MICROCHIP dsPIC33EPXXXGS70X/80X FAMILY

16-Bit Digital Signal Controllers for Digital Power Applications with Interconnected High-Speed PWM, ADC, PGA and Comparators

Operating Conditions

- 3.0V to 3.6V, -40°C to +85°C, DC to 70 MIPS
- 3.0V to 3.6V, -40°C to +125°C, DC to 60 MIPS

Flash Architecture

- Dual Partition Flash Program Memory with LiveUpdate:
 - Supports programming while operating
 - Supports partition soft swap

Core: 16-Bit dsPIC33E CPU

- Code-Efficient (C and Assembly) Architecture
- Two 40-Bit Wide Accumulators
- Single-Cycle (MAC/MPY) with Dual Data Fetch
- Single-Cycle Mixed-Sign MUL plus Hardware Divide
- 32-Bit Multiply Support
- Four Additional Working Register Sets (reduces context switching)

Clock Management

- ±0.9% Internal Oscillator
- · Programmable PLLs and Oscillator Clock Sources
- Fail-Safe Clock Monitor (FSCM)
- Independent Watchdog Timer (WDT)
- Fast Wake-up and Start-up

Power Management

- Low-Power Management modes (Sleep, Idle, Doze)
- · Integrated Power-on Reset and Brown-out Reset
- 0.5 mA/MHz Dynamic Current (typical)
- 20 µA IPD Current (typical)

High-Speed PWM

- Eight PWM Generators (two outputs per generator)
- Individual Time Base and Duty Cycle for each PWM
- 1.04 ns PWM Resolution (frequency, duty cycle, dead time and phase)
- Supports Center-Aligned, Redundant, Complementary and True Independent Output modes
- · Independent Fault and Current-Limit Inputs
- Output Override Control
- PWM Support for AC/DC, DC/DC, Inverters, PFC and Lighting

Advanced Analog Features

- High-Speed ADC module:
 - 12-bit with four dedicated SAR ADC cores and one shared SAR ADC core
 - Configurable resolution (up to 12-bit) for each ADC core
 - Up to 3.25 Msps conversion rate per channel at 12-bit resolution
 - 11 to 22 single-ended inputs
 - Dedicated result buffer for each analog channel
 - Flexible and independent ADC trigger sources
 - Two digital comparators
 - Two oversampling filters for increased resolution
- Four Rail-to-Rail Comparators with Hysteresis:
 - Dedicated 12-bit Digital-to-Analog Converter (DAC) for each analog comparator
 - Up to two DAC reference outputs
 - Up to two external reference inputs
- Two Programmable Gain Amplifiers:
 - Single-ended or independent ground reference
 - Five selectable gains (4x, 8x, 16x, 32x and 64x)
 - 40 MHz gain bandwidth

Interconnected SMPS Peripherals

- Reduces CPU Interaction to Improve Performance
- Flexible PWM Trigger Options for ADC Conversions
- High-Speed Comparator Truncates PWM (15 ns typical):
 - Supports Cycle-by-Cycle Current-mode control
 - Current Reset mode (variable frequency)

Timers/Output Compare/Input Capture

- Five 16-Bit and up to Two 32-Bit Timers/Counters
- Four Output Compare (OC) modules, Configurable as Timers/Counters
- · Four Input Capture (IC) modules

Communication Interfaces

- Two UART modules (15 Mbps):
 - Supports LIN/J2602 protocols and IrDA®
- Three Variable Width SPI modules with Operating modes:
 - 3-wire SPI
 - 8x16 or 8x8 FIFO mode
 - I²S mode
- Two I²C modules (up to 1 Mbaud) with SMBus Support
- Up to Two CAN modules
- Four-Channel DMA

Input/Output

- Constant-Current Source (10 µA nominal)
- Sink/Source up to 12 mA/15 mA, respectively; Pin-Specific for Standard VOH/VOL
- 5V Tolerant Pins
- · Selectable, Open-Drain Pull-ups and Pull-Downs
- External Interrupts on all I/O Pins
- Peripheral Pin Select (PPS) to allow Function Remap with Six Virtual I/Os

Qualification and Class B Support

- AEC-Q100 REVG (Grade 1, -40°C to +125°C)
- Class B Safety Library, IEC 60730
- The 6x6x0.55 mm UQFN Package is Designed and Optimized to ease IPC9592B 2nd Level Temperature Cycle Qualification

Debugger Development Support

- In-Circuit and In-Application Programming
- Five Program and Three Complex Data Breakpoints
- IEEE 1149.2 Compatible (JTAG) Boundary Scan
- Trace and Run-Time Watch

Digital Peripherals

- Four Configurable Logic Cells
- Peripheral Trigger Generator

		rtes		(GPIO)		Re	ma	ppal	ole F	Perip	hera	als					12- A[r		Source	
Device	Pins	Program Memory Bytes	RAM (Bytes)	General Purpose I/O (Timers ⁽¹⁾	Input Capture	Output Compare	UART	IdS	PWM ⁽²⁾	External Interrupts ⁽³⁾	CAN	Reference Clock	l ² C	CLC	ÐLd	Analog Inputs	S&H Circuits	V9d	DMA	Analog Comparator	DAC Output	Constant-Current Sou	Packages
dsPIC33EP128GS702	28	128K	8K	20	5	4	4	2	3	8x2	4	0	1	2	4	1	11	5	2	0	4	1	1	SOIC, QFN-S, UQFN
dsPIC33EP64GS804	44	64K	8K	33	5	4	4	2	3	8x2	4	2	1	2	4	1	17	5	2	4	4	1	1	
dsPIC33EP128GS704	44	128K	8K	33	5	4	4	2	3	8x2	4	0	1	2	4	1	17	5	2	0	4	1	1	QFN, TQFP
dsPIC33EP128GS804	44	128K	8K	33	5	4	4	2	3	8x2	4	2	1	2	4	1	17	5	2	4	4	1	1	i Qi i
dsPIC33EP64GS805	48	64K	8K	33	5	4	4	2	3	8x2	4	2	1	2	4	1	17	5	2	4	4	1	1	
dsPIC33EP128GS705	48	128K	8K	33	5	4	4	2	3	8x2	4	0	1	2	4	1	17	5	2	0	4	1	1	TQFP
dsPIC33EP128GS805	48	128K	8K	33	5	4	4	2	3	8x2	4	2	1	2	4	1	17	5	2	4	4	1	1	
dsPIC33EP64GS806	64	64K	8K	51	5	4	4	2	3	8x2	4	2	1	2	4	1	22	5	2	4	4	2	1	
dsPIC33EP128GS706	64	128K	8K	51	5	4	4	2	3	8x2	4	0	1	2	4	1	22	5	2	0	4	2	1	TQFP
dsPIC33EP128GS806	64	128K	8K	51	5	4	4	2	3	8x2	4	2	1	2	4	1	22	5	2	4	4	2	1	
dsPIC33EP64GS708	80	64K	8K	67	5	4	4	2	3	8x2	4	0	1	2	4	1	22	5	2	0	4	2	1	
dsPIC33EP64GS808	80	64K	8K	67	5	4	4	2	3	8x2	4	2	1	2	4	1	22	5	2	4	4	2	1	TQFP
dsPIC33EP128GS708	80	128K	8K	67	5	4	4	2	3	8x2	4	0	1	2	4	1	22	5	2	0	4	2	1	IQFP
dsPIC33EP128GS808	80	128K	8K	67	5	4	4	2	3	8x2	4	2	1	2	4	1	22	5	2	4	4	2	1	

Note 1: The external clock for Timer1, Timer2 and Timer3 is remappable.

2: PWM4 through PWM8 are remappable on 28/44/48-pin devices; on 64-pin devices, only PWM7/PWM8 are remappable.

3: External interrupts, INT0 and INT4, are not remappable.

Pin Diagrams

28-Pin SOIC

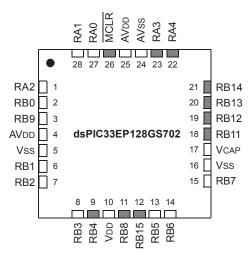
MCLR	1	\bigcirc)	28	h	AVdd
RA0	2			27		AVss
RA1	3			26		RA3
RA2	4	-		25		RA4
RB0	5	dsP		24		RB14
RB9	6	Ĩ		23		RB13
AVDD	7	dsPIC33EP128GS702		22		RB12
Vss	8	P12		21		RB11
RB1	9	Ĝ		20		VCAP
RB2	10	S7(19		Vss
RB3	11	22		18		RB7
RB4	12			17		RB6
Vdd	13			16		RB5
RB8	14			15		RB15

Pin	Pin Function	Pin	Pin Function
1	MCLR	15	PGEC3/SCL2/RP47/RB15
2	AN0/CMP1A/PGA1P1/RP16/RA0	16	TDO/AN19/PGA2N2/ RP37 /RB5
3	AN1/CMP1B/PGA1P2/PGA2P1/ RP17 /RA1	17	PGED1/TDI/AN20/SCL1/RP38/RB6
4	AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2	18	PGEC1/AN21/SDA1/ RP39 /RB7
5	AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0	19	Vss
6	AN4/CMP2C/CMP3A/ISRC4/RP41/RB9	20	VCAP
7	AVDD	21	TMS/PWM3H/ RP43 /RB11
8	Vss	22	TCK/PWM3L/ RP44 /RB12
9	OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1	23	PWM2H/ RP45 /RB13
10	OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾	24	PWM2L/ RP46 /RB14
11	PGED2/DACOUT1/AN18/INT0/RP35/RB3	25	PWM1H/ RP20 /RA4
12	PGEC2/ADTRG31/EXTREF1/ RP36 /RB4	26	PWM1L/ RP19 /RA3
13	VDD	27	AVss
14	PGED3/SDA2/FLT31/RP40/RB8	28	AVDD

Legend: Shaded pins are up to 5 VDC tolerant.

Pin Diagrams (Continued)

28-Pin QFN-S, UQFN



Pin	Pin Function	Pin	Pin Function
1	AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2	15	PGEC1/AN21/SDA1/ RP39 /RB7
2	AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0	16	Vss
3	AN4/CMP2C/CMP3A/ISRC4/RP41/RB9	17	VCAP
4	AVDD	18	TMS/PWM3H/ RP46 /RB11
5	Vss	19	TCK/PWM3L/ RP44 /RB12
6	OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1	20	PWM2H/ RP45 /RB13
7	OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/ RP34 /RB2 ⁽¹⁾	21	PWM2L/ RP46 /RB14
8	PGED2/DACOUT1/AN18/INT0/RP35/RB3	22	PWM1H/ RP20 /RA4
9	PGEC2/ADTRG31/EXTREF1/ RP36 /RB4	23	PWM1L/ RP19 /RA3
10	VDD	24	AVss
11	PGED3/SDA2/FLT31/ RP40 /RB8	25	AVDD
12	PGEC3/SCL2/RP47/RB15	26	MCLR
13	TDO/AN19/PGA2N2/ RP37 /RB5	27	AN0/CMP1A/PGA1P1/ RP16 /RA0
14	PGED1/TDI/AN20/SCL1/RP38/RB6	28	AN1/CMP1B/PGA1P2/PGA2P1/RP17/RA1

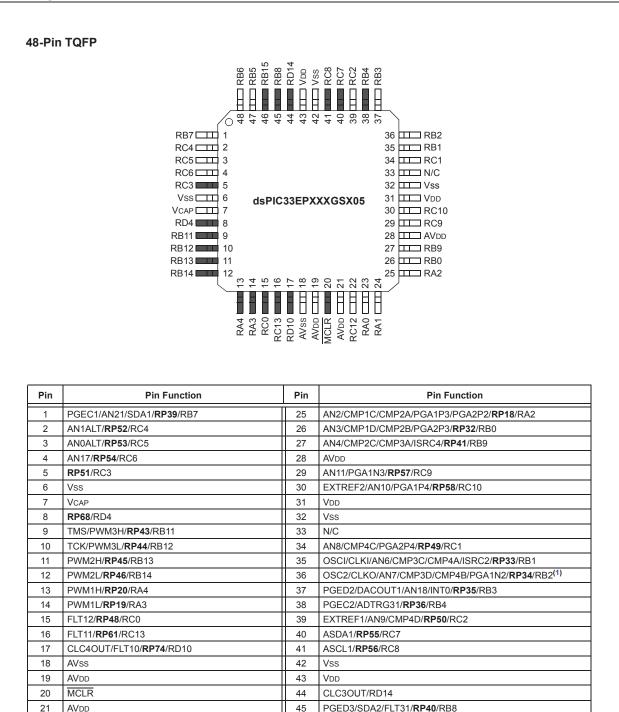
Legend: Shaded pins are up to 5 VDC tolerant.

Pin Diagrams (Continued)

	44 ■ ● 44 ■ ● 44 ■ ● 44 ■ RB6 785 785 785 7815		33 CC8 36 RC7 38 RB4 34 RB3 34 RB3 34 RB3
	RB7 ☐ 1 RC4 ☐ 2 RC5 ☐ 3 RC6 ☐ 4 RC3 ☐ 5 Vss ☐ 6 dsPIC		33 [RB2 32 [RB1 31 [RC1 30 [Vss 29 [VDD KXGSX04 28 [RC10
	VCAP 7 RB11 8 RB12 9 RB13 10 RB14 11	10 (0 5 (27 RC9 26 AVDD 25 RB9 24 RB0 23 RA2
	1 1 2 2 1 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2	10 13	
	RA4 RC0	AVSS AVDD AVDD	AVDD RC12 RA1 RA1
Pin	Pin Function PGEC1/AN21/SDA1/ RP39 /RB7	Pin 23	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/ RP18 /RA2
		_	Pin Function
1	PGEC1/AN21/SDA1/ RP39 /RB7	23	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/ RP18 /RA2
1 2	PGEC1/AN21/SDA1/ RP39 /RB7 AN1ALT/ RP52 /RC4	23 24	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/ RP18 /RA2 AN3/CMP1D/CMP2B/PGA2P3/ RP32 /RB0
1 2 3	PGEC1/AN21/SDA1/ RP39 /RB7 AN1ALT/ RP52 /RC4 AN0ALT/ RP53 /RC5	23 24 25 26 27	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9
1 2 3 4 5 6	PGEC1/AN21/SDA1/ RP39 /RB7 AN1ALT/ RP52 /RC4 AN0ALT/ RP53 /RC5 AN17/ RP54 /RC6 RP51 /RC3 Vss	23 24 25 26 27 28	Pin FunctionAN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0AN4/CMP2C/CMP3A/ISRC4/RP41/RB9AVDDAVDDAN11/PGA1N3/RP57/RC9EXTREF2/AN10/PGA1P4/RP58/RC10
1 2 3 4 5 6 7	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vcap	23 24 25 26 27 28 29	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD
1 2 3 4 5 6 7 8	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vcap TMS/PWM3H/RP43/RB11	23 24 25 26 27 28 29 30	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN1/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS
1 2 3 4 5 6 7 8 9	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12	23 24 25 26 27 28 29 30 31	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS AN8/CMP4C/PGA2P4/RP49/RC1
1 2 3 4 5 6 7 8 9 10	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vcap TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13	23 24 25 26 27 28 29 30 31 31 32	Pin FunctionAN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0AN4/CMP2C/CMP3A/ISRC4/RP41/RB9AVDDAVDDAN11/PGA1N3/RP57/RC9EXTREF2/AN10/PGA1P4/RP58/RC10VDDVssAN8/CMP4C/PGA2P4/RP49/RC1OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1
1 2 3 4 5 6 7 8 9 10 11	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12	23 24 25 26 27 28 29 30 31	Pin FunctionAN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0AN4/CMP2C/CMP3A/ISRC4/RP41/RB9AVDDAVDDAN11/PGA1N3/RP57/RC9EXTREF2/AN10/PGA1P4/RP58/RC10VDDVssAN8/CMP4C/PGA2P4/RP49/RC1
1 2 3 4 5 6 7 8 9 10	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vcap TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14	23 24 25 26 27 28 29 30 31 31 32 33	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾
1 2 3 4 5 6 7 7 8 9 10 11 12	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14 PWM1H/RP20/RA4 PWM1L/RP19/RA3	23 24 25 26 27 28 29 30 31 31 32 33 33 34	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVbb AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 Vbb AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3
1 2 3 4 5 6 7 8 9 10 11 12 13	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14 PWM1H/RP20/RA4	23 24 25 26 27 28 29 30 31 31 32 33 34 35	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVbb AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 Vbb AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3 PGEC2/ADTRG31/RP36/RB4
1 2 3 4 5 6 7 8 9 10 11 12 13 14	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss Vcap TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14 PWM1L/RP19/RA3 FLT12/RP48/RC0	23 24 25 26 27 28 29 30 31 31 32 33 34 35 36	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3 PGEC2/ADTRG31/RP36/RB4 EXTREF1/AN9/CMP4D/RP50/RC2
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VCAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14 PWM1L/RP19/RA3 FLT12/RP48/RC0 FLT11/RP61/RC13	23 24 25 26 27 28 29 30 31 31 32 33 34 35 36 37	Pin FunctionAN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0AN4/CMP2C/CMP3A/ISRC4/RP41/RB9AVDDAN11/PGA1N3/RP57/RC9EXTREF2/AN10/PGA1P4/RP58/RC10VDDVSSAN8/CMP4C/PGA2P4/RP49/RC1OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3PGEC2/ADTRG31/RP36/RB4EXTREF1/AN9/CMP4D/RP50/RC2ASDA1/RP55/RC7
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2L/RP45/RB13 PWM2L/RP46/RB14 PWM1L/RP19/RA3 FLT12/RP48/RC0 FLT11/RP61/RC13 AVss	23 24 25 26 27 28 29 30 31 31 32 33 33 34 35 36 36 37 38	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3 PGEC2/ADTRG31/RP36/RB4 EXTREF1/AN9/CMP4D/RP50/RC2 ASDA1/RP56/RC7 ASCL1/RP56/RC8
1 2 3 4 5 6 7 8 9 10 11 11 12 13 14 15 16 17	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14 PWM1L/RP19/RA3 FLT12/RP48/RC0 FLT11/RP61/RC13 AVss AVbd	23 24 25 26 27 28 29 30 31 31 32 33 33 34 35 36 37 38 39	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3 PGEC2/ADTRG31/RP36/RB4 EXTREF1/AN9/CMP4D/RP50/RC2 ASDA1/RP56/RC8 Vss
1 2 3 4 5 6 7 7 8 9 9 10 11 12 13 14 15 16 17 18	PGEC1/AN21/SDA1/RP39/RB7 AN1ALT/RP52/RC4 AN0ALT/RP53/RC5 AN17/RP54/RC6 RP51/RC3 Vss VcAP TMS/PWM3H/RP43/RB11 TCK/PWM3L/RP44/RB12 PWM2H/RP45/RB13 PWM2L/RP46/RB14 PWM1L/RP19/RA3 FLT12/RP48/RC0 FLT11/RP61/RC13 AVss AVDD MCLR	23 24 25 26 27 28 29 30 31 31 32 33 33 34 35 36 37 38 39 40	Pin Function AN2/CMP1C/CMP2A/PGA1P3/PGA2P2/RP18/RA2 AN3/CMP1D/CMP2B/PGA2P3/RP32/RB0 AN4/CMP2C/CMP3A/ISRC4/RP41/RB9 AVDD AN11/PGA1N3/RP57/RC9 EXTREF2/AN10/PGA1P4/RP58/RC10 VDD VSS AN8/CMP4C/PGA2P4/RP49/RC1 OSCI/CLKI/AN6/CMP3C/CMP4A/ISRC2/RP33/RB1 OSC2/CLKO/AN7/CMP3D/CMP4B/PGA1N2/RP34/RB2 ⁽¹⁾ PGED2/DACOUT1/AN18/INT0/RP35/RB3 PGEC2/ADTRG31/RP36/RB4 EXTREF1/AN9/CMP4D/RP50/RC2 ASDA1/RP55/RC7 ASCL1/RP56/RC8 VDD

Legend: Shaded pins are up to 5 VDC tolerant.

Pin Diagrams (Continued)



AN1/CMP1B/PGA1P2/PGA2P1/RP17/RA1 Legend: Shaded pins are up to 5 VDC tolerant.

AN14/PGA2N3/RP60/RC12

AN0/CMP1A/PGA1P1/RP16/RA0

RPn represents remappable peripheral functions. See Table 11-12 and Table 11-13 for the complete list of remappable sources. At device power-up (POR), a pulse with an amplitude around 2V and a duration greater than 500 µs, may be observed on this Note 1: device pin independent of pull-down resistors. It is recommended not to use this pin as an output driver unless the circuit being driven can endure this active duration.

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PGEC3/SCL2/RP47/RB15

TDO/AN19/PGA2N2/RP37/RB5

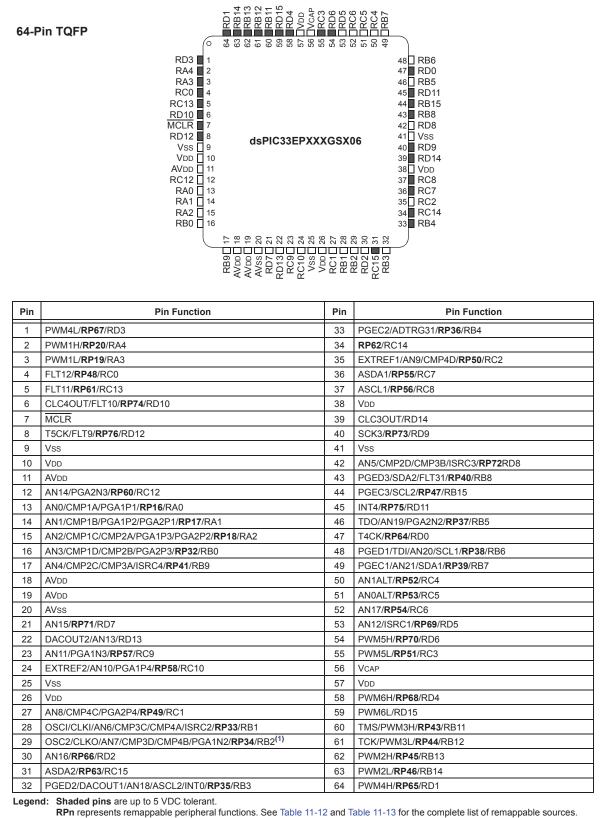
PGED1/TDI/AN20/SCL1/RP38/RB6

22

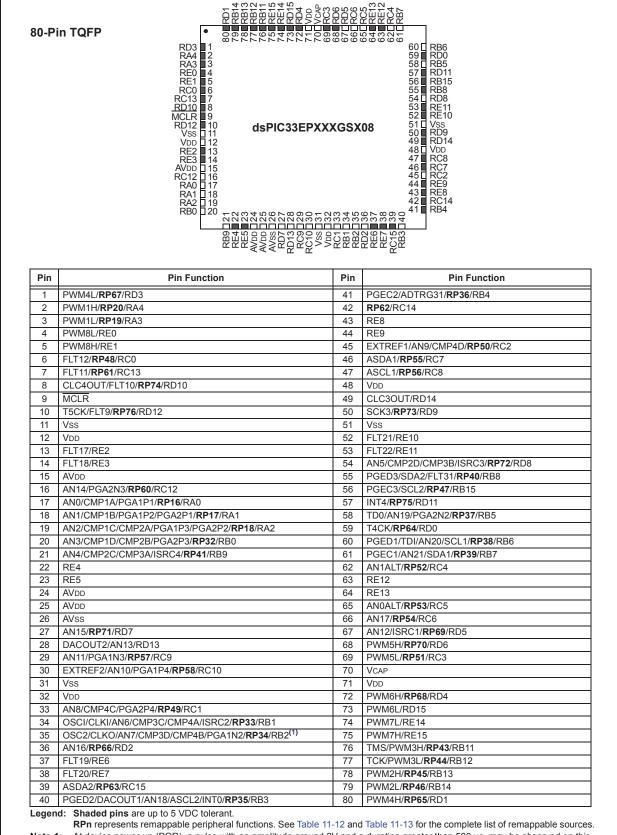
23

24

Pin Diagrams (Continued)



Pin Diagrams (Continued)



Note 1: At device power-up (POR), a pulse with an amplitude around 2V and a duration greater than 500 µs, may be observed on this device pin independent of pull-down resistors. It is recommended not to use this pin as an output driver unless the circuit being driven can endure this active duration.

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An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

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Referenced Sources

This device data sheet is based on the following individual chapters of the *"dsPIC33/PIC24 Family Reference Manual"*. These documents should be considered as the general reference for the operation of a particular module or device feature.

Note 1: To access the documents listed below, browse to the documentation section of the dsPIC33EPXXXGS70X/80X product page of the Microchip website (www.microchip.com) or select a family reference manual section from the following list.

> In addition to parameters, features and other documentation, the resulting page provides links to the related family reference manual sections.

- "dsPIC33E Enhanced CPU" (DS70005158)
- "dsPIC33E/PIC24E Program Memory" (DS70000613)
- "Data Memory" (DS70595)
- "Dual Partition Flash Program Memory" (DS70005156)
- "Flash Programming" (DS70609)
- "Reset" (DS70602)
- "Interrupts" (DS70000600)
- "Direct Memory Access (DMA)" (DS70348)
- "Oscillator Module" (DS70005131)
- "Watchdog Timer and Power-Saving Modes" (DS70615)
- "I/O Ports" (DS70000598)
- "Timers" (DS70362)
- "Input Capture with Dedicated Timer" (DS70000352)
- "Output Compare with Dedicated Timer" (DS70005159)
- "High-Speed PWM Module" (DS70000323)
- "Peripheral Trigger Generator (PTG)" (DS70000669)
- "Serial Peripheral Interface (SPI) with Audio Codec Support" (DS70005136)
- "Inter-Integrated Circuit (I²C)" (DS70000195)
- "Universal Asynchronous Receiver Transmitter (UART)" (DS70000582)
- "Configurable Logic Cell (CLC)" (DS70005298)
- "12-Bit High-Speed, Multiple SARs A/D Converter (ADC)" (DS70005213)
- "Enhanced Controller Area Network (ECAN™)" (DS70353)
- "High-Speed Analog Comparator Module" (DS70005128)
- "Programmable Gain Amplifier (PGA)" (DS70005146)
- "Device Configuration" (DS70000618)
- "Watchdog Timer and Power-Saving Modes" (DS70615)
- "CodeGuard™ Intermediate Security" (DS70005182)
- "Programming and Diagnostics" (DS70608)

NOTES:

1.0 DEVICE OVERVIEW

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive resource. To complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

This document contains device-specific information for the dsPIC33EPXXXGS70X/80X Digital Signal Controller (DSC) devices.

dsPIC33EPXXXGS70X/80X devices contain extensive Digital Signal Processor (DSP) functionality with a high-performance, 16-bit MCU architecture.

Figure 1-1 shows a general block diagram of the core and peripheral modules. Table 1-1 lists the functions of the various pins shown in the pinout diagrams.

FIGURE 1-1: dsPIC33EPXXXGS70X/80X FAMILY BLOCK DIAGRAM

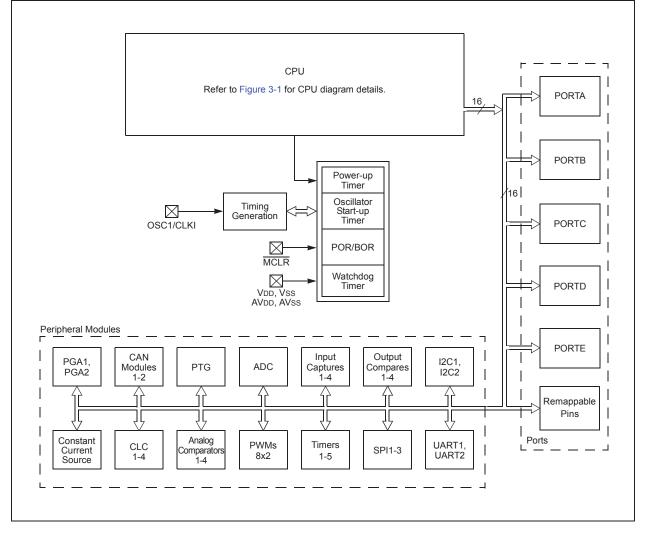


TABLE 1-1: PINOUT I/O DESCRIPTIONS

Pin Name ⁽¹⁾	Pin Type	Buffer Type	PPS	Description
AN0-AN21		Analog	No	Analog input channels.
AN0ALT-AN1ALT	I	Analog	No	Alternate analog input channels.
C1RXR	Ι	ST	Yes	CAN1 receive.
C2RXR	1	ST	Yes	CAN2 receive.
C1TX	0	ST	Yes	CAN1 transmit.
C2TX	0	ST	Yes	CAN2 transmit.
CLKI	I	ST/	No	External clock source input. Always associated with OSC1 pin
		CMOS		function.
CLKO	0		No	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes. Always associated with OSC2 pin function.
OSC1	I	ST/ CMOS	No	Oscillator crystal input. ST buffer when configured in RC mode; CMOS otherwise.
OSC2	I/O	_	No	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes.
CLC1OUT	0	DIG	Yes	CLC1 output.
CLC2OUT	0	DIG	Yes	CLC2 output.
CLC3OUT	0	DIG	No ⁽⁴⁾	CLC3 output.
CLC4OUT	0	DIG	No ⁽⁴⁾	CLC4 output.
REFCLKO	0	—	Yes	Reference clock output.
IC1-IC4	I	ST	Yes	Capture Inputs 1 through 4.
OCFA	I	ST	Yes	Compare Fault A input (for compare channels).
OC1-OC4	0	—	Yes	Compare Outputs 1 through 4.
INT0	I.	ST	No	External Interrupt 0.
INT1		ST	Yes	External Interrupt 1.
INT2		ST	Yes	External Interrupt 2.
INT4		ST	Yes	External Interrupt 4.
RA0-RA4	I/O	ST	No	PORTA is a bidirectional I/O port.
RB0-RB15	I/O	ST	No	PORTB is a bidirectional I/O port.
RC0-RC15	I/O	ST	No	PORTC is a bidirectional I/O port.
RD0-RD15	I/O	ST	No	PORTD is a bidirectional I/O port.
RE0-RE15	I/O	ST	No	PORTE is a bidirectional I/O port.
T1CK	I.	ST	Yes	Timer1 external clock input.
T2CK	I	ST		Timer2 external clock input.
T3CK		ST	Yes	Timer3 external clock input.
T4CK		ST	No	Timer4 external clock input.
T5CK		ST	No	Timer5 external clock input.
U1CTS		ST	Yes	UART1 Clear-to-Send.
U1RTS	0		Yes	UART1 Ready-to-Send.
U1RX		ST	Yes	
U1TX	0		Yes	UART1 transmit.
BCLK1	0	ST	Yes	UART1 IrDA [®] baud clock output.
Legend: CMOS = C ST = Schm PPS = Peri	itt Trigg	jer input	with CN	
110-101	Pricial			

1: Not all pins are available in all package variants. See the "Pin Diagrams" section for pin availability.

2: PWM4H/L through PWM8H/L are fixed on dsPIC33EPXXXGS708/808 devices. PWM4H/L through PWM6H/L are fixed on dsPIC33EPXXXGS706/806 devices.

3: The SCK3 pin is fixed on dsPIC33EPXXXGS706/806 and dsPIC33EPXXXGS708/808 devices.

4: PPS is available on dsPIC33EPXXXGS702 devices only.

U2CTS U2RTS U2RX U2TX BCLK2	 0 0	ST —	Yes	LIADT2 Clear to Sand
U2RX U2TX BCLK2	I	—		UART2 Clear-to-Send.
U2TX BCLK2			Yes	UART2 Ready-to-Send.
BCLK2	0	ST	Yes	UART2 receive.
		_	Yes	UART2 transmit.
0.01//	0	ST	Yes	UART2 IrDA baud clock output.
SCK1	I/O	ST	Yes	Synchronous serial clock input/output for SPI1.
SDI1	Ι	ST	Yes	SPI1 data in.
SDO1	0	—	Yes	SPI1 data out.
SS1	I/O	ST	Yes	SPI1 slave synchronization or frame pulse I/O.
	I/O	ST	Yes	Synchronous serial clock input/output for SPI2.
SDI2	Ι	ST	Yes	SPI2 data in.
SDO2	0	—	Yes	SPI2 data out.
SS2	I/O	ST	Yes	SPI2 slave synchronization or frame pulse I/O.
SCK3	I/O	ST	Yes ⁽³⁾	Synchronous serial clock input/output for SPI3.
SDI3	Ι	ST	Yes	SPI3 data in.
SDO3	0	—	Yes	SPI3 data out.
SS3	I/O	ST	Yes	SPI3 slave synchronization or frame pulse I/O.
SCL1	I/O	ST	No	Synchronous serial clock input/output for I2C1.
SDA1	I/O	ST	No	Synchronous serial data input/output for I2C1.
ASCL1	I/O	ST	No	Alternate synchronous serial clock input/output for I2C1.
ASDA1	I/O	ST	No	Alternate synchronous serial data input/output for I2C1.
SCL2	I/O	ST	No	Synchronous serial clock input/output for I2C2.
SDA2	I/O	ST	No	Synchronous serial data input/output for I2C2.
ASCL2	I/O	ST	No	Alternate synchronous serial clock input/output for I2C2.
ASDA2	I/O	ST	No	Alternate synchronous serial data input/output for I2C2.
TMS	1	ST	No	JTAG Test mode select pin.
ТСК	i	ST	No	JTAG test clock input pin.
TDI	i i	ST	No	JTAG test data input pin.
TDO	0	—	No	JTAG test data output pin.
FLT1-FLT8	1	ST	Yes	PWM Fault Inputs 1 through 8.
FLT9-FLT12	i	ST	No	PWM Fault Inputs 9 through 12.
FLT17-FLT22	i	ST	No	PWM Fault Inputs 17 through 22.
FLT31	Ì	ST	No	PWM Fault Input 31 (Class B Fault).
PWM1L-PWM3L	0		No	PWM Low Outputs 1 through 3.
PWM1H-PWM3H	0	_	No	PWM High Outputs 1 through 3.
PWM4L-PWM8L ⁽²⁾	0	_	Yes	PWM Low Outputs 4 through 8.
PWM4H-PWM8H ⁽²⁾	0	_	Yes	PWM High Outputs 4 through 8.
SYNCI1, SYNCI2	I.	ST	Yes	PWM Synchronization Inputs 1 and 2.
SYNCO1, SYNCO2	0	—	Yes	PWM Synchronization Outputs 1 and 2.

TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

 Legend:
 CMOS = CMOS compatible input or output
 Analog = Analog input
 P = Power

 ST = Schmitt Trigger input with CMOS levels
 O = Output
 I = Input

 PPS = Peripheral Pin Select
 O = Output
 I = Input

1: Not all pins are available in all package variants. See the "Pin Diagrams" section for pin availability.

2: PWM4H/L through PWM8H/L are fixed on dsPIC33EPXXXGS708/808 devices. PWM4H/L through PWM6H/L are fixed on dsPIC33EPXXXGS706/806 devices.

3: The SCK3 pin is fixed on dsPIC33EPXXXGS706/806 and dsPIC33EPXXXGS708/808 devices.

4: PPS is available on dsPIC33EPXXXGS702 devices only.

TABLE 1-1:	PINOUT I/O DESCRIPTIONS (CONTINUED)
-------------------	-------------------------------------

Pin Name ⁽¹⁾	Pin Type	Buffer Type	PPS	Description
CMP1A-CMP4A	I	Analog	No	Comparator Channels 1A through 4A inputs.
CMP1B-CMP4B	I	Analog	No	Comparator Channels 1B through 4B inputs.
CMP1C-CMP4C	I	Analog	No	Comparator Channels 1C through 4C inputs.
CMP1D-CMP4D	Ι	Analog	No	Comparator Channels 1D through 4D inputs.
ACMP1-ACMP4	0	—	Yes	Analog Comparator Outputs 1-4.
DACOUT1, DACOUT2	0		No	DAC Output Voltages 1 and 2.
EXTREF1, EXTREF2	Ι	Analog	No	External Voltage Reference Inputs 1 and 2 for the Reference DACs.
PGA1P1-PGA1P4	I	Analog	No	PGA1 Positive Inputs 1 through 4.
PGA1N1-PGA1N3	I	Analog	No	PGA1 Negative Inputs 1 through 3.
PGA2P1-PGA2P4	I	Analog	No	PGA2 Positive Inputs 1 through 4.
PGA2N1-PGA2N3	I	Analog	No	PGA2 Negative Inputs 1 through 3.
ADTRG31	I	ST	No	External ADC trigger source.
PGED1	I/O	ST	No	Data I/O pin for Programming/Debugging Communication Channel 1.
PGEC1	I.	ST	No	Clock input pin for Programming/Debugging Communication Channel 1.
PGED2	I/O	ST	No	Data I/O pin for Programming/Debugging Communication Channel 2.
PGEC2	I	ST	No	Clock input pin for Programming/Debugging Communication Channel 2.
PGED3	I/O	ST	No	Data I/O pin for Programming/Debugging Communication Channel 3.
PGEC3	I	ST	No	Clock input pin for Programming/Debugging Communication Channel 3.
MCLR	I/P	ST	No	Master Clear (Reset) input. This pin is an active-low Reset to the device.
AVdd	Р	Р	No	Positive supply for analog modules. This pin must be connected at all times.
AVss	Р	Р	No	Ground reference for analog modules. This pin must be connected at all times.
Vdd	Р		No	Positive supply for peripheral logic and I/O pins.
VCAP	Р		No	CPU logic filter capacitor connection.
Vss	Р	_	No	Ground reference for logic and I/O pins.
Legend: CMOS = CN	/IOS co	ompatible	e input o	or output Analog = Analog input P = Power

 Legend:
 CMOS = CMOS compatible input or output
 Analog = Analog input

 ST = Schmitt Trigger input with CMOS levels
 O = Output

 PPS = Peripheral Pin Select
 O = Output

1: Not all pins are available in all package variants. See the "Pin Diagrams" section for pin availability.

2: PWM4H/L through PWM8H/L are fixed on dsPIC33EPXXXGS708/808 devices. PWM4H/L through PWM6H/L are fixed on dsPIC33EPXXXGS706/806 devices.

3: The SCK3 pin is fixed on dsPIC33EPXXXGS706/806 and dsPIC33EPXXXGS708/808 devices.

4: PPS is available on dsPIC33EPXXXGS702 devices only.

I = Input

2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT DIGITAL SIGNAL CONTROLLERS

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

2.1 Basic Connection Requirements

Getting started with the dsPIC33EPXXXGS70X/80X family requires attention to a minimal set of device pin connections before proceeding with development. The following is a list of pin names which must always be connected:

- All VDD and Vss pins (see Section 2.2 "Decoupling Capacitors")
- All AVDD and AVSS pins regardless if ADC module is not used (see Section 2.2 "Decoupling Capacitors")
- VCAP (see Section 2.3 "CPU Logic Filter Capacitor Connection (VCAP)")
- MCLR pin (see Section 2.4 "Master Clear (MCLR) Pin")
- PGECx/PGEDx pins used for In-Circuit Serial Programming[™] (ICSP[™]) and debugging purposes (see Section 2.5 "ICSP Pins")
- OSC1 and OSC2 pins when external oscillator source is used (see Section 2.6 "External Oscillator Pins")

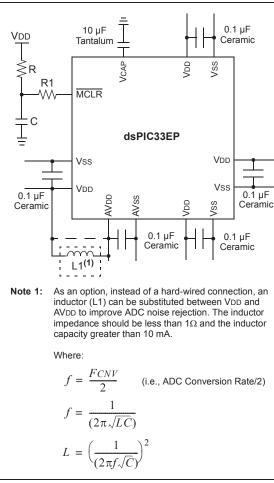
2.2 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD and AVSS is required.

Consider the following criteria when using decoupling capacitors:

- Value and type of capacitor: Recommendation of 0.1 μ F (100 nF), 10-20V. This capacitor should be a low-ESR and have resonance frequency in the range of 20 MHz and higher. It is recommended to use ceramic capacitors.
- Placement on the printed circuit board: The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is within one-quarter inch (6 mm) in length.
- Handling high-frequency noise: If the board is experiencing high-frequency noise, above tens of MHz, add a second ceramic-type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 μ F to 0.001 μ F. Place this second capacitor next to the primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible. For example, 0.1 μ F in parallel with 0.001 μ F.
- Maximizing performance: On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB track inductance.

FIGURE 2-1: RECOMMENDED MINIMUM CONNECTION



2.2.1 TANK CAPACITORS

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits, including DSCs, to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device and the maximum current drawn by the device in the application. In other words, select the tank capacitor so that it meets the acceptable voltage sag at the device. Typical values range from 4.7 μ F to 47 μ F.

2.3 CPU Logic Filter Capacitor Connection (VCAP)

A low-ESR (< 0.5 Ω) capacitor is required on the VCAP pin, which is used to stabilize the voltage regulator output voltage. The VCAP pin must not be connected to VDD and must have a capacitor greater than 4.7 μ F (10 μ F is recommended), 16V connected to ground. The type can be ceramic or tantalum. See Section 30.0 "Electrical Characteristics" for additional information.

The placement of this capacitor should be close to the VCAP pin. It is recommended that the trace length not exceed one-quarter inch (6 mm). See Section 27.4 "On-Chip Voltage Regulator" for details.

2.4 Master Clear (MCLR) Pin

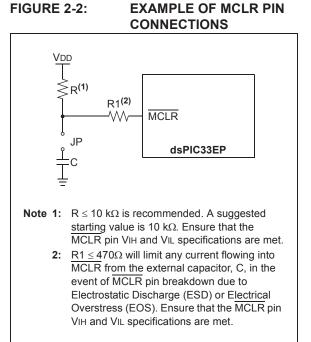
The MCLR pin provides two specific device functions:

- Device Reset
- Device Programming and Debugging.

During device programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the $\overline{\text{MCLR}}$ pin. Consequently, specific voltage levels (VIH and VIL) and fast signal transitions must not be adversely affected. Therefore, specific values of R and C will need to be adjusted based on the application and PCB requirements.

For example, as shown in Figure 2-2, it is recommended that the capacitor, C, be isolated from the MCLR pin during programming and debugging operations.

Place the components as shown in Figure 2-2, within one-quarter inch (6 mm) from the MCLR pin.



2.5 ICSP Pins

The PGECx and PGEDx pins are used for ICSP and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes and capacitors on the PGECx and PGEDx pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin Voltage Input High (VIH) and Voltage Input Low (VIL) requirements.

Ensure that the "Communication Channel Select" (i.e., PGECx/PGEDx pins) programmed into the device matches the physical connections for the ICSP to MPLAB[®] PICkit[™] 3, MPLAB ICD 3, or MPLAB REAL ICE[™].

For more information on MPLAB ICD 2, MPLAB ICD 3 and REAL ICE connection requirements, refer to the following documents that are available on the Microchip website.

- "Using MPLAB[®] ICD 3 In-Circuit Debugger" (poster) (DS51765)
- *"Development Tools Design Advisory"* (DS51764)
- "MPLAB[®] REAL ICE[™] In-Circuit Emulator User's Guide for MPLAB X IDE" (DS50002085)
- *"Using MPLAB[®] REAL ICE™ In-Circuit Emulator"* (poster) (DS51749)

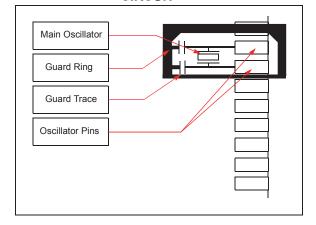
2.6 External Oscillator Pins

Many DSCs have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator. For details, see **Section 9.0 "Oscillator Configuration"** for details.

The oscillator circuit should be placed on the same side of the board as the device. Also, place the oscillator circuit close to the respective oscillator pins, not exceeding one-half inch (12 mm) distance between them. The load capacitors should be placed next to the oscillator itself, on the same side of the board. Use a grounded copper pour around the oscillator circuit to isolate them from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed. A suggested layout is shown in Figure 2-3.

FIGURE 2-3: SI

SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT



Oscillator Value Conditions on 2.7 **Device Start-up**

If the PLL of the target device is enabled and configured for the device start-up oscillator, the maximum oscillator source frequency must be limited to 3 MHz < Fin < 5.5 MHz to comply with device PLL start-up conditions. This means that if the external oscillator frequency is outside this range, the application must start up in the FRC mode first. The default PLL settings, after a POR with an oscillator frequency outside this range, will violate the device operating speed.

Once the device powers up, the application firmware can initialize the PLL SFRs, CLKDIV and PLLFBD, to a suitable value, and then perform a clock switch to the Oscillator + PLL clock source. Note that clock switching must be enabled in the device Configuration Word.

2.8 Unused I/Os

Unused I/O pins should be configured as outputs and driven to a logic low state.

Alternatively, connect a 1k to 10k resistor between Vss and unused pins, and drive the output to logic low.

2.9 **Targeted Applications**

- Power Factor Correction (PFC)
 - Interleaved PFC
 - Critical Conduction PFC
 - Bridgeless PFC
- DC/DC Converters
 - Buck, Boost, Forward, Flyback, Push-Pull
 - Half/Full-Bridge
 - Phase-Shift Full-Bridge
- Resonant Converters
- DC/AC
 - Half/Full-Bridge Inverter
 - Resonant Inverter

Examples of typical application connections are shown in Figure 2-4 through Figure 2-6.

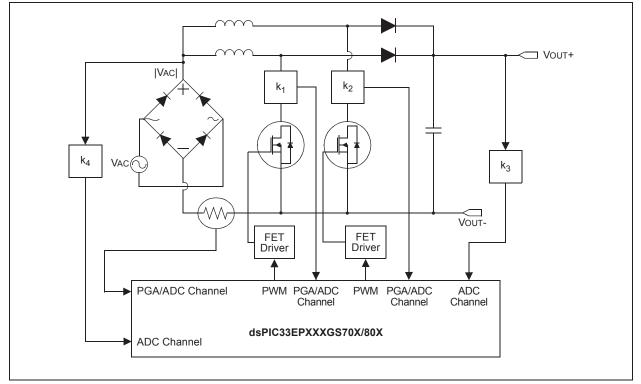


FIGURE 2-4: **INTERLEAVED PFC**

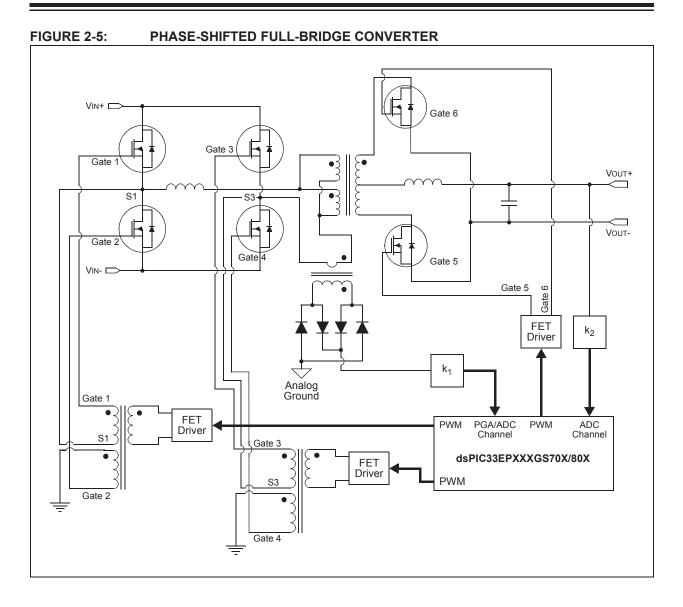
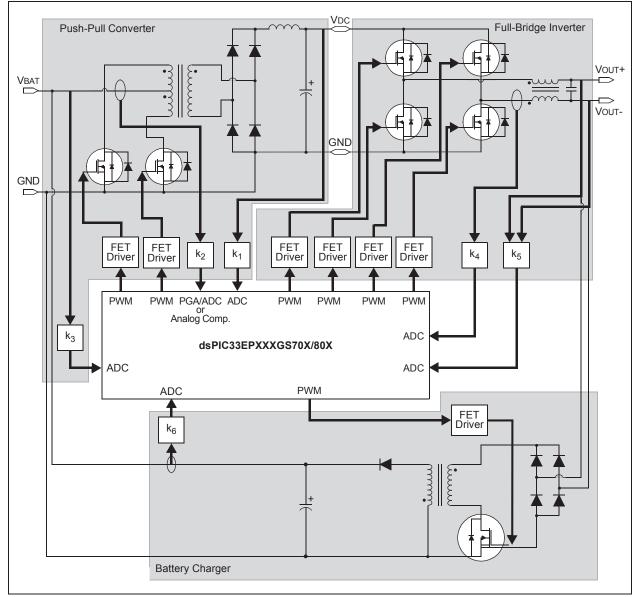


FIGURE 2-6: OFF-LINE UPS



3.0 CPU

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "dsPIC33E Enhanced CPU" (DS70005158) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set, including significant support for Digital Signal Processing (DSP). The CPU has a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M x 24 bits of user program memory space.

An instruction prefetch mechanism helps maintain throughput and provides predictable execution. Most instructions execute in a single-cycle effective execution rate, with the exception of instructions that change the program flow, the double-word move (MOV.D) instruction, PSV accesses and the table instructions. Overhead-free program loop constructs are supported using the DO and REPEAT instructions, both of which are interruptible at any point.

3.1 Registers

The dsPIC33EPXXXGS70X/80X devices have sixteen, 16-bit Working registers in the programmer's model. Each of the Working registers can act as a Data, Address or Address Offset register. The 16th Working register (W15) operates as a Software Stack Pointer for interrupts and calls.

In addition, the dsPIC33EPXXXGS70X/80X devices include four Alternate Working register sets which consist of W0 through W14. The Alternate Working registers can be made persistent to help reduce the saving and restoring of register content during Interrupt Service Routines (ISRs). The Alternate Working registers can be assigned to a specific Interrupt Priority Level (IPL1 through IPL7) by configuring the CTXTx<2:0> bits in the FALTREG Configuration register. The Alternate Working registers can also be accessed manually by using the CTXTSWP instruction. The CCTXI<2:0> and MCTXI<2:0> bits in the CTXTSTAT register can be used to identify the current, and most recent, manually selected Working register sets.

3.2 Instruction Set

The instruction set for dsPIC33EPXXXGS70X/80X devices has two classes of instructions: the MCU class of instructions and the DSP class of instructions. These two instruction classes are seamlessly integrated into the architecture and execute from a single execution unit. The instruction set includes many addressing modes and was designed for optimum C compiler efficiency.

3.3 Data Space Addressing

The base Data Space can be addressed as up to 4K words or 8 Kbytes, and is split into two blocks, referred to as X and Y data memory. Each memory block has its own independent Address Generation Unit (AGU). The MCU class of instructions operates solely through the X memory AGU, which accesses the entire memory map as one linear Data Space. Certain DSP instructions operate through the X and Y AGUs to support dual operand reads, which splits the data address space into two parts. The X and Y Data Space boundary is device-specific.

The upper 32 Kbytes of the Data Space memory map can optionally be mapped into Program Space (PS) at any 16K program word boundary. The program-to-Data Space mapping feature, known as Program Space Visibility (PSV), lets any instruction access Program Space as if it were Data Space. Refer to "**Data Memory**" (DS70595) in the "*dsPIC33/PIC24 Family Reference Manual*" for more details on PSV and table accesses.

On dsPIC33EPXXXGS70X/80X devices, overhead-free circular buffers (Modulo Addressing) are supported in both X and Y address spaces. The Modulo Addressing removes the software boundary checking overhead for DSP algorithms. The X AGU Circular Addressing can be used with any of the MCU class of instructions. The X AGU also supports Bit-Reversed Addressing to greatly simplify input or output data re-ordering for radix-2 FFT algorithms.

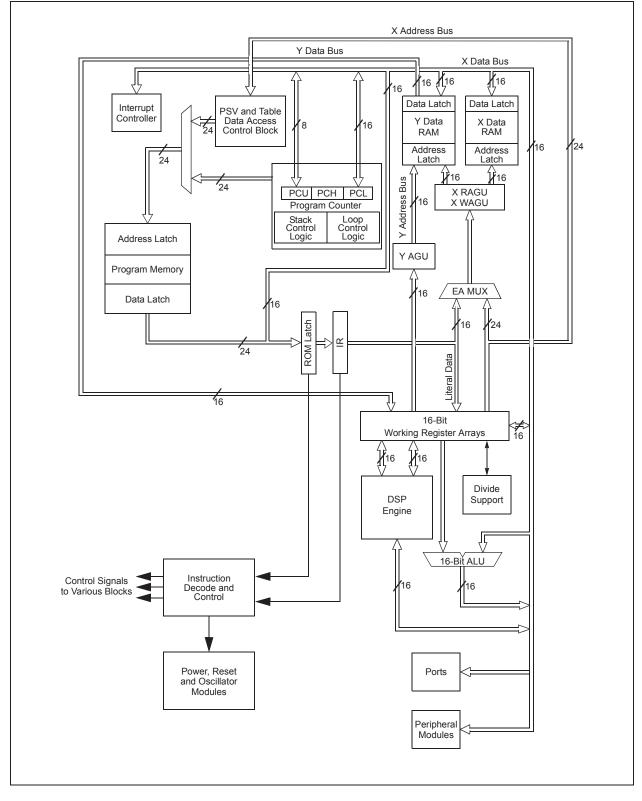
3.4 Addressing Modes

The CPU supports these addressing modes:

- Inherent (no operand)
- Relative
- Literal
- Memory Direct
- Register Direct
- Register Indirect

Each instruction is associated with a predefined addressing mode group, depending upon its functional requirements. As many as six addressing modes are supported for each instruction.

FIGURE 3-1: dsPIC33EPXXXGS70X/80X FAMILY CPU BLOCK DIAGRAM



3.5 **Programmer's Model**

The programmer's model for the dsPIC33EPXXXGS70X/ 80X family is shown in Figure 3-2. All registers in the programmer's model are memory-mapped and can be manipulated directly by instructions. Table 3-1 lists a description of each register. In addition to the registers contained in the programmer's model, the dsPIC33EPXXXGS70X/80X devices contain control registers for Modulo Addressing, Bit-Reversed Addressing and interrupts. These registers are described in subsequent sections of this document.

All registers associated with the programmer's model are memory-mapped, as shown in Table 3-1.

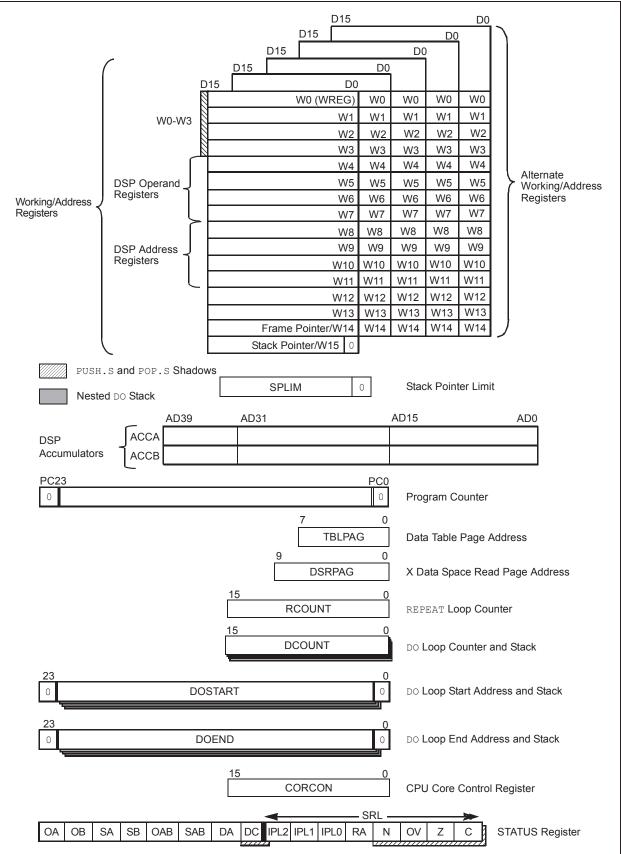
TABLE 3-1:	PROGRAMMER'S MODEL REGISTER DESCRIPTIONS

Register(s) Name	Description
W0 through W15 ⁽¹⁾	Working Register Array
W0 through W14 ⁽¹⁾	Alternate 1 Working Register Array
W0 through W14 ⁽¹⁾	Alternate 2 Working Register Array
W0 through W14 ⁽¹⁾	Alternate 3 Working Register Array
W0 through W14 ⁽¹⁾	Alternate 4 Working Register Array
ACCA, ACCB	40-Bit DSP Accumulators
PC	23-Bit Program Counter
SR	ALU and DSP Engine STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
DSRPAG	Extended Data Space (EDS) Read Page Register
RCOUNT	REPEAT Loop Counter Register
DCOUNT	DO Loop Counter Register
DOSTARTH ⁽²⁾ , DOSTARTL ⁽²⁾	DO Loop Start Address Register (High and Low)
DOENDH, DOENDL	DO Loop End Address Register (High and Low)
CORCON	Contains DSP Engine, DO Loop Control and Trap Status bits

Note 1: Memory-mapped W0 through W14 represent the value of the register in the currently active CPU context.

2: The DOSTARTH and DOSTARTL registers are read-only.





3.6 CPU Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

3.6.1 KEY RESOURCES

- "dsPIC33E Enhanced CPU" (DS70005158) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

3.7 CPU Control Registers

REGISTER 3-1: SR: CPU STATUS REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/C-0	R/C-0	R-0	R/W-0
OA	OB	SA ⁽³⁾	SB ⁽³⁾	OAB	SAB	DA	DC
bit 15	L		•		•	•	bit 8
R/W-0 ⁽²⁾	R/W-0 ⁽²⁾	R/W-0 ⁽²⁾	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 ⁽¹⁾	IPL1 ⁽¹⁾	IPL0 ⁽¹⁾	RA	Ν	OV	Z	С
bit 7							bit (
Legend:		C = Clearable					
R = Readab		W = Writable	bit	-	mented bit, read		
-n = Value a	at POR	'1'= Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	nown
bit 15		lator A Overflov	v Statua hit				
DIL 15		ator A has over					
		ator A has not o					
bit 14	OB: Accumu	lator B Overflov	v Status bit				
	1 = Accumula	ator B has over	flowed				
		ator B has not o					
bit 13		lator A Saturati					
		ator A is satura ator A is not sa		en saturated at	some time		
bit 12		lator B Saturati		tus hit ⁽³⁾			
		ator B is satura			some time		
		ator B is not sa					
bit 11	0AB: 0A 0	OB Combined A	ccumulator C	verflow Status	bit		
		ator A or B has					
		ccumulator A c					
bit 10		B Combined A					
		ator A or B is sa Accumulator A c			ed at some time	9	
bit 9	DA: DO Loop						
	1 = DO loop i						
		s not in progres					
bit 8	DC: MCU AL	U Half Carry/B	orrow bit				
		out from the 4th sult occurred	low-order bit ((for byte-sized of	data) or 8th low-	order bit (for wo	ord-sized data
	0 = No carry			bit (for byte-siz	ed data) or 8th	low-order bit (for word-size
Note 1: 7	The IPL<2:0> bits	are concatena	ted with the IF	PL<3> bit (COF	RCON<3>) to fo	rm the CPU Int	errupt Priority
L	evel. The value i PL<3> = 1.						
2: 1	The IPL<2:0> Stat	tus bits are read	d-only when th	ne NSTDIS bit	(INTCON1<15>	>) = 1.	
0. /					1		

3: A data write to the SR register can modify the SA and SB bits by either a data write to SA and SB or by clearing the SAB bit. To avoid a possible SA or SB bit write race condition, the SA and SB bits should not be modified using bit operations.

REGISTER 3-1: SR: CPU STATUS REGISTER (CONTINUED)

bit 7-5	IPL<2:0>: CPU Interrupt Priority Level Status bits ^(1,2) 111 = CPU Interrupt Priority Level is 7 (15); user interrupts are disabled 110 = CPU Interrupt Priority Level is 6 (14) 101 = CPU Interrupt Priority Level is 5 (13) 100 = CPU Interrupt Priority Level is 4 (12) 011 = CPU Interrupt Priority Level is 3 (11) 010 = CPU Interrupt Priority Level is 2 (10) 001 = CPU Interrupt Priority Level is 1 (9) 000 = CPU Interrupt Priority Level is 0 (8)
bit 4	RA: REPEAT Loop Active bit
	1 = REPEAT loop is in progress 0 = REPEAT loop is not in progress
bit 3	N: MCU ALU Negative bit
	1 = Result was negative 0 = Result was non-negative (zero or positive)
bit 2	OV: MCU ALU Overflow bit
	This bit is used for signed arithmetic (two's complement). It indicates an overflow of the magnitude that causes the sign bit to change state. 1 = Overflow occurred for signed arithmetic (in this arithmetic operation) 0 = No overflow occurred
bit 1	Z: MCU ALU Zero bit
	 1 = An operation that affects the Z bit has set it at some time in the past 0 = The most recent operation that affects the Z bit has cleared it (i.e., a non-zero result)
bit 0	C: MCU ALU Carry/Borrow bit
	 1 = A carry-out from the Most Significant bit of the result occurred 0 = No carry-out from the Most Significant bit of the result occurred
Note 1:	The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority

- Iote 1: The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL, if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
 - 2: The IPL<2:0> Status bits are read-only when the NSTDIS bit (INTCON1<15>) = 1.
 - **3:** A data write to the SR register can modify the SA and SB bits by either a data write to SA and SB or by clearing the SAB bit. To avoid a possible SA or SB bit write race condition, the SA and SB bits should not be modified using bit operations.

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0
VAR	—	US1	US0	EDT ⁽¹⁾	DL2	DL1	DL0
bit 15	1						bit
R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R-0	R/W-0	R/W-0
SATA	SATB	SATDW	ACCSAT	IPL3 ⁽²⁾	SFA	RND	IF
bit 7		1					bit
Legend:		C = Clearable	e bit				
R = Readable	bit	W = Writable	bit	U = Unimplem	ented bit, read	d as '0'	
-n = Value at F	POR	'1' = Bit is set	:	'0' = Bit is clea	ared	x = Bit is unkn	iown
bit 15	1 = Variable	e Exception Pre exception proce ception process	essing latency	is enabled			
bit 14	Unimplemen	ted: Read as	0'				
bit 13-12	US<1:0>: DS	SP Multiply Uns	igned/Signed (Control bits			
	01 = DSP en	ed gine multiplies gine multiplies gine multiplies	are unsigned	1			
bit 11	EDT: Early DO	O Loop Termina	ation Control bi	t(1)			
	1 = Terminate 0 = No effect	•	loop at the er	nd of current loo	op iteration		
bit 10-8	DL<2:0>: DO	Loop Nesting	Level Status bi	ts			
	111 = Seven	DO loops are a	ictive				
	•						
	•						
		 ○ loop is active ○ loops are active 					
bit 7		Saturation En					
		ator A saturatio ator A saturatio					
bit 6		3 Saturation En					
bit o	1 = Accumula	ator B saturatio	n is enabled				
bit 5				ine Saturation I	Enable bit		
	1 = Data Spa	ce write satura	tion is enabled				
bit 4	-	cumulator Satu					
		ration (super s ration (normal					
bit 3		terrupt Priority	,	it 3 ⁽²⁾			
	1 = CPU Inte						

REGISTER 3-2: CORCON: CORE CONTROL REGISTER

2: The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

REGISTER 3-2: CORCON: CORE CONTROL REGISTER (CONTINUED)

bit 2	 SFA: Stack Frame Active Status bit 1 = Stack frame is active; W14 and W15 address 0x0000 to 0xFFFF, regardless of DSRPAG 0 = Stack frame is not active; W14 and W15 address the base Data Space
bit 1	RND: Rounding Mode Select bit
	 1 = Biased (conventional) rounding is enabled 0 = Unbiased (convergent) rounding is enabled
bit 0	IF: Integer or Fractional Multiplier Mode Select bit
	 1 = Integer mode is enabled for DSP multiply 0 = Fractional mode is enabled for DSP multiply
Note 1:	This bit is always read as '0'.

2: The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

REGISTER 3-3: CTXTSTAT: CPU W REGISTER CONTEXT STATUS REGISTER

Legend:					montod bit road		
bit 7							bit 0
—	—	—	—	—	MCTXI2	MCTXI1	MCTXI0
U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
bit 15			•			•	bit 8
—	_	—	—	—	CCTXI2	CCTXI1	CCTXI0
U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 Unimplemented: Read as '0'

bit 10-8	CCTXI<2:0>: Current (W Register) Context Identifier bits
	111 = Reserved
	•
	•
	•
	101 = Reserved
	100 = Alternate Working Register Set 4 is currently in use
	011 = Alternate Working Register Set 3 is currently in use
	010 = Alternate Working Register Set 2 is currently in use
	001 = Alternate Working Register Set 1 is currently in use
	000 = Default register set is currently in use
bit 7-3	Unimplemented: Read as '0'
bit 2-0	MCTXI<2:0>: Manual (W Register) Context Identifier bits
	111 = Reserved
	•
	•
	•
	101 = Reserved
	100 = Alternate Working Register Set 4 was most recently manually selected
	011 = Alternate Working Register Set 3 was most recently manually selected
	010 = Alternate Working Register Set 2 was most recently manually selected
	001 = Alternate Working Register Set 1 was most recently manually selected
	000 = Default register set was most recently manually selected

3.8 Arithmetic Logic Unit (ALU)

The dsPIC33EPXXXGS70X/80X family ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are two's complement in nature. Depending on the operation, the ALU can affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

Refer to the *"16-Bit MCU and DSC Programmer's Reference Manual"* (DS70000157) for information on the SR bits affected by each instruction.

The core CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

3.8.1 MULTIPLIER

Using the high-speed, 17-bit x 17-bit multiplier, the ALU supports unsigned, signed or mixed-sign operation in several MCU Multiplication modes:

- 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit signed x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- 8-bit unsigned x 8-bit unsigned

3.8.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

- · 32-bit signed/16-bit signed divide
- 32-bit unsigned/16-bit unsigned divide
- · 16-bit signed/16-bit signed divide
- 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. 16-bit signed and unsigned DIV instructions can specify any W register for both the 16-bit divisor (Wn) and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

3.9 DSP Engine

The DSP engine consists of a high-speed 17-bit x 17-bit multiplier, a 40-bit barrel shifter and a 40-bit adder/ subtracter (with two target accumulators, round and saturation logic).

The DSP engine can also perform inherent accumulatorto-accumulator operations that require no additional data. These instructions are, ADD, SUB and NEG.

The DSP engine has options selected through bits in the CPU Core Control register (CORCON), as listed below:

- Fractional or Integer DSP Multiply (IF)
- Signed, Unsigned or Mixed-Sign DSP Multiply (USx)
- Conventional or Convergent Rounding (RND)
- Automatic Saturation On/Off for ACCA (SATA)
- Automatic Saturation On/Off for ACCB (SATB)
- Automatic Saturation On/Off for Writes to Data Memory (SATDW)
- Accumulator Saturation mode Selection (ACCSAT)

TABLE 3-2:	DSP INSTRUCTIONS
	SUMMARY

Instruction	Algebraic Operation	ACC Write-Back
CLR	A = 0	Yes
ED	$A = (x - y)^2$	No
EDAC	$A = A + (x - y)^2$	No
MAC	$A = A + (x \bullet y)$	Yes
MAC	$A = A + x^2$	No
MOVSAC	No change in A	Yes
MPY	$A = x \bullet y$	No
MPY	$A = x^2$	No
MPY.N	$A = -x \bullet y$	No
MSC	$A = A - x \bullet y$	Yes

4.0 MEMORY ORGANIZATION

Note: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "dsPIC33E/PIC24E Program Memory" (DS70000613) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).

The dsPIC33EPXXXGS70X/80X family architecture features separate program and data memory spaces, and buses. This architecture also allows the direct access of program memory from the Data Space (DS) during code execution.

4.1 Program Address Space

The program address memory space of the dsPIC33EPXXXGS70X/80X family devices is 4M instructions. The space is addressable by a 24-bit value derived either from the 23-bit PC during program execution, or from table operation or Data Space remapping, as described in Section 4.9 "Interfacing Program and Data Memory Spaces".

User application access to the program memory space is restricted to the lower half of the address range (0x000000 to 0x7FFFFF). The exception is the use of TBLRD operations, which use TBLPAG<7> to permit access to calibration data and Device ID sections of the configuration memory space.

The program memory maps for dsPIC33EPXXXGS70X/ 80X devices not operating in Dual Partition mode are shown in Figure 4-1 and Figure 4-2.

The dsPIC33EPXXXGS70X/80X devices can operate in a Dual Partition Flash Program Memory mode, where the user Program Flash Memory is arranged as two separate address spaces, one for each of the Flash partitions. The Active Partition always starts at address, 0x000000, and contains half of the available Flash memory (64k/128k, depends on device). The Inactive Partition always starts at address, 0x400000, and implements the remaining half of Flash memory. As shown in Figure 4-3 and Figure 4-4, the Active and Inactive Partitions are identical, and both contain unique copies of the Reset vector, Interrupt Vector Tables (IVT and AIVT if enabled) and the Flash Configuration Words.

4.2 Unique Device Identifier (UDID)

All dsPIC33EPXXXGS70X/80X family devices are individually encoded during final manufacturing with a Unique Device Identifier or UDID. This feature allows for manufacturing traceability of Microchip Technology devices in applications where this is a requirement. It may also be used by the application manufacturer for any number of things that may require unique identification, such as:

- · Tracking the device
- Unique serial number
- · Unique security key

The UDID comprises five 24-bit program words. When taken together, these fields form a unique 120-bit identifier.

The UDID is stored in five read-only locations, located between 800F00h and 800F08h in the device configuration space. Table 4-1 lists the addresses of the identifier words and shows their contents.

TABLE 4-1: UDID ADDRESSES

Name	Address	Bits 23:16	Bits 15:8	Bits 7:0
UDID1	800F00	UI	DID Word 1	
UDID2	800F02	UI	DID Word 2	
UDID3	800F04	UI	DID Word 3	
UDID4	800F06	U	DID Word 4	
UDID5	800F08	U	DID Word 5	

-	A I	GOTO Instruction	0x000000	
		Reset Address	0x000002	
۳.		Interrupt Vector Table	0x000004 0x0001FE	
User Memory Space		User Program Flash Memory (22,016 instructions)	0x000200 0x00AF7E	
ser Mem		Device Configuration	0x00AFFE	
n		Unimplemented (Read '0's)	0x00B000	
_		Reserved	0x7FFFE 0x800000 0x800E46	
		Calibration Data	0x800E48 0x800E78	0x800E78 0x800E7A 0x800EFE 0x800F00 0x800F08 0x800F0A 0x800F7E 0x800F7E 0x800FFC 0x800FFC 0x801000 0xF9FFFE 0xFA0000 0xFA0002
		Reserved		
		UDID	0x800F00	
Space		Reserved		
emory (User OTP Memory	0x800FFC	
ion Me		Reserved	0xF9FFFE	
Configuration Memory Space		Write Latches	0xFA0002	
ů		Reserved	0xFA0004	
		DEVID	0xFEFFFE 0xFF0000 0xFF0002	
		Reserved	0xFF0004 0xFFFFFE	

FIGURE 4-1: PROGRAM MEMORY MAP FOR dsPIC33EP64GS70X/80X DEVICES

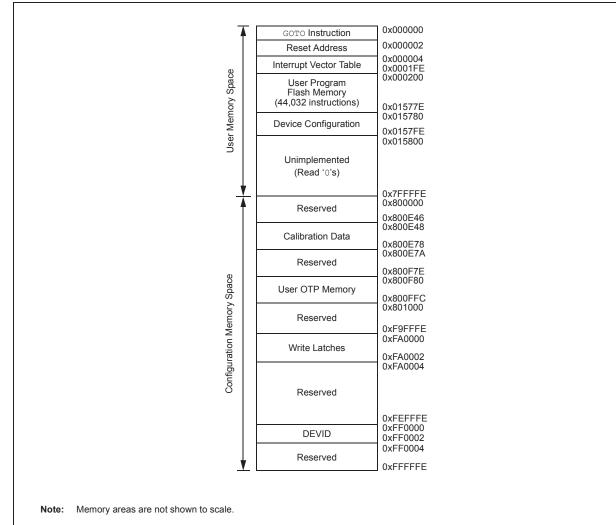
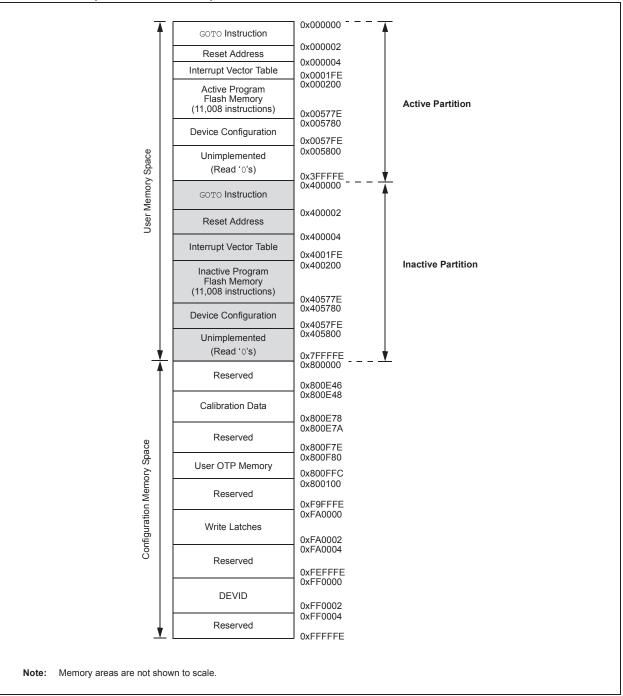
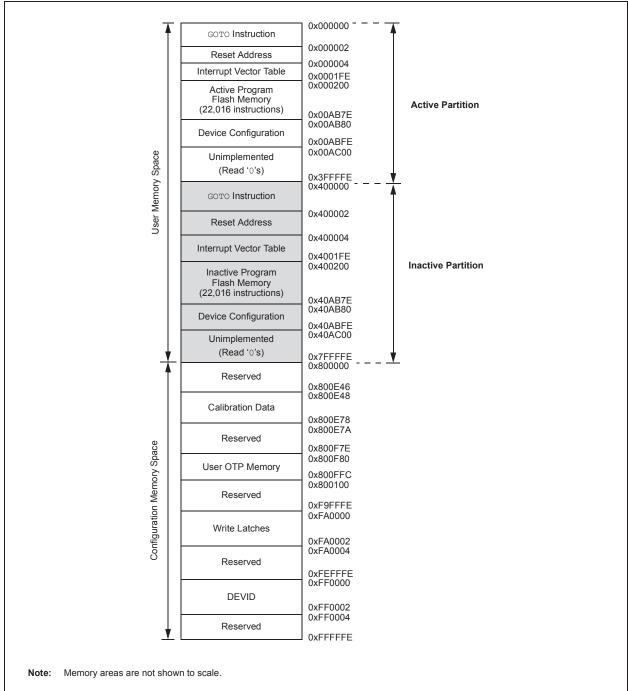


FIGURE 4-2: PROGRAM MEMORY MAP FOR dsPIC33EP128GS70X/80X DEVICES

FIGURE 4-3: PROGRAM MEMORY MAP FOR dsPIC33EP64GS70X/80X DEVICES (DUAL PARTITION)







4.2.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in wordaddressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-5).

Program memory addresses are always word-aligned on the lower word, and addresses are incremented or decremented by two, during code execution. This arrangement provides compatibility with data memory space addressing and makes data in the program memory space accessible.

4.2.2 INTERRUPT AND TRAP VECTORS

All dsPIC33EPXXXGS70X/80X family devices reserve the addresses between 0x000000 and 0x000200 for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user application at address, 0x000000, of Flash memory, with the actual address for the start of code at address, 0x000002, of Flash memory.

A more detailed discussion of the Interrupt Vector Tables (IVTs) is provided in **Section 7.1** "Interrupt Vector Table".

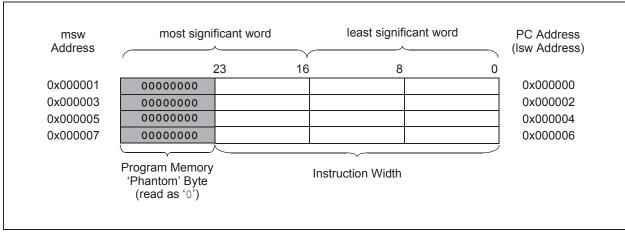


FIGURE 4-5: PROGRAM MEMORY ORGANIZATION

4.3 Data Address Space

The dsPIC33EPXXXGS70X/80X family CPU has a separate 16-bit wide data memory space. The Data Space is accessed using separate Address Generation Units (AGUs) for read and write operations. The data memory map is shown in Figure 4-6.

All Effective Addresses (EAs) in the data memory space are 16 bits wide and point to bytes within the Data Space. This arrangement gives a base Data Space address range of 64 Kbytes or 32K words.

The lower half of the data memory space (i.e., when EA<15> = 0) is used for implemented memory addresses, while the upper half (EA<15> = 1) is reserved for the Program Space Visibility (PSV).

dsPIC33EPXXXGS70X/80X family devices implement up to 12 Kbytes of data memory. If an EA points to a location outside of this area, an all-zero word or byte is returned.

4.3.1 DATA SPACE WIDTH

The data memory space is organized in byteaddressable, 16-bit wide blocks. Data is aligned in data memory and registers as 16-bit words, but all Data Space EAs resolve to bytes. The Least Significant Bytes (LSBs) of each word have even addresses, while the Most Significant Bytes (MSBs) have odd addresses.

4.3.2 DATA MEMORY ORGANIZATION AND ALIGNMENT

To maintain backward compatibility with PIC[®] MCU devices and improve Data Space memory usage efficiency, the dsPIC33EPXXXGS70X/80X family instruction set supports both word and byte operations. As a consequence of byte accessibility, all Effective Address calculations are internally scaled to step through word-aligned memory. For example, the core recognizes that Post-Modified Register Indirect Addressing mode [Ws++] results in a value of Ws + 1 for byte operations and Ws + 2 for word operations.

A data byte read, reads the complete word that contains the byte, using the LSb of any EA to determine which byte to select. The selected byte is placed onto the LSB of the data path. That is, data memory and registers are organized as two parallel, byte-wide entities with shared (word) address decode, but separate write lines. Data byte writes only write to the corresponding side of the array or register that matches the byte address. All word accesses must be aligned to an even address. Misaligned word data fetches are not supported, so care must be taken when mixing byte and word operations, or translating from 8-bit MCU code. If a misaligned read or write is attempted, an address error trap is generated. If the error occurred on a read, the instruction underway is completed. If the error occurred on a write, the instruction is executed but the write does not occur. In either case, a trap is then executed, allowing the system and/or user application to examine the machine state prior to execution of the address Fault.

All byte loads into any W register are loaded into the LSB; the MSB is not modified.

A Sign-Extend (SE) instruction is provided to allow user applications to translate 8-bit signed data to 16-bit signed values. Alternatively, for 16-bit unsigned data, user applications can clear the MSB of any W register by executing a Zero-Extend (ZE) instruction on the appropriate address.

4.3.3 SFR SPACE

The first 4 Kbytes of the Near Data Space, from 0x0000 to 0x0FFF, is primarily occupied by Special Function Registers (SFRs). These are used by the dsPIC33EPXXXGS70X/80X family core and peripheral modules for controlling the operation of the device.

SFRs are distributed among the modules that they control and are generally grouped together by module. Much of the SFR space contains unused addresses; these are read as '0'.

Note: The actual set of peripheral features and interrupts varies by the device. Refer to the corresponding device tables and pinout diagrams for device-specific information.

4.3.4 NEAR DATA SPACE

The 8-Kbyte area, between 0x0000 and 0x1FFF, is referred to as the Near Data Space. Locations in this space are directly addressable through a 13-bit absolute address field within all memory direct instructions. Additionally, the whole Data Space is addressable using MOV instructions, which support Memory Direct Addressing mode with a 16-bit address field, or by using Indirect Addressing mode using a Working register as an Address Pointer.

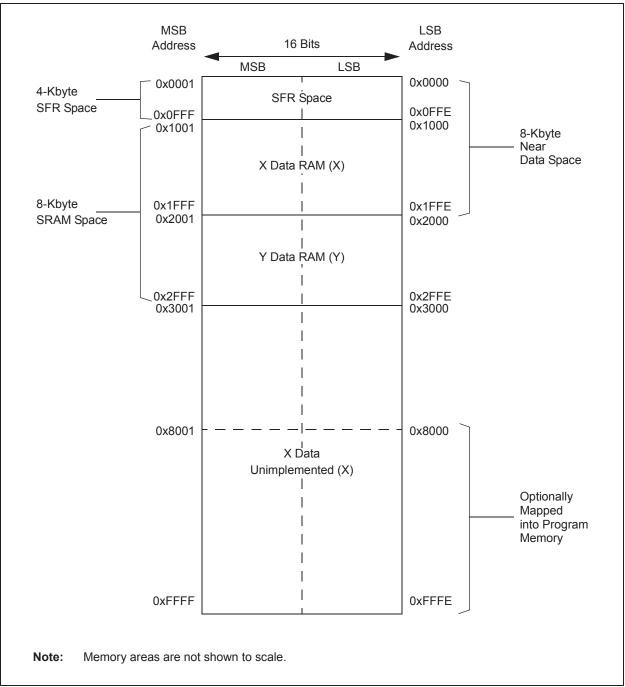


FIGURE 4-6: DATA MEMORY MAP FOR dsPIC33EP64GS70X/80X DEVICES

4.3.5 X AND Y DATA SPACES

The dsPIC33EPXXXGS70X/80X core has two Data Spaces, X and Y. These Data Spaces can be considered either separate (for some DSP instructions) or as one unified linear address range (for MCU instructions). The Data Spaces are accessed using two Address Generation Units (AGUs) and separate data paths. This feature allows certain instructions to concurrently fetch two words from RAM, thereby enabling efficient execution of DSP algorithms, such as Finite Impulse Response (FIR) filtering and Fast Fourier Transform (FFT).

The X Data Space is used by all instructions and supports all addressing modes. X Data Space has separate read and write data buses. The X read data bus is the read data path for all instructions that view Data Space as combined X and Y address space. It is also the X data prefetch path for the dual operand DSP instructions (MAC class).

The Y Data Space is used in concert with the X Data Space by the MAC class of instructions (CLR, ED, EDAC, MAC, MOVSAC, MPY, MPY.N and MSC) to provide two concurrent data read paths.

Both the X and Y Data Spaces support Modulo Addressing mode for all instructions, subject to addressing mode restrictions. Bit-Reversed Addressing mode is only supported for writes to X Data Space.

All data memory writes, including in DSP instructions, view Data Space as combined X and Y address space. The boundary between the X and Y Data Spaces is device-dependent and is not user-programmable.

4.4 Memory Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

4.4.1 KEY RESOURCES

- "dsPIC33E/PIC24E Program Memory" (DS70000613) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- · Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

4.5 Special Function Register Maps

TABLE 4-2: SFR BLOCK 000h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
Core			WREG14	01C	000000000000000000	DOSTARTL	03A	*****************
WREG0	000	000000000000000000000000000000000000000	WREG15	01E	0000100000000000	DOSTARTH	03C	00000000000xxxxxx
WREG1	002	000000000000000000000000000000000000000	SPLIM	020	******************	DOENDL	03E	***************
WREG2	004	000000000000000000000000000000000000000	ACCAL	022	*****	DOENDH	040	00000000000xxxxxx
WREG3	006	000000000000000000000000000000000000000	ACCAH	024	*****	SR	042	000000000000000000000000000000000000000
WREG4	008	000000000000000000000000000000000000000	ACCAU	026	00000000xxxxxxxx	CORCON	044	0000000000100000
WREG5	00A	000000000000000000000000000000000000000	ACCBL	028	*****	MODCON	046	000000000000000000000000000000000000000
WREG6	00C	000000000000000000000000000000000000000	ACCBH	02A	*****	XMODSRT	048	****************
WREG7	00E	000000000000000000000000000000000000000	ACCBU	02C	00000000xxxxxxxx	XMODEND	04A	******
WREG8	010	000000000000000000000000000000000000000	PCL	02E	000000000000000000000000000000000000000	YMODSRT	04C	****************
WREG9	012	000000000000000000000000000000000000000	PCH	030	000000000000000000000000000000000000000	YMODEND	04E	******
WREG10	014	000000000000000000000000000000000000000	DSRPAG	032	000000000000000000000000000000000000000	XBREV	050	*****
WREG11	016	000000000000000000000000000000000000000	DSWPAG	034	000000000000000000000000000000000000000	DISICNT	052	00xxxxxxxxxxxx
WREG12	018	000000000000000000000000000000000000000	RCOUNT	036	*****	TBLPAG	054	00000000xxxxxxxx
WREG13	01A	000000000000000000000000000000000000000	DCOUNT	038	*****	CTXTSTAT	05A	000000000000000000000000000000000000000

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

TABLE 4-3: SFR BLOCK 100h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
Timers			TMR5HLD	116	*****	IC2CON2	14A	0000000000001101
TMR1	100	*****	TMR5	118	*****	IC2BUF	14C	*****
PR1	102	111111111111111111	PR4	11A	111111111111111111	IC2TMR	14E	000000000000000000000000000000000000000
T1CON	104	000000000000000000000000000000000000000	PR5	11C	111111111111111111	IC3CON1	150	000000000000000000000000000000000000000
TMR2	106	*****	T4CON	11E	000000000000000000000000000000000000000	IC3CON2	152	0000000000001101
TMR3HLD	108	*****	T5CON	120	000000000000000000000000000000000000000	IC3BUF	154	*****
TMR3	10A	*****	Input Captur	re		IC3TMR	156	000000000000000000000000000000000000000
PR2	10C	111111111111111111	IC1CON1	140	000000000000000000000000000000000000000	IC4CON1	158	000000000000000000000000000000000000000
PR3	10E	111111111111111111	IC1CON2	142	0000000000001101	IC4CON2	15A	0000000000001101
T2CON	110	000000000000000000000000000000000000000	IC1BUF	144	*****	IC4BUF	15C	*****
T3CON	112	000000000000000000	IC1TMR	146	000000000000000000	IC4TMR	15E	000000000000000000
TMR4	114	*****	IC2CON1	148	000000000000000000			•

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
I2C1 and I2C	2		U1STA	222	000000010010000	SPI1BRGH	252	000000000000000000
I2C1CONL	200	0001000000000000	U1TXREG	224	0000000xxxxxxxxx	SPI1IMSKL	254	000000000000000000
I2C1CONH	202	000000000000000000000000000000000000000	U1RXREG	226	000000000000000000000000000000000000000	SPI1IMSKH	256	000000000000000000000000000000000000000
I2C1STAT	204	000000000000000000000000000000000000000	U1BRG	228	000000000000000000000000000000000000000	SPI1URDTL	258	000000000000000000000000000000000000000
I2C1ADD	206	000000000000000000000000000000000000000	U2MODE	230	000000000000000000000000000000000000000	SPI1URDTH	25A	000000000000000000000000000000000000000
I2C1MSK	208	000000000000000000000000000000000000000	U2STA	232	000000010010000	SPI2CON1L	260	000000000000000000000000000000000000000
I2C1BRG	20A	000000000000000000000000000000000000000	U2TXREG	234	0000000xxxxxxxxx	SPI2CON1H	262	000000000000000000000000000000000000000
I2C1TRN	20C	000000011111111	U2RXREG	236	000000000000000000000000000000000000000	SPI2CON2L	264	000000000000000000000000000000000000000
I2C1RCV	20E	000000000000000000000000000000000000000	U2BRG	238	000000000000000000000000000000000000000	SPI2CON2H	266	000000000000000000000000000000000000000
I2C2CON1	210	0001000000000000	SPI			SPI2STATL	268	0000000000101000
I2C2CON2	212	000000000000000000000000000000000000000	SPI1CON1L	240	000000000000000000000000000000000000000	SPI2STATH	26A	000000000000000000000000000000000000000
I2C2STAT	214	000000000000000000000000000000000000000	SPI1CON1H	242	000000000000000000000000000000000000000	SPI2BUFL	26C	000000000000000000000000000000000000000
I2C2ADD	216	000000000000000000000000000000000000000	SPI1CON2L	244	000000000000000000000000000000000000000	SPI2BUFH	26E	000000000000000000000000000000000000000
I2C2MSK	218	000000000000000000000000000000000000000	SPI1CON2H	246	000000000000000000000000000000000000000	SPI3STAT	270	000xxxxxxxxxxxx
I2C2BRG	21A	000000000000000000000000000000000000000	SPI1STATL	248	0000000000101000	SPI2BRGH	272	000000000000000000000000000000000000000
I2C2TRN	21C	0000000011111111	SPI1STATH	24A	000000000000000000000000000000000000000	SPI2IMSKL	274	000000000000000000000000000000000000000
I2C2RCV	21E	000000000000000000000000000000000000000	SPI1BUFL	24C	000000000000000000000000000000000000000	SPI2IMSKH	276	000000000000000000000000000000000000000
UART1 and	JART1 and UART2 SPI		SPI1BUFH	24E	000000000000000000000000000000000000000	SPI2URDTL	278	000000000000000000000000000000000000000
U1MODE	220	000000000000000000000000000000000000000	SPI1BRGL	250	000xxxxxxxxxxxx	SPI2URDTH	27A	000000000000000000000000000000000000000

TABLE 4-4: SFR BLOCK 200h

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

TABLE 4-5:	SFR	BL	оск	300h
	0110			00011

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
ADC			ADCMP0ENH	33A	000000000000000000000000000000000000000	ADTRIG4L	390	000000000000000000000000000000000000000
ADCON1L	300	000000000000000000	ADCMP0LO	33C	000000000000000000	ADTRIG4H	392	000000000000000000000000000000000000000
ADCON1H	302	000000001100000	ADCMP0HI	33E	000000000000000000	ADCMP0CON	3A0	000000000000000000000000000000000000000
ADCON2L	304	000000000000000000	ADCMP1ENL	340	000000000000000000	ADCMP1CON	3A4	000000000000000000000000000000000000000
ADCON2H	306	000000000000000000	ADCMP1ENH	342	000000000000000000	ADBASE	3C0	000000000000000000000000000000000000000
ADCON3L	308	000000000000000000	ADCMP1LO	344	000000000000000000	ADLVLTRGL	3D0	000000000000000000000000000000000000000
ADCON3H	30A	000000000000000000	ADCMP1HI	346	000000000000000000	ADLVLTRGH	3D2	000000000000000000000000000000000000000
ADCON4L	30C	000000000000000000	ADFL0DAT	368	000000000000000000	ADCORE0L	3D4	000000000000000000000000000000000000000
ADCON4H	30E	000000000000000000	ADFL0CON	36A	000000000000000000	ADCORE0H	3D6	0000001100000000
ADMOD0L	310	000000000000000000	ADFL1DAT	36C	000000000000000000	ADCORE1L	3D8	000000000000000000000000000000000000000
ADMOD0H	312	000000000000000000	ADFL1CON	36E	000000000000000000	ADCORE1H	3DA	0000001100000000
ADMOD1L	314	000000000000000000	ADTRIG0L	380	000000000000000000	ADCORE2L	3DC	000000000000000000000000000000000000000
ADIEL	320	000000000000000000	ADTRIG0H	382	000000000000000000	ADCORE2H	3DE	0000001100000000
ADIEH	322	000000000000000000	ADTRIG1L	384	000000000000000000	ADCORE3L	3E0	000000000000000000000000000000000000000
ADCSS1L	328	000000000000000000	ADTRIG1H	386	000000000000000000	ADCORE3H	3E2	0000001100000000
ADCSS1H	32A	000000000000000000	ADTRIG2L	388	000000000000000000	ADEIEL	3F0	000000000000000000000000000000000000000
ADSTATL	330	0000000000000000000	ADTRIG2H	38A	000000000000000000	ADEIEH	3F2	000000000000000000000000000000000000000
ADSTATH	332	000000000000000000	ADTRIG3L	38C	000000000000000000	ADEISTATL	3F8	000000000000000000000000000000000000000
ADCMP0ENL	338	000000000000000000	ADTRIG3H	38E	000000000000000000	ADEISTATH	3FA	000000000000000000000000000000000000000

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
ADC (Continu	ed)		C1FCTRL	486	000000000000000000000000000000000000000	C1RXM2EID	4BA	*****
ADCON5L	400	000000000000000000	C1FIFO	488	000000000000000000	C1RXF1SID	4C4	*****
ADCON5H	402	000000000000000000	C1INTF	48A	000000000000000000	C1RXF1EID	4C6	*****
ADCAL0L	404	000000000000000000	C1INTE	48C	000000000000000000	C1RXF2SID	4C8	*****
ADCAL0H	406	000000000000000000000000000000000000000	C1EC	48E	000000000000000000000000000000000000000	C1RXF2EID	4CA	*****
ADCAL1H	40A	000000000000000000000000000000000000000	C1CFG1	490	000000000000000000000000000000000000000	C1RXF3SID	4CC	*****
ADCBUF0	40C	000000000000000000000000000000000000000	C1CFG2	492	0x000xxxxxxxxxx	C1RXF3EID	4CE	*****
ADCBUF1	40E	000000000000000000000000000000000000000	C1FEN1	494	111111111111111111	C1RXF4SID	4D0	*****
ADCBUF2	410	000000000000000000000000000000000000000	C1FMSKSEL1	498	000000000000000000000000000000000000000	C1RXF4EID	4D2	*****
ADCBUF3	412	000000000000000000000000000000000000000	C1FMSKSEL2	49A	000000000000000000000000000000000000000	C1RXF5SID	4D4	*****
ADCBUF4	414	000000000000000000000000000000000000000	CAN (WIN (C1	CTRL<0>) =	= 0)	C1RXF5EID	4D6	*****
ADCBUF5	416	000000000000000000000000000000000000000	C1RXFUL1	4A0	000000000000000000000000000000000000000	C1RXF6SID	4D8	*****
ADCBUF6	418	000000000000000000000000000000000000000	C1RXFUL2	4A2	000000000000000000000000000000000000000	C1RXF6EID	4DA	*****
ADCBUF7	41A	000000000000000000000000000000000000000	C1RXOVF1	4A8	000000000000000000000000000000000000000	C1RXF7SID	4DC	*****
ADCBUF8	41C	000000000000000000000000000000000000000	C1RXOVF2	4AA	000000000000000000000000000000000000000	C1RXF7EID	4DE	*****
ADCBUF9	41E	000000000000000000000000000000000000000	C1TR01CON	4B0	000000000000000000000000000000000000000	C1RXF8SID	4E0	*****
ADCBUF10	420	000000000000000000000000000000000000000	C1TR23CON	4B2	000000000000000000000000000000000000000	C1RXF8EID	4E2	*****
ADCBUF11	422	000000000000000000000000000000000000000	C1TR45CON	4B4	000000000000000000000000000000000000000	C1RXF9SID	4E4	*****
ADCBUF12	424	000000000000000000000000000000000000000	C1TR67CON	4B6	*****	C1RXF9EID	4E6	*****
ADCBUF13	426	000000000000000000000000000000000000000	C1RXD	4C0	*****	C1RXF10SID	4E8	*****
ADCBUF14	428	000000000000000000000000000000000000000	C1TXD	4C2	*****	C1RXF10EID	4EA	*****
ADCBUF15	42A	000000000000000000000000000000000000000	CAN (WIN (C1	CTR1<0>) =	: 1)	C1RXF11SID	4EC	*****
ADCBUF16	42C	000000000000000000000000000000000000000	C1BUFPNT1	4A0	000000000000000000000000000000000000000	C1RXF11EID	4EE	*****
ADCBUF17	42E	000000000000000000000000000000000000000	C1BUFPNT2	4A2	000000000000000000000000000000000000000	C1RXF12SID	4F0	*****
ADCBUF18	430	000000000000000000000000000000000000000	C1BUFPNT3	4A4	000000000000000000000000000000000000000	C1RXF12EID	4F2	*****
ADCBUF19	432	000000000000000000000000000000000000000	C1BUFPNT4	4A6	000000000000000000000000000000000000000	C1RXF13SID	4F4	*****
ADCBUF20	434	000000000000000000000000000000000000000	C1RXM0SID	4B0	*****	C1RXF13EID	4F6	*****
ADCBUF21	436	000000000000000000000000000000000000000	C1RXM0EID	4B2	*****	C1RXF14SID	4F8	*****
CAN (WIN (C10	CTRL<0>)	= 0 OR 1)	C1RXM1SID	4B4	*****	C1RXF14EID	4FA	*****
C1CTRL1	480	000010010000000	C1RXM1EID	4B6	*****	C1RXF15SID	4FC	*****
C1CTRL2	482	000000000000000000000000000000000000000	CAN			C1RXF15EID	4FE	*****
C1VEC	484	00000001000000	C1RXM2SID	4B8	*****			

TABLE 4-6: SFR BLOCK 400h

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

TABLE 4-7: SFR BLOCK 500h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
PGA			PGA2CAL	50A	000000000000000000	CMP2DAC	546	000000000000000000000000000000000000000
ISRCCON	500	000000000000000000000000000000000000000	Comparators	6		CMP3CON	548	000000000000000000000000000000000000000
PGA1CON	504	000000000000000000000000000000000000000	CMP1CON	540	000000000000000000	CMP3DAC	54A	000000000000000000000000000000000000000
PGA1CAL	506	000000000000000000000000000000000000000	CMP1DAC	542	000000000000000000	CMP4CON	54C	000000000000000000000000000000000000000
PGA2CON	508	000000000000000000000000000000000000000	CMP2CON	544	000000000000000000	CMP4DAC	54E	000000000000000000000000000000000000000

Deviator	Address		Deviator	Address		Desister	Address	
Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
SPI			RPOR8	678	000000000000000000000000000000000000000	RPINR7	6AE	000000000000000000000000000000000000000
SPI3CON1L	600	000000000000000000000000000000000000000	RPOR9	67A	000000000000000000000000000000000000000	RPINR8	6B0	000000000000000000000000000000000000000
SPI3CON1H	602	000000000000000000000000000000000000000	RPOR10	67C	000000000000000000000000000000000000000	RPINR11	6B6	000000000000000000000000000000000000000
SPI3CON2L	604	000000000000000000000000000000000000000	RPOR11	67E	000000000000000000000000000000000000000	RPINR12	6B8	000000000000000000000000000000000000000
SPI3CON2H	606	000000000000000000000000000000000000000	RPOR12	680	000000000000000000000000000000000000000	RPINR13	6BA	000000000000000000000000000000000000000
SPI3STATL	608	0000000000101000	RPOR13	682	000000000000000000000000000000000000000	RPINR18	6C4	000000000000000000000000000000000000000
SPI3STATH	60A	000000000000000000000000000000000000000	RPOR14	684	000000000000000000000000000000000000000	RPINR19	6C6	000000000000000000000000000000000000000
SPI3BUFL	60C	000000000000000000000000000000000000000	RPOR15	686	000000000000000000000000000000000000000	RPINR20	6C8	000000000000000000000000000000000000000
SPI3BUFH	60E	000000000000000000000000000000000000000	RPOR17	68A	000000000000000000000000000000000000000	RPINR21	6CA	000000000000000000000000000000000000000
SPI3BRGL	610	000xxxxxxxxxxxx	RPOR18	68C	000000000000000000000000000000000000000	RPINR22	6CC	000000000000000000000000000000000000000
SPI3BRGH	612	000000000000000000000000000000000000000	RPOR19	68E	000000000000000000000000000000000000000	RPINR23	6CE	000000000000000000000000000000000000000
SPI3IMSKL	614	000000000000000000000000000000000000000	RPOR20	690	000000000000000000000000000000000000000	RPINR26	6D4	000000000000000000000000000000000000000
SPI3IMSKH	616	000000000000000000000000000000000000000	RPOR21	692	000000000000000000000000000000000000000	RPINR29	6DA	000000000000000000000000000000000000000
SPI3URDTL	618	000000000000000000000000000000000000000	RPOR22	694	000000000000000000000000000000000000000	RPINR30	6DC	000000000000000000000000000000000000000
SPI3URDTH	61A	000000000000000000000000000000000000000	RPOR23	696	000000000000000000000000000000000000000	RPINR37	6EA	000000000000000000000000000000000000000
RPOR0	668	000000000000000000000000000000000000000	RPOR24	698	000000000000000000000000000000000000000	RPINR38	6EC	000000000000000000000000000000000000000
RPOR1	66A	000000000000000000000000000000000000000	RPOR25	69A	000000000000000000000000000000000000000	RPINR42	6F4	000000000000000000000000000000000000000
RPOR2	66C	000000000000000000000000000000000000000	RPOR26	69C	000000000000000000000000000000000000000	RPINR43	6F6	000000000000000000000000000000000000000
RPOR3	66E	000000000000000000000000000000000000000	RPINR0	6A0	000000000000000000000000000000000000000	RPINR45	6FA	000000000000000000
RPOR4	670	000000000000000000000000000000000000000	RPINR1	6A2	000000000000000000000000000000000000000	RPINR46	6FC	000000000000000000
RPOR5	672	000000000000000000	RPINR2	6A4	000000000000000000000000000000000000000		•	
RPOR6	674	000000000000000000000000000000000000000	RPINR3	6A6	000000000000000000000000000000000000000			

TABLE 4-8: SFR BLOCK 600h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
NVM			C2INTF	78A	000000000000000000000000000000000000000	C2RXF1SID	7C4	****
NVMCON	728	000000000000000000	C2INTE	78C	0000000000000000000	C2RXF1EID	7C6	*****
NVMADR	72A	0000000000000000000	C2EC	78E	000000000000000000	C2RXF2SID	7C8	*****
NVMADRU	72C	000000000000000000000000000000000000000	C2CFG1	790	000000000000000000000000000000000000000	C2RXF2EID	7CA	*****
NVMKEY	72E	000000000000000000000000000000000000000	C2CFG2	792	0x000xxxxxxxxxx	C2RXF3SID	7CC	*****
NVMSRCADR	730	00000000000000000000	C2FEN1	794	11111111111111111	C2RXF3EID	7CE	*****
NVMSRCADRH	732	0000000000000000000	C2FMSKSEL1	798	000000000000000000	C2RXF4SID	7D0	*****
System Control			C2FMSKSEL2	79A	000000000000000000000000000000000000000	C2RXF4EID	7D2	*****
RCON	740	0x00x0x01x0xxxxx	CAN (WIN (C1	CTR1<0>)	= 0)	C2RXF5SID	7D4	*****
OSCCON	742	0000000000000000000	C2RXFUL1	7A0	000000000000000000	C2RXF5EID	7D6	*****
CLKDIV	744	000000000000000000000000000000000000000	C2RXFUL2	7A2	000000000000000000000000000000000000000	C2RXF6SID	7D8	*****
PLLFBD	746	000000000000000000000000000000000000000	C2RXOVF1	7A8	000000000000000000000000000000000000000	C2RXF6EID	7DA	*****
OSCTUN	748	000000000000000000000000000000000000000	C2RXOVF2	7AA	000000000000000000000000000000000000000	C2RXF7SID	7DC	*****
LFSR	74C	000000000000000000000000000000000000000	C2TR01CON	7B0	000000000000000000000000000000000000000	C2RXF7EID	7DE	*****
REFOCON	74E	000000000000000000000000000000000000000	C2TR23CON	7B2	000000000000000000000000000000000000000	C2RXF8SID	7E0	*****
ACLKCON	750	000000001000000	C2TR45CON	7B4	000000000000000000000000000000000000000	C2RXF8EID	7E2	*****
PMD			C2TR67CON	7B6	*****	C2RXF9SID	7E4	*****
PMD1	760	0000000000000000000	C2RXD	7C0	*****	C2RXF9EID	7E6	*****
PMD2	762	000000000000000000	C2TXD	7C2	*****	C2RXF10SID	7E8	*****
PMD3	764	000000000000000000	CAN (WIN (C1	CTR1<0>) =	= 1)	C2RXF10EID	7EA	*****
PMD4	766	000000000000000000	C2BUFPNT1	7A0	0000000000000000000	C2RXF11SID	7EC	*****
PMD6	76A	000000000000000000	C2BUFPNT2	7A2	000000000000000000	C2RXF11EID	7EE	*****
PMD7	76C	00000000000000000	C2BUFPNT3	7A4	000000000000000000000000000000000000000	C2RXF12SID	7F0	*****
PMD8	76E	000000000000000000	C2BUFPNT4	7A6	000000000000000000	C2RXF12EID	7F2	*****
CAN (WIN (C1CT	R1<0>) =	0 or 1)	C2RXM0SID	7B0	*****	C2RXF13SID	7F4	*****
C2CTRL1	780	0000010010000000	C2RXM0EID	7B2	*****	C2RXF13EID	7F6	*****
C2CTRL2	782	000000000000000000000000000000000000000	C2RXM1SID	7B4	*****	C2RXF14SID	7F8	*****
C2VEC	784	000000001000000	C2RXM1EID	7B6	*****	C2RXF14EID	7FA	*****
C2FCTRL	786	000000000000000000000000000000000000000	C2RXM2SID	7B8	*****	C2RXF15SID	7FC	*****
C2FIFO	788	000000000000000000000000000000000000000	C2RXM2EID	7BA	*****	C2RXF15EID	7FE	*****

TABLE 4-9:SFR BLOCK 700h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
Interrupt Cont	roller		IEC9	832	000000000000000000	IPC26	874	000000001000100
IFS0	800	000000000000000000	IEC10	834	000000000000000000000000000000000000000	IPC27	876	0100010000000000
IFS1	802	000000000000000000	IEC11	836	000000000000000000000000000000000000000	IPC28	878	0100010001000100
IFS2	804	000000000000000000	IPC0	840	0100010001000100	IPC29	87A	0000000001000100
IFS3	806	000000000000000000	IPC1	842	0100010001000000	IPC35	886	0100010000000000
IFS4	808	000000000000000000	IPC2	844	0100010001000100	IPC36	888	00000000000000000
IFS5	80A	000000000000000000	IPC3	846	010000001000100	IPC37	88A	01000000000000000
IFS6	80C	000000000000000000	IPC4	848	0100010001000100	IPC38	88C	0100010001000100
IFS7	80E	000000000000000000	IPC5	84A	0000000000000100	IPC39	88E	0100010001000100
IFS8	810	000000000000000000	IPC6	84C	0100010001000000	IPC40	890	0100010001000100
IFS9	812	000000000000000000	IPC7	84E	0100010001000100	IPC41	892	0100010001000100
IFS10	814	000000000000000000	IPC8	850	0000000001000100	IPC42	894	0000000001000100
IFS11	816	000000000000000000	IPC9	852	0000010001000000	IPC43	896	0000010001000000
IEC0	820	000000000000000000	IPC11	856	000000000000000000000000000000000000000	IPC44	898	0100010001000000
IEC1	822	000000000000000000	IPC12	858	0000010001000000	IPC45	89A	0000000000000100
IEC2	824	000000000000000000	IPC13	85A	0000010000000000	IPC46	89C	0100010000000000
IEC3	826	000000000000000000	IPC14	85C	0000000001000000	IPC47	89E	0000010001000100
IEC4	828	000000000000000000	IPC16	860	0000010001000000	INTCON1	8C0	000000000000000000
IEC5	82A	000000000000000000	IPC18	864	000000001000000	INTCON2	8C2	000000000000000000
IEC6	82C	000000000000000000	IPC23	86E	0100010000000000	INTCON3	8C4	000000000000000000
IEC7	82E	000000000000000000	IPC24	870	0000010001000100	INTCON4	8C6	000000000000000000
IEC8	830	000000000000000000	IPC25	872	01000000000000000	INTTREG	8C8	000000000000000000

TABLE 4-10: SFR BLOCK 800h

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

TABLE 4-11: SFR BLOCK 900h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
Output Compa	re		OC3R	91A	*****	CLC2CONH	9CE	000000000000000000000000000000000000000
OC1CON1	900	000000000000000000	OC3TMR	91C	000000000000000000000000000000000000000	CLC2SEL	9D0	000000000000000000000000000000000000000
OC1CON2	902	0000000000001100	OC4CON1	91E	000000000000000000000000000000000000000	CLC2GLSL	9D4	000000000000000000000000000000000000000
OC1RS	904	*****	OC4CON2	920	000000000001100	CLC2GLSH	9D6	000000000000000000000000000000000000000
OC1R	906	*****	OC4RS	922	*****	CLC3CONL	9D8	000000000000000000000000000000000000000
OC1TMR	908	000000000000000000	OC4R	924	*****	CLC3CONH	9DA	000000000000000000000000000000000000000
OC2CON1	90A	000000000000000000	OC4TMR	926	000000000000000000000000000000000000000	CLC3SEL	9DC	000000000000000000000000000000000000000
OC2CON2	90C	0000000000001100	CLC			CLC3GLSL	9E0	000000000000000000000000000000000000000
OC2RS	90E	*****	CLC1CONL	9C0	000000000000000000000000000000000000000	CLC3GLSH	9E2	000000000000000000000000000000000000000
OC2R	910	*****	CLC1CONH	9C2	000000000000000000000000000000000000000	CLC4CONL	9E4	000000000000000000000000000000000000000
OC2TMR	912	000000000000000000000000000000000000000	CLC1SEL	9C4	000000000000000000000000000000000000000	CLC4CONH	9E6	000000000000000000000000000000000000000
OC3CON1	914	000000000000000000	CLC1GLSL	9C8	000000000000000000000000000000000000000	CLC4SEL	9E8	000000000000000000000000000000000000000
OC3CON2	916	0000000000001100	CLC1GLSH	9CA	000000000000000000000000000000000000000	CLC4GLSL	9EC	000000000000000000000000000000000000000
OC3RS	918	*****	CLC2CONL	9CC	000000000000000000000000000000000000000	CLC4GLSH	9EE	000000000000000000000000000000000000000

TABLE 4-12: SFR BLOCK A00h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
PTG			PTGADJ	AD2	000000000000000000000000000000000000000	PTGQUE7	AE6	*****
PTGCST	AC0	000000000000000000	PTGL0	AD4	000000000000000000000000000000000000000	PTGQUE8	AE8	*****
PTGCON	AC2	000000000000000000	PTGQPTR	AD6	000000000000000000000000000000000000000	PTGQUE9	AEA	*****
PTGBTE	AC4	000000000000000000	PTGQUE0	AD8	*****	PTGQUE10	AEC	*****
PTGHOLD	AC6	000000000000000000	PTGQUE1	ADA	*****	PTGQUE11	AEE	*****
PTGT0LIM	AC8	000000000000000000	PTGQUE2	ADC	*****	PTGQUE12	AF0	*****
PTGT1LIM	ACA	000000000000000000	PTGQUE3	ADE	*****	PTGQUE13	AF2	*****
PTGSDLIM	ACC	000000000000000000	PTGQUE4	AE0	*****	PTGQUE14	AF4	*****
PTGC0LIM	ACE	000000000000000000	PTGQUE5	AE2	*****	PTGQUE15	AF6	*****
PTGC1LIM	AD0	000000000000000000	PTGQUE6	AE4	*****			

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

TABLE 4-13: SFR BLOCK B00h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
DMA			DMA1STBL	B18	000000000000000000	DMA3REQ	B32	000000000000000000000000000000000000000
DMA0CON	B00	000000000000000000	DMA1STBH	B1A	000000000000000000	DMA3STAL	B34	000000000000000000000000000000000000000
DMA0REQ	B02	000000000000000000	DMA1PAD	B1C	000000000000000000	DMA3STAH	B36	000000000000000000000000000000000000000
DMA0STAL	B04	000000000000000000	DMA1CNT	B1E	000000000000000000	DMA3STBL	B38	000000000000000000000000000000000000000
DMA0STAH	B06	000000000000000000	DMA2CON	B20	000000000000000000	DMA3STBH	B3A	000000000000000000000000000000000000000
DMA0STBL	B08	000000000000000000	DMA2REQ	B22	000000000000000000	DMA3PAD	B3C	000000000000000000000000000000000000000
DMA0STBH	B0A	000000000000000000	DMA2STAL	B24	000000000000000000	DMA3CNT	B3E	000000000000000000000000000000000000000
DMA0PAD	B0C	000000000000000000	DMA2STAH	B26	000000000000000000	DMAPWC	BF0	000000000000000000000000000000000000000
DMA0CNT	B0E	000000000000000000	DMA2STBL	B28	000000000000000000	DMARQC	BF2	000000000000000000000000000000000000000
DMA1CON	B10	000000000000000000	DMA2STBH	B2A	000000000000000000	DMAPPS	BF4	000000000000000000000000000000000000000
DMA1REQ	B12	000000000000000000	DMA2PAD	B2C	000000000000000000000000000000000000000	DMALCA	BF6	000000000001111
DMA1STAL	B14	000000000000000000	DMA2CNT	B2E	000000000000000000000000000000000000000	DSADRL	BF8	000000000000000000000000000000000000000
DMA1STAH	B16	00000000000000000	DMA3CON	B30	000000000000000000000000000000000000000	DSADRH	BFA	000000000000000000000000000000000000000

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
PWM			FCLCON3	C64	000000000000000000	IOCON6	CC2	110000000000000000000000000000000000000
PTCON	C00	000000000000000000	PDC3	C66	000000000000000000	FCLCON6	CC4	000000000000000000000000000000000000000
PTCON2	C02	000000000000000000	PHASE3	C68	000000000000000000	PDC6	CC6	000000000000000000000000000000000000000
PTPER	C04	111111111111000	DTR3	C6A	000000000000000000	PHASE6	CC8	000000000000000000000000000000000000000
SEVTCMP	C06	000000000000000000	ALTDTR3	C6C	000000000000000000	DTR6	CCA	000000000000000000000000000000000000000
MDC	C0A	000000000000000000	SDC3	C6E	000000000000000000	ALTDTR6	CCC	000000000000000000000000000000000000000
STCON	C0E	000000000000000000	SPHASE3	C70	000000000000000000	SDC6	CCE	000000000000000000000000000000000000000
STCON2	C10	000000000000000000	TRIG3	C72	000000000000000000	SPHASE6	CD0	000000000000000000000000000000000000000
STPER	C12	111111111111000	TRGCON3	C74	000000000000000000	TRIG6	CD2	000000000000000000000000000000000000000
SSEVTCMP	C14	000000000000000000	STRIG3	C76	000000000000000000	TRGCON6	CD4	000000000000000000000000000000000000000
CHOP	C1A	000000000000000000	PWMCAP3	C78	000000000000000000	STRIG6	CD6	000000000000000000000000000000000000000
PWMKEY	C1E	*****	LEBCON3	C7A	000000000000000000	PWMCAP6	CD8	000000000000000000000000000000000000000
PWM Generato	r		LEBDLY3	C7C	000000000000000000	LEBCON6	CDA	000000000000000000000000000000000000000
PWMCON1	C20	00000000000000000	AUXCON3	C7E	000000000000000000000000000000000000000	LEBDLY6	CDC	000000000000000000000000000000000000000
IOCON1	C22	110000000000000000	PWMCON4	C80	000000000000000000	AUXCON6	CDE	000000000000000000000000000000000000000
FCLCON1	C24	000000000000000000	IOCON4	C82	110000000000000000	PWMCON7	CE0	000000000000000000000000000000000000000
PDC1	C26	000000000000000000	FCLCON4	C84	000000000000000000	IOCON7	CE2	110000000000000000
PHASE1	C28	000000000000000000	PDC4	C86	000000000000000000	FCLCON7	CE4	000000000000000000000000000000000000000
DTR1	C2A	000000000000000000000000000000000000000	PHASE4	C88	000000000000000000	PDC7	CE6	000000000000000000000000000000000000000
ALTDTR1	C2C	000000000000000000000000000000000000000	DTR4	C8A	000000000000000000	PHASE7	CE8	000000000000000000000000000000000000000
SDC1	C2E	000000000000000000000000000000000000000	ALTDTR4	C8C	000000000000000000	DTR7	CEA	000000000000000000000000000000000000000
SPHASE1	C30	000000000000000000000000000000000000000	SDC4	C8E	000000000000000000	ALTDTR7	CEC	000000000000000000000000000000000000000
TRIG1	C32	000000000000000000000000000000000000000	SPHASE4	C90	000000000000000000000000000000000000000	SDC7	CEE	000000000000000000000000000000000000000
TRGCON1	C34	000000000000000000000000000000000000000	TRIG4	C92	000000000000000000	SPHASE7	CF0	000000000000000000000000000000000000000
STRIG1	C36	000000000000000000000000000000000000000	TRGCON4	C94	000000000000000000000000000000000000000	TRIG7	CF2	000000000000000000000000000000000000000
PWMCAP1	C38	000000000000000000000000000000000000000	STRIG4	C96	000000000000000000	TRGCON7	CF4	000000000000000000000000000000000000000
LEBCON1	C3A	000000000000000000000000000000000000000	PWMCAP4	C98	000000000000000000000000000000000000000	STRIG7	CF6	000000000000000000000000000000000000000
LEBDLY1	C3C	000000000000000000000000000000000000000	LEBCON4	C9A	000000000000000000000000000000000000000	PWMCAP7	CF8	000000000000000000000000000000000000000
AUXCON1	C3E	000000000000000000000000000000000000000	LEBDLY4	C9C	000000000000000000000000000000000000000	LEBCON7	CFA	000000000000000000000000000000000000000
PWMCON2	C40	000000000000000000000000000000000000000	AUXCON4	C9E	000000000000000000000000000000000000000	LEBDLY7	CFC	000000000000000000000000000000000000000
IOCON2	C42	110000000000000000	PWMCON5	CA0	000000000000000000000000000000000000000	AUXCON7	CFE	000000000000000000000000000000000000000
FCLCON2	C44	000000000000000000000000000000000000000	IOCON5	CA2	110000000000000000	PWMCON8	D00	000000000000000000000000000000000000000
PDC2	C46	000000000000000000000000000000000000000	FCLCON5	CA4	000000000000000000000000000000000000000	IOCON8	D02	110000000000000000
PHASE2	C48	000000000000000000000000000000000000000	PDC5	CA6	000000000000000000000000000000000000000	FCLCON8	D04	000000000000000000000000000000000000000
DTR2	C4A	000000000000000000000000000000000000000	PHASE5	CA8	000000000000000000000000000000000000000	PDC8	D06	000000000000000000000000000000000000000
ALTDTR2	C4C	000000000000000000000000000000000000000	DTR5	CAA	000000000000000000	PHASE8	D08	000000000000000000000000000000000000000
SDC2	C4E	000000000000000000000000000000000000000	ALTDTR5	CAC	000000000000000000000000000000000000000	ALTDTR8	D0C	000000000000000000000000000000000000000
SPHASE2	C50	000000000000000000000000000000000000000	SDC5	CAE	000000000000000000000000000000000000000	SDC8	D0E	000000000000000000000000000000000000000
TRIG2	C52	000000000000000000000000000000000000000	SPHASE5	CB0	000000000000000000000000000000000000000	SPHASE8	D10	000000000000000000000000000000000000000
TRGCON2	C54	000000000000000000000000000000000000000	TRIG5	CB2	000000000000000000000000000000000000000	TRIG8	D12	000000000000000000000000000000000000000
STRIG2	C56	000000000000000000000000000000000000000	TRGCON5	CB4	000000000000000000000000000000000000000	TRGCON8	D14	000000000000000000000000000000000000000
PWMCAP2	C58	000000000000000000000000000000000000000	STRIG5	CB6	000000000000000000000000000000000000000	STRIG8	D16	000000000000000000000000000000000000000
LEBCON2	C5A	000000000000000000000000000000000000000	PWMCAP5	CB8	000000000000000000000000000000000000000	PWMCAP8	D18	000000000000000000000000000000000000000
LEBDLY2	C5C	000000000000000000000000000000000000000	LEBCON5	CBA	000000000000000000000000000000000000000	LEBCON8	D1A	000000000000000000000000000000000000000
AUXCON2	C5E	000000000000000000000000000000000000000	LEBDLY5	CBC	000000000000000000000000000000000000000	LEBDLY8	D1C	000000000000000000000000000000000000000
PWMCON3	C60	000000000000000000000000000000000000000	AUXCON5	CBE	000000000000000000000000000000000000000	AUXCON8	D1E	000000000000000000000000000000000000000
				000				

TABLE 4-14: SFR BLOCK C00h-D00h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
PORTA			ANSELB	E1E	0000001011101111	CNPDD	E3C	000000000000000000000000000000000000000
TRISA	E00	000000000011111	PORTC			ANSELD	E3E	0010000110100100
PORTA	E02	000000000000000000	TRISC	E20	1111011111111111	PORTE	•	
LATA	E04	000000000000000000	PORTC	E22	000000000000000000	TRISE	E40	111111111111111111
ODCA	E06	000000000000000000	LATC	E24	000000000000000000	PORTE	E42	000000000000000000000000000000000000000
CNENA	E08	000000000000000000	ODCC	E26	000000000000000000	LATE	E44	000000000000000000000000000000000000000
CNPUA	E0A	000000000000000000	CNENC	E28	000000000000000000	ODCE	E46	000000000000000000000000000000000000000
CNPDA	E0C	000000000000000000	CNPUC	E2A	000000000000000000	CNENE	E48	000000000000000000000000000000000000000
ANSELA	E0E	000000000000111	CNPDC	E2C	000000000000000000	CNPUE	E4A	000000000000000000000000000000000000000
PORTB	•		ANSELC	E2E	0001011001110110	CNPDE	E4C	000000000000000000
TRISB	E10	1111101111111111	PORTD			ANSELE	E4E	000000000000000000
PORTB	E12	000000000000000000	TRISD	E30	111111111111111111	CPU	•	
LATB	E14	000000000000000000	PORTD	E32	000000000000000000	VISI	F88	0000000000000000000
ODCB	E16	000000000000000000	LATD	E34	000000000000000000	JTAG	•	
CNENB	E18	000000000000000000	ODCD	E36	000000000000000000	JDATAH	FF0	000000000000000000
CNPUB	E1A	000000000000000000	CNEND	E38	000000000000000000	JDATAL	FF2	0000000000000000000
CNPDB	E1C	000000000000000000	CNPUD	E3A	000000000000000000			

TABLE 4-15: SFR BLOCK E00h-F00h

4.5.1 PAGED MEMORY SCHEME

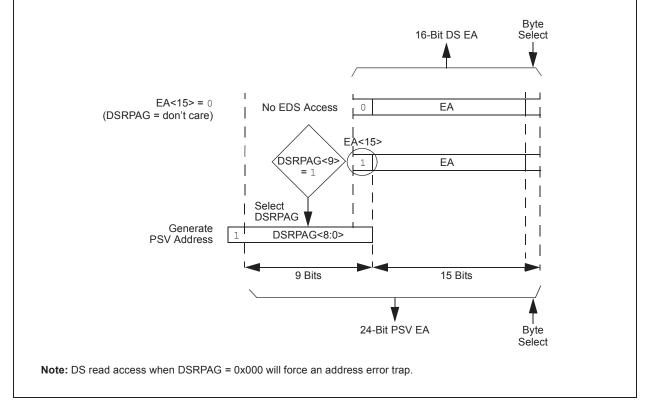
The dsPIC33EPXXXGS70X/80X family architecture extends the available Data Space through a paging scheme, which allows the available Data Space to be accessed using MOV instructions in a linear fashion for pre- and post-modified Effective Addresses (EAs). The upper half of the base Data Space address is used in conjunction with the Data Space Read Page (DSRPAG) register to form the Program Space Visibility (PSV) address.

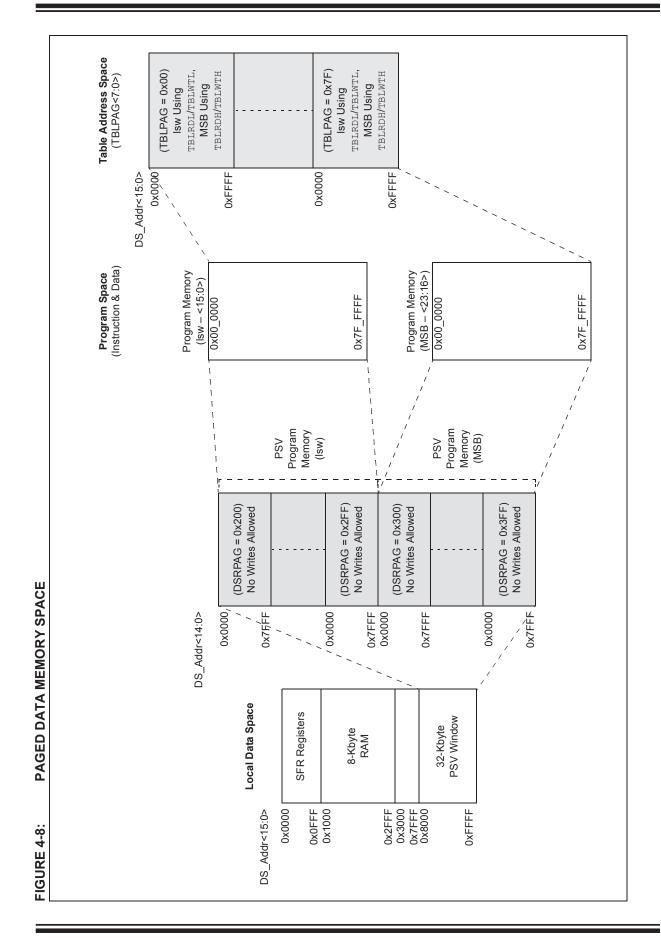
The Data Space Read Page (DSRPAG) register is located in the SFR space. Construction of the PSV address is shown in Figure 4-7. When DSRPAG<9> = 1 and the base address bit, EA<15> = 1, the DSRPAG<8:0> bits are concatenated onto EA<14:0> to form the 24-bit PSV read address.

The paged memory scheme provides access to multiple 32-Kbyte windows in the PSV memory. The Data Space Read Page (DSRPAG) register, in combination with the upper half of the Data Space address, can provide up to 8 Mbytes of PSV address space. The paged data memory space is shown in Figure 4-8.

The Program Space (PS) can be accessed with a DSRPAG of 0x200 or greater. Only reads from PS are supported using the DSRPAG register.







When a PSV page overflow or underflow occurs, EA<15> is cleared as a result of the register indirect EA calculation. An overflow or underflow of the EA in the PSV pages can occur at the page boundaries when:

- The initial address, prior to modification, addresses the PSV page
- The EA calculation uses Pre- or Post-Modified Register Indirect Addressing; however, this does not include Register Offset Addressing

In general, when an overflow is detected, the DSRPAG register is incremented and the EA<15> bit is set to keep the base address within the PSV window. When an underflow is detected, the DSRPAG register is decremented and the EA<15> bit is set to keep the base

address within the PSV window. This creates a linear PSV address space, but only when using Register Indirect Addressing modes.

Exceptions to the operation described above arise when entering and exiting the boundaries of Page 0 and PSV spaces. Table 4-16 lists the effects of overflow and underflow scenarios at different boundaries.

In the following cases, when overflow or underflow occurs, the EA<15> bit is set and the DSRPAG is not modified; therefore, the EA will wrap to the beginning of the current page:

- Register Indirect with Register Offset Addressing
- Modulo Addressing
- Bit-Reversed Addressing

TABLE 4-16 :	OVERFLOW AND UNDERFLOW SCENARIOS AT PAGE 0 AND
	PSV SPACE BOUNDARIES ^(2,3,4)

O/U,			Before		After			
0/0, R/W	Operation	DSxPAG	DS EA<15>	Page Description	DSxPAG	DS EA<15>	Page Description	
O, Read	[++Wn]	DSRPAG = 0x2FF	1	PSV: Last Isw page	DSRPAG = 0x300	1	PSV: First MSB page	
O, Read	Or [Wn++]	DSRPAG = 0x3FF	1	PSV: Last MSB page	DSRPAG = 0x3FF	0	See Note 1	
U, Read		DSRPAG = 0x001	1	PSV page	DSRPAG = 0x001	0	See Note 1	
U, Read	[Wn] Or [Wn]	DSRPAG = 0x200	1	PSV: First Isw page	DSRPAG = 0x200	0	See Note 1	
U, Read		DSRPAG = 0x300	1	PSV: First MSB page	DSRPAG = 0x2FF	1	PSV: Last Isw page	

Legend: O = Overflow, U = Underflow, R = Read, W = Write

Note 1: The Register Indirect Addressing now addresses a location in the base Data Space (0x0000-0x7FFF).

2: An EDS access, with DSRPAG = 0x000, will generate an address error trap.

3: Only reads from PS are supported using DSRPAG.

4: Pseudolinear Addressing is not supported for large offsets.

4.5.2 EXTENDED X DATA SPACE

The lower portion of the base address space range, between 0x0000 and 0x7FFF, is always accessible, regardless of the contents of the Data Space Read Page register. It is indirectly addressable through the register indirect instructions. It can be regarded as being located in the default EDS Page 0 (i.e., EDS address range of 0x000000 to 0x007FFF with the base address bit, EA<15> = 0, for this address range). However, Page 0 cannot be accessed through the upper 32 Kbytes, 0x8000 to 0xFFFF, of base Data Space in combination with DSRPAG = 0x000. Consequently, DSRPAG is initialized to 0x001 at Reset.

- Note 1: DSRPAG should not be used to access Page 0. An EDS access with DSRPAG set to 0x000 will generate an address error trap.
 - 2: Clearing the DSRPAG in software has no effect.

The remaining PSV pages are only accessible using the DSRPAG register in combination with the upper 32 Kbytes, 0x8000 to 0xFFFF, of the base address, where base address bit, EA<15> = 1.

4.5.3 SOFTWARE STACK

The W15 register serves as a dedicated Software Stack Pointer (SSP), and is automatically modified by exception processing, subroutine calls and returns; however, W15 can be referenced by any instruction in the same manner as all other W registers. This simplifies reading, writing and manipulating the Stack Pointer (for example, creating stack frames).

Note: To protect against misaligned stack accesses, W15<0> is fixed to '0' by the hardware.

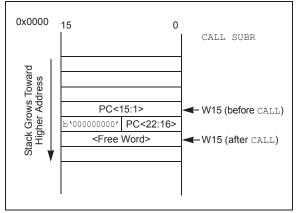
W15 is initialized to 0x1000 during all Resets. This address ensures that the SSP points to valid RAM in all dsPIC33EPXXXGS70X/80X devices and permits stack availability for non-maskable trap exceptions. These can occur before the SSP is initialized by the user software. You can reprogram the SSP during initialization to any location within Data Space.

The Software Stack Pointer always points to the first available free word and fills the software stack, working from lower toward higher addresses. Figure 4-9 illustrates how it pre-decrements for a stack pop (read) and post-increments for a stack push (writes).

When the PC is pushed onto the stack, PC<15:0> are pushed onto the first available stack word, then PC<22:16> are pushed into the second available stack location. For a PC push during any CALL instruction, the MSB of the PC is zero-extended before the push, as shown in Figure 4-9. During exception processing, the MSB of the PC is concatenated with the lower eight bits of the CPU STATUS Register, SR. This allows the contents of SRL to be preserved automatically during interrupt processing.

- **Note 1:** To maintain system Stack Pointer (W15) coherency, W15 is never subject to (EDS) paging, and is therefore, restricted to an address range of 0x0000 to 0xFFFF. The same applies to W14 when used as a Stack Frame Pointer (SFA = 1).
 - 2: As the stack can be placed in, and can access X and Y spaces, care must be taken regarding its use, particularly with regard to local automatic variables in a C development environment





4.6 Instruction Addressing Modes

The addressing modes shown in Table 4-17 form the basis of the addressing modes optimized to support the specific features of individual instructions. The addressing modes provided in the MAC class of instructions differ from those in the other instruction types.

4.6.1 FILE REGISTER INSTRUCTIONS

Most file register instructions use a 13-bit address field (f) to directly address data present in the first 8192 bytes of data memory (Near Data Space). Most file register instructions employ a Working register, W0, which is denoted as WREG in these instructions. The destination is typically either the same file register or WREG (with the exception of the MUL instruction), which writes the result to a register or register pair. The MOV instruction allows additional flexibility and can access the entire Data Space.

4.6.2 MCU INSTRUCTIONS

The three-operand MCU instructions are of the form:

Operand 3 = Operand 1 <function> Operand 2

where Operand 1 is always a Working register (that is, the addressing mode can only be Register Direct), which is referred to as Wb. Operand 2 can be a W register fetched from data memory or a 5-bit literal. The result location can either be a W register or a data memory location. The following addressing modes are supported by MCU instructions:

- Register Direct
- Register Indirect
- · Register Indirect Post-Modified
- Register Indirect Pre-Modified
- 5-Bit or 10-Bit Literal
 - Note: Not all instructions support all the addressing modes given above. Individual instructions can support different subsets of these addressing modes.

TABLE 4-17: FUNDAMENTAL ADDRESSING MODES SUPPORTED

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn form the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn form the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

4.6.3 MOVE AND ACCUMULATOR INSTRUCTIONS

Move instructions, and the DSP accumulator class of instructions, provide a greater degree of addressing flexibility than other instructions. In addition to the addressing modes supported by most MCU instructions, move and accumulator instructions also support Register Indirect with Register Offset Addressing mode, also referred to as Register Indexed mode.

Note: For the MOV instructions, the addressing mode specified in the instruction can differ for the source and destination EA. However, the 4-bit Wb (Register Offset) field is shared by both source and destination (but typically only used by one).

In summary, the following addressing modes are supported by move and accumulator instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-modified
- Register Indirect Pre-modified
- Register Indirect with Register Offset (Indexed)
- Register Indirect with Literal Offset
- 8-Bit Literal
- 16-Bit Literal
- **Note:** Not all instructions support all the addressing modes given above. Individual instructions may support different subsets of these addressing modes.

4.6.4 MAC INSTRUCTIONS

The dual source operand DSP instructions (CLR, ED, EDAC, MAC, MPY, MPY. N, MOVSAC and MSC), also referred to as MAC instructions, use a simplified set of addressing modes to allow the user application to effectively manipulate the Data Pointers through register indirect tables.

The two-source operand prefetch registers must be members of the set {W8, W9, W10, W11}. For data reads, W8 and W9 are always directed to the X RAGU, and W10 and W11 are always directed to the Y AGU. The Effective Addresses generated (before and after modification) must therefore, be valid addresses within X Data Space for W8 and W9, and Y Data Space for W10 and W11.

Note: Register Indirect with Register Offset Addressing mode is available only for W9 (in X space) and W11 (in Y space).

In summary, the following addressing modes are supported by the ${\tt MAC}$ class of instructions:

- Register Indirect
- Register Indirect Post-Modified by 2
- · Register Indirect Post-Modified by 4
- Register Indirect Post-Modified by 6
- Register Indirect with Register Offset (Indexed)

4.6.5 OTHER INSTRUCTIONS

Besides the addressing modes outlined previously, some instructions use literal constants of various sizes. For example, BRA (branch) instructions use 16-bit signed literals to specify the branch destination directly, whereas the DISI instruction uses a 14-bit unsigned literal field. In some instructions, such as ULNK, the source of an operand or result is implied by the opcode itself. Certain operations, such as a NOP, do not have any operands.

4.7 Modulo Addressing

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either Data or Program Space (since the Data Pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into Program Space) and Y Data Spaces. Modulo Addressing can operate on any W Register Pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing since these two registers are used as the Stack Frame Pointer and Stack Pointer, respectively.

In general, any particular circular buffer can be configured to operate in only one direction, as there are certain restrictions on the buffer start address (for incrementing buffers) or end address (for decrementing buffers), based upon the direction of the buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a Bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

4.7.1 START AND END ADDRESS

The Modulo Addressing scheme requires that a starting and ending address be specified and loaded into the 16-bit Modulo Buffer Address registers: XMODSRT, XMODEND, YMODSRT and YMODEND (see Table 4-2).

Note: Y space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear).

The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

4.7.2 W ADDRESS REGISTER SELECTION

The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags, as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that operate with Modulo Addressing:

- If XWM = 1111, X RAGU and X WAGU Modulo Addressing is disabled
- If YWM = 1111, Y AGU Modulo Addressing is disabled

The X Address Space Pointer W (XWM) register, to which Modulo Addressing is to be applied, is stored in MODCON<3:0> (see Table 4-2). Modulo Addressing is enabled for X Data Space when XWM is set to any value other than '1111' and the XMODEN bit is set (MODCON<15>).

The Y Address Space Pointer W (YWM) register, to which Modulo Addressing is to be applied, is stored in MODCON<7:4>. Modulo Addressing is enabled for Y Data Space when YWM is set to any value other than '1111' and the YMODEN bit (MODCON<14>) is set.

FIGURE 4-10: MODULO ADDRESSING OPERATION EXAMPLE

Byte Address		MOV MOV MOV	#0x1100, W0 W0, XMODSRT #0x1163, W0	;set modulo start address
0x1100		MOV MOV	#0x1103, W0 W0, MODEND #0x8001, W0	;set modulo end address
		MOV	W0, MODCON	;enable W1, X AGU for modulo
	↓ ()	MOV		;WO holds buffer fill value
0x1163	\square	MOV	#0x1110, W1	;point W1 to buffer
		DO MOV	AGAIN, #0x31 W0, [W1++]	;fill the 50 buffer locations ;fill the next location
E	Start Addr = 0x1100 End Addr = 0x1163 Length = 0x0032 words	AGAIN:	INC W0, W0	;increment the fill value

4.7.3 MODULO ADDRESSING APPLICABILITY

Modulo Addressing can be applied to the Effective Address (EA) calculation associated with any W register. Address boundaries check for addresses equal to:

- The upper boundary addresses for incrementing buffers
- The lower boundary addresses for decrementing buffers

It is important to realize that the address boundaries check for addresses less than or greater than the upper (for incrementing buffers) and lower (for decrementing buffers) boundary addresses (not just equal to). Address changes can therefore, jump beyond boundaries and still be adjusted correctly.

Note: The modulo corrected Effective Address is written back to the register only when Pre-Modify or Post-Modify Addressing mode is used to compute the Effective Address. When an address offset (such as [W7 + W2]) is used, Modulo Addressing correction is performed, but the contents of the register remain unchanged.

4.8 Bit-Reversed Addressing

Bit-Reversed Addressing mode is intended to simplify data reordering for radix-2 FFT algorithms. It is supported by the X AGU for data writes only.

The modifier, which can be a constant value or register contents, is regarded as having its bit order reversed. The address source and destination are kept in normal order. Thus, the only operand requiring reversal is the modifier.

4.8.1 BIT-REVERSED ADDRESSING IMPLEMENTATION

Bit-Reversed Addressing mode is enabled when all of these situations are met:

- BWMx bits (W register selection) in the MODCON register are any value other than '1111' (the stack cannot be accessed using Bit-Reversed Addressing)
- The BREN bit is set in the XBREV register
- The addressing mode used is Register Indirect with Pre-Increment or Post-Increment

If the length of a bit-reversed buffer is $M = 2^N$ bytes, the last 'N' bits of the data buffer start address must be zeros.

XB<14:0> is the Bit-Reversed Addressing modifier, or 'pivot point', which is typically a constant. In the case of an FFT computation, its value is equal to half of the FFT data buffer size.

Note:	All bit-reversed EA calculations assume word-sized data (LSb of every EA is always clear). The XB value is scaled accordingly to generate compatible (byte)
	addresses.

When enabled, Bit-Reversed Addressing is executed only for Register Indirect with Pre-Increment or Post-Increment Addressing and word-sized data writes. It does not function for any other addressing mode or for byte-sized data and normal addresses are generated instead. When Bit-Reversed Addressing is active, the W Address Pointer is always added to the address modifier (XB) and the offset associated with the Register Indirect Addressing mode is ignored. In addition, as word-sized data is a requirement, the LSb of the EA is ignored (and always clear).

Note:	Modulo Addressing and Bit-Reversed
	Addressing can be enabled simultaneously
	using the same W register, but Bit-
	Reversed Addressing operation will always
	take precedence for data writes when enabled.

If Bit-Reversed Addressing has already been enabled by setting the BREN (XBREV<15>) bit, a write to the XBREV register should not be immediately followed by an indirect read operation using the W register that has been designated as the Bit-Reversed Pointer.

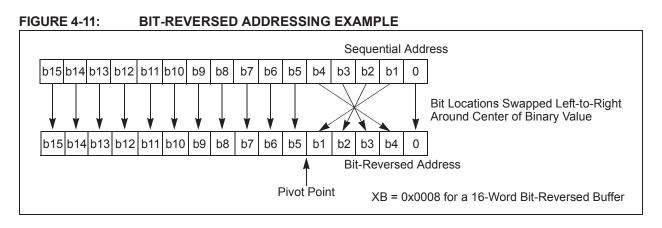


TABLE 4-18: BIT-REVERSED ADDRESSING SEQUENCE (16-ENTRY)

		Norma	al Addres	ss			Bit-Rev	ersed Ac	ldress
A3	A2	A1	A0	Decimal	A3	A2	A1	A0	Decimal
0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	8
0	0	1	0	2	0	1	0	0	4
0	0	1	1	3	1	1	0	0	12
0	1	0	0	4	0	0	1	0	2
0	1	0	1	5	1	0	1	0	10
0	1	1	0	6	0	1	1	0	6
0	1	1	1	7	1	1	1	0	14
1	0	0	0	8	0	0	0	1	1
1	0	0	1	9	1	0	0	1	9
1	0	1	0	10	0	1	0	1	5
1	0	1	1	11	1	1	0	1	13
1	1	0	0	12	0	0	1	1	3
1	1	0	1	13	1	0	1	1	11
1	1	1	0	14	0	1	1	1	7
1	1	1	1	15	1	1	1	1	15

4.9 Interfacing Program and Data Memory Spaces

The dsPIC33EPXXXGS70X/80X family architecture uses a 24-bit wide Program Space (PS) and a 16-bit wide Data Space (DS). The architecture is also a modified Harvard scheme, meaning that data can also be present in the Program Space. To use this data successfully, it must be accessed in a way that preserves the alignment of information in both spaces.

Aside from normal execution, the architecture of the dsPIC33EPXXXGS70X/80X family devices provides two methods by which Program Space can be accessed during operation:

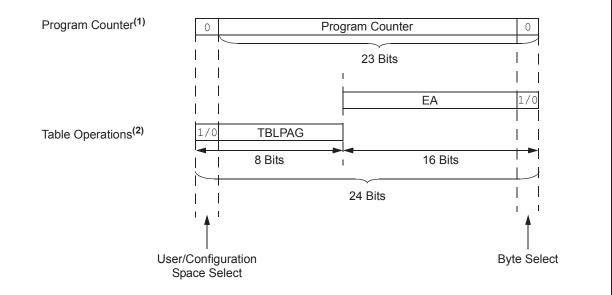
- Using table instructions to access individual bytes or words anywhere in the Program Space
- Remapping a portion of the Program Space into the Data Space (Program Space Visibility)

Table instructions allow an application to read or write to small areas of the program memory. This capability makes the method ideal for accessing data tables that need to be updated periodically. It also allows access to all bytes of the program word. The remapping method allows an application to access a large block of data on a read-only basis, which is ideal for look-ups from a large table of static data. The application can only access the least significant word of the program word.

TABLE 4-19: PROGRAM SPACE ADDRESS CONSTRUCTION

	Access	Program Space Address							
Access Type	Space	<23>	<22:16>	<15>	<14:1>	<0>			
Instruction Access	User	0		PC<22:1>					
(Code Execution)		0xxx xxxx xxxx xxxx xxxx xxx0							
TBLRD/TBLWT	User	TB	LPAG<7:0>		Data EA<15:0>				
(Byte/Word Read/Write)		02	XXX XXXX	XXXX XXXX XXXX XXXX					
	Configuration	TB	LPAG<7:0>	Data EA<15:0>					
		1>	***	****					

FIGURE 4-12: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION



Note 1: The Least Significant bit (LSb) of Program Space addresses is always fixed as '0' to maintain word alignment of data in the Program and Data Spaces.

2: Table operations are not required to be word-aligned. Table Read operations are permitted in the configuration memory space.

4.9.1 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The TBLRDL and TBLWTL instructions offer a direct method of reading or writing the lower word of any address within the Program Space without going through Data Space. The TBLRDH and TBLWTH instructions are the only method to read or write the upper eight bits of a Program Space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to Data Space addresses. Program memory can thus be regarded as two 16-bit wide word address spaces, residing side by side, each with the same address range. TBLRDL and TBLWTL access the space that contains the least significant data word. TBLRDH and TBLWTH access the space that contains the upper data byte.

Two table instructions are provided to move byte or word-sized (16-bit) data to and from Program Space. Both function as either byte or word operations.

- TBLRDL (Table Read Low):
 - In Word mode, this instruction maps the lower word of the Program Space location (P<15:0>) to a data address (D<15:0>)
 - In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when Byte Select is '1'; the lower byte is selected when it is '0'.

- TBLRDH (Table Read High):
 - In Word mode, this instruction maps the entire upper word of a program address (P<23:16>) to a data address. The 'phantom' byte (D<15:8>) is always '0'.
 - In Byte mode, this instruction maps the upper or lower byte of the program word to D<7:0> of the data address in the TBLRDL instruction. The data is always '0' when the upper 'phantom' byte is selected (Byte Select = 1).

In a similar fashion, two table instructions, TBLWTH and TBLWTL, are used to write individual bytes or words to a Program Space address. The details of their operation are explained in Section 5.0 "Flash Program Memory".

For all table operations, the area of program memory space to be accessed is determined by the Table Page register (TBLPAG). TBLPAG covers the entire program memory space of the device, including user application and configuration spaces. When TBLPAG<7> = 0, the table page is located in the user memory space. When TBLPAG<7> = 1, the page is located in configuration space.

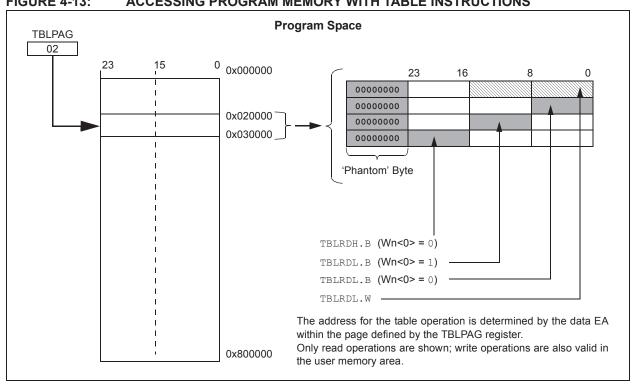


FIGURE 4-13: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS

NOTES:

5.0 FLASH PROGRAM MEMORY

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Dual Partition Flash Program Memory" (DS70005156) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com)
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family devices contain internal Program Flash Memory for storing and executing application code. The memory is readable, writable and erasable during normal operation over the entire VDD range.

Flash memory can be programmed in three ways:

- In-Circuit Serial Programming™ (ICSP™) programming capability
- Enhanced In-Circuit Serial Programming (Enhanced ICSP)
- Run-Time Self-Programming (RTSP)

ICSP allows for a dsPIC33EPXXXGS70X/80X family device to be serially programmed while in the end application circuit. This is done with a programming clock and programming data (PGECx/PGEDx) line, and three other lines for power (VDD), ground (VSS) and Master Clear (MCLR). This allows customers to

manufacture boards with unprogrammed devices and then program the device just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

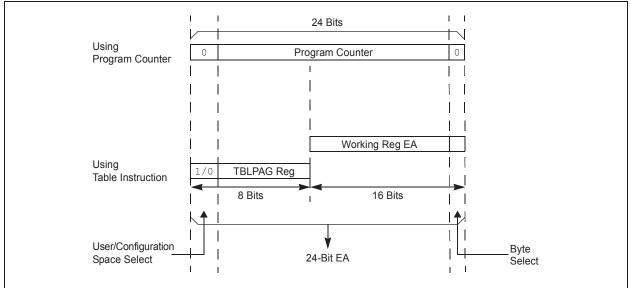
Enhanced In-Circuit Serial Programming uses an on-board bootloader, known as the Program Executive, to manage the programming process. Using an SPI data frame format, the Program Executive can erase, program and verify program memory. For more information on Enhanced ICSP, see the device programming specification.

RTSP is accomplished using TBLRD (Table Read) and TBLWT (Table Write) instructions. With RTSP, the user application can write program memory data with a single program memory word and erase program memory in blocks or 'pages' of 512 instructions (1536 bytes) at a time.

5.1 Table Instructions and Flash Programming

Regardless of the method used, all programming of Flash memory is done with the Table Read and Table Write instructions. These instructions allow direct read and write access to the program memory space, from the data memory, while the device is in normal operating mode. The 24-bit target address in the program memory is formed using bits<7:0> of the TBLPAG register and the Effective Address (EA) from a W register, specified in the table instruction, as shown in Figure 5-1. The TBLRDL and the TBLWTL instructions are used to read or write to bits<15:0> of program memory. TBLRDL and TBLWTL can access program memory in both Word and Byte modes. The TBLRDH and TBLWTH instructions are used to read or write to bits<23:16> of program memory. TBLRDH and TBLWTH can also access program memory in Word or Byte mode.

FIGURE 5-1: ADDRESSING FOR TABLE REGISTERS



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5.2 RTSP Operation

The dsPIC33EPXXXGS70X/80X family Flash program memory array is organized into rows of 64 instructions or 192 bytes. RTSP allows the user application to erase a single page (8 rows or 512 instructions) of memory at a time and to program one row at a time. It is possible to program two instructions at a time as well.

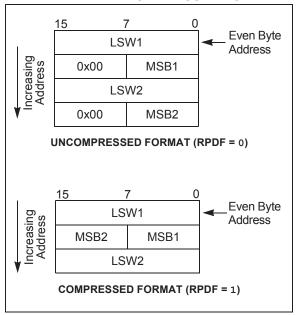
The page erase and single row write blocks are edge-aligned, from the beginning of program memory, on boundaries of 1536 bytes and 192 bytes, respectively. Figure 30-14 in Section 30.0 "Electrical Characteristics" lists the typical erase and programming times.

Row programming is performed by loading 192 bytes into data memory and then loading the address of the first byte in that row into the NVMSRCADR register. Once the write has been initiated, the device will automatically load the write latches and increment the NVMSRCADR and the NVMADR(U) registers until all bytes have been programmed. The RPDF bit (NVMCON<9>) selects the format of the stored data in RAM to be either compressed or uncompressed. See Figure 5-2 for data formatting. Compressed data helps to reduce the amount of required RAM by using the upper byte of the second word for the MSB of the second instruction.

The basic sequence for RTSP word programming is to use the TBLWTL and TBLWTH instructions to load two of the 24-bit instructions into the write latches found in configuration memory space. Refer to Figure 4-1 through Figure 4-4 for write latch addresses. Programming is performed by unlocking and setting the control bits in the NVMCON register.

All erase and program operations may optionally use the NVM interrupt to signal the successful completion of the operation. For example, when performing Flash write operations on the Inactive Partition in Dual Partition mode, where the CPU remains running, it is necessary to wait for the NVM interrupt before programming the next block of Flash program memory.

FIGURE 5-2: UNCOMPRESSED/ COMPRESSED FORMAT



5.3 **Programming Operations**

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. The processor stalls (waits) until the programming operation is finished. Setting the WR bit (NVMCON<15>) starts the operation and the WR bit is automatically cleared when the operation is finished.

5.3.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

Programmers can program two adjacent words (24 bits x 2) of Program Flash Memory at a time on every other word address boundary (0x000000, 0x000004, 0x000008, etc.). To do this, it is necessary to erase the page that contains the desired address of the location the user wants to change. For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user application must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPS.

5.4 Dual Partition Flash Configuration

For dsPIC33EPXXXGS70X/80X devices operating in Dual Partition Flash Program Memory modes, the Inactive Partition can be erased and programmed without stalling the processor. The same programming algorithms are used for programming and erasing the Flash in the Inactive Partition, as described in **Section 5.2 "RTSP Operation**". On top of the page erase option, the entire Flash memory of the Inactive Partition can be erased by configuring the NVMOP<3:0> bits in the NVMCON register.

Note 1: The application software to be loaded into the Inactive Partition will have the address of the Active Partition. The bootloader firmware will need to offset the address by 0x400000 in order to write to the Inactive Partition.

5.4.1 FLASH PARTITION SWAPPING

The Boot Sequence Number is used for determining the Active Partition at start-up and is encoded within the FBTSEQ Configuration register bits. Unlike most Configuration registers, which only utilize the lower 16 bits of the program memory, FBTSEQ is a 24-bit Configuration Word. The Boot Sequence Number (BSEQ) is a 12-bit value and is stored in FBTSEQ twice. The true value is stored in bits, FBTSEQ<11:0>, and its complement is stored in bits, FBTSEQ<23:12>. At device Reset, the sequence numbers are read and the partition with the lowest sequence number becomes the Active Partition. If one of the Boot Sequence Numbers is invalid, the device will select the partition with the valid Boot Sequence Number, or default to Partition 1 if both sequence numbers are invalid. See Section 27.0 "Special Features" for more information.

The BOOTSWP instruction provides an alternative means of swapping the Active and Inactive Partitions (soft swap) without the need for a device Reset. The BOOTSWP must always be followed by a GOTO instruction. The BOOTSWP instruction swaps the Active and Inactive Partitions, and the PC vectors to the location specified by the GOTO instruction in the newly Active Partition.

It is important to note that interrupts should temporarily be disabled while performing the soft swap sequence and that after the partition swap, all peripherals and interrupts which were enabled remain enabled. Additionally, the RAM and stack will maintain state after the switch. As a result, it is recommended that applications using soft swaps jump to a routine that will reinitialize the device in order to ensure the firmware runs as expected. The Configuration registers will have no effect during a soft swap. For robustness of operation, in order to execute the BOOTSWP instruction, it is necessary to execute the NVM unlocking sequence as follows:

- 1. Write 0x55 to NVMKEY.
- 2. Write 0xAA to NVMKEY.
- 3. Execute the BOOTSWP instruction.

If the unlocking sequence is not performed, the BOOTSWP instruction will be executed as a forced NOP and a GOTO instruction, following the BOOTSWP instruction, will be executed, causing the PC to jump to that location in the current operating partition.

The SFTSWP and P2ACTIV bits in the NVMCON register are used to determine a successful swap of the Active and Inactive Partitions, as well as which partition is active. After the BOOTSWP and GOTO instructions, the SFTSWP bit should be polled to verify the partition swap has occurred and then cleared for the next panel swap event.

5.4.2 DUAL PARTITION MODES

While operating in Dual Partition mode, the dsPIC33EPXXXGS70X/80X family devices have the option for both partitions to have their own defined security segments, as shown in Figure 27-4. Alternatively, the device can operate in Protected Dual Partition mode, where Partition 1 becomes permanently erase/ write-protected. Protected Dual Partition mode allows for a "Factory Default" mode, which provides a fail-safe backup image to be stored in Partition 1.

dsPIC33EPXXXGS70X/80X family devices can also operate in Privileged Dual Partition mode, where additional security protections are implemented to allow for protection of intellectual property when multiple parties have software within the device. In Privileged Dual Partition mode, both partitions place additional restrictions on the FBSLIM register. These prevent changes to the size of the Boot Segment and General Segment, ensuring that neither segment will be altered.

5.5 Flash Memory Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

5.5.1 KEY RESOURCES

- "Dual Partition Flash Program Memory" (DS70005156) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

5.6 Control Registers

Five SFRs are used to write and erase the Program Flash Memory: NVMCON, NVMKEY, NVMADR, NVMADRU and NVMSRCADR/H.

The NVMCON register (Register 5-1) selects the operation to be performed (page erase, word/row program, Inactive Partition erase), initiates the program or erase cycle and is used to determine the Active Partition in Dual Partition modes.

NVMKEY (Register 5-4) is a write-only register that is used for write protection. To start a programming or erase sequence, the user application must consecutively write 0x55 and 0xAA to the NVMKEY register. There are two NVM Address registers: NVMADRU and NVMADR. These two registers, when concatenated, form the 24-bit Effective Address (EA) of the selected word/row for programming operations, or the selected page for erase operations. The NVMADRU register is used to hold the upper eight bits of the EA, while the NVMADR register is used to hold the lower 16 bits of the EA.

For row programming operation, data to be written to Program Flash Memory is written into data memory space (RAM) at an address defined by the NVMSRCADR register (location of first element in row programming data).

REGISTER 5-1: NVMCON: NONVOLATILE MEMORY (NVM) CONTROL REGISTER

R/SO-0 ⁽	¹⁾ R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0	R/C-0	R-0	R/W-0	R/C-0
WR	WREN	WRERR	NVMSIDL ⁽²⁾	SFTSWP ⁽⁶⁾	P2ACTIV ⁽⁶⁾	RPDF	URERR
bit 15	·	·	·			·	bit 8
U-0	U-0	U-0	U-0	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾
_		_		NVMOP3 ^(3,4)	NVMOP2 ^(3,4)	NVMOP1 ^(3,4)	NVMOP0 ^(3,4)
bit 7							bit 0
Legend:		C = Clearab		SO = Settable	-		
R = Reada		W = Writable		-	ented bit, read		
-n = Value	at POR	'1' = Bit is se	et	'0' = Bit is clea	ired	x = Bit is unkn	own
		(, , , , , (1)					
bit 15	WR: Write C		D				
				tion is complete	on; the operation	on is sell-timed	and the bit is
				ete and inactive			
bit 14	WREN: Write	e Enable bit ⁽¹⁾					
			n/erase operat				
			/erase operation				
bit 13		•	Error Flag bit ⁽¹		maination has a	oourrod (bit is as	t outomotioally
		set attempt of t		ce allempt, or le	ermination has o	courred (bit is se	automatically
				pleted normally	/		
bit 12		-	lle Control bit ⁽²				
			or goes into Sta or is active duri	ndby mode dur ng Idle mode	ing Idle mode		
bit 11	SFTSWP: P	artition Soft Sv	vap Status bit ⁽⁶	5)			
	0 = Awaiting	successful pa		ing the BOOTSV	e BOOTSWP inst		
bit 10		artition 2 Activ					
			apped into the a apped into the a	•			
bit 9			Data Format b	-			
bit 0		U		ompressed forr	nat		
				ncompressed f			
Note 1:	These bits can or	nlv be reset or	a POR.				
2:	If this bit is set, p	-		ther reduced (II	DLE) and upon e	exiting Idle mod	e, there is a
	delay (TVREG) be				, i	0	
3:	All other combina			•			
4:	Execution of the		-	-	-		
5:	Two adjacent wo				during execution	n of this operati	ion.
6: 7:	Only applicable v		-		mod data:		
7:	The specific Boot 11 = Single Parti			or the program	inieu udla.		
	10 = Dual Partitio	on Flash mode	;				
	01 = Protected D	ual Partition F	lash mode				
	00 = Reserved						

REGISTER 5-1: NVMCON: NONVOLATILE MEMORY (NVM) CONTROL REGISTER (CONTINUED)

- bit 8 URERR: Row Programming Data Underrun Error bit
 - 1 = Indicates row programming operation has been terminated
 - 0 = No data underrun error is detected
- bit 7-4 Unimplemented: Read as '0'
- bit 3-0 NVMOP<3:0>: NVM Operation Select bits^(1,3,4)
 - 1111 = Reserved
 - 1110 = User memory bulk erase operation
 - 1011 = Reserved
 - 1010 = Reserved
 - 1001 = Reserved
 - 1000 = Boot memory double-word program operation in a Dual Partition Flash mode⁽⁷⁾
 - 0101 = Reserved
 - 0100 = Inactive Partition memory erase operation
 - 0011 = Memory page erase operation
 - 0010 = Memory row program operation
 - 0001 = Memory double-word program operation⁽⁵⁾
 - 0000 = Reserved
- Note 1: These bits can only be reset on a POR.
 - 2: If this bit is set, power consumption will be further reduced (IIDLE) and upon exiting Idle mode, there is a delay (TVREG) before Flash memory becomes operational.
 - 3: All other combinations of NVMOP<3:0> are unimplemented.
 - 4: Execution of the PWRSAV instruction is ignored while any of the NVM operations are in progress.
 - 5: Two adjacent words on a 4-word boundary are programmed during execution of this operation.
 - 6: Only applicable when operating in Dual Partition mode.
 - 7: The specific Boot mode depends on bits<1:0> of the programmed data:
 - 11 = Single Partition Flash mode
 - 10 = Dual Partition Flash mode
 - 01 = Protected Dual Partition Flash mode
 - 00 = Reserved

REGISTER 5-2: NVMADR: NONVOLATILE MEMORY LOWER ADDRESS REGISTER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			NVMA	DR<15:8>			
bit 15							bit 8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			NVMA	DR<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'							

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-0 **NVMADR<15:0>:** Nonvolatile Memory Lower Write Address bits Selects the lower 16 bits of the location to program or erase in Program Flash Memory. This register may be read or written to by the user application.

REGISTER 5-3: NVMADRU: NONVOLATILE MEMORY UPPER ADDRESS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADRU<23:16>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 NVMADRU<23:16>: Nonvolatile Memory Upper Write Address bits

Selects the upper eight bits of the location to program or erase in Program Flash Memory. This register may be read or written to by the user application.

REGISTER 5-4: NVMKEY: NONVOLATILE MEMORY KEY REGISTER

— — — — — — — bit 15 W-0 W-0 W-0 W-0 W-0 W NVMKEY<7:0> bit 7								
W-0 W-0 W-0 W-0 W-0 W NVMKEY<7:0> bit 7	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
W-0 W-0 W-0 W-0 W-0 W NVMKEY<7:0> bit 7	—	—	—	—	—	—	—	—
NVMKEY<7:0> bit 7	bit 15							bit 8
NVMKEY<7:0> bit 7								
bit 7 Legend:	W-0	W-0	W-0	W-0	W-0	VV-0	W-0	W-0
Legend:				NVMK	EY<7:0>			
-	bit 7							bit 0
R = Readable bit $W = Writable bit$ $II = I Inimplemented bit read as (0)$	Legend:							
The readable bit W - Whable bit 0 - Ohimplemented bit, read as 0	R = Readable b	vit	W = Writable b	it	U = Unimplei	mented bit, read	as '0'	

'0' = Bit is cleared

bit 15-8 **Unimplemented:** Read as '0'

-n = Value at POR

bit 7-0 **NVMKEY<7:0>:** NVM Key Register bits (write-only)

'1' = Bit is set

REGISTER 5-5: NVMSRCADR: NVM SOURCE DATA ADDRESS REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
			NVMSRO	CADR<15:8>					
bit 15							bit 8		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
			NVMSR	CADR<7:0>					
bit 7							bit 0		
Legend:									
R = Readable bit		W = Writable b	it	U = Unimpler	mented bit, rea	id as '0'			
-n = Value at POR		t POR '1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown			

bit 15-0 NVMSRCADR<15:0>: NVM Source Data Address bits

The RAM address of the data to be programmed into Flash when the NVMOP<3:0> bits are set to row programming.

x = Bit is unknown

6.0 RESETS

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Reset" (DS70602) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com)
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Reset module combines all Reset sources and controls the device Master Reset Signal, SYSRST. The following is a list of device Reset sources:

- POR: Power-on Reset
- BOR: Brown-out Reset
- MCLR: Master Clear Pin Reset
- SWR: RESET Instruction
- WDTO: Watchdog Timer Time-out Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- · IOPUWR: Illegal Condition Device Reset
 - Illegal Opcode Reset
 - Uninitialized W Register Reset
 - Security Reset

FIGURE 6-1: RESET SYSTEM BLOCK DIAGRAM

A simplified block diagram of the Reset module is shown in Figure 6-1.

Any active source of Reset will make the SYSRST signal active. On system Reset, some of the registers associated with the CPU and peripherals are forced to a known Reset state, and some are unaffected.

Note: Refer to the specific peripheral section or Section 4.0 "Memory Organization" of this data sheet for register Reset states.

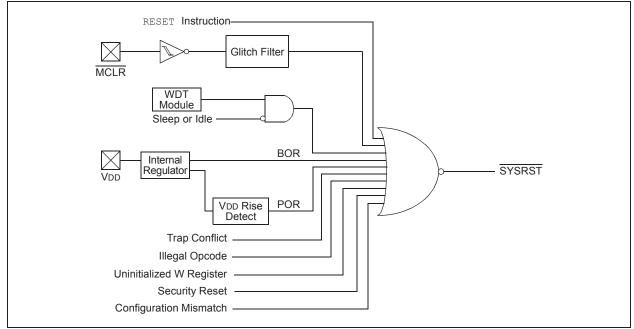
All types of device Reset set a corresponding status bit in the RCON register to indicate the type of Reset (see Register 6-1).

A POR clears all the bits, except for the BOR and POR bits (RCON<1:0>) that are set. The user application can set or clear any bit, at any time, during code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software does not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this manual.

Note: The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset is meaningful.

For all Resets, the default clock source is determined by the FNOSC<2:0> bits in the FOSCSEL Configuration register. The value of the FNOSCx bits is loaded into the NOSC<2:0> (OSCCON<10:8>) bits on Reset, which in turn, initializes the system clock.



6.1 Reset Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

6.1.1 KEY RESOURCES

- "Reset" (DS70602) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- · Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

R/W-0	R/W-0	U-0	U-0	R/W-0	U-0	R/W-0	R/W-0
TRAPR	IOPUWR		—	VREGSF		CM	VREGS
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EXTR	SWR	SWDTEN ⁽²⁾	WDTO	SLEEP	IDLE	BOR	POR
bit 7	owit	OWBIEN	WBIO	OLLEI	IDEE	Bort	bit C
Legend:							
R = Readabl	e hit	W = Writable	hit	II = Unimple	mented bit, read	1 as 'O'	
-n = Value at		'1' = Bit is set	UIL	'0' = Bit is cle		x = Bit is unki	
	FUR	I - DILIS SEL			areu	X - DILISUIKI	IOWIT
bit 15	TRAPR: Trap	Reset Flag bit					
		onflict Reset ha onflict Reset ha		d			
bit 14					cess Reset Flag	ıbit	
		÷ .		-	ode or Uninitial		er used as an
		Pointer caused					
	•	•		egister Reset h	has not occurred	1	
bit 13-12	•	ted: Read as '					
bit 11		ash Voltage Reg			p bit		
		Itage regulator i Itage regulator		• .	ring Sleep		
bit 10		ited: Read as '	-		ing cloop		
bit 9	•	ration Mismatch					
	1 = A Configu	uration Mismato uration Mismato	h Reset has				
bit 8	VREGS: Volt	age Regulator S	Standby Durir	ng Sleep bit			
	1 = Voltage r	egulator is activ	ve during Sle	ep			
	-	regulator goes i	-	mode during SI	еер		
bit 7		nal Reset (MCL	,				
		Clear (pin) Res Clear (pin) Res					
bit 6		are RESET (Insti					
		instruction has					
		instruction has					
bit 5	SWDTEN: So	oftware Enable/	Disable of W	DT bit ⁽²⁾			
	1 = WDT is e	nabled					
	0 = WDT is d	isabled					
bit 4		hdog Timer Tim	•	it			
		e-out has occur e-out has not oc					
	I of the Reset sta		set or cleare	d in software. S	Setting one of th	ese bits in soft	ware does not
	ause a device Re the WDTEN<1:0		hits are '11'	(unprogramme	ed) the WDT ie	always enable	d renardless
				(unprogramme		annays chable	a, regardiess

REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾

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of the SWDTEN bit setting.

REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾ (CONTINUED)

bit 3	SLEEP: Wake-up from Sleep Flag bit 1 = Device has been in Sleep mode 0 = Device has not been in Sleep mode
bit 2	IDLE: Wake-up from Idle Flag bit
	1 = Device has been in Idle mode0 = Device has not been in Idle mode
bit 1	BOR: Brown-out Reset Flag bit
	1 = A Brown-out Reset has occurred0 = A Brown-out Reset has not occurred
bit 0	POR: Power-on Reset Flag bit
	1 = A Power-on Reset has occurred0 = A Power-on Reset has not occurred

- **Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.
 - 2: If the WDTEN<1:0> Configuration bits are '11' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

7.0 INTERRUPT CONTROLLER

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Interrupts" (DS7000600) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the dsPIC33EPXXXGS70X/80X family CPU.

The interrupt controller has the following features:

- Six Processor Exceptions and Software Traps
- Seven User-Selectable Priority Levels
- Interrupt Vector Table (IVT) with a Unique Vector for each Interrupt or Exception Source
- Fixed Priority within a Specified User Priority Level
- Fixed Interrupt Entry and Return Latencies
- Alternate Interrupt Vector Table (AIVT) for Debug Support

7.1 Interrupt Vector Table

The dsPIC33EPXXXGS70X/80X family Interrupt Vector Table (IVT), shown in Figure 7-1, resides in program memory, starting at location, 000004h. The IVT contains six non-maskable trap vectors and up to 246 sources of interrupts. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority. This priority is linked to their position in the vector table. Lower addresses generally have a higher natural priority. For example, the interrupt associated with Vector 0 takes priority over interrupts at any other vector address.

7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT), shown in Figure 7-2, is available only when the Boot Segment is defined and the AIVT has been enabled. To enable the Alternate Interrupt Vector Table, the Configuration bit, AIVTDIS in the FSEC register, must be programmed and the AIVTEN bit must be set (INTCON2<8> = 1). When the AIVT is enabled, all interrupt and exception processes use the alternate vectors instead of the default vectors. The AIVT begins at the start of the last page of the Boot Segment, defined by BSLIM<12:0>. The second half of the page is no longer usable space. The Boot Segment must be at least two pages to enable the AIVT.

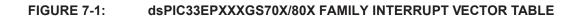
Note: Although the Boot Segment must be enabled in order to enable the AIVT, application code does not need to be present inside of the Boot Segment. The AIVT (and IVT) will inherit the Boot Segment code protection.

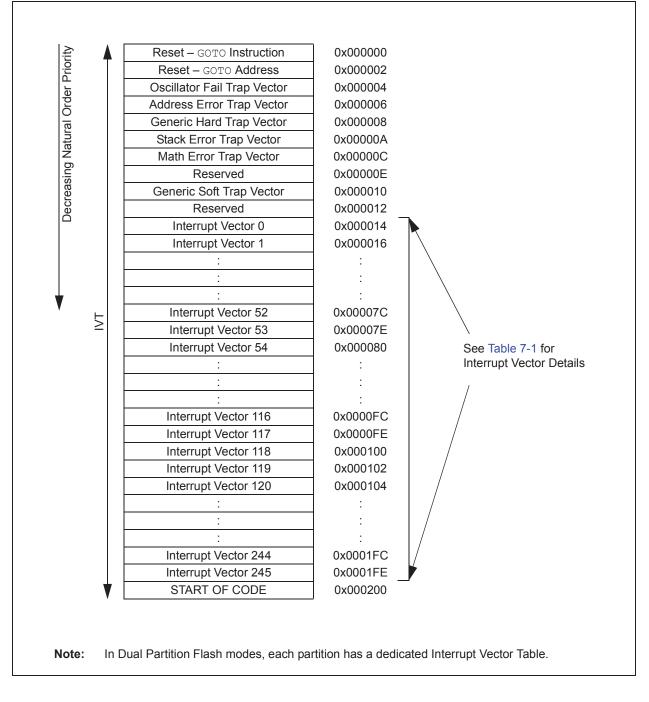
The AIVT supports debugging by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time.

7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The dsPIC33EPXXXGS70X/80X family devices clear their registers in response to a Reset, which forces the PC to zero. The device then begins program execution at location, 0x000000. A GOTO instruction at the Reset address can redirect program execution to the appropriate start-up routine.

Note: Any unimplemented or unused vector locations in the IVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.





A L	Deserved	BSLIM<12:0> ⁽¹⁾ + 0x000000	
	Reserved Reserved	BSLIM<12:0>(1) + 0x000000 BSLIM<12:0>(1) + 0x000002	
	Oscillator Fail Trap Vector	BSLIM<12:0>(1) + 0x000002 BSLIM<12:0>(1) + 0x000004	
er –	Address Error Trap Vector	BSLIM<12:0>(1) + 0x000004 BSLIM<12:0>(1) + 0x000006	
Drd –	Generic Hard Trap Vector	BSLIM<12:0>(1) + 0x000008	
	Stack Error Trap Vector	BSLIM<12:0>(1) + 0x000000A	
atri	Math Error Trap Vector	BSLIM<12:0>(1) + 0x00000C	
Ž	Reserved	BSLIM<12:0>(1) + 0x00000E	
Decreasing Natural Order Priority	Generic Soft Trap Vector	BSLIM<12:0> ⁽¹⁾ + 0x000010	
Lea	Reserved	BSLIM<12:0> ⁽¹⁾ + 0x000012	
Jec	Interrupt Vector 0	BSLIM<12:0>(1) + 0x000012	
	Interrupt Vector 1	BSLIM<12:0> ⁽¹⁾ + 0x000016	
	· ·		
		-	
VI TVI	Interrupt Vector 52	BSLIM<12:0>(1) + 0x00007C	
` ⋖ ⊢	Interrupt Vector 53	BSLIM<12:0>(1) + 0x00007E	
	Interrupt Vector 54	BSLIM<12:0> ⁽¹⁾ + 0x000080	See Table 7-1 for
	· .	- :	Interrupt Vector Details
	:		
	:		
	Interrupt Vector 116	BSLIM<12:0> ⁽¹⁾ + 0x0000FC	
	Interrupt Vector 117	BSLIM<12:0>(1) + 0x0000FE	
	Interrupt Vector 118	BSLIM<12:0> ⁽¹⁾ + 0x000100	
	Interrupt Vector 119	BSLIM<12:0> ⁽¹⁾ + 0x000102	
	Interrupt Vector 120	BSLIM<12:0> ⁽¹⁾ + 0x000104	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 244	BSLIM<12:0> ⁽¹⁾ + 0x0001FC	
	Interrupt Vector 245	BSLIM<12:0> ⁽¹⁾ + 0x0001FE	
Note 1:	The address depends on the size	e of the Boot Segment defined by	y BSLIM<12:0>.
	[(BSLIM<12:0> - 1) x 0x400] + 0		

TABLE 7-1: INTERRUPT VECTOR DETAILS

Interrupt Source	Vector	IRQ	IVT Address	Interrupt Bit Location			
interrupt Source	#	#	IVI Address	Flag	Enable	Priority	
	•	Highest N	latural Order Priority			•	
INT0 – External Interrupt 0	8	0	0x000014	IFS0<0> INT0IF	IEC0<0> INT0IE	IPC0<2:0> INT0IP<2:0>	
IC1 – Input Capture 1	9	1	0x000016	IFS0<1> IC1IF	IEC0<1> IC1IE	IPC0<6:4> IC1IP<2:0>	
OC1 – Output Compare 1	10	2	0x000018	IFS0<2> OC1IF	IEC0<2> OC1IE	IPC0<10:8> OC1IP<2:0>	
T1 – Timer1	11	3	0x00001A	IFS0<3> T1IF	IEC0<3> T1IE	IPC0<14:12> T1IP<2:0>	
DMA0 – DMA Channel 0	12	4	0x00001C	IFS0<4> DMA0IF	IEC0<4> DMA0IE	IPC1<2:0> DMA0IP<2:0>	
IC2 – Input Capture 2	13	5	0x00001E	IFS0<5> IC2IF	IEC0<5> IC2IE	IPC1<6:4> IC2IP<2:0>	
OC2 – Output Compare 2	14	6	0x000020	IFS0<6> OC2IF	IEC0<6> OC2IE	IPC1<10:8> OC2IP<2:0>	
T2 – Timer2	15	7	0x000022	IFS0<7> T2IF	IEC0<7> T2IE	IPC1<14:12> T2IP<2:0>	
T3 – Timer3	16	8	0x000024	IFS0<8> T3IF	IEC0<8> T3IE	IPC2<2:0> T3IP<2:0>	
SPI1TX – SPI1 Transfer Done	17	9	0x000026	IFS0<9> SPI1TXIF	IEC0<9> SPI1TXIE	IPC2<6:4> SPI1TXIP<2:0>	
SPI1RX – SPI1 Receive Done	18	10	0x000028	IFS0<10> SPI1RXIF	IEC0<10> SPI1RXIE	IPC2<10:8> SPI1RXIP<2:0>	
U1RX – UART1 Receiver	19	11	0x00002A	IFS0<11> U1RXIF	IEC0<11> U1RXIE	IPC2<14:12> U1RXIP<2:0>	
U1TX – UART1 Transmitter	20	12	0x00002C	IFS0<12> U1TXIF	IEC0<12> U1TXIE	IPC3<2:0> U1TXIP<2:0>	
ADC – ADC Global Convert Done	21	13	0x00002E	IFS0<13> ADCIF	IEC0<13> ADCIE	IPC3<6:4> ADCIP<2:0>	
DMA1 – DMA Channel 1	22	14	0x000030	IFS0<14> DMA1IF	IEC0<14> DMA1IE	IPC3<10:8> DMA1IP<2:0>	
NVM – NVM Write Complete	23	15	0x000032	IFS0<15> NVMIF	IEC0<15> NVMIE	IPC3<14:12> NVMIP<2:0>	
SI2C1 – I2C1 Slave Event	24	16	0x000034	IFS1<0> SI2C1IF	IEC1<0> SI2C1IE	IPC4<2:0> SI2C1IP<2:0>	
MI2C1 – I2C1 Master Event	25	17	0x000036	IFS1<1> MI2C1IF	IEC1<1> MI2C1IE	IPC4<6:4> MI2C1IP<2:0>	
AC1 – Analog Comparator 1 Interrupt	26	18	0x000038	IFS1<2> AC1IF	IEC1<2> AC1IE	IPC4<10:8> AC1IP<2:0>	
CN – Input Change Interrupt	27	19	0x00003A	IFS1<3> CNIF	IEC1<3> CNIE	IPC4<14:12> CNIP<2:0>	
INT1 – External Interrupt 1	28	20	0x00003C	IFS1<4> INT1IF	IEC1<4> INT1IE	IPC5<2:0> INT1IP<2:0>	
Reserved	29-31	21-23	0x00003E-0x000043			—	
DMA2 – DMA Channel 2	32	24	0x00044	IFS1<8> DMA2IF	IEC1<8> DMA2IE	IPC6<2:0> DMA2IP<2:0>	
OC3 – Output Compare 3	33	25	0x000046	IFS1<9> OC3IF	IEC1<9> OC3IE	IPC6<6:4> OC3IP<2:0>	
OC4 – Output Compare 4	34	26	0x000048	IFS1<10> OC4IF	IEC1<10> OC4IE	IPC6<10:8> OC4IP<2:0>	

TABLE 7-1:	INTERRUPT VECTOR DETAILS	(CONTINUED)

Interrupt Source	Vector	IRQ	IVT Address	Interrupt Bit Location			
interrupt Source	#	#	IVI Address	Flag	Enable	Priority	
T4 – Timer4	35	27	0x00004A	IFS1<11> T4IF	IEC1<11> T4IE	IPC6<14:12> T4IP<2:0>	
T5 – Timer5	36	28	0x00004C	IFS1<12> T5IF	IEC1<12> T5IE	IPC7<2:0> T5IP<2:0>	
INT2 – External Interrupt 2	37	29	0x00004E	IFS1<13> INT2IF	IEC1<13> INT2IE	IPC7<6:4> INT2IP<2:0>	
U2RX – UART2 Receiver	38	30	0x000050	IFS1<14> U2RXIF	IEC1<14> U2RXIE	IPC7<10:8> U2RXIP<2:0>	
U2TX – UART2 Transmitter	39	31	0x000052	IFS1<15> U2TXIF	IEC1<15> U2TXIE	IPC7<14:12> U2TXIP<2:0>	
SPI2TX – SPI2 Transfer Done	40	32	0x000054	IFS2<0> SPI2TXIF	IEC2<0> SPI2TXIE	IPC8<2:0> SPI2TXIP<2:0>	
SPI2RX – SPI2 Receive Done	41	33	0x000056	IFS2<1> SPI2RXIF	IEC2<1> SPI2RXIE	IPC8<6:4> SPI2RXIP<2:0>	
C1RX – CAN1 RX Data Ready	42	34	0x000058	IFS2<2> C1RXIF	IEC2<2> C1RXIE	IPC8<10:8> C1RXIP<2:0>	
C1 – CAN1 Combined Error	43	35	0x000059	IFS2<3> C1IF	IEC2<3> C1IE	IPC8<14:12> C1IP<2:0>	
DMA3 – DMA Channel 3	44	36	0x00005A	IFS2<4> DMA3IF	IEC2<4> DMA3IE	IPC9<2:0> DMA3IP<2:0>	
IC3 – Input Capture 3	45	37	0x00005E	IFS2<5> IC3IF	IEC2<5> IC3IE	IPC9<6:4> IC3IP<2:0>	
IC4 – Input Capture 4	46	38	0x000060	IFS2<6> IC4IF	IEC2<6> IC4IE	IPC9<10:8> IC4IP<2:0>	
Reserved	47-56	39-48	0x000062-0x000074	_	_	—	
SI2C2 – I2C2 Slave Event	57	49	0x000076	IFS3<1> SI2C2IF	IEC3<1> SI2C2IE	IPC12<6:4> SI2C2IP<2:0>	
MI2C2 – I2C2 Master Event	58	50	0x000078	IFS3<2> MI2C2IF	IEC3<2> MI2C2IE	IPC12<10:8> MI2C2IP<2:0>	
Reserved	59-61	51-53	0x00007A-0x00007E	_	—	_	
INT4 – External Interrupt 4	62	54	0x000080	IFS3<6> INT4IF	IEC3<6> INT4IE	IPC13<10:8> INT4IP<2:0>	
C2RX – CAN2 RX Data Ready	63	55	0x000082	IFS3<7> C2RXIF	IEC3<7> C2RXIE	IPC13<14:12> C2RXIP<2:0>	
C2 – CAN 2 Combined Error	64	56	0x000083	IFS3<8> C2IF	IEC3<8> C2IE	IPC14<2:0> C2IP<2:0>	
PSEM – PWM Special Event Match	65	57	0x000086	IFS3<9> PSEMIF	IEC3<9> PSEMIE	IPC14<6:4> PSEMIP<2:0>	
Reserved	66-72	58-64	0x000088-0x000094		_	—	
U1E – UART1 Error Interrupt	73	65	0x000096	IFS4<1> U1EIF	IEC4<1> U1EIE	IPC16<6:4> U1EIP<2:0>	
U2E – UART2 Error Interrupt	74	66	0x000098	IFS4<2> U2EIF	IEC4<2> U2EIE	IPC16<10:8> U2EIP<2:0>	
Reserved	75-77	67-69	0x00009A-0x0000A2		_	—	
C1TX – CAN1 TX Data Request	78	70	0x0000A0	IFS4<6> C1TXIF	IEC4<6> C1TXIE	IPC17<10:8> C1TXIP<2:0>	
C2TX – CAN2 TX Data Request	79	71	0x0000A	IFS4<7> C2TXIF	IEC4<7> C2TXIE	IPC17<14:12> C2TXIP<2:0>	
Reserved	80	72	0x0000A4			-	

TABLE 7-1: INTERRUPT VECTOR DETAILS (CONTINUED)

Interrupt Source	Vector	IRQ	IVT Address	Interrupt Bit Location			
interrupt Source	#	#	IVI Address	Flag	Enable	Priority	
PSES – PWM Secondary Special Event Match	81	73	0x0000A6	IFS4<9> PSESIF	IEC4<9> PSESIE	IPC18<6:4> PSESIP<2:0>	
Reserved	82-97	74-89	0x0000A8-0x0000C6			_	
SPI3TX – SPI3 Transfer Done	98	90	0x0000C8	IFS5<10> SPI3TXIF	IEC5<10> SPI3TXIE	IPC22<10:8> SPI3TXIP<2:0>	
SPI3RX – SPI3 Receive Done	99	91	0x0000CA	IFS5<10> SPI3RXIF	IEC5<11> SPI3RXIE	IPC22<14:12> SPI3RXIP<2:0>	
Reserved	100-101	92-93	0x0000CC-0x0000CE	—	—	—	
PWM1 – PWM1 Interrupt	102	94	0x0000D0	IFS5<14> PWM1IF	IEC5<14> PWM1IE	IPC23<10:8> PWM1IP<2:0>	
PWM2 – PWM2 Interrupt	103	95	0x0000D2	IFS5<15> PWM2IF	IEC5<15> PWM2IE	IPC23<14:12> PWM2IP<2:0>	
PWM3 – PWM3 Interrupt	104	96	0x0000D4	IFS6<0> PWM3IF	IEC6<0> PWM3IE	IPC24<2:0> PWM3IP<2:0>	
PWM4 – PWM4 Interrupt	105	97	0x0000D6	IFS6<1> PWM4IF	IEC6<1> PWM4IE	IPC24<6:4> PWM4IP<2:0>	
PWM5 – PWM5 Interrupt	106	98	0x0000D8	IFS6<2> PWM5IF	IEC6<2> PWM5IE	IPC24<10:8> PWM5IP<2:0>	
PWM6 – PWM6 Interrupt	107	99	0x0000DA	IFS6<3> PWM6IF	IEC6<3> PWM6IE	IPC24<14:12> PWM6IP<2:0>	
PWM7 – PWM7 Interrupt	108	100	0x0000DC	IFS6<4> PWM7IF	IEC6<4> PWM7IE	IPC25<2:0> PWM7IP<2:0>	
PWM8 – PWM8 Interrupt	109	101	0x0000DE	IFS6<5> PWM8IF	IEC6<5> PWM8IE	IPC25<6:4> PWM8IP<2:0>	
Reserved	110	102	0x0000E0	_	_	_	
AC2 – Analog Comparator 2 Interrupt	111	103	0x0000E2	IFS6<7> AC2IF	IEC6<7> AC2IE	IPC25<14:12> AC2IP<2:0>	
AC3 – Analog Comparator 3 Interrupt	112	104	0x0000E4	IFS6<8> AC3IF	IEC6<8> AC3IE	IPC26<2:0> AC3IP<2:0>	
AC4 – Analog Comparator 4 Interrupt	113	105	0x0000E6	IFS6<9> AC4IF	IEC6<9> AC4IE	IPC26<6:4> AC4IP<2:0>	
Reserved	114-117	106-109	0x0000E8-0x0000EE	_	—		
AN0 Conversion Done	118	110	0x0000F0	IFS6<14> AN0IF	IEC6<14> AN0IE	IPC27<10:8> AN0IP<2:0>	
AN1 Conversion Done	119	111	0x0000F2	IFS6<15> AN1IF	IEC6<15> AN1IE	IPC27<14:12> AN1IP<2:0>	
AN2 Conversion Done	120	112	0x0000F4	IFS7<0> AN2IF	IEC7<0> AN2IE	IPC28<2:0> AN2IP<2:0>	
AN3 Conversion Done	121	113	0x0000F6	IFS7<1> AN3IF	IEC7<1> AN3IE	IPC28<6:4> AN3IP<2:0>	
AN4 Conversion Done	122	114	0x0000F8	IFS7<2> AN4IF	IEC7<2> AN4IE	IPC28<10:8> AN4IP<2:0>	
AN5 Conversion Done	123	115	0x0000FA	IFS7<3> AN5IF	IEC7<3> AN5IE	IPC28<14:12> AN5IP<2:0>	
AN6 Conversion Done	124	116	0x0000FC	IFS7<4> AN6IF	IEC7<4> AN6IE	IPC29<2:0> AN6IP<2:0>	
AN7 Conversion Done	125	117	0x0000FE	IFS7<5> AN7IF	IEC7<5> AN7IE	IPC29<6:4> AN7IP<2:0>	
Reserved	126-131	118-123	0x000100-0x00010A	_		_	

Interrupt Source	Vector	IRQ	IVT Address	Interrupt Bit Location			
interrupt Source	#	#	IVI Address	Flag	Enable	Priority	
SPI1 Error Interrupt	132	124	0x00010C	IFS7<12> SPI1IF	IEC7<12> SPI1IE	IPC31<2:0> SPI1IP<2:0>	
SPI2 Error Interrupt	133	125	0x00010E	IFS7<13> SPI2IF	IEC7<13> SPI2IE	IPC31<6:4> SPI2IP<2:0>	
SPI3 Error Interrupt	134	126	0x000110	IFS7<13> SPI3IF	IEC7<13> SPI3IE	IPC31<10:8> SPI3IP<2:0>	
Reserved	135-145	127-137	0x000112-0x000126	—	_	—	
CLC1 Interrupt	146	138	0x000128	IFS8<10> CLC1IF	IEC8<10> CLC1IE	IPC34<10:8> CLC1IP<2:0>	
CLC2 Interrupt	147	139	0x00012A	IFS8<11> CLC2IF	IEC8<11> CLC2IE	IPC34<14:12> CLC2IP<2:0>	
CLC3 Interrupt	148	140	0x00012C	IFS8<12> CLC3IF	IEC8<12> CLC3IE	IPC35<2:0> CLC3IP<2:0>	
CLC4 Interrupt	149	141	0x00012E	IFS8<13> CLC4IF	IEC8<13> CLC4IE	IPC35<6:4> CLC4IP<2:0>	
ICD – ICD Application	150	142	0x000130	IFS8<14> ICDIF	IEC8<14> ICDIE	IPC35<10:8> ICDIP<2:0>	
JTAG – JTAG Programming	151	143	0x000132	IFS8<15> JTAGIF	IEC8<15> JTAGIE	IPC35<14:12> JTAGIP<2:0>	
Reserved	152	144	0x000134	—	_		
PTGSTEP – PTG Step	153	145	0x000136	IFS9<1> PTGSTEPIF	IEC9<1> PTGSTEPIE	IPC36<6:4> PTGSTEP<2:0	
PTGWDT – PTG WDT Time-out	154	146	0x000138	IFS9<2> PTGWDTIF	IEC9<2> PTGWDTIE	IPC36<10:8> PTGWDT<2:0>	
PTG0 – PTG Interrupt Trigger 0	155	147	0x00013A	IFS9<3> PTG0IF	IEC9<3> PTG0IE	IPC36<14:12> PTG0IP<2:0>	
PTG1 – PTG Interrupt Trigger 1	156	148	0x00013C	IFS9<4> PTG1IF	IEC9<4> PTG1IE	IPC37<2:0> PTG1IP<2:0>	
PTG2 – PTG Interrupt Trigger 2	157	149	0x00013E	IFS9<5> PTG2IF	IEC9<5> PTG2IE	IPC37<6:4> PTG2IP<2:0>	
PTG3 – PTG Interrupt Trigger 3	158	150	0x000140	IFS9<6> PTG3IF	IEC9<6> PTG3IE	IPC37<10:8> PTG3IP<2:0>	
AN8 Conversion Done	159	151	0x000142	IFS9<7> AN8IF	IEC9<7> AN8IE	IPC37<14:12> AN8IP<2:0>	
AN9 Conversion Done	160	152	0x000144	IFS9<8> AN9IF	IEC9<8> AN9IE	IPC38<2:0> AN9IP<2:0>	
AN10 Conversion Done	161	153	0x000146	IFS9<9> AN10IF	IEC9<9> AN10IE	IPC38<6:4> AN10IP<2:0>	
AN11 Conversion Done	162	154	0x000148	IFS9<10> AN11IF	IEC9<10> AN11IE	IPC38<10:8> AN11IP<2:0>	
AN12 Conversion Done	163	155	0x00014A	IFS9<11> AN12IF	IEC9<11> AN12IE	IPC38<14:12> AN12IP<2:0>	
AN13 Conversion Done	164	156	0x00014C	IFS9<12> AN13IF	IEC9<12> AN13IE	IPC39<2:0> AN13IP<2:0>	
AN14 Conversion Done	165	157	0x00014E	IFS9<13> AN14IF	IEC9<13> AN14IE	IPC39<6:4> AN14IP<2:0>	
AN15 Conversion Done	166	158	0x000150	IFS9<14> AN15IF	IEC9<14> AN15IE	IPC39<10:8> AN15IP<2:0>	
AN16 Conversion Done	167	159	0x000152	IFS9<15> AN16IF	IEC9<15> AN16IE	IPC39<14:12> AN16IP<2:0>	

TABLE 7-1: INTERRUPT VECTOR DETAILS (CONTINUED)

Interment Courses	Vector	IRQ		Interrupt Bit Location			
Interrupt Source	#	#	IVT Address	Flag	Enable	Priority	
AN17 Conversion Done	168	160	0x000154	IFS10<0> AN17IF	IEC10<0> AN17IE	IPC40<2:0> AN17IP<2:0>	
AN18 Conversion Done	169	161	0x000156	IFS10<1> AN18IF	IEC10<1> AN18IE	IPC40<6:4> AN18IP<2:0>	
AN19 Conversion Done	170	162	0x000158	IFS10<2> AN19IF	IEC10<2> AN19IE	IPC40<10:8> AN19IP<2:0>	
AN20 Conversion Done	171	163	0x00015A	IFS10<3> AN20IF	IEC10<3> AN20IE	IPC40<14:12> AN20IP<2:0>	
AN21 Conversion Done	172	164	0x00015C	IFS10<4> AN21IF	IEC10<4> AN21IE	IPC41<2:0> AN21IP<2:0>	
Reserved	173-180	165-172	0x00015C-0x00016C	_	_	—	
I2C1 – I2C1 Bus Collision	181	173	0x00016E	IFS10<13> I2C1IF	IEC10<13> I2C1IE	IPC43<6:4> I2C1IP<2:0>	
I2C2 – I2C2 Bus Collision	182	174	0x000170	IFS10<14> I2C2IF	IEC10<14> I2C2IE	IPC43<10:8> I2C2IP<2:0>	
Reserved	183-184	175-176	0x000172-0x000174	_	—	—	
ADCMP0 – ADC Digital Comparator 0	185	177	0x000176	IFS11<1> ADCMP0IF	IEC11<1> ADCMP0IE	IPC44<6:4> ADCMP0IP<2:0>	
ADCMP1 – ADC Digital Comparator 1	186	178	0x000178	IFS11<2> ADCMP1IF	IEC11<2> ADCMP1IE	IPC44<10:8> ADCMP1IP<2:0>	
ADFLTR0 – ADC Filter 0	187	179	0x00017A	IFS11<3> ADFLTR0IF	IEC11<3> ADFLTR0IE	IPC44<14:12> ADFLTR0IP<2:0>	
ADFLTR1 – ADC Filter 1	188	180	0x00017C	IFS11<4> ADFLTR1IF	IEC11<4> ADFLTR1IE	IPC45<2:0> ADFLTR1IP<2:0>	
Reserved	189-253	181-245	0x00017E-0x000192	—	—	—	

7.3 Interrupt Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

7.3.1 KEY RESOURCES

- "Interrupts" (DS70000600) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- · Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

7.4 Interrupt Control and Status Registers

dsPIC33EPXXXGS70X/80X family devices implement the following registers for the interrupt controller:

- INTCON1
- INTCON2
- INTCON3
- INTCON4
- INTTREG

7.4.1 INTCON1 THROUGH INTCON4

Global interrupt control functions are controlled from INTCON1, INTCON2, INTCON3 and INTCON4.

INTCON1 contains the Interrupt Nesting Disable bit (NSTDIS), as well as the control and status flags for the processor trap sources.

The INTCON2 register controls external interrupt request signal behavior, contains the Global Interrupt Enable bit (GIE) and the Alternate Interrupt Vector Table Enable bit (AIVTEN).

INTCON3 contains the status flags for the Auxiliary PLL and DO stack overflow status trap sources.

The INTCON4 register contains the Software Generated Hard Trap Status bit (SGHT).

7.4.2 IFSx

The IFSx registers maintain all of the interrupt request flags. Each source of interrupt has a status bit, which is set by the respective peripherals or external signal and is cleared via software.

7.4.3 IECx

The IECx registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

7.4.4 IPCx

The IPCx registers are used to set the Interrupt Priority Level (IPL) for each source of interrupt. Each user interrupt source can be assigned to one of seven priority levels.

7.4.5 INTTREG

The INTTREG register contains the associated interrupt vector number and the new CPU Interrupt Priority Level, which are latched into the Vector Number of Pending Interrupt bits (VECNUM<7:0>) and New CPU Interrupt Priority Level bits (ILR<3:0>) fields in the INTTREG register. The new Interrupt Priority Level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the same sequence as they are listed in Table 7-1. For example, the INT0 (External Interrupt 0) is shown as having Vector Number 8 and a natural order priority of 0. Thus, the INT0IF bit is found in IFS0<0>, the INT0IE bit in IEC0<0> and the INT0IP<2:0> bits in the first position of IPC0 (IPC0<2:0>).

7.4.6 STATUS/CONTROL REGISTERS

Although these registers are not specifically part of the interrupt control hardware, two of the CPU Control registers contain bits that control interrupt functionality. For more information on these registers, refer to "dsPIC33E Enhanced CPU" (DS70005158) in the "dsPIC33/PIC24 Family Reference Manual".

- The CPU STATUS Register, SR, contains the IPL<2:0> bits (SR<7:5>). These bits indicate the current CPU Interrupt Priority Level. The user software can change the current CPU Interrupt Priority Level by writing to the IPLx bits.
- The CORCON register contains the IPL3 bit which, together with IPL<2:0>, also indicates the current CPU priority level. IPL3 is a read-only bit so that trap events cannot be masked by the user software.

All Interrupt registers are described in Register 7-3 through Register 7-7 in the following pages.

REGISTER 7-1: SR: CPU STATUS REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/C-0	R/C-0	R-0	R/W-0
OA	OB	SA	SB	OAB	SAB	DA	DC
bit 15		•					bit 8
R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 ⁽²⁾	IPL1 ⁽²⁾	IPL0 ⁽²⁾	RA	N	OV	Z	С

bit 7

Legend:	C = Clearable bit			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'	
-n = Value at POR	'1'= Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 7-5	IPL<2:0>: CPU Interrupt Priority Level Status bits ^(2,3) 111 = CPU Interrupt Priority Level is 7 (15); user interrupts are disabled 110 = CPU Interrupt Priority Level is 6 (14) 101 = CPU Interrupt Priority Level is 5 (13) 100 = CPU Interrupt Priority Level is 4 (12) 011 = CPU Interrupt Priority Level is 3 (11) 010 = CPU Interrupt Priority Level is 2 (10) 001 = CPU Interrupt Priority Level is 1 (9)
	001 = CPU Interrupt Priority Level is 1 (9) 000 = CPU Interrupt Priority Level is 0 (8)

- **Note 1:** For complete register details, see Register 3-1.
 - 2: The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL, if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
 - 3: The IPL<2:0> Status bits are read-only when the NSTDIS bit (INTCON1<15>) = 1.

bit 0

REGISTER 7-2: CORCON: CORE CONTROL REGISTER⁽¹⁾

DAALO	DAALO	D 44/4	DAALO	D (0, 0		D 44/ 0	DAALO
bit 15							bit 8
VAR	—	US1	US0	EDT	DL2	DL1	DL0
R/W-0	U-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0

R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R-0	R/W-0	R/W-0
SATA	SATB	SATDW	ACCSAT	IPL3 ⁽²⁾	SFA	RND	IF
bit 7							bit 0

Legend:	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1'= Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 VAR: Variable Exception Processing Latency Control bit

1 = Variable exception processing is enabled

0 = Fixed exception processing is enabled

bit 3 IPL3: CPU Interrupt Priority Level Status bit 3⁽²⁾

1 = CPU Interrupt Priority Level is greater than 7

0 = CPU Interrupt Priority Level is 7 or less

Note 1: For complete register details, see Register 3-2.

2: The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 **NSTDIS OVAERR OVBERR** COVAERR COVBERR OVATE OVBTE COVTE bit 15 bit 8 R/W-0 R/W-0 U-0 R/W-0 R/W-0 R/W-0 R/W-0 U-0 STKERR SFTACERR **DIV0ERR** OSCFAIL ____ MATHERR ADDRERR bit 7 bit 0 Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15 **NSTDIS:** Interrupt Nesting Disable bit 1 = Interrupt nesting is disabled 0 = Interrupt nesting is enabled bit 14 **OVAERR:** Accumulator A Overflow Trap Flag bit 1 = Trap was caused by overflow of Accumulator A 0 = Trap was not caused by overflow of Accumulator A bit 13 **OVBERR:** Accumulator B Overflow Trap Flag bit 1 = Trap was caused by overflow of Accumulator B 0 = Trap was not caused by overflow of Accumulator B bit 12 COVAERR: Accumulator A Catastrophic Overflow Trap Flag bit 1 = Trap was caused by catastrophic overflow of Accumulator A 0 = Trap was not caused by catastrophic overflow of Accumulator A bit 11 **COVBERR:** Accumulator B Catastrophic Overflow Trap Flag bit 1 = Trap was caused by catastrophic overflow of Accumulator B 0 = Trap was not caused by catastrophic overflow of Accumulator B bit 10 **OVATE:** Accumulator A Overflow Trap Enable bit 1 = Trap overflow of Accumulator A 0 = Trap is disabled bit 9 **OVBTE:** Accumulator B Overflow Trap Enable bit 1 = Trap overflow of Accumulator B 0 = Trap is disabled bit 8 COVTE: Catastrophic Overflow Trap Enable bit 1 = Trap on catastrophic overflow of Accumulator A or B is enabled 0 = Trap is disabled bit 7 SFTACERR: Shift Accumulator Error Status bit 1 = Math error trap was caused by an invalid accumulator shift 0 = Math error trap was not caused by an invalid accumulator shift bit 6 DIVOERR: Divide-by-Zero Error Status bit 1 = Math error trap was caused by a divide-by-zero 0 = Math error trap was not caused by a divide-by-zero bit 5 Unimplemented: Read as '0' bit 4 MATHERR: Math Error Status bit 1 = Math error trap has occurred 0 = Math error trap has not occurred bit 3 ADDRERR: Address Error Trap Status bit 1 = Address error trap has occurred 0 = Address error trap has not occurred

REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1

REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1 (CONTINUED)

- bit 2 STKERR: Stack Error Trap Status bit
 - 1 = Stack error trap has occurred
 - 0 = Stack error trap has not occurred
- bit 1 OSCFAIL: Oscillator Failure Trap Status bit
 - 1 = Oscillator failure trap has occurred
 - 0 = Oscillator failure trap has not occurred
- bit 0 Unimplemented: Read as '0'

R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0				
GIE	DISI	SWTRAP		_		_	AIVTEN				
bit 15				L		L	bit				
U-0	U-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0				
	—	—	INT4EP	—	INT2EP	INT1EP	INT0EP				
bit 7							bit				
Logondi											
Legend: R = Readable	a hit	W = Writable	bit	II = I Inimple	mented bit, read	as '0'					
-n = Value at		'1' = Bit is set		0' = Bit is cle		x = Bit is unkr	าดพุท				
							10111				
bit 15	GIE: Global	Interrupt Enable	e bit								
		s and associate									
	0 = Interrupt	s are disabled,	but traps are s	till enabled							
bit 14		DISI: DISI Instruction Status bit									
		1 = DISI instruction is active 0 = DISI instruction is not active									
bit 13											
DIL 15	SWTRAP: Software Trap Status bit 1 = Software trap is enabled										
		e trap is disabled									
bit 12-9	Unimpleme	nted: Read as '	0'								
bit 8	AIVTEN: Alt	ernate Interrupt	Vector Table E	Enable							
		ernate Interrupt									
		andard Interrupt									
bit 7-5	-	nted: Read as '		Delevite Oele							
bit 4		ternal Interrupt 4 t on negative ed		Polarity Selec	t Dit						
		t on positive edg	•								
bit 3	•	nted: Read as '									
bit 2	-			Polarity Selec	t bit						
	INT2EP: External Interrupt 2 Edge Detect Polarity Select bit 1 = Interrupt on negative edge										
	0 = Interrupt on positive edge										
bit 1		ternal Interrupt 1	-	Polarity Selec	t bit						
		t on negative ed t on positive edg									
bit 0	•	ternal Interrupt (Polarity Selec	∿t hit						
		t on negative ed	-								
	⊥ – menupi	. on negative eu	90								

REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2

REGISTER 7-5: INTCON3: INTERRUPT CONTROL REGISTER 3

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
	_	_		_	_	_	NAE
bit 15	•		•	•	•		bit 8
U-0	U-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0
—	—	—	DOOVR	—	—	—	APLL
bit 7							bit 0
Legend:							
R = Readab	le bit	W = Writable	bit	U = Unimple	mented bit, read	as '0'	
-n = Value a	It POR	'1' = Bit is set	:	'0' = Bit is cleared		x = Bit is unknown	
bit 15-9	Unimpleme	nted: Read as	ʻ0 '				
bit 8	NAE: NVM	Address Error S	oft Trap Status	s bit			
	1 = NVM ad	dress error soft	trap has occur	rred			
	0 = NVM ad	dress error soft	trap has not o	ccurred			
bit 7-5	Unimplemented: Read as '0'						
bit 4	DOOVR: DO Stack Overflow Soft Trap S			tus bit			
	1 = DO stack	overflow soft tr	ap has occurre	ed			
	0 = DO stack	overflow soft tr	ap has not oco	curred			
h:+ 0 4	11	whends Deedlers	(c)				

- bit 3-1 Unimplemented: Read as '0'
- bit 0 APLL: Auxiliary PLL Loss of Lock Soft Trap Status bit
 - 1 = APLL lock soft trap has occurred
 - 0 = APLL lock soft trap has not occurred

REGISTER 7-6: INTCON4: INTERRUPT CONTROL REGISTER 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	—	—	—	—	—	—	—
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	SGHT
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set				'0' = Bit is cleared x = Bit is unknown			

bit 15-1 Unimplemented: Read as '0'

- SGHT: Software Generated Hard Trap Status bit
 - 1 = Software generated hard trap has occurred
 - 0 = Software generated hard trap has not occurred

bit 0

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
_	—	—	_		IL	R<3:0>	
bit 15							bi
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			VECN	IUM<7:0>			
bit 7							bit
Legend:							
R = Readab	le bit	W = Writable	bit	U = Unimpler		ad as '0'	
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unk	nown
	• • 0001 = CPU	Interrupt Priorit Interrupt Priorit Interrupt Priorit	y Level is 1	5			
bit 7-0	11111111 = 2 00001001 = 2 00001000 = 2 00000110 = 2 00000101 = 2 00000101 = 2 00000101 = 2 00000010 = 2 00000010 = 2 00000010 = 2 00000010 = 2 00000010 = 2 00000010 = 2 00000000 = 2 00000000 = 2 00000000 = 2 00000000 = 2 000000000 = 2 000000000 = 2 000000000 = 2 000000000 = 2 000000000 = 2 0000000000 = 2 0000000000 = 2 000000000 = 2 000000000 = 2 000000000 = 2 000000000 = 2 0000000000 = 2 000000000 = 2 000000000 = 2 000000000 = 2 0000000000 = 2 000000000 = 2 000000000 = 2 00000000 = 2 000000000 = 2 0000000000 = 2 0000000000 = 2 0000000000 = 2 0000000000 = 2 00000000000 = 2 000000000000000000000000000000000000	255, Reserved 9, IC1 – Input (8, INT0 – Exter 7, Reserved; d 6, Generic soft 5, Reserved; d 4, Math error tr 3, Stack error t 2, Generic hard 1, Address erro	; do not use Capture 1 rnal Interrup o not use error trap o not use ap rap d trap or trap	ling Interrupt bits			

REGISTER 7-7: INTTREG: INTERRUPT CONTROL AND STATUS REGISTER

8.0 DIRECT MEMORY ACCESS (DMA)

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Direct Memory Access (DMA)" (DS70348) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The DMA Controller transfers data between Peripheral Data registers and Data Space SRAM.

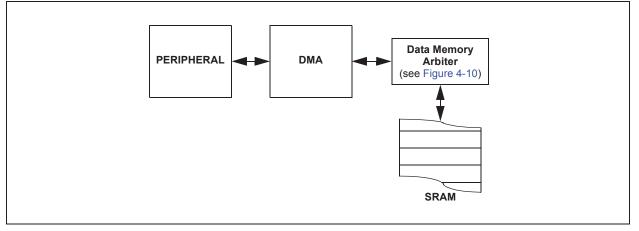
In addition, DMA can access the entire data memory space. The data memory bus arbiter is utilized when either the CPU or DMA attempts to access SRAM, resulting in potential DMA or CPU Stalls.

The DMA Controller supports four independent channels. Each channel can be configured for transfers to or from selected peripherals. The peripherals supported by the DMA Controller include:

- CAN
- UART
- Input Capture
- Output Compare
- Timers

Refer to Table 8-1 for a complete list of supported peripherals.

FIGURE 8-1: PERIPHERAL TO DMA CONTROLLER



In addition, DMA transfers can be triggered by timers as well as external interrupts. Each DMA channel is unidirectional. Two DMA channels must be allocated to read and write to a peripheral. If more than one channel receives a request to transfer data, a simple fixed priority scheme, based on channel number, dictates which channel completes the transfer and which channel, or channels, are left pending. Each DMA channel moves a block of data, after which, it generates an interrupt to the CPU to indicate that the block is available for processing.

The DMA Controller provides these functional capabilities:

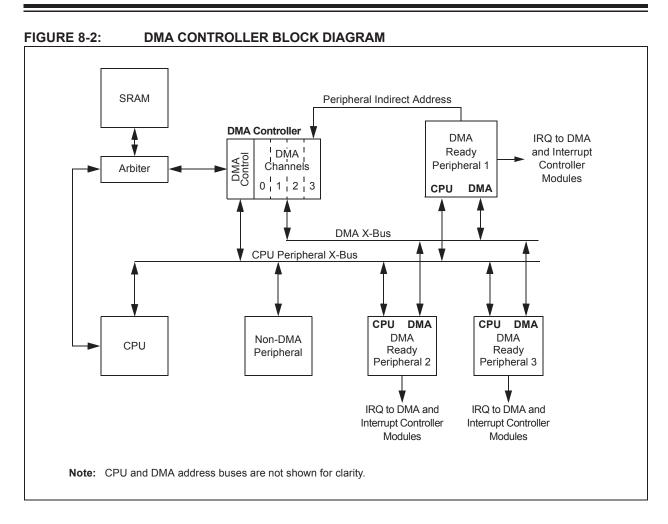
- Four DMA Channels
- Register Indirect with Post-Increment Addressing mode
- Register Indirect without Post-Increment Addressing mode

- Peripheral Indirect Addressing mode (peripheral generates destination address)
- CPU Interrupt after Half or Full Block Transfer Complete
- Byte or Word Transfers
- · Fixed Priority Channel Arbitration
- Manual (software) or Automatic (peripheral DMA requests) Transfer Initiation
- One-Shot or Auto-Repeat Block Transfer modes
- Ping-Pong mode (automatic switch between two SRAM Start addresses after each block transfer complete)
- DMA Request for each Channel can be Selected from any Supported Interrupt Source
- Debug Support Features

The peripherals that can utilize DMA are listed in Table 8-1.

Peripheral to DMA Association	DMAxREQ Register IRQSEL<7:0> Bits	DMAxPAD Register (Values to Read from Peripheral)	DMAxPAD Register (Values to Write to Peripheral)
INT0 – External Interrupt 0	00000000	—	—
IC1 – Input Capture 1	0000001	0x0144 (IC1BUF)	_
IC2 – Input Capture 2	00000101	0x014C (IC2BUF)	_
IC3 – Input Capture 3	00100101	0x0154 (IC3BUF)	_
IC4 – Input Capture 4	00100110	0x015C (IC4BUF)	_
OC1 – Output Compare 1	0000010	_	0x0906 (OC1R) 0x0904 (OC1RS)
OC2 – Output Compare 2	00000110	_	0x0910 (OC2R) 0x090E (OC2RS)
OC3 – Output Compare 3	00011001	_	0x091A (OC3R) 0x0918 (OC3RS)
OC4 – Output Compare 4	00011010	_	0x0924 (OC4R) 0x0922 (OC4RS)
TMR2 – Timer2	00000111	—	_
TMR3 – Timer3	00001000	—	_
TMR4 – Timer4	00011011	—	—
TMR5 – Timer5	00011100	—	—
UART1RX – UART1 Receiver	00001011	0x0226 (U1RXREG)	—
UART1TX – UART1 Transmitter	00001100	—	0x0224 (U1TXREG)
UART2RX – UART2 Receiver	00011110	0x0236 (U2RXREG)	
UART2TX – UART2 Transmitter	00011111	—	0x0234 (U2TXREG)
CAN1 – RX Data Ready	00100010	0x04C0 (C1RXD)	
CAN1 – TX Data Request	01000110	—	0x04C2 (C1TXD)
CAN2 – RX Data Ready	00110111	0x07C0(C2RXD)	_
CAN2 – TX Data Request	01000111		0x07C2 (C2TXD)

TABLE 8-1: DMA CHANNEL TO PERIPHERAL ASSOCIATIONS



8.1 DMA Controller Registers

Each DMA Controller Channel x (where x = 0 through 3) contains the following registers:

- 16-Bit DMA Channel x Control Register (DMAxCON)
- 16-Bit DMA Channel x IRQ Select Register (DMAxREQ)
- 32-Bit DMA Channel x Start Address Register A (DMAxSTAL/H)
- 32-Bit DMA Channel x Start Address Register B (DMAxSTBL/H)
- 16-Bit DMA Channel x Peripheral Address Register (DMAxPAD)
- 14-Bit DMA Channel x Transfer Count Register (DMAxCNT)

Additional status registers (DMAPWC, DMARQC, DMAPPS, DMALCA and DSADRL/H) are common to all DMA Controller channels. These status registers provide information on write and request collisions, as well as on last address and channel access information.

The interrupt flags (DMAxIF) are located in an IFSx register in the interrupt controller. The corresponding interrupt enable control bits (DMAxIE) are located in an IECx register in the interrupt controller and the corresponding interrupt priority control bits (DMAxIP) are located in an IPCx register in the interrupt controller.

REGISTER 8-1: DMAxCON: DMA CHANNEL x CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
CHEN	SIZE	DIR	HALF	NULLW	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0
	—	AMODE1	AMODE0	—	—	MODE1	MODE0
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	CHEN: DMA Channel Enable bit
	1 = Channel is enabled
	0 = Channel is disabled
bit 14	SIZE: DMA Data Transfer Size bit
	1 = Byte
	0 = Word
bit 13	DIR: Transfer Direction bit (source/destination bus select)
	1 = Reads from RAM address, writes to peripheral address
	0 = Reads from peripheral address, writes to RAM address
bit 12	HALF: Block Transfer Interrupt Select bit
	1 = Initiates interrupt when half of the data has been moved
	0 = Initiates interrupt when all of the data has been moved
bit 11	NULLW: Null Data Peripheral Write Mode Select bit
	1 = Null data write to peripheral in addition to RAM write (DIR bit must also be clear)
	0 = Normal operation
bit 10-6	Unimplemented: Read as '0'
bit 5-4	AMODE<1:0>: DMA Channel Addressing Mode Select bits
	11 = Reserved
	10 = Peripheral Indirect mode
	01 = Register Indirect with Post-Increment mode
h it 0 0	00 = Register Indirect with Post-Increment mode
bit 3-2	Unimplemented: Read as '0'
bit 1-0	MODE<1:0>: DMA Channel Operating Mode Select bits
	11 = One-Shot, Ping-Pong modes are enabled (one block transfer from/to each DMA buffer)
	10 = Continuous, Ping-Pong modes are enabled 01 = One-Shot, Ping-Pong modes are disabled
	00 = Continuous, Ping-Pong modes are disabled

REGISTER	8-2: DMAX	REQ: DMA C	HANNEL X	IRQ SELECT	REGISTER					
R/S-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
FORCE ⁽¹⁾	<u> </u>	—	_	—	<u> </u>	—				
bit 15							bit			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
			IRQSI	EL<7:0>						
bit 7							bit			
Legend:		S = Settable b	it							
R = Readabl	e bit	W = Writable I	oit	U = Unimplen	nented bit, read	l as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown			
bit 14-8 bit 7-0	 Forces a single DMA transfer (Manual mode) Automatic DMA transfer initiation by DMA request Unimplemented: Read as '0' IRQSEL<7:0>: DMA Peripheral IRQ Number Select bits 									
	01000111 = 01000110 = 00110111 = 00100100 = 00100100 = 00011111 = 00011100 = 00011001 = 00011001 = 00001100 = 00001000 = 00000100 = 00000100 = 00000100 = 00000100 = 00000100 = 00000100 = 00000100 = 00000100 = 00000100 = 00000010 = 00000010 = 00000010 =	CAN2 – TX dat CAN2 – TX dat CAN2 – RX dat CAN2 – RX dat IC4 – Input Cap IC3 – Input Cap CAN1 – RX dat UART2TX – U/ UART2TX – U/ UART2RX – U/ TMR5 – Timer5 TMR4 – Timer6 OC4 – Output (OC3 – Output (UART1RX – U/ TMR3 – Timer5 TMR2 – Timer5 OC2 – Output (IC2 – Input Cap OC1 – Output (IC1 – Input Cap	a request a request ta ready oture 4 oture 3 ta ready ART2 transm ART2 receive Compare 4 Compare 3 ART1 transm ART1 receive Compare 2 Compare 2 Compare 1	itter er						

REGISTER 8-2: DMAxREQ: DMA CHANNEL x IRQ SELECT REGISTER

Note 1: The FORCE bit cannot be cleared by user software. The FORCE bit is cleared by hardware when the forced DMA transfer is complete or the channel is disabled (CHEN = 0).

REGISTER 8-3: DMAxSTAH: DMA CHANNEL x START ADDRESS REGISTER A (HIGH)

R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 STA<23:16>								
R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 STA<23:16> bit 7 bit 7	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 STA<23:16> bit 7 bit 7	—	_	—	—	—	—	—	—
STA<23:16> bit 7 bit	bit 15							bit 8
STA<23:16> bit 7 bit								
bit 7 bit	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
Legend:				STA<	23:16>			
	bit 7							bit 0
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'	Legend:							
	R = Readable	bit	W = Writable b	it	U = Unimplei	mented bit, read	as '0'	

'0' = Bit is cleared

bit 15-8 Unimplemented: Read as '0'

-n = Value at POR

bit 7-0 STA<23:16>: DMA Primary Start Address bits (source or destination)

'1' = Bit is set

REGISTER 8-4: DMAxSTAL: DMA CHANNEL x START ADDRESS REGISTER A (LOW)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			STA	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			STA	<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimplen	nented bit, read	d as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
1							

bit 15-0 STA<15:0>: DMA Primary Start Address bits (source or destination)

x = Bit is unknown

REGISTER 8-5: DMAxSTBH: DMA CHANNEL x START ADDRESS REGISTER B (HIGH)

U-0	U-0	U-0	U-0	R/W-0	U-0	U-0	U-0			
—	—	—	—	—	—	—	—			
bit 15		•	·				bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
STB<23:16>										
bit 7							bit 0			

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 STB<23:16>: DMA Secondary Start Address bits (source or destination)

REGISTER 8-6: DMAxSTBL: DMA CHANNEL x START ADDRESS REGISTER B (LOW)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			STB	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			STE	3<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplen	nented bit, rea	id as '0'		
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown

bit 15-0 STB<15:0>: DMA Secondary Start Address bits (source or destination)

REGISTER 8-7: DMAxPAD: DMA CHANNEL x PERIPHERAL ADDRESS REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PAD	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PAI)<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable b	oit	U = Unimpler	mented bit, rea	id as '0'	
-n = Value at P	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknow		nown	

bit 15-0 PAD<15:0>: DMA Peripheral Address Register bits

Note 1: If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

REGISTER 8-8: DMAxCNT: DMA CHANNEL x TRANSFER COUNT REGISTER⁽¹⁾

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	_		CNT<13:8> ⁽²⁾							
bit 15							bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
			CNT<	<7:0> ⁽²⁾						
bit 7							bit 0			
Legend:										
R = Readable bit W = Writable bit			oit	U = Unimplemented bit, read as '0'						
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown			
L										

bit 15-14 Unimplemented: Read as '0'

bit 13-0 CNT<13:0>: DMA Transfer Count Register bits⁽²⁾

Note 1: If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

2: The number of DMA transfers = CNT<13:0> + 1.

REGISTER 8-9: DSADRH: DMA MOST RECENT RAM HIGH ADDRESS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			DSADR	<23:16>			
bit 7							bit 0
Legend:							
R = Readable b	it	W = Writable bi	t	U = Unimpler	nented bit, read	as '0'	

-n = Value at POR (1' = Bit is set (0' = Bit is cleared x = Bit is unknown)

bit 15-8 Unimplemented: Read as '0'

bit 7-0 DSADR<23:16>: Most Recent DMA Address Accessed by DMA bits

REGISTER 8-10: DSADRL: DMA MOST RECENT RAM LOW ADDRESS REGISTER

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			DSAD	R<15:8>			
bit 15							bit 8
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			DSAD)R<7:0>			
bit 7							bit 0
Legend:							
R = Readable b	pit	W = Writable b	it	U = Unimplemer	nted bit, rea	d as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cleare	ed	x = Bit is unkr	nown

bit 15-0 DSADR<15:0>: Most Recent DMA Address Accessed by DMA bits

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
—	—	—	—	—	—	—	—			
bit 15							bit 8			
U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0			
	—	_	—	PWCOL3	PWCOL2	PWCOL1	PWCOL0			
bit 7							bit 0			
Legend:										
R = Readable bit W = Writable bit			U = Unimplemented bit, read as '0'							
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	iown			
bit 15-4	Unimplemer	nted: Read as '	0'							
bit 3	PWCOL3: Channel 3 Peripheral Write Collision Flag bit									
	1 = Write collision is detected									
	0 = No write	collision is dete	ected							
bit 2		hannel 2 Periph		Ilision Flag bit						
		llision is detecte								
		collision is dete								
bit 1		hannel 1 Periph		Ilision Flag bit						
		llision is detecte								
		collision is dete								
			aral Mrita Ca	Illiaion Flog hit						
bit 0		hannel 0 Periph		illision Flag bit						
bit 0	1 = Write co	llision is detecte collision is detecte	ed	illision Flag bit						

REGISTER 8-12: DMARQC: DMA REQUEST COLLISION STATUS REGISTER

U-0 —	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	_	—	_					
bit 15						_	—	
DIL 15							bit 8	
U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0	
_	_	_	—	RQCOL3	RQCOL2	RQCOL1	RQCOL0	
bit 7							bit (
Legend:								
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set				'0' = Bit is cleared x = Bit is unknown				

bit 3	RQCOL3: Channel 3 Transfer Request Collision Flag bit
	1 = User FORCE and interrupt-based request collision are detected0 = No request collision is detected
bit 2	RQCOL2: Channel 2 Transfer Request Collision Flag bit
	1 = User FORCE and interrupt-based request collision are detected0 = No request collision is detected
bit 1	POCOLA: Channel 4 Transfer Deguart Collision Flog hit
	RQCOL1: Channel 1 Transfer Request Collision Flag bit
	 1 = User FORCE and interrupt-based request collision are detected 0 = No request collision is detected
bit 0	1 = User FORCE and interrupt-based request collision are detected
	1 = User FORCE and interrupt-based request collision are detected0 = No request collision is detected

REGISTER 8-13: DMALCA: DMA LAST CHANNEL ACTIVE STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
—	—	—	—	_	—	—	—	
bit 15						bit 8		
U-0	U-0	U-0	U-0	R-1	R-1	R-1	R-1	
—	—		—	LSTCH<3:0>				
bit 7							bit 0	
Legend:								
R = Readabl	le bit	W = Writable	bit	U = Unimpler	mented bit, read	as '0'		
-n = Value at	t POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown		
bit 15-4	Unimplemen	ted: Read as '	0'					
bit 3-0	LSTCH<3:0>	Last DMA Co	ntroller Chanr	nel Active Statu	us bits			
	1111 = No DMA transfer has occurred since system Reset							
	1110 = Reser	ved						
	•							
	•							
	0100 = Rese r	ved						
	0011 = Last c	lata transfer wa	as handled by	Channel 3				
		lata transfer wa						
		lata transfer wa						
	0000 = Last data transfer was handled by Channel 0							

REGISTER 8-14: DMAPPS: DMA PING-PONG STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
	_	_	_	PPST3	PPST2	PPST1	PPST0

bit 0

Legend:				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown		
bit 15-4 Unimp	emented: Read as '0'			

bit 3	PPST3: Channel 3 Ping-Pong Mode Status Flag bit
	1 = DMA3STB register is selected0 = DMA3STA register is selected
bit 2	PPST2: Channel 2 Ping-Pong Mode Status Flag bit
	1 = DMA2STB register is selected
	0 = DMA2STA register is selected
bit 1	PPST1: Channel 1 Ping-Pong Mode Status Flag bit
	1 = DMA1STB register is selected
	0 = DMA1STA register is selected
bit 0	PPST0: Channel 0 Ping-Pong Mode Status Flag bit
	1 = DMA0STB register is selected
	0 = DMA0STA register is selected

bit 7

NOTES:

9.0 OSCILLATOR CONFIGURATION

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Oscillator Module" (DS70005131) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family oscillator system provides:

- On-Chip Phase-Locked Loop (PLL) to Boost Internal Operating Frequency on Select Internal and External Oscillator Sources
- On-the-Fly Clock Switching between Various Clock Sources
- Doze mode for System Power Savings
- Fail-Safe Clock Monitor (FSCM) that Detects Clock Failure and Permits Safe Application Recovery or Shutdown
- Configuration Bits for Clock Source Selection
- Auxiliary PLL for ADC and PWM

A simplified diagram of the oscillator system is shown in Figure 9-1.

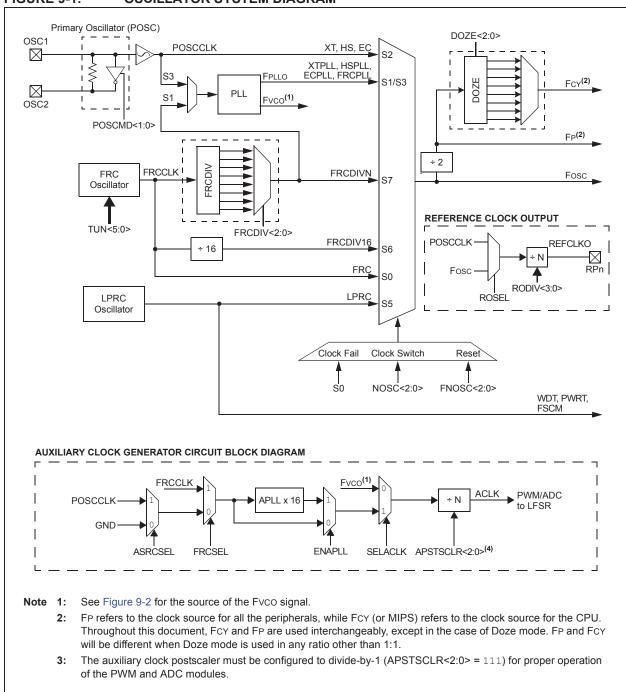


FIGURE 9-1: OSCILLATOR SYSTEM DIAGRAM

9.1 CPU Clocking System

The dsPIC33EPXXXGS70X/80X family of devices provides six system clock options:

- Fast RC (FRC) Oscillator
- FRC Oscillator with Phase-Locked Loop (FRCPLL)
- FRC Oscillator with Postscaler
- Primary (XT, HS or EC) Oscillator
- Primary Oscillator with PLL (XTPLL, HSPLL, ECPLL)
- Low-Power RC (LPRC) Oscillator

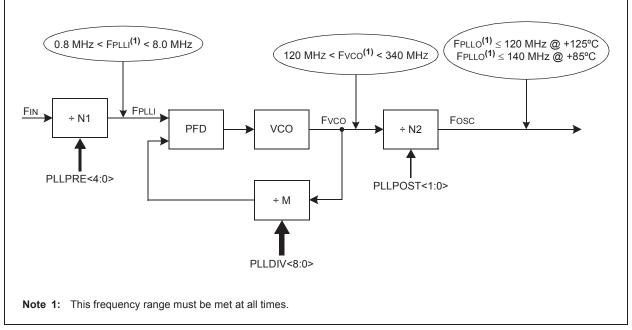


Instruction execution speed or device operating frequency, FCY, is given by Equation 9-1.

EQUATION 9-1: DEVICE OPERATING FREQUENCY

FCY = FOSC/2

Figure 9-2 is a block diagram of the PLL module. Equation 9-2 provides the relationship between Input Frequency (FIN) and Output Frequency (FPLLO). Equation 9-3 provides the relationship between Input Frequency (FIN) and VCO Frequency (FVCO).



EQUATION 9-2: FPLLO CALCULATION

$$FPLLO = FIN \times \left(\frac{M}{N1 \times N2}\right) = FIN \times \left(\frac{PLLDIV < 8:0> + 2}{(PLLPRE < 4:0> + 2) \times 2(PLLPOST < 1:0> + 1)}\right)$$

Where: M1 - PII

N1 = PLLPRE < 4:0 > +2

$$N2 = 2 \times (PLLPOST < 1:0 > +1)$$

M = PLLDIV < 8:0 > +2

EQUATION 9-3: Fvco CALCULATION

$$F_{VCO} = F_{IN} \times \left(\frac{M}{N1}\right) = F_{IN} \times \left(\frac{PLLDIV < 8:0 > +2}{(PLLPRE < 4:0 > +2)}\right)$$

TABLE 9-1 :	CONFIGURATION BIT VALUES FOR CLOCK SELECTION
--------------------	--

Oscillator Mode	Oscillator Source	POSCMD<1:0>	FNOSC<2:0>	See Notes
Fast RC Oscillator with Divide-by-n (FRCDIVN)	Internal	XX	111	1, 2
Fast RC Oscillator with Divide-by-16	Internal	XX	110	1
Low-Power RC Oscillator (LPRC)	Internal	XX	101	1
Primary Oscillator (HS) with PLL (HSPLL)	Primary	10	011	
Primary Oscillator (XT) with PLL (XTPLL)	Primary	01	011	
Primary Oscillator (EC) with PLL (ECPLL)	Primary	0.0	011	1
Primary Oscillator (HS)	Primary	10	010	
Primary Oscillator (XT)	Primary	01	010	
Primary Oscillator (EC)	Primary	0.0	010	1
Fast RC Oscillator (FRC) with Divide-by-N and PLL (FRCPLL)	Internal	XX	001	1
Fast RC Oscillator (FRC)	Internal	XX	000	1

Note 1: OSC2 pin function is determined by the OSCIOFNC Configuration bit.

2: This is the default Oscillator mode for an unprogrammed (erased) device.

9.2 Auxiliary Clock Generation

The auxiliary clock generation is used for peripherals that need to operate at a frequency unrelated to the system clock, such as PWM or ADC.

The primary oscillator and internal FRC oscillator sources can be used with an Auxiliary PLL (APLL) to obtain the auxiliary clock. The Auxiliary PLL has a fixed 16x multiplication factor.

The auxiliary clock has the following configuration restrictions:

- For proper PWM operation, auxiliary clock generation must be configured for 120 MHz (see Parameter OS56 in Section 30.0 "Electrical Characteristics"). If a slower frequency is desired, the PWM Input Clock Prescaler (Divider) Select bits (PCLKDIV<2:0>) should be used.
- To achieve 1.04 ns PWM resolution, the auxiliary clock must use the 16x Auxiliary PLL (APLL). All other clock sources will have a minimum PWM resolution of 8 ns.
- If the primary PLL is used as a source for the auxiliary clock, the primary PLL should be configured up to a maximum operation of 30 MIPS or less.

9.3 Reference Clock Generation

The reference clock output logic provides the user with the ability to output a clock signal based on the system clock or the crystal oscillator on a device pin. The user application can specify a wide range of clock scaling prior to outputting the reference clock.

9.4 Oscillator Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

9.4.1 KEY RESOURCES

- "Oscillator Module" (DS70005131) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

9.5 Oscillator Control Registers

REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER⁽¹⁾

U-0	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
—	COSC2	COSC1	COSC0	—	NOSC2 ⁽²⁾	NOSC1 ⁽²⁾	NOSC0 ⁽²⁾
bit 15							bit 8

R/W-0	R/W-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0
CLKLOCK	IOLOCK	LOCK	—	CF ⁽³⁾	—	—	OSWEN
bit 7							bit 0

Legend:	y = Value set from Cor	nfiguration bits on POR	
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-12	COSC<2:0>: Current Oscillator Selection bits (read-only)
	111 = Fast RC Oscillator (FRC) with Divide-by-n
	110 = Fast RC Oscillator (FRC) with Divide-by-16
	101 = Low-Power RC Oscillator (LPRC)
	100 = Reserved 011 = Primary Oscillator (XT, HS, EC) with PLL
	010 = Primary Oscillator (XT, HS, EC)
	001 = Fast RC Oscillator (FRC) with Divide-by-N and PLL (FRCPLL)
	000 = Fast RC Oscillator (FRC)
bit 11	Unimplemented: Read as '0'
bit 10-8	NOSC<2:0>: New Oscillator Selection bits ⁽²⁾
	111 = Fast RC Oscillator (FRC) with Divide-by-n
	110 = Fast RC Oscillator (FRC) with Divide-by-16
	101 = Low-Power RC Oscillator (LPRC) 100 = Reserved
	011 = Primary Oscillator (XT, HS, EC) with PLL
	010 = Primary Oscillator (XT, HS, EC)
	001 = Fast RC Oscillator (FRC) with Divide-by-N and PLL (FRCPLL)
	000 = Fast RC Oscillator (FRC)
bit 7	CLKLOCK: Clock Lock Enable bit
	1 = If (FCKSM0 = 1), then clock and PLL configurations are locked; if (FCKSM0 = 0), then clock and PLL configurations may be modified
	0 = Clock and PLL selections are not locked, configurations may be modified
bit 6	IOLOCK: I/O Lock Enable bit
	1 = I/O lock is active
	0 = I/O lock is not active
bit 5	LOCK: PLL Lock Status bit (read-only)
	1 = Indicates that PLL is in lock or PLL start-up timer is satisfied
	0 = Indicates that PLL is out of lock, start-up timer is in progress or PLL is disabled
Note 1:	Writes to this register require an unlock sequence.
2:	Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL mode are not
	permitted. This applies to clock switches in either direction. In these instances, the application must switch
-	to FRC mode as a transitional clock source between the two PLL modes.
3:	This bit should only be cleared in software. Setting the bit in software (= 1) will have the same effect as an

3: This bit should only be cleared in software. Setting the bit in software (= 1) will have the same effect as an actual oscillator failure and will trigger an oscillator failure trap.

REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER⁽¹⁾ (CONTINUED)

- bit 4 Unimplemented: Read as '0'
- bit 3 **CF:** Clock Fail Detect bit⁽³⁾
 - 1 = FSCM has detected a clock failure
 - 0 = FSCM has not detected a clock failure
- bit 2-1 Unimplemented: Read as '0'
- bit 0 OSWEN: Oscillator Switch Enable bit
 - 1 = Requests oscillator switch to the selection specified by the NOSC<2:0> bits
 - 0 = Oscillator switch is complete
- **Note 1:** Writes to this register require an unlock sequence.
 - 2: Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transitional clock source between the two PLL modes.
 - **3:** This bit should only be cleared in software. Setting the bit in software (= 1) will have the same effect as an actual oscillator failure and will trigger an oscillator failure trap.

REGISTER 9-2: CLKDIV: CLOCK DIVISOR REGISTER

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
ROI	DOZE2 ⁽¹⁾	DOZE1 ⁽¹⁾	DOZE0 ⁽¹⁾	DOZEN ^(2,3)	FRCDIV2	FRCDIV1	FRCDIV0
bit 15							bit 8
R/W-0	R/W-1	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PLLPOS	T1 PLLPOST0		PLLPRE4	PLLPRE3	PLLPRE2	PLLPRE1	PLLPRE0
bit 7							bit 0
Legend:							
R = Read	able bit	W = Writable	oit	U = Unimplem	nented bit, read	l as '0'	
-n = Value	e at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
bit 15 bit 14-12	1 = Interrupts 0 = Interrupts	on Interrupt bi will clear the D have no effec Processor Cloo	OZEN bit and t on the DOZE		ock, and the pe	ripheral clock ra	atio is set to 1:1
	111 = FCY div 110 = FCY div 101 = FCY div 100 = FCY div 011 = FCY div 010 = FCY div 001 = FCY div 000 = FCY div	vided by 64 vided by 32 vided by 16 vided by 8 (defa vided by 4 vided by 2	ult)				
bit 11	DOZEN: Doze 1 = DOZE<2:	e Mode Enable 0> field specifie	es the ratio bet	ween the peripl atio is forced to		d the processo	r clocks
bit 10-8	111 = FRC di 110 = FRC di 101 = FRC di 100 = FRC di 011 = FRC di 010 = FRC di 001 = FRC di	vided by 64 vided by 32 vided by 16 vided by 8 vided by 4		Postscaler bits			
bit 7-6	11 = Output d 10 = Reserve 01 = Output d	livided by 8 d livided by 4 (de		Select bits (also	o denoted as 'f	N2', PLL postsc	caler)
bit 5	00 = Output d	ted: Read as '	۱,				
bit 5	Unimplement		J				
Note 1:	The DOZE<2:0> I DOZE<2:0> are iç	•	e written to whe	en the DOZEN	bit is clear. If D	OZEN = 1, any	v writes to
2:	This bit is cleared						
3:	The DOZEN bit ca	annot be set if I	DOZE<2:0> =	000. If DOZE<2	2:0> = 000, any	y attempt by us	er software to

3: The DOZEN bit cannot be set if DOZE<2:0> = 000. If DOZE<2:0> = 000, any attempt by user software to set the DOZEN bit is ignored.

REGISTER 9-2: CLKDIV: CLOCK DIVISOR REGISTER (CONTINUED)

bit 4-0

PLLPRE<4:0>: PLL Phase Detector Input Divider Select bits (also denoted as 'N1', PLL prescaler) 11111 = Input divided by 33

- •
- 00001 = Input divided by 3

00000 =Input divided by 2 (default)

- **Note 1:** The DOZE<2:0> bits can only be written to when the DOZEN bit is clear. If DOZEN = 1, any writes to DOZE<2:0> are ignored.
 - **2:** This bit is cleared when the ROI bit is set and an interrupt occurs.
 - **3:** The DOZEN bit cannot be set if DOZE<2:0> = 000. If DOZE<2:0> = 000, any attempt by user software to set the DOZEN bit is ignored.

REGISTER 9-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—		PLLDIV8
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
			PLLDI	V<7:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-9 Unimplemented: Read as '0'

REGISTER 9-4: OSCTUN: FRC OSCILLATOR TUNING REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	_		_	—
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
0-0	0-0	10,00-0	10/00-0		<5:0>	10,00-0	10/00-0
 bit 7				TON	<5.0>		bit 0
DIL 7							bit 0
Legend:							
R = Readable	e bit	W = Writable b	pit	U = Unimplen	nented bit, read	d as '0'	
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown				
bit 15-6	Unimplemen	ted: Read as '0	,				
bit 5-0	TUN<5:0>: FI	RC Oscillator T	uning bits				
		nter frequen			7 MHz)		
	000000 = Ce	nter frequency nter frequency nter frequency	(7.37 MHz noi	minal)			
		nter frequency - nimum frequenc	•	,	ИНz)		

Note 1: OSCTUN functionality has been provided to help customers compensate for temperature effects on the FRC frequency over a wide range of temperatures. The tuning step-size is an approximation and is neither characterized nor tested.

REGISTER 9-5: ACLKCON: AUXILIARY CLOCK DIVISOR CONTROL REGISTER

R/W-0	R-0	R/W-1	U-0	U-0	R/W-1	R/W-1	R/W-1
ENAPLL	APLLCK	SELACLK	_	_	APSTSCLR2	APSTSCLR1	APSTSCLR0
bit 15	·			·		•	bit 8
R/W-0	R/W-1	U-0	U-0	U-0	U-0	U-0	U-0
ASRCSEL	EL FRCSEL — — — — — —						
bit 7							bit 0
Legend:							
R = Readabl	e bit	W = Writable b	it	U = Unimplen	nented bit, read	l as '0'	
-n = Value at		'1' = Bit is set	•	0' = Bit is cleared x = Bit is unknown		iown	
							-
bit 15	ENAPLL: Au	xiliary PLL Enabl	e bit				
	1 = APLL is e	-					
	0 = APLL is d	lisabled					
bit 14	APLLCK: AP	LL Locked Statu	s bit (read-or	nly)			
		that Auxiliary PL					
1.1.10		that Auxiliary PL					
bit 13		elect Auxiliary C				dial and	
		oscillators provid PLL (Fvco) provid					
bit 12-11	Unimplemen	ted: Read as '0'			-		
bit 10-8	APSTSCLR<	2:0>: Auxiliary C	lock Output	Divider bits			
	111 = Divideo						
	110 = Divideo						
	101 = Divideo						
	100 = Divideo 011 = Divideo						
	010 = Divideo	•					
	001 = Divideo	,					
	000 = Divideo	d by 256					
bit 7	ASRCSEL: S	elect Reference	Clock Sourc	e for Auxiliary C	Clock bit		
		scillator is the cl input is selected	ock source				
bit 6	FRCSEL: Se	lect Reference C	lock Source	for Auxiliary PL	L bit		
		ne FRC clock for					
	0 = Input cloc	k source is deter	mined by the	ASRCSEL bit	setting		
	-	ted: Read as '0'	-		0		

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ROON		ROSSLP	ROSEL	RODIV3 ⁽¹⁾	RODIV2 ⁽¹⁾	RODIV1 ⁽¹⁾	RODIV0 ⁽¹⁾
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	— hit (
bit 7							bit (
Legend:							
R = Readable	e bit	W = Writable I	oit	U = Unimplem	nented bit, read	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	nown
bit 14	0 = Reference	e oscillator outp e oscillator outp ted: Read as '0	ut is disabled	on the RPn pin ⁽	2)		
bit 13		ference Oscilla e oscillator outp		•			
		e oscillator outp					
bit 12	ROSEL: Refe	erence Oscillato	r Source Sele	ct bit			
		crystal is used lock is used as					
bit 11-8	•	Reference Os					
	1110 = Refer 1101 = Refer 100 = Refer 1011 = Refer 1010 = Refer 1000 = Refer 0111 = Refer 0110 = Refer 0101 = Refer 0100 = Refer 0101 = Refer 0011 = Refer 0011 = Refer 0011 = Refer	ence clock divid ence clock divid	ded by 16,384 ded by 8,192 ded by 4,096 ded by 2,048 ded by 1,024 ded by 512 ded by 512 ded by 256 ded by 128 ded by 64 ded by 32 ded by 16 ded by 8 ded by 4				
bit 7-0	0000 = Refer	ence clock ted: Read as '0)'				
	Sumbiomen		,				

REGISTER 9-6: REFOCON: REFERENCE OSCILLATOR CONTROL REGISTER

- **Note 1:** The reference oscillator output must be disabled (ROON = 0) before writing to these bits.
 - 2: This pin is remappable. See Section 11.6 "Peripheral Pin Select (PPS)" for more information.

REGISTER 9-7: LFSR: LINEAR FEEDBACK SHIFT REGISTER

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—				LFSR<14:8>	•		
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			LFS	R<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimplen	nented bit, rea	d as '0'	
-n = Value at POR '1' = Bit is		'1' = Bit is set	t	'0' = Bit is cle	ared	x = Bit is unkn	iown

bit 15 Unimplemented: Read as '0'

bit 14-0 LFSR<14:0>: Pseudorandom Data bits

10.0 POWER-SAVING FEATURES

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Watchdog Timer and Power-Saving Modes" (DS70615) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family devices provide the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of peripherals being clocked constitutes lower consumed power.

dsPIC33EPXXXGS70X/80X family devices can manage power consumption in four ways:

- Clock Frequency
- Instruction-Based Sleep and Idle modes
- · Software-Controlled Doze mode
- · Selective Peripheral Control in Software

Combinations of these methods can be used to selectively tailor an application's power consumption while still maintaining critical application features, such as timing-sensitive communications.

EXAMPLE 10-1: PWRSAV INSTRUCTION SYNTAX

PWRSAV#SLEEP_MODE; Put the device into Sleep modePWRSAV#IDLE; Put the device into Idle mode

10.1 Clock Frequency and Clock Switching

The dsPIC33EPXXXGS70X/80X family devices allow a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSCx bits (OSCCON<10:8>). The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in Section 9.0 "Oscillator Configuration".

10.2 Instruction-Based Power-Saving Modes

The dsPIC33EPXXXGS70X/80X family devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution. Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The assembler syntax of the PWRSAV instruction is shown in Example 10-1.

Note: SLEEP_MODE and IDLE_MODE are constants defined in the assembler include file for the selected device.

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to "wake-up".

10.2.1 SLEEP MODE

The following occurs in Sleep mode:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption is reduced to a minimum, provided that no I/O pin is sourcing current.
- The Fail-Safe Clock Monitor does not operate, since the system clock source is disabled.
- The LPRC clock continues to run in Sleep mode if the WDT is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals can continue to operate. This includes items such as the Input Change Notification on the I/O ports or peripherals that use an external clock input.
- Any peripheral that requires the system clock source for its operation is disabled.

The device wakes up from Sleep mode on any of the these events:

- Any interrupt source that is individually enabled
- · Any form of device Reset
- A WDT time-out

On wake-up from Sleep mode, the processor restarts with the same clock source that was active when Sleep mode was entered.

For optimal power savings, the internal regulator and the Flash regulator can be configured to go into standby when Sleep mode is entered by clearing the VREGS (RCON<8>) and VREGSF (RCON<11>) bits (default configuration).

If the application requires a faster wake-up time, and can accept higher current requirements, the VREGS (RCON<8>) and VREGSF (RCON<11>) bits can be set to keep the internal regulator and the Flash regulator active during Sleep mode.

10.2.2 IDLE MODE

The following occurs in Idle mode:

- The CPU stops executing instructions.
- The WDT is automatically cleared.
- The system clock source remains active. By default, all peripheral modules continue to operate normally from the system clock source, but can also be selectively disabled (see Section 10.4 "Peripheral Module Disable").
- If the WDT or FSCM is enabled, the LPRC also remains active.

The device wakes from Idle mode on any of these events:

- · Any interrupt that is individually enabled
- · Any device Reset
- A WDT time-out

On wake-up from Idle mode, the clock is reapplied to the CPU and instruction execution will begin (two to four clock cycles later), starting with the instruction following the PWRSAV instruction or the first instruction in the ISR.

All peripherals also have the option to discontinue operation when Idle mode is entered to allow for increased power savings. This option is selectable in the control register of each peripheral (for example, the TSIDL bit in the Timer1 Control register (T1CON<13>).

10.2.3 INTERRUPTS COINCIDENT WITH POWER SAVE INSTRUCTIONS

Any interrupt that coincides with the execution of a PWRSAV instruction is held off until entry into Sleep or Idle mode has completed. The device then wakes up from Sleep or Idle mode.

10.3 Doze Mode

The preferred strategies for reducing power consumption are changing clock speed and invoking one of the power-saving modes. In some circumstances, this cannot be practical. For example, it may be necessary for an application to maintain uninterrupted synchronous communication, even while it is doing nothing else. Reducing system clock speed can introduce communication errors, while using a power-saving mode can stop communications completely.

Doze mode is a simple and effective alternative method to reduce power consumption while the device is still executing code. In this mode, the system clock continues to operate from the same source and at the same speed. Peripheral modules continue to be clocked at the same speed, while the CPU clock speed is reduced. Synchronization between the two clock domains is maintained, allowing the peripherals to access the SFRs while the CPU executes code at a slower rate.

Doze mode is enabled by setting the DOZEN bit (CLKDIV<11>). The ratio between peripheral and core clock speed is determined by the DOZE<2:0> bits (CLKDIV<14:12>). There are eight possible configurations, from 1:1 to 1:128, with 1:1 being the default setting.

Programs can use Doze mode to selectively reduce power consumption in event-driven applications. This allows clock-sensitive functions, such as synchronous communications, to continue without interruption while the CPU Idles, waiting for something to invoke an interrupt routine. An automatic return to full-speed CPU operation on interrupts can be enabled by setting the ROI bit (CLKDIV<15>). By default, interrupt events have no effect on Doze mode operation.

10.4 Peripheral Module Disable

The Peripheral Module Disable (PMD) registers provide a method to disable a peripheral module by stopping all clock sources supplied to that module. When a peripheral is disabled using the appropriate PMD control bit, the peripheral is in a minimum power consumption state. The control and status registers associated with the peripheral are also disabled, so writes to those registers do not have any effect and read values are invalid.

A peripheral module is enabled only if both the associated bit in the PMD register is cleared and the peripheral is supported by the specific dsPIC[®] DSC variant. If the peripheral is present in the device, it is enabled in the PMD register by default.

Note: If a PMD bit is set, the corresponding module is disabled after a delay of one instruction cycle. Similarly, if a PMD bit is cleared, the corresponding module is enabled after a delay of one instruction cycle (assuming the module control registers are already configured to enable module operation).

10.5 Power-Saving Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

10.5.1 KEY RESOURCES

- "Watchdog Timer and Power-Saving Modes" (DS70615) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- · Software Libraries
- Webinars
- All related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
T5MD	T4MD	T3MD	T2MD	T1MD	_	PWMMD	_
bit 15	•						bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	C2MD	C1MD	ADCMD
bit 7	UZIVID	UTIVID	SPIZIVID	SPITIVID	CZIVID	CTIVID	bit
							DIL
Legend:							
R = Readable	e bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own
hit 15	TEND: Timor	E Madula Diaal	ala hit				
bit 15		5 Module Disal odule is disabl					
		odule is disable					
bit 14		4 Module Disal					
		odule is disable					
		odule is enable					
bit 13	T3MD: Timer	3 Module Disal	ole bit				
	1 = Timer3 m	odule is disable	ed				
		odule is enable					
bit 12	T2MD: Timer	2 Module Disal	ole bit				
	1 = Timer2 m	odule is disabl	ed				
	0 = Timer2 m	odule is enable	ed				
bit 11	T1MD: Timer	1 Module Disal	ole bit				
		odule is disable					
		odule is enable					
bit 10	-	ted: Read as '					
bit 9		/M Module Dis					
		dule is disableo dule is enableo					
bit 8		ted: Read as '	-				
bit 7	-	1 Module Disal					
	-	lule is disabled					
		lule is enabled					
bit 6	U2MD: UART	2 Module Disa	ıble bit				
	1 = UART2 m	nodule is disabl	ed				
	0 = UART2 m	nodule is enable	ed				
bit 5	U1MD: UART	1 Module Disa	ıble bit				
	-	nodule is disabl					
	0 = UART1 m	nodule is enable	ed				
bit 4	SPI2MD: SPI	2 Module Disa	ble bit				
		lule is disabled					
h # 0		dule is enabled					
bit 3		1 Module Disa					
		lule is disabled lule is enabled					
bit 2		2 Module Disab	le hit				
	-	dule is disable					

REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1

REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1 (CONTINUED)

- bit 1 C1MD: CAN1 Module Disable bit
 - 1 = CAN1 module is disabled
 - 0 = CAN1 module is enabled
- bit 0 ADCMD: ADC Module Disable bit
 - 1 = ADC module is disabled
 - 0 = ADC module is enabled

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	IC4MD	IC3MD	IC2MD	IC1MD
bit 15							bit 8
U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—		OC4MD	OC3MD	OC2MD	OC1MD
bit 7							bit 0
Legend:							
R = Readat	ole bit	W = Writable I	oit	U = Unimplem	nented bit, read	d as '0'	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
bit 15-12	Unimplemen	ted: Read as 'o)'				
bit 11	IC4MD: Input	Capture 4 Mod	ule Disable bi	t			
		ture 4 module i					
		ture 4 module i					
bit 10		Capture 3 Mod		I			
		ture 3 module i ture 3 module i					
bit 9		Capture 2 Mod		t			
		ture 2 module i					
	0 = Input Cap	ture 2 module i	s enabled				
bit 8	IC1MD: Input	Capture 1 Mod	ule Disable bi	t			
		ture 1 module i					
		ture 1 module i					
bit 7-4	-	ted: Read as '0					
bit 3		out Compare 4		e bit			
	•	ompare 4 modu ompare 4 modu					
bit 2		out Compare 3		e bit			
	-	ompare 3 modu		o bit			
		ompare 3 modu					
bit 1	OC2MD: Outp	out Compare 2	Module Disabl	e bit			
		ompare 2 modu					
	-	ompare 2 modu					
bit 0		out Compare 1		e bit			
		ompare 1 modu ompare 1 modu					
		mpare i modu					

REGISTER 10-2: PMD2: PERIPHERAL MODULE DISABLE CONTROL REGISTER 2

REGISTER 10-3: PMD3: PERIPHERAL MODULE DISABLE CONTROL REGISTER 3

U-0	U-0	U-0	U-0	U-0	R/W-0	U-0	U-0		
_	_	—	—	—	CMPMD	—	—		
bit 15							bit 8		
U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0		
—	—	—	—	—	_	I2C2MD	—		
bit 7							bit 0		
Legend:									
R = Readable	e bit	W = Writable I	oit	U = Unimplemented bit, read as '0'					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown					
bit 15-11	Unimplemen	ted: Read as 'o)'						
bit 10	CMPMD: Cor	nparator Modul	e Disable bit						
	1 = Comparat	or module is di	sabled						
	0 - Comparat	or module is er							

bit 9-2	Unimplemented: Read as '0'
bit 1	I2C2MD: I2C2 Module Disable bit
	1 = I2C2 module is disabled
	0 = I2C2 module is enabled
h:+ 0	Unimalemented, Deed on (o)

bit 0 Unimplemented: Read as '0'

REGISTER 10-4: PMD4: PERIPHERAL MODULE DISABLE CONTROL REGISTER 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	U-0	U-0	U-0	
—	—	—	—	REFOMD	—	—	_	
bit 7							bit 0	

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit
;

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PWM8MD	PWM7MD	PWM6MD	PWM5MD	PWM4MD	PWM3MD	PWM2MD	PWM1MD
bit 15					1		bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
				—	—		SPI3MD
bit 7							bit 0
Legend:	- L:4		- 14			L (0)	
R = Readable		W = Writable	JIC		nented bit, read		
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	IOWN
bit 15		WM8 Module D	isablo bit				
DIL 15		odule is disable					
		odule is enable					
bit 14	PWM7MD: P	WM7 Module D	isable bit				
	1 = PWM7 mo	odule is disable	d				
	0 = PWM7 mo	odule is enable	d				
bit 13		WM6 Module D					
		odule is disable odule is enable					
bit 12		WM5 Module D	-				
		odule is disable					
	0 = PWM5 m	odule is enable	d				
bit 11	PWM4MD: P	WM4 Module D	isable bit				
		odule is disable					
		odule is enable					
bit 10		WM3 Module D					
		odule is disable odule is enable					
bit 9		WM2 Module D					
		odule is disable					
	0 = PWM2 mo	odule is enable	d				
bit 8	PWM1MD: P	WM1 Module D	isable bit				
		odule is disable					
		odule is enable	-				
bit 7-1	•	ted: Read as '					
bit 0		3 Module Disat	ole bit				
		lule is disabled					
	0 - 3713 1100	lule is enabled					

REGISTER 10-5: PMD6: PERIPHERAL MODULE DISABLE CONTROL REGISTER 6

REGISTER 10-6: PMD7: PERIPHERAL MODULE DISABLE CONTROL REGISTER 7

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
_		_		CMP4MD	CMP3MD	CMP2MD	CMP1MD
bit 15	ł				L		bit 8
U-0	U-0	U-0	R/W-0	R/W-0	U-0	R/W-0	U-0
_	—	—	DMAMD	PTGMD	—	PGA1MD	—
bit 7							bit C
Legend:							
R = Readabl	e bit	W = Writable	bit	U = Unimplem	nented bit, read	t as '0'	
	n = Value at POR (1' = Bit is set			'0' = Bit is clea		x = Bit is unkr	nown
			-				-
bit 15-12	Unimpleme	nted: Read as '	0'				
bit 11	CMP4MD: C	CMP4 Module D	isable bit				
		nodule is disable					
		nodule is enable	-				
bit 10		CMP3 Module D					
		nodule is disable nodule is enable					
bit 9		CMP2 Module D					
		nodule is disable					
	0 = CMP2 m	nodule is enable	d				
bit 8	CMP1MD: C	CMP1 Module D	isable bit				
		nodule is disable					
6:4 7 F		nodule is enable					
bit 7-5 bit 4	-	nted: Read as ' MA Module Disa					
DIL 4		odule is disabled					
		odule is enabled	-				
bit 3	PTGMD: PT	G Module Disal	ole bit				
		dule is disabled					
		dule is enabled					
bit 2	-	nted: Read as					
bit 1	-	GA1 Module Di					
		odule is disable odule is enable					

U-0	U-0	U-0	U-0	U-0	R/W-0	U-0	U-0				
_	_				PGA2MD	_	_				
oit 15		1					bit				
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0				
_	_	CLC4MD	CLC3MD	CLC2MD	CLC1MD	CCSMD	_				
bit 7	I	1	L	I	L	1	bit				
Legend:											
R = Readab	ole bit	W = Writable	bit	U = Unimplem	nented bit, read	l as '0'					
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkno	wn				
bit 15-11 bit 10	PGA2MD: PG	Unimplemented: Read as '0' PGA2MD: PGA2 Module Disable bit 1 = PGA2 module is disabled									
		dule is enabled	-								
bit 9-6	Unimplemen	ted: Read as ')'								
bit 5	1 = CLC4 mo	C4 Module Dis dule is disabled dule is enabled	ł								
bit 4	1 = CLC3 mo	C3 Module Dis dule is disabled dule is enabled	1								
bit 3	1 = CLC2 mo	C2 Module Dis dule is disabled dule is enabled	1								
bit 2	1 = CLC1 mo	C1 Module Dis dule is disabled dule is enabled	ł								
bit 1	1 = Constant-	CCSMD: Constant-Current Source Module Disable bit 1 = Constant-current source module is disabled 0 = Constant-current source module is enabled									
	0 Obnotant	ourient oouroo	inouallo io ona								

REGISTER 10-7: PMD8: PERIPHERAL MODULE DISABLE CONTROL REGISTER 8

I/O PORTS 11.0

- **Note 1:** This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "I/O Ports" (DS70000598) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

Many of the device pins are shared among the peripherals and the Parallel I/O ports. All I/O input ports feature Schmitt Trigger inputs for improved noise immunity.

Parallel I/O (PIO) Ports 11.1

Generally, a Parallel I/O port that shares a pin with a peripheral is subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port has ownership of the output data and control signals of the I/O pin. The logic also prevents "loop through", in

which a port's digital output can drive the input of a peripheral that shares the same pin. Figure 11-1 illustrates how ports are shared with other peripherals and the associated I/O pin to which they are connected.

When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin can be read, but the output driver for the parallel port bit is disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin can be driven by a port.

All port pins have eight registers directly associated with their operation as digital I/Os. The Data Direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a '1', then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the latch (LATx), read the latch. Writes to the latch, write the latch. Reads from the port (PORTx), read the port pins, while writes to the port pins, write the latch.

Any bit and its associated data and control registers that are not valid for a particular device are disabled. This means the corresponding LATx and TRISx registers, and the port pin are read as zeros. Table 11-1 through Table 11-5 show ANSELx bits' availability for device variants.

When a pin is shared with another peripheral or function that is defined as an input only, it is nevertheless regarded as a dedicated port because there is no other competing source of outputs.

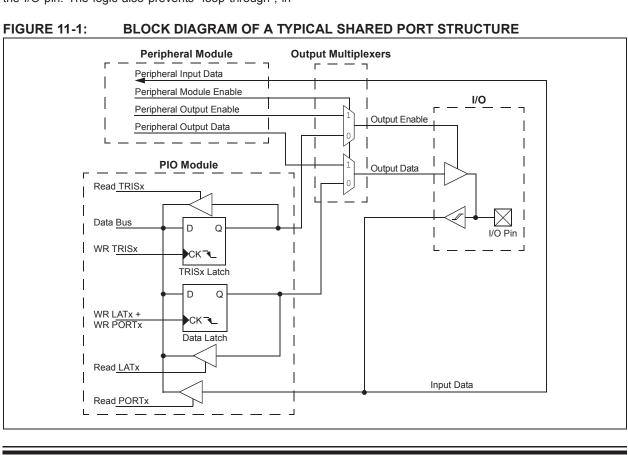


TABLE 11-1: PORTA PIN AND ANSELA AVAILABILITY

Device	PORTA I/O Pins															
Device	RA15	RA14	RA13	RA12	RA11	RA10	RA9	RA8	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0
dsPIC33EPXXXGSX08	_	—	—	—	—	—	—	—	—	—	_	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX06	_	_	_	_	_	—	_	_	_	_	_	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX05	_	—	—	—	—	—	—	—	—	_	—	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX04	_	—	—	—	_	_	—	—	—	_	—	Х	Х	Х	Х	Х
dsPIC33EPXXXGS702	_	_	_	_	_	_	_	_	_	_	_	Х	Х	Х	Х	Х
ANSELA Bit Present		_	_	_	_	_	_	_	_	_	_	_	_	Х	Х	Х

TABLE 11-2: PORTB PIN AND ANSELB AVAILABILITY

Davias							PORT	B I/O	Pins							
Device	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0
dsPIC33EPXXXGSX08	Х	Х	Х	Х	Х	—	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX06	Х	Х	Х	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX05	Х	Х	Х	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX04	Х	Х	Х	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGS702	Х	Х	Х	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
ANSELB Bit Present	_		—	—	_	—	Х	_	Х	Х	Х	_	Х	Х	Х	Х

TABLE 11-3: PORTC PIN AND ANSELC AVAILABILITY

Device							PORT	C I/O	Pins							
Device	RC15	RC14	RC13	RC12	RC11	RC10	RC9	RC8	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0
dsPIC33EPXXXGSX08	Х	Х	Х	Х	—	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX06	Х	Х	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX05	—	_	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX04	—	_	Х	Х	_	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGS702	—	_	—	—	_	—	_	—	—	—	—	—	—	—	—	—
ANSELC Bit Present	—	_		Х	_	Х	Х		_	Х	Х	Х		Х	Х	—

TABLE 11-4: PORTD PIN AND ANSELD AVAILABILITY

Device							PORT	D I/O	Pins							
Device	RD15	RD14	RD13	RD12	RD11	RD10	RD9	RD8	RD7	RD6	RD5	RD4	RD3	RD2	RD1	RD0
dsPIC33EPXXXGSX08	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX06	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX05	—	Х	_		_	Х	_	_	_	—	—	Х	_	—	_	—
dsPIC33EPXXXGSX04	—	Х			_	Х	_	_	_	—	—	Х	_	—	—	—
dsPIC33EPXXXGS702	—	_	_	—	_	_	_	—	_	—	—	—	_	—	—	—
ANSELD Bit Present	—		Х			—	—	Х	Х	—	Х		—	Х	—	—

TABLE 11-5: PORTE PIN AND ANSELE AVAILABILITY

Device							PORT	E I/O	Pins							
Device	RE15	RE14	RE13	RE12	RE11	RE10	RE9	RE8	RE7	RE6	RE5	RE4	RE3	RE2	RE1	RE0
dsPIC33EPXXXGSX08	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
dsPIC33EPXXXGSX06	—	—	—	—	—	—	—	_	—	—	—	—	—	—	—	—
dsPIC33EPXXXGSX05	_	_	_	—	_	_	_	_	_	_	_	_	_	_	_	_
dsPIC33EPXXXGSX04	_	—	—	_	—	_	—	_	—	_	—	—	_	—	—	—
dsPIC33EPXXXGS702	_	_	_	_	—	_	_	_	—	_	_	_	_	_	_	_
ANSELE Bit Present	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_

11.2 I/O Port Control Register Maps

TABLE 11-6: PORTA REGISTER MAP⁽¹⁾

File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TRISA	—	_	_	—	—	_	_	_	—	_	—		Г	RISA<4:0>		
PORTA	—	—	—	—	—	_	—	—	_	_	_			RA<4:0>		
LATA	—	—	—	—	—	_	—	—	_	—	_			LATA<4:0>		
ODCA	—	—	_	_	_	_	_	_	_	_	_		(DCA<4:0>		
CNENA	—	—	_	—	_		_	—		_	_		C	NIEA<4:0>		
CNPUA	—	—	—	—	—	_	—	—	_	—	_		С	NPUA<4:0	>	
CNPDA	—	—	—	—	—	_	—	_	_	—	_		С	NPDA<4:0	>	
ANSELA	—	—	_	_	_	—	_	_	_	_	_	_	_		ANSA<2:0>	

Legend: — = unimplemented, read as '0'.

Note 1: Refer to Table 11-1 for bit availability on each pin count variant.

TABLE 11-7: PORTB REGISTER MAP⁽¹⁾

File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TRISB		Т	RISB<15:1	>		—				1	TRISB	<9:0>				
PORTB			RB<15:11>			—	RB<9:0>									
LATB		L	ATB<15:11	>							LATB<	<9:0>				
ODCB		0	DCB<15:11	>							ODCB	<9:0>				
CNENB		С	NIEB<15:1	1>		_					CNIEB	<9:0>				
CNPUB		CI	NPUB<15:1	1>							CNPUE	3<9:0>				
CNPDB		CI	NPDB<15:1	1>			CNPDB<9:0>									
ANSELB	_	_	_	_	_	_	ANSB9	_	A	ANSB<7:5>		_		ANSB	<3:0>	

Legend: — = unimplemented, read as '0'.

Note 1: Refer to Table 11-2 for bit availability on each pin count variant.

TABLE 11-8: PORTC REGISTER MAP⁽¹⁾

File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TRISC		TRISC	C<15:12>		—					TF	RISC<10:0	>				
PORTC		RC<	:15:12>		—	RC<10:0>										
LATC		LATC	<15:12>		—	LATC<10:0>										
ODCC		ODCC	2<15:12>		—	ODCC<10:0>										
CNENC		CNIEC	C<15:12>		—					CI	VIEC<10:0	>				
CNPUC		CNPU	C<15:12>		—					CN	IPUC<10:0)>				
CNPDC		CNPD	C<15:12>		—					CN	IPDC<10:0)>				
ANSELC	_	_	_	ANSC12	_	ANSC<	:10:9>	_	_	ŀ	ANSC<6:4	>	—	ANSC	<2:1>	_
Logondi	- unimo	lomontod	road on 'o'													

Legend: — = unimplemented, read as '0'.

Note 1: Refer to Table 11-3 for bit availability on each pin count variant.

TABLE 11-9: PORTD REGISTER MAP⁽¹⁾

	-	-														
File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TRISD								TRISD	<15:0>							
PORTD								RD<	15:0>							
LATD								LATD	<15:0>							
ODCD								ODCD	<15:0>							
CNEND								CNIED)<15:0>							
CNPUD								CNPUE	D<15:0>							
CNPDD								CNPD	D<15:0>							
ANSELD	—	_	ANSD13	_	_	_		ANSD)<8:7>	_	ANSD5			ANSD2	_	

Legend: — = unimplemented, read as '0'.

Note 1: Refer to Table 11-4 for bit availability on each pin count variant.

TABLE 11-10: PORTE REGISTER MAP⁽¹⁾

TADLE	II-IV. P		LOISILI													
File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TRISE								TRISE<	:15:0>							
PORTE								RE<1	5:0>							
LATE								LATE<	15:0>							
ODCE								ODCE<	:15:0>							
CNENE								CNIEE<	<15:0>							
CNPUE								CNPUE	<15:0>							
CNPDE								CNPDE	<15:0>							
ANSELE	—	—	—	—	—	—	—	—	—	—	—	—	_	_	—	—

Legend: — = unimplemented, read as '0'.

Note 1: Refer to Table 11-5 for bit availability on each pin count variant.

11.2.1 OPEN-DRAIN CONFIGURATION

In addition to the PORTx, LATx and TRISx registers for data control, port pins can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control x register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs other than VDD by using external pull-up resistors. The maximum open-drain voltage allowed on any pin is the same as the maximum VIH specification for that particular pin. See the **"Pin Diagrams"** section for the available 5V tolerant pins and Table 30-11 for the maximum VIH specification for each pin.

11.3 Configuring Analog and Digital Port Pins

The ANSELx register controls the operation of the analog port pins. The port pins that are to function as analog inputs or outputs must have their corresponding ANSELx and TRISx bits set. In order to use port pins for I/O functionality with digital modules, such as timers, UARTs, etc., the corresponding ANSELx bit must be cleared.

The ANSELx register has a default value of 0xFFFF; therefore, all pins that share analog functions are analog (not digital) by default.

Pins with analog functions affected by the ANSELx registers are listed with a buffer type of analog in the Pinout I/O Descriptions (see Table 1-1). Table 11-1 through Table 11-5 show ANSELx bits' availability for device variants.

If the TRISx bit is cleared (output) while the ANSELx bit is set, the digital output level (VOH or VOL) is converted by an analog peripheral, such as the ADC module or comparator module.

When the PORTx register is read, all pins configured as analog input channels are read as cleared (a low level).

Pins configured as digital inputs do not convert an analog input. Analog levels on any pin, defined as a digital input (including the ANx pins), can cause the input buffer to consume current that exceeds the device specifications.

11.3.1 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be a NOP, as shown in Example 11-1.

11.4 Input Change Notification (ICN)

The Input Change Notification function of the I/O ports allows devices to generate interrupt requests to the processor in response to a Change-of-State (COS) on selected input pins. This feature can detect input Change-of-States, even in Sleep mode, when the clocks are disabled. Every I/O port pin can be selected (enabled) for generating an interrupt request on a Change-of-State.

Three control registers are associated with the ICN functionality of each I/O port. The CNENx registers contain the ICN interrupt enable control bits for each of the input pins. Setting any of these bits enables an ICN interrupt for the corresponding pins.

Each I/O pin also has a weak pull-up and a weak pull-down connected to it. The pull-ups and pulldowns act as a current source, or sink source, connected to the pin, and eliminate the need for external resistors when push button or keypad devices are connected. The pull-ups and pull-downs are enabled separately, using the CNPUx and the CNPDx registers, which contain the control bits for each of the pins. Setting any of the control bits enables the weak pull-ups and/or pull-downs for the corresponding pins.

Note: Pull-ups and pull-downs on Input Change Notification pins should always be disabled when the port pin is configured as a digital output.

EXAMPLE 11-1: PORT WRITE/READ EXAMPLE

MOV	0xFF00, WO	; Configure PORTB<15:8>
	,	; as inputs
MOV	WO, TRISB	; and PORTB<7:0>
		; as outputs
NOP		; Delay 1 cycle
BTSS	PORTB, #13	; Next Instruction

11.5 I/O Port Control Registers

REGISTER 11-1: TRISX: PORTX DATA DIRECTION CONTROL REGISTER⁽¹⁾

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			TRISx	<15:8>			
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			TRIS	<7:0>			
bit 7							bit C

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 TRISx<15:0>: PORTx Data Direction Control bits

- 1 = The pin is an input
- 0 = The pin is an output

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

REGISTER 11-2: PORTx: I/O PORTx REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PORTX	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PORT	x<7:0>			
bit 7							bit 0
Legend:							

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	1 as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8 **PORTx<15:0>:** I/O PORTx bits

1 = The pin data is '1'

0 = The pin data is '0'

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

REGISTER 11-3: LATX: PORTX DATA LATCH REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			LAT	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			LAT	x<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable b	bit	U = Unimpler	nented bit, rea	d as '0'	
-n = Value at POR '1' = Bit is set '0' = Bit is cleared		x = Bit is unki	nown				

bit 15-8 LATx<15:0>: PORTx Data Latch bits

1 = The latch content is '1'

0 = The latch content is '0'

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

REGISTER 11-4: ODCx: PORTx OPEN-DRAIN CONTROL REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			ODC	x<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			ODC	x<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown			nown	

bit 15-8 **PORTx<15:0>:** PORTx Open-Drain Control bits

1 = The pin acts as an open-drain output pin if TRISx is '0'

0 = The pin acts as a normal pin

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

REGISTER 11-5: CNENx: INPUT CHANGE NOTIFICATION INTERRUPT ENABLE x REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			CNIE	x<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			CNIE	Ex<7:0>			
bit 7							bit 0
Legend:							
R = Readable I	bit	W = Writable bit	t	U = Unimpler	nented bit, read	l as '0'	

bit 15-8 CNIEx<15:0>: Input Change Notification Interrupt Enable x bits

1 = Enables interrupt on input change

'1' = Bit is set

-n = Value at POR

0 = Disables interrupt on input change

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

'0' = Bit is cleared

x = Bit is unknown

REGISTER 11-6: CNPUX: INPUT CHANGE NOTIFICATION PULL-UP ENABLE x REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			CNPUx	<15:8>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CNPUx<7:0>							
bit 7						bit 0	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 CNPUx<15:0>: Input Change Notification Pull-up Enable bits

1 = Enables pull-up on PORTx pin

0 = Disables pull-up on PORTx pin

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

REGISTER 11-7: CNPDx: INPUT CHANGE NOTIFICATION PULL-DOWN ENABLE x REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			CNPD>	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			CNPD	x<7:0>			
bit 7							bit 0
Legend:							

· J · ·			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **CNPDx<15:0>:** Input Change Notification Pull-Down Enable x bits

1 = Enables pull-down on PORTx pin

0 = Disables pull-down on PORTx pin

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

REGISTER 11-8: ANSELX: ANALOG SELECT CONTROL X REGISTER⁽¹⁾

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			ANS	<15:8>			
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			ANS	x<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable bi	t	U = Unimpler	mented bit, read	1 as '0'	

bit 15-8 **ANSx<15:0>:** Analog PORTx Enable bits

1 = Enables analog PORTx pin

'1' = Bit is set

0 = Enables digital PORTx pin

Note 1: See Table 11-1, Table 11-2, Table 11-3, Table 11-4 and Table 11-5 for individual bit availability in this register.

'0' = Bit is cleared

-n = Value at POR

x = Bit is unknown

11.6 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features, while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin count devices. In an application where more than one peripheral needs to be assigned to a single pin, inconvenient work arounds in application code, or a complete redesign, may be the only option.

Peripheral Pin Select configuration provides an alternative to these choices by enabling peripheral set selection and placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the device to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select configuration feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of most digital peripherals to any one of these I/O pins. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

11.6.1 AVAILABLE PINS

The number of available pins is dependent on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the label, "RPn", in their full pin designation, where "n" is the remappable pin number. "RP" is used to designate pins that support both remappable input and output functions.

11.6.2 AVAILABLE PERIPHERALS

The peripherals managed by the Peripheral Pin Select are all digital only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer-related peripherals (input capture and output compare) and interrupt-on-change inputs. In comparison, some digital only peripheral modules are never included in the Peripheral Pin Select feature. This is because the peripheral's function requires special I/O circuitry on a specific port and cannot be easily connected to multiple pins. One example includes I^2C modules. A similar requirement excludes all modules with analog inputs, such as the ADC Converter.

A key difference between remappable and nonremappable peripherals is that remappable peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-remappable peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

When a remappable peripheral is active on a given I/O pin, it takes priority over all other digital I/Os and digital communication peripherals associated with the pin. Priority is given regardless of the type of peripheral that is mapped. Remappable peripherals never take priority over any analog functions associated with the pin.

11.6.3 CONTROLLING PERIPHERAL PIN SELECT

Peripheral Pin Select features are controlled through two sets of SFRs: one to map peripheral inputs and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

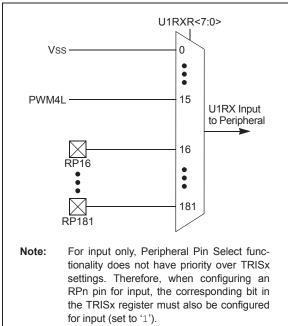
The association of a peripheral to a peripheralselectable pin is handled in two different ways, depending on whether an input or output is being mapped.

11.6.4 INPUT MAPPING

The inputs of the Peripheral Pin Select options are mapped on the basis of the peripheral. That is, a control register associated with a peripheral dictates the pin it will be mapped to. The RPINRx registers are used to configure peripheral input mapping (see Register 11-9 through Register 11-32). Each register contains sets of 8-bit fields, with each set associated with one of the remappable peripherals. Programming a given peripheral's bit field with an appropriate 8-bit index value maps the RPn pin with the corresponding value, or internal signal, to that peripheral. See Table 11-11 for a list of available inputs.

For example, Figure 11-2 illustrates remappable pin selection for the U1RX input.





11.6.4.1 Virtual Connections

The dsPIC33EPXXXGS70X/80X devices support six virtual RPn pins (RP176-RP181), which are identical in functionality to all other RPn pins, with the exception of pinouts. These six pins are internal to the devices and are not connected to a physical device pin.

These pins provide a simple way for inter-peripheral connection without utilizing a physical pin. For example, the output of the analog comparator can be connected to RP176 and the PWM Fault input can be configured for RP176 as well. This configuration allows the analog comparator to trigger PWM Faults without the use of an actual physical pin on the device.

Remap Index	Output Function
0	Vss
1	CMP1
2	CMP2
3	CMP3
4	CMP4
5	PWM4H
6	PTGO30
7	PTGO31
8-11	Reserved
12	REFO
13	SYNCO1
14	SYNCO2
15	PWM4L
16-20	RP16-RP20
21-31	Reserved
32-41	RP32-RP41
42	Reserved
43-58	RP43-RP58
59	Reserved
60-76	RP60-RP76
77-175	Reserved
176-181	RP176-RP181

TABLE 11-11: REMAPPABLE SOURCES

Input Name ⁽¹⁾	Function Name	Register	Configuration Bits	
External Interrupt 1	INT1	RPINR0	INT1R<7:0>	
External Interrupt 2	INT2	RPINR1	INT2R<7:0>	
Timer1 External Clock	T1CK	RPINR2	T1CKR<7:0>	
Timer2 External Clock	T2CK	RPINR3	T2CKR<7:0>	
Timer3 External Clock	T3CK	RPINR3	T3CKR<7:0>	
Input Capture 1	IC1	RPINR7	IC1R<7:0>	
Input Capture 2	IC2	RPINR7	IC2R<7:0>	
Input Capture 3	IC3	RPINR8	IC3R<7:0>	
Input Capture 4	IC4	RPINR8	IC4R<7:0>	
Output Compare Fault A	OCFA	RPINR11	OCFAR<7:0>	
PWM Fault 1	FLT1	RPINR12	FLT1R<7:0>	
PWM Fault 2	FLT2	RPINR12	FLT2R<7:0>	
PWM Fault 3	FLT3	RPINR13	FLT3R<7:0>	
PWM Fault 4	FLT4	RPINR13	FLT4R<7:0>	
UART1 Receive	U1RX	RPINR18	U1RXR<7:0>	
UART1 Clear-to-Send	U1CTS	RPINR18	U1CTSR<7:0>	
UART2 Receive	U2RX	RPINR19	U2RXR<7:0>	
UART2 Clear-to-Send	U2CTS	RPINR19	U2CTSR<7:0>	
SPI1 Data Input	SDI1	RPINR20	SDI1R<7:0>	
SPI1 Clock Input	SCK1	RPINR20	SCK1R<7:0>	
SPI1 Slave Select	SS1	RPINR21	SS1R<7:0>	
CAN1 Receive	C1RX	PRINR26	C1RXR<7:0>	
CAN2 Receive	C2RX	PRINR26	C2RXR<7:0>	
SPI3 Data Input	SDI3	RPINR29	SDI3R<7:0>	
SPI3 Clock Input	SCK3	RPINR29	SCK3R<7:0>	
SPI3 Slave Select	SS3	RPINR30	SS3R<7:0>	
SPI2 Data Input	SDI2	RPINR22	SDI2R<7:0>	
SPI2 Clock Input	SCK2	RPINR22	SCK2R<7:0>	
SPI2 Slave Select	SS2	RPINR23	SS2R<7:0>	
PWM Synchronous Input 1	SYNCI1	RPINR37	SYNCI1R<7:0>	
PWM Synchronous Input 2	SYNCI2	RPINR38	SYNCI2R<7:0>	
PWM Fault 5	FLT5	RPINR42	FLT5R<7:0>	
PWM Fault 6	FLT6	RPINR42	FLT6R<7:0>	
PWM Fault 7	FLT7	RPINR43	FLT7R<7:0>	
PWM Fault 8	FLT8	RPINR43	FLT8R<7:0>	
CLC Input A	CLCINA	RPINR45	CLCINA<7:0>	
CLC Input B	CLCINB	RPINR46	CLCINB<7:0>	

TABLE 11-12: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)

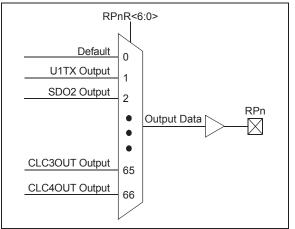
Note 1: Unless otherwise noted, all inputs use the Schmitt Trigger input buffers.

11.6.5 OUTPUT MAPPING

In contrast to inputs, the outputs of the Peripheral Pin Select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Each register contains sets of 6-bit fields, with each set associated with one RPn pin (see Register 11-33 through Register 11-56). The value of the bit field corresponds to one of the peripherals and that peripheral's output is mapped to the pin (see Table 11-13 and Figure 11-3).

A null output is associated with the output register Reset value of '0'. This is done to ensure that remappable outputs remain disconnected from all output pins by default.

FIGURE 11-3: MULTIPLEXING REMAPPABLE OUTPUTS FOR RPn



11.6.5.1 Mapping Limitations

The control schema of the peripheral select pins is not limited to a small range of fixed peripheral configurations. There are no mutual or hardware-enforced lockouts between any of the peripheral mapping SFRs. Literally any combination of peripheral mappings, across any or all of the RPn pins, is possible. This includes both many-to-one and one-to-many mappings of peripheral inputs, and outputs to pins. While such mappings may be technically possible from a configuration point of view, they may not be supportable from an electrical point of view.

Function	RPnR<6:0>	Output Name
Default PORT	0000000	RPn tied to Default Pin
U1TX	0000001	RPn tied to UART1 Transmit
U1RTS	0000010	RPn tied to UART1 Request-to-Send
U2TX	0000011	RPn tied to UART2 Transmit
U2RTS	0000100	RPn tied to UART2 Request-to-Send
SDO1	0000101	RPn tied to SPI1 Data Output
SCK1	0000110	RPn tied to SPI1 Clock Output
SS1	0000111	RPn tied to SPI1 Slave Select
SDO2	0001000	RPn tied to SPI2 Data Output
SCK2	0001001	RPn tied to SPI2 Clock Output
SS2	0001010	RPn tied to SPI2 Slave Select
C1TX	0001110	RPn tied to CAN1 Transmit
C2TX	0001111	RPn tied to CAN2 Transmit
OC1	0010000	RPn tied to Output Compare 1 Output
OC2	0010001	RPn tied to Output Compare 2 Output
OC3	0010010	RPn tied to Output Compare 3 Output
OC4	0010011	RPn tied to Output Compare 4 Output
ACMP1	0011000	RPn tied to Analog Comparator 1 Output
ACMP2	0011001	RPn tied to Analog Comparator 2 Output
ACMP3	0011010	RPn tied to Analog Comparator 3 Output
SDO3	0011111	RPn tied to SPI3 Data Output
SCK3	0100000	RPn tied to SPI3 Clock Output
SS3	0100001	RPn tied to SPI3 Slave Select
SYNCO1	0101101	RPn tied to PWM Primary Master Time Base Sync Output
SYNCO2	0101110	RPn tied to PWM Secondary Master Time Base Sync Output
REFCLKO	0110001	RPn tied to Reference Clock Output
ACMP4	0110010	RPn tied to Analog Comparator 4 Output
PWM4H	0110011	RPn tied to PWM Output Pins Associated with PWM Generator 4
PWM4L	0110100	RPn tied to PWM Output Pins Associated with PWM Generator 4
PWM5H	0110101	RPn tied to PWM Output Pins Associated with PWM Generator 5
PWM5L	0110110	RPn tied to PWM Output Pins Associated with PWM Generator 5
PWM6H	0111001	RPn tied to PWM Output Pins Associated with PWM Generator 6
PWM6L	0111010	RPn tied to PWM Output Pins Associated with PWM Generator 6
PWM7H	0111011	RPn tied to PWM Output Pins Associated with PWM Generator 7
PWM7L	0111100	RPn tied to PWM Output Pins Associated with PWM Generator 7
PWM8H	0111101	RPn tied to PWM Output Pins Associated with PWM Generator 8
PWM8L	0111110	RPn tied to PWM Output Pins Associated with PWM Generator 8
CLC1OUT	0111111	RPn tied to CLC1 Output
CLC2OUT	1000000	RPn tied to CLC2 Output
CLC3OUT ⁽¹⁾	1000001	RPn tied to CLC3 Output
CLC4OUT ⁽¹⁾	1000010	RPn tied to CLC4 Output

Note 1: PPS outputs are only available on dsPIC33EPXXXGS702 (28-pin) devices.

11.7 I/O Helpful Tips

- 1. In some cases, certain pins, as defined in Table 30-11 under "Injection Current", have internal protection diodes to VDD and Vss. The term, "Injection Current", is also referred to as "Clamp Current". On designated pins, with sufficient external current-limiting precautions by the user, I/O pin input voltages are allowed to be greater or less than the data sheet absolute maximum ratings, with respect to the Vss and VDD supplies. Note that when the user application forward biases either of the high or low-side internal input clamp diodes, that the resulting current being injected into the device, that is clamped internally by the VDD and Vss power rails, may affect the ADC accuracy by four to six counts.
- 2. I/O pins that are shared with any analog input pin (i.e., ANx) are always analog pins, by default, after any Reset. Consequently, configuring a pin as an analog input pin automatically disables the digital input pin buffer and any attempt to read the digital input level by reading PORTx or LATx will always return a '0', regardless of the digital logic level on the pin. To use a pin as a digital I/O pin on a shared ANx pin, the user application needs to configure the Analog Pin Configuration registers (i.e., ANSELx) in the I/O ports module by setting the appropriate bit that corresponds to that I/O port pin to a '0'.
- **Note:** Although it is not possible to use a digital input pin when its analog function is enabled, it is possible to use the digital I/O output function, $TRISx = 0 \times 0$, while the analog function is also enabled. However, this is not recommended, particularly if the analog input is connected to an external analog voltage source, which would create signal contention between the analog signal and the output pin driver.

- 3. Most I/O pins have multiple functions. Referring to the device pin diagrams in this data sheet, the priorities of the functions allocated to any pins are indicated by reading the pin name from left-to-right. The left most function name takes precedence over any function to its right in the naming convention. For example: AN16/T2CK/T7CK/RC1; this indicates that AN16 is the highest priority in this example and will supersede all other functions to its right in the list. Those other functions to its right, even if enabled, would not work as long as any other function to its left was enabled. This rule applies to all of the functions listed for a given pin.
- 4. Each pin has an internal weak pull-up resistor and pull-down resistor that can be configured using the CNPUx and CNPDx registers, respectively. These resistors eliminate the need for external resistors in certain applications. The internal pull-up is up to ~(VDD - 0.8), not VDD. This value is still above the minimum VIH of CMOS and TTL devices.
- 5. When driving LEDs directly, the I/O pin can source or sink more current than what is specified in the VOH/IOH and VOL/IOL DC characteristics specification. The respective IOH and IOL current rating only applies to maintaining the corresponding output at or above the VOH, and at or below the VOL levels. However, for LEDs, unlike digital inputs of an externally connected device, they are not governed by the same minimum VIH/VIL levels. An I/O pin output can safely sink or source any current less than that listed in the Absolute Maximum Ratings in Section 30.0 "Electrical Characteristics" of this data sheet. For example:

VOH = 2.4V @ IOH = -8 mA and VDD = 3.3V

The maximum output current sourced by any 8 mA I/O pin = 12 mA.

LED source current < 12 mA is technically permitted. Refer to the VOH/IOH graphs in Section 31.0 "DC and AC Device Characteristics Graphs" for additional information.

- 6. The Peripheral Pin Select (PPS) pin mapping rules are as follows:
 - a) Only one "output" function can be active on a given pin at any time, regardless if it is a dedicated or remappable function (one pin, one output).
 - b) It is possible to assign a "remappable output" function to multiple pins and externally short or tie them together for increased current drive.
 - c) If any "dedicated output" function is enabled on a pin, it will take precedence over any remappable "output" function.
 - d) If any "dedicated digital" (input or output) function is enabled on a pin, any number of "input" remappable functions can be mapped to the same pin.
 - e) If any "dedicated analog" function(s) are enabled on a given pin, "digital input(s)" of any kind will all be disabled, although a single "digital output", at the user's cautionary discretion, can be enabled and active as long as there is no signal contention with an external analog input signal. For example, it is possible for the ADC to convert the digital output logic level, or to toggle a digital output on a comparator or ADC input, provided there is no external analog input, such as for a built-in self-test.
 - f) Any number of "input" remappable functions can be mapped to the same pin(s) at the same time, including to any pin with a single output from either a dedicated or remappable "output".
 - g) The TRISx registers control only the digital I/O output buffer. Any other dedicated or remappable active "output" will automatically override the TRISx setting. The TRISx register does not control the digital logic "input" buffer. Remappable digital "inputs" do not automatically override TRISx settings, which means that the TRISx bit must be set to input for pins with only remappable input function(s) assigned.
 - h) All analog pins are enabled by default after any Reset and the corresponding digital input buffer on the pin has been disabled. Only the Analog Pin Select (ANSELx) registers control the digital input buffer, *not* the TRISx register. The user must disable the analog function on a pin using the Analog Pin Select registers in order to use any "digital input(s)" on a corresponding pin, no exceptions.

11.8 I/O Ports Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

11.8.1 KEY RESOURCES

- "I/O Ports" (DS70000598) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

11.9 Peripheral Pin Select Registers

REGISTER 11-9: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
INT1R7	INT1R6	INT1R5	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7	÷		•				bit 0
Logondy							

Legena:				
R = Readable bit	W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8 INT1R<7:0>: Assign External Interrupt 1 (INT1) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value. bit 7-0 Unimplemented: Read as '0'

REGISTER 11-10: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| INT2R7 | INT2R6 | INT2R5 | INT2R4 | INT2R3 | INT2R2 | INT2R1 | INT2R0 |
| bit 7 | • | • | | • | | | bit 0 |

Legend:			
R = Readable bit	ble bit W = Writable bit U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **INT2R<7:0>:** Assign External Interrupt 2 (INT2) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-11: F	RPINR2: PERIPHERAL PIN SELECT INPUT REGISTER 2
-------------------	--

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
T1CKR7	T1CKR6	T1CKR5	T1CKR4	T1CKR3	T1CKR2	T1CKR1	T1CKR0
bit 15						•	bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	_	—	—	—	—
bit 7						•	bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	nented bit, read	as '0'	

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 **T1CKR<7:0>:** Assign Timer1 External Clock (T1CK) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value. bit 7-0 **Unimplemented:** Read as '0'

REGISTER 11-12: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| T3CKR7 | T3CKR6 | T3CKR5 | T3CKR4 | T3CKR3 | T3CKR2 | T3CKR1 | T3CKR0 |
| bit 15 | | | | | | | bit 8 |
| | | | | | | | |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| T2CKR7 | T2CKR6 | T2CKR5 | T2CKR4 | T2CKR3 | T2CKR2 | T2CKR1 | T2CKR0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8T3CKR<7:0>: Assign Timer3 External Clock (T3CK) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0T2CKR<7:0>: Assign Timer2 External Clock (T2CK) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

-n = Value at POR		'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	iown	
R = Readable	bit	W = Writable	bit	U = Unimplen	nented bit, rea	read as '0'		
Legend:								
bit 7							bit (
IC1R7	IC1R6	IC1R5	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
bit 15							bit	
IC2R7	IC2R6	IC2R5	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	

bit 15-8IC2R<7:0>: Assign Input Capture 2 (IC2) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0IC1R<7:0>: Assign Input Capture 1 (IC1) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-14: RPINR8: PERIPHERAL PIN SELECT INPUT REGISTER 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IC4R7	IC4R6	IC4R5	IC4R4	IC4R3	IC4R2	IC4R1	IC4R0
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| IC3R7 | IC3R6 | IC3R5 | IC3R4 | IC3R3 | IC3R2 | IC3R1 | IC3R0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8IC4R<7:0>: Assign Input Capture 4 (IC4) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0IC3R<7:0>: Assign Input Capture 3 (IC3) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-15: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| OCFAR7 | OCFAR6 | OCFAR5 | OCFAR4 | OCFAR3 | OCFAR2 | OCFAR1 | OCFAR0 |
| bit 7 | • | | | | | | bit 0 |

Legend:			
R = Readable bit	1 as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **OCFAR<7:0>:** Assign Output Compare Fault A (OCFA) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-16: RPINR12: PERIPHERAL PIN SELECT INPUT REGISTER 12

FLT2R7 FLT2R6 FLT2R5	FLT2R4	FLT2R3	FLT2R2	FLT2R1	FLT2R0
		1 1 213	FLIZKZ	FLIZKI	FLIZRU
bit 15					bit 8

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| FLT1R7 | FLT1R6 | FLT1R5 | FLT1R4 | FLT1R3 | FLT1R2 | FLT1R1 | FLT1R0 |
| bit 7 | | | | | | | bit 0 |

Legend:				
R = Readable bit	W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8**FLT2R<7:0>:** Assign PWM Fault 2 (FLT2) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0**FLT1R<7:0>:** Assign PWM Fault 1 (FLT1) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-17: RPINR13: PERIPHERAL PIN SELECT INPUT REGISTER 13

R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 FLT4R7 FLT4R6 FLT4R5 FLT4R4 FLT4R3 FLT4R2 FLT4R1 bit 15								
bit 15 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 FLT3R7 FLT3R6 FLT3R5 FLT3R4 FLT3R3 FLT3R2 FLT3R1 bit 7	R/W-0							
R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 FLT3R7 FLT3R6 FLT3R5 FLT3R4 FLT3R3 FLT3R2 FLT3R1 bit 7	FLT4R0	FLT4R1	FLT4R2	FLT4R3	FLT4R4	FLT4R5	FLT4R6	FLT4R7
FLT3R7 FLT3R6 FLT3R5 FLT3R4 FLT3R3 FLT3R2 FLT3R1 bit 7	bit 8						•	bit 15
FLT3R7 FLT3R6 FLT3R5 FLT3R4 FLT3R3 FLT3R2 FLT3R1 bit 7								
bit 7	R/W-0							
	FLT3R0	FLT3R1	FLT3R2	FLT3R3	FLT3R4	FLT3R5	FLT3R6	FLT3R7
l egend:	bit 0						•	bit 7
Legend:								
								Legend:

Logona.				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8	FLT4R<7:0>: Assign PWM Fault 4 (FLT4) to the Corresponding RPn Pin bits
	See Table 11-11 which contains a list of remappable inputs for the index value.
bit 7-0	FLT3R<7:0>: Assign PWM Fault 3 (FLT3) to the Corresponding RPn Pin bits
	See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-18: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| U1CTSR7 | U1CTSR6 | U1CTSR5 | U1CTSR4 | U1CTSR3 | U1CTSR2 | U1CTSR1 | U1CTSR0 |
| bit 15 | | | | | | | bit 8 |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| U1RXR7 | U1RXR6 | U1RXR5 | U1RXR4 | U1RXR3 | U1RXR2 | U1RXR1 | U1RXR0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8U1CTSR<7:0>: Assign UART1 Clear-to-Send (U1CTS) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0U1RXR<7:0>: Assign UART1 Receive (U1RX) to the Corresponding RPn Pin bits

See Table 11-11 which contains a list of remappable inputs for the index value.

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| U2CTSR7 | U2CTSR6 | U2CTSR5 | U2CTSR4 | U2CTSR3 | U2CTSR2 | U2CTSR1 | U2CTSR0 |
| bit 15 | | | | | | | bit 8 |

REGISTER 11-19: RPINR19: PERIPHERAL PIN SELECT INPUT REGISTER 19

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| U2RXR7 | U2RXR6 | U2RXR5 | U2RXR4 | U2RXR3 | U2RXR2 | U2RXR1 | U2RXR0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **U2CTSR<7:0>:** Assign UART2 Clear-to-Send (U2CTS) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

bit 7-0 **U2RXR<7:0>:** Assign UART2 Receive (U2RX) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-20: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| SCK1INR7 | SCK1INR6 | SCK1INR5 | SCK1INR4 | SCK1INR3 | SCK1INR2 | SCK1INR1 | SCK1INR0 |
| bit 15 | | | | | | | bit 8 |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| SDI1R7 | SDI1R6 | SDI1R5 | SDI1R4 | SDI1R3 | SDI1R2 | SDI1R1 | SDI1R0 |
| bit 7 | • | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8SCK1INR<7:0>: Assign SPI1 Clock Input (SCK1) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0SDI1R<7:0>: Assign SPI1 Data Input (SDI1) to the Corresponding RPn Pin bits

See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-21: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	_	—	—	_
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SS1R7	SS1R6	SS1R5	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0
bit 7	•	•			•	•	bit 0
<u>.</u>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **SS1R<7:0>:** Assign SPI1 Slave Select (SS1) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-22: RPINR22: PERIPHERAL PIN SELECT INPUT REGISTER 22

-n = Value at POR '1' = E		'1' = Bit is set	1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	
R = Readable	bit	W = Writable	bit	U = Unimpler	nented bit, read	as '0'		
Legend:								
bit 7							bit C	
SDI2R7	SDI2R6	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
bit 15		1	1	1		1	bit 8	
SCK2INR7	SCK2INR6	SCK2INR5	SCK2INR4	SCK2INR3	SCK2INR2	SCK2INR1	SCK2INR0	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	

bit 15-8SCK2INR<7:0>: Assign SPI2 Clock Input (SCK2) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0SDI2R<7:0>: Assign SPI2 Data Input (SDI2) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-23: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| SS2R7 | SS2R6 | SS2R5 | SS2R4 | SS2R3 | SS2R2 | SS2R1 | SS2R0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **SS2R<7:0>:** Assign SPI2 Slave Select (SS2) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-24: RPINR26: PERIPHERAL PIN SELECT INPUT REGISTER 26

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| C2RXR7 | C2RXR6 | C2RXR5 | C2RXR4 | C2RXR3 | C2RXR2 | C2RXR1 | C2RXR0 |
| bit 15 | | | | • | | | bit 8 |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| C1RXR7 | C1RXR6 | C1RXR5 | C1RXR4 | C1RXR3 | C1RXR2 | C1RXR1 | C1RXR0 |
| bit 7 | | | | | | | bit 0 |

Legend:				
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8 **C2RXR<7:0>:** Assign CAN2 Receive (C2RX) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

bit 7-0 **C1RXR<7:0>:** Assign CAN1 Receive (C1RX) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-25: RPINR29: PERIPHERAL PIN SELECT INPUT REGISTER 29

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| SCK3R7 | SCK3R6 | SCK3R5 | SCK3R4 | SCK3R3 | SCK3R2 | SCK3R1 | SCK3R0 |
| bit 15 | | | | | | | bit 8 |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| SDI3R7 | SDI3R6 | SDI3R5 | SDI3R4 | SDI3R3 | SDI3R2 | SDI3R1 | SDI3R0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

 bit 15-8
 SCK3R<7:0>: Assign SPI3 Clock Input (SCK3) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

 bit 7-0
 SDI3R<7:0>: Assign SPI3 Data Input (SDI3) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-26: RPINR30: PERIPHERAL PIN SELECT INPUT REGISTER 30

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| SS3R7 | SS3R6 | SS3R5 | SS3R4 | SS3R3 | SS3R2 | SS3R1 | SS3R0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **SS3R<7:0>:** Assign SPI3 Slave Select (SS3) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-27: RPINR37: PERIPHERAL PIN SELECT INPUT REGISTER 37

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| SYNCI1R7 | SYNCI1R6 | SYNCI1R5 | SYNCI1R4 | SYNCI1R3 | SYNCI1R2 | SYNCI1R1 | SYNCI1R0 |
| bit 15 | | | | | | | bit 8 |

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 SYNCI1R<7:0>: Assign PWM Synchronization Input 1 (SYNCI1) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

bit 7-0 Unimplemented: Read as '0'

REGISTER 11-28: RPINR38: PERIPHERAL PIN SELECT INPUT REGISTER 38

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| SYNCI2R7 | SYNCI2R6 | SYNCI2R5 | SYNCI2R4 | SYNCI2R3 | SYNCI2R2 | SYNCI2R1 | SYNCI2R0 |
| bit 7 | • | | | | | | bit 0 |

Legend:				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **SYNCI2R<7:0>:** Assign PWM Synchronization Input 2 (SYNCI2) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-29: RPINR42: PERIPHERAL PIN SELECT INPUT REGISTER 42

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT6R7	FLT6R6	FLT6R5	FLT6R4	FLT6R3	FLT6R2	FLT6R1	FLT6R0
bit 15	·						bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT5R7	FLT5R6	FLT5R5	FLT5R4	FLT5R3	FLT5R2	FLT5R1	FLT5R0
bit 7	·	•		•		•	bit 0
Legend:							

Legenu.				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8	FLT6R<7:0>: Assign PWM Fault 6 (FLT6) to the Corresponding RPn Pin bits
	See Table 11-11 which contains a list of remappable inputs for the index value.
bit 7-0	FLT5R<7:0>: Assign PWM Fault 5 (FLT5) to the Corresponding RPn Pin bits
	See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-30: RPINR43: PERIPHERAL PIN SELECT INPUT REGISTER 43

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| FLT8R7 | FLT8R6 | FLT8R5 | FLT8R4 | FLT8R3 | FLT8R2 | FLT8R1 | FLT8R0 |
| bit 15 | | | | | | | bit 8 |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| FLT7R7 | FLT7R6 | FLT7R5 | FLT7R4 | FLT7R3 | FLT7R2 | FLT7R1 | FLT7R0 |
| bit 7 | • | | | | | | bit 0 |

Legend:				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8FLT8R<7:0>: Assign PWM Fault 8 (FLT8) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0FLT7R<7:0>: Assign PWM Fault 7 (FLT7) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-31: RPINR45: PERIPHERAL PIN SELECT INPUT REGISTER 45

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| CLCINAR7 | CLCINAR6 | CLCINAR5 | CLCINAR4 | CLCINAR3 | CLCINAR2 | CLCINAR1 | CLCINAR0 |
| bit 15 | • | | | | | | bit 8 |
| | | | | | | | |
| U-0 |
| — | — | — | — | _ | — | — | — |
| bit 7 | | | | | | | bit 0 |

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit,	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-8CLCINAR<7:0>: Assign CLC Input A (CLCINA) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.bit 7-0Unimplemented: Read as '0'

REGISTER 11-32: RPINR46: PERIPHERAL PIN SELECT INPUT REGISTER 46

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| CLCINBR7 | CLCINBR6 | CLCINBR5 | CLCINBR4 | CLCINBR3 | CLCINBR2 | CLCINBR1 | CLCINBR0 |
| bit 7 | | | | | | | bit 0 |

Legend:				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **CLCINBR<7:0>:** Assign CLC Input B (CLCINB) to the Corresponding RPn Pin bits See Table 11-11 which contains a list of remappable inputs for the index value.

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RP17R6	RP17R5	RP17R4	RP17R3	RP17R2	RP17R1	RP17R0
bit 15	·		·			•	bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP16R6	RP16R5	RP16R4	RP16R3	RP16R2	RP16R1	RP16R0
bit 7							bit 0
Legend:							
R = Readable bit		W = Writable	bit	U = Unimpler	mented bit, read	l as '0'	
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	
bit 15	Unimplemen	ted: Read as '	0'				
bit 14-8		RP17R<6:0>: Peripheral Output Function is Assigned to RP17 Output Pin bits (see Table 11-13 for peripheral function numbers)					
bit 7	Unimplemented: Read as '0'						

Dit 7	
bit 6-0	RP16R<6:0>: Peripheral Output Function is Assigned to RP16 Output Pin bits
	(see Table 11-13 for peripheral function numbers)

REGISTER 11-34: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP19R6	RP19R5	RP19R4	RP19R3	RP19R2	RP19R1	RP19R0
bit 15					•	·	bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP18R6	RP18R5	RP18R4	RP18R3	RP18R2	RP18R1	RP18R0
bit 7							bit 0
Legend:							
R = Readable bit		W = Writable bit		U = Unimplemented bit, read as '0'		as '0'	
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	
bit 15	Unimplemented: Read as '0'						
bit 14.8 PD10P<6:0>: Peripheral Output Function			is Assigned to		in hite		

bit 14-8**RP19R<6:0>:** Peripheral Output Function is Assigned to RP19 Output Pin bits
(see Table 11-13 for peripheral function numbers)bit 7**Unimplemented:** Read as '0'

bit 6-0 **RP18R<6:0>:** Peripheral Output Function is Assigned to RP18 Output Pin bits

(see Table 11-13 for peripheral function numbers)

U-0	R/W-0						
—	RP32R6	RP32R5	RP32R4	RP32R3	RP32R2	RP32R1	RP32R0
bit 15							bit 8
U-0	R/W-0						
—	RP20R6	RP20R5	RP20R4	RP20R3	RP20R2	RP20R1	RP20R0
bit 7							bit 0

REGISTER 11-35: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-8	RP32R<6:0>: Peripheral Output Function is Assigned to RP32 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP20R<6:0>: Peripheral Output Function is Assigned to RP20 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-36: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP34R6	RP34R5	RP34R4	RP34R3	RP34R2	RP34R1	RP34R0
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP33R6	RP33R5	RP33R4	RP33R3	RP33R2	RP33R1	RP33R0
bit 7						bit 0	
Legend:							
R = Readable bit		W = Writable	bit	U = Unimpler	mented bit, read	as '0'	

R = Readable bit	VV = VVritable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 Unimplemented: Read as '0'

bit 14-8 **RP34R<6:0>:** Peripheral Output Function is Assigned to RP34 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP33R<6:0>:** Peripheral Output Function is Assigned to RP33 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP36R6	RP36R5	RP36R4	RP36R3	RP36R2	RP36R1	RP36R0
bit 15		·				·	bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP35R6	RP35R5	RP35R4	RP35R3	RP35R2	RP35R1	RP35R0
bit 7							bit 0
Legend:							
R = Readabl	e bit	W = Writable	bit	U = Unimpler	mented bit, read	as '0'	
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	
bit 15	Unimplemen	ted: Read as '	0'				
bit 14-8	RP36R<6:0>: Peripheral Output Function is Assigned to RP36 Output Pin bits (see Table 11-13 for peripheral function numbers)						
bit 7	Unimplemented: Read as '0'						

	•
bit 6-0	RP35R<6:0>: Peripheral Output Function is Assigned to RP35 Output Pin bits
	(see Table 11-13 for peripheral function numbers)

REGISTER 11-38: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP38R6	RP38R5	RP38R4	RP38R3	RP38R2	RP38R1	RP38R0
bit 15						•	bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP37R6	RP37R5	RP37R4	RP37R3	RP37R2	RP37R1	RP37R0
bit 7						•	bit 0
Legend:							
R = Readable b	oit	W = Writable	bit	U = Unimpler	nented bit, read	l as '0'	
-n = Value at POR '1' = Bit is s		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit 14-8 **RP38R<6:0>:** Peripheral Output Function is Assigned to RP38 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP37R<6:0>:** Peripheral Output Function is Assigned to RP37 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0						
—	RP40R6	RP40R5	RP40R4	RP40R3	RP40R2	RP40R1	RP40R0
bit 15							bit 8
U-0	R/W-0						
—	RP39R6	RP39R5	RP39R4	RP39R3	RP39R2	RP39R1	RP39R0
bit 7							bit 0

REGISTER 11-39: RPOR6: PERIPHERAL PIN SELECT OUTPUT REGISTER 6

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-8	RP40R<6:0>: Peripheral Output Function is Assigned to RP40 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP39R<6:0>: Peripheral Output Function is Assigned to RP39 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-40: RPOR7: PERIPHERAL PIN SELECT OUTPUT REGISTER 7

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP43R6	RP43R5	RP43R4	RP43R3	RP43R2	RP43R1	RP43R0
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP41R6	RP41R5	RP41R4	RP41R3	RP41R2	RP41R1	RP41R0
bit 7		•	·	•			bit 0
Legend:							
P - Poodoble	hit	M = M/ritabla	hit	II – Unimplor	montod hit road	26 '0'	

R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 Unimplemented: Read as '0'

bit 14-8 **RP43R<6:0>:** Peripheral Output Function is Assigned to RP43 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP41R<6:0>:** Peripheral Output Function is Assigned to RP41 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP45R6	RP45R5	RP45R4	RP45R3	RP45R2	RP45R1	RP45R0
bit 15	·			·		•	bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP44R6	RP44R5	RP44R4	RP44R3	RP44R2	RP44R1	RP44R0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit i		'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown

REGISTER 11-41: RPOR8: PERIPHERAL PIN SELECT OUTPUT REGISTER 8

bit 15	Unimplemented: Read as '0'
bit 14-8	RP45R<6:0>: Peripheral Output Function is Assigned to RP45 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP44R<6:0>: Peripheral Output Function is Assigned to RP44 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-42: RPOR9: PERIPHERAL PIN SELECT OUTPUT REGISTER 9

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP47R6	RP47R5	RP47R4	RP47R3	RP47R2	RP47R1	RP47R0
bit 15			•				bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP46R6	RP46R5	RP46R4	RP46R3	RP46R2	RP46R1	RP46R0
bit 7							bit (
Legend:							
R = Readable	e bit	W = Writable	bit	U = Unimpler	mented bit, read	l as '0'	
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared		x = Bit is unknown		
bit 15	Unimplemented: Read as '0'						
bit 14-8	14-8 RP47R<6:0>: Perinheral Output Function is Assigned to RP47 (Pin hite	

bit 14-8 **RP47R<6:0>:** Peripheral Output Function is Assigned to RP47 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP46R<6:0>:** Peripheral Output Function is Assigned to RP46 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0						
	RP49R6	RP49R5	RP49R4	RP49R3	RP49R2	RP49R1	RP49R0
bit 15				·	•		bit 8
U-0	R/W-0						
	RP48R6	RP48R5	RP48R4	RP48R3	RP48R2	RP48R1	RP48R0
bit 7							bit 0

REGISTER 11-43: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-8	RP49R<6:0>: Peripheral Output Function is Assigned to RP49 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP48R<6:0>: Peripheral Output Function is Assigned to RP48 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-44: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP51R6	RP51R5	RP51R4	RP51R3	RP51R2	RP51R1	RP51R0
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP50R6	RP50R5	RP50R4	RP50R3	RP50R2	RP50R1	RP50R0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			U = Unimplemented bit, read as '0'				

'0' = Bit is cleared

bit 15 Unimplemented: Read as '0'

-n = Value at POR

bit 14-8 **RP51R<6:0>:** Peripheral Output Function is Assigned to RP51 Output Pin bits (see Table 11-13 for peripheral function numbers)

'1' = Bit is set

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP50R<6:0>:** Peripheral Output Function is Assigned to RP50 Output Pin bits (see Table 11-13 for peripheral function numbers)

x = Bit is unknown

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP53R6	RP53R5	RP53R4	RP53R3	RP53R2	RP53R1	RP53R0
bit 15				·			bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP52R6	RP52R5	RP52R4	RP52R3	RP52R2	RP52R1	RP52R0
bit 7	•	•				•	bit 0
Legend:							
R = Readable b	oit	W = Writable	bit	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown				
bit 15	Unimplemen	ted: Read as ')'				

REGISTER 11-45: RPOR12: PERIPHERAL PIN SELECT OUTPUT REGISTER 12

bit 14-8	RP53R<6:0>: Peripheral Output Function is Assigned to RP53 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP52R<6:0>: Peripheral Output Function is Assigned to RP52 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-46: RPOR13: PERIPHERAL PIN SELECT OUTPUT REGISTER 13

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
—	RP55R6	RP55R5	RP55R4	RP55R3	RP55R2	RP55R1	RP55R0		
bit 15	•	•		•			bit 8		
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
—	RP54R6	RP54R5	RP54R4	RP54R3	RP54R2	RP54R1	RP54R0		
bit 7		•					bit 0		
Legend:									
R = Readable I	oit	W = Writable	bit	U = Unimplemented bit, read as '0'					
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared		x = Bit is unknown				
bit 15	Unimplemented: Read as '0'								
bit 14-8 RP55R<6:0>: Peripheral Output Function is Assigned to RP55 Output Pin bits									

(see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP54R<6:0>:** Peripheral Output Function is Assigned to RP54 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0						
—	RP57R6	RP57R5	RP57R4	RP57R3	RP57R2	RP57R1	RP57R0
bit 15							bit 8
U-0	R/W-0						
—	RP56R6	RP56R5	RP56R4	RP56R3	RP56R2	RP56R1	RP56R0
bit 7							bit 0
Legend:							

REGISTER 11-47: RPOR14: PERIPHERAL PIN SELECT OUTPUT REGISTER 14

Legend:				
R = Readable bit	Readable bit W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15	Unimplemented: Read as '0'
bit 14-8	RP57R<6:0>: Peripheral Output Function is Assigned to RP57 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP56R<6:0>: Peripheral Output Function is Assigned to RP56 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-48: RPOR15: PERIPHERAL PIN SELECT OUTPUT REGISTER 15

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP60R6	RP60R5	RP60R4	RP60R3	RP60R2	RP60R1	RP60R0
bit 15	-			·			bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RP58R6	RP58R5	RP58R4	RP58R3	RP58R2	RP58R1	RP58R0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown			nown	

bit 15 Unimplemented: Read as '0'

bit 14-8 **RP60R<6:0>:** Peripheral Output Function is Assigned to RP60 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP58R<6:0>:** Peripheral Output Function is Assigned to RP58 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP62R6	RP62R5	RP62R4	RP62R3	RP62R2	RP62R1	RP62R0
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP61R6	RP61R5	RP61R4	RP61R3	RP61R2	RP61R1	RP61R0
bit 7							bit 0
Legend:							
R = Readable b	oit	W = Writable	bit	U = Unimplemented bit, read as '0'			
-n = Value at POR (1' = Bit is set			'0' = Bit is cleared x = Bit is unknown				
bit 15	Unimplemen	ted: Read as ')'				

REGISTER 11-49: RPOR16: PERIPHERAL PIN SELECT OUTPUT REGISTER 16

bit 14-8	RP62R<6:0>: Peripheral Output Function is Assigned to RP62 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP61R<6:0>: Peripheral Output Function is Assigned to RP61 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-50: RPOR17: PERIPHERAL PIN SELECT OUTPUT REGISTER 17

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
—	RP64R6	RP64R5	RP64R4	RP64R3	RP64R2	RP64R1	RP64R0		
bit 15		•				•	bit 8		
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
_	RP63R6	RP63R5	RP63R4	RP63R3	RP63R2	RP63R1	RP63R0		
bit 7		•				•	bit 0		
Legend:									
R = Readable b	oit	W = Writable	bit	U = Unimplemented bit, read as '0'					
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared		x = Bit is unknown				
bit 15	Unimplemented: Read as '0'								
bit 14-8 RP64R<6:0>: Peripheral Output Function is Assigned to RP64 Output Pin bits									

(see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 **RP63R<6:0>:** Peripheral Output Function is Assigned to RP63 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0						
—	RP66R6	RP66R5	RP66R4	RP66R3	RP66R2	RP66R1	RP66R0
bit 15							bit 8
U-0	R/W-0						
	RP65R6	RP65R5	RP65R4	RP65R3	RP65R2	RP65R1	RP65R0
bit 7							bit 0

Legend:				
R = Readable bit W = Writable bit		U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15	Unimplemented: Read as '0'
bit 14-8	RP66R<6:0>: Peripheral Output Function is Assigned to RP66 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP65R<6:0>: Peripheral Output Function is Assigned to RP65 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-52: RPOR19: PERIPHERAL PIN SELECT OUTPUT REGISTER 19

U-0	R/W-0						
—	RP68R6	RP68R5	RP68R4	RP68R3	RP68R2	RP68R1	RP68R0
bit 15							bit 8

U-0	R/W-0						
—	RP67R6	RP67R5	RP67R4	RP67R3	RP67R2	RP67R1	RP67R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 Unimplemented: Read as '0'

bit 14-8**RP68R<6:0>:** Peripheral Output Function is Assigned to RP68 Output Pin bits
(see Table 11-13 for peripheral function numbers)bit 7**Unimplemented:** Read as '0'

bit 6-0 **RP67R<6:0>:** Peripheral Output Function is Assigned to RP67 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-53: RPOR20: PERIPHERAL PIN SELECT OUTPUT REGISTER 20

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
_	RP70R6	RP70R5	RP70R4	RP70R3	RP70R2	RP70R1	RP70R0	
bit 15			•				bit 8	
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	RP69R6	RP69R5	RP69R4	RP69R3	RP69R2	RP69R1	RP69R0	
bit 7							bit (
Legend:								
R = Readabl	e bit	W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is s		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown		
bit 15	Unimplemented: Read as '0'							
bit 11_8	PD70D/C:0>: Perinheral Output Eurotion is Assigned to PD70 Output Pin hits							

bit 14-8	RP70R<6:0>: Peripheral Output Function is Assigned to RP70 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP69R<6:0>: Peripheral Output Function is Assigned to RP69 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-54: RPOR21: PERIPHERAL PIN SELECT OUTPUT REGISTER 21

U-0	R/W-0						
—	RP72R6	RP72R5	RP72R4	RP72R3	RP72R2	RP72R1	RP72R0
bit 15							bit 8
U-0	R/W-0						
_	RP71R6	RP71R5	RP71R4	RP71R3	RP71R2	RP71R1	RP71R0
bit 7				•			bit 0
							,

Legend:			
R = Readable bit W = Writable bit		U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 Unimplemented: Read as '0'

bit 14-8	RP72R<6:0>: Peripheral Output Function is Assigned to RP72 Output Pin bits
	(see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'

bit 6-0 **RP71R<6:0>:** Peripheral Output Function is Assigned to RP71 Output Pin bits (see Table 11-13 for peripheral function numbers)

U-0	R/W-0						
—	RP74R6	RP74R5	RP74R4	RP74R3	RP74R2	RP74R1	RP74R0
bit 15							bit 8
U-0	R/W-0						
—	RP73R6	RP73R5	RP73R4	RP73R3	RP73R2	RP73R1	RP73R0
bit 7							bit 0

REGISTER 11-55: RPOR22: PERIPHERAL PIN SELECT OUTPUT REGISTER 22

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-8	RP74R<6:0>: Peripheral Output Function is Assigned to RP74 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP73R<6:0>: Peripheral Output Function is Assigned to RP73 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-56: RPOR23: PERIPHERAL PIN SELECT OUTPUT REGISTER 23

U-0	R/W-0						
—	RP76R6	RP76R5	RP76R4	RP76R3	RP76R2	RP76R1	RP76R0
bit 15							bit 8
U-0	R/W-0						

0-0	10/00-0		10/00-0	10/00-0	10/00-0	10.44-0	10,00-0
—	RP75R6	RP75R5	RP75R4	RP75R3	RP75R2	RP75R1	RP75R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

Dil 15 Unimplemented: Read as U	bit 15	Unimplemented: Read as '0'
---------------------------------	--------	----------------------------

bit 14-8	RP76R<6:0>: Peripheral Output Function is Assigned to RP76 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP75R<6:0>: Peripheral Output Function is Assigned to RP75 Output Pin bits

(see Table 11-13 for peripheral function numbers)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	RP177R6	RP177R5	RP177R4	RP177R3	RP177R2	RP177R1	RP177R0
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	RP176R6	RP176R5	RP176R4	RP176R3	RP176R2	RP176R1	RP176R0
bit 7							bit C
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit io	
bit 14-8	RP177R<6:0>: Peripheral Output Function is Assigned to RP177 Output Pin bits (see Table 11-13 for peripheral function numbers)
bit 7	Unimplemented: Read as '0'
bit 6-0	RP176R<6:0>: Peripheral Output Function is Assigned to RP176 Output Pin bits (see Table 11-13 for peripheral function numbers)

REGISTER 11-58: RPOR25: PERIPHERAL PIN SELECT OUTPUT REGISTER 25

U-0	R/W-0						
—	RP179R6	RP179R5	RP179R4	RP179R3	RP179R2	RP179R1	RP179R0
bit 15							bit 8
U-0	R/W-0						
	RP178R6	RP178R5	RP178R4	RP178R3	RP178R2	RP178R1	RP178R0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 Unimplemented: Read as '0'

- bit 14-8**RP179R<6:0>:** Peripheral Output Function is Assigned to RP179 Output Pin bits
(see Table 11-13 for peripheral function numbers)bit 7**Unimplemented:** Read as '0'
- bit 6-0 **RP178R<6:0>:** Peripheral Output Function is Assigned to RP178 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7

bit 0

U-0	R/W-0						
—	RP181R6	RP181R5	RP181R4	RP181R3	RP181R2	RP181R1	RP181R0
bit 15							bit 8
U-0	R/W-0						
_	RP180R6	RP180R5	RP180R4	RP180R3	RP180R2	RP180R1	RP180R0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 Unimplemented: Read as '0'

bit 7

bit 14-8 RP181R<6:0>: Peripheral Output Function is Assigned to RP181 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 7 Unimplemented: Read as '0'

bit 6-0 RP180R<6:0>: Peripheral Output Function is Assigned to RP180 Output Pin bits (see Table 11-13 for peripheral function numbers)

bit 0

NOTES:

12.0 TIMER1

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Timers" (DS70362) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer that can operate as a free-running interval timer/counter.

The Timer1 module has the following unique features over other timers:

- Can be Operated in Asynchronous Counter mode from an External Clock Source
- The External Clock Input (T1CK) can Optionally be Synchronized to the Internal Device Clock and the Clock Synchronization is Performed after the prescaler
- A block diagram of Timer1 is shown in Figure 12-1.

The Timer1 module can operate in one of the following modes:

• Timer mode

TABI F 12-1

- Gated Timer mode
- Synchronous Counter mode
- Asynchronous Counter mode

In Timer and Gated Timer modes, the input clock is derived from the internal instruction cycle clock (FcY). In Synchronous and Asynchronous Counter modes, the input clock is derived from the external clock input at the T1CK pin.

The Timer modes are determined by the following bits:

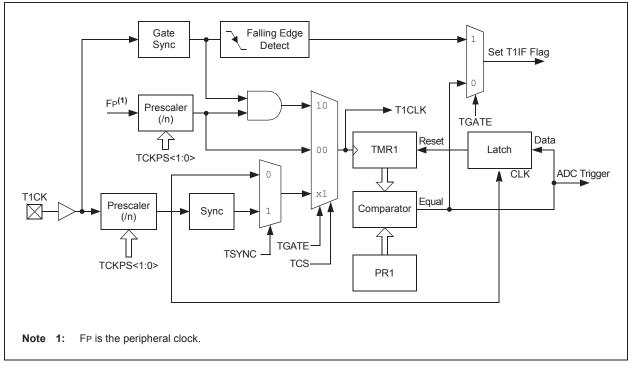
- Timer1 Clock Source Select bit (TCS): T1CON<1>
- Timer1 External Clock Input Synchronization Select bit (TSYNC): T1CON<2>
- Timer1 Gated Time Accumulation Enable bit (TGATE): T1CON<6>

Timer control bit settings for different operating modes are provided in Table 12-1.

TIMER1 MODE SETTINGS

Mode	TCS	TGATE	TSYNC		
Timer	0	0	Х		
Gated Timer	0	1	Х		
Synchronous Counter	1	х	1		
Asynchronous Counter	1	Х	0		

FIGURE 12-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM



12.1 Timer1 Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

12.1.1 KEY RESOURCES

- "Timers" (DS70362) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- · Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

12.2 Timer1 Control Register

REGISTER 12-1: T1CON: TIMER1 CONTROL REGISTER R/W-0 U-0 R/W-0 U-0 U-0 U-0 U-0 U-0 TON⁽¹⁾ _____ TSIDL ____ ____ _____ bit 15 bit 8 R/W-0 U-0 R/W-0 R/W-0 U-0 U-0 R/W-0 R/W-0 TSYNC⁽¹⁾ TCS⁽¹⁾ TGATE TCKPS1 TCKPS0 _ bit 7 bit 0 Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15 TON: Timer1 On bit⁽¹⁾ 1 = Starts 16-bit Timer1 0 = Stops 16-bit Timer1 bit 14 Unimplemented: Read as '0' bit 13 TSIDL: Timer1 Stop in Idle Mode bit 1 = Discontinues module operation when device enters Idle mode 0 = Continues module operation in Idle mode bit 12-7 Unimplemented: Read as '0' bit 6 TGATE: Timer1 Gated Time Accumulation Enable bit When TCS = 1: This bit is ignored. When TCS = 0: 1 = Gated time accumulation is enabled 0 = Gated time accumulation is disabled bit 5-4 TCKPS<1:0>: Timer1 Input Clock Prescale Select bits 11 = 1:256 10 = 1:64 01 = 1:8 00 = 1:1 bit 3 Unimplemented: Read as '0' TSYNC: Timer1 External Clock Input Synchronization Select bit⁽¹⁾ bit 2 When TCS = 1: 1 = Synchronizes external clock input 0 = Does not synchronize external clock input When TCS = 0: This bit is ignored. bit 1 TCS: Timer1 Clock Source Select bit⁽¹⁾ 1 = External clock is from pin, T1CK (on the rising edge) 0 = Internal clock (FP) bit 0 Unimplemented: Read as '0'

Note 1: When Timer1 is enabled in External Synchronous Counter mode (TCS = 1, TSYNC = 1, TON = 1), any attempts by user software to write to the TMR1 register are ignored.

NOTES:

13.0 TIMER2/3 AND TIMER4/5

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Timers" (DS70362) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Timer2/3 and Timer4/5 modules are 32-bit timers, which can also be configured as four independent 16-bit timers with selectable operating modes.

As 32-bit timers, Timer2/3 and Timer4/5 operate in three modes:

- Two Independent 16-Bit Timers (e.g., Timer2 and Timer3) with all 16-Bit Operating modes (except Asynchronous Counter mode)
- Single 32-Bit Timer
- Single 32-Bit Synchronous Counter

They also support these features:

- Timer Gate Operation
- Selectable Prescaler Settings
- Timer Operation during Idle and Sleep modes
- · Interrupt on a 32-Bit Period Register Match
- Time Base for Input Capture and Output Compare modules (Timer2 and Timer3 only)

Individually, all four of the 16-bit timers can function as synchronous timers or counters. They also offer the features listed previously, except for the event trigger; this is implemented only with Timer2/3. The operating modes and enabled features are determined by setting the appropriate bit(s) in the T2CON, T3CON, T4CON and T5CON registers. T2CON and T4CON are shown in generic form in Register 13-1. T3CON and T5CON are shown in Register 13-2.

For 32-bit timer/counter operation, Timer2 and Timer4 are the least significant word (Isw); Timer3 and Timer5 are the most significant word (msw) of the 32-bit timers.

Note: For 32-bit operation, T3CON and T5CON control bits are ignored. Only T2CON and T4CON control bits are used for setup and control. Timer2 and Timer4 clock and gate inputs are utilized for the 32-bit timer modules, but an interrupt is generated with the Timer3 and Timer5 interrupt flags.

A block diagram for an example 32-bit timer pair (Timer2/3 and Timer4/5) is shown in Figure 13-2.

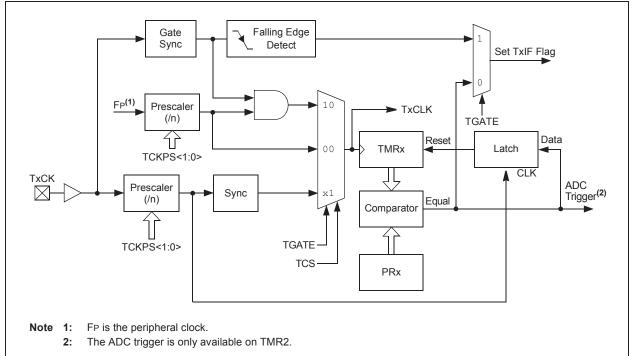
13.1 Timer Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

13.1.1 KEY RESOURCES

- "Timers" (DS70362) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

FIGURE 13-1: TIMERX BLOCK DIAGRAM (x = 2 THROUGH 5)



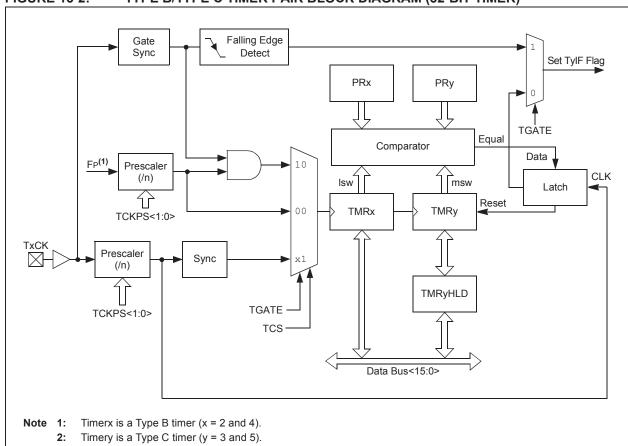


FIGURE 13-2: TYPE B/TYPE C TIMER PAIR BLOCK DIAGRAM (32-BIT TIMER)

13.2 Timer2/3 and Timer4/5 Control Registers

REGISTER 13-1: TxCON: (TIMER2 AND TIMER4) CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0	
TON	_	TSIDL	—	—		_	—	
bit 15		I	I				bit 8	
U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0	
_	TGATE	TCKPS1	TCKPS0	T32	—	TCS ⁽¹⁾		
bit 7							bit C	
Legend:	h:+		L:4		nented bit rea	d aa (0'		
R = Readable		W = Writable bit U = Unimplemented bit, read as '0'				0.11/2		
-n = Value at I	OR	'1' = Bit is set		'0' = Bit is cle	areo	x = Bit is unkn	own	
bit 15	TON: Timerx <u>When T32 = 1</u> 1 = Starts 32- 0 = Stops 32- <u>When T32 = 0</u> 1 = Starts 16- 0 = Stops 16-	<u>L:</u> bit Timerx/y bit Timerx/y) <u>:</u> bit Timerx						
bit 14		ted: Read as '	0'					
bit 13	-	x Stop in Idle N						
	 1 = Discontinues module operation when device enters Idle mode 0 = Continues module operation in Idle mode 							
bit 12-7	Unimplemen	ted: Read as '	0'					
bit 6	TGATE: Timerx Gated Time Accumulation Enable bit <u>When TCS = 1:</u> This bit is ignored. <u>When TCS = 0:</u> 1 = Gated time accumulation is enabled 0 = Gated time accumulation is disabled							
bit 5-4	TCKPS<1:0>	: Timerx Input	Clock Prescal	e Select bits				
	11 = 1:256 10 = 1:64 01 = 1:8 00 = 1:1							
bit 3	T32: 32-Bit Timer Mode Select bit							
		d Timery form d Timery act a						
bit 2	Unimplemented: Read as '0'							
bit 1	TCS: Timerx Clock Source Select bit ⁽¹⁾ 1 = External clock is from pin, TxCK (on the rising edge)							
bit 0	0 = Internal cl	ted: Read as '	0'					
~	2pionion		~					

R/W-0) U-0	R/W-0	U-0	U-0	U-0	U-0	U-0			
TON ⁽¹)	TSIDL ⁽²⁾	_	_		_	_			
bit 15				I	•	- I - I	bit			
U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0			
	TGATE ⁽¹⁾	TCKPS1 ⁽¹⁾	TCKPS0 ⁽¹⁾	_	_	TCS ^(1,3)				
bit 7	·		•				bit			
Legend:										
R = Read	able bit	W = Writable	bit	U = Unimple	mented bit, rea	d as '0'				
-n = Value	e at POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkno	own			
bit 15	TON: Timery									
		1 = Starts 16-bit Timery								
	0 = Stops 16-	2	-1							
bit 14		ted: Read as '								
bit 13		TSIDL: Timery Stop in Idle Mode bit ⁽²⁾								
					Idle mode					
bit 12-7		0 = Continues module operation in Idle mode Unimplemented: Read as '0'								
bit 6	=	ery Gated Time		Enable bit ⁽¹⁾						
	When TCS =									
	This bit is ign	ored.								
	When TCS =									
		ne accumulation ne accumulation								
bit 5-4		: Timery Input		e Select bits ⁽¹)					
	11 = 1:256	i mory mpar								
	10 = 1:64									
	01 = 1:8									
	00 = 1:1		-1							
bit 3-2	•	ted: Read as '								
bit 1		Clock Source S		o ricing odgo)						
	0 = Internal c	•		e rising eage))					
bit 0		Unimplemented: Read as '0'								
Note 1:		nen 32-bit operation is enabled (TxCON<3> = 1), these bits have no effect on Timery operation; all time notions are set through TxCON.					tion; all time			
2:	When 32-bit timer	nen 32-bit timer operation is enabled (T32 = 1) in the Timerx Control register (TxCON<3>), the TSIDL must be cleared to operate the 32-bit timer in Idle mode.								
-										

REGISTER 13-2: TyCON: (TIMER3 AND TIMER5) CONTROL REGISTER

3: The TyCK pin is not available on all devices. See the "Pin Diagrams" section for the available pins.

14.0 INPUT CAPTURE

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Input Capture with Dedicated Timer" (DS70000352) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The input capture module is useful in applications requiring frequency (period) and pulse measurements. The dsPIC33EPXXXGS70X/80X devices support four input capture channels.

Key features of the input capture module include:

- Hardware-Configurable for 32-Bit Operation in All modes by Cascading Two Adjacent modules
- Synchronous and Trigger modes of Output Compare Operation, with up to 21 User-Selectable Trigger/Sync Sources available
- A 4-Level FIFO Buffer for Capturing and Holding Timer Values for Several Events
- Configurable Interrupt Generation
- Up to Six Clock Sources available for each module, Driving a Separate Internal 16-Bit Counter

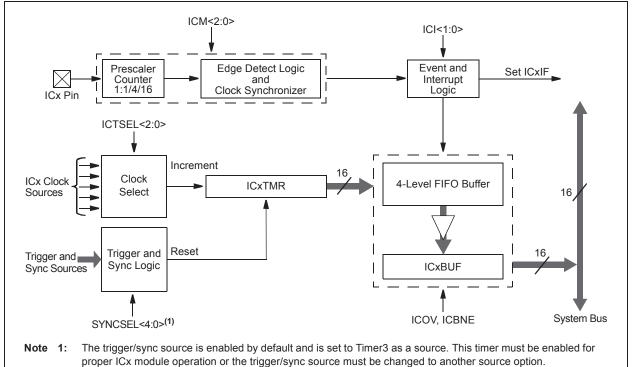
14.1 Input Capture Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

14.1.1 KEY RESOURCES

- "Input Capture with Dedicated Timer" (DS70000352) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- · Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

FIGURE 14-1: INPUT CAPTURE x MODULE BLOCK DIAGRAM



14.2 Input Capture Registers

REGISTER 14-1: ICxCON1: INPUT CAPTURE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
		ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	_
bit 15							bit 8
U-0	R/W-0	R/W-0	HC/HS/R-0	HC/HS/R-0	R/W-0	R/W-0	R/W-0
—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0
bit 7							bit 0
Legend:		HC = Hardware Clearable bit		HS = Hardware Settable bit			
R = Readable bit		W = Writable bit		U = Unimplemented bit, read as '0		d as '0'	
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit 15-14	Unimplemented: Read as '0'
bit 13	ICSIDL: Input Capture x Stop in Idle Control bit
	1 = Input capture will halt in CPU Idle mode
	0 = Input capture will continue to operate in CPU Idle mode
bit 12-10	ICTSEL<2:0>: Input Capture x Timer Select bits
	 111 = Peripheral clock (FP) is the clock source of the ICx 110 = Reserved 101 = Reserved 100 = T1CLK is the clock source of the ICx (only the synchronous clock is supported) 011 = T5CLK is the clock source of the ICx 010 = T4CLK is the clock source of the ICx 001 = T2CLK is the clock source of the ICx 000 = T3CLK is the clock source of the ICx
bit 9-7	Unimplemented: Read as '0'
bit 6-5	ICI<1:0>: Number of Captures per Interrupt Select bits (this field is not used if ICM<2:0> = 001 or 111) 11 = Interrupt on every fourth capture event 10 = Interrupt on every third capture event 01 = Interrupt on every second capture event 00 = Interrupt on every capture event
bit 4	ICOV: Input Capture x Overflow Status Flag bit (read-only)
	 1 = Input capture buffer overflow has occurred 0 = No input capture buffer overflow has occurred
bit 3	ICBNE: Input Capture x Buffer Not Empty Status bit (read-only)
	 1 = Input capture buffer is not empty, at least one more capture value can be read 0 = Input capture buffer is empty
bit 2-0	ICM<2:0>: Input Capture x Mode Select bits
	 111 = Input Capture x functions as an interrupt pin only in CPU Sleep and Idle modes (rising edge detect only, all other control bits are not applicable) 110 = Unused (module is disabled) 101 = Capture mode, every 16th rising edge (Prescaler Capture mode) 100 = Capture mode, every 4th rising edge (Prescaler Capture mode) 011 = Capture mode, every rising edge (Simple Capture mode) 010 = Capture mode, every falling edge (Simple Capture mode) 010 = Capture mode, every falling edge (Simple Capture mode) 001 = Capture mode, every rising and falling edge (Edge Detect mode, ICI<1:0> is not used in this mode) 000 = Input Capture x is turned off

REGISTER 14-2: ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	IC32
bit 15							bit 8

R/W-0	HS/R/W-0	U-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-1
ICTRIG ⁽²⁾	TRIGSTAT ⁽³⁾		SYNCSEL4(4)	SYNCSEL3(4)	SYNCSEL2(4)	SYNCSEL1(4)	SYNCSEL0 ⁽⁴⁾
bit 7							bit 0

Legend:	HS = Hardware Settable bit	t	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-9	Unimplemented: Read as '0'

bit 8 **IC32:** Input Capture x 32-Bit Timer Mode Select bit (Cascade mode)

- 1 = Odd ICx and even ICx form a single 32-bit input capture module⁽¹⁾
- 0 = Cascade module operation is disabled

bit 7 ICTRIG: Input Capture x Trigger Operation Select bit⁽²⁾

- 1 = Input source is used to trigger the input capture timer (Trigger mode)
- Input source is used to synchronize the input capture timer to a timer of another module (Synchronization mode)

bit 6 **TRIGSTAT:** Timer Trigger Status bit⁽³⁾

- 1 = ICxTMR has been triggered and is running
- 0 = ICxTMR has not been triggered and is being held clear
- bit 5 Unimplemented: Read as '0'
- **Note 1:** The IC32 bit in both the odd and even ICx must be set to enable Cascade mode.
 - 2: The input source is selected by the SYNCSEL<4:0> bits of the ICxCON2 register.
 - **3:** This bit is set by the selected input source (selected by SYNCSEL<4:0> bits); it can be read, set and cleared in software.
 - 4: Do not use the ICx module as its own sync or trigger source.
 - 5: This option should only be selected as a trigger source and not as a synchronization source.

REGISTER 14-2: ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2 (CONTINUED)

bit 4-0

- **SYNCSEL<4:0>:** Input Source Select for Synchronization and Trigger Operation bits⁽⁴⁾ 11111 = No sync or trigger source for ICx
- 111110 = **Reserved**
- 11101 = **Reserved**
- 11100 = Reserved
- 11011 = CMP4 module synchronizes or triggers $ICx^{(5)}$
- 11010 = CMP3 module synchronizes or triggers ICx⁽⁵⁾
- 11001 = CMP2 module synchronizes or triggers $ICx^{(5)}$
- 11000 = CMP1 module synchronizes or triggers $ICx^{(5)}$
- 10111 = Reserved
- 10110 = Reserved
- 10101 = Reserved
- 10100 = Reserved
- 10011 = IC4 module interrupt synchronizes or triggers ICx
- 10010 = IC3 module interrupt synchronizes or triggers ICx
- 10001 = IC2 module interrupt synchronizes or triggers ICx
- 10000 = IC1 module interrupt synchronizes or triggers ICx
- 01111 = Timer5 synchronizes or triggers ICx
- 01110 = Timer4 synchronizes or triggers ICx
- 01101 = Timer3 synchronizes or triggers ICx (default)
- 01100 = Timer2 synchronizes or triggers ICx
- 01011 = Timer1 synchronizes or triggers ICx
- 01010 = Reserved
- 01001 = Reserved
- 01000 = IC4 module synchronizes or triggers ICx
- 00111 = IC3 module synchronizes or triggers ICx
- 00110 = IC2 module synchronizes or triggers ICx
- 00101 = IC1 module synchronizes or triggers ICx
- 00100 = OC4 module synchronizes or triggers ICx
- 00011 = OC3 module synchronizes or triggers ICx
- 00010 = OC2 module synchronizes or triggers ICx
- 00001 = OC1 module synchronizes or triggers ICx
- 00000 = No sync or trigger source for ICx
- **Note 1:** The IC32 bit in both the odd and even ICx must be set to enable Cascade mode.
 - 2: The input source is selected by the SYNCSEL<4:0> bits of the ICxCON2 register.
 - **3:** This bit is set by the selected input source (selected by SYNCSEL<4:0> bits); it can be read, set and cleared in software.
 - 4: Do not use the ICx module as its own sync or trigger source.
 - 5: This option should only be selected as a trigger source and not as a synchronization source.

15.0 OUTPUT COMPARE

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Output Compare with Dedicated Timer" (DS70005159) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The output compare module can select one of six available clock sources for its time base. The module compares the value of the timer with the value of one or two Compare registers, depending on the operating mode selected. The state of the output pin changes when the timer value matches the Compare register value. The output compare module generates either a single output pulse, or a sequence of output pulses, by changing the state of the output pin on the compare match events. The output compare module can also generate interrupts on compare match events.

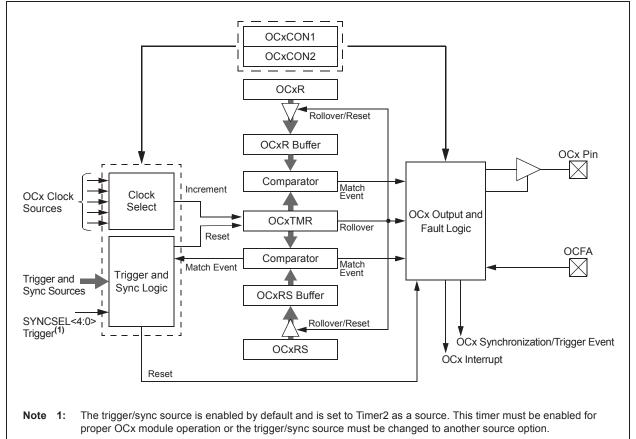
15.1 Output Compare Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

15.1.1 KEY RESOURCES

- "Output Compare with Dedicated Timer" (DS70005159) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

FIGURE 15-1: OUTPUT COMPARE x MODULE BLOCK DIAGRAM



15.2 Output Compare Control Registers

REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1

—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	_					
	•									
						bit 8				
U-0	U-0	HSC/R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0				
						bit (
	HSC = Hardwa	are Settable/Cle	arable bit							
le bit				ented bit, read a	s '0'					
t POR	'1' = Bit is set		-		x = Bit is unkr	iown				
Unimpleme	ented: Read as '0	3								
OCSIDL: O	utput Compare x	Stop in Idle Mo	de Control bit							
	•			de						
OCTSEL<2:0>: Output Compare x Clock Select bits										
111 = Peripheral clock (FP)										
010 = T4CLK is the clock source of the OCx										
001 = T3CLK is the clock source of the OCx										
-										
ENFLTA: Fault A Input Enable bit										
			s disabled							
•										
			baa aggurrad							
				ed						
TRIGMODE	E: Trigger Status N	Aode Select bit								
			$u_{\text{hon}} \cap \cap v_{\text{PS}} = 0$		oftwaro					
1 = 1RIGS	TAT (OCxCON2<	0/) is cleared w			Jiwaie					
	OCSIDL: O 1 = Output 0 = Output OCTSEL<2 111 = Perip 110 = Rese 101 = Rese 100 = T1Cl 011 = T5Cl 010 = T4Cl 001 = T3Cl 000 = T2Cl Unimpleme ENFLTA: F 1 = Output 0 = Output Unimpleme OCFLTA: P 1 = PWM F 0 = N0 PW	Ide bit W = Writable bit t POR '1' = Bit is set Unimplemented: Read as '0 OCSIDL: Output Compare x 1 = Output Compare x halts 0 = Output Compare x contin OCTSEL<2:0>: Output Compare x contin OCTSEL<2:0>: Output Compare x contin OCTSEL<2:0>: Output Compare x contin OCTSEL<2:0>: Output Compare x contin 11 = Peripheral clock (FP) 110 = Reserved 100 = T1CLK is the clock sout 011 = T5CLK is the clock sout 011 = T5CLK is the clock sout 010 = T4CLK is the clock sout 010 = T4CLK is the clock sout 000 = T2CLK is the clock sout 000 = T2CLK is the clock sout 000 = T2CLK is the clock sout 011 = Output Compare Fault A 0 = Output Compare Fault A 0 = Output Compare Fault A 0 = Output Compare Fault A 0 = Output Compare Fault A 0 = Output Compare Fault A 0 = PWM Fault A condition of 0 0 = No PWM Fault A condition of 0	We bit W = Writable bit t POR '1' = Bit is set Unimplemented: Read as '0' OCSIDL: Output Compare x Stop in Idle Mo 1 = Output Compare x halts in CPU Idle mo 0 = Output Compare x halts in CPU Idle mo 0 = Output Compare x halts in CPU Idle mo 0 = Output Compare x continues to operate OCTSEL<2:0>: Output Compare x Clock Set 11 = Peripheral clock (FP) 110 = Reserved 100 = T1CLK is the clock source of the OCX 011 = T5CLK is the clock source of the OCX 010 = T4CLK is the clock source of the OCX 011 = T3CLK is the clock source of the OCX 010 = T4CLK is the clock source of the OCX 011 = T3CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 001 = Output Compare Fault A input (OCFA) it 1 = Output Compare Fault A input (OCFA) it 0 = Output Compare Fault A input (OCFA) it 0 = Output Compare Fault A input (OCFA) it 0 = Output Compare Fault A input (OCFA) it	HSC = Hardware Settable/Clearable bit HSC = Hardware Settable/Clearable bit Unimplemented: Read as '0' OCSIDL: Output Compare x Stop in Idle Mode Control bit 1 = Output Compare x halts in CPU Idle mode 0 = Output Compare x continues to operate in CPU Idle mo OCTSEL<2:0>: Output Compare x Clock Select bits 111 = Peripheral clock (FP) 110 = Reserved 101 = Reserved 100 = T1CLK is the clock source of the OCx (only the synch 011 = T5CLK is the clock source of the OCx 010 = T4CLK is the clock source of the OCx 010 = T3CLK is the clock source of the OCx 010 = T3CLK is the clock source of the OCx 010 = T2CLK is the clock source of the OCx 010 = T4CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock source of the OCX 000 = T2CLK is the clock so	HSC = Hardware Settable/Clearable bit HSC = Hardware Settable/Clearable bit U = Unimplemented bit, read a t POR '1' = Bit is set '0' = Bit is cleared Unimplemented: Read as '0' OCSIDL: Output Compare x Stop in Idle Mode Control bit 1 = Output Compare x halts in CPU Idle mode 0 = Output Compare x continues to operate in CPU Idle mode OCTSEL<2:0>: Output Compare x Clock Select bits 111 = Peripheral clock (FP) 110 = Reserved 100 = T1CLK is the clock source of the OCx (only the synchronous clock is source of the OCx 010 = T4CLK is the clock source of the OCx 010 = T4CLK is the clock source of the OCx 010 = T4CLK is the clock source of the OCx 010 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 011 = Output Compare Fault A input (OCFA) is enabled 0 = Output Compare Fault A input (OCFA) is disabled Unimplemented: Read as '0' OCFLTA: PWM Fault A Condition Status bit 1 = PWM Fault A condition on the OCFA pin has occurred 0 = No PWM Fault A condition on the OCFA pin has occurred	HSC = Hardware Settable/Clearable bit le bit W = Writable bit U = Unimplemented bit, read as '0' Unimplemented: Read as '0' OCSIDL: Output Compare x Stop in Idle Mode Control bit 1 = Output Compare x halts in CPU Idle mode 0' = Bit is cleared 0 = Output Compare x halts in CPU Idle mode 0 0 = Output Compare x continues to operate in CPU Idle mode 0CTSEL<2:0>: Output Compare x Clock Select bits 11 = Peripheral clock (FP) 10 10 = Reserved 101 = Reserved 100 = T1CLK is the clock source of the OCx (only the synchronous clock is supported) 011 = T3CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 000 = T2CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx 001 = T3CLK is the clock source of the OCx				

Note 1: OCxR and OCxRS are double-buffered in PWM mode only.

REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1 (CONTINUED)

- bit 2-0 OCM<2:0>: Output Compare x Mode Select bits
 - 111 = Center-Aligned PWM mode: Output is set high when OCxTMR = OCxR and set low when OCxTMR = OCxRS⁽¹⁾
 - 110 = Edge-Aligned PWM mode: Output is set high when OCxTMR = 0 and set low when OCxTMR = OCxR⁽¹⁾
 - 101 = Double Compare Continuous Pulse mode: Initializes OCx pin low, toggles OCx state continuously on alternate matches of OCxR and OCxRS
 - 100 = Double Compare Single-Shot mode: Initializes OCx pin low, toggles OCx state on matches of OCxR and OCxRS for one cycle
 - 011 = Single Compare mode: Compare event with OCxR, continuously toggles OCx pin
 - 010 = Single Compare Single-Shot mode: Initializes OCx pin high, compare event with OCxR, forces OCx pin low
 - 001 = Single Compare Single-Shot mode: Initializes OCx pin low, compare event with OCxR, forces OCx pin high
 - 000 = Output compare channel is disabled
- Note 1: OCxR and OCxRS are double-buffered in PWM mode only.

REGISTER 15-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2

R/W-0
DC32
bit 8
R/W-0 NCSEL0
bit C
TA bit is
ts
module

- OCMP3 PTG trigger out [2]
- OCMP4 PTG trigger out [3]

REGISTER 15-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2 (CONTINUED)

- bit 4-0 SYNCSEL<4:0>: Trigger/Synchronization Source Selection bits
 - 11111 = OCxRS compare event is used for synchronization
 - 11110 = INT2 pin synchronizes or triggers OCx
 - 11101 = INT1 pin synchronizes or triggers OCx
 - 11100 = Reserved
 - 11011 = CMP4 module synchronizes or triggers OCx
 - 11010 = CMP3 module synchronizes or triggers OCx
 - 11001 = CMP2 module synchronizes or triggers OCx
 - 11000 = CMP1 module synchronizes or triggers OCx
 - 10111 = Reserved
 - 10110 = Reserved
 - 10101 = Reserved
 - 10100 = Reserved
 - 10011 = IC4 input capture interrupt event synchronizes or triggers OCx
 - 10010 = IC3 input capture interrupt event synchronizes or triggers OCx
 - 10001 = IC2 input capture interrupt event synchronizes or triggers OCx
 - 10000 = IC1 input capture interrupt event synchronizes or triggers OCx
 - 01111 = Timer5 synchronizes or triggers OCx
 - 01110 = Timer4 synchronizes or triggers OCx
 - 01101 = Timer3 synchronizes or triggers OCx
 - 01100 = Timer2 synchronizes or triggers OCx (default)
 - 01011 = Timer1 synchronizes or triggers OCx
 - 01010 = PTG Trigger Output x⁽³⁾
 - 01001 = Reserved
 - 01000 = IC4 input capture event synchronizes or triggers OCx
 - 00111 = IC3 input capture event synchronizes or triggers OCx
 - 00110 = IC2 input capture event synchronizes or triggers OCx
 - 00101 = IC1 input capture event synchronizes or triggers OCx
 - 00100 = OC4 module synchronizes or triggers $OCx^{(1,2)}$
 - 00011 = OC3 module synchronizes or triggers $OCx^{(1,2)}$
 - $00010 = OC2 \text{ module synchronizes or triggers } OCx^{(1,2)}$
 - 00001 = OC1 module synchronizes or triggers $OCx^{(1,2)}$
 - 00000 = No sync or trigger source for OCx
- Note 1: Do not use the OCx module as its own synchronization or trigger source.
 - 2: When the OCy module is turned off, it sends a trigger out signal. If the OCx module uses the OCy module as a trigger source, the OCy module must be unselected as a trigger source prior to disabling it.
 - 3: For each OCMPx instance, a different PTG trigger out is used:
 - OCMP1 PTG trigger out [0]
 - OCMP2 PTG trigger out [1]
 - OCMP3 PTG trigger out [2]
 - OCMP4 PTG trigger out [3]

NOTES:

16.0 HIGH-SPEED PWM

Note: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "High-Speed PWM Module" (DS70000323) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).

The high-speed PWM on dsPIC33EPXXXGS70X/80X devices supports a wide variety of PWM modes and output formats. This PWM module is ideal for power conversion applications, such as:

- AC/DC Converters
- DC/DC Converters
- Power Factor Correction
- Uninterruptible Power Supply (UPS)
- Inverters
- Battery Chargers
- Digital Lighting

16.1 Features Overview

The high-speed PWM module incorporates the following features:

- Eight PWMx Generators with Two Outputs per Generator
- · Two Master Time Base modules
- Individual Time Base and Duty Cycle for each
 PWM Output
- Duty Cycle, Dead Time, Phase Shift and a Frequency Resolution of 1.04 ns
- Independent Fault and Current-Limit Inputs
- · Redundant Output
- True Independent Output
- Center-Aligned PWM mode
- · Output Override Control
- Chop mode (also known as Gated mode)
- Special Event Trigger
- Dual Trigger from PWMx to Analog-to-Digital Converter (ADC)
- PWMxL and PWMxH Output Pin Swapping
- Independent PWMx Frequency, Duty Cycle and Phase-Shift Changes
- Enhanced Leading-Edge Blanking (LEB) Functionality
- PWM Capture Functionality

Note: Duty cycle, dead time, phase shift and frequency resolution is 8.32 ns in Center-Aligned PWM mode.

Figure 16-1 conceptualizes the PWM module in a simplified block diagram. Figure 16-2 illustrates how the module hardware is partitioned for each PWMx output pair for the Complementary PWM mode.

The PWM module contains eight PWM generators. The module has up to 16 PWMx output pins: PWM1H/ PWM1L through PWM8H/PWM8L. For complementary outputs, these 16 I/O pins are grouped into high/low pairs. PWM1 through PWM6 can be used to trigger an ADC conversion.

16.2 Feature Description

The PWM module is designed for applications that require:

- High resolution at high PWM frequencies
- The ability to drive Standard Edge-Aligned, Center-Aligned, Complementary mode and Push-Pull mode outputs
- The ability to create multiphase PWM outputs

Two common, medium power converter topologies are push-pull and half-bridge. These designs require the PWM output signal to be switched between alternate pins, as provided by the Push-Pull PWM mode.

Phase-shifted PWM describes the situation where each PWM generator provides outputs, but the phase relationship between the generator outputs is specifiable and changeable.

Multiphase PWM is often used to improve DC/DC Converter load transient response, and reduce the size of output filter capacitors and inductors. Multiple DC/DC Converters are often operated in parallel, but phase shifted in time. A single PWM output, operating at 250 kHz, has a period of 4 μ s but an array of four PWM channels, staggered by 1 μ s each, yields an effective switching frequency of 1 MHz. Multiphase PWM applications typically use a fixed-phase relationship.

Variable phase PWM is useful in Zero Voltage Transition (ZVT) power converters. Here, the PWM duty cycle is always 50% and the power flow is controlled by varying the relative phase shift between the two PWM generators.

16.2.1 WRITE-PROTECTED REGISTERS

On dsPIC33EPXXXGS70X/80X family devices, write protection is implemented for the IOCONx and FCLCONx registers. The write protection feature prevents any inadvertent writes to these registers. This protection feature can be controlled by the PWMLOCK Configuration bit (FDEVOPT<0>). The default state of the write protection feature is enabled (PWMLOCK = 1). The write protection feature can be disabled by configuring PWMLOCK = 0.

To gain write access to these locked registers, the user application must write two consecutive values (0xABCD and 0x4321) to the PWMKEY register to perform the unlock operation. The write access to the IOCONx or FCLCONx registers must be the next SFR access following the unlock process. There can be no other SFR accesses during the unlock process and subsequent write access. To write to both the IOCONx and FCLCONx registers requires two unlock operations.

The correct unlocking sequence is described in Example 16-1.

EXAMPLE 16-1: PWM WRITE-PROTECTED REGISTER UNLOCK SEQUENCE

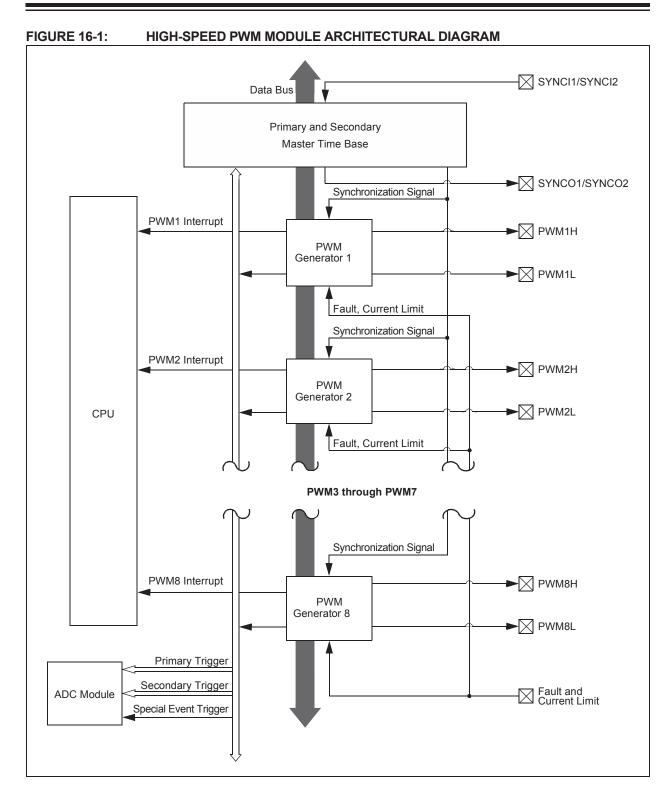
; Writing to FCLCON1	register requires unlock sequence
mov #0xabcd, w10	; Load first unlock key to w10 register
mov #0x4321, w11	; Load second unlock key to w11 register
mov #0x0000, w0	; Load desired value of FCLCON1 register in w0
mov w10, PWMKEY	; Write first unlock key to PWMKEY register
mov w11, PWMKEY	; Write second unlock key to PWMKEY register
mov w0, FCLCON1	; Write desired value to FCLCON1 register
-	and polarity using the IOCON1 register register requires unlock sequence
mov #0xabcd, w10	; Load first unlock key to w10 register
mov #0x4321, w11	; Load second unlock key to w11 register
mov #0xF000, w0	; Load desired value of IOCON1 register in w0
mov w10, PWMKEY	; Write first unlock key to PWMKEY register
mov w11, PWMKEY	; Write second unlock key to PWMKEY register
mov w0, IOCON1	; Write desired value to IOCON1 register
1	

16.3 PWM Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

16.3.1 KEY RESOURCES

- "High-Speed PWM Module" (DS70000323) in the "dsPIC33/PIC24 Family Reference Manual"
- · Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools



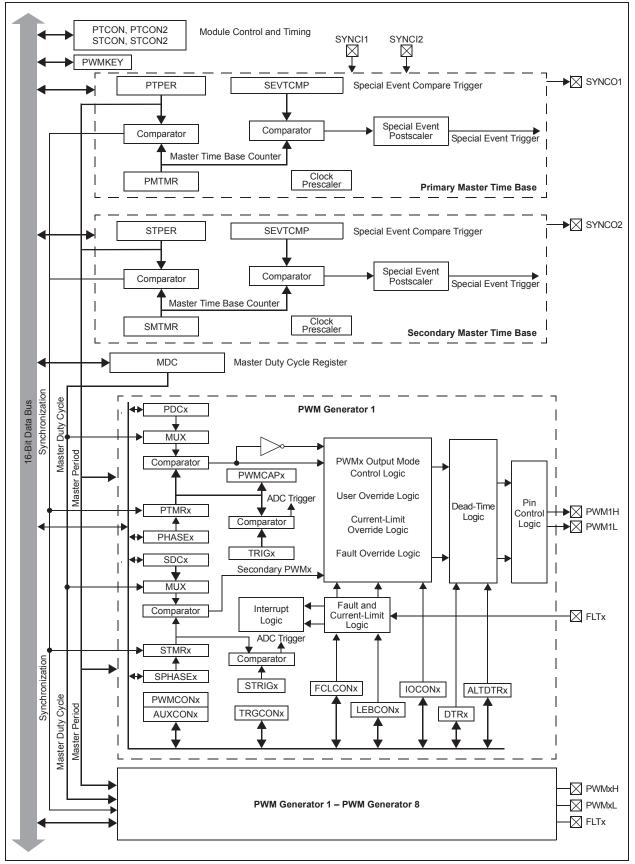


FIGURE 16-2: SIMPLIFIED CONCEPTUAL BLOCK DIAGRAM OF THE HIGH-SPEED PWM

REGISTER 16-1: PTCON: PWM TIME BASE CONTROL REGISTER

R/W-0	U-0	R/W-0	HSC/R-0	R/W-0	R/W-0	R/W-0	R/W-0
PTEN	—	PTSIDL	SESTAT	SEIEN	EIPU ⁽¹⁾	SYNCPOL ⁽¹⁾	SYNCOEN ⁽¹⁾
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SYNCEN ⁽¹⁾	SYNCSRC2 ⁽¹⁾	SYNCSRC1 ⁽¹⁾	SYNCSRC0 ⁽¹⁾	SEVTPS3 ⁽¹⁾	SEVTPS2 ⁽¹⁾	SEVTPS1 ⁽¹⁾	SEVTPS0 ⁽¹⁾
bit 7							bit 0

Legend:		HSC = Hardware Settat	ole/Clearable bit						
R = Read	able bit	W = Writable bit	U = Unimplemented bit	read as '0'					
-n = Value	e at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown					
bit 15		/M Module Enable bit							
		module is enabled module is disabled							
bit 14	Unimplem	nented: Read as '0'							
bit 13	PTSIDL: F	WM Time Base Stop in Idle	Mode bit						
		time base halts in CPU Idle r time base runs in CPU Idle n							
bit 12	SESTAT: S	Special Event Interrupt Status	s bit						
		I event interrupt is pending I event interrupt is not pendi	ng						
bit 11	SEIEN: Sp	ecial Event Interrupt Enable	bit						
		I event interrupt is enabled I event interrupt is disabled							
bit 10	EIPU: Ena	PU: Enable Immediate Period Updates bit ⁽¹⁾							
		Period register is updated in Period register updates occu	nmediately ur on PWM cycle boundaries						
bit 9	SYNCPOL	.: Synchronize Input and Out	tput Polarity bit ⁽¹⁾						
		Ix/SYNCO1 polarity is inverte Ix/SYNCO1 is active-high	ed (active-low)						
bit 8	SYNCOE	I: Primary Time Base Synch	ronization Enable bit ⁽¹⁾						
		O1 output is enabled O1 output is disabled							
bit 7	SYNCEN:	External Time Base Synchro	onization Enable bit ⁽¹⁾						
		al synchronization of primary al synchronization of primary							
bit 6-4	SYNCSRO	<2:0>: Synchronous Source	e Selection bits ⁽¹⁾						
	111 = Res 101 = Res 100 = Res 011 = PTC	served							
	010 = PTC 001 = SYN 000 = SYN								
Note 1:	These bits sho	ould be changed only when F	PTEN = 0. In addition, when us	ing the SYNCIx feature. the use					

Note 1: These bits should be changed only when PTEN = 0. In addition, when using the SYNCIx feature, the user application must program the Period register with a value that is slightly larger than the expected period of the external synchronization input signal.

REGISTER 16-1: PTCON: PWM TIME BASE CONTROL REGISTER (CONTINUED)

Note 1: These bits should be changed only when PTEN = 0. In addition, when using the SYNCIx feature, the user application must program the Period register with a value that is slightly larger than the expected period of the external synchronization input signal.

REGISTER 16-2: PTCON2: PWM CLOCK DIVIDER SELECT REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
_	—	_	—	—	PCLKDIV<2:0>(1)		
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable I	oit	U = Unimplemented bit, read as '0'			
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown			nown

bit 15-3 Unimplemented: Read as '0'

bit 2-0 PCLKDIV<2:0>: PWMx Input Clock Prescaler (Divider) Select bits⁽¹⁾

111 = Reserved

- 110 = Divide-by-64, maximum PWM timing resolution
- 101 = Divide-by-32, maximum PWM timing resolution
- 100 = Divide-by-16, maximum PWM timing resolution
- 011 = Divide-by-8, maximum PWM timing resolution
- 010 = Divide-by-4, maximum PWM timing resolution
- 001 = Divide-by-2, maximum PWM timing resolution
- 000 = Divide-by-1, maximum PWM timing resolution (power-on default)

Note 1: These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

REGISTER 16-3: PTPER: PWM PRIMARY MASTER TIME BASE PERIOD REGISTER^(1,2)

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			PTPE	R<15:8>			
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			PTPE	ER<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			it	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown			nown	

bit 15-0 **PTPER<15:0>:** Primary Master Time Base (PMTMR) Period Value bits

Note 1: The PWMx time base has a minimum value of 0x0010 and a maximum value of 0xFFF8.

2: Any period value that is less than 0x0028 must have the Least Significant three bits set to '0', thus yielding a period resolution at 8.32 ns (at fastest auxiliary clock rate).

REGISTER 16-4: SEVTCMP: PWM SPECIAL EVENT COMPARE REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
SEVTCMP<12:5>									
bit 15	bit 15								

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
	5	—	—	—			
bit 7					bit 0		

Legend:			
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-3 SEVTCMP<12:0>: Special Event Compare Count Value bits

bit 2-0 Unimplemented: Read as '0'

Note 1: One LSB = 1.04 ns (at fastest auxiliary clock rate); therefore, the minimum SEVTCMP resolution is 8.32 ns.

REGISTER 16-5: STCON: PWM SECONDARY MASTER TIME BASE CONTROL REGISTER

U-0	U-0	U-0	HSC/R-0	R/W-0	R/W-0	R/W-0	R/W-0		
	_	_	SESTAT	SEIEN	EIPU ⁽¹⁾	SYNCPOL	SYNCOEN		
bit 15							bit 8		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
SYNCEN	SYNCSRC2	SYNCSRC1	SYNCSRC0	SEVTPS3	SEVTPS2	SEVTPS1	SEVTPS0		
bit 7							bit		
Legend:		HSC = Hardw	are Settable/Cle	earable bit					
R = Readable	e bit	W = Writable	bit	U = Unimplem	nented bit, read	1 as '0'			
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	iown		
		ted: Deed on W							
bit 15-13 bit 12		ted: Read as ' cial Event Inter							
DILIZ			interrupt is pen	dina					
			interrupt is not						
bit 11	SEIEN: Special Event Interrupt Enable bit								
		condary special event interrupt is enabled							
	0 = Secondary special event interrupt is disabled								
bit 10	EIPU: Enable Immediate Period Updates bit ⁽¹⁾ 1 = Active Secondary Period register is updated immediately								
						ndaries			
bit 9		 a Active Secondary Period register updates occur on PWMx cycle boundaries SynCPOL: Synchronize Input and Output Polarity bit 							
	1 = SYNCIx/S	YNCO2 polarit	y is inverted (ac y is active-high						
bit 8	SYNCOEN: Secondary Master Time Base Synchronization Enable bit								
		output is enabl output is disab							
bit 7	SYNCEN: External Secondary Master Time Base Synchronization Enable bit								
			of secondary ti of secondary ti						
bit 6-4	SYNCSRC<2	:0>: Secondary	/ Time Base Sy	nc Source Sel	ection bits				
		ed ed igger Output 1 igger Output 1 2							
bit 3-0			ndary Special E	Event Trigger (Output Postsca	ler Select bits			
	1111 = 1:16 p 0001 = 1:2 pc	oostcaler							
	•								
	•								

Note 1: This bit only applies to the secondary master time base period.

REGISTER 16-6: STCON2: PWM SECONDARY CLOCK DIVIDER SELECT REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	_	—	—	—	—	—	—
bit 15			•		-	-	bit 8
U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	_	_	—	—	PCLKDIV<2:0>(1)		
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			oit	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x =			x = Bit is unkr	nown			

bit 15-3 Unimplemented: Read as '0'

bit 2-0

- PCLKDIV<2:0>: PWM Input Clock Prescaler (Divider) Select bits⁽¹⁾
 - 111 = Reserved
 - 110 = Divide-by-64, maximum PWM timing resolution
 - 101 = Divide-by-32, maximum PWM timing resolution
 - 100 = Divide-by-16, maximum PWM timing resolution
 - 011 = Divide-by-8, maximum PWM timing resolution
 - 010 = Divide-by-4, maximum PWM timing resolution
 - 001 = Divide-by-2, maximum PWM timing resolution
 - 000 = Divide-by-1, maximum PWM timing resolution (power-on default)
- **Note 1:** These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

REGISTER 16-7: STPER: PWM SECONDARY MASTER TIME BASE PERIOD REGISTER^(1,2)

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	
		STPE	R<15:8>				
						bit 8	
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	
		STPI	ER<7:0>				
						bit 0	
R = Readable bit W = Writable bit			U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknow			nown	
	R/W-1	R/W-1 R/W-1 bit W = Writable	R/W-1 R/W-1 STPE bit	STPER<15:8> R/W-1 R/W-1 R/W-1 R/W-1 STPER<7:0> bit W = Writable bit U = Unimplen	STPER<15:8> R/W-1 R/W-1 R/W-1 STPER<7:0> bit W = Writable bit U = Unimplemented bit, read	STPER<15:8> R/W-1 R/W-1 R/W-1 R/W-1 STPER<7:0> bit W = Writable bit U = Unimplemented bit, read as '0'	

bit 15-0 STPER<15:0>: Secondary Master Time Base (SMTMR) Period Value bits

Note 1: The PWMx time base has a minimum value of 0x0010 and a maximum value of 0xFFF8.

2: Any period value that is less than 0x0028 must have the Least Significant 3 bits set to '0', thus yielding a period resolution at 8.32 ns (at fastest auxiliary clock rate).

REGISTER 16-8: SSEVTCMP: PWM SECONDARY SPECIAL EVENT COMPARE REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			SSEVTC	MP<12:5>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
	S	SEVTCMP<4:0)>		—		—
bit 7					· · · · ·		bit 0
Legend:							

R = Readable bit	W = Writable bit U = Unimplemented bit, read as '0'		d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-3 SSEVTCMP<12:0>: Special Event Compare Count Value bits

bit 2-0 Unimplemented: Read as '0'

Note 1: One LSB = 1.04 ns (at fastest auxiliary clock rate); therefore, the minimum SSEVTCMP resolution is 8.32 ns.

REGISTER 16-9: CHOP: PWM CHOP CLOCK GENERATOR REGISTER⁽¹⁾

R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
CHPCLKEN	_	—	—	—	—	CHOPCLK6	CHOPCLK5
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
CHOPCLK4	CHOPCLK3	CHOPCLK2	CHOPCLK1	CHOPCLK0	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

 bit 15
 CHPCLKEN: Enable Chop Clock Generator bit

 1 = Chop clock generator is enabled
 0 = Chop clock generator is disabled

 bit 14-10
 Unimplemented: Read as '0'

 bit 9-3
 CHOPCLK<6:0>: Chop Clock Divider bits

 Value is in 8.32 ns increments. The frequency of the chop clock signal is given by:
Chop Frequency = 1/(16.64 * (CHOP<7:3> + 1) * Primary Master PWM Input Clock Period).

 bit 2-0
 Unimplemented: Read as '0'

Note 1: The chop clock generator operates with the primary PWM clock prescaler (PCLKDIV<2:0>) in the PTCON2 register (Register 16-2).

REGISTER 16-10: MDC: PWM MASTER DUTY CYCLE REGISTER^(1,2)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			MDC	<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			MD	C<7:0>				
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			oit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set				'0' = Bit is cleared x = Bit is unknown				

bit 15-0 MDC<15:0>: PWM Master Duty Cycle Value bits

Note 1: The smallest pulse width that can be generated on the PWM output corresponds to a value of 0x0008, while the maximum pulse width generated corresponds to a value of Period – 0x0008.

2: As the duty cycle gets closer to 0% or 100% of the PWM period (0 to 40 ns, depending on the mode of operation), PWM duty cycle resolution will increase from one to three LSBs.

REGISTER 16-11: PWMKEY: PWM PROTECTION LOCK/UNLOCK KEY REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PWMKE	Y<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PWMKI	EY<7:0>			
bit 7							bit 0
l egend:							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **PWMKEY<15:0>:** PWM Protection Lock/Unlock Key Value bits

HSC/R-0	HSC/R-0	HSC/R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLTSTAT ⁽	¹⁾ CLSTAT ⁽¹⁾	TRGSTAT	FLTIEN	CLIEN	TRGIEN	ITB ⁽³⁾	MDCS ⁽³⁾
bit 15	L						bit 8
R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
DTC1	DTC0	—	—	MTBS	CAM ^(2,3,4)	XPRES ⁽⁵⁾	IUE
bit 7							bit C
Logondi		HSC = Hardwa	ara Sattabla/Cl	ograpia bit			
Legend: R = Reada	bla bit	W = Writable b			aantad hit raad	aa 'O'	
-n = Value		'1' = Bit is set	л	-	nented bit, read		011/2
	alfur	I - DILIS SEL		'0' = Bit is clea	areu	x = Bit is unkn	OWII
bit 15	1 = Fault inter 0 = No Fault i	ult Interrupt Stat rrupt is pending nterrupt is pend ared by setting F	ing				
bit 14	1 = Current-lii 0 = No curren	rent-Limit Interru mit interrupt is p it-limit interrupt i ared by setting (ending s pending				
bit 13		igger Interrupt S					
	0 = No trigger	terrupt is pendir interrupt is pen ared by setting 1	ding				
bit 12	FLTIEN: Faul	t Interrupt Enab	e bit				
		rupt is enabled rupt is disabled	and the FLTS	TAT bit is cleare	-d		
bit 11		nt-Limit Interrup					
	1 = Current-li	mit interrupt is e mit interrupt is d	nabled	e CLSTAT bit is	cleared		
bit 10		ger Interrupt En					
	1 = A trigger e	event generates	an interrupt re		bit is cleared		
bit 9		dent Time Base					
	1 = PHASEx/	SPHASEx regis	ters provide the			Mx generator	
bit 8		er Duty Cycle Re	•	•			
	1 = MDC regi	ster provides du d SDCx register	ty cycle inform	ation for this P			
Note 1:	Software must cl	ear the interrupt	status here ar	nd in the corres	pondina IFSx b	it in the interrur	ot controller.
2:	The Independent CAM bit is ignore	Time Base mo				•	
	These bits should		d after the PW	Mx is enabled	by setting PTEN	N (PTCON<15>	·) = 1.
4:	Center-Aligned n registers. The hig the fastest clock.	node ignores the ghest Center-Ali	e Least Signific	ant three bits c	of the Duty Cycle	e, Phase and D	ead-Time
	Configure CLMOI		•) = 0 and ITB (PWMCONx<9>) = 1 to operate	in External Perio	od Reset mode
	0				, , , , , , , , , , , , , , , , , , , ,		

REGISTER 16-12: PWMCONx: PWMx CONTROL REGISTER (x = 1 to 8)

REGISTER 16-12: PWMCONx: PWMx CONTROL REGISTER (x = 1 to 8) (CONTINUED)

- bit 7-6 DTC<1:0>: Dead-Time Control bits 11 = Reserved 10 = Dead-time function is disabled 01 = Negative dead time is actively applied for Complementary Output mode 00 = Positive dead time is actively applied for all Output modes bit 5-4 Unimplemented: Read as '0' bit 3 MTBS: Master Time Base Select bit 1 = PWMx generator uses the secondary master time base for synchronization and the clock source for the PWMx generation logic (if secondary time base is available) 0 = PWMx generator uses the primary master time base for synchronization and the clock source for the PWMx generation logic CAM: Center-Aligned Mode Enable bit^(2,3,4) bit 2 1 = Center-Aligned mode is enabled 0 = Edge-Aligned mode is enabled bit 1 XPRES: External PWMx Reset Control bit⁽⁵⁾ 1 = Current-limit source resets the time base for this PWMx generator if it is in Independent Time Base mode 0 = External pins do not affect the PWMx time base bit 0 IUE: Immediate Update Enable bit 1 = Updates to the active Duty Cycle, Phase Offset, Dead-Time and local Time Base Period registers are immediate 0 = Updates to the active Duty Cycle, Phase Offset, Dead-Time and local Time Base Period registers are synchronized to the local PWMx time base Note 1: Software must clear the interrupt status here and in the corresponding IFSx bit in the interrupt controller. 2: The Independent Time Base mode (ITB = 1) must be enabled to use Center-Aligned mode. If ITB = 0, the CAM bit is ignored. 3: These bits should not be changed after the PWMx is enabled by setting PTEN (PTCON<15>) = 1.
 - 4: Center-Aligned mode ignores the Least Significant three bits of the Duty Cycle, Phase and Dead-Time registers. The highest Center-Aligned mode resolution available is 8.32 ns with the clock prescaler set to the fastest clock.
 - 5: Configure CLMOD (FCLCONx<8>) = 0 and ITB (PWMCONx<9>) = 1 to operate in External Period Reset mode.

REGISTER 16-13: PDCx: PWMx GENERATOR DUTY CYCLE REGISTER (x = 1 to 8)^(1,2,3)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PDC	x<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PDC	Cx<7:0>				
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			it	U = Unimplemented bit, read as '0'				
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown		nown		

bit 15-0 **PDCx<15:0>:** PWMx Generator Duty Cycle Value bits

Note 1: In Independent PWM mode, the PDCx register controls the PWMxH duty cycle only. In the Complementary, Redundant and Push-Pull PWM modes, the PDCx register controls the duty cycle of both the PWMxH and PWMxL.

2: The smallest pulse width that can be generated on the PWMx output corresponds to a value of 0x0008, while the maximum pulse width generated corresponds to a value of Period – 0x0008.

3: As the duty cycle gets closer to 0% or 100% of the PWM period (0 to 40 ns, depending on the mode of operation), PWMx duty cycle resolution will increase from one to three LSBs.

REGISTER 16-14: SDCx: PWMx SECONDARY DUTY CYCLE REGISTER (x = 1 to 8)^(1,2,3)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			SDC	x<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			SDC	Cx<7:0>				
bit 7							bit 0	
-								
Legend:								
R = Readable	R = Readable bit W = Writable bit		oit	U = Unimplemented bit, read as '0'				
-n = Value at I	n = Value at POR (1' = Bit is set			'0' = Bit is cleared x = Bit is unknown			nown	

bit 15-0 SDCx<15:0>: PWMx Secondary Duty Cycle for PWMxL Output Pin bits

Note 1: The SDCx register is used in Independent PWM mode only. When used in Independent PWM mode, the SDCx register controls the PWMxL duty cycle.

2: The smallest pulse width that can be generated on the PWMx output corresponds to a value of 0x0008, while the maximum pulse width generated corresponds to a value of Period – 0x0008.

3: As the duty cycle gets closer to 0% or 100% of the PWM period (0 to 40 ns, depending on the mode of operation), PWMx duty cycle resolution will increase from one to three LSBs.

REGISTER 16-15: PHASEX: PWMx PRIMARY PHASE-SHIFT REGISTER (x = 1 to 8)^(1,2)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PHASE	Ex<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PHAS	Ex<7:0>				
bit 7							bit 0	
Legend:								
R = Readable	bit	W = Writable bit U = Unimplemented bit, read as '0'						

bit 15-0 PHASEx<15:0>: PWMx Phase-Shift Value or Independent Time Base Period for the PWMx Generator bits

Note 1: If PWMCONx<9> = 0, the following applies based on the mode of operation:

'1' = Bit is set

- Complementary, Redundant and Push-Pull Output mode (IOCONx<11:10> = 00, 01 or 10); PHASEx<15:0> = Phase-shift value for PWMxH and PWMxL outputs
- True Independent Output mode (IOCONx<11:10> = 11); PHASEx<15:0> = Phase-shift value for PWMxH only
- When the PHASEx/SPHASEx registers provide the phase shift with respect to the master time base; therefore, the valid range is 0x0000 through period

'0' = Bit is cleared

x = Bit is unknown

- **2:** If PWMCONx<9> = 1, the following applies based on the mode of operation:
 - Complementary, Redundant and Push-Pull Output mode (IOCONx<11:10> = 00, 01 or 10); PHASEx<15:0> = Independent time base period value for PWMxH and PWMxL
 - True Independent Output mode (IOCONx<11:10> = 11); PHASEx<15:0> = Independent time base period value for PWMxH only
 - When the PHASEx/SPHASEx registers provide the local period, the valid range is 0x0000-0xFFF8

-n = Value at POR

REGISTER 16-16: SPHASEx: PWMx SECONDARY PHASE-SHIFT REGISTER (x = 1 to 8)^(1,2)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			SPHAS	SEx<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			SPHA	SEx<7:0>				
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			t	U = Unimplemented bit, read as '0'				
-n = Value at F	n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is un		x = Bit is unkn	iown				

bit 15-0 **SPHASEx<15:0>:** Secondary Phase Offset for PWMxL Output Pin bits (used in Independent PWM mode only)

- **Note 1:** If PWMCONx<9> = 0, the following applies based on the mode of operation:
 - Complementary, Redundant and Push-Pull Output mode (IOCONx<11:10> = 00, 01 or 10); SPHASEx<15:0> = Not used
 - True Independent Output mode (IOCONx<11:10> = 11), SPHASEx<15:0> = Phase-shift value for PWMxL only
 - **2:** If PWMCONx<9> = 1, the following applies based on the mode of operation:
 - Complementary, Redundant and Push-Pull Output mode (IOCONx<11:10> = 00, 01 or 10); SPHASEx<15:0> = Not used
 - True Independent Output mode (IOCONx<11:10> = 11); SPHASEx<15:0> = Independent time base period value for PWMxL only
 - When the PHASEx/SPHASEx registers provide the local period, the valid range of values is 0x0010-0xFFF8

REGISTER 16-17: DTRx: PWMx DEAD-TIME REGISTER (x = 1 to 8)

-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unkn			nown
R = Readable	R = Readable bit W = Writable bit		oit	U = Unimplemented bit, read as '0'			
Legend:							
bit 7							bit (
			DTF	Rx<7:0>			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
bit 15	ı						bit 8
_	_			DTRx	<13:8>		
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

bit 15-14Unimplemented: Read as '0'bit 13-0DTRx<13:0>: Unsigned 14-Bit Dead-Time Value for PWMx Dead-Time Unit bits

REGISTER 16-18: ALTDTRx: PWMx ALTERNATE DEAD-TIME REGISTER (x = 1 to 8)

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	—		ALTDTRx<13:8>					
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			ALTDT	Rx<7:0>				
bit 7							bit 0	
Legend:								

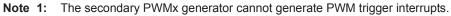
Legena:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-0 ALTDTRx<13:0>: Unsigned 14-Bit Alternate Dead-Time Value for PWMx Dead-Time Unit bits

R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0					
TRGDIV3	TRGDIV2	TRGDIV1	TRGDIV0	—	_	—	_					
bit 15		·					bit					
R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
DTM ⁽¹⁾	—	TRGSTRT5	TRGSTRT4	TRGSTRT3	TRGSTRT2	TRGSTRT1	TRGSTRTC					
bit 7							bit					
Legend:												
R = Readabl	e bit	W = Writable	oit	U = Unimplem	nented bit, read	l as '0'						
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown					
bit 15-12	TRGDIV<3:0	Trigger # Out	tput Divider bit	S								
		er output for eve										
		er output for eve										
	1101 = Trigger output for every 14th trigger event											
	1100 = Trigger output for every 13th trigger event 1011 = Trigger output for every 12th trigger event											
	1010 = Trigger output for every 11th trigger event											
	1001 = Trigger output for every 10th trigger event											
	1000 = Trigger output for every 9th trigger event											
	0111 = Trigger output for every 8th trigger event 0110 = Trigger output for every 7th trigger event											
		er output for even										
		er output for even										
	0011 = Trigger output for every 4th trigger event 0010 = Trigger output for every 3rd trigger event											
	0001 = Trigger output for every 2nd trigger event											
	0000 = Trigger output for every trigger event											
bit 11-8	-	ted: Read as '										
bit 7	DTM: Dual Tr	igger Mode bit ⁽	1)									
		ry trigger event										
		ry trigger event rate PWM trigg			nary trigger ev	ent to create a	PWM trigger					
bit 6		ted: Read as '	0	lited								
	•			nabla Salaat b	ito							
bit 5-0		:0>: Trigger Po				fter the module	ic checklod					
	•	ait 63 PWM cyc	les belore gen	eraung the linst	ingger event a		e is enabled					
	•											
	•											
		ait 2 PWM cycle										
	000001 = Wa	ait 1 PWM cycle	before genera	ating the first tri	gger event afte	er the module is	enabled					
		it 0 PWM cycle										

REGISTER 16-19: TRGCONX: PWMx TRIGGER CONTROL REGISTER (x = 1 to 8)



R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PENH	PENL	POLH	POLL	PMOD1 ⁽¹⁾	PMOD0 ⁽¹⁾	OVRENH	OVRENL
bit 15		•		•			bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OVRDAT1	OVRDAT0	FLTDAT1 ⁽²⁾	FLTDAT0 ⁽²⁾	CLDAT1 ⁽²⁾	CLDAT0 ⁽²⁾	SWAP	OSYNC
bit 7		•				•	bit (
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimplen	nented bit, read	d as '0'	
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
bit 15	PENH: PWM	KH Output Pin	Ownership bit				
		odule controls t		1			
		dule controls th	•				
bit 14		L Output Pin C	-				
		odule controls t dule controls th					
bit 13		kH Output Pin F					
		in is active-low					
		oin is active-hig					
bit 12	POLL: PWMx	L Output Pin P	olarity bit				
		in is active-low in is active-higl					
bit 11-10	PMOD<1:0>:	PWMx I/O Pin	Mode bits ⁽¹⁾				
		′O pin pair is in			mode		
		O pin pair is in		•			
		'O pin pair is in 'O pin pair is in			node		
bit 9		verride Enable f	-	• •	loue		
DIL 9		1 provides data			1		
		nerator provide					
bit 8	OVRENL: OV	erride Enable f	or PWMxL Pin	bit			
	1 = OVRDAT) provides data	for output on t	he PWMxL pin			
	0 = PWMx ge	nerator provide	es data for the I	PWMxL pin			
bit 7-6	OVRDAT<1:0	>: Data for PW	/MxH, PWMxL	Pins if Overrid	e is Enabled bi	ts	
		1, OVRDAT1 p 1, OVRDAT0 p					
bit 5-4	FLTDAT<1:0>	State for PW	MxH and PWM	IxL Pins if FLTI	MOD<1:0> are	Enabled bits(2))
		CLCONx<15>) :					
		ve, then FLTDA					
		ve, then FLTDA	•				
		LCONx<15>): is active, then				pin.	
		ve, then FLTDA				F	

REGISTER 16-20: IOCONX: PWMx I/O CONTROL REGISTER (x = 1 to 8)

2: State represents the active/inactive state of the PWMx depending on the POLH and POLL bits settings.

REGISTER 16-20: IOCONx: PWMx I/O CONTROL REGISTER (x = 1 to 8) (CONTINUED)

bit 3-2	CLDAT<1:0>: State for PWMxH and PWMxL Pins if CLMOD is Enabled bits ⁽²⁾
	IFLTMOD (FCLCONx<15>) = 0: Normal Fault mode:
	If current limit is active, then CLDAT1 provides the state for the PWMxH pin.
	If current limit is active, then CLDAT0 provides the state for the PWMxL pin.
	IFLTMOD (FCLCONx<15>) = 1: Independent Fault mode:
	CLDAT<1:0> bits are ignored.
bit 1	SWAP: SWAP PWMxH and PWMxL Pins bit
	1 = PWMxH output signal is connected to the PWMxL pins; PWMxL output signal is connected to the PWMxH pins
	0 = PWMxH and PWMxL pins are mapped to their respective pins
bit 0	OSYNC: Output Override Synchronization bit
	1 = Output overrides via the OVRDAT<1:0> bits are synchronized to the PWMx time base
	0 = Output overrides via the OVRDAT<1:0> bits occur on the next CPU clock boundary
N	

- **Note 1:** These bits should not be changed after the PWMx module is enabled (PTEN = 1).
 - 2: State represents the active/inactive state of the PWMx depending on the POLH and POLL bits settings.

REGISTER 16-21: TRIGX: PWMx PRIMARY TRIGGER COMPARE VALUE REGISTER (x = 1 to 8)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			TRGC	MP<12:5>				
bit 15 bit								
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	
		TRGCMP<4:0>	>		—	—	—	
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'				
-n = Value at I	= Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is		x = Bit is unkn	nown				

bit 15-3 **TRGCMP<12:0>:** Trigger Compare Value bits When the primary PWMx functions in the local time base, this register contains the compare values that can trigger the ADC module.

bit 2-0 Unimplemented: Read as '0'

REGISTER 16-22: FCLCONX: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IFLTMOD	CLSRC4	CLSRC3	CLSRC2	CLSRC1	CLSRC0	CLPOL ⁽¹⁾	CLMOD
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
FLTSRC4	FLTSRC3	FLTSRC2	FLTSRC1	FLTSRC0	FLTPOL ⁽¹⁾	FLTMOD1	FLTMOD0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	1 as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 IFLTMOD: Independent Fault Mode Enable bit

- I = Independent Fault mode: Current-limit input maps FLTDAT1 to the PWMxH output and the Fault input maps FLTDAT0 to the PWMxL output; the CLDAT<1:0> bits are not used for override functions
 0 = Normal Fault mode: Current-Limit mode maps CLDAT<1:0> bits to the PWMxH and PWMxL
- outputs; the PWM Fault mode maps FLTDAT<1:0> to the PWMxH and PWMxL outputs

bit 14-10 CLSRC<4:0>: Current-Limit Control Signal Source Select for PWMx Generator bits

11111 = FLT31	
---------------	--

- 10001 = Reserved
- 10000 = Analog Comparator 4 01111 = Analog Comparator 3
- 01110 = Analog Comparator 2
- 01110 Analog Comparator 2 01101 = Analog Comparator 1
- 01100 = Fault 12
- 01011 = Fault 11
- 01010 = Fault 10
- 01001 = Fault 9
- 01000 = Fault 8
- 00111 = Fault 7
- 00110 = Fault 6
- 00101 = Fault 5
- 00100 = Fault 4
- 00011 = Fault 3
- 00010 = Fault 2
- 00001 = Fault 1
- 00000 = Reserved
- bit 9 CLPOL: Current-Limit Polarity for PWMx Generator bit⁽¹⁾
 - 1 = The selected current-limit source is active-low
 - 0 = The selected current-limit source is active-high
- bit 8 CLMOD: Current-Limit Mode Enable for PWMx Generator bit
 - 1 = Current-Limit mode is enabled
 - 0 = Current-Limit mode is disabled
- Note 1: These bits should be changed only when PTEN = 0 (PTCON<15>).

REGISTER 16-22: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER (x = 1 to 8) (CONTINUED)

bit 7-3 FLTSRC<4:0>: Fault Control Signal Source Select for PWMx Generator bits

11111 = Fault 31 (Default) 11110-10111 = Reserved 10110 = Fault 22 10101 = Fault 21 10100 = Fault 20 10011 = Fault 19 10010 = Fault 18 10001 = Fault 17 10000 = Analog Comparator 4 01111 = Analog Comparator 3 01110 = Analog Comparator 2 01101 = Analog Comparator 1 01100 = Fault 12 01011 = Fault 11 01010 = Fault 10 01001 = Fault 9 01000 = Fault 8 00111 = Fault 7 00110 = Fault 6 00101 = Fault 5 00100 = Fault 4 00011 = Fault 3 00010 = Fault 2 00001 = Fault 1 00000 = Reserved bit 2 FLTPOL: Fault Polarity for PWMx Generator bit⁽¹⁾ 1 = The selected Fault source is active-low 0 = The selected Fault source is active-high bit 1-0 FLTMOD<1:0>: Fault Mode for PWMx Generator bits

- 11 = Fault input is disabled
- 10 = Reserved
- 01 = The selected Fault source forces the PWMxH, PWMxL pins to FLTDATx values (cycle)
- 00 = The selected Fault source forces the PWMxH, PWMxL pins to FLTDATx values (latched condition)
- Note 1: These bits should be changed only when PTEN = 0 (PTCON<15>).

REGISTER 16-23: STRIGX: PWMx SECONDARY TRIGGER COMPARE VALUE REGISTER (x = 1 to 8)⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			STRGO	CMP<12:5>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
		STRGCMP<4:0		—	—	—	
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable	bit	U = Unimplem	ented bit, read	as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknow			nown
bit 15-3	STRGCMP<	12:0>: Seconda	ry Trigger Co	mpare Value bits	3		
	When the se	condary PWMx	functions in tl	ne local time base	e, this register (contains the co	mpare values
	that can trigg	ger the ADC mod	dule.				

bit 2-0 Unimplemented: Read as '0'

Note 1: STRIGx cannot generate the PWM trigger interrupts.

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0					
PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	_						
bit 15	I		1				bit 8					
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
	—	BCH ⁽¹⁾	BCL ⁽¹⁾	BPHH	BPHL	BPLH	BPLL					
bit 7							bit C					
Legend:												
R = Readal	ble bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'						
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkn	iown					
bit 15	PHR: PWMx	H Rising Edge	Trigger Enable	e bit								
	0	0	00	Leading-Edge E	0	er						
	-	• •	-	ing edge of PWI	MxH							
bit 14		H Falling Edge										
	•	•		Leading-Edge l	•	er						
bit 13	-	L Rising Edge T	-									
DIL 15				Leading-Edge E	Ranking counte	2r						
				ing edge of PWI								
bit 12	-	L Falling Edge 1	-									
				Leading-Edge E	Blanking count	er						
				lling edge of PW								
bit 11	FLTLEBEN:	FLTLEBEN: Fault Input Leading-Edge Blanking Enable bit										
	•	 1 = Leading-Edge Blanking is applied to the selected Fault input 0 = Leading-Edge Blanking is not applied to the selected Fault input 										
	-	• •			-							
bit 10	CLLEBEN: Current-Limit Leading-Edge Blanking Enable bit											
	 1 = Leading-Edge Blanking is applied to the selected current-limit input 0 = Leading-Edge Blanking is not applied to the selected current-limit input 											
bit 9-6	-	nted: Read as '										
bit 5 0	•			al High Enable b	_{it} (1)							
bit 5		BCH: Blanking in Selected Blanking Signal High Enable bit ⁽¹⁾ 1 = State blanking (of current-limit and/or Fault input signals) when the selected blanking signal is high										
		\perp = State blanking (of current-limit and/or Fault input signals) when the selected blanking signal is high 0 = No blanking when the selected blanking signal is high										
bit 4	BCL: Blanki	BCL: Blanking in Selected Blanking Signal Low Enable bit ⁽¹⁾										
		1 = State blanking (of current-limit and/or Fault input signals) when the selected blanking signal is low										
	0 = No blank	king when the se	elected blankir	ng signal is low								
bit 3		king in PWMxH	-									
				Fault input signa is high	lls) when the P	WMxH output i	s high					
	0 = No blanking when the PWMxH output is high											
bit 2	BPHL: Blank	KING IN PVVIVIXH	BPHL: Blanking in PWMxH Low Enable bit 1 = State blanking (of current-limit and/or Fault input signals) when the PWMxH output is low									
bit 2	1 = State bla	-	t-limit and/or I	Fault input signa	lls) when the P	WMxH output i	s low					



REGISTER 16-24: LEBCONX: PWMx LEADING-EDGE BLANKING (LEB) CONTROL REGISTER (x = 1 to 8) (CONTINUED)

- bit 1
 BPLH: Blanking in PWMxL High Enable bit

 1 = State blanking (of current-limit and/or Fault input signals) when the PWMxL output is high

 0 = No blanking when the PWMxL output is high

 bit 0
 BPLL: Blanking in PWMxL Low Enable bit
 - 1 = State blanking (of current-limit and/or Fault input signals) when the PWMxL output is low
 0 = No blanking when the PWMxL output is low
- **Note 1:** The blanking signal is selected via the BLANKSEL<3:0> bits in the AUXCONx register.

REGISTER 16-25: LEBDLYx: PWMx LEADING-EDGE BLANKING DELAY REGISTER (x = 1 to 8)

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—		LEB	<8:5>	
bit 15	·	·					bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
		LEB<4:0>			—	_	—
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable I	bit	U = Unimplemented bit, read as '0'			
-n = Value at	POR	'1' = Bit is set		0' = Bit is cleared x = Bit is unknown			

bit 15-12 Unimplemented: Read as '0'

bit 11-3 **LEB<8:0>:** Leading-Edge Blanking Delay for Current-Limit and Fault Inputs bits The value is in 8.32 ns increments.

bit 2-0 Unimplemented: Read as '0'

REGISTER 16-26: AUXCONx: PWMx AUXILIARY CONTROL REGISTER (x = 1 to 8) R/W-0 R/W-0 U-0 U-0 R/W-0 R/W-0 R/W-0 R/W-0 HRPDIS **HRDDIS** ____ ____ BLANKSEL3 **BLANKSEL2 BLANKSEL1 BLANKSEL0** bit 15 bit 8 U-0 U-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 CHOPSEL3 CHOPSEL2 CHOPSEL1 CHOPSEL0 CHOPHEN CHOPLEN bit 7 bit 0 Leaend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '0' = Bit is cleared '1' = Bit is set x = Bit is unknown bit 15 HRPDIS: High-Resolution PWMx Period Disable bit 1 = High-resolution PWMx period is disabled to reduce power consumption 0 = High-resolution PWMx period is enabled bit 14 HRDDIS: High-Resolution PWMx Duty Cycle Disable bit 1 = High-resolution PWMx duty cycle is disabled to reduce power consumption 0 = High-resolution PWMx duty cycle is enabled bit 13-12 Unimplemented: Read as '0' bit 11-8 BLANKSEL<3:0>: PWMx State Blank Source Select bits The selected state blank signal will block the current-limit and/or Fault input signals (if enabled via the BCH and BCL bits in the LEBCONx register). 1001 = Reserved 1000 = PWM8H is selected as the state blank source 0111 = PWM7H is selected as the state blank source 0110 = PWM6H is selected as the state blank source 0101 = PWM5H is selected as the state blank source 0100 = PWM4H is selected as the state blank source 0011 = PWM3H is selected as the state blank source 0010 = PWM2H is selected as the state blank source 0001 = PWM1H is selected as the state blank source 0000 = No state blanking bit 7-6 Unimplemented: Read as '0' bit 5-2 CHOPSEL<3:0>: PWMx Chop Clock Source Select bits The selected signal will enable and disable (chop) the selected PWMx outputs. 1001 = Reserved 1000 = PWM8H is selected as the chop clock source 0111 = PWM7H is selected as the chop clock source 0110 = PWM6H is selected as the chop clock source 0101 = PWM5H is selected as the chop clock source 0100 = PWM4H is selected as the chop clock source 0011 = PWM3H is selected as the chop clock source 0010 = PWM2H is selected as the chop clock source 0001 = PWM1H is selected as the chop clock source 0000 = Chop clock generator is selected as the chop clock source bit 1 CHOPHEN: PWMxH Output Chopping Enable bit 1 = PWMxH chopping function is enabled 0 = PWMxH chopping function is disabled CHOPLEN: PWMxL Output Chopping Enable bit bit 0 1 = PWMxL chopping function is enabled 0 = PWMxL chopping function is disabled

REGISTER 16-27: PWMCAPx: PWMx PRIMARY TIME BASE CAPTURE REGISTER (x = 1 to 8)

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			PWMCAF	<12:5> ^(1,2,3,4)			
bit 15	bit 15						
R-0	R-0	R-0	R-0	R-0	U-0	U-0	U-0
	PW	MCAP<4:0> ^{(1,2,}	3,4)		—		—
bit 7						-	bit 0
Legend:							
R = Readable bit		W = Writable b	it	U = Unimplem	nented bit, read	d as '0'	

bit 15-3 **PWMCAP<12:0>:** PWMx Primary Time Base Capture Value bits^(1,2,3,4) The value in this register represents the captured PWMx time base value when a leading edge is detected on the current-limit input.

'0' = Bit is cleared

x = Bit is unknown

bit 2-0 Unimplemented: Read as '0'

-n = Value at POR

Note 1: The capture feature is only available on a primary output (PWMxH).

'1' = Bit is set

2: This feature is active only after LEB processing on the current-limit input signal is complete.

3: The minimum capture resolution is 8.32 ns.

4: This feature can be used when the XPRES bit (PWMCONx<1>) is set to '0'.

NOTES:

17.0 PERIPHERAL TRIGGER GENERATOR (PTG) MODULE

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Peripheral Trigger Generator (PTG)" (DS70000669) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

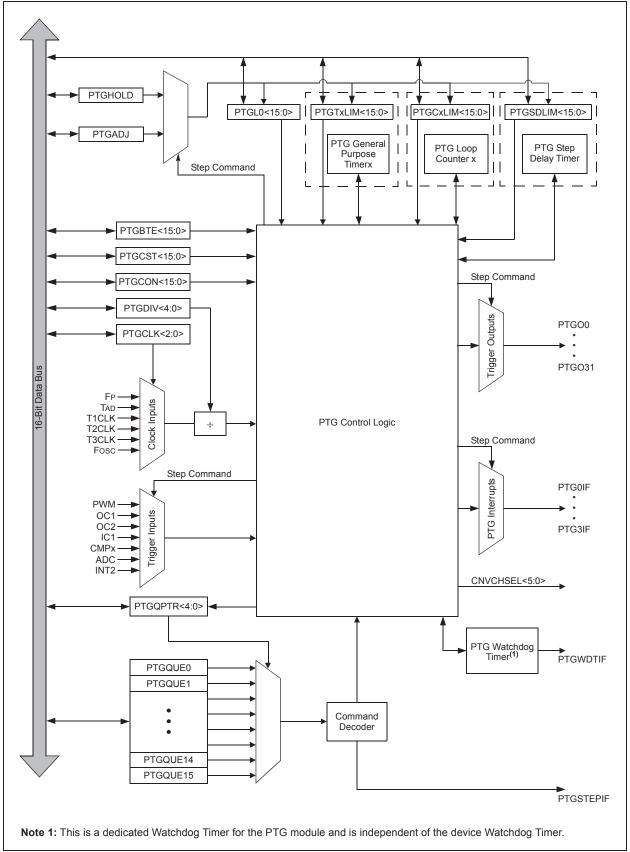
17.1 Module Introduction

The Peripheral Trigger Generator (PTG) provides a means to schedule complex, high-speed peripheral operations that would be difficult to achieve using software. The PTG module uses 8-bit commands, called "Steps", that the user writes to the PTG Queue register (PTGQUE0-PTQUE15) which performs operations, such as wait for input signal, generate output trigger and wait for timer.

The PTG module has the following major features:

- Multiple Clock Sources
- Two 16-Bit General Purpose Timers
- Two 16-Bit General Limit Counters
- Configurable for Rising or Falling Edge Triggering
- Generates Processor Interrupts to include:
 - Four configurable processor interrupts
 - Interrupt on a Step event in Single-Step modeInterrupt on a PTG Watchdog Timer time-out
- Able to Receive Trigger Signals from these Peripherals:
 - ADC
 - PWM
 - Output Compare
 - Input Capture
 - Comparator
 - INT2
- Able to Trigger or Synchronize to these Peripherals:
 - Watchdog Timer
 - Output Compare
 - Input Capture
 - ADC
 - PWM
 - Comparator





17.2 PTG Control Registers

REGISTER 17-1: PTGCST: PTG CONTROL/STATUS REGISTER

	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0			
PTGEN		PTGSIDL	PTGTOGL		PTGSWT ⁽²⁾	PTGSSEN	PTGIVIS			
bit 15							bit			
R/W-0	HS-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0			
PTGSTRT	PTGWDTO					PTGITM1 ⁽¹⁾	PTGITM0 ⁽¹			
bit 7							bit			
Legend:		HS = Hardware	e Settable bit							
R = Readable	bit	W = Writable b	it	U = Unimple	mented bit, rea	d as '0'				
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	nown			
bit 15		G Module Enable	e bit							
		dule is enabled dule is disabled								
bit 14	Unimplemen	ted: Read as '0	3							
bit 13	PTGSIDL: P	TG Stop in Idle N	Node bit							
	 1 = Discontinues module operation when device enters Idle mode 0 = Continues module operation in Idle mode 									
		•								
bit 12	PTGTOGL: PTG TRIG Output Toggle Mode bit									
	 1 = Toggles the state of the PTGOx for each execution of the PTGTRIG command 0 = Each execution of the PTGTRIG command will generate a single PTGOx pulse determined by the 									
		ecunion of the Pi	GTRIG COMME	and will genera	ate a single PT(GOx pulse dete	rmined by th			
		the PTGPWDx b		and will genera	ate a single PT0	GOx pulse dete	rmined by th			
bit 11	value in t		oits	and will genera	ate a single PT0	GOx pulse dete	rmined by th			
bit 11 bit 10	value in t Unimplemen	the PTGPWDx b	, ,	and will genera	ate a single PTC	GOx pulse dete	rmined by th			
	value in t Unimplemen PTGSWT: PT 1 = Triggers t	the PTGPWDx t Ited: Read as '0 IG Software Trig the PTG module	pits , ger bit ⁽²⁾	-	ate a single PTC	GOx pulse dete	rmined by th			
bit 10	value in t Unimplemen PTGSWT: PT 1 = Triggers t 0 = No action	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module n (clearing this bi	bits , iger bit ⁽²⁾ it will have no e	-	ate a single PTC	GOx pulse dete	rmined by th			
bit 10	value in t Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module n (clearing this bi PTG Enable Sing	bits , iger bit ⁽²⁾ it will have no e gle-Step bit	-	ate a single PTC	GOx pulse dete	rmined by th			
bit 10	value in t Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F 1 = Enables S	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module n (clearing this bi PTG Enable Sing Single-Step mod	bits , gger bit ⁽²⁾ it will have no e gle-Step bit le	-	ate a single PTC	GOx pulse dete	rmined by th			
bit 10 bit 9	value in f Unimplement PTGSWT: PT 1 = Triggers to 0 = No action PTGSSEN: PT 1 = Enables S 0 = Disables	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module o (clearing this bio PTG Enable Sing Single-Step mod Single-Step mod	bits , gger bit ⁽²⁾ it will have no e gle-Step bit le de	effect)	ate a single PTC	GOx pulse dete	rmined by th			
	value in t Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: PT 1 = Enables 0 = Disables PTGIVIS: PT	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module o (clearing this bi PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time	bits ger bit ⁽²⁾ it will have no e gle-Step bit le de r Visibility Cont	effect)	-					
bit 10 bit 9	value in f Unimplement PTGSWT: PT 1 = Triggers to 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads o correspo	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module (clearing this bi PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time of the PTGSDLII onding Counter/T	bits ger bit ⁽²⁾ it will have no e gle-Step bit le de vr Visibility Cont M, PTGCxLIM imer registers	effect) trol bit or PTGTxLIM (PTGSD, PTG	registers retur Cx, PTGTx)	n the current v	values of the			
bit 10 bit 9	value in f Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of 0 = Reads of	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module of (clearing this bit PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time of the PTGSDLIM onding Counter/T f the PTGSDLIM	bits ger bit ⁽²⁾ it will have no e gle-Step bit le r Visibility Cont M, PTGCxLIM Timer registers I, PTGCxLIM of	effect) trol bit or PTGTxLIM (PTGSD, PTG	registers retur Cx, PTGTx)	n the current v	values of the			
bit 10 bit 9 bit 8	value in f Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of correspo 0 = Reads of those PT	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module of (clearing this bit PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time of the PTGSDLIM onding Counter/T f the PTGSDLIM IG Limit register	bits ger bit ⁽²⁾ it will have no e gle-Step bit le r Visibility Cont M, PTGCxLIM imer registers I, PTGCxLIM of s	effect) trol bit or PTGTxLIM (PTGSD, PTG	registers retur Cx, PTGTx)	n the current v	values of the			
bit 10 bit 9 bit 8	value in f Unimplement PTGSWT: PT 1 = Triggers to 0 = No action PTGSSEN: PT 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of correspon 0 = Reads of those PT PTGSTRT: S	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module of (clearing this bit PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time of the PTGSDLIM onding Counter/T f the PTGSDLIM IG Limit register tart PTG Seque	bits ger bit ⁽²⁾ it will have no e gle-Step bit le de r Visibility Cont M, PTGCxLIM Timer registers I, PTGCxLIM of s ncer bit	effect) trol bit or PTGTxLIM (PTGSD, PTG r PTGTxLIM re	registers retur Cx, PTGTx) egisters return t	n the current v	values of the			
bit 10 bit 9 bit 8	value in f Unimplement PTGSWT: PT 1 = Triggers to 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of correspo 0 = Reads of those PT PTGSTRT: S 1 = Starts to s	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module of (clearing this bit PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time of the PTGSDLIM onding Counter/T f the PTGSDLIM IG Limit register	bits ger bit ⁽²⁾ it will have no e gle-Step bit le de r Visibility Cont M, PTGCxLIM Timer registers I, PTGCxLIM of s ncer bit cute command	effect) trol bit or PTGTxLIM (PTGSD, PTG r PTGTxLIM re	registers retur Cx, PTGTx) egisters return t	n the current v	values of the			
bit 10 bit 9	value in f Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of correspon 0 = Reads of those PT PTGSTRT: S 1 = Starts to s 0 = Stops exe	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module of (clearing this bit PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time of the PTGSDLIM onding Counter/T f the PTGSDLIM IG Limit register tart PTG Sequel sequentially exe	bits ger bit ⁽²⁾ it will have no e gle-Step bit le r Visibility Cont M, PTGCxLIM Timer registers I, PTGCxLIM of s ncer bit cute command ds	effect) trol bit or PTGTxLIM (PTGSD, PTG r PTGTxLIM re s (Continuous	registers retur Cx, PTGTx) egisters return t	n the current v	values of the			
bit 10 bit 9 bit 8 bit 7	value in f Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of correspon 0 = Reads of those PT PTGSTRT: S 1 = Starts to s 0 = Stops exe PTGWDTO: 1 1 = PTG Wat	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module (clearing this bi PTG Enable Sing Single-Step mod G Counter/Time of the PTGSDLIM IG Limit register tart PTG Sequel sequentially exe ecuting comman PTG Watchdog Time has tard Sequentially exe	bits ger bit ⁽²⁾ it will have no e gle-Step bit le r Visibility Cont M, PTGCxLIM Timer registers I, PTGCxLIM of s ncer bit cute command ds Timer Time-out s timed out	effect) trol bit or PTGTxLIM (PTGSD, PTG r PTGTxLIM re s (Continuous t Status bit	registers retur Cx, PTGTx) egisters return t	n the current v	values of the			
bit 10 bit 9 bit 8 bit 7	value in f Unimplement PTGSWT: PT 1 = Triggers t 0 = No action PTGSSEN: F 1 = Enables S 0 = Disables PTGIVIS: PT 1 = Reads of correspo 0 = Reads of those PT PTGSTRT: S 1 = Starts to s 0 = Stops exe PTGWDTO: I 1 = PTG Wat 0 = PTG Wat	the PTGPWDx b nted: Read as '0 IG Software Trig the PTG module (clearing this bi PTG Enable Sing Single-Step mod Single-Step mod G Counter/Time onding Counter/Time onding Counter/Time f the PTGSDLIM IG Limit register tart PTG Sequentially exe ecuting comman PTG Watchdog	bits ger bit ⁽²⁾ it will have no e gle-Step bit le de r Visibility Cont M, PTGCxLIM imer registers I, PTGCxLIM of s ncer bit cute command ds Timer Time-out s timed out s not timed out.	effect) trol bit or PTGTxLIM (PTGSD, PTG r PTGTxLIM re s (Continuous t Status bit	registers retur Cx, PTGTx) egisters return t	n the current v	values of the			

2: This bit is only used with the PTGCTRL Step command software trigger option.

REGISTER 17-1: PTGCST: PTG CONTROL/STATUS REGISTER (CONTINUED)

- bit 1-0 **PTGITM<1:0>:** PTG Input Trigger Command Operating Mode bits⁽¹⁾
 - 11 = Single level detect with Step delay is not executed on exit of command (regardless of PTGCTRL command)
 - 10 = Single level detect with Step delay is executed on exit of command
 - 01 = Continuous edge detect with Step delay is not executed on exit of command (regardless of PTGCTRL command)
 - 00 = Continuous edge detect with Step delay is executed on exit of command
- Note 1: These bits apply to the PTGWHI and PTGWLO commands only.
 - **2:** This bit is only used with the PTGCTRL Step command software trigger option.

REGISTER	-2. FIGU		NIROL REG	ISTER			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGCLK2	PTGCLK1	PTGCLK0	PTGDIV4	PTGDIV3	PTGDIV2	PTGDIV1	PTGDIV0
bit 15	•		·				bit 8
R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
PTGPWD3	PTGPWD2	PTGPWD1	PTGPWD0	—	PTGWDT2	PTGWDT1	PTGWDT0
bit 7		-	·				bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimplei	mented bit, read	as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkn	iown
bit 15-13 bit 12-8	111 = CLC2 110 = CLC1 101 = PTG m 100 = PTG m 011 = PTG m 010 = PTG m 001 = PTG m	 Select PTG odule clock so 	urce will be T3 urce will be T2 urce will be T1 urce will be T4 urce will be F6 urce will be F6	BCLK CLK CLK D DSC	ts		
	11111 = Divid 11110 = Divid • • • • • • • • • • • • • • • • • • •	de-by-31 de-by-2					
bit 7-4	1111 = All trig 1110 = All trig • • • • • •	0>: PTG Trigge gger outputs ar gger outputs ar gger outputs ar gger outputs ar	e 16 PTG cloc e 15 PTG cloc e 2 PTG clock	k cycles wide k cycles wide cycles wide			
bit 3	Unimplemen	ted: Read as '	0'				
bit 2-0	-			ner Time-out	Count Value bit	S	
	111 = Watcho 110 = Watcho 101 = Watcho 010 = Watcho 011 = Watcho 010 = Watcho 001 = Watcho	dog Timer will t dog Timer is dis	ime-out after 5 ime-out after 2 ime-out after 1 ime-out after 6 ime-out after 3 ime-out after 1 ime-out after 8	12 PTG clock 56 PTG clock 28 PTG clock 4 PTG clocks 2 PTG clocks 6 PTG clocks 6 PTG clocks	55 55 55		

REGISTER 17-2: PTGCON: PTG CONTROL REGISTER

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
	_	_	ADCTS1	IC4TSS	IC3TSS	IC2TSS	IC1TSS					
bit 15					1		bit					
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
OC4CS	OC3CS	OC2CS	OC1CS	OC4TSS	OC3TSS	OC2TSS	OC1TSS					
bit 7	00303	00203	00103	004133	003133	002100	bit					
Legend:												
R = Readable	e bit	W = Writable	bit	U = Unimple	mented bit, read	l as '0'						
-n = Value at	POR	'1' = Bit is se	t	'0' = Bit is cle	ared	x = Bit is unkr	nown					
bit 15-13	Unimplemen	ted: Read as	ʻ0 '									
bit 12	ADCTS1: Sa	mple Trigger F	TGO12 for AE	OCx bit								
			the broadcast									
		• ••			nand is execute	d						
bit 11			zation Source									
		1 = Generates trigger/synchronization when the broadcast command is executed										
bit 10		 Does not generate trigger/synchronization when the broadcast command is executed IC3TSS: Trigger/Synchronization Source for IC3 bit 										
DIL TU		1 = Generates trigger/synchronization when the broadcast command is executed										
							ed					
bit 9		 Does not generate trigger/synchronization when the broadcast command is executed IC2TSS: Trigger/Synchronization Source for IC2 bit 										
bit o	1 = Generate	s trigger/synch	nronization whe	en the broadca	ast command is broadcast com		ed					
bit 8		 Does not generate trigger/synchronization when the broadcast command is executed IC1TSS: Trigger/Synchronization Source for IC1 bit 										
	1 = Generate	s trigger/synch	nronization whe	en the broadca	ast command is broadcast com		ed					
bit 7		es not generate trigger/synchronization when the broadcast command is executed : Clock Source for OC4 bit										
			when the broad k pulse when t			cuted						
bit 6		 Does not generate clock pulse when the broadcast command is executed OC3CS: Clock Source for OC3 bit 										
	1 = Generate	s clock pulse v	when the broad		d is executed command is exe	cuted						
bit 5		-	-									
	1 = Generate	OC2CS: Clock Source for OC2 bit 1 = Generates clock pulse when the broadcast command is executed										
		0 = Does not generate clock pulse when the broadcast command is executed										
bit 4	OC1CS: Cloc	k Source for C	DC1 bit									
			when the broad k pulse when t		d is executed command is exe	cuted						
bit 3	OC4TSS: Trig	gger/Synchron	ization Source	for OC4 bit								
					ast command is broadcast com		ed					
bit 2	OC3TSS: Trig	gger/Synchron	ization Source	for OC3 bit								
					ast command is broadcast com		ed					
	nis register is rea ΓGSTRT = 1).	id-only when t	ne PTG modul	e is executing	Step commands	s (PTGEN = 1 a	and					
	,	v used with the		DETON - 1111	Stop command							

REGISTER 17-3: PTGBTE: PTG BROADCAST TRIGGER ENABLE REGISTER^(1,2)

2: This register is only used with the PTGCTRL OPTION = 1111 Step command.

REGISTER 17-3: PTGBTE: PTG BROADCAST TRIGGER ENABLE REGISTER^(1,2) (CONTINUED)

bit 1	OC2TSS: Trigger/Synchronization Source for OC2 bit
	1 = Generates trigger/synchronization when the broadcast command is executed
	0 = Does not generate trigger/synchronization when the broadcast command is executed
bit 0	OC1TSS: Trigger/Synchronization Source for OC1 bit
	1 = Generates trigger/synchronization when the broadcast command is executed

- 1 = Generates trigger/synchronization when the broadcast command is executed
 0 = Does not generate trigger/synchronization when the broadcast command is executed
- **Note 1:** This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).
 - 2: This register is only used with the PTGCTRL OPTION = 1111 Step command.

REGISTER 17-4: PTGT0LIM: PTG TIMER0 LIMIT REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PTGT0	LIM<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PTGT)LIM<7:0>				
bit 7							bit 0	
Legend:								
R = Readable	bit	W = Writable b	it	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is			x = Bit is unki	nown				

bit 15-0 **PTGT0LIM<15:0>:** PTG Timer0 Limit Register bits

General purpose Timer0 Limit register (effective only with a ${\tt PTGT0}$ Step command).

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-5: PTGT1LIM: PTG TIMER1 LIMIT REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
PTGT1LIM<15:8>								
bit 15							bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
PTGT1LIM<7:0>									
bit 7							bit 0		

Legend:				
R = Readable bit	dable bit W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

- bit 15-0 **PTGT1LIM<15:0>:** PTG Timer1 Limit Register bits General purpose Timer1 Limit register (effective only with a PTGT1 Step command).
- **Note 1:** This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-6: PTGSDLIM: PTG STEP DELAY LIMIT REGISTER^(1,2)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGSDL	IM<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGSDI	_IM<7:0>			
bit 7							bit 0
bit 7			PTGSDI	_IM<7:0>			

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **PTGSDLIM<15:0>:** PTG Step Delay Limit Register bits Holds a PTG Step delay value, representing the number of additional PTG clocks, between the start of a Step command and the completion of a Step command.

- **Note 1:** A base Step delay of one PTG clock is added to any value written to the PTGSDLIM register (Step Delay = (PTGSDLIM) + 1).
 - 2: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-7: PTGC0LIM: PTG COUNTER 0 LIMIT REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
			PTGC0L	_IM<15:8>							
bit 15	bit 15 bit 8										
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
			PTGC0	LIM<7:0>							
bit 7							bit 0				
Legend:											
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'											

bit 15-0 PTGC0LIM<15:0>: PTG Counter 0 Limit Register bits

'1' = Bit is set

May be used to specify the loop count for the PTGJMPC0 Step command or as a limit register for the General Purpose Counter 0.

'0' = Bit is cleared

-n = Value at POR

x = Bit is unknown

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-8: PTGC1LIM: PTG COUNTER 1 LIMIT REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PTGC1	LIM<15:8>				
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			PTGC ²	1LIM<7:0>				
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			t	U = Unimplemented bit, read as '0'				
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unkı	nown	

bit 15-0 **PTGC1LIM<15:0>:** PTG Counter 1 Limit Register bits May be used to specify the loop count for the PTGJMPC1 Step command or as a limit register for the General Purpose Counter 1.

REGISTER 17-9: PTGHOLD: PTG HOLD REGISTER⁽¹⁾

'1' = Bit is set

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGHC)LD<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGH	OLD<7:0>			
bit 7							bit 0
Legend:							
R = Readable b	bit	W = Writable bit	:	U = Unimpler	mented bit, read	l as '0'	

bit 15-0 **PTGHOLD<15:0>:** PTG General Purpose Hold Register bits Holds user-supplied data to be copied to the PTGTxLIM, PTGCxLIM, PTGSDLIM or PTGL0 register with the PTGCOPY command.

'0' = Bit is cleared

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

-n = Value at POR

x = Bit is unknown

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-10: PTGADJ: PTG ADJUST REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGA	DJ<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGA	\DJ<7:0>			
bit 7							bit 0
Legend:							
R = Readable bi	it	W = Writable bit	t	U = Unimpler	mented bit, read	l as '0'	

R = Readable bit	vv = vvntable bit	O = Onimplemented bit, read	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **PTGADJ<15:0>:** PTG Adjust Register bits This register holds user-supplied data to be added to the PTGTxLIM, PTGCxLIM, PTGSDLIM or PTGL0 register with the PTGADD command.

REGISTER 17-11: PTGL0: PTG LITERAL 0 REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGL0)<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTGL	0<7:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **PTGL0<15:0>:** PTG Literal 0 Register bits

This register holds the 6-bit value to be written to the CNVCHSEL<5:0> bits (ADCON3L<5:0>) with the PTGCTRL Step command.

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-12: PTGQPTR: PTG STEP QUEUE POINTER REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	_	—	—	—
bit 15	•	•		•			bit 8
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—			PTGQPTR<4:0	>	
bit 7	•	•					bit 0
Legend:							
R = Readable b	bit W = Writable bit U = Unimplemented bit, read as '0'						
-n = Value at P	OR	'1' = Bit is set	t '0' = Bit is cleared x = Bit is unknown			nown	

bit 15-5 Unimplemented: Read as '0'

bit 4-0 **PTGQPTR<4:0>:** PTG Step Queue Pointer Register bits This register points to the currently active Step command in the Step queue.

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 17-13: PTGQUEX: PTG STEP QUEUE REGISTER x (x = 0-15)^(1,3)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
1011 0	1011 0	10110		- 1)<7:0> ⁽²⁾	1011 0		10110
bit 15				1) 11.0			bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STEP(2x)<7:0> ⁽²⁾							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8STEP(2x + 1)<7:0>: PTG Step Queue Pointer Register bits⁽²⁾
A queue location for storage of the STEP(2x +1) command byte.bit 7-0STEP(2x)<7:0>: PTG Step Queue Pointer Register bits⁽²⁾

A queue location for storage of the STEP(2x) command byte.

- **Note 1:** This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).
 - 2: Refer to Table 17-1 for the Step command encoding.
 - 3: The Step registers maintain their values on any type of Reset.

17.3 Step Commands and Format

TABLE 17-1: PTG STEP COMMAND FORMAT

Step Command Byte:			
	STEPx<7:0>		
CMD<3:0	>	OPTION<3:0>	
bit 7	bit 4 bit 3		bit 0

bit 7-4	CMD<3:0>	Step Command	Command Description
	0000	PTGCTRL	Execute control command as described by OPTION<3:0>
	0001	PTGADD	Add contents of PTGADJ register to target register as described by OPTION<3:0>
		PTGCOPY	Copy contents of PTGHOLD register to target register as described by OPTION<3:0>
	001x	PTGSTRB	Copy the value contained in CMD0:OPTION<3:0> to the CNVCHSEL<5:0> bits (ADCON3L<5:0>)
	0100	PTGWHI	Wait for a low-to-high edge input from selected PTG trigger input as described by OPTION<3:0>
	0101	PTGWLO	Wait for a high-to-low edge input from selected PTG trigger input as described by OPTION<3:0>
	0110	Reserved	Reserved
	0111	PTGIRQ	Generate individual interrupt request as described by OPTION<3:0>
	100x	PTGTRIG	Generate individual trigger output as described by < <cmd0>:OPTION<3:0>></cmd0>
	101x	PTGJMP	Copy the value indicated in < <cmd0>:OPTION<3:0>> to the PTG Queue Pointer (PTGQPTR) and jump to that Step queue</cmd0>
	110x	PTGJMPC0	PTGC0 = PTGC0LIM: Increment the PTG Queue Pointer (PTGQPTR)
			$PTGC0 \neq PTGC0LIM$: Increment PTG Counter 0 (PTGC0) and copy the value indicated in < <cmd0>:OPTION<3:0>> to the PTG Queue Pointer (PTGQPTR) and jump to that Step queue</cmd0>
	111x	PTGJMPC1	PTGC1 = PTGC1LIM: Increment the PTG Queue Pointer (PTGQPTR)
			PTGC1 \neq PTGC1LIM: Increment PTG Counter 1 (PTGC1) and copy the value indicated in < <cmd0>:OPTION<3:0>> to the PTG Queue Pointer (PTGQPTR) and jump to that Step queue</cmd0>

Note 1: All reserved commands or options will execute but have no effect (i.e., execute as a NOP instruction).

2: Refer to Table 17-2 for the trigger output descriptions.

3-0	Step Command	OPTION<3:0>	Option Description
	PTGCTRL ⁽¹⁾	0000	Reserved
		0001	Reserved
		0010	Disable PTG Step Delay Timer (PTGSD)
		0011	Reserved
		0100	Reserved
		0101	Reserved
		0110	Enable PTG Step Delay Timer (PTGSD)
		0111	Reserved
		1000	Start and wait for the PTG Timer0 to match the PTG Timer0 Limit register
		1001	Start and wait for the PTG Timer1 to match the PTG Timer1 Limit register
		1010	Reserved
		1011	Wait for software trigger bit transition from low-to-high before continuing (PTGSWT = 0 to 1)
		1100	Copy contents of the PTG Counter 0 register to the CNVCHSEL<5:0> bits (ADCON3L<5:0>)
		1101	Copy contents of the PTG Counter 1 register to the CNVCHSEL<5:0> bits (ADCON3L<5:0>)
		1110	Copy contents of the PTG Literal 0 register to the CNVCHSEL<5:0> bits (ADCON3L<5:0>)
		1111	Generate the triggers indicated in the PTG Broadcast Trigger Enable register (PTGBTE)
	PTGADD ⁽¹⁾	0000	Add contents of PTGADJ register to the PTG Counter 0 Limit register (PTGC0L
		0001	Add contents of PTGADJ register to the PTG Counter 1 Limit register (PTGC1L
		0010	Add contents of PTGADJ register to the PTG Timer0 Limit register (PTGT0LIM)
		0011	Add contents of PTGADJ register to the PTG Timer1 Limit register (PTGT1LIM
		0100	Add contents of PTGADJ register to the PTG Step Delay Limit register (PTGSDLIM)
		0101	Add contents of PTGADJ register to the PTG Literal 0 register (PTGL0)
		0110	Reserved
		0111	Reserved
	PTGCOPY ⁽¹⁾	1000	Copy contents of PTGHOLD register to the PTG Counter 0 Limit register (PTGC0LIM)
		1001	Copy contents of PTGHOLD register to the PTG Counter 1 Limit register (PTGC1LIM)
		1010	Copy contents of PTGHOLD register to the PTG Timer0 Limit register (PTGT0L
		1011	Copy contents of PTGHOLD register to the PTG Timer1 Limit register (PTGT1L
		1100	Copy contents of PTGHOLD register to the PTG Step Delay Limit register (PTGSDLIM)
		1101	Copy contents of PTGHOLD register to the PTG Literal 0 register (PTGL0)
		1110	Reserved
		1111	Reserved

TABLE 17-1: PTG STEP COMMAND FORMAT (CONTINUED)

Note 1: All reserved commands or options will execute but have no effect (i.e., execute as a NOP instruction).

2: Refer to Table 17-2 for the trigger output descriptions.

bit 3-0	Step Command	OPTION<3:0>	Option Description	
	PTGWHI(1) or	0000	PWM Special Event Trigger	
	PTGWLO(1)	0001	PWM master time base synchronization output	
		0010	PWM1 interrupt	
		0011	PWM2 interrupt	
		0100	PWM3 interrupt	
		0101	PWM4 interrupt	
		0110	PWM5 interrupt	
		0111	OC1 trigger event	
		1000	OC2 trigger event	
		1001	IC1 trigger event	
		1010	CMP1 trigger event	
		1011	CMP2 trigger event	
		1100 1101 1110	CMP3 trigger event	
			CMP4 trigger event	
			ADC conversion done interrupt	
		1111	INT2 external interrupt	
	PTGIRQ ⁽¹⁾	0000	Generate PTG Interrupt 0	
		0001	Generate PTG Interrupt 1	
		0010	Generate PTG Interrupt 2	
		0011	Generate PTG Interrupt 3	
		0100	Reserved	
		•	•	
		•	•	
		1111	Reserved	
	PTGTRIG ⁽²⁾	00000	PTGO0	
	11011(10	00001	PTGO1	
		•	•	
		•	•	
		•	•	
		11110	PTGO30	
		11111	PTGO31	

TABLE 17-1: PTG STEP COMMAND FORMAT (CONTINUED)

Note 1: All reserved commands or options will execute but have no effect (i.e., execute as a NOP instruction).

2: Refer to Table 17-2 for the trigger output descriptions.

PTG Output Number	PTG Output Description
PTGO0	Trigger/synchronization source for OC1
PTGO1	Trigger/synchronization source for OC2
PTGO2	Trigger/synchronization source for OC3
PTGO3	Trigger/synchronization source for OC4
PTGO4	Clock source for OC1
PTGO5	Clock source for OC2
PTGO6	Clock source for OC3
PTGO7	Clock source for OC4
PTGO8	Trigger/synchronization source for IC1
PTGO9	Trigger/synchronization source for IC2
PTGO10	Trigger/synchronization source for IC3
PTGO11	Trigger/synchronization source for IC4
PTGO12	Sample trigger for ADC
PTGO13	Reserved
PTGO14	Reserved
PTGO15	Reserved
PTGO16	PWM time base synchronous source for PWM3
PTGO17	PWM time base synchronous source for PWM4
PTGO18	Reserved
PTGO19	Reserved
PTGO20	Reserved
PTGO21	Reserved
PTGO22	Reserved
PTGO23	Reserved
PTGO24	Reserved
PTGO25	Reserved
PTGO26	CLC1 input
PTGO27	CLC2 input
PTGO28	CLC3 input
PTGO29	CLC4 input
PTGO30	PTG output to PPS input selection, RPI6
PTGO31	PTG output to PPS input selection, RPI7

TABLE 17-2: PTG OUTPUT DESCRIPTIONS

18.0 SERIAL PERIPHERAL INTERFACE (SPI)

Note: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Serial Peripheral Interface (SPI) with Audio Codec Support" (DS70005136) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).

The Serial Peripheral Interface (SPI) module is a synchronous serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, shift registers, display drivers, A/D Converters, etc. The SPI module is compatible with the Motorola[®] SPI and SIOP interfaces. All devices in the dsPIC33EPXXXGS70X/80X family include three SPI modules.

The module supports operation in two buffer modes. In Standard mode, data is shifted through a single serial buffer. In Enhanced Buffer mode, data is shifted through a FIFO buffer. The FIFO level depends on the configured mode.

Variable length data can be transmitted and received, from 2 to 32 bits.

Note:	Do not perform Read-Modify-Write opera-
	tions (such as bit-oriented instructions) on
	the SPIxBUF register in either Standard or
	Enhanced Buffer mode.

The module also supports a basic framed SPI protocol while operating in either Master or Slave mode. A total of four framed SPI configurations are supported.

SPI3 also supports Audio modes. Four different Audio modes are available.

- I²S
- · Left Justified
- Right Justified
- PCM/DSP

In each of these modes, the serial clock is free-running and audio data is always transferred.

If an audio protocol data transfer takes place between two devices, then usually one device is the master and the other is the slave. However, audio data can be transferred between two slaves. Because the audio protocols require free-running clocks, the master can be a third party controller. In either case, the master generates two free-running clocks: SCKx and LRC (Left, Right Channel Clock/SSx/FSYNC). The SPI serial interface consists of four pins:

- SDIx: Serial Data Input
- SDOx: Serial Data Output
- SCKx: Shift Clock Input or Output
- SSx: Active-Low Slave Select or Frame Synchronization I/O Pulse

The SPI module can be configured to operate using two, three or four pins. In the 3-pin mode, \overline{SSx} is not used. In the 2-pin mode, both SDOx and \overline{SSx} are not used.

The SPI module has the ability to generate three interrupts, reflecting the events that occur during the data communication. The following types of interrupts can be generated:

- 1. Receive interrupts are signalled by SPIxRXIF.
 - This event occurs when:
 - RX watermark interrupt
 - SPIROV = 1
 - SPIRBF = 1
 - SPIRBE = 1

provided the respective mask bits are enabled in SPIxIMSKL/H.

- 2. Transmit interrupts are signalled by SPIxTXIF. This event occurs when:
 - TX watermark interrupt
 - SPITUR = 1
 - SPITBF = 1
 - SPITBE = 1

provided the respective mask bits are enabled in SPIxIMSKL/H.

- 3. General interrupts are signalled by SPIxIF. This event occurs when
 - FRMERR = 1
 - SPIBUSY = 1
 - SRMT = 1

provided the respective mask bits are enabled in SPIxIMSKL/H.

Block diagrams of the module in Standard and Enhanced modes are shown in Figure 18-1 and Figure 18-2.

Note: In this section, the SPI modules are referred to together as SPIx, or separately as SPI1, SPI2 or SPI3. Special Function Registers will follow a similar notation. For example, SPIxCON1 and SPIxCON2 refer to the control registers for any of the three SPI modules.

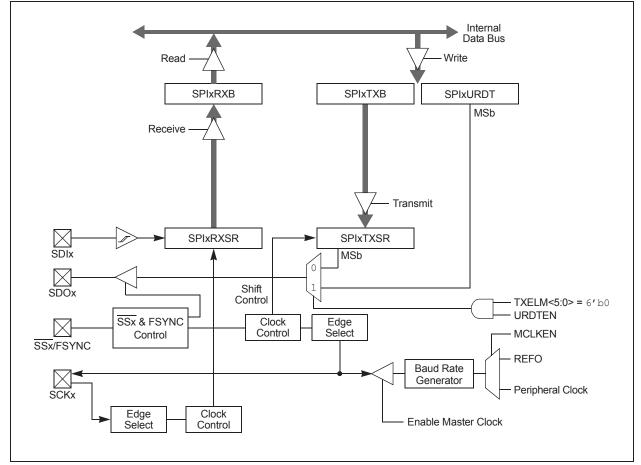
To set up the SPIx module for the Standard Master mode of operation:

- 1. If using interrupts:
 - a) Clear the interrupt flag bits in the respective IFSx register.
 - b) Set the interrupt enable bits in the respective IECx register.
 - c) Write the SPIxIP bits in the respective IPCx register to set the interrupt priority.
- Write the desired settings to the SPIxCON1L and SPIxCON1H registers with the MSTEN bit (SPIxCON1L<5>) = 1.
- 3. Clear the SPIROV bit (SPIxSTATL<6>).
- 4. Enable SPIx operation by setting the SPIEN bit (SPIxCON1L<15>).
- 5. Write the data to be transmitted to the SPIxBUFL and SPIxBUFH registers. Transmission (and reception) will start as soon as data is written to the SPIxBUFL and SPIxBUFH registers.

To set up the SPIx module for the Standard Slave mode of operation:

- 1. Clear the SPIxBUF registers.
- 2. If using interrupts:
 - a) Clear the SPIxBUFL and SPIxBUFH registers.
 - b) Set the interrupt enable bits in the respective IECx register.
 - c) Write the SPIxIP bits in the respective IPCx register to set the interrupt priority.
- Write the desired settings to the SPIxCON1L, SPIxCON1H and SPIxCON2L registers with the MSTEN bit (SPIxCON1L<5>) = 0.
- 4. Clear the SMP bit.
- If the CKE bit (SPIxCON1L<8>) is set, then the SSEN bit (SPIxCON1L<7>) must be set to enable the SSx pin.
- 6. Clear the SPIROV bit (SPIxSTATL<6>).
- Enable SPIx operation by setting the SPIEN bit (SPIxCON1L<15>).

FIGURE 18-1: SPIx MODULE BLOCK DIAGRAM (STANDARD MODE)



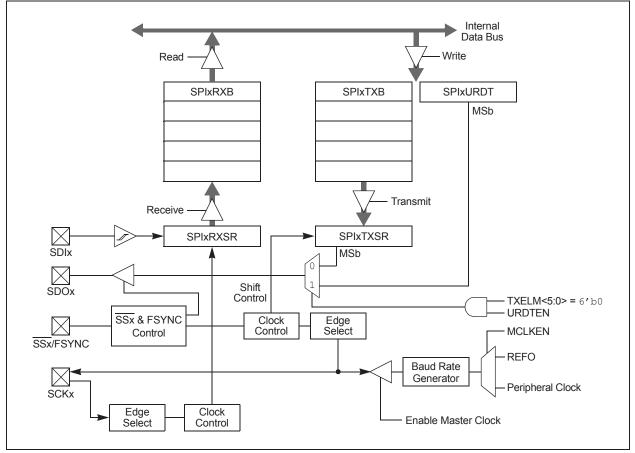
To set up the SPIx module for the Enhanced Buffer Master mode of operation:

- 1. If using interrupts:
 - a) Clear the interrupt flag bits in the respective IFSx register.
 - b) Set the interrupt enable bits in the respective IECx register.
 - c) Write the SPIxIP bits in the respective IPCx register.
- Write the desired settings to the SPIxCON1L, SPIxCON1H and SPIxCON2L registers with MSTEN (SPIxCON1L<5>) = 1.
- 3. Clear the SPIROV bit (SPIxSTATL<6>).
- 4. Select Enhanced Buffer mode by setting the ENHBUF bit (SPIxCON1L<0>).
- 5. Enable SPIx operation by setting the SPIEN bit (SPIxCON1L<15>).
- Write the data to be transmitted to the SPIxBUFL and SPIxBUFH registers. Transmission (and reception) will start as soon as data is written to the SPIxBUFL and SPIxBUFH registers.

To set up the SPIx module for the Enhanced Buffer Slave mode of operation:

- 1. Clear the SPIxBUFL and SPIxBUFH registers.
- 2. If using interrupts:
 - a) Clear the interrupt flag bits in the respective IFSx register.
 - b) Set the interrupt enable bits in the respective IECx register.
 - c) Write the SPIxIP bits in the respective IPCx register to set the interrupt priority.
- Write the desired settings to the SPIxCON1L, SPIxCON1H and SPIxCON2L registers with the MSTEN bit (SPIxCON1L<5>) = 0.
- 4. Clear the SMP bit.
- 5. If the CKE bit is set, then the SSEN bit must be set, thus enabling the SSx pin.
- 6. Clear the SPIROV bit (SPIxSTATL<6>).
- 7. Select Enhanced Buffer mode by setting the ENHBUF bit (SPIxCON1L<0>).
- 8. Enable SPIx operation by setting the SPIEN bit (SPIxCON1L<15>).





To set up the SPIx module for Audio mode:

- 1. Clear the SPIxBUFL and SPIxBUFH registers.
- 2. If using interrupts:
 - a) Clear the interrupt flag bits in the respective IFSx register.
 - b) Set the interrupt enable bits in the respective IECx register.
 - a) Write the SPIxIP bits in the respective IPCx register to set the interrupt priority.
- Write the desired settings to the SPIxCON1L, SPIxCON1H and SPIxCON2L registers with AUDEN (SPIxCON1H<15>) = 1.
- 4. Clear the SPIROV bit (SPIxSTATL<6>).
- 5. Enable SPIx operation by setting the SPIEN bit (SPIxCON1L<15>).
- 6. Write the data to be transmitted to the SPIxBUFL and SPIxBUFH registers. Transmission (and reception) will start as soon as data is written to the SPIxBUFL and SPIxBUFH registers.

REGISTER 18-1: SPIxCON1L: SPIx CONTROL REGISTER 1 LOW

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SPIEN	—	SPISIDL	DISSDO	MODE32 ^(1,4)	MODE16 ^(1,4)	SMP	CKE ⁽¹⁾
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEN ⁽²⁾	CKP	MSTEN	DISSDI	DISSCK	MCLKEN ⁽³⁾	SPIFE	ENHBUF
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable I	bit	U = Unimplem	nented bit, read	as '0'	

			4 45 0
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 SPIEN: SPIx On bit

- 1 = Enables module
- 0 = Turns off and resets module, disables clocks, disables interrupt event generation, allows SFR modifications
- bit 14 Unimplemented: Read as '0'
- bit 13 SPISIDL: SPIx Stop in Idle Mode bit
 - 1 = Halts in CPU Idle mode
 - 0 = Continues to operate in CPU Idle mode

bit 12 **DISSDO:** Disable SDOx Output Port bit

- 1 = SDOx pin is not used by the module; pin is controlled by port function
- 0 = SDOx pin is controlled by the module

bit 11-10 **MODE32** and **MODE16**: Serial Word Length Select bits^(1,4)

MODE32	MODE16	AUDEN	Communication
1	X		32-Bit
0	1	0	16-Bit
0	0		8-Bit
1	1		24-Bit Data, 32-Bit FIFO, 32-Bit Channel/64-Bit Frame
1	0	1	32-Bit Data, 32-Bit FIFO, 32-Bit Channel/64-Bit Frame
0	1	1	16-Bit Data, 16-Bit FIFO, 32-Bit Channel/64-Bit Frame
0	0		16-Bit FIFO, 16-Bit Channel/32-Bit Frame

Note 1: When AUDEN (SPIxCON1H<15>) = 1, this module functions as if CKE = 0, regardless of its actual value.

- 2: When FRMEN = 1, SSEN is not used.
- 3: MCLKEN can only be written when the SPIEN bit = 0.
- 4: This channel is not meaningful for DSP/PCM mode as LRC follows FRMSYPW.

REGISTER 18-1: SPIx CONTROL REGISTER 1 LOW (CONTINUED)

bit 9	SMP: SPIx Data Input Sample Phase bit
	<u>Master Mode:</u> 1 = Input data is sampled at the end of data output time
	0 = Input data is sampled at the middle of data output time
	Slave Mode:
	Input data is always sampled at the middle of data output time, regardless of the SMP setting.
bit 8	CKE: SPIx Clock Edge Select bit ⁽¹⁾
	 1 = Transmit happens on transition from active clock state to Idle clock state 0 = Transmit happens on transition from Idle clock state to active clock state
bit 7	SSEN: Slave Select Enable bit (Slave mode) ⁽²⁾
	1 = \overline{SSx} pin is used by the macro in Slave mode; \overline{SSx} pin is used as the slave select input 0 = \overline{SSx} pin is not used by the macro (\overline{SSx} pin will be controlled by the port I/O)
bit 6	CKP: Clock Polarity Select bit
	 1 = Idle state for clock is a high level; active state is a low level 0 = Idle state for clock is a low level; active state is a high level
bit 5	MSTEN: Master Mode Enable bit
	1 = Master mode 0 = Slave mode
bit 4	DISSDI: Disable SDIx Input Port bit
	 1 = SDIx pin is not used by the module; pin is controlled by port function 0 = SDIx pin is controlled by the module
bit 3	DISSCK: Disable SCKx Output Port bit
	 1 = SCKx pin is not used by the module; pin is controlled by port function 0 = SCKx pin is controlled by the module
bit 2	MCLKEN: Master Clock Enable bit ⁽³⁾
	 1 = REFO is used by the Baud Rate Generator (BRG) 0 = Peripheral clock is used by the BRG
bit 1	SPIFE: Frame Sync Pulse Edge Select bit
	 1 = Frame Sync pulse (Idle-to-active edge) coincides with the first bit clock 0 = Frame Sync pulse (Idle-to-active edge) precedes the first bit clock
bit 0	ENHBUF: Enhanced Buffer Enable bit
	 1 = Enhanced Buffer mode is enabled 0 = Enhanced Buffer mode is disabled
Note 1: 2 [.]	When AUDEN (SPIxCON1H<15>) = 1, this module functions as if CKE = 0, regardless of its actual value.

- When FRMEN 1, SSEN is not used. 2:
- **3:** MCLKEN can only be written when the SPIEN bit = 0.
- 4: This channel is not meaningful for DSP/PCM mode as LRC follows FRMSYPW.

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AUDEN ⁽¹⁾	SPISGNEXT	IGNROV	IGNTUR	AUDMONO ⁽²⁾	URDTEN ⁽³⁾	AUDMOD1 ⁽⁴⁾	AUDMOD0 ⁽⁴
bit 15						• •	bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FRMEN	FRMSYNC	FRMPOL	MSSEN	FRMSYPW	FRMCNT2	FRMCNT1	FRMCNT0
bit 7			MOOLIY		1141101112		bit 0
Logondu							
Legend: R = Readab	ole bit	W = Writable I	nit	U = Unimplem	ented hit read	las '0'	
-n = Value a		'1' = Bit is set		'0' = Bit is clea		x = Bit is unkr	nown
bit 15		o Codec Suppo					
	this modu regardles		if FRMEN = 1 I values	ntrols the directio			
bit 14	•			Read Data Enab	le bit		
		RX FIFO is sig RX FIFO is no		ed			
bit 13	•	ore Receive Ov					
	by the rec	eive data		critical error; duri	ng ROV, data	in the FIFO is r	not overwritter
bit 12		a critical error ore Transmit Ur	-	roperation			
	1 = A Transm until the S		UR) is NOT a empty	a critical error and	d data indicate	ed by URDTEN	is transmitted
bit 11		Audio Data For					
		a is mono (i.e.,		ord is transmitted	on both left ar	nd right channe	ls)
bit 10		nsmit Underru	n Data Enable	e bit ⁽³⁾			
				ster during Transr g Transmit Under			
bit 9-8	AUDMOD<1:0)>: Audio Proto	ocol Mode Se	lection bits ⁽⁴⁾			
	01 = Left Justi	stified mode: Thi	s module fun	nctions as if SPIF ctions as if SPIFE if SPIFE = 0, rega	E = 1, regardle	ess of its actual	
bit 7		ned SPIx Supp		C			
		Plx support is e Plx support is e		pin is used as th	e FSYNC inpu	ıt/output)	
2: A 3: L	JRDTEN is only	only be written valid when IGN	when the SPI ITUR = 1.	IEN bit = 0 and is	-		
4: T	The AUDMOD<1	:0> bits can on	ly be written v	vhen the SPIEN b	oit = 0 and are	only valid when	n AUDEN = 1

4: The AUDMOD<1:0> bits can only be written when the SPIEN bit = 0 and are only valid when AUDEN = 1. When NOT in PCM/DSP mode, this module functions as if FRMSYPW = 1, regardless of its actual value.

REGISTER 18-2: SPIxCON1H: SPIx CONTROL REGISTER 1 HIGH (CONTINUED)

bit 6	FRMSYNC: Frame Sync Pulse Direction Control bit
	1 = Frame Sync pulse input (slave)
	0 = Frame Sync pulse output (master)
bit 5	FRMPOL: Frame Sync/Slave Select Polarity bit
	 1 = Frame Sync pulse/slave select is active-high 0 = Frame Sync pulse/slave select is active-low
bit 4	MSSEN: Master Mode Slave Select Enable bit
	1 = SPIx slave select support is enabled with polarity determined by FRMPOL (SSx pin is automatically driven during transmission in Master mode)
	0 = Slave select SPIx support is disabled (SSx pin will be controlled by port I/O)
bit 3	FRMSYPW: Frame Sync Pulse-Width bit
	 1 = Frame Sync pulse is one serial word length wide (as defined by MODE<32,16>/WLENGTH<4:0>) 0 = Frame Sync pulse is one clock (SCK) wide
bit 2-0	FRMCNT<2:0>: Frame Sync Pulse Counter bits
	Controls the number of serial words transmitted per Sync pulse.
	110 = Reserved
	101 = Generates a Frame Sync pulse on every 32 serial words
	100 = Generates a Frame Sync pulse on every 16 serial words
	011 = Generates a Frame Sync pulse on every 8 serial words
	010 = Generates a Frame Sync pulse on every 4 serial words
	001 = Generates a Frame Sync pulse on every 2 serial words (value used by audio protocols)

000 = Generates a Frame Sync pulse on each serial word

Note 1: AUDEN can only be written when the SPIEN bit = 0.

- **2:** AUDMONO can only be written when the SPIEN bit = 0 and is only valid for AUDEN = 1.
- **3:** URDTEN is only valid when IGNTUR = 1.
- **4:** The AUDMOD<1:0> bits can only be written when the SPIEN bit = 0 and are only valid when AUDEN = 1. When NOT in PCM/DSP mode, this module functions as if FRMSYPW = 1, regardless of its actual value.

REGISTER 18-3: SPIxCON2L: SPIx CONTROL REGISTER 2 LOW

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	_					_		
bit 15							bit 8	
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			R/W-U		ENGTH<4:0>		K/W-U	
bit 7							bit	
Legend:								
R = Readat	ole bit	W = Writable	bit	U = Unimplem	nented bit, read	l as '0'		
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own	
bit 15-5	Unimplom	nted: Dood oo '	o'					
bit 4-0	-	ented: Read as ' <4:0>: Variable \		hite(1,2)				
	11111 = 32		Nord Length L	10				
	11110 = 31							
	11101 = 30							
	11100 = 29							
	11011 = 28-bit data							
	11010 = 27-bit data							
	11001 = 26	6-bit data						
	11000 = 25	5-bit data						
	10111 = 24							
	10110 = 23							
	10101 = 22							
	10100 = 21							
	10011 = 20							
	10010 = 19							
	10001 = 18							
	10000 = 17							
	01111 = 16							
	01110 = 15							
	01101 = 14 01100 = 1 3							
	01100 = 13 01011 = 12							
	01011 - 12 01010 = 11							
	01001 = 10							
	01000 = 9-							
	00111 = 8 -							
	00110 = 7-							
	00101 = 6 -							
	00100 = 5-							
	00011 = 4-							
	00010 = 3 -							
	00001 = 2 -	bit data						

- **Note 1:** These bits are effective when AUDEN = 0 only.
 - 2: Varying the length by changing these bits does not affect the depth of the TX/RX FIFO.

REGISTER 18-4: SPIxSTATL: SPIx STATUS REGISTER LOW
--

U-0	U-0	U-0	HS/R/C-0	HSC/R-0	U-0	U-0	HSC/R-0
—	—	—	FRMERR	SPIBUSY	—	—	SPITUR ⁽¹⁾
oit 15							bit 8
HSC/R-0	HS/R/C-0	HSC/R-1	U-0	HSC/R-1	U-0	HSC/R-0	HSC/R-0
SRMT	SPIROV	SPIRBE	—	SPITBE	—	SPITBF	SPIRBF
bit 7							bit
_egend:		C = Clearable	hit	LI = Unimplem	ented, read as	·́∩'	
R = Readabl	e hit	W = Writable b			are Settable/Cl		
-n = Value at		'1' = Bit is set		'0' = Bit is clea		HS = Hardwa	e Settable bit
		I - Dit is set			icu		
bit 15-13	Unimplemen	ted: Read as '0	,				
bit 12	-	Plx Frame Error					
	1 = Frame er	ror is detected					
	0 = No frame	error is detecte	d				
pit 11	SPIBUSY: SP	Plx Activity State	us bit				
		currently busy					
	•	ng transactions		d)			
bit 10-9	-	ted: Read as '0					
bit 8		x Transmit Und					
		buffer has enco					
L:1 7		buffer does not		nit Underrun co	nation		
bit 7		Register Empty		naithar SDIvT		CD containa da	to to transmit
		nt or pending tra r pending transa		, neither SPIXT	AD OF SPIXIA	SR contains da	
oit 6		x Receive Over					
	1 = A new by 0 = No overfle	te/half-word/wo	rd has been co	ompletely receiv	ved when the	SPIxRXB was f	ull
bit 5	SPIRBE: SPI	x RX Buffer Em	ptv Status bit				
	1 = RX buffer		pry clarac bit				
	0 = RX buffer						
	Standard Buff						
	•	set in hardware en SPIx transfei				RXB. Automati	cally cleared i
	Enhanced Bu Indicates RXI		0000.				

 SPITUR is cleared when SPIEN = 0. When IGNTUR = 1, SPITUR provides dynamic status of the Transmit Underrun condition, but does not stop RX/TX operation and does not need to be cleared by software.

REGISTER 18-4: SPIx STATL: SPIx STATUS REGISTER LOW (CONTINUED)

- bit 3 SPITBE: SPIx Transmit Buffer Empty Status bit 1 = SPIxTXB is empty 0 = SPIxTXB is not empty Standard Buffer mode: Automatically set in hardware when SPIx transfers data from SPIxTXB to SPIxTXSR. Automatically cleared in hardware when SPIxBUF is written, loading SPIxTXB. Enhanced Buffer mode: Indicates TXELM<5:0> = 000000. bit 2 Unimplemented: Read as '0' bit 1 SPITBF: SPIx Transmit Buffer Full Status bit 1 = SPIxTXB is full 0 = SPIxTXB not full Standard Buffer mode: Automatically set in hardware when SPIxBUF is written, loading SPIxTXB. Automatically cleared in hardware when SPIx transfers data from SPIxTXB to SPIxTXSR. Enhanced Buffer mode: Indicates TXELM<5:0> = 111111. SPIRBF: SPIx Receive Buffer Full Status bit bit 0 1 = SPIxRXB is full 0 = SPIxRXB is not full Standard Buffer mode: Automatically set in hardware when SPIx transfers data from SPIxRXSR to SPIxRXB. Automatically cleared in hardware when SPIxBUF is read from, reading SPIxRXB. Enhanced Buffer mode: Indicates RXELM<5:0> = 111111.
- **Note 1:** SPITUR is cleared when SPIEN = 0. When IGNTUR = 1, SPITUR provides dynamic status of the Transmit Underrun condition, but does not stop RX/TX operation and does not need to be cleared by software.

REGISTER 18-5: SPIxSTATH: SPIx STATUS REGISTER HIGH

— — RXELM	15 ⁽³⁾ RXELM4 ⁽²⁾	RXELM3 ⁽¹⁾	RXELM2	RXELM1	RXELM0
		10 (EEIIIO	TOTELINE		IVILLINO
bit 15					bit 8

U-0	U-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0
_	—	TXELM5 ⁽³⁾	TXELM4 ⁽²⁾	TXELM3 ⁽¹⁾	TXELM2	TXELM1	TXELM0
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 **RXELM<5:0>:** Receive Buffer Element Count bits (valid in Enhanced Buffer mode)^(1,2,3)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **TXELM<5:0>:** Transmit Buffer Element Count bits (valid in Enhanced Buffer mode)^(1,2,3)

Note 1: RXELM3 and TXELM3 bits are only present when FIFODEPTH = 8 or higher.

2: RXELM4 and TXELM4 bits are only present when FIFODEPTH = 16 or higher.

3: RXELM5 and TXELM5 bits are only present when FIFODEPTH = 32.

U-0	U-0	U-0	R/W-0	R/W-0	U-0	U-0	R/W-0			
—		—	FRMERREN	BUSYEN	_	—	SPITUREN			
oit 15							bit 8			
R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0			
SRMTEN	SPIROVEN	SPIRBEN	—	SPITBEN	_	SPITBFEN	SPIRBFEN			
bit 7							bit C			
anandı										
L egend: R = Readable	hit	W = Writable	hit	U = Unimplem	onted hit rea	d as '0'				
n = Value at l		'1' = Bit is set		'0' = Bit is clea		x = Bit is unkr	own			
		1 - Dit 13 301								
bit 15-13	Unimplement	ted: Read as '	0'							
bit 12	-		ipt Events via Fl	RMERR bit						
			an interrupt even							
		0	enerate an interr	•						
pit 11		-	Events via SPIB	USY bit						
		•	interrupt event erate an interrup	t event						
oit 10-9	Unimplement	-	-	e o vont						
pit 8	•		ot Events via SP	ITUR bit						
	1 = Transmit Underrun (TUR) generates an interrupt event									
			not generate a	-	nt					
oit 7			Events via SRM							
	•		RMT) generates es not generate							
bit 6	•		ot Events via SP	•	.0					
			(ROV) generate		event					
			does not genera	-	event					
bit 5			Events via SPIF							
	 1 = SPIx RX buffer empty generates an interrupt event 0 = SPIx RX buffer empty does not generate an interrupt event 									
bit 4	Unimplement		-	s an interrupt e	vent					
oit 3	-			BE bit						
	SPITBEN: Enable Interrupt Events via SPITBE bit 1 = SPIx transmit buffer empty generates an interrupt event									
			oty does not ger							
pit 2	Unimplement	ted: Read as '	0'							
bit 1		-	t Events via SPI							
	 1 = SPIx transmit buffer full generates an interrupt event 0 = SPIx transmit buffer full does not generate an interrupt event 									
			UDES HOLDEDED		eveni					
vit O			-	-						
bit 0	SPIRBFEN: E	Enable Interrup	ot Events via SP generates an inte	IRBF bit						

REGISTER 18-6: SPIxIMSKL: SPIx INTERRUPT MASK REGISTER LOW

REGISTER 18-7: SPIxIMSKH: SPIx INTERRUPT MASK REGISTER HIGH

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
RXWIEN	—	RXMSK5 ⁽¹⁾	RXMSK4 ^(1,4)	RXMSK3 ^(1,3)	RXMSK2 ^(1,2)	RXMSK1 ⁽¹⁾	RXMSK0 ⁽¹⁾
bit 15							bit 8

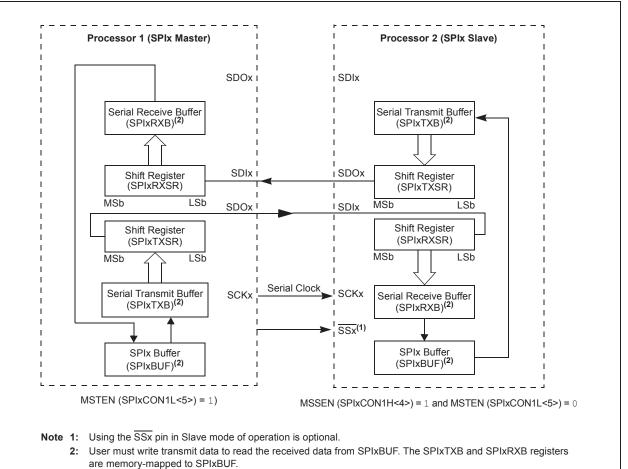
R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
TXWIEN	—	TXMSK5 ⁽¹⁾	TXMSK4 ^(1,4)	TXMSK3 ^(1,3)	TXMSK2 ^(1,2)	TXMSK1 ⁽¹⁾	TXMSK0 ⁽¹⁾
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	RXWIEN: Receive Watermark Interrupt Enable bit
	1 = Triggers receive buffer element watermark interrupt when RXMSK<5:0> \leq RXELM<5:0> 0 = Disables receive buffer element watermark interrupt
bit 14	Unimplemented: Read as '0'
bit 13-8	RXMSK<5:0>: RX Buffer Mask bits ^(1,2,3,4)
	RX mask bits; used in conjunction with the RXWIEN bit.
bit 7	TXWIEN: Transmit Watermark Interrupt Enable bit
	 1 = Triggers transmit buffer element watermark interrupt when TXMSK<5:0> = TXELM<5:0> 0 = Disables transmit buffer element watermark interrupt
bit 6	Unimplemented: Read as '0'
bit 5-0	TXMSK<5:0>: TX Buffer Mask bits ^(1,2,3,4)
	TX mask bits; used in conjunction with the TXWIEN bit.

- **Note 1:** Mask values higher than FIFODEPTH are not valid. The module will not trigger a match for any value in this case.
 - **2**: RXMSK2 and TXMSK2 bits are only present when FIFODEPTH = 8 or higher.
 - **3:** RXMSK3 and TXMSK3 bits are only present when FIFODEPTH = 16 or higher.
 - 4: RXMSK4 and TXMSK4 bits are only present when FIFODEPTH = 32.





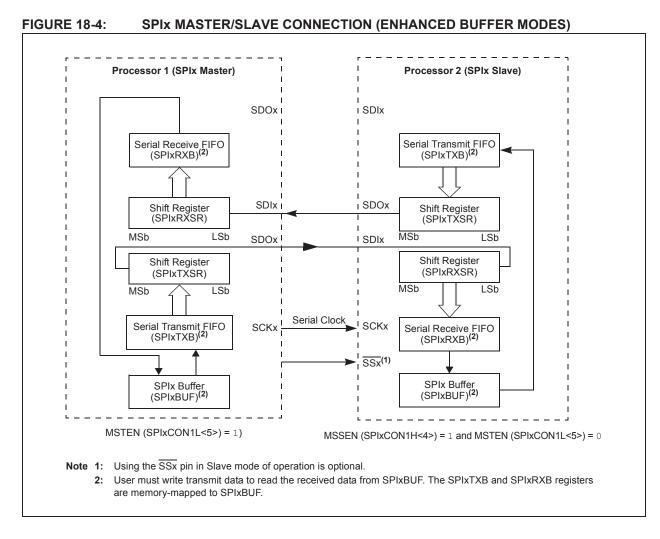


FIGURE 18-5: SPIX MASTER, FRAME MASTER CONNECTION DIAGRAM

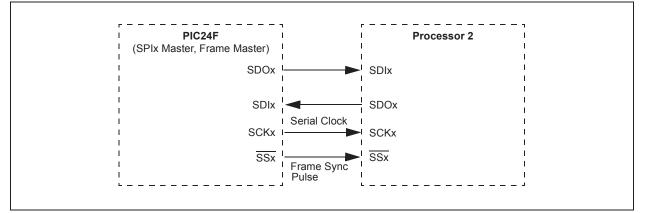


FIGURE 18-6: SPIx MASTER, FRAME SLAVE CONNECTION DIAGRAM

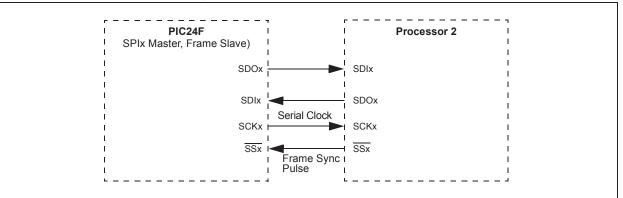


FIGURE 18-7: SPIx SLAVE, FRAME MASTER CONNECTION DIAGRAM

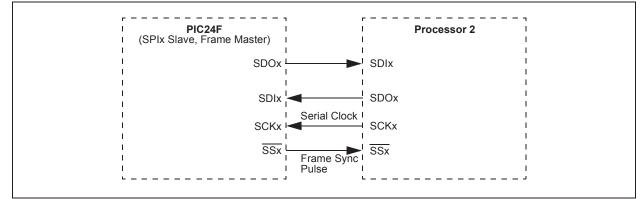
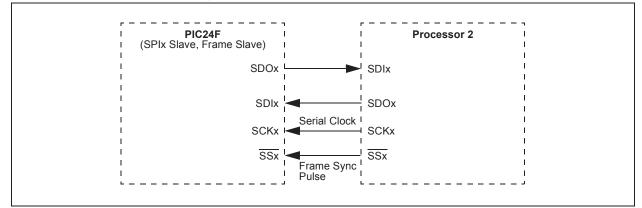


FIGURE 18-8: SPIx SLAVE, FRAME SLAVE CONNECTION DIAGRAM



EQUATION 18-1: RELATIONSHIP BETWEEN DEVICE AND SPIX CLOCK SPEED

$$Baud Rate = \frac{F_{PB}}{(2 * (SPIxBRG + 1))}$$

Where:

FPB is the Peripheral Bus Clock Frequency.

19.0 INTER-INTEGRATED CIRCUIT (I²C)

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Inter-Integrated Circuit (I²C)" (DS70000195) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family of devices contains two Inter-Integrated Circuit (I²C) modules: I2C1 and I2C2.

The I^2C module provides complete hardware support for both Slave and Multi-Master modes of the I^2C serial communication standard, with a 16-bit interface.

The I²C module has a 2-pin interface:

- The SCLx/ASCLx pin is clock
- · The SDAx/ASDAx pin is data

The I²C module offers the following key features:

- I²C Interface supporting both Master and Slave modes of Operation
- I²C Slave mode Supports 7 and 10-Bit Addressing
- I²C Master mode Supports 7 and 10-Bit Addressing
- I²C Port allows Bidirectional Transfers between Master and Slaves
- Serial Clock Synchronization for I²C Port can be used as a Handshake Mechanism to Suspend and Resume Serial Transfer (SCLREL control)
- I²C Supports Multi-Master Operation, Detects Bus Collision and Arbitrates Accordingly
- System Management Bus (SMBus) Support
- Alternate I²C Pin Mapping (ASCLx/ASDAx)

19.1 I²C Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

19.1.1 KEY RESOURCES

- "Inter-Integrated Circuit (I²C)" (DS70000195) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

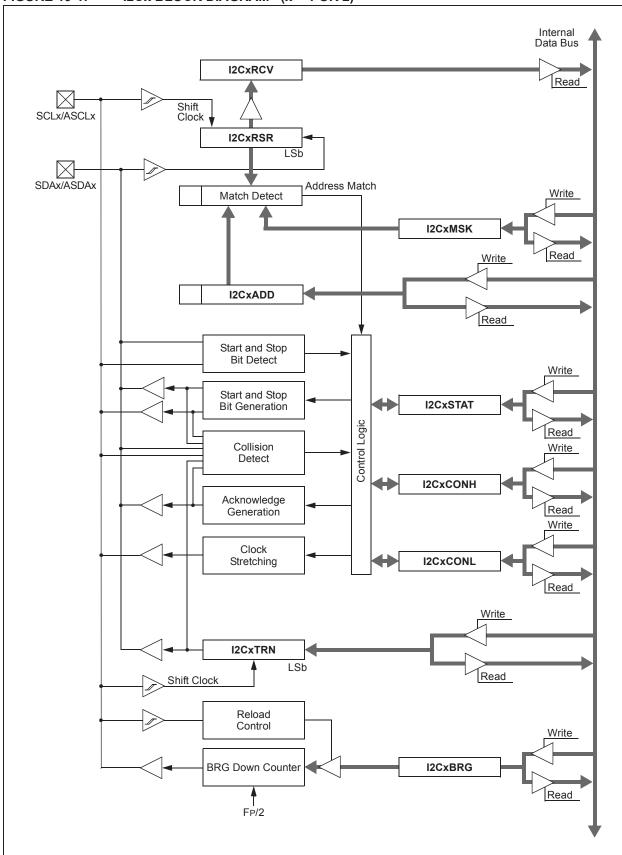


FIGURE 19-1: I2Cx BLOCK DIAGRAM (x = 1 OR 2)

19.2 I²C Control Registers

REGISTER 19-1: I2CxCONL: I2Cx CONTROL REGISTER LOW

R/W-0	U-0	R/W-0	HC/R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL	STRICT	A10M	DISSLW	SMEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0	HC/R/W-0	HC/R/W-0	HC/R/W-0	HC/R/W-0	HC/R/W-0
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7			·	•			bit 0

Legend:	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	I2CEN: I2Cx Enable bit
	1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins 0 = Disables the I2Cx module; all I ² C pins are controlled by port functions
bit 14	Unimplemented: Read as '0'
bit 13	I2CSIDL: I2Cx Stop in Idle Mode bit
	 1 = Discontinues module operation when device enters Idle mode 0 = Continues module operation in Idle mode
bit 12	SCLREL: SCLx Release Control bit (when operating as I ² C slave)
	1 = Releases SCLx clock
	0 = Holds SCLx clock low (clock stretch)
	$\frac{ \text{f STREN = 1}}{ \text{Figure 1} }$
	Bit is R/W (i.e., software can write '0' to initiate stretch and write '1' to release clock). It is cleared by hard- ware at the beginning of every slave data byte transmission. It is cleared by hardware at the end of every slave address byte reception. It is cleared by hardware at the end of every slave data byte reception.
	If STREN = 0:
	Bit is R/S (i.e., software can only write '1' to release clock). It is cleared by hardware at the beginning
	of every slave data byte transmission. It is cleared by hardware at the end of every slave address byte
	reception.
bit 11	STRICT: Strict I2Cx Reserved Address Enable bit
	1 = <u>Strict Reserved Addressing is Enabled:</u>
	In Slave mode, the device will NACK any reserved address. In Master mode, the device is allowed to generate addresses within the reserved address space.
	0 = <u>Reserved Addressing is Acknowledged:</u>
	In Slave mode, the device will ACK any reserved address. In Master mode, the device should not address a slave device with a reserved address.
bit 10	A10M: 10-Bit Slave Address bit
DIL TO	1 = 12CxADD is a 10-bit slave address
	0 = I2CxADD is a 7-bit slave address
bit 9	DISSLW: Disable Slew Rate Control bit
	1 = Slew rate control is disabled
	0 = Slew rate control is enabled
bit 8	SMEN: SMBus Input Levels bit
	1 = Enables I/O pin thresholds compliant with SMBus specification
	0 = Disables SMBus input thresholds

REGISTER 19-1: I2CxCONL: I2Cx CONTROL REGISTER LOW (CONTINUED)

bit 7	GCEN: General Call Enable bit (when operating as I ² C slave) 1 = Enables interrupt when a general call address is received in I2CxRSR (module is enabled for reception) 0 = General call address is disabled
bit 6	STREN: SCLx Clock Stretch Enable bit (when operating as I ² C slave) Used in conjunction with the SCLREL bit. 1 = Enables software controlled clock stretching 0 = Disables software controlled clock stretching
bit 5	ACKDT: Acknowledge Data bit (when operating as I ² C master, applicable during master receive) Value that is transmitted when the software initiates an Acknowledge sequence. 1 = Sends NACK during Acknowledge 0 = Sends ACK during Acknowledge
bit 4	 ACKEN: Acknowledge Sequence Enable bit (when operating as I²C master, applicable during master receive) 1 = Initiates Acknowledge sequence on SDAx and SCLx pins and transmits ACKDT data bit; it is cleared by hardware at the end of the master Acknowledge sequence 0 = Acknowledge sequence is not in progress
bit 3	 RCEN: Receive Enable bit (when operating as I²C master) 1 = Enables Receive mode for I²C; it is cleared by hardware at the end of the eighth bit of the master receive data byte 0 = Receive sequence is not in progress
bit 2	 PEN: Stop Condition Enable bit (when operating as I²C master) 1 = Initiates Stop condition on SDAx and SCLx pins; it is cleared by hardware at the end of the master Stop sequence 0 = Stop condition is not in progress
bit 1	 RSEN: Repeated Start Condition Enable bit (when operating as I²C master) 1 = Initiates Repeated Start condition on SDAx and SCLx pins; it is cleared by hardware at the end of the master Repeated Start sequence 0 = Repeated Start condition is not in progress
bit 0	 SEN: Start Condition Enable bit (when operating as I²C master) 1 = Initiates Start condition on SDAx and SCLx pins; it is cleared by hardware at the end of the master Start sequence

0 = Start condition is not in progress

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	—	—	_	—	—	—	
bit 15							bit 8
F							
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	PCIE	SCIE	BOEN	SDAHT	SBCDE	AHEN	DHEN
bit 7							bit 0
Legend: R = Readab	lo hit	W = Writable I	oit	II – Unimplom	ontod hit road	as '0'	
-n = Value a		'1' = Bit is set	JIL	'0' = Bit is clea	nented bit, read	x = Bit is unkn	
	IL FOR	I – DILIS SEL			areu		IOWIT
bit 15-7	Unimplemen	ted: Read as ')'				
bit 6	-			I ² C Slave mode	only)		
		nterrupt on dete			57		
	0 = Stop dete	ction interrupts	are disabled				
bit 5			•	(I ² C Slave mode			
				or Restart condi	tions		
h:+ 4		ection interrupts		ave mode only)			
bit 4			•	ave mode only) rated for a recei	vod addroce/dr	ata buta janarin	a the state of
		V only if the RE			veu audress/ua	ala byte, ignorin	ig the state of
		/ is only update		/ is clear			
bit 3	SDAHT: SDA	x Hold Time Se	election bit				
				after the falling			
1.1.0				after the falling	•		
bit 2				Enable bit (I ² C	Slave mode on	IY)	
		slave bus collisi s collision interr		led			
	If the rising e	dge of SCLx an	d SDAx is sar	mpled low when			
		•		node is only valid	d during data a	nd ACK transm	it sequences.
bit 1		ess Hold Enable	`				
				CLx for a match and SCLx will be		address byte,	the SCLREL
		holding is disat					
bit 0		Hold Enable bit		ode only)			
				x for a received	d data byte, the	e slave hardwa	are clears the
		(I2CxCONL<1	2>) bit and S	CLx is held low			
		ding is disabled					

REGISTER 19-2: I2CxCONH: I2Cx CONTROL REGISTER HIGH

REGISTER 19-3: I2CxSTAT: I2Cx STATUS REGISTER

HSC/R-0	HSC/R-0	HSC/R-0	U-0	U-0	HS/R/C-0	HSC/R-0	HSC/R-0
ACKSTAT	TRSTAT	ACKTIM		_	BCL	GCSTAT	ADD10
bit 15	1				L	l	bit 8
HS/R/C-0	HS/R/C-0	HSC/R-0	HSC/R/C-0	HSC/R/C-0	HSC/R-0	HSC/R-0	HSC/R-0
IWCOL	I2COV	D_A	Р	S	R_W	RBF	TBF
bit 7							bit 0
Legend:		C = Clearable	bit	'0' = Bit is clea	ared	HS = Hardware S	Settable bit
R = Readabl	e bit	W = Writable	oit	HSC = Hardw	are Settable/Cle	earable bit	
-n = Value at	POR	'1' = Bit is set		U = Unimplem	nented bit, read a	as 'O'	
bit 15	1 = NACK w 0 = ACK was	as received from	om slave n slave	n operating as I nd of a slave A		cable to master tra	ansmit operation)
bit 14					•	le to master trans	mit operation)
	1 = Master tr 0 = Master tr	ransmit is in pr ransmit is not i ardware at the	ogress (8 bits n progress	s + ACK)			t the end of slave
bit 13	$1 = I^2 C$ bus i	s an Acknowle	edge sequend		Bth falling edge		
bit 12-11		nted: Read as	-	ared on the 9th	n rising edge of	SCLX	
bit 12-11	-	r Bus Collision					
bit TO	1 = A bus co 0 = No bus c		en detected d ed	uring a master us collision.	operation		
bit 9	GCSTAT: Ge	eneral Call Sta	tus bit				
	0 = General	call address w call address w ardware when	as not receiv		ral call address	. It is cleared by	hardware at Stop
bit 8	ADD10: 10-E	Bit Address St	atus bit				
	0 = 10-bit ad		matched	2nd byte of the	matched 10-bi	t address. It is clea	ared by hardware
bit 7		x Write Collision					
	0 = No collis	ion		-		C module is busy isy (cleared by sc	oftware).
bit 6			0		/as still holding	the previous byte	
	It is set by ha	ardware at an	attempt to tra	insfer I2CxRS	R to I2CxRCV (cleared by softwa	ire).

REGISTER 19-3: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)

bit 5	D_A: Data/Address bit (I ² C Slave mode only)
	1 = Indicates that the last byte received was data
	0 = Indicates that the last byte received was a device address
	It is cleared by hardware at a device address match. It is set by hardware by reception of a slave byte.
bit 4	P: Stop bit
	1 = Indicates that a Stop bit has been detected last
	0 = Stop bit was not detected last
	It is set or cleared by hardware when a Start, Repeated Start or Stop is detected.
bit 3	S: Start bit
	 I = Indicates that a Start (or Repeated Start) bit has been detected last 0 = Start bit was not detected last
	It is set or cleared by hardware when a Start, Repeated Start or Stop is detected.
bit 2	R_W: Read/Write Information bit (I ² C Slave mode only)
	1 = Read – Indicates data transfer is output from the slave
	0 = Write – Indicates data transfer is input to the slave
	It is set or cleared by hardware after reception of an I ² C device address byte.
bit 1	RBF: Receive Buffer Full Status bit
	1 = Receive is complete, I2CxRCV is full
	0 = Receive is not complete, I2CxRCV is empty
	It is set by hardware when I2CxRCV is written with a received byte. It is cleared by hardware when
	software reads I2CxRCV.
bit 0	TBF: Transmit Buffer Full Status bit
	1 = Transmit is in progress, I2CxTRN is full
	0 = Transmit is complete, I2CxTRN is empty
	It is set by hardware when software writes to I2CxTRN. It is cleared by hardware at completion of a data transmission.

REGISTER 19-4: I2CxMSK: I2Cx SLAVE MODE ADDRESS MASK REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
_	_	—	_	_	_	AMSł	<9:8>
bit 15		•					bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			AMS	SK<7:0>			
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable I	bit	U = Unimpler	nented bit, rea	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown

bit 15-10 Unimplemented: Read as '0'

bit 9-0 AMSK<9:0>: Address Mask Select bits

For 10-Bit Address:

1 = Enables masking for bit Ax of incoming message address; bit match is not required in this position

0 = Disables masking for bit Ax; bit match is required in this position

For 7-Bit Address (I2CxMSK<6:0> only):

1 = Enables masking for bit Ax + 1 of incoming message address; bit match is not required in this position

0 = Disables masking for bit Ax + 1; bit match is required in this position

20.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Universal Asynchronous Receiver Transmitter (UART)" (DS70000582) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family of devices contains two UART modules.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the dsPIC33EPXXXGS70X/80X device family. The UART is a full-duplex, asynchronous system that can communicate with peripheral devices, such as personal computers, LIN/J2602, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins, and also includes an IrDA[®] encoder and decoder.

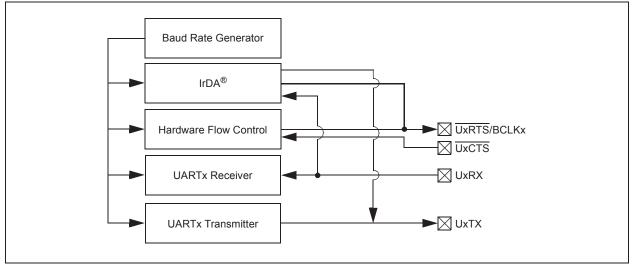
The primary features of the UARTx module are:

- Full-Duplex, 8 or 9-Bit Data Transmission through the UxTX and UxRX Pins
- Even, Odd or No Parity Options (for 8-bit data)
- One or Two Stop bits
- Hardware Flow Control Option with UxCTS and UxRTS Pins
- Fully Integrated Baud Rate Generator with 16-Bit Prescaler
- Baud Rates Ranging from 4.375 Mbps to 67 bps in 16x mode at 70 MIPS
- Baud Rates Ranging from 17.5 Mbps to 267 bps in 4x mode at 70 MIPS
- 4-Deep First-In First-Out (FIFO) Transmit Data Buffer
- 4-Deep FIFO Receive Data Buffer
- Parity, Framing and Buffer Overrun Error Detection
- Support for 9-Bit mode with Address Detect (9th bit = 1)
- · Transmit and Receive Interrupts
- A Separate Interrupt for all UARTx Error Conditions
- · Loopback mode for Diagnostic Support
- · Support for Sync and Break Characters
- Support for Automatic Baud Rate Detection
- IrDA[®] Encoder and Decoder Logic
- 16x Baud Clock Output for IrDA Support

A simplified block diagram of the UARTx module is shown in Figure 20-1. The UARTx module consists of these key hardware elements:

- · Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

FIGURE 20-1: UARTX SIMPLIFIED BLOCK DIAGRAM



20.1 UART Helpful Tips

- In multi-node, direct connect UART networks, UART receive inputs react to the complementary logic level defined by the URXINV bit (UxMODE<4>), which defines the Idle state, the default of which is logic high (i.e., URXINV = 0). Because remote devices do not initialize at the same time, it is likely that one of the devices, because the RX line is floating, will trigger a Start bit detection and will cause the first byte received, after the device has been initialized, to be invalid. To avoid this situation, the user should use a pullup or pull-down resistor on the RX pin depending on the value of the URXINV bit.
 - a) If URXINV = 0, use a pull-up resistor on the UxRX pin.
 - b) If URXINV = 1, use a pull-down resistor on the UxRX pin.
- 2. The first character received on a wake-up from Sleep mode, caused by activity on the UxRX pin of the UARTx module, will be invalid. In Sleep mode, peripheral clocks are disabled. By the time the oscillator system has restarted and stabilized from Sleep mode, the baud rate bit sampling clock, relative to the incoming UxRX bit timing, is no longer synchronized, resulting in the first character being invalid; this is to be expected.

20.2 UART Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

20.2.1 KEY RESOURCES

- "Universal Asynchronous Receiver Transmitter (UART)" (DS70000582) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- · Application Notes
- Software Libraries
- · Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

20.3 UART Control Registers

REGISTER 20-1: UXMODE: UARTX MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN ⁽¹⁾	_	USIDL	IREN ⁽²⁾	RTSMD		UEN1	UEN0
bit 15							bit 8
HC/R/W-0	R/W-0	HC/R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7							bit (
Legend:		HC = Hardwar	e Clearable b	it			
R = Readabl	e bit	W = Writable I	oit	U = Unimplen	nented bit, read	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkn	own
bit 15	1 = UARTx is		ARTx pins are			ied by UEN<1:0> UARTx power co	
bit 14	Unimplemen	ited: Read as '0)'				
bit 13	USIDL: UAR	Tx Stop in Idle N	/lode bit				
		nues module op es module opera		device enters Ic ode	lle mode		
bit 12	IREN: IrDA [®]	Encoder and De	ecoder Enable	e bit ⁽²⁾			
		oder and decoc					
oit 11		de Selection for		t			
		oin is in Simplex oin is in Flow Co					
bit 10	Unimplemen	ited: Read as 'o)'				
bit 9-8	UEN<1:0>: L	JARTx Pin Enab	le bits				
	10 = UxTX, U 01 = UxTX, U	JxRX, UxCTS a JxRX and UxRT nd UxRX pins a	nd UxRTS pir S pins are en	ns are enabled a abled and used	and used ; UxCTS pin is	controlled by PC controlled by PC BCLKx pins are	ORT latches
bit 7	WAKE: Wake	e-up on Start Bit	Detect During	g Sleep Mode E	nable bit		
	in hardw	continues to san are on the follow -up is enabled			generated on	the falling edge;	bit is cleared
bit 6		ARTx Loopback	Mode Select	bit			
	1 = Enables	Loopback mode k mode is disab	e				
"a		Family Referen				0000582) in the JARTx module fo	or receive or
	-			modo (PPCH -	()		

2: This feature is only available for the 16x BRG mode (BRGH = 0).

REGISTER 20-1: UXMODE: UARTX MODE REGISTER (CONTINUED)

bit 5	ABAUD: Auto-Baud Enable bit
	 1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h) before other data; cleared in hardware upon completion 0 = Baud rate measurement is disabled or completed
bit 4	URXINV: UARTx Receive Polarity Inversion bit
	1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	BRGH: High Baud Rate Enable bit
	 1 = BRG generates 4 clocks per bit period (4x baud clock, High-Speed mode) 0 = BRG generates 16 clocks per bit period (16x baud clock, Standard mode)
bit 2-1	PDSEL<1:0>: Parity and Data Selection bits
	 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	STSEL: Stop Bit Selection bit
	1 = Two Stop bits 0 = One Stop bit
Note 1: F	Refer to "Universal Asynchronous Receiver Transmitter (UART)" (DS70000582) in the

"dsPIC33/PIC24 Family Reference Manual" for information on enabling the UARTx module for receive or transmit operation.

2: This feature is only available for the 16x BRG mode (BRGH = 0).

REGISTER 20-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	U-0	HC/R/W-0	R/W-0	R-0	R-1
UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN ⁽¹⁾	UTXBF	TRMT
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

Legend:	C = Clearable bit	HC = Hardware Clearab	ole bit
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15,13 UTXISEL<1:0>: UARTx Transmission Interrupt Mode Selection bits

- 11 = Reserved; do not use
- 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR), and as a result, the transmit buffer becomes empty
- 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed
- 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)
- bit 14 UTXINV: UARTx Transmit Polarity Inversion bit
 - $\frac{\text{If IREN = 0:}}{1 = \text{UxTX Idle state is '0'}}$
 - 0 = UxTX Idle state is '1'
 - If IREN = 1:
 - $1 = IrDA^{\textcircled{R}}$ encoded, UxTX Idle state is '1'
 - 0 = IrDA encoded, UxTX Idle state is '0'
- bit 12 Unimplemented: Read as '0'
- bit 11 UTXBRK: UARTx Transmit Break bit
 - 1 = Sends Sync Break on next transmission Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
 - 0 = Sync Break transmission is disabled or completed
- bit 10 UTXEN: UARTx Transmit Enable bit⁽¹⁾
 - 1 = Transmit is enabled, UxTX pin is controlled by UARTx
 0 = Transmit is disabled, any pending transmission is aborted and buffer is reset; UxTX pin is controlled
- by the PORT bit 9 UTXBF: UARTx Transmit Buffer Full Status b
 - UTXBF: UARTx Transmit Buffer Full Status bit (read-only)
 1 = Transmit buffer is full
 - 0 = Transmit buffer is not full, at least one more character can be written
- bit 8 **TRMT:** Transmit Shift Register Empty bit (read-only)
 - 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)
 - 0 = Transmit Shift Register is not empty, a transmission is in progress or queued
- bit 7-6 URXISEL<1:0>: UARTx Receive Interrupt Mode Selection bits
 - 11 = Interrupt is set on UxRSR transfer, making the receive buffer full (i.e., has four data characters)
 - 10 = Interrupt is set on UxRSR transfer, making the receive buffer 3/4 full (i.e., has three data characters)
 - 0x = Interrupt is set when any character is received and transferred from the UxRSR to the receive buffer; receive buffer has one or more characters
- **Note 1:** Refer to "Universal Asynchronous Receiver Transmitter (UART)" (DS70000582) in the "dsPIC33/ PIC24 Family Reference Manual" for information on enabling the UARTx module for transmit operation.

REGISTER 20-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)

bit 5	 ADDEN: Address Character Detect bit (bit 8 of received data = 1) 1 = Address Detect mode is enabled; if 9-bit mode is not selected, this does not take effect 0 = Address Detect mode is disabled
bit 4	RIDLE: Receiver Idle bit (read-only) 1 = Receiver is Idle 0 = Receiver is active
bit 3	 PERR: Parity Error Status bit (read-only) 1 = Parity error has been detected for the current character (character at the top of the receive FIFO) 0 = Parity error has not been detected
bit 2	<pre>FERR: Framing Error Status bit (read-only) 1 = Framing error has been detected for the current character (character at the top of the receive FIFO) 0 = Framing error has not been detected</pre>
bit 1	 OERR: Receive Buffer Overrun Error Status bit (clear/read-only) 1 = Receive buffer has overflowed 0 = Receive buffer has not overflowed; clearing a previously set OERR bit (1 → 0 transition) resets the receiver buffer and the UxRSR to the empty state
bit 0	 URXDA: UARTx Receive Buffer Data Available bit (read-only) 1 = Receive buffer has data, at least one more character can be read 0 = Receive buffer is empty

Note 1: Refer to "Universal Asynchronous Receiver Transmitter (UART)" (DS70000582) in the "dsPIC33/ PIC24 Family Reference Manual" for information on enabling the UARTx module for transmit operation.

21.0 CONFIGURABLE LOGIC CELL (CLC)

Note: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Configurable Logic Cell (CLC)" (DS70005298) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com). The Configurable Logic Cell (CLC) module allows the user to specify combinations of signals as inputs to a logic function and to use the logic output to control other peripherals or I/O pins. This provides greater flexibility and potential in embedded designs, since the CLC module can operate outside the limitations of software execution and supports a vast amount of output designs.

There are four input gates to the selected logic function. These four input gates select from a pool of up to 32 signals that are selected using four data source selection multiplexers. Figure 21-1 shows an overview of the module. Figure 21-3 shows the details of the data source multiplexers and logic input gate connections.

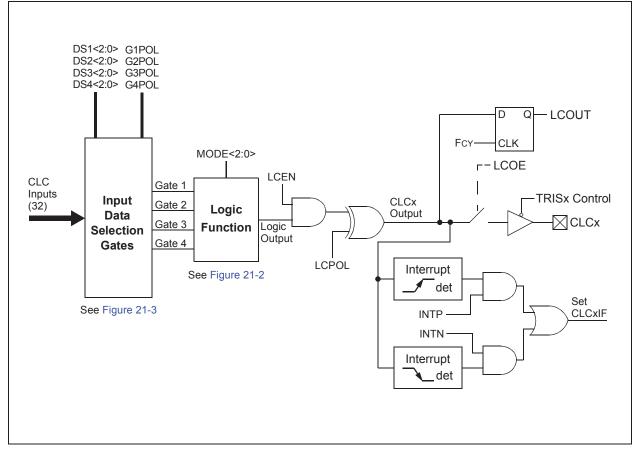
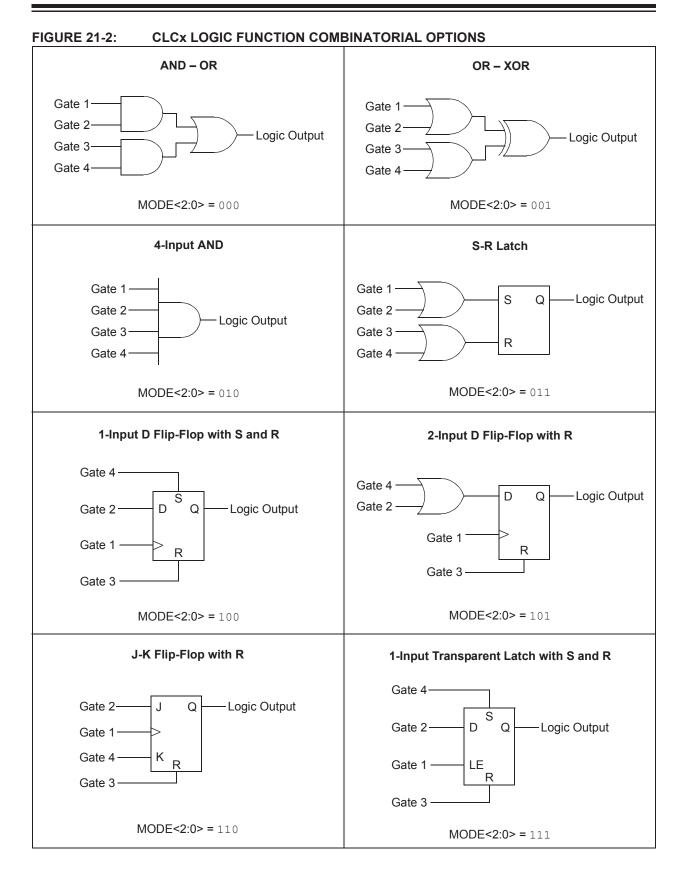
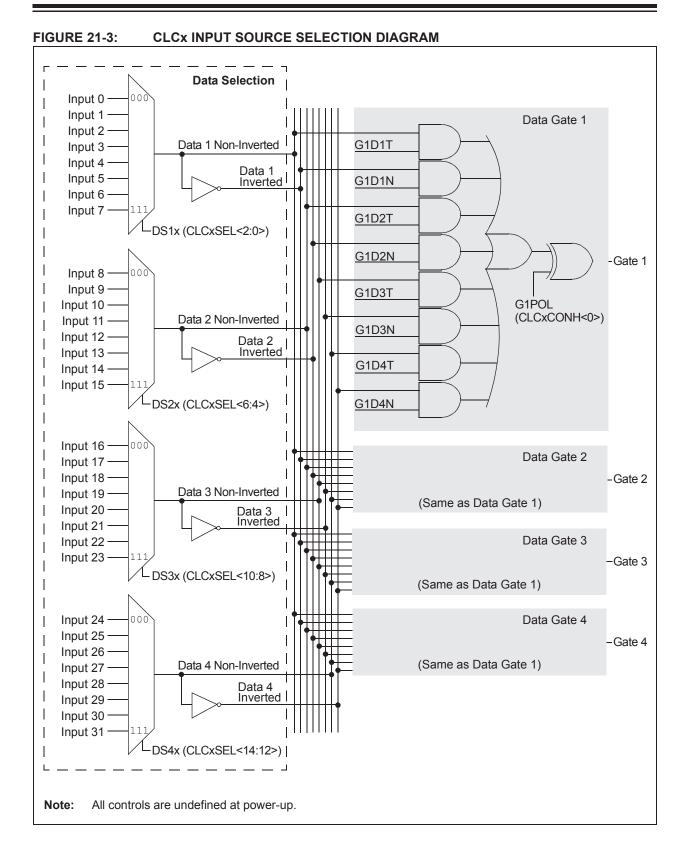


FIGURE 21-1: CLCx MODULE





21.1 Control Registers

The CLCx module is controlled by the following registers:

- CLCxCONL
- CLCxCONH
- CLCxSEL
- CLCxGLSL
- CLCxGLSH

The CLCx Control registers (CLCxCONL and CLCxCONH) are used to enable the module and interrupts, control the output enable bit, select output polarity and select the logic function. The CLCx Control registers also allow the user to control the logic polarity of not only the cell output, but also some intermediate variables. The CLCx Input MUX Select register (CLCxSEL) allows the user to select up to four data input sources using the four data input selection multiplexers. Each multiplexer has a list of eight data sources available.

The CLCx Gate Logic Input Select registers (CLCxGLSL and CLCxGLSH) allow the user to select which outputs from each of the selection MUXes are used as inputs to the input gates of the logic cell. Each data source MUX outputs both a true and a negated version of its output. All of these eight signals are enabled, ORed together by the logic cell input gates.

REGISTER 21-1: CLCxCONL: CLCx CONTROL REGISTER (LOW)

0 = CLCx is	U-0 		R/W-0 INTP U-0 U-0 U = Unimplen '0' = Bit is clea	R/W-0 INTN R/W-0 MODE2 hented bit, read	U-0 — R/W-0 MODE1 d as '0' x = Bit is unkn	U-0 bit 8 R/W-0 MODE0 bit 0
LCOUT Dit OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	UCPOL W = Writable k '1' = Bit is set Enable bit enabled and mix		U-0 — U = Unimplen	R/W-0 MODE2	MODE1	R/W-0 MODE0 bit 0
LCOUT Dit OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	UCPOL W = Writable k '1' = Bit is set Enable bit enabled and mix		U = Unimplen	MODE2	MODE1	R/W-0 MODE0 bit 0
LCOUT Dit OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	UCPOL W = Writable k '1' = Bit is set Enable bit enabled and mix		U = Unimplen	MODE2	MODE1	MODE0 bit 0
LCOUT Dit OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	UCPOL W = Writable k '1' = Bit is set Enable bit enabled and mix		U = Unimplen	MODE2	MODE1	MODE0 bit 0
Dit OR L CEN: CLCx 1 = CLCx is 0 = CLCx is	W = Writable b '1' = Bit is set Enable bit enabled and mix			nented bit, read	1 as '0'	bit 0
OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	'1' = Bit is set Enable bit enabled and mix					
OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	'1' = Bit is set Enable bit enabled and mix					nown
OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	'1' = Bit is set Enable bit enabled and mix					iown
OR LCEN: CLCx 1 = CLCx is 0 = CLCx is	'1' = Bit is set Enable bit enabled and mix					iown
LCEN: CLCx 1 = CLCx is 0 = CLCx is	Enable bit enabled and mix	vina input sia	'0' = Bit is clea	ared	x = Bit is unkn	iown
1 = CLCx is 0 = CLCx is	enabled and mix	vina input sia				
1 = CLCx is 0 = CLCx is	enabled and mix	vina innut sia				
0 = CLCx is			nale			
Jumplemen	ted: Read as '0	0				
NTP: CLCx	Positive Edge In	iterrupt Enabl	le bit			
	will be generate		ing edge occurs	on LCOUT		
	will not be gene					
	Negative Edge I	•				
	will be generate will not be gene		ling edge occurs	on LCOUT		
	nted: Read as '0					
•	Port Enable bit					
	rt pin output is e					
	rt pin output is d					
LCOUT: CLC	x Data Output S	Status bit				
1 = CLCx out						
o = CLCx out	•					
			od			
1 = The outp			Cu			
1 = The outp 0 = The outp).				
	CPOL: CLC	CPOL: CLCx Output Polari = The output of the module = The output of the module	CPOL: CLCx Output Polarity Control bit = The output of the module is inverted	 CPOL: CLCx Output Polarity Control bit The output of the module is inverted The output of the module is not inverted 	 CPOL: CLCx Output Polarity Control bit The output of the module is inverted The output of the module is not inverted 	 CPOL: CLCx Output Polarity Control bit The output of the module is inverted The output of the module is not inverted

REGISTER 21-1: CLCxCONL: CLCx CONTROL REGISTER (LOW) (CONTINUED)

- bit 2-0 MODE<2:0>: CLCx Mode bits
 - 111 = Single Input Transparent Latch with S and R
 - 110 = JK Flip-Flop with R
 - 101 = Two-Input D Flip-Flop with R
 - 100 = Single Input D Flip-Flop with S and R
 - 011 = SR Latch
 - 010 = Four-Input AND
 - 001 = Four-Input OR-XOR
 - 000 = Four-Input AND-OR

REGISTER 21-2: CLCxCONH: CLCx CONTROL REGISTER (HIGH)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	G4POL	G3POL	G2POL	G1POL
bit 7							bit 0

Legend:

Legena.				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-4	Unimplemented: Read as '0'
bit 3	G4POL: Gate 4 Polarity Control bit
	 1 = Channel 4 logic output is inverted when applied to the logic cell 0 = Channel 4 logic output is not inverted
bit 2	G3POL: Gate 3 Polarity Control bit
	 1 = Channel 3 logic output is inverted when applied to the logic cell 0 = Channel 3 logic output is not inverted
bit 1	G2POL: Gate 2 Polarity Control bit
	 1 = Channel 2 logic output is inverted when applied to the logic cell 0 = Channel 2 logic output is not inverted
bit 0	G1POL: Gate 1 Polarity Control bit
	1 = Channel 1 logic output is inverted when applied to the logic cell0 = Channel 1 logic output is not inverted

U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
_		DS4<2:0>		_		DS3<2:0>	
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
—		DS2<2:0>				DS1<2:0>	
bit 7							bit (
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimpler	nented bit, rea	d as '0'	
-n = Value a	at POR	'1' = Bit is set	'0' = Bit is cleared		ared	x = Bit is unknown	
bit 15	Unimplemer	nted: Read as ')'				
bit 14-12	DS4<2:0>: [ata Selection M	IUX 4 Signal	Selection bits			
	See Table 21	-1 for input sele	ctions.				
bit 11	Unimplemer	nted: Read as ')'				
bit 10-8	DS3<2:0>: [ata Selection M	IUX 3 Signal	Selection bits			
	See Table 21	-1 for input sele	ctions.				
bit 7	Unimplemer	nted: Read as ')'				
bit 6-4	DS2<2:0>: [ata Selection M	IUX 2 Signal	Selection bits			
		-1 for input sele	-				
bit 3	Unimplemer	nted: Read as ')'				
bit 2-0	-	ata Selection M		Selection bits			
-		-1 for input sele	•				
			-				

REGISTER 21-3: CLCxSEL: CLCx INPUT MUX SELECT REGISTER

	DSx<2:0>	Signal Source
	000	CLCINA
	001	System Clock
Λ	010	Timer1 Match
	011	PWM1H
DS1<2:0>	100	PWM5L
Δ	101	High-Speed PWM Clock
	110	Timer2 Match
	111	Timer3 Match
	000	CLCINB
	001	CLC2 Out
^	010	CMP1 Out
DS2<2:0>	011	UART1 TX Out
32<	100	ADC End-of-Conversion
ő	101	DMA Channel 0 Interrupt
	110	PWM1L
	111	PWM5H
	000	CLCINA
	001	CLC1 Out
^	010	CMP2 Out
5:0	011	SPI1 SDO Out
DS3<2:0>	100	UART1 RX
ä	101	PWM2H
	110	PWM6L
	111	OCMP2 Sync Output
	000	CLCINB
	001	CLC2 Out
<u> </u>	010	CMP3 Out
DS4<2:0>	011	SDI1
S4<	100	PTGO26
ă	101	ECAN1
	110	PWM2L
	111	PWM6H

TABLE 21-1:CLC1 MULTIPLEXER INPUT SOURCES

	D\$x<2:0>	Signal Source
	000	CLCINA
	001	System Clock
<u>^</u>	010	Timer1 Match
2:0	011	PWM3H
DS1<2:0>	100	PWM7L
Δ	101	High-Speed PWM Clock
	110	Timer2 Match
	111	Timer3 Match
	000	CLCINB
	001	CLC1 Out
٨	010	CMP1 Out
DS2<2:0>	011	UART2 TX Out
S2<	100	ADC End-of-Conversion
ő	101	DMA Channel 0 Interrupt
	110	PWM3L
	111	PWM7H
	000	CLCINA
	001	CLC2 Out
^	010	CMP2 Out
5:0	011	SPI2 SDO Out
DS3<2:0>	100	UART2 RX
Ō	101	PWM4H
	110	PWM8L
	111	OCMP2 Sync Output
	000	CLCINB
	001	CLC1 Out
^	010	CMP3 Out
DS4<2:0>	011	SDI2
S4<	100	PTGO27
Ó	101	ECAN1
	110	PWM4L
	111	PWM8H

TABLE 21-2: CLC2 MULTIPLEXER INPUT SOURCES

	D\$x<2:0>	Signal Source
	000	CLCINA
	001	System Clock
<u>^</u>	010	Timer1 Match
:2:0	011	PWM5H
DS1<2:0>	100	REFO1 Clock Output
	101	High-Speed PWM Clock
	110	Timer2 Match
	111	PWM3L
	000	CLCINB
	001	CLC4 Out
^	010	CMP1 Out
DS2<2:0>	011	PWM5L
S2<	100	ADC End-of-Conversion
ő	101	PWM3H
	110	ICAP1 Sync Output
	111	ICAP2 Sync Output
	000	CLCINA
	001	CLC3 Out
^	010	CMP2 Out
DS3<2:0>	011	PWM6H
23	100	UART1 RX
ő	101	DMA Channel 1 Interrupt
	110	OCMP1 Sync Output
	111	PWM4L
	000	CLCINB
	001	CLC4 Out
^	010	CMP3 Out
5:0	011	PWM6L
DS4<2:0>	100	PTGO28
ő	101	PWM4H
	110	PC_PWM
	111	OCMP3 Sync Output

TABLE 21-3: CLC3 MULTIPLEXER INPUT SOURCES

	DSx<2:0>	Signal Source
	000	CLCINA
	001	PWM7H
^	010	Timer1 Match
.2:0	011	INTOSC/LPRC Clock
DS1<2:0>	100	REFO1 Clock Output
Δ	101	High-Speed PWM Clock
	110	Timer2 Match
	111	PWM1L
	000	CLCINB
	001	CLC3 Out
^	010	CMP1 Out
5:0	011	PWM7L
DS2<2:0>	100	ADC End-of-Conversion
ă	101	PWM1H
	110	ICAP1 Sync Output
	111	ICAP2 Sync Output
	000	CLCINA
	001	CLC4 Out
^	010	CMP2 Out
DS3<2:0>	011	PWM8H
23<	100	UART2 RX
Ď	101	DMA Channel 1 Interrupt
	110	OCMP1 Sync Output
	111	PWM2L
	000	CLCINB
	001	CLC3 Out
^	010	CMP3 Out
DS4<2:0>	011	PWM8L
S4<	100	PTGO29
ö	101	PWM2H
	110	PWM Sync Output
	111	OCMP3 Sync Output

TABLE 21-4: CLC4 MULTIPLEXER INPUT SOURCES

REGISTER 21-4: CLCxGLSL: CLCx GATE LOGIC INPUT SELECT LOW REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
G2D4T	G2D4N	G2D3T	G2D3N	G2D2T	G2D2N	G2D1T	G2D1N			
bit 15	•			•		•	bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
G1D4T	G1D4N	G1D3T	G1D3N	G1D2T	G1D2N	G1D1T	G1D1N			
bit 7							bit 0			
Lananda										
Legend:	a hit		- i+		aantad hit raa					
R = Readabl		W = Writable k '1' = Bit is set	אנ	0 = Onimpien	nented bit, read					
-n = value at	PUR	I = DILIS SEL			areu	x = Bit is unkr	IOWI			
bit 15	G2D4T: Gate	2 Data Source	4 True Enable	bit						
bit to		rce 4 non-invert			2					
		rce 4 non-invert	•							
bit 14	G2D4N: Gate	2 Data Source	4 Negated Er	able bit						
		rce 4 inverted s	0							
bit 13		rce 4 inverted s	•							
DIL 15	012011 0440	G2D3T: Gate 2 Data Source 3 True Enable bit								
		 1 = Data Source 3 non-inverted signal is enabled for Gate 2 0 = Data Source 3 non-inverted signal is disabled for Gate 2 								
bit 12	G2D3N: Gate 2 Data Source 3 Negated Enable bit									
	1 = Data Source 3 inverted signal is enabled for Gate 2									
1.1.44		rce 3 inverted s	•							
bit 11	G2D2T: Gate 2 Data Source 2 True Enable bit 1 = Data Source 2 non-inverted signal is enabled for Gate 2									
		rce 2 non-invert								
bit 10		2 Data Source	-							
		rce 2 inverted s	0							
		rce 2 inverted s	•							
bit 9		2 Data Source			0					
		 1 = Data Source 1 non-inverted signal is enabled for Gate 2 0 = Data Source 1 non-inverted signal is disabled for Gate 2 								
bit 8		2 Data Source	•							
		rce 1 inverted s	•							
	0 = Data Sour	rce 1 inverted s	ignal is disable	ed for Gate 2						
bit 7		1 Data Source								
		rce 4 non-invert	•							
bit 6	 Data Source 4 non-inverted signal is disabled for Gate 1 G1D4N: Gate 1 Data Source 4 Negated Enable bit 									
bit o	G1D4N: Gate 1 Data Source 4 Negated Enable bit 1 = Data Source 4 inverted signal is enabled for Gate 1									
		rce 4 inverted s	•							
bit 5	G1D3T: Gate	1 Data Source	3 True Enable	bit						
		rce 3 non-invert	•							
L:1 /		rce 3 non-invert	-		91					
bit 4		1 Data Source	-							
		rce 3 inverted s rce 3 inverted s								

REGISTER 21-4: CLCxGLSL: CLCx GATE LOGIC INPUT SELECT LOW REGISTER (CONTINUED)

bit 3	G1D2T: Gate 1 Data Source 2 True Enable bit
	1 = Data Source 2 non-inverted signal is enabled for Gate 1
	0 = Data Source 2 non-inverted signal is disabled for Gate 1
bit 2	G1D2N: Gate 1 Data Source 2 Negated Enable bit
	 1 = Data Source 2 inverted signal is enabled for Gate 1 0 = Data Source 2 inverted signal is disabled for Gate 1
bit 1	G1D1T: Gate 1 Data Source 1 True Enable bit
	 1 = Data Source 1 non-inverted signal is enabled for Gate 1 0 = Data Source 1 non-inverted signal is disabled for Gate 1
bit 0	G1D1N: Gate 1 Data Source 1 Negated Enable bit
	1 = Data Source 1 inverted signal is enabled for Gate 1
	0 = Data Source 1 inverted signal is disabled for Gate 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
G4D4T	G4D4N	G4D3T	G4D3N	G4D2T	G4D2N	G4D1T	G4D1N
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| bit 7 | | | | | | | bit 0 |

egend:						
= Readable	e bit	W = Writable bit	U = Unimplemented bit	, read as '0'		
n = Value at	POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		
it 15	G4D4T: (Gate 4 Data Source 4 True E	nable bit			
	 1 = Data Source 4 non-inverted signal is enabled for Gate 4 0 = Data Source 4 non-inverted signal is disabled for Gate 4 					
it 14	G4D4N: Gate 4 Data Source 4 Negated Enable bit 1 = Data Source 4 inverted signal is enabled for Gate 4 0 = Data Source 4 inverted signal is disabled for Gate 4					
it 13	G4D3T: Gate 4 Data Source 3 True Enable bit 1 = Data Source 3 non-inverted signal is enabled for Gate 4 0 = Data Source 3 non-inverted signal is disabled for Gate 4					
it 12	G4D3N: 1 = Data	Gate 4 Data Source 3 Negati Source 3 inverted signal is e Source 3 inverted signal is d	ed Enable bit nabled for Gate 4			
it 11	G4D2T: (1 = Data	Gate 4 Data Source 2 True E Source 2 non-inverted signa Source 2 non-inverted signa	nable bit I is enabled for Gate 4			
it 10	G4D2N: 1 = Data	Gate 4 Data Source 2 Negati Source 2 inverted signal is e Source 2 inverted signal is d	ed Enable bit nabled for Gate 4			
it 9	G4D1T: (1 = Data	Gate 4 Data Source 1 True E Source 1 non-inverted signa Source 1 non-inverted signa	nable bit I is enabled for Gate 4			
it 8	G4D1N: 1 = Data	Gate 4 Data Source 1 Negate Source 1 inverted signal is e Source 1 inverted signal is d	ed Enable bit nabled for Gate 4			
it 7	G3D4T: (1 = Data	Gate 3 Data Source 4 True E Source 4 non-inverted signa Source 4 non-inverted signa	nable bit I is enabled for Gate 3			
it 6	G3D4N: 1 = Data	Gate 3 Data Source 4 Negate Source 4 inverted signal is e Source 4 inverted signal is d	ed Enable bit nabled for Gate 3			
it 5	G3D3T: (1 = Data	Gate 3 Data Source 3 True E Source 3 non-inverted signa Source 3 non-inverted signa	nable bit I is enabled for Gate 3			
it 4	G3D3N: 1 = Data	Gate 3 Data Source 3 Negate Source 3 inverted signal is e Source 3 inverted signal is d	ed Enable bit nabled for Gate 3			

REGISTER 21-5: CLCxGLSH: CLCx GATE LOGIC INPUT SELECT HIGH REGISTER (CONTINUED)

bit 3	G3D2T: Gate 3 Data Source 2 True Enable bit
	1 = Data Source 2 non-inverted signal is enabled for Gate 3
	0 = Data Source 2 non-inverted signal is disabled for Gate 3
bit 2	G3D2N: Gate 3 Data Source 2 Negated Enable bit
	 1 = Data Source 2 inverted signal is enabled for Gate 3 0 = Data Source 2 inverted signal is disabled for Gate 3
bit 1	G3D1T: Gate 3 Data Source 1 True Enable bit
	 1 = Data Source 1 non-inverted signal is enabled for Gate 3 0 = Data Source 1 non-inverted signal is disabled for Gate 3
bit 0	G3D1N: Gate 3 Data Source 1 Negated Enable bit
	1 = Data Source 1 inverted signal is enabled for Gate 3
	0 = Data Source 1 inverted signal is disabled for Gate 3

22.0 HIGH-SPEED, 12-BIT ANALOG-TO-DIGITAL CONVERTER (ADC)

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "12-Bit High-Speed, Multiple SARs A/D Converter (ADC)" (DS70005213) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

dsPIC33EPXXXGS70X/80X devices have a high-speed, 12-bit Analog-to-Digital Converter (ADC) that features a low conversion latency, high resolution and oversampling capabilities to improve performance in AC/DC, DC/DC power converters.

22.1 Features Overview

The high-speed, 12-bit multiple SARs Analog-to-Digital Converter (ADC) includes the following features:

- Five ADC Cores: Four Dedicated Cores and One Shared (common) Core
- User-Configurable Resolution of up to 12 Bits for each Core
- Up to 3.25 Msps Conversion Rate per Channel at 12-Bit Resolution
- Low Latency Conversion
- Up to 22 Analog Input Channels, with a Separate 16-Bit Conversion Result Register for each Input
- Conversion Result can be Formatted as Unsigned or Signed Data, on a per Channel Basis, for All Channels
- Single-Ended and Pseudodifferential Conversions are available on All ADC Cores

- Simultaneous Sampling of up to Five Analog Inputs
- Channel Scan Capability
- Multiple Conversion Trigger Options for each Core, including:
 - PWM1 through PWM6 (primary and secondary triggers, and current-limit event trigger)
 - PWM Special Event Trigger
 - Timer1/Timer2 period match
 - Output Compare 1 and event trigger
 - External pin trigger event (ADTRG31)
 - Software trigger
- Two Integrated Digital Comparators with Dedicated Interrupts:
 - Multiple comparison options
 - Assignable to specific analog inputs
- Two Oversampling Filters with Dedicated Interrupts:
 - Provide increased resolution
 - Assignable to a specific analog input

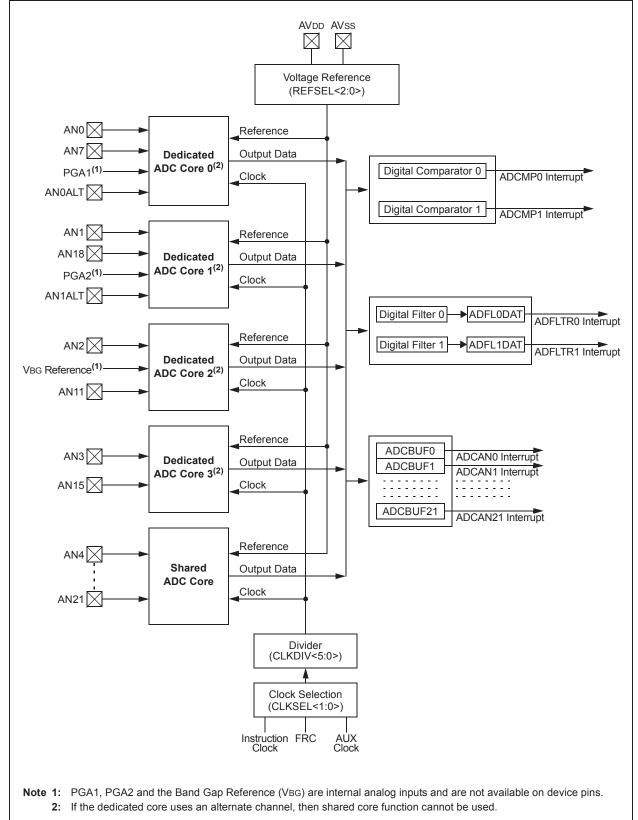
The module consists of five independent SAR ADC cores. Simplified block diagrams of the multiple SARs 12-bit ADC are shown in Figure 22-1, Figure 22-2 and Figure 22-3.

The analog inputs (channels) are connected through multiplexers and switches to the Sample-and-Hold (S&H) circuit of each ADC core. The core uses the channel information (the output format, the Measurement mode and the input number) to process the analog sample. When conversion is complete, the result is stored in the result buffer for the specific analog input, and passed to the digital filter and digital comparator if they were configured to use data from this particular channel.

The ADC module can sample up to five inputs at a time (four inputs from the dedicated SAR cores and one from the shared SAR core). If multiple ADC inputs request conversion on the shared core, the module will convert them in a sequential manner, starting with the lowest order input.

The ADC provides each analog input the ability to specify its own trigger source. This capability allows the ADC to sample and convert analog inputs that are associated with PWM generators operating on independent time bases.





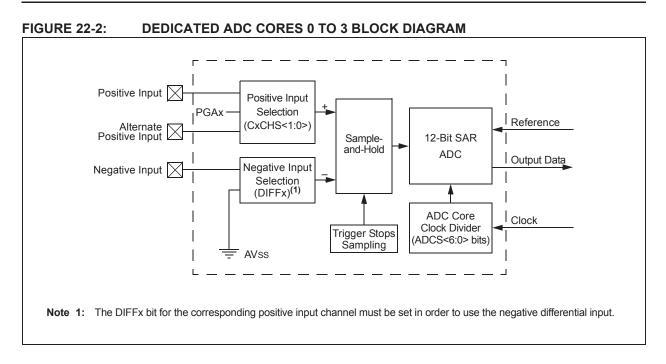
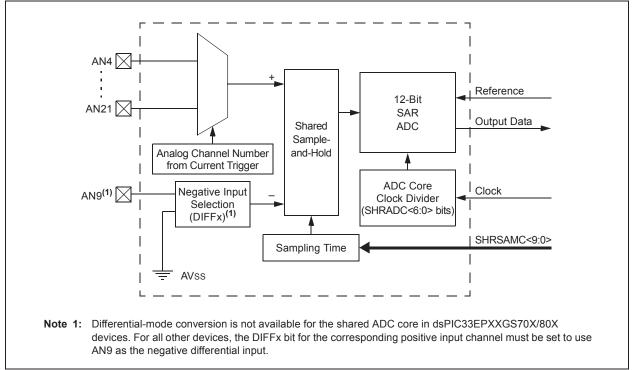


FIGURE 22-3: SHARED ADC CORE BLOCK DIAGRAM



22.2 Analog-to-Digital Converter Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

22.2.1 KEY RESOURCES

- "12-Bit High-Speed, Multiple SARs A/D Converter (ADC)" (DS70005213) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

REGISTER 22-1: ADCON1L: ADC CONTROL REGISTER 1 LOW

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0	
ADON ⁽¹)	ADSIDL	—	_	_	_	_	
bit 15	pit 15							
R/W-0		r-0	r-0	r-0	U-0	U-0	U-0	
NRE ⁽²⁾	—	—	—		_	—		
bit 7							bit 0	
Logondu		r = Reserved	- it					
Legend:								
R = Reada			DIL					
-n = Value at POR '1' = Bit is				'0' = Bit is cle	ared	x = Bit is unkr	nown	
bit 15		Enable bit(1)						
DIL 15		ADON: ADC Enable bit ⁽¹⁾ 1 = ADC module is enabled						
		0 = ADC module is off						
bit 14	Unimpleme	nted: Read as 'd)'					
bit 13	ADSIDL: AD	ADSIDL: ADC Stop in Idle Mode bit						
		 1 = Discontinues module operation when device enters Idle mode 0 = Continues module operation in Idle mode 						
bit 12-8	Unimpleme	Unimplemented: Read as '0'						
bit 7	NRE: Noise	Reduction Enab	le bit ⁽²⁾					
		onversion proce	ss for one TAE	CORE when an	other core con	npletes conver	sion to reduce	
		noise between cores 0 = Noise reduction feature is disabled						
bit 6-3		laintain as '0'	is uisableu					
bit 0-3		nted: Read as '0	۱,					
DIL 2-0	ommpieme	inted. Nead as)					
Note 1:	Set the ADON bi ADON = 1 will re				red. Changing	ADC Configura	ation bits when	
2:	between ADC co	DON = 1 will result in unpredictable behavior. the NRE bit in the ADCON1L register is set, the end of conversion time is adjusted to reduce the noise etween ADC cores. Depending on the number of cores converting and the priority of the input, a few						

additional TADs may be inserted, making the conversion time slightly less deterministic.

REGISTER 22-2: ADCON1H: ADC CONTROL REGISTER 1 HIGH

r-0	r-0	r-0	r-0	r-0	r-0	r-0	r-0
—	—	—	—	—	—	—	—
bit 15 bit 8						bit 8	

R/W-0	R/W-1	R/W-1	r-0	r-0	r-0	r-0	r-0
FORM	SHRRES1	SHRRES0	—	—	—	—	—
bit 7 bit						bit 0	

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Reserved: Maintain as '0'	bit 15-8	Reserved: Maintain as '0'
---	----------	---------------------------

bit 7 FORM: Fractional Data Output Format bit

1 = Fractional

0 = Integer

bit 6-5 SHRRES<1:0>: Shared ADC Core Resolution Selection bits

- 11 = 12-bit resolution
- 10 = 10-bit resolution
- 01 = 8-bit resolution
- 00 = 6-bit resolution
- bit 4-0 Reserved: Maintain as '0'

R/W-0	R/W-0	r-0	R/W-0	r-0	R/W-0	R/W-0	R/W-0	
REFCIE	REFERCIE	_	EIEN	_	SHREISEL2(1) SHREISEL1 ⁽¹⁾	SHREISEL0(1)	
bit 15							bit 8	
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—				SHRADCS	<6:0>			
bit 7							bit 0	
Legend:		r = Reserved	bit					
R = Reada	able bit	W = Writable	bit	U = Unimple	emented bit, rea	d as '0'		
-n = Value at POR		'1' = Bit is set		'0' = Bit is c	leared	x = Bit is unkno	x = Bit is unknown	
bit 15	1 = Commor 0 = Commor	n interrupt will b n interrupt is dis	e generated v abled for the	when the ban band gap rea	•	ne ready		
bit 14	1 = Commor	n interrupt will b	e generated v	when a band	mmon Interrupt gap or reference d reference volta	e voltage error is o	detected	
bit 13	Reserved: N	/aintain as '0'						
bit 12	EIEN: Early Interrupts Enable bit							
						ots (when the EIS ⁻ when the ANxRD`		
bit 11	Reserved: N	/laintain as '0'						
bit 10-8	SHREISEL<	2:0>: Shared C	ore Early Inte	errupt Time S	election bits ⁽¹⁾			
	110 = Early i 101 = Early i 100 = Early i 011 = Early i 010 = Early i 001 = Early i	111 = Early interrupt is set and interrupt is generated eight TADCORE clocks prior to when the data is rea 101 = Early interrupt is set and interrupt is generated seven TADCORE clocks prior to when the data is rea 101 = Early interrupt is set and interrupt is generated six TADCORE clocks prior to when the data is rea 100 = Early interrupt is set and interrupt is generated five TADCORE clocks prior to when the data is rea 101 = Early interrupt is set and interrupt is generated five TADCORE clocks prior to when the data is rea 100 = Early interrupt is set and interrupt is generated four TADCORE clocks prior to when the data is rea 011 = Early interrupt is set and interrupt is generated three TADCORE clocks prior to when the data is rea 010 = Early interrupt is set and interrupt is generated three TADCORE clocks prior to when the data is rea 001 = Early interrupt is set and interrupt is generated two TADCORE clocks prior to when the data is rea 000 = Early interrupt is set and interrupt is generated one TADCORE clocks prior to when the data is rea					the data is ready he data is ready	
bit 7	Unimpleme	nted: Read as	0'					
bit 6-0	SHRADCS<	6:0>: Shared A	DC Core Inpu	ut Clock Divid	er bits			
	Clock Period			RESRC (Sourc	e Clock Periods	s) for one shared	TADCORE (Core	
	•							
	0000010 = 2 0000001 = 2	 Source Clock Source Clock Source Clock Source Clock Source Clock 	Periods Periods					
Note 1:		1', are not valid	l and should r	ot be used. F	or the 8-bit shar	ISEL<2:0> setting ed ADC core reso not valid and shou	lution	

REGISTER 22-4: ADCON2H: ADC CONTROL REGISTER 2 HI

HSC/R-0	HSC/R-0	r-0	r-0	r-0	r-0	R/W-0	R/W-0	
REFRDY	REFERR			—	—	SHRSA	VC<9:8>	
bit 15	L.			•			bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
			SHRSAI	MC<7:0>				
bit 7							bit (
Lonordi			.:4			d aa '0'		
Legend:	-			U = Unimplem				
	R = Readable bit W = Writable bit		DIT	HSC = Hardware Settable/Clearable bit				
-n = Value at POR (1' = Bit is set				'0' = Bit is clea	ared	x = Bit is unkn	own	
bit 14	 1 = Band gap is ready 0 = Band gap is not ready REFERR: Band Gap or Reference Voltage Error Flag bit 1 = Band gap was removed after the ADC module was enabled (ADON = 1) 0 = No band gap error was detected 							
bit 13-10	Reserved: Ma	aintain as '0'						
bit 9-0				le Time Selection C Core Clock		ORE) for the sha	ared ADC core	

	REGISTER 22-5:	ADCON3L: ADC CONTROL REGISTER 3 LOW
--	----------------	-------------------------------------

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	HSC/R-0	R/W-0	HSC/R-0
REFSEL2	REFSEL1	REFSEL0	SUSPEND	SUSPCIE	SUSPRDY	SHRSAMP	CNVRTCH
bit 15							bit 8

R/W-0	HSC/R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SWLCTRG	SWCTRG	CNVCHSEL5	CNVCHSEL4	CNVCHSEL3	CNVCHSEL2	CNVCHSEL1	CNVCHSEL0
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'					
R = Readable bit	W = Writable bit	HSC = Hardware Settable/C	Clearable bit			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-13 **REFSEL<2:0>:** ADC Reference Voltage Selection bits

Value	VREFH	VREFL
000	AVdd	AVss

001-111 = Unimplemented: Do not use bit 12 SUSPEND: All ADC Cores Triggers Disable bit 1 = All new trigger events for all ADC cores are disabled 0 = All ADC cores can be triggered bit 11 SUSPCIE: Suspend All ADC Cores Common Interrupt Enable bit 1 = Common interrupt will be generated when ADC core triggers are suspended (SUSPEND bit = 1) and all previous conversions are finished (SUSPRDY bit becomes set) 0 = Common interrupt is not generated for suspend ADC cores event bit 10 SUSPRDY: All ADC Cores Suspended Flag bit 1 = All ADC cores are suspended (SUSPEND bit = 1) and have no conversions in progress 0 = ADC cores have previous conversions in progress bit 9 SHRSAMP: Shared ADC Core Sampling Direct Control bit This bit should be used with the individual channel conversion trigger controlled by the CNVRTCH bit. It connects an analog input, specified by the CNVCHSEL<5:0> bits, to the shared ADC core and allows extending the sampling time. This bit is not controlled by hardware and must be cleared before the conversion starts (setting CNVRTCH to '1'). 1 = Shared ADC core samples an analog input specified by the CNVCHSEL<5:0> bits 0 = Sampling is controlled by the shared ADC core hardware bit 8 **CNVRTCH:** Software Individual Channel Conversion Trigger bit 1 = Single trigger is generated for an analog input specified by the CNVCHSEL<5:0> bits; when the bit is set, it is automatically cleared by hardware on the next instruction cycle 0 = Next individual channel conversion trigger can be generated bit 7 SWLCTRG: Software Level-Sensitive Common Trigger bit 1 = Triggers are continuously generated for all channels with the software, level-sensitive common trigger selected as a source in the ADTRIGxL and ADTRIGxH registers 0 = No software, level-sensitive common triggers are generated bit 6 SWCTRG: Software Common Trigger bit 1 = Single trigger is generated for all channels with the software, common trigger selected as a source in the ADTRIGxL and ADTRIGxH registers; when the bit is set, it is automatically cleared by hardware on the next instruction cycle 0 = Ready to generate the next software common trigger bit 5-0 CNVCHSEL <5:0>: Channel Number Selection for Software Individual Channel Conversion Trigger bits

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CLKSEL1	CLKSEL0	CLKDIV5	CLKDIV4	CLKDIV3	CLKDIV2	CLKDIV1	CLKDIV0
bit 15			-		-	_	bit 8
R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
SHREN		_	_	C3EN	C2EN	C1EN	C0EN
bit 7		•					bit C
Legend:							
R = Readable	e bit	W = Writable	bit		nented bit, rea		
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
bit 15-14	11 = APLL 10 = FRC	>: ADC Module ystem Clock x : /stem Clock)		Selection bits			
	module clock TCORESRC clo register or the 111111 = 64	source selecte	d by the CLKS re-specific TAD :0> bits in the A Periods eriods eriods eriods	EL<1:0> bits. T CORE clock us	hen, each AD	dedicated) from C core individua <6:0> bits in th	ally divides the
bit 7	1 = Shared Al	red ADC Core I DC core is ena DC core is disa	bled				
bit 6-4	Unimplement	ted: Read as ')'				
bit 3	1 = Dedicated	ated ADC Core I ADC Core 3 is I ADC Core 3 is	s enabled				
bit 2	1 = Dedicated	ated ADC Core I ADC Core 2 is I ADC Core 2 is	s enabled				
bit 1	1 = Dedicated	ated ADC Core I ADC Core 1 is I ADC Core 1 is	senabled				
bit 0	1 = Dedicated	ated ADC Core I ADC Core 0 is I ADC Core 0 is	s enabled				

REGISTER 22-6: ADCON3H: ADC CONTROL REGISTER 3 HIGH

REGISTER 22-7: ADCON4L: ADC CONTROL REGISTER 4 LOW										
U-0	U-0	U-0	U-0	U-0	U-0	U-0				
_	_	—	_	—	—					
						bit 8				
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0				
			SAMC3EN	SAMC2EN	SAMC1EN	SAMC0EN				
						bit 0				
le bit	W = Writable I	oit	U = Unimplem	nented bit, read	l as '0'					
t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown				
Unimplemer	nted: Read as '0)'								
			•							
1 = After trigger, the conversion will be delayed and the ADC core will continue sampling during the										
					version will be	started on the				
•		.9 20 0.01		.,						
SAMC2EN:	Dedicated ADC	Core 2 Conve	ersion Delay Ena	able bit						
					continue samp	ling during the				
		ig will be stop		ly and the con-		started on the				
	,	Core 1 Conve	ersion Delay Ena	able bit						
					continue samp	ling during the				
time spe	cified by the SA	MC<9:0> bits	in the ADCORE	n the ADCORE1L register						
0 = After trigger, the sampling will be stopped immediately and the conversion will be started on the										
			,		continue samo	ling during the				
					sommue samp					
0 = After trig	ger, the samplin				version will be	started on the				
next core	e clock cycle									
	U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0	U-0 U-0 U-0 U-0 D-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0 U-0	U-0 U-0 U-0 U-0 U-0 U	U-0 U-0 U-0 U-0 U-0 U-0 U-0 R/W-0 U-0 U-0 U-0 R/W-0 Image: Imag	U-0 U-0 U-0 U-0 U-0 — — — — — U-0 U-0 U-0 R/W-0 R/W-0 — — — — — U-0 U-0 U-0 R/W-0 R/W-0 — — — — — He bit W = Writable bit U = Unimplemented bit, read tPOR '1' = Bit is set '0' = Bit is cleared Unimplemented: Read as '0' SAMC3EN: Dedicated ADC Core 3 Conversion Delay Enable bit 1 = After trigger, the conversion will be delayed and the ADC core will ot time specified by the SAMC<9:0> bits in the ADCORE3L register 0 = After trigger, the sampling will be stopped immediately and the conversion ext core clock cycle SAMC2EN: Dedicated ADC Core 2 Conversion Delay Enable bit 1 = After trigger, the sampling will be stopped immediately and the conversion ext core clock cycle SAMC1EN: Dedicated ADC Core 1 Conversion Delay Enable bit 1 = After trigger, the conversion will be delayed and the ADC core will ot time specified by the SAMC<9:0> bits in the ADCORE1L register 0 = After trigger, the sampling will be stopped immediately and the conversencock cycle S	U-0 U-0 U-0 U-0 U-0 U-0 - - - - - - U-0 U-0 U-0 R/W-0 R/W-0 R/W-0 - - - - - - U-0 U-0 U-0 R/W-0 R/W-0 R/W-0 - - - - - - - U-0 U-0 U-0 R/W-0 R/W-0 R/W-0 - - - - SAMC3EN SAMC1EN Unimplemented: Read as '0' SAMC3EN: Dedicated ADC Core 3 Conversion Delay Enable bit 1 After trigger, the conversion will be delayed and the ADC core will continue samp time specified by the SAMC<9:0> bits in the ADCORE3L register 0 After trigger, the sampling will be stopped immediately and the conversion will be next core clock cycle SAMC2EN: Dedicated ADC Core 2 Conversion Delay Enable bit 1 After trigger, the sampling will be stopped immediately and the conversion will be next core clock cycle SAMC1EN: Dedicated ADC Core 1 Conversion Delay Enable bit 1 After trigger, the conversion will be delayed and the ADC core will continue samp time specified by the SAMC<9:0> bits in the ADCORE1L register 0				

REGISTER 22-7: ADCON4L: ADC CONTROL REGISTER 4 LOW

REGISTER 22-8: ADCON4H: ADC CONTROL REGISTER 4 HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
_	—	—	_	—	—	—	_			
bit 15					•	•	bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
C3CHS1	C3CHS0	C2CHS1	C2CHS0	C1CHS1	C1CHS0	COCHS1	COCHSO			
bit 7	0001100	0201101	0201100		0101100	0001101	bit (
Legend:										
R = Readabl	e bit	W = Writable	bit	U = Unimplen	nented bit, read	l as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown			
bit 5-4	00 = AN3 C2CHS<1:0> 11 = Reserve 10 = VREF ba 01 = AN11 (d 00 = AN2	C2CHS<1:0>: Dedicated ADC Core 2 Input Channel Selection bits 11 = Reserved 10 = VREF band gap 01 = AN11 (differential negative input when DIFF2 (ADMOD0L<5>) = 1)								
bit 3-2	11 = AN1ALT 10 = PGA2	▶: Dedicated AE Γ differential nega	·							
bit 1-0	11 = AN0ALT 10 = PGA1	Dedicated AE f fferential negati	·							

HSC/R-0	U-0	U-0	U-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0			
SHRRDY	_	_		C3RDY	C2RDY	C1RDY	CORDY			
bit 15			•		I		bit a			
R/W-0	U-0	U-0	U-0		R/W-0	R/W-0				
SHRPWR	0-0	0-0	0-0	R/W-0 C3PWR	C2PWR	C1PWR	R/W-0 C0PWR			
bit 7	—	—	_	CJEWK	02FWR	CIEWK	bit			
Legend:		U = Unimplen	nented bit, rea	ad as 'O'						
R = Readabl	e bit	W = Writable	bit	HSC = Hardw	are Settable/Cl	earable bit				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown			
bit 15	SHRRDY: Sh	ared ADC Core	e Readv Flag	bit						
	1 = ADC core	e is powered an e is not ready fo	d ready for or							
bit 14-12	Unimplemen	ted: Read as '	כי							
bit 11	C3RDY: Dedi	icated ADC Co	re 3 Ready Fl	ag bit						
		e is powered an e is not ready fo		peration						
bit 10	C2RDY: Dedicated ADC Core 2 Ready Flag bit									
	1 = ADC core is powered and ready for operation									
bit 9	 0 = ADC core is not ready for operation C1RDY: Dedicated ADC Core 1 Ready Flag bit 									
DIL 9		is powered an		•						
		e is not ready fo								
bit 8	CORDY: Dedicated ADC Core 0 Ready Flag bit									
		e is powered an e is not ready fo		peration						
bit 7				able hit						
	SHRPWR: Shared ADC Core x Power Enable bit 1 = ADC Core x is powered									
	0 = ADC Core	•								
bit 6-4	Unimplemen	ted: Read as '	כי							
bit 3		licated ADC Co	ore 3 Power E	nable bit						
	1 = ADC core									
bit 2	 a ADC core is off C2PWR: Dedicated ADC Core 2 Power Enable bit 									
SIL Z	1 = ADC core									
	0 = ADC core is off									
bit 1		licated ADC Co	ore 1 Power E	nable bit						
	1 = ADC core 0 = ADC core									
bit 0		licated ADC Co	ore 0 Power E	nable bit						
	1 = ADC core									

REGISTER 22-10: ADCON5H: ADC CONTROL REGISTER 5 HIGH

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0					
_	_	_	_	10000		ME<3:0>	1044.0					
bit 15							bit 8					
R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0					
SHRCIE		—		C3CIE	C2CIE	C1CIE	COCIE					
bit 7							bit 0					
Legend:						(0)						
R = Readab		W = Writable		•	ented bit, read							
-n = Value a	IT POR	'1' = Bit is set	['0' = Bit is clea	ared	x = Bit is unkn	iown					
bit 15-12	Unimplomo	nted: Read as	٠́٠'									
bit 11-8	-			x Power-up Del	av bits							
bit II o				in the number o	-	rce Clock Perio	ds (Tcoresrc)					
	for all ADC of	cores.					, , , , , , , , , , , , , , , , , , ,					
		1111 = 32768 Source Clock Periods										
		1110 = 16384 Source Clock Periods 1101 = 8192 Source Clock Periods										
		1101 = 8192 Source Clock Periods 1100 = 4096 Source Clock Periods										
		1011 = 2048 Source Clock Periods										
		1010 = 1024 Source Clock Periods										
		1001 = 512 Source Clock Periods 1000 = 256 Source Clock Periods										
		Source Clock F Source Clock F										
		Source Clock Pe										
		Source Clock Pe										
		Source Clock Pe										
		Source Clock Pe										
bit 7			-	non Interrupt Er								
		•	•	when ADC core	•	ready for oper	ation					
bit 6-4		nted: Read as										
bit 3	-			mmon Interrupt	Enable bit							
			-	vhen ADC Core		nd ready for op	peration					
	0 = Commo	n interrupt is dis	sabled for an A	DC Core 3 read	dy event							
bit 2				ommon Interrupt								
				when ADC Core		nd ready for op	peration					
bit 1		-		DC Core 2 read	-							
bit 1			-	mmon Interrupt		nd roady for an	oration					
				when ADC Core		nu ready for op	Deration					
bit 0		-		mmon Interrupt	-							
			-	when ADC Core		nd ready for or	peration					
				DC Core 0 read		J						

REGISTER 22-11: ADCOREXL: DEDICATED ADC CORE x CONTROL REGISTER LOW (x = 0 to 3)

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0				
—	—	—	—	—	—	SAMC<9:8>					
bit 15							bit 8				
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
			SAM	C<7:0>							
bit 7							bit 0				
Legend:											
R = Readab	le bit	W = Writable b	it	U = Unimplemented bit, read as '0'							
-n = Value at POR		'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unknown					
bit 15-10	Unimpleme	nted: Read as '0	,								
bit 9-0	SAMC<9:0>	: Dedicated ADC	Core x Conv	ersion Delay Se	election bits						
		These bits determine the time between the trigger event and the start of conversion in the number of									

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
_	—	_	EISEL2	EISEL1	EISEL0	RES1	RES0
bit 15				·		•	bit
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
				ADCS<6:0>			
bit 7							bit
Legend:							
R = Readal	ble bit	W = Writable	bit	U = Unimplem	nented bit, read	as '0'	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own
bit 15-13	Unimplemen	ted: Read as ')'				
bit 12-10	EISEL<2:0>:	ADC Core x Ea	rly Interrupt Tin	ne Selection bits	6		
bit 9-8	001 = Early in 000 = Early in	terrupt is set an terrupt is set an DC Core x Res solution solution olution	d an interrupt is d an interrupt is	generated three generated two s generated one on bits	TADCORE clocks	prior to when th	e data is read
bit 7	Unimplemen	ted: Read as ')'				
bit 6-0	ADCS<6:0>:	ADC Core x In	put Clock Divid	ler bits			
	(TADCORE).	etermine the n 54 Source Cloc		rce Clock Peric	ods (TCORESRC) for one Core	Clock Peric
	0000010 = 4 0000001 = 2	Source Clock I Source Clock I Source Clock I Source Clock I	⊃eriods ⊃eriods				
	For the 6-bit ADC not valid and shou						

settings, '110' and '111', are not valid and should not be used.

REGISTER 22-12: ADCORExH: DEDICATED ADC CORE x CONTROL REGISTER HIGH (x = 0 to 3)⁽¹⁾

REGISTER 22-13: ADLVLTRGL: ADC LEVEL-SENSITIVE TRIGGER CONTROL REGISTER LOW

R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
			LVLE	N<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			LVLE	EN<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable b	ritable bit U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown			nown				

bit 15-0 LVLEN<15:0>: Level Trigger for Corresponding Analog Input Enable bits

1 = Input trigger is level-sensitive

0 = Input trigger is edge-sensitive

REGISTER 22-14: ADLVLTRGH: ADC LEVEL-SENSITIVE TRIGGER CONTROL REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—			LVLEN•	<21:16>		
bit 7							bit 0

Legend:				
R = Readable bit	W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-6 Unimplemented: Read as '0'

bit 5-0 LVLEN<21:16>: Level Trigger for Corresponding Analog Input Enable bits

1 = Input trigger is level-sensitive

0 = Input trigger is edge-sensitive

REGISTER 22-15: ADEIEL: ADC EARLY INTERRUPT ENABLE REGISTER LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			EIEN<	<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			EIEN	<7:0>			
bit 7							bit 0
Legend:							

Logona.					
R = Readable bit	W = Writable bit	Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-0 EIEN<15:0>: Early Interrupt Enable for Corresponding Analog Inputs bits

1 = Early interrupt is enabled for the channel

0 = Early interrupt is disabled for the channel

REGISTER 22-16: ADEIEH: ADC EARLY INTERRUPT ENABLE REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
—	_	—	—	—	_	—	—	
bit 15							bit 8	
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
_	_			EIEN<	:21:16>			
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'				

'0' = Bit is cleared

bit 15-6 **Unimplemented:** Read as '0'

-n = Value at POR

bit 5-0 **EIEN<21:16>:** Early Interrupt Enable for Corresponding Analog Inputs bits

1 = Early interrupt is enabled for the channel

'1' = Bit is set

0 = Early interrupt is disabled for the channel

x = Bit is unknown

REGISTER 22-17: ADEISTATL: ADC EARLY INTERRUPT STATUS REGISTER LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			EIST	AT<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			EIST	AT<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit U = Unimpleme			nented bit, rea	d as '0'			
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit 15-0 EISTAT<15:0>: Early Interrupt Status for Corresponding Analog Inputs bits

1 = Early interrupt was generated

0 = Early interrupt was not generated since the last ADCBUFx read

REGISTER 22-18: ADEISTATH: ADC EARLY INTERRUPT STATUS REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15	·	•		•		•	bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—			EISTAT	<21:16>		
bit 7	·	•					bit 0
l egend.							

Legena:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-6 Unimplemented: Read as '0'

bit 5-0 EISTAT<21:16>: Early Interrupt Status for Corresponding Analog Inputs bits

1 = Early interrupt was generated

0 = Early interrupt was not generated since the last ADCBUFx read

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIFF7	SIGN7	DIFF6	SIGN6	DIFF5	SIGN5	DIFF4	SIGN4
bit 15			•	•	•		bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIFF3	SIGN3	DIFF2	SIGN2	DIFF1	SIGN1	DIFF0	SIGN0
bit 7			•	•	•		bit 0

REGISTER 22-19: ADMOD0L: ADC INPUT MODE CONTROL REGISTER 0 LOW

Legend:				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-1(odd) DIFF<7:0>: Differential-Mode for Corresponding Analog Inputs bits

- 1 = Channel is differential
- 0 = Channel is single-ended

bit 14-0 (even) SIGN<7:0>: Output Data Sign for Corresponding Analog Inputs bits

- 1 = Channel output data is signed
- 0 = Channel output data is unsigned

REGISTER 22-20: ADMOD0H: ADC INPUT MODE CONTROL REGISTER 0 HIGH

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIFF15	SIGN15	DIFF14	SIGN14	DIFF13	SIGN13	DIFF12	SIGN12
bit 15	1			•	I		bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIFF11	SIGN11	DIFF10	SIGN10	DIFF9	SIGN9	DIFF8	SIGN8
bit 7				·			bit 0
Legend:							
R = Readable bit W = Writable bit		oit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set		'0' = Bit is cleared x = Bit is unknown			nown		

DIFF<15:8>: Differential-Mode for Corresponding Analog Inputs bits bit 15-1(odd)

1 = Channel is differential

0 = Channel is single-ended

bit 14-0 (even) SIGN<15:8>: Output Data Sign for Corresponding Analog Inputs bits

- 1 = Channel output data is signed
- 0 = Channel output data is unsigned

REGISTER 22-21: ADMOD1L: ADC INPUT MODE CONTROL REGISTER 1 LOW

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	—	_	DIFF21	SIGN21	DIFF20	SIGN20
bit 15	•						bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIFF19	SIGN19	DIFF18	SIGN18	DIFF17	SIGN17	DIFF16	SIGN16
bit 7							bit 0
Legend:							
D - Doodabla	bit	M = M/ritoblo I	ait	II – Unimplon	contod bit road	1 00 '0'	

R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 Unimplemented: Read as '0'

bit 11-1(odd) DIFF<21:16>: Differential-Mode for Corresponding Analog Inputs bits

1 = Channel is differential

0 = Channel is single-ended

bit 10-0 (even) **SIGN<21:16>:** Output Data Sign for Corresponding Analog Inputs bits

1 = Channel output data is signed

0 = Channel output data is unsigned

REGISTER 22-22: ADIEL: ADC INTERRUPT ENABLE REGISTER LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			IE<	<15:8>			
bit 15							bit 8
r							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			IE	<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1'		'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown

bit 15-0 IE<15:0>: Common Interrupt Enable bits

1 = Common and individual interrupts are enabled for the corresponding channel

0 = Common and individual interrupts are disabled for the corresponding channel

REGISTER 22-23: ADIEH: ADC INTERRUPT ENABLE REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—			IE<2	1:16>		
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-6 Unimplemented: Read as '0'

bit 5-0

IE<21:16>: Common Interrupt Enable bits

1 = Common and individual interrupts are enabled for the corresponding channel

0 = Common and individual interrupts are disabled for the corresponding channel

REGISTER 22-24: ADSTATL: ADC DATA READY STATUS REGISTER LOW

HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	
			AN<15	:8>RDY				
bit 15	bit 15 bit 8							
HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	
			AN<7:	0>RDY				
bit 7							bit 0	
Legend:		U = Unimplem	nented bit, rea	d as '0'				
R = Readable	bit	W = Writable I	bit	HSC = Hardware Settable/Clearable bit				
-n = Value at POR '1' = Bit is set			'0' = Bit is clea	ared	x = Bit is unkr	nown		

bit 15-0 AN<15:0>RDY: Common Interrupt Enable for Corresponding Analog Inputs bits

1 = Channel conversion result is ready in the corresponding ADCBUFx register

0 = Channel conversion result is not ready

REGISTER 22-25: ADSTATH: ADC DATA READY STATUS REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0		
—	—		AN<21:16>RDY						
bit 7							bit 0		

Legend:	U = Unimplemented bit, read as '0'			
R = Readable bit	W = Writable bit	HSC = Hardware Settable/Clearable bit		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-6 Unimplemented: Read as '0'

bit 5-0 AN<21:16>RDY: Common Interrupt Enable for Corresponding Analog Inputs bits

1 = Channel conversion result is ready in the corresponding ADCBUFx register

0 = Channel conversion result is not ready

REGISTER 22-26: ADTRIGXL: ADC CHANNEL TRIGGER x SELECTION REGISTER LOW

(x = 0 to 5)

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
_	_	_		TRGSRC(4x+1)<4:0>					
bit 15	•						bit 8		
<u> </u>									
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
_	_	_		TR	GSRC(4x)<4:0	>			
bit 7		•					bit 0		
Legend:									

Leaend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit

bit 15-13	Unimplemented: Read as '0'
bit 12-8	•
DIL 12-0	TRGSRC(4x+1)<4:0>: Trigger Source Selection for Corresponding Analog Inputs bits
	11111 = ADTRG31
	11110 = PTG Trigger Output 12
	11101 = PWM Generator 6 current-limit trigger
	11100 = PWM Generator 5 current-limit trigger
	11011 = PWM Generator 4 current-limit trigger
	11010 = PWM Generator 3 current-limit trigger 11001 = PWM Generator 2 current-limit trigger
	11000 = PWM Generator 1 current-limit trigger
	10111 = Output Compare 2 trigger
	10111 = Output Compare 2 trigger
	10101 = CLC2 output
	10100 = PWM Generator 6 secondary trigger
	10011 = PWM Generator 5 secondary trigger
	10010 = PWM Generator 4 secondary trigger
	10001 = PWM Generator 3 secondary trigger
	10000 = PWM Generator 2 secondary trigger
	01111 = PWM Generator 1 secondary trigger
	01110 = PWM secondary Special Event Trigger
	01101 = Timer2 period match
	01100 = Timer1 period match
	01011 = CLC1 output
	01010 = PWM Generator 6 primary trigger
	01001 = PWM Generator 5 primary trigger
	01000 = PWM Generator 4 primary trigger
	00111 = PWM Generator 3 primary trigger
	00110 = PWM Generator 2 primary trigger
	00101 = PWM Generator 1 primary trigger
	00100 = PWM Special Event Trigger
	00011 = Reserved
	00010 = Level software trigger
	00001 = Common software trigger
	00000 = No trigger is enabled
bit 7-5	Unimplemented: Read as '0'

REGISTER 22-26: ADTRIGXL: ADC CHANNEL TRIGGER x SELECTION REGISTER LOW (x = 0 to 5) (CONTINUED)

bit 4-0 TRGSRC(4x)<4:0>: Trigger Source Selection for Corresponding Analog Inputs bits 11111 = ADTRG31 11110 = PTG Trigger Output 30 11101 = PWM Generator 6 current-limit trigger 11100 = PWM Generator 5 current-limit trigger 11011 = PWM Generator 4 current-limit trigger 11010 = PWM Generator 3 current-limit trigger 11001 = PWM Generator 2 current-limit trigger 11000 = PWM Generator 1 current-limit trigger 10111 = Output Compare 2 trigger 10110 = Output Compare 1 trigger 10101 = CLC2 output 10100 = PWM Generator 6 secondary trigger 10011 = PWM Generator 5 secondary trigger 10010 = PWM Generator 4 secondary trigger 10001 = PWM Generator 3 secondary trigger 10000 = PWM Generator 2 secondary trigger 01111 = PWM Generator 1 secondary trigger 01110 = PWM secondary Special Event Trigger 01101 = Timer2 period match 01100 = Timer1 period match 01011 = CLC1 output 01010 = PWM Generator 6 primary trigger 01001 = PWM Generator 5 primary trigger 01000 = PWM Generator 4 primary trigger 00111 = PWM Generator 3 primary trigger 00110 = PWM Generator 2 primary trigger 00101 = PWM Generator 1 primary trigger 00100 = PWM Special Event Trigger 00011 = Reserved 00010 = Level software trigger 00001 = Common software trigger

00000 = No trigger is enabled

REGISTER 22-27: ADTRIGXH: ADC CHANNEL TRIGGER x SELECTION REGISTER HIGH (x = 0 to 5)

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	—	—	TRGSRC(4x+3)<4:0>					
bit 15							bit 8	

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	—	—	TRGSRC(4x+2)<4:0>					
bit 7							bit 0	

Legend:

=ogona.				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read a	is '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-13 Unimplemented: Read as '0'

01015-13	Unimplemented: Read as 0
bit 12-8	TRGSRC(4x+3)<4:0>: Trigger Source Selection for Corresponding Analog Inputs bits
	11111 = ADTRG31
	11110 = PTG Trigger Output 30
	11101 = PWM Generator 6 current-limit trigger
	11100 = PWM Generator 5 current-limit trigger
	11011 = PWM Generator 4 current-limit trigger
	11010 = PWM Generator 3 current-limit trigger
	11001 = PWM Generator 2 current-limit trigger
	11000 = PWM Generator 1 current-limit trigger
	10111 = Output Compare 2 trigger
	10110 = Output Compare 1 trigger
	10101 = CLC2 output
	10100 = PWM Generator 6 secondary trigger
	10011 = PWM Generator 5 secondary trigger
	10010 = PWM Generator 4 secondary trigger
	10001 = PWM Generator 3 secondary trigger
	10000 = PWM Generator 2 secondary trigger
	01111 = PWM Generator 1 secondary trigger
	01110 = PWM secondary Special Event Trigger
	01101 = Timer2 period match
	01100 = Timer1 period match
	01011 = CLC1 output
	01010 = PWM Generator 6 primary trigger
	01001 = PWM Generator 5 primary trigger
	01000 = PWM Generator 4 primary trigger
	00111 = PWM Generator 3 primary trigger
	00110 = PWM Generator 2 primary trigger
	00101 = PWM Generator 1 primary trigger
	00100 = PWM Special Event Trigger
	00011 = Reserved
	00010 = Level software trigger
	00001 = Common software trigger
	00000 = No trigger is enabled
bit 7-5	Unimplemented: Read as '0'

REGISTER 22-27: ADTRIGXH: ADC CHANNEL TRIGGER x SELECTION REGISTER HIGH (x = 0 to 5) (CONTINUED)

bit 4-0 TRGSRC(4x+2)<4:0>: Trigger Source Selection for Corresponding Analog Inputs bits 11111 = ADTRG31 11110 = PTG Trigger Output 30 11101 = PWM Generator 6 current-limit trigger 11100 = PWM Generator 5 current-limit trigger 11011 = PWM Generator 4 current-limit trigger 11010 = PWM Generator 3 current-limit trigger 11001 = PWM Generator 2 current-limit trigger 11000 = PWM Generator 1 current-limit trigger 10111 = Output Compare 2 trigger 10110 = Output Compare 1 trigger 10101 = CLC2 output 10100 = PWM Generator 6 secondary trigger 10011 = PWM Generator 5 secondary trigger 10010 = PWM Generator 4 secondary trigger 10001 = PWM Generator 3 secondary trigger 10000 = PWM Generator 2 secondary trigger 01111 = PWM Generator 1 secondary trigger 01110 = PWM secondary Special Event Trigger 01101 = Timer2 period match 01100 = Timer1 period match 01011 = CLC1 output 01010 = PWM Generator 6 primary trigger 01001 = PWM Generator 5 primary trigger 01000 = PWM Generator 4 primary trigger 00111 = PWM Generator 3 primary trigger 00110 = PWM Generator 2 primary trigger 00101 = PWM Generator 1 primary trigger 00100 = PWM Special Event Trigger 00011 = Reserved 00010 = Level software trigger

- 00001 = Common software trigger
- 00000 = No trigger is enabled

REGISTER 22-28: ADCAL0L: ADC CALIBRATION REGISTER 0 LOW

HSC/R-0	U-0	U-0	U-0	r-0	R/W-0	R/W-0	R/W-0			
CAL1RDY	_	_		_	CAL1DIFF	CAL1EN	CAL1RUN			
bit 15		-	I	1			bit 8			
HSC/R-0	U-0	U-0	U-0	r-0	R/W-0	R/W-0	R/W-0			
CALORDY		—	—	—	CAL0DIFF	CAL0EN	CALORUN			
bit 7							bit C			
			1.11			(0)				
Legend:	. 1.11	r = Reserved			mented bit, read					
R = Readabl -n = Value at		W = Writable			vare Settable/Cl		/ -			
-n = value at	PUR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkı	IOWII			
bit 15	CAL1RDY:	Dedicated ADC	Core 1 Calibra	tion Status Fla	a bit					
		d ADC Core 1 d			9 - 11					
	0 = Dedicate	d ADC Core 1 d	alibration is in	progress						
bit 14-12	Unimpleme	nted: Read as ')'							
bit 11	Reserved: N	laintain as '0'								
bit 10		Dedicated ADC								
		d ADC Core 1 v			•					
bit 9	 Dedicated ADC Core 1 will be calibrated in Single-Ended Input mode CAL1EN: Dedicated ADC Core 1 Calibration Enable bit 									
DIL 9	1 = Dedicated ADC Core 1 calibration bits (CALxRDY, CALxDIFF and CALxRUN) can be accessed by									
	software									
	0 = Dedicate	ed ADC Core 1	calibration bits	are disabled						
bit 8		Dedicated ADC								
		it is set by soft		icated ADC C	ore 1 calibration	n cycle is star	ted; this bit is			
	automatically cleared by hardware 0 = Software can start the next calibration cycle									
bit 7		Dedicated ADC			q bit					
		d ADC Core 0 d			0					
	0 = Dedicated ADC Core 0 calibration is in progress									
bit 6-4	Unimpleme	nted: Read as ')'							
bit 3	Reserved: N	laintain as '0'								
bit 2		Dedicated ADC								
		d ADC Core 0 v d ADC Core 0 v								
bit 1	CALOEN: De	edicated ADC C	ore 0 Calibrati	on Enable bit						
	1 = Dedicate software	ed ADC Core 0 o	calibration bits	(CALxRDY, CA	LxDIFF and CA	LxRUN) can b	e accessed by			
	0 = Dedicate	ed ADC Core 0	calibration bits	are disabled						
bit 0		Dedicated ADC								
	 1 = If this bit is set by software, the dedicated ADC Core 0 calibration cycle is started; this bit is automatically cleared by hardware 0 = Software can start the next calibration cycle 									
	0 = Software	e can start the n	ext calibration	cycle						

HSC/R-0 U-0 U-0 U-0 r-0 R/W-0 R/W-0 R/W-0 CAL3RDY ____ ____ ____ ____ **CAL3DIFF** CAL3EN CAL3RUN bit 15 bit 8 HSC/R-0 U-0 U-0 U-0 r-0 R/W-0 R/W-0 R/W-0 CAL2RDY CAL2DIFF CAL2EN ____ CAL2RUN ____ ____ _____ bit 7 bit 0 Legend: r = Reserved bit U = Unimplemented bit, read as '0' R = Readable bit W = Writable bit HSC = Hardware Settable/Clearable bit -n = Value at POR '0' = Bit is cleared x = Bit is unknown '1' = Bit is set bit 15 CAL3RDY: Dedicated ADC Core 3 Calibration Status Flag bit 1 = Dedicated ADC Core 3 calibration is finished 0 = Dedicated ADC Core 3 calibration is in progress bit 14-12 Unimplemented: Read as '0' Reserved: Maintain as '0' bit 11 bit 10 CAL3DIFF: Dedicated ADC Core 3 Differential-Mode Calibration bit 1 = Dedicated ADC Core 3 will be calibrated in Differential Input mode 0 = Dedicated ADC Core 3 will be calibrated in Single-Ended Input mode bit 9 CAL3EN: Dedicated ADC Core 3 Calibration Enable bit 1 = Dedicated ADC Core 3 calibration bits (CALxRDY, CALxDIFF and CALxRUN) can be accessed by software 0 = Dedicated ADC Core 3 calibration bits are disabled bit 8 CAL3RUN: Dedicated ADC Core 3 Calibration Start bit 1 = If this bit is set by software, the dedicated ADC Core 3 calibration cycle is started; this bit is automatically cleared by hardware 0 = Software can start the next calibration cycle bit 7 CAL2RDY: Dedicated ADC Core 2 Calibration Status Flag bit 1 = Dedicated ADC Core 2 calibration is finished 0 = Dedicated ADC Core 2 calibration is in progress bit 6-4 Unimplemented: Read as '0' bit 3 Reserved: Maintain as '0' CAL2DIFF: Dedicated ADC Core 2 Differential-Mode Calibration bit bit 2 1 = Dedicated ADC Core 2 will be calibrated in Differential Input mode 0 = Dedicated ADC Core 2 will be calibrated in Single-Ended Input mode bit 1 CAL2EN: Dedicated ADC Core 2 Calibration Enable bit 1 = Dedicated ADC Core 2 calibration bits (CALxRDY, CALxDIFF and CALxRUN) can be accessed by software 0 = Dedicated ADC Core 2 calibration bits are disabled bit 0 CAL2RUN: Dedicated ADC Core 2 Calibration Start bit 1 = If this bit is set by software, the dedicated ADC Core 2 calibration cycle is started; this bit is automatically cleared by hardware 0 = Software can start the next calibration cycle

REGISTER 22-30:	ADCAL1H: ADC CALIBRATION REGISTER 1 HIGH
-----------------	--

CSHRRDY bit 15	—	_						
bit 15			_	_	CSHRDIFF	CSHREN	CSHRRUN	
		•			•		bit 8	
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	—		_			—	—	
bit 7							bit (
Legend:		r = Reserved	oit	U = Unimpler	mented bit, read	l as '0'		
R = Readable	e bit	W = Writable	oit	HS = Hardwa	are Settable bit			
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown	
bit 15 bit 14-12 bit 11 bit 10	1 = Shared A 0 = Shared A Unimplemen Reserved: M CSHRDIFF: 1 = Shared A	Shared ADC Co \DC core calibra \DC core calibra ited: Read as '() laintain as '0' Shared ADC Co \DC core will be \DC core will be	tion is finishe tion is in prog ore Differentia calibrated in	d gress I-Mode Calibrat Differential Inpu	ion bit ut mode			
bit 9	CSHREN: Shared A 1 = Shared A software	nared ADC Core ADC core calibr	e Calibration E ation bits (CS	Enable bit SHRRDY, CSHF		IRRUN) can b	e accessed by	
bit 8 bit 7-0	 CSHRRUN: Shared ADC Core Calibration Start bit 1 = If this bit is set by software, the shared ADC core calibration cycle is started; this bit is cleared automatically by hardware 0 = Software can start the next calibration cycle Unimplemented: Read as '0' 							

bit 7-0 Unimplemented: Read as '0'

REGISTER 22-31: ADCMPxCON: ADC DIGITAL COMPARATOR x CONTROL REGISTER (x = 0 or 1)

U-0	U-0	U-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0	HSC/R-0			
_	—	_			CHNL<4:0>					
bit 15							bit 8			
R/W-0	R/W-0	HC/HS/R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
CMPEN	IE	STAT	BTWN	HIHI	HILO	LOHI	LOLO			
bit 7							bit 0			
Legend:				U = Unimplem						
					are Settable/Cle					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	HS = Hardwar	e Settable bit			
bit 15-13	-	ted: Read as '0								
bit 12-8		Input Channel I ator has detecte		a abannal thi		oor in writton to	those bits			
	111111 = Res			a channer, this			litese bits.			
	•									
	• 10110 – Doo	onvod								
	10110 = Reserved 10101 = AN21									
	10100 = AN20									
	•									
	• 00001 = AN1									
	00000 = ANO									
bit 7	CMPEN: Com	nparator Enable	bit							
	1 = Comparat			tatus bit is slas						
hit C	•	tor is disabled a			ired					
bit 6		or Common AD ADC interrupt v			arator detects a	comparison e	/ent			
		ADC interrupt v	•			companson c	Vent			
bit 5	STAT: Compa	arator Event Sta	tus bit							
		ared by hardwa					bits.			
	•	 1 = A comparison event has been detected since the last read of the CHNL<4:0> bits 0 = A comparison event has not been detected since the last read of the CHNL<4:0> bits 								
bit 4		een Low/High C					15			
		s a comparator	-		DCBUFx < AD	CMPxHI				
		generate a digi					CMPxHI			
bit 3	HIHI: High/Hig	gh Comparator	Event bit							
		s a digital comp								
		generate a digi	•	event when Al	DCBUFx ≥ AD0	CMPxHI				
bit 2	•	ow Comparator								
		s a digital comp generate a digi								
bit 1		gh Comparator	-							
		s a digital comp		/hen ADCBUF>	< ≥ ADCMPxLC)				
		generate a digi								
bit 0		ow Comparator								
		s a digital comp								
	- $ -$	Generate a digi	a comparator	event when Al	DCBUFx < AD					

REGISTER 22-32: ADCMPxENL: ADC DIGITAL COMPARATOR x CHANNEL ENABLE REGISTER LOW (x = 0 or 1)

bit 15							bit 8
D/M//0	D/M/ 0		DAMO				
R/W/0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 CMPEN<15:0>: Comparator Enable for Corresponding Input Channels bits

0 = Conversion result for corresponding channel is not used by the comparator

REGISTER 22-33: ADCMPxENH: ADC DIGITAL COMPARATOR x CHANNEL ENABLE REGISTER HIGH (x = 0 or 1)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—			CMPEN	<21:16>		
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-6 Unimplemented: Read as '0'

bit 5-0

CMPEN<21:16>: Comparator Enable for Corresponding Input Channels bits

- 1 = Conversion result for corresponding channel is used by the comparator
 - 0 = Conversion result for corresponding channel is not used by the comparator

^{1 =} Conversion result for corresponding channel is used by the comparator

~

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	HSC/R-0				
FLEN	MODE1	MODE0	OVRSAM2	OVRSAM1	OVRSAM0	IE	RDY				
bit 15	WIODET	MODEU	OVRSAIVIZ	UVRSAIVIT	OVRSAIVIO	IC	bit				
DIL 15							DILC				
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—		_			FLCHSEL<4:0>						
bit 7							bit (
Legend:		U = Unimpler	nented bit, read	as '0'							
R = Readab	le hit	W = Writable			vare Settable/Cle	arable bit					
-n = Value a		'1' = Bit is set		'0' = Bit is cle		x = Bit is unk	nown				
					arca						
bit 15	FLEN: Filter	Enable bit									
	1 = Filter is e										
			RDY bit is clea	ared							
bit 14-13	MODE<1:0>	: Filter Mode bi	ts								
	11 = Averaging mode										
		10 = Reserved 01 = Reserved									
		mpling mode									
bit 12-10	OVRSAM<2:0>: Filter Averaging/Oversampling Ratio bits										
	$\frac{\text{If MODE} < 1:0> = 0:0}{111} = 128x (16-bit result in the ADFLxDAT register is in 12.4 format)$										
	111 = 128x (16-bit result in the ADFLxDAT register is in 12.4 format) 110 = 32x (15-bit result in the ADFLxDAT register is in 12.3 format)										
	101 = 8x (14-bit result in the ADFLxDAT register is in 12.2 format)										
			ADFLxDAT reg								
		•	the ADFLxDAT	•	,						
			e ADFLxDAT re								
	000 = 4x (13-bit result in the ADFLxDAT register is in 12.1 format) If MODE<1:0> = 11 (12-bit result in the ADFLxDAT register in all instances):										
	111 = 256x	$D > = \perp \perp (12 - D) (12)$	esuit in the ADF	-LXDAT registe	er in all instance	<u>s):</u>					
	110 = 128x										
	101 = 64x										
	100 = 32x										
	011 = 16x										
	010 = 8x 001 = 4x										
	001 = 4x 000 = 2x										
bit 9		nmon ADC Inte	rrupt Enable bit								
	1 = Commor	ADC interrupt	-	ed when the fill	ter result will be	ready					
bit 8		-	ata Ready Flag								
Dit U					m the ADFLxDA	T register					
		•				riegioton					
	1 = Data in t	he ADFLxDAT r	egister is ready		in the ADFLxDA	·	not ready				

REGISTER 22-34: ADFLxCON: ADC DIGITAL FILTER x CONTROL REGISTER (x = 0 or 1) (CONTINUED)

> 00001 = AN1 00000 = AN0

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NOTES:

23.0 CONTROLLER AREA NETWORK (CAN) MODULE (dsPIC33EPXXXGS80X DEVICES ONLY)

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Enhanced Controller Area Network (ECAN™)" (DS70353) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

23.1 Overview

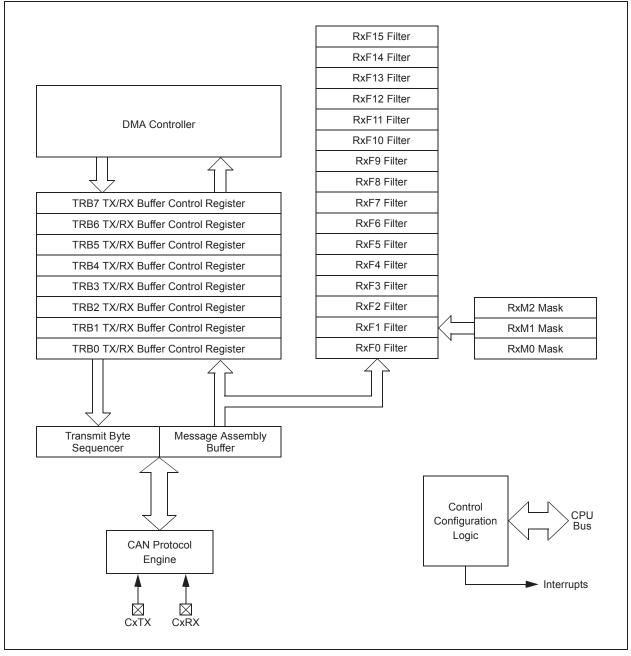
The Controller Area Network (CAN) module is a serial interface, useful for communicating with other CAN modules or microcontroller devices. This interface/ protocol was designed to allow communications within noisy environments. The dsPIC33EPXXXGS80X devices contain two CAN modules.

The CAN module is a communication controller, implementing the CAN 2.0 A/B protocol, as defined in the BOSCH CAN specification. The module supports CAN 1.2, CAN 2.0A, CAN 2.0B Passive and CAN 2.0B Active versions of the protocol. The module implementation is a full CAN system. The CAN specification is not covered within this data sheet. The reader can refer to the BOSCH CAN specification for further details. The CAN module features are as follows:

- Implementation of the CAN Protocol, CAN 1.2, CAN 2.0A and CAN 2.0B
- Standard and Extended Data Frames
- 0-8 Bytes of Data Length
- Programmable Bit Rate, up to 1 Mbit/sec
- Automatic Response to Remote Transmission Requests
- Up to Eight Transmit Buffers with Application Specified Prioritization and Abort Capability (each buffer can contain up to 8 bytes of data)
- Up to 32 Receive Buffers (each buffer can contain up to 8 bytes of data)
- Up to 16 Full (Standard/Extended Identifier) Acceptance Filters
- Three Full Acceptance Filter Masks
- DeviceNet[™] Addressing Support
- Programmable Wake-up Functionality with Integrated Low-Pass Filter
- Programmable Loopback mode supports Self-Test Operation
- Signaling via Interrupt Capabilities for All CAN Receiver and Transmitter Error States
- Programmable Clock Source
- Programmable Link to Input Capture 2 (IC2) module for Timestamping and Network Synchronization
- Low-Power Sleep and Idle modes

The CAN bus module consists of a protocol engine and message buffering/control. The CAN protocol engine handles all functions for receiving and transmitting messages on the CAN bus. Messages are transmitted by first loading the appropriate data registers. Status and errors can be checked by reading the appropriate registers. Any message detected on the CAN bus is checked for errors and then matched against filters to see if it should be received and stored in one of the receive registers.

FIGURE 23-1: CANX MODULE BLOCK DIAGRAM



23.2 Modes of Operation

The CANx module can operate in one of several operation modes selected by the user. These modes include:

- · Initialization mode
- · Disable mode
- Normal Operation mode
- · Listen Only mode
- Listen All Messages mode
- · Loopback mode

Modes are requested by setting the REQOP<2:0> bits (CxCTRL1<10:8>). Entry into a mode is Acknowledged by monitoring the OPMODE<2:0> bits (CxCTRL1<7:5>). The module does not change the mode and the OPMODEx bits until a change in mode is acceptable, generally during bus Idle time, which is defined as at least eleven consecutive recessive bits.

23.3 CAN Control Registers

REGISTER 23-1: CxCTRL1: CANx CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
—	—	CSIDL	ABAT	CANCKS	REQOP2	REQOP1	REQOP0
bit 15							bit 8
R-1	R-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0
OPMODE2	OPMODE1	OPMODE0	—	CANCAP	—	—	WIN
bit 7	•	•		•		•	bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13	CSIDL: CANx Stop in Idle Mode bit
	 1 = Discontinues module operation when device enters Idle mode 0 = Continues module operation in Idle mode
bit 12	ABAT: Abort All Pending Transmissions bit
	 1 = Signals all transmit buffers to abort transmission 0 = Module will clear this bit when all transmissions are aborted
bit 11	CANCKS: CANx Module Clock (FCAN) Source Select bit
	1 = FCAN is equal to 2 * FP 0 = FCAN is equal to FP
bit 10-8	REQOP<2:0>: Request Operation Mode bits
	111 = Set Listen All Messages mode
	110 = Reserved 101 = Reserved
	100 = Set Configuration mode
	011 = Set Listen Only mode
	010 = Set Loopback mode 001 = Set Disable mode
	000 = Set Normal Operation mode
bit 7-5	OPMODE<2:0>: Operation Mode bits
	111 = Module is in Listen All Messages mode
	110 = Reserved 101 = Reserved
	100 = Module is in Configuration mode
	011 = Module is in Listen Only mode
	010 = Module is in Loopback mode 001 = Module is in Disable mode
	000 = Module is in Normal Operation mode
bit 4	Unimplemented: Read as '0'
bit 3	CANCAP: CANx Message Receive Timer Capture Event Enable bit
	 1 = Enables input capture based on CAN message receive 0 = Disables CAN capture
bit 2-1	Unimplemented: Read as '0'
bit 0	WIN: SFR Map Window Select bit
	1 = Uses filter window
	0 = Uses buffer window

REGISTER 23-2: CxCTRL2: CANx CONTROL REGISTER 2

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
—	—	—	—	—	—	—	_	
bit 15							bit 8	
U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0	
—	—	—		DNCNT<4:0>				
bit 7							bit 0	
Legend:								
R = Readable	bit	W = Writable	bit	U = Unimpler	nented bit, read	as '0'		
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cleared			x = Bit is unknown	
bit 15-5	Unimplemen	ted: Read as '	0'					
bit 4-0	DNCNT<4:0>	•: DeviceNet™	Filter Bit Num	ber bits				
	10010-11111	1 = Invalid sele	ction					
	10001 = Con	npare up to Dat	a Byte 3, bit 6	with EID<17>				
	•		-					
	•							
	•							
		npare up to Dat		with EID<0>				
	00000 = Do r	not compare da	ita bytes					

U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0			
	—		FILHIT4	FILHIT3	FILHIT2	FILHIT1	FILHIT0			
bit 15							bit 8			
U-0	R-1	R-0	R-0	R-0	R-0	R-0	R-0			
0-0	ICODE6	ICODE5	ICODE4	ICODE3	ICODE2	ICODE1	ICODE0			
bit 7	ICODE0	ICODES	ICODL4	ICODES	ICODE2	ICODET	bit 0			
							DILO			
Legend:										
R = Readab	le bit	W = Writable	bit	U = Unimplemented bit, read as '0'						
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown						
bit 15-13	Unimplemen	ted: Read as '	0'							
bit 12-8	FILHIT<4:0>:	Filter Hit Num	ber bits							
	10000-11111									
	01111 = Filter 15									
	•									
	•									
	00001 = Filte 00000 = Filte									
bit 7			0'							
bit 6-0	Unimplemented: Read as '0' ICODE<6:0>: Interrupt Flag Code bits									
	1000101-1111111 = Reserved									
		IFO almost full								
		eceiver overflo /ake-up interru								
	1000001 = E		ρι							
	1000000 = N	o interrupt								
	•									
	•									
		11111 = Reser								
		B15 buffer inte	rrupt							
	•									
	•									
		B9 buffer inter								
		RB7 buffer inte								
		RB6 buffer inte								
		RB5 buffer inte RB4 buffer inte								
		RB3 buffer inte	•							
	0000010 = T	RB2 buffer inte	errupt							
		RB1 buffer inte RB0 buffer inte								
	0000000 = 1		mupt							

REGISTER 23-3: CxVEC: CANx INTERRUPT CODE REGISTER

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
DMABS2	DMABS1	DMABS0	_	—			
oit 15							bit 8
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—		—	FSA4	FSA3	FSA2	FSA1	FSA0
bit 7							bit (
Legend:							
R = Readabl		W = Writable b	bit	•	nented bit, rea		
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unknown	
	101 = 24 buff 100 = 16 buff 011 = 12 buff 010 = 8 buffe 001 = 6 buffe 000 = 4 buffe	fers in RAM fers in RAM ers in RAM ers in RAM ers in RAM					
bit 12-5	•	ited: Read as '0					
bit 4-0	11111 = Rec 11110 = Rec • • • • •	IFO Area Starts eive Buffer RB3 eive Buffer RB3 nsmit/Receive B	uffer TRB1	its			

REGISTER 23-4: CxFCTRL: CANx FIFO CONTROL REGISTER

— — FBP5 FBP4 FBP3 FBP2 FBP1	R-0
	FBP0
bit 15	bit
U-0 U-0 R-0 R-0 R-0 R-0 R-0	R-0
— — FNRB5 FNRB4 FNRB3 FNRB2 FNRB	I FNRB0
bit 7	bit (
<u> </u>	
Legend:	
R = Readable bit $W = Writable bit$ $U = Unimplemented bit, read as '0'V = Unimplemented bit, read as '0'$	
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is r	unknown
bit 15-14 Unimplemented: Read as '0'	
•	
bit 13-8 FBP<5:0>: FIFO Buffer Pointer bits	
011111 = RB31 buffer	
011110 = RB30 buffer	
•	
•	
000001 = TRB1 buffer	
000000 = TRB0 buffer	
bit 7-6 Unimplemented: Read as '0'	
bit 5-0 FNRB<5:0>: FIFO Next Read Buffer Pointer bits	
011111 = RB31 buffer	
011110 = RB30 buffer	
•	
•	
• 000001 = TRB1 buffer	
000000 = TRB0 buffer	

REGISTER 23-5: CxFIFO: CANx FIFO STATUS REGISTER

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	TXBO	TXBP	RXBP	TXWAR	RXWAR	EWARN
bit 15							bit 8
R/C-0	R/C-0	R/C-0	U-0	R/C-0	R/C-0	R/C-0	R/C-0
IVRIF	WAKIF	ERRIF	_	FIFOIF	RBOVIF	RBIF	TBIF
bit 7	1		1				bit (
Legend:		C = Writable I	oit, but only '0	' can be Writte	n to Clear bit		
R = Readabl	le bit	W = Writable	bit	U = Unimpler	mented bit, read	d as '0'	
-n = Value at	t POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	nown
bit 15-14	Unimplemen	ted: Read as '	n'				
bit 13	-	mitter in Error S		hit			
		er is in Bus Off		5 M			
	0 = Transmitt	er is not in Bus	Off state				
bit 12		mitter in Error S		sive bit			
		er is in Bus Pa		_			
bit 11		er is not in Bus iver in Error Sta					
		is in Bus Passi		vebit			
		is not in Bus Passi					
bit 10	TXWAR: Trar	nsmitter in Erro	r State Warni	ng bit			
		er is in Error W		0			
	0 = Transmitt	er is not in Erro	or Warning sta	ate			
bit 9		ceiver in Error S	•	bit			
		is in Error War					
bit 8		is not in Error \ nsmitter or Rec	•		hit		
DILO		er or receiver is		•	DIL		
		er or receiver is					
bit 7		Message Inter		U			
	1 = Interrupt	request has oc	curred				
		request has not					
bit 6		Wake-up Activi		ag bit			
		request has oc					
bit 5	-	request has not		ources in CvIN	TF<13:8> regis	tor)	
DIL D		request has oc			TF<15.02 Tegis	iter)	
		request has not					
bit 4	-	ted: Read as '					
bit 3	FIFOIF: FIFO	Almost Full In	terrupt Flag b	it			
		request has oc					
	•	request has no					
bit 2		Buffer Overflow	-	ag bit			
		request has oc					
	0 = interrupt	request has not	occurred				

REGISTER 23-6: CxINTF: CANx INTERRUPT FLAG REGISTER (CONTINUED)

bit 1	RBIF: RX Buffer Interrupt Flag bit
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred
bit 0	TBIF: TX Buffer Interrupt Flag bit
	 Interrupt request has occurred
	Interrupt request has not accurred

0 = Interrupt request has not occurred

REGISTER 23-7: CxINTE: CANx INTERRUPT ENABLE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
IVRIE	WAKIE	ERRIE	—	FIFOIE	RBOVIE	RBIE	TBIE
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Unimplemented: Read as '0'
bit 7	IVRIE: Invalid Message Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 6	WAKIE: Bus Wake-up Activity Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 5	ERRIE: Error Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 4	Unimplemented: Read as '0'
bit 3	FIFOIE: FIFO Almost Full Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 2	RBOVIE: RX Buffer Overflow Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 1	RBIE: RX Buffer Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 0	TBIE: TX Buffer Interrupt Enable bit
	 Interrupt request is enabled
	0 = Interrupt request is not enabled

REGISTER 23-8: CxEC: CANX TRANSMIT/RECEIVE ERROR COUNT REGISTER

| R-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| TERRCNT7 | TERRCNT6 | TERRCNT5 | TERRCNT4 | TERRCNT3 | TERRCNT2 | TERRCNT1 | TERRCNT0 |
| bit 15 | | | | | | | bit 8 |

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
RERRCNT7	RERRCNT6	RERRCNT5	RERRCNT4	RERRCNT3	RERRCNT2	RERRCNT1	RERRCNT0
bit 7 bit 0							

Legend:			
R = Readable bit W = Writable bit		U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 TERRCNT<7:0>: Transmit Error Count bits

bit 7-0 **RERRCNT<7:0>:** Receive Error Count bits

REGISTER 23-9: CxCFG1: CANx BAUD RATE CONFIGURATION REGISTER 1

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
		_	_	_	_		_			
bit 15		-	1	_	•		bit			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
SJW1	SJW0	BRP5	BRP4	BRP3	BRP2	BRP1	BRP0			
bit 7		-	1	_	•	•	bit			
Legend:										
R = Readab	ole bit	W = Writable	bit	U = Unimpler	mented bit, read	l as '0'				
-n = Value a	at POR	'1' = Bit is set	t	'0' = Bit is cleared		x = Bit is unknown				
bit 15-8	Unimpleme	nted: Read as '	0'							
bit 7-6	SJW<1:0>: Synchronization Jump Width bits									
		11 = Length is 4 x TQ								
		10 = Length is 3 x TQ								
	$01 = \text{Length is } 2 \times TQ$									
	00 = Length									
bit 5-0	BRP<5:0>: E	BRP<5:0>: Baud Rate Prescaler bits								
	11 1111 = TQ = 2 x 64 x 1/FCAN									
	•									
	•									
	•									
		ΓQ = 2 x 3 x 1/F ΓQ = 2 x 2 x 1/F								
		TQ = 2 x 2 x 1/F TQ = 2 x 1 x 1/F								
	00 0000 -		CAN							

REGISTER 23-10: CxCFG2: CANx BAUD RATE CONFIGURATION REGISTER 2

U-0	R/W-x	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x			
	WAKFIL	_	_	_	SEG2PH2	SEG2PH1	SEG2PH0			
bit 15							bit 8			
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x			
SEG2PHTS	SAM	SEG1PH2	SEG1PH1	SEG1PH0	PRSEG2	PRSEG1	PRSEG0			
bit 7							bit 0			
Legend:										
R = Readable	e bit	W = Writable	oit	U = Unimpler	mented bit, read	1 as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown			
bit 15	Unimplemer	ted: Read as ')'							
bit 14	WAKFIL: Se	lect CAN Bus Li	ne Filter for V	Vake-up bit						
		1 = Uses CAN bus line filter for wake-up								
		line filter is not		e-up						
bit 13-11	-	nted: Read as '								
bit 10-8	SEG2PH<2:0>: Phase Segment 2 bits									
	111 = Length is 8 x TQ									
	•									
	•									
	000 = Length									
bit 7	SEG2PHTS: Phase Segment 2 Time Select bit									
	 Freely programmable Maximum of SEG1PHx bits or Information Processing Time (IPT), whichever is greater 									
							ater			
bit 6		n of SEG1PHx b		tion Processin	g Time (IPT), w	hichever is gre	ater			
bit 6	SAM: Sample	n of SEG1PHx b e of the CAN Bu	is Line bit		g Time (IPT), w	/hichever is gre	ater			
bit 6	SAM: Sample	n of SEG1PHx b	is Line bit times at the	sample point	g Time (IPT), w	/hichever is gre	ater			
bit 6 bit 5-3	SAM: Sample 1 = Bus line i 0 = Bus line i	n of SEG1PHx t e of the CAN Bu s sampled three	us Line bit times at the at the sampl	sample point	g Time (IPT), w	/hichever is gre	ater			
	SAM: Sample 1 = Bus line i 0 = Bus line i	n of SEG1PHx b e of the CAN Bu s sampled three s sampled once)>: Phase Segn	us Line bit times at the at the sampl	sample point	g Time (IPT), w	/hichever is gre	ater			
	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:0	n of SEG1PHx b e of the CAN Bu s sampled three s sampled once)>: Phase Segn	us Line bit times at the at the sampl	sample point	g Time (IPT), w	/hichever is gre	ater			
	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:0	n of SEG1PHx b e of the CAN Bu s sampled three s sampled once)>: Phase Segn	us Line bit times at the at the sampl	sample point	g Time (IPT), w	/hichever is gre	ater			
	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:0	n of SEG1PHx b e of the CAN Bu s sampled three s sampled once D>: Phase Segn n is 8 x TQ	us Line bit times at the at the sampl	sample point	g Time (IPT), w	/hichever is gre	ater			
	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:(111 = Length	n of SEG1PHx b e of the CAN Bu s sampled three s sampled once D>: Phase Segn n is 8 x TQ	us Line bit e times at the e at the sampl nent 1 bits	sample point e point	g Time (IPT), w	/hichever is gre	ater			
bit 5-3	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:(111 = Length	n of SEG1PHx t e of the CAN Bu s sampled three s sampled once D>: Phase Segn n is 8 x TQ n is 1 x TQ : Propagation	us Line bit e times at the e at the sampl nent 1 bits	sample point e point	g Time (IPT), w	/hichever is gre	ater			
bit 5-3	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:(111 = Length 000 = Length PRSEG<2:02	n of SEG1PHx t e of the CAN Bu s sampled three s sampled once D>: Phase Segn n is 8 x TQ n is 1 x TQ : Propagation	us Line bit e times at the e at the sampl nent 1 bits	sample point e point	g Time (IPT), w	/hichever is gre	ater			
bit 5-3	SAM: Sampl 1 = Bus line i 0 = Bus line i SEG1PH<2:(111 = Length 000 = Length PRSEG<2:02	n of SEG1PHx t e of the CAN Bu s sampled three s sampled once D>: Phase Segn n is 8 x TQ n is 1 x TQ : Propagation	us Line bit e times at the e at the sampl nent 1 bits	sample point e point	g Time (IPT), w	/hichever is gre	ater			

REGISTER 23-11: CxFEN1: CANx ACCEPTANCE FILTER ENABLE REGISTER 1

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			FLTE	N<15:8>			
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			FLTE	N<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		oit	U = Unimplemented bit, read as '0'		id as '0'		
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit 15-0

FLTEN<15:0>: Enable Filter n to Accept Messages bits

1 = Enables Filter n

0 = Disables Filter n

REGISTER 23-12: CxBUFPNT1: CANx FILTERS 0-3 BUFFER POINTER REGISTER 1

R/W-0 R/W-0 <th< th=""><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></th<>											
bit 15 bit R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 F1BP3 F1BP2 F1BP1 F1BP0 F0BP3 F0BP2 F0BP1 F0BP0 bit 7 bit bit bit bit bit Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer - 1110 = Filter hits received in RX Buffer 1 0001 = Filter hits received in RX Buffer 1 - - 0001 = Filter hits received in RX Buffer 0 bit 11-8 F2BP<3:0>: RX Buffer Mask for Filter 2 bits (same values as bits 15-12) bit 11-8 bit 11-8 F2BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12) - -	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 F1BP3 F1BP2 F1BP1 F1BP0 F0BP3 F0BP2 F0BP1 F0BP0 bit 7 bit bit bit bit Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 	F3BP3	F3BP2	F3BP1	F3BP0	F2BP3	F2BP2	F2BP1	F2BP0			
F1BP3 F1BP2 F1BP1 F1BP0 F0BP3 F0BP2 F0BP1 F0BP0 bit 7 bit bit bit bit bit Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' - -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 1 0001 = Filter hits received in RX Buffer 1 0001 = Filter hits received in RX Buffer 1 0001 = Filter hits received in RX Buffer 0 bit 11-8 F2BP<3:0>: RX Buffer Mask for Filter 2 bits (same values as bits 15-12) bit 7-4 F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)	bit 15		•					bit 8			
F1BP3 F1BP2 F1BP1 F1BP0 F0BP3 F0BP2 F0BP1 F0BP0 bit 7 bit bit bit bit Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'											
bit 7 bit Legend: W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 • • •<	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 •	F1BP3	F1BP2	F1BP1	F1BP0	F0BP3	F0BP2	F0BP1	F0BP0			
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 • • 0001 = Filter hits received in RX Buffer 1 0000 = Filter hits received in RX Buffer 1 0000 = Filter hits received in RX Buffer 0 bit 11-8 F2BP<3:0>: RX Buffer Mask for Filter 2 bits (same values as bits 15-12) bit 7-4	bit 7		-		•		•	bit 0			
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 • • 0001 = Filter hits received in RX Buffer 1 0000 = Filter hits received in RX Buffer 1 0000 = Filter hits received in RX Buffer 0 bit 11-8 F2BP<3:0>: RX Buffer Mask for Filter 2 bits (same values as bits 15-12) bit 7-4	l egend:										
bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14	-	e bit	W = Writable	bit	U = Unimplemented bit, read as '0'						
 bit 15-12 F3BP<3:0>: RX Buffer Mask for Filter 3 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 . <l< td=""><td>-n = Value at</td><td>POR</td><td>'1' = Bit is set</td><td></td><td colspan="3">(0) = Bit is cleared x = Bit is unknown</td><td>nown</td></l<>	-n = Value at	POR	'1' = Bit is set		(0) = Bit is cleared x = Bit is unknown			nown			
 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 . .<th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th>											
 1110 = Filter hits received in RX Buffer 14 . .<td>bit 15-12</td><td colspan="9">F3BP<3:0>: RX Buffer Mask for Filter 3 bits</td>	bit 15-12	F3BP<3:0>: RX Buffer Mask for Filter 3 bits									
 i. <		1111 = Filter hits received in RX FIFO buffer									
bit 11-8F2BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)bit 7-4F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)		1110 = Filter hits received in RX Buffer 14									
bit 11-8F2BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)bit 7-4F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)		•	•								
bit 11-8F2BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)bit 7-4F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)		•									
bit 11-8F2BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)bit 7-4F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)		• 0001 - Filtor	•								
bit 11-8F2BP<3:0>: RX Buffer Mask for Filter 2 bits (same values as bits 15-12)bit 7-4F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)		0001									
bit 7-4 F1BP<3:0>: RX Buffer Mask for Filter 1 bits (same values as bits 15-12)	bit 11-8				its (same value	es as bits 15-12)				
	bit 7-4				-		-				
······································	bit 3-0										
					· · · · · · · · · · · · · · · · · · ·		,				

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F7BP3	F7BP2	F7BP1	F7BP0	F6BP3	F6BP2	F6BP1	F6BP0
bit 15	•				·	•	bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F5BP3	F5BP2	F5BP1	F5BP0	F4BP3	F4BP2	F4BP1	F4BP0
bit 7				·	•	•	bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	mented bit, read	as '0'	
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unkr	nown
bit 15-12	1111 = Filter 1110 = Filter • • • • •	RX Buffer Masl hits received ir hits received ir hits received ir hits received ir	n RX FIFO but n RX Buffer 14 n RX Buffer 1	ffer			

REGISTER 23-13: CxBUFPNT2: CANx FILTERS 4-7 BUFFER POINTER REGISTER 2

bit 11-8	F6BP<3:0>: RX Buffer Mask for Filter 6 bits (same values as bits 15-12)

bit 7-4	F5BP<3:0>: RX Buffer Mask for Filter 5 bits (same values as bits 15-12)
---------	---

bit 3-0	F4BP<3:0>: RX Buffer Mask for Filter 4 bits (same values as bits 15-12)

REGISTER 23-14: CxBUFPNT3: CANx FILTERS 8-11 BUFFER POINTER REGISTER 3

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| F11BP3 | F11BP2 | F11BP1 | F11BP0 | F10BP3 | F10BP2 | F10BP1 | F10BP0 |
| bit 15 | | | | | | | bit 8 |
| | | | | | | | |
| R/W-0 |
F9BP3	F9BP2	F9BP1	F9BP0	F8BP3	F8BP2	F8BP1	F8BP0
bit 7			•				bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12	F11BP<3:0>: RX Buffer Mask for Filter 11 bits 1111 = Filter hits received in RX FIFO buffer 1110 = Filter hits received in RX Buffer 14 •
bit 11-8 bit 7-4	 0001 = Filter hits received in RX Buffer 1 0000 = Filter hits received in RX Buffer 0 F10BP<3:0>: RX Buffer Mask for Filter 10 bits (same values as bits 15-12) F9BP<3:0>: RX Buffer Mask for Filter 9 bits (same values as bits 15-12)
bit 3-0	F8BP<3:0>: RX Buffer Mask for Filter 8 bits (same values as bits 15-12)

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R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
F15BP3	F15BP2	F15BP1	F15BP0	F14BP3	F14BP2	F14BP1	F14BP0			
bit 15	-	·	•	·			bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
F13BP3	F13BP2	F13BP1	F13BP0	F12BP3	F12BP2	F12BP1	F12BP0			
bit 7							bit 0			
Legend:										
R = Readabl	e bit	W = Writable bit		U = Unimplemented bit, read as '0'						
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown				
bit 15-12	F15BP<3:0>	BP<3:0>: RX Buffer Mask for Filter 15 bits								
	1111 = Filter hits received in RX FIFO buffer									
	1110 = Filter	1110 = Filter hits received in RX Buffer 14								
	•									
	•									
	0001 = Filter	hits received in	n RX Buffer 1							
	0001	hits received in								
bit 11-8	F14BP<3:0>	: RX Buffer Ma	sk for Filter 14	1 bits (same va	lues as bits 15-	12)				
bit 7-4	F13BP<3:0>	: RX Buffer Ma	sk for Filter 13	3 bits (same va	lues as bits 15-	12)				

REGISTER 23-15: CxBUFPNT4: CANx FILTERS 12-15 BUFFER POINTER REGISTER 4

bit 3-0 F12BP<3:0>: RX Buffer Mask for Filter 12 bits (same values as bits 15-12)

REGISTER 23-16: CxRXFnSID: CANx ACCEPTANCE FILTER n STANDARD IDENTIFIER REGISTER (n = 0-15)

		· · ·	- /					
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3	
bit 15	·	·		·		·	bit 8	
R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x	
SID2	SID1	SID0	—	EXIDE	—	EID17	EID16	
bit 7		1			L		bit 0	
Legend:								
R = Readable bit W = Writable bit				U = Unimplemented bit, read as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unkr	nown	
bit 4	0 = Message	address bit, Sl address bit, Sl ited: Read as '	Dx, must be '					
bit 3	EXIDE: Extended Identifier Enable bit							
		only messages only messages DE bit.						
bit 2	Unimplemer	ted: Read as '	0'					
bit 1-0	EID<17:16>:	Extended Iden	tifier bits					
	•	address bit, El address bit, El						

REGISTER 23-17: CxRXFnEID: CANx ACCEPTANCE FILTER n EXTENDED IDENTIFIER REGISTER (n = 0-15)

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			EID	<15:8>			
bit 15							bit 8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			EID)<7:0>			
bit 7							bit C
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown

bit 15-0 EID<15:0>: Ex

EID<15:0>: Extended Identifier bits

1 = Message address bit, EIDx, must be '1' to match filter

 ${\tt 0}$ = Message address bit, EIDx, must be '0' to match filter

			-				
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F7MSK1	F7MSK0	F6MSK1	F6MSK0	F5MSK1	F5MSK0	F4MSK1	F4MSK0
bit 15				•	•		bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F3MSK1	F3MSK0	F2MSK1	F2MSK0	F1MSK1	F1MSK0	F0MSK1	F0MSK0
bit 7							bit (
Legend:							
R = Readable bit		W = Writable	W = Writable bit		U = Unimplemented bit, read as '0'		
-n = Value at POR		'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 15-14	F7MSK<1:0>: Mask Source for Filter 7 b 11 = Reserved 10 = Acceptance Mask 2 registers contai 01 = Acceptance Mask 1 registers contai 00 = Acceptance Mask 0 registers contai			n mask n mask			
bit 13-12	F6MSK<1:0>	·: Mask Source	for Filter 6 bi	ts (same value	s as bits 15-14)		
bit 11-10	F5MSK<1:0>	: Mask Source	for Filter 5 bi	ts (same value	s as bits 15-14)		
bit 9-8	F4MSK<1:0>	: Mask Source	for Filter 4 bi	ts (same value	s as bits 15-14)		
bit 7-6	F3MSK<1:0>	: Mask Source	for Filter 3 bi	ts (same value	s as bits 15-14)		
bit 5-4	F2MSK<1:0>	: Mask Source	for Filter 2 bi	ts (same value	s as bits 15-14)		
bit 3-2	F1MSK<1:0>	: Mask Source	for Filter 1 bit	ts (same value	s as bits 15-14)		
L:1 4 0	FOMOK (4.0)	Martin Carrier		· · · · · · · · · · · · · · · · · · ·			

REGISTER 23-18: CxFMSKSEL1: CANx FILTERS 7-0 MASK SELECTION REGISTER 1

bit 1-0 **F0MSK<1:0>:** Mask Source for Filter 0 bits (same values as bits 15-14)

REGISTER 23-19: CxFMSKSEL2: CANx FILTERS 15-8 MASK SELECTION REGISTER 2

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| F15MSK1 | F15MSK0 | F14MSK1 | F14MSK0 | F13MSK1 | F13MSK0 | F12MSK1 | F12MSK0 |
| bit 15 | | | | | | | bit 8 |

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F11MSK1	F11MSK0	F10MSK1	F10MSK0	F9MSK1	F9MSK0	F8MSK1	F8MSK0
bit 7							bit 0

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit,	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

REGISTER 23-20: CxRXMnSID: CANx ACCEPTANCE FILTER MASK n STANDARD IDENTIFIER REGISTER (n = 0-2)

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x		
SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3		
bit 15				-			bit 8		
R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x		
SID2	SID1	SID0	_	MIDE	_	EID17	EID16		
bit 7	ł						bit 0		
Legend:									
R = Readable	e bit	W = Writable	bit	U = Unimplemented bit, read as '0'					
-n = Value at POR '1' = Bit is set				'0' = Bit is cle	ared	x = Bit is unkr	nown		
bit 15-5 bit 4 bit 3	1 = Includes 0 = Bit, SIDx Unimplemen MIDE: Identif	SID<10:0>: Standard Identifier bits I = Includes bit, SIDx, in filter comparison Bit, SIDx, is a don't care in filter comparison Unimplemented: Read as '0' MIDE: Identifier Receive Mode bit 							
bit 2	0 = Matches (i.e., if (F	either standard	or extended a essage SIDx)	address messag	address) that c ge if filters match (/EIDx) = (Messa	י. ו			
bit 1-0	EID<17:16>: 1 = Includes	Extended Iden bit, EIDx, in fill , is a don't care	tifier bits er compariso						

REGISTER 23-21: CxRXMnEID: CANx ACCEPTANCE FILTER MASK n EXTENDED IDENTIFIER REGISTER (n = 0-2)

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
			EID	<15:8>				
bit 15							bit 8	
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
			EID)<7:0>				
bit 7							bit (
Legend:								
R = Readable	bit	W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared		x = Bit is unknown			

bit 15-0 EID<15:0>: Extended Identifier bits

1 = Includes bit, EIDx, in filter comparison

0 = Bit, EIDx, is a don't care in filter comparison

REGISTER 23-22: CxRXFUL1: CANx RECEIVE BUFFER FULL REGISTER 1

bit 7							bit 0
			RXFU	L<7:0>			
R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
bit 15							bit 8
			RXFUL	.<15:8>			
R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0

Legend:	C = Writable bit, but only '0	' can be Written to Clear bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **RXFUL<15:0>:** Receive Buffer n Full bits

1 = Buffer is full (set by module)

0 = Buffer is empty (cleared by user software)

REGISTER 23-23: CxRXFUL2: CANx RECEIVE BUFFER FULL REGISTER 2

R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
			RXFUL	_<31:24>			
bit 15							bit 8
R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
			RXFUL	_<23:16>			
bit 7							bit 0
Legend:		C = Writable b	it, but only 'C	' can be Written	to Clear bit		
R = Readable	bit	W = Writable b	oit	U = Unimplem	ented bit, rea	d as '0'	
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown						nown	

bit 15-0

RXFUL<31:16>: Receive Buffer n Full bits

1 = Buffer is full (set by module)

0 = Buffer is empty (cleared by user software)

REGISTER 23-24: CxRXOVF1: CANx RECEIVE BUFFER OVERFLOW REGISTER 1

				U = Unimplemented bit, read as '0'				
Legend: C = Writable bit, but only '0' can be Written to Clear bit								
bit 7							bit 0	
			RXOV	F<7:0>				
R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	
bit 15							bit 8	
			RXOVI	-<15:8>				
R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	

'0' = Bit is cleared

bit 15-0 **RXOVF<15:0>:** Receive Buffer n Overflow bits

-n = Value at POR

1 = Module attempted to write to a full buffer (set by module)

0 = No overflow condition (cleared by user software)

'1' = Bit is set

REGISTER 23-25: CxRXOVF2: CANx RECEIVE BUFFER OVERFLOW REGISTER 2

R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
			RXOVF	<31:24>			
bit 15							bit 8
R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
			RXOVF	<23:16>			
bit 7							bit 0
Legend:		C = Writable I	bit, but only '0	' can be Writter	n to Clear bit		
R = Readable bit W = Writable bit U = Unimplemented bit, read as			d as '0'				
-n = Value at POR '1' = Bit is set				'0' = Bit is cleared x = Bit is unknown			nown

bit 15-0 RXOVF<31:16>: Receive Buffer n Overflow bits

1 = Module attempted to write to a full buffer (set by module)

0 = No overflow condition (cleared by user software)

x = Bit is unknown

REGISTER 23-26: CxTRmnCON: CANx TX/RX BUFFER mn CONTROL REGISTER

(m = 0,2,4,6; n = 1,3,5,7)

	(m = 0	,2,4,6; n = 1,3	3,5,7)							
R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0			
TXENn	TXABTn	TXLARBn	TXERRn	TXREQn	RTRENn	TXnPRI1	TXnPRI0			
bit 15							bit 8			
R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0			
TXENm	TXABTm ⁽¹⁾	TXLARBm ⁽¹⁾	TXERRm ⁽¹⁾	TXREQm	RTRENm	TXmPRI1	TXmPRI0			
bit 7						1	bit (
Legend:										
R = Readable	e bit	W = Writable	bit	U = Unimpler	mented bit, read	l as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown			
bit 15-8	See Definitior	n for bits 7-0, co	ontrols Buffer r	ı.						
bit 7	TXENm: TX/RX Buffer m Selection bit									
	1 = Buffer, TRBm, is a transmit buffer									
	0 = Buffer, TF	RBm, is a receiv	/e buffer							
bit 6	TXABTm: Message Aborted bit ⁽¹⁾									
	1 = Message was aborted									
	0 = Message completed transmission successfully									
bit 5	TXLARBm: Message Lost Arbitration bit ⁽¹⁾ 1 = Message lost arbitration while being sent									
	0	lost arbitration did not lose arl	0							
bit 4	TXERRm: Error Detected During Transmission bit ⁽¹⁾									
		or occurred whi or did not occu								
bit 3	 0 = A bus error did not occur while the message was being sent TXREQm: Message Send Request bit 									
		that a message the bit to '0' wh			v clears when the abort	e message is su	ccessfully ser			
bit 2	RTRENm: Au	uto-Remote Tra	nsmit Enable I	bit						
		emote transmit emote transmit	,							
bit 1-0	TXmPRI<1:0	>: Message Tra	ansmission Pri	ority bits						
	10 = High inte	message priori ermediate mess ermediate mess	age priority age priority							
Note 1: Th	is bit is cleared	message priori	-							

Note 1: This bit is cleared when TXREQmn is set.

Note: The buffers, SIDx, EIDx, DLCx, Data Field and Receive Status registers, are located in DMA RAM.

23.4 CAN Message Buffers

CAN Message Buffers are part of RAM memory. They are not CAN Special Function Registers. The user application must directly write into the RAM area that is configured for CAN Message Buffers. The location and size of the buffer area is defined by the user application.

BUFFER 21-1: CANx MESSAGE BUFFER WORD 0

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x				
_	—	_	SID10	SID9	SID8	SID7	SID6				
bit 15			•			•	bit 8				
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x				
SID5	SID4	SID3	SID2	SID1	SID0	SRR	IDE				
bit 7							bit 0				
Legend:											
R = Readable bit W = Writable bit				U = Unimpler	mented bit, read	l as '0'					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown				
bit 15-13	Unimplemen	ted: Read as '	0'								
bit 12-2	SID<10:0>: S	Standard Identif	ier bits								
bit 1	SRR: Substitut	ute Remote Re	quest bit								
	When IDE =	When IDE = 0:									
	1 = Message	1 = Message will request remote transmission									
	0 = Normal m	nessage									
	When IDE =										
	The SRR bit I	must be set to '	1'.								
bit 0	IDE: Extende	d Identifier bit									
	1 = Message	will transmit ar	Extended Id	entifier							
		will transmit a									

BUFFER 21-2: CANx MESSAGE BUFFER WORD 1

U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x		
		—			EID<17:14>				
bit 15							bit 8		
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x		
			EID	<13:6>					
bit 7							bit		
Legend:									
R = Readable	bit	W = Writable	W = Writable bit		U = Unimplemented bit, read as '0'				
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown			

bit 15-12 Unimplemented: Read as '0'

bit 11-0 EID<17:6>: Extended Identifier bits

BUFFER 21-3:	CANx MESSAGE BUFFER WORD 2
---------------------	----------------------------

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x				
EID5	EID4	EID3	EID2	EID1	EID0	RTR	RB1				
bit 15							bit 8				
U-x	U-x	U-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x				
_	—	—	RB0	DLC3	DLC2	DLC1	DLC0				
bit 7							bit (
Legend:											
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'							
-n = Value at POR (1' = Bit is set			:	'0' = Bit is cle	ared	x = Bit is unkr	nown				
bit 15-10	EID<5:0>: E>	tended Identifi	er bits								
bit 9	RTR: Remote Transmission Request bit										
	When IDE = 1:										
	1 = Message will request remote transmission										
		0 = Normal message									
		<u>When IDE = 0:</u> The RTR bit is ignored.									
bit 8	RB1: Reserve	-									
DILO											
		t this bit to '0' p	-								
bit 7-5	•	ted: Read as '	0								
bit 4	RB0: Reserve										
		t this bit to '0' p		col.							
bit 3-0	DLC<3:0>: D	ata Length Co	de bits								

BUFFER 21-4: CANx MESSAGE BUFFER WORD 3

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
			Byte	1<15:8>				
bit 15							bit 8	
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
			Byte	0<7:0>				
bit 7							bit (
Legend:								
R = Readable I	oit	W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown		

bit 15-8	Byte 1<15:8>: CANx Message Byte 1 bits

bit 7-0 Byte 0<7:0>: CANx Message Byte 0 bits

BUFFER 21-5: CANx MESSAGE BUFFER WORD 4

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			Byte	3<15:8>			
bit 15							bit 8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			Byte	2<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable I	bit	U = Unimpler	mented bit, rea	d as '0'	
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is		x = Bit is unkr	nown	

bit 15-8 Byte 3<15:8>: CANx Message Byte 3 bits

bit 7-0 Byte 2<7:0>: CANx Message Byte 2 bits

BUFFER 21-6: CANx MESSAGE BUFFER WORD 5

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			Byte	5<15:8>			
bit 15							bit 8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			Byte	4<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable I	bit	U = Unimplemented bit, read as '0'			
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unkr	nown

bit 7-0 Byte 4<7:0>: CANx Message Byte 4 bits

BUFFER 21-7: CANx MESSAGE BUFFER WORD 6

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
			Byte	7<15:8>				
bit 15							bit 8	
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
			Byte	6<7:0>				
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit			oit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown		nown			

bit 7-0 Byte 6<7:0>: CANx Message Byte 6 bits

BUFFER 21-8: CANx MESSAGE BUFFER WORD 7

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
_	—	—			FILHIT<4:0> ⁽¹)	
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13	Unimplemented: Read as '0'
bit 12-8	FILHIT<4:0>: Filter Hit Code bits ⁽¹⁾

Encodes number of filter that resulted in writing this buffer.

bit 7-0 Unimplemented: Read as '0'

Note 1: Only written by module for receive buffers, unused for transmit buffers.

NOTES:

24.0 HIGH-SPEED ANALOG COMPARATOR

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "High-Speed Analog Comparator Module" (DS70005128) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The high-speed analog comparator module monitors current and/or voltage transients that may be too fast for the CPU and ADC to capture.

24.1 Features Overview

The Switch Mode Power Supply (SMPS) comparator module offers the following major features:

- Four Rail-to-Rail Analog Comparators
- Dedicated 12-Bit DAC for each Analog Comparator
- Up to Six Selectable Input Sources per Comparator:
 - Four external inputs
 - Two internal inputs from the PGAx module
- Programmable Comparator Hysteresis
- Programmable Output Polarity
- Up to Two DAC Outputs to Device Pins
- Multiple Voltage References for the DAC:
 External References (EXTREF1 or EXTREF2)
 - AVDD
- Interrupt Generation Capability
- Functional Support for PWMx:
 - PWM duty cycle control
 - PWM period control
 - PWM Fault detected

24.2 Module Description

Figure 24-1 shows a functional block diagram of one analog comparator from the high-speed analog comparator module. The analog comparator provides high-speed operation with a typical delay of 15 ns. The negative input of the comparator is always connected to the DACx circuit. The positive input of the comparator is connected to an analog multiplexer that selects the desired source pin. The analog comparator input pins are typically shared with pins used by the Analog-to-Digital Converter (ADC) module. Both the comparator and the ADC can use the same pins at the same time. This capability enables a user to measure an input voltage with the ADC and detect voltage transients with the comparator.

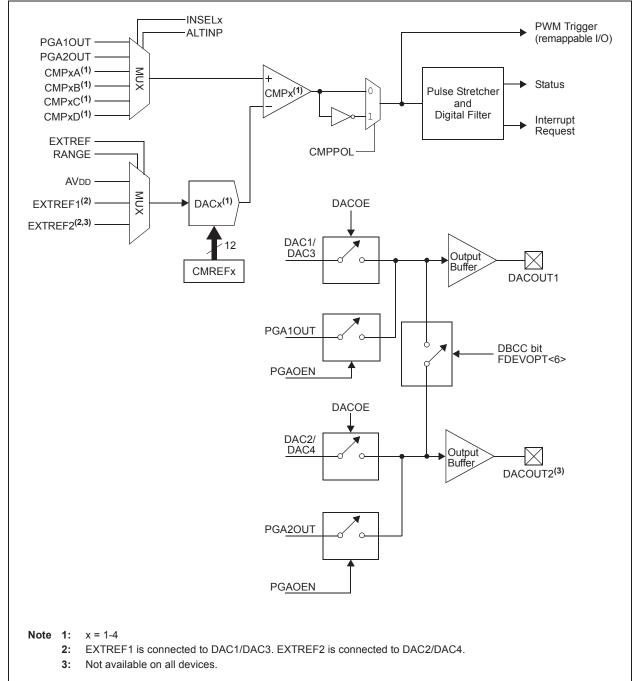


FIGURE 24-1: HIGH-SPEED ANALOG COMPARATOR x MODULE BLOCK DIAGRAM

24.3 Module Applications

This module provides a means for the SMPS dsPIC[®] DSC devices to monitor voltage and currents in a power conversion application. The ability to detect transient conditions and stimulate the dsPIC DSC processor and/or peripherals, without requiring the processor and ADC to constantly monitor voltages or currents, frees the dsPIC DSC to perform other tasks.

The comparator module has a high-speed comparator and an associated 12-bit DAC that provides a programmable reference voltage to the inverting input of the comparator. The polarity of the comparator output is user-programmable. The output of the module can be used in the following modes:

- Generate an Interrupt
- Trigger an ADC Sample and Convert Process
- Truncate the PWM Signal (current limit)
- Truncate the PWM Period (current minimum)
- Disable the PWM Outputs (Fault latch)

The output of the comparator module may be used in multiple modes at the same time, such as: 1) generate an interrupt, 2) have the ADC take a sample and convert it, and 3) truncate the PWM output in response to a voltage being detected beyond its expected value.

The comparator module can also be used to wake-up the system from Sleep or Idle mode when the analog input voltage exceeds the programmed threshold voltage.

24.4 Digital-to-Analog Comparator (DAC)

Each analog comparator has a dedicated 12-bit DAC that is used to program the comparator threshold voltage via the CMPxDAC register. The DAC voltage reference source is selected using the EXTREF and RANGE bits in the CMPxCON register.

The EXTREF bit selects either the external voltage reference, EXTREFx, or an internal source as the voltage reference source. The EXTREFx input enables users to connect to a voltage reference that better suits their application. The RANGE bit enables AVDD as the voltage reference source for the DAC when an internal voltage reference is selected.

Note: EXTREF2 is not available on all devices.

Each DACx has an output enable bit, DACOE, in the CMPxCON register that enables the DACx reference voltage to be routed to an external output pin (DACOUTx). Refer to Figure 24-1 for connecting the DACx output voltage to the DACOUTx pins.

Note 1:	Ensure that multiple DACOE bits are not
	set in software. The output on the
	DACOUTx pin will be indeterminate if
	multiple comparators enable the DACx
	output.

2: DACOUT2 is not available on all devices.

24.5 Pulse Stretcher and Digital Logic

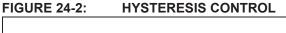
The analog comparator can respond to very fast transient signals. After the comparator output is given the desired polarity, the signal is passed to a pulse stretching circuit. The pulse stretching circuit has an asynchronous set function and a delay circuit that ensures the minimum pulse width is three system clock cycles wide to allow the attached circuitry to properly respond to a narrow pulse event.

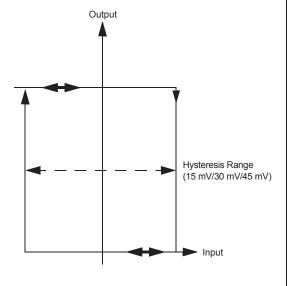
The pulse stretcher circuit is followed by a digital filter. The digital filter is enabled via the FLTREN bit in the CMPxCON register. The digital filter operates with the clock specified via the FCLKSEL bit in the CMPxCON register. The comparator signal must be stable in a high or low state, for at least three of the selected clock cycles, for it to pass through the digital filter.

24.6 Hysteresis

An additional feature of the module is hysteresis control. Hysteresis can be enabled or disabled and its amplitude can be controlled by the HYSSEL<1:0> bits in the CMPxCON register. Three different values are available: 15 mV, 30 mV and 45 mV. It is also possible to select the edge (rising or falling) to which hysteresis is to be applied.

Hysteresis control prevents the comparator output from continuously changing state because of small perturbations (noise) at the input (see Figure 24-2).





24.7 Analog Comparator Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

24.7.1 KEY RESOURCES

- "High-Speed Analog Comparator Module" (DS70005128) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CMPON	_	CMPSIDL	HYSSEL1	HYSSEL0	FLTREN	FCLKSEL	DACOE
bit 15	•			•		•	bit 8
R/W-0	R/W-0	R/W-0	R/W-0	HS/HC-0	R/W-0	R/W-0	R/W-0
INSEL1	INSEL0	EXTREF	HYSPOL	CMPSTAT	ALTINP	CMPPOL	RANGE
bit 7							bit 0
Legend:		HC = Hardware	e Clearable bit	HS = Hardwa	re Settable bit		
R = Readable	e bit	W = Writable b	bit	U = Unimpler	nented bit, rea	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 15	CMPON: Co	omparator Opera	ting Mode bit				
		ator module is er ator module is di		es power consu	imption)		
bit 14	Unimpleme	nted: Read as ')'				
bit 13	CMPSIDL: (Comparator Stop	in Idle Mode b	pit			
	0 = Continue	nues module opera	tion in Idle mo	de			
		s multiple compa	-		1' disables all c	omparators while	e in Idle mode.
bit 12-11		0>: Comparator	Hysteresis Se	lect bits			
	11 = 45 mV 10 = 30 mV						
	01 = 15 mV						
	00 = No hys	teresis is selecte	ed				
bit 10		gital Filter Enabl	e bit				
		ter is enabled ter is disabled					
bit 9	FCLKSEL:	Digital Filter and	Pulse Stretche	er Clock Select	bit		
	0	ter and pulse str ter and pulse str					
bit 8	DACOE: DA	Cx Output Enab	le bit				
		nalog voltage is o					
		nalog voltage is i			Tx pin		
bit 7-6		: Input Source S					
		0, Select from C CMPxD input p		uts:			
		CMPxC input p					
		CMPxB input p					
		CMPxA input p					
	<u>If ALTINP =</u> 11 = Reserv	1, Select from A	iternate Inputs	• •			
	10 = Reserv						
		BPGA2 output					
	00 = Selects	PGA1 output					
		o associated on	ly with a single	comporator at	any aiyon time	The coffwore	man and a man ma

REGISTER 24-1: CMPxCON: COMPARATOR x CONTROL REGISTER

Note 1: DACOUTx can be associated only with a single comparator at any given time. The software must ensure that multiple comparators do not enable the DACx output by setting their respective DACOE bit.

REGISTER 24-1: CMPxCON: COMPARATOR x CONTROL REGISTER (CONTINUED)

bit 5	EXTREF: Enable External Reference bit
	1 = External source provides reference to DACx (maximum DAC voltage is determined by the external voltage source)
	0 = AVDD provides reference to DACx (maximum DAC voltage is AVDD)
bit 4	HYSPOL: Comparator Hysteresis Polarity Select bit
	 1 = Hysteresis is applied to the falling edge of the comparator output 0 = Hysteresis is applied to the rising edge of the comparator output
bit 3	CMPSTAT: Comparator Current State bit
	Reflects the current output state of Comparator x, including the setting of the CMPPOL bit.
bit 2	ALTINP: Alternate Input Select bit
	1 = INSEL<1:0> bits select alternate inputs
	0 = INSEL<1:0> bits select comparator inputs
bit 1	CMPPOL: Comparator Output Polarity Control bit
	1 = Output is inverted
	0 = Output is non-inverted
bit 0	RANGE: DACx Output Voltage Range Select bit
	1 = AVDD is the maximum DACx output voltage
	0 = Unimplemented, do not use

Note 1: DACOUTx can be associated only with a single comparator at any given time. The software must ensure that multiple comparators do not enable the DACx output by setting their respective DACOE bit.

REGISTER 24-2: CMPxDAC: COMPARATOR x DAC CONTROL REGISTER

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	_	—		CMREI	F<11:8>	
bit 15		-					bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			CMRE	F<7:0>			
bit 7							bit 0
Legend:							
R = Readabl	e bit	W = Writable	bit	U = Unimplemented bit, read as '0'			
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	
bit 15-12	Unimplemen	ted: Read as '	0'				
bit 11-0	CMREF<11:0)>: Comparator	Reference Vo	oltage Select bi	its		
	1111111111	.11					
	•						
	•						
	•						
	•	OF ([CMR	EF<11:0>] * (EXTREF)/409	6) volts (EXTRI	EF = ⊥)	
	•						
	0000000000	000					

NOTES:

25.0 PROGRAMMABLE GAIN AMPLIFIER (PGA)

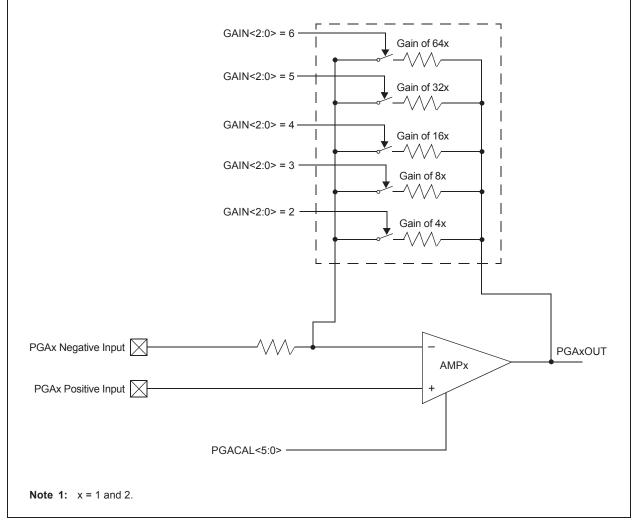
- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Programmable Gain Amplifier (PGA)" (DS70005146) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family devices have two Programmable Gain Amplifiers (PGA1, PGA2). The PGA is an op amp-based, non-inverting amplifier with user-programmable gains. The output of the PGA can be connected to a number of dedicated Sampleand-Hold inputs of the Analog-to-Digital Converter and/ or to the high-speed analog comparator module. The PGA has five selectable gains and may be used as a ground referenced amplifier (single-ended) or used with an independent ground reference point.

Key features of the PGA module include:

- Single-Ended or Independent Ground Reference
- Selectable Gains: 4x, 8x, 16x, 32x and 64x
- High Gain Bandwidth
- · Rail-to-Rail Output Voltage
- Wide Input Voltage Range





25.1 Module Description

The Programmable Gain Amplifiers are used to amplify small voltages (i.e., voltages across burden/shunt resistors) to improve the signal-to-noise ratio of the measured signal. The PGAx output voltage can be read by any of the four dedicated Sample-and-Hold circuits on the ADC module. The output voltage can also be fed to the comparator module for overcurrent/ voltage protection. Figure 25-2 shows a functional block diagram of the PGAx module. Refer to **Section 22.0 "High-Speed, 12-Bit Analog-to-Digital Converter (ADC)"** and **Section 24.0 "High-Speed Analog Comparator"** for more interconnection details.

The gain of the PGAx module is selectable via the GAIN<2:0> bits in the PGAxCON register. There are five selectable gains, ranging from 4x to 64x. The SELPI<2:0> and SELNI<2:0> bits in the PGAxCON register select one of four positive/negative inputs to the PGAx module. For single-ended applications, the SELNI<2:0> bits will select the ground as the negative

input source. To provide an independent ground reference, the PGAxN2 and PGAxN3 pins are available as the negative input source to the PGAx module.

Note 1: Not all PGA positive/negative inputs are available on all devices. Refer to the specific device pinout for available input source pins.

The output voltage of the PGAx module can be connected to the DACOUTx pin by setting the PGAOEN bit in the PGAxCON register. When the PGAOEN bit is enabled, the output voltage of PGA1 is connected to DACOUT1 and PGA2 is connected to DACOUT2. For devices with a single DACOUTx pin, the output voltage of PGA2 can be connected to DACOUT1 by configuring the DBCC Configuration bit in the FDEVOPT register (FDEVOPT<6>).

If both the DACx output voltage and PGAx output voltage are connected to the DACOUTx pin, the resulting output voltage would be a combination of signals. There is no assigned priority between the PGAx module and the DACx module.

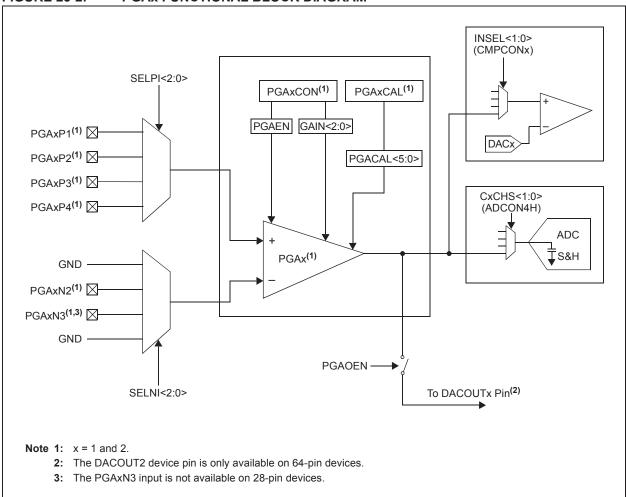


FIGURE 25-2: PGAx FUNCTIONAL BLOCK DIAGRAM

25.2 PGA Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

25.2.1 KEY RESOURCES

- "Programmable Gain Amplifier (PGA)" (DS70005146) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- · Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

REGISTER 25-1: PGAxCON: PGAx CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
PGAEN	PGAOEN	SELPI2	SELPI1	SELPI0	SELNI2	SELNI1	SELNI0			
bit 15	•	•	•	•	•	-	bit 8			
U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0			
	—	—	—	—	GAIN2	GAIN1	GAIN0			
bit 7							bit C			
Legend:										
R = Readabl	e bit	W = Writable	bit	U = Unimpler	mented bit, read	1 as '0'				
-n = Value at	POR	'1' = Bit is set	t	'0' = Bit is cle	eared	x = Bit is unkr	nown			
bit 15		dule is enable	••	wer consumpti	ion)					
				wer consumpti	ion)					
bit 14	PGAOEN: PGAx Output Enable bit 1 = PGAx output is connected to the DACOUTx pin									
	0 = PGAx output is not connected to the DACOUTx pin									
bit 13-11	SELPI<2:0>: PGAx Positive Input Selection bits									
	111 = Reserv 110 = Reserv 101 = Reserv 100 = Reserv 011 = PGAXF 010 = PGAXF 001 = PGAXF 000 = PGAXF	ved ved ved 24 23 22								
bit 10-8	SELNI<2:0>:	SELNI<2:0>: PGAx Negative Input Selection bits								
	010 = PGAxN 001 = PGAxN	ved ved ved d (Single-Ende ଏ3								
bit 7-3	Unimplemen	ted: Read as '	0'							

REGISTER 25-1: PGAxCON: PGAx CONTROL REGISTER (CONTINUED)

- bit 2-0 GAIN<2:0>: PGAx Gain Selection bits
 - 111 = Reserved
 - 110 = Gain of 64x
 - 101 = Gain of 32x
 - 100 = Gain of 16x
 - 011 = Gain of 8x
 - 010 = Gain of 4x
 - 001 = Reserved
 - 000 = Reserved

REGISTER 25-2: PGAxCAL: PGAx CALIBRATION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	_	—	_	—	—	—	—
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	_			PGAC	CAL<5:0>		
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	mented bit, read	l as '0'	
-n = Value at P	OR	'1' = Bit is set	'1' = Bit is set '0' = Bit is cleared x = Bit is unknown				

bit 15-6 Unimplemented: Read as '0'

bit 5-0 **PGACAL<5:0>:** PGAx Offset Calibration bits

The calibration values for PGA1 and PGA2 must be copied from Flash addresses, 0x800E48 and 0x800E4C, respectively, into these bits before the module is enabled. Refer to the calibration data address table (Table 27-3) in **Section 27.0** "**Special Features**" for more information.

26.0 CONSTANT-CURRENT SOURCE

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The constant-current source module is a precision current generator and is used in conjunction with the ADC module to measure the resistance of external resistors connected to device pins.

26.1 Features Overview

The constant-current source module offers the following major features:

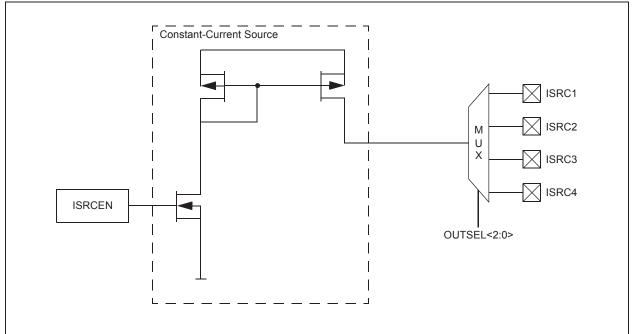
- Constant-Current Generator (10 µA nominal)
- Internal Selectable Connection to One of Four Pins
- Enable/Disable bit

26.2 Module Description

Figure 26-1 shows a functional block diagram of the constant-current source module. It consists of a precision current generator with a nominal value of 10 μ A. The module can be enabled and disabled using the ISRCEN bit in the ISRCCON register. The output of the current generator is internally connected to a device pin. The dsPIC33EPXXXGS70X/80X family can have up to four selectable current source pins. The OUTSEL<2:0> bits in the ISRCCON register allow selection of the target pin.

The current source is calibrated during testing.

FIGURE 26-1: CONSTANT-CURRENT SOURCE MODULE BLOCK DIAGRAM



26.3 Current Source Control Register

REGISTER 26-1: ISRCCON: CONSTANT-CURRENT SOURCE CONTROL REGISTER

R/W-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
ISRCEN			_	_	OUTSEL2 ⁽¹⁾	OUTSEL1 ⁽¹⁾	OUTSEL0 ⁽¹⁾
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
		ISRCCAL5	ISRCCAL4	ISRCCAL3	ISRCCAL2	ISRCCAL1	ISRCCAL0
bit 7							bit C
Legend:	1- 1-14		L :4				
R = Readab		W = Writable			nented bit, read		
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	iown
		> Output Con	stant-Current	Select bits ⁽¹⁾			
bit 10-8	111 = Reserv 110 = Reserv 101 = Reserv 100 = Reserv 011 = Input p 010 = Input p 001 = Input p	ed ed ed in, ISRC4 (AN4 in, ISRC3 (AN4 in, ISRC3 (AN4	4) 5) 6)				
	111 = Reserv 110 = Reserv 101 = Reserv 100 = Reserv 011 = Input pi 010 = Input pi 001 = Input pi	ed ed ed in, ISRC4 (AN4 in, ISRC3 (AN4 in, ISRC2 (AN4 in, ISRC1 (AN	4) 5) 6) 12)				
bit 10-8 bit 7-6 bit 5-0	111 = Reserv 110 = Reserv 101 = Reserv 100 = Reserv 011 = Input pi 010 = Input pi 001 = Input pi 000 = Input pi	ed ed ed in, ISRC4 (AN4 in, ISRC3 (AN4 in, ISRC3 (AN4	4) 5) 6) 12) 0'		15		

Note 1: ISRC1 and ISCR3 are not available on 28, 44 and 48-pin packages. Refer to the "Pin Diagrams" section for availability.

27.0 SPECIAL FEATURES

Note: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Device Configuration" (DS70000618), "Watchdog Timer and Power-Saving Modes" (DS70615) and "CodeGuard™ Intermediate Security" (DS70005182) in the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website (www.microchip.com).

The dsPIC33EPXXXGS70X/80X family devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard[™] Security
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming[™] (ICSP[™])
- In-Circuit Emulation
- Brown-out Reset (BOR)

27.1 Configuration Bits

In dsPIC33EPXXXGS70X/80X family devices, the Configuration Words are implemented as volatile memory. This means that configuration data must be programmed each time the device is powered up. Configuration data is stored at the end of the on-chip program memory space, known as the Flash Configuration Words. Their specific locations are shown in Table 27-1 with detailed descriptions in Table 27-2. The configuration data is automatically loaded from the Flash Configuration Words to the proper Configuration Shadow registers during device Resets.

For devices operating in Dual Partition Flash modes, the BSEQx bits (FBTSEQ<11:0>) determine which panel is the Active Partition at start-up and the Configuration Words from that panel are loaded into the Configuration Shadow registers.

Note:	Configuration data is reloaded on all types
	of device Resets.

When creating applications for these devices, users should always specifically allocate the location of the Flash Configuration Words for configuration data in their code for the compiler. This is to make certain that program code is not stored in this address when the code is compiled. Program code executing out of configuration space will cause a device Reset.

Note: Performing a page erase operation on the last page of program memory clears the Flash Configuration Words.

TABLE 27-1: CONFIGURATION REGISTER MAP⁽³⁾

Name	Address	Device Memory Size (Kbytes)	Bits 23-16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0										
FSEC	00AF80	64		AIVTDIS	_	_	_	CSS<2:0> CWRP GSS<			GSS<1	:0>	GWRP	_	BSEN	BSS<1	1:0> BWRP												
	015780	128																											
FBSLIM	00AF90	64		_	_	_		BSLIM<12:0>																					
	015790	128																											
FSIGN	00AF90	64		Reserved ⁽²⁾	—	_	_	_	_	_	_	_	_	_	_	—	_	_	_										
	015794 00AF98	128																											
FOSCSEL	00AF98 015798	64 128		—	—	—	—	—	—	—	—	IESO	—	—	—	—	FI	NOSC<2:0)>										
	015798 00AF9C	64																											
FOSC	01579C	128	-			—	—	—	. _		PLLKEN	FCKSM<	:1:0> IOL1WAY		—	—	OSCIOFNC POSCN		CMD<1:0>										
	00AFA0	64														-													
FWDT	0157A0	128	-	—	—	—	—			/IN<1:0>	WINDIS WDTEN		EN<1:0> WDTPRE			WDTPOST<3:0>													
	00AFA4	64																		(1)									
FPOR	0157A4	128	-	—	_	-	-	—	-	—	—	—	-	-	—	—	—	—	Reserved ⁽¹⁾										
5100	00AFA8	64												D.T.O.L.D								D (1)		174.0511					
FICD	0157A8	128	_	BTSWP	—	_		_	_	_	—	Reserved ⁽¹⁾	—	JTAGEN	—	—	_	ICS	S<1:0>										
FDEVOPT	00AFAC	64											DDCC		ALTI2C2	ALTI2C1	Reserved ⁽¹⁾		PWMLOCK										
	0157AC	128	_	_		_	_	_	_	_	_	-	DBCC	—	AL112C2	ALTIZUT	Reserved		PWWILOCK										
FALTREG	00AFB0	64	—	_	C.	TYT4~2.0				TYT2-2	·0>			CTYT2 <2-	05	_	C.	TXT1 <2:0											
	0157B0	128	CTXT4<2:0>					- CTXT3<3:0> - CTXT2 <2:0>						0-		C	171172.0	J-											
FBTSEQ	00AFFC	64	IBSEQ<11:0>						BSEQ<11:0>																				
	0157FC	128																											
FBOOT ⁽⁴⁾	801000	—	—	—	—	—	—	—	—	—	_	—	—	—	—	—	_	BTMC	DDE<1:0>										

Note 1: These bits are reserved and must be programmed as '1'.

2: This bit is reserved and must be programmed as '0'.

3: When operating in Dual Partition Flash mode, each partition will have dedicated Configuration registers. On a device Reset, the configuration values of the Active Partition are read at start-up, but during a soft swap condition, the configuration settings of the newly Active Partition are ignored.

4: FBOOT resides in configuration memory space.

Bit Field Description BSS<1:0> Boot Segment Code-Protect Level bits 11 = Boot Segment is not code-protected other than BWRP 10 = Standard security 0x = High security **BSEN** Boot Segment Control bit 1 = No Boot Segment is enabled 0 = Boot Segment size is determined by the BSLIM<12:0> bits BWRP Boot Segment Write-Protect bit 1 = Boot Segment can be written 0 = Boot Segment is write-protected BSLIM<12:0> Boot Segment Flash Page Address Limit bits Contains the last active Boot Segment page. The value to be programmed is the inverted page address, such that programming additional '0's can only increase the Boot Segment size (i.e., 0x1FFD = 2 Pages or 1024 IW). GSS<1:0> General Segment Code-Protect Level bits 11 = User program memory is not code-protected 10 = Standard security 0x = High security GWRP General Segment Write-Protect bit 1 = User program memory is not write-protected 0 = User program memory is write-protected CWRP Configuration Segment Write-Protect bit 1 = Configuration data is not write-protected 0 = Configuration data is write-protected CSS<2:0> Configuration Segment Code-Protect Level bits 111 = Configuration data is not code-protected 110 = Standard security 10x = Enhanced security 0xx = High security BTSWP BOOTSWP Instruction Enable/Disable bit 1 = BOOTSWP instruction is disabled 0 = BOOTSWP instruction is enabled BSEQ<11:0> Boot Sequence Number bits (Dual Partition modes only) Relative value defining which partition will be active after device Reset; the partition containing a lower boot number will be active. Inverse Boot Sequence Number bits (Dual Partition modes only) IBSEQ<11:0> The one's complement of BSEQ<11:0>; must be calculated by the user and written for device programming. If BSEQx and IBSEQx are not complements of each other, the Boot Sequence Number is considered to be invalid. AIVTDIS⁽¹⁾ Alternate Interrupt Vector Table bit 1 = Alternate Interrupt Vector Table is disabled 0 = Alternate Interrupt Vector Table is enabled if INTCON2<8> = 1 **IESO** Two-Speed Oscillator Start-up Enable bit 1 = Starts up device with FRC, then automatically switches to the user-selected oscillator source when ready 0 = Starts up device with the user-selected oscillator source PWMLOCK PWMx Lock Enable bit 1 = Certain PWMx registers may only be written after a key sequence 0 = PWMx registers may be written without a key sequence

TABLE 27-2: CONFIGURATION BITS DESCRIPTION

Bit Field	Description						
FNOSC<2:0>	Oscillator Selection bits 111 = Fast RC Oscillator with Divide-by-N (FRCDIVN) 110 = Fast RC Oscillator with Divide-by-16 101 = Low-Power RC Oscillator (LPRC) 100 = Reserved; do not use 011 = Primary Oscillator with PLL module (XT+PLL, HS+PLL, EC+PLL) 010 = Primary Oscillator (XT, HS, EC) 001 = Fast RC Oscillator with Divide-by-N with PLL module (FRCPLL)						
FCKSM<1:0>	000 = Fast RC Oscillator (FRC) Clock Switching Mode bits 1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled 01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled						
IOL1WAY	 00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled Peripheral Pin Select Configuration bit 1 = Allows only one reconfiguration 0 = Allows multiple reconfigurations 						
OSCIOFNC	OSC2 Pin Function bit (except in XT and HS modes) 1 = OSC2 is the clock output 0 = OSC2 is a general purpose digital I/O pin						
POSCMD<1:0>	Primary Oscillator Mode Select bits 11 = Primary Oscillator is disabled 10 = HS Crystal Oscillator mode 01 = XT Crystal Oscillator mode 00 = EC (External Clock) mode						
WDTEN<1:0>	 Watchdog Timer Enable bits 11 = Watchdog Timer is always enabled (LPRC oscillator cannot be disabled; clearing the SWDTEN bit in the RCON register will have no effect) 10 = Watchdog Timer is enabled/disabled by user software (LPRC can be disabled by clearing the SWDTEN bit in the RCON register) 01 = Watchdog Timer is enabled only while device is active and is disabled while in Sleep mode; software control is disabled in this mode 00 = Watchdog Timer and SWDTEN bit are disabled 						
WINDIS	Watchdog Timer Window Enable bit 1 = Watchdog Timer is in Non-Window mode 0 = Watchdog Timer is in Window mode						
PLLKEN	PLL Lock Enable bit 1 = PLL lock is enabled 0 = PLL lock is disabled						
WDTPRE	Watchdog Timer Prescaler bit 1 = 1:128 0 = 1:32						
WDTPOST<3:0>	Watchdog Timer Postscaler bits 1111 = 1:32,768 1110 = 1:16,384 • • • • • • • • • • • • •						

TABLE 27-2: CONFIGURATION BITS DESCRIPTION (CONTINUED)

Bit Field	Description
WDTWIN<1:0>	Watchdog Timer Window Select bits
	11 = WDT window is 25% of the WDT period
	10 = WDT window is 37.5% of the WDT period
	01 = WDT window is 50% of the WDT period
	00 = WDT window is 75% of the WDT period
ALTI2C1	Alternate I2C1 Pin bit
	1 = I2C1 is mapped to the SDA1/SCL1 pins
	0 = I2C1 is mapped to the ASDA1/ASCL1 pins
ALTI2C2	Alternate I2C2 Pin bit
	1 = I2C2 is mapped to the SDA2/SCL2 pins
	0 = I2C2 is mapped to the ASDA2/ASCL2 pins
JTAGEN	JTAG Enable bit
	1 = JTAG is enabled
	0 = JTAG is disabled
ICS<1:0>	ICD Communication Channel Select bits
	11 = Communicates on PGEC1 and PGED1
	10 = Communicates on PGEC2 and PGED2
	01 = Communicates on PGEC3 and PGED3
	00 = Reserved, do not use
DBCC	DACx Output Cross Connection Select bit
	1 = No cross connection between DAC outputs
	0 = Interconnects DACOUT1 and DACOUT2
CTXT1<2:0>	Alternate Working Register Set 1 Interrupt Priority Level (IPL) Select bits
	111 = Reserved
	110 = Assigned to IPL of 7
	101 = Assigned to IPL of 6
	100 = Assigned to IPL of 5
	011 = Assigned to IPL of 4
	010 = Assigned to IPL of 3
	001 = Assigned to IPL of 2 000 = Assigned to IPL of 1
CTXT2<2:0>	
GTXT2<2.0>	Alternate Working Register Set 2 Interrupt Priority Level (IPL) Select bits
	111 = Reserved 110 = Assigned to IPL of 7
	101 = Assigned to IPL of 7 101 = Assigned to IPL of 6
	100 = Assigned to IPL of 5
	011 = Assigned to IPL of 4
	010 = Assigned to IPL of 3
	001 = Assigned to IPL of 2
	000 = Assigned to IPL of 1
CTXT3<2:0>	Alternate Working Register Set 3 Interrupt Priority Level (IPL) Select bits
	111 = Reserved
	110 = Assigned to IPL of 7
	101 = Assigned to IPL of 6
	100 = Assigned to IPL of 5
	011 = Assigned to IPL of 4
	010 = Assigned to IPL of 3
	001 = Assigned to IPL of 2
	000 = Assigned to IPL of 1

TABLE 27-2: CONFIGURATION BITS DESCRIPTION (CONTINUED)

TABLE 27-2: CONFIGURATION BITS DESCRIPTION (CONTINUED)

Bit Field	Description
CTXT4<2:0>	Alternate Working Register Set 4 Interrupt Priority Level (IPL) Select bits
	111 = Reserved
	110 = Assigned to IPL of 7
	101 = Assigned to IPL of 6
	100 = Assigned to IPL of 5
	011 = Assigned to IPL of 4
	010 = Assigned to IPL of 3
	001 = Assigned to IPL of 2
	000 = Assigned to IPL of 1
BTMODE<1:0>	Boot Mode Configuration bits
	11 = Single Partition mode
	10 = Dual Partition mode
	01 = Protected Dual Partition mode
	00 = Privileged Dual Partition mode

27.2 Device Calibration and Identification

The PGAx and current source modules on the dsPIC33EPXXXGS70X/80X family devices require Calibration Data registers to improve performance of the module over a wide operating range. These Calibration registers are read-only and are stored in configuration memory space. Prior to enabling the module, the calibration data must be read (TBLPAG and Table Read instruction) and loaded into its respective SFR registers. The device calibration addresses are shown in Table 27-3.

The dsPIC33EPXXXGS70X/80X devices have two Identification registers near the end of configuration memory space that store the Device ID (DEVID) and Device Revision (DEVREV). These registers are used to determine the mask, variant and manufacturing information about the device. These registers are read-only and are shown in Register 27-1 and Register 27-2.

Calibration Name	Address	Bits 23-16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PGA1CAL	800E48	—	_	_	_	_	—	—	_	_	_	_	PGA1 Calibration Data					
PGA2CAL	800E4C	_	—	—	—	—	_	—	—	—	—	—	PGA2 Calibration Data					
ISRCCAL	800E78	—	_	—	—	—	_	—	—	—	—	—	Current Source Calibration Data			ata		

Note 1: The calibration data must be copied into its respective SFR registers prior to enabling the module.

REGISTER 27-1: DEVID: DEVICE ID REGISTER

R	R	R	R	R	R	R	R
			DEVID<	23:16>			
bit 23							bit 16
R	R	R	R	R	R	R	R
			DEVID	<15:8>			
bit 15							bit 8
R	R	R	R	R	R	R	R
			DEVID	<7:0>			
bit 7							bit 0
Legend:	gend: R = Read-Only bit U = Unimplemented bit						

bit 23-0 **DEVID<23:0>:** Device Identifier bits

REGISTER 27-2: DEVREV: DEVICE REVISION REGISTER

_	-	-		-	-	-	_
R	R	R	R	R	R	R	R
			DEVREV	/<23:16>			
bit 23							bit 16
R	R	R	R	R	R	R	R
			DEVRE	/<15:8>			
bit 15							bit 8
R	R	R	R	R	R	R	R
			DEVRE	V<7:0>			
bit 7							bit 0
Legend: R = Read-only bit U = Unimplemented bit							

bit 23-0 **DEVREV<23:0>:** Device Revision bits

27.3 User OTP Memory

The dsPIC33EPXXXGS70X/80X family devices contain 64 words of user One-Time-Programmable (OTP) memory, located at addresses, 0x800F80 through 0x800FFC. The user OTP Words can be used for storing checksum, code revisions, product information, such as serial numbers, system manufacturing dates, manufacturing lot numbers and other application-specific information. These words can only be written once at program time and not at run time; they can be read at run time.

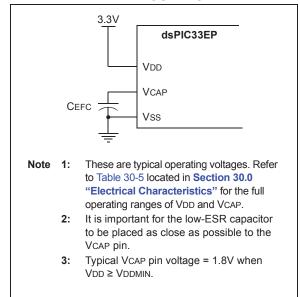
27.4 On-Chip Voltage Regulator

All the dsPIC33EPXXXGS70X/80X family devices power their core digital logic at a nominal 1.8V. This can create a conflict for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, all devices in the dsPIC33EPXXXGS70X/80X family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator provides power to the core from the other VDD pins. A low-ESR (less than 1 Ohm) capacitor (such as tantalum or ceramic) must be connected to the VCAP pin (Figure 27-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in Table 30-5, located in Section 30.0 "Electrical Characteristics".

Note:	It is important for the low-ESR capacitor to
	be placed as close as possible to the VCAP
	pin.

FIGURE 27-1: CONNECTIONS FOR THE ON-CHIP VOLTAGE REGULATOR^(1,2,3)



27.5 Brown-out Reset (BOR)

The Brown-out Reset (BOR) module is based on an internal voltage reference circuit that monitors the regulated supply voltage, VCAP. The main purpose of the BOR module is to generate a device Reset when a brown-out condition occurs. Brown-out conditions are generally caused by glitches on the AC mains (for example, missing portions of the AC cycle waveform due to bad power transmission lines or voltage sags due to excessive current draw when a large inductive load is turned on).

A BOR generates a Reset pulse which resets the device. The BOR selects the clock source based on the device Configuration bit values (FNOSC<2:0> and POSCMD<1:0>).

If an Oscillator mode is selected, the BOR activates the Oscillator Start-up Timer (OST). The system clock is held until OST expires. If the PLL is used, the clock is held until the LOCK bit (OSCCON<5>) is '1'.

Concurrently, the Power-up Timer (PWRT) Time-out (TPWRT) is applied before the internal Reset is released. If TPWRT = 0 and a crystal oscillator is being used, then a nominal delay of TFSCM is applied. The total delay in this case is TFSCM. Refer to Parameter SY35 in Table 30-23 of **Section 30.0 "Electrical Characteristics**" for specific TFSCM values.

The BOR status bit (RCON<1>) is set to indicate that a BOR has occurred. The BOR circuit continues to operate while in Sleep or Idle modes and resets the device should VDD fall below the BOR threshold voltage.

27.6 Watchdog Timer (WDT)

For dsPIC33EPXXXGS70X/80X family devices, the WDT is driven by the LPRC oscillator. When the WDT is enabled, the clock source is also enabled.

27.6.1 PRESCALER/POSTSCALER

The nominal WDT clock source from LPRC is 32 kHz. This feeds a prescaler that can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the WDTPRE Configuration bit. With a 32 kHz input, the prescaler yields a WDT Time-out Period (TWDT), as shown in Parameter SY12 in Table 30-23.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPOST<3:0> Configuration bits (FWDT<3:0>), which allow the selection of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler time-out periods, ranges from 1 ms to 131 seconds can be achieved.

The WDT, prescaler and postscaler are reset:

- · On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSCx bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

Note: The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

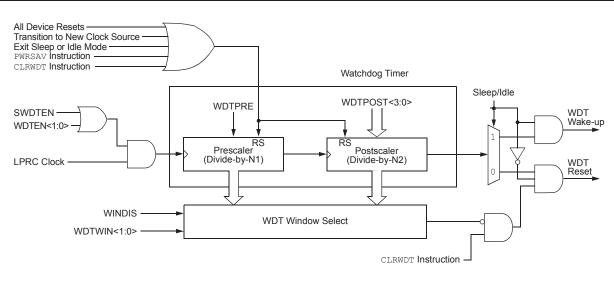


FIGURE 27-2: WDT BLOCK DIAGRAM

27.6.2 SLEEP AND IDLE MODES

If the WDT is enabled, it continues to run during Sleep or Idle modes. When the WDT time-out occurs, the device wakes and code execution continues from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bit (RCON<3:2>) needs to be cleared in software after the device wakes up.

27.6.3 ENABLING WDT

The WDT is enabled or disabled by the WDTEN<1:0> Configuration bits in the FWDT Configuration register. When the WDTEN<1:0> Configuration bits have been programmed to '0b11', the WDT is always enabled.

The WDT can be optionally controlled in software when the WDTEN<1:0> Configuration bits have been programmed to '0b10'. The WDT is enabled in software by setting the SWDTEN control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user application to enable the WDT for critical code segments and disables the WDT during non-critical segments for maximum power savings.

The WDT Time-out flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

27.6.4 WDT WINDOW

The Watchdog Timer has an optional Windowed mode, enabled by programming the WINDIS bit in the WDT Configuration register (FWDT<7>). In the Windowed mode (WINDIS = 0), the WDT should be cleared based on the settings in the programmable Watchdog Timer Window select bits (WDTWIN<1:0>).

27.7 JTAG Interface

The dsPIC33EPXXXGS70X/80X family devices implement a JTAG interface, which supports boundary scan device testing. Detailed information on this interface is provided in future revisions of the document.

Note:	Refer to "Programming and Diagnostics"
	(DS70608) in the "dsPIC33/PIC24 Family
	Reference Manual" for further information on
	usage, configuration and operation of the
	JTAG interface.

27.8 In-Circuit Serial Programming™ (ICSP™)

The dsPIC33EPXXXGS70X/80X family devices can be serially programmed while in the end application circuit. This is done with two lines for clock and data, and three other lines for power, ground and the programming sequence. Serial programming allows customers to manufacture boards with unprogrammed devices and then program the device just before shipping the product. Serial programming also allows the most recent firmware or a custom firmware to be programmed. Refer to the *"dsPIC33E/PIC24E Flash Programming Specification for Devices with Volatile Configuration Bits"* (DS70663) for details about In-Circuit Serial ProgrammingTM (ICSPTM).

Any of the three pairs of programming clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

27.9 In-Circuit Debugger

When MPLAB[®] ICD 3 or REAL ICE[™] emulator is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the PGECx (Emulation/Debug Clock) and PGEDx (Emulation/Debug Data) pin functions.

Any of the three pairs of debugging clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

To use the in-circuit debugger function of the device, the design must implement ICSP connections to $\overline{\text{MCLR}}$, VDD, VSS and the PGECx/PGEDx pin pair. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins (PGECx and PGEDx).

27.10 Code Protection and CodeGuard™ Security

dsPIC33EPXXXGS70X/80X devices offer multiple levels of security for protecting individual intellectual property. The program Flash protection can be broken up into three segments: Boot Segment (BS), General Segment (GS) and Configuration Segment (CS). Boot Segment has the highest security privilege and can be thought to have limited restrictions when accessing other segments. General Segment has the least security and is intended for the end user system code. Configuration Segment contains only the device user configuration data which is located at the end of the program memory space.

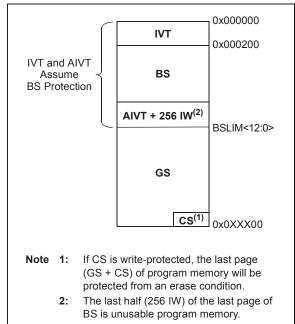
The code protection features are controlled by the Configuration registers, FSEC and FBSLIM. The FSEC register controls the code-protect level for each segment and if that segment is write-protected. The size of BS and GS will depend on the BSLIM<12:0> bits setting and if the Alternate Interrupt Vector Table (AIVT) is enabled. The BSLIM<12:0> bits define the number of pages for BS with each page containing 512 IW. The smallest BS size is one page, which will consist of the Interrupt Vector Table (IVT) and 256 IW of code protection.

If the AIVT is enabled, the last page of BS will contain the AIVT and will not contain any BS code. With AIVT enabled, the smallest BS size is now two pages (1024 IW), with one page for the IVT and BS code, and the other page for the AIVT. Write protection of the BS does not cover the AIVT. The last page of BS can always be programmed or erased by BS code. The General Segment will start at the next page and will consume the rest of program Flash except for the Flash Configuration Words. The IVT will assume GS security only if BS is not enabled. The IVT is protected from being programmed or page erased when either security segment has enabled write protection.

Note: Refer to "CodeGuard™ Intermediate Security" (DS70005182) in the "dsPIC33/ PIC24 Family Reference Manual" for further information on usage, configuration and operation of CodeGuard Security.

The different device security segments are shown in Figure 27-3. Here, all three segments are shown but are not required. If only basic code protection is required, then GS can be enabled independently or combined with CS, if desired.

FIGURE 27-3: SECURITY SEGMENTS EXAMPLE FOR dsPIC33EPXXXGS70X/80X DEVICES



dsPIC33EPXXXGS70X/80X family devices can be operated in Dual Partition mode, where security is required for each partition. When operating in Dual Partition mode, the Active and Inactive Partitions both contain unique copies of the Reset vector, Interrupt Vector Tables (IVT and AIVT, if enabled) and the Flash Configuration Words. Both partitions have the three security segments described previously. Code may not be executed from the Inactive Partition, but it may be programmed by, and read from, the Active Partition, subject to defined code protection. Figure 27-4 and Figure 27-5 show the different security segments for devices operating in Dual Partition mode.

The device may also operate in a Protected Dual Partition mode or in Privileged Dual Partition mode. In Protected Dual Partition mode, Partition 1 is permanently erase/write-protected. This implementation allows for a "Factory Default" mode, which provides a fail-safe backup image to be stored in Partition 1. For example, a fail-safe bootloader can be placed in Partition 1, along with a fail-safe backup code image, which can be used or rewritten into Partition 2 in the event of a failed Flash update to Partition 2.

Privileged Dual Partition mode performs the same function as Protected Dual Partition mode, except additional constraints are applied in an effort to prevent code in the Boot Segment and General Segment from being used against each other.

FIGURE 27-4:

SECURITY SEGMENTS EXAMPLE FOR dsPIC33EP64GS70X/80X DEVICES (DUAL PARTITION MODES)

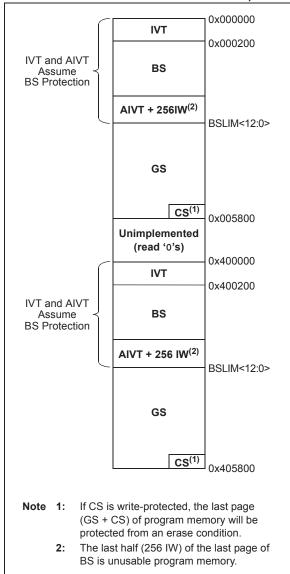
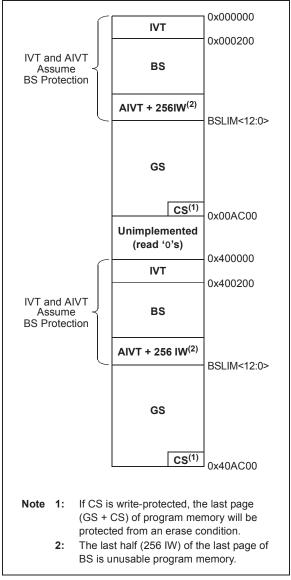


FIGURE 27-5: SECURITY SEGMENTS EXAMPLE FOR dsPIC33EP128GS70X/80X DEVICES (DUAL PARTITION MODES)



NOTES:

28.0 INSTRUCTION SET SUMMARY

Note: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/ 80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip web site (www.microchip.com).

The dsPIC33EP instruction set is almost identical to that of the dsPIC30F and dsPIC33F.

Most instructions are a single program memory word (24 bits). Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word, divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction.

The instruction set is highly orthogonal and is grouped into five basic categories:

- Word or byte-oriented operations
- · Bit-oriented operations
- · Literal operations
- DSP operations
- Control operations

Table 28-1 lists the general symbols used in describing the instructions.

The dsPIC33E instruction set summary in Table 28-2 lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand, which is typically a register 'Wb' without any address modifier
- The second source operand, which is typically a register 'Ws' with or without an address modifier
- The destination of the result, which is typically a register 'Wd' with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- · The file register specified by the value 'f'
- The destination, which could be either the file register 'f' or the W0 register, which is denoted as 'WREG'

Most bit-oriented instructions (including simple rotate/ shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of 'Ws' or 'f')
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register 'Wb')

The literal instructions that involve data movement can use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by 'k')
- The W register or file register where the literal value is to be loaded (specified by 'Wb' or 'f')

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand, which is a register 'Wb' without any address modifier
- The second source operand, which is a literal value
- The destination of the result (only if not the same as the first source operand), which is typically a register 'Wd' with or without an address modifier

The MAC class of DSP instructions can use some of the following operands:

- The accumulator (A or B) to be used (required operand)
- The W registers to be used as the two operands
- The X and Y address space prefetch operations
- The X and Y address space prefetch destinations
- · The accumulator write back destination

The other DSP instructions do not involve any multiplication and can include:

- The accumulator to be used (required)
- The source or destination operand (designated as Wso or Wdo, respectively) with or without an address modifier
- The amount of shift specified by a W register 'Wn' or a literal value

The control instructions can use some of the following operands:

- A program memory address
- The mode of the Table Read and Table Write instructions

Most instructions are a single word. Certain double-word instructions are designed to provide all the required information in these 48 bits. In the second word, the eight MSbs are '0's. If this second word is executed as an instruction (by itself), it executes as a NOP.

The double-word instructions execute in two instruction cycles.

Most single-word instructions are executed in a single instruction cycle, unless a conditional test is true or the Program Counter is changed as a result of the instruction, or a PSV or Table Read is performed. In these cases, the execution takes multiple instruction cycles, with the additional instruction cycle(s) executed as a NOP. Certain instructions that involve skipping over the subsequent instruction require either two or three cycles if the skip is performed, depending on whether the instruction being skipped is a single-word or two-word instruction. Moreover, double-word moves require two cycles.

Note: For more details on the instruction set, refer to the *"16-Bit MCU and DSC Programmer's Reference Manual"* (DS70000157).

Field	Description
#text	Means literal defined by "text"
(text)	Means "content of text"
[text]	Means "the location addressed by text"
{}	Optional field or operation
$a\in\{b,c,d\}$	a is selected from the set of values b, c, d
<n:m></n:m>	Register bit field
.b	Byte mode selection
.d	Double-Word mode selection
.S	Shadow register select
.W	Word mode selection (default)
Acc	One of two accumulators {A, B}
AWB	Accumulator Write-Back Destination Address register \in {W13, [W13]+ = 2}
bit4	4-bit bit selection field (used in word addressed instructions) $\in \{015\}$
C, DC, N, OV, Z	MCU Status bits: Carry, Digit Carry, Negative, Overflow, Sticky Zero
Expr	Absolute address, label or expression (resolved by the linker)
f	File register address ∈ {0x00000x1FFF}
lit1	1-bit unsigned literal $\in \{0,1\}$
lit4	4-bit unsigned literal ∈ {015}
lit5	5-bit unsigned literal ∈ {031}
lit8	8-bit unsigned literal \in {0255}
lit10	10-bit unsigned literal \in {0255} for Byte mode, {0:1023} for Word mode
lit14	14-bit unsigned literal ∈ {016384}
lit16	16-bit unsigned literal ∈ {065535}
lit23	23-bit unsigned literal \in {08388608}; LSb must be '0'
None	Field does not require an entry, can be blank
OA, OB, SA, SB	DSP Status bits: ACCA Overflow, ACCB Overflow, ACCA Saturate, ACCB Saturate
PC	Program Counter
Slit10	10-bit signed literal \in {-512511}
Slit16	16-bit signed literal ∈ {-3276832767}
Slit6	6-bit signed literal ∈ {-1616}
Wb	Base W register ∈ {W0W15}
Wd	Destination W register ∈ { Wd, [Wd], [Wd++], [Wd], [++Wd], [Wd] }
Wdo	Destination W register ∈ { Wnd, [Wnd], [Wnd++], [Wnd], [++Wnd], [Wnd], [Wnd+Wb] }
Wm,Wn	Dividend, Divisor Working register pair (Direct Addressing)

TABLE 28-1: SYMBOLS USED IN OPCODE DESCRIPTIONS

TABLE 28-1:	SYMBOLS USED IN OPCODE DESCRIPTIONS (CONTINUED)

Field	Description
Wm*Wm	Multiplicand and Multiplier Working register pair for Square instructions ∈ {W4 * W4,W5 * W5,W6 * W6,W7 * W7}
Wm*Wn	Multiplicand and Multiplier Working register pair for DSP instructions \in {W4 * W5,W4 * W6,W4 * W7,W5 * W6,W5 * W7,W6 * W7}
Wn	One of 16 Working registers \in {W0W15}
Wnd	One of 16 Destination Working registers ∈ {W0W15}
Wns	One of 16 Source Working registers ∈ {W0W15}
WREG	W0 (Working register used in file register instructions)
Ws	Source W register ∈ { Ws, [Ws], [Ws++], [Ws], [++Ws], [Ws] }
Wso	Source W register ∈ { Wns, [Wns], [Wns++], [Wns], [++Wns], [Wns], [Wns+Wb] }
Wx	X Data Space Prefetch Address register for DSP instructions ∈ {[W8] + = 6, [W8] + = 4, [W8] + = 2, [W8], [W8] - = 6, [W8] - = 4, [W8] - = 2, [W9] + = 6, [W9] + = 4, [W9] + = 2, [W9], [W9] - = 6, [W9] - = 4, [W9] - = 2, [W9 + W12], none}
Wxd	X Data Space Prefetch Destination register for DSP instructions ∈ {W4W7}
Wy	Y Data Space Prefetch Address register for DSP instructions ∈ {[W10] + = 6, [W10] + = 4, [W10] + = 2, [W10], [W10] - = 6, [W10] - = 4, [W10] - = 2, [W11] + = 6, [W11] + = 4, [W11] + = 2, [W11], [W11] - = 6, [W11] - = 4, [W11] - = 2, [W11 + W12], none}
Wyd	Y Data Space Prefetch Destination register for DSP instructions ∈ {W4W7}

	TABLE 28-2:	INSTRUCTION SET	OVERVIEW
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Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
1	ADD	ADD	Acc	Add Accumulators	1	1	OA,OB,SA,SB
		ADD	f	f = f + WREG	1	1	C,DC,N,OV,Z
		ADD	f,WREG	WREG = f + WREG	1	1	C,DC,N,OV,Z
		ADD	#lit10,Wn	Wd = lit10 + Wd	1	1	C,DC,N,OV,Z
		ADD	Wb,Ws,Wd	Wd = Wb + Ws	1	1	C,DC,N,OV,Z
		ADD	Wb,#lit5,Wd	Wd = Wb + lit5	1	1	C,DC,N,OV,Z
		ADD	Wso,#Slit4,Acc	16-bit Signed Add to Accumulator	1	1	OA,OB,SA,SB
2	ADDC	ADDC	f	f = f + WREG + (C)	1	1	C,DC,N,OV,Z
		ADDC	f,WREG	WREG = $f + WREG + (C)$	1	1	C,DC,N,OV,Z
		ADDC	#lit10,Wn	Wd = lit10 + Wd + (C)	1	1	C,DC,N,OV,Z
		ADDC	Wb,Ws,Wd	Wd = Wb + Ws + (C)	1	1	C,DC,N,OV,Z
		ADDC	Wb,#lit5,Wd	Wd = Wb + lit5 + (C)	1	1	C,DC,N,OV,Z
3	AND	AND	f	f = f .AND. WREG	1	1	N,Z
		AND	f,WREG	WREG = f .AND. WREG	1	1	N,Z
		AND	#lit10,Wn	Wd = lit10 .AND. Wd	1	1	N,Z
		AND	Wb,Ws,Wd	Wd = Wb .AND. Ws	1	1	N,Z
		AND	Wb,#lit5,Wd	Wd = Wb .AND. lit5	1	1	N,Z
4	ASR	ASR	f	f = Arithmetic Right Shift f	1	1	C,N,OV,Z
		ASR	f,WREG	WREG = Arithmetic Right Shift f	1	1	C,N,OV,Z
		ASR	Ws,Wd	Wd = Arithmetic Right Shift Ws	1	1	C,N,OV,Z
		ASR	Wb,Wns,Wnd	Wnd = Arithmetic Right Shift Wb by Wns	1	1	N,Z
		ASR	Wb,#lit5,Wnd	Wnd = Arithmetic Right Shift Wb by lit5	1	1	N,Z
5	BCLR	BCLR	f,#bit4	Bit Clear f	1	1	None
6	BOOTSWP	BCLR BOOTSWP	Ws,#bit4	Bit Clear Ws Swap the Active and Inactive Program	1	1	None None
	2001011	2001011		Flash Space		_	
7	BRA	BRA	C,Expr	Branch if Carry	1	1 (4)	None
		BRA	GE,Expr	Branch if Greater Than or Equal	1	1 (4)	None
		BRA	GEU,Expr	Branch if Unsigned Greater Than or Equal	1	1 (4)	None
		BRA	GT,Expr	Branch if Greater Than	1	1 (4)	None
		BRA	GTU,Expr	Branch if Unsigned Greater Than	1	1 (4)	None
		BRA	LE,Expr	Branch if Less Than or Equal	1	1 (4)	None
		BRA	LEU,Expr	Branch if Unsigned Less Than or Equal	1	1 (4)	None
		BRA	LT,Expr	Branch if Less Than	1	1 (4)	None
		BRA	LTU,Expr	Branch if Unsigned Less Than	1	1 (4)	None
		BRA	N,Expr	Branch if Negative	1	1 (4)	None
		BRA	NC,Expr	Branch if Not Carry	1	1 (4)	None
		BRA	NN, Expr	Branch if Not Negative	1	1 (4)	None
		BRA	NOV,Expr	Branch if Not Overflow	1	1 (4)	None
		BRA	NZ,Expr	Branch if Not Zero	1	1 (4)	None
		BRA	OA, Expr	Branch if Accumulator A Overflow	1	1 (4)	None
		BRA	OB, Expr	Branch if Accumulator B Overflow	1	1 (4)	None
		BRA	OV,Expr	Branch if Overflow	1	1 (4)	None
		BRA	SA,Expr	Branch if Accumulator A Saturated	1	1 (4)	None
		BRA	SB,Expr	Branch if Accumulator B Saturated	1	1 (4)	None
		BRA	Expr	Branch Unconditionally	1	4	None
		BRA	Z,Expr	Branch if Zero	1	1 (4)	None
		BRA	Wn	Computed Branch	1	4	None
8	BSET	BSET	f,#bit4	Bit Set f	1	1	None
		BSET	Ws,#bit4	Bit Set Ws	1	1	None

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
9	BSW	BSW.C	Ws,Wb	Write C bit to Ws <wb></wb>	1	1	None
		BSW.Z	Ws,Wb	Write Z bit to Ws <wb></wb>	1	1	None
10	BTG	BTG	f,#bit4	Bit Toggle f	1	1	None
		BTG	Ws,#bit4	Bit Toggle Ws	1	1	None
11	BTSC	BTSC	f,#bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None
		BTSC	Ws,#bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None
12	BTSS	BTSS	f,#bit4	Bit Test f, Skip if Set	1	1 (2 or 3)	None
		BTSS	Ws,#bit4	Bit Test Ws, Skip if Set	1	1 (2 or 3)	None
13	BTST	BTST	f,#bit4	Bit Test f	1	1	Z
		BTST.C	Ws,#bit4	Bit Test Ws to C	1	1	С
		BTST.Z	Ws,#bit4	Bit Test Ws to Z	1	1	Z
		BTST.C	Ws,Wb	Bit Test Ws <wb> to C</wb>	1	1	С
		BTST.Z	Ws,Wb	Bit Test Ws <wb> to Z</wb>	1	1	Z
14	BTSTS	BTSTS	f,#bit4	Bit Test then Set f	1	1	Z
		BTSTS.C	Ws,#bit4	Bit Test Ws to C, then Set	1	1	С
		BTSTS.Z	Ws,#bit4	Bit Test Ws to Z, then Set	1	1	Z
15	CALL	CALL	lit23	Call Subroutine	2	4	SFA
		CALL	Wn	Call Indirect Subroutine	1	4	SFA
		CALL.L	Wn	Call Indirect Subroutine (long address)	1	4	SFA
16	CLR	CLR	f	f = 0x0000	1	1	None
		CLR	WREG	WREG = 0x0000	1	1	None
		CLR	Ws	Ws = 0x0000	1	1	None
		CLR	Acc,Wx,Wxd,Wy,Wyd,AWB	Clear Accumulator	1	1	OA,OB,SA,SE
17	CLRWDT	CLRWDT		Clear Watchdog Timer	1	1	WDTO,Sleep
18	COM	COM	f	f = f	1	1	N,Z
		СОМ	f,WREG	WREG = f	1	1	N,Z
		СОМ	Ws,Wd	$Wd = \overline{Ws}$	1	1	N,Z
19	CP	CP	f	Compare f with WREG	1	1	C,DC,N,OV,Z
10	01	CP	Wb,#lit8	Compare Wb with lit8	1	1	C,DC,N,OV,Z
		CP	Wb,Ws	Compare Wb with Ws (Wb – Ws)	1	1	C,DC,N,OV,Z
20	CPO	CPO	f	Compare f with 0x0000	1	1	C,DC,N,OV,Z
	010	CPO	Ws	Compare Ws with 0x0000	1	1	C,DC,N,OV,Z
21	CPB	CPB	f	Compare f with WREG, with Borrow	1	1	C,DC,N,OV,Z
		CPB	Wb,#lit8	Compare Wb with lit8, with Borrow	1	1	C,DC,N,OV,Z
		CPB	Wb,Ws	Compare Wb with Ws, with Borrow $(Wb - Ws - \overline{C})$	1	1	C,DC,N,OV,Z
22	CPSEQ	CPSEQ	Wb,Wn	Compare Wb with Wn, Skip if =	1	1 (2 or 3)	None
	CPBEQ	CPBEQ	Wb,Wn,Expr	Compare Wb with Wn, Branch if =	1	1 (5)	None
23	CPSGT	CPSGT	Wb,Wn	Compare Wb with Wn, Skip if >	1	1 (2 or 3)	None
	CPBGT	CPBGT	Wb,Wn,Expr	Compare Wb with Wn, Branch if >	1	1 (5)	None
24	CPSLT	CPSLT	Wb,Wn	Compare Wb with Wn, Skip if <	1	1 (2 or 3)	None
	CPBLT	CPBLT	Wb,Wn,Expr	Compare Wb with Wn, Branch if <	1	1 (5)	None
25	CPSNE	CPSNE	Wb,Wn	Compare Wb with Wn, Skip if ≠	1	1 (2 or 3)	None
	CPBNE	CPBNE	Wb,Wn,Expr	Compare Wb with Wn, Branch if ≠	1	1 (5)	None

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
26	CTXTSWP	CTXTSWP	#lit3	Switch CPU Register Context to Context Defined by lit3	1	2	None
		CTXTSWP	Wn	Switch CPU Register Context to Context Defined by Wn	1	2	None
27	DAW	DAW	Wn	Wn = Decimal Adjust Wn	1	1	С
28	DEC	DEC	f	f = f - 1	1	1	C,DC,N,OV,Z
		DEC	f,WREG	WREG = $f - 1$	1	1	C,DC,N,OV,Z
		DEC	Ws,Wd	Wd = Ws - 1	1	1	C,DC,N,OV,Z
29	DEC2	DEC2	f	f = f - 2	1	1	C,DC,N,OV,Z
		DEC2	f,WREG	WREG = $f - 2$	1	1	C,DC,N,OV,Z
		DEC2	Ws,Wd	Wd = Ws - 2	1	1	C,DC,N,OV,Z
30	DISI	DISI	#lit14	Disable Interrupts for k Instruction Cycles	1	1	None
31	DIV	DIV.S	Wm,Wn	Signed 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.SD	Wm,Wn	Signed 32/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.U	Wm,Wn	Unsigned 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.UD	Wm,Wn	Unsigned 32/16-bit Integer Divide	1	18	N,Z,C,OV
32	DIVF	DIVF	Wm,Wn	Signed 16/16-bit Fractional Divide	1	18	N,Z,C,OV
33	DO	DO	#lit15,Expr	Do Code to PC + Expr, lit15 + 1 Times	2	2	None
		DO	Wn,Expr	Do Code to PC + Expr, (Wn) + 1 Times	2	2	None
34	ED	ED	Wm*Wm, Acc, Wx, Wy, Wxd	Euclidean Distance (no accumulate)	1	1	OA,OB,OAB, SA,SB,SAB
35	EDAC	EDAC	Wm*Wm, Acc, Wx, Wy, Wxd	Euclidean Distance	1	1	OA,OB,OAB, SA,SB,SAB
36	EXCH	EXCH	Wns,Wnd	Swap Wns with Wnd	1	1	None
37	FBCL	FBCL	Ws,Wnd	Find Bit Change from Left (MSb) Side	1	1	С
38	FF1L	FF1L	Ws,Wnd	Find First One from Left (MSb) Side	1	1	С
39	FF1R	FF1R	Ws,Wnd	Find First One from Right (LSb) Side	1	1	С
40	GOTO	GOTO	Expr	Go to Address	2	4	None
		GOTO	Wn	Go to Indirect	1	4	None
		GOTO.L	Wn	Go to Indirect (long address)	1	4	None
41	INC	INC	f	f = f + 1	1	1	C,DC,N,OV,Z
		INC	f,WREG	WREG = f + 1	1	1	C,DC,N,OV,Z
		INC	Ws,Wd	Wd = Ws + 1	1	1	C,DC,N,OV,Z
42	INC2	INC2	f	f = f + 2	1	1	C,DC,N,OV,Z
		INC2	f,WREG	WREG = f + 2	1	1	C,DC,N,OV,Z
		INC2	Ws,Wd	Wd = Ws + 2	1	1	C,DC,N,OV,Z
13	IOR	IOR	f	f = f .IOR. WREG	1	1	N,Z
		IOR	f,WREG	WREG = f .IOR. WREG	1	1	N,Z
		IOR	#lit10,Wn	Wd = lit10 .IOR. Wd	1	1	N,Z
		IOR	Wb,Ws,Wd	Wd = Wb .IOR. Ws	1	1	N,Z
		IOR	Wb,#lit5,Wd	Wd = Wb .IOR. lit5	1	1	N,Z
44	LAC	LAC	Wso,#Slit4,Acc	Load Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
45	LNK	LNK	#lit14	Link Frame Pointer	1	1	SFA
46	LSR	LSR	f	f = Logical Right Shift f	1	1	C,N,OV,Z
		LSR	f,WREG	WREG = Logical Right Shift f	1	1	C,N,OV,Z
		LSR	Ws,Wd	Wd = Logical Right Shift Ws	1	1	C,N,OV,Z
		LSR	Wb,Wns,Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N,Z
		LSR	Wb,#lit5,Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N,Z
47	MAC	MAC	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd,AWB	Multiply and Accumulate	1	1	OA,OB,OAB, SA,SB,SAB
		MAC	Wm*Wm,Acc,Wx,Wxd,Wy,Wyd	Square and Accumulate	1	1	OA,OB,OAB, SA,SB,SAB

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
48	MOV	MOV	f,Wn	Move f to Wn	1	1	None
		MOV	f	Move f to f	1	1	None
		MOV	f,WREG	Move f to WREG	1	1	None
		MOV	#lit16,Wn	Move 16-bit Literal to Wn	1	1	None
		MOV.b	#lit8,Wn	Move 8-bit Literal to Wn	1	1	None
		MOV	Wn,f	Move Wn to f	1	1	None
		MOV	Wso,Wdo	Move Ws to Wd	1	1	None
		MOV	WREG, f	Move WREG to f	1	1	None
		MOV.D	Wns,Wd	Move Double from W(ns):W(ns + 1) to Wd	1	2	None
		MOV.D	Ws,Wnd	Move Double from Ws to W(nd + 1):W(nd)	1	2	None
49	MOVPAG	MOVPAG	#lit10,DSRPAG	Move 10-bit Literal to DSRPAG	1	1	None
-10		MOVPAG	#lit8,TBLPAG	Move 8-bit Literal to TBLPAG	1	1	None
		MOVPAGW	Ws, DSRPAG	Move Ws<9:0> to DSRPAG	1	1	None
		MOVPAGW	Ws, TBLPAG	Move Ws<7:0> to TBLPAG	1	1	None
50	MOVSAC	MOVSAC	Acc,Wx,Wxd,Wy,Wyd,AWB	Prefetch and Store Accumulator	1	1	None
51	MPY	MPY	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd	Multiply Wm by Wn to Accumulator	1	1	OA,OB,OAB SA,SB,SAB
		MPY	Wm*Wm,Acc,Wx,Wxd,Wy,Wyd	Square Wm to Accumulator	1	1	OA,OB,OAB SA,SB,SAB
52	MPY.N	MPY.N	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd	-(Multiply Wm by Wn) to Accumulator	1	1	None
53	MSC	MSC	Wm*Wm, Acc, Wx, Wxd, Wy, Wyd, AWB	Multiply and Subtract from Accumulator	1	1	OA,OB,OAB SA,SB,SAB
54	MUL	MUL.SS	Wb,Ws,Wnd	{Wnd + 1, Wnd} = Signed(Wb) * Signed(Ws)	1	1	None
		MUL.SS	Wb,Ws,Acc	Accumulator = Signed(Wb) * Signed(Ws)	1	1	None
		MUL.SU	Wb,Ws,Wnd	{Wnd + 1, Wnd} = Signed(Wb) * Unsigned(Ws)	1	1	None
		MUL.SU	Wb,Ws,Acc	Accumulator = Signed(Wb) * Unsigned(Ws)	1	1	None
		MUL.SU	Wb,#lit5,Acc	Accumulator = Signed(Wb) * Unsigned(lit5)	1	1	None
		MUL.US	Wb,Ws,Wnd	{Wnd + 1, Wnd} = Unsigned(Wb) * Signed(Ws)	1	1	None
		MUL.US	Wb,Ws,Acc	Accumulator = Unsigned(Wb) * Signed(Ws)	1	1	None
		MUL.UU	Wb,Ws,Wnd	{Wnd + 1, Wnd} = Unsigned(Wb) * Unsigned(Ws)	1	1	None
		MUL.UU	Wb,#lit5,Acc	Accumulator = Unsigned(Wb) * Unsigned(lit5)	1	1	None
		MUL.UU	Wb,Ws,Acc	Accumulator = Unsigned(Wb) * Unsigned(Ws)	1	1	None
		MULW.SS	Wb,Ws,Wnd	Wnd = Signed(Wb) * Signed(Ws)	1	1	None
		MULW.SU	Wb,Ws,Wnd	Wnd = Signed(Wb) * Unsigned(Ws)	1	1	None
		MULW.US	Wb,Ws,Wnd	Wnd = Unsigned(Wb) * Signed(Ws)	1	1	None
		MULW.UU	Wb,Ws,Wnd	Wnd = Unsigned(Wb) * Unsigned(Ws)	1	1	None
		MUL.SU	Wb,#lit5,Wnd	{Wnd + 1, Wnd} = Signed(Wb) * Unsigned(lit5)	1	1	None
		MUL.SU	Wb,#lit5,Wnd	Wnd = Signed(Wb) * Unsigned(lit5)	1	1	None
		MUL.UU	Wb,#lit5,Wnd	{Wnd + 1, Wnd} = Unsigned(Wb) * Unsigned(lit5)	1	1	None
		MUL.UU	Wb,#lit5,Wnd	Wnd = Unsigned(Wb) * Unsigned(lit5)	1	1	None
		MUL	f	W3:W2 = f * WREG	1	1	None

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
55	NEG	NEG	Acc	Negate Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
		NEG	f	$f = \overline{f} + 1$	1	1	C,DC,N,OV,Z
		NEG	f,WREG	WREG = \overline{f} + 1	1	1	C,DC,N,OV,Z
		NEG	Ws,Wd	$Wd = \overline{Ws} + 1$	1	1	C,DC,N,OV,Z
56	NOP	NOP		No Operation	1	1	None
		NOPR		No Operation	1	1	None
57	POP	POP	f	Pop f from Top-of-Stack (TOS)	1	1	None
		POP	Wdo	Pop from Top-of-Stack (TOS) to Wdo	1	1	None
		POP.D	Wnd	Pop from Top-of-Stack (TOS) to W(nd):W(nd + 1)	1	2	None
		POP.S		Pop Shadow Registers	1	1	All
58	PUSH	PUSH	f	Push f to Top-of-Stack (TOS)	1	1	None
58		PUSH	Wso	Push Wso to Top-of-Stack (TOS)	1	1	None
		PUSH.D	Wns	Push W(ns):W(ns + 1) to Top-of-Stack (TOS)	1	2	None
		PUSH.S		Push Shadow Registers	1	1	None
59	PWRSAV	PWRSAV	#lit1	Go into Sleep or Idle mode	1	1	WDTO,Sleep
60	RCALL	RCALL	Expr	Relative Call	1	4	SFA
		RCALL	Wn	Computed Call	1	4	SFA
61	REPEAT	REPEAT	#lit15	Repeat Next Instruction lit15 + 1 Times	1	1	None
		REPEAT	Wn	Repeat Next Instruction (Wn) + 1 Times	1	1	None
62	RESET	RESET		Software Device Reset	1	1	None
63	RETFIE	RETFIE		Return from Interrupt	1	6 (5)	SFA
64	RETLW	RETLW	#lit10,Wn	Return with Literal in Wn	1	6 (5)	SFA
65	RETURN	RETURN		Return from Subroutine	1	6 (5)	SFA
66	RLC	RLC	f	f = Rotate Left through Carry f	1	1	C,N,Z
		RLC	f,WREG	WREG = Rotate Left through Carry f	1	1	C,N,Z
		RLC	Ws,Wd	Wd = Rotate Left through Carry Ws	1	1	C,N,Z
67	RLNC	RLNC	f	f = Rotate Left (No Carry) f	1	1	N,Z
		RLNC	f,WREG	WREG = Rotate Left (No Carry) f	1	1	N,Z
		RLNC	Ws,Wd	Wd = Rotate Left (No Carry) Ws	1	1	N,Z
68	RRC	RRC	f	f = Rotate Right through Carry f	1	1	C,N,Z
		RRC	f,WREG	WREG = Rotate Right through Carry f	1	1	C,N,Z
		RRC	Ws,Wd	Wd = Rotate Right through Carry Ws	1	1	C,N,Z
69	RRNC	RRNC	f	f = Rotate Right (No Carry) f	1	1	N,Z
		RRNC	f,WREG	WREG = Rotate Right (No Carry) f	1	1	N,Z
		RRNC	Ws,Wd	Wd = Rotate Right (No Carry) Ws	1	1	N,Z
70	SAC	SAC	Acc,#Slit4,Wdo	Store Accumulator	1	1	None
		SAC.R	Acc,#Slit4,Wdo	Store Rounded Accumulator	1	1	None
71	SE	SE	Ws,Wnd	Wnd = Sign-Extended Ws	1	1	C,N,Z
72	SETM	SETM	f	f = 0xFFFF	1	1	None
		SETM	WREG	WREG = 0xFFFF	1	1	None
70		SETM	Ws	Ws = 0xFFF	1	1	None
73	SFTAC	SFTAC	Acc,Wn	Arithmetic Shift Accumulator by (Wn)	1	1	OA,OB,OAB, SA,SB,SAB
		SFTAC	Acc,#Slit6	Arithmetic Shift Accumulator by Slit6	1	1	OA,OB,OAB, SA,SB,SAB

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽¹⁾	Status Flags Affected
74	SL	SL	f	f = Left Shift f	1	1	C,N,OV,Z
		SL	f,WREG	WREG = Left Shift f	1	1	C,N,OV,Z
		SL	Ws,Wd	Wd = Left Shift Ws	1	1	C,N,OV,Z
		SL	Wb,Wns,Wnd	Wnd = Left Shift Wb by Wns	1	1	N,Z
75		SL	Wb,#lit5,Wnd	Wnd = Left Shift Wb by lit5	1	1	N,Z
75	SUB	SUB	Acc	Subtract Accumulators	1	1	OA,OB,OAB, SA,SB,SAB
		SUB	f	f = f – WREG	1	1	C,DC,N,OV,Z
		SUB	f,WREG	WREG = f – WREG	1	1	C,DC,N,OV,Z
		SUB	#lit10,Wn	Wn = Wn - lit10	1	1	C,DC,N,OV,Z
		SUB	Wb,Ws,Wd	Wd = Wb – Ws	1	1	C,DC,N,OV,Z
		SUB	Wb,#lit5,Wd	Wd = Wb - lit5	1	1	C,DC,N,OV,Z
76	SUBB	SUBB	f	$f = f - WREG - (\overline{C})$	1	1	C,DC,N,OV,Z
		SUBB	f,WREG	WREG = $f - WREG - (\overline{C})$	1	1	C,DC,N,OV,Z
		SUBB	#lit10,Wn	$Wn = Wn - lit10 - (\overline{C})$	1	1	C,DC,N,OV,Z
		SUBB	Wb,Ws,Wd	$Wd = Wb - Ws - (\overline{C})$	1	1	C,DC,N,OV,Z
		SUBB	Wb,#lit5,Wd	$Wd = Wb - lit5 - (\overline{C})$	1	1	C,DC,N,OV,Z
77	SUBR	SUBR	f	f = WREG – f	1	1	C,DC,N,OV,Z
		SUBR	f,WREG	WREG = WREG – f	1	1	C,DC,N,OV,Z
		SUBR	Wb,Ws,Wd	Wd = Ws – Wb	1	1	C,DC,N,OV,Z
		SUBR	Wb,#lit5,Wd	Wd = lit5 – Wb	1	1	C,DC,N,OV,Z
78	SUBBR	SUBBR	f	$f = WREG - f - (\overline{C})$	1	1	C,DC,N,OV,Z
		SUBBR	f,WREG	WREG = WREG – f – (\overline{C})	1	1	C,DC,N,OV,Z
		SUBBR	Wb,Ws,Wd	$Wd = Ws - Wb - (\overline{C})$	1	1	C,DC,N,OV,Z
		SUBBR	Wb,#lit5,Wd	$Wd = lit5 - Wb - (\overline{C})$	1	1	C,DC,N,OV,Z
79	SWAP	SWAP.b	Wn	Wn = Nibble Swap Wn	1	1	None
		SWAP	Wn	Wn = Byte Swap Wn	1	1	None
80	TBLRDH	TBLRDH	Ws,Wd	Read Prog<23:16> to Wd<7:0>	1	5	None
81	TBLRDL	TBLRDL	Ws,Wd	Read Prog<15:0> to Wd	1	5	None
82	TBLWTH	TBLWTH	Ws,Wd	Write Ws<7:0> to Prog<23:16>	1	2	None
83	TBLWTL	TBLWTL	Ws,Wd	Write Ws to Prog<15:0>	1	2	None
84	ULNK	ULNK		Unlink Frame Pointer	1	1	SFA
85	XOR	XOR	f	f = f .XOR. WREG	1	1	N,Z
		XOR	f,WREG	WREG = f .XOR. WREG	1	1	N,Z
		XOR	#lit10,Wn	Wd = lit10 .XOR. Wd	1	1	N,Z
		XOR	Wb,Ws,Wd	Wd = Wb .XOR. Ws	1	1	N,Z
		XOR	Wb,#lit5,Wd	Wd = Wb .XOR. lit5	1	1	N,Z
86	ZE	ZE	Ws,Wnd	Wnd = Zero-Extend Ws	1	1	C,Z,N

NOTES:

29.0 DEVELOPMENT SUPPORT

The PIC[®] microcontrollers (MCU) and dsPIC[®] digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
- MPLAB[®] X IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB XC Compiler
 - MPASM[™] Assembler
 - MPLINK[™] Object Linker/ MPLIB[™] Object Librarian
 - MPLAB Assembler/Linker/Librarian for Various Device Families
- · Simulators
 - MPLAB X SIM Software Simulator
- Emulators
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
 - MPLAB ICD 3
 - PICkit™ 3
- Device Programmers
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits and Starter Kits
- Third-party development tools

29.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows[®], Linux and Mac $OS^{®}$ X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- · Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- · Call graph window
- Project-Based Workspaces:
- Multiple projects
- Multiple tools
- · Multiple configurations
- · Simultaneous debugging sessions

File History and Bug Tracking:

- · Local file history feature
- Built-in support for Bugzilla issue tracker

29.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16 and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- · Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- · Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

29.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel[®] standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline
 assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

29.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

29.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- · Support for the entire device instruction set
- · Support for fixed-point and floating-point data
- Command-line interface
- · Rich directive set
- Flexible macro language
- · MPLAB X IDE compatibility

29.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

29.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

29.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a highspeed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

29.9 PICkit 3 In-Circuit Debugger/ Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a fullspeed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming[™] (ICSP[™]).

29.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

29.11 Demonstration/Development Boards, Evaluation Kits and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM[™] and dsPICDEM[™] demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ[®] security ICs, CAN, IrDA[®], PowerSmart battery management, SEEVAL[®] evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page (www.microchip.com) for the complete list of demonstration, development and evaluation kits.

29.12 Third-Party Development Tools

Microchip also offers a great collection of tools from third-party vendors. These tools are carefully selected to offer good value and unique functionality.

- Device Programmers and Gang Programmers from companies, such as SoftLog and CCS
- Software Tools from companies, such as Gimpel and Trace Systems
- Protocol Analyzers from companies, such as Saleae and Total Phase
- Demonstration Boards from companies, such as MikroElektronika, Digilent[®] and Olimex
- Embedded Ethernet Solutions from companies, such as EZ Web Lynx, WIZnet and IPLogika[®]

30.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of the dsPIC33EPXXXGS70X/80X family electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the dsPIC33EPXXXGS70X/80X family are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these, or any other conditions above the parameters indicated in the operation listings of this specification, is not implied.

Absolute Maximum Ratings⁽¹⁾

Ambient temperature under bias	40°C to +125°C
Storage temperature	65°C to +150°C
Voltage on VDD with respect to Vss	-0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to Vss ⁽³⁾	0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to Vss when $VDD \ge 3.0V^{(3)}$	-0.3V to +5.5V
Voltage on any 5V tolerant pin with respect to Vss when VDD < 3.0V ⁽³⁾	-0.3V to +3.6V
Maximum current out of Vss pin	
Maximum current into VDD pin ⁽²⁾	
Maximum current sunk/sourced by any 4x I/O pin	
Maximum current sunk/sourced by any 8x I/O pin	
Maximum current sunk by all ports ⁽²⁾	200 mA

- **Note 1:** Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those, or any other conditions above those indicated in the operation listings of this specification, is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.
 - 2: Maximum allowable current is a function of device maximum power dissipation (see Table 30-2).
 - 3: See the "Pin Diagrams" section for the 5V tolerant pins.

30.1 DC Characteristics

TABLE 30-1: OPERATING MIPS vs. VOLTAGE

Characteristic	VDD Range	Temperature Range	Maximum MIPS			
Glaracteristic	(in Volts)	(in °C)	dsPIC33EPXXXGS70X/80X Family			
			70			
—	3.0V to 3.6V ⁽¹⁾	-40°C to +125°C	60			

Note 1: Device is functional at VBORMIN < VDD < VDDMIN. Analog modules (ADC, PGAs and comparators) may have degraded performance. Device functionality is tested but not characterized. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

TABLE 30-2: THERMAL OPERATING CONDITIONS

Rating	Symbol	Min.	Тур.	Max.	Unit
Industrial Temperature Devices					
Operating Junction Temperature Range	TJ	-40	—	+125	°C
Operating Ambient Temperature Range	TA	-40	—	+85	°C
Extended Temperature Devices					
Operating Junction Temperature Range	TJ	-40	—	+140	°C
Operating Ambient Temperature Range	TA	-40	—	+125	°C
Power Dissipation: Internal Chip Power Dissipation: $PINT = VDD x (IDD - \Sigma IOH)$ I/O Pin Power Dissipation:	PD	I	Pint + Pi/c)	W
$I/O = \Sigma (\{VDD - VOH\} \times IOH) + \Sigma (VOL \times IOL)$					
Maximum Allowed Power Dissipation	PDMAX	(TJ — TA)/θJ	A	W

TABLE 30-3: THERMAL PACKAGING CHARACTERISTICS

Characteristic	Symbol	Тур.	Max.	Unit	Notes
Package Thermal Resistance, 80-Pin TQFP 12x12x1 mm	θJA	53.0	_	°C/W	1
Package Thermal Resistance, 64-Pin TQFP 10x10x1 mm	θJA	49.0	_	°C/W	1
Package Thermal Resistance, 48-Pin TQFP 7x7x1 mm	θJA	63.0	—	°C/W	1
Package Thermal Resistance, 44-Pin QFN 8x8 mm	θја	29.0		°C/W	1
Package Thermal Resistance, 44-Pin TQFP 10x10x1 mm	θја	50.0		°C/W	1
Package Thermal Resistance, 28-Pin QFN-S 6x6x0.9 mm	θја	30.0		°C/W	1
Package Thermal Resistance, 28-Pin UQFN 6x6x0.55 mm	θја	26.0		°C/W	1
Package Thermal Resistance, 28-Pin SOIC 7.50 mm	θJA	70.0	_	°C/W	1

Note 1: Junction to ambient thermal resistance, Theta-JA (θ JA) numbers are achieved by package simulations.

TABLE 30-4 :	DC TEMPERATURE AND VOLTAGE SPECIFICATIONS

DC CHARACTERISTICS			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions	
Operati	ng Voltag	e						
DC10	Vdd	Supply Voltage	3.0	_	3.6	V		
DC12	Vdr	RAM Retention Voltage ⁽²⁾	_	_	1.95	V	+25°C, +85°C, +125°C	
				_	2.0	V	-40°C	
DC16	VPOR	VDD Start Voltage to Ensure Internal Power-on Reset Signal	—	_	Vss	V		
DC17	SVDD	VDD Rise Rate to Ensure Internal Power-on Reset Signal	1.0	_	—	V/ms	0V-3V in 3 ms	

Note 1: Device is functional at VBORMIN < VDD < VDDMIN. Analog modules (ADC, PGAs and comparators) may have degraded performance. Device functionality is tested but not characterized. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

2: This is the limit to which VDD may be lowered and the RAM contents will always be retained.

TABLE 30-5: FILTER CAPACITOR (CEFC) SPECIFICATIONS

	Standard Operating Conditions (unless otherwise stated):Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for Extended								
Param No.	Symbol Characteristics Min Typ Max Units Comments								
	CEFC External Filter Capacitor 4.7 — 10 μF Capacitor must have a low series resistance (<1 Ohm)								

Note 1: Typical VCAP Voltage = 1.8 volts when VDD \ge VDDMIN.

DC CHARACTE	ERISTICS		(unless oth		s: 3.0V to 3.6V ≤ TA ≤ +85°C for Indu ≤ TA ≤ +125°C for Ex			
Parameter No.	Тур.	Max.	Units	s Conditions				
Operating Curi	rent (IDD) ⁽¹⁾		·					
DC20d	8	13	mA	-40°C				
DC20a	8	13	mA	+25°C	- 3.3V	10 MIPS		
DC20b	8	13	mA	+85°C	- 3.3V	10 101195		
DC20c	8	13	mA	+125°C				
DC22d	12	20	mA	-40°C				
DC22a	12	20	mA	+25°C	2.21/	20 MIPS		
DC22b	12	20	mA	+85°C	- 3.3V	20 101195		
DC22c	12	20	mA	+125°C				
DC24d	19	30	mA	-40°C		40 MIPS		
DC24a	19	30	mA	+25°C	- 3.3V			
DC24b	19	30	mA	+85°C	5.5V			
DC24c	19	30	mA	+125°C				
DC25d	27	42	mA	-40°C				
DC25a	27	42	mA	+25°C	- 3.3V	60 MIPS		
DC25b	27	42	mA	+85°C	5.5V	00 MIF 3		
DC25c	27	42	mA	+125°C				
DC26d	30	46	mA	-40°C				
DC26a	30	46	mA	+25°C	3.3V	70 MIPS		
DC26b	30	46	mA	+85°C				
DC27d	57	75	mA	-40°C				
DC27a	57	75	mA	+25°C	3.3V	70 MIPS (Note 2)		
DC27b	57	75	mA	+85°C				

TABLE 30-6: DC CHARACTERISTICS: OPERATING CURRENT (IDD)

Note 1: IDD is primarily a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows:

• Oscillator is configured in EC mode with PLL, OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)

- · CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to Vss
- MCLR = VDD, WDT and FSCM are disabled
- · CPU, SRAM, program memory and data memory are operational
- No peripheral modules are operating or being clocked (all defined PMDx bits are set)
- CPU is executing while (1) statement
- JTAG is disabled
- **2:** For this specification, the following test conditions apply:
 - · APLL clock is enabled
 - All 8 PWMs enabled and operating at maximum speed (PTCON2<2:0> = 000), PTPER = 1000h, 50% duty cycle
 - All other peripherals are disabled (corresponding PMDx bits are set)

DC CHARACTERISTICS			(unless oth	$\begin{array}{llllllllllllllllllllllllllllllllllll$						
Parameter No.	Тур.	Max.	Units Conditions							
Idle Current (III	DLE) ⁽¹⁾		•							
DC40d	2	4	mA	-40°C						
DC40a	2	4	mA	+25°C	- 3.3V	10 MIPS				
DC40b	2	4	mA	+85°C	3.3V	10 101195				
DC40c	2	4	mA	+125°C						
DC42d	3	6	mA	-40°C						
DC42a	3	6	mA	+25°C	- 3.3V	20 MIPS				
DC42b	4	7	mA	+85°C	3.3V	20 MIFS				
DC42c	4	7	mA	+125°C						
DC44d	6	12	mA	-40°C						
DC44a	6	12	mA	+25°C	- 3.3V	40 MIPS				
DC44b	6	12	mA	+85°C	3.3V	40 WIPS				
DC44c	6	12	mA	+125°C						
DC45d	9	17	mA	-40°C						
DC45a	9	17	mA	+25°C	2.21/					
DC45b	9	17	mA	+85°C	- 3.3V	60 MIPS				
DC45c	9	17	mA	+125°C						
DC46d	10	20	mA	-40°C						
DC46a	10	20	mA	+25°C	3.3V	70 MIPS				
DC46b	10	20	mA	+85°C						

TABLE 30-7: DC CHARACTERISTICS: IDLE CURRENT (lidle)

Note 1: Base Idle current (IIDLE) is measured as follows:

• CPU core is off, oscillator is configured in EC mode and external clock is active; OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)

- CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to Vss
- $\overline{\text{MCLR}}$ = VDD, WDT and FSCM are disabled
- No peripheral modules are operating or being clocked (all defined PMDx bits are set)
- The NVMSIDL bit (NVMCON<12>) = 1 (i.e., Flash regulator is set to standby while the device is in Idle mode)
- The VREGSF bit (RCON<11>) = 0 (i.e., Flash regulator is set to standby while the device is in Sleep mode)
- JTAG is disabled

TABLE 30-8: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

DC CHARACT	ERISTICS		$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$				
Parameter No.	Тур.	Max.	Units Conditions				
Power-Down	Current (IPD) ⁽¹⁾						
DC60d	15	110	μA	-40°C			
DC60a	20	150	μA	+25°C	3.3V		
DC60b	150	500	μΑ				
DC60c	500	1200	μΑ				

Note 1: IPD (Sleep) current is measured as follows:

• CPU core is off, oscillator is configured in EC mode and external clock is active; OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)

- · CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to Vss
- MCLR = VDD, WDT and FSCM are disabled
- All peripheral modules are disabled (PMDx bits are all set)
- The VREGS bit (RCON<8>) = 0 (i.e., core regulator is set to standby while the device is in Sleep mode)
- The VREGSF bit (RCON<11>) = 0 (i.e., Flash regulator is set to standby while the device is in Sleep mode)
- JTAG is disabled

TABLE 30-9: DC CHARACTERISTICS: WATCHDOG TIMER DELTA CURRENT $(\triangle IwDT)^{(1)}$

DC CHARACTER	RISTICS		(unless otherv	perature $-40^{\circ}C \le TA \le +8$				
Parameter No.	Тур.	Max.	Units	Conditions				
DC61d	1	10	μΑ	-40°C				
DC61a	1	10	μA	+25°C				
DC61b	2	17	μA	+85°C 3.3V				
DC61c	2	20	μA +125°C					

Note 1: The $\triangle I W D T$ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current. All parameters are characterized but not tested during manufacturing.

DC CHARACTER	ISTICS	(unless ot	$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Parameter No.	Тур.	Doze Ratio	Units		Con	ditions		
Doze Current (IDC	DZE) ⁽¹⁾							
DC73a ⁽²⁾	20	40	1:2	mA	-40°C	2.21/	Fosc = 140 MHz	
DC73g	10	22	1:128	mA	-40 C	3.3V		
DC70a ⁽²⁾	20	40	1:2	mA	+25°C	3.3V	Fosc = 140 MHz	
DC70g	10	22	1:128	mA	+25 C	3.3V		
DC71a ⁽²⁾	20	40	1:2	mA	195%	2 21/	Food = 140 MHz	
DC71g	10	22	1:128	mA	+85°C	3.3V	Fosc = 140 MHz	
DC72a ⁽²⁾	20	40	1:2	mA	112500	2 2)/	Food = 120 MHz	
DC72g	10	22	1:128	mA	+125°C	3.3V	Fosc = 120 MHz	

TABLE 30-10: DC CHARACTERISTICS: DOZE CURRENT (IDOZE)

Note 1: IDOZE is primarily a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDOZE measurements are as follows:

• Oscillator is configured in EC mode and external clock is active, OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)

- · CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to Vss
- MCLR = VDD, WDT and FSCM are disabled
- CPU, SRAM, program memory and data memory are operational
- No peripheral modules are operating or being clocked (all defined PMDx bits are set)
- CPU is executing while (1) statement
- · JTAG is disabled
- 2: These parameter are characterized but not tested in manufacturing.

TABLE 30-11: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS

DC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Conditions	
	VIL	Input Low Voltage						
DI10		Any I/O Pin and MCLR	Vss	_	0.2 Vdd	V		
DI18		I/O Pins with SDAx, SCLx	Vss	—	0.3 Vdd	V	SMBus disabled	
DI19		I/O Pins with SDAx, SCLx	Vss	—	0.8	V	SMBus enabled	
	Vih	Input High Voltage						
DI20		I/O Pins Not 5V Tolerant ⁽⁴⁾	0.8 Vdd	—	Vdd	V		
		I/O Pins 5V Tolerant and MCLR ⁽⁴⁾	0.8 Vdd	_	5.5	V		
		5V Tolerant I/O Pins with SDAx, SCLx ⁽⁴⁾	0.8 VDD	—	5.5	V	SMBus disabled	
		5V Tolerant I/O Pins with SDAx, SCLx ⁽⁴⁾	2.1	—	5.5	V	SMBus enabled	
		I/O Pins with SDAx, SCLx Not 5V Tolerant ⁽⁴⁾	0.8 VDD	—	Vdd	V	SMBus disabled	
		I/O Pins with SDAx, SCLx Not 5V Tolerant ⁽⁴⁾	2.1	—	Vdd	V	SMBus enabled	
DI30	ICNPU	Input Change Notification Pull-up Current	100	230	550	μA	VDD = 3.3V, VPIN = VSS	
DI31	ICNPD	Input Change Notification Pull-Down Current ⁽⁵⁾	100	230	400	μΑ	VDD = 3.3V, VPIN = VDD	

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.

- 3: Negative current is defined as current sourced by the pin.
- 4: See the "Pin Diagrams" section for the 5V tolerant I/O pins.
- 5: VIL Source < (Vss 0.3). Characterized but not tested.
- **6:** VIH Source > (VDD + 0.3) for pins that are not 5V tolerant only.
- 7: Digital 5V tolerant pins do not have internal high-side diodes to VDD and cannot tolerate any "positive" input injection current.
- 8: | Injection Currents | > 0 can affect the ADC results by approximately 4-6 counts.
- **9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical "absolute instantaneous" sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

DC СН/	DC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param No.	Symbol	Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Conditions			
	lil	Input Leakage Current ^(2,3)								
DI50		I/O Pins 5V Tolerant ⁽⁴⁾	-1	—	+1	μA	$\label{eq:VSS} \begin{split} VSS &\leq V PIN \leq V DD, \\ \text{pin at high-impedance} \end{split}$			
DI51		I/O Pins Not 5V Tolerant ⁽⁴⁾	-1	—	+1	μΑ	$\label{eq:VSS} \begin{array}{l} VSS \leq VPIN \leq VDD, \\ pin \text{ at high-impedance}, \\ -40^\circC \leq TA \leq +85^\circC \end{array}$			
DI51a		I/O Pins Not 5V Tolerant ⁽⁴⁾	-1	_	+1	μA	Analog pins shared with external reference pins, $-40^{\circ}C \le TA \le +85^{\circ}C$			
DI51b		I/O Pins Not 5V Tolerant ⁽⁴⁾	-1	_	+1	μA	$\label{eq:VSS} \begin{array}{l} VSS \leq VPIN \leq VDD, \\ pin \ at \ high-impedance, \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \end{array}$			
DI51c		I/O Pins Not 5V Tolerant ⁽⁴⁾	-1	_	+1	μA	Analog pins shared with external reference pins, $-40^{\circ}C \le TA \le +125^{\circ}C$			
DI55		MCLR	-5	—	+5	μA	$Vss \leq V \text{PIN} \leq V \text{DD}$			
DI56		OSC1	-5	—	+5	μΑ	$\label{eq:VSS} \begin{array}{l} VSS \leq VPIN \leq VDD, \\ XT \text{ and } HS \text{ modes} \end{array}$			

TABLE 30-11: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.

- 3: Negative current is defined as current sourced by the pin.
- 4: See the "Pin Diagrams" section for the 5V tolerant I/O pins.

5: VIL Source < (Vss – 0.3). Characterized but not tested.

6: VIH Source > (VDD + 0.3) for pins that are not 5V tolerant only.

7: Digital 5V tolerant pins do not have internal high-side diodes to VDD and cannot tolerate any "positive" input injection current.

8: | Injection Currents | > 0 can affect the ADC results by approximately 4-6 counts.

9: Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical "absolute instantaneous" sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

TABLE 30-11: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic	Min. Typ. ⁽¹⁾ Max. Units Conditions					
DI60a	licl	Input Low Injection Current	0	_	-5 ^(5,8)	mA	All pins except VDD, VSS, AVDD, AVSS, MCLR, VCAP and RB7	
DI60b	Іісн	Input High Injection Current	0	_	+5 ^(6,7,8)	mA	All pins except VDD, VSS, AVDD, AVSS, MCLR, VCAP, RB7 and all 5V tolerant pins ⁽⁷⁾	
DI60c	∑IICT	Total Input Injection Current (sum of all I/O and control pins)	-20 ⁽⁹⁾ — +20 ⁽⁹⁾ mA Absolute instantal sum of all ± input currents from all I. (IICL + IICH)					

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

- 2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- **3:** Negative current is defined as current sourced by the pin.
- 4: See the "Pin Diagrams" section for the 5V tolerant I/O pins.
- **5:** VIL Source < (Vss 0.3). Characterized but not tested.
- **6:** VIH Source > (VDD + 0.3) for pins that are not 5V tolerant only.
- 7: Digital 5V tolerant pins do not have internal high-side diodes to VDD and cannot tolerate any "positive" input injection current.
- 8: | Injection Currents | > 0 can affect the ADC results by approximately 4-6 counts.
- **9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical "absolute instantaneous" sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

DC CHARACTERISTICS			(unles	$\begin{array}{llllllllllllllllllllllllllllllllllll$						
Param.	Symbol	Characteristic	Min. Typ. Max. Units Conditions							
DO10 Vol		Output Low Voltage 4x Sink Driver Pins ⁽²⁾	-		0.4	V	$V_{DD} = 3.3V$, $I_{OL} \le 6 \text{ mA}, -40^{\circ}\text{C} \le \text{Ta} \le +85^{\circ}\text{C},$ $I_{OL} \le 5 \text{ mA}, +85^{\circ}\text{C} < \text{Ta} \le +125^{\circ}\text{C}$			
		Output Low Voltage 8x Sink Driver Pins ⁽³⁾	_	—	0.4	V	$V_{DD} = 3.3V$, $I_{OL} \le 12 \text{ mA}$, $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$, $I_{OL} \le 8 \text{ mA}$, $+85^{\circ}\text{C} < \text{TA} \le +125^{\circ}\text{C}$			
DO20	Vон	Output High Voltage 4x Source Driver Pins ⁽²⁾	2.4	_	_	V	IOH ≥ -10 mA, VDD = 3.3V			
		Output High Voltage 8x Source Driver Pins ⁽³⁾	2.4	_	_	V	IOH ≥ -15 mA, VDD = 3.3V			
DO20A	Von1	Output High Voltage	1.5 ⁽¹⁾	_	_	V	ІОн ≥ -14 mA, VDD = 3.3V			
		4x Source Driver Pins ⁽²⁾	2.0 ⁽¹⁾	_	_		ІОН ≥ -12 mA, VDD = 3.3V			
			3.0 ⁽¹⁾	_	—	1	$IOH \ge -7 \text{ mA}, \text{ VDD} = 3.3 \text{ V}$			
		Output High Voltage	1.5 ⁽¹⁾	_	—	V	$IOH \ge -22 \text{ mA}, \text{ VDD} = 3.3 \text{V}$			
		8x Source Driver Pins ⁽³⁾	2.0 ⁽¹⁾	_	_	1	Іон ≥ -18 mA, VDD = 3.3V			
			3.0 ⁽¹⁾	_	—		$IOH \ge -10 \text{ mA}, \text{ VDD} = 3.3 \text{V}$			

TABLE 30-12: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

Note 1: Parameters are characterized but not tested.

2: Includes RA0-RA2, RB0-RB1, RB9, RC1-RC2, RC9-RC10, RC12, RD7, RD8, RE4-RE5, RE8-RE9 and RE12-RE13 pins.

3: Includes all I/O pins that are not 4x driver pins (see Note 2).

TABLE 30-13: ELECTRICAL CHARACTERISTICS: BOR

			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$						
Param No.	Symbol	Characteristic	Min. ⁽²⁾	Тур.	Max.	Units	Conditions		
BO10	VBOR	BOR Event on VDD Transition High-to-Low	2.65	_	2.95	V	VDD (Notes 2 and 3)		

Note 1: Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, PGAs and comparators) may have degraded performance.

2: Parameters are for design guidance only and are not tested in manufacturing.

3: The VBOR specification is relative to VDD.

DC CHARACTERISTICS			(unless	-	vise state	anditions: 3.0V to 3.6V ed) $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for Extended		
Param No.	Symbol	Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Conditions	
	Program Flash Memory							
D130	Eр	Cell Endurance	10,000	—	—	E/W	-40°C to +125°C	
D131	Vpr	VDD for Read	3.0	—	3.6	V		
D132b	VPEW	VDD for Self-Timed Write	3.0	—	3.6	V		
D134	TRETD	Characteristic Retention	20	—	_	Year	Provided no other specifications are violated, -40°C to +125°C	
D135	IDDP	Supply Current during Programming ⁽²⁾	—	10	—	mA		
D136	IPEAK	Instantaneous Peak Current During Start-up	-	—	150	mA		
D137a	TPE	Page Erase Time	19.7	—	20.1	ms	TPE = 146893 FRC cycles, Ta = +85°C (Note 3)	
D137b	TPE	Page Erase Time	19.5	—	20.3	ms	TPE = 146893 FRC cycles, TA = +125°C (Note 3)	
D138a	Tww	Word Write Cycle Time	46.5	—	47.3	μs	Tww = 346 FRC cycles, Ta = +85°C (Note 3)	
D138b	Tww	Word Write Cycle Time	46.0	-	47.9	μs	Tww = 346 FRC cycles, Ta = +125°C (Note 3)	
D139a	Trw	Row Write Time	667	-	679	μs	Trw = 4965 FRC cycles, TA = +85°C (Note 3)	
D139b	Trw	Row Write Time	660	-	687	μs	Trw = 4965 FRC cycles, Ta = +125°C (Note 3)	

TABLE 30-14: DC CHARACTERISTICS: PROGRAM MEMORY

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

2: Parameter characterized but not tested in manufacturing.

3: Other conditions: FRC = 7.37 MHz, TUN<5:0> = 011111 (for Minimum), TUN<5:0> = 100000 (for Maximum). This parameter depends on the FRC accuracy (see Table 30-20) and the value of the FRC Oscillator Tuning register (see Register 9-4). For complete details on calculating the Minimum and Maximum time, see Section 5.3 "Programming Operations".

30.2 AC Characteristics and Timing Parameters

This section defines the dsPIC33EPXXXGS70X/80X family AC characteristics and timing parameters.

TABLE 30-15: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC

	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)
AC CHARACTERISTICS	$\begin{array}{ll} \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$
	Operating voltage VDD range as described in Section 30.1 "DC Characteristics".

FIGURE 30-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

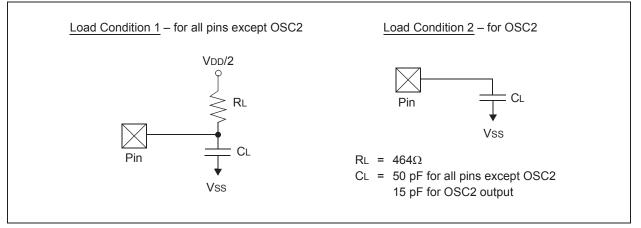
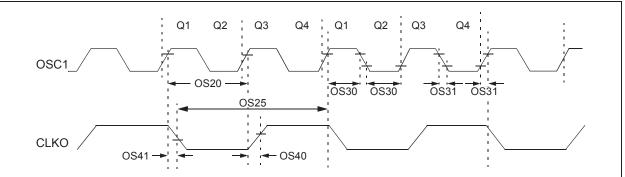


TABLE 30-16: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS

Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions
DO50	Cosco	OSC2 Pin	_	—	15		In XT and HS modes, when external clock is used to drive OSC1
DO56	Сю	All I/O Pins and OSC2	—	—	50	pF	EC mode
DO58	Св	SCLx, SDAx	—	—	400	рF	In I ² C mode

FIGURE 30-2: EXTERNAL CLOCK TIMING



АС СНА	AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$							
Param No.	Sym	Characteristic	Min.	Typ. ⁽¹⁾	Max.	Units	Conditions				
OS10 FIN		External CLKI Frequency (External clocks allowed only in EC and ECPLL modes)	DC	—	60	MHz	EC				
		Oscillator Crystal Frequency	3.5	—	10	MHz	XT				
0000	Taga		10		40	MHz	HS				
OS20	Tosc	Tosc = 1/Fosc	8.33	—	DC	ns	+125°C				
	Tosc = 1/Fosc	7.14	—	DC	ns	+85°C					
OS25	TCY	Instruction Cycle Time ⁽²⁾	16.67	—	DC	ns	+125°C				
		Instruction Cycle Time ⁽²⁾	14.28	—	DC	ns	+85°C				
OS30	TosL, TosH	External Clock in (OSC1) High or Low Time	0.45 x Tosc	—	0.55 x Tosc	ns	EC				
OS31	TosR, TosF	External Clock in (OSC1) Rise or Fall Time	_	—	20	ns	EC				
OS40	TckR	CLKO Rise Time ^(3,4)	_	5.2	_	ns					
OS41	TckF	CLKO Fall Time ^(3,4)	_	5.2		ns					
OS42	Gм	External Oscillator Transconductance ⁽⁴⁾	-	12	—	mA/V	HS, VDD = 3.3V, TA = +25°C				
			-	6	_	mA/V	XT, VDD = 3.3V, TA = +25°C				

TABLE 30-17: EXTERNAL CLOCK TIMING REQUIREMENTS

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

2: Instruction cycle period (Tcr) equals two times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type, under standard operating conditions, with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "Minimum" values with an external clock applied to the OSC1 pin. When an external clock input is used, the "Maximum" cycle time limit is "DC" (no clock) for all devices.

- 3: Measurements are taken in EC mode. The CLKO signal is measured on the OSC2 pin.
- 4: This parameter is characterized but not tested in manufacturing.

TABLE 30-18: PLL CLOCK TIMING SPECIFICATIONS

			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic	Min. Typ. ⁽¹⁾ Max. Units Conditions				Conditions	
OS50	Fplli	PLL Voltage Controlled Oscillator (VCO) Input Frequency Range	0.8	—	8.0	MHz	ECPLL, XTPLL modes	
OS51	Fvco	On-Chip VCO System Frequency	120	—	340	MHz		
OS52	OS52 TLOCK PLL Start-up Time (Lock Time)		0.9	1.5	3.1	ms		
OS53	OS53 DCLK CLKO Stability (Jitter) ⁽²⁾			0.5	3	%		

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: This jitter specification is based on clock cycle-by-clock cycle measurements. To get the effective jitter for individual time bases, or communication clocks used by the application, use the following formula:

$$Effective Jitter = \frac{DCLK}{\sqrt{\frac{FOSC}{Time Base or Communication Clock}}}$$

For example, if Fosc = 120 MHz and the SPIx bit rate = 10 MHz, the effective jitter is as follows:

Effective Jitter =
$$\frac{DCLK}{\sqrt{\frac{120}{10}}} = \frac{DCLK}{\sqrt{12}} = \frac{DCLK}{3.464}$$

TABLE 30-19: AUXILIARY PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			$\begin{array}{llllllllllllllllllllllllllllllllllll$						
Param No.	Symbol	Characteris	Min	Typ ⁽¹⁾	Max	Units	Conditions		
OS56	Fhpout	On-Chip 16x PLL CC Frequency	0	112	118	120	MHz		
OS57	Fhpin	On-Chip 16x PLL Phase Detector Input Frequency		7.0	7.37	7.5	MHz		
OS58	Tsu	Frequency Generato Time	_	_	10	μs			

Note 1: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested in manufacturing.

TABLE 30-20: INTERNAL FRC ACCURACY

АС СНА	RACTERISTICS		$\begin{array}{ll} \mbox{Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$									
Param No.	Characteristic	Min.	Тур.	Max.	Units	Conditio	ons					
Internal	FRC Accuracy @ FRC Fre	equency =	7.37 MHz	(1)								
F20a	FRC	-2	0.5	+2	%	$-40^{\circ}C \le TA \le -10^{\circ}C$	VDD = 3.0-3.6V					
		-0.9	0.5	+0.9	%	$-10^{\circ}C \le TA \le +85^{\circ}C$	VDD = 3.0-3.6V					
F20b	FRC	-2	-2 1 +2 % $+85^{\circ}C \le TA \le +125^{\circ}C$ VDD = 3.0-									

Note 1: Frequency is calibrated at +25°C and 3.3V. TUNx bits can be used to compensate for temperature drift.

TABLE 30-21: INTERNAL LPRC ACCURACY

АС СН	ARACTERISTICS		$\begin{array}{llllllllllllllllllllllllllllllllllll$									
Param No.	Characteristic	Min.	Тур.	Max.	Units	Conditio	ons					
LPRC (@ 32.768 kHz ⁽¹⁾											
F21a	LPRC	-30	_	+30	%	$-40^\circ C \le T A \le -10^\circ C$	VDD = 3.0-3.6V					
			_	+20	%	$-10^{\circ}C \le TA \le +85^{\circ}C$	VDD = 3.0-3.6V					
F21b	LPRC	-30	—	+30	%	$+85^{\circ}C \leq TA \leq +125^{\circ}C$	VDD = 3.0-3.6V					

Note 1: This is the change of the LPRC frequency as VDD changes.



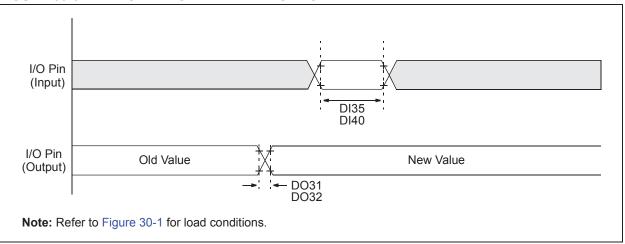


TABLE 30-22: I/O TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq T_A \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq T_A \leq +125^\circ C \mbox{ for Extended} \end{array}$				
Param No.	Symbol	Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Conditions
DO31	TIOR	Port Output Rise Time		5	10	ns	
DO32	TIOF	Port Output Fall Time		5	10	ns	
DI35	TINP	INTx Pin High or Low Time (input)	20	_	_	ns	
DI40	Trbp	CNx High or Low Time (input)	2	—	_	Тсү	

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

FIGURE 30-4: BOR AND MASTER CLEAR RESET TIMING CHARACTERISTICS

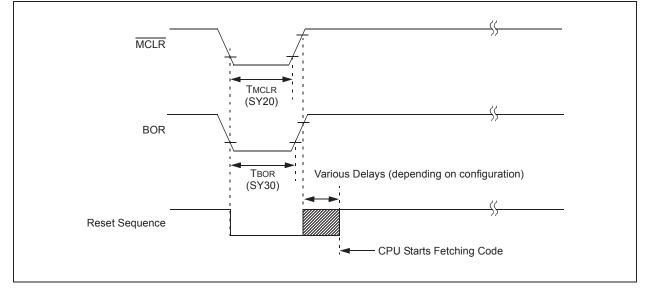


TABLE 30-23: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER TIMING REQUIREMENTS

			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param No.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions		
SY00	Τρυ	Power-up Period	_	400	600	μs			
SY10	Tost	Oscillator Start-up Time	—	1024 Tosc	_	_	Tosc = OSC1 period		
SY12 Twdt	Twdt	Watchdog Timer Time-out Period	0.81	_	1.22	ms	WDTPRE = 0, WDTPOST<3:0> = 0000, using LPRC tolerances indicated in F21 (see Table 30-21) at +85°C		
			3.25		4.88	ms	WDTPRE = 1, WDTPOST<3:0> = 0000, using LPRC tolerances indicated in F21 (see Table 30-21) at +85°C		
SY13	Tioz	I/O High-Impedance from MCLR Low or Watchdog Timer Reset	0.68	0.72	1.2	μs			
SY20	TMCLR	MCLR Pulse Width (low)	2	_	_	μs			
SY30	TBOR	BOR Pulse Width (low)	1	_	_	μs			
SY35	TFSCM	Fail-Safe Clock Monitor Delay	—	500	900	μs	-40°C to +85°C		
SY36	TVREG	Voltage Regulator Standby-to-Active mode Transition Time	—	—	30	μs			
SY37	Toscdfrc	FRC Oscillator Start-up Delay	—	48	_	μs			
SY38	TOSCDLPRC	LPRC Oscillator Start-up Delay	_	_	70	μs			

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

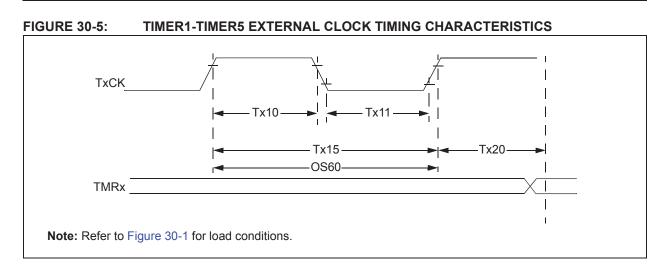


TABLE 30-24: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS⁽¹⁾

				$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Chai	racteristic ⁽²⁾	Min.	Тур.	Max.	Units	Conditions	
TA10	ТтхН	T1CK High Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	_	_	ns	Must also meet Parameter TA15, N = Prescale Value (1, 8, 64, 256)	
			Asynchronous mode	35		—	ns		
TA11	ΤτχL	T1CK Low Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	_	_	ns	Must also meet Parameter TA15, N = Prescale Value (1, 8, 64, 256)	
			Asynchronous mode	10		—	ns		
TA15	ΤτχΡ	T1CK Input Period	Synchronous mode	Greater of: 40 or (2 Tcy + 40)/N	—	—	ns	N = Prescale Value (1, 8, 64, 256)	
OS60	Ft1	Range (oscill	tor Input Frequency lator enabled by CS (T1CON<1>))	DC	—	50	kHz		
TA20	TCKEXTMRL	Edge to Time	xternal T1CK Clock er Increment	0.75 Tcy + 40	_	1.75 Tcy + 40	ns		

Note 1: Timer1 is a Type A timer.

2: These parameters are characterized but not tested in manufacturing.

TABLE 30-25: TIMER2 AND TIMER4 (TYPE B TIMER) EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS				Standard Op (unless other Operating terr	wise st	e -40°C ≤ TA ≤	≤ +85°C	6V for Industrial C for Extended
Param No.	Symbol	Cha	racteristic ⁽¹⁾	Min.	Тур.	Max.	Units	Conditions
TB10	TtxH	TxCK High Time	Synchronous mode	Greater of: 20 or (TCY + 20)/N	_	_	ns	Must also meet Parameter TB15, N = Prescale Value (1, 8, 64, 256)
TB11	TtxL	TxCK Low Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	_	_	ns	Must also meet Parameter TB15, N = Prescale Value (1, 8, 64, 256)
TB15	TtxP	TxCK Input Period	Synchronous mode	Greater of: 40 or (2 Tcy + 40)/N	—	_	ns	N = Prescale Value (1, 8, 64, 256)
TB20	TCKEXTMRL		External TxCK to Timer Increment	0.75 Tcy + 40	_	1.75 Tcy + 40	ns	

Note 1: These parameters are characterized but not tested in manufacturing.

TABLE 30-26: TIMER3 AND TIMER5 (TYPE C TIMER) EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Charac	teristic ⁽¹⁾	Min. Typ. Max. Units Condition				
TC10	TtxH	TxCK High Time	Synchronous	Tcy + 20		—	ns	Must also meet Parameter TC15
TC11	TtxL	TxCK Low Time	Synchronous	Tcy + 20	—	_	ns	Must also meet Parameter TC15
TC15	TtxP	TxCK Input Period	Synchronous with Prescaler	2 Tcy + 40		—	ns	N = Prescale Value (1, 8, 64, 256)
TC20	TCKEXTMRL	Delay from Ext Clock Edge to	ernal TxCK Timer Increment	0.75 Tcy + 40		1.75 Tcy + 40	ns	

Note 1: These parameters are characterized but not tested in manufacturing.

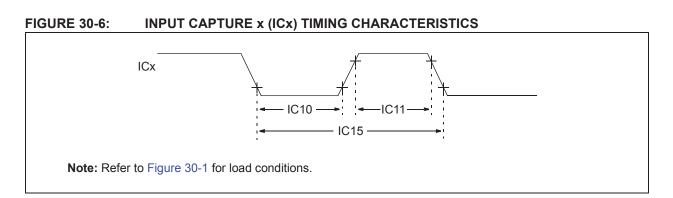


TABLE 30-27: INPUT CAPTURE x MODULE TIMING REQUIREMENTS

АС СНА	RACTERI	STICS	$\begin{array}{ll} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$						
Param. No.	Symbol	Characteristics ⁽¹⁾	Min.	Max.	Units	Units Conditions			
IC10	TccL	ICx Input Low Time	Greater of: 12.5 + 25 or (0.5 Tcy/N) + 25	_	ns	Must also meet Parameter IC15			
IC11	ТссН	ICx Input High Time	Greater of: 12.5 + 25 or (0.5 Tcy/N) + 25	_	ns	Must also meet Parameter IC15 N = Prescale Valu (1, 4, 16)			
IC15	TCCP	ICx Input Period	Greater of: 25 + 50 or (1 Tcy/N) + 50	—	ns				

Note 1: These parameters are characterized but not tested in manufacturing.

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FIGURE 30-7: OUTPUT COMPARE x MODULE (OCx) TIMING CHARACTERISTICS

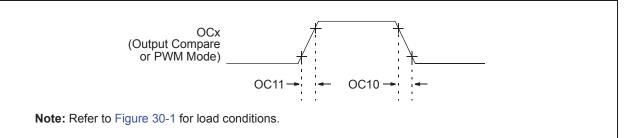


TABLE 30-28: OUTPUT COMPARE x MODULE TIMING REQUIREMENTS

АС СНА	AC CHARACTERISTICS			$\begin{array}{ll} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic ⁽¹⁾	Min. Typ. Max. Units Condition				Conditions		
OC10	TccF	OCx Output Fall Time	— — — ns See Parameter DO32						
OC11	TccR	OCx Output Rise Time	— — ns See Parameter DO31						

Note 1: These parameters are characterized but not tested in manufacturing.

FIGURE 30-8: OCx/PWMx MODULE TIMING CHARACTERISTICS

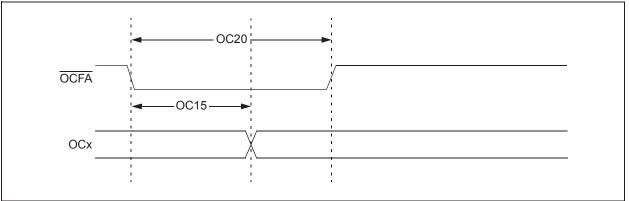


TABLE 30-29: OCx/PWMx MODULE TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param No.	Symbol	Characteristic ⁽¹⁾	Min. Typ. Max. Units Conditions						
OC15	Tfd	Fault Input to PWMx I/O Change	— — Tcy + 20 ns						
OC20	TFLT	Fault Input Pulse Width	Tcy + 20 — ns						

Note 1: These parameters are characterized but not tested in manufacturing.

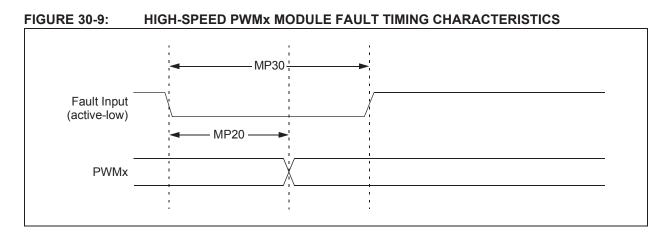


FIGURE 30-10: HIGH-SPEED PWMx MODULE TIMING CHARACTERISTICS

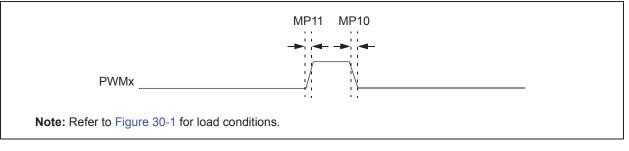


TABLE 30-30: HIGH-SPEED PWMx MODULE TIMING REQUIREMENTS

			(unless	rd Opera otherwi ng tempe	se statec rature -	l) -40°C ≤ T	3.0V to 3.6V $A \le +85^{\circ}C$ for Industrial $A \le +125^{\circ}C$ for Extended	
Param No.	Symbol	Characteristic ⁽¹⁾	Min. Typ. Max. Units Conditions					
MP10	TFPWM	PWMx Output Fall Time	_	—	—	ns	See Parameter DO32	
MP11	TRPWM	PWMx Output Rise Time	_	—	_	ns	See Parameter DO31	
MP20	Tfd	Fault Input ↓ to PWMx I/O Change	_	_	15	ns		
MP30	Tfh	Fault Input Pulse Width	15	—	—	ns		

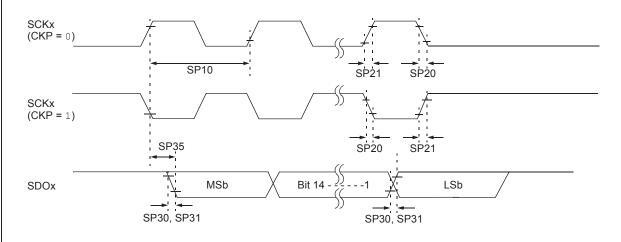
Note 1: These parameters are characterized but not tested in manufacturing.

TABLE 30-31: SPI1, SPI2 AND SPI3 MAXIMUM DATA/CLOCK RATE SUMMARY⁽¹⁾

AC CHARA	CTERISTICS		$\begin{array}{llllllllllllllllllllllllllllllllllll$					
Maximum Data Rate	Master Transmit Only (Half-Duplex)	Master Transmit/Receive (Full-Duplex)	Slave Transmit/Receive (Full-Duplex)	CKE	СКР	SMP		
15 MHz	Table 30-32	_	—	0,1	0,1	0,1		
9 MHz	_	Table 30-33	—	1	0,1	1		
9 MHz	—	Table 30-34	—	0	0,1	1		
15 MHz	—	—	Table 30-35	1	0	0		
11 MHz	—	—	Table 30-36	1	1	0		
15 MHz	_	—	Table 30-37	0	1	0		
11 MHz	—	—	Table 30-38	0	0	0		

Note 1: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

FIGURE 30-11: SPI1, SPI2 AND SPI3 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS^(1,2)



Note 1: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

2: Refer to Figure 30-1 for load conditions.

FIGURE 30-12: SPI1, SPI2 AND SPI3 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 1) TIMING CHARACTERISTICS^(1,2)

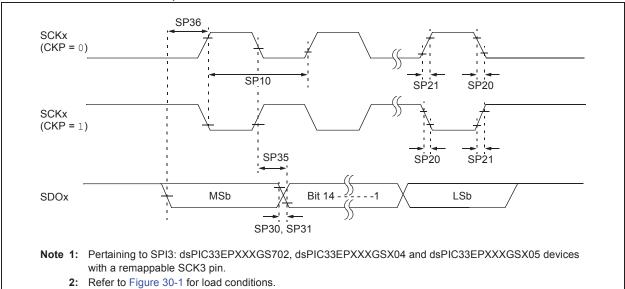


TABLE 30-32: SPI1, SPI2 AND SPI3 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS⁽⁵⁾

АС СНА	$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param. Symbol Characteristic ⁽¹⁾ Min. Typ. ⁽²⁾ Max. Units Conditions							Conditions
SP10	FscP	Maximum SCKx Frequency	—	—	15	MHz	(Note 3)
SP20	TscF	SCKx Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCKx Output Rise Time	—	—		ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDOx Data Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDOx Data Output Rise Time	—	—		ns	See Parameter DO31 (Note 4)
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	
SP36	TdiV2scH, TdiV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

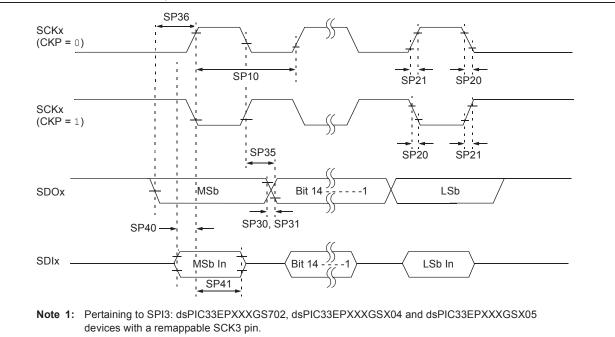
2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

FIGURE 30-13: SPI1, SPI2 AND SPI3 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING CHARACTERISTICS^(1,2)



2: Refer to Figure 30-1 for load conditions.

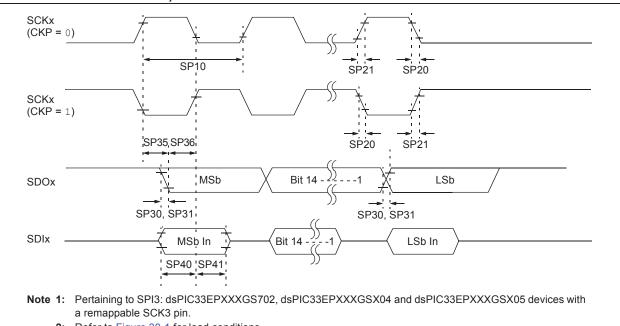
TABLE 30-33:SPI1, SPI2 AND SPI3 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1)TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			(unless	s otherw	ise stat	proditions: 3.0V to 3.6V ed) -40°C \leq TA \leq +85°C for Industrial -40°C \leq TA \leq +125°C for Extended		
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions	
SP10	FscP	Maximum SCKx Frequency		—	9	MHz	(Note 3)	
SP20	TscF	SCKx Output Fall Time	_	—		ns	See Parameter DO32 (Note 4)	
SP21	TscR	SCKx Output Rise Time	_	—		ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDOx Data Output Fall Time	_	—		ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDOx Data Output Rise Time	_	—		ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	_	6	20	ns		
SP36	TdoV2sc, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—		ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—		ns		

Note 1: These parameters are characterized, but are not tested in manufacturing.

- 2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.
- **3:** The minimum clock period for SCKx is 111 ns. The clock generated in Master mode must not violate this specification.
- 4: Assumes 50 pF load on all SPIx pins.
- 5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

FIGURE 30-14: SPI1, SPI2 AND SPI3 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1) TIMING CHARACTERISTICS^(1,2)



2: Refer to Figure 30-1 for load conditions.

TABLE 30-34:SPI1, SPI2 AND SPI3 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			Standard Operating Co (unless otherwise state Operating temperature			ed)		
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions	
SP10	FscP	Maximum SCKx Frequency	_	_	9	MHz	-40°C to +125°C (Note 3)	
SP20	TscF	SCKx Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)	
SP21	TscR	SCKx Output Rise Time	—		—	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDOx Data Output Rise Time	_	—	—	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	_	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns		

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

- **3:** The minimum clock period for SCKx is 111 ns. The clock generated in Master mode must not violate this specification.
- **4:** Assumes 50 pF load on all SPIx pins.
- 5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

FIGURE 30-15: SPI1, SPI2 AND SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING CHARACTERISTICS^(1,2)

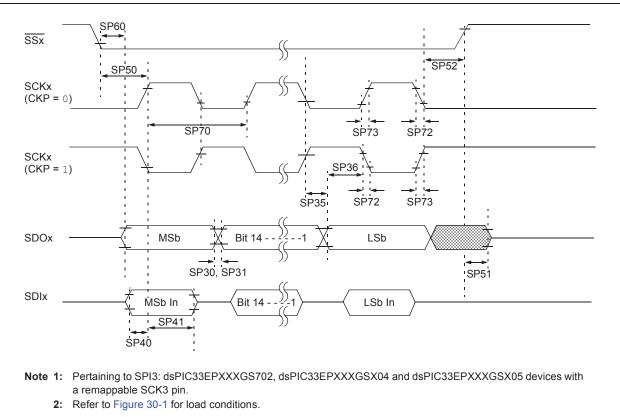


TABLE 30-35:SPI1, SPI2 AND SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

АС СНА		TICS	$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Тур. ⁽²⁾	Max.	Units	Conditions	
SP70	FscP	Maximum SCKx Input Frequency	_	_	15	MHz	(Note 3)	
SP72	TscF	SCKx Input Fall Time	—	_	—	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCKx Input Rise Time	—	_	_	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDOx Data Output Fall Time	—	_	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDOx Data Output Rise Time	—	_	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	_	—	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	_	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	_	_	ns		
SP50	TssL2scH, TssL2scL	SSx ↓ to SCKx ↑ or SCKx ↓ Input	120	_	_	ns		
SP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH TscL2ssH	SSx ↑ after SCKx Edge	1.5 TCY + 40	—	_	ns	(Note 4)	
SP60	TssL2doV	SDOx Data Output Valid after SSx Edge	—	_	50	ns		

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 66.7 ns. Therefore, the SCKx clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

FIGURE 30-16: SPI1, SPI2 AND SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS^(1,2)

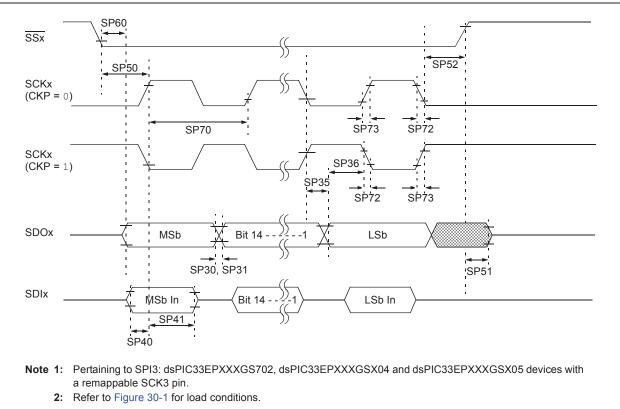


TABLE 30-36:SPI1, SPI2 AND SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

АС СНА		rics	$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Conditions				
SP70	FscP	Maximum SCKx Input Frequency			11	MHz	(Note 3)	
SP72	TscF	SCKx Input Fall Time			_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCKx Input Rise Time	—	_	—	ns	See Parameter DO31 (Note 4	
SP30	TdoF	SDOx Data Output Fall Time	—	_	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	_		ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	_		ns		
SP50	TssL2scH, TssL2scL	SSx ↓ to SCKx ↑ or SCKx ↓ Input	120	_	_	ns		
SP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH TscL2ssH	SSx ↑ after SCKx Edge	1.5 Tcy + 40	—	_	ns	(Note 4)	
SP60	TssL2doV	SDOx Data Output Valid after SSx Edge	—	—	50	ns		

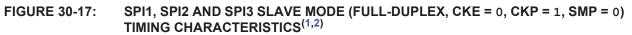
Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 91 ns. Therefore, the SCKx clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.



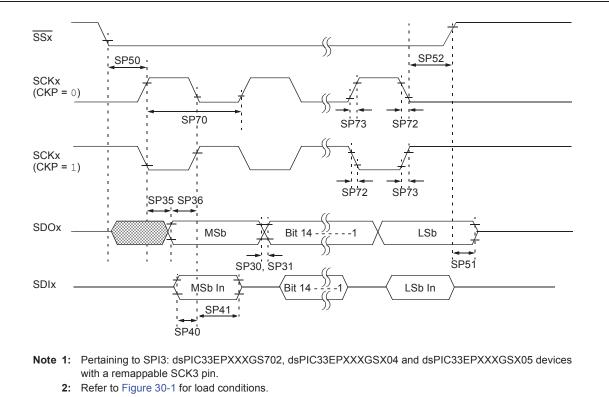


TABLE 30-37:SPI1, SPI2 AND SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Conditions				
SP70	FscP	Maximum SCKx Input Frequency	—	—	15	MHz	(Note 3)	
SP72	TscF	SCKx Input Fall Time	_	—	_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCKx Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4	
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDOx Data Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—		ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	_	ns		
SP50	TssL2scH, TssL2scL	SSx ↓ to SCKx ↑ or SCKx ↓ Input	120	—	—	ns		
SP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH TscL2ssH	SSx ↑ after SCKx Edge	1.5 Tcy + 40	—		ns	(Note 4)	

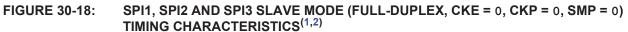
Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 66.7 ns. Therefore, the SCKx clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.



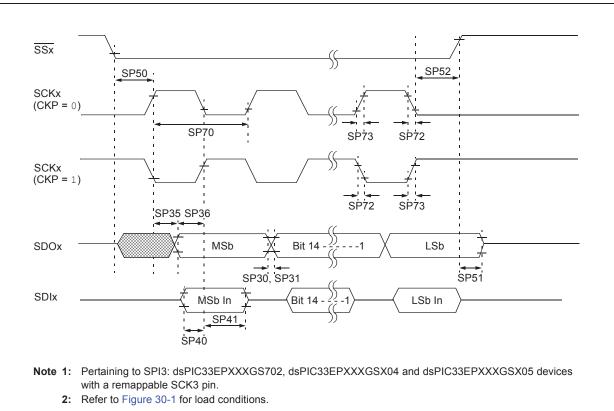


TABLE 30-38:SPI1, SPI2 AND SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Conditions			
SP70	FscP	Maximum SCKx Input Frequency	—	—	11	MHz	(Note 3)	
SP72	TscF	SCKx Input Fall Time	_	—	_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCKx Input Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDOx Data Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	_	ns		
SP50	TssL2scH, TssL2scL	SSx ↓ to SCKx ↑ or SCKx ↓ Input	120	—	_	ns		
SP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH TscL2ssH	SSx ↑ after SCKx Edge	1.5 TCY + 40	—		ns	(Note 4)	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 91 ns. Therefore, the SCKx clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

5: Pertaining to SPI3: dsPIC33EPXXXGS702, dsPIC33EPXXXGSX04 and dsPIC33EPXXXGSX05 devices with a remappable SCK3 pin.

TABLE 30-39: SPI3 MAXIMUM DATA/CLOCK RATE SUMMARY⁽¹⁾

AC CHARA	CTERISTICS		$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Maximum Data Rate	Master Transmit Only (Half-Duplex)	Master Transmit/Receive (Full-Duplex)	Slave Transmit/Receive (Full-Duplex)	CKE	СКР	SMP			
25 MHz	Table 30-40	_	_	0,1	0,1	0,1			
25 MHz	—	Table 30-41	_	1	0,1	1			
25 MHz	—	Table 30-42	—	0	0,1	1			
25 MHz	—	_	Table 30-43	1	0	0			
25 MHz	—		Table 30-44	1	1	0			
25 MHz	_		Table 30-45	0	1	0			
25 MHz		_	Table 30-46	0	0	0			

Note 1: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

FIGURE 30-19: SPI3 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS^(1,2)

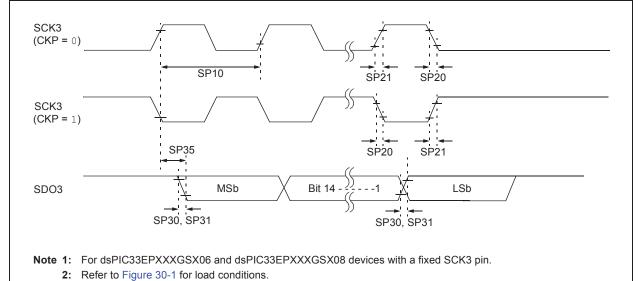


FIGURE 30-20: SPI3 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 1) TIMING CHARACTERISTICS^(1,2)

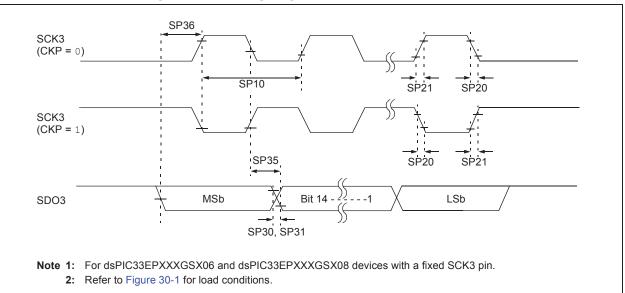


TABLE 30-40: SPI3 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions	
SP10	FscP	Maximum SCK3 Frequency	—	—	25	MHz	(Note 3)	
SP20	TscF	SCK3 Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)	
SP21	TscR	SCK3 Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO3 Data Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO3 Data Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	—	6	20	ns		
SP36	TdiV2scH, TdiV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	_	_	ns		

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK3 is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

- 4: Assumes 50 pF load on all SPI3 pins.
- 5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

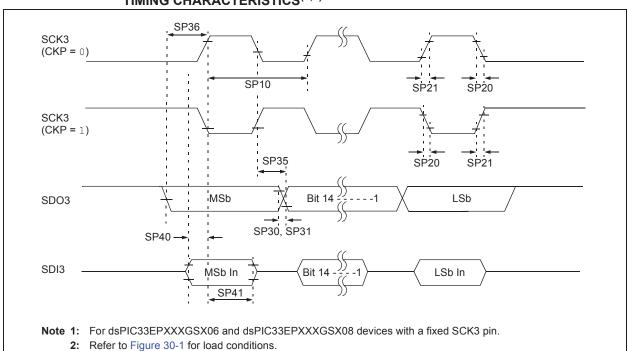


FIGURE 30-21: SPI3 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING CHARACTERISTICS^(1,2)

TABLE 30-41:SPI3 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1)TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$						
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions		
SP10	FscP	Maximum SCK3 Frequency	_	—	25	MHz	(Note 3)		
SP20	TscF	SCK3 Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)		
SP21	TscR	SCK3 Output Rise Time	_		_	ns	See Parameter DO31 (Note 4)		
SP30	TdoF	SDO3 Data Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)		
SP31	TdoR	SDO3 Data Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)		
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	_	6	20	ns			
SP36	TdoV2sc, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	—	_	ns			
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20 — — ns						
SP41	TscH2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3 Edge	15	—		ns			

Note 1: These parameters are characterized, but are not tested in manufacturing.

- 2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.
- **3:** The minimum clock period for SCK3 is 100 ns. The clock generated in Master mode must not violate this specification.
- **4:** Assumes 50 pF load on all SPI3 pins.
- 5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.



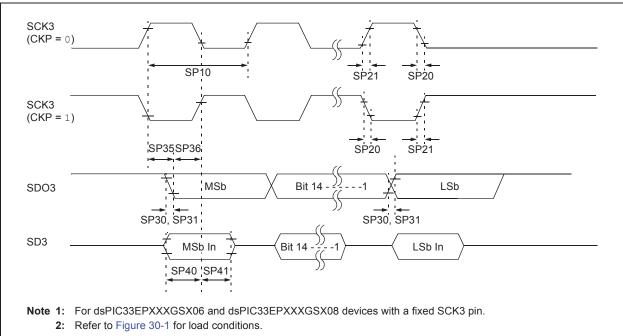


TABLE 30-42:SPI3 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			Standard Operating Co (unless otherwise state Operating temperature			ed)		
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions	
SP10	FscP	Maximum SCK3 Frequency		_	25	MHz	-40°C to +125°C (Note 3)	
SP20	TscF	SCK3 Output Fall Time	_	_	—	ns	See Parameter DO32 (Note 4)	
SP21	TscR	SCK3 Output Rise Time		—		ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO3 Data Output Fall Time	_	_	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO3 Data Output Rise Time		—	—	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge		6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	—	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20	—	—	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3Edge	20	—	—	ns		

Note 1: These parameters are characterized, but are not tested in manufacturing.

- 2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.
- **3:** The minimum clock period for SCK3 is 100 ns. The clock generated in Master mode must not violate this specification.
- **4:** Assumes 50 pF load on all SPI3 pins.
- 5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

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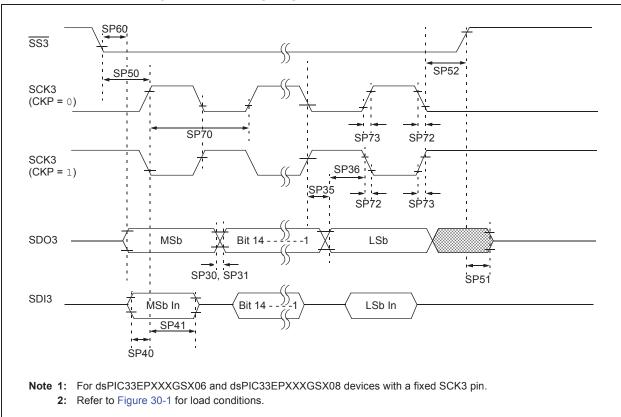


FIGURE 30-23: SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING CHARACTERISTICS^(1,2)

TABLE 30-43:SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

АС СНА		rics	Standard Op (unless othe Operating ter	erwise st	t ated) e -40°	C ≤ TA ≤	IV to 3.6V +85°C for Industrial +125°C for Extended
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Тур. ⁽²⁾	Max.	Units	Conditions
SP70	FscP	Maximum SCK3 Input Frequency	—	—	25	MHz	(Note 3)
SP72	TscF	SCK3 Input Fall Time			_	ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK3 Input Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO3 Data Output Fall Time			_	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO3 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	_		ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20	_	_	ns	
SP41	TscH2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3 Edge	15	—	_	ns	
SP50	TssL2scH, TssL2scL	SS3 ↓ to SCK3 ↑ or SCK3 ↓ Input	120	_	_	ns	
SP51	TssH2doZ	SS3 ↑ to SDO3 Output High-Impedance	10	—	50	ns	(Note 4)
SP52	TscH2ssH TscL2ssH	SS3 ↑ after SCK3 Edge	1.5 Tcy + 40	—	_	ns	(Note 4)
SP60	TssL2doV	SDO3 Data Output Valid after SS3 Edge	—	_	50	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK3 is 66.7 ns. Therefore, the SCK3 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI3 pins.

5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

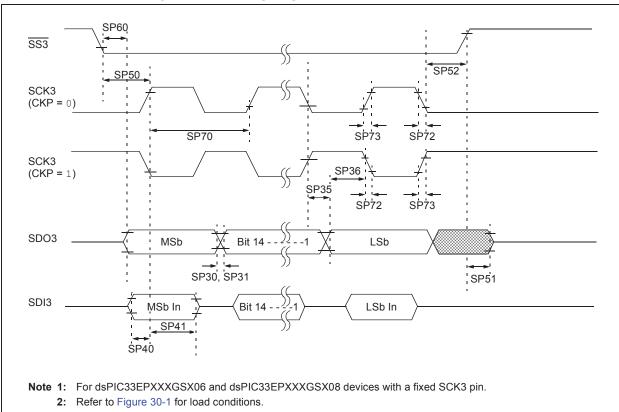


FIGURE 30-24: SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS^(1,2)

TABLE 30-44:SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

АС СНА		rics	$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Тур. ⁽²⁾	Max.	Units	Conditions	
SP70	FscP	Maximum SCK3 Input Frequency	—	_	25	MHz	(Note 3)	
SP72	TscF	SCK3 Input Fall Time			_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCK3 Input Rise Time	—	_	_	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO3 Data Output Fall Time			_	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO3 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	_		ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20	_	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3 Edge	15	_	_	ns		
SP50	TssL2scH, TssL2scL	SS3 ↓ to SCK3 ↑ or SCK3 ↓ Input	120	_	_	ns		
SP51	TssH2doZ	SS3 ↑ to SDO3 Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH, TscL2ssH	SS3 ↑ after SCK3 Edge	1.5 Tcy + 40	—	_	ns	(Note 4)	
SP60	TssL2doV	SDO3 Data Output Valid after SS3 Edge	—		50	ns		

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK3 is 91 ns. Therefore, the SCK3 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI3 pins.

5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

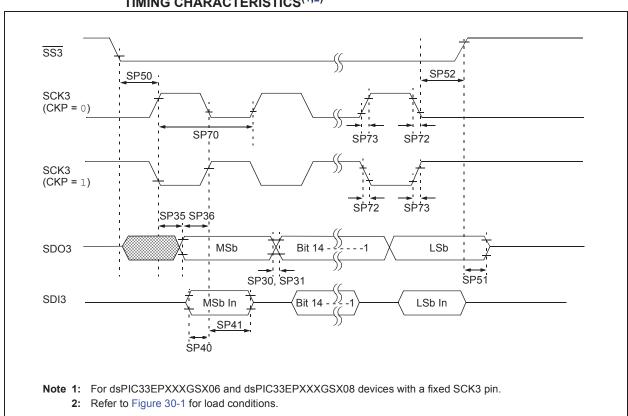


FIGURE 30-25: SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING CHARACTERISTICS^(1,2)

TABLE 30-45:SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Conditions				
SP70	FscP	Maximum SCK3 Input Frequency	—	—	25	MHz	(Note 3)	
SP72	TscF	SCK3 Input Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCK3 Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO3 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO3 Data Output Rise Time	—	—		ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	—	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20	—		ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3 Edge	15	—	_	ns		
SP50	TssL2scH, TssL2scL	SS3 ↓ to SCK3 ↑ or SCK3 ↓ Input	120	—	—	ns		
SP51	TssH2doZ	SS3 ↑ to SDO3 Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH, TscL2ssH	SS3 ↑ after SCK3 Edge	1.5 Tcy + 40	—	_	ns	(Note 4)	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK3 is 66.7 ns. Therefore, the SCK3 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI3 pins.

5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

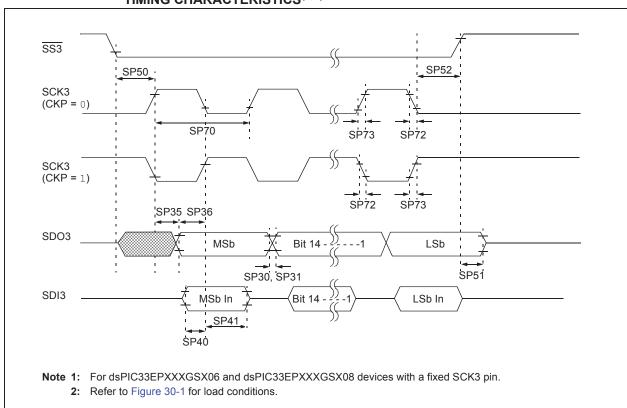


FIGURE 30-26: SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING CHARACTERISTICS^(1,2)

TABLE 30-46:SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0)TIMING REQUIREMENTS⁽⁵⁾

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Тур. ⁽²⁾	Conditions			
SP70	FscP	Maximum SCK3 Input Frequency	—	—	25	MHz	(Note 3)	
SP72	TscF	SCK3 Input Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCK3 Input Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO3 Data Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO3 Data Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	—	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20	—	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3 Edge	15	—	_	ns		
SP50	TssL2scH, TssL2scL	SS3 ↓ to SCK3 ↑ or SCK3 ↓ Input	120	—	_	ns		
SP51	TssH2doZ	SS3 ↑ to SDO3 Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH, TscL2ssH	SS3	1.5 Tcy + 40	—		ns	(Note 4)	

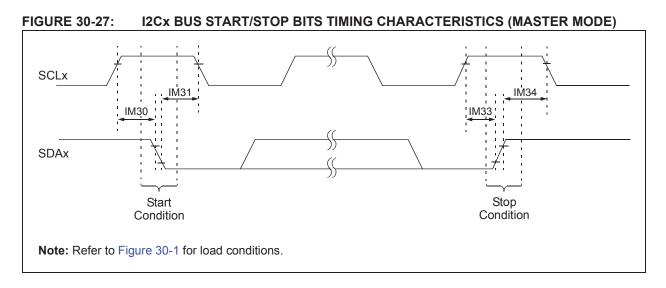
Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

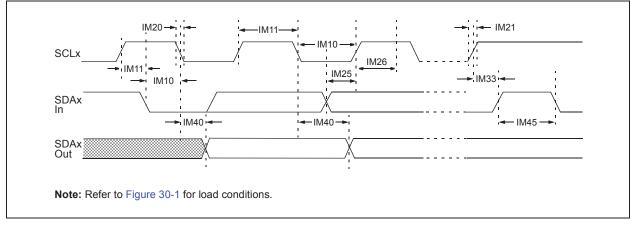
3: The minimum clock period for SCK3 is 91 ns. Therefore, the SCK3 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI3 pins.

5: For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.







АС СНА	RACTER	ISTICS		Standard Operatin (unless otherwise Operating tempera	stated) iture -40)°C ≤ Ta ≤	PV to 3.6V +85°C for Industrial +125°C for Extended
Param No.	Symbol	Characte	eristic ⁽⁴⁾	Min. ⁽¹⁾	Max.	Units	Conditions
IM10	TLO:SCL	Clock Low Time	100 kHz mode	Tcy/2 (BRG + 2)	_	μs	
			400 kHz mode	Tcy/2 (BRG + 2)	—	μs	
			1 MHz mode ⁽²⁾	Tcy/2 (BRG + 2)	—	μs	
IM11	THI:SCL	Clock High Time	100 kHz mode	Tcy/2 (BRG + 2)	_	μs	
			400 kHz mode	Tcy/2 (BRG + 2)		μs	
			1 MHz mode ⁽²⁾	Tcy/2 (BRG + 2)	—	μs	
IM20	TF:SCL	SDAx and SCLx	100 kHz mode	_	300	ns	CB is specified to be
		Fall Time	400 kHz mode	20 + 0.1 Св	300	ns	from 10 to 400 pF
			1 MHz mode ⁽²⁾	_	100	ns	-
IM21	TR:SCL	SDAx and SCLx	100 kHz mode		1000	ns	CB is specified to be
		Rise Time	400 kHz mode	20 + 0.1 Св	300	ns	from 10 to 400 pF
			1 MHz mode ⁽²⁾	_	300	ns	-
IM25	TSU:DAT	Data Input	100 kHz mode	250	_	ns	
		Setup Time	400 kHz mode	100	_	ns	-
			1 MHz mode ⁽²⁾	40	_	ns	-
IM26	THD:DAT	Data Input	100 kHz mode	0		μs	
		Hold Time	400 kHz mode	0	0.9	μs	-
			1 MHz mode ⁽²⁾	0.2	_	μs	-
IM30	TSU:STA	Start Condition	100 kHz mode	TCY/2 (BRG + 2)	_	μs	Only relevant for
		Setup Time	400 kHz mode	Tcy/2 (BRG + 2)	_	μs	Repeated Start
			1 MHz mode ⁽²⁾	TCY/2 (BRG + 2)	_	μs	condition
IM31	THD:STA	Start Condition	100 kHz mode	TCY/2 (BRG + 2)	_	μs	After this period, the
		Hold Time	400 kHz mode	Tcy/2 (BRG +2)	_	μs	first clock pulse is
			1 MHz mode ⁽²⁾	TCY/2 (BRG + 2)	_	μs	generated
IM33	Tsu:sto	Stop Condition	100 kHz mode	Tcy/2 (BRG + 2)		μs	
		Setup Time	400 kHz mode	Tcy/2 (BRG + 2)	_	μs	-
			1 MHz mode ⁽²⁾	Tcy/2 (BRG + 2)	_	μs	-
IM34	THD:STO	Stop Condition	100 kHz mode	Tcy/2 (BRG + 2)	_	μs	
		Hold Time	400 kHz mode	Tcy/2 (BRG + 2)	_	μs	-
			1 MHz mode ⁽²⁾	Tcy/2 (BRG + 2)	_	μs	-
IM40	TAA:SCL	Output Valid	100 kHz mode		3500	ns	
		from Clock	400 kHz mode		1000	ns	
			1 MHz mode ⁽²⁾		400	ns	
IM45	TBF:SDA	Bus Free Time	100 kHz mode	4.7		μs	Time the bus must be
			400 kHz mode	1.3	—	μs	free before a new
			1 MHz mode ⁽²⁾	0.5		μs	
IM50	Св	Bus Capacitive L			400	pF	
IM51	TPGD	Pulse Gobbler De	Ŧ	65	390	ns	(Note 3)

TABLE 30-47: I2Cx BUS DATA TIMING REQUIREMENTS (MASTER MODE)

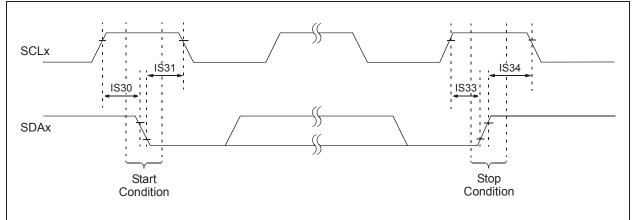
Note 1: BRG is the value of the I²C Baud Rate Generator.

2: Maximum Pin Capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

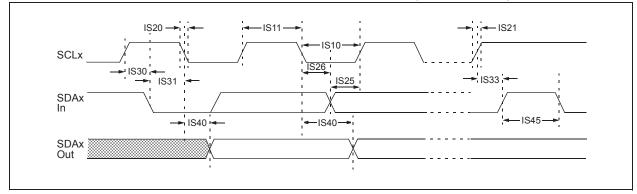
3: Typical value for this parameter is 130 ns.

4: These parameters are characterized but not tested in manufacturing.

FIGURE 30-29: I2Cx BUS START/STOP BITS TIMING CHARACTERISTICS (SLAVE MODE)







AC CHARACTERISTICS				$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic ⁽³⁾		Min.	Max.	Units	Conditions		
IS10	TLO:SCL	Clock Low Time	100 kHz mode	4.7	—	μs			
			400 kHz mode	1.3	—	μs			
			1 MHz mode ⁽¹⁾	0.5	—	μs			
IS11	THI:SCL	Clock High Time	100 kHz mode	4.0	—	μs	Device must operate at a minimum of 1.5 MHz		
			400 kHz mode	0.6	-	μs	Device must operate at a minimum of 10 MHz		
			1 MHz mode ⁽¹⁾	0.5	—	μs			
IS20	TF:SCL	SDAx and SCLx	100 kHz mode	—	300	ns	CB is specified to be from		
		Fall Time	400 kHz mode	20 + 0.1 Св	300	ns	10 to 400 pF		
			1 MHz mode ⁽¹⁾	—	100	ns			
IS21	TR:SCL	SDAx and SCLx Rise Time	100 kHz mode	_	1000	ns	CB is specified to be from		
			400 kHz mode	20 + 0.1 Св	300	ns	10 to 400 pF		
			1 MHz mode ⁽¹⁾	—	300	ns			
IS25	TSU:DAT	Data Input Setup Time	100 kHz mode	250	—	ns			
			400 kHz mode	100	—	ns			
			1 MHz mode ⁽¹⁾	100	—	ns			
IS26	THD:DAT	Data Input Hold Time	100 kHz mode	0	—	μs			
			400 kHz mode	0	0.9	μs			
			1 MHz mode ⁽¹⁾	0	0.3	μs			
IS30	TSU:STA	Start Condition Setup Time	100 kHz mode	4.7	—	μs	Only relevant for Repeate Start condition		
			400 kHz mode	0.6	—	μs			
			1 MHz mode ⁽¹⁾	0.25	—	μs			
IS31	THD:STA	Start Condition Hold Time	100 kHz mode	4.0	—	μs	After this period, the first		
			400 kHz mode	0.6	—	μs	clock pulse is generated		
			1 MHz mode ⁽¹⁾	0.25	—	μs			
IS33	TSU:STO	Stop Condition	100 kHz mode	4.7	—	μs	_		
		Setup Time	400 kHz mode	0.6	—	μs			
			1 MHz mode ⁽¹⁾	0.6	—	μs			
IS34	THD:STO	Stop Condition	100 kHz mode	4	—	μs			
		Hold Time	400 kHz mode	0.6	—	μs			
			1 MHz mode ⁽¹⁾	0.25		μs			
IS40	TAA:SCL	Output Valid from	100 kHz mode	0	3500	ns			
		Clock	400 kHz mode	0	1000	ns			
0.45	-		1 MHz mode ⁽¹⁾	0	350	ns			
IS45	TBF:SDA	Bus Free Time	100 kHz mode	4.7		μs	Time the bus must be free		
			400 kHz mode	1.3		μs	before a new transmission can start		
			1 MHz mode ⁽¹⁾	0.5	—	μs			
IS50	Св	Bus Capacitive Lo		400	pF				
IS51	TPGD	Pulse Gobbler Del m Pin Capacitance	•	65	390	ns	(Note 2)		

TABLE 30-48: I2Cx BUS DATA TIMING REQUIREMENTS (SLAVE MODE)

Note 1: Maximum Pin Capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

- 2: Typical value for this parameter is 130 ns.
- **3:** These parameters are characterized but not tested in manufacturing.

FIGURE 30-31: CANx MODULE I/O TIMING CHARACTERISTICS

CxTX Pin (output)	Old Value		New Value	
CxRX Pin	_	CA10 CA11	Ţ.	
		CA20		

TABLE 30-49: CANX MODULE I/O TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$				
Param No.	Symbol	Characteristic ⁽¹⁾	Min.	Тур. ⁽²⁾	Max.	Units	Conditions
CA10	TIOF	Port Output Fall Time		_	_	ns	See Parameter DO32
CA11	TIOR	Port Output Rise Time	—	—	—	ns	See Parameter DO31
CA20	TCWF	Pulse Width to Trigger CAN Wake-up Filter	120	—		ns	

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

FIGURE 30-32: UARTX MODULE I/O TIMING CHARACTERISTICS

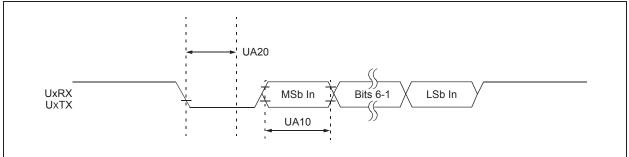


TABLE 30-50: UARTX MODULE I/O TIMING REQUIREMENTS

				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}C \le TA \le +125^{\circ}C$					
Param No.	Symbol Characteristic ¹			Тур. ⁽²⁾	Max.	Units	Conditions		
UA10	TUABAUD	UARTx Baud Time	66.67	—	_	ns			
UA11	FBAUD	UARTx Baud Frequency	_		15	Mbps			
UA20 TCWF Start Bit Pulse Wid UARTx Wake-up		Start Bit Pulse Width to Trigger UARTx Wake-up	500	—		ns			

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 30-51: ANALOG CURRENT SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V(unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +125^{\circ}C$				
Param No. Symbol Characteristic ⁽¹⁾		Min. Typ. ⁽²⁾ Max			Units	Conditions	
AVD01	IDD	Analog Modules Current Consumption	_	9			Characterized data with the following modules enabled: APLL, 5 ADC Cores, 2 PGAs and 4 Analog Comparators

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 30-52: ADC MODULE SPECIFICATIONS

АС СНА		STICS	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)(unless otherwise stated)($^{(5)}$ Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for Extended						
Param No.	Symbol	Characteristics	Min.	Typical	-40°C ≤ IA Max.	\leq +125	Conditions		
	•	·	Device	Supply			•		
AD01	AVDD	Module VDD Supply	Greater of: VDD – 0.3 or 3.0	_	Lesser of: VDD + 0.3 or 3.6	V	Within 300 mV of VDD at all times, including device power-up		
AD02	AVss	Module Vss Supply	Vss	_	Vss + 0.3	V			
		•	Referenc	e Inputs			•		
AD06	Vrefl	Reference Voltage Low	_	AVss	—	V	(Note 1)		
AD07	Vref	Absolute Reference Voltage (VREFH – VREFL)	2.7	_	AVDD	V	(Note 3)		
AD08	IREF	Reference Input Current	_	5	10	μA	ADC operating or in standby		
			Analog	g Input					
AD12	VINH-VINL	Full-Scale Input Span	AVss	_	AVdd	V			
AD14	Vin	Absolute Input Voltage	AVss - 0.3	—	AVDD + 0.3	V			
AD17	Rin	Recommended Impedance of Analog Voltage Source	_	100	—	Ω	For minimum sampling time (Note 1)		
AD66	Vbg	Internal Voltage Reference Source	—	1.2	—	V			
		ADC Ac	curacy: Pseu	udodiffere	ntial Input		•		
AD20a	Nr	Resolution		12		bits			
AD21a	INL	Integral Nonlinearity	> -3	—	< 3	LSb	AVss = 0V, AVDD = 3.3V		
AD22a	DNL	Differential Nonlinearity	> -1	_	< 1	LSb	AVss = 0V, AVDD = 3.3V (Note 2)		
AD23a	Gerr	Gain Error (Dedicated Core)	> 0	8	< 15	LSb	AVss = 0V, AVDD = 3.3V		
		Gain Error (Shared Core)	> 5	15	< 22	LSb			
AD24a	Eoff	Offset Error (Dedicated Core)	> 0	5	< 10	LSb	AVss = 0V, AVDD = 3.3V		
		Offset Error (Shared Core)	> 2	8	< 13	LSb			
AD25a	_	Monotonicity		_	_	_	Guaranteed		

Note 1: These parameters are not characterized or tested in manufacturing.

2: No missing codes, limits based on characterization results.

3: These parameters are characterized but not tested in manufacturing.

4: Characterized with a 15 kHz sine wave.

5: The ADC module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is ensured, but not characterized.

AC CHARACTERISTICS			(unless oth	erwise stat	pnditions: 3.0V to 3.6V ed) ⁽⁵⁾ $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for Extended			
Param No.	Symbol	Characteristics	Min.	Typical	Max.	Units	Conditions	
		ADC	Accuracy: S	ingle-Ende	d Input	•	·	
AD20b Nr Resolution				12		bits		
AD21b	INL	Integral Nonlinearity	> 5	> 5 — < 5			AVss = 0V, AVDD = 3.3V	
AD22b	DNL	Differential Nonlinearity	> -1 — < 1			LSb	AVss = 0V, AVDD = 3.3V (Note 2)	
AD23b	Gerr	Gain Error (Dedicated Core)	> 0	8	< 15	LSb	AVss = 0V, AVdd = 3.3V	
		Gain Error (Shared Core)	> 5	15	< 22	LSb		
AD24b	Eoff	Offset Error (Dedicated Core)	> 2	9	< 15	LSb	AVss = 0V, AVDD = 3.3V	
		Offset Error (Shared Core)	> 5	17	< 22	LSb		
AD25b	—	Monotonicity	_	_	_	_	Guaranteed	
	•		Dynamic P	erformanc	e			
AD31b	SINAD	Signal-to-Noise and Distortion	63	_	> 65	dB	(Notes 3, 4)	
AD34b	ENOB	Effective Number of Bits	10.3	_	_	bits	(Notes 3, 4)	

TABLE 30-52: ADC MODULE SPECIFICATIONS (CONTINUED)

Note 1: These parameters are not characterized or tested in manufacturing.

2: No missing codes, limits based on characterization results.

3: These parameters are characterized but not tested in manufacturing.

4: Characterized with a 15 kHz sine wave.

5: The ADC module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is ensured, but not characterized.

АС СН	ARACTE	$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)}^{(2)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristics	Min.	Typ. ⁽¹⁾	Max.	Units	Conditions
				Clo	ck Para	meters	
AD50	Tad	ADC Clock Period	14.28	_	_	ns	
		•		Thr	oughpu	ut Rate	
AD51	Ftp	SH0-SH3	—	_	3.25	Msps	70 MHz ADC clock, 12 bits, no pending
		SH4	_	_	3.25	Msps	conversion at time of trigger

TABLE 30-53: ANALOG-TO-DIGITAL CONVERSION TIMING REQUIREMENTS

Note 1: These parameters are characterized but not tested in manufacturing.

2: The ADC module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is ensured, but not characterized.

TABLE 30-54: HIGH-SPEED ANALOG COMPARATOR MODULE SPECIFICATIONS

AC/DC	CHARAC	TERISTICS	(unless	otherwis	e stated) (ature -40	2))°C ≤ T/	3.0V to 3.6V $A \le +85^{\circ}C$ for Industrial $A \le +125^{\circ}C$ for Extended		
Param No.	Symbol	Characteristic	Min. Typ. Max. Units Comments						
CM10	VIOFF	Input Offset Voltage	-35	±5	35	mV			
CM11	VICM	Input Common-Mode Voltage Range ⁽¹⁾	0	_	AVdd	V			
CM13	CMRR	Common-Mode Rejection Ratio	60	_		dB			
CM14	TRESP	Large Signal Response	—	15	_	ns	V+ input step of 100 mV while V- input is held at AVDD/2. Delay measured from analog input pin to PWMx output pin.		
CM15	VHYST	Input Hysteresis	5 10 20 mV Depends on HYSSEL<1:0>						
CM16	TON	Comparator Enabled to Valid Output	_	_	1	μs			

Note 1: These parameters are for design guidance only and are not tested in manufacturing.

2: The comparator module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

TABLE 30-55: DACx MODULE SPECIFICATIONS

AC/DC	AC/DC CHARACTERISTICS			otherw	r ise stated erature -) ⁽²⁾ 40°C ≤ T⁄	3.0V to 3.6V $A \le +85^{\circ}C$ for Industrial $A \le +125^{\circ}C$ for Extended		
Param No.	Symbol	Characteristic	Min. Typ. Max. Units Comments						
DA01	EXTREF	External Voltage Reference ⁽¹⁾	1	—	AVdd	V			
DA02	CVRES	Resolution		12		bits			
DA03	INL	Integral Nonlinearity Error	-16	-12	0	LSB			
DA04	DNL	Differential Nonlinearity Error	-1.8	±1	1.8	LSB			
DA05	EOFF	Offset Error	-8	3	15	LSB			
DA06	EG	Gain Error	-1.2	-0.5	0	%			
DA07	TSET	Settling Time ⁽¹⁾	—	700	_	ns	Output with 2% of desired output voltage with a 10-90% or 90-10% step		

Note 1: Parameters are for design guidance only and are not tested in manufacturing.

2: The DACx module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

DC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)}^{(1)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Comments		
DA11	RLOAD	Resistive Output Load Impedance	10k		_	Ohm			
DA11a	CLOAD	Output Load Capacitance	_		35	pF	Including output pin capacitance		
DA12	Ιουτ	Output Current Drive Strength		300	—	μA	Sink and source		
DA13	VRANGE	Output Drive Voltage Range at Current Drive of 300 µA	AVss + 250 mV		AVdd - 900 mV	V			
DA14	VLRANGE	Output Drive Voltage Range at Reduced Current Drive of 50 μΑ	AVss + 50 mV	—	AVDD – 500 mV	V			
DA15	IDD	Current Consumed when Module is Enabled	—		1.3 x IOUT	μA	Module will always consume this current, even if no load is connected to the output		
DA30	VOFFSET	Input Offset Voltage		±5	—	mV			

TABLE 30-56: DACX OUTPUT (DACOUTX PIN) SPECIFICATIONS

Note 1: The DACx module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

TABLE 30-57: PGAx MODULE SPECIFICATIONS

AC/DC	CHARAC	TERISTICS		$ \begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)}^{(1)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array} $					
Param No.	Symbol	Characteris	tic	Min.	Тур.	Max.	Units	Comments	
PA01	Vin	Input Voltage Range		AVss - 0.3	—	AVDD + 0.3	V		
PA02	Vсм	Common-Mode Inp Voltage Range	ut	AVss	—	AVDD - 1.6	V		
PA03	Vos	Input Offset Voltage	9	-10	—	10	mV		
PA04	Vos	Input Offset Voltage with Temperature	e Drift	—	±15	—	µV/∘C		
PA05	Rin+	Input Impedance of Positive Input		—	>1M 7 pF	—	Ω pF		
PA06	Rin-	Input Impedance of Negative Input		—	10k 7 pF	—	Ω pF		
PA07	Gerr	Gain Error		-2	—	2	%	Gain = 4x, 8x	
				-3	—	3	%	Gain = 16x	
				-4	—	4	%	Gain = 32x, 64x	
PA08	Lerr	Gain Nonlinearity E	rror	—	—	0.5	%	% of full scale, Gain = 16x	
PA09	IDD	Current Consumption	on	—	2.0	—	mA	Module is enabled with a 2-volt P-P output voltage swing	
PA10a	BW	Small Signal	G = 4x	_	10	—	MHz		
PA10b		Bandwidth (-3 dB)	G = 8x	_	5	—	MHz		
PA10c			G = 16x	—	2.5	—	MHz		
PA10d			G = 32x	_	1.25	—	MHz		
PA10e			G = 64x	—	0.625	—	MHz		
PA11	OST	Output Settling Time to 1% of Final Value		—	0.4	—	μs	Gain = 16x, 100 mV input step change	
PA12	SR	Output Slew Rate		_	40	—	V/µs	Gain = 16x	
PA13	TGSEL	Gain Selection Tim	e		1	—	μs		
PA14	TON	Module Turn On/Set	ting Time	_	_	10	μs		

Note 1: The PGAx module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

TABLE 30-58: CONSTANT-CURRENT SOURCE SPECIFICATIONS

DC CHARACTERISTICS				(unles	$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)}^{(1)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$			
Param No.	Symbol	Characteristic	Min.	Typ. Max. Units Conditions				
CC01	Idd	Current Consumption	_	30	—	μA		
CC02	IREG	Regulation of Current with Voltage On		±3 — %				
CC03								

Note 1: The constant-current source module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

TABLE 30-59: DMA MODULE TIMING REQUIREMENTS

		$\begin{tabular}{lllllllllllllllllllllllllllllllllll$						
Param No.	Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Conditions		
DM1	DMA Byte/Word Transfer Latency	1 Tcy ⁽²⁾ — — ns						

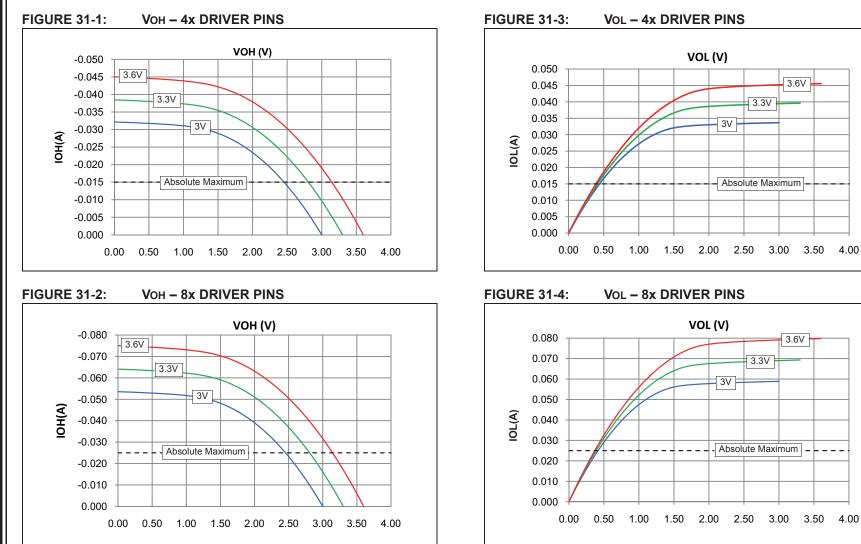
Note 1: These parameters are characterized, but not tested in manufacturing.

2: Because DMA transfers use the CPU data bus, this time is dependent on other functions on the bus.

NOTES:

DC AND AC DEVICE CHARACTERISTICS GRAPHS 31.0

The graphs provided following this note are a statistical summary based on a limited number of samples and are provided for design guidance purposes Note: only. The performance characteristics listed herein are not tested or guaranteed. In some graphs, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore, outside the warranted range.



4.00

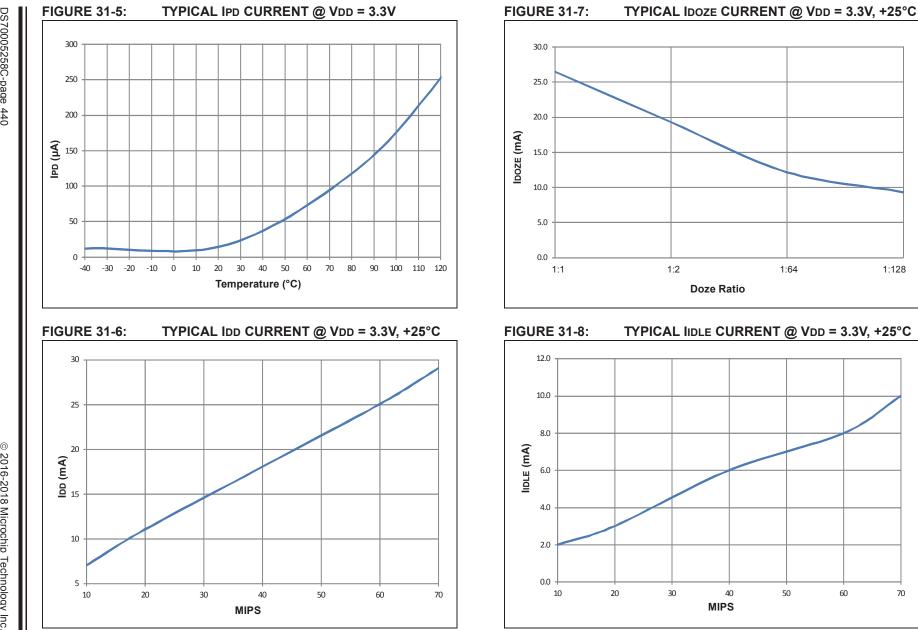
DS70005258C-page 439



1:128

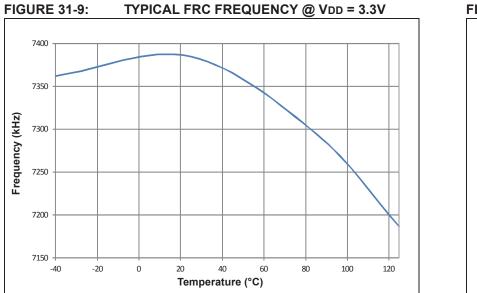
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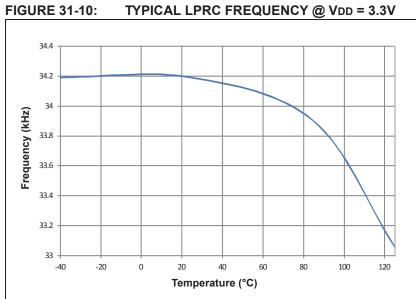
70



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NOTES:

32.0 PACKAGING INFORMATION

32.1 Package Marking Information

28-Lead SOIC (7.50 mm)



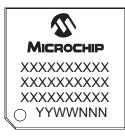
28-Lead UQFN (6x6x0.55 mm)



28-Lead QFN-S (6x6x0.9 mm)



44-Lead TQFP (10x10x1 mm)



Example



Example



Example



Example



Legen	d: XXX Y YY WW NNN	Customer-specific information Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code
Note:	be carried	nt the full Microchip part number cannot be marked on one line, it will d over to the next line, thus limiting the number of available s for customer-specific information.

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32.1 Package Marking Information (Continued)

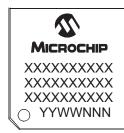
44-Lead QFN (8x8 mm)



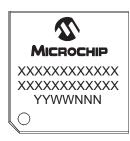
48-Lead TQFP (7x7x1.0 mm)



64-Lead TQFP (10x10x1 mm)



80-Lead TQFP (12x12x1 mm)





Example



Example



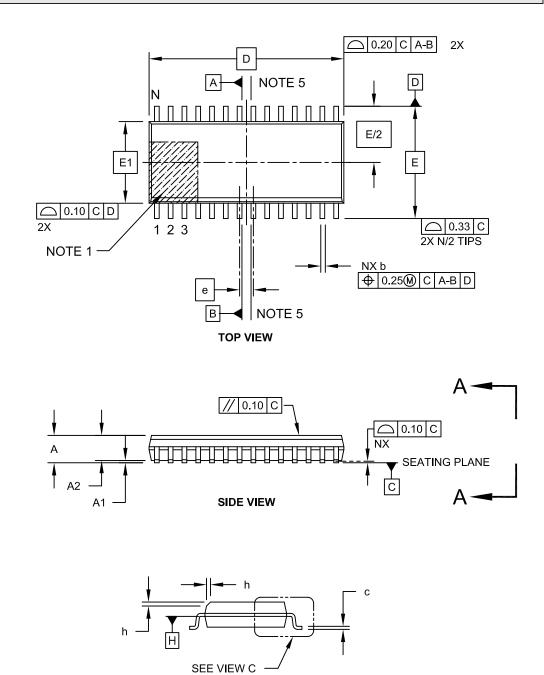
Example



32.2 Package Details

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

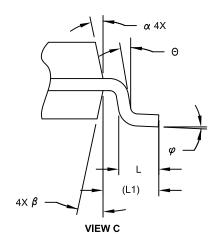


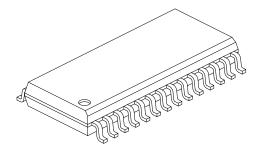
VIEW A-A

Microchip Technology Drawing C04-052C Sheet 1 of 2

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging





	Units	N	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX		
Number of Pins	N		28			
Pitch	е		1.27 BSC			
Overall Height	Α	-	-	2.65		
Molded Package Thickness	A2	2.05	-	-		
Standoff §	A1	0.10	-	0.30		
Overall Width	E		10.30 BSC			
Molded Package Width	E1	7.50 BSC				
Overall Length	D	17.90 BSC				
Chamfer (Optional)	h	0.25	-	0.75		
Foot Length	L	0.40	-	1.27		
Footprint	L1		1.40 REF			
Lead Angle	Θ	0°	-	-		
Foot Angle	φ	0°	-	8°		
Lead Thickness	Lead Thickness C			0.33		
Lead Width	b	0.31 - 0.51				
Mold Draft Angle Top	α	5° - 15°				
Mold Draft Angle Bottom	β	5°	-	15°		

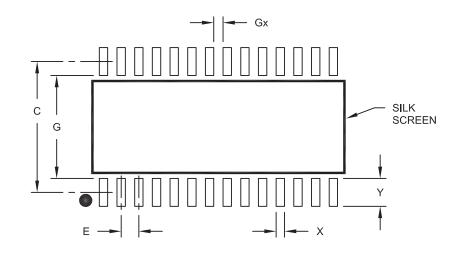
Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.
- 5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	MILLIMETERS				
Dimension	Dimension Limits			MAX	
Contact Pitch	E	1.27 BSC			
Contact Pad Spacing	С		9.40		
Contact Pad Width (X28)	Х			0.60	
Contact Pad Length (X28)	Y			2.00	
Distance Between Pads	Gx	0.67			
Distance Between Pads	G	7.40			

Notes:

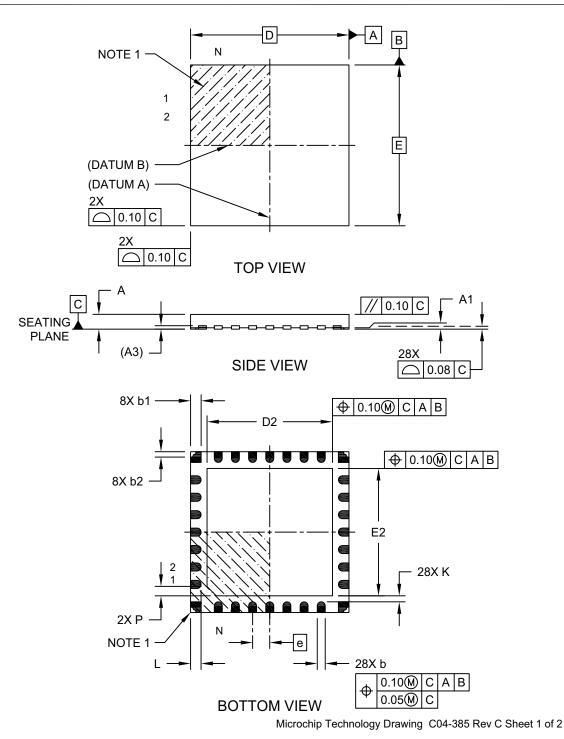
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A

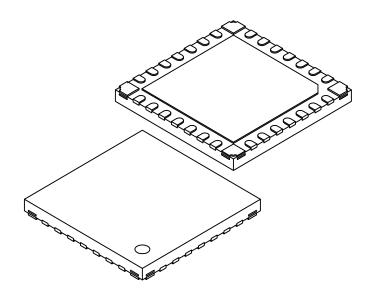
28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (2N) - 6x6x0.55 mm Body [UQFN] With 4.65x4.65 mm Exposed Pad and Corner Anchors

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (2N) - 6x6x0.55 mm Body [UQFN] With 4.65x4.65 mm Exposed Pad and Corner Anchors

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	Ν	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX		
Number of Terminals	N		28			
Pitch	е		0.65 BSC			
Overall Height	A	0.45	0.50	0.55		
Standoff	A1	0.00	0.02	0.05		
Terminal Thickness	A3		0.127 REF			
Overall Width	E		6.00 BSC			
Exposed Pad Width	E2	4.55	4.65	4.75		
Overall Length	D		6.00 BSC			
Exposed Pad Length	D2	4.55	4.65	4.75		
Exposed Pad Corner Chamfer	Р	-	0.35	-		
Terminal Width	b	0.25	0.30	0.35		
Corner Anchor Pad	b1	0.35	0.40	0.43		
Corner Pad, Metal Free Zone	b2	0.15	0.20	0.25		
Terminal Length	Terminal Length L			0.50		
Terminal-to-Exposed-Pad	К	0.20	-	-		

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M

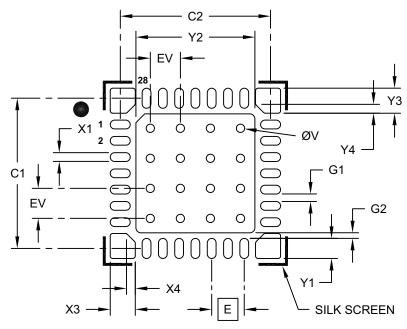
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-385 Rev C Sheet 2 of 2

28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (2N) - 6x6x0.55 mm Body [UQFN] With 4.65x4.65 mm Exposed Pad and Corner Anchors

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension	Dimension Limits		NOM	MAX
Contact Pitch	E		0.65 BSC	
Optional Center Pad Width	X2			4.75
Optional Center Pad Length	Y2			4.75
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X28)	X1			0.35
Contact Pad Length (X28)	Y1			0.80
Corner Anchor (X4)	X3			1.00
Corner Anchor (X4)	Y3			1.00
Corner Anchor Chamfer (X4)	X4			0.35
Corner Anchor Chamfer (X4)	Y4			0.35
Contact Pad to Pad (X28)	G1	0.20		
Contact Pad to Center Pad (X28)	G2	0.20		
Thermal Via Diameter	V		0.33	
Thermal Via Pitch	EV		1.20	

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

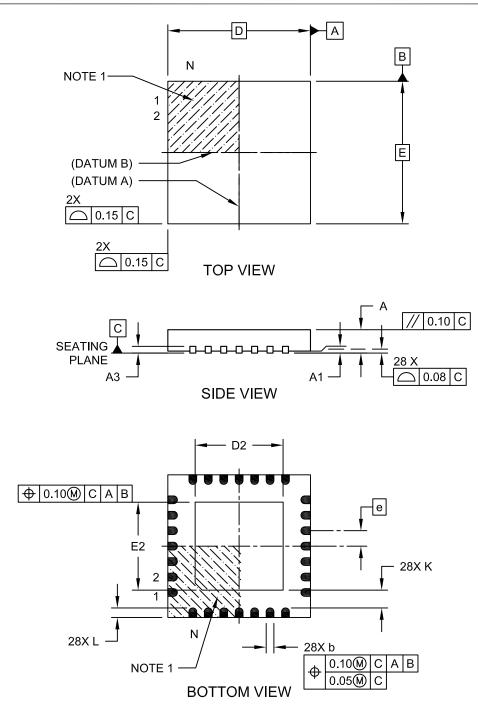
2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2385B

Note: Corner anchor pads are not connected internally and are designed as mechanical features when the package is soldered to the PCB.

28-Lead Plastic Quad Flat, No Lead Package (MM) - 6x6x0.9mm Body [QFN-S] With 0.40 mm Terminal Length

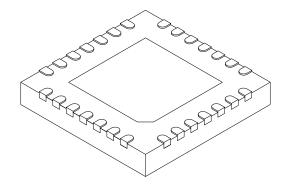
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-124C Sheet 1 of 2

28-Lead Plastic Quad Flat, No Lead Package (MM) - 6x6x0.9mm Body [QFN-S] With 0.40 mm Terminal Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimensior	ו Limits	MIN	NOM	MAX
Number of Pins	Ν		28	
Pitch	е		0.65 BSC	
Overall Height	Α	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3	0.20 REF		
Overall Width	Е		6.00 BSC	
Exposed Pad Width	E2	3.65	3.70	4.70
Overall Length	D		6.00 BSC	
Exposed Pad Length	D2	3.65	3.70	4.70
Terminal Width	b	0.23	0.30	0.35
Terminal Length	L	0.30	0.40	0.50
Terminal-to-Exposed Pad	К	0.20	-	-

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated

3. Dimensioning and tolerancing per ASME Y14.5M

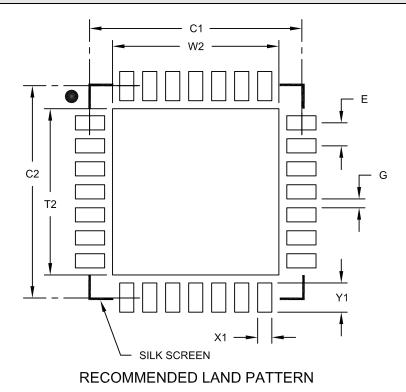
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-124C Sheet 2 of 2

28-Lead Plastic Quad Flat, No Lead Package (MM) – 6x6x0.9 mm Body [QFN-S] with 0.40 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Contact Pitch	E				
Optional Center Pad Width	W2			4.70	
Optional Center Pad Length	T2			4.70	
Contact Pad Spacing	C1		6.00		
Contact Pad Spacing	C2		6.00		
Contact Pad Width (X28)	X1			0.40	
Contact Pad Length (X28)	Y1			0.85	
Distance Between Pads	G	0.25			

Notes:

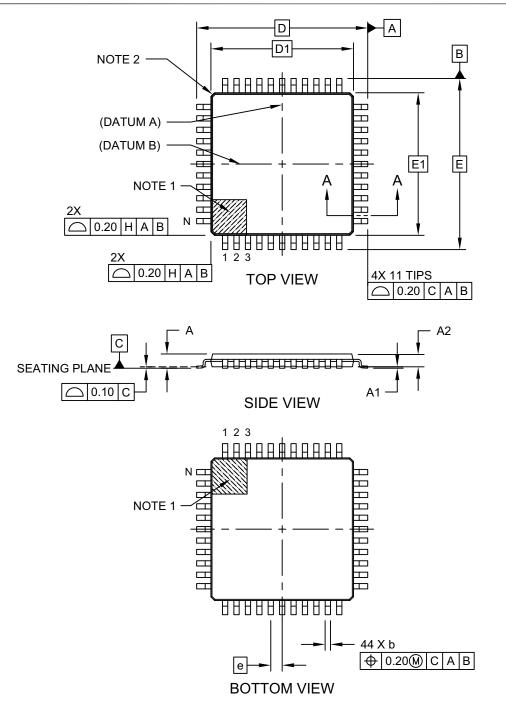
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2124A

44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

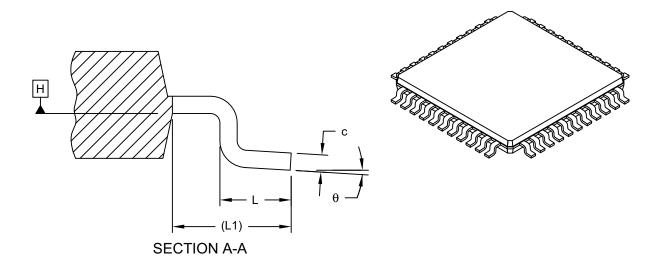
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-076C Sheet 1 of 2

44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	N	IILLIMETER	S	
Dimension Limits		MIN	NOM	MAX
Number of Leads	Ν		44	
Lead Pitch	е		0.80 BSC	
Overall Height	Α	-	-	1.20
Standoff	A1	0.05	-	0.15
Molded Package Thickness	A2	0.95	1.00	1.05
Overall Width	E	12.00 BSC		
Molded Package Width	E1	10.00 BSC		
Overall Length	D		12.00 BSC	
Molded Package Length	D1		10.00 BSC	
Lead Width	b	0.30	0.37	0.45
Lead Thickness	С	0.09	-	0.20
Lead Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	θ	0°	3.5°	7°

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Exact shape of each corner is optional.

3. Dimensioning and tolerancing per ASME Y14.5M

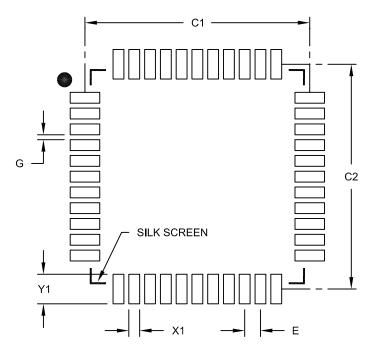
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-076C Sheet 2 of 2

44-Lead Plastic Thin Quad Flatpack (PT) 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

		-			
Units		MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Contact Pitch	E		0.80 BSC		
Contact Pad Spacing	C1		11.40		
Contact Pad Spacing	C2		11.40		
Contact Pad Width (X44)	X1			0.55	
Contact Pad Length (X44)	Y1			1.50	
Distance Between Pads	G	0.25			

Notes:

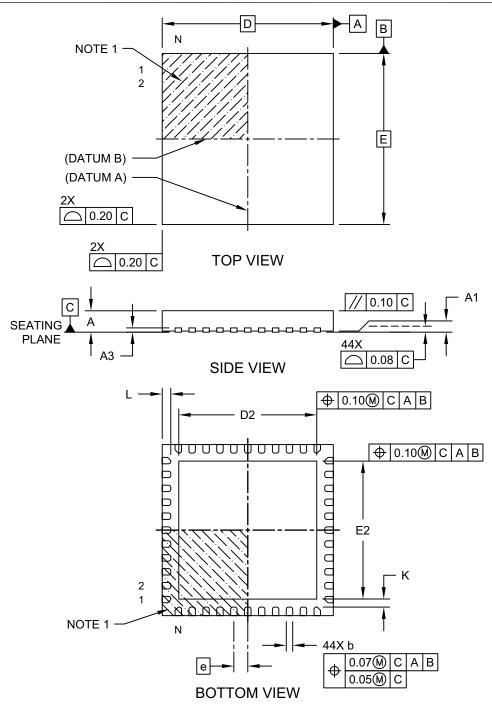
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN or VQFN]

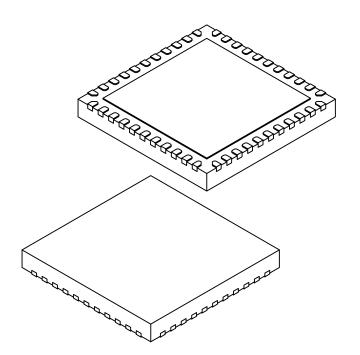
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-103D Sheet 1 of 2

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN or VQFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units			S
Dimension	Dimension Limits		NOM	MAX
Number of Pins	Ν		44	
Pitch	е		0.65 BSC	
Overall Height	А	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3	0.20 REF		
Overall Width	Е	8.00 BSC		
Exposed Pad Width	E2	6.25	6.45	6.60
Overall Length	D		8.00 BSC	
Exposed Pad Length	D2	6.25	6.45	6.60
Terminal Width	b	0.20	0.30	0.35
Terminal Length	L	0.30	0.40	0.50
Terminal-to-Exposed-Pad	К	0.20	-	-

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated

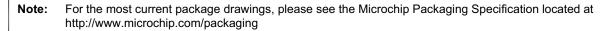
3. Dimensioning and tolerancing per ASME Y14.5M

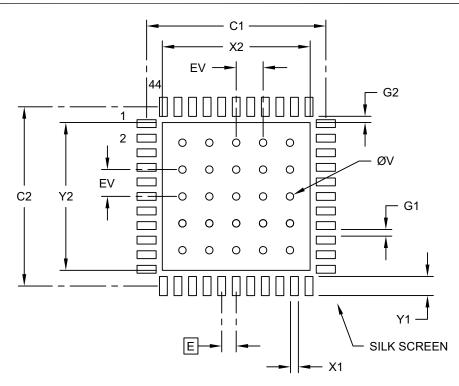
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-103D Sheet 2 of 2

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN or VQFN]





RECOMMENDED LAND PATTERN

	Ν	IILLIMETER	S	
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.65 BSC	
Optional Center Pad Width	X2			6.60
Optional Center Pad Length	Y2			6.60
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.85
Contact Pad to Contact Pad (X40)	G1	0.30		
Contact Pad to Center Pad (X44)	G2	0.28		
Thermal Via Diameter	V		0.33	
Thermal Via Pitch	EV		1.20	

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

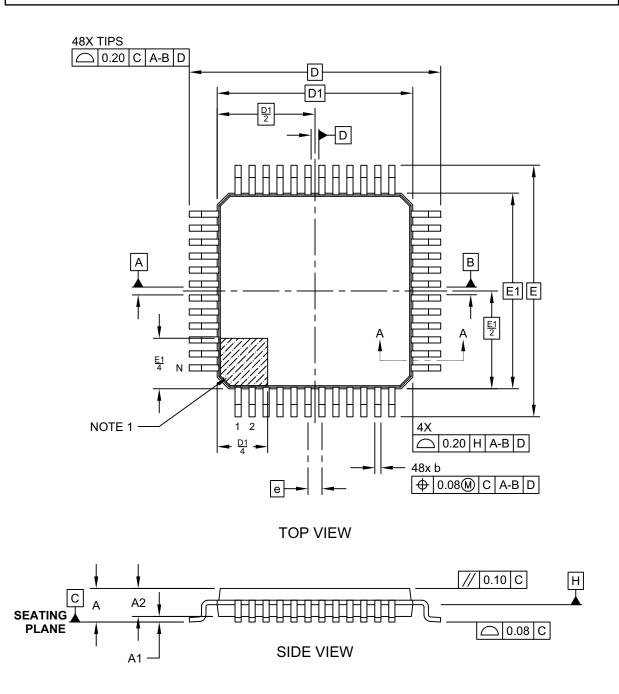
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing No. C04-2103C

48-Lead Thin Quad Flatpack (PT) - 7x7x1.0 mm Body [TQFP]

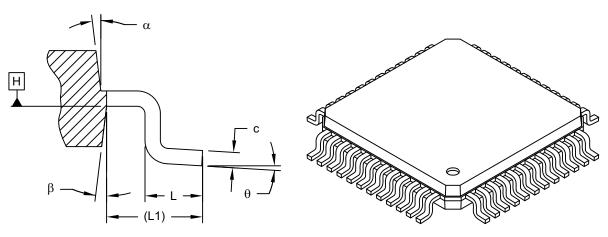
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-300-PT Rev A Sheet 1 of 2

48-Lead Thin Quad Flatpack (PT) - 7x7x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



SECTION A-A

	MILLIMETERS			
Dimension	Dimension Limits		NOM	MAX
Number of Leads	N		48	
Lead Pitch	е		0.50 BSC	
Overall Height	Α	-	-	1.20
Standoff	A1	0.05	-	0.15
Molded Package Thickness	A2	0.95	1.00	1.05
Foot Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	¢	0°	3.5°	7°
Overall Width	E		9.00 BSC	
Overall Length	D		9.00 BSC	
Molded Package Width	E1		7.00 BSC	
Molded Package Length	D1		7.00 BSC	
Lead Thickness	С	0.09	-	0.16
Lead Width	b	0.17	0.22	0.27
Mold Draft Angle Top	α	11°	12°	13°
Mold Draft Angle Bottom	β	11°	12°	13°

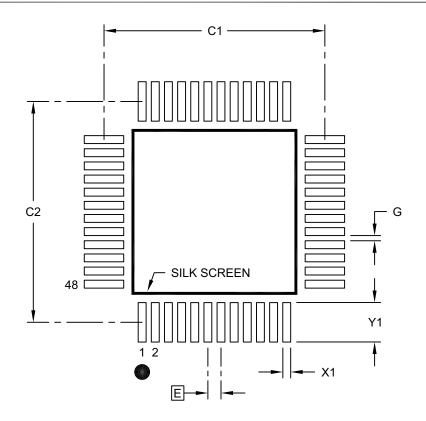
Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Chamfers at corners are optional; size may vary.
- 3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.
- 5. Datums A-B and D to be determined at center line between leads where leads exit plastic body at datum plane

Microchip Technology Drawing C04-300-PT Rev A Sheet 2 of 2

48-Lead Thin Quad Flatpack (PT) - 7x7x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	Units		MILLIMETERS		
Dimensio	Dimension Limits		NOM	MAX	
Contact Pitch	E	0.50 BSC			
Contact Pad Spacing	C1		8.40		
Contact Pad Spacing	C2		8.40		
Contact Pad Width (X48)	X1			0.30	
Contact Pad Length (X48)	Y1			1.50	
Distance Between Pads	G	0.20			

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

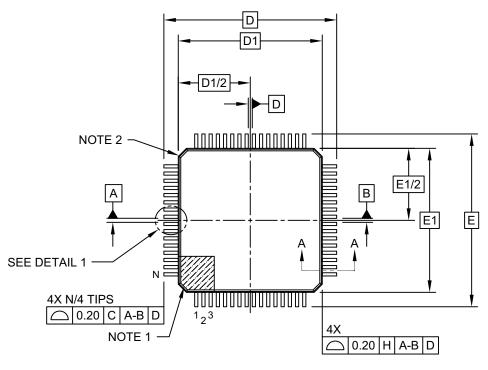
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

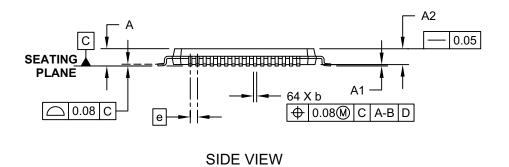
Microchip Technology Drawing C04-2300-PT Rev A

64-Lead Plastic Thin Quad Flatpack (PT)-10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



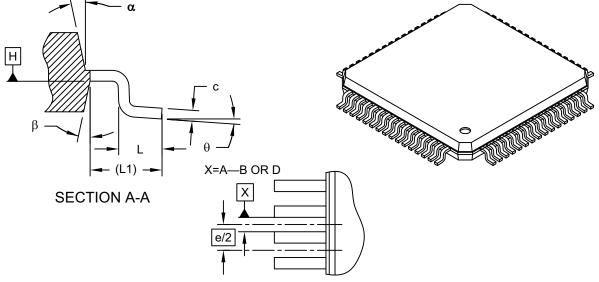




Microchip Technology Drawing C04-085C Sheet 1 of 2

64-Lead Plastic Thin Quad Flatpack (PT)-10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



DETAIL 1

	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX
Number of Leads	Ν		64	
Lead Pitch	е		0.50 BSC	
Overall Height	Α	-	-	1.20
Molded Package Thickness	A2	0.95	1.00	1.05
Standoff	A1	0.05	-	0.15
Foot Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	¢	0° 3.5° 7°		
Overall Width	E		12.00 BSC	
Overall Length	D		12.00 BSC	
Molded Package Width	E1		10.00 BSC	
Molded Package Length	D1		10.00 BSC	
Lead Thickness	С	0.09	-	0.20
Lead Width	b	0.17	0.22	0.27
Mold Draft Angle Top	α	11°	12°	13°
Mold Draft Angle Bottom	β	11°	12°	13°

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Chamfers at corners are optional; size may vary.

3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25mm per side.

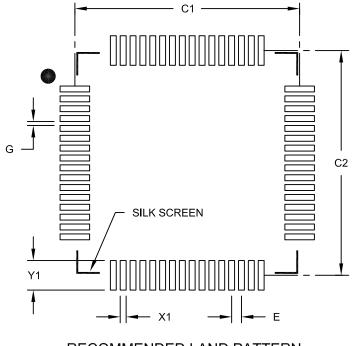
- 4. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-085C Sheet 2 of 2

64-Lead Plastic Thin Quad Flatpack (PT) 10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Contact Pitch	E	0.50 BSC			
Contact Pad Spacing	C1		11.40		
Contact Pad Spacing	C2		11.40		
Contact Pad Width (X64)	X1			0.30	
Contact Pad Length (X64)	Y1			1.50	
Distance Between Pads	G	0.20			

Notes:

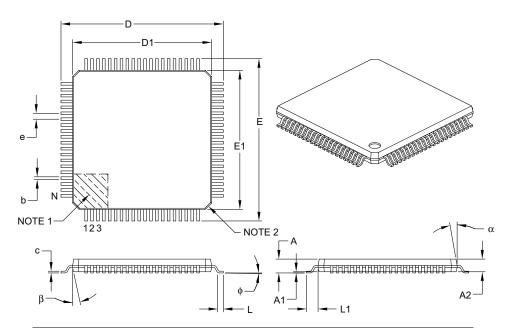
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2085B

80-Lead Plastic Thin Quad Flatpack (PT) – 12x12x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS		
	Dimension Limits	MIN	NOM	MAX	
Number of Leads	N		80		
Lead Pitch	е		0.50 BSC		
Overall Height	А	-	-	1.20	
Molded Package Thickness	A2	0.95	1.00	1.05	
Standoff	A1	0.05	-	0.15	
Foot Length	L	0.45	0.60	0.75	
Footprint	L1	1.00 REF			
Foot Angle	ф	0°	3.5°	7°	
Overall Width	E		14.00 BSC		
Overall Length	D		14.00 BSC		
Molded Package Width	E1		12.00 BSC		
Molded Package Length	D1		12.00 BSC		
Lead Thickness	С	0.09	-	0.20	
Lead Width	b	0.17	0.22	0.27	
Mold Draft Angle Top	α	11°	12°	13°	
Mold Draft Angle Bottom	β	11°	12°	13°	

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Chamfers at corners are optional; size may vary.

3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.

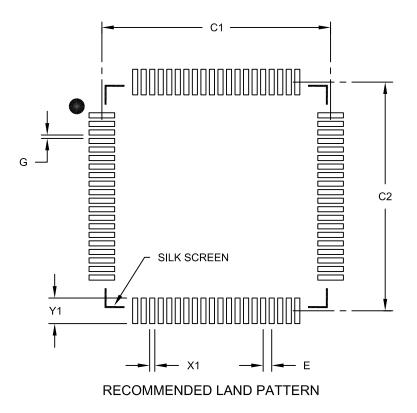
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-092B

80-Lead Plastic Thin Quad Flatpack (PT)-12x12x1mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	Е	0.50 BSC		
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X80)	X1			0.30
Contact Pad Length (X80)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2092B

NOTES:

APPENDIX A: REVISION HISTORY

Revision A (May 2016)

This is the initial version of the document.

Revision B (January 2017)

- Sections:
 - Updates Note 1 in Section 5.0 "Flash Program Memory".
- Tables:
 - Updates the device description table on page 2.
 - Updates Table 1-1, Table 4-2, Table 4-11, Table 7-1, Table 8-1, Table 11-11, Table 11-13, Table 17-1, Table 30-3, Table 30-4, Table 30-6, Table 30-7, Table 30-8, Table 30-9, Table 30-10, Table 30-11, Table 30-52, Table 30-54 and Table 30-55.
 - Adds Table 11-6, Table 11-7, Table 11-8, Table 11-9 and Table 11-10.
- Figures:
 - Updates the Pin Function tables in the Pin Diagram figures on pages 5 through 8.
 - Updates Figure 4-1, Figure 17-1, Figure 18-1 and Figure 18-2.
- Registers:
 - Updates Register 3-3, Register 16-5, Register 17-11, Register 18-1 and Register 19-2.
 - Adds Register 11-1, Register 11-2, Register 11-3, Register 11-4, Register 11-5, Register 11-6, Register 11-7 and Register 11-8.

Revision C (October 2018)

- Sections:
 - Adds Note 1 to all "Pin Diagrams".
 - Updates Section 2.5 "ICSP Pins", Section 4.5.2 "Extended X Data Space", Section 8.0 "Direct Memory Access (DMA)", Section 11.7 "I/O Helpful Tips", Section 16.2 "Feature Description", Section 24.1 "Features Overview" and Section 24.3 "Module Applications".
- Tables:
 - Updates Table 1-1, Table 4-9, Table 4-15, Table 8-1, Table 21-1, Table 21-2, Table 21-3, Table 21-4, Table 30-11, Table 30-56 and Table 30-57.
- Registers:
 - Updates Register 3-2, Register 5-1, Register 9-4, Register 9-5, Register 10-1, Register 11-8, Register 14-1, Register 16-1, Register 16-2, Register 16-3, Register 16-4, Register 16-5, Register 16-6, Register 16-7, Register 16-8, Register 16-9, Register 16-10, Register 16-11, Register 16-13, Register 16-14, Register 16-16, Register 16-22, Register 19-1, Register 19-3, Register 21-3, Register 22-1, Register 22-28, Register 22-29, Register 22-30 and Register 26-1.
- · Figures:
 - Updates Figure 16-2, Figure 18-1, Figure 18-2 and Figure 30-30.

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Architecture:	33 = 16-Bit Digital Signal Controller	
Flash Memory Family:	EP = Enhanced Performance	
Product Group:	GS = SMPS Family	
Pin Count:	02 = 28-pin 04 = 44-pin 05 = 48-pin 06 = 64-pin 08 = 80-pin	
Temperature Range:	I = -40° C to $+85^{\circ}$ C (Industrial) E = -40° C to $+125^{\circ}$ C (Extended)	
Package:	ML=Plastic Quad, No Lead Package - (44-pin) 8x8 mm body (QFN)MM=Plastic Quad, No Lead Package - (28-pin) 6x6 mm body (QFN-S)2N=Plastic Quad Flat, No Lead Package - (28-pin) 6x6 mm body (UQFN)PT=Plastic Thin Quad Flatpack - (44-pin) 10x10 mm body (TQFP)PT=Plastic Thin Quad Flatpack - (48-pin) 7x7 mm body (TQFP)PT=Plastic Thin Quad Flatpack - (64-pin) 10x10 mm body (TQFP)PT=Plastic Thin Quad Flatpack - (64-pin) 10x10 mm body (TQFP)PT=Plastic Thin Quad Flatpack - (69-pin) 12x12 mm body (TQFP)SO=Plastic Small Outline, Wide - (28-pin) 7.50 mm body (SOIC)	

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