## PSR-...-24DC/ESD/5X1/1X2/300

## Safety relay for emergency stop, safety door and light grid monitoring with adjustable delay time



Data sheet
102104_en_04
© PHOENIX CONTACT 2016-04-29

## 1 Description

## Intended Use

The safety relay is used for emergency stop, safety door, and light grid monitoring.
The safety relay interrupts circuits in a safety-related way.

## Possible signal generators

- Emergency stop button
- Door locking mechanisms
- Light grids


## Contact type

- 3 undelayed enabling current paths
- 2 delayed enabling current paths
- 1 undelayed enabling current path

The undelayed enabling current paths and the signaling current path drop out according to stop category 0 (EN 60204-1).
The delayed enabling current paths drop out according to stop category 1 (EN 60204-1).

## Control

- Single or two channel
- Automatic or manual, monitored start


## Achievable safety integrity

- Undelayed contacts suitable up to category 4, PL e (EN ISO 13849-1), SILCL 3 (EN 62061)
- Dropout delayed contacts suitable up to category 3, PL d (EN ISO 13849-1), SILCL 2 (EN 62061)


## Additional features

- Adjustable delay time ( 0.2 s ... 300 s , 24 increments)
- Cross circuiting detection
- Option of screw or spring-cage terminal blocks for plugin
- $\quad 45 \mathrm{~mm}$ housing width


WARNING: Risk of electric shock
Observe the safety regulations and installation notes in the corresponding section.

Make sure you always use the latest documentation.
It can be downloaded from the product at phoenixcontact.net/products.

This document is valid for the products listed in the "Ordering data".
This document meets the same requirements as the original operating instructions with respect to the contents.
2 Table of contents
1 Description ..... 1
2 Table of contents ..... 2
3 Ordering data ..... 3
4 Technical data ..... 3
5 Safety regulations and installation notes. ..... 7
6 Function description ..... 8
7 Function and time diagrams ..... 8
8 Basic circuit diagram ..... 9
9 Derating ..... 9
10 Load curve ..... 9
11 Operating and indication elements ..... 10
12 Mounting and removing ..... 11
13 Wiring ..... 11
14 Startup ..... 12
15 Configuration ..... 13
16 Calculating the power dissipation ..... 14
17 Diagnostics ..... 14
18 Application examples ..... 15
19 Attachment ..... 19

## 3 Ordering data

|  | Description |
| :---: | :---: |
|  | Safety relay for emergency stop and safety door monitoring up to SIL 3 or Cat. 4, PL e (EN ISO 13849), one- or two-channel operation, automatic or manual activation, $3 \mathrm{~N} / \mathrm{O}$ contacts, $1 \mathrm{~N} / \mathrm{C}$ contact, $2 \mathrm{~N} / \mathrm{O}$ contacts with dropout delay of 0.2 s to 300 s , plug-in screw terminal block |
|  | Safety relay for emergency stop and safety door monitoring up to SIL 3 or Cat. 4, PL e (EN ISO 13849), one- or two-channel operation, automatic or manual activation, 3 N/O contacts, 1 N/C contact, 2 N/O contacts with dropout delay of 0.2 s to 300 s , plug-in spring-cage terminal block |

Documentation

User manual, English, for applications for PSR safety relay

| Type | Order No. | Pcs./Pkt. |
| :--- | :--- | :--- |
| PSR-SCP- 24DC/ESD/5X1/1X2/300 | 2981428 | 1 |
| PSR-SPP- 24DC/ESD/5X1/1X2/300 | 2981431 | 1 |
| Type | Order No. | Pcs./Pkt. |
| UM EN SAFETY RELAY <br> APPLICATION | 2888712 | 1 |

## 4 Technical data

| Hardware/firmware version |  |
| :---: | :---: |
| HW/FW | $\geq 09 /$-- |
| The technical data and safety characteristics are valid as of the specified HW/FW version. |  |
| Input data |  |
| Rated control circuit supply voltage $U_{S}$ | 24 V DC-15 \% / +10 \% |
| Rated control supply current $I_{S}$ | typ. 155 mA |
| Typical inrush current | $200 \mathrm{~mA}\left(\right.$ at $\mathrm{U}_{\mathrm{S}}$ ) <br> $<40 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 10 ) <br> $<150 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 12 ) <br> $>-60 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 22 ) <br> $<40 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 34 ) <br> $<40 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{l}_{\mathrm{x}}$ to S35) |
| Current consumption | $<40 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 10 ) <br> $<50 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{S}} / \mathrm{I}_{\mathrm{x}}$ to S 12 ) <br> $>-40 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 22 ) <br> 0 mA (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 34 ) <br> $<5 \mathrm{~mA}$ (with $\mathrm{U}_{\mathrm{s}} / \mathrm{I}_{\mathrm{x}}$ to S 35 ) |
| Power consumption at $\mathrm{U}_{\mathrm{S}}$ | typ. 3.72 W |
| Voltage at input/start and feedback circuit | 24 V DC-15 \% / +10 \% |
| Filter time | 1 ms (at A 1 in the event of voltage dips at $\mathrm{U}_{\mathrm{s}}$ ) <br> max. 1.5 ms (at S10, S12; test pulse width) <br> 7.5 ms (at S10, S12; test pulse rate) <br> Test pulse rate $=5 \times$ Test pulse width |
| Max. permissible overall conductor resistance (Input and reset circuit at $\mathrm{U}_{\mathrm{S}}$ ) | approx. $22 \Omega$ (Input and start circuits at $\mathrm{U}_{\mathrm{S}}$ ) |
| Typical response time at $U_{S}$ | $<600 \mathrm{~ms}$ (automatic start) <br> $<70 \mathrm{~ms}$ (manual start) |
| Typical starting time with $U_{s}$ | $<600 \mathrm{~ms}$ (when controlled via A1) |
| Typical release time with $U_{s}$ | $<20 \mathrm{~ms}$ (when controlled via S11/S12 and S21/S22) <br> $<20 \mathrm{~ms}$ (when controlled via A1) |
| Delay time range | $0.2 \mathrm{~s} \ldots 300 \mathrm{~s} \pm 20 \%$ (K3(t), K4(t) can be parameterized) |
| Recovery time | $<1$ s |
| Maximum switching frequency | 0.5 Hz |
| Concurrence input 1/2 | $\infty$ |


| Input data |  |
| :---: | :---: |
| Operating voltage display | 1 x green LED |
| Status display | $4 \times$ green LEDs |
| Protective circuit | Surge protection Suppressor diode |
| Output data |  |
| Contact type | 3 enabling current paths undelayed 2 enabling current paths delayed <br> 1 signaling current path undelayed |
| Contact material | $\mathrm{AgSnO}_{2}$ |
| Minimum switching voltage | 5 V AC/DC |
| Maximum switching voltage | 250 V AC/DC (Observe the load curve) |
| Limiting continuous current | 6 A (N/O contact, pay attention to the derating) 6 A (N/C contact) |
| Maximum inrush current | 20 A ( $\Delta \mathrm{t} \leq 100 \mathrm{~ms}$, undelayed contacts) 8 A (delayed contacts) |
| Inrush current, minimum | 10 mA |
| Sq. Total current $I_{T H}{ }^{2}=I_{1}^{2}+I_{2}^{2}+\ldots+I_{N}^{2}$ | $55 \mathrm{~A}^{2}$ (observe derating) |
| Interrupting rating (ohmic load) max. | $\begin{aligned} & 144 \mathrm{~W}(24 \mathrm{~V} \text { DC, } \tau=0 \mathrm{~ms}) \\ & 288 \mathrm{~W}(48 \mathrm{~V} \text { DC, } \tau=0 \mathrm{~ms}) \\ & 110 \mathrm{~W}(110 \mathrm{~V} \mathrm{DC,} \tau=0 \mathrm{~ms} \text {, delayed contacts: } 77 \mathrm{~W}) \\ & 88 \mathrm{~W}(220 \mathrm{~V} \text { DC, } \tau=0 \mathrm{~ms}) \\ & 1500 \text { VA ( } 250 \text { V AC, } \tau=0 \mathrm{~ms} \text {, delayed contacts: } 2000 \mathrm{VA}) \end{aligned}$ |
| Maximum interrupting rating (inductive load) | $42 \mathrm{~W}(24 \mathrm{~V} D C, \tau=40 \mathrm{~ms}$, delayed contacts: 48 W ) $42 \mathrm{~W}(48 \mathrm{~V}$ DC, $\tau=40 \mathrm{~ms}$, delayed contacts: 40 W ) $42 \mathrm{~W}(110 \mathrm{~V}$ DC, $\tau=40 \mathrm{~ms}$, delayed contacts: 35 W ) $42 \mathrm{~W}(220 \mathrm{~V} D C, \tau=40 \mathrm{~ms}$, delayed contacts: 33 W ) |
| Switching capacity min. | 50 mW |
| Mechanical service life | $10 \times 10^{6}$ cycles |
| Switching capacity ( $360 / \mathrm{h}$ cycles) | $\begin{aligned} & 4 \text { A ( } 24 \mathrm{~V} \text { DC) } \\ & 4 \text { A (230 V AC) } \end{aligned}$ |
| Switching capacity ( $3600 / \mathrm{h}$ cycles) | $\begin{aligned} & 2.5 \mathrm{~A}(24 \mathrm{~V}(\mathrm{DC} 13)) \\ & 3 \mathrm{~A}(230 \mathrm{~V}(\mathrm{AC} 15)) \end{aligned}$ |
| Output fuse | $10 \mathrm{AgL} / \mathrm{gG}$ (N/O contact) 6 A gL/gG (N/C contact) |
| General data |  |
| Relay type | Electromechanical relay with forcibly guided contacts in accordance with EN 50205 |
| Nominal operating mode | 100\% operating factor |
| Degree of protection | IP20 |
| Min. degree of protection of inst. location | IP54 |
| Mounting type | DIN rail mounting |
| Mounting position | any |
| Type of housing | PBT yellow |
| Air clearances and creepage distances between the power circuits | according to <br> DIN EN 50178/VDE 0160 |
| Rated insulation voltage | 250 V AC |
| Rated surge voltage/insulation | Basic insulation 4 kV : <br> between all current paths and housing <br> Safe isolation, reinforced insulation 6 kV : between $13 / 14,23 / 24,33 / 34$, and the remaining current paths between 13/14, 23/24, 33/34 among one another |
| Degree of pollution | 2 |
| Overvoltage category | III |



## Safety characteristic data according to EN ISO 13849

| Category | 4 (undelayed contacts) <br> 3 (delayed contacts) |
| :--- | :--- |
| Performance level | e (for delayed contacts PL d) |
| Duration of use | 240 Months |
| For applications in PLe, the required demand rate for the safety function is once per month. |  |
| Calculation basis |  |
| $B_{10 \mathrm{~L}}$ | 230000 (At 3 A AC15) |
| $d_{\text {op }}$ | 365.25 Days |
| $h_{\text {op }}$ | 24 h |
| $t_{\text {Cycle }}$ | 3600 s |

## Safety parameters for EN 62061

SILCL
3 (for delayed contacts SILCL 2)

## 5 Safety regulations and installation notes

Depending on the application, incorrect handling of the device may pose serious risks for the user or cause damage to equipment.

- Observe all the safety notes and warning instructions provided in this chapter and elsewhere in this document.


## General

- Observe the safety regulations of electrical engineering and industrial safety and liability associations.
Disregarding these safety regulations may result in death, serious personal injury or damage to equipment.
- Only use power supply units with safe isolation and SELV/PELV according to EN 50178/VDE 0160.


## Startup, mounting, and modifications

Startup, mounting, modifications, and upgrades may only be carried out by an electrically skilled person.

- Before working on the device, disconnect the power.
- Carry out wiring according to the application. Refer to the "Application examples" section for this.
Reliable operation is only ensured if the device is installed in housing protected from dust and humidity.
- Install the device in housing protected from dust and humidity (min. IP54).


## In operation

During operation, parts of electrical switching devices carry hazardous voltages.

- Protective covers must not be removed when operating electrical switching devices.
For emergency stop applications, automatic startup of the machine can pose serious risks for the user.
- The machine must be prevented from restarting automatically by a higher-level controller.
With the manual, monitored reset device, a machine start may not be triggered in accordance with EN ISO 13849-1.

Inductive loads can lead to welded relay contacts.

- Connect a suitable and effective protective circuit to inductive loads.
- Implement the protective circuit parallel to the load and not parallel to the switch contact.

Noise emission may occur when operating relay modules. Wireless reception may be disrupted in residential areas.
The device is a Class A product.

- Observe the requirements for noise emission for electrical and electronic equipment (EN 61000-6-4).
- Implement appropriate precautions against noise emission.
Surge voltages can destroy the device.
- Make sure that the output voltage of the voltage supply does not exceed 37 V even in the event of error.


## Faulty devices

The devices may be damaged following an error. Correct operation can no longer be ensured.

- In the event of an error, replace the device.

Only the manufacturer or their authorized representative may perform the following activities. Otherwise the warranty is invalidated.

- Repairs to the device
- Opening the housing

Taking out of service and disposal

- Dispose of the device in accordance with environmental regulations.
- Make sure that the device can never be reused.


## 6 Function description

### 6.1 Single-channel sensor circuit

The sensor circuit is not designed with redundancy.
The safety relay does not detect short and cross-circuits in the sensor circuit.

### 6.2 Two-channel sensor circuit

The sensor circuit is designed with redundancy.
Depending on the wiring, the safety relay has cross-circuit detection.

With the corresponding wiring, the safety relay detects short and cross-circuits in the sensor circuit.

### 6.3 Automatic start

The device starts automatically after the sensor circuit has been closed.

### 6.4 Manual, monitored start

The device starts with closed sensor circuit once the start circuit has been closed by pressing the reset button.
A connected reset button (connected to S33/S34) is monitored.

### 6.5 Safe shutdown

When the sensor circuit is opened, the enabling current paths $13 / 14,23 / 24$, and $33 / 34$ open without delay.
The enabling current paths 57/58 and 67/68 open after the delay time has elapsed.
When the enabling current paths are open, the device is in the safe state.
The signaling current path closes.

### 6.6 Off delay

The enabling current paths 57/58 and 67/68 drop out after the set delay time has elapsed (stop category 1).
Use the rotary switch and DIP switch on the device to set the delay time in 24 increments from 0.2 s to 300 s .


## 7 Function and time diagrams

7.1 Time diagram for automatic start, two-channel control

- Cross-circuit detection activated


Figure 1 Time diagram for automatic start, two-channel control
7.2 Time diagram for manual start, single-channel control


Figure 2 Time diagram for manual start, single-channel control

Key:

| A1/A2 | Power supply |
| :--- | :--- |
| S34 | Start circuit |
| S35 |  |
| S10 / S12 / S22 | Input sensor circuit |
| $\mathbf{1 3 / 1 4 , 2 3 / 2 4 , 3 3 / 3 4}$ | Undelayed enabling current paths |
| $\mathbf{5 7 / 5 8}, \mathbf{6 7 / 6 8}$ | Delayed enabling current paths |
| $\mathbf{4 1 / 4 2}$ | Signaling current path, undelayed |
| $\mathbf{t}_{\mathbf{d}}$ | Delay time |

## 8 Basic circuit diagram



Figure 3 Block diagram
Key:
A1
A2
S33, S34, S35
Y1/Y2
S10, S12
S11
S21
S22
13/14, 23/24, 33/34
41/42
57/58, 67/68
24 V DC power supply
0 V power supply
Start and feedback circuit
Feedback circuit
Input sensor circuit
Output 24 V
Output 0 V
Input sensor circuit
Undelayed enabling current paths
Signaling current path
Delayed enabling current paths

## 9 Derating

### 9.1 Any mounting position

The derating curve applies for the following conditions:

- Mounting on a DIN rail in any mounting position
- Devices mounted next to each other without spacing


Figure 4 Derating curve - any mounting position, without spacing

## 10 Load curve

10.1 Ohmic load


Figure 5 Relay load curve - ohmic load

## 11 Operating and indication elements

### 11.1 Connection versions



Figure 6 Connection versions

### 11.2 Connection assignment



S10, S12 Input sensor circuit
S33, S34, S35 Start and feedback circuit
S11 Output 24 V
A1
S21 Output 0 V
S22 Input sensor circuit
A2 0 V power supply
Y1/Y2
Feedback circuit
Power Power LED (green)
K1
K2
K3(t)
K4(t) Status indicator safety circuit; LED (green)
57/58
67/68
41/42
13/14
23/24
33/34

## 12 Mounting and removing

- Mount the device on a 35 mm DIN rail according to EN 60715.
- To remove the device, use a screwdriver to release the snap-on foot.


Figure 7 Mounting and removing

## 13 Wiring

- Connect the cables to the connection terminal blocks using a screwdriver.


Figure 8 Connecting the cables for PSR-SCP-... (Screw terminal block)

PSR-SPP-...


Figure 9 Connecting the cables for PSR-SPP-... (Spring-cage terminal block)


It is recommended that ferrules are used to connect stranded cables.

For compliance with UL approval, use copper wire that is approved up to $60^{\circ} \mathrm{C} / 75^{\circ} \mathrm{C}$.

### 13.1 Signal generator connection versions

- Connect suitable signal generators to S10/S11/S12 and S21/S22.

1


2


3


Figure 10 Signal generator connection versions
1 Two-channel connection with cross-circuit monitoring
2 Two-channel connection without cross-circuit monitoring
3 Single-channel connection

### 13.2 Start and feedback circuit connection variants

## Automatic start

- Bridge contacts $\mathrm{S} 33 / \mathrm{S} 35$ as well as $\mathrm{Y} 1 / \mathrm{Y} 2$.


## Manual, monitored start

- Connect a reset button to contacts S33/S34.
- Bridge contacts Y1/Y2.

A connected reset button is monitored.

## Start and feedback circuit

- Place the relevant $\mathrm{N} / \mathrm{C}$ contact in feedback circuit $\mathrm{Y} 1 / \mathrm{Y} 2$ or in path S33/S34 or S33/S35 to monitor external contactors or extension devices with force-guided contacts.


Figure 11 Start and feedback circuit connection variants
1 Automatic start
2 Automatic start with monitored contact extension
3 Manual, monitored start with monitored contact
extension
4 Manual, monitored start


## 14 Startup

- Apply the rated control circuit supply voltage (24 V DC) at terminal blocks A1/A2.
The Power LED lights up.
- Close contacts S10/S11/S12 and S21/S22


## Automatic start

The enabling current paths $13 / 14,23 / 24,33 / 34$ as well as 57/58, 67/68 close.
Signaling current path $41 / 42$ opens.
The K1, K2, K3(t) and K43(t) LEDs light up.

## Manual, monitored start

- Press the reset button.

The enabling current paths $13 / 14,23 / 24,33 / 34$ as well as 57/58, 67/68 close.
Signaling current path $41 / 42$ opens.
The K1, K2, K3(t) and K43(t) LEDs light up.

## 15 Configuration

### 15.1 Setting the delay time

Use the rotary switch and DIP switch on the device to set the delay time in 24 increments from 0.2 s to 300 s .
The 24 increments are the result of four periods (DIP switch), each with six delay times (rotary switch), see figure.
To configure the safety relay, proceed as follows:

1. Set a time period using the DIP switches.
2. Set the desired delay time with the rotary switch.

|  | 1 | 2 | 3 | 4 | 5 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\square$ $\mathbf{B}$ <br> $\square$  <br>  $\mathbf{A}$ | 0,2 | 0,4 | 0,6 | 0,8 | 1 | 1,2 |
| $\square$  <br> $\square$ A <br> $\square$  | 0,8 | 1,6 | 2,4 | 3,2 | 4 | 4,8 |
|  | 6,4 | 12,8 | 19,2 | 25 | 32 | 38 |
|  | 50 | 100 | 150 | 200 | 250 | 300 |

Figure 12 Configuration of the delay time (in seconds)


WARNING: Danger due to incorrect setting.
An incorrect configuration can result in dangerous machine or system states.

- Check the configuration before starting up for the first time.


### 15.2 Protection against manipulation

Once the time has been set, the rotary switch and the DIP switch can be protected against manipulation by covering with the label provided.
Operate the safety relay in a locked control cabinet to protect the configuration against manipulation.


Figure 13 Applying the label

## 16 Calculating the power dissipation



The total power dissipation of the safety relay is based on the input power dissipation and the contact power dissipation for the same and for different load currents.

Input power dissipation
$P_{\text {Input }}=U_{B}^{2} /\left(U_{S} / I_{S}\right)$
Contact power dissipation
With the same load currents:

## 17 Diagnostics

For the diagnostic description, please refer to the application manual for PSR safety relays.

## Function test/proof test



Use the function test to test the safety function. To do this, request the safety function once by pressing the emergency stop button, for example. Check whether the safety function is executed correctly by then switching the device on again via the sensor circuits.
$P_{\text {Contact }}=n \bullet \mathrm{I}_{\mathrm{L}}{ }^{2} \cdot 200 \mathrm{~m} \Omega$
With different load currents:
$\mathrm{P}_{\text {Contact }}=\left(\mathrm{I}_{\mathrm{L} 1}{ }^{2}+\mathrm{I}_{\mathrm{L} 2}{ }^{2}+\ldots+\mathrm{I}_{\mathrm{Ln}}{ }^{2}\right) \cdot 200 \mathrm{~m} \Omega$

## Total power dissipation

$\mathrm{P}_{\text {Total }}=\mathrm{P}_{\text {Input }}+\mathrm{P}_{\text {Contact }}$
therefore
$\mathrm{P}_{\text {Total }}=\mathrm{U}_{\mathrm{B}}{ }^{2} /\left(\mathrm{U}_{\mathrm{S}} / \mathrm{I}_{\mathrm{S}}\right)+\mathrm{n} \bullet \mathrm{I}_{\mathrm{L}}{ }^{2} \cdot 200 \mathrm{~m} \Omega$
or
$P_{\text {Total }}=U_{B}^{2} /\left(U_{S} / I_{S}\right)+\left(I_{L 1}{ }^{2}+I_{L}{ }^{2}+\ldots+I_{\mathrm{Ln}}{ }^{2}\right) \cdot 200 \mathrm{~m} \Omega$
Key:
P Power dissipation in mW
$\mathbf{U}_{\mathbf{B}} \quad$ Applied operating voltage
$\mathbf{U}_{\mathbf{S}} \quad$ Rated control circuit supply voltage
$I_{\mathbf{S}} \quad$ Rated control supply current
n Number of enabling current paths used
IL Contact load current

## 18 Application examples

18.1 Single-channel emergency stop monitoring

- Manual, monitored start
- Monitoring of external contactors
- Suitable up to category 1, PL c (EN ISO 13849-1), SIL 1 (EN 62061)


Figure 14 Single-channel emergency stop monitoring/manual, monitored start
Key:
$\begin{array}{ll}\text { S1 } & \text { Emergency stop button } \\ \text { K3/K4 } & \text { Contactors }\end{array}$

### 18.2 Two-channel emergency stop monitoring

- Manual, monitored start
- Cross circuiting detection
- Monitoring of external contactors
- $\quad$ Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061)

L+
(L1)


Figure 15 Emergency stop monitoring/manual, monitored start
Key:

| S1 | Emergency stop button |
| :--- | :--- |
| K3/K4 | Contactors |

18.3 Two-channel safety door monitoring

- Manual, monitored start
- Cross circuiting detection
- Monitoring of external contactors
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061)

L+


Figure 16 Safety door monitoring/manual, monitored start
Key:
B1/B2 Mechanical safety door switches
K3/K4 Contactors
18.4 Light grid monitoring/automatic start

- Automatic start
- Cross-circuit detection via light grid
- Monitoring of external contactors
- $\quad$ Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061)


Figure 17 Light grid monitoring/automatic start
Key:
K3/K4 Contactors

## 19 Attachment

19.1 Using PSR devices at altitudes greater than 2000 m above sea level


The following section describes the special conditions for using PSR devices at altitudes greater than 2000 m above sea level. Observe the relevant device-specific data (technical data, derating, etc.) according to the product documentation for the individual device.

Using the device at altitudes greater
than 2000 m above sea level up to max. 4500 m above sea level is possible under the following conditions:

1. Limit the rated control circuit supply voltage $\left(U_{S}\right)$ in accordance with the table below. Observe the technical data for the device.

| $U_{\mathrm{S}}$ according to the <br> technical data for the <br> device | $\mathrm{U}_{\mathrm{S}}$ when used at altitudes <br> greater than <br> $\mathbf{2 0 0 0} \mathbf{m}$ above sea level |
| :--- | :--- |
| $<150 \mathrm{~V} \mathrm{AC/DC}$ | $\mathrm{U}_{\mathrm{S}}$ according to the <br> technical data for the device <br> still valid |
| $>150 \mathrm{~V} \mathrm{AC/DC}$ | Limited to max. $150 \mathrm{~V} \mathrm{AC/}$ <br> DC |

2. Limit the maximum switching voltage in accordance with the table below. Observe the technical data for the device.

| Max. switching voltage <br> according to the <br> technical data for the <br> device | Max. switching voltage <br> when used at altitudes <br> greater than <br> 2000 $\mathbf{m}$ above sea level |
| :--- | :--- |
| $<150$ V AC/DC | Max. switching voltage <br> according to the technical <br> data for the device still valid |
| $>150$ V AC/DC | Limited to max. $150 \mathrm{~V} \mathrm{AC/}$ <br> DC |

3. Reduce the maximum ambient temperature for operation by the corresponding factor in accordance with the table below.
4. If derating is specified, offset all the points of the derating curve by the corresponding factor in accordance with the table below.

| Altitude above sea <br> level | Temperature derating factor |
| :--- | :--- |
| 2000 m | 1 |
| 2500 m | 0.953 |
| 3000 m | 0.906 |
| 3500 m | 0.859 |
| 4000 m | 0.813 |
| 4500 m | 0.766 |

## Example calculation for 3000 m



The following calculation and the illustrated derating curve are provided as examples. Perform the actual calculation and offset the derating curve for the device used according to the technical data and the "Derating" section.
$27^{\circ} \mathrm{C} \cdot 0.906 \approx 24^{\circ} \mathrm{C}$ $55^{\circ} \mathrm{C} \cdot 0.906 \approx 49^{\circ} \mathrm{C}$


Figure 18 Example of a suspended derating curve (red)

### 19.2 Revision history

| Version | Date | Contents |
| :--- | :--- | :--- |
| 04 | $2016-02-04$ | New edition of the data sheet |

