RSL10-SENSE-GEVK (and RSL10-SENSE-DB-GEVK) User Guide

Introduction

The **RSL10-SENSE-GEVK** (and RSL10-SENSE-DB-GEVK) is a comprehensive, compact, node-to-cloud IoT sensor platform that allows development of various Bluetooth Low Energy based use cases. Along with the hardware and software, the RSL10-SENSE-GEVK includes a mobile app to interact with sensors and actuators. The board features RSL10, Industry's lowest power Bluetooth® 5 SoC and several sensors from ON Semiconductor and Bosch. By combining motion, environmental, ambient light sensing with the ultra-low power of the Bluetooth 5 Certified RSL10 and will enable customers to realize a new class of battery powered static, mobile and wearable smart sensors targeting consumer and industrial applications in the IoT.

The overall deep sleep consumption of 20 μ A results in a battery life of over 1 year. For further increase in battery life, software configuration wizard allows flexible timing setup as discussed in the following sections.

Variants

There are two SKUs of the RSL10 Sensor kit. Both variants are pre-loaded with an ultra-low power firmware and include a 3 V CR2032 coin cell and a flexible NFC antenna.

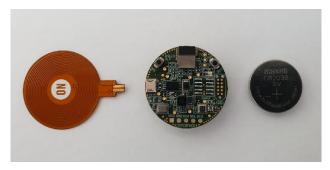


Figure 1.

RSL10–SENSE–GEVK: Firmware can be flashed via 10–pin needle adapter (e.g. TC2050 from Tag–Connect) (not included). The 10–pin header for debugger is not populated on the board.

RSL10–SENSE–DB–GEVK: The "debug" (–DB) version of the board also includes a low cost Segger debugger J–Link LITE CortexM and a USB cable. Users can directly debug/communicate/flash the firmware over the populated–pin header.



ON Semiconductor®

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EVAL BOARD USER'S MANUAL

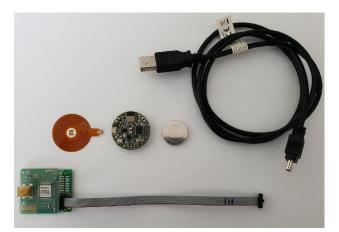


Figure 2.

Scope

The board starts functioning as soon as the coin cell is in place. This document covers the setup, software architecture, documentation and provides instructions on downloading firmware to the board. The details regarding the mobile app and cloud connectivity are not covered in this document.

Default Configuration

In addition to the RSL10 SiP (System-in-Package), the following sensors are present on the board.

- NOA1305, ambient Light sensor
- N24RF64, NFC EEPROM
- BME680, environmental sensor (temperature, humidity, pressure, air quality)
- BHI160 + BMM150, 3-axis accelerometer, gyroscope, magnetometer. Together returnabsolute orientation supported in software
- INMP522 -> ultra-low power microphone for audio applications
- User can insert NFC flexible antenna into dedicated connector and bend underneath the battery holder for custom packaging / cases.

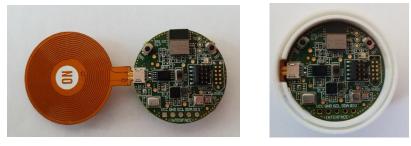


Figure 3.

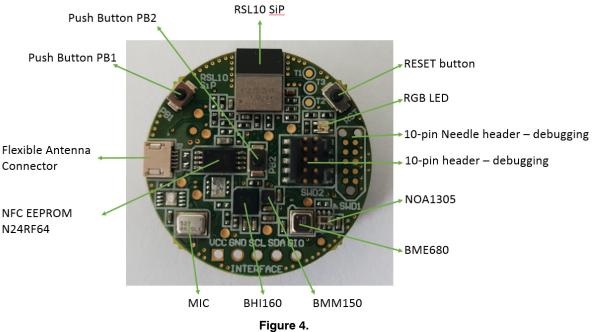


Figure 4

Both kits are shipped with the ultra-low power firmware pre-loaded into the boards.

Powering the Board

To power RSL10–SENSE–GEVK, one has to insert CR2032 (3 V) battery into battery holder located on the bottom side of the board.



Figure 5.

SOFTWARE

The RSL10–SENSE–GEVK boards are, by default, configured with the ultra–low power firmware. For users that want to download different firmware versions, this section details the involved steps.

Prerequisities

- 1. Install 64-bit version of Java from https://www.java.com/en/download/
- 2. Install J–Link Version 6.32i or later from <u>https://www.segger.com/downloads/jlink</u> (select J–Link software and documentation pack)

3. Download and install

"ON Semiconductor IDE Installer" from https://www.onsemi.com/PowerSolutions/product. do?id=RSL10

a.) Download the "RSL10 SDK Getting Started Guide" and RSL10 CMSIS pack under "RSL10 Software Package" from the above site. All of these are highlighted in the picture below. Save the CMSIS pack in a folder, for example, C:\cmsis_packs

Download	RSL10 Getting Started Guide	Download	RSL10 Documentation Package	Download	RSL10 Software Utility Apps
Download	ON Semiconductor IDE Installer	Download	RSL10 Bluetooth Mesh Package	Download	RSL10 LPDSP32 Software Package
Download	RSL10 Software Package	Download	RSL10 USB Dongle BLE Explorer		

Figure 6.

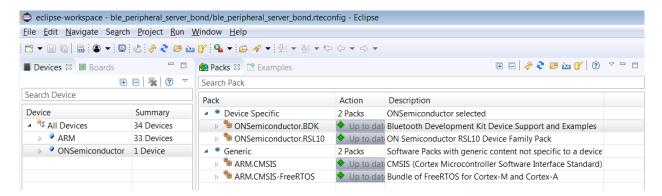
- 4. Download the B–ID CMSIS pack from https://www.onsemi.com/B–IDK and save it in the same folder as the RSL10 CMSIS pack (see 3.a above)
- 5. CMSIS pack at item 4. is dependent on ARM CMSIS pack as well. Please install ARM CMSIS pack 5.5.1 or higher after download from: <u>https://github.com/ARM-software/CMSIS_5/relea</u> <u>ses</u>
- 6. CMSIS pack at item 4. is also dependent on ARM CMSIS – FreeRTOS version 10.2.0 or higher for users exposed to design the code under FreeRTOS with RSL10:

https://github.com/ARM-software/CMSIS-FreeR TOS/releases The next section provides details on importing the downloaded CMSIS packs into the SDK.

Importing CMSIS Packages

1. Launch the RSL10 ON Semiconductor IDE

- NOTE: Please import RSL10 CMSIS pack first as the B-IDK CMSIS pack (step 4 in the Prerequisites section) depends on the RSL10 CMSIS pack (step 3.a) in the Prerequisites section)
 - 2. Refer to Chapter 3 of RSL10 SDK Getting Started Guide (step 3.a) for step-by-step instructions on importing the CMSIS packs.
 - 3. Once all packs are successfully imported, they can be viewed in the CMSIS pack manager perspective as shown below (Figure 7)





Compiling and Flashing of Ultra Low Power Firmware

4. Examples related to RSL10–SENSE–GEVK are highlighted in brackets. Choose the example *Custom Service Firmware with Deep Sleep* (RSL10–SENSE–GEVK)

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Figure 8.

5. Right click and copy the project into workspace

⊳	Custom Service Firmware (BDK-GEVK)						
\triangleright	Custom Service Firmware (RSL10-SENSE-GEVK)						
⊳	Custom Service Firmware with Deep Sleep (RSL10-SENSE-GEVK)						
⊳	IDK Custom Service 🖪 Expand Selected						
⊳	LED Ballast Shield E 🐟 Copy						
⊳	NOA1305 Sensor Example (BDK-GEVK)						



NOTE: Once the example is copied, it can be viewed under Project Explorer. All source files including main are located in the src folder.

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sense_ics_firmware_sleep.rteconfig	330 static void App_StateMachine(void)

Figure 10.

- 6. Now user has to build the project as this creates binaries to be flashed to RSL10-SENSE-GEVK. For the sensor board, there are two options:a.) 1 Debug
 - b.) 2 Release go to hammer icon inside IDE and click Release. Project is automatically build

Debug mode enables user to debug application over serial terminal connected to GPIO pin on expansion connector. It's the option how to fine tune the sleep mode code. RSL10–SENSE–GEVK natively doesn't support serial communication, only RTT over JTAG.

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NOTE: If the binaries are not seen, press F5 (refresh)

Alternatively you can build the project: right click on project under Project Explorer -> Build Configurations -> Set Active -> 2 Release

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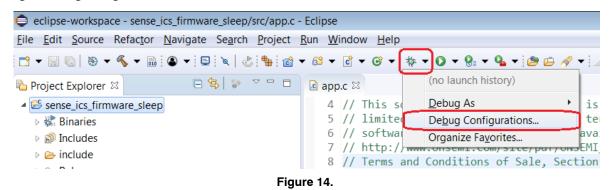
Figure 12.

- 7. Once the build is done, the code is ready to be flashed to the RSL10–SENSE–GEVK.
 - a.) Insert the battery into the board. Mandatory step as it creates the voltage reference for SWD logic signals.
 - b.) Connect the low cost Debugger (RSL10–SENSE–DB–GEVK version) / 10–pin needle adapter with J–LINK (RSL10–SENSE–GEVK version)



Figure 13.

8. Select the project (sense_ics_firmware_sleep), and go to debug configurations as shown below.



a.) Double click GDB Segger J-Link Debugging to create the debug configuration for the selected example.

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type filter text C (/C++ Application C /C++ Attach to Application C /C++ Remote Application C GDB Hardware Debugging C GDB SEGGER J-Link Debugging C GDB SEGGER J-Link Debugging C sense_ics_firmware_sleep Release C Launch Group ► Launch Group (Deprecated)	Main Debugger Startup Source Common Story SVD Path Project:	
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	Build (if required) before launching Build Configuration: Select Automatically © Enable auto build © Disable auto build @ Use workspace settings Configure Workspace Settings	
	Figure 15.	

NOTE: The debug configuration for the selected example is automatically saved and there's no need to re-create it. Make sure you have the Release version of binary (.elf). Click on Search Project and Qualifier returns *Release* in the path. For debugging purposes you can build and switch Debug version as discussed in step 12 a/b.

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Filter matched 10 of 10 iter	Э ОК	Cancel	Reyert Apply Debug Close

Figure 16.

b.) On the Debugger tab, set RSL10 as the device name. Click Debug.

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 C/C++ Postmortem Debugger C/C++ Remote Application 	Executable path: \$(jlink_path)/\$(jlink_gdbserver) Browse Variable
GDB Hardware Debugging GDB OpenOCD Debugging	Actual executable: C/Program Files (x86)/SEGGER/ILink_V632i/ILinkGDBServerCLexe (to change it use the global or workspace preferences pages or the project properties page
GDB SEGGER J-Link Debugging E sense ics_firmware_sleep Release	Device name: RSL10 Supported device name
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	Interface: SWD JTAG
	Initial speed: O Auto Adaptiv Fixed 1000 kHz
	GDB port: 2331
	SWO port: 2332 Verify downloads 🗹 Initialize registers on sta

Figure 17.

9. For application debugging, confirm perspective switch by clicking Yes.

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ialize	This Debug perspective is designed to support application debugging. It incorporates views for displaying the debug stack, variables and breakpoint management.	
"\r\n\ı	Do you want to open this perspective now?	
ialize = NCS30 DEBUG(1 0_PIR_0		

Figure 18.

10. The debug session is now launched. Click Resume (F8) to start the target CPU. Green LED briefly flashes. By default, in Release version is no Logging option and terminal doesn't return useful data. By terminating the session, user closes connection with DBG server.

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Figure 19.

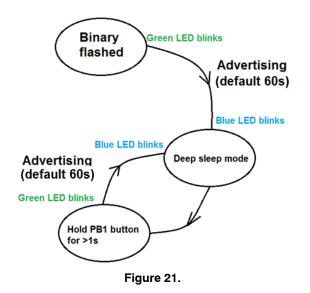
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<pre>22 [22 Device_Initialize(); 24 25 /* Indication - Initialization complete. */ 26 LED_On(LED_GREEN); 27 HAL_Delay(250); 28 LED_Off(LED_GREEN); 29</pre>				 main(void) : i ⁵ App_StateMa Main_Loop(v) 	chine(void) :
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Figure 20.

 Disconnect debugger, download and open the mobile app available under store (Android and iOS). App name is *RSL10 Sense and Control* (www.onsemi.com/b-idk)

IMPORTANT NOTE:

When the board is flashed, Green LED shortly blinks. Board starts BLE advertising only and is visible on the mobile app. When connection with mobile app is not made for next 60s (by default), blue LED blinks and RSL10–SENSE–GEVK goes into deep sleep mode. You can resume operation by holding button PB1 for >1s. Green LED blinks and process repeats. See below the state diagram.



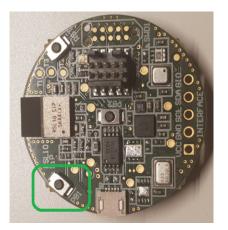


Figure 22.

- 12. User is exposed to set various parameters that have impact on battery longevity. Three main parameters can be configured in CMSIS:a.) BLE Advertising Interval (Default 1000 ms)
 - b.) Advertising stop Timeout (Default 60 s)
 - c.) Wake-up Button Check Interval (Default 1500 ms)

To get into the CMSIS Configuration Wizard, right click on RTE_app_config.h and open CMSIS Configuration Wizard. Change parameters, save the project and build it starting from step 12.

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app_trace.h		I2C Bus Speed	Fast+	4	
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CSN_LP_AO.h		Integration Time [ms]	12.5		
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Figure 23.

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	BLE Advertising Interval [ms] Determines how often to send advertising pac Default: 1000 ms Source Editor [CMSIS Configuration Wizard]	ikets.	19	,



Mobile App Usage

13. Within the Advertising Stop Timeout interval, board is visible on the app screen. RSL10-SENSE-GEVK is advertising only over BLE. When multiple boards (sensor nodes) are present, each has unique MAC address and user selects the desired one -> HB_BLE_Terminal.

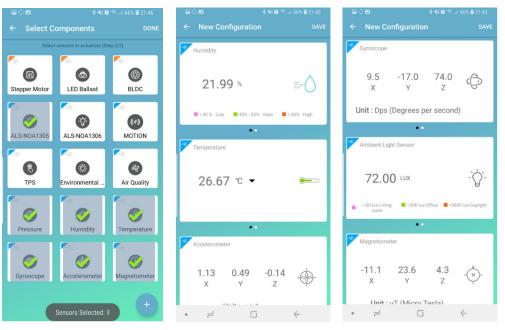


Figure 25.

14. When the appropriate board is selected, one can choose what sensor data to observe. Below are depicted all supported sensors and quantities taken. More simultaneous sensors in place equals more power required.

RSL10–SENSE–GEVK supports also cloud connectivity via the same mobile app that functions as a gateway.

NOTE: Air quality is not supported in this low power mode example due to heating element and consequent need for higher power consumption. However it's available under *BME680* + *BSEC example* or *Custom Service Firmware* in CMSIS.





Ultra-low Power Firmware Modes

- 15. The following are the low power features of above described firmware:
- BDK libraries adapted for use with deep sleep mode of RSL10.
- HAL library for RTC and RTC based low power timer.
- Low power IDK Custom Service nodes for: a.) ALS (NOA1305)
 - b.) Environmental sensing (BME680 + BSEC software)
 - c.) Absolute Orientation (BHI160 + BMM150)
- Automatic on demand sensor activation.
- Automatically stops BLE advertising if no connection is made.
- BLE advertising can be restarted by holding push button (PB1).
- Configurable using RTE configuration header.
 - 16. Environmental Sensing Node (BME680 + BSEC software):
- Provides two sample rates (every 3 seconds or every 5 minutes). By default, due to reduced power consumption, environmental sensors updates each 5 minutes.
- Option to disable IAQ measurement to save power.
- Long term average power consumption:
 - a.) Outputs: Indoor Air Quality, Compensated Temperature, Compensated Humidity, Pressure
 - i. Low Power mode $-900 \,\mu\text{A}$ (3 s sample rate),
 - ii. Ultra-low power mode 90 µA (5 min sample rate)
 - b.) Outputs: Compensated Temperature, Compensated Humidity, Pressure
 - i. < 5.2 μ A (1 s sample rate)

• Gas sensor uses too much power and is not suitable for CR2032 battery powered systems. By default, this feature is disabled in ultra-low power firmware

17. Ambient Light Node (NOA1305):

- Sensor is activated only when ambient light value is requested by peer device.
- Power consumption depends on number of requests received from peer device.
 a.) ~80 μA current draw when sensor is active
- Sensor remains active for 4 measurement cycles (integration times) to stabilize sensor output.
- Integration time and number of cycles are configurable from RTE header.
 - 18. BLE Connection Interval Possible Power savings:
- BLE allows devices to negotiate connection parameter, most notably **Slave Connection Interval**
 - a.) BLE communication always occurs at every connection interval even if the devices do not have anything to exchange (just send empty packets).
 - b.) Configurable from 1.25 ms up to 4000 ms.
 - c.) Bigger Slave Connection Interval -> Less energy consumed by HB.
 - d.) Master (phone) has complete control over used connection interval.
- Android allows only 3 specific interval configurations:
- i. High (11.25 15 ms), Balanced (30 50 ms), Low Power (100 – 125 ms)
- All Android apps do not allow to set connection interval and always force balanced mode.

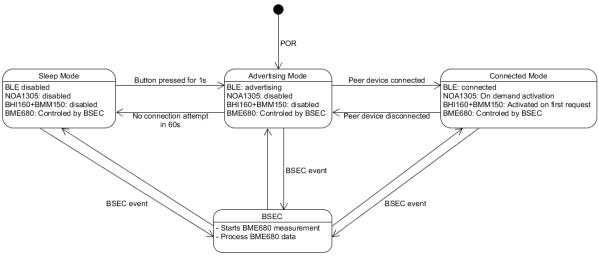


Figure 27.

19. Short term power consumption (100s interval):

- Deep Sleep mode:
 - a.) 1.5 s periodic button check
 - b.) Consumption: 18.7 uA @ 3 V
- Advertising mode:
 c.) 1 Hz BLE advertising interval
 d.) Consumption: 24.5 uA @ 3 V
- Connected mode: e.) Full operation connected to RSL10 Sense & Control:
 - i. ALS: 1 s measurement & report rate ii. Absolute Orientation: 12.5 Hz measure rate, 1 s
 - report rate iii. Environmental data (IAQ disabled): 5 min. measure rate, 3 s report rate
 - f.) Consumption: ~3000 uA @ 3 V
 - 20. Low power firmware block diagram. The diagram in Figure 27 depicts detailed high level operation of ultra-low power firmware.

Compiling and Flashing of the Rest Examples Attached to RSL10–SENSE

In this section user is guided on how to flash software for all remaining examples in the CMSIS pack. The procedure is similar as for Ultra-Low power FW. Let's pick up *On-board Sensor Tests* that enables microphone functionality and returns sensors data into console.

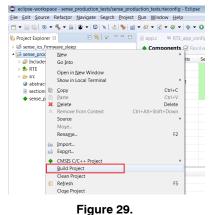
21. Right click and copy the project into workspace



Figure 28.

22. Right click on the project and build it

NOTE: If the binaries are not seen, press F5 (refresh)



- -igule 29.
- 23. Once the project is build, go to Debug configurations, double click on GDB SEGGER J-Link Debugging that automatically creates Session and import binaries ready to be flashed. Click on Debug button.

rteconfig -	Eclip	se					
ow <u>H</u> elp							
- © -	脊	• • •	9 - 9	- 2) 🕞 🔗 🤜		
≔ RTE_a	1 sense ics firmware sleen Release						fig ដ
onents		<u>D</u> ebug	, As				•
Jonenta		Debug Configurations					
Compone		Organ	ize Fa <u>v</u> or	ites			sion
.10	_				ONSemic	onduc	
:			RUK		ONSemic	onduc	1/10
			Figure	e 30.			

Name: sense_production_tests Debug	purce 🔲 Common 🛱 SVD Path			
Project: Browse sense_production_tests Browse C/C++ Application: C/C++				
Variables Search Project Build (if required) before launching Build Configuration: Select Automatically				
Use workspace settings	Configure Workspace Settings			
	Reyert	Apply		
	C/C++ Application: Debug\sense_production_tests.elf Build (if required) before launching Build Configuration; Select Automatica © Enable auto build	C/C++ Application: Debug\sense_production_testself UariablesSearch Project Build (if required) before launching Build Configuration: Select Automatically © Enable auto build © Disable auto build © Use workspace settings Configure Workspace Settings.		

Figure 31.

24. When the debug session is launched, click on Resume button (F8).

	• ↔ ↔ • { • { • { • { • • •			Quick Access 🔡 🛱
Debug 12 Resume (15) E sense_production, tests Debug (GDB SEGGER J-Link Debugging)	74 JF	% i ♥ ♥ ■ □ O+ Variable 32 ♥ Breakpoints III Re Name ↔ retval ↔ timestamp		Value -738672248 756375673
app.c ■ RTE_app_config.h ◆ sense_production_tests.rteconfig @ main.c 82 79 int32_t retval = 0;		4		Outline 22 문 년 전 文 • 북 · · · bme680_status : imi32_t
<pre>80 /* Initialize BDK library, set system clock (default 80Hz). */ 82 BDK_InitializeFreq(HAL_CLK_COMP_80HZ); 83 HAL_IZC_SetBusSpeed(HAL_IZC_BUS_SPEED_FAST); 84 85 /* Initialize all LEDs */ 85 (LED_Initialize(LED_BEED); 87 LED_Initialize(LED_BEED); 81 LED_Initialize(LED_BUE); 89 9 /* Test LEDs are working */ 81 84 84 85 85 85 85 85 85 85 85 85 85 85 85 85</pre>		Ξ.	 bme680_output: struct BME680_ENV_Data bhy_status : int32_t bhy_ointation: bhy_data_vector_t eeprom_status: int32_t eeprom_iZCEeprom eeprom_ef: const uint3_t] eeprom_ref_length: const uint3_t dmic_value: int32_t 	
91 LED_On(LED_RED);			-	 dmic_min : int32_t main(void) : int



Logging/Debugging

This is the next step after launching the session. For logging/debugging the downloaded Firmware, either J–Link RTT or Eclipse Console may be used. This section provides instructions for both.

Using J-Link RTT

- 25. After step 30 is done, open J–Link RTT viewer 6.32i (should be installed when J–Link software package was installed per Step 2)
- 26. Select USB / Existing session and click OK. As the debugger is in operation, easiest way is to utilize Existing Session.

J-Link RTT Viewer V6.32i Configurati 💌
Connection to J-Link
© <u>U</u> SB
<u> Т</u> СР/IР
Existing Session Auto reconnect
OK Cancel

Figure 33.

J-Link RTT Viewer V6.34c		
Eile Terminals Input Log Log All Terminals Terr	J-Link RTT Viewer V6.34c Configuration ?	
LOG: J-Link RTT Vie LOG: Terminal 0 add	<u>USB</u> <u>Serial No</u> ICP/IP <u>Existing Session</u>	
	Specify Target Device	
	Script file (optional)	
	Target Interface & Speed	
	SWD • 4000 kHz •	
	RTT Control Block Auto Detection <u>A</u> ddress Search Range	
	OK Cancel	Enter Clear
Ready.		0.00 MB

Figure 34.

27. RTT prompts you to select the appropriate microcontroller. Select RSL10 and click OK. The serial terminal is ready to use and the events from RSL10 can be observed by clicking the All Terminals Window.

J-Link RTT View	ver V6.34c		• ×
<u>Eile</u> <u>T</u> erminals <u>I</u>	Input Logging <u>H</u> elp		
Log All Termina	als Terminal 0		
LOG: J-Link LOG: Termina	RTT Viewer V6.34c: Logging started. al 0 added.		
🔜 J-Lin	nk V6.34c Device Selection	X	
0	The selected device "UNSPECIFIED" is unknown to this version of the J-Link software Please make sure that at least the core J-Link shall connect to, is selected. Proper device selection is required to use the J-Link internal flash loaders for flash downlaad or unlimited flash breakpoints. For some devices which require a special handling, selection of the correct device is		
		Enter	Clear
Ready.	Establishing J-Link connection 0.00 M	В	

Figure 35.

GGER J-Link V	6.34c - Ta	arget device set	tings				— ×
Filter Manufacturer *	•	Device RSL10	Core	,	•	Little	endian 💌
Manufacturer	Device		Core		NumCo	Flash size	RAM size
ON Semicond	RSL10		Cortex-N	13 r2p1	1	390 KB	24 KB
s flash downloa	e is not re d, modifice	quired for most d ation of flash mem y (Flash Breakpo	ory during a deb				<u>C</u> ancel
case of doubt :	select the	first entry in the lis	t "Unspecified E	levice".			<u>0</u> K

Figure 36.

28. Console returns the actual values from all sensors assembled on the board

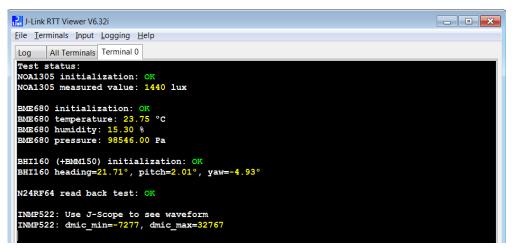
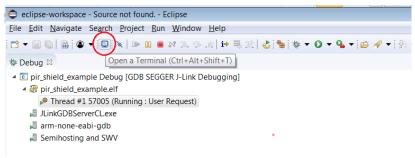


Figure 37.

Using Eclipse RTT Console

29. Click the Open a Terminal Icon





30. Enter the values shown below and launch the session. The incoming events are printed on the terminal window.

Caunch Terminal	
Choose terminal:	Telnet Terminal 🔻
Settings	
Hosts:	
Host:	localhost
Port:	19021 🔹
Timeout (sec):	5
End of Line:	CR+NUL -
Encoding: Defa	ult (ISO-8859-1) 🔹
?	OK Cancel

Figure 39.

31. Terminal window returns the same data format as using the J–LINK RTT viewer.

<pre>85 /* Initialize all LEDs */ 86 LED_Initialize(LED_RED); 87 LED_Initialize(LED_GREEN); 97 00 000000000000000000000000000000000</pre>
(
🗳 Console 🧔 Tasks 🖹 Problems 📀 Executables 🍠 Terminal 🛛 🗟 Debugger Console 🔋 Memory
E Telnet localhost (1/30/19 10:19 AM)
Test status: NOA1305 initialization: OK
NOA1305 measured value: 1478 lux
BME680 initialization: OK BME680 temperature: 23.92 °C BME680 humidity: 14.92 % BME680 pressure: 98550.00 Pa
BHI160 (+BMM150) initialization: OK BHI160 heading=359.12°, pitch=1.41°, yaw=-4.83°
N24RF64 read back test: OK
INMP522: Use J-Scope to see waveform INMP522: dmic_min=-7277, dmic_max=32767
Connected - Encoding: Default (ISO-8859-1)

Figure 40.

Using J-scope for MIC data visualization 32. Launch Segger J-Scope and click on New project

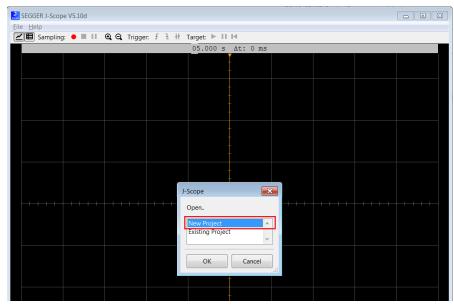


Figure 41.

33. When your Eclipse debug session is launched, use existing Session (alternatively you use USB), set Sample rate every 10us and load elf. file (binary) that is located under Eclipse–workspace and Debug folder.

V5.10d		
● ■ II @ Q Trigger. f t # Target: ▶ II M		Quick Acce
05.000 s Δt: 0 ms	gisters 🛋 Modules 🔀 Peripherals	1 1
	Туре	Value
J-Scope Configuration	Open Elf file	Search Debug
Connection to J-Link	Organize • New folder	≣ • □ 0
CEP/IP Existing Session Sampling Source RTT (synchron) HSS (asynchron) Sampling Rate	Loracle_jre_usage J.p2 AppData Contacts Desktop Downloads Lecipse-workspace	Date modified Type 1/30/2019 10:03 A File folder 1/30/2019 10:09 A File folder 1/30/2019 10:09 A ELF File
Sample every 10 µs Sample Rate: 100.0kHz Elf File	metadata RemoteSystemsTempFile sense_jroduction_tests settings Debug RTE	
	File game: sense_production_tests.elf	▼ ELF files (.elf;axf;out) ▼ Qpen Cancel

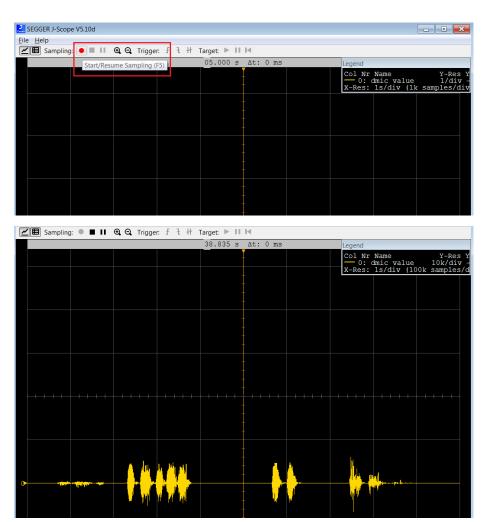
Figure 42.

34. J–Scope symbol section opens. Check dmic_value box and hit OK button.

J-Se	cope Symbol Selection		×
	2		
Na	ame	Add Symbol	
	/src/main.c		<u>^</u>
Ŧ	bhy_orientation [struct]	Expand to select items	11
	bhy_status [long]		
Œ	bme680_output [struct BME680_ENV_Da	ta Expand to select items	
	bme680_status [long]		
	dmic_max [long]		
-	dmic min [long]		
	dmic_value [long]		
Ŧ	eeprom [struct]	Expand to select items	-
	(7		
	nic_value [long]		
	re: 4 Byte(s) pe: long		
	ope: Global		
Fi	ilter Symbols by name		\otimes
	OK Cancel		
L	Calicer		

Figure 43.

35. Visualization of the audio is started when Red Sampling button is pushed (or F5.)





Configuration Setup

System settings can be configured directly from within the CMSIS pack. Each example is equipped with basic system configuration that covers three main categories. These are accessible in the RTE/BDK folder within the project. Each system configuration starts with "RTE_". As shown below,

opening the RTE_... header files using the CMSIS configuration wizard (right click on the header file), displays the configuration table. Various application specific parameters can be set. This allows pre-configuration of RSL10 without the need for explicit programming.

<u>File Edit Source Refactor Navigate Search Project</u>	<u>R</u> un <u>W</u> indow <u>H</u> elp						
🖆 🕶 🔚 🏀 🛞 🕶 🔦 🕶 📾 🕥 🕶 😂 🔌 🕹 🍓 :	• 🚳 • 🖻 • 🚱 • 🔯 •	•	8 • % • 🙋	🗁 🔗 🔻	R I		▼ 🖓 ▼ 🏷 🗘 ▼ 🖒 ▼
ြာ Project Explorer 🛛 🕞 🤹 🗢 🗖	ⓓ app.c ≔ RTE_app_cc	onfig.h	sense_ics	_firmware.	rtecor	nfig 🛙	
 Sense_bme680_bsec Sense ics firmware 	💠 Components 🗹 Res	olve					
Sense_ics_firmware_sleep	Software Components RSL10		Variant Vendor ONSemico		anduc	Version	Description ARM Cortex-M3 48 MHz, 24 k
 ▲ Sense_production_tests ▶ Some Debug ▲ Debug ▲ RTE ▶ BLE ▲ Board_Support ▶ BHI160_NDOF.c [ONSemiconductor.RSL10-SE ▶ Buby_support.c [ONSemiconductor.RSL10-SE 	 ▷ ◆ BLE ▷ ◆ Board Support ▷ ◆ Components ▷ ◆ Device 			ONSemico	onduc	c 1.4.0	RSL10 BLE stack implementat Board Support package for R Platform independent drivers
 BME680_ENV.c [ONSemiconductor.RSL10-SE Botton_api.c [ONSemiconductor.RSL10-SENS C2CEeprom.c [ONSemiconductor.RSL10-SENS C2CEeprom.c [ONSemiconductor.RSL10-SENSE-C NOA1305_ALS.c [ONSemiconductor.RSL10 NOA1305_ALS.c [ONSemiconductor.RSL10 M RTE_HB_BHI160_NDOF.h [ONSemiconductor.RSL10 	New Open			•			
 RTE_HB_BME680_ENV.h [ONSemiconduct RTE_HB_Button.h [ONSemiconductor.RSL1 RTE_HB_NOA1305_ALS.h [ONSemiconduct Components Device RTE_Components.h Strc abstract.html sections.ld sense_production_tests.rteconfig 	Open With Show in Local Terminal Copy Paste Delete Remove from Context Source Moye Rename	Ctrl+C Ctrl+V Delete Ctrl+Alt+Shift+Down			Generic Te Text Editor System Ed In-Place Ec Default Ed Other	nfiguration Wizard	

Figure 45.

A brief description on the header files is given in the wizard for various sensors.

CMSIS Configuration Wizard		CMSIS Configuration Wizard	CMSIS Configuration Wizard						
Option	Value	Option	Option Value						
BHI160 Interrupt Source	3	 Temperature measurement 		Option	Value				
	0	Oversampling	2x	 Enable Interrupt generation for NOA1305 					
	1	 Pressure measurement 		Interrupt signal DIO Pad	13				
	2	Oversampling	2x	DIO Interrupt Source	2				
	3 3	 Humidity measurement 							
		Oversampling	2x						
		IIR Filter Size	1						
			0						
			• 1						
			3						
			7						
			15						
			31						
			63						
			127						
BHI160 Interrupt Source Determines which of the four DIO Interrup Default: 2	ot Configuration registers to use for BHI	1160. Reduces the bandwidth of temperature a See section '3.3.4 IIR filter' of BME680 dat	nd pressure output signals and increases the resolution of output data to 20	Interrupt signal DIO Pad DIO used for NOA1305 interrupt signal. Dit. Default: DIO13 for HB-GEVK board.					



DOCUMENTATION

Detailed documentation of all functions, code, APIs, HALs is part of the CMSIS package. Every use case (for a particular daughter card, service, etc.) copied into the workspace has its own manual with key description in the abstract.html page. URL Information and orderable part numbers are also provided as shown below.

*.rteconfig

The *.rteconfig file lists the software components within the CMSIS pack. To access the components, double click *.rteconfig file. Extensive help is provided under the description tab.

<u>Eile E</u> dit <u>S</u> ource Refac <u>t</u> or <u>N</u> avigate Se <u>a</u> rch <u>P</u> ro	oject <u>R</u> un <u>W</u> indow <u>H</u> elp					
🖆 🕶 🔛 🐚 🛞 🕶 🔦 🕶 📾 👁 🕶 🗳 👟	@ ▼ @ ▼ @ ▼ ☆ ▼	0 -	9: • 9 . • 😕	🗀 🛷 🔻 📴 🗉	n : M	▼ 刻 ▼ ╬ ◆ ▼ ♀ ▼
🔓 Project Explorer 🛛 📄 🗣 👘 🔻 🖻	° □	.h	sense_product	ion_tests.rteconfi	g 🛙	
b 😂 sense_bme680_bsec	🚸 Components 🗹 Re					
Sense_ics_firmware	Software Components	Sel	Variant	Vendor	Version	Description
sense_ics_firmware_sleep	RSI 10		· and ·	ONSemiconduc	. croiteri	ARM Cortex-M3 48 MHz, 24 kB RAM, 384 kB ROM
sense_production_tests	A SEL		BDK	ONSemiconduc	140	RSL10 BLE stack implementations for BDK based applications.
Includes	Peripheral Serve	r	DOK	ONSerniconduc	1.4.0	A NEED BLE stack implementations for BDR based applications.
Debug	 Peripheral Server A Solution Support 		RSI 10-SENSE-G	ONSemiconduc	1.4.0	Board Support package for RSL10-SENSE-GEVK and RSL10-SENSE-DB-GEVK evaluatio
▶ 🌭 RTE	ICS Protocol					
Src	▲ ◆ Libraries					
 abstract.html sections.ld 	BHI160 NDC	FØ				Nine degrees of freedom sensor hub
sections.id sense_production_tests.rteconfig	BME680 BSE					Measure indoor air quality, temperature, humidity and atmospheric pressure using BM
sense_production_tests.rteconing	BME680 ENV					Measure temperature, humidity and atmospheric pressure using BME680 environmenta
	Button					On-board Push Button support
	I2C Eeprom					Generic library for reding / writing I2C EEPROM memories.
	✓ LED					On-board LED support
	NOA1305_AI	s⊠				Measure ambient light level using NOA1305 ambient light sensor
	Pinmap					Defines pin mappings that will be used by HAL drivers
	A & Components					Platform independent drivers for various external components and IC.
	Ambient Light S	e				
	Environmental 5	ie				
	LED Driver					
	Motion Sensor					
	Motor Driver					
	A I Device					
	BDK					BDK software components compatible with all evaluation boards.
	Bluetooth Profil	e				
	Libraries					
	Startup		release	ONSemiconduc	2.3.18	RSL10-CMSIS Startup Library and Include Folders (libcmsis)



Main Help Page The main help page is accessible via Device/BDK, visible for all use cases in *.rteconfig file. It's further divided into various modules as shown below.

Software Components	Sel.	Variant	Vendor	Version	Description
RSL10			ONSemiconduc		ARM Cortex-M3 48 MHz, 32 kB RAM, 384 kB ROM
BLE		BDK	ONSemiconduc	1.0.0	RSL10 BLE stack implementations for BDK based applications.
Board Support		BDK-GEVK	ONSemiconduc	1.0.0	Board Support package for BDK-GEVK evaluation board.
Components					Platform independent drivers for various external components and IC.
🔺 💠 Device					
🔺 🌳 BDK					BDK software components compatible with all evaluation boards.
AES			ONSemiconduc	1.0.0	AES module from mbedTLS
Event Callback			ONSemiconduc	1.0.0	Library for assigning of multiple callbacks to events.
HAL			ONSemiconduc	1.0.0	Peripheral HAL drivers and RSL10 configuration
Output Redirection		SEGGER RTT	ONSemiconduc	1.0.0	Redirects standart output calls using SEGGER RTT
Scheduling			ONSemiconduc	1.0.0	Management layer for Event Kernel Application Task
Software Timer			ONSemiconduc	1.0.0	Allows to create multiple timer events while using only single hardware timer.
Bluetooth Profiles					
Libraries					
Startup		release	ONSemiconduc	2.1.10	RSL10-CMSIS Startup Library and Include Folders (libcmsis)

Figure 48.

ON Semiconductor [®] BDK v1.0.0 Bluetooth LE Development Kit for RSL10
BDK
Abstraction layers for RSL10 Bluetooth Development Kit based applications. More
Modules
COMPONENTS
TASK_APP Management Application Task management & custom event scheduling.
Event Callback Library for attaching multiple callback functions (listeners) to single event source.
HAL Peripheral Hardware Abstraction Layer for RSL10.
Software Timer Allows creation of unlimited number of software timers with Ticker, Timeout and Timer functionality.
ANSI Terminal Color support Bring color to your terminal screen.
Target Evaluation board specific definitions.
API
Bluetooth Low Energy Library for handling of BLE functionality and libraries of supported BLE profiles.

Figure 49.

Sub-sections may be expanded for further information (Ex: HAL interfaces shown below)

HAL Dik	
eripheral Hardware Abstraction Layer for RSL10. More	
Nodules	
Clock Configurations Defines possible clock configurations for proper operation of BDK.	
I2C I2C interface for communication with connected shields.	
SPI SPI interface for communication with connected shields.	
UART UART interface for communication with connected shields.	
<i>N</i> acros	
#define HAL_TIME_RESOLUTION_US (1000)	
#define HAL_TIME_ELAPSED_SINCE(start_timestamp) (HAL_Time() - start_timestamp)	
#define HAL OK (0)	

Figure 50.

CMSIS also provides software timers and applications task manager abstraction layers to enable management of specific tasks and timing within the event kernel.



IVI	oddies
	COMPONENTS
	TASK_APP Management
	Application Task management & custom event scheduling.
	Event Callback
	Library for attaching multiple callback functions (listeners) to single event source.
	HAL
	Peripheral Hardware Abstraction Layer for RSL10.
T	Software Timer
	Allows creation of unlimited number of software timers with Ticker, Timeout and Timer functionality.
	ANSI Terminal Color support
	Bring color to your terminal screen.
	Target
	Evaluation board specific definitions.
	API
	Bluetooth Low Energy
	Library for handling of BLE functionality and libraries of supported BLE profiles.

Figure 51.

Every example attached to the RSL10–SENSE–GEVK is equipped with addl. help under *abstract.html*

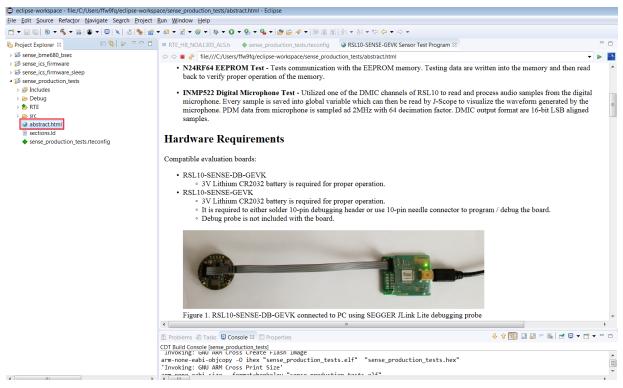


Figure 52.

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