## CT Series

## DIN W48×H48mm, W72×H36mm, W72×H72mm Counter/Timer

## - Features

- Communication function supported (communication model): RS485 (Modbus RTU)
- One-shot output time setting range -0.01 sec to 99.99 sec by setting per 10 ms
-[Counter]
Prescale value setting range - 6-digit model: 0.00001 to 99999.9 /
4-digit model: 0.001 to 999.9
9 input modes/11 output modes
BATCH counter,
Count Start Point (counting initial value) setting function
- [Timer]


13 output modes
Various time setting range-6-digit model: 0.001 sec to 99999.9 hour / 4-digit model: 0.001 sec to 9999 hour ' 0 ' time setting function
Selectable timer memory retention function for indicator model.

$\square$ DAQMaster (Comprehensive Device Management Program)

- DAQMaster is comprehensive device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and comprehensive device management program.

| Item | Minimum requirements |
| :--- | :--- |
| System | IBM PC compatible computer with Intel Pentium III or above |
| Operations | Microsoft Windows 98/NT/XP/Vista/7/8/10 |
| Memory | $256 \mathrm{MB}+$ |
| Hard disk | 1GB+ of available hard disk space |
| VGA | Resolution: $1024 \times 768$ or higher |
| Others | RS-232 serial port (9-pin), USB port |

< DAQMaster screen >


## Ordering Information


※1: CT4S model does not support indicatior type.

## - Communication Specification

| Comm. protocol | Modbus RTU with 16-bit CRC |
| :--- | :--- |
| Connection type | RS485 |
| Application standard | Compliance with EIA RS485 |
| Max. connection | 31 units (address: 1 to 127) |
| Synchronous method | Asynchronous |
| Comm. type | Two-wire half duplex |
| Comm. distance | Max. 800 m |
| Comm. speed | $2400,4800,9600$ (factory default), 19200, 38400bps |
| Comm. response time | 5 to 99ms (factory default: 20ms) |
| Start bit | 1-bit (fixed) |
| Data bit | 8-bit (fixed) |
| Parity bit | None (factory default), Even, Odd |
| Stop bit | 1, 2-bit (factory default: 2-bit) |

[^0] separately), SCM-US48I (USB to RS485 converter, sold separately), SCM-38I (RS232C to RS485 converter, sold separately), SCM-US (USB to Serial converter, sold separately). Please use twisted pair wire for RS485 communication.

## Programmable Counter/Timer

$\square$ Specifications

| Series |  |  |  | CTS |  | CTY |  | CTM |  | Photoelectric Sensors |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mode | 1-stage preset |  |  | CT4S-1P $\square \square$ | CT6S-1P $\square \square$ | CT6Y-1P $\square \square$ |  | CT6M-1P $\square \square$ |  | (B) <br> Fiber Optic Sensors |
|  | 2-stage preset |  |  | CT4S-2P $\square \square$ | CT6S-2P $\square \square$ | CT6Y-2P $\square \square$ |  | CT6M-2P $\square \square$ |  |  |
|  | Indicator |  |  | - | CT6S-1 $\square \square$ | CT6Y-I $\square$ |  | CT6M-I $\square$ |  |  |
| Display digits |  |  |  | 4-digit | 6-digit | 6-digit |  | 6-digit |  | (C) Door/Area Sensors |
| Display method |  |  |  | 7 segment (counting value: red, setting value: yellow-green) LED method |  |  |  |  |  |  |
| Character size $(W \times H)$ |  | Counting value |  | $6.5 \times 10 \mathrm{~mm}$ | $4.5 \times 10 \mathrm{~mm}$ | $4.2 \times 9.5 \mathrm{~mm}$ |  | $6.6 \times 13 \mathrm{~mm}$ |  |  |
|  |  | Setting value |  | $4.5 \times 8 \mathrm{~mm}$ | $3.5 \times 7 \mathrm{~mm}$ | $3.5 \times 7 \mathrm{~mm}$ |  | $5 \times 9 \mathrm{~mm}$ |  | $\begin{aligned} & \text { (D) } \\ & \text { Proximity } \\ & \text { Sensors } \end{aligned}$ |
| Power supply |  | AC voltage |  | 100-240VAC $\sim 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |
|  |  | AC/DC voltage |  | $24 \mathrm{VAC} \sim 50 / 60 \mathrm{~Hz}, 24-48 \mathrm{VDC}=-$ |  |  |  |  |  | (E) <br> Pressure Sensors |
| Permissible voltage range |  |  |  | 90 to 110\% of rated voltage |  |  |  |  |  |  |
| Power consumption |  | AC voltage |  | Max. 12VA |  |  |  |  |  |  |
|  |  | AC/DC voltage |  | AC: Max. 10VA, DC: Max. 8W |  |  |  |  |  | (F) Rotary |
| Coun | INA/INB <br> Max. counting speed |  |  | Selectable 1cps/30cps/1kcps/5kcps/10kcps |  |  |  |  |  | Encoders <br> (G) |
|  | Counting range |  |  | -999 to 9999 | -99999 to 999999 |  |  |  |  | Connectors/ <br> Connector Cables/ |
|  | Scale |  |  | Decimal point up to third digit | Decimal point up to fifth digit |  |  |  |  | Sensor Distribution <br> Boxes/Sockets <br> (H) |
|  | Min. input signal width |  |  | RESET: Selectable $1 \mathrm{~ms} / 20 \mathrm{~ms}$ |  |  |  |  |  | ( H ) <br> Temperature Controllers |
| Time | Time range |  | 4-digit | 9.999s, 99.99s, 999.9s, 9999s, 99m59s, 999.9m, 9999m, 99h59m, 9999h |  |  |  |  |  |  |
|  |  |  | 6-digit | 99h59m59s, 9999h59m, 99999.9h |  |  |  |  |  | (I) <br> SSRs / Power Controllers |
|  | Operation method |  |  | Count up, Count down, Count Up/Down |  |  |  |  |  |  |
|  | Min. input signal width |  |  | INA, INH, RESET: Selectable 1ms/20ms |  |  |  | INA, RESET, INHIBIT, BATCH RESET: Selectable $1 \mathrm{~ms} / 20 \mathrm{~ms}$ |  | (J) Counters |
|  | Repeat error |  |  | In case of power ON start: Max. $\pm 0.01 \% \pm 0.05$ s In case of signal start: Max. $\pm 0.01 \% \pm 0.03 \mathrm{~s}$ |  |  |  |  |  | $\begin{aligned} & \text { (K) } \\ & \text { Timers } \end{aligned}$ |
|  | Set error |  |  |  |  |  |  |  |  |  |
|  | Voltage error |  |  |  |  |  |  |  |  |  |
|  | Temp. error |  |  |  |  |  |  |  |  |  |
| Input method |  |  |  | Selectable voltage input or no-voltage input <br> [Voltage input]-input impedance: $5.4 \mathrm{k} \Omega,[\mathrm{H}]: 5-30 \mathrm{VDC}=-\mathrm{e}$, [L]: 0-2VDC <br> [No-voltage input]-short-circuit impedance: Max. $1 \mathrm{k} \Omega$, short-circuit residual voltage: Max. 2VDC=-- |  |  |  |  |  | Panel <br> Meters <br> (M) |
| One-shot output time |  |  |  | 0.01s to 99.99s setting |  |  |  |  |  | (M) <br> Tacho / <br> Speed / Pulse <br> Meters |
|  |  |  |  | Standard | Comm. | Standard | Comm. | Standard | Comm. |  |
|  | Contact output | Type | 1-stage | SPDT(1c): 1 |  | SPDT(1c): 1 |  | SPDT(1c): 1 |  | ( N ) Display Units |
|  |  |  | 2-stage | SPST(1a): 2 |  | $\begin{aligned} & \text { SPST(1a): 1, } \\ & \text { SPDT(1c): } \end{aligned}$ | SPST(1a): 2 | SPST(1a): 1, SPDT(1c): 1 |  |  |
|  |  | Capacity |  | $\begin{aligned} & \text { 250VAC~5A, 30VDC=-=5A } \\ & \text { resistive load } \end{aligned}$ |  | $250 \mathrm{VAC} \sim 3 \mathrm{~A}, 30 \mathrm{VDC}=-=3 \mathrm{~A}$ <br> resistive load |  | $\begin{aligned} & \text { 250VAC~5A, 30VDC=-=5A } \\ & \text { resistive load } \end{aligned}$ |  | (O) <br> Sensor <br> Controllers |
|  | Solid state output (NPN open collector) |  | 1-stage | 1 |  | 1 | 1 | 2 | 2 | (P) <br> Switching Mode Power Supplies |
|  |  |  | 2-stage |  |  |  |  | 3 |  |  |
|  |  | Capacity |  | Max. 30VDC $=-=, 100 \mathrm{~mA}$ |  |  |  |  |  |  |
| External power supply |  |  |  | Max. 12VDC=- $\pm 10 \%$, 100mA |  |  |  |  |  | (Q) Stepper Motors \& Drivers \& Controllers |
| Memory retention |  |  |  | Approx. 10 years (non-volatile memory) |  |  |  |  |  |  |
| Insulation resistance |  |  |  | Over 100M ${ }^{\text {at }}$ (a00VDC megger) |  |  |  |  |  | (R) Logic Panels |
| Dielectric strength |  |  |  | $2,000 \mathrm{VAC} 50 / 60 \mathrm{~Hz}$ for 1 min |  |  |  |  |  |  |
| Noise immunity |  |  |  | Square-wave noise by noise simulator (pulse width $1 \mu \mathrm{~s}$ ) $\pm 2 \mathrm{kV}$ |  |  |  |  |  |  |
| Vibration |  | Mechanical |  | 0.75 mm amplitude at frequency 10 to 55 Hz (for 1 min ) in each $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ direction for 1 hour |  |  |  |  |  | (S) Field Network Devices |
|  |  | Malfunction |  | 0.5 mm amplitude at frequency 10 to 55 Hz (for 1 min ) in each $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ direction for 10 minutes |  |  |  |  |  |  |
| Shock |  | Mechanical |  | $300 \mathrm{~m} / \mathrm{s}^{2}$ (approx. 30G) in each X, Y, Z direction for 3 times |  |  |  |  |  |  |
|  |  | Malfunction |  | $100 \mathrm{~m} / \mathrm{s}^{2}$ (approx. 10G) in each $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ direction for 3 times |  |  |  |  |  | (T) Software |
| Relay life cycle |  | Mechanical |  | Min. 10,000,000 operations |  |  |  |  |  |  |
|  |  | Malfunction |  | Min. 100,000 operations |  |  |  |  |  |  |
| Protection structure |  |  |  | IP65 (front part, IEC standard) |  |  |  |  |  |  |
| Environmental |  | Ambient temp. |  | -10 to $55^{\circ} \mathrm{C}$, storage: -25 to $65^{\circ} \mathrm{C}$ |  |  |  |  |  |  |
|  |  | Ambient humi. |  | 35 to $85 \%$ RH, storage: 35 to $85 \%$ RH |  |  |  |  |  |  |
| Approval |  |  |  | C ${ }_{\text {c }} \mathrm{MN}_{\text {us }}$ |  |  |  |  |  |  |
| Weight ${ }^{* 1}$ |  |  |  | Approx. 212g (approx. 159g) |  | Approx. 228g (approx. 140g) |  | Approx. 322g (approx. 252g) |  |  |

※1: The weight includes packaging. The weight in parenthesis is for unit only.
※Environment resistance is rated at no freezing or condensation.


## Programmable Counter/Timer

- CT6Y-I



## © CTM Series

## - CT6M-1P $\square$



- CT6M-2P $\square$

- Ст6M- $\square$

※1: AC Voltage: 100-240VAC $50 / 60 \mathrm{~Hz}$
AC/DC Voltage: 24 VAC $50 / 60 \mathrm{~Hz}, 24-48 V D C$
※2: Counter operation: If INHIBIT signal is applied, count input will be prohibited.
Timer operation: If INHIBIT signal is applied, time progressing will stop. (HOLD)


## CT Series

$\square$ Dimensions
© CTS Series

© CTY Series

© CTM Series

© Bracket

- CTS Series

- CTY Series

- CTM Series


© Panel cut-out - CTS Series



## - CTM Series



# Programmable Counter／Timer 

## Sold Separately

© Communication converter
－SCM－WF48
（Wi－Fi to RS485－USB wireless communication converter） （ $\in$ 通
－SCM－US48I
（USB to RS485 converter）
C $\in$ 通


O Display Units（DS／DA－T Series）
－DS／DA－T Series
（RS485 communication input type display unit）$C \epsilon$


DS16－$\quad$ T


DS22／DA22－TT


DS40／DA40－TT
－SCM－38I
（RS232C to RS485 converter）
C $\in$ 淙


DS60／DA60－TT
※Connect RS485 communication input type display unit（DS／DA－T Series）and RS485 communication output model of CT Series， the display unit displays present value of the device without PC／PLC．
$\square$ Unit Description
© CTS Series

© CTY Series

© CTM Series


1．Counting value display component（red）
RUN mode：Displays counting value for counter operation or time progress value for timer operation．
Function setting mode：Displays setting item．
2．Setting value display component（yellow－green）
RUN mode：Displays setting value．
Function setting mode：Displays setting content．
3．Key lock indicator（LOCK）：Turns ON for key lock setting．
4．Counter indicator（CNT）：Turns ON for counter operation．
5．Timer indicator（TMR）：Flashes（progressing time）or Turns ON（stoping time）for timer operation．
6．Preset value checking and changing indicator（PS1，PS2）
：Turns ON when checking and changing preset value．
7．Output indicator（OUT1，OUT2）：Turns ON for the dedicated control output ON．
8．RST key
RUN mode：Press the RST key to reset the counting value．
BATCH counter mode：Press the RST key to reset the batch counting value．
9．MD key
RUN mode：Hold the MD key over 3 sec to enter function setting mode（parameter setting）． Hold the MD key over 5 sec to enter function setting mode（communication setting）．
Function setting mode：Press the MD key to select function setting mode parameter． Hold the MD key over 3 sec to return RUN mode．
10．《，娄，园 key
1）《 key
RUN mode：Press the 《 key to enter preset mode．
Preset mode：Press the $<$ key to move preset digits．
2）包，图 key
RUN mode：Hold the 图 key over 1 sec to enter Function setting check mode．
Preset mode：Used for increasing or decreasing preset value．
Function setting mode：Changes the settings．
Function setting check mode：Press the 圈key to move the previous parameter．
Press the 因 key to the next parameter．
11．BA key
RUN mode：Press the RST key to enter BATCH counter indication mode．
12．BATCH output indicator（BA．O）（red）
13．BATCH preset value checking and changing indicator（BA．S）（yellow－green）
：Turns ON when checking and changing BATCH preset value．
※The indicator type does not exist in CT4S model．

## CT Series

## $\square$ Input Connections

## © No-voltage input (NPN)

- Solid-state input (standard sensor: NPN output type sensor)

- Contact input

※1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part
※2: Counting speed: 1 or 30 cps setting (counter)
© Voltage input (PNP)
- Solid-state input (standard sensor: PNP output type sensor)
- Contact input

※1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part
※2: Counting speed: 1 or 30 cps setting (counter)


## Input Logic Selection [No-Voltage Input (NPN)/Voltage Input (PNP)]



## ※How to change settings

Power OFF $\rightarrow$ change settings $\rightarrow$ power ON $\rightarrow$ press RST key or input signal (min. 20ms)
Error Display and Output Operation

| Error Display | Error description | Troubleshooting |
| :---: | :--- | :--- |
| $\varepsilon_{r r 0}$ | Setting value is 0. | Change the setting value anything but 0. |

[^1]
# Programmable Counter／Timer 

## Output Connections

## © Contact output


※Use proper load not to exceed the capacity．

※Use proper load and power for load not to excess ON／OFF capacity（Max．30VDC， 100 mA ）of solid state output． ※Be sure not to apply reverse polarity of power．
※1：When using inductive load（relay etc．），surge absorber
（diode，varistor etc．）must be connected between both sides of the load．

Operations and Functions


## © Change of preset（counter／timer）

－Even if changing the preset value，input operation and output control will continue．In addition，the preset value could be set to 0 and the output of 0 preset value turns ON．According to output mode，preset value could not be set to 0 ． （When setting to 0 ，preset value＂ 0 ＂will flash 3 times．）


In RUN mode，press the $\mathbb{<}$ key to enter preset mode．
＇PS1＇indicator turns ON and first digit of preset value flashes．


Press the $\mathbb{《}$ ，园 and $\boxtimes$ keys to set the desired value（example， 180）．Press the MD key to enter the PS2 setting mode．


Press the $\mathbb{《}$ ，图 and keys to set the desired value（example， 200）．Press the MD key to return RUN mode．

## © Function setting check mode



## © Switching display function in preset indicator

Setting value1（PS1）and setting value2（PS2）are displayed each time pressing MD key in PRESET2 model． （in timer，it is available for and，and．I or and．e output mode．）

## © Reset

In RUN mode or function setting mode，if pressing RST key or applying the signal to the RESET terminal on the back side，present value will be reset and output will maintain off status．When selecting voltage input（PNP），short no． 10 and no． 12 terminals，or when selecting no－voltage input（NPN），short no． 11 and no． 12 terminals to reset．

## BATCH Counter (for CT6M-1P $\square \square / C T 6 M-2 P \square \square$ Model Only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

## © Change of BATCH setting value

If pressing BA key in Run mode, it will enter into BATCH counter indication mode.
1.

2.


BATCH value is set to ' 200 ' using $\mathbb{<}$, , and keys, then press MD key to complete BATCH setting value and move to BATCH counter indication mode.
© BATCH counter operation

() BATCH counting operation

- BATCH counting value is increasing until BATCH reset signal applied. BATCH counting value will be circulated when it is over 999999.

1) BATCH counting operation in Counter: Counts the number of reaching setting value of CT6M-1P or reaching dual setting value of CT6M-2P $\square \square$
2) BATCH counting operation in Timer: Counts the number of reaching setting time. (In case of "FL $\mu$ " output mode, count the number of reaching T.off setting time and T.on setting time.)

## © BATCH output

- If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- When the power is cut off then resupplied in status of BATCH output is ON, BATCH output maintains ON status until BATCH reset signal is applied.


## © BATCH reset input

- If pressing RST key or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset. When selecting voltage input (PNP), short terminals 10 and 14, or when selecting no-voltage input (NPN), short terminals 11 and 14 to reset.
- When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.


## © Application of BATCH counter function <br> - Counter

In case, put 5 products in a box then pack the boxes when they reaches to 200.

- Counter preset setting value="5", BATCH setting value="200"
- When the count value of counter reaches to the preset value " 5 ", the control output (OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to " 200 ", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for packing.


## - Timer

Fills milk into the bottle for 3 sec (setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on. (Setting time: 3 sec, BATCH setting value: 500 )


## Programmable Counter/Timer

Flow Chart for Function Setting Mode


Parameter Setting（Counter）
（ND key：Moves the settings，包，图 key：Changes the settings）

| Parameter | Setting |
| :---: | :---: |
| Counter／ <br> Timer $[[-t]$ |  |
| Input mode $\left[\begin{array}{ll}{\left[\begin{array}{ll}1\end{array}\right]}\end{array}\right.$ | Ud－$\leftrightarrows \leftrightarrow U P \leftrightarrow U P-1 \leftrightarrow U P-2 \leftrightarrow d n \leftrightarrow d n-1 \leftrightarrow d n-2 \leftrightarrow U d-$ 月 $\leftrightarrow U d-b$ |
| Output mode ［out．in］ | －Input mode is $U P, U P-1, U P-2$ or $d n, d n-1, d n-2$ ， <br> －Input mode is $U d-A, U d-b, U d-[$ ， <br> ※If max．counting speed is 5 kcps or 10 kcps ，and output mode is $d$ ，max．counting speed is automatically changed as 30 cps ，factory default． |
| Indication <br> mode <br> ［d5P．in］ | －In case of the indicator type $※$ In case of the indicator type，indicate mode selection［ $d 5 P . \bar{n}$ ］is displayed． HoLd $\longleftrightarrow$ Lothi $\quad ※$ It is the added function to set the preset value when selecting HoLd． |
| Max．counting <br> speed <br> ［［P5］ |  |
| OUT2 output time ${ }^{* 1}$ ［out2］ | ※Set one－shot output time of OUT2． <br> ※Setting range： 00.01 to 99.99 sec <br> ※When input mode is $F, n, 5, t, d, \circ \cup t 2$ does not appear．（fixed as HOLD） |
| OUT1 output time ${ }^{* 1}$ ［out 1］ | ※Set one－shot output time of OUT1． <br> ※Setting range： 00.01 to 99.99 sec ，Hold． <br> ※When 1st digit is flashing，press the 《 key once and HoLd appears． <br> ※When input mode is $5, t, d, \circ \Delta t$｜does not appear．（fixed as HOLD） |
| OUT output time＊＊ ［out．t］ | ※Setting range： 00.01 to 99.99 sec <br> ※When input mode is $F, n, 5, t, d, \square \cup t . t$ does not appear．（fixed as HOLD） |
| Decimal point ${ }^{* 2}$ ［dP］ | －6－digit type <br> －4－digit type <br> 4 <br> ※Decimal point is applied to counting value and setting value． |
| Min．reset time［－5t］ |  |
| Input logic ［5：©］ | $\cap P_{\cap}:$ No－voltage input，$P_{\cap} P$ ：Voltage input ※Check input logic value（PNP，NPN）． |
| Prescale decimal point ${ }^{* 2}$ ［5．$\left[. \mathrm{dP}^{\text {P }}\right.$ ］ |  |
| Prescale value［5［L］ | ※Setting range of prescale value 6－digit type： 0.00001 to 99999.9 ，4－digit type： 0.001 to 999.9 |
| Start point value <br> ［5trt］ | ※Setting range（linked with decimal point［dP］）： 6－digit type： 0.00001 to 999999,4 －digit type： 0.001 to 9999 ※When input mode is $d n, d n-1, d n-2$ ，start point value does not appear． |
| Memory protection ［d月LA］ | $\operatorname{LLr} \longleftrightarrow r E\left[\begin{array}{l}\text { KLLr：Resets the counting value when power OFF．} \\ r E[: \text { Maintains the counting value when power OFF．} \\ \text {（memory protection）}\end{array}\right.$ |
| Key lock <br> ［ LoLf ］ |  |

※1：For PRESET1 model，oUt I does not appear．The output time of out 2 is displayed as out．t．
※2：Decimal point and prescale decimal point
Decimal point：Set the decimal point for display value regardless of prescale value．
Prescale decimal point：Set the decimal point for prescale value of counting value regardless of decimal point of display value．

## Programmable Counter/Timer

## $\square$ Input Operation Mode (Counter)

| Input mode | Counting chart | Operation |
| :---: | :---: | :---: |
| UP <br> [UP] |  | ※When INA is counting input, INB is no counting input. When INB is counting input, INA is no counting input. |
| $\left[\begin{array}{l} U P-1 \\ {[U P-1]} \end{array}\right.$ |  | ※When INA input signal is rising ( $\sqrt{-}$ ), it counts. <br> ※INA: Counting input <br> ※INB: No counting input |
| $\left[\begin{array}{l} \text { UP-2 } \\ {[U P-2]} \end{array}\right.$ |  | ※When INA input signal is falling ( $\quad$ L), it counts. ※INA: Counting input <br> ※INB: No counting input |
| $\begin{aligned} & \text { Down } \\ & {\left[\begin{array}{l} d n] \end{array}\right]} \end{aligned}$ |  | ※When INA is counting input, INB is no counting input. <br> When INB is counting input, INA is no counting input. |
| $\left[\begin{array}{l} \text { Down-1 } \\ {[d n-1]} \end{array}\right.$ |  | ※When INA input signal is rising ( $\mathbb{\sim}$ ), it counts. <br> ※INA: Counting input <br> ※INB: No counting input |
| Down-2 $[d n-2]$ |  | ※When INA input signal is falling ( Z ), it counts. <br> ※INA: Counting input <br> ※INB: No counting input |
| Up/ <br> Down-A <br> [ $\because d-$ - $]$ |  | ※INA: Counting input <br> INB: Counting command input <br> ※When INB is "L", counting command is up. When INB is "H", it is counting command is down. |

Input Operation Mode (Counter)

| Input mode | Counting chart | Operation |
| :---: | :---: | :---: |
| Up/ Down-B [Ud-b] |  | ※INA: Up counting input <br> INB: Down counting input <br> ※When INA and INB input signals are rising ( $F$ ) at the same time, it maintains previous counting value. |
| Up/ Down-C [Ud-c] |  | ※When connecting encoder output <br> A, B phase with counter input, INA, INB, set input mode [i $\cap . \overline{\mathrm{n}}$ ] as phase different input [ $\lrcorner d-\lceil$ ] for counter operation. |

※1: For selectable no-voltage input (PNP), voltage input (NPN) model.
※A: over min. signal width, B: over than $1 / 2$ of min. signal width. If the signal is smaller than these width, it may cause counting error $( \pm 1)$.
※The meaning of "H", "L"

$\left.$| Character |  | Input metholtage input <br> (PNP) |
| :--- | :--- | :--- | | No-voltage input |
| :--- |
| (NPN) | \right\rvert\, | Short |  |
| :--- | :--- |
| H | 5-30VDC |
| S | O-2VDC |

※Min. signal width by counting speed

| Counting <br> speed | Min. <br> signal width |
| :--- | :--- |
| 1 cps | 500 ms |
| 30 cps | 16.7 ms |
| 1 kcps | 0.5 ms |
| 5 kcps | 0.1 ms |
| 10 kcps | 0.05 ms |

$1 \mathrm{cps}=1 \mathrm{~Hz}$

## Prescale Function (Counter)

This function is to set and display calculated unit for actual length, liquid, position, etc. It is called "prescale value" for measured length, liquid, or position, etc per 1 pulse. For example, when moving L, the desired length to be measured, and $P$, the number of pulses per 1 revolution of a rotary encoder, occurs, prescale value is L/P.
E.g.) Positioning control by counter and encoder


Set decimal point[ $\mathrm{d}_{\mathrm{P}}$ ] as [----.-], prescale decimal point [5[.dP] as [---.-- ], prescale value [5[L] as [D.069] at function setting mode. It is available to control conveyer position by 0.1 mm unit.

## Start Point Function (Counter)

This function is that start at initial value set at Start Point [ $5 t r t$ ] when on counting mode.

- In case of $d n, d n-1$ or $d n-\sum$ in timer input mode, it is not available.
- When reset is applied, the present value is initialized to start point.
- In case of $[, r, P, q$ output operation mode, the present value starts at START POINT value after counting up.


# Programmable Counter/Timer 

$\square$ Output Operation Mode (Counter)

(A)

Photoelectric
Sensors Sensors
※After count-up, counting display value and OUT1 retained output are maintained until RESET input is applied.
※OUT1 one-shot output time is operated regardless of OUT2 output.

Output Operation Mode (Counter)
Retained output Coincidence output

| Output mode | Up/Down - A, B, C | Operation |
| :---: | :---: | :---: |
| $\begin{aligned} & \mathrm{S} \\ & {[5]} \end{aligned}$ |  | ※OUT1 and OUT2 keep ON status in following condition: <br> Counting display value $\geqq$ PRESET1 <br> Counting display value $\geqq$ PRESET2 |
| $\left[\begin{array}{l} \mathrm{T} \\ {[L]} \end{array}\right.$ |  | ※OUT1 output is off: <br> Counting display value $\geqq$ PRESET1 ※OUT2 keeps ON status in following condition: <br> Counting display value $\geqq$ PRESET2 |
| $\left[\begin{array}{l} D \\ {[d]} \end{array}\right.$ |  | ※When counting display value is equal to setting value [PRESET1, PRESET2) only, OUT1 or OUT2 output keeps ON status. <br> ※When setting 1 kcps for counting speed, solid state contact output should be used. |

※The PRESET1 type output (OUT) is operated as OUT2 of PRESET2 type.
※The PRESET2 model OUT1 output is operated as one-shot or retained output. (except $5, t, d$ mode)
※OUT1 output could be set to 0 in all modes and 0 value output turns ON.
※OUT2 output could not set to 0 in $\mathrm{C}[\mathrm{L}], \mathrm{R}[r], \mathrm{P}[\mathrm{P}]$ or $\mathrm{Q}[9]$ output mode.
Counter Operation of the Indicator (CT6S-I, CT6Y-I, CT6M-I)
※Only displays on indicator models

| Indicate mode [dSP.̄̄] | Count chart |  | Operation |
| :---: | :---: | :---: | :---: |
|  | In case of input mode is Up (Up, Up-1, Up-2) | In case of input mode is Down (Down, Down-1, Down-2) |  |
| TOTAL [tothi] | $\begin{array}{lll:l} \hline \text { RESET } & & & \\ 999999 & & & \\ 0 & & & \end{array}$ |  | Count value increases or decreases until RESET input is applied. <br> When input is over max./min. counting value, it displays 0 . When Reset input is applied, it displays 0(Up)/999999(Down). |
| $\left[\begin{array}{l} \mathrm{HOLD} \\ {[\mathrm{HoL} \mathrm{~d}]} \end{array}\right.$ |  |  | Count value increases or decreases until RESET input is applied. When input is reaching preset value(Up)/0(Down), the display value is hold. When Reset input is applied, it displays $0(\mathrm{Up}) /$ preset value(Down). |

- In case of the Command input [ $\omega d$ - 7 ], Individual input [ud-b], Phase difference input [ $u d-[$ ] mode.

※In case of UP/DOWN [Ud-A, $U d-b, U d-[]$ input mode, indication mode [ $\alpha 5 P \cdot \bar{n}$ ] of the configuration is not displayed.


# Programmable Counter／Timer 

Parameter Setting（Timer）
（MD key：Moves the settings，圈，图 key：Changes the settings）

| Parameter | Setting |
| :---: | :---: |
| Counter／Timer $\left[\begin{array}{ll}{[-t]}\end{array}\right.$ | CoUn $\longrightarrow$ tiñ $\quad$※「aUn：Counter <br> LinE：Timer |
| Time range ［Hourlni n／5E［］ |  |
| Up／Down mode［ $\mathrm{U}-\mathrm{d}$ ］ | $U P \longleftrightarrow d n \quad \begin{array}{r}\text { ※uP：Time progresses from＇} 0 \text {＇to the setting time，} \\ d n: \text { Time progresses from the setting time to＇} 0 \text {＇．}\end{array}$ |
| Indication mode ［d5P．ㄷ．］ | ※Used for the indicator type only． <br> ※It is added that the feature which set the setting time when selecting HoLd or ant．d |
| Memory protection ［ dRLR ］ | $\left[\mathrm{Lr} \longleftrightarrow r E\left[\begin{array}{l}\text { KUsed for the indicator type only．} \\ \text { ※［Lr：Reset time value when power is off．} \\ \text { reL：Memorizes time value at the moment of power off．}\end{array}\right.\right.$ |
| Output mode ［out．in］ |  |
| OUT2 output time ［oUt $\mathrm{U}^{*}{ }^{* 1}$ | ※Set one－shot output time of OUT2． <br> ※Setting range： 00.01 to 99.99 sec ，Hold． <br> ※When 1st digit is flashing，press the $\mathbb{}$ key once and HoL d appears． |
| OUT1 output time ［out $]^{* 1}$ | ※Set one－shot output time of OUT1． <br> ※Setting range： 00.01 to 99.99 sec ，Hold． <br> ※When 1st digit is flashing，press the $\mathbb{}$ key once and HoL d appears． |
| OUT output time ［out．t ］${ }^{* 1}$ | ※Setting range： 00.01 to 99.99 sec，Hold． <br> ※When 1st digit is flashing，press the $\mathbb{}$ key once and HoLd appears． |
| Input logic $\left[\begin{array}{lll} 51 & 6 \end{array}\right.$ | $\cap P_{n}$ ：No－voltage input，$P_{\cap} P$ ：Voltage input ※Check input logic value（PNP，NPN）． |
| Input signal time［1 n．t ］ | ※CTS／CTY：Set min．width of INA，INH，RESET signal． <br> ※CTM：Set min．width of INA，RESET，INHIBIT，BATCH RESET signal． |
| Key lock <br> ［ L ［LU］ |  |

（A）
Photoelectric
Photoele
Sensors
（B）
Fiber
Fiber
Optic
Optic
Sensors
（C）
Door／Area
Sensors
（D）
Proximity
Sensors
（E）
Pressure
Sensors
（F）
Rotar
Encoders
（G）
Connectors／
Connector Cables／
Sensor Distribution
Boxes／Sockets
（H）
Temperature
Controllers
（I）
Controllers
（J）
Counters
（K）
Timers
（L）
Panel
Meters
（M）
Tacho
Tacho／
Speed／Pulse ${ }_{\text {Meters }}^{\text {Speed } / \mathrm{Pu}}$
（N）

| Display |
| :--- |
| Units |

（0）
Sensor
Controllers
（P）
Switch
（P）
Switching
Mode Power
Mode Pow
（Q）
（Q）
Stepper Motors
Stepper Mo
\＆Controllers
（R）
Graphic
Logic
Panels
（S）
Field
Field
Network
Devices
（T）
Software
Software

appear．The output time of out 己 is displayed as aUt．t．When output mode is and，and I，and．己，int．己，aUt 1 appears．
※2：int．2 mode is available only for PRESET2 model．


[^2]
# Programmable Counter/Timer 



[^3]
※Power Reset: There is no memory protection. (Initializes the display value when power is off)
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

## Programmable Counter/Timer


※Power Reset: There is no memory protection. (Initializes the display value and the output status when re-supplying the power.)
Power Hold: There is memory protection. (It memorizes the status of power off. When re-supplying the power, it returns the memorized display value and the output status.)

## Timer Operation of the Indicator (CT6S-I, CT6Y-I, CT6M-I)



# Programmable Counter/Timer 

## $\square$ Timer '0' Time Setting

© Available output operation mode to set ' 0 ' time setting
 and, and. 1 , and.l, nFd, nFd. 1
© Operation according to output mode (at 0 time setting)

1) OND (Signal ON Delay) mode [ond]

- Setting time 1 is set to 0


2) OND. 1 (Signal ON Delay 1) mode [ond. i]

- Setting time1 is set to 0


3) OND. 2 (Power ON Delay2) mode [ond.2]

- Setting time 1 is set to 0


4) NFD (ON-OFF Delay) mode [ $n$ F ${ }^{6}$ ]

- OFF_Delay setting time is set to 0


5) NFD. 1 (ON-OFF Delay1) mode [ $n$ Fd.i]

- OFF_Delay setting time is set to 0



## © Setting value1 (PS1) is higher than Setting value2 (PS2)

OND[and], OND. 1 [ond. 1 ] or OND. 2 [ond.2] output mode

- UP mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.
- DOWN mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON. If the setting value 1 is same as the setting value 2 and START signal is applied, OUT1 output turns ON immediately.

Communication Mode
© Parameter setting
（MD key：To select setting mode，团 or key：To change setting value）

| Setting mode | How to set |  |  |
| :---: | :---: | :---: | :---: |
| Comm．address ［Addr］ | To shift flashing digits of Comm．address人：To change the flashing digits． | ※Settin ※If the it will | nge of Comm e address is work correct |
| Comm．speed ［bP5］ |  |  |  |
| Comm．parity [Prty] | ※nonE：None EuEn：Even number odd：Odd number |  |  |
| Comm．stop bit ［5LP］ | $1 \longleftrightarrow 2$ |  |  |
| esponse waiting time ［－5 L！ L ］ |  |  |  |
| Comm．write ［［ ロп… $]$ | $\text { EnR } \longleftrightarrow d i 5 \text { A }$ <br> ※EnA：Permits Comm．write（Enable） di 5月：Prohibits Comm．write（Disable） |  |  |

© Application of system organization
※Only for RS485 communication output model．

※It is recommended to use Autonics communication converter；SCM－WF48（Wi－Fi to RS485•USB wireless communication converter，sold separately），SCM－US48I（USB to RS485 converter，sold separately），SCM－38I（RS232C to RS485 converter，sold separately），SCM－US（USB to Serial converter，sold separately）．
Please use twisted pair wire，which is suitable for RS485 communication，for SCM－WF48，SCM－US48I and SCM－38I．

## © Communication control ordering

1．The communication method is Modbus RTU（PI－MBUS－300－REV．J）．
2．After 1 sec of power supply into the high order system，it starts to communicate．
3．Initial communication will be started by the high order system．When a command comes out from the high order system，
CT Series will respond．


## Programmable Counter/Timer

## © Communication command and block

The format of query and response

1) Read coil status (func. 01 H ),

Read input status (func. 02 H )

- Query (master)

| Slave <br> Address | Function | Starting <br> Address |  | No. of Points |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

CRC 16

- Response (slave)

| Slave <br> Address | Function | Byte <br> Count | Data | Data | Data | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | Low | High |  |  |  |  |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

CRC 16
2) Read holding registers (func. 03 H ),

Read input registers (func. 04 H )

- Query (master)

| Slave <br> Address | Function | Starting <br> Address |  | No. of Points |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

$$
\leftarrow
$$

CRC 16

- Response (slave)

| Slave Address | Function | Byte Count | Data |  | Data |  | Data |  | Error Check (CRC 16) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | High | Low | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1 Byte | 1Byte | 1Byte | 1Byte | 1 Byte | 1Byte | 1Byte | 1Byte |

CRC 16
3) Force single coil. (func. 05 H )

- Query (master)

| Slave <br> Address | Function | Coil Address  Force Data  Error Check  <br> (CRC 16)      |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |



## - Response (slave)

| Slave <br> Address | Function | Coil Address |  | Force Data |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

CRC 16
4) Preset single register (func. 06 H )

- Query (master)

| Slave <br> Address | Function | Register <br> Address |  | Preset Data |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

## CRC 16

## - Response (slave)

| Slave <br> Address | Function | Register <br> Address |  | Preset Data |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| $\longleftrightarrow$ CRC 16 |  |  |  |  |  |  |  |

CRC 16
5) Preset multiple registers (func. 10 H )

- Query (master)

- Response (slave)


CRC 16

## 6) Application

Read Coil Status (func. 01 H )
Master reads OUT2 $000002(0001 \mathrm{H})$ to $000003(0002 \mathrm{H})$,
OUT1 output status (ON: 1, OFF: 0) from the Slave (Address 01).

- Query (master)

| Slave <br> Address | Function | Starting Address |  | No. of Points |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 01 H | 01 H | 00 H | 01 H | 00 H | 02 H | EC H | 0B H |

On slave side OUT2 000003 (0002H): OFF,
OUT1 000002 (0001H): ON

- Response (slave)

| Slave <br> Address | Function | Byte Count | Data <br> $(00003$ to <br> $00001)$ | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  | Low | High |  |
| 01 H | 01 H | 01 H | 02 H | D0 H | 49 H |

Read Input Register (Func. 04 H )Master reads preset value 301004 (03EBH) to 301005 ( 03 ECH ) of counter/ timer, Slave (Address 15).

## - Query (master)

| Slave <br> Address | Function | Starting Address |  | No. of Points |  | Error Check <br> (CRC 16) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| OF H | 04 H | 03 H | EB H | 00 H | 02 H | 00 H | 95 H |

In case that the present value is $123456(0001 \mathrm{E} 240 \mathrm{H})$ in slave side, 301004 (03EBH): E240 H, 301005 (03ECH): 0001H

- Response (slave)

| Slave <br> Address | Function | Byte <br> Count |  | Data |  | Error Check |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  |  |  |  |  |  |

## CT Series

## © Modbus mapping table

1) Reset/Output

| No. (Address) | Func. | Explanation | Setting range | Notice |
| :--- | :--- | :--- | :--- | :--- |
| $000001(0000)$ | $01 / 05$ | Reset | $0:$ OFF 1:ON | - |
| $000002(0001)$ | 01 | OUT2 output | $0:$ OFF 1:ON | - |
| $000003(0002)$ | 01 | OUT1 output | $0:$ OFF 1:ON | - |
| $000004(0003)$ | 01 | BATCH <br> output | $0:$ OFF 1:ON | For BATCH <br> output model |
| $000005(0004)$ | $01 / 05$ | BATCH <br> resets | $0:$ OFF 1:ON | For BATCH <br> output model |

## 2) Terminal input status

| No. (Address) | Func. | Explanation | Setting range | Notice |
| :--- | :--- | :--- | :--- | :--- |
| $100001(0000)$ | 02 | INA input <br> status | $0:$ OFF <br> $1:$ ON | Terminal input <br> status |
| $100002(0001)$ | 02 | INB input <br> status | $0:$ OFF <br> $1:$ ON | Terminal input <br> status |
| $100003(0002)$ | 02 | INHIBIT input <br> status | $0:$ OFF <br> $1:$ ON | Terminal input <br> status |
| $100004(0003)$ | 02 | RESET input <br> status | $0:$ OFF <br> $1:$ ON | Terminal input <br> status |
| $100005(0004)$ | 02 | BATCH <br> RESET <br> input status | $0:$ OFF <br> $1:$ ON | Terminal input <br> status |

## 3) Product information

| No. (Address) | Func. | Explanation | Notice |
| :---: | :---: | :---: | :---: |
| 300001 to 300100 | 04 | Reserved | - |
| 300101 (0064) | 04 | Product number H | Model ID |
| 300102 (0065) | 04 | Product number L | Model ID |
| 300103 (0066) | 04 | Hardware version | - |
| 300104 (0067) | 04 | Software version | - |
| 300105 (0068) | 04 | Model no. 1 | "CT" |
| 300106 (0069) | 04 | Model no. 2 | "6M" |
| 300107 (006A) | 04 | Model no. 3 | "-2" |
| 300108 (006B) | 04 | Model no. 4 | "PT" |
| 300109 (006C) | 04 | Reserved | - |
| 300110 (006D) | 04 | Reserved | - |
| 300111 (006E) | 04 | Reserved | - |
| 300112 (006F) | 04 | Reserved | - |
| 300113 (0070) | 04 | Reserved | - |
| 300114 (0071) | 04 | Reserved | - |
| 300115 (0072) | 04 | Reserved | - |
| 300116 (0073) | 04 | Reserved | - |
| 300117 (0074) | 04 | Reserved | - |
| 300118 (0075) | 04 | Coil Status Start Address | 0000 |
| 300119 (0076) | 04 | Coil Status Quantity | - |
| 300120 (0077) | 04 | Input Status Start Address | 0000 |
| 300121 (0078) | 04 | Input Status Quantity | - |
| 300122 (0079) | 04 | Holding Register Start Address | 0000 |
| 300123 (007A) | 04 | Holding Register Quantity | - |
| 300124 (007B) | 04 | Input Register Start Address | 0064 |
| 300125 (007C) | 04 | Input Register Quantity | - |

4) Monitoring data

| No. (Address) | Func. | Explanation | Setting range | Notice |
| :---: | :---: | :---: | :---: | :---: |
| 301001 (03E8) | 04 | $\begin{aligned} & \text { BA.O LED } \\ & \text { display status } \end{aligned}$ | 0:OFF 1:ON | Bit 5 |
|  |  | OUT2 LED display status | 0:OFF 1:ON | Bit 6 |
|  |  | OUT1 LED display status | 0:OFF 1:ON | Bit 7 |
|  |  | BA.S LED display status | 0:OFF 1:ON | Bit 10 |
|  |  | $\begin{aligned} & \text { LOCK LED } \\ & \text { display status } \end{aligned}$ | 0:OFF 1:ON | Bit 11 |
|  |  | $\begin{aligned} & \text { PS2 LED } \\ & \text { display status } \\ & \hline \end{aligned}$ | 0:OFF 1:ON | Bit 12 |
|  |  | PS1 LED display status | 0:OFF 1:ON | Bit 13 |
|  |  | TMR LED display status | 0:OFF 1:ON | Bit 14 |
|  |  | CNT LED display status | 0:OFF 1:ON | Bit 15 |
| 301002 (03E9) | 04 | Present value of BATCH counter | 0 to 999999 | For BATCH output model |
| 301003 (03EA) |  |  |  |  |
| 301004 (03EB) | 04 | Present value of counter/timer | [Counter] <br> 6digit type <br> - -99999 to 999999 <br> 4digit type | Use counter and timer in common |
| 301005 (03EC) |  |  | : -999 to 9999 <br> [Timer]: Within <br> time setting range |  |
| 301006 (03ED) | 04 | Display unit | [Counter] <br> : decimal point of display value [Timer] <br> : Time range | Counter: <br> 40058 Data <br> Timer: <br> 40102 Data |
| 301007 (03EE) | 04 | PS (2) setting value | [Counter] <br> 6digit type <br> : -99999 to 999999 <br> 4digit type <br> : -999 to 9999 <br> [Timer]: Within <br> time setting range | Use counter and timer in common |
| 301008 (03EF) |  |  |  |  |
| 301009 (03F0) | 04 | PS1 setting value |  |  |
| 301010 (03F1) |  |  |  |  |
| 301011 (03F2) |  |  | 0 to 999999 | Use counter |
| 301012 (03F3) | 04 | counter | O to 999999 | common |
| 301013 (03F4) | 04 | Checking the input logic | 0: NPN, 1: PNP |  |

- Date format of 301001 (03E8) address bit

| Bit | Explanation | Data | Bit | Explanation | Data |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Bit0 | - | 0 | Bit8 | - | 0 |
| Bit1 | - | 0 | Bit9 | - | 0 |
| Bit2 | - | 0 | Bit10 | BA.S | 0 or 1 |
| Bit3 | - | 0 | Bit11 | Lock | 0 or 1 |
| Bit4 | - | 0 | Bit12 | PRESET2 | 0 or 1 |
| Bit5 | BA.O | 0 or 1 | Bit13 | PRESET1 | 0 or 1 |
| Bit6 | OUT2 | 0 or 1 | Bit14 | TMR | 0 or 1 |
| Bit7 | OUT1 | 0 or 1 | Bit15 | CNT | 0 or 1 |

※2 Words data format: Upper data has high number address.
E.g.)301004: Present Value (Low Word), 301005: Present Value (High Word)

## 5) Preset value setting group

| No. (Address) | Func. | Explanation | Setting range | Notice |
| :---: | :---: | :---: | :---: | :---: |
| 400001 (0000) | $\begin{aligned} & 03 / \\ & 06 / \\ & 16 \end{aligned}$ | PS2 setting value PS setting value | [Counter] <br> 6digit type <br> : 0 to 999999 <br> 4digit type: 0 to 9999 <br> [Timer]: Within time <br> setting range | Use counter and timer in common |
| 400002 (0001) |  |  |  |  |
| 400003 (0002) |  |  |  |  |
| 400004 (0003) |  | PS1 setting value |  |  |
| 400005 (0004) |  |  |  |  |
| 400006 (0005) |  | setting value |  |  |

## Programmable Counter／Timer

6）Function setting mode（counter group）

| No．（Address） | Func． | Explanation | Setting range | Notice |
| :---: | :---: | :---: | :---: | :---: |
| 400051 （0032） | 03／06／16 | Counter／Timer［［－t ］ | 1：Loun 1：tiñ | Use counter and timer in common |
| 400052 （0033） | 03／06／16 | Input mode［1 $n$ ］ |  | － |
| 400053 （0034） | 03／06／16 | Indication mode［di 5 ̄］ | 0：tothl 1：HoLd | For the indicator |
| 400054 （0035） | 03／06／16 | Output mode［out．in］ |  | － |
| 400055 （0036） | 03／06／16 | Maximum counting speed ［LPS］ | $0: 1$ $2: 14$ $4: 10 ム$ <br> $1: 30$ $3: 5 ム$  | － |
| 400056 （0037） | 03／06／16 | OUT2（OUT）output time ［out 2（out．t）］ | 0001 to 9999 | unit：$\times 10 \mathrm{~ms}$ |
| 400057 （0038） | 03／06／16 | OUT1 Output time ［oUt 1］ | 0001 to 9999 | unit：$\times 10 \mathrm{~ms}$ |
| 400058 （0039） | 03／06／16 | Decimal point［dP］ |  | $\begin{aligned} & \text { 4digit type 0:---- } \\ & \text { 1:---. 2: }--.--3:-.-- \end{aligned}$ |
| 400059 （003A） | 03／06／16 | Min．reset time［ r 5 t ］ | 0：1 1：20 | unit：ms |
| 400060 （003B） | 03／06／16 | Prescale decimal point position［5［L．d］ | 0：－－－－－－ 3：－－－．－－ <br> 2：$----------------~$ 4：－－－－－ | 4digit type 1:---- 2: --.-- 3:-.--- |
| $\begin{array}{\|l\|} \hline 400061 \text { (003C) } \\ \hline 400062 \text { (003D) } \\ \hline \end{array}$ | 03／06／16 | Prescale value［5［L］ | 6digit type： 0.00001 to 999999 4digit type： 0.001 to 9999 | Connected with prescale decimal point position |
| 400063 （003E） | 03／06／16 | Start value［5trt］ | 6digit type： 000000 to 999999 4digit type： 0000 to 9999 | Connected with decimal point position of display value |
| 400065 （0040） | 03／06／16 | Memory protection［ d AL A ］ | 0：Llr 1：rec | Use counter and timer in common |
| 400066 （0041） | 03／06／16 |  | 0：L．off 1：LoC． 1 2：LoL．2 3：LoL．3 |  |

（A）
$\stackrel{\text { Photoelectric }}{ }$
Sensors
（B）
Fiber
Optic
Sensors
（C）
Door／
Door／Area
Sensors
（D）
Proximity
Sensors
（E）
Pressure
Pressure
Sensors
（F）
Rotary
Encoders

Connectors／
Connector Cables／
Sensor Distribution
Boxes／Sockets

| （H） |  |
| :--- | :--- |
| Te |  |
| C |  |
|  |  |
|  |  |
| S |  |
|  |  |

Temperature
Controllers
（I）
SSRs／Power
SSRs／Power
Controllers
（J）
Count
Counters
7）Function setting mode（timer group）

| No．（Address） | Func． | Explanation | Setting range |  |  |  | Notice |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 400101 （0064） | 03／06／16 | Counter／Timer［ $[-t$ ］ | 0：Coun 1：tine |  |  |  | Use counter and timer in common |
| 400102 （0065） | 03／06／16 | Time range ［Habr／nín／5E［］ | 4digit type |  |  |  | － |
|  |  |  | 0： 0.001 s to 9.999 s 5： 0.1 m to 999.9 m <br> $1: 0.01 \mathrm{~s}$ to 99.99 s 6： 1 m to 9999 m <br> 2： 0.1 s to 999.9 s 7： 1 m to 99 h 59 m <br> $3: 1 \mathrm{~s}$ to 9999 s 8： 1 h to 9999 h <br> $4: 1 \mathrm{~s}$ to 99 m 59 s  |  |  |  |  |
|  |  |  | 6digit type |  |  |  |  |
|  |  |  | $0: 0.001 \mathrm{~s}$ to 999.999 s 6： 1 s to 9999 m 59 s <br> $1: 0.01 \mathrm{~s}$ to 9999.99 s $7: 1 \mathrm{~m}$ to 99999.9 m <br> 2： 0.1 s to 99999.9 s 8： 1 m to 999999 m <br> 3： 1 s to 999999 s 9： 1 s to 99 h 59 m 59 s <br> $4: 0.01 \mathrm{~s}$ to 99 m 59.99 s $10: 1 \mathrm{~m}$ to 9999959 m <br> 5： 0.1 s to 999 m 59.9 s 11： 0.1 h to 99999.9 h |  |  |  |  |
| 400103 （0066） | 03／06／16 | UP／Down mode［ $u-d$ ］ | 0：UP 1：dn |  |  |  | － |
| 400104 （0067） | 03／06／16 | Output mode［oUt．in］ | $\begin{aligned} & \text { 0: and } \\ & \text { 1: and. } \\ & 2: \text { and. } \end{aligned}$ | $\begin{aligned} & \text { 3: FLU } \\ & \text { 4: FLU. } \\ & \text { 5: FLU.Z } \end{aligned}$ | $\begin{aligned} & \text { 7: i nt. } 1 \\ & \text { 8: i nt.己 } \\ & \text { 9: ofd } \end{aligned}$ | $\begin{aligned} & \text { 10: } n F d \\ & \text { 11: } n F d .1 \\ & \text { 12: i nt. } \end{aligned}$ | － |
| 400105 （0068） | 03／06／16 | OUT2（OUT）Output time ［out ᄅ］ | 0000 to 9999 （0：Hold） |  |  |  | unit：$\times 10 \mathrm{~ms}$ |
| 400106 （0069） | 03／06／16 | OUT1 Output time ［oUt 1］ | 0000 to 9999 （0：Hold） |  |  |  | unit：$\times 10 \mathrm{~ms}$ |
| 400107 （006A） | 03／06／16 | Input signal time［ i пt］ | 0：1 1：20 |  |  |  | unit：ms |
| 400108 （006B） | 03／06／16 | Memory protection ［dALR］ | 0：Llr 1：rec |  |  |  | Use counter and timer in common |
| 400109 （006C） | 03／06／16 | Lock key［Lo［ L ］ | 0：L．off 1：LaL． 1 2：LaL．2 3：LaL．ق |  |  |  | Use counter and timer in common |
| 400110 （006D） | 03／06／16 | ndication mode［d5P．̄］ | 0：tathl 1：HaLd 2：ant．d |  |  |  | For the indicator |

## 8）Function setting mode（communication group）

| No．（Address） | Func． | Explanation | Setting range | Notice |
| :---: | :---: | :---: | :---: | :---: |
| 400151 （0096） | 03／06／16 | Comm．address［ Addr ］ | 1 to 127 | － |
| 400152 （0097） | 03／06／16 | Comm．speed［6－5］ | 0： 24 1：48 2：96 3：192 4：384 | unit：$\times 100 \mathrm{bps}$ |
| 400153 （0098） | 03／06／16 | Comm．parity［Prレy］ | 0：nonE 1：EuEn 2：odd | － |
| 400154 （0099） | 03／06／16 | Stop bit［5ヒP］ | 0：1 1： 2 | － |
| 400155 （009A） | 03／06／16 |  | 05 to 99 | unit：ms |
| 400156 （009B） | 03／06／16 | Comm．writing［［ם ¢－ | 0：EnA 1：di 5A | － |

## © Exception processing

When communication error occurs，the highest bit of received function is set
to 1 ，then sends response command and transmits exception code．

| Slave Address | Exception Code | Error Check（CRC16） |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

－Illeegal Function（Exception Code：01H）：Not supporting command
－Illegal Data Address（Exception Code：02H）
：Mismatch between the number of asked data and the number of ansmittable data．
－Illegal Data Value（Exception Code： 03
：Mismatch between asked the number of data and transmittable the number of data in device
－Slave Device Failure（Exception Code：04H）：Command is processed incorrectly．

## Example）

Master reads output status（ON：1，OFF：0）of non existing coil 01001 （03E8 H）from Slave（Address17）．

## －Query（master）

| Slave Address | Function | Starting Address |  |  | No．of Points | Error Check（CRC16） |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | High | Low | High | Low | Low | High |
| 11 H | 01 H | 03 H | E8H | 00 H | 01 H | \＃\＃H |  |

## －Response（slave）

| Slave Address | Function +80 H | Exception Code | Error Check（CRC16） |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  | High |  |
|  | 81 H | 02 H | \＃\＃H | \＃\＃H |

## Read and Write of Parameter Value Using Communication

## © Read of the parameter area

000002 （OUT2）， 000003 （OUT1）， 000004 （BA，0）， 100001 to 100005 （terminal input），
300101 to 300125 （product information）， 301001 to 301013 （Monitoring data）

## © Read and write of the parameter area

000001 （reset starts）， 000005 （BATCH reset starts）， 400001 to 400006 （setting value saving group），
400051 to 400066 （counter setting group）， 400101 to 400110 （timer setting group），
400151 to 400156 （communication setting group）

## （O）Read of communication

Read parameter value using communication．（function：01H，02H，03H，04H）
It is able to read communication regardless of permitting／prohibiting communication writing．

## © Communication write

Change parameter value using communication．（function： $05 \mathrm{H}, 06 \mathrm{H}, 10 \mathrm{H}$ ）
－When changing the parameter setting value of＇回 Function setting mode Counter group＇or＇■ Function setting mode Timer group＇using communication，reset indication will flash in 3 sec and display value will be reset．（counting display value and progress time before changing parameter setting value are not saved．）
－When changing the parameter setting value of＇■ Preset value setting group＇or＇■ Function setting mode Communication group＇using communication，counting display value or progress time will not be reset．
－In prohibit writing communication setting（ $[\square \bar{n}, \underline{u}=1: d i 5 R$ ），a write command does not process．
－If setting value beyond the setting range，this setting value is substituted for the value within the setting range and then memorized．

## Programmable Counter／Timer

Factory Default

| － | Parameter | Factory default |
| :---: | :---: | :---: |
| Counter | in | Ud－［ |
|  | －ᄂUt．ก̄ | F |
|  | dSP．${ }^{\text {® }}$ | tothi |
|  | ［P5 | 30 |
|  | －Uヒ2（ロUt．t） | Hold（fixed） |
|  | 㖋 1 | 00.10 |
|  | $d^{\prime}$ | －－－－－－ |
|  | r5t | 20 |
|  | 51. | $n \mathrm{Pn}$ |
|  | 5 L．dP | 6－digit type：－．－－－－－ |
|  | 5［L | 6－digit type： 1.00000 4－digit type： 1.000 |
|  | 5trt | 000000 |
|  | dAtA | ［Lr |
| Timer | Hourlni n／5E［ | 6－digit type： $0.00 \mathrm{Is}-999.999 \mathrm{~s}$ <br> 4－digit type： 0.00 is－9．999s |
|  | U－d | UP |
|  | d5P．п | tothi |
|  | d月ta | ［Lr |
|  | －Uと．п̄ | and |
|  | －UL2（oUt．t） | Hold |
|  | 㖋 1 | 00.10 |
|  | 51. | $n \mathrm{P}$ |
|  | 1 n．t | 20 |
| General | LoLt | L．oFF |
|  | PS1 | 1000 |
|  | PS2 | 5000 |
| Comm． | Addr | 001 |
|  | bP5 | 96 |
|  | Prty | nonE |
|  | 5tP | 2 |
|  | －5枵 | 20 |
|  | ［0ํ．． | EnA |

## $\square$ Cautions during Use

1．Follow instructions in＇Cautions during Use＇． Otherwise，it may cause unexpected accidents．
2．24－48VDC，24VAC power supply should be insulated and limited voltage／current or Class 2，SELV power supply device．
3．Use the product， 0.1 sec after supplying power．
4．When supplying or turning off the power，use a switch or etc．to avoid chattering．
5．Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power．
6．In case of contact input，set count speed to low speed mode（1cps or 30cps）to operate．
If set to high speed mode（ $1 \mathrm{k}, 5 \mathrm{k}, 10 \mathrm{kcps}$ ），counting error occurs due to chattering．
7．Keep away from high voltage lines or power lines to prevent inductive noise．
In case installing power line and input signal line closely， use line filter or varistor at power line and shielded wire at input signal line．
Do not use near the equipment which generates strong magnetic force or high frequency noise．
8．This product may be used in the following environments． （1）Indoors（in the environment condition rated in
＇Specifications＇）
（2）Altitude max． $2,000 \mathrm{~m}$
（3）Pollution degree 2
（4）Installation category II


[^0]:    ※It is recommended to use Autonics communication converter; SCM-WF48 (Wi-Fi to RS485-USB wireless communication converter, sold

[^1]:    ※When error occurs, the output turns OFF.
    ※When 1st setting value is set as 0 (zero), OUT1 maintains OFF
    When 2nd setting value is smaller than 1st setting value, 1st setting value is ignored and only OUT2 output operates. ※Indicator model does not have error display function.

[^2]:    ※Power Reset: There is no memory protection. (Initializes the display value when power is off)
    Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

[^3]:    ※Power Reset: There is no memory protection. (Initializes the display value when power is off)
    Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

