DIN W48×H48mm, W72×H36mm, W72×H72mm Counter/Timer

Features

• Communication function supported (communication model): RS485 (Modbus RTU)

4-digit model: 0.001 to 999.9

One-shot output time setting range - 0.01 sec to 99.99 sec by setting per 10ms

•[Counter]

Prescale value setting range – 6-digit model: 0.00001 to 99999.9 /

9 input modes/11 output modes

BATCH counter,

Count Start Point (counting initial value) setting function

•[Timer]

13 output modes

Various time setting range— 6-digit model: 0.001 sec to 99999.9 hour / 4-digit model: 0.001 sec to 9999 hour '0' time setting function

Selectable timer memory retention function for indicator model.

Please read "Safety Considerations" in operation manual before using.



DAQMaster (Comprehensive Device Management Program)

- DAQMaster is comprehensive device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and comprehensive device management program.

| Item | Minimum requirements |
|------------|--|
| System | IBM PC compatible computer with Intel Pentium III or above |
| Operations | Microsoft Windows 98/NT/XP/Vista/7/8/10 |
| Memory | 256MB+ |
| Hard disk | 1GB+ of available hard disk space |
| VGA | Resolution: 1024×768 or higher |
| Others | RS-232 serial port (9-pin), USB port |

< DAQMaster screen >

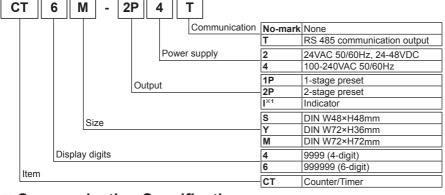
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Ordering Information



X1: CT4S model does not support indicatior type.

■ Communication Specification

| Connection type RS485 Application standard Compliance with EIA RS485 Max. connection 31 units (address: 1 to 127) Synchronous method Asynchronous Comm. type Two-wire half duplex Comm. distance Max. 800 m Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | | The H. Diff. W. 40 LY ODG |
|---|----------------------|---|
| Application standard Compliance with EIA RS485 Max. connection 31 units (address: 1 to 127) Synchronous method Asynchronous Comm. type Two-wire half duplex Comm. distance Max. 800 m Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Comm. protocol | Modbus RTU with 16-bit CRC |
| Max. connection 31 units (address: 1 to 127) Synchronous method Asynchronous Comm. type Two-wire half duplex Comm. distance Max. 800 m Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Connection type | RS485 |
| Synchronous method Asynchronous Comm. type Two-wire half duplex Comm. distance Max. 800 m Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Application standard | Compliance with EIA RS485 |
| Comm. type Two-wire half duplex Comm. distance Max. 800 m Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Max. connection | 31 units (address: 1 to 127) |
| Comm. distance Max. 800 m Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Synchronous method | Asynchronous |
| Comm. speed 2400, 4800, 9600 (factory default), 19200, 38400bps Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Comm. type | Two-wire half duplex |
| Comm. response time 5 to 99ms (factory default: 20ms) Start bit 1-bit (fixed) | Comm. distance | Max. 800 m |
| Start bit 1-bit (fixed) | Comm. speed | 2400, 4800, 9600 (factory default), 19200, 38400bps |
| | Comm. response time | 5 to 99ms (factory default: 20ms) |
| Data bit 8-bit (fixed) | Start bit | 1-bit (fixed) |
| | Data bit | 8-bit (fixed) |
| Parity bit None (factory default), Even, Odd | Parity bit | None (factory default), Even, Odd |
| Stop bit 1, 2-bit (factory default: 2-bit) | Stop bit | 1, 2-bit (factory default: 2-bit) |

Specifications

| Seri | es | | | | CTS | | CTY | | СТМ | |
|--|--|--|--|---|---|---|--|--|---|--|
| | | 1-stag | ge prese | et | CT4S-1P□□ | CT6S-1P□□ | CT6Y-1P□□ | | CT6M-1P□□ | |
| Mod | Model 2-stage preset | | et | CT4S-2P□□ | CT6S-2P□□ | CT6Y-2P□□ | | CT6M-2P□□ | | |
| Indicator | | | CT6S-I□□ | CT6Y-I□□ | | СТ6М-І□□ | | | | |
| Display digits | | 4-digit | 6-digit | 6-digit | | 6-digit | | | | |
| Disp | lay m | ethod | | | 7 segment (cou | nting value: red, | setting value: yel | low-green) LED | method | |
| Cha | racter | r | Countin | g value | 6.5×10mm | 4.5×10mm | 4.2×9.5mm | | 6.6×13mm | |
| size | (W×H | 1) 5 | Setting | value | 4.5×8mm | 3.5×7mm | 3.5×7mm | | 5×9mm | |
| _ | | . / | AC volta | age | 100-240VAC~ | 50/60Hz | , | | • | |
| Pow | er su | pply | AC/DC | voltage | 24VAC~ 50/60 | Hz, 24-48VDC= | : | | | , |
| Perr | nissib | le volta | ige rand | ne | 90 to 110% of ra | ated voltage | | | | |
| Pow | | | AC volta | | Max. 12VA | | | | | |
| | sumpt | _ <u>_</u> | | voltage | AC: Max. 10VA | . DC: Max. 8W | | | | |
| | | INA/IN | | | | , | | | | |
| | | Max. co | | speed | Selectable 1cps | s/30cps/1kcps/5k | cps/10kcps | | | |
| _ | | Countin | ng rang | е | -999 to 9999 | -99999 to 9999 | 999 | | | |
| Cou | nter | Scale | | | Decimal point up to third digit | Decimal point u | up to fifth digit | | | |
| | | Min. in | put sigr | nal width | RESET: Selecta | able 1ms/20ms | , | | | |
| | | <u> </u> | | -digit | | | 9m59s, 999.9m, | 9999m, 99h59m. | 9999h | |
| | | Time ra | ange 6 | -digit | , | .99s, 99999.9s, 9 99h59m, 99999.9 | , | 9s, 999m59.9s, 9 | 9999m59s, 99999. | 9m, 999999m, |
| | | Operat | ion me | thod | Count up, Coun | t down, Count Up | o/Down | | | |
| Time | er | Min. in | put sigr | nal width | INA, INH, RESE | ET: Selectable 1r | ns/20ms | | INA, RESET, IN RESET: Selecta | |
| | | Repeat | t error | | | | | | | |
| | | Set err | or | | In case of powe | er ON start: Max. | ±0.01% ±0.05s | | | |
| | | Voltage error | | In case of power ON start: Max. ±0.01% ±0.05s In case of signal start: Max. ±0.01% ±0.03s | | | | | | |
| | | vollage | e error | | In case of signa | ıl start: Max. ±0.0 | 01% ±0.03s | | | |
| | | Temp. | | | | | | | | |
| | t metl | Temp. | error | | Selectable volta [Voltage input]- [No-voltage inp | age input or no-v input impedance ut]-short-circuit i | oltage input : 5.4kΩ, [H]: 5-30 | | /DC t residual voltage | : Max. 2VDC= |
| | | Temp. | error | | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s | age input or no-vinput impedance ut]-short-circuit i setting | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. | 1kΩ, short-circu | t residual voltage | |
| | | Temp. | error | 1 store | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard | age input or no-v input impedance ut]-short-circuit i | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard | | t residual voltage Standard | : Max. 2VDC= |
| | | Temp. | time | 1-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s | age input or no-vinput impedance ut]-short-circuit i setting | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 | 1kΩ, short-circu | t residual voltage | |
| One | -shot | Temp. | error | 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard | age input or no-vinput impedance ut]-short-circuit i setting | oltage input : 5.4kΩ, [H]: 5-3(mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, | 1kΩ, short-circu | t residual voltage Standard | Comm. |
| One | -shot | Temp. | time | 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 | age input or no-vinput impedance ut]-short-circuit i setting Comm. | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, | 1kΩ, short-circu Comm. SPST(1a): 2 | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, | Comm. PDT(1c): 1 |
| One | -shot Conta | Temp. hod output | time Type | 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 | age input or no-vinput impedance ut]-short-circuit i setting Comm. | oltage input : 5.4kΩ, [H]: 5-3(mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load | Comm. PDT(1c): 1 |
| ontrol output | -shot Conta | Temp. hod output | time Type | 2-stage ity | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 | age input or no-vinput impedance ut]-short-circuit i setting Comm. | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, | 1kΩ, short-circu Comm. SPST(1a): 2 | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 | Comm. PDT(1c): 1 |
| Control output | -shot Conta | Temp. hod output act ut state ut open | time Type Capaci | 2-stage ity 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load | age input or no-vinput impedance ut]-short-circuit i setting Comm. | oltage input : 5.4kΩ, [H]: 5-3(mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load | Comm. PDT(1c): 1 30VDC== 5A |
| Control output | -shot Conta | nect state it open ctor) | time Type Capaci Type Capaci | 2-stage ity 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=-, | age input or no-vinput impedance ut]-short-circuit i setting Comm. | oltage input : 5.4kΩ, [H]: 5-3(mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 | Comm. PDT(1c): 1 30VDC== 5A |
| Control output | Solid output (NPN collecternal p | note that the state of the stat | time Type Capaci Type Capaci upply | 2-stage ity 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=, Max. 12VDC= | age input or no-vinput impedance ut]-short-circuit i setting Comm. | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 | Comm. PDT(1c): 1 30VDC== 5A |
| One Courtol output | Solid outpu (NPN collections) | state ut l open ctor) cower s etention | time Type Capaci Type Capaci upply | 2-stage ity 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=, Max. 12VDC= Approx. 10 year | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC== 5A 100mA ±10%, 100mA | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 | Comm. PDT(1c): 1 30VDC== 5A |
| One Control ontbut | Solid output (NPN collecternal processing pr | state ut l open ctor) cower s etention resista | time Type Capaci Type Capaci upply | 2-stage ity 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=, Max. 12VDC= Approx. 10 year Over 100MΩ (a | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC== 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC megger | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 | Comm. PDT(1c): 1 30VDC== 5A |
| One Control ontbut Men Insul | Solid outpu (NPN collectrical phory relation ectric | state ut l open ctor) cower s etention resista strengt | time Type Capaci Type Capaci upply | 2-stage ity 1-stage 2-stage | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=, Max. 12VDC= Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC== 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC meggo | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 | Comm. PDT(1c): 1 30VDC== 5A |
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| One Court on that on the Court | Conta output Solid output (NPN) Financy r nory r lation ectric se imn | state ut open ctor) cower s etention resista strengt munity | time Type Capaci Type Capaci upply n nce h | 2-stage ty 1-stage 2-stage ty iical | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC== 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC meggo OHz for 1 min oise by noise simulde at frequency 1 de at frequency 1 | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) nulator (pulse wid 10 to 55Hz (for 1 0 to 55Hz (for 1 | 1kΩ, short-circui Comm. SPST(1a): 2 30VDC= 3A 1 th 1μs) ±2kV min) in each X, Y, min) in each X, Y, | standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
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| One Courtol onthat Men Insu Diel | -shot Contactoric | state it open ctor) Dower s etentior resista strengt nunity | time Type Capaci Type Capaci upply n nce ih Mechan Malfunc Mechan Malfunc | 2-stage ty 1-stage 2-stage ty ical tion ical tion | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud 300m/s² (approx) | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC meggo 0Hz for 1 min oise by noise simude at frequency 1 x. 30G) in each 2 x. 10G) in each 2 | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) nulator (pulse wid 10 to 55Hz (for 1 0 to 55Hz (for 1 | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 — th 1μs) ±2kV min) in each X, Y, y, or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
| One Courtor Ontrol Ont | Solid output Solid output Solid output Solid output Innory relation ectric se imn ation | state ut open ctor) Dower s etention resista strengt nunity | time Type Capaci Type Capaci upply n nce h Mechan Malfunc Mechan Malfunc Mechan | 2-stage ty 1-stage 2-stage ty iical tion iical tion iical | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud 300m/s² (approximent) Min. 10,000,000 | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC meggo OHz for 1 min oise by noise simude at frequency 1 x. 30G) in each 2 x. 10G) in each 20 operations | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) nulator (pulse wid 10 to 55Hz (for 1 0 to 55Hz (for 1 K, Y, Z direction for | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 — th 1μs) ±2kV min) in each X, Y, y, or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
| One thousand the state of the s | -shot Contact output Solid output (NPN collect ernal proory r lation ectric e imn ation ck | state act open ctor) Dower s etention resista strengt nunity N Cycle | time Type Capaci Type Capaci upply n nce h Mechan Malfunc Mechan Malfunc Mechan Malfunc Mechan Malfunc | 2-stage ty 1-stage 2-stage ty iical tion iical tion iical | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud 300m/s² (approximate) 100m/s² (approximate) Min. 10,000,000 Min. 100,000 op | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m the 500VDC meggood of the for 1 min oise by noise simulate at frequency 1 x. 30G) in each 2 x. 10G) in each 2 to operations perations | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) nulator (pulse wid 10 to 55Hz (for 1 0 to 55Hz (for 1 K, Y, Z direction for | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 — th 1μs) ±2kV min) in each X, Y, y, or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
| One thousand the state of the s | -shot Contact output Solid output (NPN collect ernal proory r lation ectric e imn ation ck | state act open ctor) Dower s etention resista strengt nunity Cycle n structure | time Type Capaci Type Capaci upply n nce th Mechan Malfunc Mechan Malfunc Mechan Malfunc Mechan Malfunc | 2-stage ty 1-stage 2-stage ty ical tion ical tion ical tion | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load -1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave ni 0.75mm amplitud 300m/s² (approximate) 100m/s² (approximate) Min. 10,000,000 Min. 100,000 op IP65 (front part) | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m to 500VDC meggo OHz for 1 minoise by noise simulate at frequency 1 x. 30G) in each 2 x. 10G) in each 2 to operations perations, IEC standard) | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) nulator (pulse wid 10 to 55Hz (for 1 0 to 55Hz (for 1 0, Y, Z direction for | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 — th 1μs) ±2kV min) in each X, Y, y, or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
| One Indino loutuo O Exter Men Insu Diele Noise Vibr Sho Relæ | -shot Contact output Solid output (NPN collect ernal proory r lation ectric e imn ation ck | state act att appendix strengt nunity Cycle n structurental feet and appendix appen | time Type Capaci Type Capaci upply nnce th Mechan Malfunc Mechan Malfunc Mechan Malfunc Mechan Malfunc | 2-stage ty 1-stage 2-stage ty ical tion ical tion ical tion | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load 1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud 300m/s² (appro 100m/s² (appro Min. 10,000,000 Min. 100,000 op IP65 (front part -10 to 55°C, store | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC meggrodhz for 1 min oise by noise simule at frequency 1 x. 30G) in each 2 x. 10G) in each 2 to operations operations perations perations peraticular impedance in each 2 to 65°C | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) mulator (pulse wid 10 to 55Hz (for 1) 0 to 55Hz (for 1) 0, Y, Z direction for | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 — th 1μs) ±2kV min) in each X, Y, y, or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
| One tndtno loutuoo Extee Men Insu Diele Noise Vibr Prot Envi | -shot Contact output Solid output (NPN collect ernal proper relation ectric ee imn ation ck ection ronmer | state act att appendix strengt nunity Cycle n structurental feet and appendix appen | time Type Capaci Type Capaci upply n nce th Mechan Malfunc Mechan Malfunc Mechan Malfunc Mechan Malfunc | 2-stage ty 1-stage 2-stage ty ical tion ical tion ical tion | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load 1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud 300m/s² (appro 100m/s² (appro Min. 10,000,000 Min. 100,000 op IP65 (front part -10 to 55°C, stot 35 to 85%RH, s | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m to 500VDC meggo OHz for 1 minoise by noise simulate at frequency 1 x. 30G) in each 2 x. 10G) in each 2 to operations perations, IEC standard) | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) mulator (pulse wid 10 to 55Hz (for 1) 0 to 55Hz (for 1) 0, Y, Z direction for | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 — th 1μs) ±2kV min) in each X, Y, y, or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 |
| One Dielectric Sho Relaction Prot App | Solid output Solid | state act att appendix strengt nunity Cycle n structurental feet and appendix appen | time Type Capaci Type Capaci upply nnce th Mechan Malfunc Mechan Malfunc Mechan Malfunc Mechan Malfunc | 2-stage ty 1-stage 2-stage ty ical tion ical tion ical tion | Selectable volta [Voltage input]- [No-voltage inp 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC~ 5A, 3 resistive load 1 Max. 30VDC=- Approx. 10 year Over 100MΩ (a 2,000VAC 50/6 Square-wave no 0.75mm amplitud 300m/s² (appro 100m/s² (appro Min. 10,000,000 Min. 100,000 op IP65 (front part -10 to 55°C, store | age input or no-vinput impedance ut]-short-circuit i setting Comm. 30VDC= 5A 100mA ±10%, 100mA rs (non-volatile m t 500VDC meggrodhz for 1 min oise by noise simule at frequency 1 x. 30G) in each 2 x. 10G) in each 2 to operations perations perations perations perations; 1EC standard) rage: -25 to 65°C storage: 35 to 85°C storage: 35 to 85°C | oltage input : 5.4kΩ, [H]: 5-30 mpedance: Max. Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC~ 3A, resistive load 1 nemory) er) mulator (pulse wid 10 to 55Hz (for 1) 0 to 55Hz (for 1) 0, Y, Z direction for | 1kΩ, short-circu Comm. SPST(1a): 2 30VDC= 3A 1 th 1μs) ±2kV min) in each X, Y, yor 3 times or 3 times | Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC~ 5A, resistive load 2 3 | Comm. PDT(1c): 1 30VDC== 5A -2 hour minutes |

Autonics J-9

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature

(I) SSRs / Power Controllers

> (J) Counters

> > K) imers

.) anel leters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

> O) ensor ontrollers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

> S) letwork levices

Software

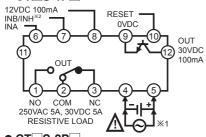
XEnvironment resistance is rated at no freezing or condensation.

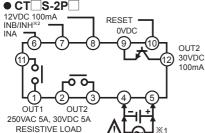
CT Series

Connections

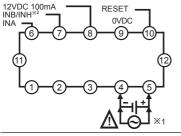
CTS Series

● CT S-1P



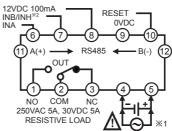


● CT6S-I

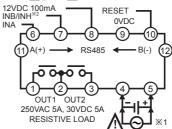


Be sure that connection is varied by supporting RS485 communication.

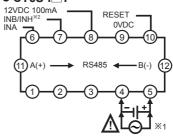
● CT S-1P T



● CT S-2P T

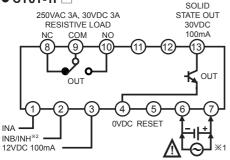


● CT6S-I□T

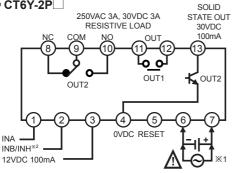


CTY Series

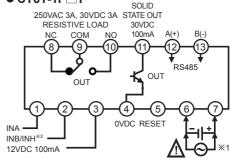
● CT6Y-1P



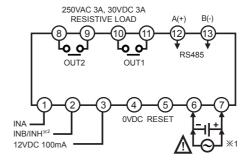
● CT6Y-2P

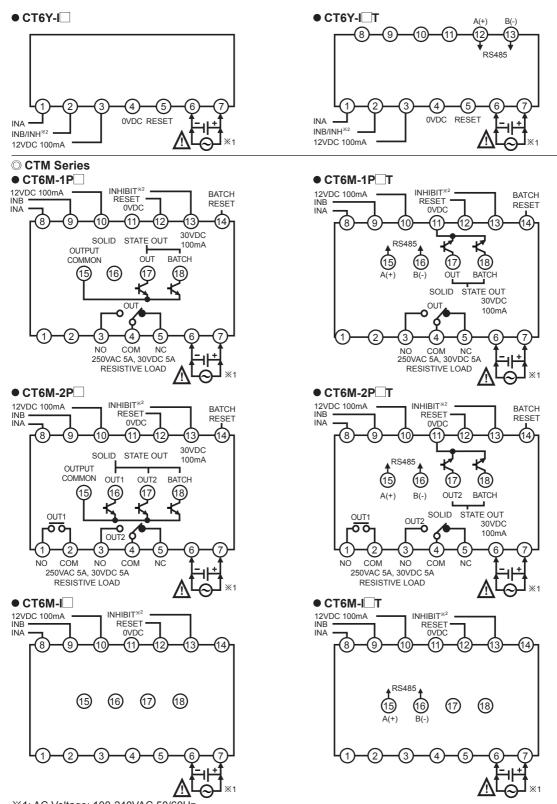


● CT6Y-1P



● CT6Y-2P□T





(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure

36113013

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K)

L)

(M) Tacho /

(N) Display Units

> O) Sensor

(P) Switching Mode Power Supplies

(Q) Stepper Motors

(R) Graphic/ Logic Panels

Panels (S)

Field Network Devices

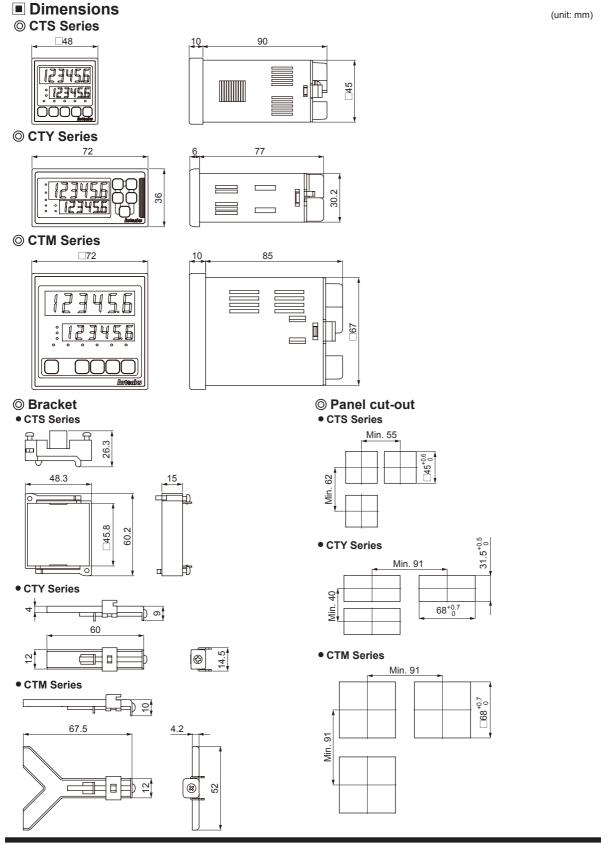
> T) Software

X1: AC Voltage: 100-240VAC 50/60Hz

AC/DC Voltage: 24VAC 50/60Hz, 24-48VDC

※2: Counter operation: If INHIBIT signal is applied, count input will be prohibited. Timer operation: If INHIBIT signal is applied, time progressing will stop. (HOLD)

CT Series



J-12

Sold Separately

© Communication converter

SCM-WF48

(Wi-Fi to RS485-USB wireless communication converter)



 SCM-US48I (USB to RS485 converter)

C€ [©

 SCM-38I (RS232C to RS485 converter)

(€ 🖫





O Display Units (DS/DA-T Series)

DS/DA-T Series

(RS485 communication input type display unit) C€









DS16-□T

DS22/DA22-_T

DS40/DA40-UT

DS60/DA60-UT

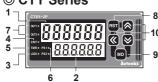
*Connect RS485 communication input type display unit (DS/DA-T Series) and RS485 communication output model of CT Series. the display unit displays present value of the device without PC/PLC

Unit Description

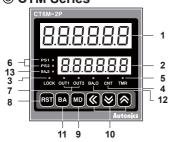
CTS Series



© CTY Series



O CTM Series



| Model | Changed | Notice |
|---------|----------|--|
| CT4S-1P | | |
| CT6S-1P | PS2→PS | There are no |
| CT6Y-1P | OUT2→OUT | PS1, OUT1 LEDs. |
| CT6M-1P | | |
| CT6S-I | | There are no PS1, OUT1, OUT2 LEDS. |
| CT6Y-I | PS2→PS | There are no PS1, OUT1, OUT2, |
| CT6M-I | | BA.S, BA.O LEDs, BA key. |

1. Counting value display component (red)

RUN mode: Displays counting value for counter operation or time progress value for timer operation

Function setting mode: Displays setting item.

2. Setting value display component (yellow-green)

RUN mode: Displays setting value.

Function setting mode: Displays setting content.

- 3. Key lock indicator (LOCK): Turns ON for key lock setting.
- 4. Counter indicator (CNT): Turns ON for counter operation.
- 5. Timer indicator (TMR): Flashes (progressing time) or Turns ON (stoping time) for timer

6. Preset value checking and changing indicator (PS1, PS2)

: Turns ON when checking and changing preset value.

7. Output indicator (OUT1, OUT2): Turns ON for the dedicated control output ON.

8. RST key

RUN mode: Press the RST key to reset the counting value.

BATCH counter mode: Press the RST key to reset the batch counting value.

9. MD key

RUN mode: Hold the MD key over 3 sec to enter function setting mode(parameter setting). Hold the MD key over 5 sec to enter function setting mode (communication

Function setting mode: Press the [MD] key to select function setting mode parameter. Hold the MD key over 3 sec to return RUN mode.

10. **(**€, **≥**, **key**

1) < key

RUN mode: Press the key to enter preset mode.

Preset mode: Press the key to move preset digits.

2) ⊌. kev

RUN mode: Hold the key over 1 sec to enter Function setting check mode.

Preset mode: Used for increasing or decreasing preset value.

Function setting mode: Changes the settings.

Function setting check mode: Press the

key to move the previous parameter. Press the key to the next parameter.

11. BA key

RUN mode: Press the RST key to enter BATCH counter indication mode.

12. BATCH output indicator (BA.O) (red)

13. BATCH preset value checking and changing indicator (BA.S) (yellow-green)

: Turns ON when checking and changing BATCH preset value.

XThe indicator type does not exist in CT4S model.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(F) Rotary Encode

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Power Controllers

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

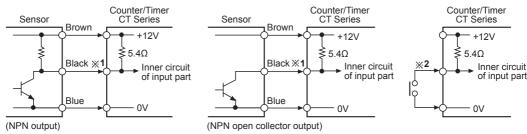
(R) Graphic/ Logic Panels

J-13 **Autonics**

Input Connections

Solid-state input (standard sensor: NPN output type sensor)

Contact input



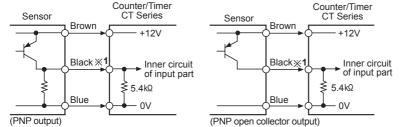
X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

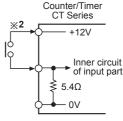
X2: Counting speed: 1 or 30cps setting (counter)

O Voltage input (PNP)

Solid-state input (standard sensor: PNP output type sensor)

Contact input

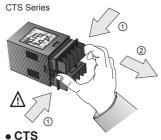




X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

X2: Counting speed: 1 or 30cps setting (counter)

Input Logic Selection [No-Voltage Input (NPN)/Voltage Input (PNP)]



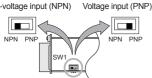
- 1. The power must be cut off.
- 2. Squeeze toward ① and pull toward ② as the figure. (CTS/CTY Series)
- 3. Select input logic by using input logic switch (SW1) inside Counter/Timer.
- 4. Push a case in the opposite direction of ②.
- 5. Then supply the power to counter/timer.

Turn OFF the power before changing input logic (PNP/NPN)



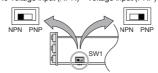
Voltage input (PNP) No-Voltage input (NPN) PNP NPN NPN SW1





CTY

No-voltage input (NPN) Voltage input (PNP)



Power OFF → change settings → power ON → press RST key or input signal (min. 20ms)

Error Display and Output Operation

| Error Display | Error description | Troubleshooting |
|---------------|---------------------|--|
| ErrO | Setting value is 0. | Change the setting value anything but 0. |

*When error occurs, the output turns OFF.

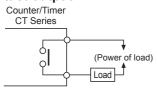
*When 1st setting value is set as 0 (zero), OUT1 maintains OFF.

When 2nd setting value is smaller than 1st setting value, 1st setting value is ignored and only OUT2 output operates. XIndicator model does not have error display function.

J-14 Autonics

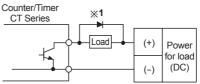
Output Connections

© Contact output



XUse proper load not to exceed the capacity.

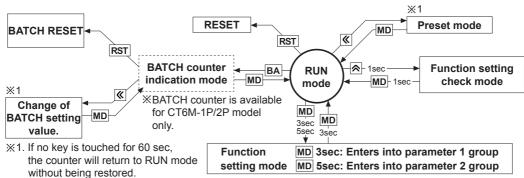
O Solid-state output



XBe sure not to apply reverse polarity of power.

X1: When using inductive load (relay etc.), surge absorber (diode, varistor etc.) must be connected between both sides of the load.

Operations and Functions



O Change of preset (counter/timer)

• Even if changing the preset value, input operation and output control will continue. In addition, the preset value could be set to 0 and the output of 0 preset value turns ON. According to output mode, preset value could not be set to 0. (When setting to 0, preset value "0" will flash 3 times.)



In RUN mode, press the key to enter preset mode.
'PS1' indicator turns ON and first digit of preset value flashes.



Press the <a> , <a> and <a> keys to set the desired value (example, 180). Press the <a> MD key to enter the PS2 setting mode.



Press the <a> , <a> and <a> keys to set the desired value (example, 200). Press the <a> MD key to return RUN mode.

Function setting check mode

Setting value of function setting mode can be confirmed using the ⋈ and ⋈ keys.

Switching display function in preset indicator

Setting value1 (PS1) and setting value2 (PS2) are displayed each time pressing MD key in PRESET2 model. (in timer, it is available for pnd, pnd, or pnd, output mode.)

Reset

In RUN mode or function setting mode, if pressing RST key or applying the signal to the RESET terminal on the back side, present value will be reset and output will maintain off status. When selecting voltage input (PNP), short no. 10 and no. 12 terminals, or when selecting no-voltage input (NPN), short no.11 and no.12 terminals to reset.

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

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(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

> K) imers

Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

Field Network Devices

(T) Software

■ BATCH Counter (for CT6M-1P□□ /CT6M-2P□□ Model Only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

Ochange of BATCH setting value

If pressing **BA** key in Run mode, it will enter into BATCH counter indication mode.

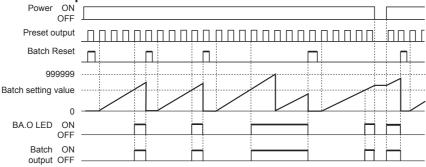


It enters into settingvalue change mode using <a> key. (BA.S lights, first digit of setting value flashes.)



BATCH value is set to '200' using , and w keys, then press MD key to complete BATCH setting value and move to BATCH counter indication mode.

© BATCH counter operation



BATCH counting operation

- BATCH counting value is increasing until BATCH reset signal applied. BATCH counting value will be circulated when it is over 999999.

 1) BATCH counting operation in Counter: Counts the number of reaching setting value of CT6M-1P or reaching dual setting value of CT6M-2P
 - 2) BATCH counting operation in Timer: Counts the number of reaching setting time. (In case of "FL "" output mode, count the number of reaching T.off setting time and T.on setting time.)

◎ BATCH output

- If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- When the power is cut off then resupplied in status of BATCH output is ON, BATCH output maintains ON status until BATCH reset signal is applied.

BATCH reset input

- If pressing RST key or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset. When selecting voltage input (PNP), short terminals 10 and 14, or when selecting no-voltage input (NPN), short terminals 11 and 14 to reset.
- When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.

Application of BATCH counter function

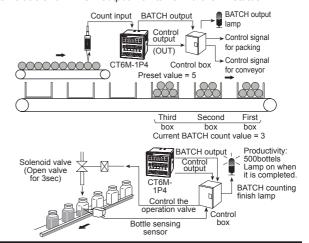
Counter

In case, put 5 products in a box then pack the boxes when they reaches to 200.

Counter preset setting value="5", BATCH setting value="200"
 When the count value of counter reaches to the preset value "5", the control output (OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to "200", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for packing.

Timer

Fills milk into the bottle for 3sec (setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on. (Setting time: 3sec, BATCH setting value: 500)



(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Power Controllers

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

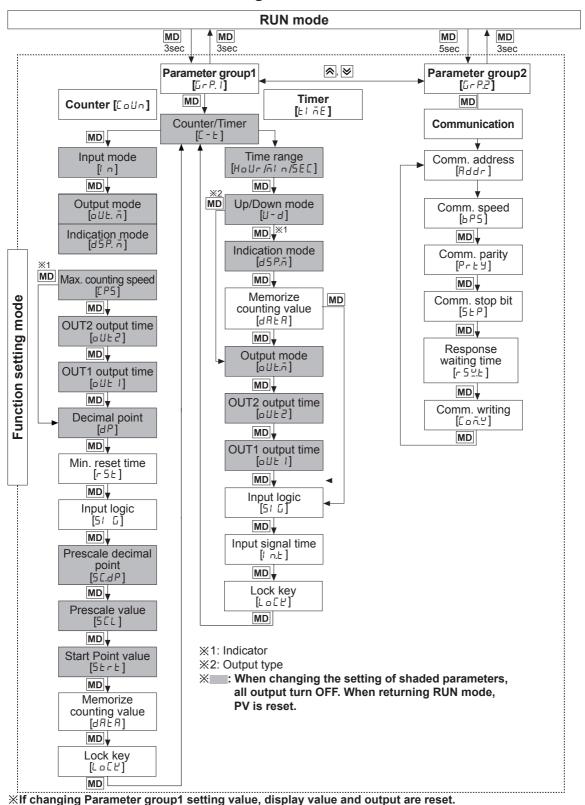
(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers

(R) Graphic/ Logic Panels

■ Flow Chart for Function Setting Mode



XParameter 2 group is not available to non-communication models.

J-17 Autonics

■ Parameter Setting (Counter)

(MD key: Moves the settings, ⋈, key: Changes the settings)

| Parameter | Setting |
|---|--|
| Counter/ Timer [[- +] | EoUn ← ► EI ĀE *Counter EI ĀE: Timer |
| Input mode | Ud-C ←→ UP ←→ UP- 1 ←→ UP- 2 ←→ dn ←→ dn- 1 ←→ dn- 2 ←→ Ud-R ←→ Ud-b |
| Output mode | • Input mode is UP, UP-1, UP-2 ordn, dn-1, dn-2, F → → n → ► C → ► C → ► C → ► P → ► P → ► P • Input mode is UP, UP-1, UP-2 ordn, dn-1, dn-2, F → → n → ► C → ► C → ► P → P → |
| | • Input mode is Ud-A, Ud-b, Ud-E, F←→ n ←→ E←→ r ←→ P ←→ P ←→ P ←→ B ←→ B ←→ B ←→ B ←→ B |
| | ※If max. counting speed is 5kcps or 10kcps, and output mode is d, max. counting speed is automatically changed as 30cps, factory default. |
| Indication mode [d5P.ā] | ■ In case of the indicator type ※In case of the indicator type, indicate mode selection [d5P.ā] is displayed. Hald → Falfil ※It is the added function to set the preset value when selecting Hald. |
| Max. counting speed [[P5] | **Max. counting speed is when duty ratio of INA or INB input signal is 1:1. ∃□ → Iピ → 5ピ → I□ ピ → I It is applied for INA, or INB input as same. **When output mode is d, set max. counting speed one among 1cps, 30cps, or 1kcps. |
| OUT2 output time*1 [allt?] | ※Set one-shot output time of OUT2. ※Setting range: 00.01 to 99.99sec ※When input mode is F, n, 5, Ł, d, ɒˈʊˈt-ʔ does not appear. (fixed as HOLD) |
| OUT1 output time*1 [oUt 1] | XSet one-shot output time of OUT1. XSetting range: 00.01 to 99.99sec, Hold. XWhen 1st digit is flashing, press the key once and H□L d appears. XWhen input mode is 5, Ł, d, □UŁ I does not appear. (fixed as HOLD) |
| OUT output time*1 | ※Setting range: 00.01 to 99.99sec ※When input mode is F, n, 5, E, d, o UEE does not appear. (fixed as HOLD) |
| Decimal point ^{≪2} [dP] | • 6-digit type |
| Min. reset time [-5] | ! ←→ 2 □, unit: ms |
| Input logic | nPn: No-voltage input, PnP: Voltage input |
| Prescale decimal | • 6-digit type |
| point ^{*2} [5 <i>C.dP</i>] | ◆ 4-digit type **Decimal point of prescale should not set smaller than decimal point [dP]. |
| Prescale value [5 [L] | XSetting range of prescale value 6-digit type: 0.00001 to 99999.9, 4-digit type: 0.001 to 999.9 |
| Start point value [5 + r +] | ※Setting range (linked with decimal point [dP]): 6-digit type: 0.00001 to 999999, 4-digit type: 0.001 to 9999 ※When input mode is do, do - 1, do - 2, start point value does not appear. |
| Memory protection [日日上日] | |
| Key lock | Loff ← → Lof. 1 |

X1: For PRESET1 model, □UE I does not appear. The output time of □UE2 is displayed as □UEE.

^{※2:} Decimal point and prescale decimal point

Decimal point: Set the decimal point for display value regardless of prescale value.

Prescale decimal point: Set the decimal point for prescale value of counting value regardless of decimal point of display value.

■ Input Operation Mode (Counter)

| Input mode | Counting chart | Operation |
|---------------------------|---|---|
| UP [UP] | INA H INB H No counting No counting No counting A A A A A A A A A A A A A A A A A A A | When INA is counting input, INB is no counting input. When INB is counting input, INA is no counting input. |
| UP-1 [UP- 1] | INA H INB H No counting 4 5 | ※When INA input signal is rising (♠), it counts. ※INA: Counting input ※INB: No counting input |
| UP-2 [UP-2] | INA H INB H No counting 2 Count 0 | ※When INA input signal is falling (¬L), it counts. ※INA: Counting input ※INB: No counting input |
| Down [dn] | INA H No counting INB H No counting n-2 n-3 n-4 n-5 n-6 n-7 | When INA is counting input, INB is no counting input. When INB is counting input, INA is no counting input. |
| Down-1 [dn - 1] | INA H INB H No counting 0 | |
| Down-2 [dn - ₽] | INA H INB H No counting O No counting 1 n-1 n-2 n-3 n-4 n-5 | |
| Up/ Down-A [Ud - A] | INA H INB H Count 1 2 3 4 3 2 1 2 3 4 | XINA: Counting input INB: Counting command input When INB is "L", counting command is up. When INB is "H", it is counting command is down. |

(A) Photoelectric Sensors (C) Door/Area Sensors (D) Proximity Sensors (G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets (I) SSRs / Power Controllers (M) Tacho / Speed / Pulse Meters (N) Display Units

> (P) Switching Mode Power Supplies

(R) Graphic/ Logic Panels

■ Input Operation Mode (Counter)

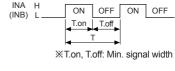
| Input mode | Counting chart | Operation |
|---------------------------|---|--|
| Up/ Down-B [IJd-b] | INA HINB HINB HINB HINB HINB HINB HINB HINB | ※INA: Up counting input INB: Down counting input ※When INA and INB input signals are rising (→) at the same time, it maintains previous counting value. |
| Up/ Down-C [Ud - [] | INA H BBBB INB H 2 3 2 1 2 3 Count 0 | *When connecting encoder output A, B phase with counter input, INA, INB, set input mode [i n.ñ] as phase different input [ud-[] for counter operation. |

- X1: For selectable no-voltage input (PNP), voltage input (NPN) model.
- «A: over min. signal width, B: over than 1/2 of min. signal width. If the signal is smaller than these width, it may cause counting error (±1).
- XThe meaning of "H", "L"

| Input method | Voltage input | No-voltage input |
|--------------|---------------|------------------|
| Character | (PNP) | (NPN) |
| Н | 5-30VDC | Short |
| L | 0-2VDC | Open |

※Min. signal width by counting speed

| Counting | Min. |
|----------|--------------|
| speed | signal width |
| 1cps | 500ms |
| 30cps | 16.7ms |
| 1kcps | 0.5ms |
| 5kcps | 0.1ms |
| 10kcps | 0.05ms |

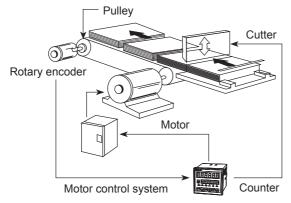


1cps=1Hz

Prescale Function (Counter)

This function is to set and display calculated unit for actual length, liquid, position, etc. It is called "prescale value" for measured length, liquid, or position, etc per 1 pulse. For example, when moving L, the desired length to be measured, and P, the number of pulses per 1 revolution of a rotary encoder, occurs, prescale value is L/P.

E.g.) Positioning control by counter and encoder



[Diameter (D) of pulley connected with encoder= 22mm, the number of pulses by 1 rotation of encoder=1,000]

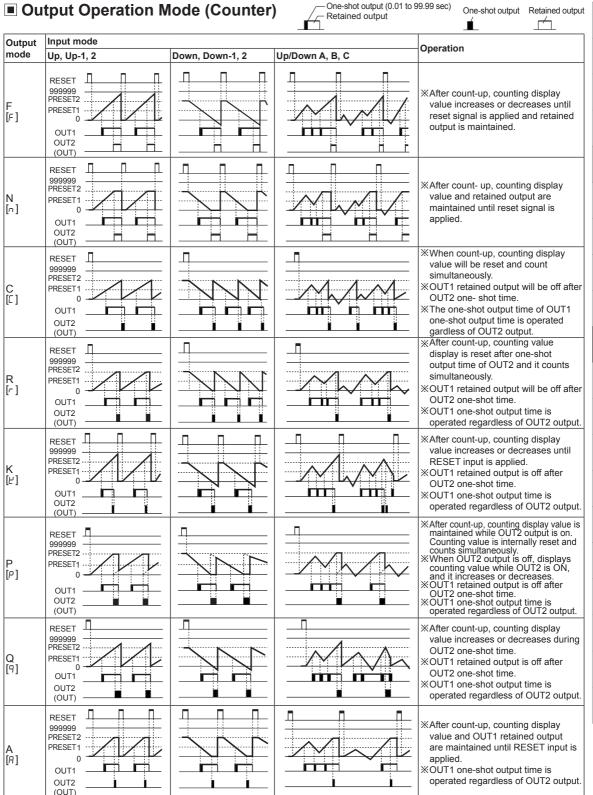
•Prescale value $= \frac{\pi \times \text{Diameter (D) of pulley}}{\text{The number of pulses by 1}}$ $= \frac{3.1416 \times 22}{1000}$ = 0.069 mm/pulse

Set decimal point[AP] as [-----], prescale decimal point [5LAP] as [-----], prescale value [5LL] as [0.069] at function setting mode. It is available to control conveyer position by 0.1mm unit.

Start Point Function (Counter)

This function is that start at initial value set at Start Point [5£ r £] when on counting mode.

- In case of dn, dn-1 or dn-2 in timer input mode, it is not available.
- When reset is applied, the present value is initialized to start point.
- In case of [, r, P, q output operation mode, the present value starts at START POINT value after counting up.



**The PRESET1 type output (OUT) is operated as OUT2 of PRESET2 type.

Autonics J-21

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure

(F)

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

> J) ounters

K)

_) anel

(M) Tacho / Speed / Pulse

(N) Display Units

nits O)

o) ensor ontrollers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network

Network Devices

(T) Software

^{*}OUT1 output could be set to 0 in all modes and 0 value output turns ON.

 $[\]times$ OUT2 output could not set to 0 in C[[], R[-], P[P] or Q[9] output mode.

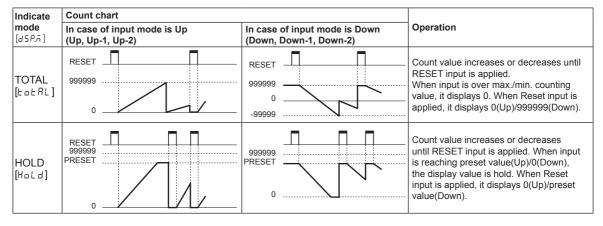
Retained output Coincidence output Output Operation Mode (Counter) Output mode Up/Down - A, B, C Operation RESET 999999 **XOUT1** and OUT2 keep ON status in PRESET2 S PRESET1 following condition: 0 Counting display value ≧ PRESET1 [5] -99999 Counting display value ≥ PRESET2 OUT1 OUT2 (OUT) П RESET 999999 **XOUT1** output is off: PRESET2 Counting display value ≥ PRESET1 PRESET1 **XOUT2** keeps ON status in following [Ŀ] -99999 condition: OUT1 Counting display value ≥ PRESET2 OUT2 (OUT) RESET XWhen counting display value is equal 999999 to setting value [PRESET1, PRESET2) PRESET2 only, OUT1 or OUT2 output keeps ON PRESET1 [6] When setting 1kcps for counting speed, -99999 solid state contact output should be OUT1

- **The PRESET1 type output (OUT) is operated as OUT2 of PRESET2 type.
- **The PRESET2 model OUT1 output is operated as one-shot or retained output. (except 5, b, d mode)
- XOUT1 output could be set to 0 in all modes and 0 value output turns ON.
- \times OUT2 output could not set to 0 in C[[,], R[,], P[,P]] or Q[,P]] output mode.

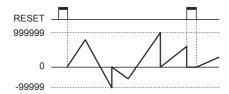
■ Counter Operation of the Indicator (CT6S-I, CT6Y-I, CT6M-I)

XOnly displays on indicator models

OUT2



• In case of the Command input [⊔⊿-月], Individual input [⊔⊿-Ь], Phase difference input [⊔⊿-Е] mode.



※In case of UP/DOWN [Ud-A, Ud-b, Ud-E] input mode, indication mode [d5P.n] of the configuration is not displayed.

used.

J-22 Autonics

■ Parameter Setting (Timer)

(MD key: Moves the settings, ⋈, key: Changes the settings)

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Power Controllers

(N) Display Units

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

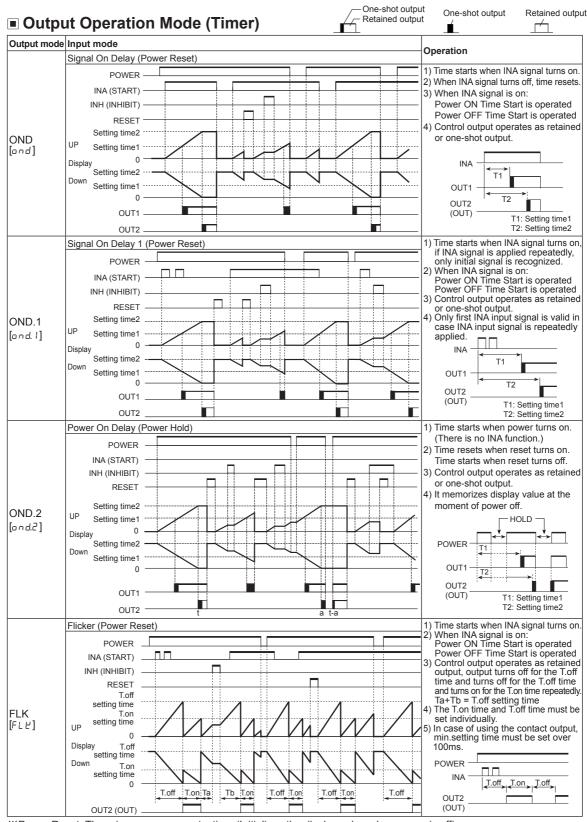
(R) Graphic/ Logic Panels

| Parameter | Setting | | | |
|-----------------------------|---|--|--|--|
| Counter/Timer | EpUn ← → Łi ōE | | | |
| [[C - E] | • 6-digit type | | | |
| | | | | |
| | 999999 | | | |
| | 0.001s to 0.01s to 0.1s to 0.01s to | | | |
| | 999.99s 9999.99s 999999s 99m59.99s | | | |
| | Hour 5 | | | |
| | 999999 999599 | | | |
| | 0.1h to 0.1s to | | | |
| | 99999.9h 999m59.9s | | | |
| T: | Hā HāS āin āin āS | | | |
| Time range [Holle/āl n/5E[] | 999959 995959 999999 999959 | | | |
| [1001 111 111 200] | 1m to 1s to 1m to 0.1m to 1s to | | | |
| | 9999h59m 99h59m59s 999999m 99999.9m 9999m59s • 4-digit type | | | |
| | SEC SEC SEC 5EC 5EC | | | |
| | 9.999 | | | |
| | 0.001s to 0.01s to 0.1s to 1s to | | | |
| | 9.999s 99.99s 9999s 99m59s | | | |
| | Hour Hā āin āin | | | |
| | 9999 9959 9999 999.9 | | | |
| | 1h to 1m to 0.1m to | | | |
| | 9999h 99h59m 9999m 999.9m **UP: Time progresses from '0' to the setting time. | | | |
| Up/Down mode [비-립] | UP ← → dn | | | |
| Indication mode | *Used for the indicator type only. *XI is added that the feature which set the setting | | | |
| [d5P.ñ] | time when selecting HoLd or on E.d | | | |
| Memory protection | *Used for the indicator type only. | | | |
| [4868] | ELr ← → rEE | | | |
| Output mode | and \rightarrow and $l \rightarrow$ and $l \rightarrow$ filt $l \rightarrow$ filt. $l \rightarrow$ filt. $l \rightarrow$ filt. | | | |
| [oUt.ā] | ↑ | | | |
| | VSet one shot subjutting of OUT? | | | |
| OUT2 output time | Set one-shot output time of OUT2. Setting range: 00.01 to 99.99sec, Hold. | | | |
| [oUE2]*1 | ※When 1st digit is flashing, press the « key once and H□L d appears. | | | |
| OUT1 output time | **Set one-shot output time of OUT1. | | | |
| [oUt 1]*1 | XSetting range: 00.01 to 99.99sec, Hold. XWhen 1st digit is flashing, press the ⟨⟨ key once and HoLd appears. Appears Appears | | | |
| OUT output time | *Setting range: 00.01 to 99.99sec, Hold. | | | |
| [oUt.t] ^{*1} | When 1st digit is flashing, press the key once and H□Ld appears. | | | |
| Input logic | nPn: No-voltage input, PnP: Voltage input | | | |
| [5 <i>i</i> 6] | **Check input logic value (PNP, NPN). | | | |
| Input signal | / ← → ≥□, ※CTS/CTY: Set min. width of INA, INH, RESET signal. | | | |
| time [/ n.t] | unit: ms | | | |
| Koy look | Loff Loc. 1 XLoff: Unlock keys, key lock indicator turns OFF Loc. 1: Locks RST key, key lock indicator turns ON | | | |
| Key lock [Lo[t] | L □ E. 2: Locks RST key, key lock indicator turns ON L □ E. 2: Locks RST key, key lock indicator turns ON | | | |
| [222] | LoC3 ← ► LoC.2 Locks RST, (€), ⋈ keys, key lock indicator turns ON | | | |
| | | | | |

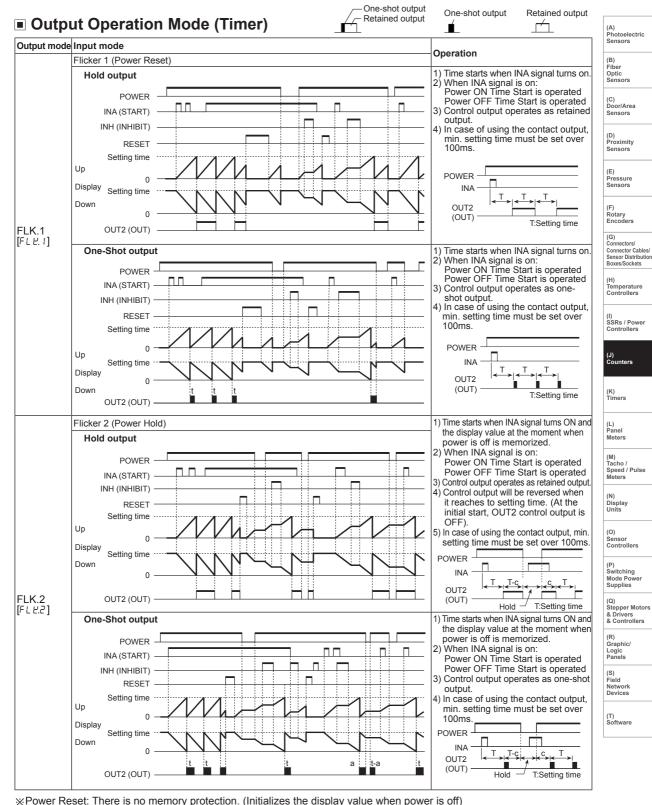
^{*1:} When output mode is FLE.1, FLE.2, I nE 0 and and, and.1, and.2 of PRESET1 model, all E 1 does not appear. The output time of all E 2 is displayed as all E.E. When output mode is and, and I, and 2, I nE.2, all E 1 appears.

J-23

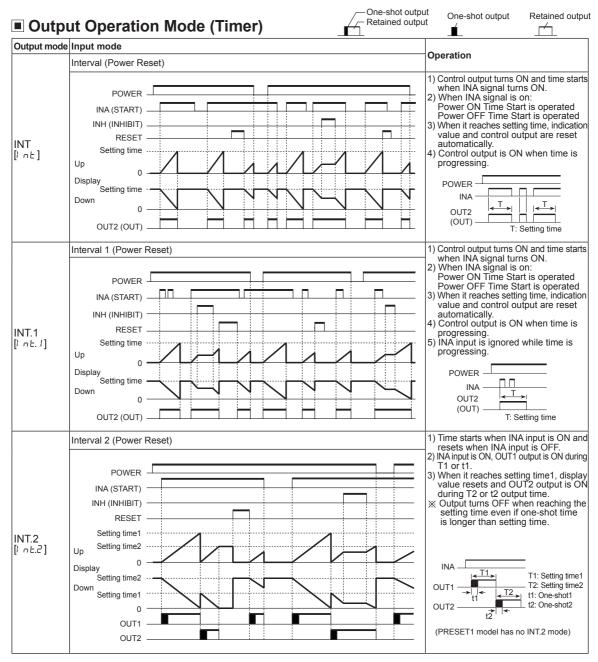
^{※2:} I n Ł. ≥ mode is available only for PRESET2 model.



※Power Reset: There is no memory protection. (Initializes the display value when power is off)
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

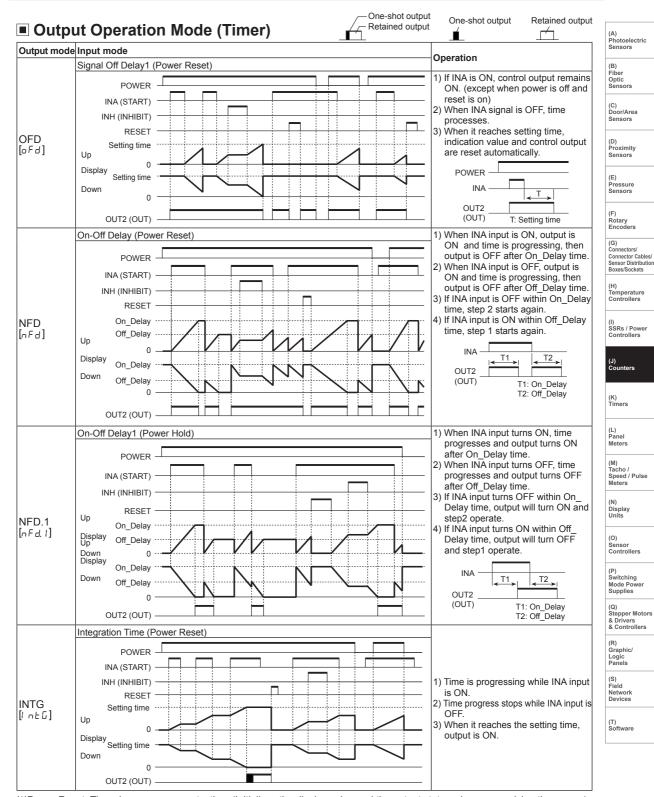


Power Hold: There is no memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)



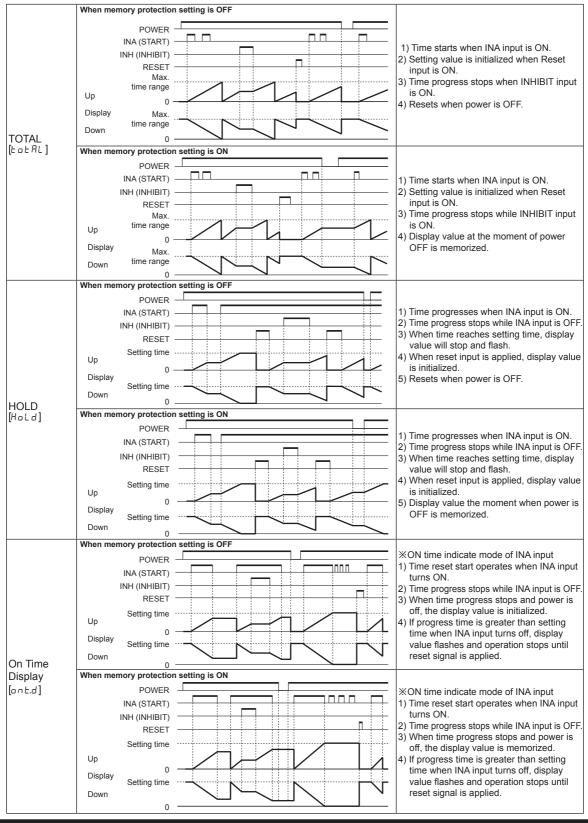
※Power Reset: There is no memory protection. (Initializes the display value when power is off)
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

J-26 Autonics



※Power Reset: There is no memory protection. (Initializes the display value and the output status when re-supplying the power.)
Power Hold: There is memory protection. (It memorizes the status of power off. When re-supplying the power, it returns the memorized display value and the output status.)

■ Timer Operation of the Indicator (CT6S-I, CT6Y-I, CT6M-I)



J-28 Autonics

- Timer '0' Time Setting
- Available output operation mode to set '0' time setting ond, ond. 1, ond.2, nFd, nFd. 1



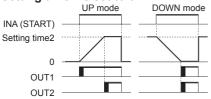
Retained output

- Operation according to output mode (at 0 time setting)

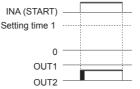
1) OND (Signal ON Delay) mode [and]

One-shot output (0.01 to 99.99 sec)

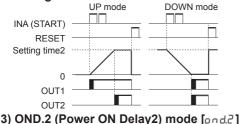
Setting time1 is set to 0



Setting time2 is set to 0



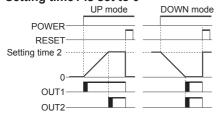
- 2) OND.1 (Signal ON Delay 1) mode [and. 1]
- Setting time1 is set to 0



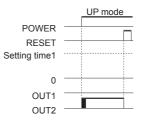
• Setting time2 is set to 0



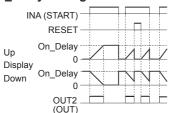
- Setting time1 is set to 0



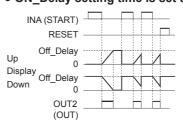
• Setting time2 is set to 0



- 4) NFD (ON-OFF Delay) mode [nFd]
- OFF Delay setting time is set to 0

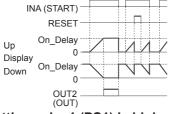


• ON Delay setting time is set to 0

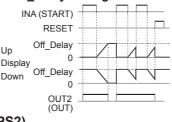


5) NFD.1 (ON-OFF Delay1) mode [nFd.1]

• OFF Delay setting time is set to 0



• ON Delay setting time is set to 0



- Setting value1 (PS1) is higher than Setting value2 (PS2)
 - OND[and], OND.1[and.1] or OND.2[and.2] output mode
 - UP mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.
 - DOWN mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON. If the setting value 1 is same as the setting value2 and START signal is applied, OUT1 output turns ON immediately.

Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets (I) SSRs / Powe Controllers

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

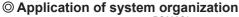
J-29 **Autonics**

Communication Mode

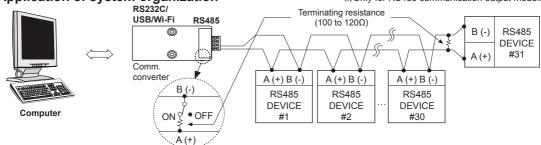
Parameter setting

(MD key: To select setting mode, ♥ or ♠ key: To change setting value)

| Setting mode | How to set | | | |
|------------------------|---|--|--|--|
| Comm. address | ★Setting range of Comm. address: 1 to 127 ★If the same address is applied during multiComm., it will not work correctly. | | | |
| Comm. speed [6 P 5] | 24 ←→ 48 ←→ 96 ←→ 192 ←→ 384 ×2400/4800/9600/19200/38400bps | | | |
| Comm. parity [Pィヒリ] | nonE ← → EuEn ← → odd | | | |
| Comm. stop bit [5 £ P] | 1 ←→ 2 | | | |
| | Setting range according to comm. speed. | | | |
| | 【 To shift flashing digits position of 2400bps 16ms to 99ms | | | |
| esponse waiting time | Comm. response waiting time. 4800bps 8ms to 99ms | | | |
| [r 5 Y.b] | I♥, ♠: To change the flashing digits 9600bps 5ms to 99ms | | | |
| | position value. 19200bps 5ms to 99ms | | | |
| | 38400bps 5ms to 99ms | | | |
| Comm. write | EnR ← → dl 5R **EnR: Permits Comm. write (Enable) dl 5R: Prohibits Comm. write (Disable) | | | |



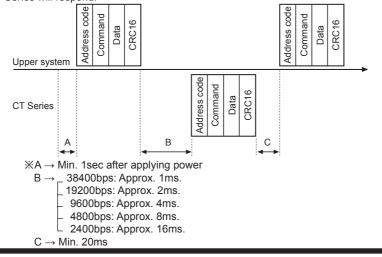
XOnly for RS485 communication output model.



XIt is recommended to use Autonics communication converter; SCM-WF48 (Wi-Fi to RS485·USB wireless communication converter, sold separately), SCM-US48I (USB to RS485 converter, sold separately), SCM-38I (RS232C to RS485 converter, sold separately), SCM-US (USB to Serial converter, sold separately).
Please use twisted pair wire, which is suitable for RS485 communication, for SCM-WF48, SCM-US48I and SCM-38I.

O Communication control ordering

- 1. The communication method is Modbus RTU (PI-MBUS-300-REV.J).
- 2. After 1sec of power supply into the high order system, it starts to communicate.
- Initial communication will be started by the high order system. When a command comes out from the high order system, CT Series will respond.



J-30 Autonics

O Communication command and block

The format of query and response

1) Read coil status (func. 01 H), Read input status (func. 02 H)

• Query (master)

| Slave Address | | Starting Address | | No. of F | oints | Error Check (CRC 16) | |
|------------------|-------|---------------------|-------|----------|-------|-------------------------|-------|
| Address | | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| | | | | | | | |

CRC 16

• Response (slave)

| Slave Address | Function | Byte | Data | Data | | Error Ch (CRC 1 | |
|------------------|----------|-------|-------|-------|-------|--------------------|-------|
| Address | | Count | | | | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| - | | | | | | | |

CRC 16

2) Read holding registers (func. 03 H), Read input registers (func. 04 H)

• Query (master)

| Slave Address Function | | Address | | No. of Points | | Error Check (CRC 16) | |
|---------------------------|-------|---------|-------|---------------|-------|-------------------------|-------|
| Address | | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| | | | | | | | |

CRC 16

• Response (slave)

| Slave Address | Function | Byte | Data | | Data | | Data | | Error (CRC | Check 16) |
|------------------|----------|-------|-------|-------|-------|-------|-------|-------|---------------|--------------|
| Address | | Count | High | Low | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

CRC 16

3) Force single coil. (func. 05 H)

Query (master)

| Slave Address | Function | Coil Address | | | | Error Check (CRC 16) | |
|------------------|----------|--------------|-------|-------|-------|-------------------------|-------|
| Address | | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| | | | | | | i . | |

CRC 16

Response (slave)

| | Slave Address | | Coil Address | | Force Data | | Error Check (CRC 16) | |
|--|------------------|-------|--------------|-------|------------|-------|-------------------------|-------|
| | | | High | Low | High | Low | Low | High |
| | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| | | | | | | | | |

CRC 16

4) Preset single register (func. 06 H)

Query (master)

| | Slave Address | Function | Register Address | | | | Error Check (CRC 16) | |
|--|------------------|----------|---------------------|-------|-------|-------|-------------------------|-------|
| | | | High | Low | High | Low | Low | High |
| | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| | | | | | | | 1 | |

CRC 16

• Response (slave)

| Slave Fi | Function | Register Address | | Preset Data | | Error Check (CRC 16) | |
|----------|----------|---------------------|-------|-------------|-------|-------------------------|-------|
| Address | | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

CRC 16

5) Preset multiple registers (func. 10 H)

• Query (master)

| Slave Address | Eunction | 1 - 1 - 1 - 1 | | - 3 | | Byte Count | Data | | Data | | Error Check (CRC 16) | |
|------------------|----------|---------------|-------|-------|-------|---------------|-------|-------|-------|-------|----------------------------|-------|
| | | High | Low | High | Low | | High | Low | High | Low | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |
| | | | | | | | | | | | | |

CRC 16

Response (slave)

| Slave Address | Function | Starting Address | | No. of Re | | | eck | | |
|------------------|-----------|------------------|-------|-----------|-------|-------|-------|--|--|
| | i dilodon | High | Low | High | Low | Low | High | | |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | 1Byte | | |
| - | | | | | | | | | |

CRC 16

6) Application

Read Coil Status (func. 01 H)
Master reads OUT2 000002 (0001H) to 000003 (0002H),
OUT1 output status (ON: 1, OFF: 0) from the Slave
(Address 01).

• Query (master)

| Slave Address | Function | | | | | Error Check (CRC 16) | | | | | |
|------------------|----------|------|------|------|------|-------------------------|------|--|--|--|--|
| | | High | Low | High | Low | Low | High | | | | |
| 01 H | 01 H | 00 H | 01 H | 00 H | 02 H | EC H | 0B H | | | | |

On slave side OUT2 000003 (0002H): OFF, OUT1 000002 (0001H): ON

Response (slave)

| Slave | Function | Byte Count | Data | Error Check (CRC 16) | | |
|---------|----------|------------|--------|-------------------------|------|--|
| Address | | 1 | 00001) | Low | High | |
| 01 H | 01 H | 01 H | 02 H | D0 H | 49 H | |

Read Input Register (Func. 04 H)Master reads preset value 301004 (03EBH) to 301005 (03ECH) of counter/timer, Slave (Address 15).

• Query (master)

| | Slave Address | Function | | | No. of Points | | Error Check (CRC 16) | |
|--|------------------|----------|------|------|---------------|------|-------------------------|------|
| | | | High | Low | High | Low | Low | High |
| | 0F H | 04 H | 03 H | EB H | 00 H | 02 H | 00 H | 95 H |

In case that the present value is 123456 (0001 E240 H) in slave side, 301004 (03EBH): E240 H, 301005 (03ECH): 0001H

• Response (slave)

| Slave | Function | Count | Data | | Data | | Error Check (CRC 16) | |
|---------|----------|-------|------|------|------|------|-------------------------|------|
| Address | | | High | Low | High | Low | Low | High |
| 0F H | 04 H | 04 H | E2 H | 40 H | 00 H | 01 H | E2 H | 28 H |

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors (D) Proximity Sensors

(E) Pressure

(F) Rotary

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

> J) Counters

Timers

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

⊚ Modbus mapping table

1) Reset/Output

| No. (Address) | Func. | Explanation | Setting | range | Notice |
|---------------|-------|--------------|---------|-------|------------------------|
| 000001 (0000) | 01/05 | Reset | 0:OFF | 1:ON | _ |
| 000002 (0001) | 01 | OUT2 output | 0:OFF | 1:ON | |
| 000003 (0002) | 01 | OUT1 output | | | |
| 000004 (0003) | 01 | | | | For BATCH output model |
| 000005 (0004) | 01/05 | BATCH resets | 0:OFF | 1:ON | For BATCH output model |

2) Terminal input status

| No. (Address) | Func. | Explanation | Setting range | Notice |
|---------------|-------|---------------|---------------|----------------|
| 100001 (0000) | 02 | INA input | 0:OFF | Terminal input |
| 100001 (0000) | 02 | status | 1:ON | status |
| 100002 (0001) | 02 | INB input | 0:OFF | Terminal input |
| 100002 (0001) | 02 | status | 1:ON | status |
| 100003 (0002) | 02 | INHIBIT input | 0:OFF | Terminal input |
| 100003 (0002) | | status | 1:ON | status |
| 100004 (0003) | 02 | RESET input | 0:OFF | Terminal input |
| 100004 (0003) | 02 | status | 1:ON | status |
| | | BATCH | 0:OFF | Terminal input |
| 100005 (0004) | 02 | RESET | 1:ON | status |
| | | input status | 1.01 | Sidius |

3) Product information

| No. (Address) | Func. | Explanation | Notice |
|------------------|-------|-----------------------------------|-------------|
| 300001 to 300100 | 04 | Reserved | _ |
| 300101 (0064) | 04 | Product number H | Model ID |
| 300102 (0065) | 04 | Product number L | Iviouei iD |
| 300103 (0066) | 04 | Hardware version | _ |
| 300104 (0067) | 04 | Software version | |
| 300105 (0068) | 04 | Model no. 1 | "CT" |
| 300106 (0069) | 04 | Model no. 2 | "6M" |
| 300107 (006A) | 04 | Model no. 3 | "-2" |
| 300108 (006B) | 04 | Model no. 4 | "PT" |
| 300109 (006C) | 04 | Reserved | |
| 300110 (006D) | 04 | Reserved | |
| 300111 (006E) | 04 | Reserved | |
| 300112 (006F) | 04 | Reserved | |
| 300113 (0070) | 04 | Reserved | _ |
| 300114 (0071) | 04 | Reserved | |
| 300115 (0072) | 04 | Reserved | |
| 300116 (0073) | 04 | Reserved | _ |
| 300117 (0074) | 04 | Reserved | |
| 300118 (0075) | 04 | Coil Status Start Address | 0000 |
| 300119 (0076) | 04 | Coil Status Quantity | _ |
| 300120 (0077) | 04 | Input Status Start Address | 0000 |
| 300121 (0078) | 04 | Input Status Quantity | _ |
| 300122 (0079) | 04 | Holding Register Start Address | 0000 |
| 300123 (007A) | 04 | Holding Register Quantity | _ |
| 300124 (007B) | 04 | Input Register Start Address | 0064 |
| 300125 (007C) | 04 | Input Register Quantity | _ |

4) Monitoring data

| No. (Address) | Func. | Explanation | Setting range | Notice | |
|---------------|-------|-----------------------------|---|--|--|
| | | BA.O LED display status | 0:OFF 1:ON | Bit 5 | |
| | | OUT2 LED display status | 0:OFF 1:ON | Bit 6 | |
| | | OUT1 LED display status | 0:OFF 1:ON | Bit 7 | |
| | | BA.S LED display status | 0:OFF 1:ON | Bit 10 | |
| 301001 (03E8) | 04 | LOCK LED display status | 0:OFF 1:ON | Bit 11 | |
| | | PS2 LED display status | 0:OFF 1:ON | Bit 12 | |
| | | PS1 LED display status | 0:OFF 1:ON | Bit 13 | |
| | | TMR LED display status | 0:OFF 1:ON | Bit 14 | |
| | | CNT LED display status | 0:OFF 1:ON | Bit 15 | |
| 301002 (03E9) | -04 | Present value of BATCH | 0.4- 000000 | For BATCH | |
| 301003 (03EA) | 04 | counter | 0 to 999999 | output model | |
| 301004 (03EB) | -04 | Present value of | [Counter] 6digit type : -99999 to 999999 4digit type | and timer | |
| 301005 (03EC) | | counter/timer | : -999 to 9999 [Timer]: Within time setting range | in common | |
| 301006 (03ED) | 04 | Display unit | [Counter] : decimal point of display value [Timer] : Time range | Counter: 40058 Data Timer: 40102 Data | |
| 301007 (03EE) | -04 | PS (2) | [Counter] 6digit type | | |
| 301008 (03EF) | 04 | setting value | : -99999 to 999999 -4digit type | Use counter | |
| 301009 (03F0) | -04 | PS1 | : -999 to 9999 | in common | |
| 301010 (03F1) | J- | setting value | [Timer]: Within time setting range | | |
| 301011 (03F2) | 0.4 | Setting value | 0.1000000 | Use counter | |
| 301012 (03F3) | -04 | of BATCH counter | 0 to 999999 | and timer in common | |
| 301013 (03F4) | 04 | Checking the input logic | 0: NPN, 1: PNP | | |

• Date format of 301001 (03E8) address bit

| Bit | Explanation | Data | Bit | Explanation | Data |
|------|-------------|--------|-------|-------------|--------|
| Bit0 | | 0 | Bit8 | | 0 |
| Bit1 | | 0 | Bit9 | | 0 |
| Bit2 | <u> </u> | 0 | Bit10 | BA.S | 0 or 1 |
| Bit3 | | 0 | Bit11 | Lock | 0 or 1 |
| Bit4 | <u> </u> | 0 | Bit12 | PRESET2 | 0 or 1 |
| Bit5 | BA.O | 0 or 1 | Bit13 | PRESET1 | 0 or 1 |
| Bit6 | OUT2 | 0 or 1 | Bit14 | TMR | 0 or 1 |
| Bit7 | OUT1 | 0 or 1 | Bit15 | CNT | 0 or 1 |

 $\ensuremath{\mathbb{X}}\xspace2$ Words data format: Upper data has high number address.

E.g.)301004: Present Value (Low Word), 301005: Present Value (High Word)

5) Preset value setting group

| No. (Address) | | | Setting range | Notice |
|---------------|-----------|-------------------|------------------------------------|-----------------|
| 400001 (0000) | | PS2 setting value | [Counter] | |
| 400002 (0001) | | PS setting value | 6digit type : 0 to 999999 | |
| 400003 (0002) | | | 4digit type: 0 to 9999 | |
| 400004 (0003) | 06/ 16 | PS1 setting value | [Timer]: Within time setting range | and timer in |
| 400005 (0004) | | BATCH counter | 0 to 999999 | common |
| 400006 (0005) | | setting value | 0 10 333333 | |

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6) Function setting mode (counter group)

| No. (Address) | Func. | Explanation | Setting range | Notice |
|---------------|-----------|--|---|---------------------------------------|
| 400051 (0032) | 03/06/16 | Counter/Timer [[- +] | 1: CoUn 1: El ñE | Use counter and timer in common |
| 400052 (0033) | 03/06/16 | | 0: UP 5: dn - 2 1: UP - 1 6: Ud - R 2: UP - 2 7: Ud - b 3: dn 8: Ud - E 4: dn - 1 | |
| 400053 (0034) | 03/06/16 | Indication mode [dl 5ñ] | O: E o E A L 1: H o L d | For the indicator |
| 400054 (0035) | 03/06/16 | Output mode [all E.ā] | 0:F 3:r 6:9 9:E 1:n 4:E 7:A 10:d 2:E 5:P 8:5 | _ |
| 400055 (0036) | 03/06/16 | | 0: I 2: IE 4: IDE 1: 30 3: 5E | |
| 400056 (0037) | 03/06/16 | [[0]] | 000 I to 9999 | unit: ×10ms |
| 400057 (0038) | 03/06/16 | [[oUt I] | 000 I to 9999 | unit: ×10ms |
| 400058 (0039) | 03/06/16 | Decimal point [dP] | 0: 2: 4: 1: 3: 5: | 4digit type 0: 1: 2: 3: |
| 400059 (003A) | 03/06/16 | Min. reset time [-5] | 0: 1 1: 20 | unit: ms |
| 400060 (003B) | 03/06/16 | Prescale decimal point position [5 [L.d] | 0: 3: 5: 2: 4: | 4digit type 1: 2: 3: |
| 400061 (003C) | 03/06/16 | Prescale value [5[L] | 6digit type: 0.00001 to 9999999 | Connected with prescale decimal point |
| 400062 (003D) | 703/00/10 | Prescale value [JLL] | 4digit type: 0.00 / to 9999 | position |
| 400063 (003E) | 03/06/16 | Start value [5 + r +] | 6digit type: 000000 to 999999 | Connected with decimal point position |
| 400064 (003F) | | | 4digit type: 0000 to 9999 | of display value |
| 400065 (0040) | 03/06/16 | 71 | 0: ELr 1: r E E | -Use counter and timer in common |
| 400066 (0041) | 03/06/16 | Lock key [Lo[l] | 0: L.o F | Ose counter and times in common |

7) Function setting mode (timer group)

| No. (Address) | Func. | Explanation | Setting range | Notice |
|---------------|----------|---------------------------------|--|---------------------------------|
| 400101 (0064) | 03/06/16 | Counter/Timer[[-+] | 0: CoUn 1: E! ñE | Use counter and timer in common |
| | | | 4digit type | |
| | | | 0: 0.001s to 9.999s 5: 0.1m to 999.9m 1: 0.01s to 99.99s 6: 1m to 9999m 2: 0.1s to 999.9s 7: 1m to 99h59m 3: 1s to 9999s 8: 1h to 9999h | |
| 400102 (0065) | 03/06/16 | Time range | 4: 1s to 99m59s 6digit type | <u> </u> |
| 400102 (0000) | 03/06/16 | [Hour/ĀĬ n/SEC] | 0: 0.001s to 999.999s 6: 1s to 9999m59s 1: 0.01s to 9999.99s 7: 1m to 99999.9m 2: 0.1s to 99999.9s 8: 1m to 999999m 3: 1s to 9999999 9: 1s to 99h59m59s 4: 0.01s to 99m59.99s 10: 1m to 99999.9h 5: 0.1s to 999m59.9s 11: 0.1h to 99999.9h | |
| 400103 (0066) | 03/06/16 | UP/Down mode [비- 리] | 0: UP 1: dn | _ |
| 400104 (0067) | 03/06/16 | Output mode [all Ł.ñ] | 0: and 3: FLE 7: Int. I 10: nFd 1: and I 4: FLE I 8: Int. 2 11: nFd I 2: and 2 5: FLE 9: aFd 12: Int. 5 | _ |
| 400105 (0068) | 03/06/16 | OUT2 (OUT) Output time | 0000 to 9999 (0: Hold) | unit: ×10ms |
| 400106 (0069) | 03/06/16 | OUT1 Output time | 0000 to 9999 (0: Hold) | unit: ×10ms |
| 400107 (006A) | 03/06/16 | Input signal time [I n E] | 0: 1 1: 20 | unit: ms |
| 400108 (006B) | 03/06/16 | Memory protection [d 月 上 月] | 0: [Lr 1: r E [| Use counter and timer in common |
| 400109 (006C) | 03/06/16 | Lock key [Lo[t] | 0: L.oFF 1: LoC. 1 2: LoC.2 3: LoC.3 | Use counter and timer in common |
| 400110 (006D) | 03/06/16 | ndication mode [d5P.ñ] | O: totAL 1: Hold 2: ont.d | For the indicator |

(A) Photoelectric Sensors (C) Door/Area Sensors (D) Proximity Sensors (G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets (I) SSRs / Power Controllers (M) Tacho / Speed / Pulse Meters (N) Display Units (P) Switching Mode Power Supplies (R) Graphic/ Logic Panels

8) Function setting mode (communication group)

| No. (Address) | Func. | Explanation | Setting range | Notice |
|---------------|----------|-------------------------------|----------------------------|---------------|
| 400151 (0096) | 03/06/16 | Comm. address [Addr] | 1 to 127 | _ |
| 400152 (0097) | 03/06/16 | Comm. speed [b P 5] | 0:24 1:48 2:96 3:192 4:384 | unit: ×100bps |
| 400153 (0098) | 03/06/16 | Comm. parity [Prty] | O:nonE 1:EuEn 2:odd | _ |
| 400154 (0099) | 03/06/16 | Stop bit [5 t P] | 0: / 1:2 | |
| 400155 (009A) | 03/06/16 | Response waiting time [-54.6] | 05 to 99 | unit: ms |
| 400156 (009B) | 03/06/16 | Comm. writing [[añ.#] | 0:EnR 1:d/5R | <u> </u> |

Exception processing

When communication error occurs, the highest bit of received function is set to 1, then sends response command and transmits exception code.

| Slave Address | Function + 80H | Exception Code | Error Check (CRC16) | |
|---------------|------------------|----------------|---------------------|-------|
| | l unction + sort | Lxception code | Low | High |
| 1Byte | 1Byte | 1Byte | 1Byte | 1Byte |

- Illeegal Function (Exception Code: 01H): Not supporting command
- Illegal Data Address (Exception Code: 02H)
- : Mismatch between the number of asked data and the number of ansmittable data.
- Illegal Data Value (Exception Code: 03
- : Mismatch between asked the number of data and transmittable the number of data in device
- Slave Device Failure (Exception Code: 04H): Command is processed incorrectly.

Example)

Master reads output status (ON:1, OFF:0) of non existing coil 01001 (03E8 H) from Slave (Address17).

Query (master)

| Slave Address | Function | Starting Address | | No. of Points | | Error Check (CRC16) | |
|---------------|----------|------------------|-----|---------------|-----|---------------------|------|
| | | High | Low | High | Low | Low | High |
| 11H | 01H | 03H | E8H | 00H | 01H | ##H | ##H |

Response (slave)

| Slave Address | Function + 80H | Exception Code | Error Check (CRC16) | | |
|---------------|-----------------|----------------|---------------------|------|--|
| Slave Address | FullClion + oun | Exception code | Low | High | |
| 11H | 81H | 02H | ##H | ##H | |

Read and Write of Parameter Value Using Communication

Read of the parameter area

000002 (OUT2), 000003 (OUT1), 000004 (BA, 0), 100001 to 100005 (terminal input), 300101 to 300125 (product information), 301001 to 301013 (Monitoring data)

Read and write of the parameter area

000001 (reset starts), 000005 (BATCH reset starts), 400001 to 400006 (setting value saving group), 400051 to 400066 (counter setting group), 400101 to 400110 (timer setting group).

400151 to 400156 (communication setting group)

Read of communication

Read parameter value using communication. (function: 01H, 02H, 03H, 04H) It is able to read communication regardless of permitting/prohibiting communication writing.

© Communication write

Change parameter value using communication. (function: 05H, 06H, 10H)

- When changing the parameter setting value of '■ Function setting mode Counter group' or '■ Function setting mode
 Timer group' using communication, reset indication will flash in 3 sec and display value will be reset. (counting display
 value and progress time before changing parameter setting value are not saved.)
- When changing the parameter setting value of '
 Preset value setting group' or '
 Function setting mode
 Communication group' using communication, counting display value or progress time will not be reset.
- If setting value beyond the setting range, this setting value is substituted for the value within the setting range and then memorized.

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■ Factory Default

| | Parameter | Factory default |
|---------|---------------|--|
| | | Ud-E |
| | 1 n | |
| | o U E.ñ | F |
| | d5P.ñ | t o t A L |
| | CP5 | 30 |
| | oUE2(oUE.E) | Hold (fixed) |
| | oUE I | 00.10 |
| Counter | dР | |
| | r5t | 20 |
| | 51 G | nPn |
| | SC.dP | 6-digit type: 4-digit type: |
| | SEL | 6-digit type: 1.0000 4-digit type: 1.000 |
| | Strt | 000000 |
| | dAF8 | [Lr |
| | Hour/ñi n/SEC | 6-digit type: 0.00 is-999.999s 4-digit type: 0.00 is-9.999s |
| | U - d | ÜP |
| | d5P.ñ | E o E A L |
| Timer | dR L R | [Lr |
| imer | oUŁ.ñ | ond |
| | oUt 2 (oUt.t) | HoLd |
| | oUt I | 00.10 |
| | 51 6 | nPn |
| | I n.t | 20 |
| | Lo[L | L.oFF |
| General | PS1 | 1000 |
| | PS2 | 5000 |
| | Addr | 00 1 |
| | 6P5 | 96 |
| Comm. | Prty | nonE |
| Comm. | 5 Ł P | 2 |
| | r526 | 20 |
| | Coñ.Y | EnA |

Cautions during Use

- Follow instructions in 'Cautions during Use'.
 Otherwise, it may cause unexpected accidents.
- 2. 24-48VDC, 24VAC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device
- 3. Use the product, 0.1 sec after supplying power.
- 4. When supplying or turning off the power, use a switch or etc. to avoid chattering.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- 6. In case of contact input, set count speed to low speed mode (1cps or 30cps) to operate.
 - If set to high speed mode (1k, 5k, 10kcps), counting error occurs due to chattering.
- Keep away from high voltage lines or power lines to prevent inductive noise.
- In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.
- Do not use near the equipment which generates strong magnetic force or high frequency noise.
- This product may be used in the following environments.
 Indoors (in the environment condition rated in 'Specifications')
 - ②Altitude max. 2,000m
 - ③Pollution degree 2
 - (4) Installation category II

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

Pressure Sensors

F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel

(M) Tacho / Speed / Pulse Meters

> l) isplay

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software