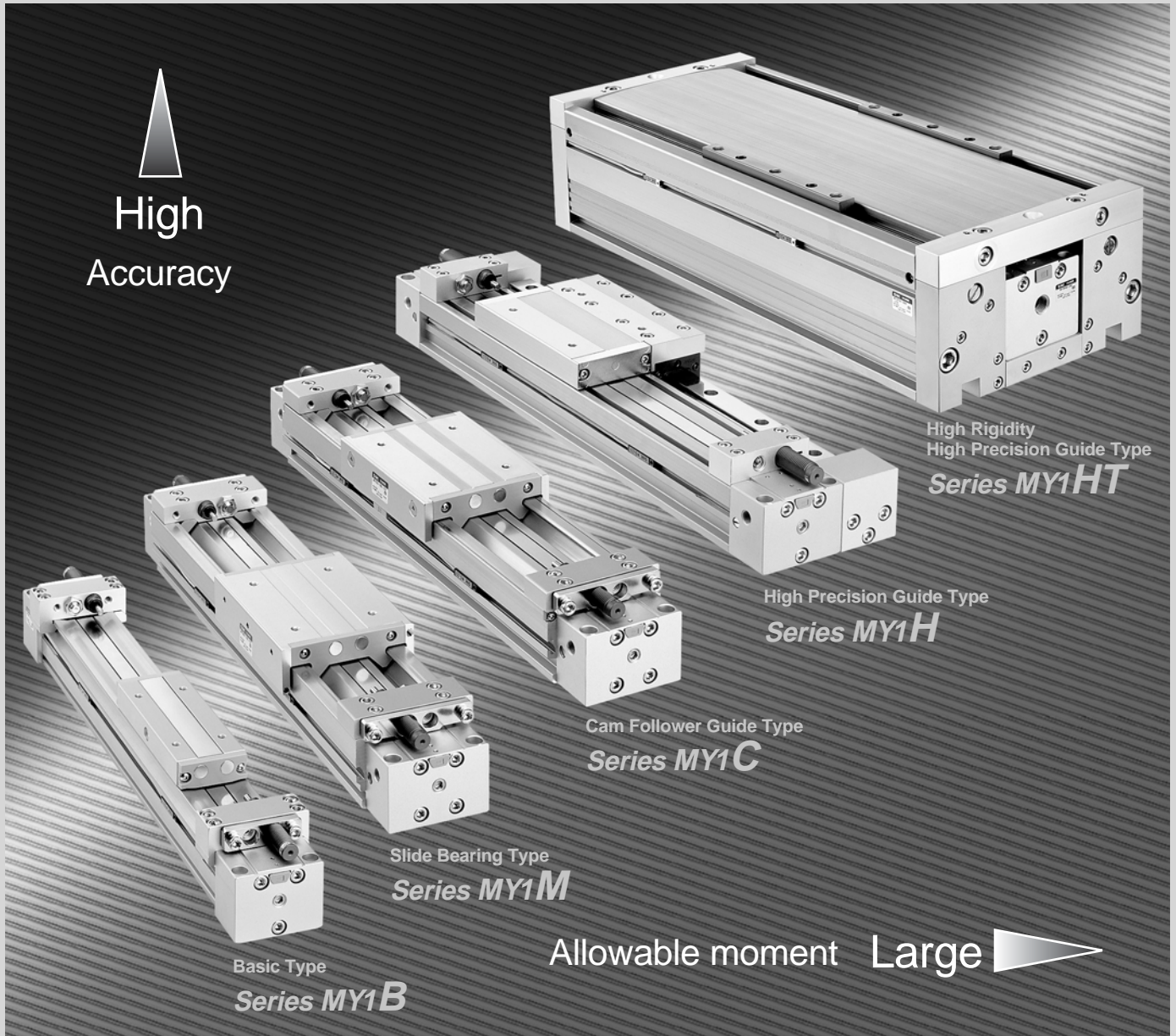


Mechanically Jointed Rodless Cylinder

Series MY1



Five guide models allow a wide range of selections

Mechanically Jointed Rodless Cylinder

Series MY1

Basic Type

Series MY1B

Can be combined with a variety of guides to accommodate conditions. Simple design without guide facilitates space savings.

Basic type



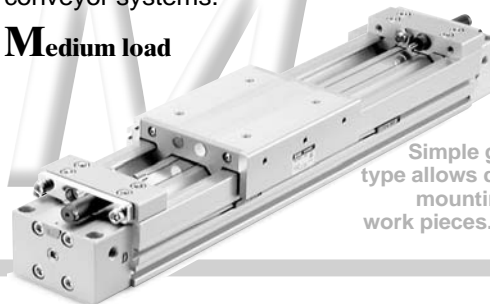
Wide variations from $\phi 10$ to $\phi 100$

Slide Bearing Type

Series MY1M

Integral guide allows use in a wide range of conveyor systems.

Medium load



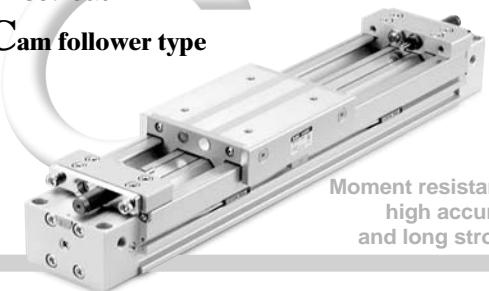
Simple guide type allows direct mounting of work pieces.

Cam Follower Guide type

Series MY1C

Makes smooth operation possible even with an off-set load.

Cam follower type



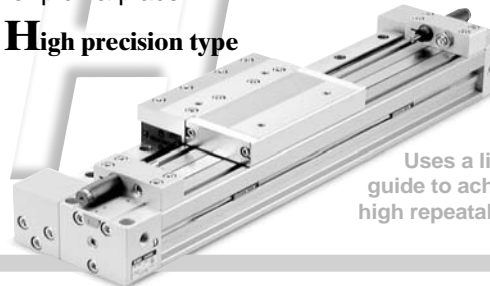
Moment resistance, high accuracy and long strokes

High Precision Guide type

Series MY1H

Small and medium sizes $\phi 10$ to $\phi 40$ are ideal for pick & place.

High precision type



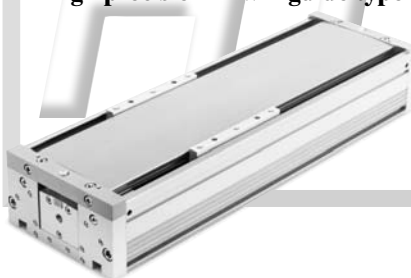
Uses a linear guide to achieve high repeatability

High Rigidity High Precision Guide Type

Series MY1HT

High load, high moment and high precision. Ideal for transfer and pick & place of high load work pieces.

High precision Twin guide type



Higher load work pieces can be accommodated by using two linear guides.

Stroke availability

Strokes are selectable in 1mm units.

Stroke adjusting unit

Stroke Adjusting is possible on one side or on both sides.

- Adjusting bolt
- Low load shock absorber + Adjusting bolt (L unit)
- High load shock absorber + Adjusting bolt (H unit)

Interchangeability

The bodies and work piece mountings are interchangeable between series MY1M and MY1C.

Centralized piping

Piping ports are concentrated on one side.

Side support

Prevents cylinder tube deflection in long strokes.

Minimum size

Basic type MY1B



- Even when equipped with a floating bracket, the height is only 28.5mm.

Series variations

Series	Guide
MY1B	
MY1M	
MY1C	C
MY1H	H
MY1HT	H

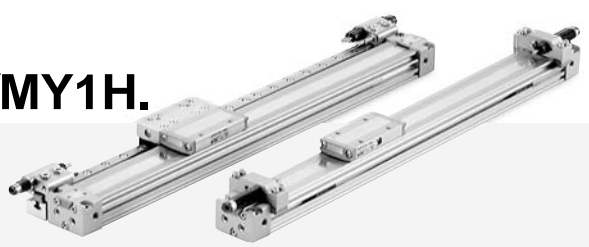


Size of $\phi 10$ introduced to series MY1B/MY1H.


type 310

Height **27** mm

High precision guide type **MY1H10**



- Stroke adjusting unit can be mounted
- The stroke adjusting unit (H unit) does not protrude above the table height.
- Centralized piping type (standard)



Options	Piping type	Bore size (mm)									Air cushion	Stroke adjusting unit	Side support	Floating bracket	End lock	Order made
		10	16	20	25	32	40	50	63	80						
Basic	Centralized piping Standard piping	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
Slide bearing		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
Cam follower guide		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
High precision guide		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
High rigidity High precision guide		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●

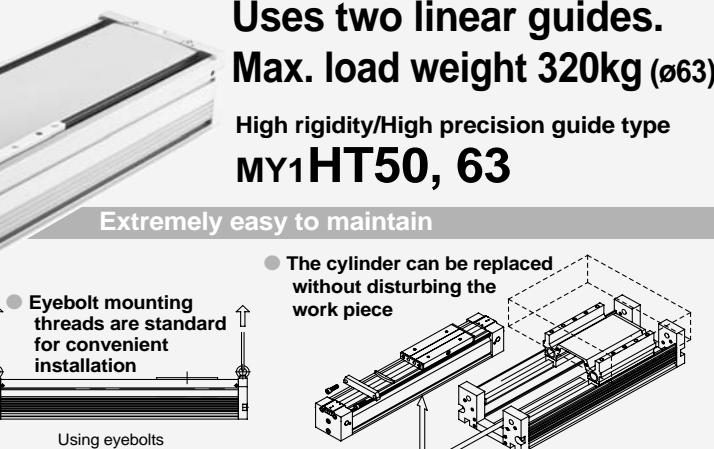
Note 1) $\phi 10$ is available with central piping only. Note 2) $\phi 10$ is available with rubber bumper only.

Uses two linear guides.
Max. load weight 320kg ($\phi 63$)

High rigidity/High precision guide type **MY1HT50, 63**

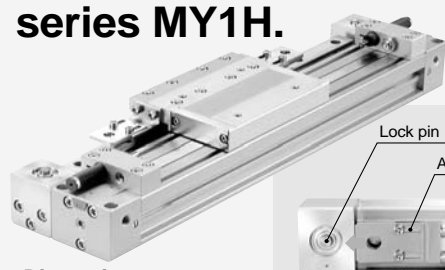
Extremely easy to maintain

- The cylinder can be replaced without disturbing the work piece
- Eyebolt mounting threads are standard for convenient installation



Using eyebolts

End lock type introduced to series MY1H.



Lock pin
Allows fine stroke control

- Dimensions same as standard
- Can be locked on one side or on both sides

Series MY1 Model Selection

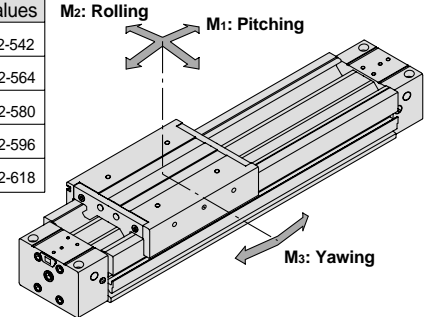
The following are steps for selection of the series MY1 best suited to your application.

Standards for Tentative Model Selection

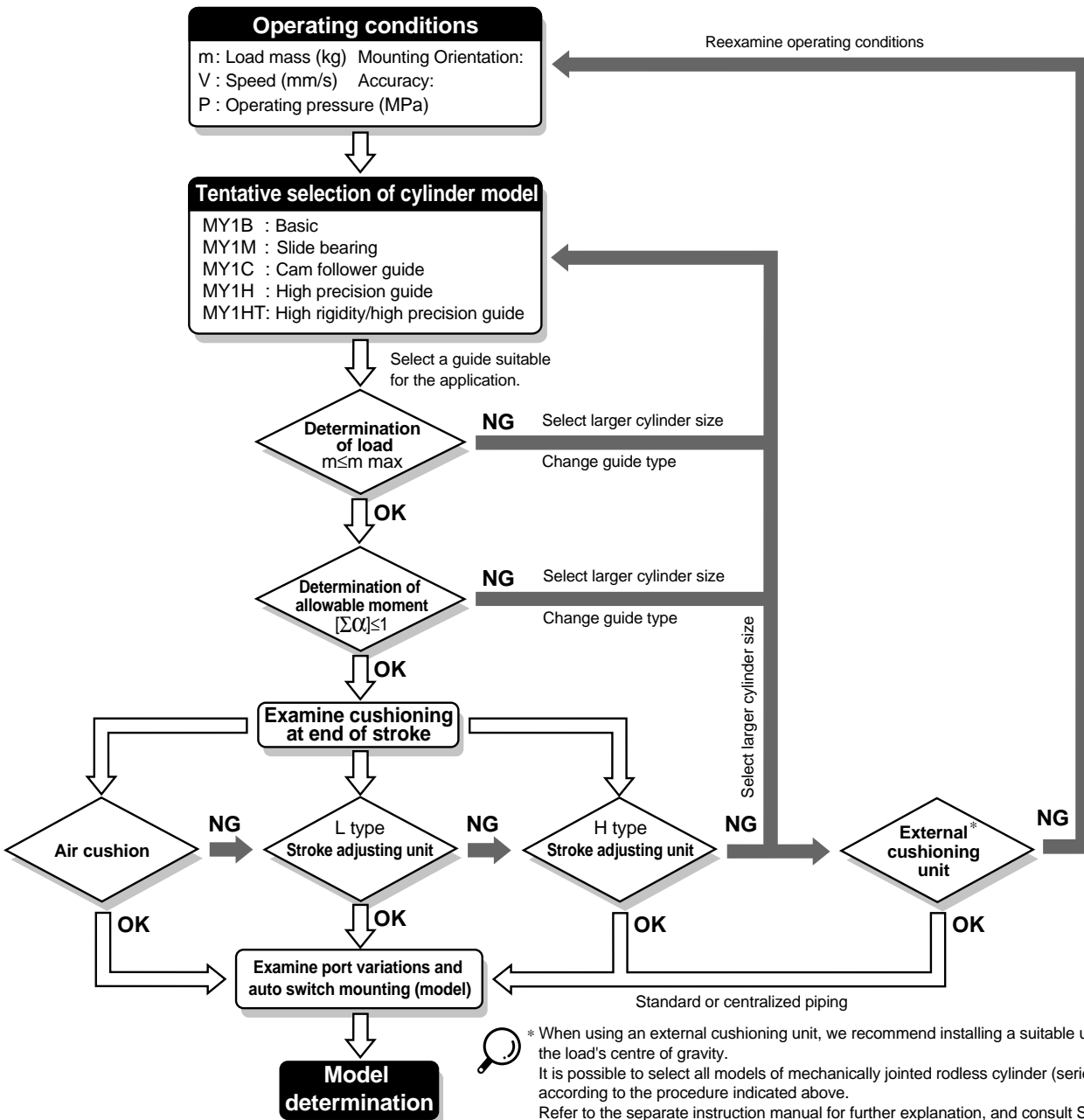
Cylinder model	Guide type	Standards for guide selection	Graphs for related allowable values
MY1B	Basic	Guaranteed accuracy not required, generally combined with separate guide	Refer to page 2-542
MY1M	Slide bearing	Slide table accuracy approx. $\pm 0.12\text{mm}$ <small>Note 2)</small>	Refer to page 2-564
MY1C	Cam follower guide	Slide table accuracy approx. $\pm 0.05\text{mm}$ <small>Note 2)</small>	Refer to page 2-580
MY1H	High precision guide	Slide table accuracy of $\pm 0.05\text{mm}$ or less required <small>Note 2)</small>	Refer to page 2-596
MY1HT	High rigidity/high precision guide	Slide table accuracy of $\pm 0.05\text{mm}$ or less required <small>Note 2)</small>	Refer to page 2-618

Note 1) Use as a standard when making selections regarding guide accuracy. Consult SMC when guaranteed accuracy is required for MY1C/MY1H.

Note 2) Accuracy indicates displacement of the table (at stroke end) when 50% of the allowable moment shown in the catalog is applied. (reference value)



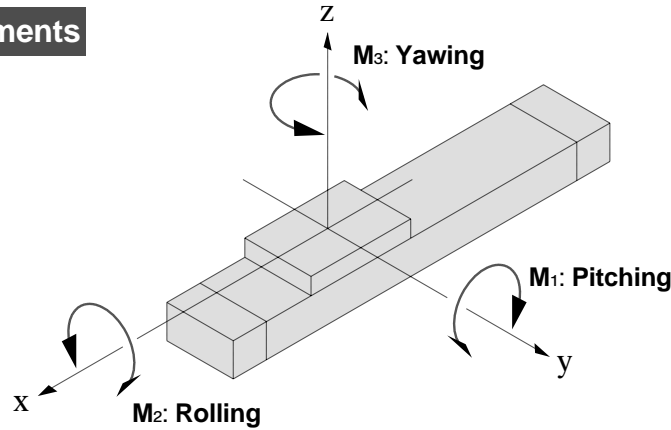
Selection Flow Chart



Types of Moment Applied to Rodless Cylinders

Multiple moments may be generated depending on the mounting orientation, load and position of the centre of gravity.

Coordinates and moments



Static moment

Horizontal mounting

Ceiling mounting

Wall mounting

Vertical mounting

g: Gravitational acceleration

Mounting orientation	Horizontal	Ceiling	Wall	Vertical
Static load m	m_1	m_2	m_3	m_4 (Note)
Static moment	M_1	$m_1 \times g \times X$	$m_2 \times g \times X$	—
	M_2	$m_1 \times g \times Y$	$m_2 \times g \times Y$	$m_3 \times g \times Z$
	M_3	—	—	$m_3 \times g \times X$
				$m_4 \times g \times Z$

Note) m_2 is a mass movable by thrust. Use 0.3 to 0.7 times the thrust (differs depending on the operating speed) as a guide for actual use.

Dynamic moment

Mounting orientation	Horizontal	Ceiling	Wall	Vertical
Dynamic load F_E		$\frac{1.4}{100} \times U_a \times m_n \times g$		
Dynamic moment	M_{1E}	$\frac{1}{3} \times F_E \times Z$		
	M_{2E}	Dynamic moment M_{2E} does not occur.		
	M_{3E}	$\frac{1}{3} \times F_E \times Y$		

Note) Regardless of the mounting orientation, dynamic moment is calculated with the formulae above.

g: Gravitational acceleration, U_a : Average speed

Series MY1 Model Selection

The following are steps for selection of the series MY1 best suited to your application.

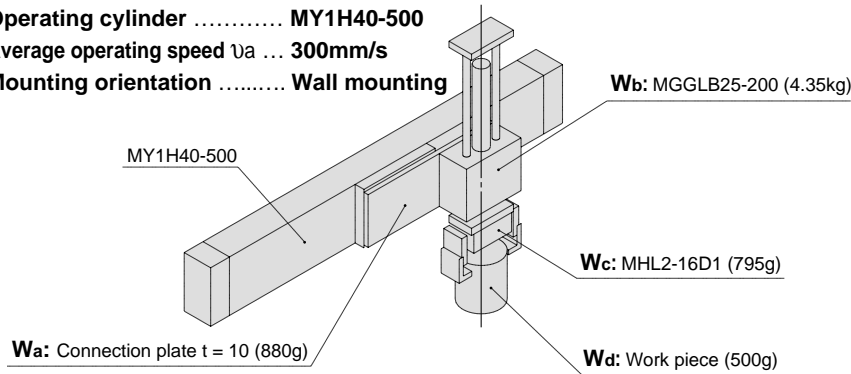
Calculation of Guide Load Factor

1 Operating conditions

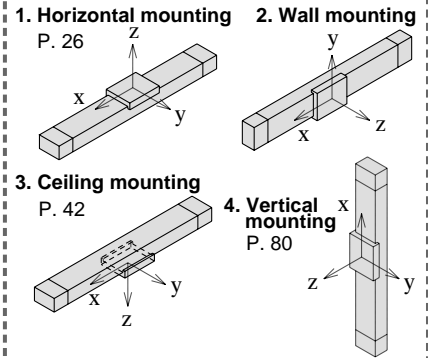
Operating cylinder MY1H40-500

Average operating speed v_a ... 300mm/s

Mounting orientation Wall mounting

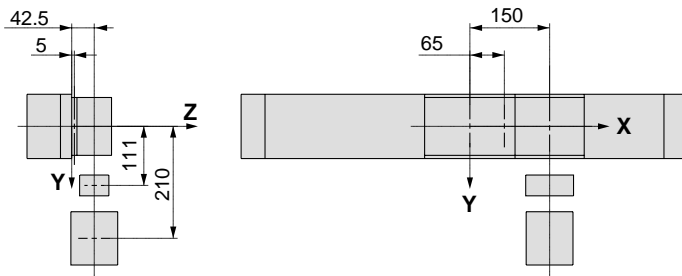


Mounting orientation



Refer to the pages above for actual examples of calculation for each orientation.

2 Load blocking



Work piece mass and centre of gravity

Work piece no. W_n	Mass m_n	Center of gravity		
		X-axis X_n	Y-axis Y_n	Z-axis Z_n
Wa	0.88kg	65mm	0mm	5mm
Wb	4.35kg	150mm	0mm	42.5mm
Wc	0.795kg	150mm	111mm	42.5mm
Wd	0.5kg	150mm	210mm	42.5mm

$n = a, b, c, d$

3 Calculation of composite centre of gravity

$$m_3 = \sum m_n$$

$$= 0.88 + 4.35 + 0.795 + 0.5 = \mathbf{6.525kg}$$

$$X = \frac{1}{m_3} \times \sum (m_n \times X_n)$$

$$= \frac{1}{6.525} (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 0.5 \times 150) = \mathbf{138.5mm}$$

$$Y = \frac{1}{m_3} \times \sum (m_n \times Y_n)$$

$$= \frac{1}{6.525} (0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 0.5 \times 210) = \mathbf{29.6mm}$$

$$Z = \frac{1}{m_3} \times \sum (m_n \times Z_n)$$

$$= \frac{1}{6.525} (0.88 \times 5 + 4.35 \times 42.5 + 0.795 \times 42.5 + 0.5 \times 42.5) = \mathbf{37.4mm}$$

4 Calculation of load factor for static load

m_3 : Mass

m_3 max (from 1 of graph MY1H/ m_3) = 50 (kg)

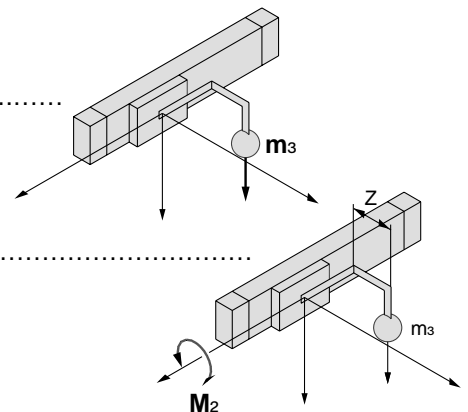
Load factor $\alpha_1 = m_3 / m_3 \text{ max} = 6.525/50 = \mathbf{0.13}$

M_2 : Moment

M_2 max (from 2 of graph MY1H/ M_2) = 50 (N·m)

$M_2 = m_3 \times g \times Z = 6.525 \times 9.8 \times 37.4 \times 10^{-3} = 2.39$ (N·m)

Load factor $\alpha_2 = M_2 / M_2 \text{ max} = 2.39/50 = \mathbf{0.05}$

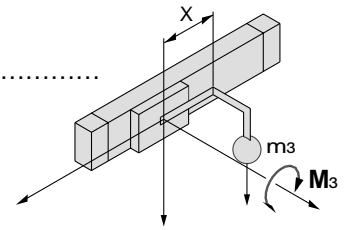


M₃: Moment

M₃ max (from 3 of graph MY1H/M₃) = 38.7 (N·m)

$$M_3 = m_3 \times g \times X = 6.525 \times 9.8 \times 138.5 \times 10^{-3} = 8.86 \text{ (N·m)}$$

$$\text{Load factor } \alpha_3 = M_3 / M_{3 \text{ max}} = 8.86 / 38.7 = \mathbf{0.23}$$



5 Calculation of load factor for dynamic moment

Equivalent load FE at impact

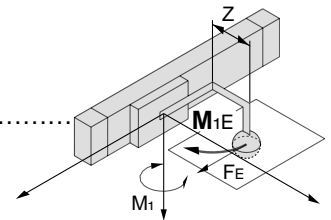
$$F_E = \frac{1.4}{100} \times v_a \times g \times m = \frac{1.4}{100} \times 300 \times 9.8 \times 6.525 = 268.6 \text{ (N)}$$

M_{1E}: Moment

M_{1E} max (from 4 of graph MY1H/M₁ where 1.4v_a = 420mm/s) = 35.9 (N·m)

$$M_{1E} = \frac{1}{3} \times F_E \times Z = \frac{1}{3} \times 268.6 \times 37.4 \times 10^{-3} = 3.35 \text{ (N·m)}$$

$$\text{Load factor } \alpha_4 = M_{1E} / M_{1E \text{ max}} = 3.35 / 35.9 = \mathbf{0.09}$$

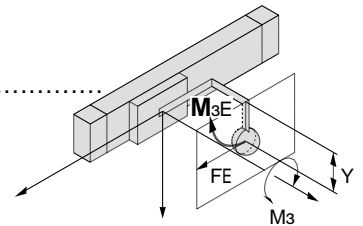


M_{3E}: Moment

M_{3E} max (from 5 of graph MY1H/M₃ where 1.4v_a = 420mm/s) = 27.6 (N·m)

$$M_{3E} = \frac{1}{3} \times F_E \times Y = \frac{1}{3} \times 268.6 \times 29.6 \times 10^{-3} = 2.65 \text{ (N·m)}$$

$$\text{Load factor } \alpha_5 = M_{3E} / M_{3E \text{ max}} = 2.65 / 27.6 = \mathbf{0.10}$$



6 Sum and examination of guide load factors

$$\Sigma \alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 = \mathbf{0.60} \leq 1$$

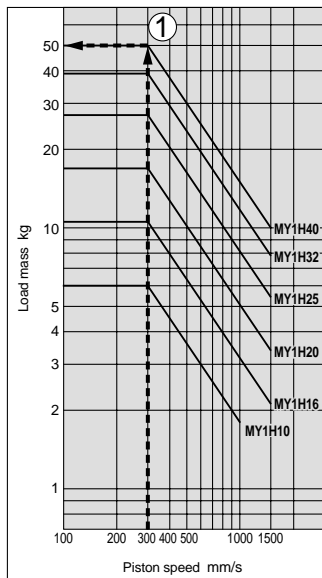
The above calculation is within the allowable value and the selected model can be used.

Select a separate shock absorber.

In an actual calculation, when the sum of guide load factors $\Sigma \alpha$ in the formula above is more than 1, consider decreasing the speed, increasing the bore size, or changing the product series. Also, this calculation can be performed easily with the "SMC Pneumatics CAD System".

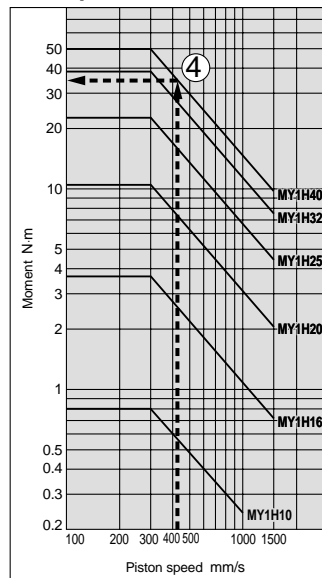
Load mass

MY1H/m₃

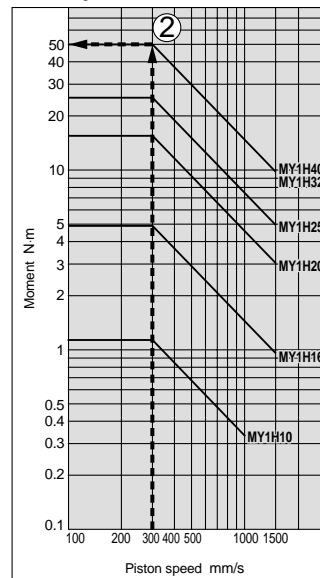


Allowable moment

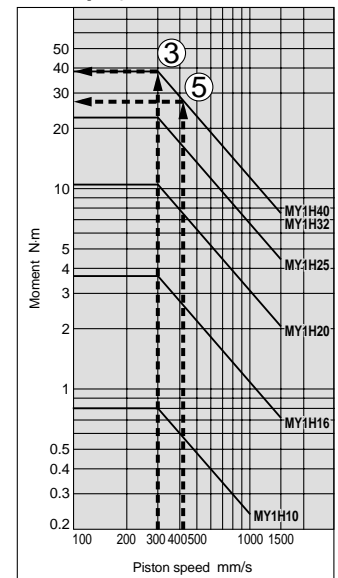
MY1H/M₁



MY1H/M₂



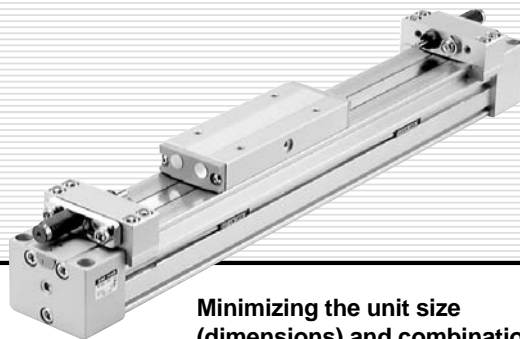
MY1H/M₃



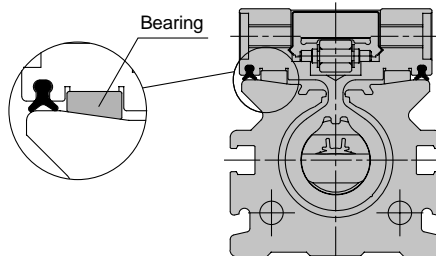
Series MY1 **B**

Basic Type

ø10, ø16, ø20, ø25, ø32, ø40, ø50, ø63, ø80, ø100



Minimizing the unit size
(dimensions) and combination
with other guides is possible.



Before Operating Series MY1B

Maximum Allowable Moment/Maximum Allowable Load

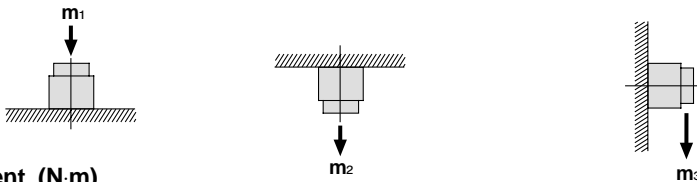
Model	Bore size (mm)	Max. allowable moment (N-m)			Max. allowable load (kg)		
		M ₁	M ₂	M ₃	m ₁	m ₂	m ₃
MY1B	10	0.8	0.1	0.3	5.0	1.0	0.5
	16	2.5	0.3	0.8	15	3.0	1.7
	20	5.0	0.6	1.5	21	4.2	3.0
	25	10	1.2	3.0	29	5.8	5.4
	32	20	2.4	6.0	40	8.0	8.8
	40	40	4.8	12	53	10.6	14
	50	78	9.3	23	70	14	20
	63	160	19	48	83	16.6	29
	80	315	37	95	120	24	42
100	615	73	184	150	30	60	

The above values are the maximum allowable values for moment and load weight. Refer to each graph regarding the maximum allowable moment and maximum allowable load for a particular piston speed.

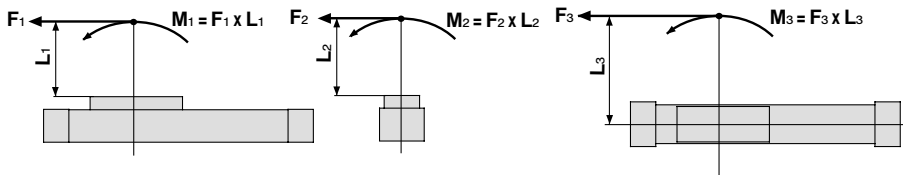
Design precautions

We recommend installing an external shock absorber when the cylinder is combined with another guide (connection with floating bracket, etc.) and the maximum allowable load is exceeded, or when the operating speed is 1000 to 1500mm/s for bore sizes ø16, ø50, ø63, ø80 and ø100.

Load (kg)



Moment (N-m)



<Calculation of guide load factor>

1. Maximum allowable load (1), static moment (2), and dynamic moment (at the time of impact with stopper) (3) must be examined for the selection calculations.

* To evaluate, use \bar{v} a (average speed) for (1) and (2), and v (impact speed $v = 1.4\bar{v}$ a) for (3). Calculate m max for (1) from the maximum allowable load graph (m_1, m_2, m_3) and M max for (2) and (3) from the maximum allowable moment graph (M_1, M_2, M_3).

$$\text{Sum of guide load factors } \sum \alpha = \frac{\text{Load mass [m]}}{\text{Maximum allowable load [m max]}} + \frac{\text{Static moment [M] }^{Note 1}}{\text{Allowable static moment [Mmax]}} + \frac{\text{Dynamic moment [ME] }^{Note 2}}{\text{Allowable dynamic moment [MEmax]}} \leq 1$$

Note 1) Moment caused by the load, etc., with cylinder in resting condition.
 Note 2) Moment caused by the impact load equivalent at the stroke end (at the time of impact with stopper).
 Note 3) Depending on the shape of the work piece, multiple moments may occur. When this happens, the sum of the load factors ($\sum \alpha$) is the total of all such moments.

2. Reference formulae [Dynamic moment at impact]
 Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

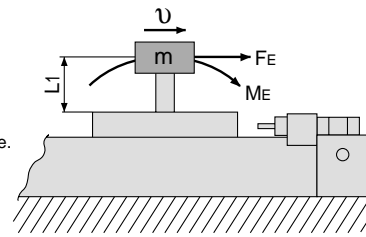
- m : Load mass (kg)
- F : Load (N)
- F_E : Load equivalent to impact (at impact with stopper) (N)
- \bar{v} a : Average speed (mm/s)
- M : Static moment (N-m)
- v : Impact speed (mm/s)
- L_1 : Distance to the load's center of gravity (m)
- M_E : Dynamic moment (N-m)
- g : Gravitational acceleration (9.8m/s²)

$$v = 1.4\bar{v}a \text{ (mm/s)} \quad F_E = \frac{1.4}{100} \bar{v}a \cdot g \cdot m \quad \text{Note 4)}$$

$$\therefore M_E = \frac{1}{3} \cdot F_E \cdot L_1 = 0.05\bar{v}a \cdot m \cdot L_1 \text{ (N-m)} \quad \text{Note 5)}$$

Note 4) $\frac{1.4}{100} \bar{v}a$ is a dimensionless coefficient for calculating impact force.

Note 5) Average load coefficient ($= \frac{1}{3}$):
 This coefficient is for averaging the maximum load moment at the time of stopper impact according to service life calculations.



3. Refer to pages 2-544 and 2-545 for detailed selection procedures.



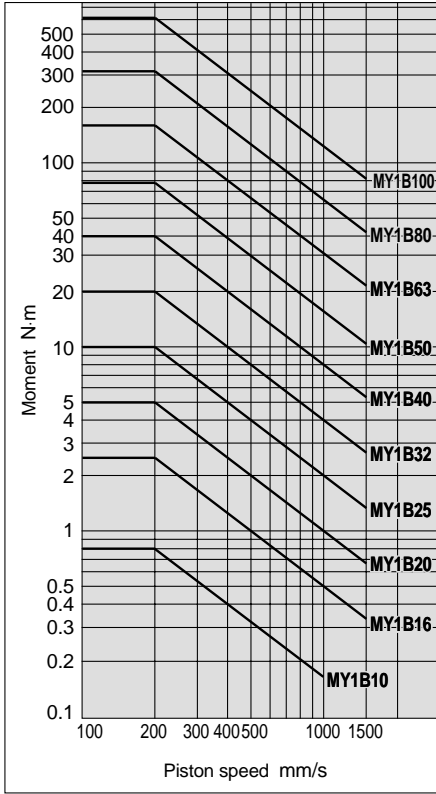
Maximum allowable moment

Select the moment from within the range of operating limits shown in the graphs. Note that the maximum allowable load value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable load for the selected conditions.

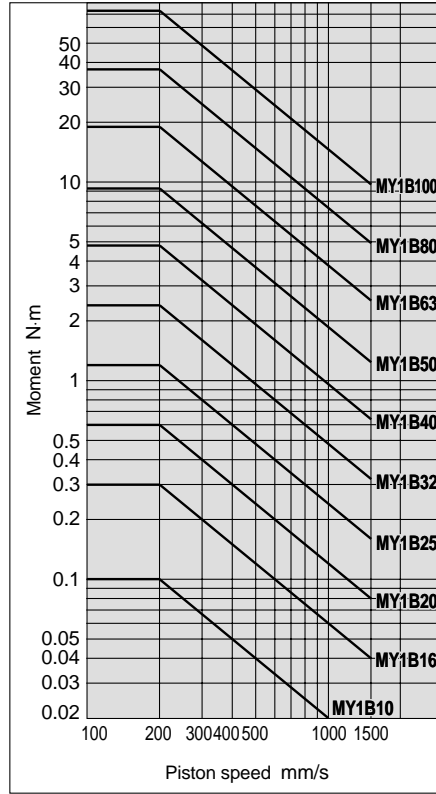
Maximum allowable load

Select the load from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.

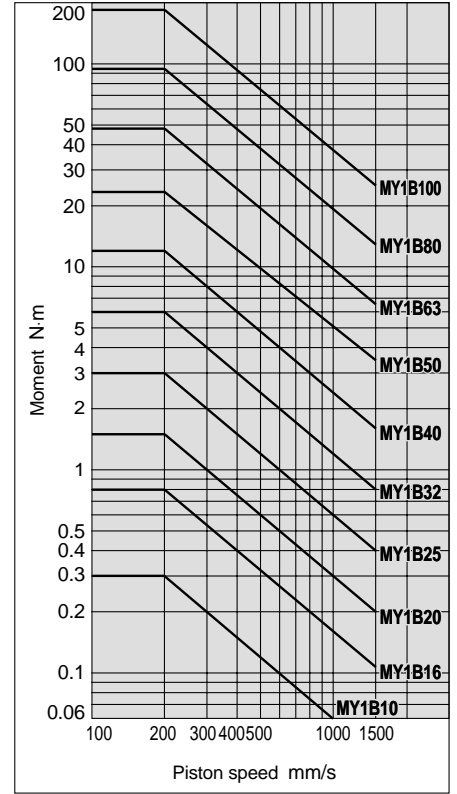
MY1B/M₁



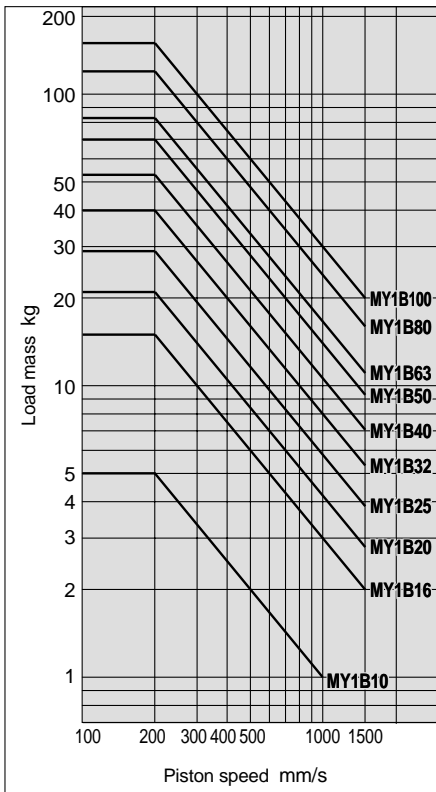
MY1B/M₂



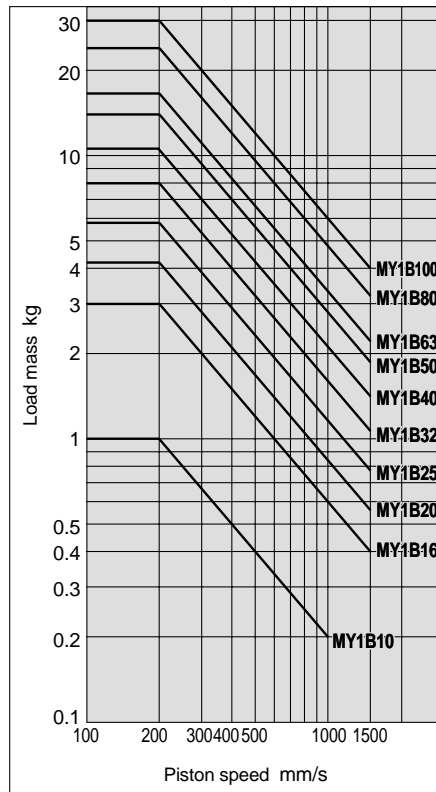
MY1B/M₃



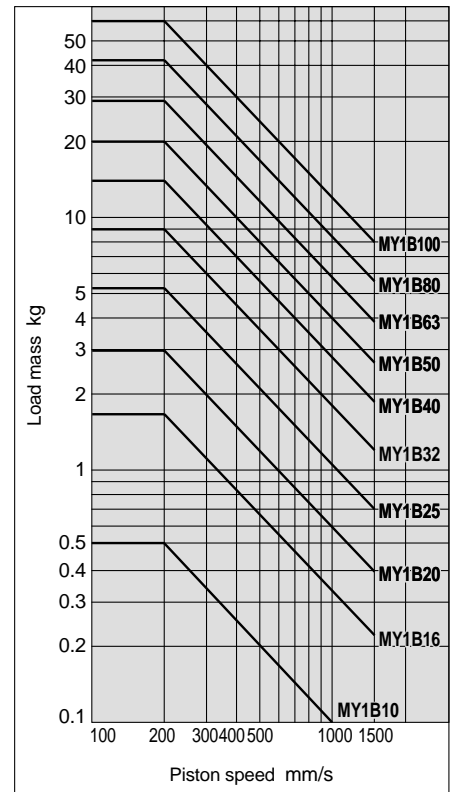
MY1B/m₁



MY1B/m₂



MY1B/m₃



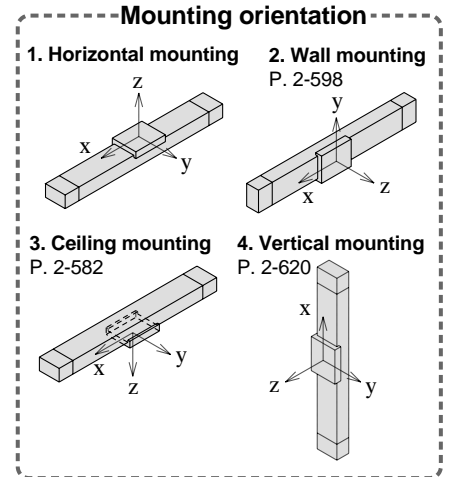
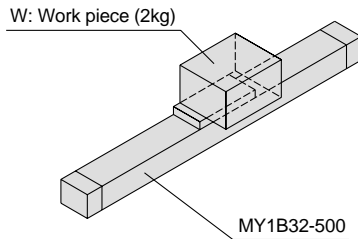
Series MY1B Model Selection

The following are steps for selection of the series MY1 best suited to your application.

Calculation of Guide Load Factor

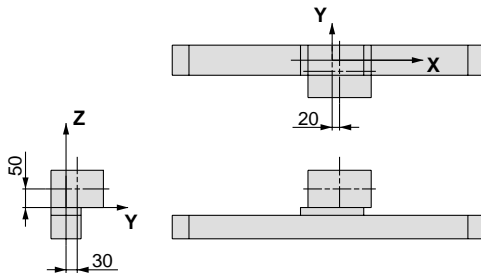
1 Operating conditions

Cylinder MY1B32-500
 Average operating speed v_a 300mm/s
 Mounting orientation Horizontal mounting



Refer to the pages above for actual examples of calculation for each orientation.

2 Load blocking



Work piece mass and centre of gravity

Work piece no.	Mass m	Center of gravity		
		X-axis	Y-axis	Z-axis
W	2kg	20mm	30mm	50mm

3 Calculation of load factor for static load

m₁: Mass

m_1 max (from 1 of graph MY1B/ m_1 = 27 (kg)

Load factor $\alpha_1 = m_1/m_1 \text{ max} = 2/27 = 0.07$

M₁: Moment

M_1 max (from 2 of graph MY1B/ M_1) = 13 (N·m)

$M_1 = m_1 \times g \times X = 2 \times 9.8 \times 20 \times 10^{-3} = 0.39$ (N·m)

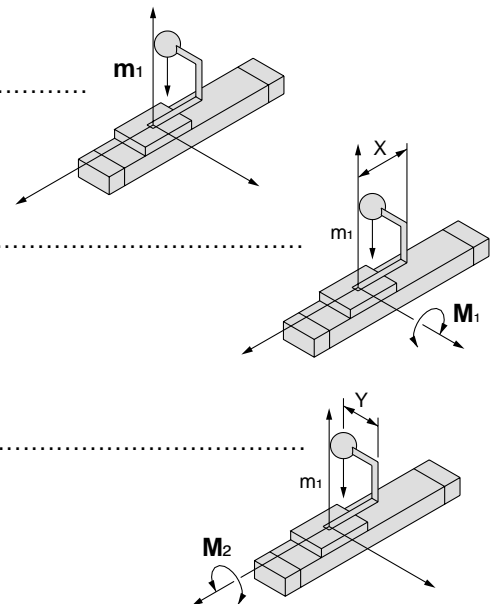
Load factor $\alpha_2 = M_1/M_1 \text{ max} = 0.39/13 = 0.03$

M₂: Moment

M_2 max (from 3 of graph MY1B/ M_2) = 1.6 (N·m)

$M_2 = m_1 \times g \times Y = 2 \times 9.8 \times 30 \times 10^{-3} = 0.59$ (N·m)

Load factor $\alpha_3 = M_2/M_2 \text{ max} = 0.59/1.6 = 0.37$



4 Calculation of load factor for dynamic moment

Equivalent load FE at impact

$$F_E = \frac{1.4}{100} \times v_a \times g \times m = \frac{1.4}{100} \times 300 \times 9.8 \times 2 = 82.3 \text{ (N)}$$

M_{1E}: Moment

M_{1E} max (from 4 of graph MY1B/M₁ where 1.4v_a = 420mm/s) = 9.5 (N·m)

$$M_{1E} = \frac{1}{3} \times F_E \times Z = \frac{1}{3} \times 82.3 \times 50 \times 10^{-3} = 1.37 \text{ (N·m)}$$

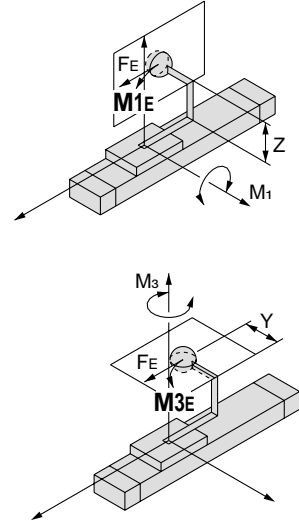
Load factor $\alpha_4 = M_{1E}/M_{1E \text{ max}} = 1.37/9.5 = \mathbf{0.14}$

M_{3E}: Moment

M_{3E} max (from 5 of graph MY1B/M₃ where 1.4v_a = 420mm/s) = 2.9 (N·m)

$$M_{3E} = \frac{1}{3} \times F_E \times Y = \frac{1}{3} \times 82.3 \times 30 \times 10^{-3} = 0.82 \text{ (N·m)}$$

Load factor $\alpha_5 = M_{3E}/M_{3E \text{ max}} = 0.82/2.9 = \mathbf{0.28}$



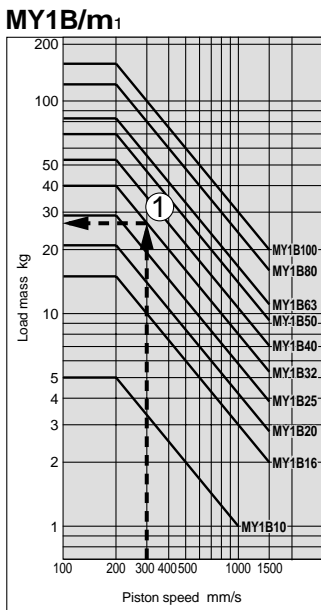
5 Sum and examination of guide load factors

$$\Sigma\alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 = \mathbf{0.89} \leq 1$$

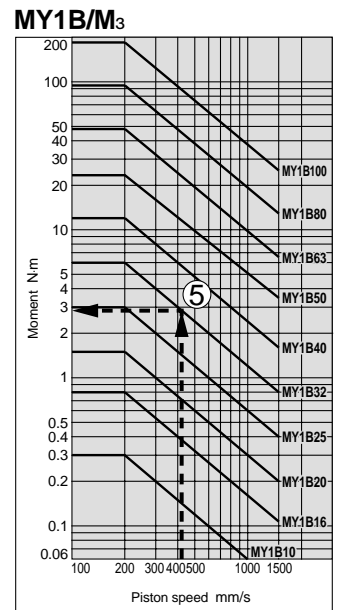
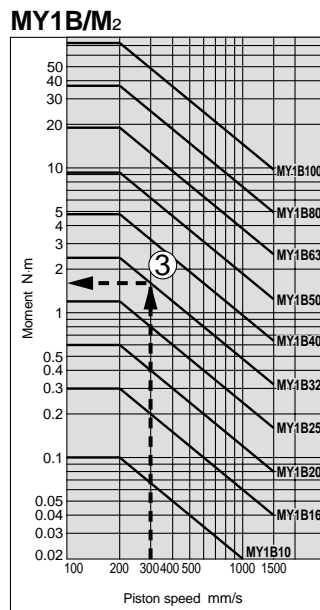
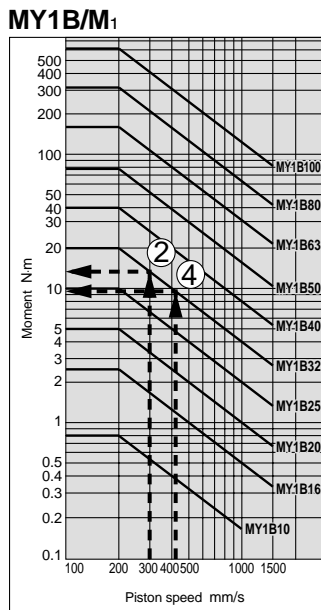
The above calculation is within the allowable value and the selected model can be used. Select a separate shock absorber.

In an actual calculation, when the sum of guide load factors $\Sigma\alpha$ in the formula above is more than 1, consider decreasing the speed, increasing the bore size, or changing the product series. Also, this calculation can be performed easily with the "SMC Pneumatics CAD System".

Load mass



Allowable moment



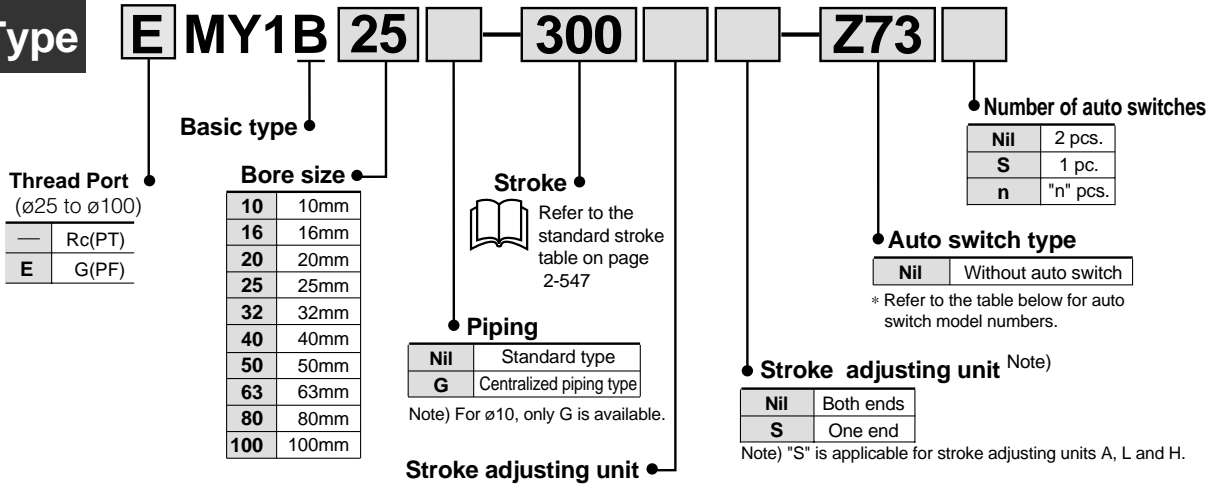
Mechanically Jointed Rodless Cylinder

Series MY1B

Basic Type/ø10, ø16, ø20, ø25, ø32, ø40, ø50, ø63, ø80, ø100

How to Order

Basic Type



Only the A unit is available for ø16. Stroke adjusting unit is not available for ø50, ø63, ø80 and ø100. Refer to page 2-549 for detailed information on stroke adjusting unit specifications.

Nil	Without adjusting unit
A	With adjusting bolt
L	With low load shock absorber + adjusting bolt
H	With high load shock absorber + adjusting bolt
AL	With one A unit and one L unit each
AH	With one A unit and one H unit each
LH	With one L unit and one H unit each

Shock absorbers for L and H units

Bore size (mm)	10	20	25	32	40
Unit no.	—	RB0806	RB1007	RB1412	RB2015
L unit	—	RB0806	RB1007	RB1412	RB2015
H unit	RB0805	RB1007	RB1412	RB2015	—

Options

Stroke adjusting unit numbers

Bore size (mm)	10	16	20	25	32
Unit no.	—	—	—	—	—
A unit	MY-A10A	MY-A16A	MY-A20A	MY-A25A	MY-A32A
L unit	—	—	MY-A20L	MY-A25L	MY-A32L
H unit	MY-A10H	—	MY-A20H	MY-A25H	MY-A32H

Bore size (mm)	40
Unit no.	—
A unit	MY-A40A
L unit	MY-A40L
H unit	MY-A40H

Side support numbers

Bore size (mm)	10	16	20	25	32
Type	—	—	—	—	—
Side support A	MY-S10A	MY-S16A	MY-S20A	MY-S25A	—
Side support B	MY-S10B	MY-S16B	MY-S20B	MY-S25B	—
Bore size (mm)	40	50	63	80	100
Type	—	—	—	—	—
Side support A	MY-S32A	MY-S50A	MY-S63A	MY-S80A	MY-S100A
Side support B	MY-S32B	MY-S50B	MY-S63B	MY-S80B	MY-S100B

Refer to page 2-557 for detailed information on dimensions, etc.

Applicable auto switches/ For ø10, ø16, ø20

Type	Special function	Electrical entry	Indicator/light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load								
					DC	AC	Electrical entry direction	In-line	0.5 (Nil)	3 (L)	5 (Z)	IC circuit	Relay, PLC							
Reed switch	—	Grommet	No	2 wire	24V	5V 12V or less	100V 100V	A90V A90	A93	●	●	—	—	IC circuit	Relay, PLC					
																A96V A96	●	●	—	—
Solid state switch	—	Grommet	Yes	3 wire (NPN equiv.)	24V	12V	—	M9NV M9N	M9P	●	●	—	—	—	Relay, PLC					
																M9PV M9P	●	●	—	—
																M9BV M9B	●	●	—	—
																M9NVV M9NV	●	●	○	—
																M9PWV M9PW	●	●	○	—
																M9BWW M9BW	●	●	○	—

* Lead wire length symbols: 0.5m..... Nil (Example) M9NV
3m..... L M9NWL
5m..... Z M9NZZ

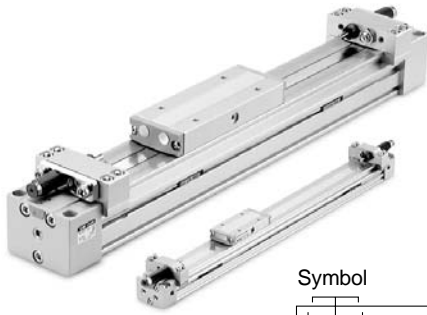
** Solid state switches marked with a "○" symbol are produced upon receipt of order.

For ø25, ø32, ø40, ø50, ø63, ø80, ø100

Type	Special function	Electrical entry	Indicator/light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load									
					DC	AC	Electrical entry direction	In-line	0.5 (Nil)	3 (L)	5 (Z)	IC circuit	Relay, PLC								
Reed switch	—	Grommet	Yes	3 wire (NPN equiv.)	24V	5V 12V or less	100V 100V	—	Z76	●	●	—	—	IC circuit	Relay, PLC						
																Z73	●	●	●	—	—
Solid state switch	—	Grommet	Yes	3 wire (NPN equiv.)	24V	5V 12V or less	100V 100V	—	Y69A Y59A	●	●	○	—	—	Relay, PLC						
																Y7PV Y7P	●	●	○	—	—
																Y69B Y59B	●	●	○	—	—
																Y7NWW Y7NW	●	●	○	—	—
																Y7PWV Y7PW	●	●	○	—	—
																Y7BWW Y7BW	●	●	○	—	—

* Lead wire length symbols: 0.5m..... Nil (Example) Y59A
3m..... L Y59AL
5m..... Z Y59AZ

** Solid state switches marked with a "○" symbol are produced upon receipt of order.



Order made specifications

Refer to page 2-645 regarding order made specifications for series MY1B.

Specifications

Bore size (mm)	10	16	20	25	32	40	50	63	80	100
Fluid	Air									
Action	Double acting									
Operating pressure range	0.2 to 0.8MPa		0.1 to 0.8MPa							
Proof pressure	1.2MPa									
Ambient and fluid temperature	5 to 60°C									
Cushion	Rubber bumper	Air cushion								
Lubrication	Non-lube									
Stroke length tolerance	1000 or less ^{+1.8} ₀		2700 or less ^{+1.8} ₀ , 2701 to 5000 ^{+2.8} ₀							
Port size	Front/Side ports	M5 x 0.8			1/8	1/4	3/8		1/2	
	Bottom ports (centralized piping type only)	∅4	∅5	∅6	∅8	∅10	∅11	∅16	∅18	

Stroke adjusting unit specifications

Bore size (mm)	10		16	20			25			32			40		
Unit symbol	A	H	A	A	L	H	A	L	H	A	L	H	A	L	H
Configuration and shock absorber	With adjusting bolt	RB 0805 + With adjusting bolt	With adjusting bolt	With adjusting bolt	RB 0806 + With adjusting bolt	RB 1007 + With adjusting bolt	With adjusting bolt	RB 1007 + With adjusting bolt	RB 1412 + With adjusting bolt	With adjusting bolt	RB 1412 + With adjusting bolt	RB 2015 + With adjusting bolt	With adjusting bolt	RB 1412 + With adjusting bolt	RB 2015 + With adjusting bolt
Stroke fine adjusting range (mm)	0 to -5		0 to -5.6	0 to -6			0 to -11.5			0 to -12			0 to -16		
Stroke adjusting range	When exceeding the stroke fine adjusting range: Use order made specifications "-X416" and "-X417". (Refer to page 2-645 for details.)														

Shock absorber specifications

Model	RB 0805	RB 0806	RB 1007	RB 1412	RB 2015	
Max. energy absorption (J)	1.0	2.9	5.9	19.6	58.8	
Stroke absorption (mm)	5	6	7	12	15	
Max. impact speed (mm/s)	1000	1500	1500	1500	1500	
Max. operating frequency (cycles/min)	80	80	70	45	25	
Spring force (N)	Extended	1.96	1.96	4.22	6.86	8.34
	Compressed	3.83	4.22	6.86	15.98	20.50
Operating temperature range (°C)	5 to 60					

Piston speed

Bore size (mm)	10	16 to 100
Without stroke adjusting unit	100 to 500mm/s	100 to 1000mm/s
Stroke adjusting unit	A unit	100 to 200mm/s
	L unit and H unit	100 to 1000mm/s

Note 1) Be aware that when the stroke adjusting range is increased by manipulating the adjusting bolt, the air cushion capacity decreases. Also, when exceeding the air cushion stroke ranges on page 2-549, the **piston speed** should be **100 to 200mm per second**.

Note 2) For centralized piping, the piston speed is 100 to 1000mm per second.

Note 3) Use at a speed within the absorption capacity range. Refer to page 2-548

Theoretical output

Unit: N

Bore size (mm)	Piston area (mm ²)	Operating pressure (MPa)							
		0.2	0.3	0.4	0.5	0.6	0.7	0.8	
10	78	15	23	31	39	46	54	62	
16	200	40	60	80	100	120	140	160	
20	314	62	94	125	157	188	219	251	
25	490	98	147	196	245	294	343	392	
32	804	161	241	322	402	483	563	643	
40	1256	251	377	502	628	754	879	1005	
50	1962	392	588	784	981	1177	1373	1569	
63	3115	623	934	1246	1557	1869	2180	2492	
80	5024	1004	1507	2009	2512	3014	3516	4019	
100	7850	1570	2355	3140	3925	4710	5495	6280	

1N = Approx. 0.102kgf, 1MPa = Approx. 10.2kgf/cm²

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)

Calculation method

Example: **MY1B25-300A**

Basic weight 1.33kg
 Cylinder stroke 300mm
 Additional weight..... 0.12/50mm stroke
 1.33 + 0.12 x 300 ÷ 50 + 0.06 x 2 = Approx. 2.17kg
 Weight of A unit 0.06kg

Standard strokes

Bore size (mm)	Standard stroke (mm)*	Max. manufacturable stroke (mm)
10 and 16	100, 200, 300, 400, 500, 600, 700	3000
20, 25, 32, 40, 50, 63, 80, 100	800, 900, 1000, 1200, 1400, 1600, 1800, 2000	5000

* Strokes are manufacturable in 1mm increments, up to the maximum stroke. However, when exceeding a 2000mm stroke, specify "-XB11" at the end of the model number. Refer to the order made specifications on page 2-645

Weights

Unit: kg

Bore size (mm)	Basic weight	Additional weight per 50mm of stroke	Side support weight (per set)	Stroke adjusting unit weight (per unit)		
			Type A and B	A unit	L unit	H unit
10	0.15	0.04	0.003	0.01	—	0.02
16	0.61	0.06	0.01	0.04	—	—
20	1.06	0.10	0.02	0.05	0.05	0.10
25	1.33	0.12	0.02	0.06	0.10	0.18
32	2.65	0.18	0.02	0.12	0.21	0.40
40	3.87	0.27	0.04	0.23	0.32	0.49
50	7.78	0.44	0.04	—	—	—
63	13.10	0.70	0.08	—	—	—
80	20.70	1.18	0.17	—	—	—
100	35.70	1.97	0.17	—	—	—

Series MY1B

Cushion Capacity

Cushion selection

<Rubber bumper>

Rubber bumpers are a standard feature on MY1B10.

Since the stroke absorption of rubber bumpers is short, when adjusting the stroke with an A unit, install an external shock absorber.

<Air cushion>

Air cushions are a standard feature on mechanically jointed rodless cylinders. (Except $\phi 10$.)

The air cushion mechanism is installed to avoid excessive impact of the piston at the stroke end during high speed operation. The air cushion does not act to decelerate the piston near the stroke end.

The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

<Stroke adjusting unit with shock absorber>

Use this unit when operating with a load or speed exceeding the air cushion limit line, or when cushioning is necessary because the cylinder stroke is outside of the effective air cushion stroke range due to stroke adjustment.

L unit

Use this unit when cushioning is necessary outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

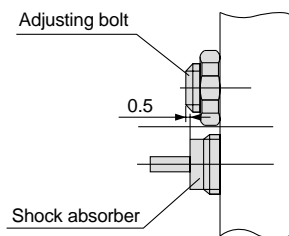
H unit

Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

⚠ Caution

1. Refer to the diagram below when using the adjusting bolt to perform stroke adjustment.

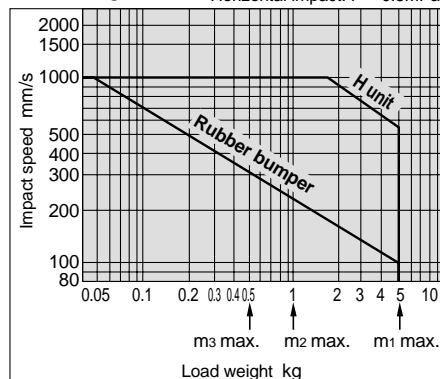
When the effective stroke of the shock absorber decreases as a result of stroke adjustment, the absorption capacity decreases dramatically. Secure the adjusting bolt at the position where it protrudes approximately 0.5mm from the shock absorber.



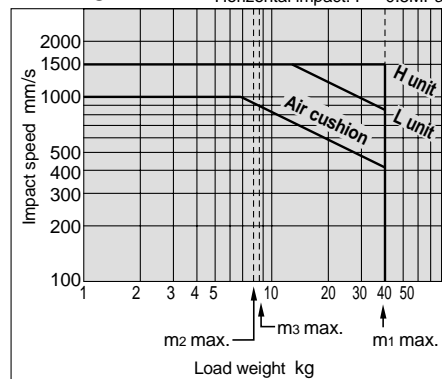
2. Do not use a shock absorber and air cushion together.

Absorption capacity of rubber bumper, air cushion and stroke adjusting units

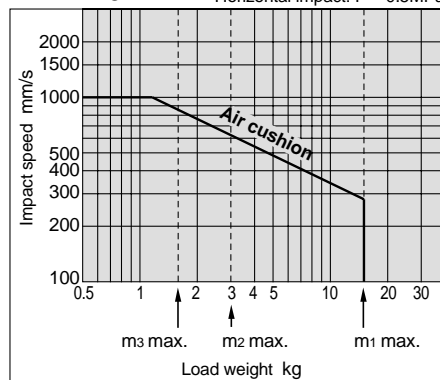
MY1B10 Horizontal impact: P = 0.5MPa



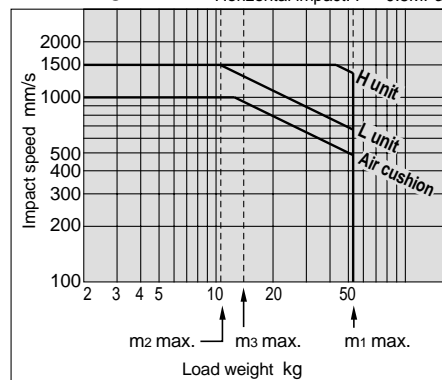
MY1B32 Horizontal impact: P = 0.5MPa



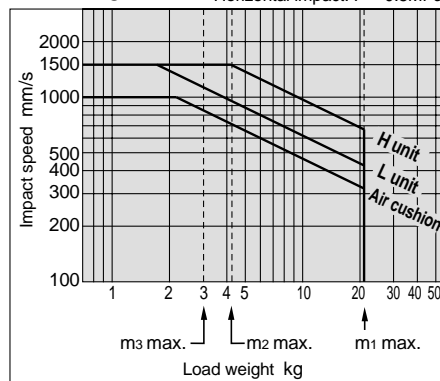
MY1B16 Horizontal impact: P = 0.5MPa



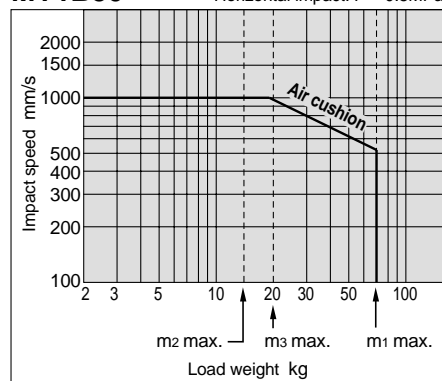
MY1B40 Horizontal impact: P = 0.5MPa



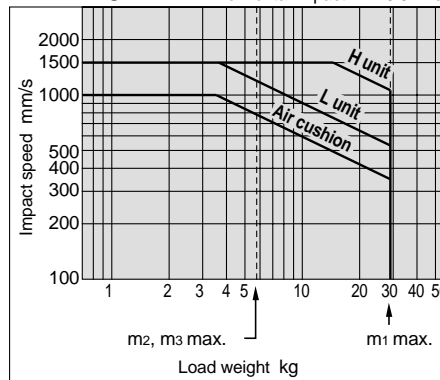
MY1B20 Horizontal impact: P = 0.5MPa



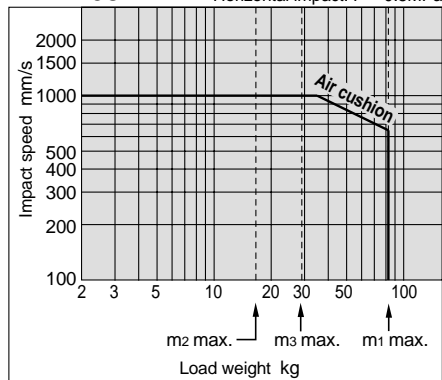
MY1B50 Horizontal impact: P = 0.5MPa



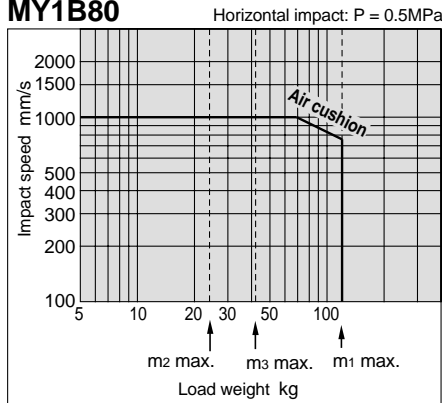
MY1B25 Horizontal impact: P = 0.5MPa



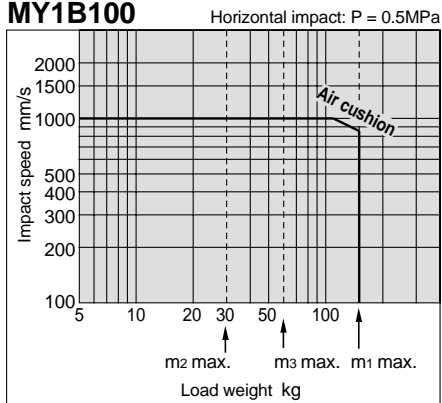
MY1B63 Horizontal impact: P = 0.5MPa



MY1B80



MY1B100



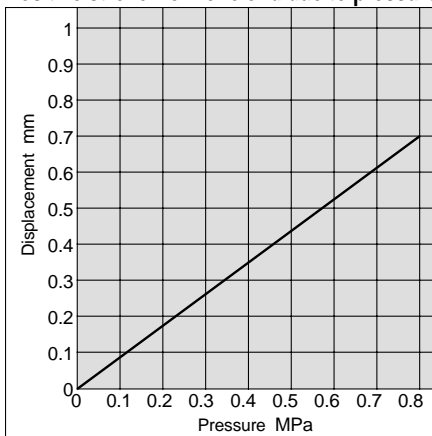
Air cushion stroke

Unit: mm

Bore size (mm)	Cushion stroke
16	12
20	15
25	15
32	19
40	24
50	30
63	37
80	40
100	40

Rubber bumper (∅10 only)

Positive stroke from one end due to pressure



Stroke adjusting unit holding bolt tightening torque

Unit: N·m

Bore size (mm)	Unit	Tightening torque
10	A	0.3
	H	
16	A	0.6
	H	
20	A	1.5
	L	
25	A	3.0
	H	
32	A	5.0
	L	
40	A	10
	H	

Stroke adjusting unit lock plate holding bolt tightening torque

Unit: N·m

Bore size (mm)	Unit	Tightening torque
20	H	1.2
	L	1.2
25	H	3.3
	L	3.3
32	H	10
	L	10
40	L	3.3
	H	10

Calculation of absorption energy for stroke adjusting unit with shock absorber

Unit: N·m

	Horizontal	Vertical (downward)	Vertical (upward)
Type of impact			
Kinetic energy E ₁		$\frac{1}{2} m \cdot v^2$	
Thrust energy E ₂	F·s	F·s + m·g·s	F·s - m·g·s
Absorbed energy E		E ₁ + E ₂	

Symbols

v : Speed of impacting object (m/s)

m : Weight of impacting object (kg)

F : Cylinder thrust (N)

g : Gravitational acceleration (9.8m/s²)

s : Shock absorber stroke (m)

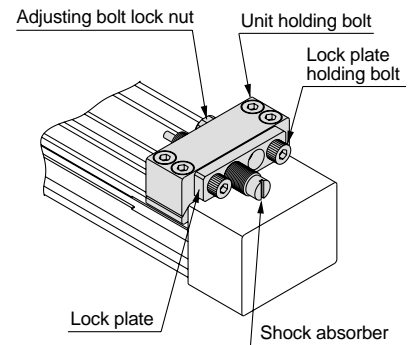
Note) The speed of the impacting object is measured at the time of impact with the shock absorber.

Specific product precautions

Caution

Be careful not to get hands caught in the unit.

- When using a product with stroke adjusting unit, the space between the slide table (slider) and the stroke adjusting unit becomes narrow, causing a danger of hands getting caught. Install a protective cover to prevent direct contact with the human body.



<Fastening of unit>

The unit can be fastened by uniformly tightening the four unit holding bolts.

Caution

Do not operate with the stroke adjusting unit fixed in an intermediate position.

When the stroke adjusting unit is fixed in an intermediate position, slippage can occur depending on the amount of energy released at the time of an impact. In this case, we recommend using the adjusting bolt mounting brackets available with order made specifications -X 416 and -X 417. (Except ∅10.)

For other lengths, consult SMC. (Refer to "Stroke adjustment unit holding bolt tightening torque".)

<Stroke adjustment with adjusting bolt>

Loosen the adjusting bolt lock nut, and adjust the stroke from the lock plate side using a hexagon wrench. Re-tighten the lock nut.

<Stroke adjustment with shock absorber>

Loosen the two lock plate holding bolts, turn the shock absorber and adjust the stroke. Then, uniformly tighten the lock plate holding bolts to secure the shock absorber.

Take care not to over-tighten the holding bolts. (Except ∅20 L unit.) (Refer to "Stroke adjustment unit lock plate holding bolt tightening torque".)

Note)

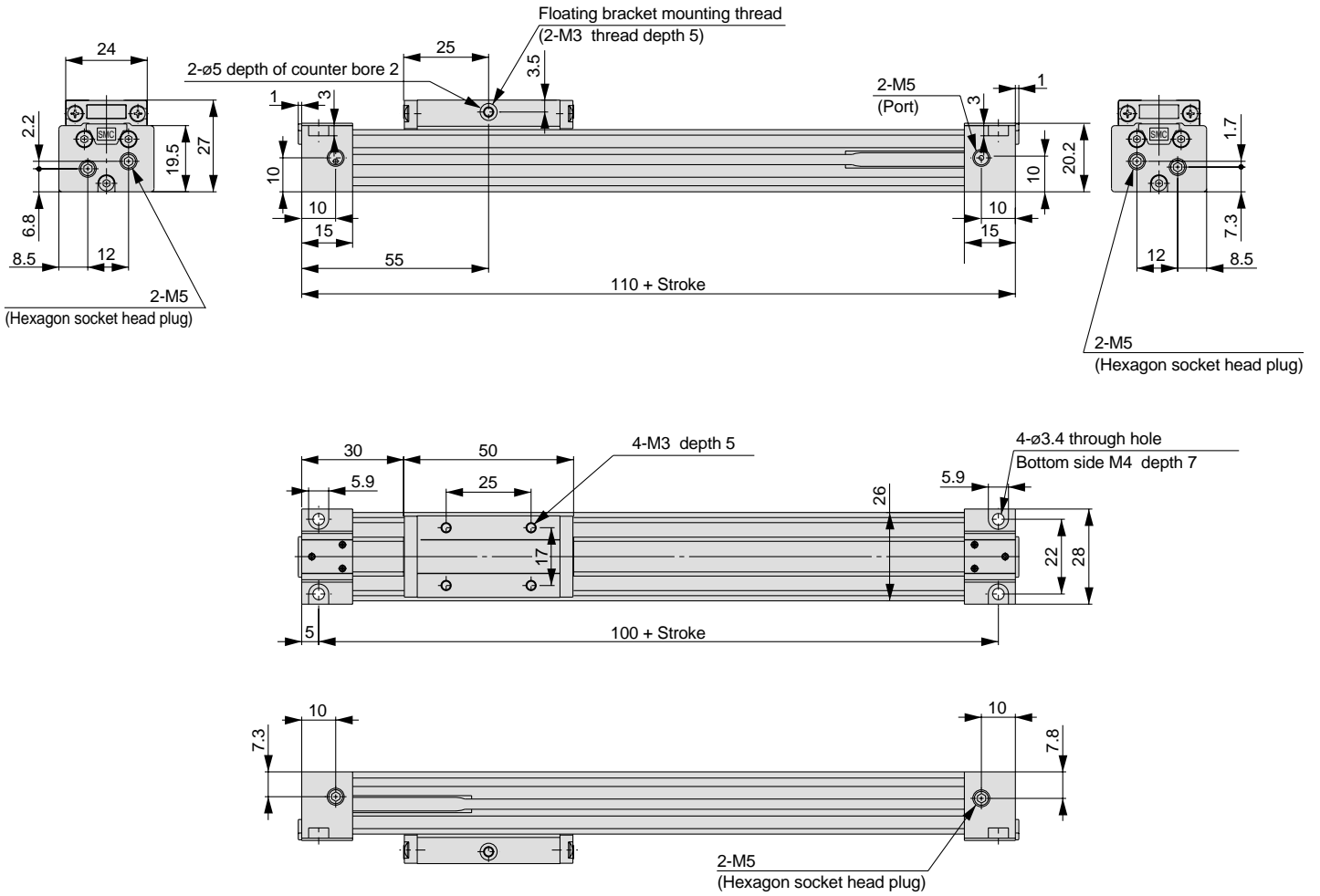
Slight bending may occur in the lock plate due to tightening of the lock plate holding bolts. This is not a problem for the shock absorber and locking function.

Series MY1B

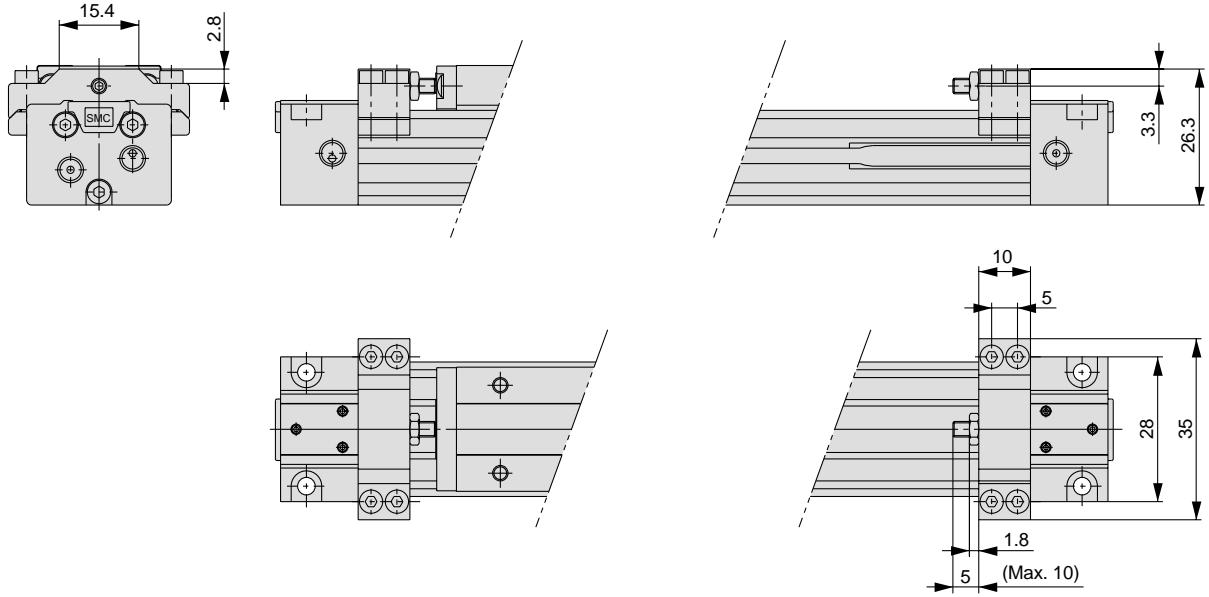
Centralized Piping Type $\varnothing 10$

[Refer to page 2-648 regarding centralized piping port variations.]

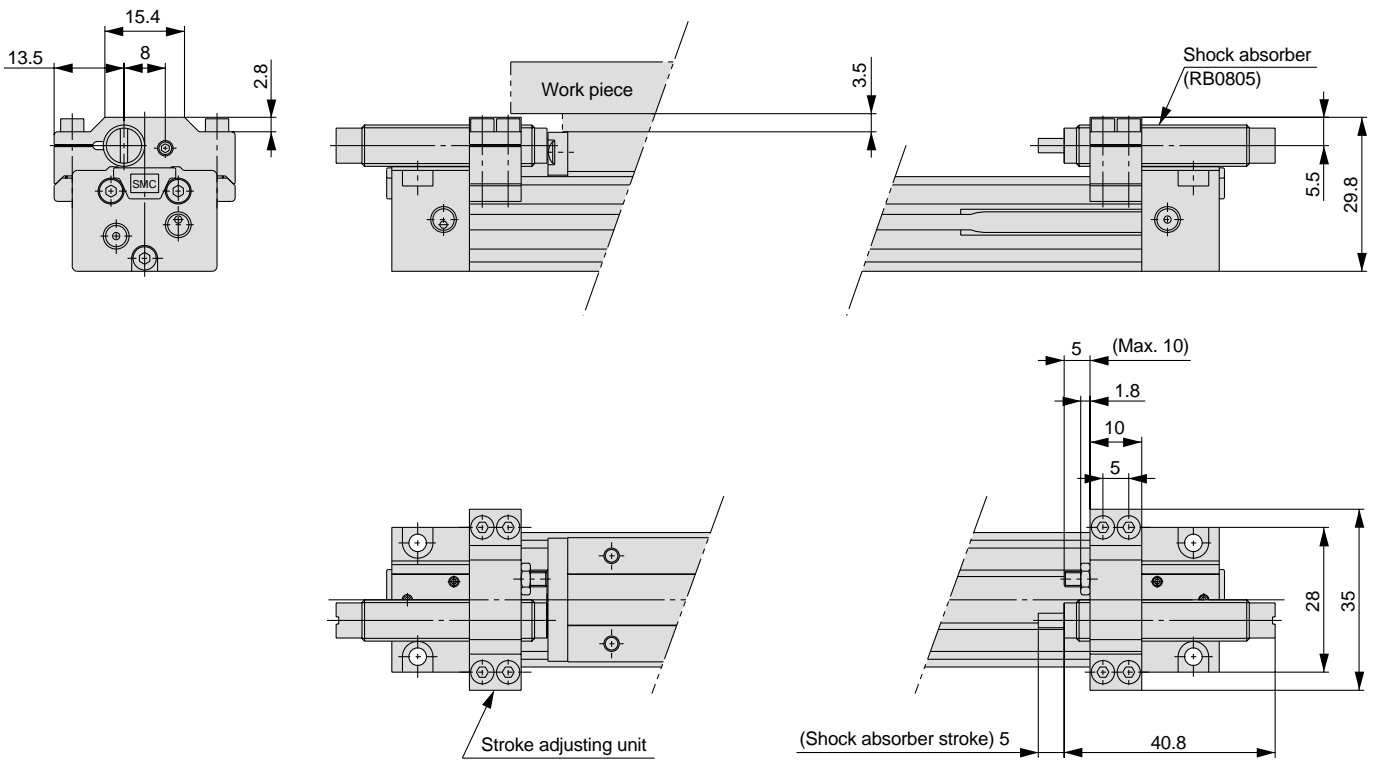
MY1B10G — Stroke



MY1B10G — Stroke A (with adjusting bolt)



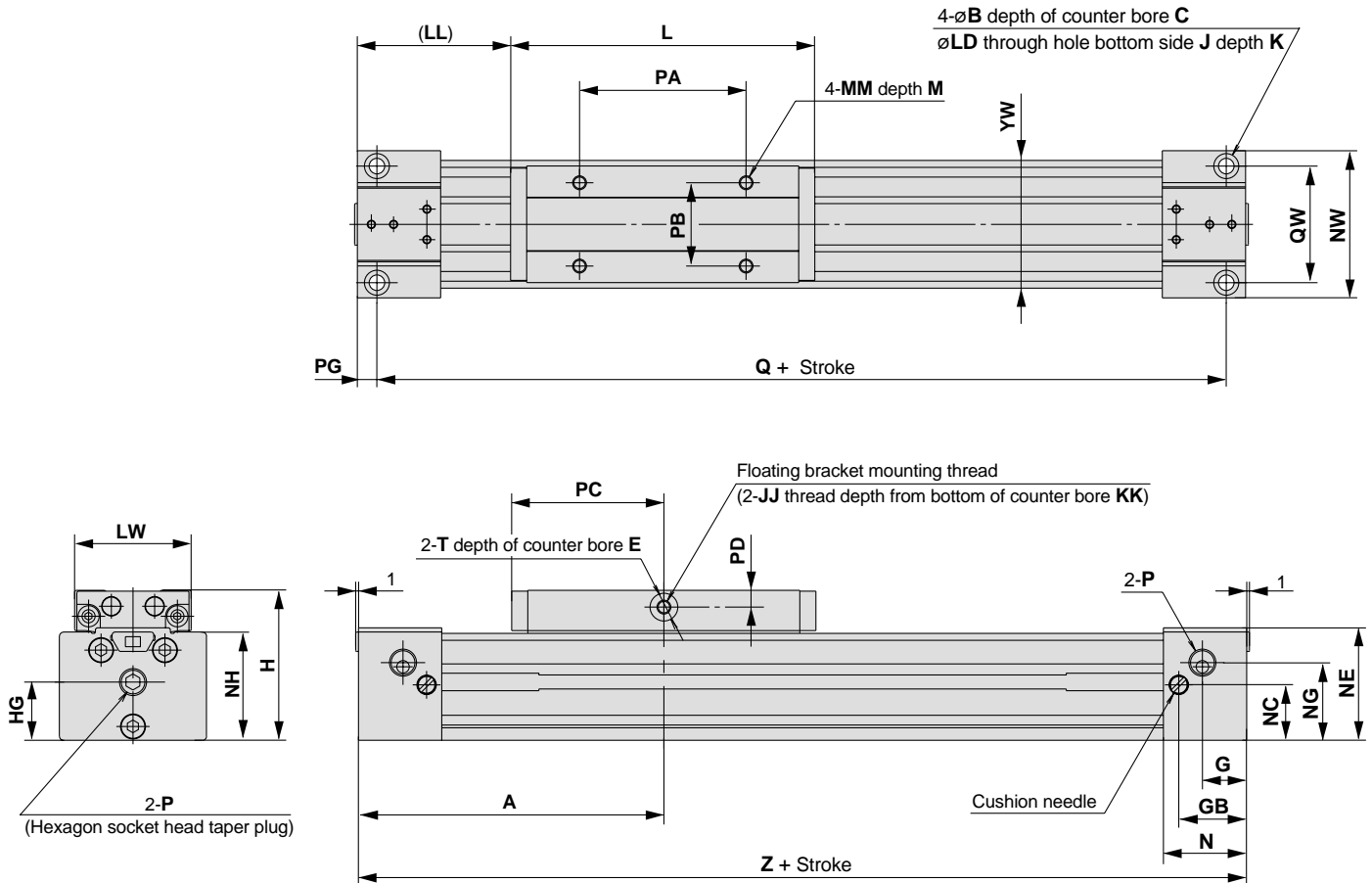
MY1B10G — Stroke H (with high load shock absorber + stopper bolt)



Series MY1B

Standard Type $\varnothing 16$ to $\varnothing 40$

MY1B Bore size — Stroke



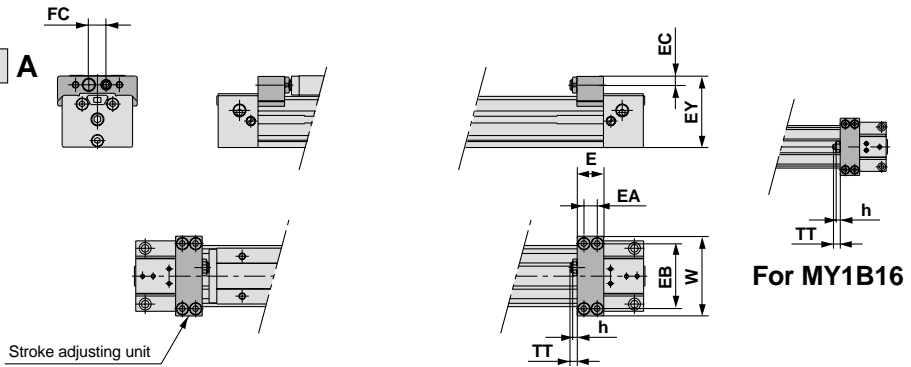
Model	A	B	C	E	G	GB	H	HG	J	JJ	K	KK	L	LD	LL	LW	PG
MY1B16	80	6	3.5	2	9	16	37	13.5	M5	M4 x 0.7	10	6.5	80	3.5	40	30	3.5
MY1B20	100	7.5	4.5	2	12.5	20.5	46	17.5	M6	M4 x 0.7	12	10	100	4.5	50	37	4.5
MY1B25	110	9	5.5	2	16	24.5	54	21	M6	M5 x 0.8	9.5	9	110	5.6	55	42	7
MY1B32	140	11	6.5	2	19	30	68	26	M8	M5 x 0.8	16	10	140	6.8	70	52	8
MY1B40	170	14	8.5	2	23	36.5	84	33.5	M10	M6 x 1	15	13.0	170	8.6	85	64	9

Model	M	MM	N	NC	NE	NG	NH	NW	P	PA	PB	PC	PD	Q	QW	T	YW	Z
MY1B16	6	M4	20	13.5	27.8	13.5	27	37	M5	40	20	40	4.5	153	30	7	32	160
MY1B20	8	M5	25	17.5	34	17.5	33.5	45	M5	50	25	50	5	191	36	8	40	200
MY1B25	9	M5	30	20	40.5	28	39	53	1/8	60	30	55	6	206	42	10	46	220
MY1B32	12	M6	37	25	50	33	49	64	1/8	80	35	70	10	264	51	10	55	280
MY1B40	12	M6	45	30.5	63	42.5	61.5	75	1/4	100	40	85	12.0	322	59	14	67	340

"P" indicates cylinder supply ports. * The plug for MY1B16-20-P is a hexagon socket head plug.

Stroke Adjusting Unit
With adjusting bolt

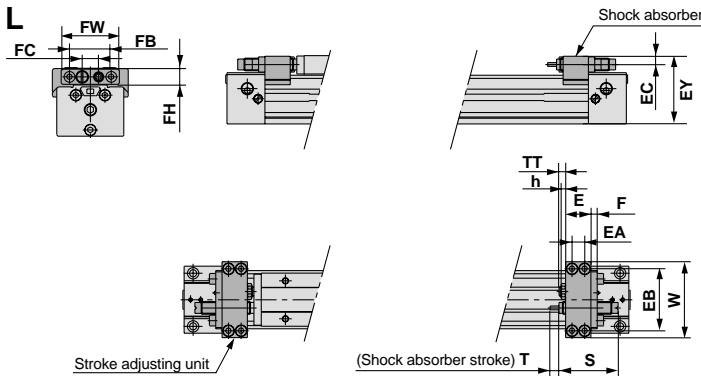
MY1B **Bore size** — **Stroke** **A**



Applicable cylinder	E	EA	EB	EC	EY	FC	h	TT	W
MY1B16	14.6	7	34.4	4.2	36.5	—	2.4	5.4 (max. 11)	43
MY1B20	19	9	43	5.8	45.6	13	3.2	6 (max. 12)	53
MY1B25	20	10	49	6.5	53.5	13	3.5	5 (max. 16.5)	60
MY1B32	25	12	61	8.5	67	17	4.5	8 (max. 20)	74
MY1B40	31	15	76	9.5	81.5	17	4.5	9 (max. 25)	94

Low load shock absorber + Adjusting bolt

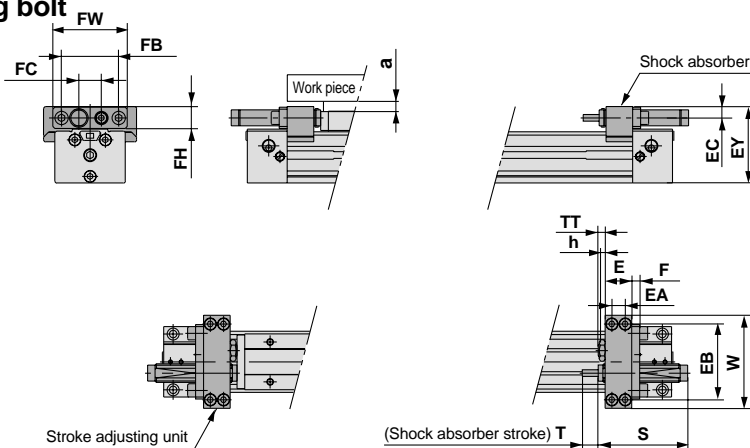
MY1B **Bore size** — **Stroke** **L**



Applicable cylinder	E	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	T	TT	W	Shock absorber model
MY1B20	19	9	43	5.8	45.6	4	—	13	—	—	3.2	40.8	6	6 (max. 12)	53	RB0806
MY1B25	20	10	49	6.5	53.5	6	33	13	12	46	3.5	46.7	7	5 (max. 16.5)	60	RB1007
MY1B32	25	12	61	8.5	67	6	43	17	16	56	4.5	67.3	12	8 (max. 20)	74	RB1412
MY1B40	31	15	76	9.5	81.5	6	43	17	16	56	4.5	67.3	12	9 (max. 25)	94	

High load shock absorber + Adjusting bolt

MY1B **Bore size** — **Stroke** **H**



* Since dimension EY of the H type unit is greater than the table top height (dimension H), when mounting a workpiece that exceeds the overall length (dimension L) of the slide table, allow a clearance of dimension "a" or larger on the work piece side.

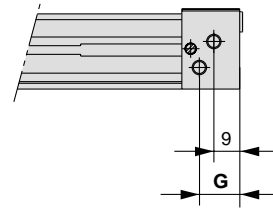
Applicable cylinder	E	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	T	TT	W	Shock absorber model	a
MY1B20	20	10	49	6.5	47.5	6	33	13	12	46	3.5	46.7	7	5 (max. 11)	60	RB1007	2.5
MY1B25	20	10	57	8.5	57.5	6	43	17	16	56	4.5	67.3	12	5 (max. 16.5)	70	RB1412	4.5
MY1B32	25	12	74	11.5	73	8	57	22	22	74	5.5	73.2	15	8 (max. 20)	90	RB2015	6
MY1B40	31	15	82	12	87	8	57	22	22	74	5.5	73.2	15	9 (max. 25)	100		4

Series MY1B

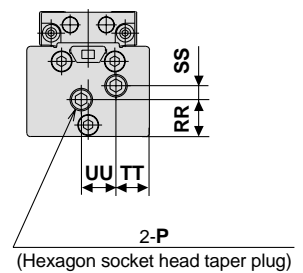
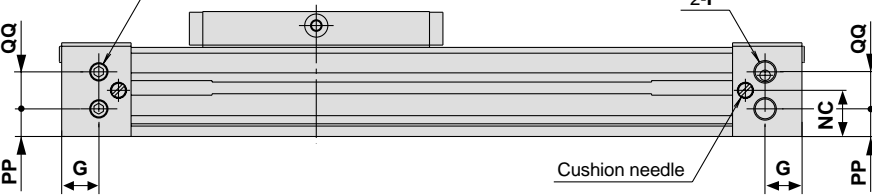
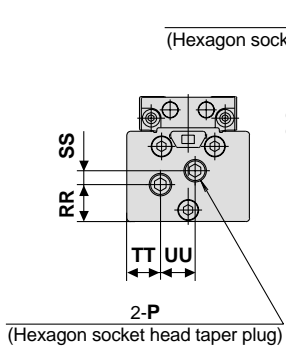
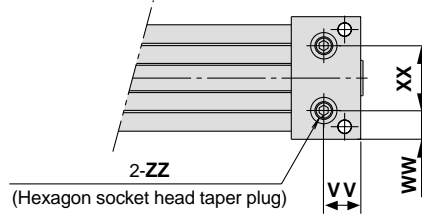
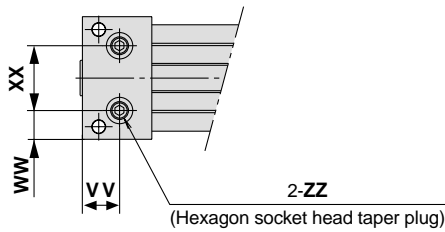
Centralized Piping Type $\varnothing 16$ to $\varnothing 40$

Refer to page 2-648 regarding centralized piping port variations.
 Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions.
 Refer to pages 2-552 and 2-553 for details regarding dimensions, etc.

MY1B Bore size G — Stroke

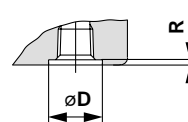
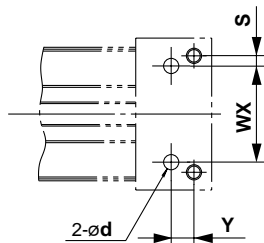


For MY1B16



Model	G	NC	P	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1B16G	14	14	M5	7.5	9	11	3	9	10.5	10	7.5	22	M5
MY1B20G	12.5	17.5	M5	11.5	11	14.5	5	10.5	12	12.5	10.5	24	M5
MY1B25G	16	20	1/8	12	16	16	6	14.5	15	16	12.5	28	1/16
MY1B32G	19	25	1/8	17	16	23	4	16	16	19	16	32	1/16
MY1B40G	23	30.5	1/4	18.5	24	27	10.5	20	22	23	19.5	36	1/8

*"P" indicates cylinder supply ports. * The plug for MY1B16/20-P-ZZ is a hexagon socket head plug.



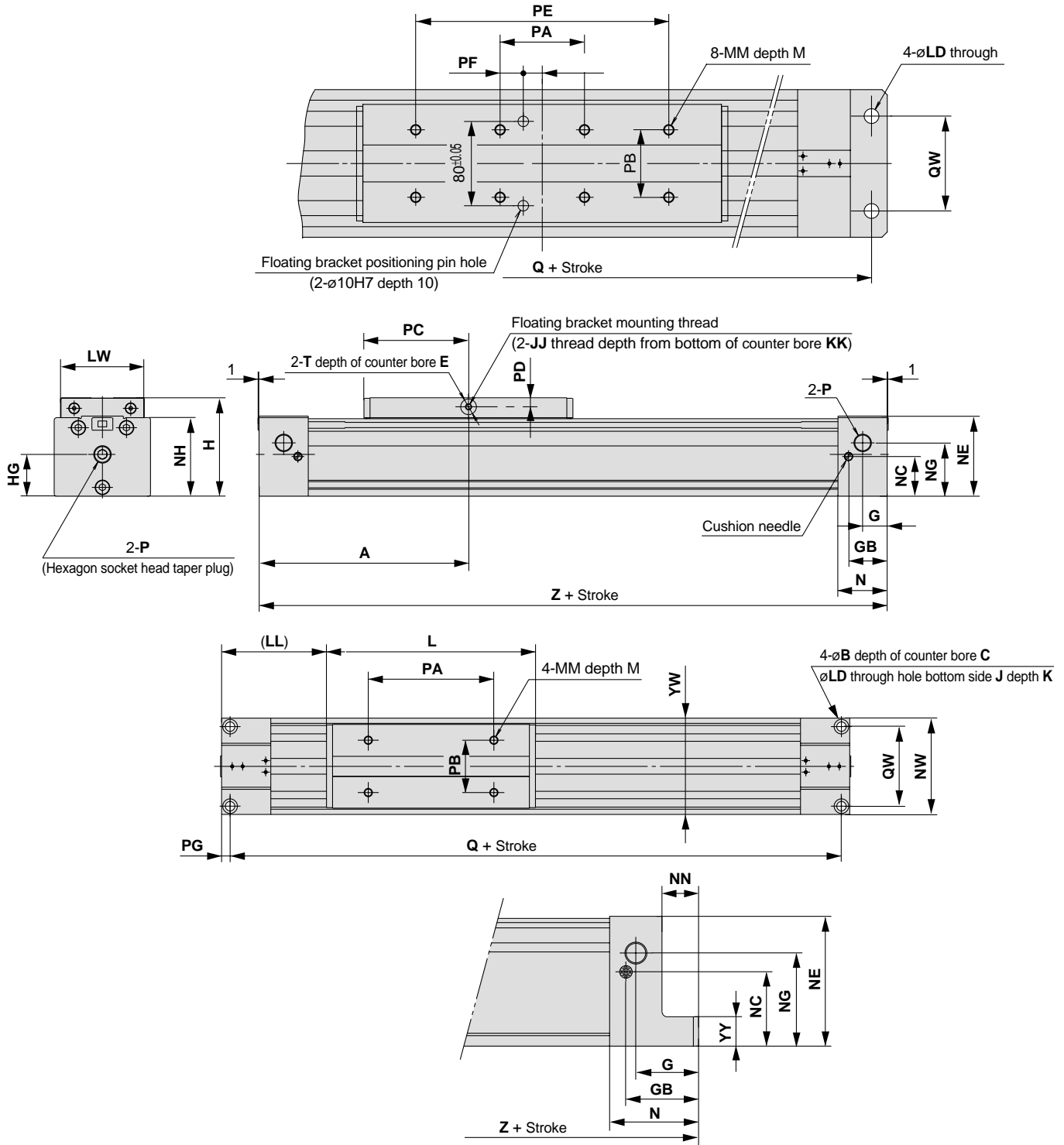
Bottom side (ZZ) piping
(applicable O-ring)

Hole sizes for centralized piping on the bottom (Machine the mounting side to the dimensions below.)

Model	WX	Y	S	d	D	R	Applicable O-ring
MY1B16G	22	6.5	4	4	8.4	1.1	C6
MY1B20G	24	8	6	4	8.4	1.1	
MY1B25G	28	9	7	6	11.4	1.1	C9
MY1B32G	32	11	9.5	6	11.4	1.1	
MY1B40G	36	14	11.5	8	13.4	1.1	C11.2

Standard Type **∅50 to ∅100**

MY1B **Bore size** — **Stroke**



For MY1B80, 100

Model	A	B	C	E	G	GB	H	HG	J	JJ	K	KK	L	LD	LL	LW	NN	YY	PG
MY1B 50	200	14	8.5	3	23.5	37	94	40	M12	M6	25	17	200	9	100	80	—	—	8
MY1B 63	230	17	10.5	3	25	39	116	51	M14	M8	28	24	230	11	115	96	—	—	10
MY1B 80	345	—	—	—	60	71.5	150	66	—	—	—	—	340	14	175	112	35	28	15
MY1B100	400	—	—	—	70	79.5	190	85	—	—	—	—	400	18	200	140	45	35	20

Model	M	MM	N	NC	NE	NG	NH	NW	P	PA	PB	PC	PD	PE	PF	Q	QW	T	YW	Z
MY1B 50	14	M8	47	38	76.5	51	75	92	3/8	120	50	100	8.5	—	—	384	76	15	92	400
MY1B 63	16	M8	50	51	100	59	95	112	3/8	140	60	115	9.5	—	—	440	92	16	112	460
MY1B 80	20	M10	85	65	124	82	124	140	1/2	80	65	—	—	240	22	660	90	—	140	690
MY1B100	25	M12	95	85	157	103	157	176	1/2	120	85	—	—	280	42	760	120	—	176	800

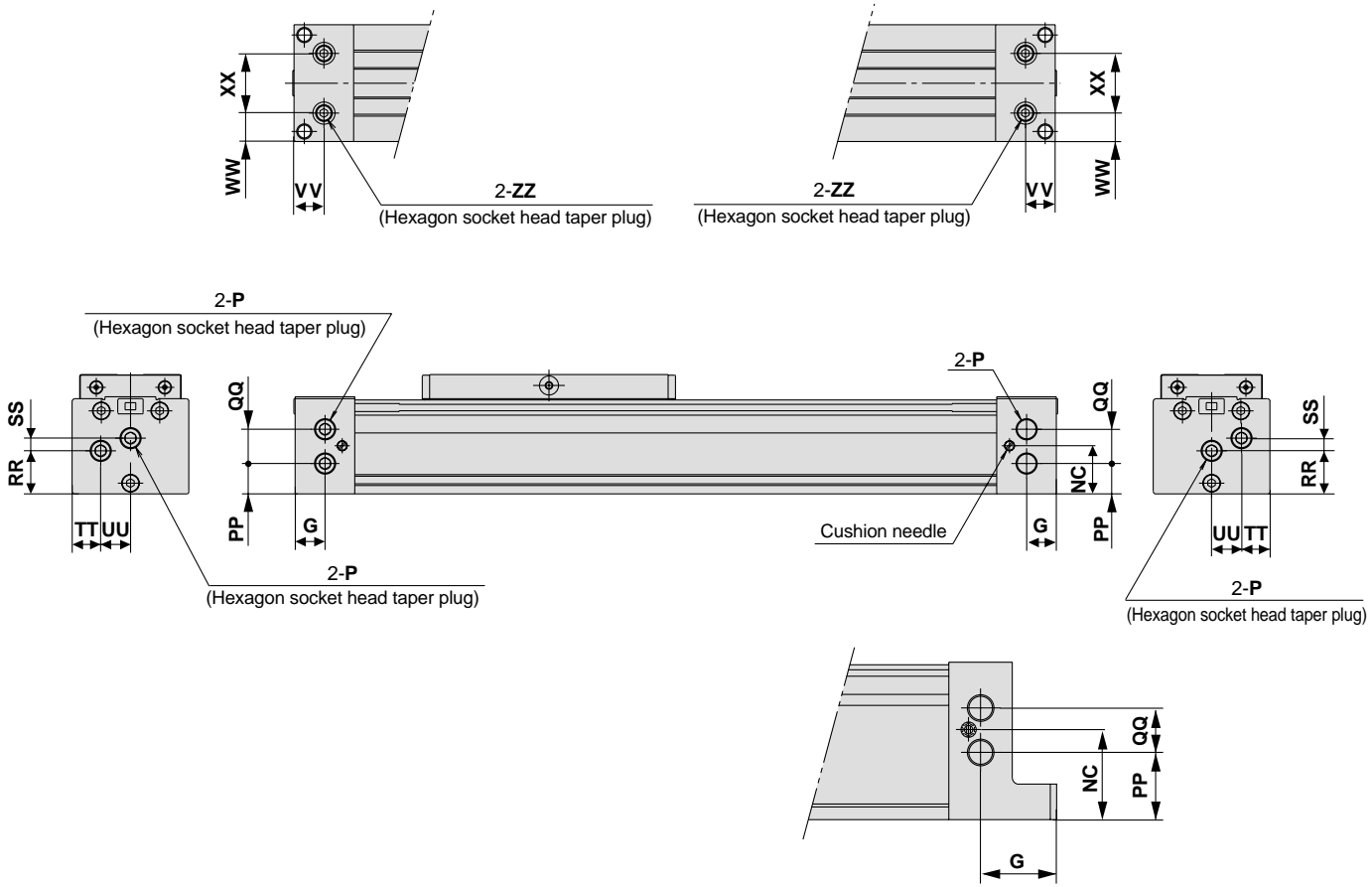
* "P" indicates cylinder supply ports.

Series MY1B

Centralized Piping Type $\varnothing 50$ to $\varnothing 100$

Refer to page 2-648 regarding centralized piping port variations.
 Dimensions for types other than centralized piping are identical to the standard type dimensions.
 Refer to pages 2-555 for details regarding dimensions etc.

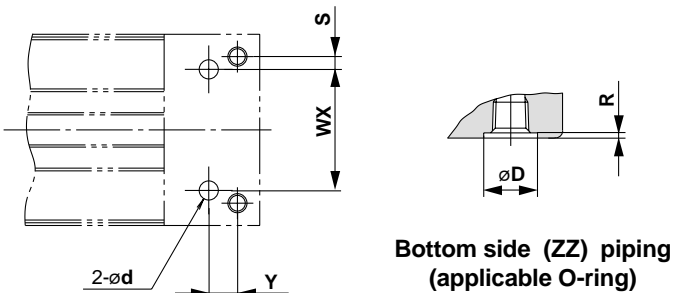
MY1B Bore size G — Stroke



For MY1B80, 100

Model	G	P	NC	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1B 50G	23.5	3/8	38	24	27	34	10	22.5	23.5	23.5	22.5	47	1/4
MY1B 63G	25	3/8	51	37.5	29.5	45.5	13.5	27	29	25	28	56	1/4
MY1B 80G	60	1/2	71	53	35	61	15	30	40	60	25	90	1/2
MY1B100G	70	1/2	88	69	38	75	20	40	48	70	28	120	1/2

* "P" indicates cylinder supply ports.



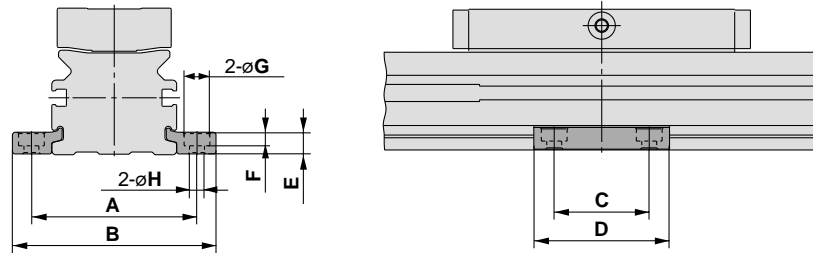
Bottom side (ZZ) piping (applicable O-ring)

(Machine the mounting side to the dimensions below.)

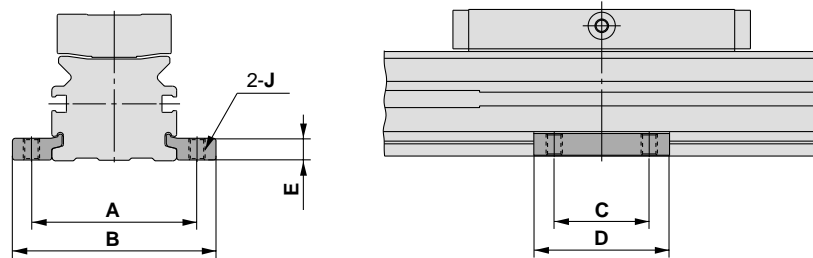
Model	WX	Y	S	d	D	R	Applicable O-ring
MY1B 50G	47	15.5	14.5	10	17.5	1.1	C15
MY1B 63G	56	15	18	10	17.5	1.1	
MY1B 80G	90	45	—	18	26	1.8	P22
MY1B100G	120	50	—	18	26	1.8	

Side Support

Side support A MY-S□A



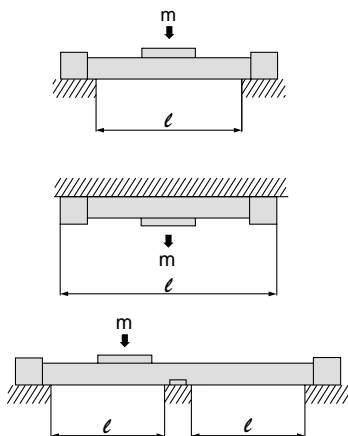
Side support B MY-S□B



Model	Applicable cylinder	A	B	C	D	E	F	G	H	J
MY-S10 ^A _B	MY1B 10	35	43.6	12	21	3.6	1.8	6.5	3.4	M4
MY-S16 ^A _B	MY1B 16	43	53.6	15	26	4.9	3	6.5	3.4	M4
MY-S20 ^A _B	MY1B 20	53	65.6	25	38	6.4	4	8	4.5	M5
MY-S25 ^A _B	MY1B 25	61	75	35	50	8	5	9.5	5.5	M6
	MY1B 32	70	84							
MY-S32 ^A _B	MY1B 40	87	105	45	64	11.7	6	11	6.6	M8
	MY1B 50	113	131							
MY-S50 ^A _B	MY1B 63	136	158	55	80	14.8	8.5	14	9	M10
MY-S63 ^A _B	MY1B 80	170	200	70	100	18.3	10.5	17.5	11.5	M12
	MY1B100	206	236							

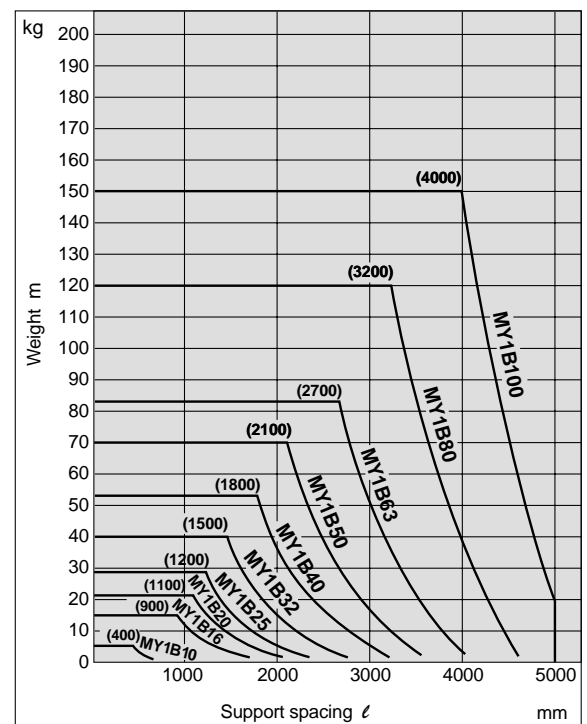
Guide for Using Side Supports

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load weight. In such a case, use a side support in the middle section. The spacing (ℓ) of the support must be no more than the values shown in the graph on the right.



⚠ Caution

1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting. Also, for long stroke operation involving vibration and impact, use of a side support is recommended even if the spacing value is within the allowable limits shown in the graph.
2. Support brackets are not for mounting; use them solely for providing support.



Series MY1B

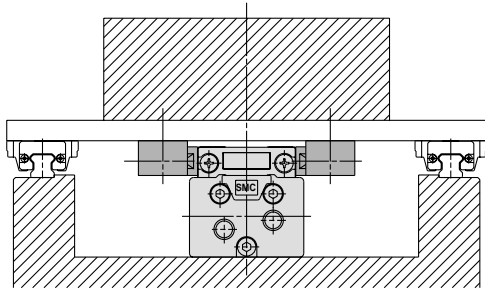
Floating Bracket

Facilitates connection to other guide systems.

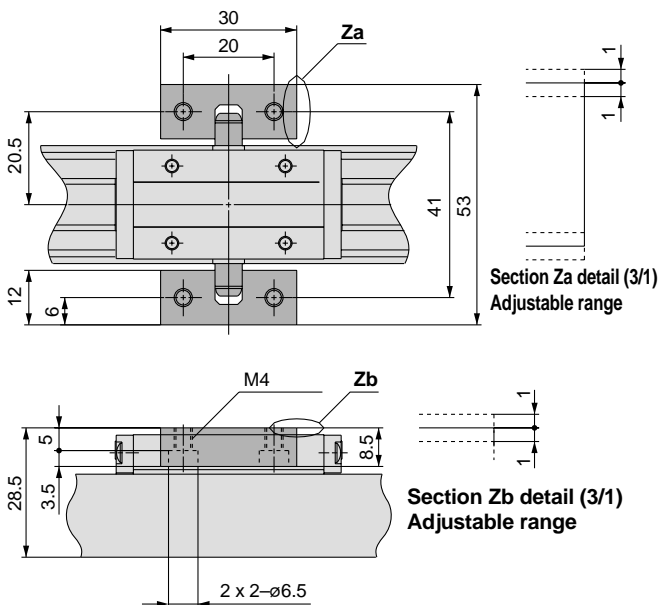
Applicable bore size

ø10

Application example



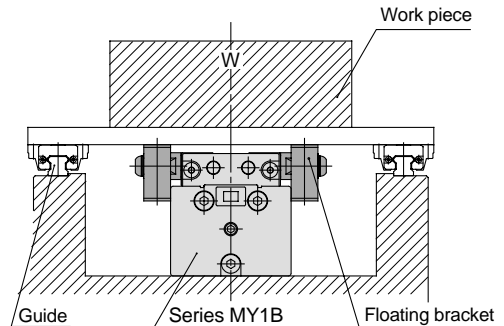
Mounting example



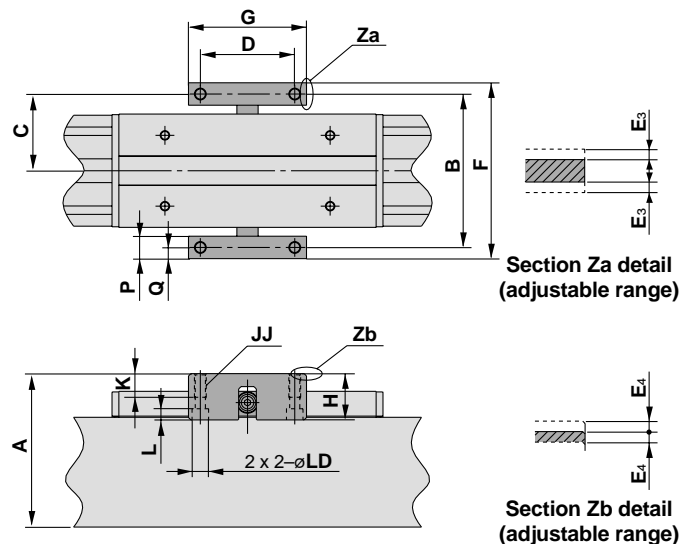
Applicable bore size

ø16, ø20

Application example



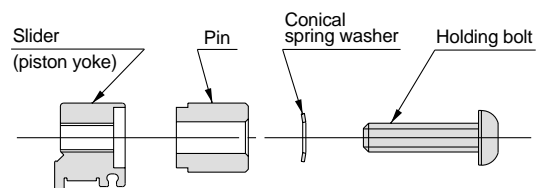
Mounting example



Model	Applicable cylinder	A	B	C	D	F	G	H
MY-J16	MY1B16□	45	45	22.5	30	52	38	18
MY-J20	MY1B20□	55	52	26	35	59	50	21

Model	Applicable cylinder	JJ	K	L	P	Q	E ₃	E ₄	LD
MY-J16	MY1B16□	M4	10	4	7	3.5	1	1	6
MY-J20	MY1B20□	M4	10	4	7	3.5	1	1	6

Installation of holding bolts



Holding bolt tightening torque

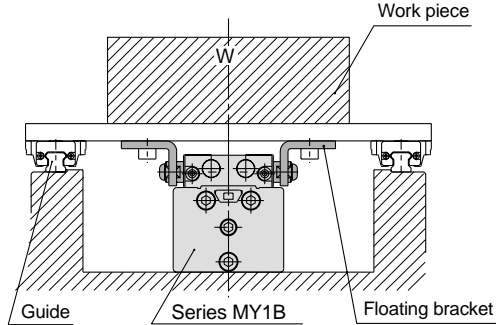
Unit: N·m

Model	Tightening torque	Model	Tightening torque	Model	Tightening torque
MY-J10	0.6	MY-J25	3	MY-J50	5
MY-J16	1.5	MY-J32	5	MY-J63	13
MY-J20	1.5	MY-J40	5		

Applicable bore size

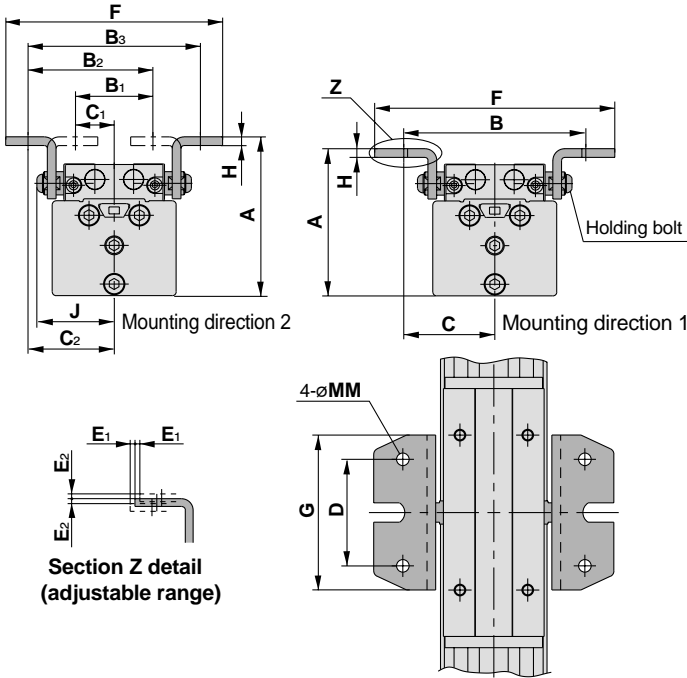
∅25, ∅32, ∅40

Application example



Mounting example

One set of brackets can be mounted in two directions for compact combinations.



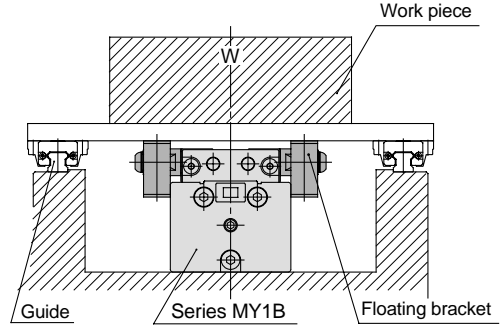
Model	Applicable cylinder	Common					Mounting direction 1			
		D	G	H	J	MM	A	B	C	F
MY-J25	MY1B25□	40	60	3.2	35	5.5	63	78	39	100
MY-J32	MY1B32□	55	80	4.5	40	6.5	76	94	47	124
MY-J40	MY1B40□	74	100	4.5	47	6.5	92	112	56	144
Model	Applicable cylinder	Mounting direction 2							Adjustable range	
		A	B ₁	B ₂	B ₃	C ₁	C ₂	F	E ₁	E ₂
MY-J25	MY1B25□	65	28	53	78	14	39	96	1	1
MY-J32	MY1B32□	82	40	64	88	20	44	111	1	1
MY-J40	MY1B40□	98	44	76	108	22	54	131	1	1

Note) One set of floating brackets consists of one right piece and one left piece.

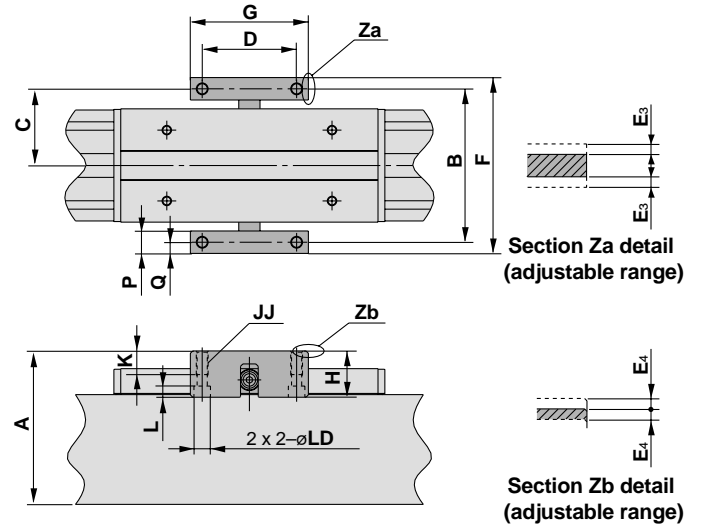
Applicable bore size

∅50, ∅63

Application example



Mounting example



Model	Applicable cylinder	A	B	C	D	F	G	H	
MY-J50	MY1B50□	110	110	55	70	126	90	37	
MY-J63	MY1B63□	131	130	65	80	149	100	37	
Model	Applicable cylinder	JJ	K	L	P	Q	E ₃	E ₄	LD
MY-J50	MY1B50□	M8	20	7.5	16	8	2.5	2.5	11
MY-J63	MY1B63□	M10	20	9.5	19	9.5	2.5	2.5	14

Series MY1B

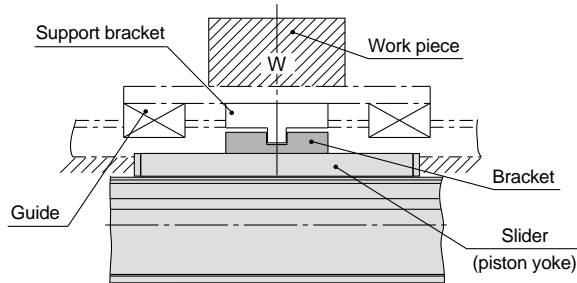
Floating Bracket

Facilitates connection to other guide systems.

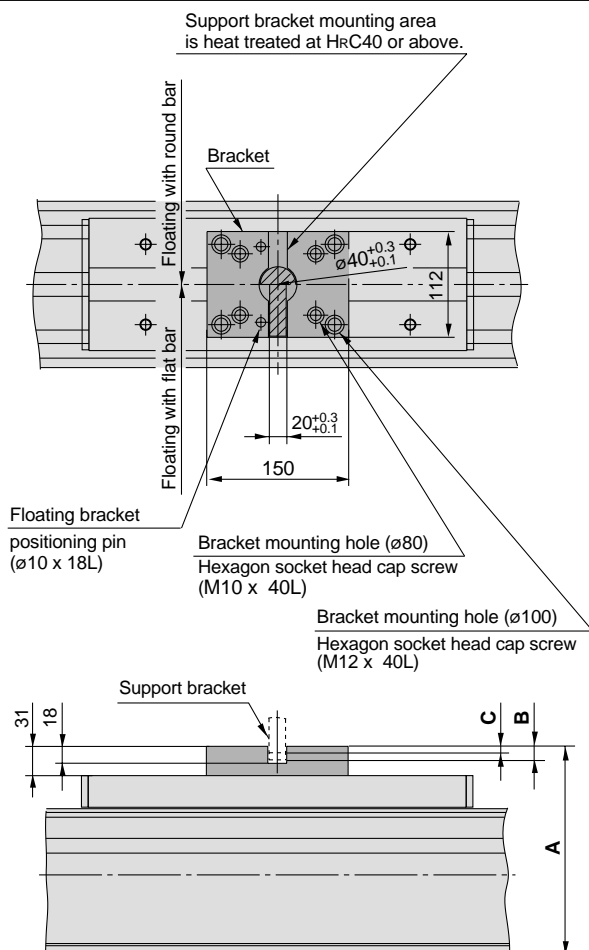
Applicable bore size

ø80, ø100

Application example



Mounting example



Hexagon socket head cap screw tightening torque

Unit: N·m

Model	Applicable cylinder	A	B (max.)	C (min.)	Model	Tightening torque
MY-J 80	MY1B 80	181	15	9	MY-J 80	25
MY-J100	MY1B100	221	15	9	MY-J100	44

- Note) • Flat bar or round bar mounting are possible for the support bracket (slanted lines) mounted by the customer.
- The floating bracket is packaged with (4) hexagon socket head cap screws and (2) parallel pins at the time of shipment.
 - "B" and "C" indicate the allowable mounting dimensions for the support bracket (flat bar or round bar).
 - Consider support brackets with dimensions that allow the floating mechanism to function properly.

Floating bracket operating precautions

⚠ Caution

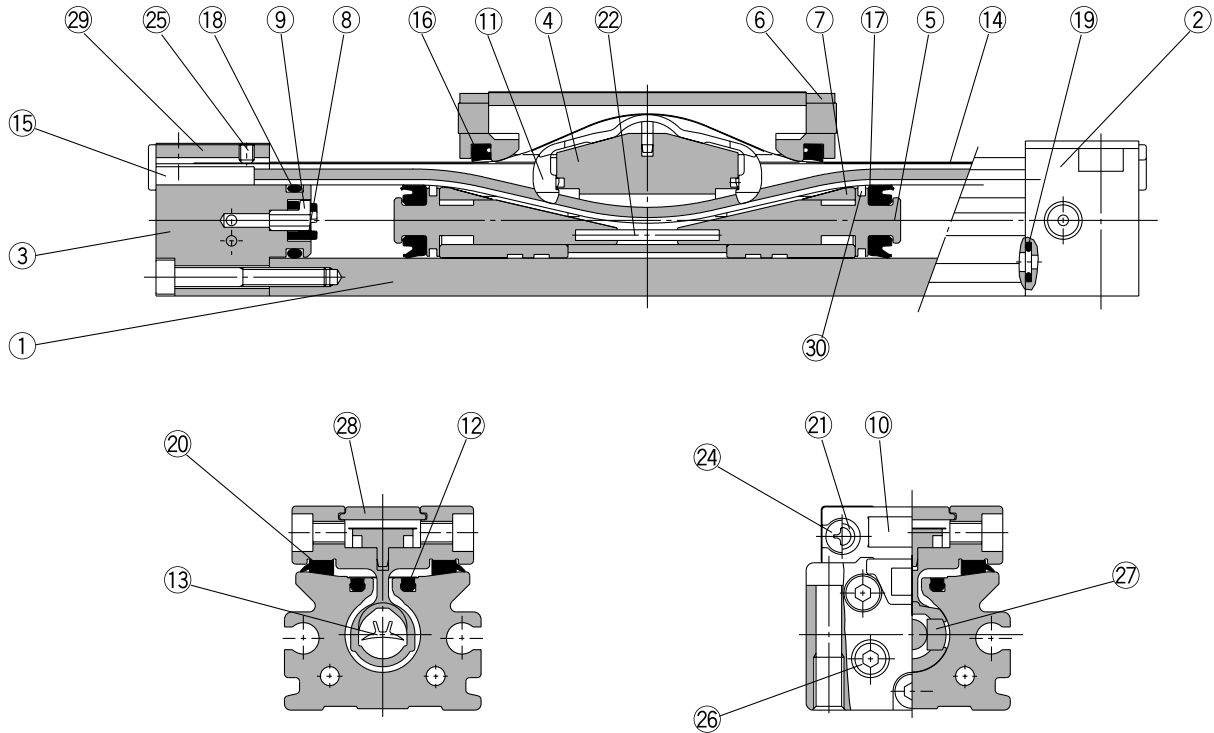
Make sure that the amount of divergence from the external guide is within the adjustable range.

Using the floating bracket facilitates connection to an external guide. However, with a rod type guide, etc., the amount of displacement is large and the floating bracket may not be able to absorb the variation. Check the amount of displacement and mount the floating bracket within the adjustable range.

When the displacement amount exceeds the adjustable range, use a separate floating mechanism.

Construction/ $\varnothing 10$

Centralized piping type/MY1B10G



Parts list

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover WR	Aluminum alloy	Hard anodized
3	Head cover WL	Aluminum alloy	Hard anodized
4	Piston yoke	Aluminum alloy	Hard anodized
5	Piston	Aluminum alloy	Chromated
6	End cover	Special resin	
7	Wear ring	Special resin	
8	Bumper	Polyurethane rubber	
9	Holder	Stainless steel	
10	Stopper	Carbon steel	Nickel plated
11	Belt separator	Special resin	
12	Seal magnet	Rubber magnet	

Parts list

No.	Description	Material	Note
15	Belt clamp	Special resin	
20	Bearing	Special resin	
21	Spacer	Chrome molybdenum steel	Nickel plated
22	Spring pin	Stainless steel	
23	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
24	Round head Phillips screw	Carbon steel	Nickel plated
25	Hexagon socket head set screw	Carbon steel	Black zinc chromated
26	Hexagon socket head plug	Carbon steel	Nickel plated
27	Magnet	Rare earth magnet	
28	Top plate	Stainless steel	
29	Head plate	Stainless steel	
30	Felt	Felt	

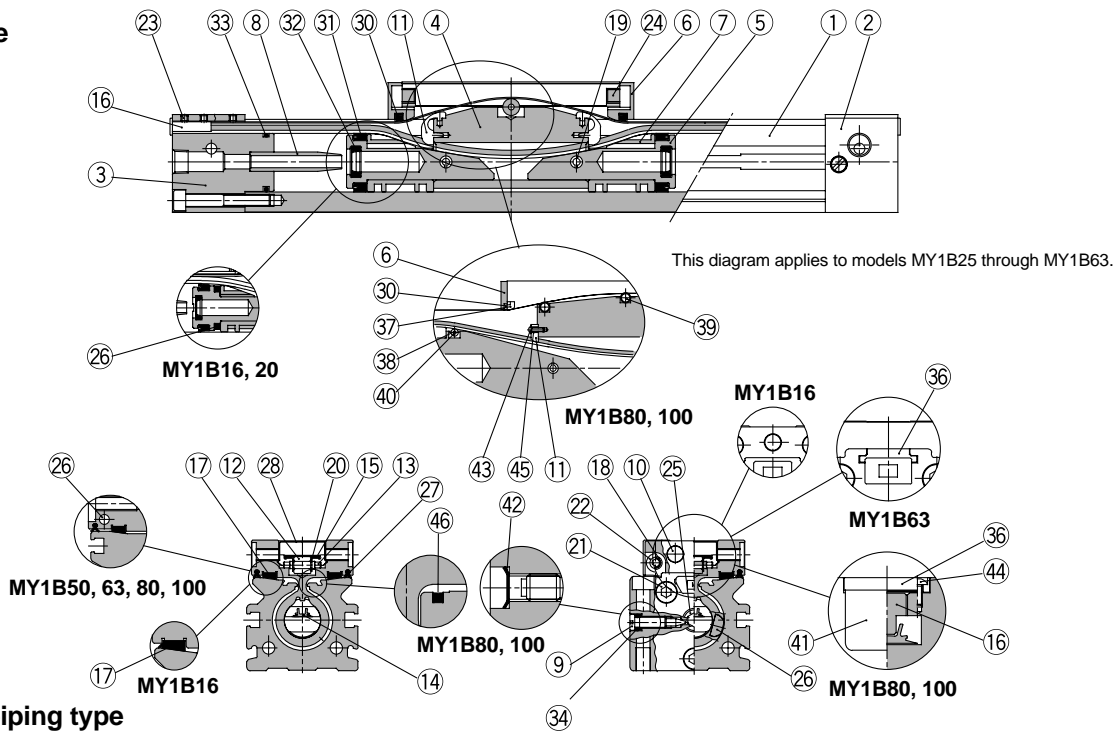
Seal list

No.	Description	Material	Qty.	MY1B10
13	Seal belt	Special resin	1	MY10-16A-stroke
14	Dust seal band	Stainless steel	1	MY10-16B-stroke
16	Scraper	NBR	2	MYB10-15AR0597
17	Piston seal	NBR	2	
18	Tube gasket	NBR	2	
19	O-ring	NBR	4	

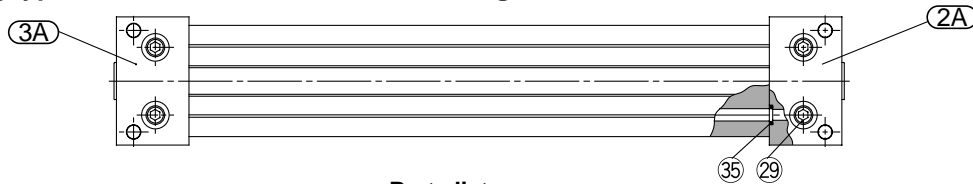
Series MY1B

Construction/∅16 to ∅100

Standard type



Centralized piping type



Parts list

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover R	Aluminum alloy	Hard anodized
2A	Head cover WR	Aluminum alloy	Hard anodized
3	Head cover L	Aluminum alloy	Hard anodized
3A	Head cover WL	Aluminum alloy	Hard anodized
4	Piston yoke	Aluminum alloy	Hard anodized
5	Piston	Aluminum alloy	Chromated
6	End cover	Special resin Carbon steel	Nickel plated (∅80 and ∅100)
7	Wear ring	Special resin	
8	Cushion ring	Brass	
9	Cushion needle	Rolled steel	Nickel plated
10	Stopper	Carbon steel	Nickel plated (∅16 to ∅40)
11	Belt separator	Special resin	
12	Guide roller	Special resin	
13	Guide roller shaft	Stainless steel	
16	Belt clamp	Special resin Aluminum alloy	Chromated (∅80 and ∅100)
17	Bearing	Special resin	
18	Spacer	Stainless steel	
19	Spring pin	Carbon tool steel	Black zinc chromated

Parts list

No.	Description	Material	Note
20	Type E retaining ring	Cold rolled special steel strip	
21	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
22	Hexagon socket head button bolt	Chrome molybdenum steel	Nickel plated
23	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated/Nickel plated
24	Double round parallel key	Carbon steel	(∅16 to ∅40)
25	Hexagon socket head taper plug	Carbon steel	Nickel plated
26	Magnet	Rare earth magnet	
27	Side scraper	Special resin	(Except ∅16)
28	Top cover	Stainless steel	
29	Hexagon socket head taper plug	Carbon steel	Nickel plated
36	Head plate	Aluminum alloy	Hard anodized (∅63 to ∅100)
37	Backup plate	Special resin	
38	Guide roller B	Special resin	(∅80 and ∅100)
39	Guide roller A	Stainless steel	(∅80 and ∅100)
40	Guide roller shaft B	Stainless steel	(∅80 and ∅100)
41	Side cover	Aluminum alloy	Hard anodized (∅80 and ∅100)
42	Type CR retaining ring	Spring steel	(∅80 and ∅100)
43	Hexagon socket head button bolt	Chrome molybdenum steel	Nickel plated (∅80 and ∅100)
44	Hexagon socket head button bolt	Chrome molybdenum steel	Nickel plated (∅80 and ∅100)
45	Spacer B	Stainless steel	(∅80 and ∅100)
46	Seal magnet	Rubber magnet	(∅80 and ∅100)

Seal list

No.	Description	Material	Qty.	MY1B16	MY1B20	MY1B25	MY1B32	MY1B40	MY1B50	MY1B63	MY1B80	MY1B100
14	Seal belt	Special resin	1	MY16-16A-Stroke	MY20-16A-Stroke	MY25-16A-Stroke	MY32-16A-Stroke	MY40-16A-Stroke	MY50-16A-Stroke	MY63-16A-Stroke	MY80-16A-Stroke	MY100-16A-Stroke
Note) 15	Dust seal band	Stainless steel	1	MY16-16B-Stroke	MY20-16B-Stroke	MY25-16B-Stroke	MY32-16B-Stroke	MY40-16B-Stroke	MY50-16B-Stroke	MY63-16B-Stroke	MY80-16B-Stroke	MY100-16B-Stroke
30	Scraper	NBR	2	MYB16-15AA7163	MYB20-15AA7164	MYB25-15AA5900	MYB32-15AA5901	MYB40-15AA5902	MYB50-15AA7165	MYB63-15AA7166	MYB80-15AK2470	MYB100-15AK2471
31	Piston seal	NBR	2									
32	Cushion seal	NBR	2									
33	Tube gasket	NBR	2									
34	O-ring	NBR	2									
35	O-ring	NBR	2									

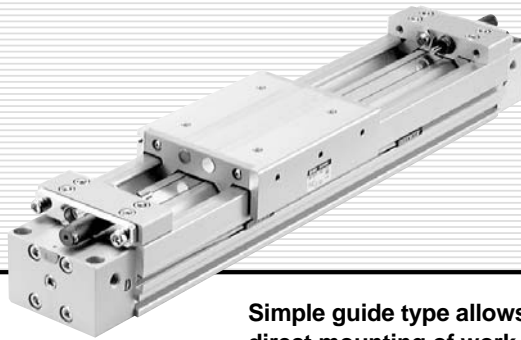
Note) Two types of dust seal band are available. Verify the type to use, since the part number varies depending on the treatment of the hexagon socket head set screw 23.

(A) Black zinc chromated → MY□□-16B-Stroke (B) Nickel plated → MY□□-16BW-Stroke

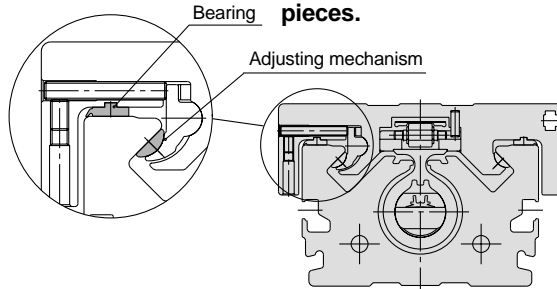
Series MY1M

Slide Bearing Type

ø16, ø20, ø25, ø32, ø40, ø50, ø63



Simple guide type allows direct mounting of work pieces.



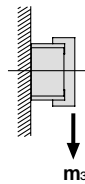
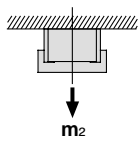
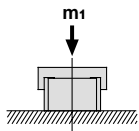
Before Operating Series MY1M

Maximum Allowable Moment/Maximum Allowable Load

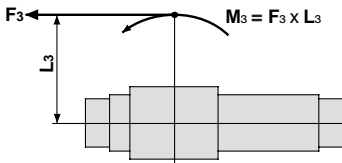
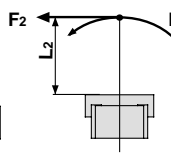
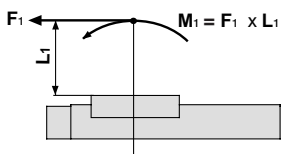
Model	Bore size (mm)	Max. allowable moment (N·m)			Max. allowable load (kg)		
		M ₁	M ₂	M ₃	m ₁	m ₂	m ₃
MY1M	16	6.0	3.0	1.0	18	7	2.1
	20	10	5.2	1.7	26	10.4	3
	25	15	9.0	2.4	38	15	4.5
	32	30	15	5.0	57	23	6.6
	40	59	24	8.0	84	33	10
	50	115	38	15	120	48	14
	63	140	60	19	180	72	21

The above values are the maximum allowable values for moment and load. Refer to each graph regarding the maximum allowable moment and maximum allowable load for a particular piston speed.

Load (kg)



Moment (N·m)



Maximum allowable moment

Select the moment from within the range of operating limits shown in the graphs. Note that the maximum allowable load value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable load for the selected conditions.

<Calculation of guide load factor>

1. Maximum allowable load (1), static moment (2), and dynamic moment (at the time of impact with stopper) (3) must be examined for the selection calculations.

* To evaluate, use \bar{v} (average speed) for (1) and (2), and v (impact speed $v = 1.4\bar{v}$) for (3).

Calculate m_{max} for (1) from the maximum allowable load graph (m_1, m_2, m_3) and M_{max} for (2) and (3) from the maximum allowable moment graph (M_1, M_2, M_3).

Maximum allowable load

Select the load from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.

$$\text{Sum of guide load factors } \Sigma \alpha = \frac{\text{Load mass [m]}}{\text{Maximum allowable load [m}_{max}\text{]}} + \frac{\text{Static moment [M]}^{\text{Note 1}}}{\text{Allowable static moment [M}_{max}\text{]}} + \frac{\text{Dynamic moment [ME]}^{\text{Note 2}}}{\text{Allowable dynamic moment [ME}_{max}\text{]}} \leq 1$$

Note 1) Moment caused by the load, etc., with cylinder in resting condition.

Note 2) Moment caused by the impact load equivalent at the stroke end (at the time of impact with stopper).

Note 3) Depending on the shape of the work piece, multiple moments may occur. When this happens, the sum of the load factors ($\Sigma \alpha$) is the total of all such moments.

2. Reference formulae [Dynamic moment at impact]

Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

- m : Load mass (kg)
- F : Load (N)
- F_E : Load equivalent to impact (impact with stopper)
- \bar{v} : Average speed (mm/s)
- M : Static moment (N·m)
- v : Impact speed (mm/s)
- L_1 : Distance to the load's center of gravity (m)
- ME : Dynamic moment (N·m)
- g : Gravitational acceleration (9.8m/s²)

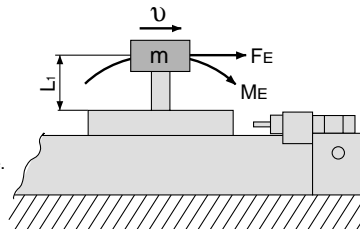
$$v = 1.4\bar{v} \text{ (mm/s)} \quad F_E = \frac{1.4}{100} \bar{v} a \cdot g \cdot m$$

$$\therefore ME = \frac{1}{3} \cdot F_E \cdot L_1 = 0.05\bar{v} a \cdot m \cdot L_1 \text{ (N·m)}$$

Note 4) $\frac{1.4}{100} \bar{v} a$ is a dimensionless coefficient for calculating impact force.

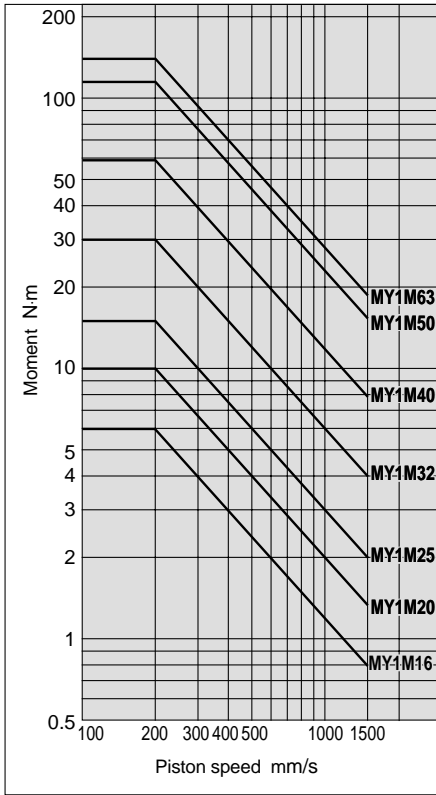
Note 5) Average load coefficient ($= \frac{1}{3}$):

This coefficient is for averaging the maximum load moment at the time of stopper impact according to service life calculations.

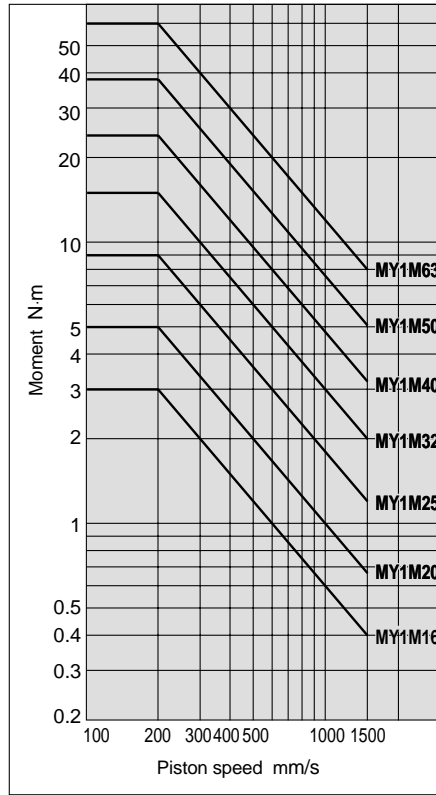


3. Refer to pages 2-566 and 2-567 for detailed selection procedures.

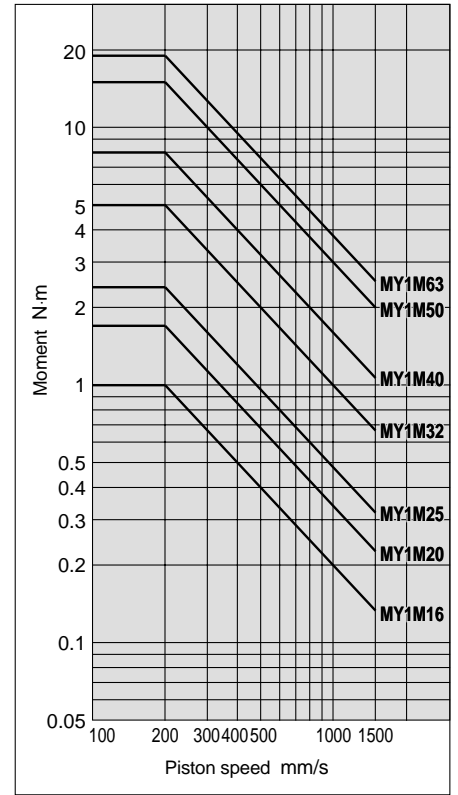
MY1M/M₁



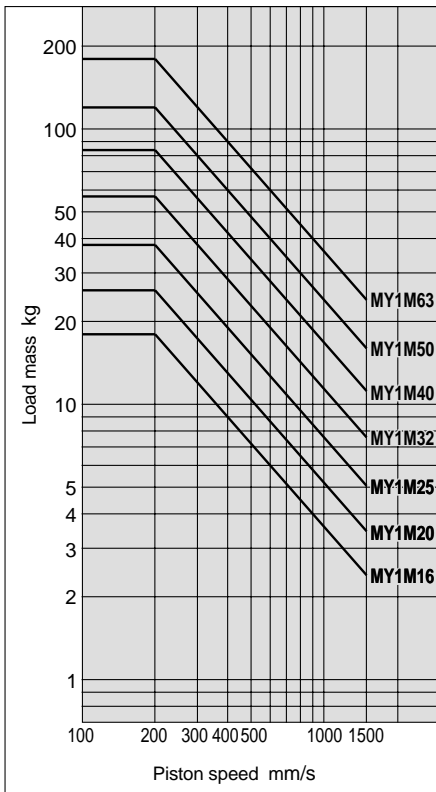
MY1M/M₂



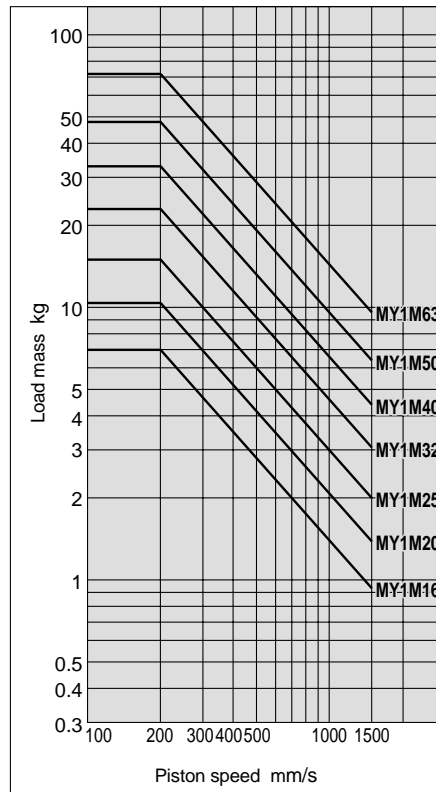
MY1M/M₃



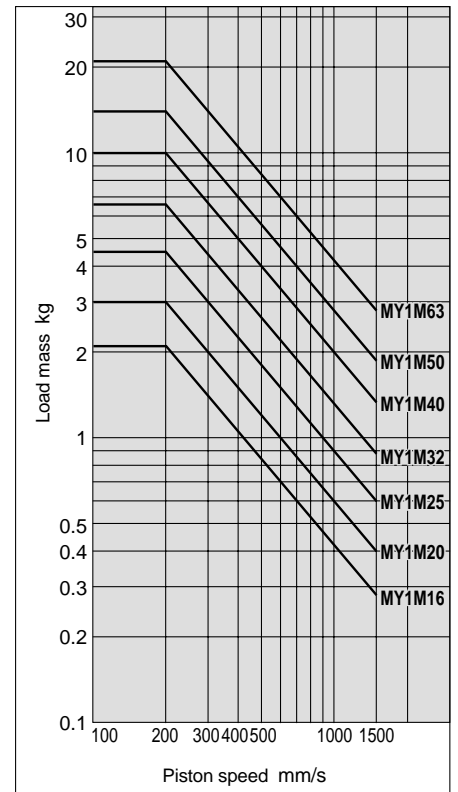
MY1M/m₁



MY1M/m₂



MY1M/m₃



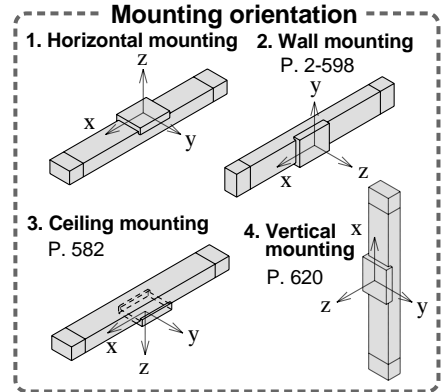
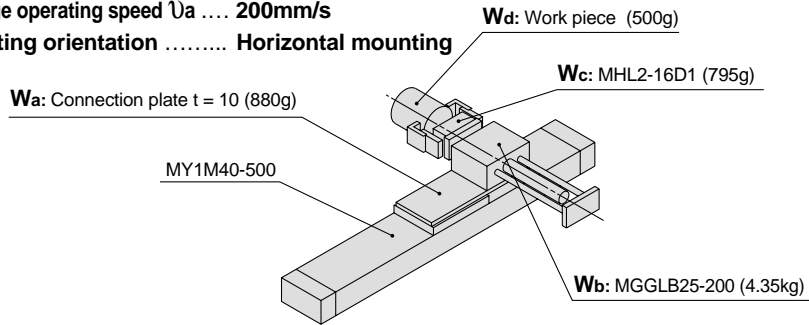
Series MY1M Model Selection

The following are steps for selection of the series MY1 best suited to your application.

Calculation of Guide Load Factor

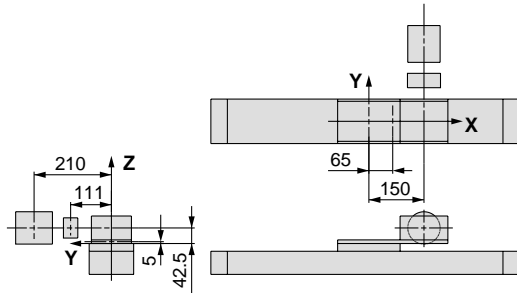
1 Operating conditions

Cylinder **MY1M40-500**
Average operating speed v_a **200mm/s**
Mounting orientation **Horizontal mounting**



Refer to the pages above for actual examples of calculation for each orientation.

2 Load blocking



Mass and centre of gravity for each work piece

Work piece no.	Mass m	Center of gravity		
		X-axis X_n	Y-axis Y_n	Z-axis Z_n
Wa	0.88kg	65mm	0mm	5mm
Wb	4.35kg	150mm	0mm	42.5mm
Wc	0.795kg	150mm	111mm	42.5mm
Wd	0.5kg	150mm	210mm	42.5mm

$n = a, b, c, d$

3 Composite centre of gravity calculation

$$m_1 = \sum m_n$$

$$= 0.88 + 4.35 + 0.795 + 0.5 = \mathbf{6.525kg}$$

$$X = \frac{1}{m_1} \times \sum (m_n \times X_n)$$

$$= \frac{1}{6.525} (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 0.5 \times 150) = \mathbf{138.5mm}$$

$$Y = \frac{1}{m_1} \times \sum (m_n \times y_n)$$

$$= \frac{1}{6.525} (0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 0.5 \times 210) = \mathbf{29.6mm}$$

$$Z = \frac{1}{m_1} \times \sum (m_n \times z_n)$$

$$= \frac{1}{6.525} (0.88 \times 5 + 4.35 \times 42.5 + 0.795 \times 42.5 + 0.5 \times 42.5) = \mathbf{37.4mm}$$

4 Calculation of load factor for static load

m_1 : Mass

m_1 max (from 1 of graph MY1M/ m_1) = 84 (kg)

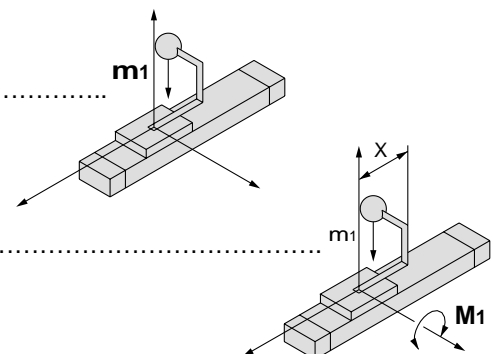
Load factor $\alpha_1 = m_1 / m_1 \text{ max} = 6.525 / 84 = \mathbf{0.08}$

M_1 : Moment

M_1 max (from 2 of graph MY1M/ M_1) = 59 (N·m)

$M_1 = m_1 \times g \times X = 6.525 \times 9.8 \times 138.5 \times 10^{-3} = 8.86$ (N·m)

Load factor $\alpha_2 = M_1 / M_1 \text{ max} = 8.86 / 59 = \mathbf{0.15}$

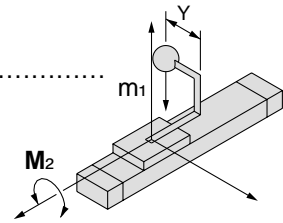


M₂: Moment

$M_2 \text{ max (from 3 of graph MY1M/M}_2) = 24 \text{ (N}\cdot\text{m) } \dots\dots\dots$

$M_3 = m_1 \times g \times Y = 6.525 \times 9.8 \times 29.6 \times 10^{-3} = 1.89 \text{ (N}\cdot\text{m)}$

Load factor $\alpha_3 = M_3/M_2 \text{ max} = 1.89/24 = \mathbf{0.08}$



5 Calculation of load factor for dynamic moment

Equivalent load F_E at impact

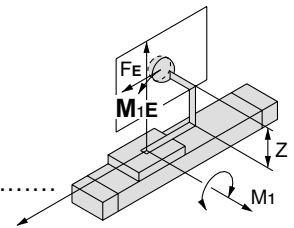
$F_E = \frac{1.4}{100} \times v_a \times g \times m = \frac{1.4}{100} \times 200 \times 9.8 \times 6.525 = 179.1 \text{ (N)}$

M_{1E}: Moment

$M_{1E} \text{ max (from 4 of graph MY1M/M}_1 \text{ where } 1.4v_a = 280\text{mm/s}) = 42.1 \text{ (N}\cdot\text{m) } \dots\dots\dots$

$M_{1E} = \frac{1}{3} \times F_E \times Z = \frac{1}{3} \times 179.1 \times 37.4 \times 10^{-3} = 2.23 \text{ (N}\cdot\text{m)}$

Load factor $\alpha_4 = M_{1E}/M_{1E} \text{ max} = 2.23/42.1 = \mathbf{0.05}$

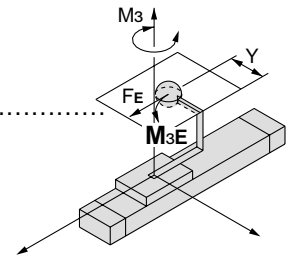


M_{3E}: Moment

$M_{3E} \text{ max (from 5 of graph MY1M/M}_3 \text{ where } 1.4v_a = 280\text{mm/s}) = 5.7 \text{ (N}\cdot\text{m) } \dots\dots\dots$

$M_{3E} = \frac{1}{3} \times F_E \times Y = \frac{1}{3} \times 179.1 \times 29.6 \times 10^{-3} = 1.77 \text{ (N}\cdot\text{m)}$

Load factor $\alpha_5 = M_{3E}/M_{3E} \text{ max} = 1.77/5.7 = \mathbf{0.31}$



6 Sum and examination of guide load factors

$\Sigma\alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 = \mathbf{0.67} \leq 1$

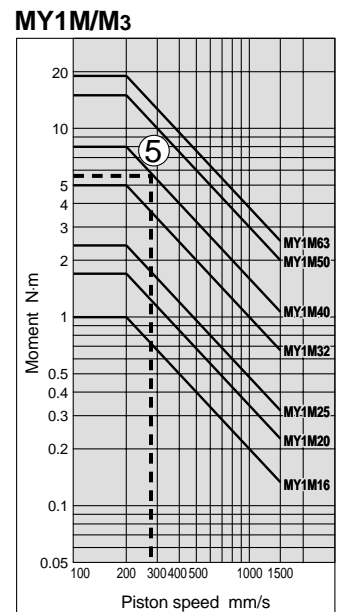
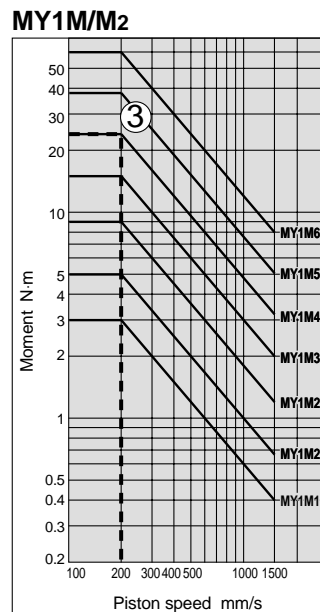
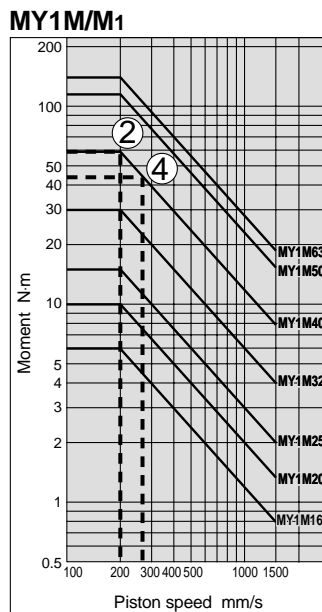
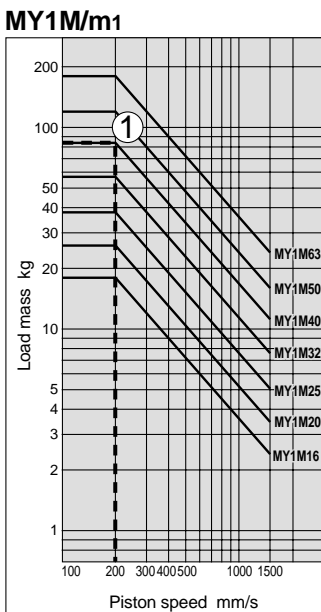
The above calculation is within the allowable value and the selected model can be used.

Select a separate shock absorber.

In an actual calculation, when the sum of guide load factors $\Sigma\alpha$ in the formula above is more than 1, consider decreasing the speed, increasing the bore size, or changing the product series. Also, this calculation can be performed easily with the "SMC Pneumatics CAD System".

Load mass

Allowable moment



Mechanically Jointed Rodless Cylinder

Series MY1M

Slide Bearing Type/ø16, ø20, ø25, ø32, ø40, ø50, ø63

How to Order

Slide Bearing Guide Type **E MY1M 25** **300** **Z73**

Thread Port (ø25 to ø63)

—	Rc(PT)
E	G(PF)

Slider bearing guide type

Bore size

16	16mm
20	20mm
25	25mm
32	32mm
40	40mm
50	50mm
63	63mm

Stroke
Refer to the standard stroke table on page 2-569

Piping

Nil	Standard type
G	Centralized piping type

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	"n" pcs.

Auto switch type

Nil	Without auto switch
------------	---------------------

* Refer to the table below for auto switch model numbers.

Stroke adjusting unit (Note)

Nil	Both ends
S	One end

Note) "S" is applicable for stroke adjusting units A, L and H.

Nil	Without adjusting unit
A	With adjusting bolt
L	With low load shock absorber + adjusting bolt
H	With high load shock absorber + adjusting bolt
AL	With one A unit and one L unit each
AH	With one A unit and one H unit each
LH	With one L unit and one H unit each

Shock absorbers for L and H units

Bore size (mm)	16	20	25	32	40	50	63
L unit	RB0806	RB1007	RB1412	RB2015	RB2015		
H unit	—	RB1007	RB1412	RB2015	RB2725		

Note) MY1M16 is not available with H unit.

Options

Stroke adjusting unit numbers

Bore size (mm)	16	20	25	32
A unit	MYM-A16A	MYM-A20A	MYM-A25A	MYM-A32A
L unit	MYM-A16L	MYM-A20L	MYM-A25L	MYM-A32L
H unit	—	MYM-A20H	MYM-A25H	MYM-A32H

Bore size (mm)	40	50	63
A unit	MYM-A40A	MYM-A50A	MYM-A63A
L unit	MYM-A40L	MYM-A50L	MYM-A63L
H unit	MYM-A40H	MYM-A50H	MYM-A63H

Side support numbers

Bore size (mm)	16	20	25	32
Side support A	MY-S16A	MY-S20A	MY-S25A	MY-S32A
Side support B	MY-S16B	MY-S20B	MY-S25B	MY-S32B

Bore size (mm)	40	50	63
Side support A	MY-S40A	MY-S63A	
Side support B	MY-S40B	MY-S63B	

Refer to page 2-576 for detailed information on dimensions, etc.

Applicable auto switches/

For ø16, ø20

Type	Special function	Electrical entry	Indicator/light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load								
					DC	AC	Electrical entry direction		0.5 (Nil)	3 (L)	5 (Z)	Applicable load								
							Perpendicular	In-line				IC circuit	Relay, PLC							
Reed switch	—	Grommet	No	2 wire	24V	5V 12V 100V or less	A90V	A90	●	●	—	IC circuit	Relay, PLC							
									Yes	3 wire (NPN equiv.)	—	5V		—	A96V	A96	●	●	—	IC circuit
																	Solid state switch	—	Grommet	Yes
3 wire (NPN)	M9PV	M9P	●	●	—															
			3 wire (PNP)	M9BV	M9B	●	●	—												
2 wire	M9NWV	M9NW				●	●	○	—	Relay, PLC										
			3 wire (NPN)	M9PWV	M9PW	●	●	○												
3 wire (PNP)	M9B WV	M9B W				●	●	○												
			2 wire																	

* Lead wire length symbols: 0.5m Nil (Example) M9NW
3m L M9NWL
5m Z M9NWZ

** Solid state switches marked with a "O" symbol are produced upon receipt of order.

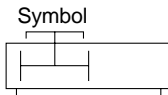
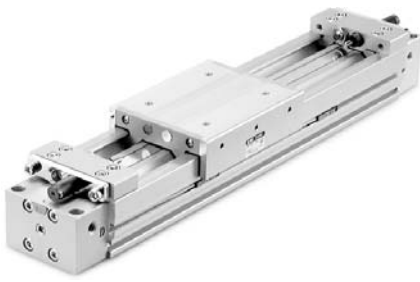
For ø25, ø32, ø40, ø50, ø63

Type	Special function	Electrical entry	Indicator/light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load		
					DC	AC	Electrical entry direction		0.5 (Nil)	3 (L)	5 (Z)	Applicable load		
							Perpendicular	In-line				IC circuit	Relay, PLC	
Reed switch	—	Grommet	Yes	3 wire (NPN equiv.)	24V	5V 12V 100V or less	—	Z76	●	●	—	IC circuit	—	
									No	2 wire	—	—		—
Solid state switch	—	Grommet	Yes	3 wire (NPN)	24V	5V 12V	—	Y69A					Y59A	
									3 wire (PNP)	Y7PV	Y7P	●		●
				2 wire	12V	—	—	—				Y69B	Y59B	●
									3 wire (NPN)	24V	5V 12V			—
				3 wire (PNP)	Y7PWV	Y7PW	●	●				○		
							2 wire	12V	—	—	—	Y7B WV	Y7B W	●

* Lead wire length symbols: 0.5m Nil (Example) Y59A
3m L Y59AL
5m Z Y59AZ

** Solid state switches marked with a "O" symbol are produced upon receipt of order.

Specifications



Bore size (mm)	16	20	25	32	40	50	63
Fluid	Air						
Action	Double acting						
Operating pressure range	0.15 to 0.8MPa						
Proof pressure	1.2MPa						
Ambient and fluid temperature	5 to 60°C						
Cushion	Air cushion						
Lubrication	Non-lube						
Stroke length tolerance	1000 or less ^{+1.8} ₀ 1001 to 3000 ^{+2.8} ₀		2700 or less ^{+1.8} ₀ , 2701 to 5000 ^{+2.8} ₀				
Port size	Front/Side ports		M5 x 0.8		1/8	1/4	3/8
	Bottom ports (centralized piping type only)		∅4	∅5	∅6	∅8	∅10 ∅11

Stroke adjusting unit specifications

Bore size (mm)	16		20			25			32			40			50			63			
Unit symbol	A	L	A	L	H	A	L	H	A	L	H	A	L	H	A	L	H	A	L	H	
Configuration and shock absorber	With adjusting bolt	With RB 0806 + adjusting bolt	With adjusting bolt	With RB 0806 + adjusting bolt	With RB 1007 + adjusting bolt	With adjusting bolt	With RB 1007 + adjusting bolt	With RB 1412 + adjusting bolt	With adjusting bolt	With RB 1412 + adjusting bolt	With RB 2015 + adjusting bolt	With adjusting bolt	With RB 1412 + adjusting bolt	With RB 2015 + adjusting bolt	With adjusting bolt	With RB 2015 + adjusting bolt	With RB 2725 + adjusting bolt	With adjusting bolt	With RB 2015 + adjusting bolt	With RB 2725 + adjusting bolt	
Stroke fine adjusting range (mm)	0 to -5.6		0 to -6			0 to -11.5			0 to -12			0 to -16			0 to -20			0 to -25			
Stroke adjusting range	When exceeding the stroke fine adjusting range: Use order made specifications "-X416" and "-X417". (Refer to page 2-645 for details.)																				

Shock absorber specifications

Model	RB 0806	RB 1007	RB 1412	RB 2015	RB 2725	
Max. energy absorption (J)	2.9	5.9	19.6	58.8	147	
Stroke absorption (mm)	6	7	12	15	25	
Max. impact speed (mm/s)	1500					
Max. operating frequency (cycles/min)	80	70	45	25	10	
Spring force (N)	Extended	1.96	4.22	6.86	8.34	8.83
	Compressed	4.22	6.86	15.98	20.50	20.01
Operating temperature range (°C)	5 to 60					

Piston speed

Bore size (mm)	16 to 63	
Without stroke adjusting unit	100 to 1000mm/s	
Stroke adjusting unit	A unit	100 to 1000mm/s Note 1)
	L unit and H unit	100 to 1500mm/s Note 2)

Note 1) Be aware that when the stroke adjusting range is increased by manipulating the adjusting bolt, the air cushion capacity decreases. Also, when exceeding the air cushion stroke ranges on page 2-570, the **piston speed** should be **100 to 200mm per second**.

Note 2) For centralized piping, the piston speed is 100 to 1000mm per second.

Note 3) Use at a speed within the absorption capacity range. Refer to page 2-570

Theoretical output

Unit: N

Bore size (mm)	Piston area (mm ²)	Operating pressure (MPa)							
		0.2	0.3	0.4	0.5	0.6	0.7	0.8	
16	200	40	60	80	100	120	140	160	
20	314	62	94	125	157	188	219	251	
25	490	98	147	196	245	294	343	392	
32	804	161	241	322	402	483	563	643	
40	1256	251	377	502	628	754	879	1005	
50	1962	392	588	784	981	1177	1373	1569	
63	3115	623	934	1246	1557	1869	2180	2492	

1N = Approx. 0.102kgf. 1MPa = Approx.10.2kgf/cm²

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)



Order made specifications

Refer to page 2-645 regarding order made specifications for series MY1M.

Standard strokes

Bore size (mm)	Standard stroke (mm)*	Max. manufacturable stroke (mm)
16	100, 200, 300, 400, 500, 600, 700	3000
20, 25, 32, 40, 50, 63	800, 900, 1000, 1200, 1400, 1600, 1800, 2000	5000

* Strokes are manufacturable in 1mm increments, up to the maximum stroke. However, when exceeding a 2000mm stroke, specify "-XB11" at the end of the model number. Refer to the order made specifications on page 2-644

Weights

Unit: kg

Bore size (mm)	Basic weight	Additional weight per 50mm of stroke	Side support weight (per set)	Stroke adjusting unit weight (per unit)		
			Type A and B	A unit	L unit	H unit
16	0.67	0.12	0.01	0.03	0.04	—
20	1.11	0.16	0.02	0.04	0.05	0.08
25	1.64	0.24	0.02	0.07	0.11	0.18
32	3.27	0.38	0.04	0.14	0.23	0.39
40	5.88	0.56	0.08	0.25	0.34	0.48
50	10.06	0.77	0.08	0.36	0.51	0.81
63	16.57	1.11	0.17	0.68	0.83	1.08

Calculation method Example: **MY1M25-300A**

Basic weight 1.64kg Cylinder stroke 300mm
 Additional weight 0.24/50mm stroke 1.64 + 0.24 x 300 ÷ 50 + 0.07 x 2 = Approx. 3.22kg
 Weight of A unit 0.07kg



Series MY1M

Cushion Capacity

Cushion selection

<Air cushion>

Air cushions are a standard feature on mechanically jointed rodless cylinders.

The air cushion mechanism is installed to avoid excessive impact of the piston at the stroke end during high speed operation. The air cushion does not act to decelerate the piston near the stroke end.

The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

<Stroke adjusting unit with shock absorber>

Use this unit when operating with a load or speed exceeding the air cushion limit line, or when cushioning is necessary because the cylinder stroke is outside of the effective air cushion stroke range due to stroke adjustment.

L unit

Use this unit when the cylinder stroke is outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

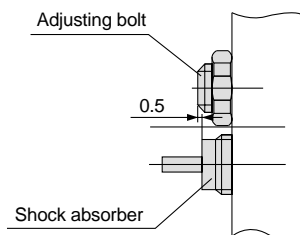
H unit

Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

⚠ Caution

1. Refer to the diagram below when using the adjusting bolt to perform stroke adjustment.

When the effective stroke of the shock absorber decreases as a result of stroke adjustment, the absorption capacity decreases dramatically. Secure the adjusting bolt at the position where it protrudes approximately 0.5mm from the shock absorber.



2. Do not use a shock absorber and air cushion together.

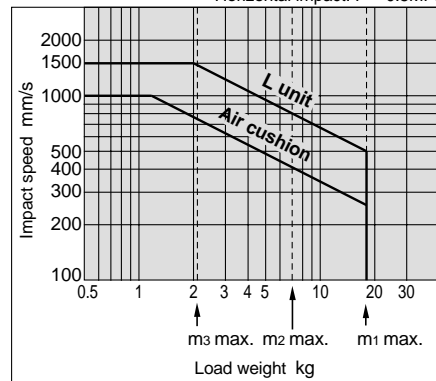
Air cushion stroke

Unit: mm

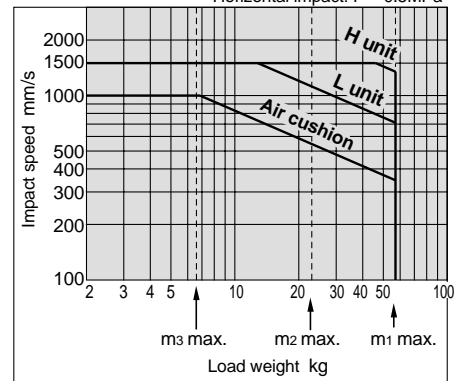
Bore size (mm)	Cushion stroke
16	12
20	15
25	15
32	19
40	24
50	30
63	37

Absorption capacity of air cushion and stroke adjusting units

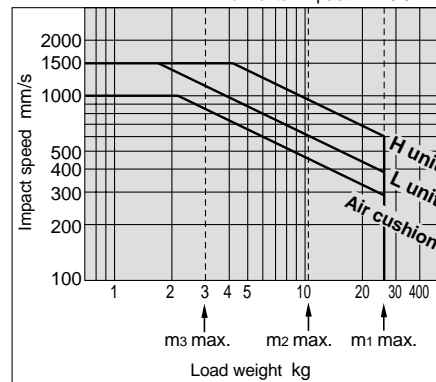
MY1M16 Horizontal impact: P = 0.5MPa



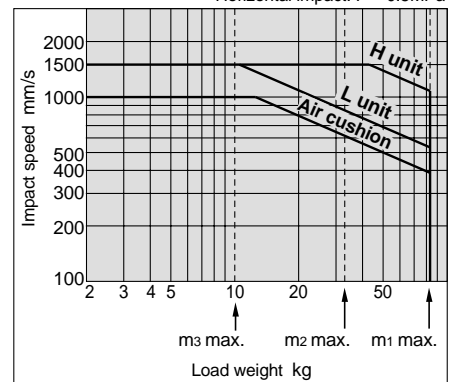
MY1M32 Horizontal impact: P = 0.5MPa



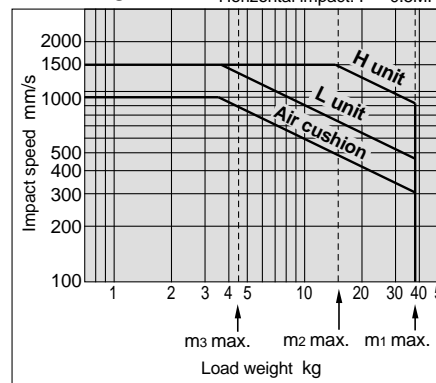
MY1M20 Horizontal impact: P = 0.5MPa



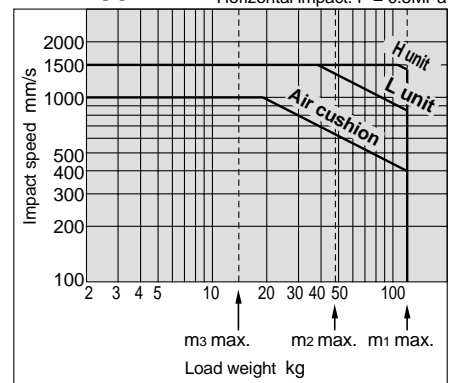
MY1M40 Horizontal impact: P = 0.5MPa



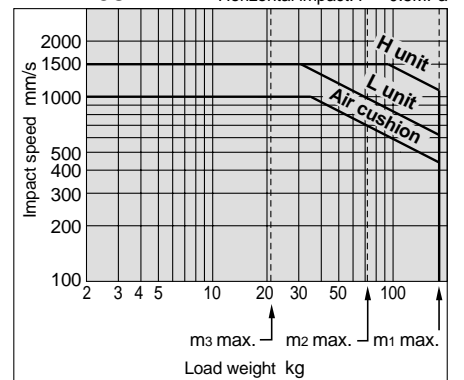
MY1M25 Horizontal impact: P = 0.5MPa



MY1M50 Horizontal impact: P = 0.5MPa



MY1M63 Horizontal impact: P = 0.5MPa



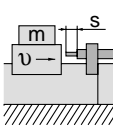
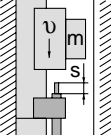
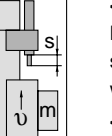
Stroke adjusting unit holding bolt tightening torque Unit: N·m

Bore size (mm)	Unit	Tightening torque
16	A	0.6
	L	
20	A	1.5
	L	
	H	
25	A	3.0
	L	
	H	
32	A	5.0
	L	
	H	
40	A	12
	L	
	H	
50	A	12
	L	
	H	
63	A	24
	L	
	H	

Stroke adjusting unit lock plate holding bolt tightening torque Unit: N·m

Bore size (mm)	Unit	Tightening torque
25	L	1.2
	H	3.3
32	L	3.3
	H	10
40	L	3.3
	H	10

Calculation of absorbed energy for stroke adjusting unit with shock absorber Unit: N·m

Type of impact	Horizontal	Vertical (downward)	Vertical (upward)
Kinetic energy E_1			
Thrust energy E_2	$F \cdot s$	$F \cdot s + m \cdot g \cdot s$	$F \cdot s - m \cdot g \cdot s$
Absorbed energy E	$E_1 + E_2$		

Symbols

- v : Speed of impacting object (m/s)
- m : Weight of impacting object (kg)
- F : Cylinder thrust (N)
- g : Gravitational acceleration (9.8m/s²)
- s : Shock absorber stroke (m)

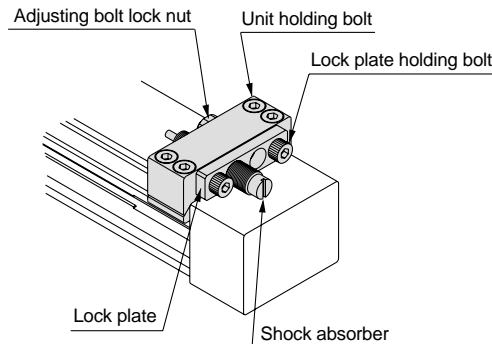
(Note) The speed of the impacting object is measured at the time of impact with the shock absorber.

Specific product precautions

Caution

Be careful not to get hands caught in the unit.

- When using a product with stroke adjusting unit, the space between the slide table (slider) and the stroke adjusting unit becomes narrow, causing a danger of hands getting caught. Install a protective cover to prevent direct contact with the human body.



<Fastening of unit>

The unit can be fastened by uniformly tightening the four unit holding bolts.

Caution

Do not operate with the stroke adjusting unit fixed in an intermediate position.

When the stroke adjusting unit is fixed in an intermediate position, slippage can occur depending on the amount of energy released at the time of an impact. In this case, we recommend using the adjusting bolt mounting brackets available with order made specifications – X 416 and – X 417.

For other lengths, consult SMC. (Refer to "Stroke adjustment unit holding bolt tightening torque".)

<Stroke adjustment with adjusting bolt>

Loosen the adjusting bolt lock nut, and adjust the stroke from the lock plate side using a hexagon wrench. Re-tighten the lock nut.

<Stroke adjustment with shock absorber>

Loosen the two lock plate holding bolts, turn the shock absorber and adjust the stroke. Then, uniformly tighten the lock plate holding bolts to secure the shock absorber.

Take care not to over-tighten the holding bolts. (Except ø10 and ø20 L unit.) (Refer to "Stroke adjusting unit lock plate holding bolt tightening torque".)

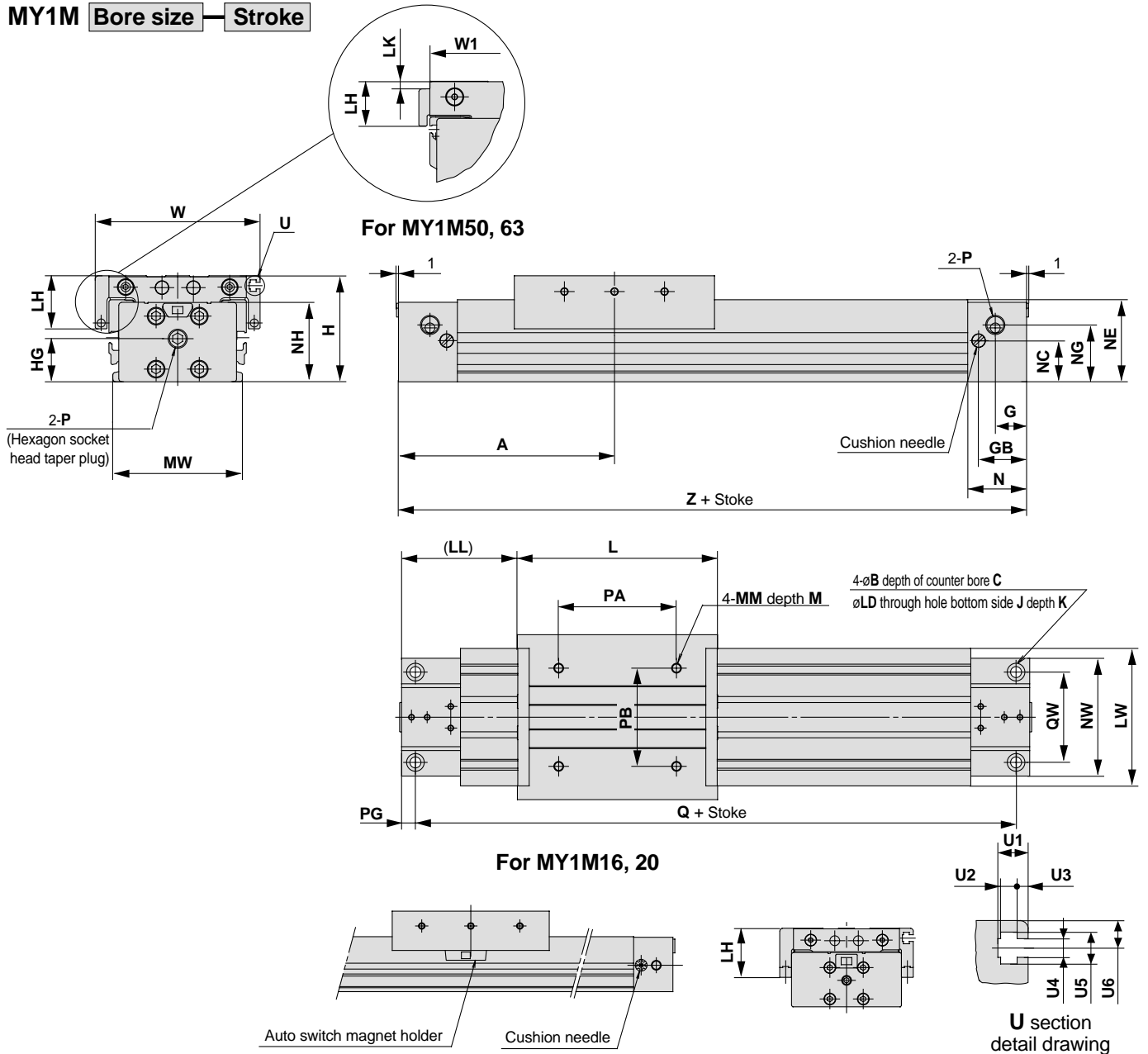
Note)

Slight bending may occur in the lock plate due to tightening of the lock plate holding bolts. This is not a problem for the shock absorber and locking function.

Series MY1M

Standard Type $\varnothing 16$ to $\varnothing 63$

MY1M Bore size — Stroke



Model	A	B	C	G	GB	H	HG	J	K	L	LD	LH	(LL)	LW	M	MM	MW	N
MY1M16	80	6	3.5	8.5	16.2	40	13.5	M5 x 0.8	10	80	3.6	22.5	40	54	6	M4 x 0.7	—	20
MY1M20	100	7.5	4.5	10.5	20	46	17	M6 x 1	12	100	4.8	23	50	58	7.5	M5 x 0.8	—	25
MY1M25	110	9	5.5	16	24.5	54	22	M6 x 1	9.5	102	5.6	27	59	70	10	M5 x 0.8	66	30
MY1M32	140	11	6.5	19	30	68	27	M8 x 1.25	16	132	6.8	35	74	88	13	M6 x 1	80	37
MY1M40	170	14	8.5	23	36.5	84	34.5	M10 x 1.5	15	162	8.6	38	89	104	13	M6 x 1	96	45
MY1M50	200	17	10.5	25	37.5	107	45	M14 x 2	28	200	11	29	100	128	15	M8 x 1.25	—	47
MY1M63	230	19	12.5	27.5	39.5	130	59	M16 x 2	32	230	13.5	32.5	115	152	16	M10 x 1.5	—	50

Model	NC	NE	NG	NH	NW	P	PA	PB	PG	Q	QW	W	W1	LK	Z
MY1M16	13.5	28	13.5	27.7	56	M5 x 0.8	40	40	3.5	153	48	68	—	—	160
MY1M20	17	34	17	33.7	60	M5 x 0.8	50	40	4.5	191	45	72	—	—	200
MY1M25	21	41.8	29	40.5	60	1/8	60	50	7	206	46	84	—	—	220
MY1M32	26	52.3	34	50	74	1/8	80	60	8	264	60	102	—	—	280
MY1M40	32	65.3	42.5	63.5	94	1/4	100	80	9	322	72	118	—	—	340
MY1M50	43.5	84.5	54	83.5	118	3/8	120	90	10	380	90	144	128	2	400
MY1M63	56	104	68	105	142	3/8	140	110	12	436	110	168	152	5.5	460

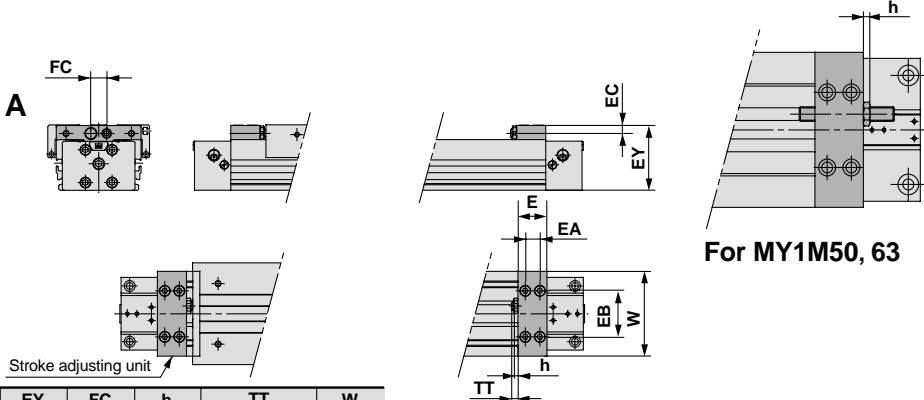
U section detail dimensions

Model	U1	U2	U3	U4	U5	U6
MY1M16	5.5	3	2	3.4	5.8	5
MY1M20	5.5	3	2	3.4	5.8	5.5
MY1M25	5.5	3	2	3.4	5.8	5
MY1M32	5.5	3	2	3.4	5.8	7
MY1M40	6.5	3.8	2	4.5	7.3	8
MY1M50	6.5	3.8	2	4.5	7.3	8
MY1M63	8.5	5	2.5	5.5	8.4	8

*P indicates cylinder supply ports. * The plug for MY1M16/20-P is a hexagon socket head plug.

**Stroke Adjusting Unit
With adjusting bolt**

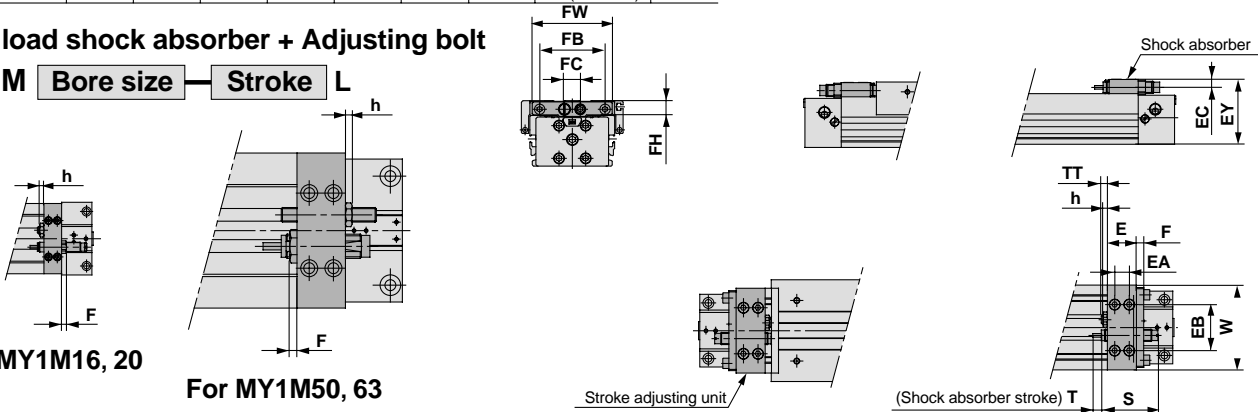
MY1M **Bore size** — **Stroke** **A**



Model	E	EA	EB	EC	EY	FC	h	TT	W
MY1M16	14.6	7	30	5.8	39.5	14	3.6	5.4 (max. 11)	58
MY1M20	20	10	32	5.8	45.5	14	3.6	5 (max. 11)	58
MY1M25	24	12	38	6.5	53.5	13	3.5	5 (max. 16.5)	70
MY1M32	29	14	50	8.5	67	17	4.5	8 (max. 20)	88
MY1M40	35	17	57	10	83	17	4.5	9 (max. 25)	104
MY1M50	40	20	66	14	106	26	5.5	13 (max. 33)	128
MY1M63	52	26	77	14	129	31	5.5	13 (max. 38)	152

Low load shock absorber + Adjusting bolt

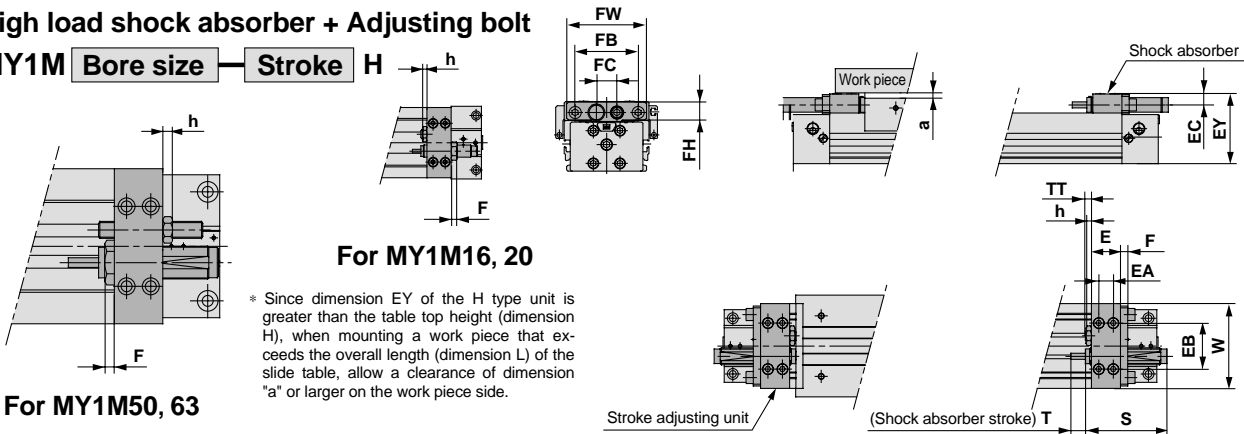
MY1M **Bore size** — **Stroke** **L**



Model	E	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	T	TT	W	Shock absorber model
MY1M16	14.6	7	30	5.8	39.5	4	—	14	—	—	3.6	40.8	6	5.4 (max. 11)	58	RB0806
MY1M20	20	10	32	5.8	45.5	4	—	14	—	—	3.6	40.8	6	5 (max. 11)	58	RB0806
MY1M25	24	12	38	6.5	53.5	6	54	13	13	66	3.5	46.7	7	5 (max. 16.5)	70	RB1007
MY1M32	29	14	50	8.5	67	6	67	17	16	80	4.5	67.3	12	8 (max. 20)	88	RB1412
MY1M40	35	17	57	10	83	6	78	17	17.5	91	4.5	67.3	12	9 (max. 25)	104	RB1412
MY1M50	40	20	66	14	106	6	—	26	—	—	5.5	73.2	15	13 (max. 33)	128	RB2015
MY1M63	52	26	77	14	129	6	—	31	—	—	5.5	73.2	15	13 (max. 38)	152	RB2015

High load shock absorber + Adjusting bolt

MY1M **Bore size** — **Stroke** **H**



* Since dimension EY of the H type unit is greater than the table top height (dimension H), when mounting a work piece that exceeds the overall length (dimension L) of the slide table, allow a clearance of dimension "a" or larger on the work piece side.

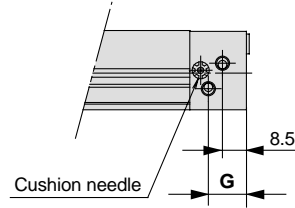
Model	E	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	T	TT	W	Shock absorber model	a
MY1M20	20	10	32	7.7	50	5	—	14	—	—	3.5	46.7	7	5 (max. 11)	58	RB1007	5
MY1M25	24	12	38	9	57.5	6	52	17	16	66	4.5	67.3	12	5 (max. 16.5)	70	RB1412	4.5
MY1M32	29	14	50	11.5	73	8	67	22	22	82	5.5	73.2	15	8 (max. 20)	88	RB2015	6
MY1M40	35	17	57	12	87	8	78	22	22	95	5.5	73.2	15	9 (max. 25)	104	RB2015	4
MY1M50	40	20	66	18.5	115	8	—	30	—	—	11	99	25	13 (max. 33)	128	RB2725	9
MY1M63	52	26	77	19	138.5	8	—	35	—	—	11	99	25	13 (max. 38)	152	RB2725	9.5

Series MY1M

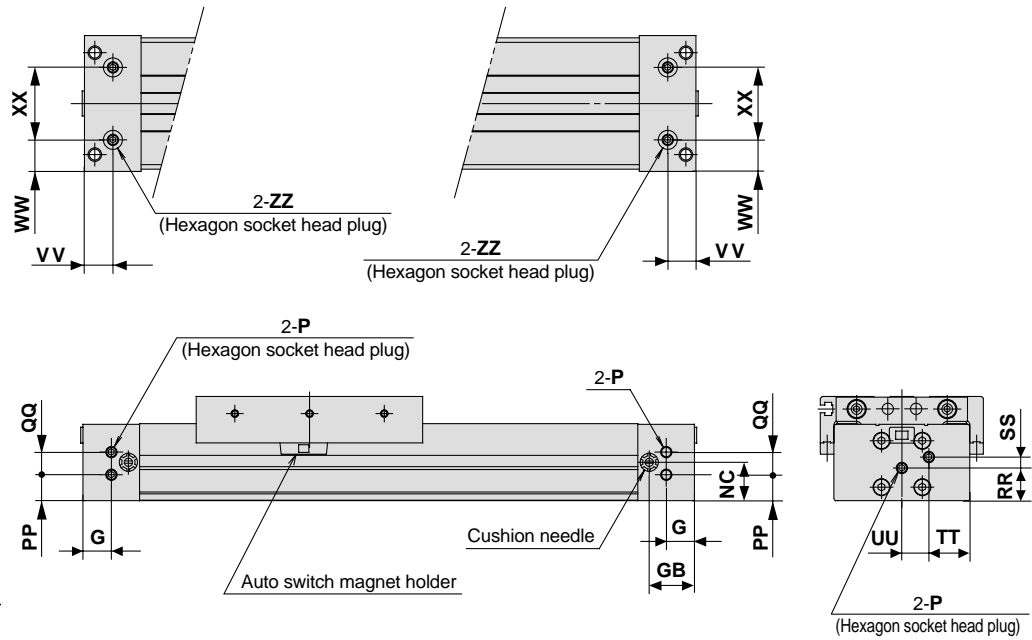
Centralized Piping Type $\varnothing 16, \varnothing 20$

Refer to page 2-648 regarding centralized piping port variations. Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions. Refer to pages 2-572 and 2-573 for details regarding dimensions etc.

MY1M Bore size **G** — Stroke

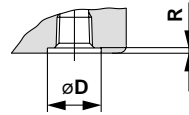
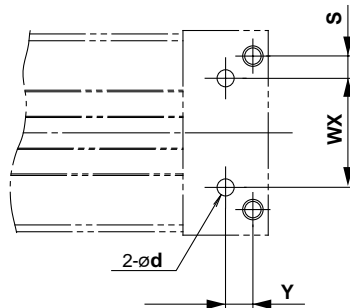


For MY1M16



Model	G	GB	NC	P	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1M16G	13.5	16.2	14	M5	7.5	9	11	2.5	15	14	10	13	30	M5
MY1M20G	12.5	20	17	M5	11.5	10	14.5	5	18	12	12.5	14	32	M5

*"P" indicates cylinder supply ports.



Bottom side (ZZ) piping (applicable O-ring)

Hole sizes for centralized piping on the bottom

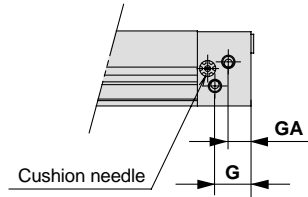
(Machine the mounting side to the dimensions below.)

Model	WX	Y	S	d	D	R	Applicable O-ring
MY1M16G	30	6.5	9	4	8.4	1.1	C6
MY1M20G	32	8	6.5	4	8.4	1.1	

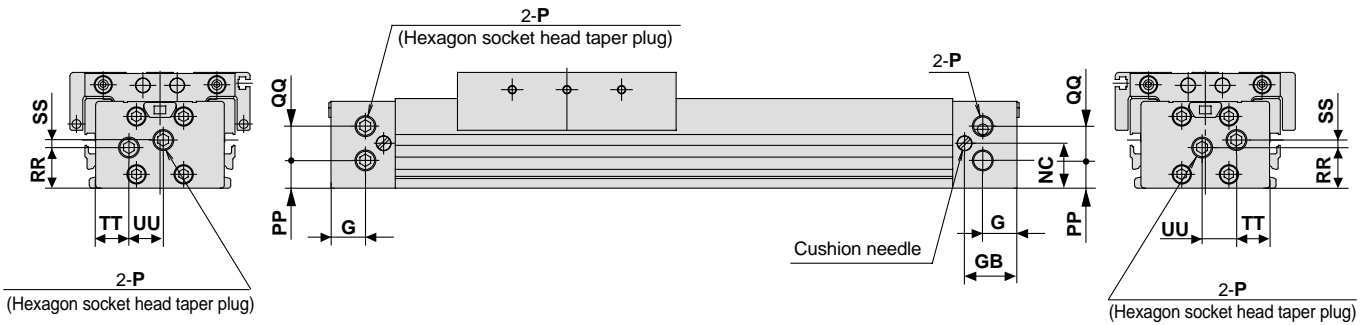
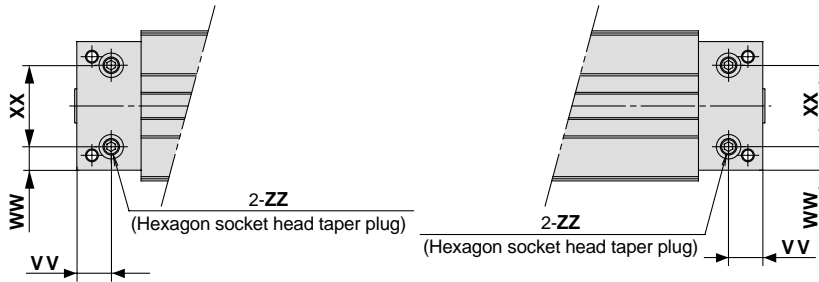
Centralized Piping Type $\varnothing 25$ to $\varnothing 63$

Refer to page 2-648 regarding centralized piping port variations.
Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions.
Refer to pages 2-572 and 2-573 for details regarding dimensions, etc.

MY1M Bore size **G** — Stroke

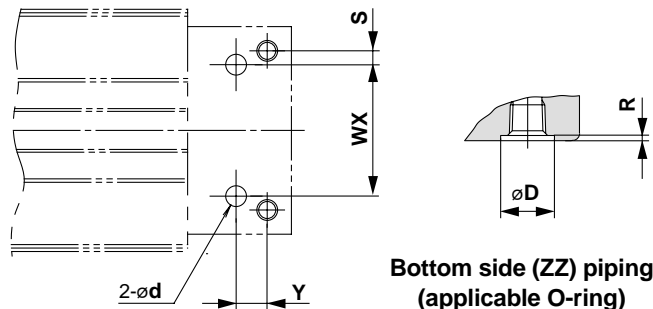


For MY1M50, 63



Model	G	GA	GB	NC	P	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1M25G	16	—	24.5	21	1/8	13	16	19	3.5	15.5	16	16	11	38	1/16
MY1M32G	19	—	30	26	1/8	18	16	24	4	21	16	19	13	48	1/16
MY1M40G	23	—	36.5	32	1/4	16.5	26	25.5	10.5	22.5	24.5	23	20	54	1/8
MY1M50G	27	25	37.5	43.5	3/8	26	28	35	10	35	24	28	22	74	1/4
MY1M63G	29.5	27.5	39.5	60	3/8	42	30	49	13	43	28	30	25	92	1/4

P indicates cylinder supply ports.



Bottom side (ZZ) piping
(applicable O-ring)

Hole sizes for centralized piping on the bottom

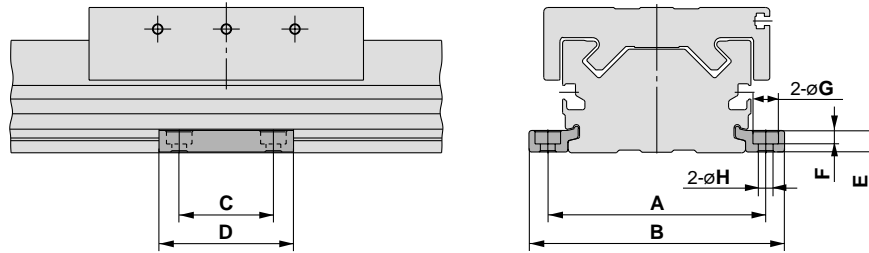
(Machine the mounting side to the dimensions below.)

Model	WX	Y	S	d	D	R	Applicable O-ring
MY1M25G	38	9	4	6	11.4	1.1	C9
MY1M32G	48	11	6			1.1	
MY1M40G	54	14	9	8	13.4	1.1	C11.2
MY1M50G	74	18	8	10	17.5	1.1	C15
MY1M63G	92	18	9	10	17.5	1.1	

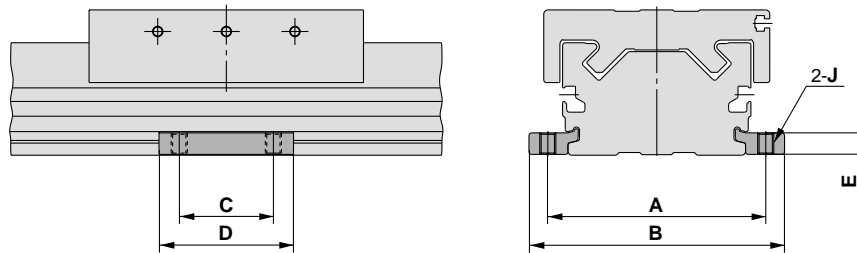
Series MY1M

Side Support

Side support A MY-S□A



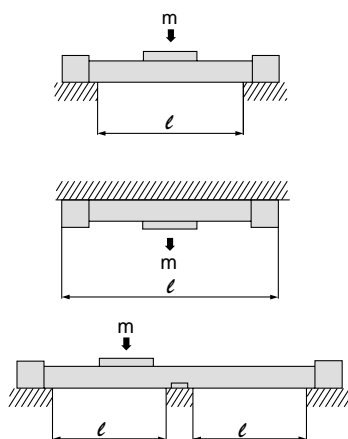
Side support B MY-S□B



Model	Applicable cylinder	A	B	C	D	E	F	G	H	J
MY-S16 ^A _B	MY1M16	61	71.6	15	26	4.9	3	6.5	3.4	M4
MY-S20 ^A _B	MY1M20	67	79.6	25	38	6.4	4	8	4.5	M5
MY-S25 ^A _B	MY1M25	81	95	35	50	8	5	9.5	5.5	M6
MY-S32 ^A _B	MY1M32	100	118	45	64	11.7	6	11	6.6	M8
MY-S40 ^A _B	MY1M40	120	142	55	80	14.8	8.5	14	9	M10
	MY1M50	142	164							
MY-S63 ^A _B	MY1M63	172	202	70	100	18.3	10.5	17.5	11.5	M12

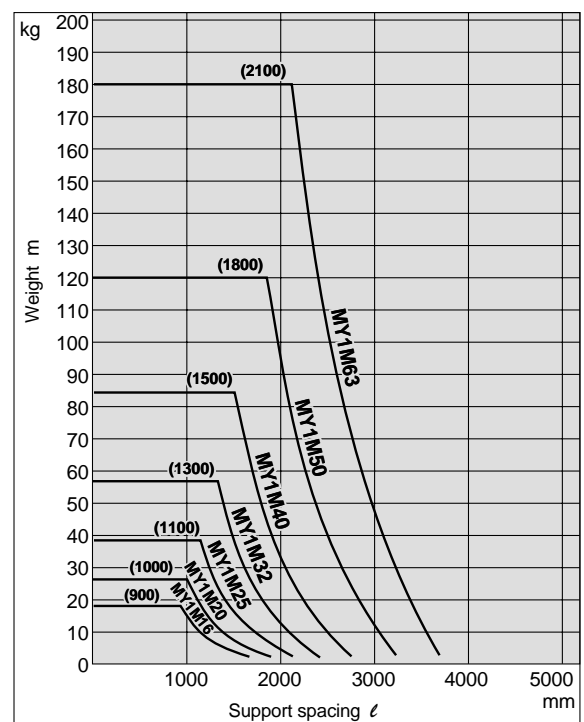
Guide for Using Side Supports

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load weight. In such a case, use a side support in the middle section. The spacing (ℓ) of the support must be no more than the values shown in the graph on the right.



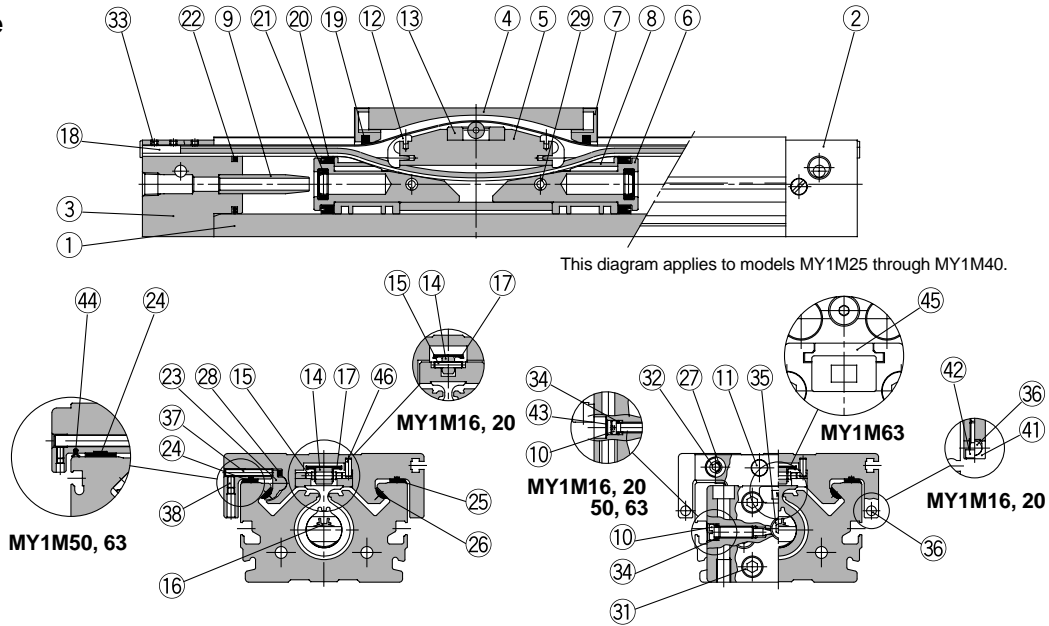
Caution

1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting. Also, for long stroke operation involving vibration and impact, use of a side support is recommended even if the spacing value is within the allowable limits shown in the graph.
2. Support brackets are not for mounting; use them solely for providing support.

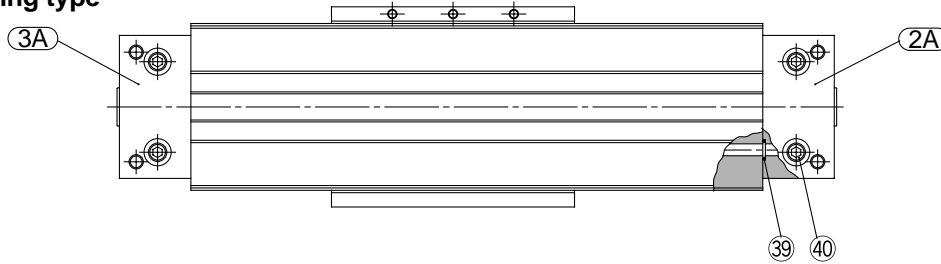


Construction

Standard type



Centralized piping type



Parts list

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover R	Aluminum alloy	Hard anodized
2A	Head cover WR	Aluminum alloy	Hard anodized
3	Head cover L	Aluminum alloy	Hard anodized
3A	Head cover WL	Aluminum alloy	Hard anodized
4	Slide table	Aluminum alloy	Hard anodized
5	Piston yoke	Aluminum alloy	Chromated
6	Piston	Aluminum alloy	Chromated
7	End cover	Special resin	
8	Wear ring	Special resin	
9	Cushion ring	Brass	
10	Cushion needle	Rolled steel	Nickel plated
11	Stopper	Carbon steel	
12	Belt separator	Special resin	
13	Coupler	Sintered iron material	
14	Guide roller	Special resin	
15	Guide roller shaft	Stainless steel	
18	Belt clamp	Special resin	
23	Adjusting arm	Aluminum alloy	Hard anodized
24	Bearing R	Special resin	

Parts list

No.	Description	Material	Note
25	Bearing L	Special resin	
26	Bearing S	Special resin	
27	Spacer	Stainless steel	
28	Backup spring	Stainless steel	
29	Spring pin	Carbon tool steel	Black zinc chromated
31	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
32	Hexagon socket head button bolt	Chrome molybdenum steel	Nickel plated
33	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated/Nickel plated
35	Hexagon socket head taper plug	Carbon steel	Nickel plated
36	Magnet	Rare earth magnet	
37	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated
38	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated
40	Hexagon socket head taper plug	Carbon steel	Nickel plated
41	Magnet holder	Special resin	($\phi 16$, $\phi 20$)
42	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
43	Type CR retaining ring	Spring steel	(except $\phi 25$ to $\phi 40$)
44	Side scraper	Special resin	($\phi 50$, $\phi 63$)
45	Head plate	Aluminum alloy	Hard anodized ($\phi 63$)
46	Parallel pin	Stainless steel	(except $\phi 16$, $\phi 20$)

Seal list

No.	Description	Material	Qty.	MY1M16	MY1M20	MY1M25	MY1M32	MY1M40	MY1M50	MY1M63
16	Seal belt	Special resin	1	MY16-16A-Stroke	MY20-16A-Stroke	MY25-16A-Stroke	MY32-16A-Stroke	MY40-16A-Stroke	MY50-16A-Stroke	MY63-16A-Stroke
Note) 17	Dust seal band	Stainless steel	1	MY16-16B-Stroke	MY20-16B-Stroke	MY25-16B-Stroke	MY32-16B-Stroke	MY40-16B-Stroke	MY50-16B-Stroke	MY63-16B-Stroke
19	Scraper	NBR	2	MYM16-15AK0500	MYM20-15AK0501	MYM25-15AA5903	MYM32-15AA5904	MYM40-15AA5905	MYM50-15AK0502	MYM63-15AK0503
20	Piston seal	NBR	2							
21	Cushion seal	NBR	2							
22	Tube gasket	NBR	2							
34	O-ring	NBR	2							
39	O-ring	NBR	4							

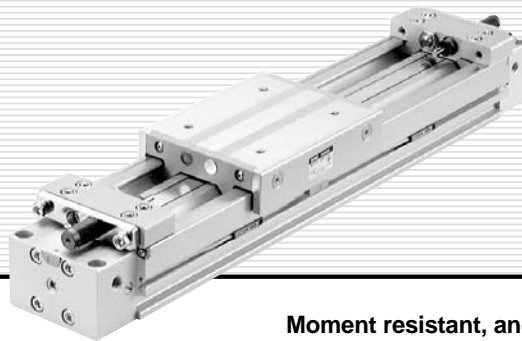
Note) Two types of dust seal band are available. Verify the type to use, since the part number varies depending on the treatment of the hexagon socket head set screw 33.

(A) Black zinc chromated → MY□□-16B-Stroke (B) Nickel plated → MY□□-16BW-Stroke

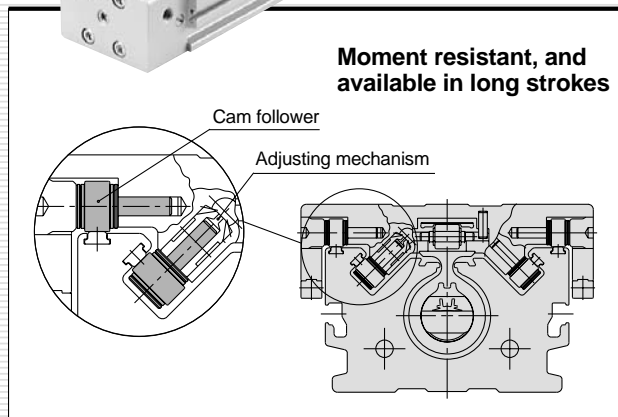
Series MY1C

Cam Follower Guide Type

ø16, ø20, ø25, ø32, ø40, ø50, ø63



Moment resistant, and available in long strokes



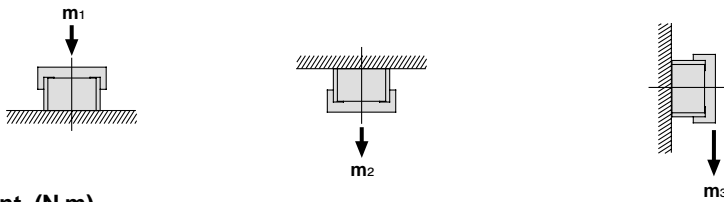
Before Operating Series MY1C

Maximum Allowable Moment/Maximum Allowable Load

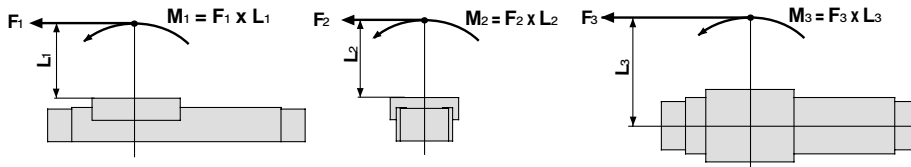
Model	Bore size (mm)	Max. allowable moment (N·m)			Max. allowable load (kg)		
		M ₁	M ₂	M ₃	m ₁	m ₂	m ₃
MY1C	16	6.0	3.0	2.0	18	7	2.1
	20	10	5.0	3.0	25	10	3
	25	15	8.5	5.0	35	14	4.2
	32	30	14	10	49	21	6
	40	60	23	20	68	30	8.2
	50	115	35	35	93	42	11.5
63	150	50	50	130	60	16	

The above values are the maximum allowable values for moment and load. Refer to each graph regarding the maximum allowable moment and maximum allowable load for a particular piston speed.

Load (kg)



Moment (N·m)



<Calculation of guide load factor>

1. Maximum allowable load (1), static moment (2), and dynamic moment (at the time of impact with stopper) (3) must be examined for the selection calculations.

* To evaluate, use \bar{U}_a (average speed) for (1) and (2), and U (impact speed $U = 1.4\bar{U}_a$) for (3).

Calculate m_{max} for (1) from the maximum allowable load graph (m_1, m_2, m_3) and M_{max} for (2) and (3) from the maximum allowable moment graph (M_1, M_2, M_3).

$$\text{Sum of guide load factors } \Sigma \alpha = \frac{\text{Load mass [m]}}{\text{Maximum allowable load [m}_{max}\text{]}} + \frac{\text{Static moment [M]}^{\text{Note 1}}}{\text{Allowable static moment [M}_{max}\text{]}} + \frac{\text{Dynamic moment [ME]}^{\text{Note 2}}}{\text{Allowable dynamic moment [ME}_{max}\text{]}} \leq 1$$

Note 1) Moment caused by the load, etc., with cylinder in resting condition.

Note 2) Moment caused by the impact load equivalent at the stroke end (at the time of impact with stopper).

Note 3) Depending on the shape of the work piece, multiple moments may occur. When this happens, the sum of the load factors ($\Sigma \alpha$) is the total of all such moments.

2. Reference formulae [Dynamic moment at impact]

Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

- m : Load mass (kg)
- F : Load (N)
- F_E : Load equivalent to impact (at impact with stopper) (N)
- \bar{U}_a : Average speed (mm/s)
- M : Static moment (N·m)
- U : Impact speed (mm/s)
- L_1 : Distance to the load's center of gravity (m)
- M_E : Dynamic moment (N·m)
- g : Gravitational acceleration (9.8m/s²)

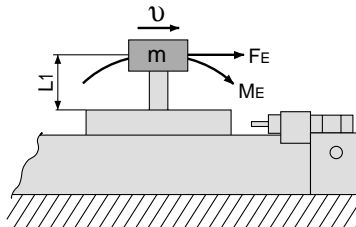
$$U = 1.4\bar{U}_a \text{ (mm/s)} \quad F_E = \frac{1.4}{100} \bar{U}_a \cdot g \cdot m \quad \text{Note 4)}$$

$$\therefore M_E = \frac{1}{3} \cdot F_E \cdot L_1 = 0.05\bar{U}_a m L_1 \text{ (N·m)} \quad \text{Note 5)}$$

Note 4) $\frac{1.4}{100}\bar{U}_a$ is a dimensionless coefficient for calculating impact force.

Note 5) Average load coefficient ($= \frac{1}{3}$):

This coefficient is for averaging the maximum load moment at the time of stopper impact according to service life calculations.



3. Refer to pages 2-582 and 2-583 for detailed selection procedures.

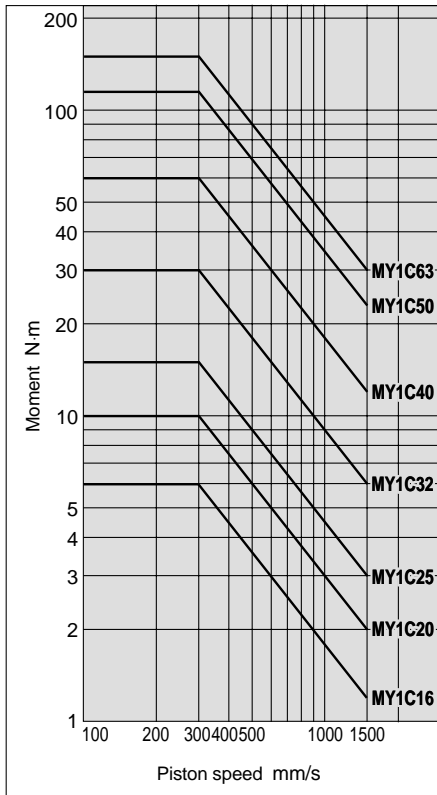
Maximum allowable moment

Select the moment from within the range of operating limits shown in the graphs. Note that the maximum allowable load value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable load for the selected conditions.

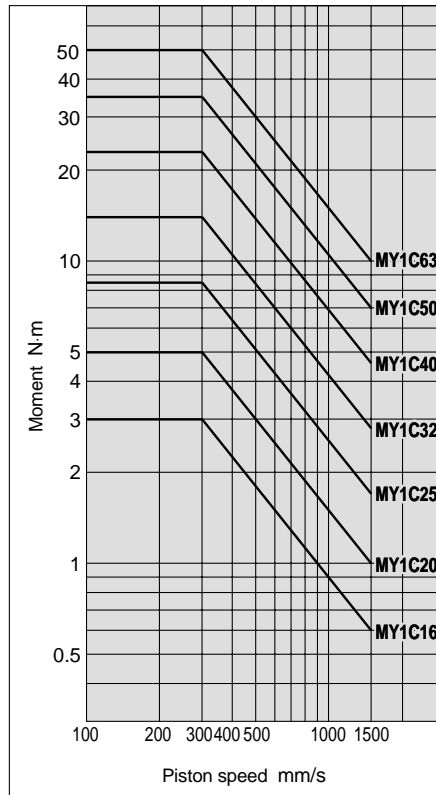
Maximum allowable load

Select the load from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.

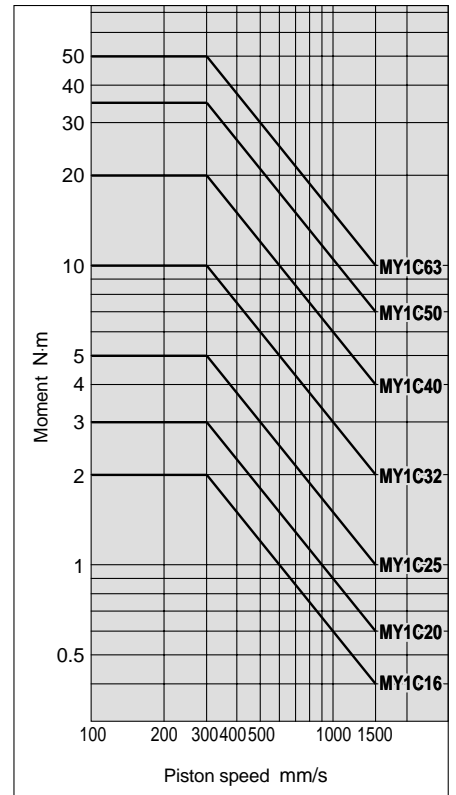
MY1C/M₁



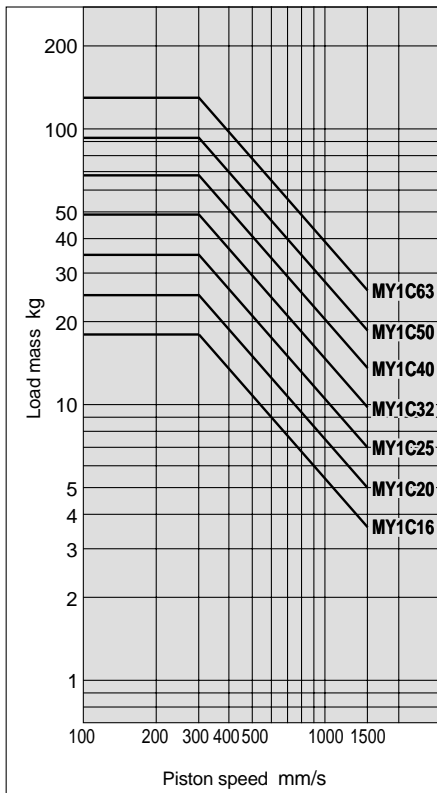
MY1C/M₂



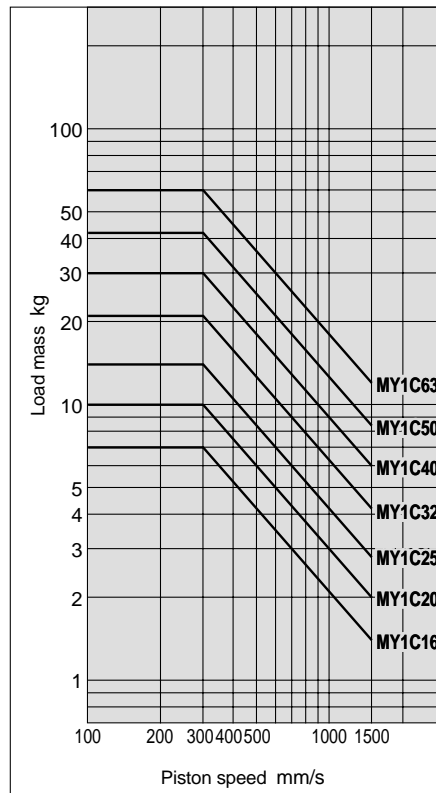
MY1C/M₃



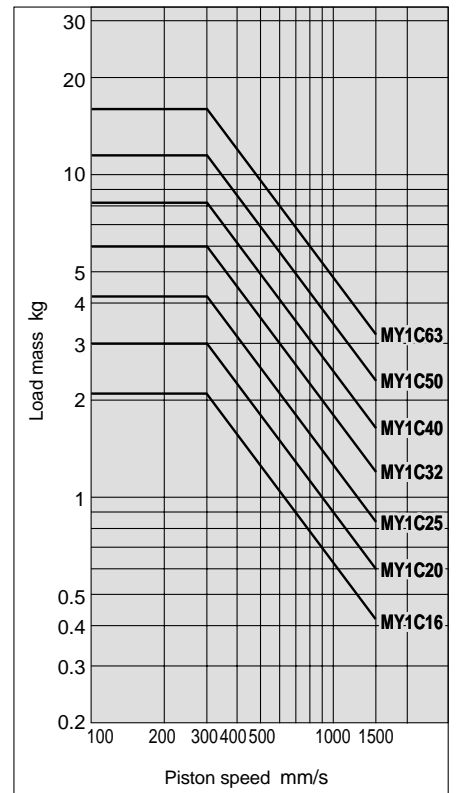
MY1C/m₁



MY1C/m₂



MY1C/m₃



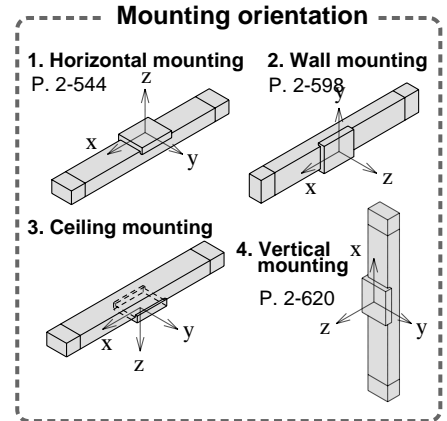
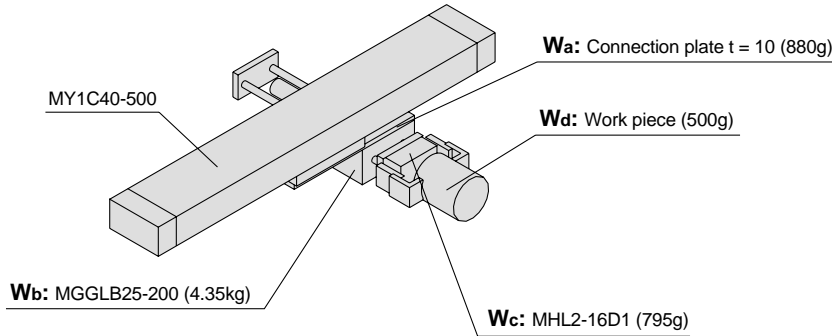
Series MY1C Model Selection

The following are steps for selection of the series MY1 best suited to your application.

Calculation of Guide Load Factor

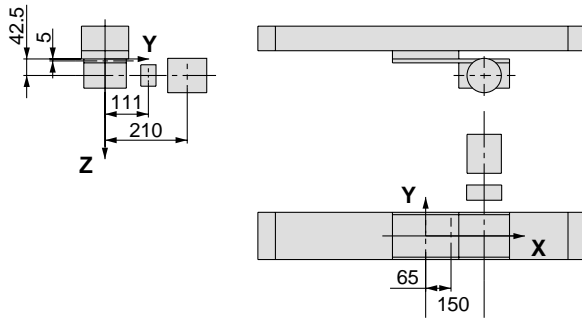
1 Operating conditions

Cylinder **MY1H40-500**
 Average operating speed v_a ... **300mm/s**
 Mounting orientation **Ceiling mounting**



Refer to the pages above for actual examples of calculation for each orientation.

2 Load blocking



Mass and centre of gravity for each work piece

Work piece no. W_n	Mass m_n	Center of gravity		
		X-axis X_n	Y-axis Y_n	Z-axis Z_n
Wa	0.88kg	65mm	0mm	5mm
Wb	4.35kg	150mm	0mm	42.5mm
Wc	0.795kg	150mm	111mm	42.5mm
Wd	0.5kg	150mm	210mm	42.5mm

$n = a, b, c, d$

3 Composite centre of gravity calculation

$$m_2 = \sum m_n$$

$$= 0.88 + 4.35 + 0.795 + 0.5 = \mathbf{6.525kg}$$

$$X = \frac{1}{m_2} \times \sum (m_n \times x_n)$$

$$= \frac{1}{6.525} (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 0.5 \times 150) = \mathbf{138.5mm}$$

$$Y = \frac{1}{m_2} \times \sum (m_n \times y_n)$$

$$= \frac{1}{6.525} (0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 0.5 \times 210) = \mathbf{29.6mm}$$

$$Z = \frac{1}{m_2} \times \sum (m_n \times z_n)$$

$$= \frac{1}{6.525} (0.88 \times 5 + 4.35 \times 42.5 + 0.795 \times 42.5 + 0.5 \times 42.5) = \mathbf{37.4mm}$$

4 Calculation of load factor for static load

m_2 : Mass

m_2 max (from 1 of graph MY1C/ m_2) = 30 (kg)

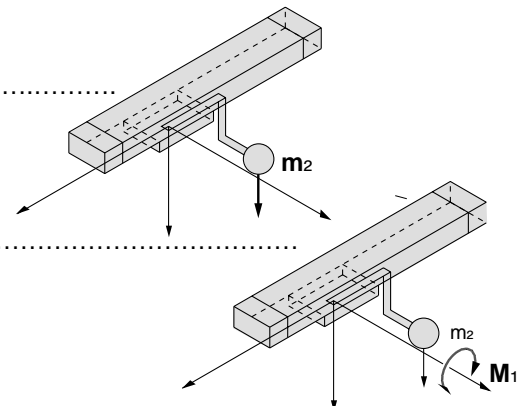
Load factor $\alpha_1 = m_2 / m_2 \text{ max} = 6.525/30 = \mathbf{0.22}$

M_1 : Moment

M_1 max (from 2 of graph MY1C/ M_1) = 60 (N·m)

$M_1 = m_2 \times g \times X = 6.525 \times 9.8 \times 138.5 \times 10^{-3} = 8.86$ (N·m)

Load factor $\alpha_2 = M_1 / M_1 \text{ max} = 8.86/60 = \mathbf{0.15}$

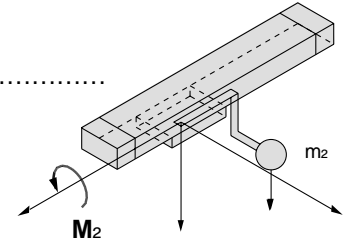


M₂: Moment

M₂ max (from 3 of graph MY1C/M₂) = 23.0 (N·m)

$$M_2 = m_2 \times g \times X = 6.525 \times 9.8 \times 29.6 \times 10^{-3} = 1.89 \text{ (N·m)}$$

$$\text{Load factor } \alpha_3 = M_2 / M_{2 \text{ max}} = 1.89 / 23.0 = \mathbf{0.08}$$



5 Calculation of load factor for dynamic moment

Equivalent load FE at impact

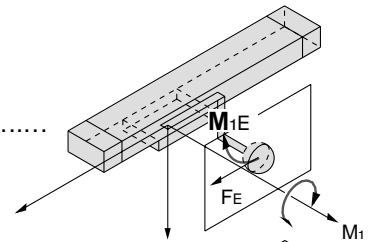
$$F_E = \frac{1.4}{100} \times v_a \times g \times m = \frac{1.4}{100} \times 300 \times 9.8 \times 6.525 = 268.6 \text{ (N)}$$

M_{1E}: Moment

M_{1E} max (from 4 of graph MY1C/M₁ where 1.4v_a = 420mm/s) = 42.9 (N·m)

$$M_{1E} = \frac{1}{3} \times F_E \times Z = \frac{1}{3} \times 268.6 \times 37.4 \times 10^{-3} = 3.35 \text{ (N·m)}$$

$$\text{Load factor } \alpha_4 = M_{1E} / M_{1E \text{ max}} = 3.35 / 42.9 = \mathbf{0.08}$$

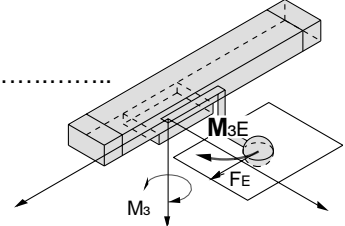


M_{3E}: Moment

M_{3E} max (from 5 of graph MY1C/M₃ where 1.4v_a = 420mm/s) = 14.3 (N·m)

$$M_{3E} = \frac{1}{3} \times F_E \times Y = \frac{1}{3} \times 268.6 \times 29.6 \times 10^{-3} = 2.65 \text{ (N·m)}$$

$$\text{Load factor } \alpha_5 = M_{3E} / M_{3E \text{ max}} = 2.65 / 14.3 = \mathbf{0.19}$$



6 Sum and examination of guide load factors

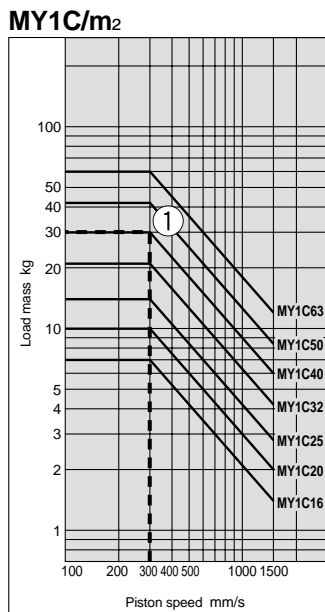
$$\Sigma \alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 = \mathbf{0.89} \leq 1$$

The above calculation is within the allowable value and the selected model can be used.

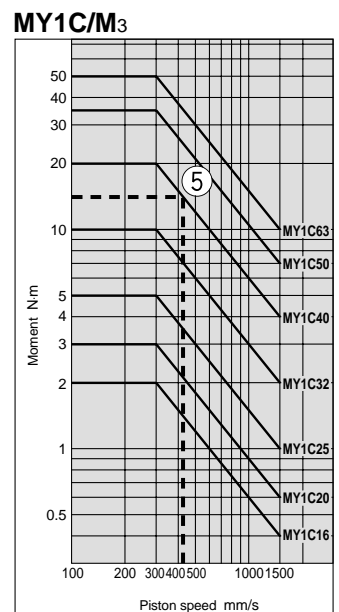
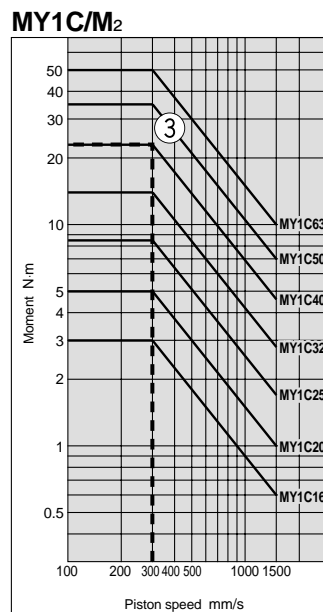
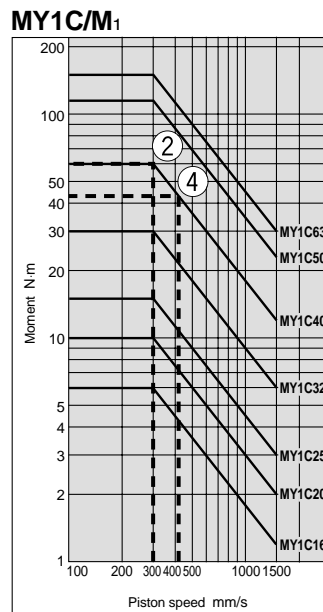
Select a separate shock absorber.

In an actual calculation, when the sum of guide load factors $\Sigma \alpha$ in the formula above is more than 1, consider decreasing the speed, increasing the bore size, or changing the product series. Also, this calculation can be performed easily with the "SMC Pneumatics CAD System".

Load mass



Allowable moment



Mechanically Jointed Rodless Cylinder

Series MY1C

Cam Follower Guide Type/ø16, ø20, ø25, ø32, ø40, ø50,

How to Order

Cam Follower Guide Type **E MY1C 25** **300** **Z73**

Thread Port (ø25 to ø63)

—	Rc(PT)
E	G(PF)

Cam follower guide type

Bore size

16	16mm
20	20mm
25	25mm
32	32mm
40	40mm
50	50mm
63	63mm

Stroke
Refer to the standard stroke table on page 2-585

Piping

Nil	Standard type
G	Centralized piping type

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	"n" pcs.

Auto switch type

Nil	Without auto switch
-----	---------------------

* Refer to the table below for auto switch model numbers.

Stroke adjusting unit (Note)

Nil	Both ends
S	One end

Note) "S" is applicable for stroke adjusting units A, L and H.

Stroke adjusting unit

Nil	Without adjusting unit
A	With adjusting bolt
L	With low load shock absorber + adjusting bolt
H	With high load shock absorber + adjusting bolt
AL	With one A unit and one L unit each
AH	With one A unit and one H unit each
LH	With one L unit and one H unit each

Applicable auto switches/ For ø16, ø20

Type	Special function	Electrical entry	Indicator light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load		
					DC	AC	Perpendicular	In-line	0.5 (Nil)	3 (L)	5 (Z)	IC circuit	Relay, PLC	
Reed switch	—	Grommet	No	2 wire	24V	5V 12V	100V 100V	A90V	A90	●	●	—	IC circuit	Relay, PLC
			Yes	3 wire (NPN equiv.)	—	5V	—	A93V	A93	●	●	—	—	—
Solid state switch	—	Grommet	Yes	3 wire (NPN)	24V	12V	—	M9NV	M9N	●	●	—	—	Relay, PLC
				3 wire (PNP)				M9PV	M9P	●	●	—		
				2 wire				M9BV	M9B	●	●	—		
				3 wire (NPN)				M9NWV	M9NW	●	●	○		
				3 wire (PNP)				M9PWV	M9PW	●	●	○		
				2 wire				M9BWV	M9BW	●	●	○		

* Lead wire length symbols: 0.5m..... Nil (Example) M9NW
3m..... L M9NWL
5m..... Z M9NWZ

** Solid state switches marked with a "O" symbol are produced upon receipt of order.

For ø25, ø32, ø40, ø50, ø63

Type	Special function	Electrical entry	Indicator light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load		
					DC	AC	Perpendicular	In-line	0.5 (Nil)	3 (L)	5 (Z)	IC circuit	Relay, PLC	
Reed switch	—	Grommet	Yes	3 wire (NPN equiv.)	24V	12V	100V	—	Z76	●	●	—	IC circuit	—
				2 wire				—	Z80	●	●	—	IC circuit	—
Solid state switch	—	Grommet	Yes	3 wire (NPN)	24V	12V	—	Y69A	Y59A	●	●	○	IC circuit	Relay, PLC
				3 wire (PNP)				Y7PV	Y7P	●	●	○	—	
				2 wire				Y69B	Y59B	●	●	○	—	
				3 wire (NPN)				Y7NWV	Y7NW	●	●	○	IC circuit	
				3 wire (PNP)				Y7PWV	Y7PW	●	●	○	—	
				2 wire				Y7BWV	Y7BW	●	●	○	—	

* Lead wire length symbols: 0.5m..... Nil (Example) Y59A
3m..... L Y59AL
5m..... Z Y59AZ

** Solid state switches marked with a "O" symbol are produced upon receipt of order.

Shock absorbers for L and H units

Bore size (mm)	16	20	25	32	40	50	63
Unit no.	RB0806	RB1007	RB1412	RB2015	RB2725	—	—
L unit	—	RB0806	RB1007	RB1412	RB2015	RB2725	—
H unit	—	RB1007	RB1412	RB2015	RB2725	—	—

Note) MY1C16 is not available with H unit.

Options

Stroke adjusting unit numbers

Bore size (mm)	16	20	25	32
Unit type	MYM-A16A	MYM-A20A	MYM-A25A	MYM-A32A
A unit	MYM-A16A	MYM-A20A	MYM-A25A	MYM-A32A
L unit	MYM-A16L	MYM-A20L	MYM-A25L	MYM-A32L
H unit	—	MYM-A20H	MYM-A25H	MYM-A32H

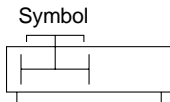
Bore size (mm)	40	50	63
Unit type	MYM-A40A	MYM-A50A	MYM-A63A
A unit	MYM-A40A	MYM-A50A	MYM-A63A
L unit	MYM-A40L	MYM-A50L	MYM-A63L
H unit	MYM-A40H	MYM-A50H	MYM-A63H

Side support numbers

Bore size (mm)	16	20	25	32
Type	MY-S16A	MY-S20A	MY-S25A	MY-S32A
Side support A	MY-S16A	MY-S20A	MY-S25A	MY-S32A
Side support B	MY-S16B	MY-S20B	MY-S25B	MY-S32B

Bore size (mm)	40	50	63
Type	MY-S40A	MY-S50A	MY-S63A
Side support A	MY-S40A	MY-S50A	MY-S63A
Side support B	MY-S40B	MY-S50B	MY-S63B

Refer to page 2-592 for detailed information on dimensions, etc.



Specifications

Bore size (mm)		16	20	25	32	40	50	63
Fluid		Air						
Action		Double acting						
Operating pressure range		0.1 to 0.8MPa						
Proof pressure		1.2MPa						
Ambient and fluid temperature		5 to 60°C						
Cushion		Air cushion						
Lubrication		Non-lube						
Stroke length tolerance		1000 or less ^{+1.8} ₀ 1001 to 3000 ^{+2.8} ₀		2700 or less ^{+1.8} ₀ , 2701 to 5000 ^{+2.8} ₀				
Port size	Front/Side ports	M5 x 0.8			1/8	1/4	3/8	
	Bottom ports (centralized piping type only)	ø4			ø5	ø6	ø8	ø10

Stroke adjusting unit specifications

Bore size (mm)	16			20			25			32			40			50			63								
	A	L	H	A	L	H	A	L	H	A	L	H	A	L	H	A	L	H									
Unit symbol	A L H			A L H			A L H			A L H			A L H			A L H			A L H								
Configuration and shock absorber	With adjusting bolt			With RB 0806 + adjusting bolt			With RB 1007 + adjusting bolt			With RB 1007 + adjusting bolt			With RB 1412 + adjusting bolt			With RB 1412 + adjusting bolt			With RB 2015 + adjusting bolt			With RB 2015 + adjusting bolt			With RB 2725 + adjusting bolt		
Stroke fine adjusting range (mm)	0 to -5.6			0 to -6			0 to -11.5			0 to -12			0 to -16			0 to -20			0 to -25								
Stroke adjusting range	When exceeding the stroke fine adjusting range: Use order made specifications "-X416" and "-X417". (Refer to page 2-645 for details.)																										

Shock absorber specifications

Model	RB 0806	RB 1007	RB 1412	RB 2015	RB 2725	
Max. energy absorption (J)	2.9	5.9	19.6	58.8	147	
Stroke absorption (mm)	6	7	12	15	25	
Max. impact speed (mm/s)	1500					
Max. operating frequency (cycles/min)	80	70	45	25	10	
Spring force (N)	Extended	1.96	4.22	6.86	8.34	8.83
	Compressed	4.22	6.86	15.98	20.50	20.01
Operating temperature range (°C)	5 to 60					

Piston speed

Bore size (mm)		16 to 63
Without stroke adjusting unit		100 to 1000mm/s
Stroke adjusting unit	A unit	100 to 1000mm/s ^{Note 1)}
	L unit and H unit	100 to 1500mm/s ^{Note 2)}

Note 1) Be aware that when the stroke adjusting range is increased by manipulating the adjusting bolt, the air cushion capacity decreases. Also, when exceeding the air cushion stroke ranges on page 2-586, the **piston speed** should be **100 to 200mm per second**.

Note 2) For centralized piping, the piston speed is 100 to 1000mm per second.

Note 3) Use at a speed within the absorption capacity range. Refer to page 2-586

Theoretical output

Unit: N

Bore size (mm)	Piston area (mm ²)	Operating pressure (MPa)						
		0.2	0.3	0.4	0.5	0.6	0.7	0.8
16	200	40	60	80	100	120	140	160
20	314	62	94	125	157	188	219	251
25	490	98	147	196	245	294	343	392
32	804	161	241	322	402	483	563	643
40	1256	251	377	502	628	754	879	1005
50	1962	392	588	784	981	1177	1373	1569
63	3115	623	934	1246	1557	1869	2180	2492

1N = Approx. 0.102kgf, 1MPa = Approx. 10.2kgf/cm²

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)

Standard strokes

Bore size (mm)	Standard stroke (mm)*	Max. manufacturable stroke (mm)
16	100, 200, 300, 400, 500, 600, 700 800, 900, 1000, 1200, 1400, 1600 1800, 2000	3000
20, 25, 32, 40 50, 63		5000

* Strokes are manufacturable in 1mm increments, up to the maximum stroke. However, when exceeding a 2000mm stroke, specify "-XB11" at the end of the model number. Refer to the order made specifications on page 2-644

Weights

Unit: kg

Bore size (mm)	Basic weight	Additional weight per 50mm of stroke	Side support weight (per set)	Stroke adjusting unit weight (per unit)		
			Type A and B	A unit	L unit	H unit
16	0.67	0.12	0.01	0.03	0.04	—
20	1.06	0.15	0.02	0.04	0.05	0.08
25	1.58	0.24	0.02	0.07	0.11	0.18
32	3.14	0.37	0.04	0.14	0.23	0.39
40	5.60	0.52	0.08	0.25	0.34	0.48
50	10.14	0.76	0.08	0.36	0.51	0.81
63	16.67	1.10	0.17	0.68	0.83	1.08

Calculation method Example: **MY1C25-300A**

Basic weight 1.58kg Cylinder stroke 300mm
 Additional weight 0.24/50mm stroke 1.58 + 0.24 x 300 ÷ 50 + 0.07 x 2 = Approx. 3.16kg
 Weight of A unit 0.07kg



Order made specifications

Refer to page 2-645 regarding order made specifications for series MY1C.

Series MY1C

Cushion Capacity

Cushion selection

<Air cushion>

Air cushions are a standard feature on mechanically jointed rodless cylinders.

The air cushion mechanism is installed to avoid excessive impact of the piston at the stroke end during high speed operation. The air cushion does not act to decelerate the piston near the stroke end.

The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

<Stroke adjusting unit with shock absorber>

Use this unit when operating with a load or speed exceeding the air cushion limit line, or when cushioning is necessary because the cylinder stroke is outside of the effective air cushion stroke range due to stroke adjustment.

L unit

Use this unit when the cylinder stroke is outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

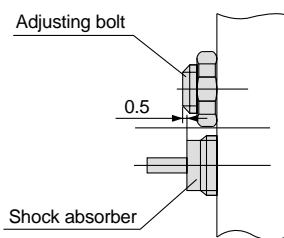
H unit

Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

⚠ Caution

1. Refer to the diagram below when using the adjusting bolt to perform stroke adjustment.

When the effective stroke of the shock absorber decreases as a result of stroke adjustment, the absorption capacity decreases dramatically. Secure the adjusting bolt at the position where it protrudes approximately 0.5mm from the shock absorber.



2. Do not use a shock absorber and air cushion together.

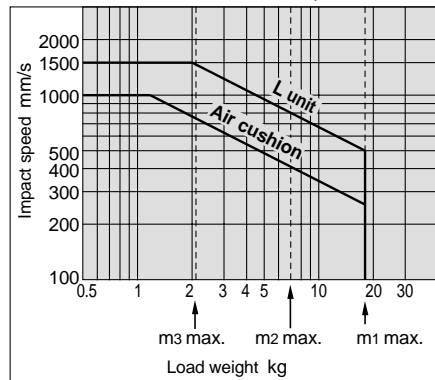
Air cushion stroke

Unit: mm

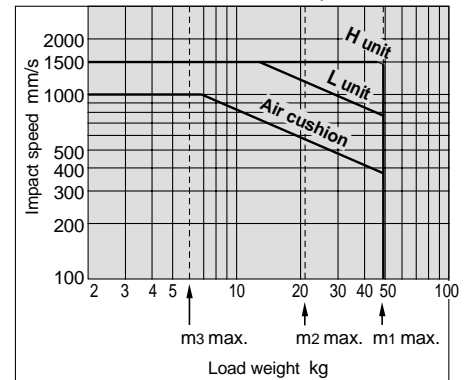
Bore size (mm)	Cushion stroke
16	12
20	15
25	15
32	19
40	24
50	30
63	37

Absorption capacity of air cushion and stroke adjusting units

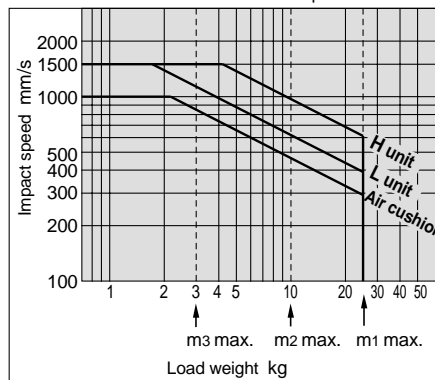
MY1C16 Horizontal impact: P = 0.5MPa



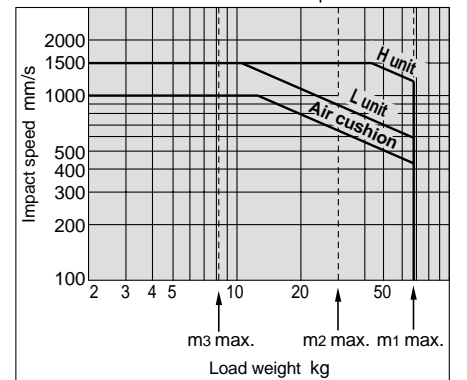
MY1C32 Horizontal impact: P = 0.5MPa



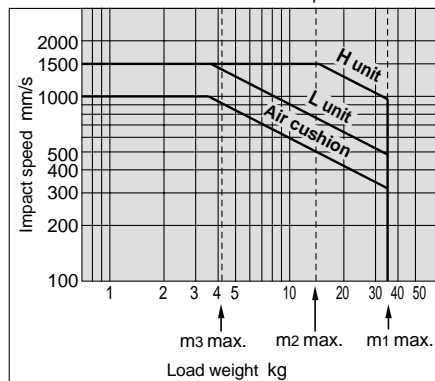
MY1C20 Horizontal impact: P = 0.5MPa



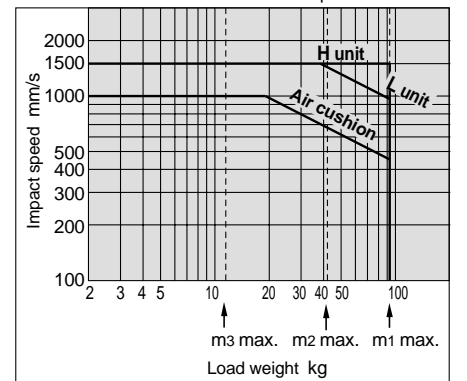
MY1C40 Horizontal impact: P = 0.5MPa



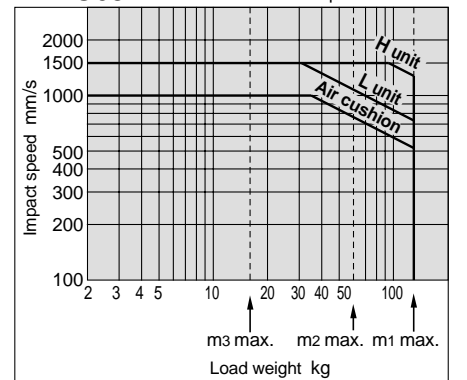
MY1C25 Horizontal impact: P = 0.5MPa



MY1C50 Horizontal impact: P = 0.5MPa



MY1C63 Horizontal impact: P = 0.5MPa



Stroke adjusting unit holding bolt tightening torque Unit: N·m

Bore size (mm)	Unit	Tightening torque
16	A	0.6
	L	
20	A	1.5
	L	
	H	
25	A	3.0
	L	
	H	
32	A	5.0
	L	
	H	
40	A	12
	L	
	H	
50	A	12
	L	
	H	
63	A	24
	L	
	H	

Stroke adjusting unit lock plate holding bolt tightening torque Unit: N·m

Bore size (mm)	Unit	Tightening torque
25	L	1.2
	H	3.3
32	L	3.3
	H	10
40	L	3.3
	H	10

Calculation of absorbed energy for stroke adjusting unit with shock absorber Unit: N·m

Type of impact	Horizontal	Vertical (downward)	Vertical (upward)
Kinetic energy E ₁		$\frac{1}{2} m \cdot v^2$	
Thrust energy E ₂	F·s	F·s + m·g·s	F·s - m·g·s
Absorbed energy E	E ₁ + E ₂		

Symbols

v: Speed of impacting object (m/s)

m: Weight of impacting object (kg)

F: Cylinder thrust (N)

g: Gravitational acceleration (9.8m/s²)

s: Shock absorber stroke (m)

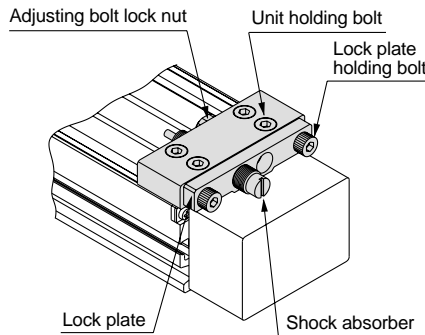
Note) The speed of the impacting object is measured at the time of impact with the shock absorber.

Specific product precautions

Caution

Be careful not to get hands caught in the unit.

- When using a product with stroke adjusting unit, the space between the slide table (slider) and the stroke adjusting unit becomes narrow, causing a danger of hands getting caught. Install a protective cover to prevent direct contact with the human body.



<Fastening of unit>

The unit can be fastened by uniformly tightening the four unit holding bolts.

Caution

Do not operate with the stroke adjusting unit fixed in an intermediate position.

When the stroke adjusting unit is fixed in an intermediate position, slippage can occur depending on the amount of energy released at the time of an impact. In this case, we recommend using the adjusting bolt mounting brackets available with order made specifications – X 416 and – X 417. For other lengths, consult SMC. (Refer to "Stroke adjustment unit holding bolt tightening torque".)

<Stroke adjustment with adjusting bolt>

Loosen the adjusting bolt lock nut, and adjust the stroke from the lock plate side using a hexagon wrench. Re-tighten the lock nut.

<Stroke adjustment with shock absorber>

Loosen the two lock plate holding bolts, turn the shock absorber and adjust the stroke. Then, uniformly tighten the lock plate holding bolts to secure the shock absorber.

Take care not to over-tighten the holding bolts. (Except ø16, ø20, ø50, ø63)

(Refer to "Stroke adjusting unit lock plate holding bolt tightening torque".)

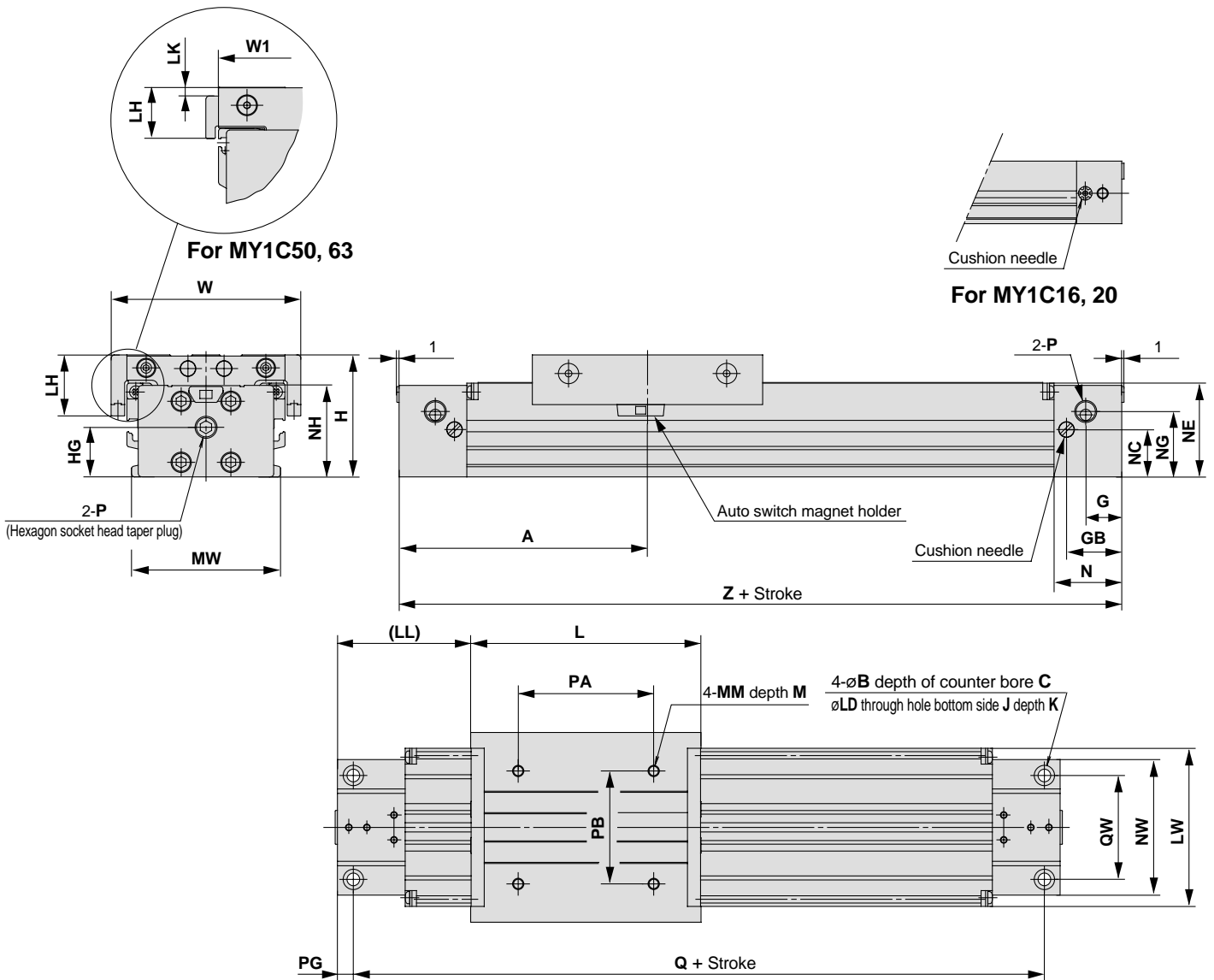
Note)

Slight bending may occur in the lock plate due to tightening of the lock plate holding bolts. This is not a problem for the shock absorber and locking function.

Series MY1C

Standard Type $\varnothing 16$ to $\varnothing 63$

MY1C Bore size — Stroke



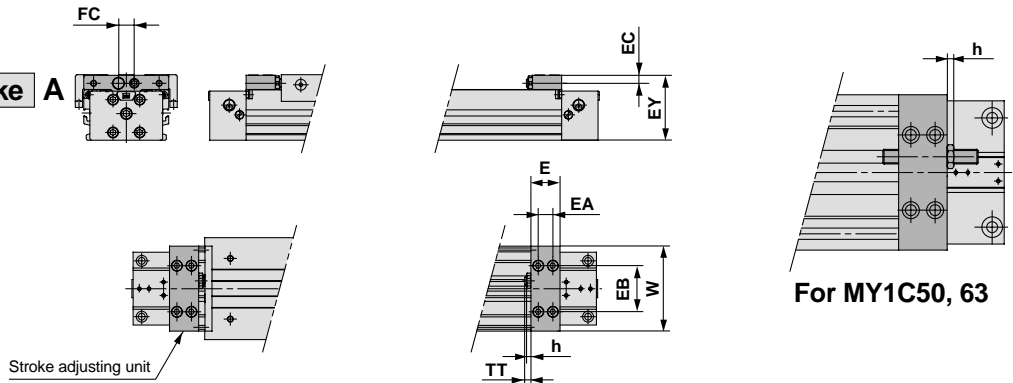
Model	A	B	C	G	GB	H	HG	J	K	L	LD	LH	LK	(LL)	LW	M	MM	MW
MY1C16	80	6	3.5	8.5	16.2	40	13.5	M5	10	80	3.6	22.5	—	40	54	6	M4	—
MY1C20	100	7.5	4.5	10.5	20	46	17	M6	12	100	4.8	23	—	50	58	7.5	M5	—
MY1C25	110	9	5.5	16	24.5	54	22	M6	9.5	102	5.6	27	—	59	70	10	M5	66
MY1C32	140	11	6.5	19	30	68	27	M8	16	132	6.8	35	—	74	88	13	M6	80
MY1C40	170	14	8.5	23	36.5	84	34.5	M10	15	162	8.6	38	—	89	104	13	M6	96
MY1C50	200	17	10.5	25	37.5	107	45	M14	28	200	11	29	2	100	128	15	M8	—
MY1C63	230	19	12.5	27.5	39.5	130	59	M16	32	230	13.5	32.5	5.5	115	152	16	M10	—

Model	N	NC	NE	NG	NH	NW	P	PA	PB	PG	Q	QW	W	W1	Z
MY1C16	20	13.5	28	13.5	27.7	56	M5	40	40	3.5	153	48	68	—	160
MY1C20	25	17	34	17	33.7	60	M5	50	40	4.5	191	45	72	—	200
MY1C25	30	21	41.8	29	40.5	60	1/8	60	50	7	206	46	84	—	220
MY1C32	37	26	52.3	34	50	74	1/8	80	60	8	264	60	102	—	280
MY1C40	45	32	65.3	42.5	63.5	94	1/4	100	80	9	322	72	118	—	340
MY1C50	47	43.5	84.5	54	83.5	118	3/8	120	90	10	380	90	144	128	400
MY1C63	50	56	104	68	105	142	3/8	140	110	12	436	110	168	152	460

"P" indicates cylinder supply ports. * The plug for MY1C16/20-P is a hexagon socket head plug.

**Stroke adjusting unit
With adjusting bolt**

MY1C **Bore size** — **Stroke** **A**

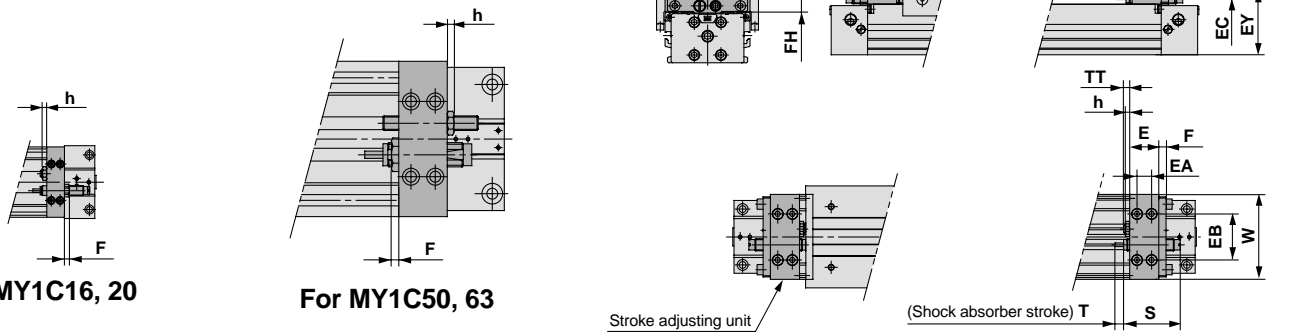


For MY1C50, 63

Model	E	EA	EB	EC	EY	FC	h	TT	W
MY1C16	14.6	7	30	5.8	39.5	14	3.6	5.4 (max. 11)	58
MY1C20	20	10	32	5.8	45.5	14	3.6	5 (max. 11)	58
MY1C25	24	12	38	6.5	53.5	13	3.5	5 (max. 16.5)	70
MY1C32	29	14	50	8.5	67	17	4.5	8 (max. 20)	88
MY1C40	35	17	57	10	83	17	4.5	9 (max. 25)	104
MY1C50	40	20	66	14	106	26	5.5	13 (max. 33)	128
MY1C63	52	26	77	14	129	31	5.5	13 (max. 38)	152

Low load shock absorber + Adjusting bolt

MY1C **Bore size** — **Stroke** **L**



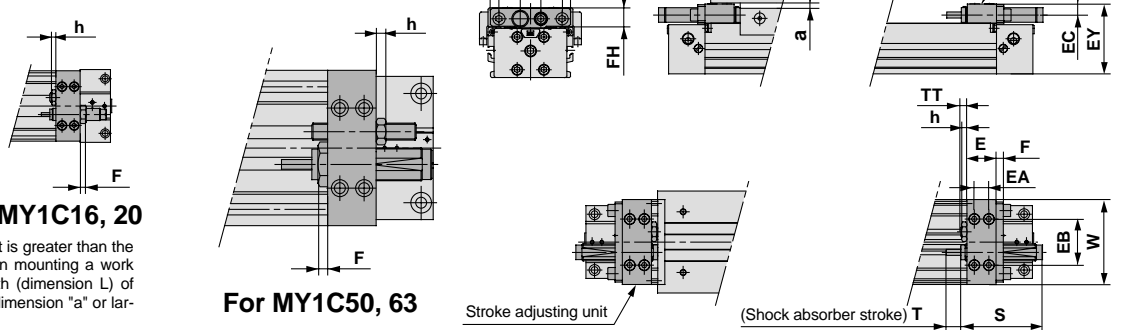
For MY1C16, 20

For MY1C50, 63

Model	E	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	T	TT	W	Shock absorber model
MY1C16	14.6	7	30	5.8	39.5	4	—	14	—	—	3.6	40.8	6	5.4 (max. 11)	58	RB0806
MY1C20	20	10	32	5.8	45.5	4	—	14	—	—	3.6	40.8	6	5 (max. 11)	58	RB0806
MY1C25	24	12	38	6.5	53.5	6	54	13	13	66	3.5	46.7	7	5 (max. 16.5)	70	RB1007
MY1C32	29	14	50	8.5	67	6	67	17	16	80	4.5	67.3	12	8 (max. 20)	88	RB1412
MY1C40	35	17	57	10	83	6	78	17	17.5	91	4.5	67.3	12	9 (max. 25)	104	RB1412
MY1C50	40	20	66	14	106	6	—	26	—	—	5.5	73.2	15	13 (max. 33)	128	RB2015
MY1C63	52	26	77	14	129	6	—	31	—	—	5.5	73.2	15	13 (max. 38)	152	RB2015

High load shock absorber + Adjusting bolt

MY1C **Bore size** — **Stroke** **H**



For MY1C16, 20

For MY1C50, 63

* Since dimension EY of the H type unit is greater than the table top height (dimension H), when mounting a work piece that exceeds the overall length (dimension L) of the slide table, allow a clearance of dimension "a" or larger on the work piece side.

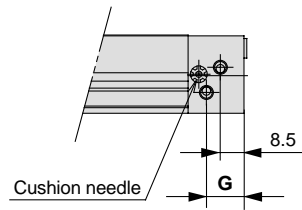
Model	E	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	T	TT	W	Shock absorber model	a
MY1C20	20	10	32	7.7	50	5	—	14	—	—	3.5	46.7	7	5 (max. 11)	58	RB1007	5
MY1C25	24	12	38	9	57.5	6	52	17	16	66	4.5	67.3	12	5 (max. 16.5)	70	RB1412	4.5
MY1C32	29	14	50	11.5	73	8	67	22	22	82	5.5	73.2	15	8 (max. 20)	88	RB2015	6
MY1C40	35	17	57	12	87	8	78	22	22	95	5.5	73.2	15	9 (max. 25)	104	RB2015	4
MY1C50	40	20	66	18.5	115	8	—	30	—	—	11	99	25	13 (max. 33)	128	RB2725	9
MY1C63	52	26	77	19	138.5	8	—	35	—	—	11	99	25	13 (max. 38)	152	RB2725	9.5

Series MY1C

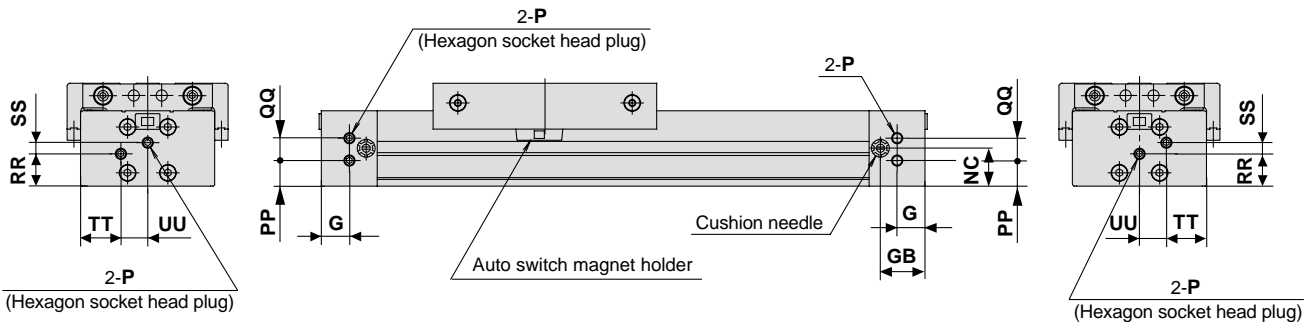
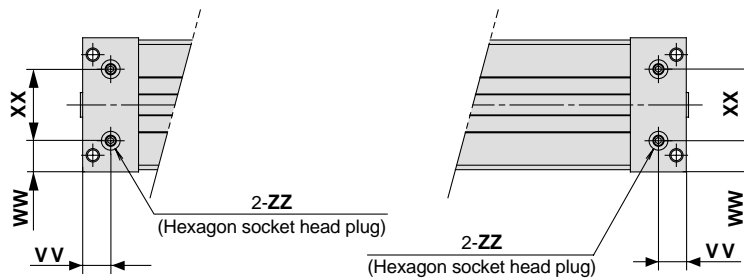
Centralized Piping Type $\varnothing 16$ to $\varnothing 20$

Refer to page 2-648 regarding centralized piping port variations. Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions. Refer to pages 2-588 and 2-589 for details regarding dimensions, etc.

MY1C Bore size **G** — Stroke

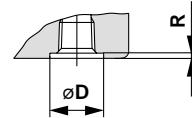
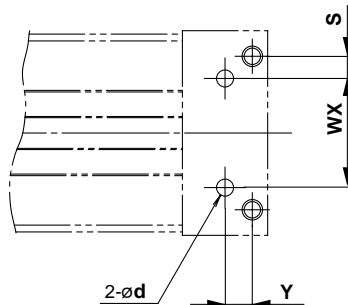


For MY1C16



Model	G	GB	NC	P	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1C16G	13.5	16.2	14	M5	7.5	9	11	2.5	15	14	10	13	30	M5
MY1C20G	12.5	20	17	M5	11.5	10	14.5	5	18	12	12.5	14	32	M5

P indicates cylinder supply ports.



Bottom side (ZZ) piping (applicable O-ring)

Hole sizes for centralized piping on the bottom

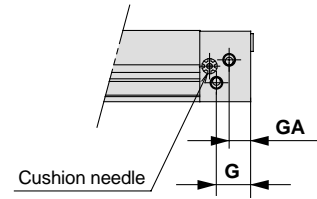
(Machine the mounting side to the dimensions below.)

Model	WX	Y	S	d	D	R	Applicable O-ring
MY1C16G	30	6.5	9	4	8.4	1.1	C6
MY1C20G	32	8	6.5	4	8.4	1.1	

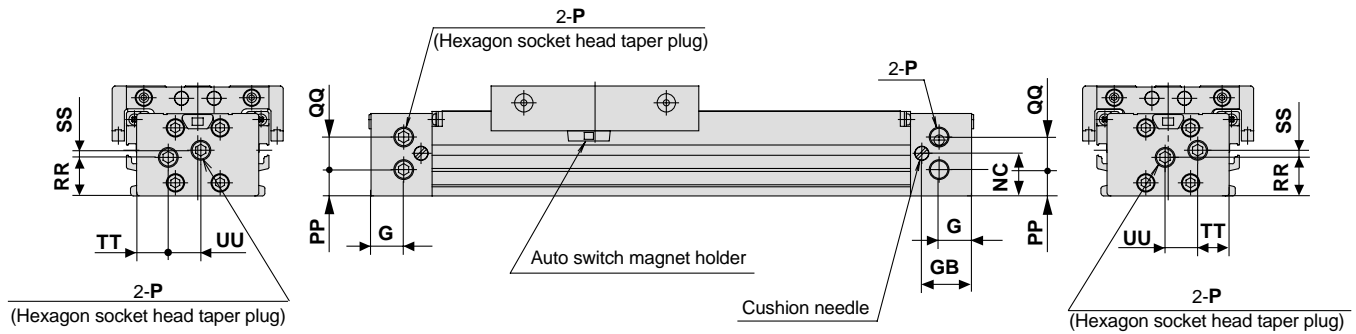
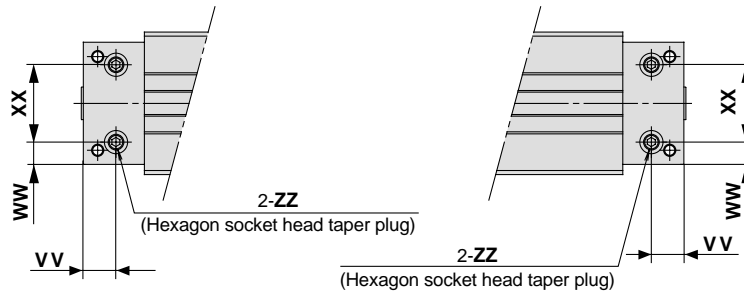
Centralized Piping Type $\varnothing 25$ to $\varnothing 63$

Refer to page 2-648 regarding centralized piping port variations.
Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions.
Refer to pages 2-588 and 2-589 for details regarding dimensions, etc.

MY1C Bore size G—Stroke

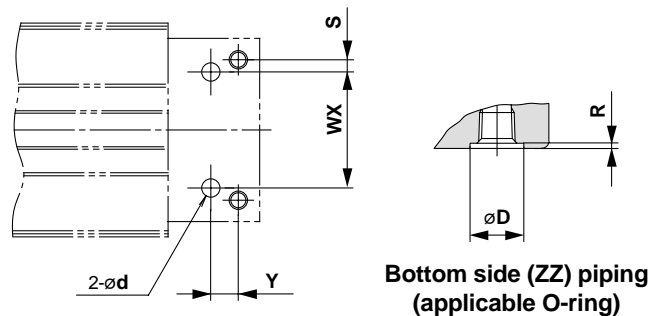


For MY1C50, 63



Model	G	GA	GB	NC	P	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1C25G	16	—	24.5	21	1/8	13	16	19	3.5	15.5	16	16	11	38	1/16
MY1C32G	19	—	30	26	1/8	18	16	24	4	21	16	19	13	48	1/16
MY1C40G	23	—	36.5	32	1/4	16.5	26	25.5	10.5	22.5	24.5	23	20	54	1/8
MY1C50G	27	25	37.5	43.5	3/8	26	28	35	10	35	24	28	22	74	1/4
MY1C63G	29.5	27.5	39.5	60	3/8	42	30	49	13	43	28	30	25	92	1/4

P indicates cylinder supply ports.



Hole sizes for centralized piping on the bottom

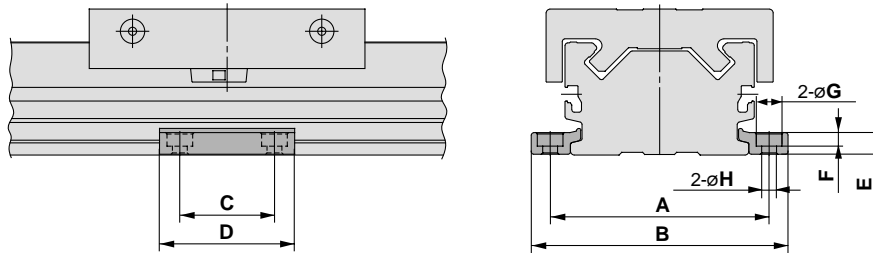
(Machine the mounting side to the dimensions below.)

Model	WX	Y	S	d	D	R	Applicable O-ring
MY1C25G	38	9	4	6	11.4	1.1	C9
MY1C32G	48	11	6			1.1	
MY1C40G	54	14	9	8	13.4	1.1	C11.2
MY1C50G	74	18	8	10	17.5	1.1	C15
MY1C63G	92	18	9	10	17.5	1.1	

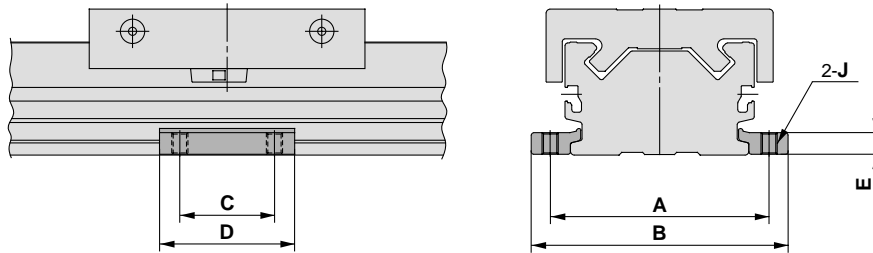
Series MY1C

Side Support

Side support A MY-S□A



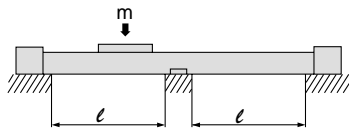
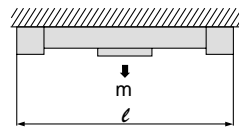
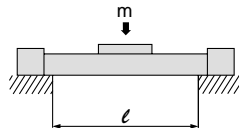
Side support B MY-S□B



Model	Applicable cylinder	A	B	C	D	E	F	G	H	J
MY-S16 _B ^A	MY1C16	61	71.6	15	26	4.9	3	6.5	3.4	M4
MY-S20 _B ^A	MY1C20	67	79.6	25	38	6.4	4	8	4.5	M5
MY-S25 _B ^A	MY1C25	81	95	35	50	8	5	9.5	5.5	M6
MY-S32 _B ^A	MY1C32	100	118	45	64	11.7	6	11	6.6	M8
MY-S40 _B ^A	MY1C40	120	142	55	80	14.8	8.5	14	9	M10
	MY1C50	142	164							
MY-S63 _B ^A	MY1C63	172	202	70	100	18.3	10.5	17.5	11.5	M12

Guide for Using Side Supports

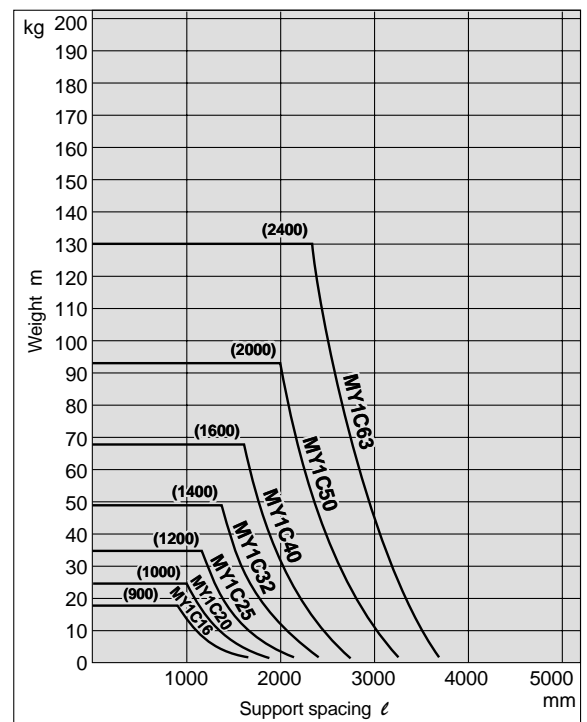
For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load weight. In such a case, use a side support in the middle section. The spacing (ℓ) of the support must be no more than the values shown in the graph on the right.



⚠ Caution

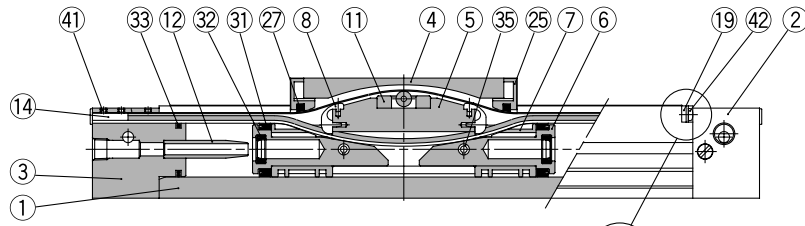
1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting. Also, for long stroke operation involving vibration and impact, use of a side support is recommended even if the spacing value is within the allowable limits shown in the graph.

2. Support brackets are not for mounting; use them solely for providing support.

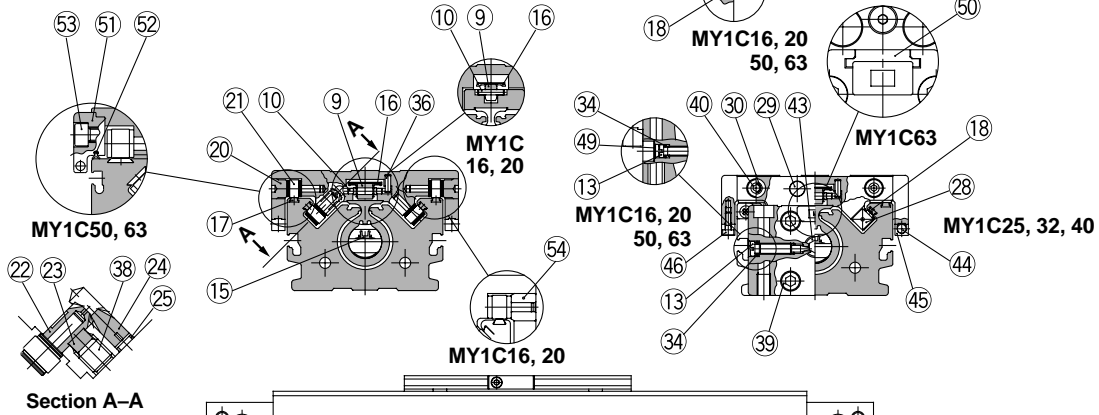


Construction

Standard type

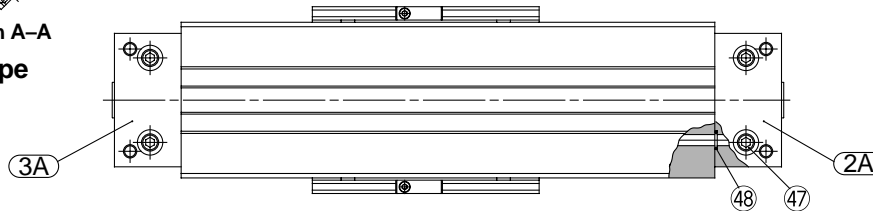


This diagram applies to models MY1C25 through MY1C140.



Section A-A

Centralized piping type



Parts list

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover R	Aluminum alloy	Hard anodized
2A	Head cover WR	Aluminum alloy	Hard anodized
3	Head cover L	Aluminum alloy	Hard anodized
3A	Head cover WL	Aluminum alloy	Hard anodized
4	Slide table	Aluminum alloy	Electroless nickel plated Hard anodized (ø50, ø63)
5	Piston yoke	Aluminum alloy	Chromated
6	Piston	Aluminum alloy	Chromated
7	Wear ring	Special resin	
8	Belt separator	Special resin	
9	Guide roller	Special resin	
10	Guide roller shaft	Stainless steel	
11	Coupler	Sintered iron material	
12	Cushion ring	Brass	
13	Cushion needle	Rolled steel	Nickel plated
14	Belt clamp	Special resin	
17	Rail	Hard steel wire material	
18	End spacer	Special resin	
19	End clamp	Stainless steel	Rubber lining (ø25 to ø40)
20	Cam follower cap	Special resin	
21	Cam follower	—	
22	Eccentric gear	Stainless steel	
23	Gear bracket	Carbon steel	Black zinc chromated

Parts list

No.	Description	Material	Note
24	Adjustment gear	Stainless steel	
25	Retaining ring	Stainless steel	
26	End cover	Special resin	
28	Backup plate	Special resin	(ø25 to ø40)
29	Stopper	Carbon steel	Nickel plated
30	Spacer	Stainless steel	
35	Spring pin	Carbon tool steel	Black zinc chromated
36	Parallel pin	Stainless steel	(Except ø16, ø20)
38	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated
39	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
40	Hexagon socket head button bolt	Chrome molybdenum steel	Nickel plated
41	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated/Nickel plated
42	Round head Phillips screw	Chrome molybdenum steel	Nickel plated
43	Hexagon socket head taper plug	Carbon steel	Nickel plated
44	Magnet	Rare earth magnet	
45	Magnet holder	Special resin	(Except ø50, ø63)
46	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated (except ø50, ø63)
47	Hexagon socket head taper plug	Carbon steel	Nickel plated
49	Type CR retaining ring	Spring steel	(Except ø25 to ø40)
50	Head plate	Aluminum alloy	Hard anodized
51	Side cover	Aluminum alloy	Hard anodized
52	Side scraper	Special resin	(ø50, ø63)
53	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated (ø50, ø63)
54	Bushing	Aluminum alloy	Hard anodized (ø16, ø20)

Seal list

No.	Description	Material	Qty.	MY1C16	MY1C20	MY1C25	MY1C32	MY1C40	MY1C50	MY1C63
15	Seal belt	Special resin	1	MY16-16A-Stroke	MY20-16A-Stroke	MY25-16A-Stroke	MY32-16A-Stroke	MY40-16A-Stroke	MY50-16A-Stroke	MY63-16A-Stroke
Note) 16	Dust seal band	Stainless steel	1	MY16-16B-Stroke	MY20-16B-Stroke	MY25-16B-Stroke	MY32-16B-Stroke	MY40-16B-Stroke	MY50-16B-Stroke	MY63-16B-Stroke
27	Scraper	NBR	2	MYM16-15AK0500	MYM20-15AK0501	MYM25-15AA5903	MYM32-15AA5904	MYM40-15AA5905	MYM50-15AK0502	MYM63-15AK0503
31	Piston seal	NBR	2							
32	Cushion seal	NBR	2							
33	Tube gasket	NBR	2							
34	O-ring	NBR	2							
48	O-ring	NBR	4							

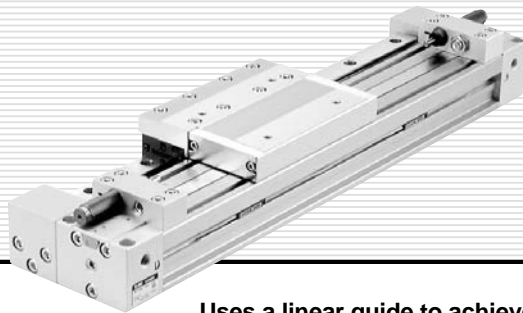
Note) Two types of dust seal band are available. Verify the type to use, since the part number varies depending on the treatment of the hexagon socket head set screw ④1.

(A) Black zinc chromated → MY□□-16B-Stroke (B) Nickel plated → MY□□-16BW-Stroke

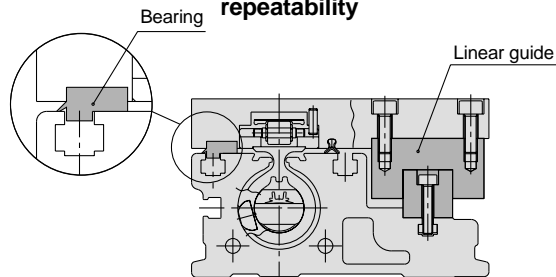
Series MY1H

High Precision Guide Type

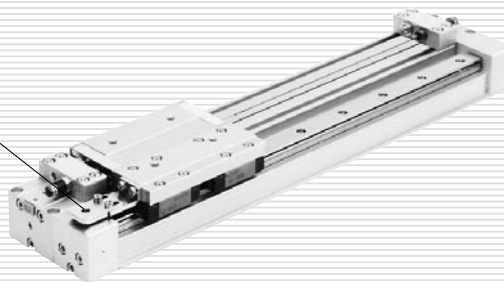
ø10, ø16, ø20, ø25, ø32, ø40



Uses a linear guide to achieve high linearity and high repeatability



End lock type capable of holding a position at the stroke end (except bore size ø10)



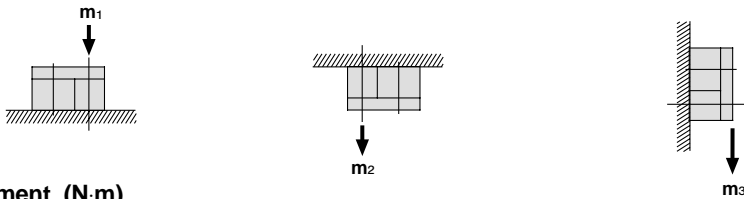
Before Operating Series MY1H

Maximum Allowable Moment/Maximum Allowable Load

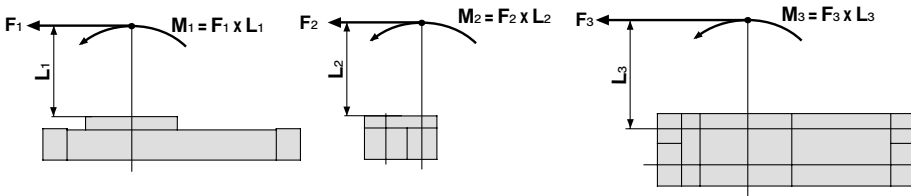
Model	Bore size (mm)	Max. allowable moment (N·m)			Max. allowable load (kg)		
		M ₁	M ₂	M ₃	m ₁	m ₂	m ₃
MY1H	10	0.8	1.1	0.8	6.1	6.1	6.1
	16	3.7	4.9	3.7	10.8	10.8	10.8
	20	11	16	11	17.6	17.6	17.6
	25	23	26	23	27.5	27.5	27.5
	32	39	50	39	39.2	39.2	39.2
	40	50	50	39	50	50	50

The above values are the maximum allowable values for moment and load. Refer to each graph regarding the maximum allowable moment and maximum allowable load for a particular piston speed.

Load (kg)



Moment (N·m)



<Calculation of guide load factor>

1. Maximum allowable load (1), static moment (2), and dynamic moment (at the time of impact with stopper) (3) must be examined for the selection calculations.

* To evaluate, use \bar{v} (average speed) for (1) and (2), and v (impact speed $v = 1.4\bar{v}$) for (3).

Calculate m_{max} for (1) from the maximum allowable load graph (m_1, m_2, m_3) and M_{max} for (2) and (3) from the maximum allowable moment graph (M_1, M_2, M_3).

$$\text{Sum of guide load factors } \Sigma\alpha = \frac{\text{Load mass [m]}}{\text{Maximum allowable load [m}_{max}\text{]}} + \frac{\text{Static moment [M]}^{\text{Note 1}}}{\text{Allowable static moment [M}_{max}\text{]}} + \frac{\text{Dynamic moment [ME]}^{\text{Note 2}}}{\text{Allowable dynamic moment [ME}_{max}\text{]}} \leq 1$$

Note 1) Moment caused by the load, etc., with cylinder in resting condition.

Note 2) Moment caused by the impact load equivalent at the stroke end (at the time of impact with stopper).

Note 3) Depending on the shape of the work piece, multiple moments may occur. When this happens, the sum of the load factors ($\Sigma\alpha$) is the total of all such moments.

2. Reference formulae [Dynamic moment at impact]

Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

m : Load mass (kg)

v : Impact speed (mm/s)

F : Load (N)

L_1 : Distance to the load's center of gravity (m)

F_E : Load equivalent to impact (at impact with stopper) (N) M_E : Dynamic moment (N·m)

\bar{v} : Average speed (mm/s)

g : Gravitational acceleration (9.8m/s²)

M : Static moment (N·m)

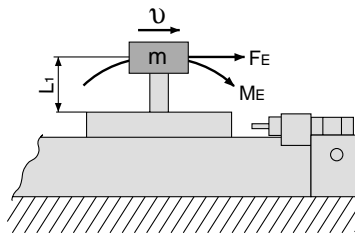
$$v = 1.4\bar{v} \text{ (mm/s)} \quad F_E = \frac{1.4}{100} \bar{v} a \cdot g \cdot m \quad \text{Note 4)}$$

$$\therefore M_E = \frac{1}{3} \cdot F_E \cdot L_1 = 0.05\bar{v} a \cdot m \cdot L_1 \text{ (N·m)} \quad \text{Note 5)}$$

Note 4) $\frac{1.4}{100} \bar{v} a$ is a dimensionless coefficient for calculating impact force.

Note 5) Average load coefficient ($= \frac{1}{3}$):

This coefficient is for averaging the maximum load moment at the time of stopper impact according to service life calculations.



3. Refer to pages 2-598 and 2-599 for detailed selection procedures.

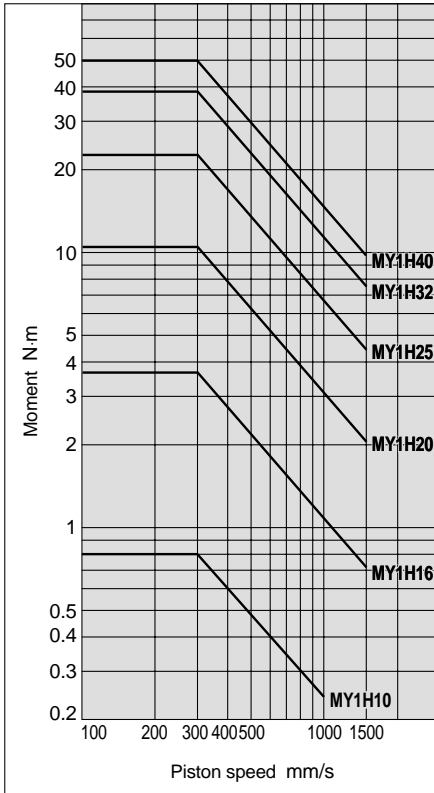
Maximum allowable moment

Select the moment from within the range of operating limits shown in the graphs. Note that the maximum allowable load value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable load for the selected conditions.

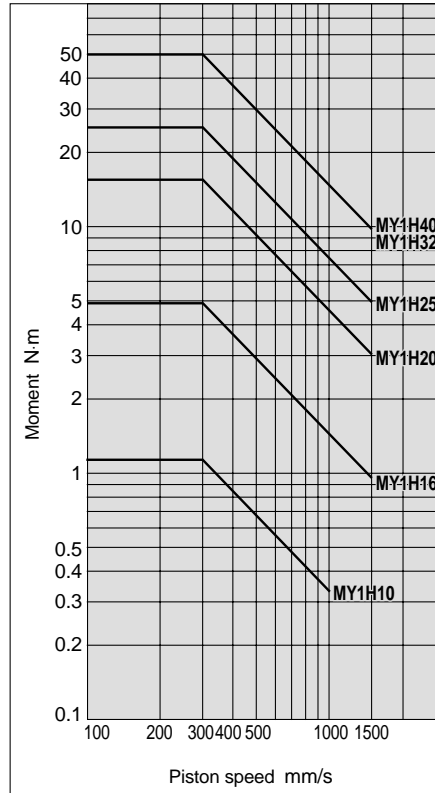
Maximum allowable load

Select the load from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.

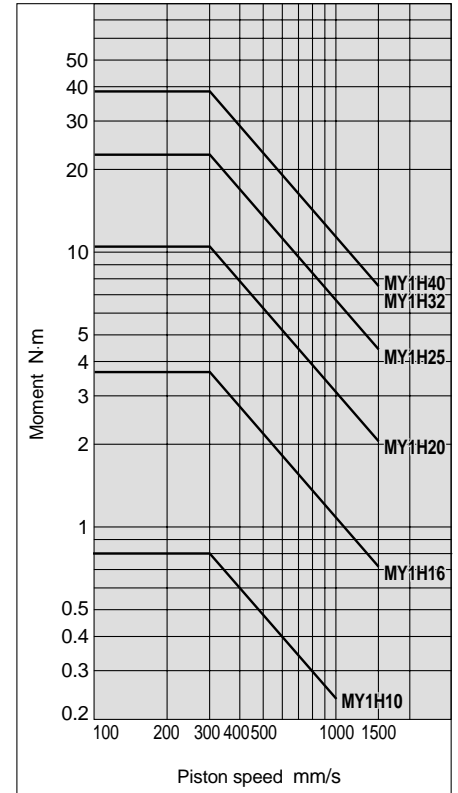
MY1H/M₁



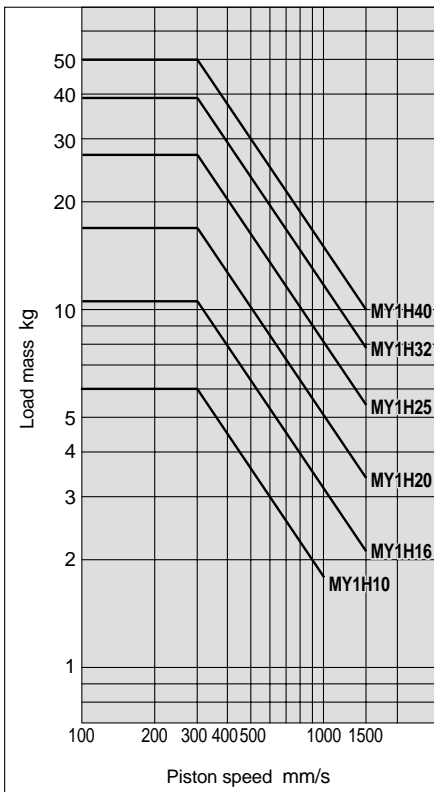
MY1H/M₂



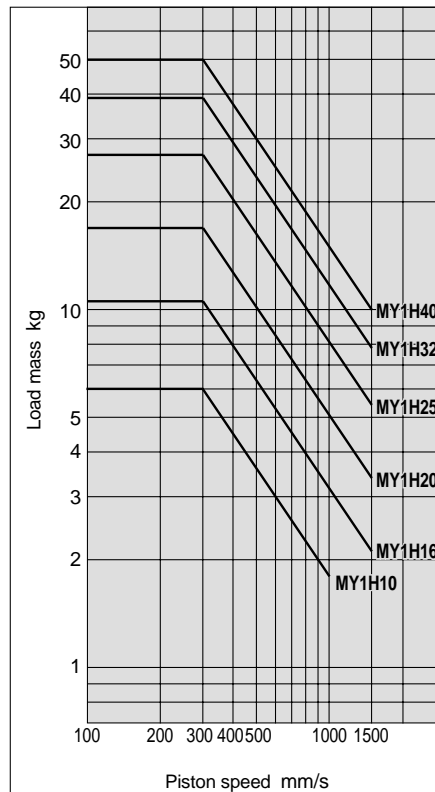
MY1H/M₃



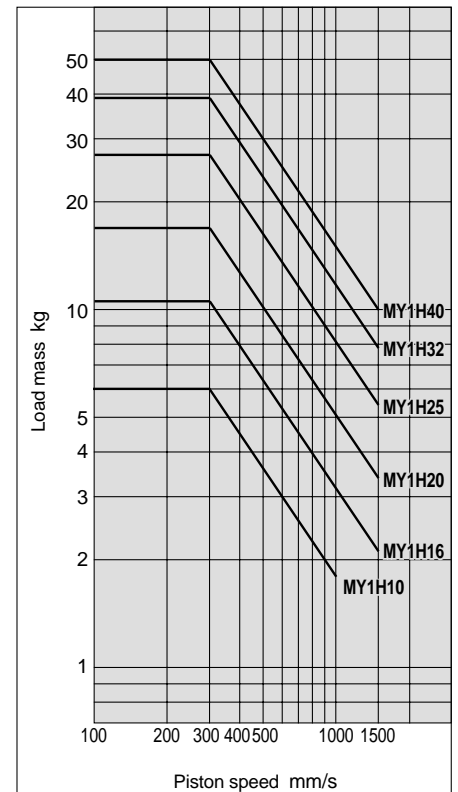
MY1H/m₁



MY1H/m₂



MY1H/m₃



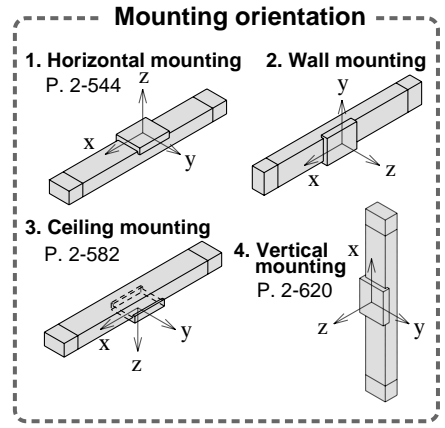
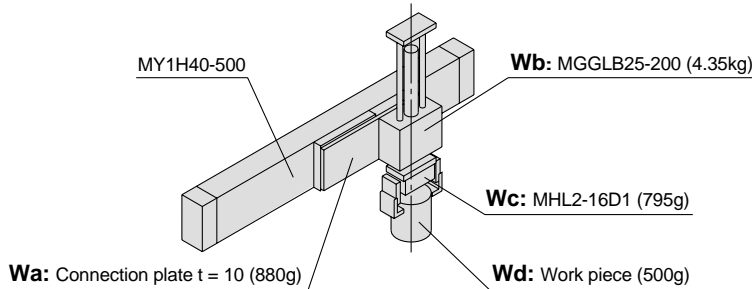
Series MY1H Model Selection

The following are steps for selection of the series MY1H best suited to your application.

Calculation of Guide Load Factor

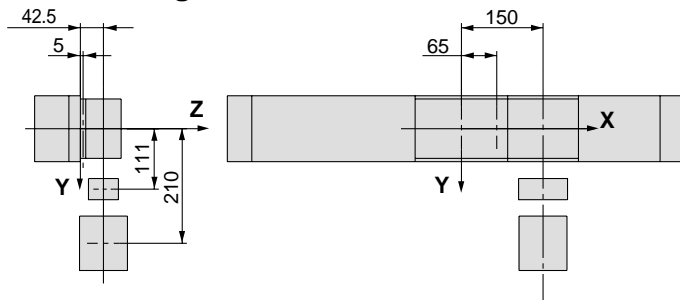
1 Operating conditions

Cylinder MY1H40-500
Average operating speed v_a ... 300mm/s
Mounting orientation Wall mounting



Refer to the pages above for actual examples of calculation for each orientation.

2 Load blocking



Mass and centre of gravity for each work piece

Work piece no. W_n	Mass m_n	Center of gravity		
		X-axis X_n	Y-axis Y_n	Z-axis Z_n
Wa	0.88kg	65mm	0mm	5mm
Wb	4.35kg	150mm	0mm	42.5mm
Wc	0.795kg	150mm	111mm	42.5mm
Wd	0.5kg	150mm	210mm	42.5mm

$n = a, b, c, d$

3 Composite centre of gravity calculation

$$m_3 = \sum m_n$$

$$= 0.88 + 4.35 + 0.795 + 0.5 = \mathbf{6.525kg}$$

$$X = \frac{1}{m_3} \times \sum (m_n \times X_n)$$

$$= \frac{1}{6.525} (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 0.5 \times 150) = \mathbf{138.5mm}$$

$$Y = \frac{1}{m_3} \times \sum (m_n \times Y_n)$$

$$= \frac{1}{6.525} (0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 0.5 \times 210) = \mathbf{29.6mm}$$

$$Z = \frac{1}{m_3} \times \sum (m_n \times Z_n)$$

$$= \frac{1}{6.525} (0.88 \times 5 + 4.35 \times 42.5 + 0.795 \times 42.5 + 0.5 \times 42.5) = \mathbf{37.4mm}$$

4 Calculation of load factor for static load

m_3 : Mass

m_3 max (from 1 of graph MY1H/ m_3) = 50 (kg)

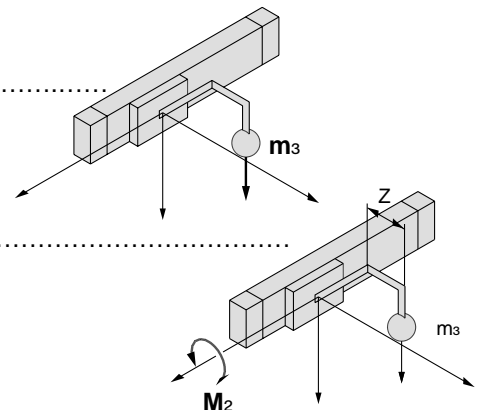
$$\text{Load factor } \alpha_1 = m_3 / m_3 \text{ max} = 6.525/50 = \mathbf{0.13}$$

M_2 : Moment

M_2 max (from 2 of graph MY1H/ M_2) = 50 (N·m)

$$M_2 = m_3 \times g \times Z = 6.525 \times 9.8 \times 37.4 \times 10^{-3} = 2.39 \text{ (N·m)}$$

$$\text{Load factor } \alpha_2 = M_2 / M_2 \text{ max} = 2.39/50 = \mathbf{0.05}$$

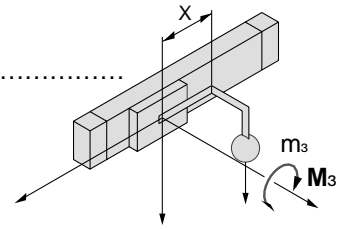


M₃: Moment

M₃ max (from 3 of graph MY1H/M₃) = 38.7 (N·m)

$$M_3 = m_3 \times g \times X = 6.525 \times 9.8 \times 138.5 \times 10^{-3} = 8.86 \text{ (N·m)}$$

$$\text{Load factor } \alpha_3 = M_3 / M_{3 \text{ max}} = 8.86 / 38.7 = \mathbf{0.23}$$



5 Calculation of load factor for dynamic moment

Equivalent load FE at impact

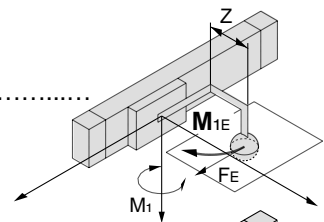
$$F_E = \frac{1.4}{100} \times v_a \times g \times m = \frac{1.4}{100} \times 300 \times 9.8 \times 6.525 = 268.6 \text{ (N)}$$

M_{1E}: Moment

M_{1E} max (from 4 of graph MY1H/M₁ where 1.4v_a = 420mm/s) = 35.9 (N·m)

$$M_{1E} = \frac{1}{3} \times F_E \times Z = \frac{1}{3} \times 268.6 \times 37.4 \times 10^{-3} = 3.35 \text{ (N·m)}$$

$$\text{Load factor } \alpha_4 = M_{1E} / M_{1E \text{ max}} = 3.35 / 35.9 = \mathbf{0.09}$$

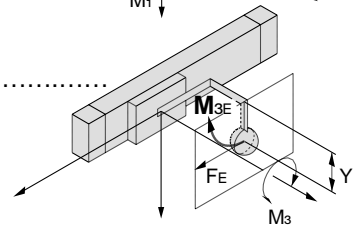


M_{3E}: Moment

M_{3E} max (from 5 of graph MY1H/M₃ where 1.4v_a = 420mm/s) = 27.6 (N·m)

$$M_{3E} = \frac{1}{3} \times F_E \times Y = \frac{1}{3} \times 268.6 \times 29.6 \times 10^{-3} = 2.65 \text{ (N·m)}$$

$$\text{Load factor } \alpha_5 = M_{3E} / M_{3E \text{ max}} = 2.65 / 27.6 = \mathbf{0.10}$$



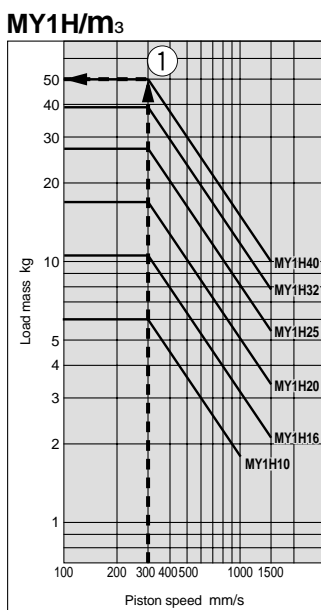
6 Sum and examination of guide load factors

$$\Sigma \alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 = \mathbf{0.60} \leq 1$$

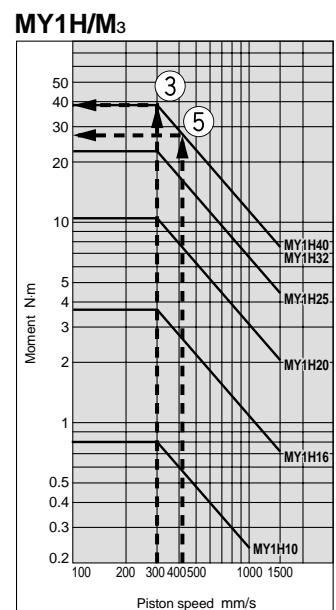
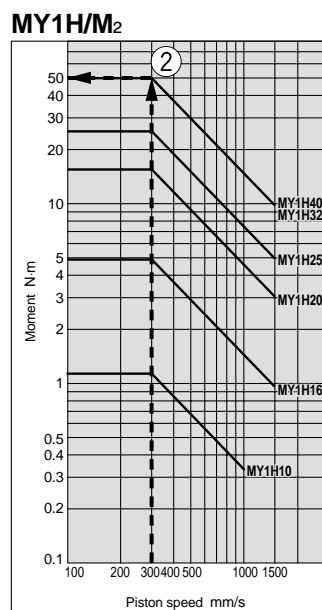
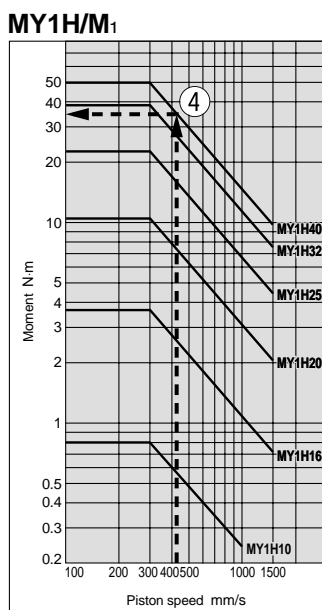
The above calculation is within the allowable value and the selected model can be used.
Select a separate shock absorber.

In an actual calculation, when the sum of guide load factors $\Sigma \alpha$ in the formula above is more than 1, consider decreasing the speed, increasing the bore size, or changing the product series. Also, this calculation can be performed easily with the "SMC Pneumatics CAD System".

Load mass



Allowable moment



Mechanically Jointed Rodless Cylinder

Series MY1H

High Precision Guide Type/ø10, ø16, ø20, ø25, ø32, ø40

How to Order

High Precision Guide Type

E MY1H 25 **300** **Z73**

Thread Port (ø25 to ø40)

—	Rc(PT)
E	G(PF)

High precision guide type

Bore size

10	10mm
16	16mm
20	20mm
25	25mm
32	32mm
40	40mm



Stroke
Refer to the standard stroke table on page 2-601

Piping

Nil	Standard type
G	Centralized piping type

Note) For ø10, only G is available.

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	"n" pcs.

Auto switch type

Nil	Without auto switch
------------	---------------------

* Refer to the table below for auto switch model numbers.

End lock position

Nil	Without end lock
E	Right side
F	Left side
W	Both sides

* MY1H10 is not available with end lock.
* Refer to page 2-612 for end lock positions.

Stroke adjusting unit

Nil	Both ends
S	One end

Note) "S" is applicable for stroke adjusting units A, L and H.

Stroke adjusting unit

Nil	Without adjusting unit
A	With adjusting bolt
L	With low load shock absorber + adjusting bolt
H	With high load shock absorber + adjusting bolt
AL	With one A unit and one L unit each
AH	With one A unit and one H unit each
LH	With one L unit and one H unit each

Shock absorbers for L and H units

Bore size (mm)	10	16	20	25	32	40
Unit type	—	RB0806	RB1007	RB1412	RB1412	RB2015
L unit	—	RB0806	RB1007	RB1412	RB1412	RB2015
H unit	RB0805	—	RB1007	RB1412	RB1412	RB2015

Note) MY1H16 is not available with H unit.
MY1H10 is not available with A and L units.

Options

Stroke adjusting unit numbers

Bore size (mm)	10	16	20
Unit type	—	MYH-A16A	MYH-A20A
A unit	—	MYH-A16A	MYH-A20A
L unit	—	MYH-A16L	MYH-A20L
H unit	MYH-A10H	—	MYH-A20H

Bore size (mm)	25	32	40
Unit type	MYH-A25A	MYH-A32A	MYH-A40A
A unit	MYH-A25A	MYH-A32A	MYH-A40A
L unit	MYH-A25L	MYH-A32L	MYH-A40L
H unit	MYH-A25H	MYH-A32H	MYH-A40H

Side support numbers

Bore size (mm)	10	16	20
Type	MY-S10A	MY-S16A	MY-S20A
Side support A	MY-S10A	MY-S16A	MY-S20A
Side support B	MY-S10B	MY-S16B	MY-S20B

Bore size (mm)	25	32	40
Type	MY-S25A	MY-S32A	MY-S40A
Side support A	MY-S25A	MY-S32A	MY-S40A
Side support B	MY-S25B	MY-S32B	MY-S40B

Refer to page 2-613 for detailed information on dimensions, etc.

Applicable auto switches/ For ø10, ø16, ø20

Type	Special function	Electrical entry	Indicator light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load		
					DC	AC	Electrical entry direction	Perpendicular	In-line	0.5 (Nil)	3 (L)		5 (Z)	
Reed switch	—	Grommet	No	2 wire	24V	5V	100V	A90V	A90	●	●	—	IC circuit	Relay, PLC
						12V	100V	A93V	A93	●	●	—	—	
				3 wire (NPN equiv.)	—	5V	—	A96V	A96	●	●	—	—	IC circuit
Solid state switch	—	Grommet	Yes	3 wire (NPN)	24V	12V	—	M9NV	M9N	●	●	—	Relay, PLC	
								M9PV	M9P	●	●	—		
				3 wire (PNP)	2 wire	M9BV	M9B	●	●	—				
				2 wire		M9NV	M9NW	●	●	○				
				3 wire (NPN)	3 wire (PNP)	M9PW	M9PW	●	●	○				
				2 wire		M9BV	M9BW	●	●	○				

* Lead wire length symbols: 0.5m..... Nil (Example) M9NW
3m..... L M9NWL
5m..... Z M9NZ

** Solid state switches marked with a "○" symbol are produced upon receipt of order.

For ø25, ø32, ø40,

Type	Special function	Electrical entry	Indicator light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load		
					DC	AC	Electrical entry direction	Perpendicular	In-line	0.5 (Nil)	3 (L)		5 (Z)	
Reed switch	—	Grommet	Yes	3 wire (NPN equiv.)	24V	12V	100V	—	Z76	●	●	—	IC circuit	Relay, PLC
								5V	100V	—	Z73	●	●	
Solid state switch	—	Grommet	Yes	3 wire (NPN)	24V	12V	—	Y69A	Y59A	●	●	○	IC circuit	Relay, PLC
								Y7PV	Y7P	●	●	○	—	
				3 wire (PNP)	2 wire	Y69B	Y59B	●	●	○	—			
				2 wire		Y7NW	Y7NW	●	●	○	IC circuit			
				3 wire (NPN)	3 wire (PNP)	Y7PW	Y7PW	●	●	○	—			
				2 wire		Y7BW	Y7BW	●	●	○	—			

* Lead wire length symbols: 0.5m..... Nil (Example) Y59A
3m..... L Y59AL
5m..... Z Y59AZ

** Solid state switches marked with a "○" symbol are produced upon receipt of order.

Series MY1H

Cushion Capacity

Cushion selection

<Rubber bumper>

Rubber bumpers are a standard feature on MY1B10.

Since the stroke absorption of rubber bumpers is short, when adjusting the stroke with an A unit, install an external shock absorber.

The load and speed range which can be absorbed by a rubber bumper is inside the rubber bumper limit line of the graph.

<Air cushion>

Air cushions are a standard feature on mechanically jointed rodless cylinders.

The air cushion mechanism is installed to avoid excessive impact of the piston at the stroke end during high speed operation. The air cushion does not act to decelerate the piston near the stroke end.

The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

<Stroke adjusting unit with shock absorber>

Use this unit when operating with a load or speed exceeding the air cushion limit line, or when cushioning is necessary because the cylinder stroke is outside of the effective air cushion stroke range due to stroke adjustment.

L unit

Use this unit when cushioning is necessary outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

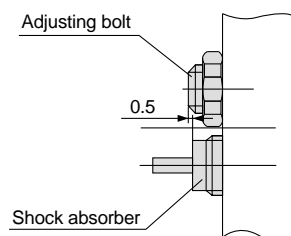
H unit

Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

⚠ Caution

1. Refer to the diagram below when using the adjusting bolt to perform stroke adjustment.

When the effective stroke of the shock absorber decreases as a result of stroke adjustment, the absorption capacity decreases dramatically. Secure the adjusting bolt at the position where it protrudes approximately 0.5mm from the shock absorber.



2. Do not use a shock absorber and air cushion together.

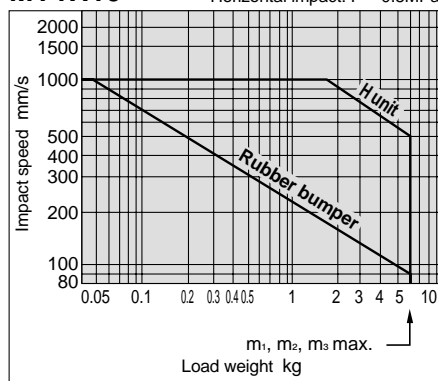
Air cushion stroke

Unit: mm

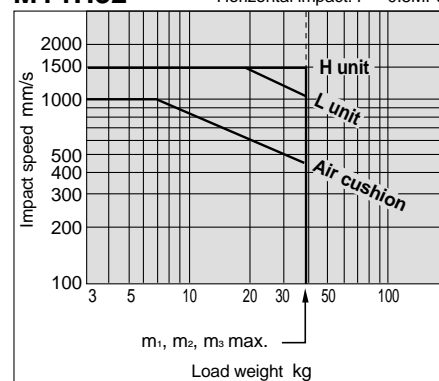
Bore size (mm)	Cushion stroke
16	12
20	15
25	15
32	19
40	24

Absorption capacity of rubber bumper, air cushion and stroke adjusting units

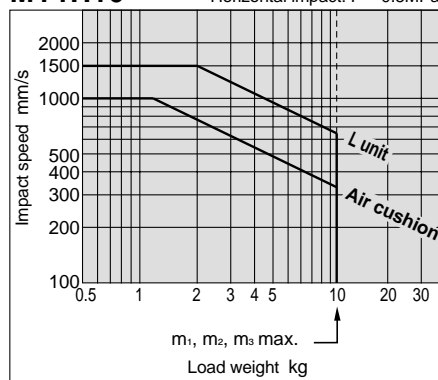
MY1H10 Horizontal impact: P = 0.5MPa



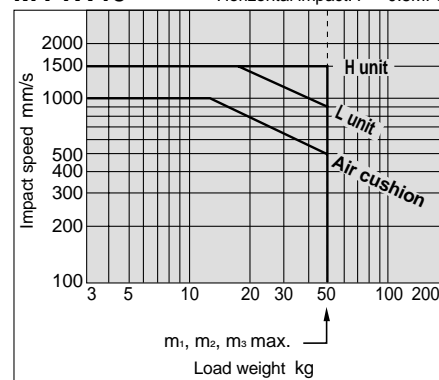
MY1H32 Horizontal impact: P = 0.5MPa



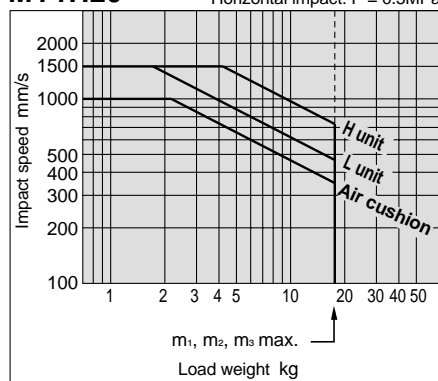
MY1H16 Horizontal impact: P = 0.5MPa



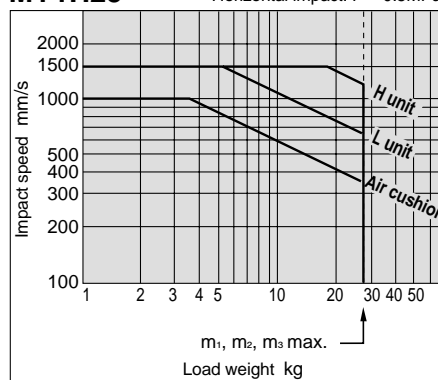
MY1H40 Horizontal impact: P = 0.5MPa



MY1H20 Horizontal impact: P = 0.5MPa



MY1H25 Horizontal impact: P = 0.5MPa



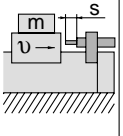
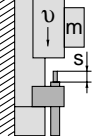
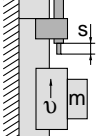
Stroke adjusting unit holding bolt tightening torque

Unit: N·m

Bore size (mm)	Tightening torque
10	Refer to page 64 for unit adjusting procedure.
16	0.6
20	1.5
25	1.5
32	3.0
40	5.0

Calculation of absorbed energy for stroke adjusting unit with shock absorber

Unit: N·m

Type of impact	Horizontal	Vertical (downward)	Vertical (upward)
			
Kinetic energy E_1	$\frac{1}{2} m \cdot v^2$		
Thrust energy E_2	F·s	F·s + m·g·s	F·s - m·g·s
Absorbed energy E	$E_1 + E_2$		

Symbols

v: Speed of impacting object (m/s)

m: Weight of impacting object (kg)

F: Cylinder thrust (N)

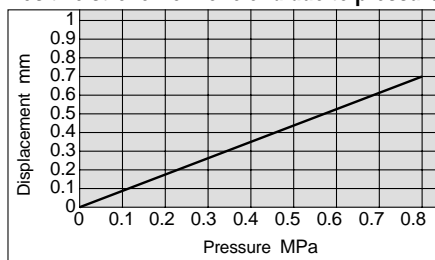
g: Gravitational acceleration (9.8m/s²)

s: Shock absorber stroke (m)

Note) The speed of the impacting object is measured at the time of impact with the shock absorber.

Rubber bumper (ø10 only)

Positive stroke from one end due to pressure

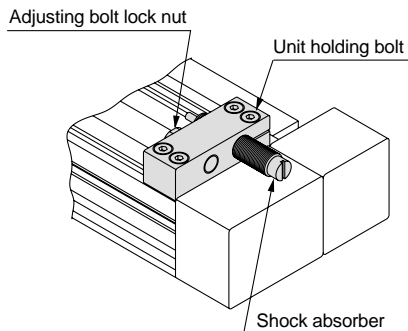


⚠ Specific Product Precautions

⚠ Caution

Be careful not to get hands caught in the unit.

- When using a product with stroke adjusting unit, the space between the slide table (slider) and the stroke adjusting unit becomes narrow at the stroke end, causing a danger of hands getting caught. Install a protective cover to prevent direct contact with the human body.



<Fastening of unit>

The unit can be fastened by uniformly tightening the four unit holding bolts.

⚠ Caution

Do not operate with the stroke adjusting unit fixed in an intermediate position.

When the stroke adjusting unit is fixed in an intermediate position, slippage can occur depending on the amount of energy released at the time of an impact. In this case, we recommend using the adjusting holder mounting brackets available with order made specifications - X 416 and - X 417. (Except $\phi 10$.)

For other lengths, consult SMC. (Refer to "Stroke adjusting unit holding bolt tightening torque".)

<Stroke adjustment with adjusting bolt>

Loosen the adjusting bolt lock nut, and adjust the stroke from the head cover side using a hexagon wrench. Re-tighten the lock nut.

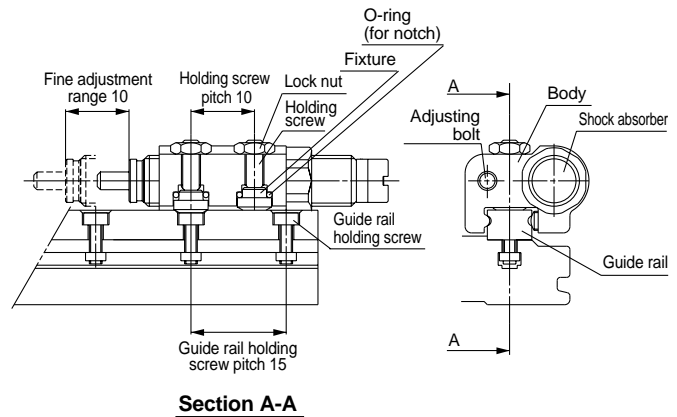
<Stroke adjustment with shock absorber>

Loosen the two unit holding bolts on the shock absorber side, turn the shock absorber and adjust the stroke. Then, uniformly tighten the unit holding bolts to secure the shock absorber.

Take care not to over-tighten the holding bolts. (Except $\phi 16$ and $\phi 20$) (Refer to "Stroke adjusting unit holding bolt tightening torque".)

⚠ Caution

To adjust the stroke adjusting unit of the MY1H10, follow the procedure shown below.



Adjusting Procedure

- Loosen the two lock nuts, and then loosen the holding screws by turning them approximately two turns.
- Move the body to the notch just before the desired stroke. (The notches are found in alternating increments of 5mm and 10mm.)
- Tighten the holding screw to 0.3N·m. Make sure that the tightening does not cause excessive torque.
The fixture fits into the fastening hole in the guide rail to prevent slippage, which enables fastening with low torque.
- Tighten the lock nut to 0.6N·m.
- Make fine adjustments with the adjusting bolt and shock absorber.

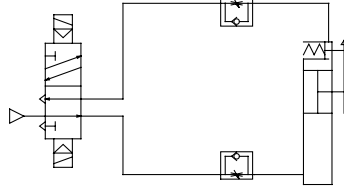
⚠ Specific Product Precautions

With End Locks

Recommended Pneumatic Circuits

⚠ Caution

This is necessary for the correct locking and unlocking actions.



Operating Precautions

⚠ Caution

1. Do not use 3 position solenoid valves.

Avoid use in combination with 3 position solenoid valves (especially closed centre metal seal types). If pressure is trapped in the port on the lock mechanism side, the cylinder cannot be locked.

Furthermore, even after being locked, the lock may be released after some time due to air leaking from the solenoid valve and entering the cylinder.

2. Back pressure is required when releasing the lock.

Before starting operation, be sure to control the system so that air is supplied to the side without the lock mechanism (in case of locks on both ends, the side where the slide table is not locked) as shown in the figure above. There is a possibility that the lock may not be released. (Refer to the section on releasing the lock.)

3. Release the lock when mounting or adjusting the cylinder.

If mounting or other work is performed when the cylinder is locked, the lock unit may be damaged.

4. Operate at 50% or less of the theoretical output.

If the load exceeds 50% of the theoretical output, this may cause problems such as failure of the lock to release, or damage to the lock unit.

5. Do not operate multiple synchronized cylinders.

Avoid applications in which two or more end lock cylinders are synchronized to move one work piece, as one of the cylinder locks may not be able to release when required.

6. Use a speed controller with meter-out control.

It may not be possible to release the lock with meter-in control.

7. Be sure to operate completely to the cylinder stroke end on the side with the lock.

If the cylinder piston does not reach the end of the stroke, locking and unlocking may not be possible. (Refer to the section on adjusting the end lock mechanism.)

Operating Pressure

⚠ Caution

1. Apply pressure of at least 0.15MPa to the port on the lock mechanism side. This is necessary to release the lock.

Exhaust Speed

⚠ Caution

1. Locking will occur automatically if the pressure applied to the port on the lock mechanism side falls to 0.05MPa or less. In cases where the piping on the lock mechanism side is long and thin, or the speed controller is separated at some distance from the cylinder port, note that the exhaust speed will be reduced and some time may be required for the lock to engage. In addition, clogging of a silencer mounted on the solenoid valve exhaust port can produce the same effect.

Relation to Cushion

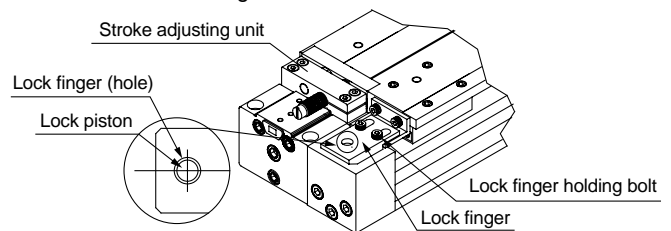
⚠ Caution

1. When the air cushion on the lock mechanism side is in a fully closed or nearly closed state, there is a possibility that the slide table will not reach the stroke end, in which case locking will not occur.

Adjusting the End Lock Mechanism

⚠ Caution

1. The end lock mechanism is adjusted at the time of shipping. Therefore, adjustment for operation at the stroke end is unnecessary.
2. Adjust the end lock mechanism after the stroke adjusting unit has been adjusted. The adjusting bolt and shock absorber of the stroke adjusting unit must be adjusted and secured first. Locking and unlocking may not occur otherwise.
3. Perform fine adjustment of the end lock mechanism as follows. Loosen the lock finger holding bolts, and then adjust by aligning the center of the lock piston with the center of the lock finger hole. Secure the lock finger.



Releasing the Lock

⚠ Warning

1. Before releasing the lock, be sure to supply air to the side without the lock mechanism, so that there is no load applied to the lock mechanism when it is released. (Refer to the recommended pneumatic circuits.) If the lock is released when the port on the side without the lock is in an exhaust state, and with a load applied to the lock unit, the lock unit may be subjected to an excessive force and be damaged. Furthermore, sudden movement of the slide table is very dangerous.

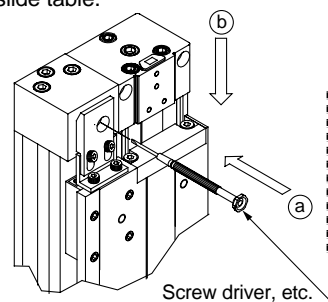
Manual Release

⚠ Caution

1. When manually releasing the end lock, be sure to release the pressure.

If the end lock is released while pressure remains, unexpected lurching may damage work pieces, etc.

2. Perform manual release of the end lock mechanism as follows. Push the lock piston down with a screw driver, etc., and move the slide table.



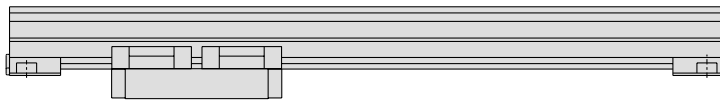
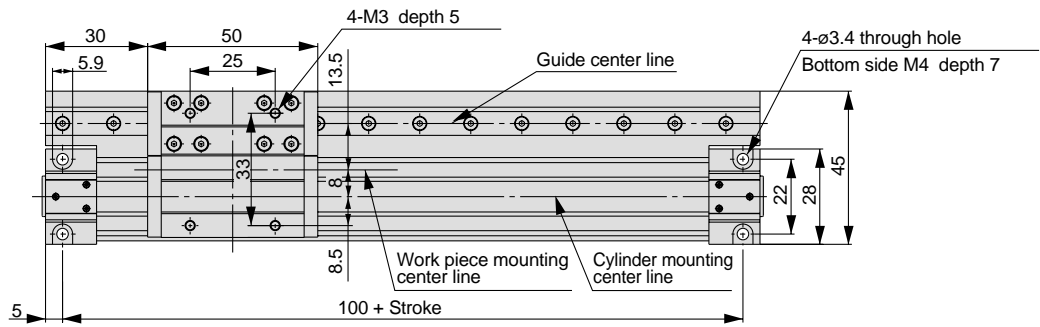
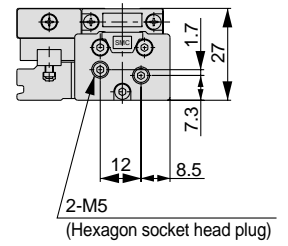
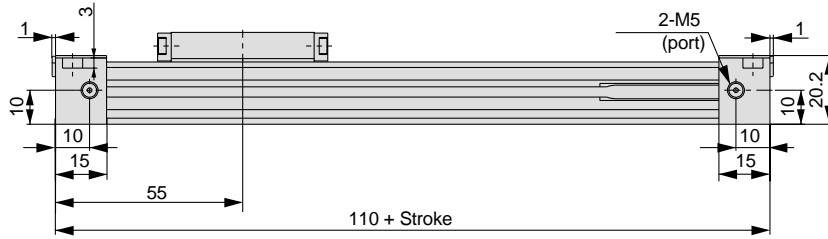
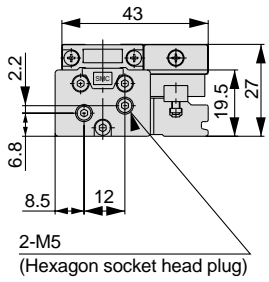
Other handling precautions regarding mounting, piping, and environment are the same as the standard series.

Series MY1H

Centralized Piping Type $\varnothing 10$

[Refer to page 2-648 regarding centralized piping port variations.]

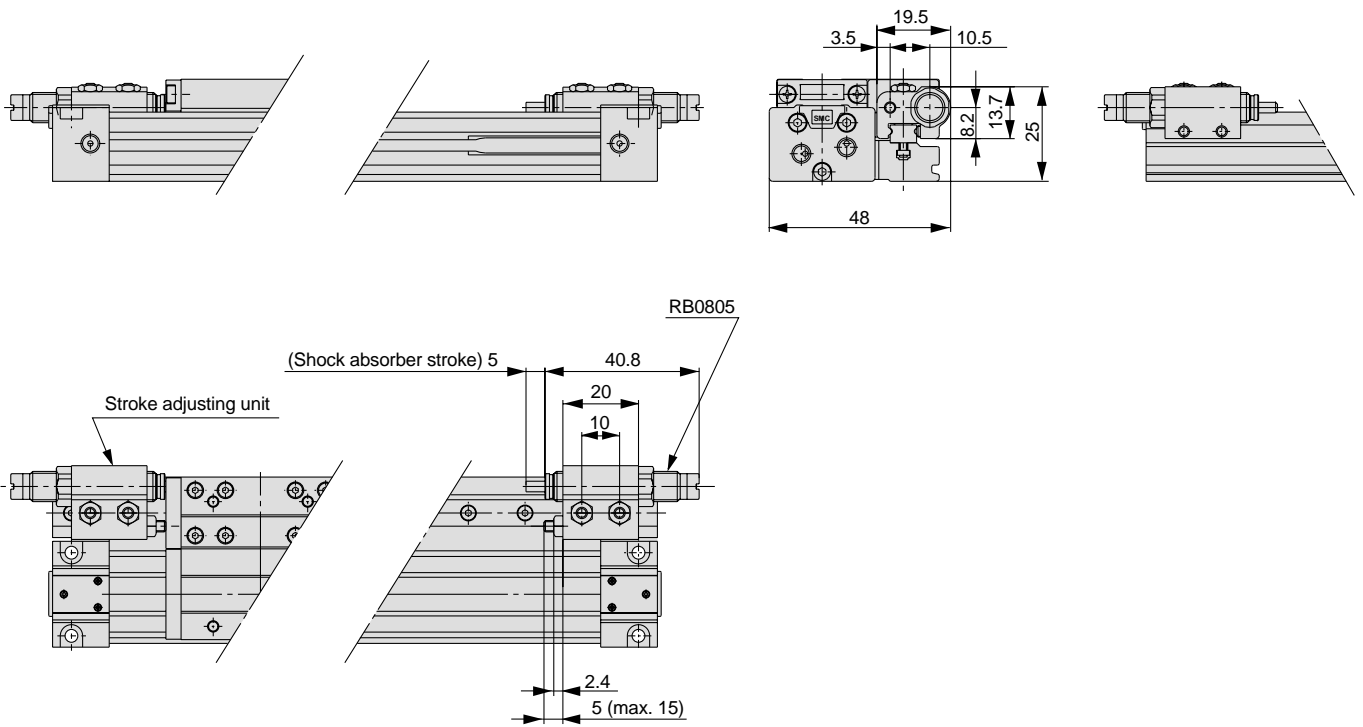
MY1H10G—Stroke



Stroke adjusting unit

Shock absorber + Adjusting bolt

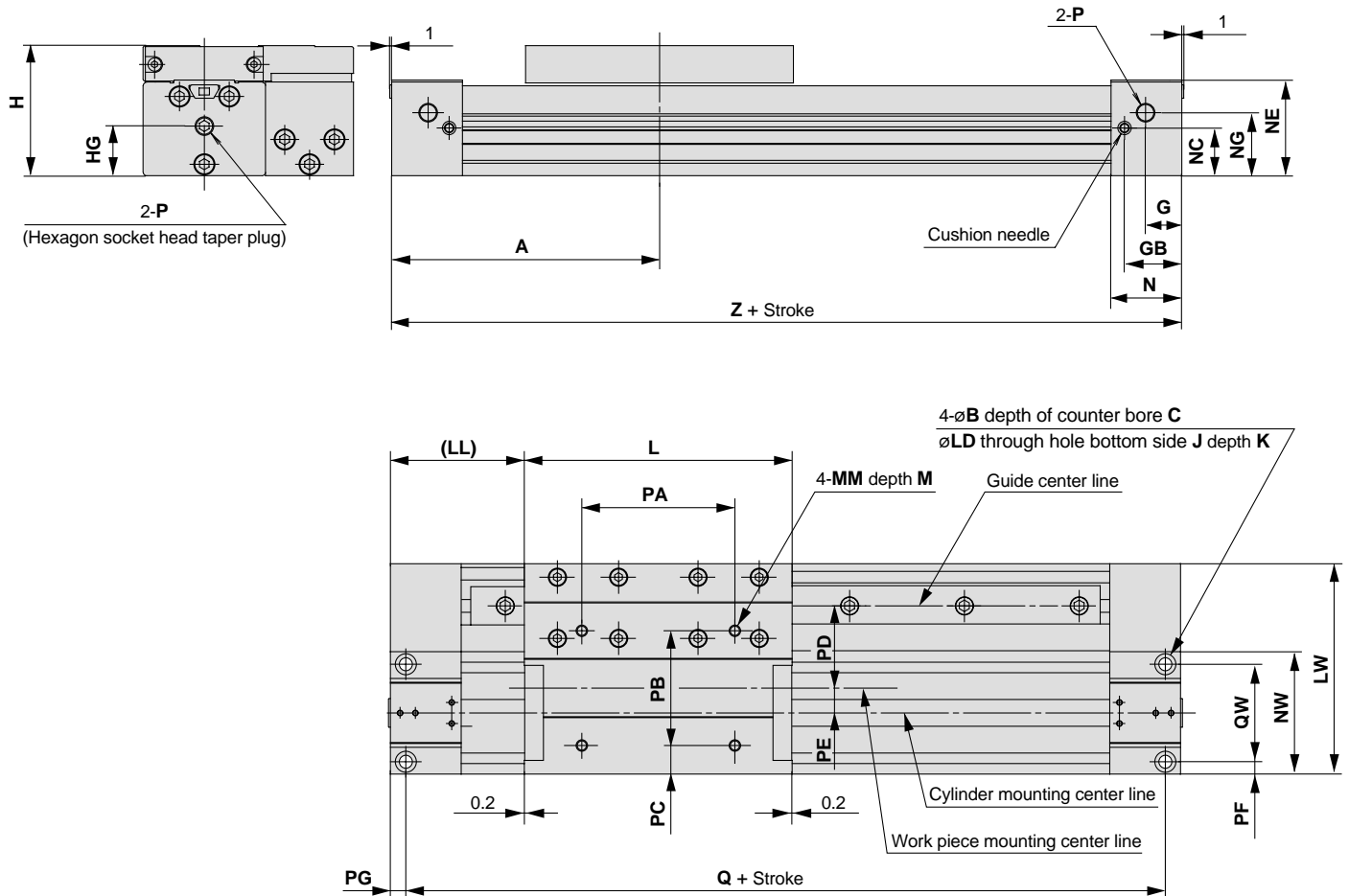
MY1H10G — Stroke H



Series MY1H

Standard Type $\varnothing 16$ to $\varnothing 40$

MY1H Bore size — Stroke



Model	A	B	C	G	GB	H	HG	J	K	L	LD	(LL)	LW	M	MM	N
MY1H16	80	6	3.5	9	16	40	13.5	M5	10	80	3.5	40	60	7	M4	20
MY1H20	100	7.5	4.5	12.5	20.5	46	17.5	M6	12	100	4.5	50	78	8	M5	25
MY1H25	110	9	5.5	16	24.5	54	21	M6	9.5	114	5.6	53	90	9	M5	30
MY1H32	140	11	6.6	19	30	68	26	M8	16	140	6.8	70	110	13	M6	37
MY1H40	170	14	8.5	23	36.5	84	33.5	M10	15	170	8.6	85	121	13	M6	45

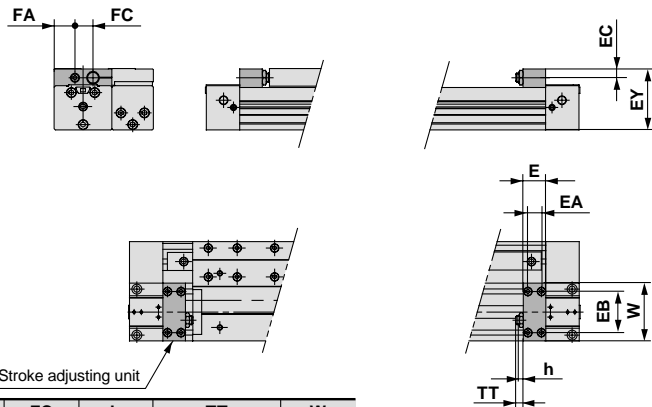
Model	NC	NE	NG	NW	P	PA	PB	PC	PD	(PE)	PF	PG	Q	QW	Z
MY1H16	13.5	27.8	13.5	37	M5	40	40	7.5	21	9	3.5	3.5	153	30	160
MY1H20	17.5	34	17.5	45	M5	50	40	14.5	27	12	4.5	4.5	191	36	200
MY1H25	20	40.5	28	53	1/8	60	50	14.5	32	13	5.5	7	206	42	220
MY1H32	25	50	33	64	1/8	80	60	15	42	13	6.5	8	264	51	280
MY1H40	30.5	63	42.5	75	1/4	100	80	20.5	37.5	23	8	9	322	59	340

*P indicates cylinder supply ports. * The plug for MY1H16/20-P is a hexagon socket head plug.

Stroke adjusting unit

With adjusting bolt

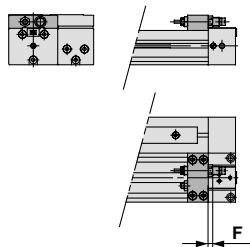
MY1H **Bore size** — **Stroke** A



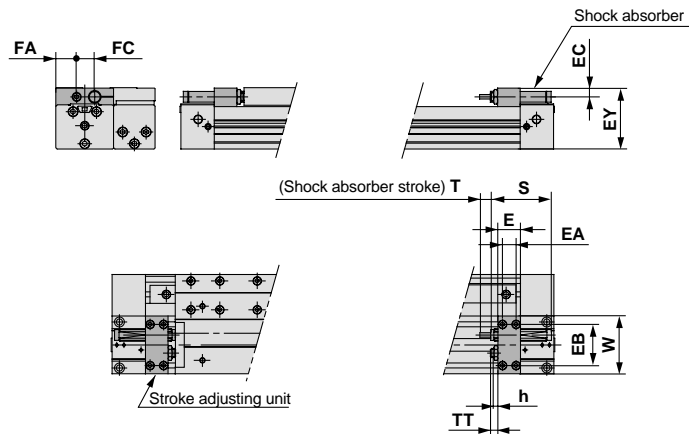
Model	E	EA	EB	EC	EY	FA	FC	h	TT	W
MY1H16	14.6	7	28	5.8	39.5	11.5	13	3.6	5.4 (max. 11)	37
MY1H20	19	10	33	5.8	45.5	15	14	3.6	6 (max. 12)	45
MY1H25	18	9	40	7.5	53.5	16	21	3.5	5 (max. 16.5)	53
MY1H32	25	14	45.6	9.5	67.5	23	20	4.5	8 (max. 20)	64
MY1H40	31	19	55	11	82	24.5	26	4.5	9 (max. 25)	75

Low load shock absorber + Adjusting bolt

MY1H **Bore size** — **Stroke** L



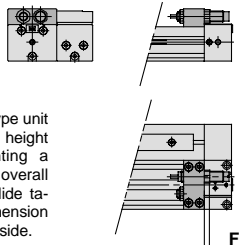
For MY1H16, 20



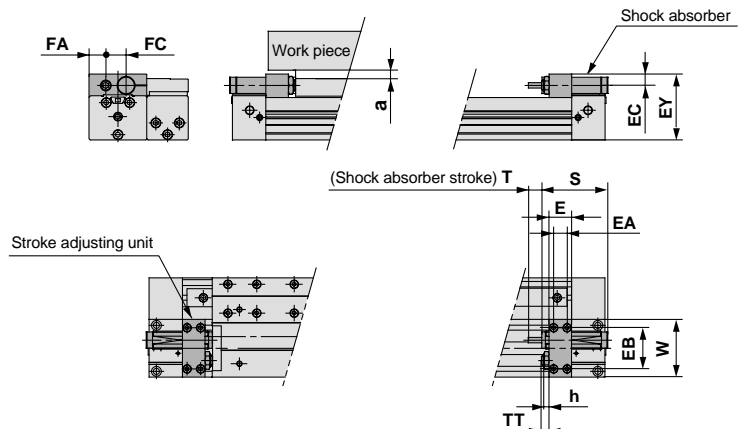
Model	E	EA	EB	EC	EY	F	FA	FC	h	S	T	TT	W	Shock absorber model
MY1H16	14.6	7	28	5.8	39.5	4	11.5	13	3.6	40.8	6	5.4 (max. 11)	37	RB0806
MY1H20	19	10	33	5.8	45.5	4	15	14	3.6	40.8	6	6 (max. 12)	45	RB0806
MY1H25	18	9	40	7.5	53.5	—	16	21	3.5	46.7	7	5 (max. 16.5)	53	RB1007
MY1H32	25	14	45.6	9.5	67.5	—	23	20	4.5	67.3	12	8 (max. 20)	64	RB1412
MY1H40	31	19	55	11	82	—	24.5	26	4.5	67.3	12	9 (max. 25)	75	RB1412

High load shock absorber + Adjusting bolt

MY1H **Bore size** — **Stroke** H



For MY1H20



Since dimension EY of the H type unit is greater than the table top height (dimension H), when mounting a workpiece that exceeds the overall length (dimension L) of the slide table, allow a clearance of dimension "a" or larger on the work piece side.

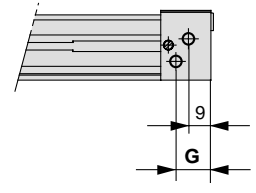
Model	E	EA	EB	EC	EY	F	FA	FC	h	S	T	TT	W	Shock absorber model	a
MY1H20	19	10	33	7.7	49.5	5	14.3	15.7	3.5	46.7	7	6 (max. 12)	45	RB1007	4
MY1H25	18	9	40	9	57	—	18	17.5	4.5	67.3	12	5 (max. 16.5)	53	RB1412	3.5
MY1H32	25	14	45.6	12.4	73	—	18.5	22.5	5.5	73.2	15	8 (max. 20)	64	RB2015	5.5
MY1H40	31	19	55	12.4	86	—	26.5	22	5.5	73.2	15	9 (max. 25)	75	RB2015	2.5

Series MY1H

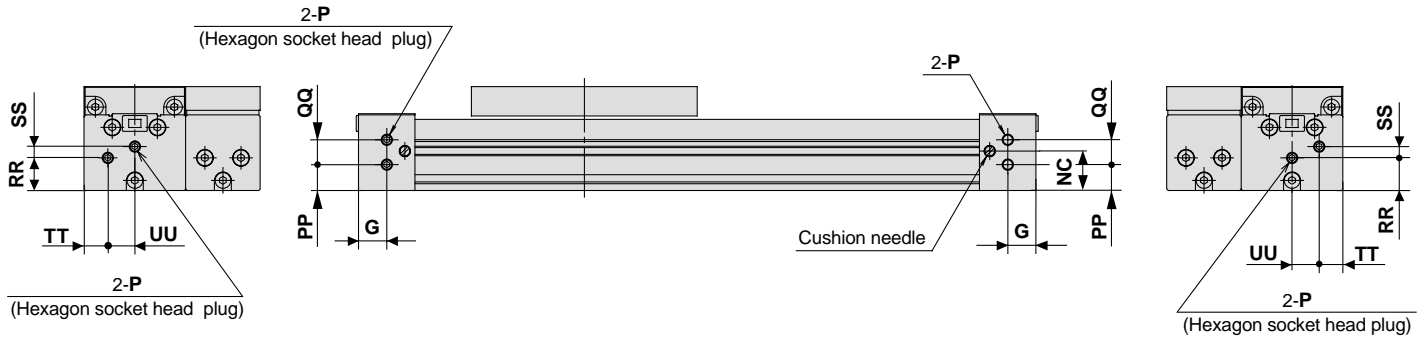
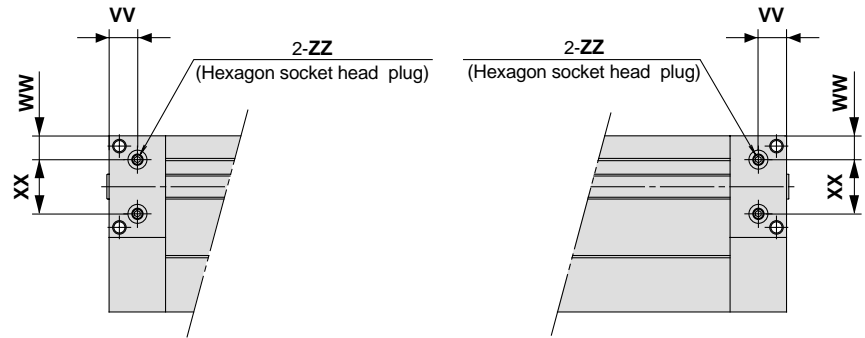
Centralized Piping Type $\varnothing 16, \varnothing 20$

Refer to page 2-648 regarding centralized piping port variations. Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions. Refer to pages 2-608 and 2-609 for details regarding dimensions, etc.

MY1H Bore size G — Stroke

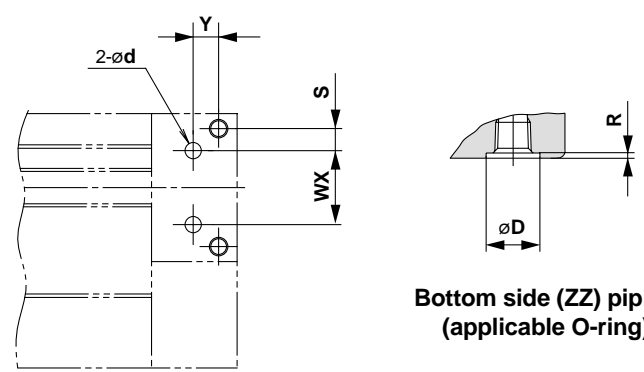


For MY1H16



Model	G	NC	P	PP	QQ	RR	SS	TT	UU	V V	WW	XX	ZZ
MY1H16G	14	14	M5	7.5	9	11	3	9	10.5	10	7.5	22	M5
MY1H20G	12.5	17.5	M5	11.5	11	14.5	5	10.5	12	12.5	10.5	24	M5

"P" indicates cylinder supply ports.



Bottom side (ZZ) piping (applicable O-ring)

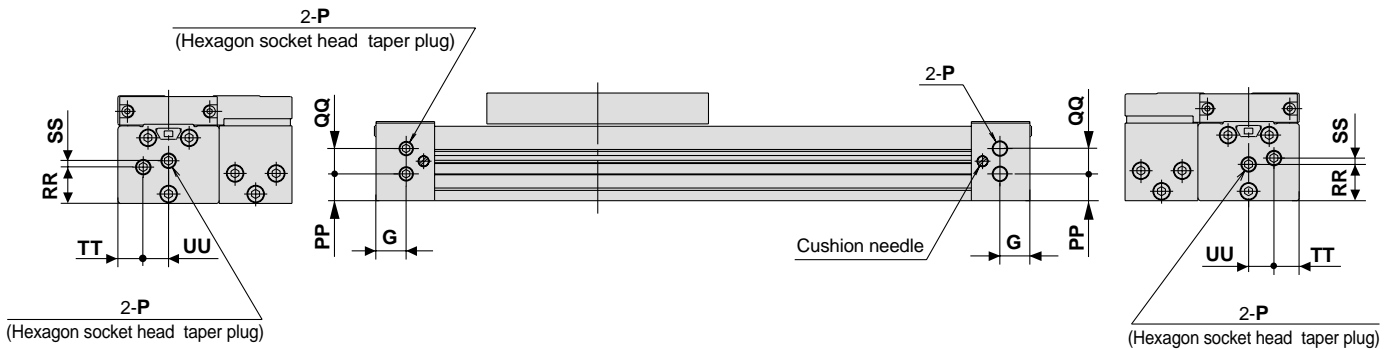
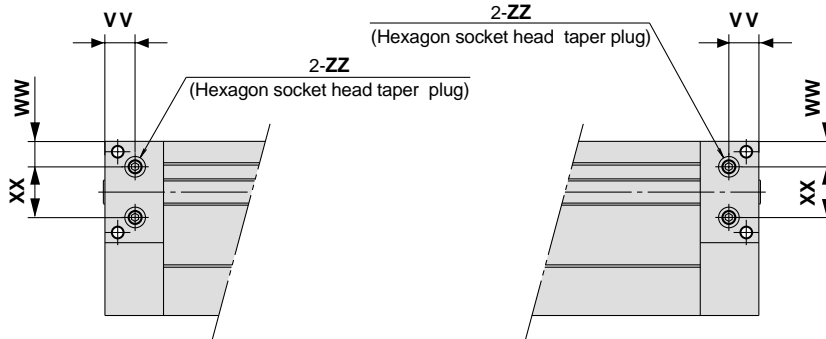
Hole sizes for centralized piping on the bottom (Machine the mounting side to the dimensions below.)

Model	WX	Y	S	d	D	R	Applicable O-ring
MY1H16G	22	6.5	4	4	8.4	1.1	C6
MY1H20G	24	8	6	4	8.4	1.1	

Centralized Piping Type $\varnothing 25$ to $\varnothing 40$

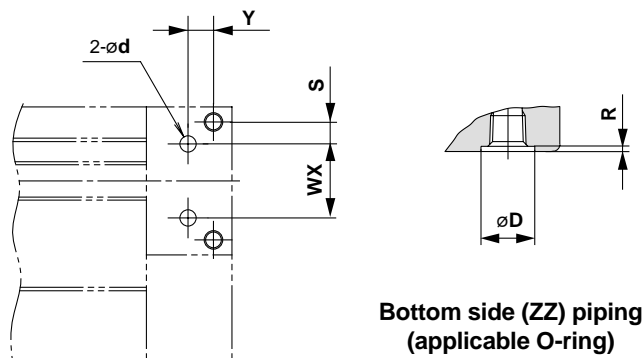
Refer to page 2-648 regarding centralized piping port variations.
Dimensions for types other than centralized piping and for the stroke adjusting unit are identical to the standard type dimensions.
Refer to pages 2-608 and 2-609 for details regarding dimensions, etc.

MY1H Bore size **G** — Stroke



Model	G	P	PP	QQ	RR	SS	TT	UU	VV	WW	XX	ZZ
MY1H25G	16	1/8	12	16	16	6	14.5	15	16	12.5	28	Rc 1/16
MY1H32G	19	1/8	17	16	23	4	16	16	19	16	32	Rc 1/16
MY1H40G	23	1/4	18.5	24	27	10.5	20	22	23	19.5	36	Rc 1/8

"P" indicates cylinder supply ports.



Bottom side (ZZ) piping
(applicable O-ring)

Hole sizes for centralized piping on the bottom

(Machine the mounting side to the dimensions below.)

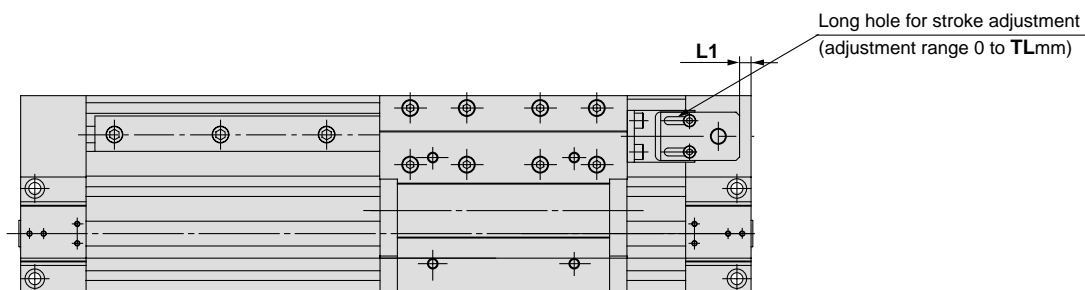
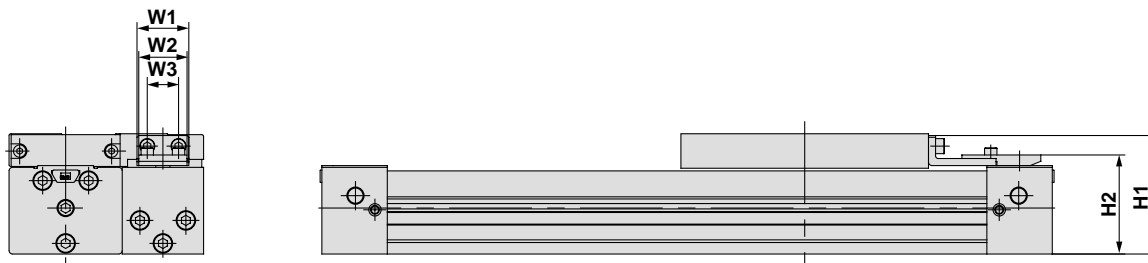
Model	WX	Y	S	d	D	R	Applicable O-ring
MY1H25G	28	9	7	6	11.4	1.1	C9
MY1H32G	32	11	9.5	6	11.4	1.1	
MY1H40G	36	14	11.5	8	13.4	1.1	C11.2

Series MY1H

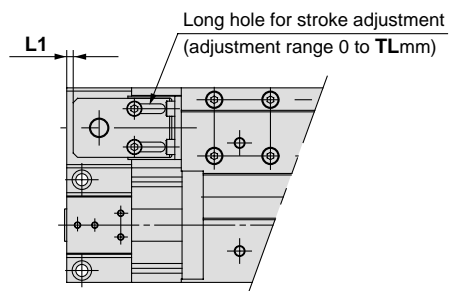
End Lock $\varnothing 16$ to $\varnothing 40$

Dimensions for types other than end lock are identical to the standard type dimensions.
Refer to page 2-609 for details regarding dimensions, etc.

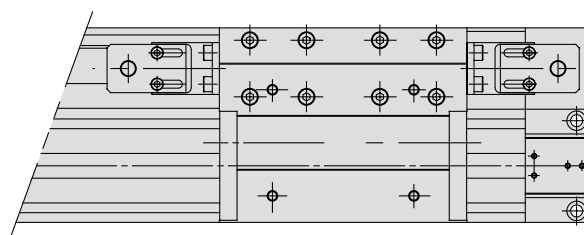
For MY1H□-□E
(right side)



For MY1H□-□F
(left side)



For MY1H□-□W
(both sides)



Dimensions

(mm)

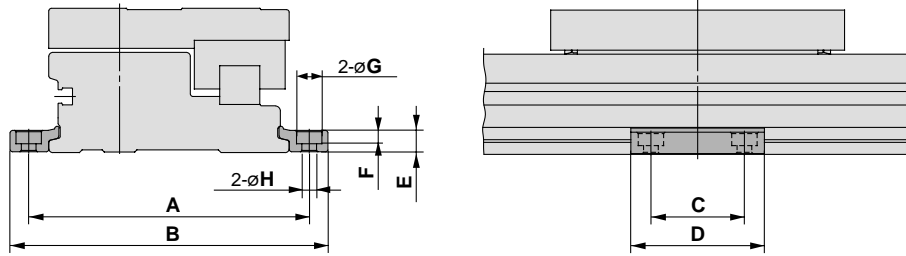
Model	H1	H2	L1	TL	W1	W2	W3
MY1H16	39.2	33	0.5	5.6	18	16	10.4
MY1H20	45.7	39.5	3	6	18	16	10.4
MY1H25	53.5	46	3	11.5	29.3	27.3	17.7
MY1H32	67	56	6.5	12	29.3	27.3	17.7
MY1H40	83	68.5	10.5	16	38	35	24.4

P indicates cylinder supply ports.

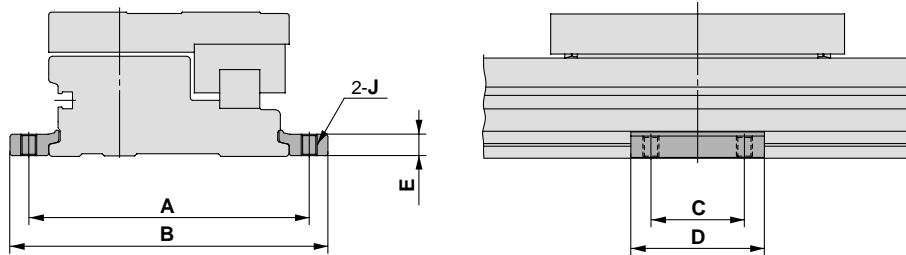
* The plug for MY1H16/20-P is a hexagon socket head plug.

Side Support

Side support A MY-S□A



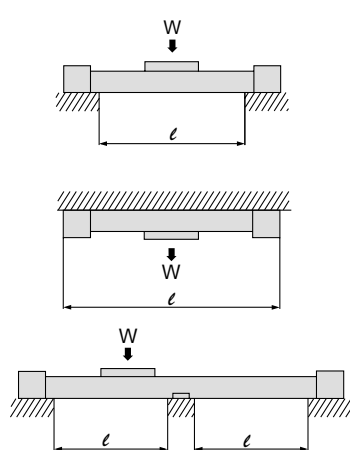
Side support B MY-S□B



Model	Applicable cylinder	A	B	C	D	E	F	G	H	J
MY-S10 _B	MY1H10	53	61.6	12	21	3.6	1.8	6.5	3.4	M4
MY-S16 _B	MY1H16	71	81.6	15	26	4.9	3	6.5	3.4	M4
MY-S20 _B	MY1H20	91	103.6	25	38	6.4	4	8	4.5	M5
MY-S25 _B	MY1H25	105	119	35	50	8	5	9.5	5.5	M6
MY-S32 _B	MY1H32	130	148	45	64	11.7	6	11	6.6	M8
MY-S40 _B	MY1H40	145	167	55	80	14.8	8.5	14	9	M10

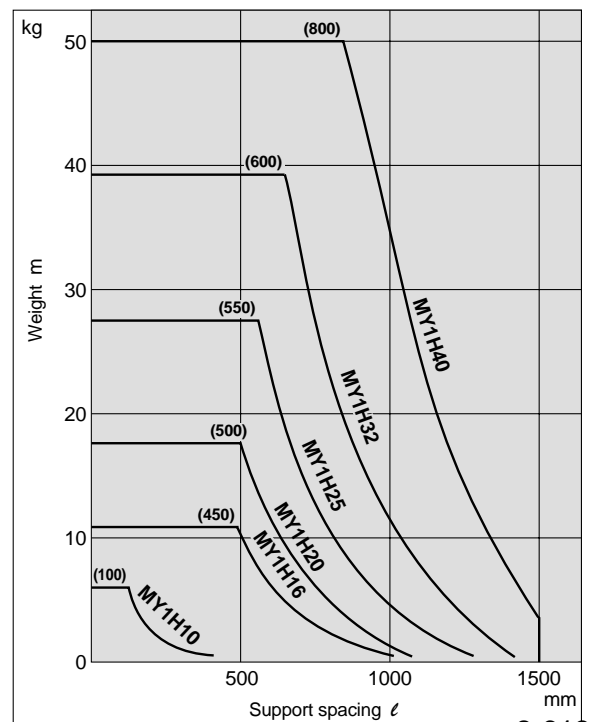
Guide for Using Side Supports

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load weight. In such a case, use a side support in the middle section. The spacing (ℓ) of the support must be no more than the values shown in the graph on the right.



⚠ Caution

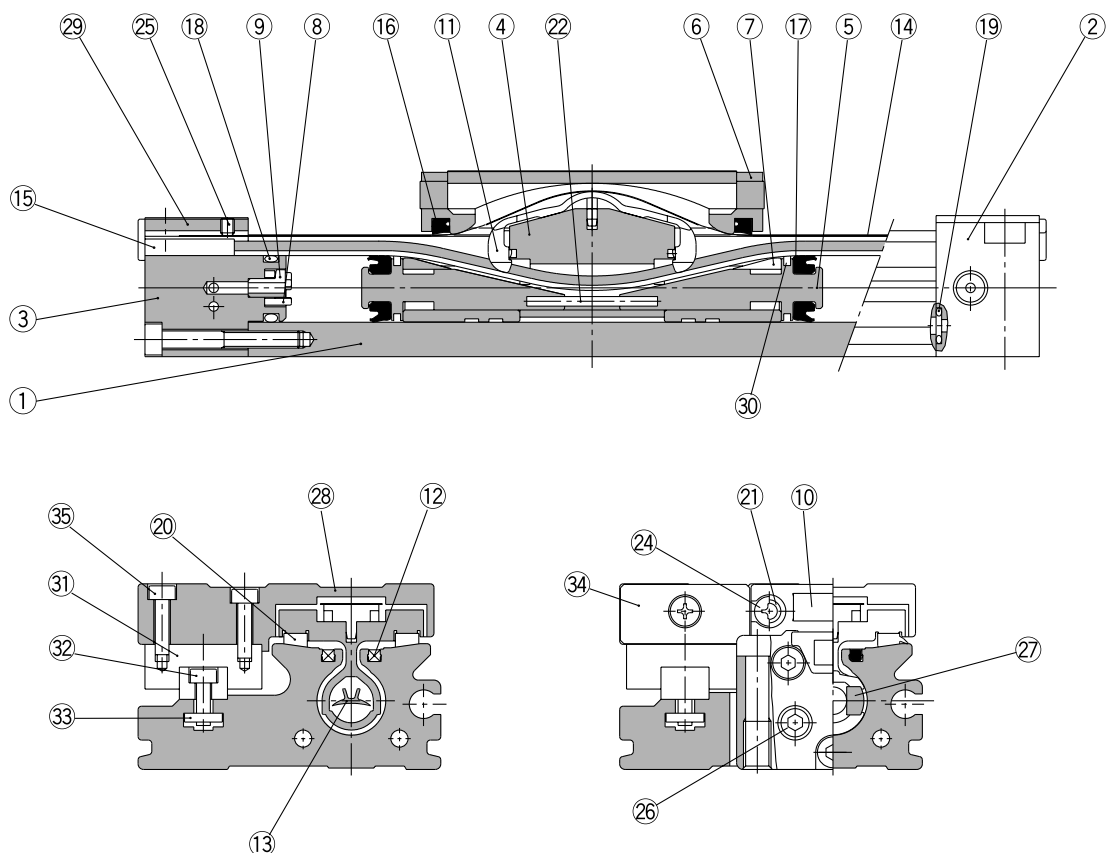
1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting. Also, for long stroke operation involving vibration and impact, use of a side support is recommended even if the spacing value is within the allowable limits shown in the graph.
2. Support brackets are not for mounting; use them solely for providing support.



Series MY1H

Construction

Centralized piping type/MY1H10G



Parts list

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover WR	Aluminum alloy	Hard anodized
3	Head cover WL	Aluminum alloy	Hard anodized
4	Piston yoke	Aluminum alloy	Hard anodized
5	Piston	Aluminum alloy	Chromated
6	End cover	Special resin	
7	Wear ring	Special resin	
8	Bumper	Polyurethane rubber	
9	Holder	Stainless steel	
10	Stopper	Carbon steel	Nickel plated
11	Belt separator	Special resin	
12	Seal magnet	Rubber magnet	
15	Belt clamp	Special resin	
20	Bearing	Special resin	
21	Spacer	Chrome molybdenum steel	Nickel plated

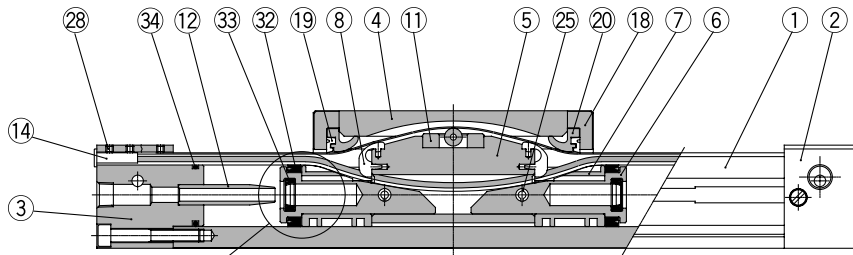
Parts list

No.	Description	Material	Note
22	Spring pin	Stainless steel	
23	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
24	Round head Phillips screw	Carbon steel	Nickel plated
25	Hexagon socket head set screw	Carbon steel	Black zinc chromated
26	Hexagon socket head plug	Carbon steel	Nickel plated
27	Magnet	Rare earth magnet	
28	Slide Table	Aluminum alloy	Hard anodized
29	Head plate	Stainless steel	
30	Felt	Felt	
31	Linear guide	—	
32	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
33	Square nut	Carbon steel	Nickel plated
34	Stopper plate	Carbon steel	Nickel plated
35	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated

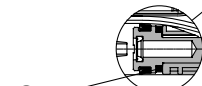
Seal list

No.	Description	Material	Qty.	MY1B10
13	Seal belt	Special resin	1	MY10-16A-stroke
14	Dust seal band	Stainless steel	1	MY10-16B-stroke
16	Scraper	NBR	2	MYB10-15AR0597
17	Piston seal	NBR	2	
18	Tube gasket	NBR	2	
19	O-ring	NBR	4	

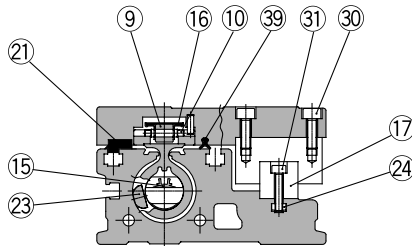
Standard type



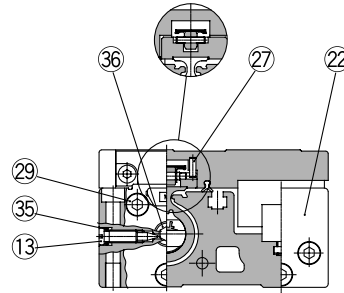
This diagram applies to models MY1H25 through MY1H40.



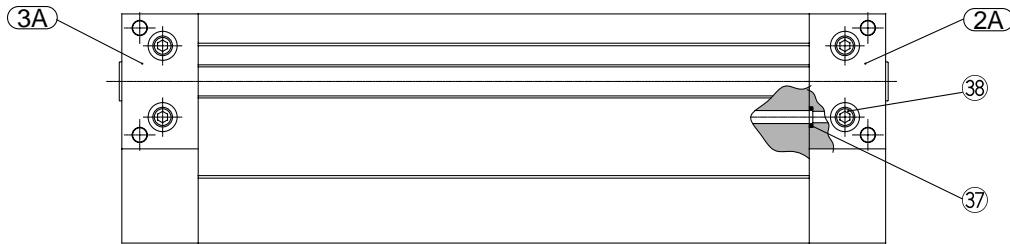
MY1H16, 20



MY1H16, 20



Centralized piping type



Parts list

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover R	Aluminum alloy	Hard anodized
2A	Head cover WR	Aluminum alloy	Hard anodized
3	Head cover L	Aluminum alloy	Hard anodized
3A	Head cover WL	Aluminum alloy	Hard anodized
4	Slide table	Aluminum alloy	Hard anodized
5	Piston yoke	Aluminum alloy	Chromated
6	Piston	Aluminum alloy	Chromated
7	Wear ring	Special resin	
8	Belt separator	Special resin	
9	Guide roller	Special resin	
10	Guide roller shaft	Stainless steel	
11	Coupler	Sintered iron material	
12	Cushion ring	Brass	
13	Cushion needle	Rolled steel	Nickel plated
14	Belt clamp	Special resin	

Parts list

No.	Description	Material	Note
17	Guide	—	
18	End cover	Chrome molybdenum steel	Nickel plated
20	Backup plate	Special resin	
21	Bearing	Special resin	
22	Guide cover	Aluminum alloy	Hard anodized
23	Magnet	Rare earth magnet	
24	Square nut	Carbon steel	Nickel plated
25	Spring pin	Carbon tool steel	Black zinc chromated
27	Parallel pin	Stainless steel	(except ø16, ø20)
28	Hexagon socket head set screw	Chrome molybdenum steel	Black zinc chromated/Nickel plated
29	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
30	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
31	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
36	Hexagon socket head taper plug	Carbon steel	Nickel plated
38	Hexagon socket head taper plug	Carbon steel	Nickel plated
39	Side scraper	Special resin	

Seal list

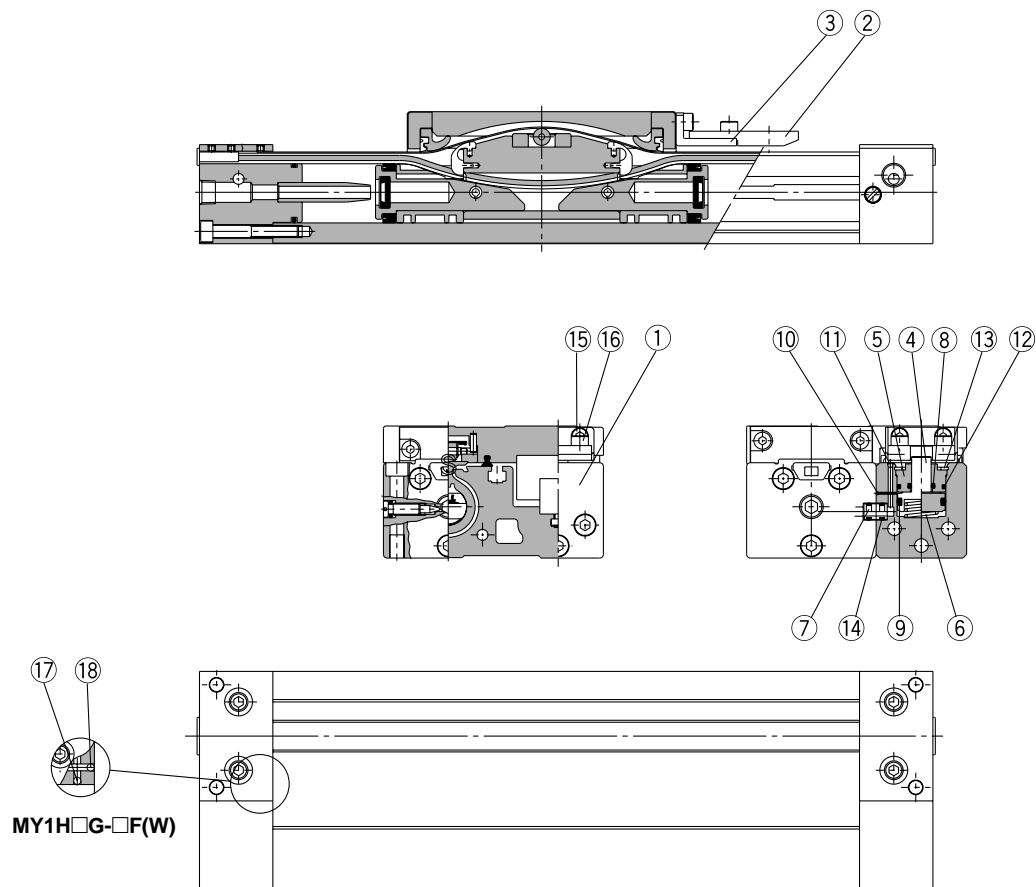
No.	Description	Material	Qty.	MY1H16	MY1H20	MY1H25	MY1H32	MY1H40
15	Seal belt	Special resin	1	MY16-16A-Stroke	MY20-16A-Stroke	MY25-16A-Stroke	MY32-16A-Stroke	MY40-16A-Stroke
16	Dust seal band	Stainless steel	1	MY16-16B-Stroke	MY20-16B-Stroke	MY25-16B-Stroke	MY32-16B-Stroke	MY40-16B-Stroke
19	Scraper	NBR	2	MYH16-15AK2900	CYP025-15A29721	CYP032-15A29722	CYP040-15A29723	CYP40-15A29723
32	Piston seal	NBR	2					
33	Cushion seal	NBR	2					
34	Tube gasket	NBR	2					
35	O-ring	NBR	2					
37	O-ring	NBR	4					

Note) Two types of dust seal band are available. Verify the type to use, since the part number varies depending on the treatment of the hexagon socket head set screw 28.
(A) Black zinc chromated → MY□□-16B-Stroke (B) Nickel plated → MY□□-16BW-Stroke

Series MY1H

Construction

With end lock



Parts list

No.	Description	Material	Note
1	Lock body	Aluminum alloy	Hard anodized
2	Lock finger	Carbon tool steel	Nickel plated
3	Lock finger bracket	Carbon steel	Nickel plated
4	Lock piston	Carbon tool steel	Electroless nickel plated
5	Rod cover	Aluminum alloy	Hard anodized
6	Return spring	Spring steel	Zinc chromated
7	Bypass pipe	Aluminum alloy	Hard anodized
10	Steel ball	High carbon chrome bearing steel	
11	Steel ball	High carbon chrome bearing steel	
13	Round R type retainer	Carbon tool steel	Nickel plated
15	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
16	Hexagon socket head cap screw	Chrome molybdenum steel	Nickel plated
17	Steel ball	High carbon chrome bearing steel	
18	Steel ball	High carbon chrome bearing steel	

Seal list

No.	Description	Material	Qty.
8	Rod seal	NBR	1
9	Piston seal	NBR	1
12	O-ring	NBR	1
14	O-ring	NBR	2

Series MY1HT

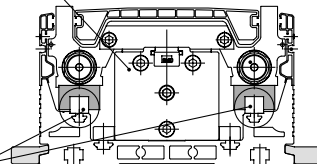
High Rigidity/ High Precision Guide Type

ø50, ø63



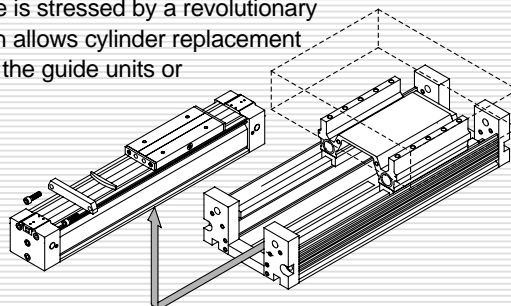
The use of two linear guides allows a maximum load of 320kg. (ø63)

Rodless cylinder
MY1BH



2 linear guides

Easy maintenance is stressed by a revolutionary construction which allows cylinder replacement without disturbing the guide units or work piece.



Before Operating Series MY1HT

Maximum Allowable Moment/Maximum Allowable Load

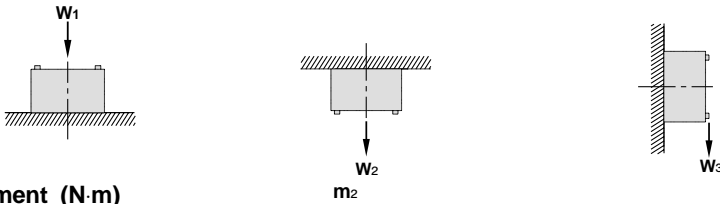
Model	Bore size (mm)	Max. allowable moment (N·m)			Max. allowable load (kg)		
		M ₁	M ₂	M ₃	m ₁	m ₂	m ₃
MY1HT	50	140	180	140	200	140	200
	63	240	300	240	320	220	320

The above values are the maximum allowable values for moment and load. Refer to each graph regarding the maximum allowable moment and maximum allowable load for a particular piston speed.

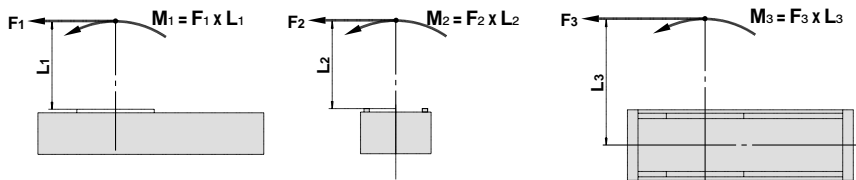
Maximum allowable moment

Select the moment from within the range of operating limits shown in the graphs. Note that the maximum allowable load value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable load for the selected conditions.

Load (kg)



Moment (N·m)



<Calculation of guide load factor>

1. Maximum allowable load (1), static moment (2), and dynamic moment (at the time of impact with stopper) (3) must be examined for the selection calculations.

* To evaluate, use \bar{v} a (average speed) for (1) and (2), and v (impact speed $v = 1.4\bar{v}$ a) for (3).

Calculate m_{max} for (1) from the maximum allowable load graph (m_1, m_2, m_3) and M_{max} for (2) and (3) from the maximum allowable moment graph (M_1, M_2, M_3).

$$\text{Sum of guide load factors } \Sigma\alpha = \frac{\text{Load mass [m]}}{\text{Maximum allowable load [m}_{max}]}} + \frac{\text{Static moment [M]^{Note 1}}}{\text{Allowable static moment [M}_{max}]}} + \frac{\text{Dynamic moment [ME]^{Note 2}}}{\text{Allowable dynamic moment [ME}_{max}]}} \leq 1$$

Note 1) Moment caused by the load, etc., with cylinder in resting condition.

Note 2) Moment caused by the impact load equivalent at the stroke end (at the time of impact with stopper).

Note 3) Depending on the shape of the work piece, multiple moments may occur. When this happens, the sum of the load factors ($\Sigma\alpha$) is the total of all such moments.

2. Reference formulae [Dynamic moment at impact]

Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

m : Load mass (kg)

F : Load (N)

F_E : Load equivalent to impact (at impact with stopper) (N)

\bar{v} a : Average speed (mm/s)

M : Static moment (N·m)

v : Impact speed (mm/s)

L_1 : Distance to the load's center of gravity (m)

ME : Dynamic moment (N·m)

g : Gravitational acceleration (9.8m/s²)

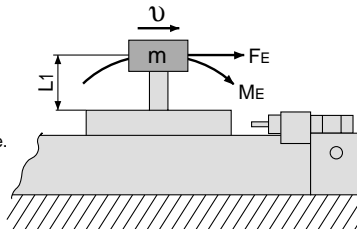
$$v = 1.4\bar{v}a \text{ (mm/s)} \quad F_E = \frac{1.4}{100} \bar{v}a \cdot g \cdot m \text{ (Note 4)}$$

$$\therefore ME = \frac{1}{3} \cdot F_E \cdot L_1 = 0.05\bar{v}a \cdot m \cdot L_1 \text{ (N·m) (Note 5)}$$

Note 4) $\frac{1.4}{100} \bar{v}a$ is a dimensionless coefficient for calculating impact force.

Note 5) Average load coefficient ($=\frac{1}{3}$):

This coefficient is for averaging the maximum load moment at the time of stopper impact according to service life calculations.

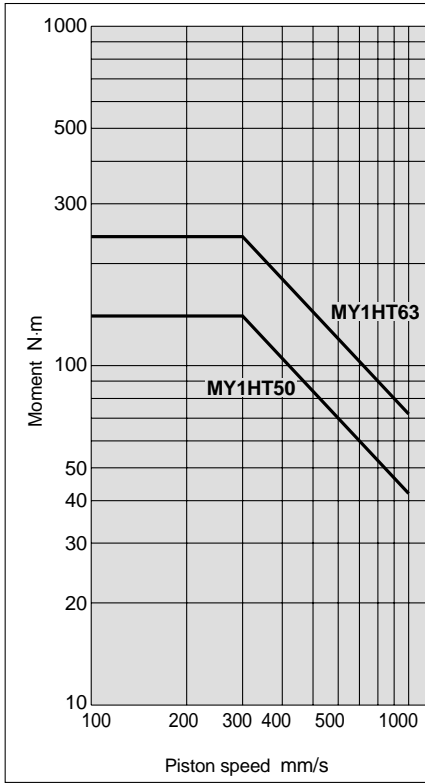


3. Refer to pages 2-620 and 2-621 for detailed selection procedures.

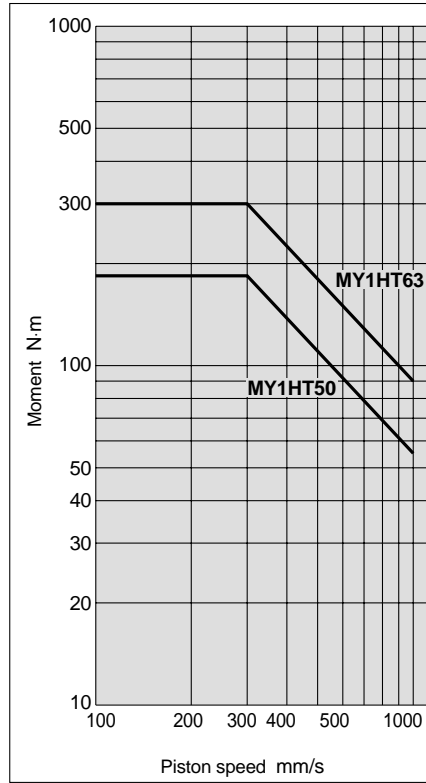
Maximum allowable load

Select the load from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.

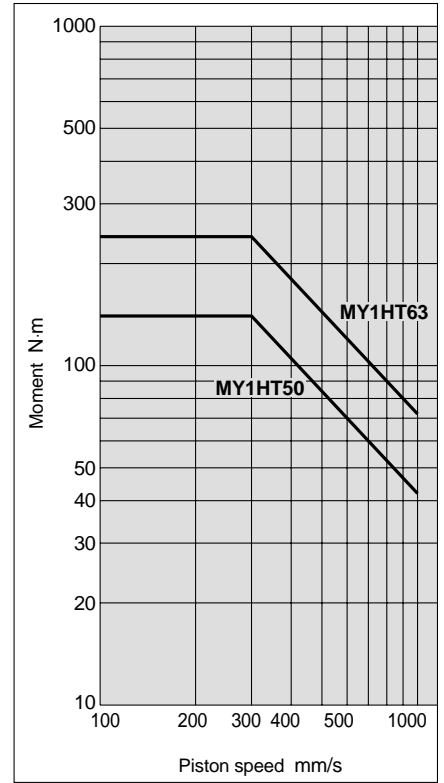
MY1HT/M₁



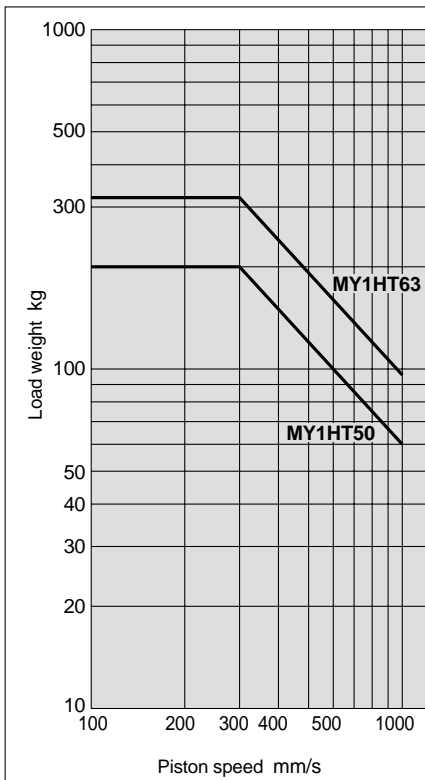
MY1HT/M₂



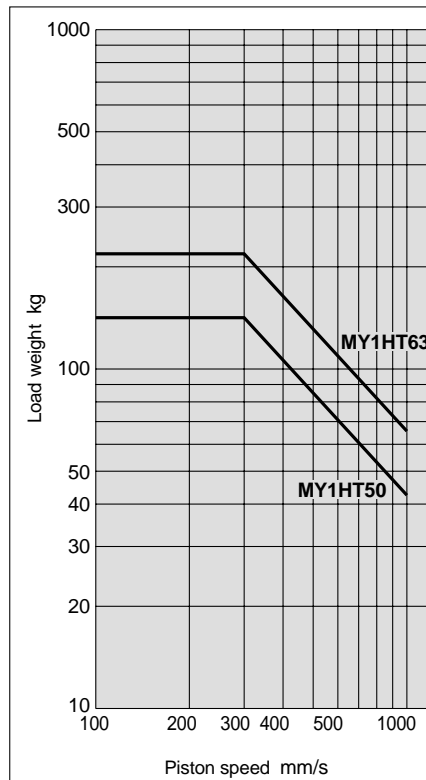
MY1HT/M₃



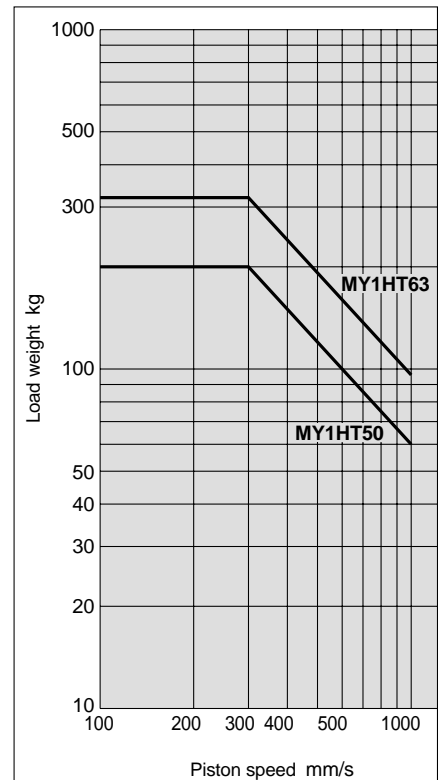
MY1HT/m₁



MY1HT/m₂



MY1HT/m₃



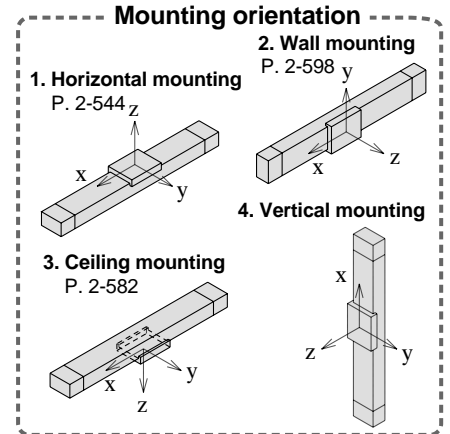
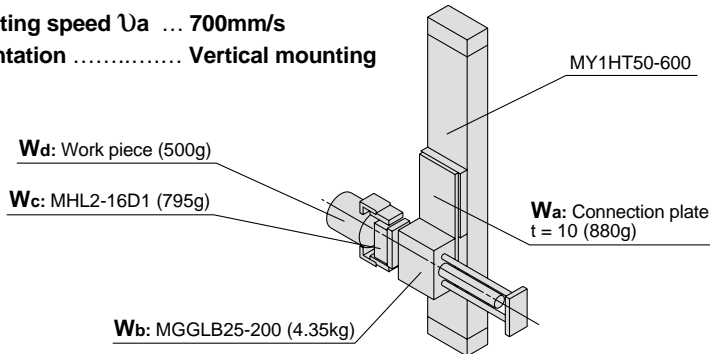
Series MY1HT Model Selection

The following are steps for selection of the series MY1 best suited to your application.

Calculation of Guide Load Factor

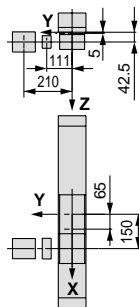
1 Operating conditions

Cylinder MY1HT50-600
Average operating speed V_a ... 700mm/s
Mounting orientation Vertical mounting



Refer to the pages above for actual examples of calculation for each orientation.

2 Load blocking



Mass and centre of gravity for each work piece

Work piece no. W_n	Mass m	Center of gravity		
		X-axis X_n	Y-axis Y_n	Z-axis Z_n
Wa	0.88kg	65mm	0mm	5mm
Wb	4.35kg	150mm	0mm	42.5mm
Wc	0.795kg	150mm	111mm	42.5mm
Wd	0.5kg	150mm	210mm	42.5mm

$n = a, b, c, d$

3 Composite centre of gravity calculation

$$m_4 = \sum m_n$$

$$= 0.88 + 4.35 + 0.795 + 0.5 = \mathbf{6.525kg}$$

$$X = \frac{1}{m_4} \times \sum (m_n \times x_n)$$

$$= \frac{1}{6.525} (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 0.5 \times 150) = \mathbf{138.5mm}$$

$$Y = \frac{1}{m_4} \times \sum (m_n \times y_n)$$

$$= \frac{1}{6.525} (0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 0.5 \times 210) = \mathbf{29.6mm}$$

$$Z = \frac{1}{m_4} \times \sum (m_n \times z_n)$$

$$= \frac{1}{6.525} (0.88 \times 5 + 4.35 \times 42.5 + 0.795 \times 42.5 + 0.5 \times 42.5) = \mathbf{37.4mm}$$

4 Calculation of load factor for static load

m_4 : Mass

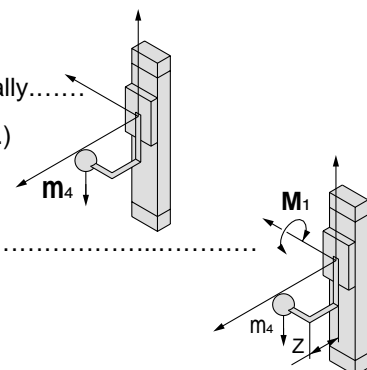
m_4 is the mass which can be transferred by the thrust, and as a rule, is actually..... about 0.3 to 0.7 of the thrust. (This differs depending on the operating speed.)

M_1 : Moment

$$M_1 \text{ max (from 1 of graph MY1MHT/M}_1) = 60 \text{ (N}\cdot\text{m) } \dots\dots\dots$$

$$M_1 = m_4 \times g \times Z = 6.525 \times 9.8 \times 37.4 \times 10^{-3} = 2.39 \text{ (N}\cdot\text{m)}$$

$$\text{Load factor } \alpha_1 = M_1 / M_1 \text{ max} = 2.39 / 60 = \mathbf{0.04}$$

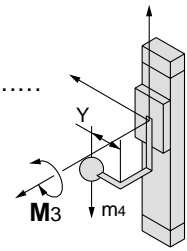


M₃: Moment

$M_3 \text{ max (from 2 of graph MY1HT/M}_3) = 60 \text{ (N}\cdot\text{m) } \dots\dots\dots$

$M_3 = m_4 \times g \times Y = 6.525 \times 9.8 \times 29.6 \times 10^{-3} = 1.89 \text{ (N}\cdot\text{m)}$

Load factor $\alpha_2 = M_3/M_3 \text{ max} = 1.89/60 = \mathbf{0.03}$



5 Calculation of load factor for dynamic moment

Equivalent load at impact FE

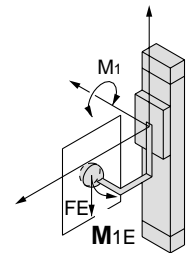
$$FE = \frac{1.4}{100} \times v_a \times g \times m = \frac{1.4}{100} \times 700 \times 9.8 \times 6.525 = 626.7 \text{ (N)}$$

M_{1E}: Moment

$M_{1E} \text{ max (from 3 of graph MY1HT/M}_1 \text{ where } 1.4v_a = 980\text{mm/s}) = 42.9 \text{ (N}\cdot\text{m) } \dots\dots\dots$

$$M_{1E} = \frac{1}{3} \times FE \times Z = \frac{1}{3} \times 626.7 \times 37.4 \times 10^{-3} = 7.82 \text{ (N}\cdot\text{m)}$$

Load factor $\alpha_3 = M_{1E}/M_{1E} \text{ max} = 7.82/42.9 = \mathbf{0.18}$

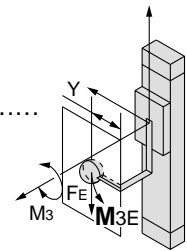


M_{3E}: Moment

$M_{3E} \text{ max (from 4 of graph MY1HT/M}_3 \text{ where } 1.4v_a = 980\text{mm/s}) = 42.9 \text{ (N}\cdot\text{m) } \dots\dots\dots$

$$M_{3E} = \frac{1}{3} \times FE \times Y = \frac{1}{3} \times 626.7 \times 29.6 \times 10^{-3} = 6.19 \text{ (N}\cdot\text{m)}$$

Load factor $\alpha_4 = M_{3E}/M_{3E} \text{ max} = 6.19/42.9 = \mathbf{0.14}$



5 Sum and examination of guide load factors

$$\Sigma\alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 = \mathbf{0.39} \leq 1$$

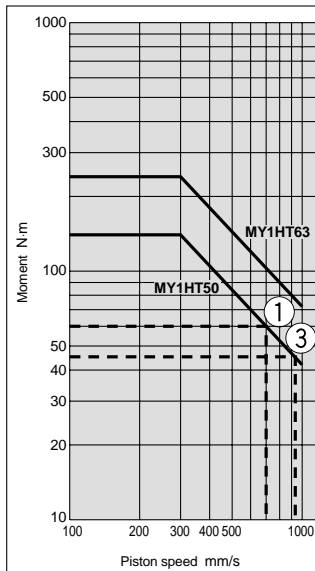
The above calculation is within the allowable value and the selected model can be used.

Select a separate shock absorber.

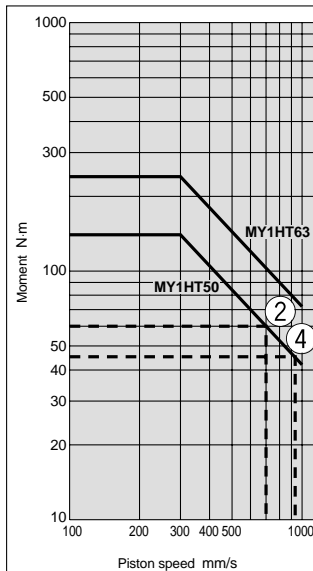
In an actual calculation, when the sum of guide load factors $\Sigma\alpha$ in the formula above is more than 1, consider decreasing the speed, increasing the bore size, or changing the product series. Also, this calculation can be performed easily with the "SMC Pneumatics CAD System".

Allowable moment

MY1HT/m₁



MY1HT/M₃



Mechanically Jointed Rodless Cylinder

Series MY1HT

High Rigidity/High Precision Guide Type/ø50, ø63

How to Order

High Rigidity
High Precision Guide Type

E MY1HT **50** **400** **L** **Z73**

Thread Port

—	Rc(PT)
E	G(PF)

High rigidity/High precision guide type
(2 linear guides)

Cylinder bore size

50	50mm
63	63mm

Piping

Nil	Standard type
G	Centralized piping type

Stroke
Refer to the standard stroke table.

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	"n" pcs.

Auto switch type

Nil	Without auto switch
------------	---------------------

* Refer to the table below for auto switch model numbers.

Stroke adjusting unit

L	One shock absorber at each stroke end
H	Two shock absorbers at each stroke end
LH	One shock absorber at one end, two shock absorbers at one end

Options

Stroke adjusting unit numbers

Bore size (mm)	50	63
Unit type	MYT-A50L	MYT-A63L

Side support numbers

	Bore size (mm)	50	63
Type			
Side support A		MY-S63A	
Side support B		MY-S63B	

Refer to page 2-628 for detailed information on dimensions, etc.

Applicable auto switches

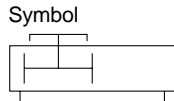
Type	Special function	Electrical entry	Indicator light	Wiring (output)	Load voltage		Auto switch models		Lead wire length (m)*			Applicable load		
					DC	AC	Electrical entry direction		0.5 (Nil)	3 (L)	5 (Z)			
							Perpendicular	In-line						
Reed switch	—	Grommet	Yes	3 wire (NPN equiv.)	—	5V	—	—	Z76	●	●	—	IC circuit	—
				2 wire	12V	100V	—	Z73	●	●	●	—	Relay, PLC	
					5V, 12V	100V or less	—	Z80	●	●	—	IC circuit	—	
Solid state switch	—	Grommet	Yes	3 wire (NPN)	24V	5V, 12V	—	Y69A	Y59A	●	●	○	IC circuit	Relay, PLC
				3 wire (PNP)				Y7PV	Y7P	●	●	○	—	
				2 wire				Y69B	Y59B	●	●	○	—	
				3 wire (NPN)				Y7NWV	Y7NW	●	●	○	—	
				3 wire (PNP)				Y7PWV	Y7PW	●	●	○	IC circuit	
				2 wire				Y7BWV	Y7BW	●	●	○	—	



* Lead wire length symbols: 0.5m Nil (Example) Y59A
3m L Y59AL
5m Z Y59AZ

* Solid state switches marked with a "○" symbol are produced upon receipt of order.
(Note) Separate switch spacers (MB-32-36-L8509) are required for retrofitting of auto switches.

Specifications



Bore size (mm)	50	63
Fluid	Air	
Action	Double acting	
Operating pressure range	0.1 to 0.8MPa	
Proof pressure	1.2MPa	
Ambient and fluid temperature	5 to 60°C	
Piston speed	100 to 1000mm/s	
Cushion	Double side shock absorber (standard)	
Lubrication	Non-lube	
Stroke length tolerance	2700 or less ^{+1.8} ₀ , 2701 to 5000 ^{+2.8} ₀	
Port size	Side port	3/8



Note) Use at a speed within the absorption capacity. Refer to page 2-624

Stroke Adjusting Unit Specifications

Applicable bore size (mm)	50		63	
Unit symbol, contents	L	H	L	H
	RB2015 and adjusting bolt: 1 set each	RB2015 and adjusting bolt: 2 sets each	RB2725 and adjusting bolt: 1 set each	RB2725 and adjusting bolt: 2 sets each
Stroke fine adjusting range (mm)	0 to -60		0 to -85	
Stroke adjusting range	Refer to page 2-625 for adjustment method.			

Shock absorber model	RB2015 x 1 pc.	RB2015 x 2 pcs.	RB2725 x 1 pc.	RB2725 x 2 pcs.
Max. energy absorption (J)	58.8	88.2	147	220.5
Stroke absorption (mm)	15	15	25	25
Max. impact speed (mm/s)	1000		1000	
Max. operating frequency (cycles/min)	25	25	10	10
Spring force (N)	Extended	16.68	8.83	17.66
	Compressed	41.00	20.01	40.02
Operating temperature range (°C)	5 to 60			

Note) Maximum energy absorption for 2 pcs. is calculated by multiplying the value for 1 pc. by 1.5.

Theoretical Output

Unit: N

Bore size (mm)	Piston area (mm ²)	Operating pressure (MPa)						
		0.2	0.3	0.4	0.5	0.6	0.7	0.8
50	1962	392	588	784	981	1177	1373	1569
63	3115	623	934	1246	1557	1869	2180	2492

1N = Approx. 0.102kgf, 1MPa = Approx. 10.2kgf/cm²

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)

Order made specifications

Refer to page 2-645 regarding order made specifications for series MY1H.

Standard Strokes

Bore size (mm)	Standard stroke (mm)*	Max. manufacturable stroke (mm)
50, 63	200, 400, 600, 800, 1000, 1500, 2000	5000



Note) Strokes other than standard are produced after receipt of order.

Weights

Unit: kg

Bore size (mm)	Basic weight	Additional weight per 25mm of stroke	Side support weight (per set)	Stroke adjusting unit weight		
			Type A and B	L unit	LH unit	H unit
50	30.62	0.87	0.17	0.62	0.93	1.24
63	41.69	1.13	0.17	1.08	1.62	2.16

Calculation method Example: **MY1HT50-400L**

Basic weight 30.62kg

Additional weight 0.87/25mm stroke

L unit weight 0.62kg

Cylinder stroke 400mm

30.62 + 0.87 x 400 ÷ 25 + 0.62 x 2 = approx. 45.8

Series MY1HT

Cushion Capacity

Cushion Selection

<Stroke adjusting unit with built-in shock absorber>

L unit

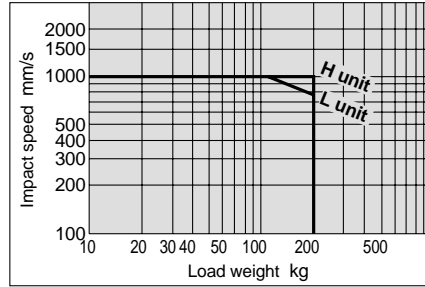
Use this unit when cushioning is necessary outside the air cushion stroke range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

H unit

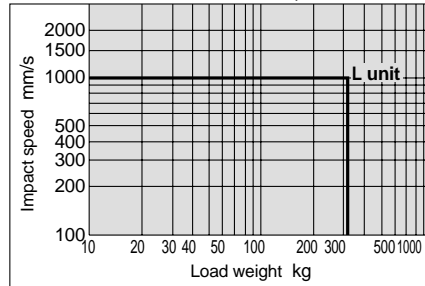
Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

Stroke Adjusting Unit Absorption Capacity

MY1HT50 Horizontal impact: P = 0.5MPa



MY1HT63 Horizontal impact: P = 0.5MPa



Stopper Bolt Holding Screw Tightening Torque

Stopper bolt holding screw tightening torque

Unit: N·m

Bore size (mm)	Tightening torque
50	0.6
63	1.5

Calculation of absorbed energy for stroke adjusting unit with built-in shock absorber

Unit: N·m

Type of impact	Horizontal	Vertical (downward)	Vertical (upward)
Kinetic energy E ₁	$\frac{1}{2} m \cdot v^2$		
Thrust energy E ₂	F · s	F · s + m · g · s	F · s - m · g · s
Absorbed energy E	E ₁ + E ₂		

Symbols

v: Speed of impacting object (m/s)

m: Weight of impacting object (kg)

F: Cylinder thrust (N)

g: Gravitational acceleration (9.8m/s²)

s: Shock absorber stroke (m)

Note) The speed of the impacting object is measured at the time of impact with the shock absorber.

⚠ Specific Product Precautions

Mounting

⚠ Caution

1. Do not apply strong impact or excessive moment to the slide table (slider).

Since the slide table (slider) is supported by precision bearings, do not subject it to strong impact or excessive moment when mounting work pieces.

2. Perform careful alignment when connecting to a load which has an external guide mechanism.

Mechanically jointed rodless cylinders can be used with a direct load within the allowable range for each type of guide, but careful alignment is necessary for connection to a load which has an external guide mechanism. Since fluctuation of the center axis increases as the stroke becomes longer, use a method of connection which can absorb the variations (floating mechanism).

3. Do not put hands or fingers inside when the body is suspended.

Since the body is heavy, use eye bolts when suspending it. (The eye bolts are not included with the body.)

Handling

⚠ Caution

1. Do not inadvertently move the setting of the guide adjustment unit.

The guide is already adjusted at the factory, and readjustment is not necessary under normal operating conditions. Therefore, do not inadvertently move the setting of the guide adjustment unit.

Handling

⚠ Caution

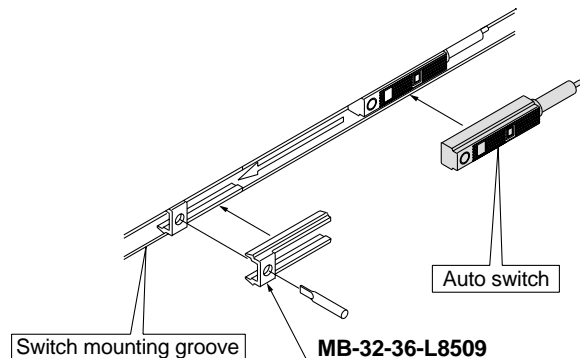
2. Air leakage will result from negative pressure.

Under operating conditions which create negative pressure inside the cylinder due to external forces or inertial forces, note that air leakage may occur due to separation of the seal belt.

Auto Switch Mounting

⚠ Caution

1. Insert the auto switch into the cylinder's switch mounting groove, then slide it sideways in the direction shown below and place it inside the switch spacer (with the spacer positioned over it).
2. Use a flat head watchmakers screw driver to fasten the switch, tightening with a torque of 0.05 to 0.1N·m. As a rule, it should be turned about 90° past the point at which tightening can be



Stroke Adjustment

⚠ Caution

- As shown in Figure 1, to adjust the stopper bolt within the adjustment range A, insert a hexagon wrench from the top to loosen the hexagon socket head set screw by approximately one turn, and then adjust the stopper bolt with a flat head screw driver.
- When the adjustment described in 1 above is insufficient, the shock absorber can be adjusted. Remove the covers as shown in Figure 2 and make further adjustment by loosening the hexagon nut.
- Various dimensions are indicated in Table 1. Never make an adjustment that exceeds the dimensions in the table, as it may cause an accident and/or damage.

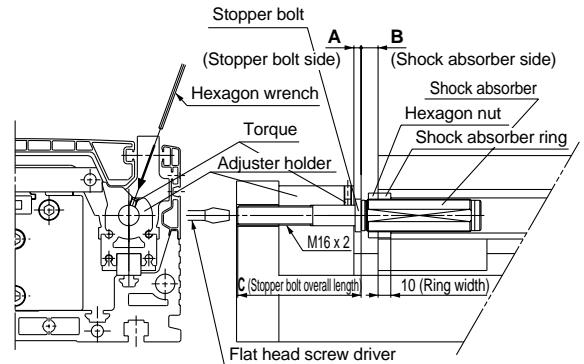


Figure 1. Stroke adjusting section detail

Table 1 (mm)

Bore size (mm)	50	63
A to A MAX.	6 to 26	6 to 31
B to B MAX.	14 to 54	14 to 74
C	87	102
Max. adjustment range	60	85

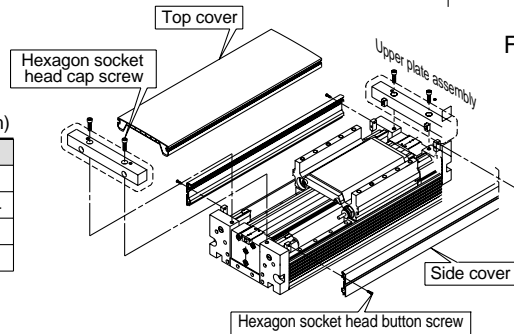


Figure 2. Cover installation and removal

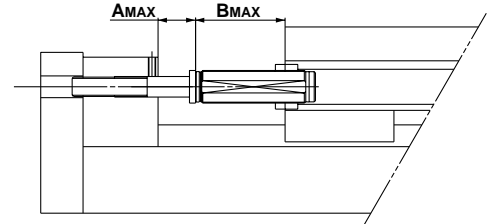


Figure 3. Maximum stroke adjustment detail

Disassembly and Assembly Procedure

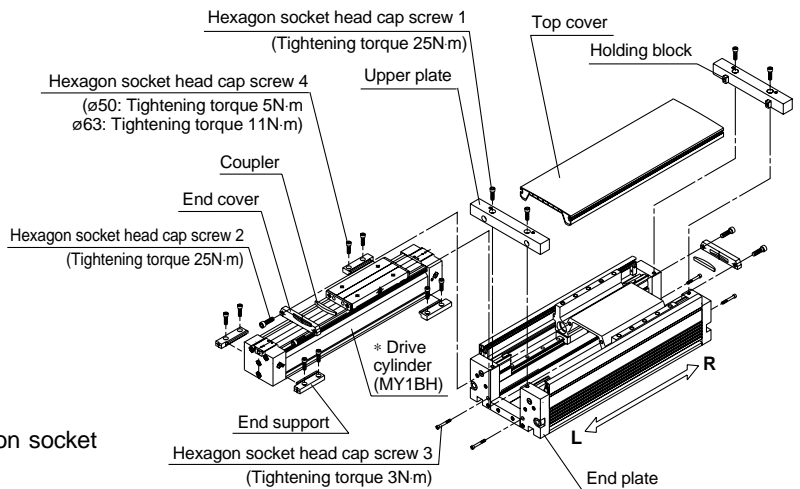
⚠ Caution

Disassembly procedure

- Remove the hexagon socket head cap screws 1, and remove the upper plates.
- Remove the top cover.
- Remove the hexagon socket head cap screws 2, and remove the end covers and couplers.
- Remove the hexagon socket head cap screws 3.
- Remove the hexagon socket head cap screws 4, and remove the end supports.
- Remove the cylinder.

Assembly procedure

- Insert the MY1BH cylinder.
- Temporarily fasten the end supports with the hexagon socket head cap screws 4.
- With two hexagon socket head cap screws 3 on the L or R side, pull the end support and the cylinder.
- Tighten the hexagon socket head cap screws 3 on the other side to eliminate the looseness in the axial direction. (At this point, a space is created between the end support and the end plate on one side, but this is not a problem.)
- Re-tighten the hexagon socket head cap screws 4.



- Fasten the end cover with the hexagon socket head cap screws 2, while making sure that the coupler is in the right direction.
- Place the top cover on the body.
- Insert the holding blocks into the top cover and fasten the upper plates with the hexagon socket head cap screws 1.

*** Drive Cylinder (Series MY1BH)**

Since series MY1BH is a drive cylinder for series MY1HT, its construction is different from series MY1B. Do not use series MY1B as a drive cylinder, because it will cause damage.

How to order

High rigidity
High precision guide type

Drive cylinder

MY1HT 50 300 L Z73

MY1BH 50 300

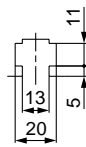
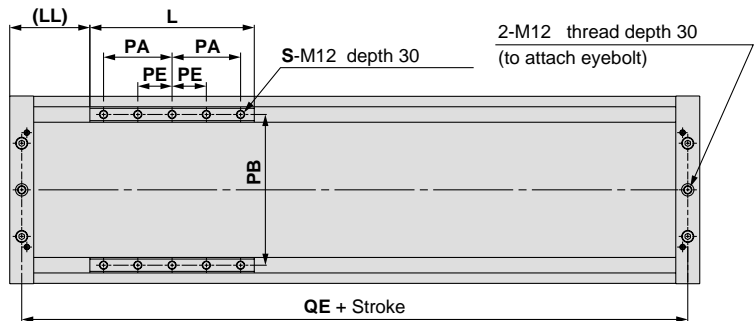
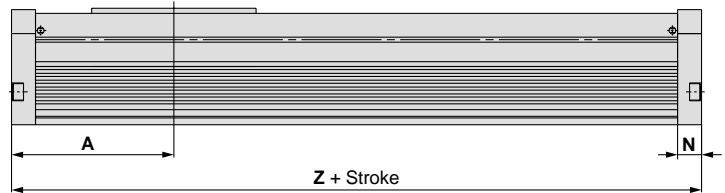
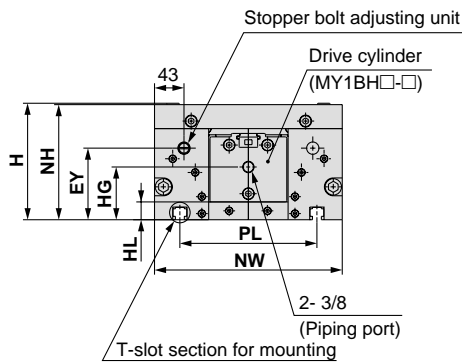
Stroke (mm)

Bore size		Piping	
50	50mm	Nil	Standard type
63	63mm	G	Centralized piping type

Series MY1HT

Standard Type $\varnothing 50, \varnothing 63$

MY1HT Bore size Stroke L



Applicable nut JIS B1163
Square nut M12

Dimensions of T-slot for mounting

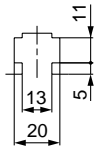
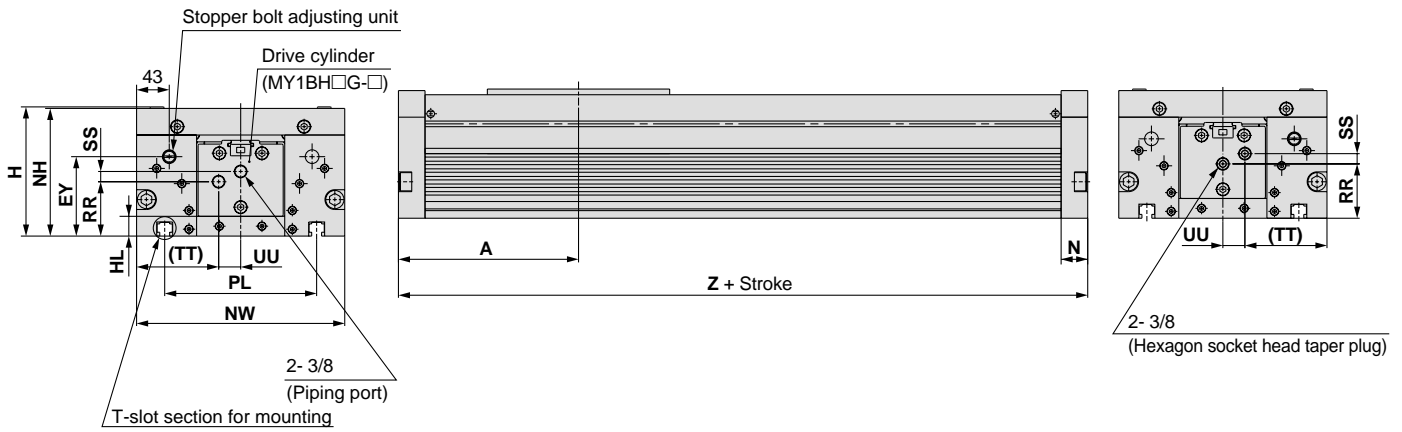
Model	A	EY	H	HG	HL	L	LL	N	NH	NW	PA	PB	PE
MY1HT50	207	97.5	145	63	23	210	102	30	143	254	90	200	—
MY1HT63	237	104.5	170	77	26	240	117	35	168	274	100	220	50

Model	PL	QE	S	Z
MY1HT50	180	384	6	414
MY1HT63	200	439	10	474

Centralized Piping Type **Ø50, Ø63**

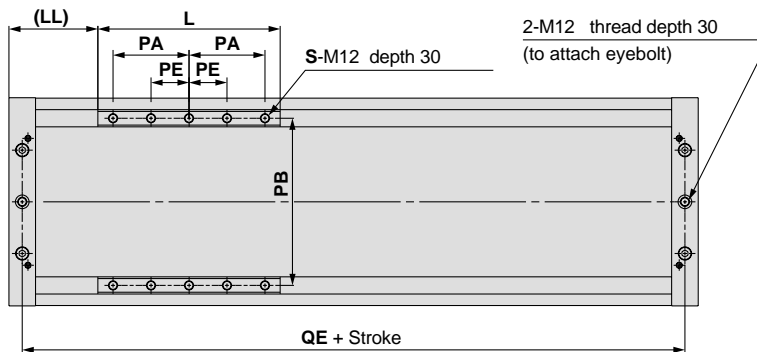
(Refer to page 2-648 regarding centralized piping port variations.)

MY1HT Bore size **G** — Stroke **L**



Applicable nut JIS B1163
Square nut M12

Dimensions of
T-slot for mounting



Model	A	EY	H	HL	L	LL	N	NH	NW	PA	PB	PE
MY1HT50	207	97.5	145	23	210	102	30	143	254	90	200	—
MY1HT63	237	104.5	170	26	240	117	35	168	274	100	220	50

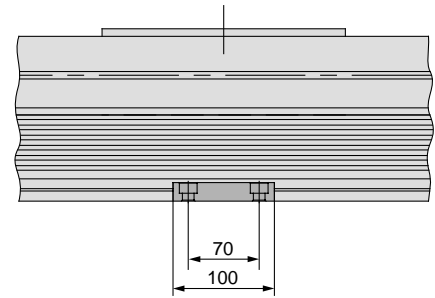
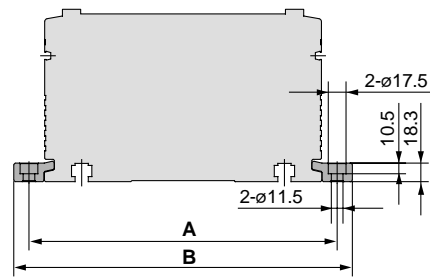
Model	PL	QE	S	Z	RR	SS	TT	UU
MY1HT50	180	384	6	414	57	10	103.5	23.5
MY1HT63	200	439	10	474	71.5	13.5	108	29

Note) For centralized piping specifications, the drive cylinder has centralized piping specifications (MY1BH□G-□).

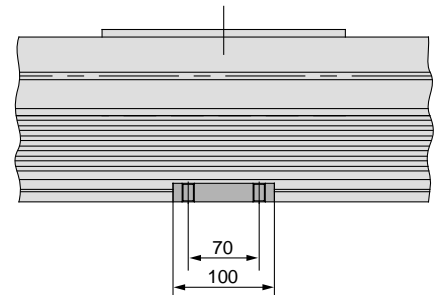
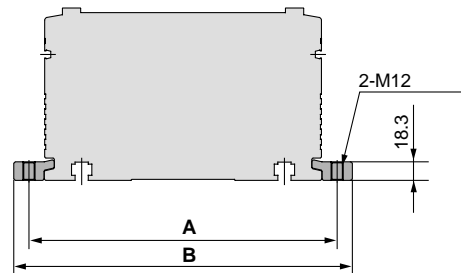
Series MY1HT

Side Support

Side support A MY-S63A



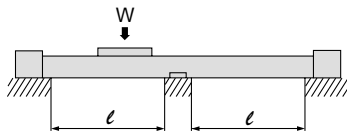
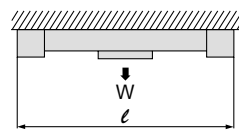
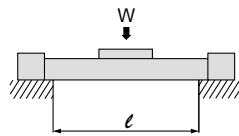
Side support B MY-S63B



Dimensions		(mm)	
Model	Applicable cylinder	A	B
MY-S63 ^A _B	MY1HT50	284	314
	MY1HT63	304	334

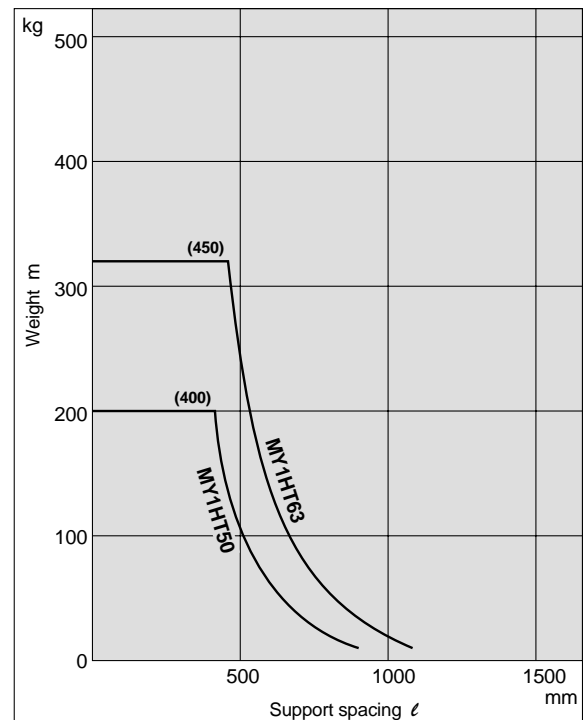
Guide for Using Side Supports

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load weight. In such a case, use a side support in the middle section. The spacing (ℓ) of the support must be no more than the values shown in the graph on the right.



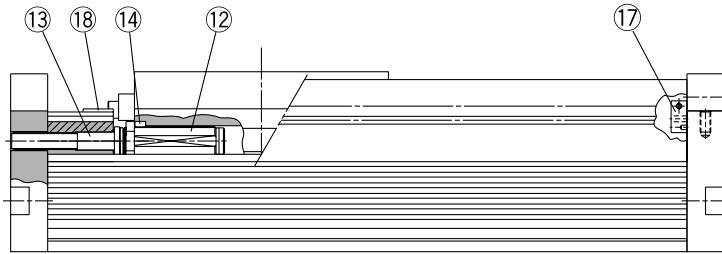
⚠ Caution

1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting. Also, for long stroke operation involving vibration and impact, use of a side support is recommended even if the spacing value is within the allowable limits shown in the graph.
2. Support brackets are not for mounting; use them solely for providing support.

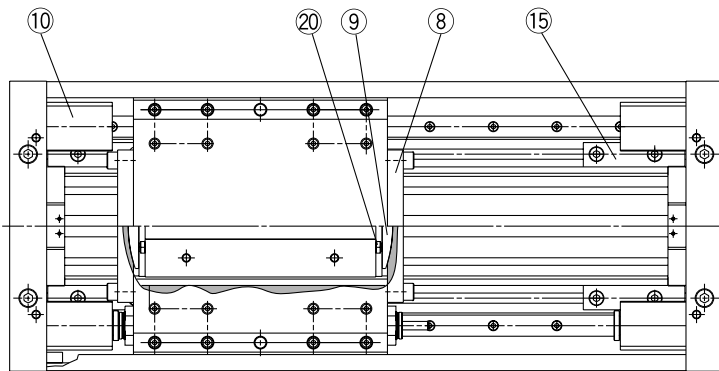
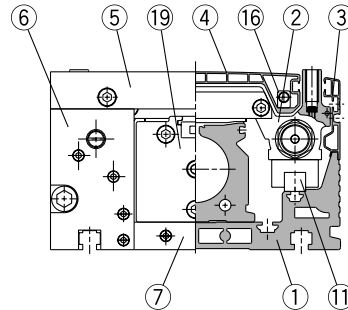


Construction

Standard type



Note) With top cover removed



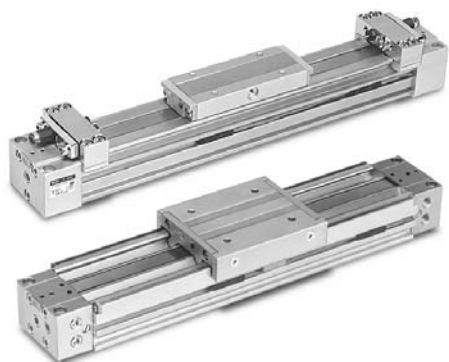
Note) With top cover removed

Parts list

No.	Description	Material	Note
1	Guide frame	Aluminum alloy	Hard anodized
2	Slide table	Aluminum alloy	Hard anodized
3	Side cover	Aluminum alloy	Hard anodized
4	Top cover	Aluminum alloy	Hard anodized
5	Upper plate	Aluminum alloy	Hard anodized
6	End plate	Aluminum alloy	Hard anodized
7	Bottom plate	Aluminum alloy	Hard anodized
8	End Cover	Aluminum alloy	Chromated
9	Coupler	Aluminum alloy	Chromated
10	Adjuster holder	Aluminum alloy	Hard anodized
11	Guide	—	
12	Shock absorber	—	
13	Stopper bolt	Carbon steel	Nickel plated
14	Absorber ring	Rolled steel	Nickel plated
15	End support	Aluminum alloy	Hard anodized
16	Top block	Aluminum alloy	Chromated
17	Side block	Aluminum alloy	Chromated
18	Slide plate	Special resin	
19	Rodless cylinder	—	MY1BH
20	Stopper	Carbon steel	Nickel plated

Series MY1

Auto Switch Specifications



Applicable auto switches

Auto switch models		Electrical entry
Reed switches	D-A9□	Grommet (In-line)
	D-A9□V	Grommet (Perpendicular)
	D-Z7□, Z80	Grommet (In-line)
Solid switches	D-M9□	Grommet (In-line)
	D-M9□V	Grommet (Perpendicular)
	D-M9□W	Grommet (2 colour indicator, In-line)
	D-M9□WV	Grommet (2 colour indicator, Perpendicular)
	D-Y59A, Y59B, Y7P	Grommet (In-line)
	D-Y69A, Y69B, Y7PV	Grommet (Perpendicular)
	D-Y7□W	Grommet (2 colour indicator, In-line)
	D-Y7□WV	Grommet (2 colour indicator, Perpendicular)

Reed Switches

D-A9□/3 Wire, 2 Wire (Direct Mount Type)

D-A90(V), D-A93(V), D-A96(V)



Applicable cylinder series

- MY1B (Basic)
- MY1M (Slide bearing)
- MY1C (Cam follower guide)
- MY1H (High precision guide)

Bore size (mm)		10	16	20	25	32	40	50	63	80	100
MY1B (Basic)		●	●	●							
MY1M (Slide bearing)			●	●							
MY1C (Cam follower guide)			●	●							
MY1H (High precision guide)		●	●	●							

Auto Switch Specifications

D-A90, D-A90V (without indicator light)

Auto switch part no.	D-A90	D-A90V	
Electrical entry direction	In-line	Perpendicular	
Applicable load	IC circuit, Relay, PLC		
Load voltage	24V _{DC} ^{AC} or less	48V _{DC} ^{AC} or less	100V _{DC} ^{AC} or less
Maximum load current	50mA	40mA	20mA
Contact protection circuit	None		
Internal voltage drop	1Ω or less (including lead wire length of 3m)		

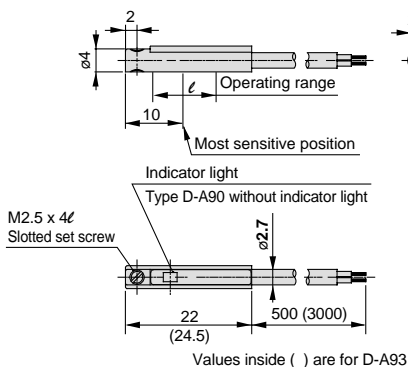
D-A93, A93V, D-A96, A96V (with indicator light)

Auto switch part no.	D-A93		D-A93V		D-A96	D-A96V
Electrical entry direction	In-line		Perpendicular		In-line	Perpendicular
Applicable loads	Relay, PLC				IC circuit	
Load voltage	24VDC	100VAC	24VDC	100VAC	4 to 8VDC	
Load current range and max. load current	5 to 40mA	5 to 20mA	5 to 40mA	5 to 20mA	20mA	
Contact protection circuit	None					
Internal voltage drop	2.4V or less (to 20mA) 3V or less (to 40mA)		2.7V or less		0.8V or less	
Indicator light	Red LED lights up when ON					

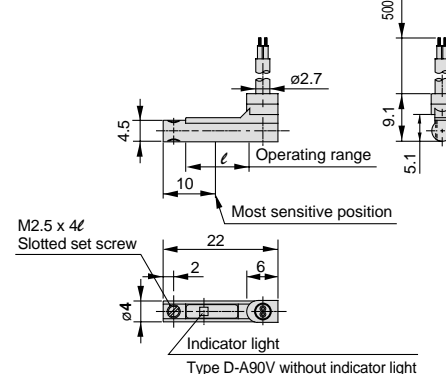
- Lead wires — Heavy duty oil resistant vinyl cord, ø2.7, 0.5m
D-A90(V), D-A93(V) 0.18mm² x 2 wire (Brown, Blue [Red, Black])
D-A96(V) 0.15mm² x 3 wire (Brown, Black, Blue [Red, White, Black])
 - Insulation resistance — 50MΩ or more at 500VDC (between lead wire and case)
 - Withstand voltage — 1000VAC for 1min. (between lead wire and case)
 - Operating time — 1.2ms
 - Ambient temperature — -10 to 60°C
 - Impact resistance — 300m/s²
 - Leakage current — None
 - Enclosure — IEC529 standard IP67, watertight (JISC0920)
- For a lead wire length of 3m, "L" is shown at the end of the part number. Example) D-A90L

Auto Switch Dimensions

D-A90, D-A93, D-A96



D-A90V, D-A93V, D-A96V



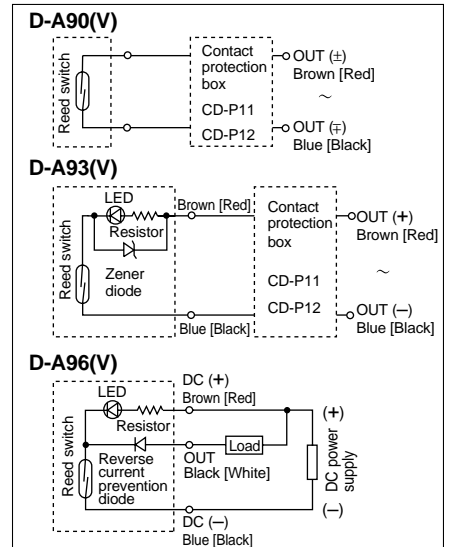
Auto switch weights

Unit: g

Model	Lead wire length 0.5m	Lead wire length 3m
D-A9/A9□V	8	41

Auto switch internal circuits

Lead wire colors inside () are those prior to conformity with IEC standards.



Contact Protection Boxes/CD-P11, CD-P12

D-A9□ and D-A9□ type switches do not have internal contact protection circuits.

1. The operated load is an induction load.
2. The length of wiring to the load is 5m or more.
3. The load voltage is 100VAC.

A contact protection box should be used in any of the above situations.

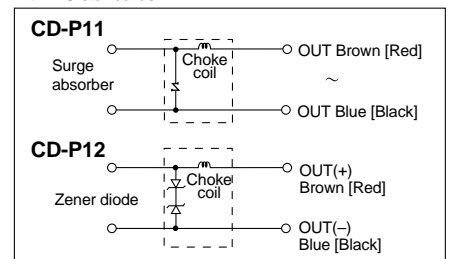
Contact protection box specifications

Part No.	CD-P11	CD-P12
Load voltage	100VAC	24VDC
Max. load current	25mA	50mA

* Lead wire lengths Switch connection side 0.5m
Load connection side 0.5m

Contact protection box internal circuits

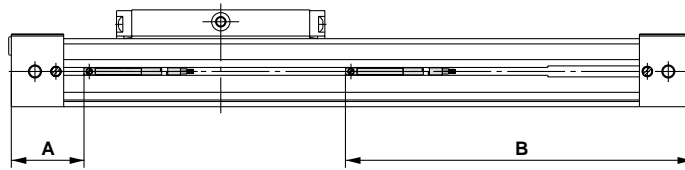
Lead wire colours inside () are those prior to conformity with IEC standards.



Auto Switch Mounting Positions/D-A9□(V)

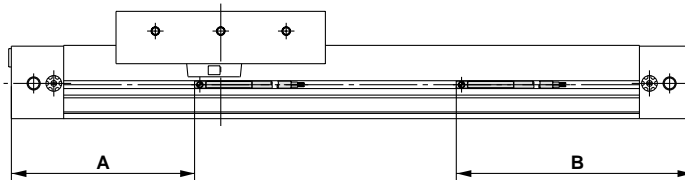
Note) The operating range is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as ±30%) depending on the ambient environment.

MY1B (Basic type)



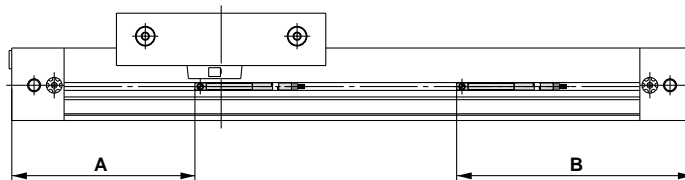
Mounting position	ø10	ø16	ø20
A	20	27	35
B	90	133	165
Operating range ℓ <small>Note)</small>	6	6.5	8.5

MY1M (Slide bearing type)



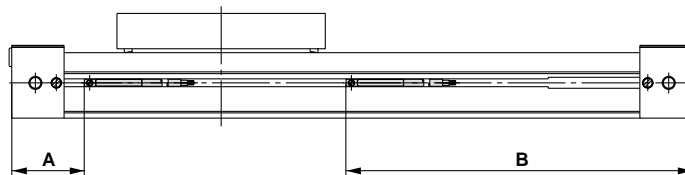
Mounting position	ø16	ø20
A	70	90
B	90	110
Operating range ℓ <small>Note)</small>	11	7.5

MY1C (Cam follower guide type)



Mounting position	ø16	ø20
A	70	90
B	90	110
Operating range ℓ <small>Note)</small>	11	7.5

MY1H (High precision guide type)



Mounting position	ø10	ø16	ø20
A	20	27	35
B	90	133	165
Operating range ℓ <small>Note)</small>	11	6.5	8.5

Reed Switches

D-Z7□, Z80/3 Wire, 2 Wire (Direct Mount Type)

D-Z73, D-Z76, D-Z80



Applicable cylinder series

MY1B (Basic)
MY1M (Slide bearing)
MY1C (Cam follower guide)
MY1H (High precision guide)
MY1HT (High rigidity/ High precision guide)

Bore size (mm)		16	20	25	32	40	50	63	80	100
MY1B (Basic)				●	●	●	●	●	●	●
MY1M (Slide bearing)				●	●	●	●	●	●	●
MY1C (Cam follower guide)				●	●	●	●	●	●	●
MY1H (High precision guide)				●	●	●	●	●	●	●
MY1HT (High rigidity/ High precision guide)							●	●		

Auto Switch Specifications

D-Z7□ (with indicator light)

Auto switch part no.	D-Z73		D-Z76
Electrical entry direction	In-line		
Applicable load	Relay, PLC		IC circuit
Load voltage	24VDC	100VAC	4 to 8VDC
Load current range and max. load current	5 to 40mA	5 to 20mA	20mA
Contact protection circuit	None		
Internal voltage drop	2.4V or less (to 20mA)/3V or less (to 40mA)		0.8V or less
Indicator light	Red LED lights up when ON		

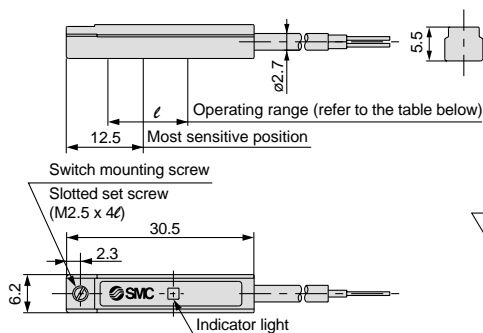
D-Z80 (without indicator light)

Auto switch part no.	D-Z80		
Electrical entry direction	In-line		
Applicable load	Relay, PLC, IC circuit,		
Load voltage	24V ^{AC} _{DC} or less	48V ^{AC} _{DC} or less	100V ^{AC} _{DC} or less
Maximum load current	50mA	40mA	20mA
Contact protection circuit	None		
Internal voltage drop	1Ω or less (including lead wire length of 3m)		

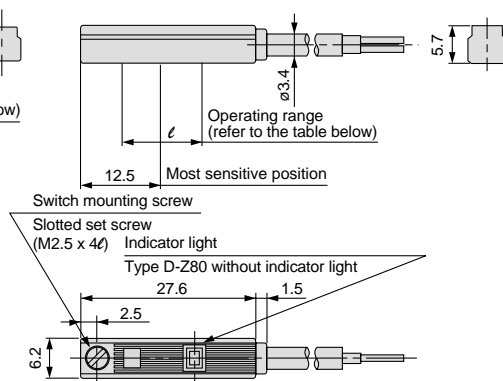
- Leakage current — None
 - Operating time — 1.2ms
 - Lead wires — Heavy duty oil resistant vinyl cord, ø3.4, 0.2mm², 2 wire (Brown, Blue [Red, Black]), 3 wire (Brown, Black, Blue [Red, White, Black]), 0.5m² D-Z73 only ø2.7, 0.18mm², 2 wire
 - Impact resistance — 300m/S²
 - Insulation resistance — 50MΩ or more at 500VDC (between lead wire and case)
 - Withstand voltage — 1500VAC for 1min. (between lead wire and case)
 - Ambient temperature — -10 to 60°C
 - Enclosure — IEC529 standard IP67, watertight (JISC0920)
- * For a lead wire length of 3m, "L" is shown at the end of the part number. Example) D-Z73L

Auto Switch Dimensions

D-Z73



D-Z76, Z80



Bore size	Bore size (mm)	
Operating range	180	200
Operating range ℓ (mm)	15	15

Note) There is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as ±30%) depending on the ambient environment.

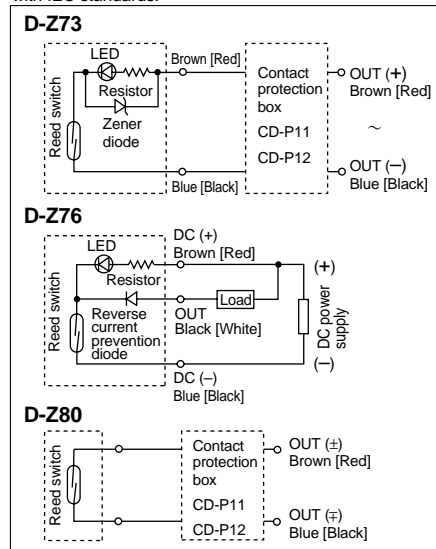
Auto switch weights

Unit: g

Model	Lead wire length 0.5m	Lead wire length 3m
D-Z73	7	31
D-Z76	10	55
D-Z80	9	49

Auto switch internal circuits

Lead wire colors inside () are those prior to conformity with IEC standards.



Contact Protection Boxes/CD-P11, CD-P12

D-Z7□ and D-Z80□ type switches do not have internal contact protection circuits.

- The operated load is an induction load.
 - The length of wiring to the load is 5m or more.
 - The load voltage is 100VAC.
- A contact protection box should be used in any of the above situations.

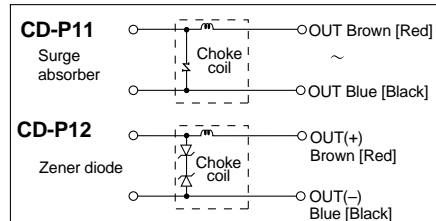
Contact protection box specifications

Part No.	CD-P11	CD-P12
Load voltage	100VAC	24VDC
Max. load current	25mA	50mA

D-Z80 type switches are 100VAC or less. Since there is no particular specified voltage, select a type based on the operating voltage.

Contact protection box internal circuits

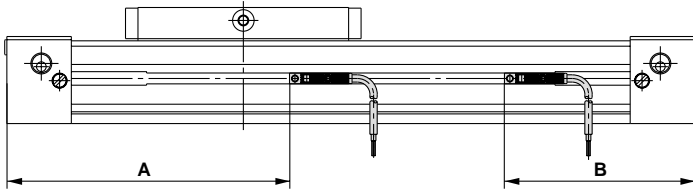
Lead wire colours inside () are those prior to conformity with IEC standards.



Note) The operating range is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as $\pm 30\%$) depending on the ambient environment.

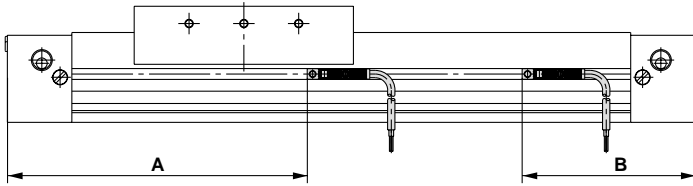
Auto Switch Mounting Positions/D-Z7□, D-Z80□

MY1B (Basic type)



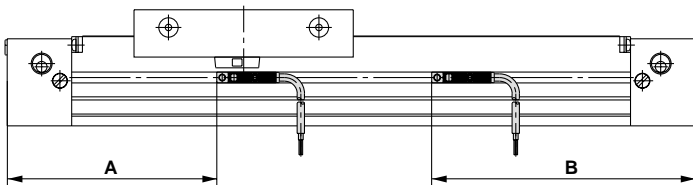
Mounting position	ø25	ø32	ø40	ø50	ø63	ø80	ø100
A	131.5	180	216	272.5	317.5	484.5	569.5
B	88.5	100	124	127.5	142.5	205.5	230.5
Operating range ℓ (Note)	8.5	11.5	11.5	11.5	11.5	11.5	11.5

MY1M (Slide bearing type)



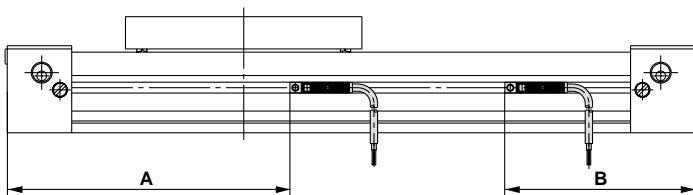
Mounting position	ø25	ø32	ø40	ø50	ø63
A	139.5	184.5	229.5	278.5	323.5
B	80.5	95.5	110.5	121.5	136.5
Operating range ℓ (Note)	12	12	12	11.5	11.5

MY1C (Cam follower guide type)



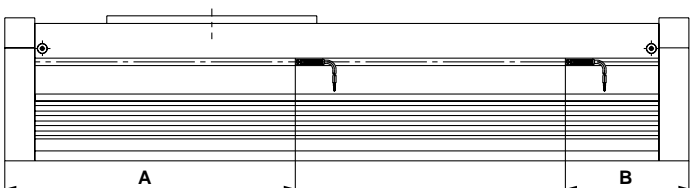
Mounting position	ø25	ø32	ø40	ø50	ø63
A	97.5	127.5	157.5	278.5	323.5
B	122.5	152.5	182.5	121.5	136.5
Operating range ℓ (Note)	12	12	12	11.5	11.5

MY1H (High precision guide type)



Mounting position	ø25	ø32	ø40
A	131.5	180	216
B	88.5	100	124
Operating range ℓ (Note)	8.5	11.5	11.5

MY1HT (High rigidity/High precision guide type)



Mounting position	ø50	ø63
A	290.5	335.5
B	123.5	138.5
Operating range ℓ (Note)	11	11

Solid State Switches

D-M9/3 Wire, 2 Wire (Direct Mount Type)

D-M9N (V), D-M9P (V), D-M9B (V)



Applicable cylinder series

MY1B (Basic)
MY1M (Slide bearing)
MY1C (Cam follower guide)
MY1H (High precision guide)

		Bore size (mm)									
		10	16	20	25	32	40	50	63	80	100
MY1B (Basic)		●	●	●							
MY1M (Slide bearing)			●	●							
MY1C (Cam follower guide)			●	●							
MY1H (High precision guide)		●	●	●							

Auto Switch Specifications

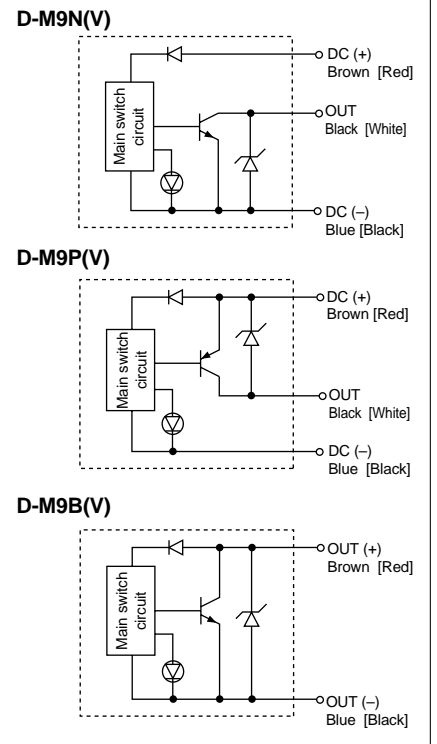
D-M9□, D-M9□V (with indicator light)

Auto switch part no.	D-M9N	D-M9NV	D-M9P	D-M9PV	D-M9B	D-M9BV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3 wire			2 wire		
Output type	NPN			PNP		
Applicable load	IC circuit, Relay, PLC			24VDC Relay, PLC		
Power supply voltage	5, 12, 24VDC (4.5 to 28VDC)			—		
Current consumption	10mA or less			—		
Load voltage	28VDC or less			—		
Load current	40mA or less			80mA or less		
Internal voltage drop	1.5V or less (0.8V or less at 10mA load current)			0.8V or less		
Leakage current	100μA or less at 24VDC			0.8mA or less at 24VDC		
Indicator light	Red LED lights up when ON					

- Lead wires — Heavy duty oil resistant vinyl cord, $\phi 2.7$, 0.5m
D-M9N(V), D-M9P(V) 0.15mm² x 3 wire (Brown, Black, Blue [Red, White, Black])
D-M9B(V) 0.18mm² x 2 wire (Brown, Blue [Red, Black])
 - Insulation resistance — 50M Ω or more at 500VDC (between lead wire and case)
 - Withstand voltage — 1000VAC for 1min. (between lead wire and case)
 - Indicator light — Lights up when ON
 - Ambient temperature — -10 to 60°C
 - Operating time — 1ms or less
 - Enclosure — IEC529 standard IP67, watertight (JIS C0920)
 - Impact resistance — 1000m/s²
- For a lead wire length of 3m, "L" is shown at the end of the part number. Example) D-M9NL

Auto switch internal circuits

Lead wire colours inside () are those prior to conformity with IEC standards.



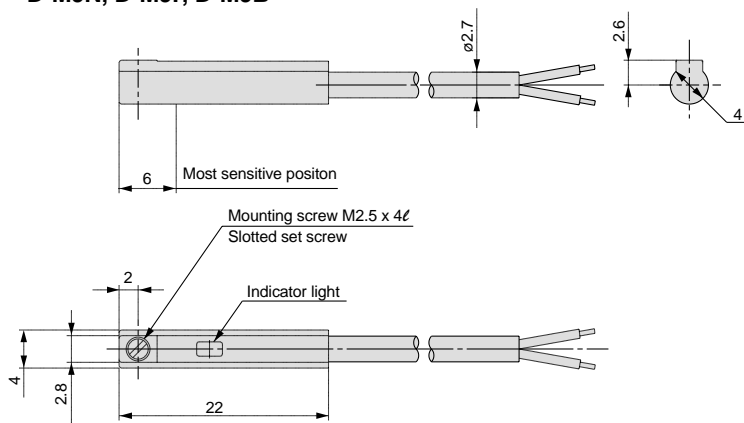
Auto switch weights

Unit: g

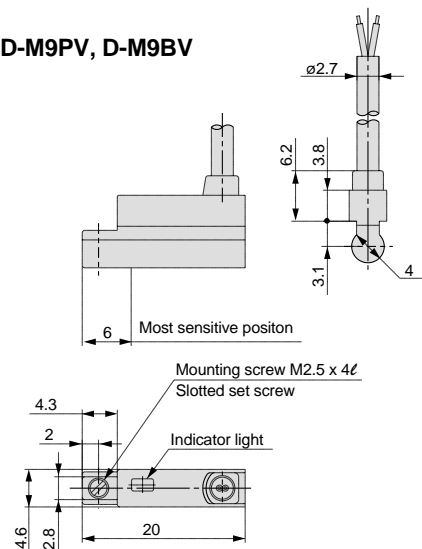
Model	D-M9N	D-M9P	D-M9B	D-M9NV	D-M9PV	D-M9BV
Lead wire length 0.5m	7	7	6	7	7	6
Lead wire length 3m	37	37	31	37	37	31

Auto Switch Dimensions

D-M9N, D-M9P, D-M9B



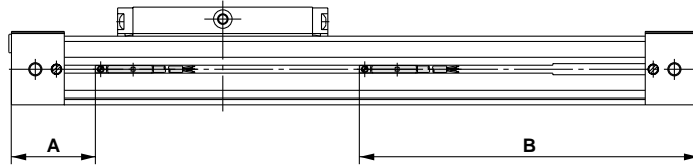
D-M9NV, D-M9PV, D-M9BV



Note) The operating range is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as $\pm 30\%$) depending on the ambient environment.

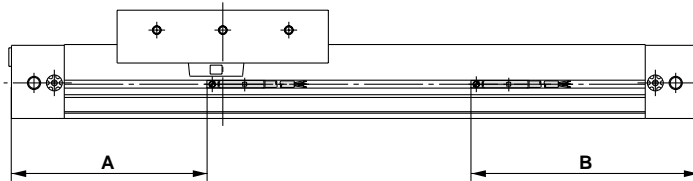
Auto Switch Mounting Positions/D-M9□, D-M9□V

MY1B (Basic type)



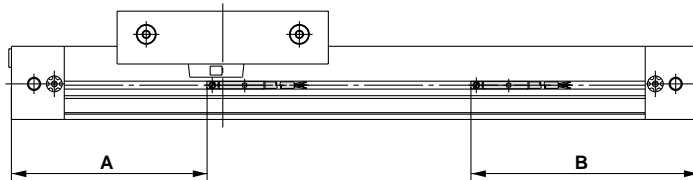
Mounting position	ø10	ø16	ø20
A	24	31	39
B	86	129	161
Operating range ℓ (Note)	3	4	5

MY1M (Slide bearing type)



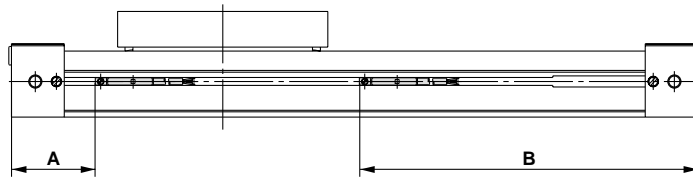
Mounting position	ø16	ø20
A	74	94
B	86	106
Operating range ℓ (Note)	8.5	6.5

MY1C (Cam follower guide type)



Mounting position	ø16	ø20
A	74	94
B	86	106
Operating range ℓ (Note)	8.5	6.5

MY1H (High precision guide type)



Mounting position	ø10	ø16	ø20
A	24	31	39
B	86	129	161
Operating range ℓ (Note)	3	4	5

2 Color Indication Solid State Switches

D-M9□W/3 Wire, 2 Wire

D-M9NW(V), D-M9PW(V), D-M9BW(V)



Applicable cylinder series	Bore size (mm)									
	10	16	20	25	32	40	50	63	80	100
MY1B (Basic)	●	●	●							
MY1M (Slide bearing)		●	●							
MY1C (Cam follower guide)		●	●							
MY1H (High precision guide)	●	●	●							

Auto Switch Specifications

D-M9□W, D-M9□WV (with indicator light)

Auto switch part no	D-M9NW	D-M9NWV	D-M9PW	D-M9PWV	D-M9BW	D-M9BWV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3 wire			2 wire		
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24VDC Relay, PLC	
Power supply voltage	5, 12, 24VDC (4.5 to 28VDC)				—	
Current consumption	10mA or less				—	
Load voltage	28VDC or less		—		24VDC (10 to 28VDC)	
Load current	40mA or less		80mA or less		5 to 40mA	
Internal voltage drop	1.5V or less (0.8V or less at 10mA load current)		0.8V or less		4V or less	
Leakage current	100μA or less at 24VDC				0.8mA or less at 24VDC	
Indicator light	Actuated position Red LED lights up Optimum operating position Green LED lights up					

- **Lead wires** — Heavy duty oil resistant vinyl cord, $\phi 2.7$, 0.5m
D-M9NW(V), D-M9PW(V) 0.15mm² x 3 wire (Brown, Black, Blue [Red, White, Black])
D-M9BW(V) 0.18mm² x 2 wire (Brown, Blue [Red, Black])
- **Insulation resistance** — 50M Ω or more at 500VDC (between lead wire and case)
- **Withstand voltage** — 1000VAC for 1min. (between lead wire and case)
- **Ambient temperature** — -10 to 60°C • **Operating time** — 1ms or less • **Impact resistance** — 1000m/s²
- **Enclosure** — IEC529 standard IP67, watertight (JISC0920)
- For a lead wire length of 3m, "L" is shown at the end of the part number. Example) D-M9NWL

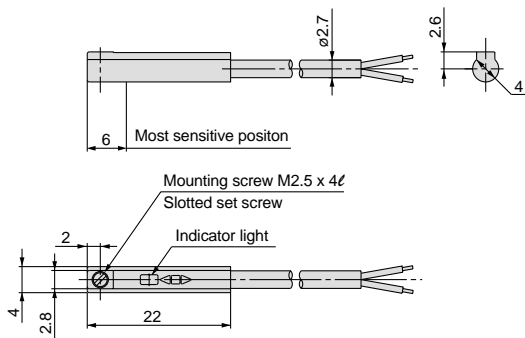
Auto switch weights

Model	D-M9NW	D-M9NWV	D-M9PW	D-M9PWV	D-M9BW	D-M9BWV
Lead wire length 0.5m	7	7	7	7	7	7
Lead wire length 3m	34	34	34	34	32	32

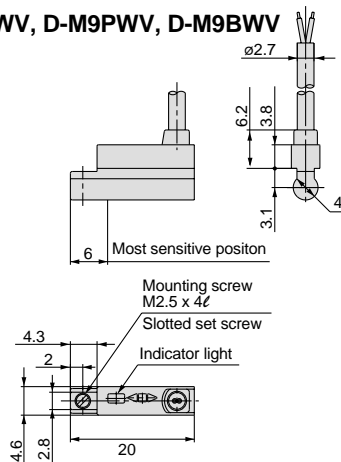
Unit: g

Auto Switch Dimensions

D-M9NW, D-M9PW, D-M9BW



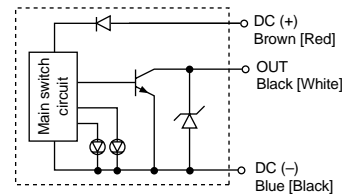
D-M9NWV, D-M9PWV, D-M9BWV



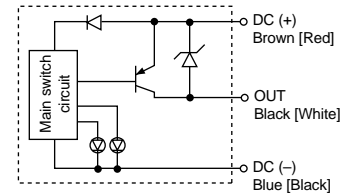
Auto switch internal circuits

Lead wire colours inside () are those prior to conformity with IEC standards.

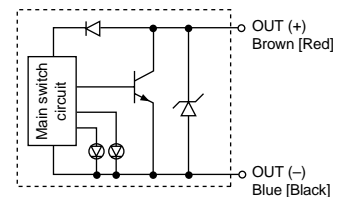
D-M9NW(V)



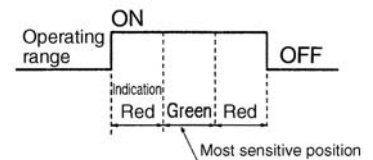
D-M9PW(V)



D-M9BW(V)



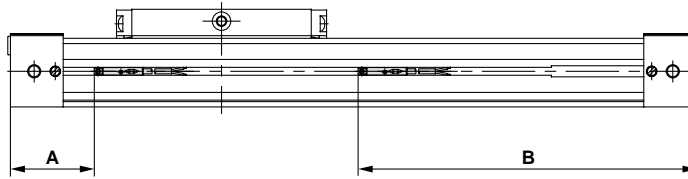
Indicator light/Display method



Note) The operating range is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as $\pm 30\%$) depending on the ambient environment.

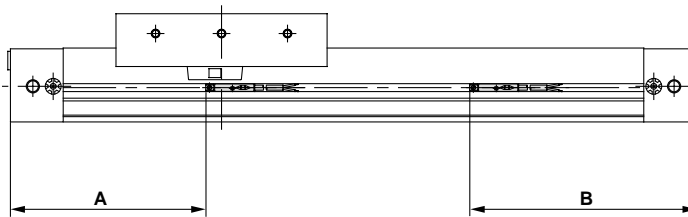
Auto Switch Mounting Positions/D-M9□W, D-M9□WV

MY1B (Basic type)



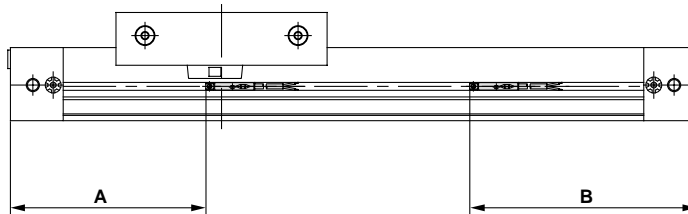
Mounting position	ø10	ø16	ø20
A	24	30	38
B	86	130	162
Operating range ℓ <small>Note)</small>	3	4	5

MY1M (Slide bearing type)



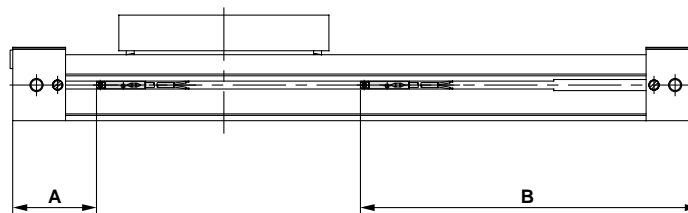
Mounting position	ø16	ø20
A	73	93
B	87	107
Operating range ℓ <small>Note)</small>	8.5	6.5

MY1C (Cam follower guide type)



Mounting position	ø16	ø20
A	73	93
B	87	107
Operating range ℓ <small>Note)</small>	8.5	6.5

MY1H (High precision guide type)



Mounting position	ø10	ø16	ø20
A	24	30	38
B	86	130	162
Operating range ℓ <small>Note)</small>	3	4	5

Solid State Auto Switches

D-Y5, Y6, Y7P(V)/3 Wire, 2 Wire (Direct Mount Type)

D-Y59^A_B, D-Y69^A_B, D-Y7P(V)



Applicable
cylinder series

MY1B (Basic)	16	20	25	32	40	50	63	80	100
MY1M (Slide bearing)									
MY1C (Cam follower guide)									
MY1H (High precision guide)									
MY1HT (High rigidity/High precision guide)									

Bore size (mm)									
	16	20	25	32	40	50	63	80	100
MY1B (Basic)									
MY1M (Slide bearing)									
MY1C (Cam follower guide)									
MY1H (High precision guide)									
MY1HT (High rigidity/High precision guide)									

Auto Switch Specifications

D-Y5, D-Y6, D-Y7P, D-Y7PV (with indicator light)

Auto switch model no.	D-Y59A	D-Y69A	D-Y7P	D-Y7PV	D-Y59B	D-Y69B
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3 wire			2 wire		
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24VDC Relay, PLC	
Power supply voltage	5, 12, 24VDC (4.5 to 28VDC)				—	
Current consumption	10mA or less				—	
Load voltage	28VDC or less		—		24VDC (10 to 28VDC)	
Load current	40mA or less		80mA or less		5 to 40mA	
Internal voltage drop	1.5V or less (0.8V or less at 10mA load current)		0.8V or less		4V or less	
Leakage current	100μA or less at 24VDC				0.8mA or less at 24VDC	
Indicator light	Red LED lights up when ON				—	

- Operating time — 1ms or less
- Lead wires — Heavy duty oil resistant flexible vinyl cord, $\phi 3.4$, 0.15mm², 3 wire (Brown, Black, Blue [Red, White, Black]), 2 wire (Brown, Blue [Red, Black]) 0.5m*
- * For a lead wire length of 3m, "L" is shown at the end of the part number. Example) D-Y59AL
- Impact resistance — 1000m/S²
- Insulation resistance — 50MΩ or more at 500VDC (between lead wire and case)
- Withstand voltage — 1000VAC for 1min. (between lead wire and case)
- Ambient temperature — -10 to 60°C
- Enclosure — IEC529 standard IP67, watertight (JISC0920)

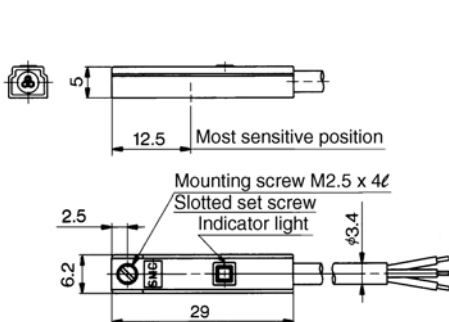
Auto switch weights

Model	Lead wire length 0.5m	Lead wire length 3m
D-Y59A, Y69A, Y7P, Y7PV	10	53
D-Y59B, Y69B	9	50

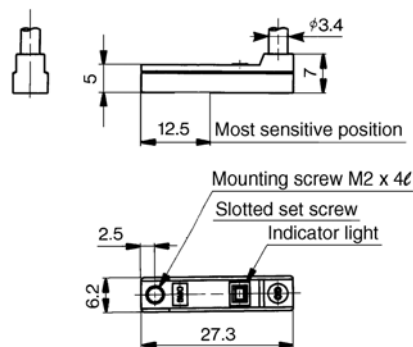
Unit: g

Auto Switch Dimensions

D-Y59A, D-Y7P, D-Y59B



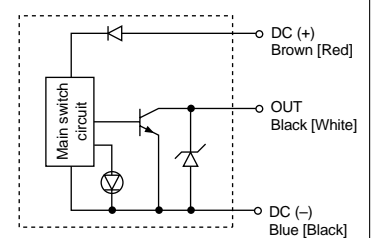
D-Y69A, D-Y7PV, D-Y69B



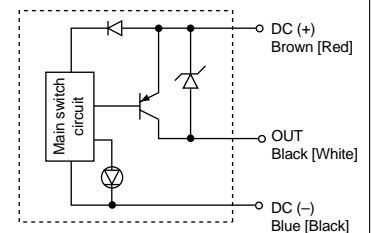
Auto switch internal circuits

Lead wire colours inside () are those prior to conformity with IEC standards.

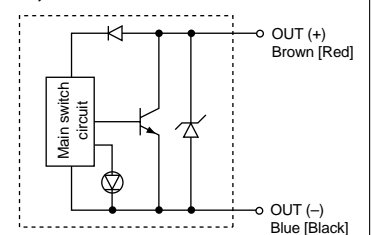
D-Y59A, D-Y69A



D-Y7P(V)



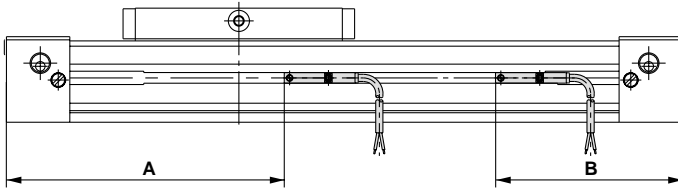
D-Y59B, D-Y69B



Note) The operating range is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as $\pm 30\%$) depending on the ambient environment.

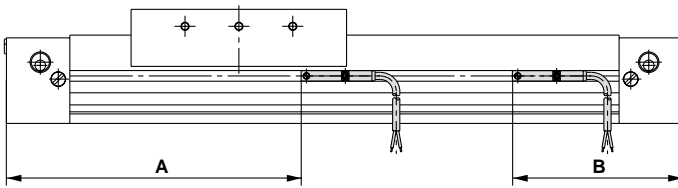
Auto Switch Mounting Positions/D-Y5, D-Y6, D-Y7P(V)

MY1B (Basic type)



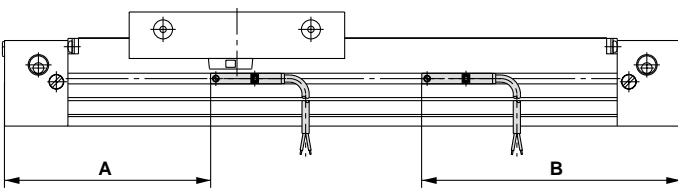
Mounting position	ø25	ø32	ø40	ø50	ø63	ø80	ø100
A	131.5	180	216	272.5	317.5	484.5	569.5
B	88.5	100	124	127.5	142.5	205.5	230.5
Operating range ℓ (Note)	6	9	10	3.5	3.5	3.5	3.5

MY1M (Slide bearing type)



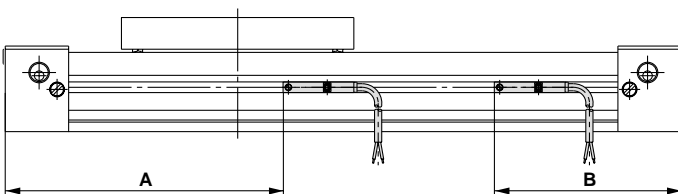
Mounting position	ø25	ø32	ø40	ø50	ø63
A	139.5	184.5	229.5	278.5	323.5
B	80.5	95.5	110.5	121.5	136.5
Operating range ℓ (Note)	5	5	5	5.5	5.5

MY1C (Cam follower guide type)



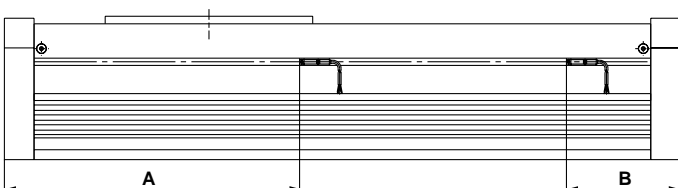
Mounting position	ø25	ø32	ø40	ø50	ø63
A	97.5	127.5	157.5	278.5	323.5
B	122.5	152.5	182.5	121.5	136.5
Operating range ℓ (Note)	5	5	5	5.5	5.5

MY1H (High precision guide type)



Mounting position	ø25	ø32	ø40
A	131.5	180	216
B	88.5	100	124
Operating range ℓ (Note)	6	9	10

MY1HT (High rigidity/High precision guide type)



Mounting position	ø50	ø63
A	290.5	335.5
B	123.5	138.5
Operating range ℓ (Note)	5	5

Solid State Switches

D-Y7□W/3 Wire, 2 Wire (Direct Mount Type)

D-Y7NW(V), D-Y7PW(V), D-Y7BW(V)



Applicable cylinder series

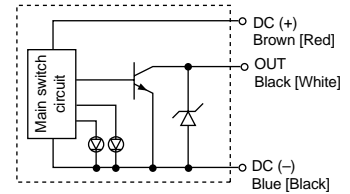
MY1B (Basic)	●	●	●	●	●	●	●	●
MY1M (Slide bearing)	●	●	●	●	●	●	●	●
MY1C (Cam follower guide)	●	●	●	●	●	●	●	●
MY1H (High precision guide)	●	●	●	●	●	●	●	●
MY1HT (High rigidity/High precision guide)	●	●	●	●	●	●	●	●

Bore size (mm)									
	16	20	25	32	40	50	63	80	100

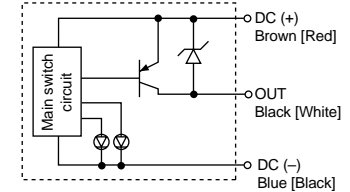
Auto switch internal circuits

Lead wire colours inside () are those prior to conformity with IEC standards.

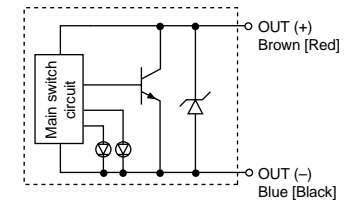
D-Y7NW(V)/3 wire NPN output



D-Y7PW(V)/3 wire PNP output



D-Y7BW(V)/2 wire



Auto Switch Specifications

D-Y7□W, D-Y7□WV (with indicator light)

Auto switch part no	D-Y7NW	D-Y7NWV	D-Y7PW	D-Y7PWV	D-Y7BW	D-Y7BWV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3 wire			2 wire		
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC			24VDC Relay, PLC		
Power supply voltage	5, 12, 24VDC (4.5 to 28VDC)			—		
Current consumption	10mA or less			—		
Load voltage	28VDC or less		—		24VDC (10 to 28VDC)	
Load current	40mA or less		80mA or less		5 to 40mA	
Internal voltage drop	1.5V or less (0.8V or less at 10mA load current)		0.8V or less		4 or less	
Leakage current	100μA or less at 24VDC			0.8mA or less at 24VDC		
Indicator light	Actuated position Red LED lights up Optimum operating position Green LED lights up					

- Operating time — 1ms or less
- Lead wires — Heavy duty oil resistant flexible vinyl cord, $\phi 3.4$, 0.15mm²; 3 wire (Brown, Black, Blue [Red, White, Black]), 2 wire (Brown, Blue [Red, Black]), 0.5m*
- Impact resistance — 1000m/s²
- Insulation resistance — 50M Ω or more at 500VDC (between lead wire and case)
- Withstand voltage — 1000VAC for 1min. (between lead wire and case)
- Ambient temperature — -10 to 60°C
- Enclosure — IEC529 standard IP67, watertight (JISC0920)

* For a lead wire length of 3m, "L" is shown at the end of the part number. Example) D-Y7NWL

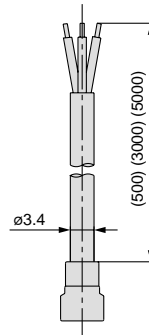
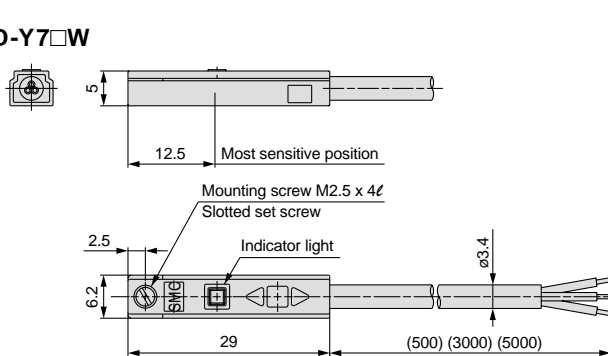
Auto switch weights

Unit: g

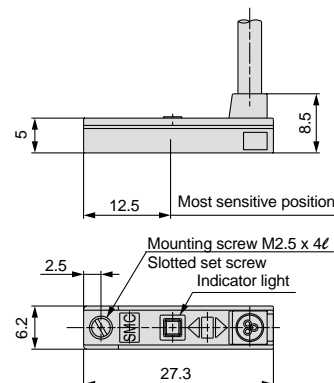
Model	Lead wire length 0.5m	Lead wire length 3m
D-Y7NW, Y7PW, Y7BW	10	53
D-Y7NWV, Y7PWV, Y7BWV	9	50

Auto Switch Dimensions


D-Y7□W



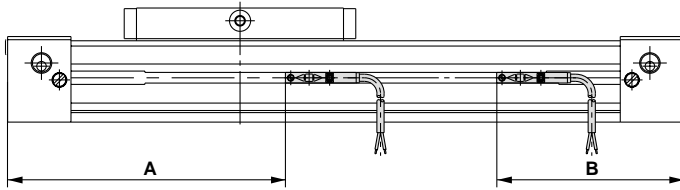
D-Y7□WV



Auto Switch Mounting Positions/D-Y7□W, D-Y7□WV

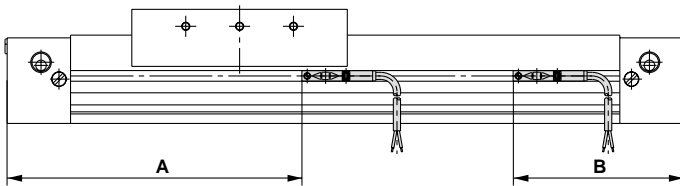
 Note) The operating range is a guide including hysteresis, but is not guaranteed. There may be large variations (as much as ±30%) depending on the ambient environment.

MY1B (Basic type)



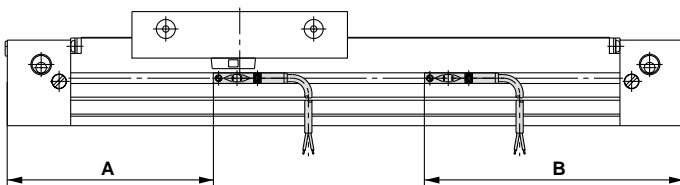
Mounting position	ø25	ø32	ø40	ø50	ø63	ø80	ø100
A	131.5	180	216	272.5	317.5	484.5	569.5
B	88.5	100	124	127.5	142.5	205.5	230.5
Operating range ℓ (Note)	6	9	10	3.5	3.5	3.5	3.5

MY1M (Slide bearing type)



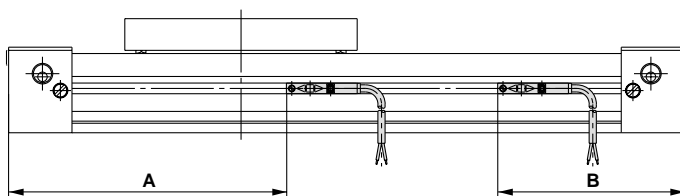
Mounting position	ø25	ø32	ø40	ø50	ø63
A	139.5	184.5	229.5	278.5	323.5
B	80.5	95.5	110.5	121.5	136.5
Operating range ℓ (Note)	5	5	5	5.5	5.5

MY1C (Cam follower guide type)



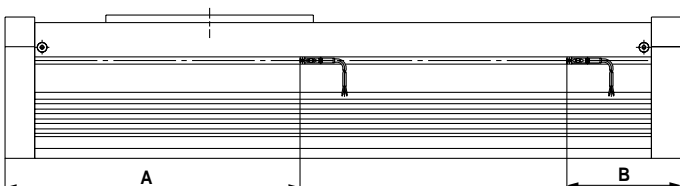
Mounting position	ø25	ø32	ø40	ø50	ø63
A	97.5	127.5	157.5	278.5	323.5
B	122.5	152.5	182.5	121.5	136.5
Operating range ℓ (Note)	5	5	5	5.5	5.5

MY1H (High precision guide type)



Mounting position	ø25	ø32	ø40
A	131.5	180	216
B	88.5	100	124
Operating range ℓ (Note)	6	9	10

MY1HT (High rigidity/High precision guide type)



Mounting position	ø50	ø63
A	290.5	335.5
B	123.5	138.5
Operating range ℓ (Note)	5	5

Series MY1 Order Made Specifications

Contact SMC for detailed dimensions, specifications and lead times.

Order made application list

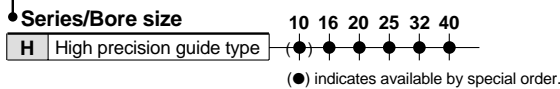
		Intermediate stroke XB10	Long stroke XB11	Helical insert threads X168	Dust seal band NBR XC67	Holder mounting bracket X416, X417	Copper-free 20-
MY1B	Basic type	Standard	●	●	●	●	●
MY1M	Slide bearing guide type	Standard	●	●	●	●	●
MY1C	Cam follower guide type	Standard	●	●	●	●	●
MY1H	High precision guide type	●	●	●	●	●	●
MY1HT	High rigidity/High precision guide type				●		●

1 Intermediate Stroke -XB10

Intermediate strokes are available within the standard stroke range. The stroke can be set in 1mm increments. Series other than MY1H are available with intermediate strokes as standard.

■ Stroke range: 51 to 599mm

MY1 H Bore size Stroke Auto switch Symbol -XB10



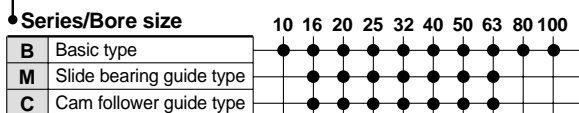
Example) MY1H40G-599L-Z73-XB10

2 Long Stroke -XB11

Available with long strokes exceeding the standard strokes. The stroke can be set in 1mm increments.

■ Stroke range: 2001 to 5000mm (ø10, ø16 are 2001 to 3000mm.)

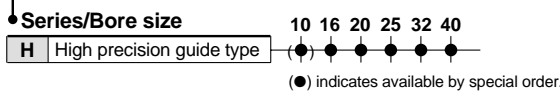
MY1 B Bore size Stroke Auto switch Symbol -XB11



Example) MY1B40G-4999L-Z73-XB11

■ Stroke range: 601 to 1500mm (ø16, ø20 are 601 to 1000mm.)

MY1 H Bore size Stroke Auto switch Symbol -XB11

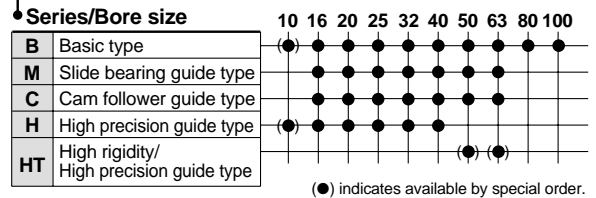


Example) MY1H40G-999L-Z73-XB11

3 Helical Insert Thread Specification -X168

The mounting threads of the slider are changed to helical insert threads. The thread size is the same as standard.

MY1 B Bore size Stroke Auto switch Symbol -X168



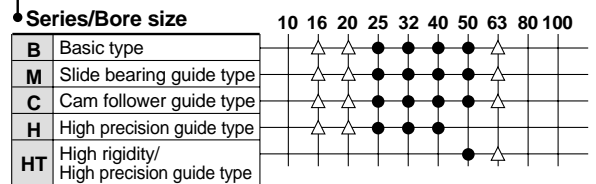
Example) MY1B40G-300L-Z73-X168

4 Dust Seal Band NBR Lining Specification -XC67

The standard vinyl chloride lining specification is changed to NBR lining. Improved oil resistance and peeling resistance.

Note) Consult SMC for specific oil resistance.

MY1 B Bore size Stroke Auto switch Symbol -XC67



Contact SMC for Δ. Furthermore, ø10, ø80 and ø100 are available only in stainless steel plate and the NBR lining specification is not available.

Example) MY1B40G-300L-Z73-XC67

For ordering dust seal band (NBR lining) only

MY Bore size -16 B N - Stroke

Dust seal band
NBR lining

Dust seal band hexagon socket
head set screw treatment

Nil	Black zinc chromated
W	Nickel plated

Refer to "Dust seal band" in the construction figures of each series for details.

Example) MY25-16BNW-300

Series MY1 Order Made Specifications

Contact SMC for detailed dimensions, specifications and lead times.

5 Holder Mounting Bracket ①, ②

-X416, X417

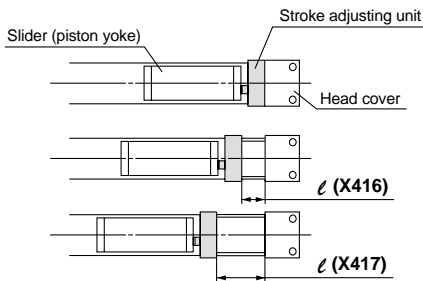
Holder mounting brackets are used to fasten the stroke adjusting unit at an intermediate stroke position.

Holder mounting bracket ① -X416 Holder mounting bracket ② -X417

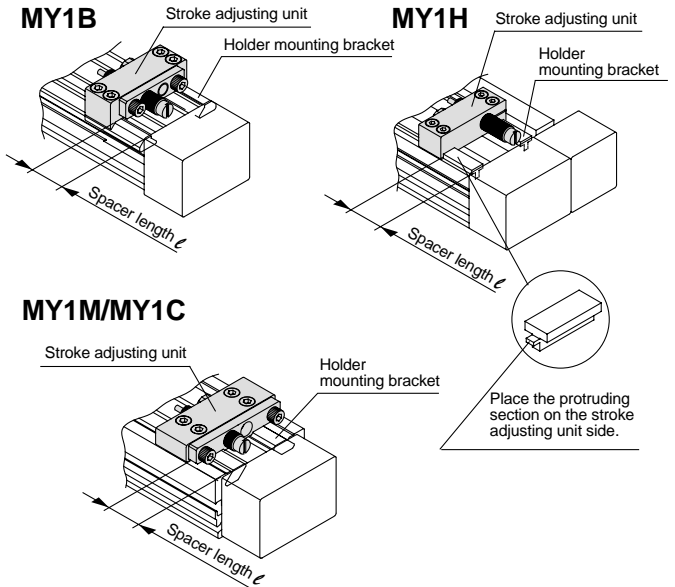
Fine stroke adjustment range

(Treated as a special order when exceeding the adjustment ranges shown below.) Unit: mm

Bore size (mm)	-X416 (one side)				-X417 (one side)					
	Spacer length ℓ	Adjustment range				Spacer length ℓ	Adjustment range			
		MY1B	MY1M	MY1C	MY1H		MY1B	MY1M	MY1C	MY1H
16	5.6	-5.6 to -11.2				11.2	-11.2 to -16.8			
20	6	-6 to -12				12	-12 to -18			
25	11.5	-11.5 to -23				23	-23 to -34.5			
32	12	-12 to -24				24	-24 to -36			
40	16	-16 to -32				32	-32 to -48			
50	20	—	-20 to -40		—	40	—	-40 to -60		—
63	25	—	-25 to -50		—	50	—	-50 to -75		—



Holder Mounting Bracket Illustration



MY1 **B** Bore size - 300 **L** - X416

Combination symbol

Refer to the table below for applicable symbols.

Holder mounting bracket

Refer to the table below for applicable symbols.

Stroke adjusting unit

Refer to the table below for applicable symbols.

Stroke

Note) Indicates the stroke prior to mounting the stroke adjusting unit.

Series/Bore size

	10	16	20	25	32	40	50	63	80	100
B Basic type	●	●	●	●	●	●	●	●	●	●
M Slide bearing guide type										
C Cam follower guide type										
H High precision guide type										

Stroke adjusting unit	Holder mounting bracket	Symbol	Mounting pcs.		Combination description
			X416	X417	
A, L, H, AS, LS, HS	X416	Nil	1		X416 on one side
A, L, H		W	2		X416 on both sides
AL, AH		Z	1	1	X416 on one side, X417 on the other side
AL, LH		A	1		X416 on A unit side
AH, LH		L	1		X416 on L unit side
AL, AH		H	1		X416 on H unit side
AL, LH		AZ	1	1	X416 on A unit side, X417 on the other side
AH, LH		LZ	1	1	X416 on L unit side, X417 on the other side
AH, LH		HZ	1	1	X416 on H unit side, X417 on the other side
A, L, H, AS, LS, HS		X417	Nil		1
A, L, H	W			2	X417 on both sides
AL, AH	A			1	X417 on A unit side
AL, LH	L			1	X417 on L unit side
AH, LH	H			1	X417 on H unit side

Note) For AS, LS and HS, the stroke adjusting unit is mounted on one side only.

Series MY1

Order Made Specifications

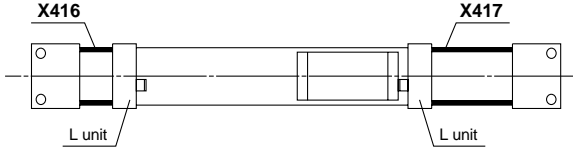
Contact SMC for detailed dimensions, specifications and lead times.

5 Holder Mounting Bracket ①, ②

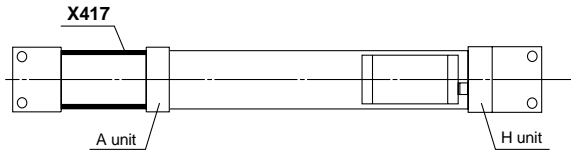
-X416, X417

Example

- L units with one each of X416 and X417
MY1B25G-300L-X416Z



- A and H units, where X417 is mounted on A unit only and nothing on H unit
MY1B25G-300AH-X417A



How to order single pieces of stroke adjusting unit and holder mounting bracket

MYH-A16A - X417

Combination Symbol

Nil	Stroke adjusting unit + Holder mounting bracket
N	Holder mounting bracket only

Holder mounting bracket

X416	Holder mounting bracket 1
X417	Holder mounting bracket 2

Stroke adjusting unit model

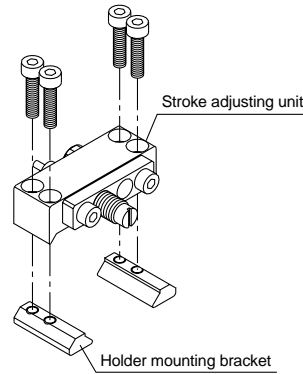
Note) Refer to the options table of "How to Order" for each series.

- MY1B → P. 6
- MY1M → P. 28
- MY1C → P. 44
- MY1H → P. 60

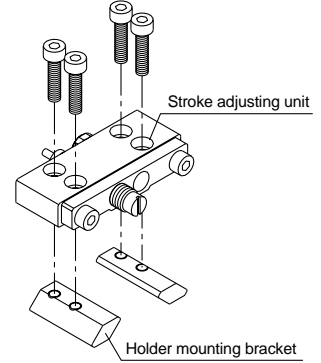
Example

- Stroke adjusting unit with holder mounting bracket
MY-A25L-X416 (L unit for MY1B25 and X416 bracket)
- Holder mounting bracket only
MY-A25L-X416N (X416 bracket for MY1B25 and L unit)

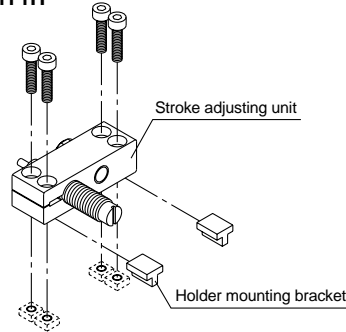
MY1B



MY1M/MY1C



MY1H



Note) For MY1H, the parts are packed together when shipped.

6 Copper-free Specification

20-

Copper-free compatible.

20-MY1 **B** Bore size Stroke Auto switch Symbol

Series/Bore size

		10	16	20	25	32	40	50	63	80	100
B	Basic type	•	•	•	•	•	•	•	•	•	•
M	Slide bearing guide type	•	•	•	•	•	•	•	•	•	•
C	Cam follower guide type	•	•	•	•	•	•	•	•	•	•
H	High precision guide type	•	•	•	•	•	•	•	•	•	•
HT	High rigidity/High precision guide type	•	•	•	•	•	•	•	•	•	•



Series MY1/Specific Product Precautions

Be sure to read before handling.

Caution Mounting

1. Do not apply strong impact or excessive moment to the slide table (slider)

- Since the slide table (slider) is supported by precision bearings (MY1C, MY1H) or resin bearings, do not subject it to strong impact or excessive moment when mounting work pieces.

2. Perform careful alignment when connecting to a load which has an external guide mechanism.

- Mechanically jointed rodless cylinders can be used with a direct load within the allowable range for each type of guide, but careful alignment is necessary for connection to a load which has an external guide mechanism.

Since fluctuation of the center axis increases as the stroke becomes longer, use a method of connection which can absorb the variations (floating mechanism).

Furthermore, use the special floating brackets (pages 18 to 20) which have been provided for series MY1B.

3. Avoid use in environments where a cylinder will come in contact with coolants, cutting oil, water, adhesive matter, or dust, etc. Also avoid operation with compressed air that contains drainage or foreign matter, etc.

- Foreign matter or liquids on the cylinder's interior or exterior can wash out the lubricating grease, which can lead to deterioration and damage of dust seal band and seal materials, causing a danger of malfunction.

When operating in locations with exposure to water and oil, or in dusty locations, provide protection such as a cover to prevent direct contact with the cylinder, or mount so that the dust seal band surface faces downward, and operate with clean compressed air.

Caution

1. Do not inadvertently move the setting of the guide adjustment unit.

- The guide is already adjusted at the factory, and readjustment is not necessary under normal operating conditions. Therefore, do not inadvertently move the setting of the guide adjustment unit. However, series other than series MY1H allow readjustment and bearing replacement, etc.

In this case, refer to the outline for bearing replacement in the instruction manual.

Caution

1. External air leakage may occur.

- In operating conditions where negative pressure is generated inside the cylinder because of external or inertial forces, etc., take note that external air leakage may occur due to separation of the seal belt.



Series MY1/Specific Product Precautions

Be sure to read before handling.

⚠ Caution

Centralized Piping Port Variations

- Head cover ports can be freely selected to best suit different situations.

Applicable cylinder	Port variations
<p>MY1B10 MY1H10</p>	<p>Note 1) These ports are not applicable to MY1H10.</p> <p style="text-align: center;">Slide table operating direction</p>
<p>MY1B16 to 100 MY1M16 to 63 MY1C16 to 63 MY1H16 to 40</p> <p>O-ring Piping tube</p> <p>Note 2) Refer to the above diagram for bottom piping.</p>	<p style="text-align: center;">Slide table operating direction</p>
<p>MY1HT50, 63</p>	<p style="text-align: center;">Slide table operating direction</p>