description
ERRORSRC	0x480	Error source
		Note: this register is read / write one to clear.
ENABLE	0x500	Enable UART
PSEL.RTS	0x508	Pin select for RTS signal
PSEL.TXD	0x50C	Pin select for TXD signal
PSEL.CTS	0x510	Pin select for CTS signal
PSEL.RXD	0x514	Pin select for RXD signal
BAUDRATE	0x524	Baud rate. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534	Data pointer
RXD.MAXCNT	0x538	Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C	Number of bytes transferred in the last transaction
TXD.PTR	0x544	Data pointer
TXD.MAXCNT	0x548	Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C	Number of bytes transferred in the last transaction
CONFIG	0x56C	Configuration of parity and hardware flow control

Table 113: Register overview

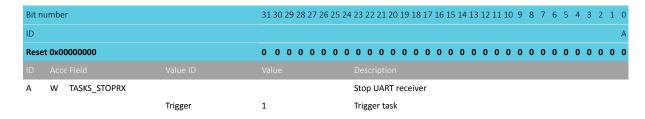
6.28.9.1 TASKS_STARTRX

Address offset: 0x000 Start UART receiver



6.28.9.2 TASKS_STOPRX

Address offset: 0x004 Stop UART receiver



6.28.9.3 TASKS_STARTTX

Address offset: 0x008 Start UART transmitter



Bit nu	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STARTTX			Start UART transmitter
		Trigger	1	Trigger task

6.28.9.4 TASKS_STOPTX

Address offset: 0x00C Stop UART transmitter

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOPTX			Stop UART transmitter
		Trigger	1	Trigger task

6.28.9.5 TASKS_FLUSHRX

Address offset: 0x02C

Flush RX FIFO into RX buffer

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_FLUSHRX			Flush RX FIFO into RX buffer
		Trigger	1	Trigger task

6.28.9.6 EVENTS_CTS

Address offset: 0x100

CTS is activated (set low). Clear To Send.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_CTS			CTS is activated (set low). Clear To Send.
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.28.9.7 EVENTS_NCTS

Address offset: 0x104

CTS is deactivated (set high). Not Clear To Send.



Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_NCTS			CTS is deactivated (set high). Not Clear To Send.
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.28.9.8 EVENTS_RXDRDY

Address offset: 0x108

Data received in RXD (but potentially not yet transferred to Data RAM)

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_RXDRDY			Data received in RXD (but potentially not yet transferred to
				Data RAM)
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.28.9.9 EVENTS_ENDRX

Address offset: 0x110

Receive buffer is filled up

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_ENDRX			Receive buffer is filled up
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.28.9.10 EVENTS_TXDRDY

Address offset: 0x11C

Data sent from TXD

Bit r	number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Res	et 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
				Description
Α	RW EVENTS_TXDRDY			Data sent from TXD
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.28.9.11 EVENTS_ENDTX

Address offset: 0x120 Last TX byte transmitted



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_ENDTX			Last TX byte transmitted
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.28.9.12 EVENTS_ERROR

Address offset: 0x124

Error detected

Bit n	umber		31	30	29 2	28 2	7 26	25	24 2	23 2	22 2	1 20) 19	18	17 1	6 15	5 14	13	12 1	1 10	9	8	7	6	5	4	3 2	2 1	0
ID																													Α
Rese	t 0x00000000		0	0	0	0 0	0	0	0	0 (0 0	0	0	0	0 (0	0	0	0 (0	0	0	0	0	0	0	0 (0	0
ID																													
Α	RW EVENTS_ERROR								1	Erro	r de	etec	ted																
		NotGenerated	0						1	Ever	nt n	ot g	gene	erate	ed														
		Generated	1						1	Ever	nt g	ene	rate	ed															

6.28.9.13 EVENTS_RXTO

Address offset: 0x144 Receiver timeout

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_RXTO			Receiver timeout
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.28.9.14 EVENTS_RXSTARTED

Address offset: 0x14C
UART receiver has started

Bit number		31 30 29	28 2	7 26	25	24 2	23 22	221	20 1	19 1	8 17	7 16	15	14	13 1	L2 1:	1 10	9	8	7	6	5	4	3 2	1 0
ID																									А
Reset 0x00000000		0 0 0	0 0	0	0	0	0 0	0	0	0 (0	0	0	0	0	0 0	0	0	0	0	0	0	0	0 0	0 0
ID Acce Field																									
A RW EVENTS_RXSTARTED						ι	JART	rec	eive	er ha	as st	art	ed												
1	NotGenerated	0				E	ent	t not	ge	nera	ited														
(Generated	1				E	ent	t ger	nera	ited															

6.28.9.15 EVENTS_TXSTARTED

Address offset: 0x150

UART transmitter has started



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_TXSTARTED			UART transmitter has started
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.28.9.16 EVENTS_TXSTOPPED

Address offset: 0x158 Transmitter stopped

Bit n	umber		31	30	29 2	8 27	7 26	25 :	24 2	3 2:	2 21	1 20	19	18 1	7 1	5 15	14	13 :	12 1	1 10	9	8	7	6	5	4 3	2	1	0
ID																													Α
Rese	t 0x00000000		0	0	0	0 0	0	0	0	0	0	0	0	0	0 0	0	0	0	0 (0	0	0	0	0	0	0 0	0	0	0
ID																													
Α	RW EVENTS_TXSTOPPED								Т	ran	smi	tter	sto	ppe	d														
		NotGenerated	0						E	ven	nt no	ot g	ene	rate	d														
		Generated	1						E	ven	nt ge	ener	rate	d															

6.28.9.17 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		3	1 30	0 2	9 28	3 27	26	25	24	1 23	22	2 2:	1 20	0 1	9 18	3 17	16	5 1!	5 14	1 1	3 12	11	10	9	8	7 (5 5	4	. 3	2	1	0
ID																											[) (;				
Rese	t 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0) (0	0	0	0	0	0
ID																																	
С	RW ENDRX_STARTRX										Sh	or	tcu	t b	etw	/eei	ı ev	/en	t E	ND	RX	and	tas	sk S	TAR	TRX							
		Disabled	0								Di	sak	ble	sho	orto	ut																	
		Enabled	1								En	nab	le s	sho	rtc	ut																	
D	RW ENDRX_STOPRX										Sh	or	tcu	t b	etw	/eei	ı ev	/en	t E	ND	RX	and	tas	sk S	ГОР	RX							
		Disabled	0								Di	sak	ble	sho	orto	ut																	
		Enabled	1								En	nab	le s	sho	rtc	ut																	

6.28.9.18 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit number		31 30 29 28 2	7 26 25 24 2	3 22 21 2	20 19 1	.8 17	16 15	14 13	3 12 :	11 10	9 8	7	6	5 4	1 3	2	1 0
ID				L	J I	Н					G F	E		0)	С	ВА
Reset 0x0000	0000	0 0 0 0 0	0 0 0 0	0 0	0 0	0 0	0 0	0 0	0	0 0	0 0	0	0	0 (0	0	0 0
ID Acce F																	
A RW C	rs		E	nable or	disabl	e inte	rrupt	for e	vent	CTS							
	Disabled	0	D	sable													
	Enabled	1	E	nable													
B RW N	CTS		E	nable or	disabl	e inte	rrupt	for e	vent	NCTS							
	Disabled	0	D	sable													
	Enabled	1	E	nable													



Disabled 0 Disable Enabled 1 Enable F RW ENDTX Disabled 0 Disable Enable or disable interrupt for event ENDTX Disabled 1 Enable G RW ERROR Disabled 0 Disable Enabled 1 Enable Enable or disable interrupt for event ERROR Disabled 0 Disable Enable Enable or disable interrupt for event RROR Disabled 1 Enable H RW RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 1 Enable I RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXTO Disable Enable or disable interrupt for event RXTARTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED					
Reset 0x00000000000000000000000000000000000	Bit n	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
D Acce Field Value D Value Description	ID				L J I H G F E D C B A
C RW RXDRDY Disabled 0 Disable Enabled 1 Enable D RW ENDRX Disabled 0 Disable Enabled 1 Enable Disabled 0 Disable Enabled 0 Disable Enable 0 Disable Enabled 1 Enable Enable 0 Disable Enable 0 Disable Enable 0 Disable Enabled 1 Enable Enable 0 Disable Enabled 1 Enable Enable 0 Disable Enabled 1 Enable Enable 0 Disable	Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Disabled 0 Disable Enable 1 Enable Enable Disable Enable Disable Enable Disable Enable Disable Disable Disable Enable Disable					
Enabled 1 Enable D RW ENDRX Disabled 0 Disable Enable or disable interrupt for event ENDRX Disabled 1 Enable Enable or disable interrupt for event TXDRDY Disabled 0 Disable Enabled 1 Enable or disable interrupt for event TXDRDY Disabled 0 Disable Enabled 1 Enable or disable interrupt for event ENDTX Disabled 0 Disable Enabled 1 Enable or disable interrupt for event ENDTX Disabled 0 Disable Enable or disable interrupt for event ENDTX Disabled 1 Enable Enable or disable interrupt for event ERROR Disable Enabled 1 Enable Enable or disable interrupt for event ERROR Disable Enabled 1 Enable Enable or disable interrupt for event RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 1 Enable Enable or disable interrupt for event RXTARTED Disabled 0 Disable Enable or disable interrupt for event RXTARTED Disabled 1 Enable Enable or disable interrupt for event RXTARTED Disabled 1 Enable Enable or disable interrupt for event TXTARTED Disabled 1 Enable Enable or disable interrupt for event TXTARTED Disabled 0 Disable Enable or disable interrupt for event TXTARTED Disabled 1 Enable Enable or disable interrupt for event TXTARTED Disabled 1 Enable Enable or disable interrupt for event TXTARTED Disabled 1 Enable Enable	С	RW RXDRDY			Enable or disable interrupt for event RXDRDY
D RW ENDRX Disabled 0 Disable Enabled 1 Enable E RW TXDRDY Disabled 0 Disable Enabled 1 Enable E RW ENDTX Disabled 0 Disable Enabled 1 Enable F RW ENDTX Disabled 0 Disable Enabled 1 Enable F RW ERROR Disabled 0 Disable Enabled 1 Enable F Enable or disable interrupt for event ENDTX Disabled 0 Disable Enabled 1 Enable F Enable or disable interrupt for event ENDTX Disabled 0 Disable Enabled 1 Enable F Enable or disable interrupt for event ERROR Disabled 0 Disable Enabled 1 Enable H RW RXTO Disabled 0 Disable Enabled 1 Enable I Enable or disable interrupt for event ERROR Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 0 Disable Enable or disable interrupt for event RXTATTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 1 Enable Disable Enable ODisable			Disabled	0	Disable
Disabled Disabled Disabled Disable			Enabled	1	Enable
E RW TXDRDY Disabled 0 Disable Enable of disable interrupt for event TXDRDY Disabled 1 Enable Enable of disable interrupt for event ENDTX Disabled 0 Disable Enable of Disable interrupt for event ENDTX Disabled 0 Disable Enable of Disable interrupt for event ENDTX Disabled 1 Enable Enable of Disable interrupt for event ERROR Disabled 0 Disable Enable of Disable Enable Enable of Disable Enable Enable of Disable Enable	D	RW ENDRX			Enable or disable interrupt for event ENDRX
E RW TXDRDY Disabled Disabled Enabled Disabled Enabled Disabled Enabled Disable Enable or disable interrupt for event TXDRDY Disable Enabled Disabled Disabled Enabled Disabled Disabled Enabled Disabled Disabled Enabled Disabled Disabled Disabled Enabled Disabled Disabled Disable Enable Disabled Disabled Disabled Disable Enabled Disabled Disable Enable Disabled Disabled Disable Enable Disable Dis			Disabled	0	Disable
Disabled 0 Disable Enabled 1 Enable F RW ENDTX Disabled 0 Disable Enable 0 Disable Enable or disable interrupt for event ENDTX Disable Enable 0 Disable Enable 0 Disable Enable or disable interrupt for event ERROR Disable Enable 0 Disable Enable or disable interrupt for event RXTO Disable Enable 0 Disable Enable O Disable Enable			Enabled	1	Enable
Finabled 1 Enable Enable Enable Enable Enable Enable or disable interrupt for event ENDTX Disabled 0 Disable Enable Enabled 1 Enable Enable Enable Enable Finable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Enable Enable Enable Enable Enable Enable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Disable Enable Enable Enable Enable Enable Disable Disable Enable Disable Disable Enable Disable Enable Disable Enable Disable Enable Disable Disab	E	RW TXDRDY			Enable or disable interrupt for event TXDRDY
F RW ENDTX Disabled 0 Disable Enabled 1 Enable Enable or disable interrupt for event ENDTX Disabled 1 Enable Enable or disable interrupt for event ERROR Disabled 0 Disable Enable or disable interrupt for event ERROR Disabled 1 Enable H RW RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 0 Disable Enable Enable or disable interrupt for event RXTO Disabled 1 Enable Enable or disable interrupt for event RXTO Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable Finable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTOPPED Disabled 0 Disable			Disabled	0	Disable
Disabled 0 Disable Enabled 1 Enable GRW ERROR ERROR Disabled 0 Disable Enable 0 Disable Enabled 1 Enable H RW RXTO Disabled 0 Disable Enabled 1 Enable Enable Disabled 0 Disable Enabled 1 Enable Enable Disable Enabled 1 Enable Enable or disable interrupt for event RXTO Disable Enabled 1 Enable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 1 Enable Finable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable Enable L RW TXSTOPPED Disabled 0 Disable			Enabled	1	Enable
Enabled 1 Enable G RW ERROR Disabled 0 Disable Enable Enable or disable interrupt for event ERROR Disabled 1 Enable Enable or disable interrupt for event RXTO Enable or disable interrupt for event RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 1 Enable I RW RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable I Enable I Enable I Enable I Enable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTOPPED Disabled 0 Disable Enable or disable interrupt for event TXSTOPPED	F	RW ENDTX			Enable or disable interrupt for event ENDTX
Finable or disable interrupt for event ERROR Disabled Disabled Enable Enable Enable Enable Enable Enable Enable Enable Disable Enable Disable Enable Disable Enable E			Disabled	0	Disable
Disabled 0 Disable Enabled 1 Enable H RW RXTO Disabled 0 Disable Enable or disable interrupt for event RXTO Disabled 1 Enable or disable interrupt for event TXSTARTED Disable Enable Disable Enable Enable Disable			Enabled	1	Enable
H RW RXTO Disabled 0 Disable Inabled 1 Enable or disable interrupt for event RXTO Disabled 0 Disable Enabled 1 Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enabled 0 Disable Disabled 1 Enable Disabled 1 Enable Finable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Disable Enable or disable interrupt for event TXSTOPPED Disabled 0 Disable	G	RW ERROR			Enable or disable interrupt for event ERROR
H RW RXTO Disabled 0 Disable Enabled 1 Enable RW RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXTO Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable Enable Enable Enable Enable Enable Enable or disable interrupt for event RXSTARTED Disabled 1 Enable Enable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable Enable Enable Disable Enable Disable			Disabled	0	Disable
Disabled 0 Disable Enabled 1 Enable I RW RXSTARTED Disabled 0 Disable Enable or disable interrupt for event RXSTARTED Disabled 0 Disable Enable I Enable Enable Enable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable or disable interrupt for event TXSTARTED Disabled 1 Enable Enable Enable Disable Disable Disable Disable Disable Disable Disable Disable Disable			Enabled	1	Enable
Enabled 1 Enable RW RXSTARTED Disabled 0 Disable Enabled 1 Enable Enable or disable interrupt for event RXSTARTED Disable Enable Enable Enable Enable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable Enable Enable Disable Enable Disable Disable Disable Disable Disable Disable	Н	RW RXTO			Enable or disable interrupt for event RXTO
RW RXSTARTED Disabled Disabled Enabled Disable Enable Enable Disable Enable Disable Enable Disable Enable or disable interrupt for event RXSTARTED Disable Enable Enable Disable Enable or disable interrupt for event TXSTARTED Disable Enable Enable Enable Disable Disable Disable Disable Disable Disable Disable Disable Disable			Disabled	0	Disable
Disabled 0 Disable Enabled 1 Enable J RW TXSTARTED Disabled 0 Disable or disable interrupt for event TXSTARTED Disabled 0 Disable Enable Enable Enable Disable			Enabled	1	Enable
Enabled 1 Enable J RW TXSTARTED Disabled 0 Disable Enable Disable Enabled 1 Enable Enable Enable Enable Disable	I	RW RXSTARTED			Enable or disable interrupt for event RXSTARTED
A RW TXSTARTED Disabled Disabled Enabled Disable Enable Enable Enable Disable			Disabled	0	Disable
Disabled 0 Disable Enabled 1 Enable L RW TXSTOPPED Enabled 0 Disable Disabled 0 Disable			Enabled	1	Enable
Enabled 1 Enable L RW TXSTOPPED Enable or disable interrupt for event TXSTOPPED Disabled 0 Disable	J	RW TXSTARTED			Enable or disable interrupt for event TXSTARTED
L RW TXSTOPPED Enable or disable interrupt for event TXSTOPPED Disabled 0 Disable			Disabled	0	Disable
Disabled 0 Disable			Enabled	1	Enable
	L	RW TXSTOPPED			Enable or disable interrupt for event TXSTOPPED
Enabled 1 Enable			Disabled	0	Disable
			Enabled	1	Enable

6.28.9.19 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				L J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CTS			Write '1' to enable interrupt for event CTS
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW NCTS			Write '1' to enable interrupt for event NCTS
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW RXDRDY			Write '1' to enable interrupt for event RXDRDY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				L JIH GFE D CBA
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
D	RW ENDRX			Write '1' to enable interrupt for event ENDRX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW TXDRDY			Write '1' to enable interrupt for event TXDRDY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW ENDTX			Write '1' to enable interrupt for event ENDTX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW ERROR			Write '1' to enable interrupt for event ERROR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW RXTO			Write '1' to enable interrupt for event RXTO
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
I	RW RXSTARTED			Write '1' to enable interrupt for event RXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW TXSTARTED			Write '1' to enable interrupt for event TXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
L	RW TXSTOPPED			Write '1' to enable interrupt for event TXSTOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.28.9.20 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			L J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CTS			Write '1' to disable interrupt for event CTS
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
B RW NCTS			Write '1' to disable interrupt for event NCTS
	Clear	1	Disable
	Disabled	0	Read: Disabled



Bit r	umber		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				L J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Enabled	1	Read: Enabled
С	RW RXDRDY			Write '1' to disable interrupt for event RXDRDY
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ENDRX			Write '1' to disable interrupt for event ENDRX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW TXDRDY			Write '1' to disable interrupt for event TXDRDY
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW ENDTX			Write '1' to disable interrupt for event ENDTX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW ERROR			Write '1' to disable interrupt for event ERROR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW RXTO			Write '1' to disable interrupt for event RXTO
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
I	RW RXSTARTED			Write '1' to disable interrupt for event RXSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW TXSTARTED			Write '1' to disable interrupt for event TXSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
L	RW TXSTOPPED			Write '1' to disable interrupt for event TXSTOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.28.9.21 ERRORSRC

Address offset: 0x480

Error source

Note: this register is read / write one to clear.



Bit r	number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Res	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW OVERRUN			Overrun error
				A start bit is received while the previous data still lies in
				RXD. (Previous data is lost.)
		NotPresent	0	Read: error not present
		Present	1	Read: error present
В	RW PARITY			Parity error
				A character with bad parity is received, if HW parity check is
				enabled.
		NotPresent	0	Read: error not present
		Present	1	Read: error present
С	RW FRAMING			Framing error occurred
				A valid stop bit is not detected on the serial data input after
				all bits in a character have been received.
		NotPresent	0	Read: error not present
		Present	1	Read: error present
D	RW BREAK			Break condition
				The serial data input is '0' for longer than the length of a
				data frame. (The data frame length is 10 bits without parity
				bit, and 11 bits with parity bit.).
		NotPresent	0	Read: error not present
		Present	1	Read: error present

6.28.9.22 ENABLE

Address offset: 0x500

Enable UART

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	ААА
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	Value Description
A RW ENABLE	Enable or disable UARTE
Disabled	0 Disable UARTE
Enabled	8 Enable UARTE

6.28.9.23 PSEL.RTS

Address offset: 0x508

Pin select for RTS signal



Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C	A A A A A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.28.9.24 PSEL.TXD

Address offset: 0x50C

Pin select for TXD signal

Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	ААААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.28.9.25 PSEL.CTS

Address offset: 0x510

Pin select for CTS signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	ААААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.28.9.26 PSEL.RXD

Address offset: 0x514

Pin select for RXD signal

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

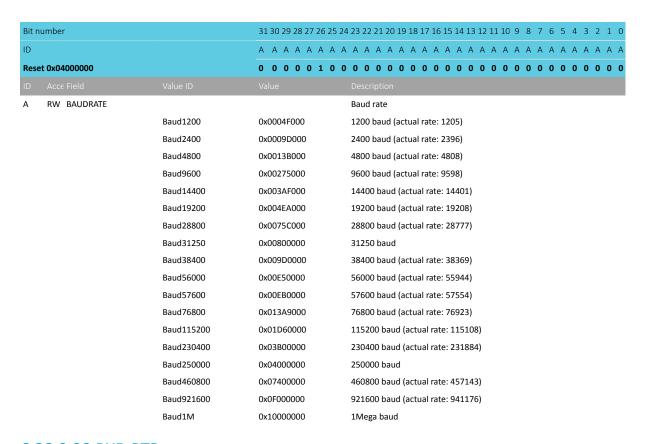




6.28.9.27 BAUDRATE

Address offset: 0x524

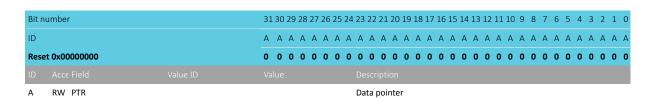
Baud rate. Accuracy depends on the HFCLK source selected.



6.28.9.28 RXD.PTR

Address offset: 0x534

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.28.9.29 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer



Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 Reset 0x000000000 D Acce Field Value D Value Description D D D D D D D D D
ID AAAAAAAA
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 1 (

6.28.9.30 RXD.AMOUNT

Address offset: 0x53C

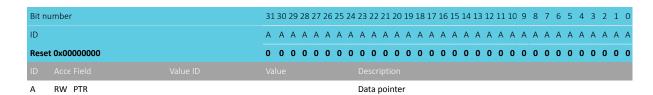
Number of bytes transferred in the last transaction

Α	R AMOUNT	[00x3FF]	Number of bytes transferred in the last transaction
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A
Bit	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.28.9.31 TXD.PTR

Address offset: 0x544

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.28.9.32 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer

_	RW MAXCNT	[00x3FF]	Maximum number of bytes in transmit buffer
ID			
Rese	et 0x00000000	0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID			A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.28.9.33 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last transaction

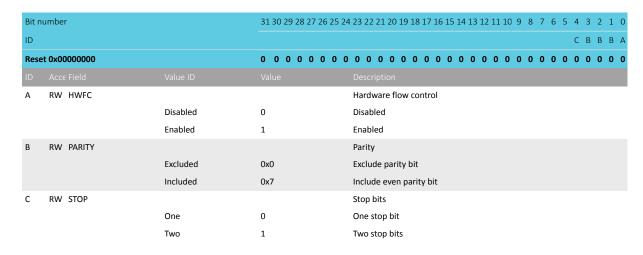


A R	AMOUNT	[00x3F	F1			Num	ber o	of by	tes t	rans	ferre	d in	the I	ast ti	ransa	actio	on					
ID A						Desc																
Reset 0x	00000000	0 0 0	0 0	0 0	0	0 0	0	0 0	0	0 (0 0	0	0 0	0 (0	0	0	0	0 0	0	0	D 0
ID															Α	Α	Α	Α	A A	Α	Α .	A A
Bit numl	per	31 30 29	28 27	26 25	5 24 :	23 22	2 21	20 19	9 18	17 1	6 15	14 :	l3 12	11 1	0 9	8	7	6	5 4	3	2	1 0

6.28.9.34 CONFIG

Address offset: 0x56C

Configuration of parity and hardware flow control



6.28.10 Electrical specification

6.28.10.1 UARTE electrical specification

Symbol	Description	Min.	Typ.	Max.	Units
·,	2000.1911011	141111	.,,	···un	-
f _{UARTE}	Baud rate for UARTE ³⁴ .			1000	kbps
t _{UARTE,CTSH}	CTS high time	1			μs
t _{UARTE.START}	Time from STARTRX/STARTTX task to transmission started				μs

6.29 WDT — Watchdog timer

A countdown watchdog timer using the low-frequency clock source (LFCLK) offers configurable and robust protection against application lock-up.

The watchdog timer is started by triggering the START task.

The watchdog can be paused during long CPU sleep periods for low power applications and when the debugger has halted the CPU. The watchdog is implemented as a down-counter that generates a TIMEOUT event when it wraps over after counting down to 0. When the watchdog timer is started through the START task, the watchdog counter is loaded with the value specified in the CRV register. This counter is also reloaded with the value specified in the CRV register when a reload request is granted.

High baud rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.



The watchdog's timeout period is given by:

```
timeout [s] = (CRV + 1) / 32768
```

When started, the watchdog will automatically force the 32.768 kHz RC oscillator on as long as no other 32.768 kHz clock source is running and generating the 32.768 kHz system clock, see chapter CLOCK — Clock control on page 65.

6.29.1 Reload criteria

The watchdog has eight separate reload request registers, which shall be used to request the watchdog to reload its counter with the value specified in the CRV register. To reload the watchdog counter, the special value 0x6E524635 needs to be written to all enabled reload registers.

One or more RR registers can be individually enabled through the RREN register.

6.29.2 Temporarily pausing the watchdog

By default, the watchdog will be active counting down the down-counter while the CPU is sleeping and when it is halted by the debugger. It is however possible to configure the watchdog to automatically pause while the CPU is sleeping as well as when it is halted by the debugger.

6.29.3 Watchdog reset

A TIMEOUT event will automatically lead to a watchdog reset.

See Reset on page 56 for more information about reset sources. If the watchdog is configured to generate an interrupt on the TIMEOUT event, the watchdog reset will be postponed with two 32.768 kHz clock cycles after the TIMEOUT event has been generated. Once the TIMEOUT event has been generated, the impending watchdog reset will always be effectuated.

The watchdog must be configured before it is started. After it is started, the watchdog's configuration registers, which comprise registers CRV, RREN, and CONFIG, will be blocked for further configuration.

The watchdog can be reset from several reset sources, see Reset behavior on page 57.

When the device starts running again, after a reset, or waking up from OFF mode, the watchdog configuration registers will be available for configuration again.

6.29.4 Registers

Base address	Peripheral	Instance	Description	Configuration
0x40010000	WDT	WDT	Watchdog timer	

Table 114: Instances

TASKS_START 0x000 Start the watchdog
EVENTS_TIMEOUT 0x100 Watchdog timeout
INTENSET 0x304 Enable interrupt
INTENCLR 0x308 Disable interrupt
RUNSTATUS 0x400 Run status
REQSTATUS 0x404 Request status
CRV 0x504 Counter reload value
RREN 0x508 Enable register for reload request registers



Register	Offset	Description
CONFIG	0x50C	Configuration register
RR[0]	0x600	Reload request 0
RR[1]	0x604	Reload request 1
RR[2]	0x608	Reload request 2
RR[3]	0x60C	Reload request 3
RR[4]	0x610	Reload request 4
RR[5]	0x614	Reload request 5
RR[6]	0x618	Reload request 6
RR[7]	0x61C	Reload request 7

Table 115: Register overview

6.29.4.1 TASKS_START

Address offset: 0x000 Start the watchdog

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_START			Start the watchdog
		Trigger	1	Trigger task

6.29.4.2 EVENTS_TIMEOUT

Address offset: 0x100 Watchdog timeout

Bit n	umber		313	0 2	9 28	27	26	25 2	24 2	23 2	22 2	21 2	0 19	9 18	3 17	16	15	14	13	12 1	1 10	9	8	7	6	5	4	3 2	2 1	0
ID																														Α
Rese	t 0x00000000		0 (0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0
ID																														
Α	RW EVENTS_TIMEOUT								١	Wat	tch	dog	tim	ieou	ıt															
		NotGenerated	0						1	Eve	nt ı	not	gen	era	ted															
		Generated	1						ı	Eve	nt g	gene	erat	ed																

6.29.4.3 INTENSET

Address offset: 0x304 Enable interrupt

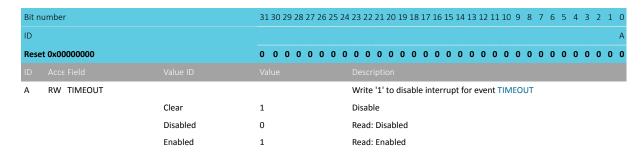
Bit nu	ımber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Reset	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW TIMEOUT			Write '1' to enable interrupt for event TIMEOUT
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



6.29.4.4 INTENCLR

Address offset: 0x308

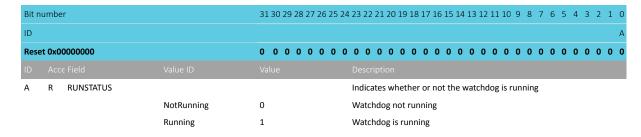
Disable interrupt



6.29.4.5 RUNSTATUS

Address offset: 0x400

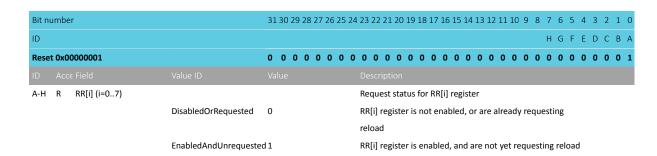
Run status



6.29.4.6 REQSTATUS

Address offset: 0x404

Request status



6.29.4.7 CRV

Address offset: 0x504
Counter reload value



Bit n	umber		313	30 2	9 2	8 2	7 26	5 25	5 24	23	22	21	20 1	9 1	8 17	⁷ 16	15	14	13	12	11	10	9	8	7	6 !	5 4	3	2	1 0
ID			А	A A	Α Α	\ <i>A</i>	A	Α	A	Α	Α	Α	Α /	Δ Α	A	Α	Α	Α	Α	Α	Α	Α	Α	Α.	A	Α /	4 A	Α	Α	АА
Rese	t OxFFF	FFFFF	1	1 1	L 1	. 1	. 1	1	1	1	1	1	1 :	1 1	1	1	1	1	1	1	1	1	1	1	1	1 :	1 1	1	1	1 1
ID																														
Α	RW (CRV	[0x0]	0000	000	OF.	.0xF	FFI	FFF	F E jc	unt	er r	eloa	ad v	alue	e in	nur	nbe	er o	f cy	/cle	s of	f th	e 3	2.7	68 I	kHz			

clock

6.29.4.8 RREN

Address offset: 0x508

Enable register for reload request registers

Bit number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			HGFEDCBA
Reset 0x00000001		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-H RW RR[i] (i=07)			Enable or disable RR[i] register
	Disabled	0	Disable RR[i] register
	Enabled	1	Enable RR[i] register

6.29.4.9 CONFIG

Address offset: 0x50C Configuration register

Bit n	umber		31 30 29 28 27 26 2	5 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C A
Rese	t 0x00000001		0 0 0 0 0 0	0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW SLEEP				Configure the watchdog to either be paused, or kept
					running, while the CPU is sleeping
		Pause	0		Pause watchdog while the CPU is sleeping
		Run	1		Keep the watchdog running while the CPU is sleeping
С	RW HALT				Configure the watchdog to either be paused, or kept
					running, while the CPU is halted by the debugger
		Pause	0		Pause watchdog while the CPU is halted by the debugger
		Run	1		Keep the watchdog running while the CPU is halted by the
					debugger

6.29.4.10 RR[n] (n=0..7)

Address offset: $0x600 + (n \times 0x4)$

Reload request n

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		
A W RR		Reload request register
Reload	0x6E524635	Value to request a reload of the watchdog timer



6.29.5 Electrical specification

6.29.5.1 Watchdog Timer Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{WDT}	Time out interval	458 μs		36 h	



7 Hardwa

Hardware and layout

7.1 Pin assignments

The pin assignment figures and tables describe the pinouts for the product variants of the chip.

The nRF52810 device provides flexibility when it comes to routing and configuration of the GPIO pins. However, some pins have limitations or recommendations for how the pin should be configured or what it should be used for.

7.1.1 QFN48 pin assignments

The nRF52810 QFN48 pin assignment table and figure describe the pinouts for this variant of the chip.

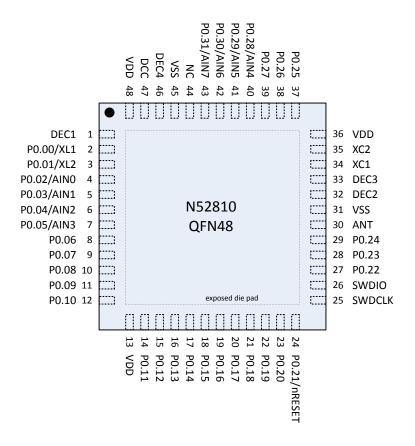


Figure 139: QFN48 pin assignments, top view

Pin	Name	Туре	Description
1	DEC1	Power	0.9 V regulator digital supply
			decoupling
2	P0.00	Digital I/O	General purpose I/O
	XL1	Analog input	Connection for 32.768 kHz crystal (LFXO)



Pin	Name	Туре	Description
3	P0.01	Digital I/O	General purpose I/O
	XL2	Analog input	Connection for 32.768 kHz crystal
			(LFXO)
4	P0.02	Digital I/O	General purpose I/O
	AIN0	Analog input	COMP input
			SAADC input
5	P0.03	Digital I/O	General purpose I/O
,			
	AIN1	Analog input	COMP input
			SAADC input
6	P0.04	Digital I/O	General purpose I/O
	AIN2	Analog input	COMP input
			SAADC input
7	P0.05	Digital I/O	General purpose I/O
		-	
	AIN3	Analog input	COMP input
			SAADC input
8	P0.06	Digital I/O	General purpose I/O
9	P0.07	Digital I/O	General purpose I/O
10	P0.08	Digital I/O	General purpose I/O
11	P0.09	Digital I/O	General purpose I/O
12 13	P0.10 VDD	Digital I/O Power	General purpose I/O
14	P0.11	Digital I/O	Power supply General purpose I/O
15	P0.12	Digital I/O	General purpose I/O
16	P0.13	Digital I/O	General purpose I/O
17	P0.14	Digital I/O	General purpose I/O
10		-	
18	P0.15	Digital I/O	General purpose I/O
19	P0.16	Digital I/O	General purpose I/O
20	P0.17	Digital I/O	General purpose I/O
21	P0.18	Digital I/O	General purpose I/O
22	P0.19	Digital I/O	General purpose I/O
23	P0.20	Digital I/O	General purpose I/O
24	P0.21	Digital I/O	General purpose I/O
	nRESET		Configurable as pin reset
25	SWDCLK	Digital input	Serial wire debug clock input for debug
		Ç ,	and programming
26	SWDIO	Digital I/O	Serial wire debug I/O for debug and
		-	programming
27	P0.22	Digital I/O	General purpose I/O
28	P0.23	Digital I/O	General purpose I/O
29	P0.24	Digital I/O	General purpose I/O
30	ANT	RF	Single-ended radio antenna
			connection
31	VSS	Power	Ground (radio supply)
32	DEC2	Power	1.3 V regulator supply decoupling
			(radio supply)
33	DEC3	Power	Power supply decoupling
34	XC1	Analog input	Connection for 32 MHz crystal
35	XC2	Analog input	Connection for 32 MHz crystal
36	VDD	Power	Power supply



P0.26 Digital I/O General purpose I/O P0.27 Digital I/O General purpose I/O P0.28 Digital I/O General purpose I/O P0.28 Digital I/O General purpose I/O AINA Analog input COMP input SAADC input P0.29 Digital I/O General purpose I/O AINS Analog input COMP input SAADC input P0.30 Analog input COMP input SAADC input P0.30 Aln6 Analog input COMP input SAADC input P0.31 Digital I/O General purpose I/O AIN7 Analog input COMP input SAADC inpu	Pin	Name	Туре	Description
P0.27 Digital I/O General purpose I/O 40 P0.28 Digital I/O General purpose I/O 40 AIN4 Analog input COMP input 5AADC input 41 P0.29 Digital I/O General purpose I/O 41 AIN5 Analog input COMP input 5AADC input 42 P0.30 Digital I/O General purpose I/O 48 Analog input COMP input 5AADC input 49 Analog input COMP input 5AADC input 40 Analog input COMP input 5AADC input 41 AIN6 Analog input COMP input 5AADC input 42 Analog input COMP input 5AADC input 43 Analog input COMP input 5AADC input 44 COMP input 5AADC input 45 Analog input COMP input 5AADC input 6AADC	37	P0.25	Digital I/O	General purpose I/O
AlN4 Analog input COMP input SAADC input 41 P0.29 Digital I/O General purpose I/O AlN5 Analog input COMP input SAADC input COMP input SAADC input COMP input SAADC input COMP input SAADC input COMP input SAADC input COMP input SAADC input COMP input SAADC input SAADC input COMP input SAADC input COMP input SAADC input COMP input SAADC input AlN6 Analog input COMP input SAADC input SAADC input SAADC input COMP input SAADC input COMP input SAADC input AlN7 Analog input COMP input SAADC input SAADC input AlN7 Analog input COMP input SAADC input SAADC input AlN7 SAADC input SAADC input SAADC input AlN7 SAADC input AlN7 SAADC input SAADC input SAADC input SAADC input SAADC input SAADC input AlN7 SAADC input AlN7 SAADC input SAADC input	38	P0.26	Digital I/O	General purpose I/O
AlN4 Analog input COMP input SAADC input 41 P0.29 Digital I/O General purpose I/O AlN5 Analog input COMP input SAADC input COMP input SAADC input 42 P0.30 Digital I/O General purpose I/O AlN6 Analog input COMP input SAADC input 43 P0.31 Digital I/O General purpose I/O input 44 SAADC input Analog input COMP input SAADC input SAADC input 44 Power Ground 45 VSS Power Ground 46 DEC4 Power I.3 V regulator supply decoupling Input from DC/DC regulator Output from DC/DC regulator Output from DC/DC regulator	39	P0.27	Digital I/O	General purpose I/O
SAADC input P0.29 Digital I/O General purpose I/O AINS Analog input COMP input SAADC input P0.30 Digital I/O General purpose I/O AIN6 Analog input COMP input SAADC input Analog input COMP input SAADC input SAADC input Analog input COMP input SAADC input Analog input SAADC input Analog input SAADC input Analog input SAADC input Analog input COMP input SAADC input Analog input Input from DC/DC regulator Input from DC/DC regulator Output from 1.3 V LDO	40	P0.28	Digital I/O	General purpose I/O
P0.29 Digital I/O General purpose I/O AINS Analog input COMP input SAADC input P0.30 Digital I/O General purpose I/O AIN6 Analog input COMP input SAADC input AIN6 Analog input COMP input SAADC input P0.31 Digital I/O General purpose I/O pin AIN7 Analog input COMP input SAADC input AND SAADC input Input from DC/DC regulator		AIN4	Analog input	COMP input
AINS Analog input COMP input \$AADC input 42 P0.30 Digital I/O General purpose I/O AIN6 Analog input COMP input \$AADC input 43 P0.31 Digital I/O General purpose I/O input AIN7 Analog input COMP input \$AADC input COMP input COMP input COMP input SAADC input ANO COMP input SAADC input ANO COMP input Leave unconnected 44 VSS Power Ground 45 Power I.3 V regulator supply decoupling input from DC/DC regulator Output from DC/DC regulator Output from DC/DC regulator				SAADC input
SAADC input 42 P0.30 Digital I/O General purpose I/O AIN6 Analog input COMP input 5AADC input 43 P0.31 Digital I/O General purpose I/O pin AIN7 Analog input COMP input 5AADC input	41	P0.29	Digital I/O	General purpose I/O
P0.30 Digital I/O General purpose I/O AIN6 Analog input COMP input SAADC input 43 P0.31 Digital I/O General purpose I/O pin AIN7 Analog input COMP input SAADC input SAADC input SAADC input SAADC input Leave unconnected Leave unconnected 45 VSS Power Ground 46 DEC4 Power Input from DC/DC regulator Input from DC/DC regulator Output from 1.3 V LDO		AIN5	Analog input	COMP input
AIN6 Analog input COMP input SAADC input 43 P0.31 Digital I/O General purpose I/O pin COMP input SAADC input COMP input SAADC input Analog input COMP input SAADC input No connect Leave unconnected 45 VSS Power Ground 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO				SAADC input
SAADC input P0.31	42	P0.30	Digital I/O	General purpose I/O
43 P0.31 Digital I/O General purpose I/O pin AIN7 Analog input COMP input SAADC input 44 No connect Leave unconnected 45 VSS Power Ground 46 DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO		AIN6	Analog input	COMP input
AIN7 Analog input COMP input SAADC input 44 NC No connect Leave unconnected 45 VSS Power Ground 46 DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO				SAADC input
SAADC input NC No connect Leave unconnected VSS Power Ground DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO	43	P0.31	Digital I/O	General purpose I/O pin
NC Leave unconnected VSS Power Ground DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO		AIN7	Analog input	COMP input
Leave unconnected VSS Power Ground DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO				SAADC input
45 VSS Power Ground 46 DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO	44	NC		No connect
46 DEC4 Power 1.3 V regulator supply decoupling Input from DC/DC regulator Output from 1.3 V LDO				Leave unconnected
Input from DC/DC regulator Output from 1.3 V LDO	45	VSS	Power	Ground
Output from 1.3 V LDO	46	DEC4	Power	1.3 V regulator supply decoupling
				Input from DC/DC regulator
				Output from 1.3 V LDO
47 DCC Power DC/DC regulator output	47	DCC	Power	DC/DC regulator output
48 VDD Power Power supply	48	VDD	Power	Power supply
Die pad VSS Power Ground pad	Die pad	VSS	Power	Ground pad
Exposed die pad must be connected				Exposed die pad must be connected
to ground (VSS) for proper device				to ground (VSS) for proper device
operation.				operation.

Table 116: QFN48 pin assignments

7.1.2 QFN32 pin assignments

The nRF52810 QFN32 pin assignment table and figure describe the pinouts for this variant of the chip.



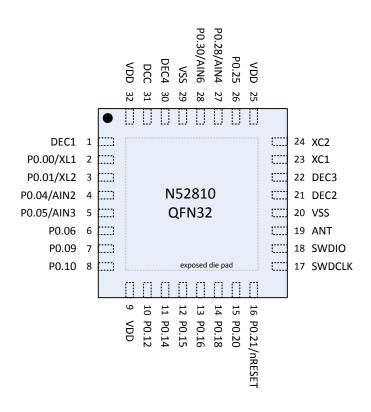


Figure 140: QFN32 pin assignments, top view

_					
Pin	Name	Туре	Description		
1	DEC1	Power	0.9 V regulator digital supply		
			decoupling		
2	P0.00	Digital I/O	General purpose I/O		
	XL1	Analog input	Connection for 32.768 kHz crystal		
		• •	(LFXO)		
3	P0.01	Digital I/O	General purpose I/O		
	XL2	Analog input	Connection for 22 769 kHz crystal		
	XLZ	Analog Input	Connection for 32.768 kHz crystal		
			(LFXO)		
4	P0.04	Digital I/O	General purpose I/O		
	AIN2	Analog input	COMP input		
			SAADC input		
5	P0.05	Digital I/O	General purpose I/O		
	AIN3	Analog input	COMP input		
			CAADC in must		
-			SAADC input		
6	P0.06	Digital I/O	General purpose I/O		
7	P0.09	Digital I/O	General purpose I/O		
8	P0.10	Digital I/O	General purpose I/O		
9	VDD	Power	Power supply		
10	P0.12	Digital I/O	General purpose I/O		
11	P0.14	Digital I/O	General purpose I/O		
12	P0.15	Digital I/O	General purpose I/O		



Pin	Name	Туре	Description		
13	P0.16	Digital I/O	General purpose I/O		
14	P0.18	Digital I/O	General purpose I/O		
			Single wire output		
15	P0.20	Digital I/O	General purpose I/O		
16	P0.21	Digital I/O	General purpose I/O		
	nRESET		Configurable as pin reset		
17	SWDCLK	Digital input	Serial wire debug clock input for debug		
			and programming		
18	SWDIO	Digital I/O	Serial wire debug I/O for debug and		
			programming		
19	ANT	RF	Single-ended radio antenna		
			connection		
20	VSS	Power	Ground (radio supply)		
21	DEC2	Power	1.3 V regulator supply decoupling		
			(radio supply)		
22	DEC3	Power	Power supply decoupling		
23	XC1	Analog input	Connection for 32 MHz crystal		
24	XC2	Analog input	Connection for 32 MHz crystal		
25	VDD	Power	Power supply		
26	P0.25	Digital I/O	General purpose I/O		
27	P0.28	Digital I/O	General purpose I/O		
	AIN4	Analog input	COMP input		
			SAADC input		
28	P0.30	Digital I/O	General purpose I/O		
		-			
	AIN6	Analog input	COMP input		
			SAADC input		
29	VSS	Power	Ground		
30	DEC4	Power	1.3 V regulator supply decoupling		
			Input from DC/DC regulator		
			Output from 1.3 V LDO		
31	DCC	Power	DC/DC regulator output		
32	VDD	Power	Power supply		
Die pad	VSS	Power	Ground pad		
			Exposed die pad must be connected		
			to ground (VSS) for proper device		
			operation.		

Table 117: QFN32 pin assignments

7.1.3 WLCSP ball assignments

The nRF52810 ball assignment table and figure describe the assignments for this variant of the chip.



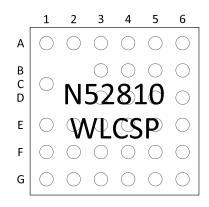


Figure 141: WLCSP ball assignments, top view

Balls not mentioned in the ball assignments table below are not connected (NC) and must be soldered to the PCB.

Pin	Name	Туре	Description		
A1	XC1	Analog input	Connection for 32 MHz crystal		
A2	XC2	Analog input	Connection for 32 MHz crystal		
A3	DEC2	Power	1.3 V regulator supply decoupling		
			(radio supply)		
A4	DEC4	Power	1.3 V analog supply.		
			Input from DC/DC converter. Output		
			from 1.3 V LDO.		
A5	DCC	Power	DC/DC converter output (3.3 V PWM)		
A6	VDD	Power	Power (battery) supply		
B3	VSS	Power	Ground		
B4	VSS	Power	Ground		
B5	P0.00	Digital I/O	General purpose I/O		
	XL1	Analog input	Connection for 22 769 kHz crustal		
	XLI	Analog input	Connection for 32.768 kHz crystal		
В6	DEC1	Power	(LFXO) 0.9 V regulator digital supply		
ВО	DECI	rowei	decoupling		
C1	VSS_PA	Power	Ground		
D3	VSS_FA	Power	Ground		
D4	VSS	Power	Ground		
D5	P0.01	Digital I/O	General purpose I/O		
	XL2	Analog input	Connection for 32.768 kHz crystal		
			(LFXO)		
D6	P0.03	Digital I/O	General purpose I/O		
	AIN1	Analog input	SAADC/COMP/LPCOMP input		
E1	ANT	RF	Single-ended radio antenna		
			connection		
E2	P0.18	Digital I/O	General purpose I/O		
E3	VSS	Power	Ground		
E4	VSS	Power	Ground		
E5	P0.04	Digital I/O	General purpose I/O		
	AIN2	Analog input	SAADC/COMP/LPCOMP input		
E6	P0.05	Digital I/O	General purpose I/O		
	AIN3	Analog input	SAADC/COMP/LPCOMP input		
F1	SWDIO	Digital I/O	Serial wire debug I/O for debug and		
		•	programming		
F2	P0.21	Digital I/O	General purpose I/O		
	»DECET		Configurable as pin reset		
F2	nRESET	Digital I/O	,		
F3	P0.17 P0.14	Digital I/O Digital I/O	General purpose I/O General purpose I/O		
F5		-			
	P0.11	Digital I/O	General purpose I/O		
F6 G1	P0.08 SWDCLK	Digital I/O Digital input	General purpose I/O Social wire debug clock input for debug		
01	JAADCEN	Digital Input	Serial wire debug clock input for debug and programming		
G2	P0.20	Digital I/O	General purpose I/O		
G3	P0.16	Digital I/O	General purpose I/O General purpose I/O		
G4	P0.15	Digital I/O	General purpose I/O		
G5	P0.15	Digital I/O	General purpose I/O		
G6	VDD	Power	Power (battery) supply		
OU .	VUU	FUWEI	rower (battery) supply		

Table 118: WLCSP ball assignments



7.1.4 GPIO pins located near the radio

Radio performance parameters, such as sensitivity, may be affected by high frequency digital I/O with large sink/source current close to the radio power supply and antenna pins.

GPIO recommended usage on page 396 identifies some GPIO pins that have recommended usage guidelines for maximizing radio performance in an application.

GPIO	QFN48 pin	QFN32 pin	Recommended usage
P0.25	37	26	Low drive, low frequency I/O only.
P0.26	38		
P0.27	39		
P0.28	40	27	
P0.29	41		

Table 119: GPIO recommended usage

7.2 Mechanical specifications

The mechanical specifications for the packages show the dimensions in millimeters.

7.2.1 QFN48 6 x 6 mm package

Dimensions in millimeters for the nRF52810 QFN48 6 x 6 mm package.

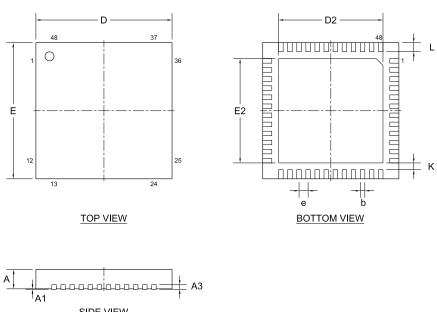


Figure 142: QFN48 6 x 6 mm package

	A	A1	А3	b	D, E	D2, E2	е	К	L
Min.	0.80	0.00		0.15		4.50		0.20	0.35
Nom.	0.85	0.04	0.20	0.20	6.00	4.60	0.40		0.40
Max.	0.90	0.05		0.25		4.70			0.45

Table 120: QFN48 dimensions in millimeters



7.2.2 QFN32 5 x 5 mm package

Dimensions in millimeters for the nRF52810 QFN32 5 x 5 mm package.

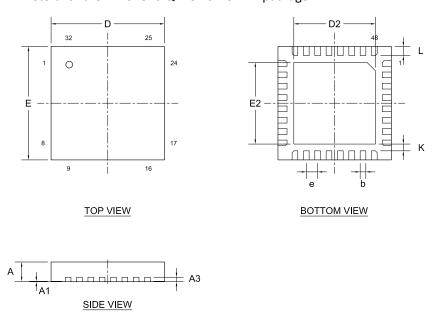


Figure 143: QFN32 5 x 5 mm package

	Α	A1	А3	b	D, E	D2, E2	е	K	L
Min.	0.80	0.00		0.20		3.40		0.25	0.35
Nom.	0.85	0.04	0.20	0.25	5.00	3.50	0.50		0.40
Max.	0.90	0.05		0.30		3.60			0.45

Table 121: QFN32 dimensions in millimeters

7.2.3 WLCSP 2.482 x 2.464 mm package

Dimensions in millimeters for the nRF52810 WLCSP 2.482 x 2.464 mm package.

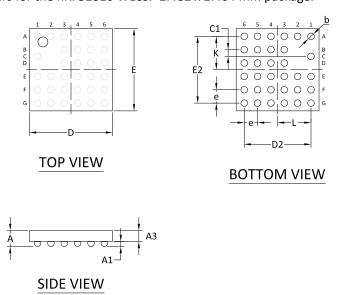


Figure 144: WLCSP 2.482 x 2.464 mm package



	Α	A1	А3	b	C1	D	E	D2	E2	е	K	L
Min.	0.419	0.12	0.299	0.197		2.452	2.434					
Nom.	0.477		0.327		0.2	2.482	2.464	2.0	2.0	0.4	1.0	1.0
Max.	0.535	0.18	0.355	0.257		2.512	2.494					

Table 122: WLCSP dimensions in millimeters

7.3 Reference circuitry

To ensure good RF performance when designing PCBs, it is highly recommended to use the PCB layouts and component values provided by Nordic Semiconductor.

Documentation for the different package reference circuits, including Altium Designer files, PCB layout files, and PCB production files can be downloaded from the product page for the nRF52810 on www.nordicsemi.com.

7.3.1 Schematic QFAA QFN48 with internal LDO regulator setup

In addition to the schematic, the bill of material (BOM) is also provided.

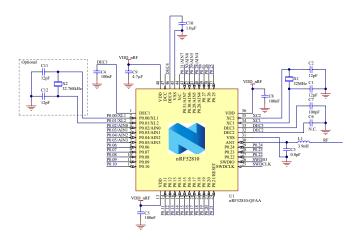


Figure 145: QFAA QFN48 with internal LDO regulator setup

Note: For PCB reference layouts, see the product page for the nRF52810 on www.nordicsemi.com.



Designator	Value	Description	Footprint
C1, C2, C11, C12	12 pF	Capacitor, NPO, ±2%	0402
C3	0.8 pF	Capacitor, NPO, ±5%	0402
C4, C5, C8	100 nF	Capacitor, X7R, ±10%	0402
C6	N.C.	Not mounted	0402
C7	100 pF	Capacitor, NPO, ±5%	0402
C 9	4.7 μF	Capacitor, X5R, ±10%	0603
C10	1.0 μF	Capacitor, X7R, ±10%	0603
L1	3.9 nH	High frequency chip inductor ±5%	0402
U1	nRF52810- QFAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	QFN-48
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016
X2	32.768 kHz	XTAL SMD 3215, 32.768 kHz, Cl = 9 pF, Total Tol: ±20 ppm	XTAL_3215

Table 123: Bill of material for QFAA QFN48 with internal LDO regulator setup

7.3.2 Schematic QFAA QFN48 with DC/DC regulator setup

In addition to the schematic, the bill of material (BOM) is also provided.

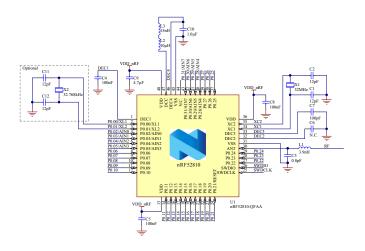


Figure 146: QFAA QFN48 with DC/DC regulator setup

Note: For PCB reference layouts, see the product page for the nRF52810 on www.nordicsemi.com.



Designator	Value	Description	Footprint
C1, C2, C11, C12	12 pF	Capacitor, NPO, ±2%	0402
C3	0.8 pF	Capacitor, NPO, ±5%	0402
C4, C5, C8	100 nF	Capacitor, X7R, ±10%	0402
C6	N.C.	Not mounted	0402
C7	100 pF	Capacitor, NPO, ±5%	0402
C 9	4.7 μF	Capacitor, X5R, ±10%	0603
C10	1.0 μF	Capacitor, X7R, ±10%	0603
L1	3.9 nH	High frequency chip inductor ±5%	0402
L2	10 μΗ	Chip inductor, IDC,min = 50 mA, ±20%	0603
L3	15 nH	High frequency chip inductor ±10%	0402
U1	nRF52810- QFAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	QFN-48
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016
X2	32.768 kHz	XTAL SMD 3215, 32.768 kHz, Cl = 9 pF, Total Tol: ±20 ppm	XTAL_3215

Table 124: Bill of material for QFAA QFN48 with DC/DC regulator setup

7.3.3 Schematic QCAA QFN32 with internal LDO regulator setup

In addition to the schematic, the bill of material (BOM) is also provided.

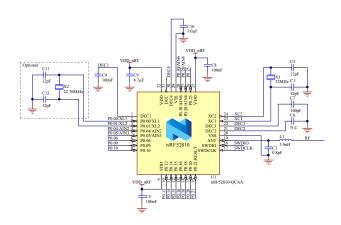


Figure 147: QCAA QFN32 with internal LDO regulator setup



Designator	Value	Description	Footprint
C1, C2, C11, C12	12 pF	Capacitor, NPO, ±2%	0402
C3	0.8 pF	Capacitor, NPO, ±5%	0402
C4, C5, C8	100 nF	Capacitor, X7R, ±10%	0402
C6	N.C.	Not mounted	0402
C7	100 pF	Capacitor, NPO, ±5%	0402
C9	4.7 μF	Capacitor, X5R, ±10%	0603
C10	1.0 μF	Capacitor, X7R, ±10%	0603
L1	3.9 nH	High frequency chip inductor ±5%	0402
U1	nRF52810-QCAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	QFN-32
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016
X2	32.768 kHz	XTAL SMD 3215, 32.768 kHz, Cl = 9 pF, Total Tol: ±20 ppm	XTAL_3215

Table 125: Bill of material for QCAA QFN32 with internal LDO regulator setup

7.3.4 Schematic QCAA QFN32 with DC/DC regulator setup

In addition to the schematic, the bill of material (BOM) is also provided.

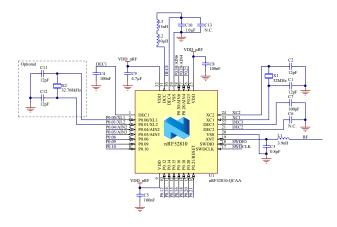


Figure 148: QCAA QFN32 with DC/DC regulator setup



Designator	Value	Description	Footprint
C1, C2, C11, C12	12 pF	Capacitor, NPO, ±2%	0402
C3	0.8 pF	Capacitor, NPO, ±5%	0402
C4, C5, C8	100 nF	Capacitor, X7R, ±10%	0402
C6	N.C.	Not mounted	0402
C7	100 pF	Capacitor, NPO, ±5%	0402
C9	4.7 μF	Capacitor, X5R, ±10%	0603
C10	1.0 μF	Capacitor, X7R, ±10%	0603
L1	3.9 nH	High frequency chip inductor ±5%	0402
L2	10 μΗ	Chip inductor, IDC,min = 50 mA, ±20%	0603
L3	15 nH	High frequency chip inductor ±10%	0402
U1	nRF52810-QCAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	QFN-32
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016
X2	32.768 kHz	XTAL SMD 3215, 32.768 kHz, Cl = 9 pF, Total Tol: ±20 ppm	XTAL_3215

Table 126: Bill of material for QCAA QFN32 with DC/DC regulator setup

7.3.5 Schematic CAAA WLCSP with internal LDO regulator setup

In addition to the schematic, the bill of material (BOM) is also provided.



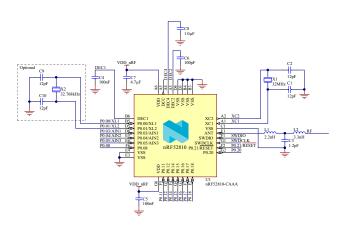


Figure 149: CAAA WLCSP with internal LDO regulator setup

Designator	Value	Description	Footprint
C1, C2, C9, C10	12 pF	Capacitor, NPO, ±2 %	0201
C3	1.2 pF	Capacitor, NPO, ±5 %	0201
C4, C5	100 nF	Capacitor, X5R, ±10 %	0201
C6	100 pF	Capacitor, NPO, ±2 %	0201
C7	4.7 μF	Capacitor, X5R, ±10 %	0603
C8	1.0 μF	Capacitor, X5R, ±5 %	0402
L1	2.2 nH	High frequency chip inductor ±5 %	0201
L2	3.3 nH	High frequency chip inductor ±5 %	0201
U1	nRF52810- CAAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	WLCSP-33
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016
X2	32.768 kHz	XTAL SMD 2012, 32.768 kHz, Cl = 9 pF, Total Tol: ±50 ppm	XTAL_2012

Table 127: Bill of material for CAAA WLCSP with internal LDO regulator setup

7.3.6 Schematic CAAA WLCSP with DC/DC regulator setup

In addition to the schematic, the bill of material (BOM) is also provided.



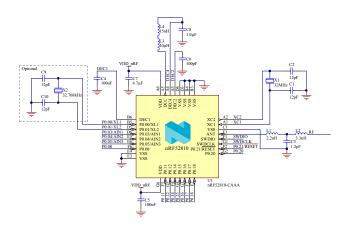


Figure 150: CAAA WLCSP with DC/DC regulator setup

Designator	Value	Description	Footprint
C1, C2, C9, C10	12 pF	Capacitor, NPO, ±2 %	0201
C3	1.2 pF	Capacitor, NPO, ±5 %	0201
C4, C5	100 nF	Capacitor, X5R, ±10 %	0201
C6	100 pF	Capacitor, NPO, ±2 %	0201
C7	4.7 μF	Capacitor, X5R, ±10 %	0603
C8	1.0 μF	Capacitor, X5R, ±5 %	0402
L1	2.2 nH	High frequency chip inductor ±5 %	0201
L2	3.3 nH	High frequency chip inductor ±5 %	0201
L3	10 μΗ	Chip inductor, IDC,min = 50 mA, ±20 %	0603
L4	15 nH	High frequency chip inductor ±10 %	0402
U1	nRF52810- CAAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	WLCSP-33
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016
X2	32.768 kHz	XTAL SMD 2012, 32.768 kHz, Cl = 9 pF, Total Tol: ±50 ppm	XTAL_2012

Table 128: Bill of material for CAAA WLCSP with DC/DC regulator setup



7.3.7 Schematic CAAA WLCSP with two layers

In addition to the schematic, the bill of material (BOM) is also provided.

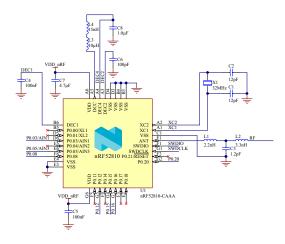


Figure 151: CAAA WLCSP 2-layer setup

Note: For PCB reference layouts, see the product page for the nRF52810 on www.nordicsemi.com.



Designator	Value	Description	Footprint
C1, C2	12 pF	Capacitor, NPO, ±2 %	0201
C3	1.2 pF	Capacitor, NPO, ±5 %	0201
C4, C5	100 nF	Capacitor, X5R, ±10 %	0201
C6	100 pF	Capacitor, NPO, ±2 %	0201
C7	4.7 μF	Capacitor, X5R, ±10 %	0603
C8	1.0 μF	Capacitor, X5R, ±5 %	0402
L1	2.2 nH	High frequency chip inductor ±5 %	0201
L2	3.3 nH	High frequency chip inductor ±5 %	0201
L3	10 μΗ	Chip inductor, IDC,min = 50 mA, ±20 %	0603
L4	15 nH	High frequency chip inductor ±10 %	0402
U1	nRF52810- CAAA	Multiprotocol Bluetooth [®] low energy, ANT, and 2.4 GHz proprietary System on Chip	WLCSP-33
X1	32 MHz	XTAL SMD 2016, 32 MHz, Cl = 8 pF, Total Tol: ±40 ppm	XTAL_2016

Table 129: Bill of material for CAAA WLCSP 2-layer setup

7.3.8 PCB guidelines

A well designed PCB is necessary to achieve good RF performance. Poor layout can lead to loss in performance or functionality.

A qualified RF layout for the IC and its surrounding components, including matching networks, can be downloaded from www.nordicsemi.com.

To ensure optimal performance it is essential that you follow the schematics and layout references closely. Especially in the case of the antenna matching circuitry (components between device pin ANT and the antenna), any changes to the layout can change the behavior, resulting in degradation of RF performance or a need to change component values. All reference circuits are designed for use with a $50~\Omega$ single-ended antenna.

A PCB with a minimum of two layers, including a ground plane, is recommended for optimal performance. On PCBs with more than two layers, put a keep-out area on the inner layers directly below the antenna matching circuitry (components between device pin ANT and the antenna) to reduce the stray capacitances that influence RF performance.

A matching network is needed between the RF pin ANT and the antenna, to match the antenna impedance (normally $50~\Omega$) to the optimum RF load impedance for the chip. For optimum performance, the impedance for the matching network should be set as described in the recommended package reference circuitry in Reference circuitry on page 398.

The DC supply voltage should be decoupled as close as possible to the VDD pins with high performance RF capacitors. See the schematics for recommended decoupling capacitor values. The supply voltage for the chip should be filtered and routed separately from the supply voltages of any digital circuitry.

Long power supply lines on the PCB should be avoided. All device grounds, VDD connections, and VDD bypass capacitors must be connected as close as possible to the IC. For a PCB with a topside RF ground plane, the VSS pins should be connected directly to the ground plane. For a PCB with a bottom ground plane, the best technique is to have via holes as close as possible to the VSS pads. A minimum of one via hole should be used for each VSS pin.



Fast switching digital signals should not be routed close to the crystal or the power supply lines. Capacitive loading of fast switching digital output lines should be minimized in order to avoid radio interference.

7.3.9 PCB layout example

The PCB layout shown in the following figures is a reference layout for the QFN48 package with internal LDO setup.

Important: Pay attention to how the capacitor C3 is grounded. It is not directly connected to the ground plane, but grounded via VSS pin 31. This is done to create additional filtering of harmonic components.

For all available reference layouts, see the product page for the nRF52810 on www.nordicsemi.com.

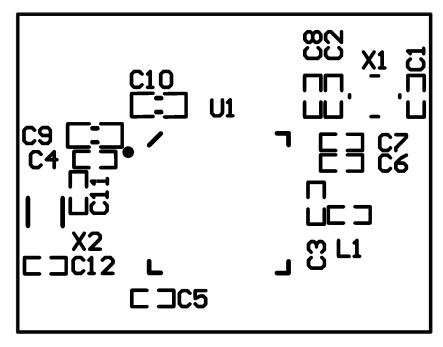


Figure 152: Top silk layer

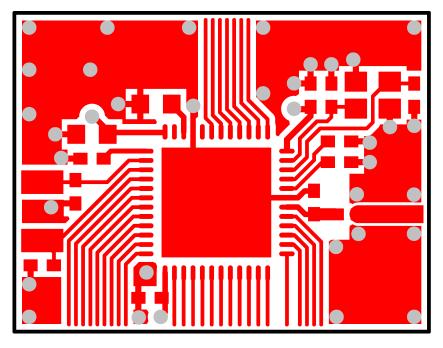


Figure 153: Top layer



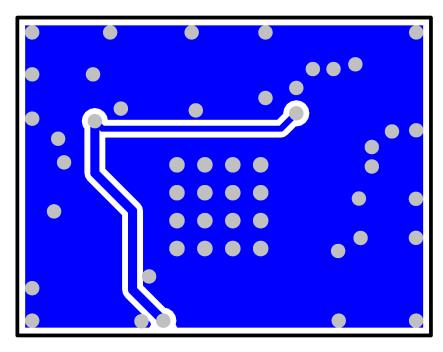


Figure 154: Bottom layer

Important: No components in bottom layer.



8

Recommended operating conditions

The operating conditions are the physical parameters that the chip can operate within.

Symbol	Parameter	Notes	Min.	Nom.	Max.	Units
VDD	Supply voltage, independent of DCDC enable		1.7	3.0	3.6	V
t_{R_VDD}	Supply rise time (0 V to 1.7 V)				60	ms
TA	Operating temperature		-40	25	85	°C

Table 130: Recommended operating conditions

Important: The on-chip power-on reset circuitry may not function properly for rise times longer than the specified maximum.

8.1 WLCSP light sensitivity

WLCSP package variants are sensitive to visible and near infrared light, which means that a final product design must shield the chip properly.

For the WLCSP package variant, the marking side is covered with a light absorbing film, while the side edges of the chip and the ball side must be protected by coating or other means.



9 Absolute maximum ratings

Maximum ratings are the extreme limits to which the chip can be exposed for a limited amount of time without permanently damaging it. Exposure to absolute maximum ratings for prolonged periods of time may affect the reliability of the device.

	Note	Min.	Max.	Unit
Supply voltages				
VDD		-0.3	+3.9	V
VSS			0	V
I/O pin voltage				
V _{I/O} , VDD ≤ 3.6 V		-0.3	VDD + 0.3	V
V _{I/O} , VDD > 3.6 V		-0.3	3.9	V
Radio				
RF input level			10	dBm
Environmental QFN package				
Storage temperature		-40	+125	°C
MSL	Moisture Sensitivity Level		2	
ESD HBM	Human Body Model		4	kV
ESD HBM Class	Human Body Model Class		3A	
ESD CDM	Charged Device Model		1	kV
Environmental WLCSP 2.482 x 2.464 mm pack	age			
Storage temperature		-40	+125	°C
MSL	Moisture Sensitivity Level		1	
ESD HBM	Human Body Model		2	kV
ESD HBM Class	Human Body Model Class		2	
ESD CDM	Charged Device Model		1	kV
Flash memory				
Endurance		10 000		Write/erase cycles
Retention		10 years at 40°C		

Table 131: Absolute maximum ratings





10 Ordering information

This chapter contains information on IC marking, ordering codes, and container sizes.

10.1 IC marking

The nRF52810 package is marked as shown in the following figure.

N	5	2	8	1	0
<p< th=""><th>P></th><th><></th><th>></th><th>*</th><th><p></p></th></p<>	P>	<>	>	*	<p></p>
<y< th=""><th>Y></th><th><w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<></th></y<>	Y>	<w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<>	W>	<l< th=""><th>L></th></l<>	L>

Figure 155: Package marking

10.2 Box labels

The following figures show the box labels used for nRF52810.

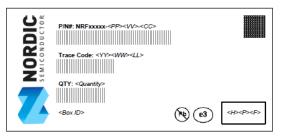


Figure 156: Inner box label

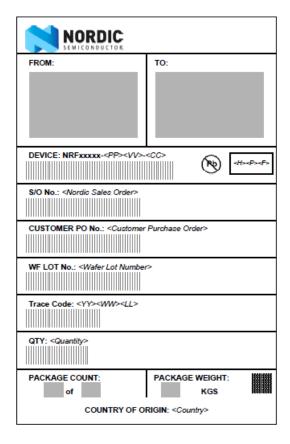


Figure 157: Outer box label

10.3 Order code

The following are the order codes and definitions for nRF52810.

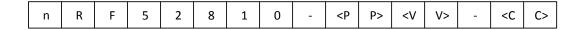


Figure 158: Order code



Abbreviation	Definition and implemented codes	
N52/nRF52	nRF52 Series product	
810	Part code	
<pp></pp>	Package variant code	
<vv></vv>	Function variant code	
<h><p><f></f></p></h>	Build code H - Hardware version code P - Production configuration code (production site, etc.) F - Firmware version code (only visible on shipping container label)	
<yy><ww><ll></ll></ww></yy>	Tracking code YY - Year code WW - Assembly week number LL - Wafer lot code	
<cc></cc>	Container code	

Table 132: Abbreviations

10.4 Code ranges and values

Defined here are the nRF52810 code ranges and values.

<pp></pp>	Package	Size (mm)	Pin/Ball count	Pitch (mm)
QF	QFN	6 x 6	48	0.4
QC	QFN	5 x 5	32	0.5
CA	WLCSP	2.482 x 2.464	33	0.4

Table 133: Package variant codes

<vv></vv>	Flash (kB)	RAM (kB)	Access port protection
AA	192	24	Controlled by hardware
AA-E	192	24	Controlled by hardware and software

Table 134: Function variant codes

<h>></h>	Description
[A Z]	Hardware version/revision identifier (incremental)

Table 135: Hardware version codes



<p></p>	Description
[09]	Production device identifier (incremental)
[A Z]	Engineering device identifier (incremental)

Table 136: Production configuration codes

<f></f>	Description
[A N, P Z]	Version of preprogrammed firmware
[0]	Delivered without preprogrammed firmware

Table 137: Production version codes

<yy></yy>	Description
[0099]	Production year: 2000 to 2099

Table 138: Year codes

<ww></ww>	Description
[152]	Week of production

Table 139: Week codes

<ll></ll>	Description
[AA ZZ]	Wafer production lot identifier

Table 140: Lot codes

<cc></cc>	Description
R7	7" Reel
R	13" Reel
Т	Tray

Table 141: Container codes

10.5 Product options

Defined here are the nRF52810 product options.



Order code	MOQ ³⁵	Comment
nRF52810-QFAA-R7	1000	Not recommended for new designs
nRF52810-QFAA-R	3000	Not recommended for new designs
nRF52810-QFAA-T	490	Not recommended for new designs
nRF52810-QFAA-E-R7	1000	
nRF52810-QFAA-E-R	3000	
nRF52810-QCAA-R7	1500	Not recommended for new designs
nRF52810-QCAA-R	4000	Not recommended for new designs
nRF52810-QCAA-T	490	Not recommended for new designs
nRF52810-QCAA-E-R7	1500	
nRF52810-QCAA-E-R	4000	
nRF52810-CAAA-R7	1500	Not recommended for new designs
nRF52810-CAAA-R	7000	Not recommended for new designs
nRF52810-CAAA-E-R7	1500	
nRF52810-CAAA-E-R	7000	

Table 142: nRF52810 order codes

Order code	Description
nRF52-DK	nRF52832 development kit with tools to support nRF52810 development.

Table 143: Development tools order code



³⁵ Minimum Ordering Quantity

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