

# PE4314

Document Category: Product Specification

UltraCMOS® RF Digital Step Attenuator, 1 MHz–2.5 GHz



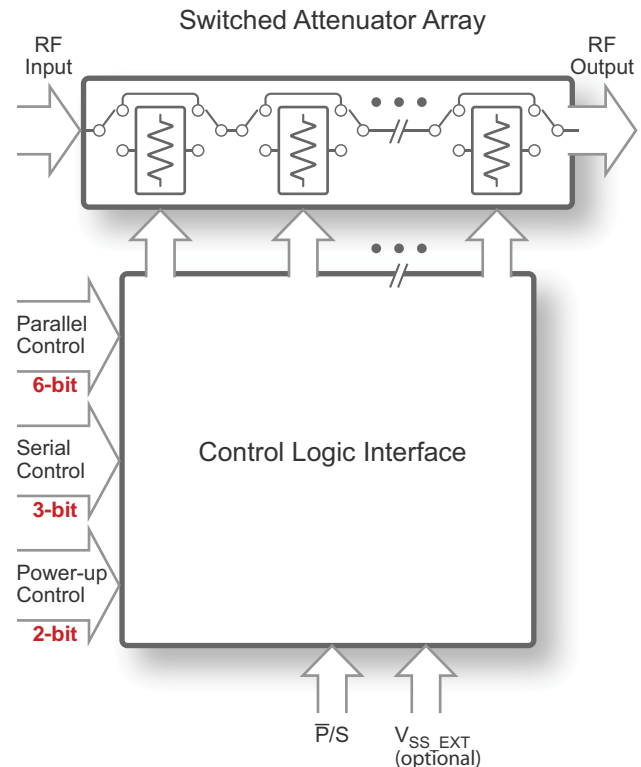
## Features

- Attenuation step of 0.5 dB up to 31.5 dB
- Glitch-less attenuation state transitions
- Low distortion for CATV and multi-carrier applications
- Extended +105 °C operating temperature
- Parallel and Serial programming interfaces
- Packaging – 20-lead 4 × 4 × 0.85 mm QFN

## Applications

- DOCSIS 3.1/0 customer premises equipment (CPE) and infrastructure
- Satellite CPE and infrastructure
- Fiber CPE and infrastructure

Figure 1 • PE4314 Functional Diagram



## Product Description

The PE4314 is a 75Ω HaRP™ technology-enhanced, 6-bit RF digital step attenuator (DSA) that supports a frequency range from 1 MHz to 2.5 GHz. It features glitch-less attenuation state transitions and supports 1.8V control voltage and an extended operating temperature range up to +105 °C, making this device ideal for multiple wired broadband applications.

The PE4314 is a pin-compatible upgraded version of the PE4304, PE4307, PE4308 and PE43404. An integrated digital control interface supports both Serial and Parallel programming of the attenuation, including the capability to program an initial attenuation state at power up.

The PE4314 covers a 31.5 dB attenuation range in a 0.5 dB step. It is capable of maintaining 0.5 dB monotonicity through 2.5 GHz. In addition, no external blocking capacitors are required if 0 VDC is present on the RF ports.

The PE4314 is manufactured on Peregrine's UltraCMOS® process, a patented variation of silicon-on-insulator (SOI) technology on a sapphire substrate.

©2015–2016, Peregrine Semiconductor Corporation. All rights reserved. • Headquarters: 9380 Carroll Park Drive, San Diego, CA, 92121

Peregrine's HaRP technology enhancements deliver high linearity and excellent harmonics performance. It is an innovative feature of the UltraCMOS process, offering the performance of GaAs with the economy and integration of conventional CMOS.

### Optional External $V_{SS}$

For proper operation, the  $V_{SS\_EXT}$  pin must be grounded or tied to the  $V_{SS}$  voltage specified in **Table 2**. When the  $V_{SS\_EXT}$  pin is grounded, FETs in the switch are biased with an internal negative voltage generator. For applications that require the lowest possible spur performance,  $V_{SS\_EXT}$  can be applied externally to bypass the internal negative voltage generator.

## Absolute Maximum Ratings

Exceeding absolute maximum ratings listed in **Table 1** may cause permanent damage. Operation should be restricted to the limits in **Table 2**. Operation between operating range maximum and absolute maximum for extended periods may reduce reliability.

### ESD Precautions

When handling this UltraCMOS device, observe the same precautions as with any other ESD-sensitive devices. Although this device contains circuitry to protect it from damage due to ESD, precautions should be taken to avoid exceeding the rating specified in **Table 1**.

### Latch-up Immunity

Unlike conventional CMOS devices, UltraCMOS devices are immune to latch-up.

**Table 1 • Absolute Maximum Ratings for PE4314**

Parameter/Condition	Min	Max	Unit
Supply voltage, $V_{DD}$	-0.3	5.5	V
Digital input voltage	-0.3	3.6	V
RF input power, 75 $\Omega$ 1–30 MHz $\geq 30$ MHz–2.5 GHz		See Fig. 5 +30	dBm dBm
Storage temperature range	-65	+150	$^{\circ}$ C
ESD voltage HBM <sup>(1)</sup> , all pins		1500	V
ESD voltage CDM <sup>(2)</sup> , all pins		1000	V
<b>Notes:</b> 1) Human body model (MIL-STD 883 Method 3015). 2) Charged device model (JEDEC JESD22-C101).			

## Recommended Operating Conditions

Table 2 lists the recommended operating conditions for the PE4314. Devices should not be operated outside the recommended operating conditions listed below.

Table 2 • Recommended Operating Conditions for PE4314

Parameter	Min	Typ	Max	Unit
<b>Normal mode, <math>V_{SS\_EXT} = 0V^{(1)}</math></b>				
Supply voltage, $V_{DD}$	2.3	3.3	5.5	V
Supply current, $I_{DD}$		130	200	$\mu A$
<b>Bypass mode, <math>V_{SS\_EXT} = -3.4V^{(2)}</math></b>				
Supply voltage, $V_{DD}$ (Table 3 spec compliance applies for $V_{DD} \geq 3.4V$ .)	2.7	3.4	5.5	V
Supply current, $I_{DD}$		50	80	$\mu A$
Negative supply voltage, $V_{SS\_EXT}$	-3.6		-3.2	V
Negative supply current, $I_{SS}$	-40	-16		$\mu A$
<b>Normal or bypass mode</b>				
Digital input high	1.17		3.6	V
Digital input low	-0.3		0.6	V
Digital input current <sup>(3)</sup>			20	$\mu A$
RF input power, CW <sup>(4)</sup> 1–30 MHz $\geq 30$ MHz–2.5 GHz			Fig. 5 +24	dBm dBm
RF input power, pulsed <sup>(5)</sup> 1–30 MHz $\geq 30$ MHz–2.5 GHz			Fig. 5 +27	dBm dBm
Operating temperature range	-40	+25	+105	$^{\circ}C$
<b>Notes:</b> 1) Normal mode: connect $V_{SS\_EXT}$ (pin 12) to GND ( $V_{SS\_EXT} = 0V$ ) to enable internal negative voltage generator. 2) Bypass mode: use $V_{SS\_EXT}$ (pin 12) to bypass and disable internal negative voltage generator. 3) Applies to all pins except pins 1, 5, 7 and 20. Pins 1, 7 and 20 have an internal 1 M $\Omega$ pull-down resistor to ground and pin 5 has an internal 2 M $\Omega$ pull-up resistor to internal $V_{DD}$ . 4) 100% duty cycle, all bands, 75 $\Omega$ . 5) Pulsed, 5% duty cycle of 4620 $\mu s$ period, 75 $\Omega$ .				

## Electrical Specifications

Table 3 provides the PE4314 key electrical specifications @ +25 °C,  $Z_S = Z_L = 75\Omega$ , unless otherwise specified. Normal mode<sup>(1)</sup> is @  $V_{DD} = 3.3V$  and  $V_{SS\_EXT} = 0V$ . Bypass mode<sup>(2)</sup> is @  $V_{DD} = 3.4V$  and  $V_{SS\_EXT} = -3.4V$ .

Table 3 • PE4314 Electrical Specifications

Parameter	Condition	Frequency	Min	Typ	Max	Unit
Operating frequency			1 MHz		2.5 GHz	As shown
Attenuation range	0.5 dB step			0–31.5		dB
Insertion loss	Reference state	1–204 MHz		1.0	1.25	dB
		204–870 MHz		1.2	1.50	dB
		870–1218 MHz		1.3	1.80	dB
		1218–2500 MHz		1.5	1.90	dB
Attenuation error	Any bit or bit combination	1–204 MHz		See Fig. 13– Fig. 17	$\pm(0.15 + 2\%$ of attenuation setting)	dB
		204–1218 MHz			$\pm(0.15 + 3\%$ of attenuation setting)	dB
		1218–1794 MHz			$\pm(0.15 + 4\%$ of attenuation setting)	dB
		1794–2500 MHz			$\pm(0.15 + 8\%$ of attenuation setting)	dB
Return loss	Input and output ports, reference state	1–204 MHz		19		dB
		204–870 MHz		17		dB
		870–1794 MHz		16		dB
		1794–2500 MHz		19		dB
Relative phase	All states	870 MHz		9		deg
		1000 MHz		11		deg
		1218 MHz		14		deg
Input 0.1dB compression point <sup>(3)</sup>		30–2500 MHz		30		dBm
Input IP2	Two tones at +15 dBm 10 kHz spacing 0 dB and 31.5 dB attenuation states	5 MHz 10 MHz 17 MHz 35 MHz 500 MHz 1000 MHz 1900 MHz 2500 MHz		0 dB	31.5 dB	dBm dBm dBm dBm dBm dBm dBm dBm
				70	100	
				76	101	
				80	104	
				88	105	
				104	110	
				106	113	
				98	102	
				110	99	

Table 3 • PE4314 Electrical Specifications (Cont.)

Parameter	Condition	Frequency	Min	Typ		Max	Unit
				0 dB	31.5 dB		
Input IP3	Two tones at +15 dBm 10 kHz spacing 0 dB and 31.5 dB attenuation states	5 MHz		57	62		dBm
		10 MHz		69	61		dBm
		17 MHz		63	62		dBm
		35 MHz		62	61		dBm
		500 MHz		62	62		dBm
		1000 MHz		59	55		dBm
		1900 MHz		60	55		dBm
		2500 MHz		58	57		dBm
Video feed-through	DC measurement			7			mV <sub>PP</sub>
Settling time	50% CTRL to 0.05 dB of final value			1.8			μs
Settling time	50% CTRL to 0.5 dB of final value			0.4			μs
Switching time	50% CTRL to 90% or 10% RF			370		700	ns
Attenuation transient (envelope)		250 MHz		0.5			dB

**Notes:**

- 1) Normal mode: connect V<sub>SS\_EXT</sub> (pin 12) to GND (V<sub>SS\_EXT</sub> = 0V) to enable internal negative voltage generator.
- 2) Bypass mode: use V<sub>SS\_EXT</sub> (pin 12) to bypass and disable internal negative voltage generator.
- 3) The input 0.1dB compression point is a linearity figure of merit. Refer to Table 2 for the operating RF input power (75Ω).

## Switching Frequency

The PE4314 has a maximum 25 kHz switching frequency in normal mode (pin 12 tied to ground). A faster switching frequency is available in bypass mode (pin 12 tied to  $V_{SS\_EXT}$ ). The rate at which the PE4314 can be switched is then limited to the switching time as specified in **Table 3**.

Switching frequency is defined to be the speed at which the DSA can be toggled across attenuation states. Switching time is the time duration between the point the control signal reached 50% of the final value and the point the output signal reaches within 10% or 90% of its target value.

## Spur-Free Performance

The typical spurious performance of the PE4314 in normal mode is  $-158$  dBm/Hz (pin 12 tied to ground). The spur fundamental occurs around 2.6 MHz and it has a bandwidth of 100 kHz. This results in a CATV band typical spurious level for frequencies above 5 MHz of  $-154$  dBm. If spur-free performance is desired, the internal negative voltage generator can be disabled by applying a negative voltage to  $V_{SS\_EXT}$  (pin 12).

## Glitch-less Attenuation State Transitions

The PE4314 features a novel architecture to provide the best-in-class glitch-less transition behavior when changing attenuation states. When RF input power is applied, the output power spikes are greatly reduced (0.5 dB) during attenuation state changes when comparing to previous generations of DSAs.

## Thermal Data

Psi-JT ( $\Psi_{JT}$ ), junction top-of-package, is a thermal metric to estimate junction temperature of a device on the customer application PCB (JEDEC JESD51-2).

$$\Psi_{JT} = (T_J - T_T)/P$$

where

$\Psi_{JT}$  = junction-to-top of package characterization parameter, °C/W

$T_J$  = die junction temperature, °C

$T_T$  = package temperature (top surface, in the center), °C

P = power dissipated by device, Watts

**Table 4 • Thermal Data for PE4314**

Parameter	Typ	Unit
Maximum junction temperature, $T_{JMAX}$ (RF input power, CW = 24 dBm, +105 °C ambient)	124	°C
$\Psi_{JT}$	25	°C/W
$\theta_{JA}$ , junction-to-ambient thermal resistance	74	°C/W

## Truth Tables

**Table 5** and **Table 6** provide the truth tables for the PE4314.

**Table 5 • Parallel Truth Table for PE4314<sup>(\*)</sup>**

$\bar{P}/S$	C16	C8	C4	C2	C1	C0.5	Attenuation Setting RF1–RF2
0	0	0	0	0	0	0	Reference IL
0	0	0	0	0	0	1	0.5 dB
0	0	0	0	0	1	0	1 dB
0	0	0	0	1	0	0	2 dB
0	0	0	1	0	0	0	4 dB
0	0	1	0	0	0	0	8 dB
0	1	0	0	0	0	0	16 dB
0	1	1	1	1	1	1	31.5 dB

Note: \* Not all 64 possible combinations of C0.5–C16 are shown.

**Table 6 • Parallel Power-up Truth Table for PE4314<sup>(\*)</sup>**

$\bar{P}/S$	LE	PUP1	PUP2	Attenuation Setting RF1–RF2
0	0	0	0	Reference IL
0	0	0	1	8 dB
0	0	1	0	16 dB
0	0	1	1	31.5 dB
0	1	X	X	Defined by C0.5–C16

Note: \* Power up with LE = 1 provides normal parallel operation with C0.5–C16, and PUP1 and PUP2 are not active.

## Programming Options

### Parallel/Serial Selection

Either a Parallel or Serial interface can be used to control the PE4314. The  $\overline{P/S}$  bit provides this selection, with  $\overline{P/S} = \text{LOW}$  selecting the Parallel interface and  $\overline{P/S} = \text{HIGH}$  selecting the Serial interface.

### Parallel Mode Interface

The Parallel interface consists of six CMOS-compatible control lines that select the desired attenuation state, as shown in **Table 5**.

The Parallel interface timing requirements are defined by **Figure 3**, **Table 8** and switching time in **Table 3**.

For Latched Parallel programming, the latched enable (LE) should be held LOW while changing attenuation state control values, then pulsed LE HIGH to LOW (per **Figure 3**) to latch new attenuation state into the device.

For Direct Parallel programming, the LE line should be pulled HIGH. Changing attenuation state control values will change device state to new attenuation. Direct mode is ideal for manual control of the device (using hardware, switches or jumpers).

In Parallel mode, DATA and CLOCK (CLK) pins are “don’t care” and may be tied to logic LOW or logic HIGH.

### Serial Interface

The Serial interface is a 6-bit Serial-in, Parallel-out shift register buffered by a transparent latch. It is controlled by using three CMOS-compatible signals: DATA, CLK and LE. The DATA and CLK inputs allow data to be serially entered into the shift register, a process that is independent of the state of the LE input. Serial data is clocked in MSB first.

The LE input controls the latch. When LE is HIGH, the latch is transparent and the contents of the Serial shift register control the attenuator. When LE is brought LOW, data in the shift register is latched.

The shift register must be loaded while LE is held LOW to prevent the attenuator value from changing as data is entered. The LE input should then be toggled HIGH and brought LOW again, latching the

new data into the DSA. The Serial timing for the operation is defined by **Figure 2** and **Table 7**.

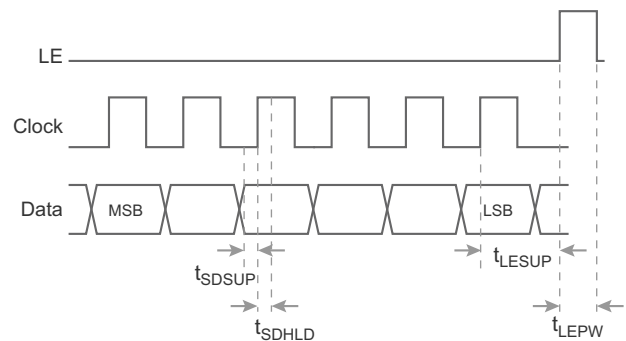
### Power-up Control Settings

The PE4314 always assumes a specifiable attenuation setting on power up. This feature exists for both the Serial and Parallel modes of operation, and allows a known attenuation state to be established before an initial Serial or Parallel control word is provided.

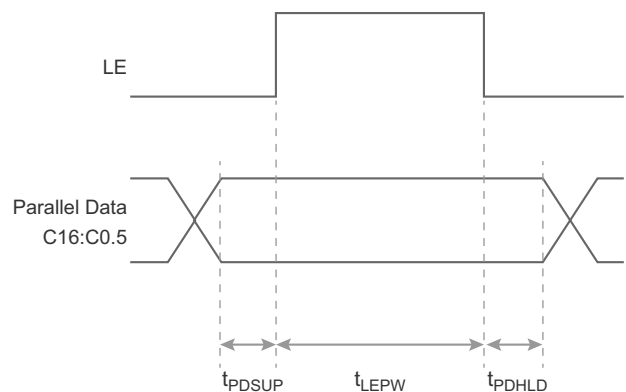
When the attenuator powers up in Serial mode ( $\overline{P/S} = 1$ ), the six control bits are set to whatever data is present on the six Parallel data inputs (C0.5–C16). This allows any one of the 64 attenuation settings to be specified as the power-up state.

When the attenuator powers up in Parallel mode ( $\overline{P/S} = 0$ ) with LE = 0, the control bits are automatically set to one of four possible values. These four values are selected by the two power-up (PUP) control bits, PUP1 and PUP2, as shown in **Table 6**.

**Figure 2 • Serial Interface Timing Diagram**



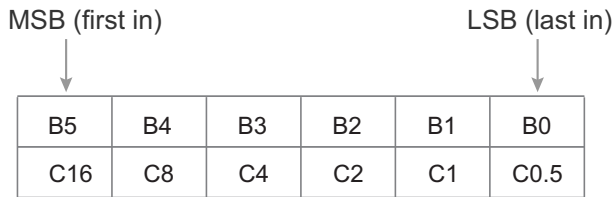
**Figure 3 • Parallel Interface Timing Diagram**



## Serial Register Map

Figure 4 provides the Serial programming register map for the PE4314.

Figure 4 • *Serial Register Map*<sup>(\*)</sup>



Note: \* For backward compatibility, the same programming scheme can be used.

Table 7 • *Serial Interface AC Characteristics*<sup>(1)</sup>

Parameter	Min	Max	Unit
Serial data clock frequency, $f_{CLK}^{(2)}$		10	MHz
Serial clock HIGH time, $t_{CLKH}$	30		ns
Serial clock LOW time, $t_{CLKL}$	30		ns
LE set-up time after last clock rising edge, $t_{LESUP}$	10		ns
LE minimum pulse width, $t_{LEPW}$	30		ns
Serial data set-up time before clock rising edge, $t_{SDSUP}$	10		ns
Serial data hold time after clock rising edge, $t_{SDHLD}$	10		ns

**Notes:**  
 1)  $V_{DD} = 3.3V$  or  $5.0V$ ,  $-40\text{ }^{\circ}\text{C} < T_A < +105\text{ }^{\circ}\text{C}$ , unless otherwise specified.  
 2)  $f_{CLK}$  is verified during the functional pattern test. Serial programming sections of the functional pattern are clocked at 10 MHz to verify  $f_{CLK}$  specification.

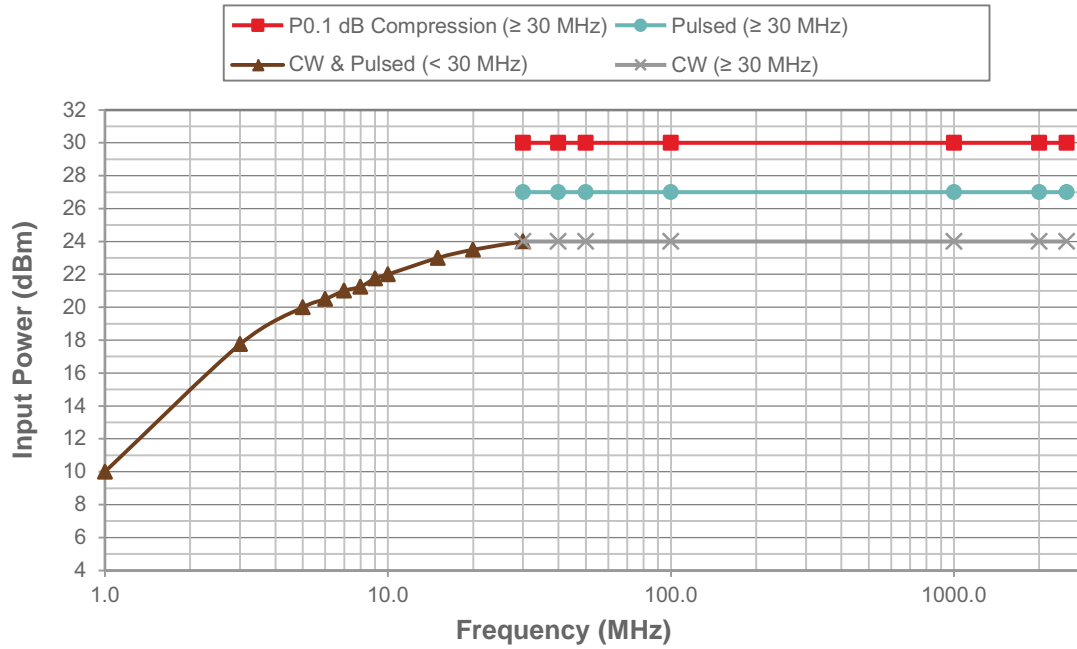
Table 8 • *Parallel Interface AC Characteristics*<sup>(\*)</sup>

Parameter	Min	Max	Unit
LE minimum pulse width, $t_{LEPW}$	10		ns
Data set-up time before rising edge of LE, $t_{PDSUP}$	10		ns
Data hold time after falling edge of LE, $t_{PDHLD}$	10		ns

Note: \*  $V_{DD} = 3.3V$  or  $5.0V$ ,  $-40\text{ }^{\circ}\text{C} < T_A < +105\text{ }^{\circ}\text{C}$ , unless otherwise specified.



Figure 5 • Power De-rating Curve, 1 MHz–2.5 GHz, –40 to +105 °C Ambient, 75Ω



## Typical Performance Data

Figure 6–Figure 27 show the typical performance data at +25 °C,  $V_{DD} = 3.3V$ ,  $Z_S = Z_L = 75\Omega$ , unless otherwise specified.

Figure 6 • *Insertion Loss vs Temperature*

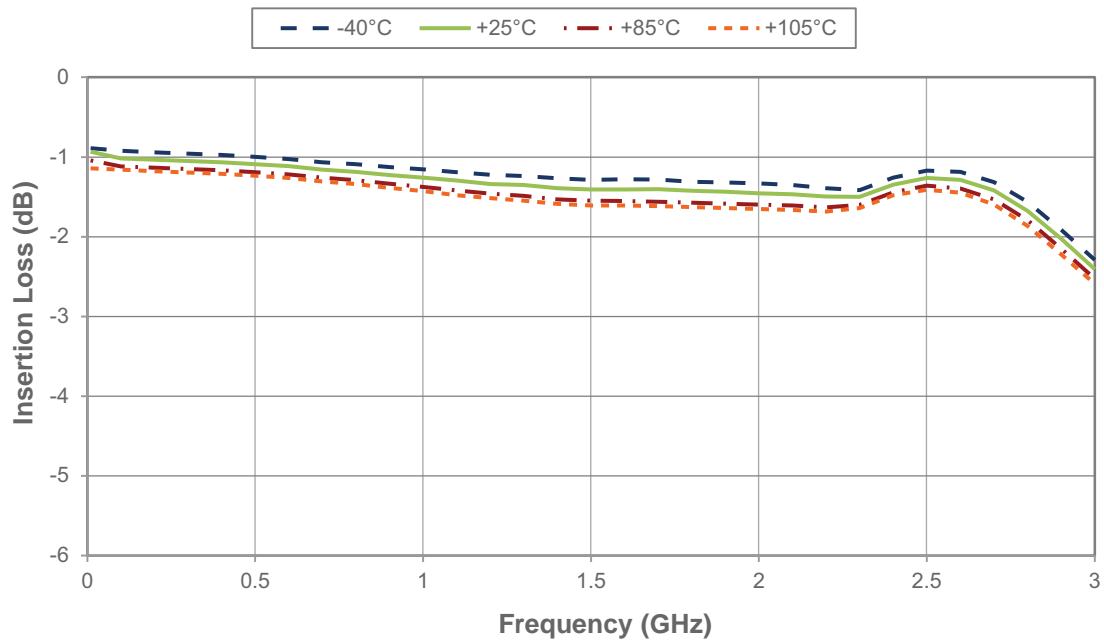


Figure 7 • *Input Return Loss vs Attenuation Setting*

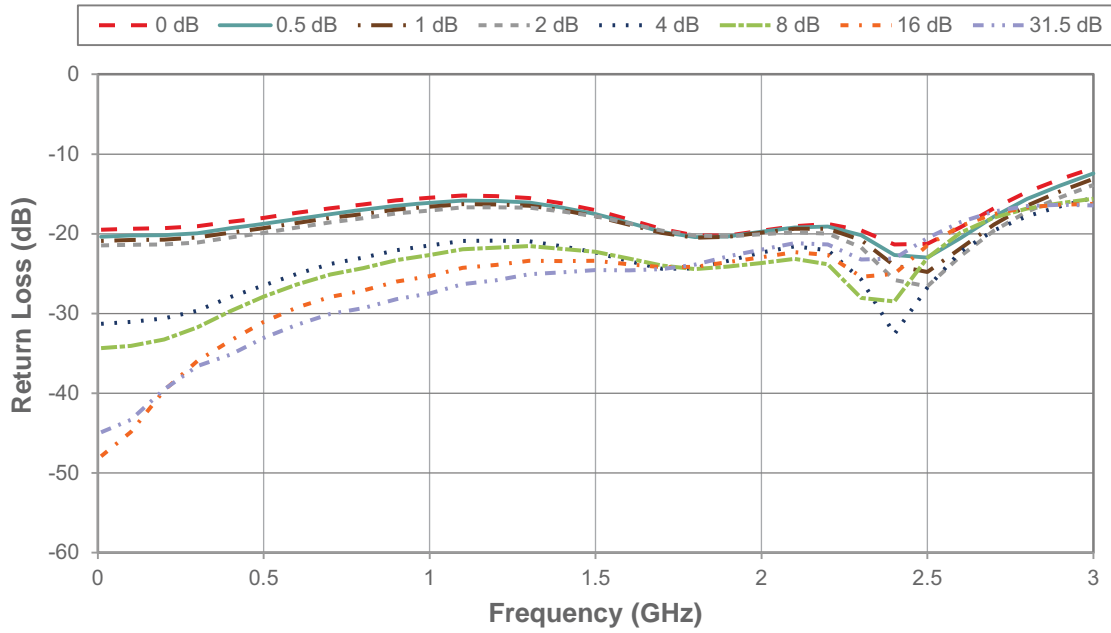


Figure 8 • *Output Return Loss vs Attenuation Setting*

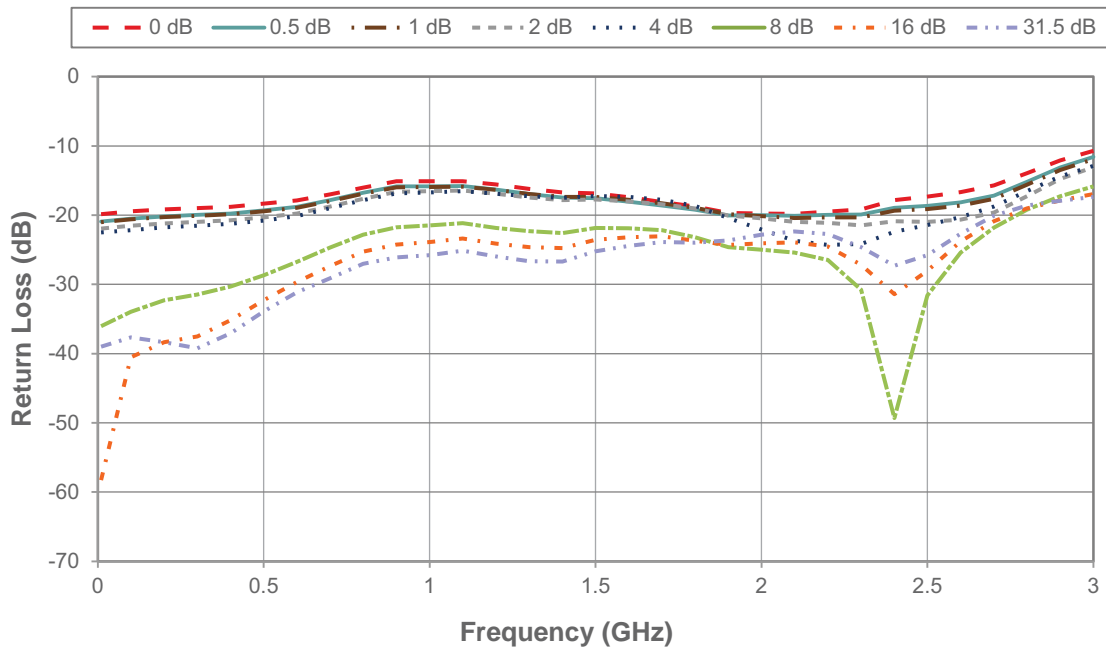


Figure 9 • Input Return Loss for 16 dB Attenuation Setting vs Temperature

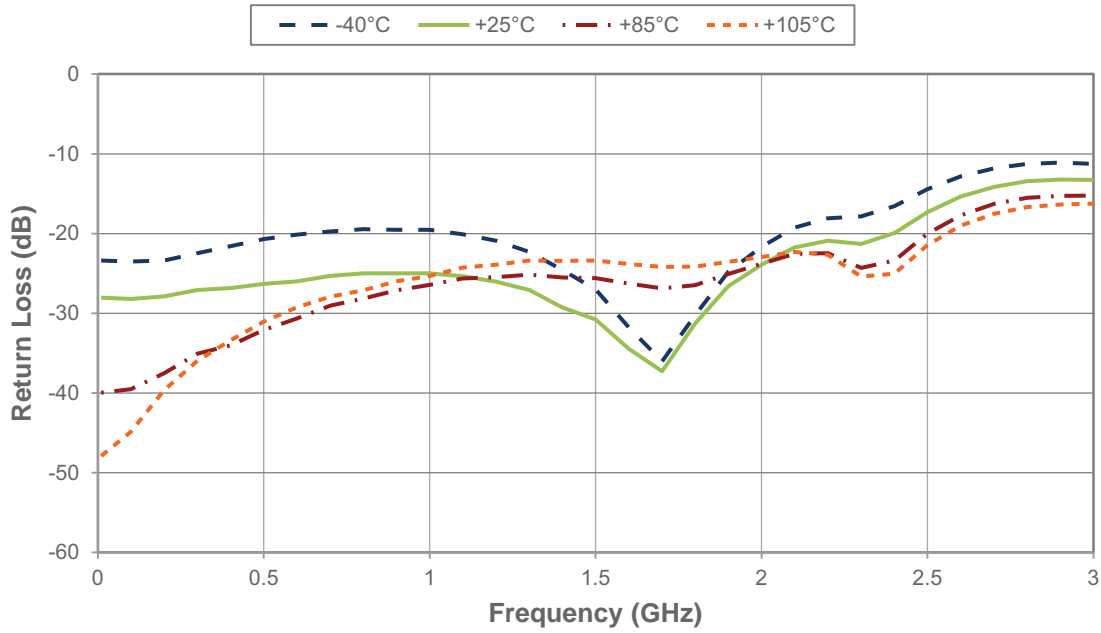


Figure 10 • Output Return Loss for 16 dB Attenuation Setting vs Temperature

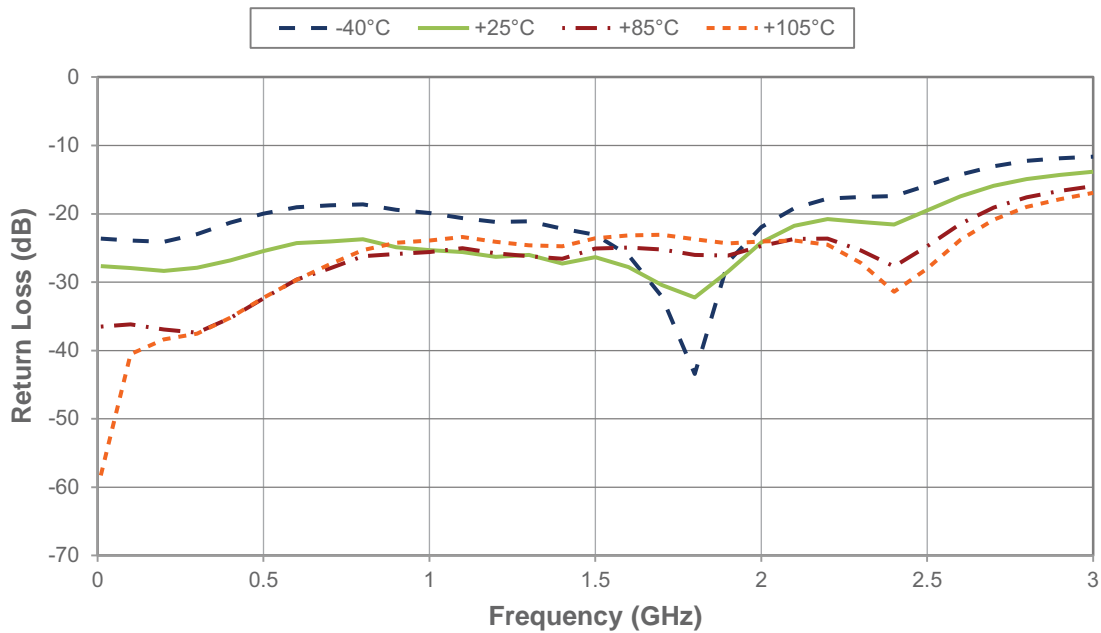


Figure 11 • Relative Phase Error vs Attenuation Setting

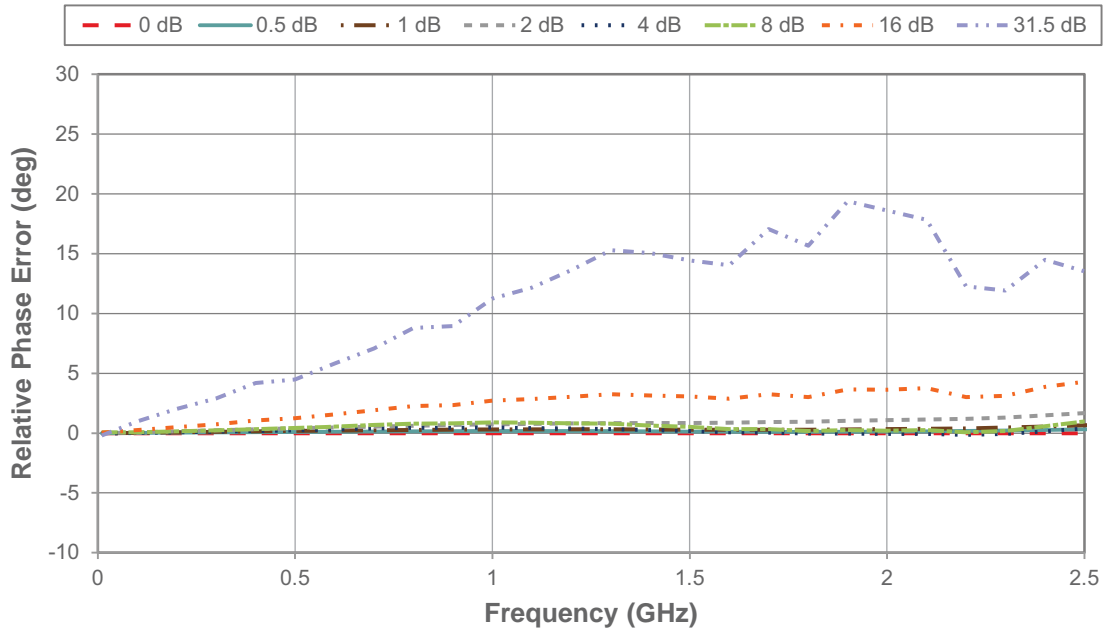


Figure 12 • Relative Phase Error for 31.5 dB Attenuation Setting vs Frequency

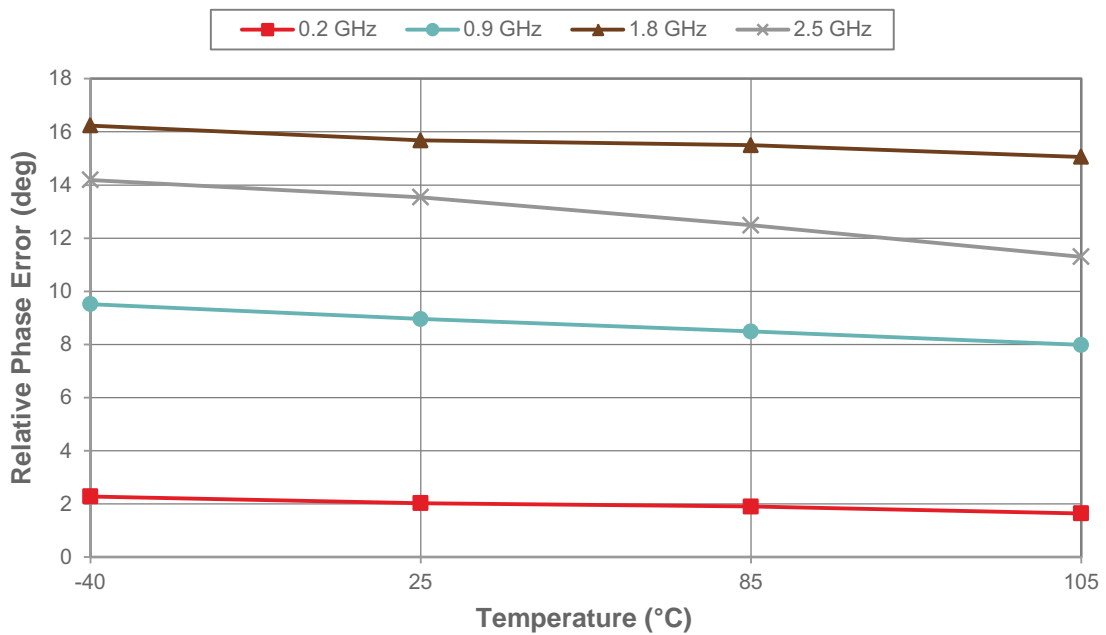
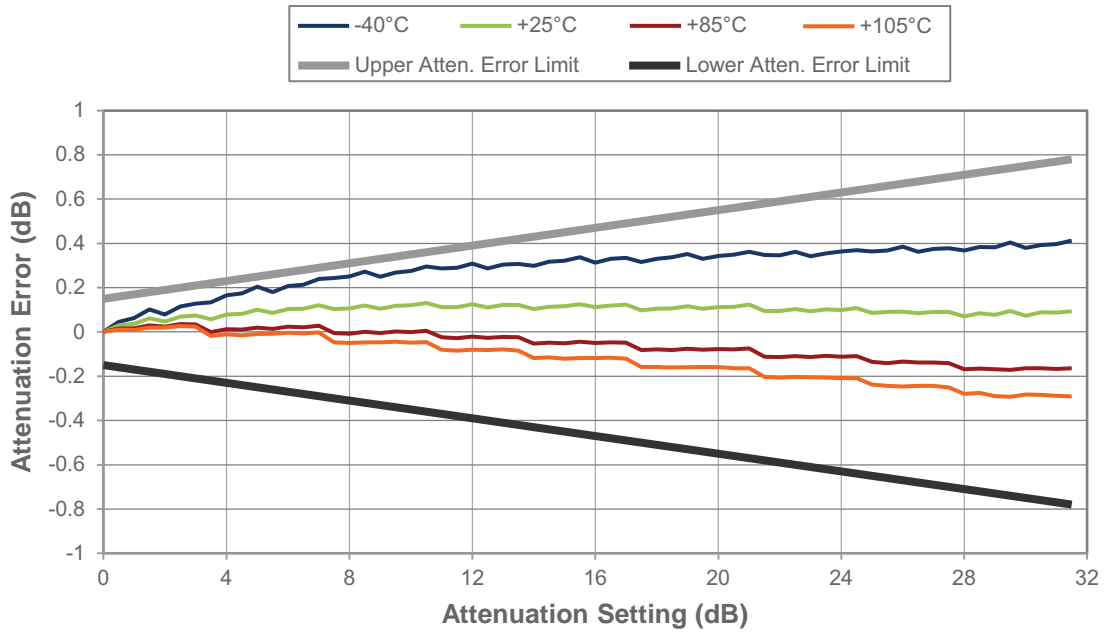
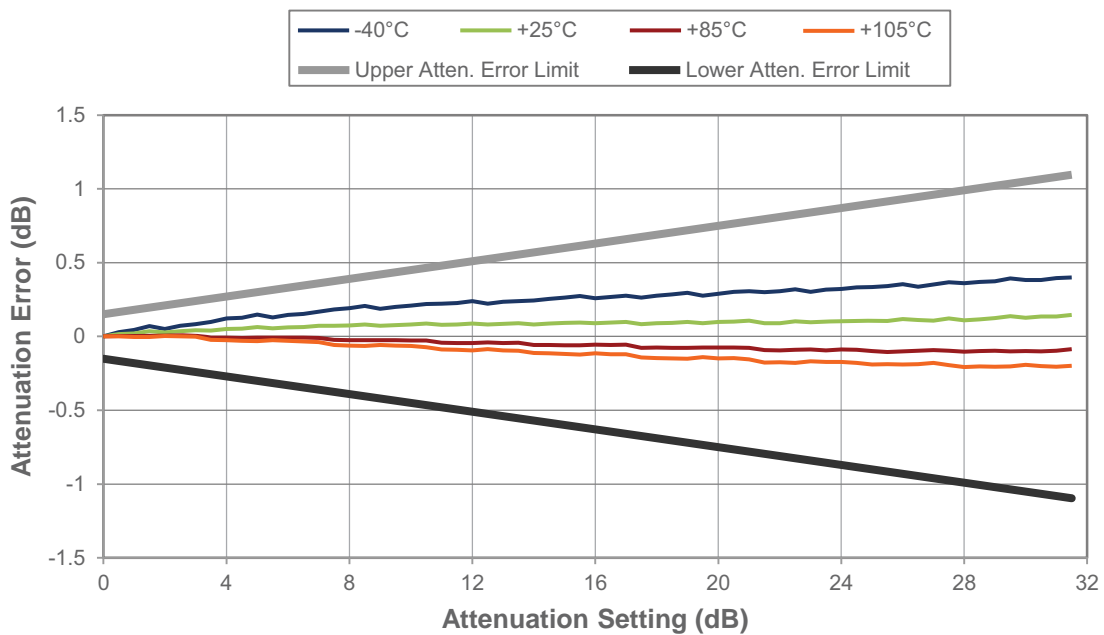


Figure 13 • Attenuation Error @ 200 MHz vs Temperature<sup>(\*)</sup>



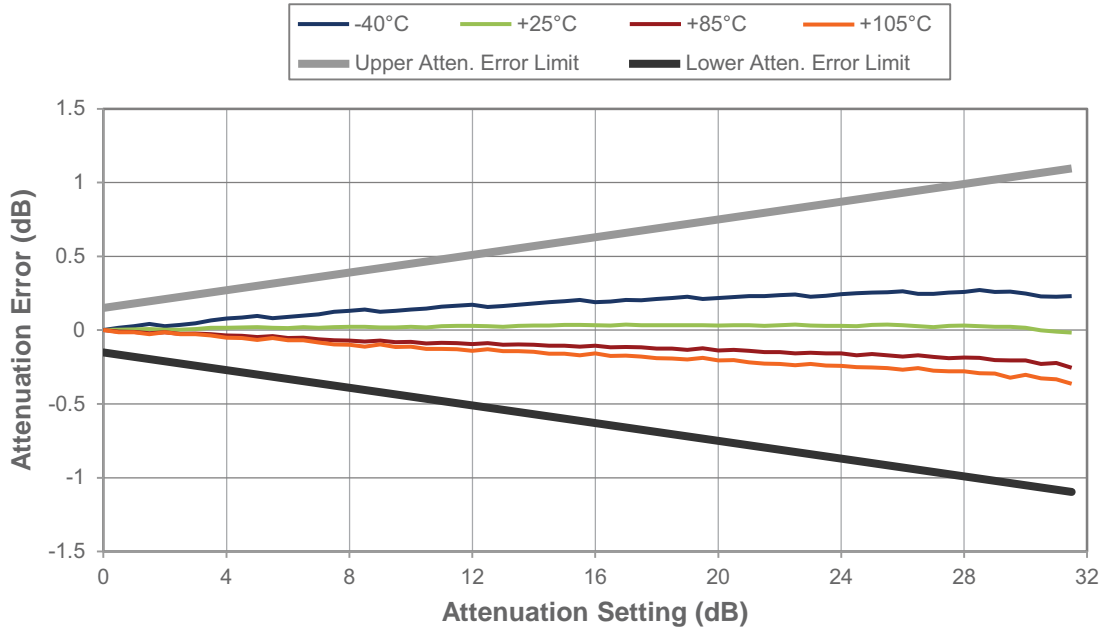
Note: \* Attenuation error limit @  $\pm(0.15 + 2\%$  of attenuation setting).

Figure 14 • Attenuation Error @ 870 MHz vs Temperature<sup>(\*)</sup>



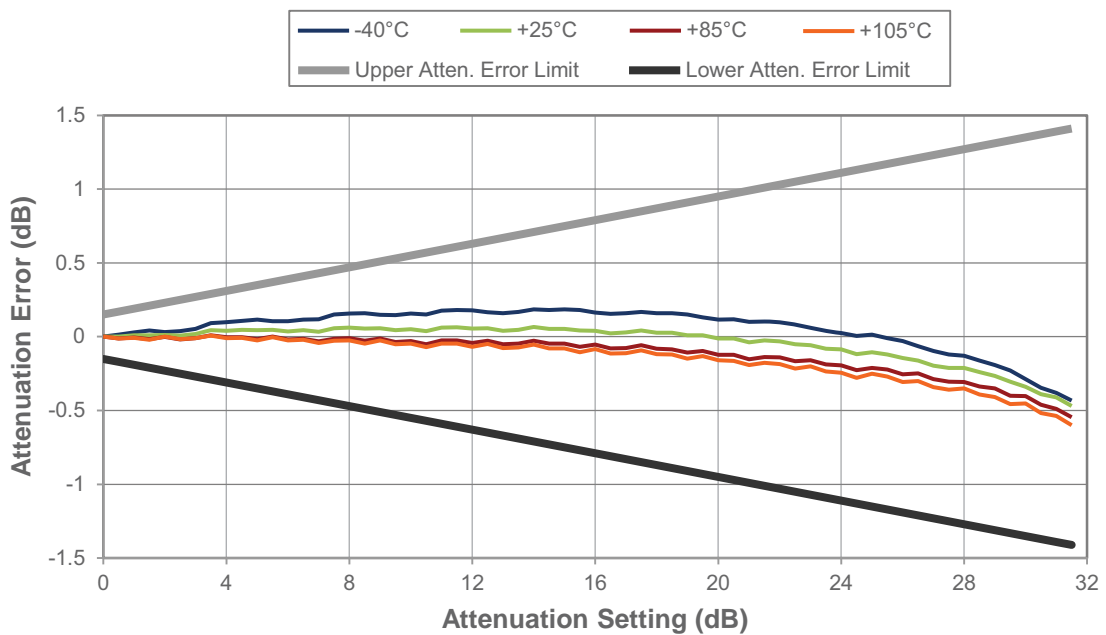
Note: \* Attenuation error limit @  $\pm(0.15 + 3\%$  of attenuation setting).

Figure 15 • Attenuation Error @ 1218 MHz vs Temperature<sup>(\*)</sup>



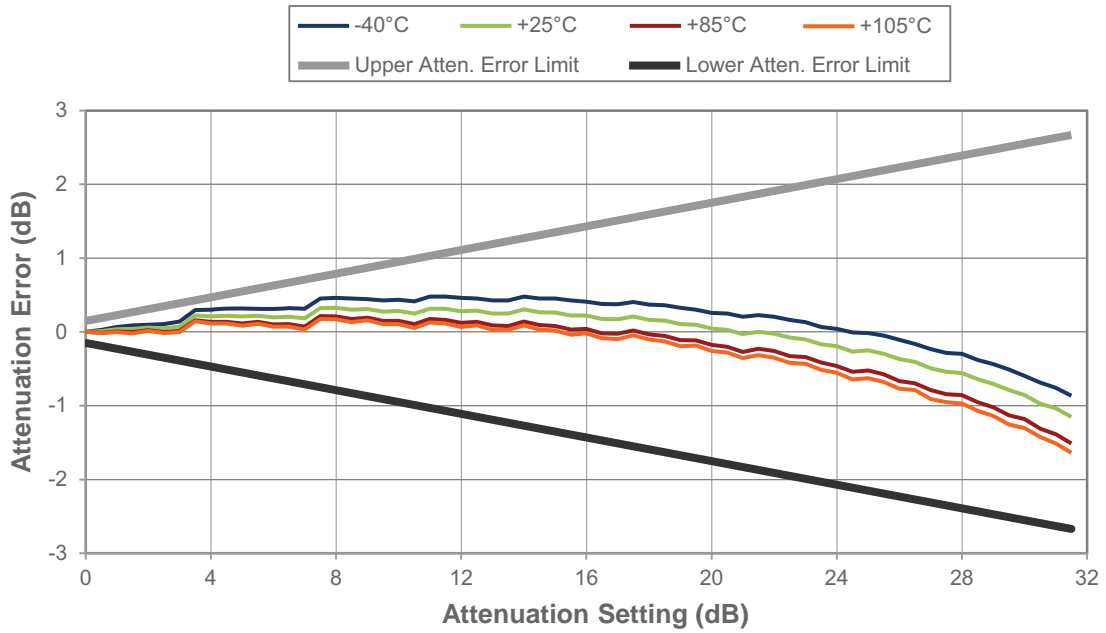
Note: \* Attenuation error limit @  $\pm(0.15 + 3\%$  of attenuation setting).

Figure 16 • Attenuation Error @ 1790 MHz vs Temperature<sup>(\*)</sup>



Note: \* Attenuation error limit @  $\pm(0.15 + 4\%$  of attenuation setting).

Figure 17 • Attenuation Error @ 2500 MHz vs Temperature<sup>(\*)</sup>



Note: \* Attenuation error limit @  $\pm(0.15 + 8\% \text{ of attenuation setting})$ .

Figure 18 • IIP3 vs Attenuation Setting (Low Frequencies)

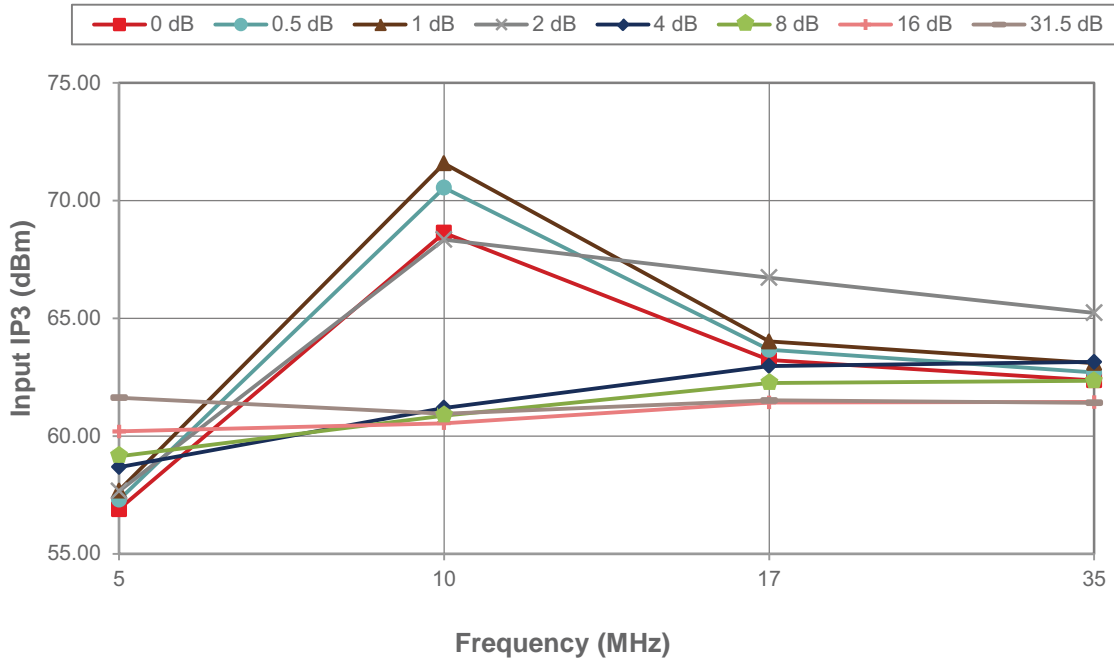




Figure 19 • IIP3 vs Attenuation Setting (High Frequencies)

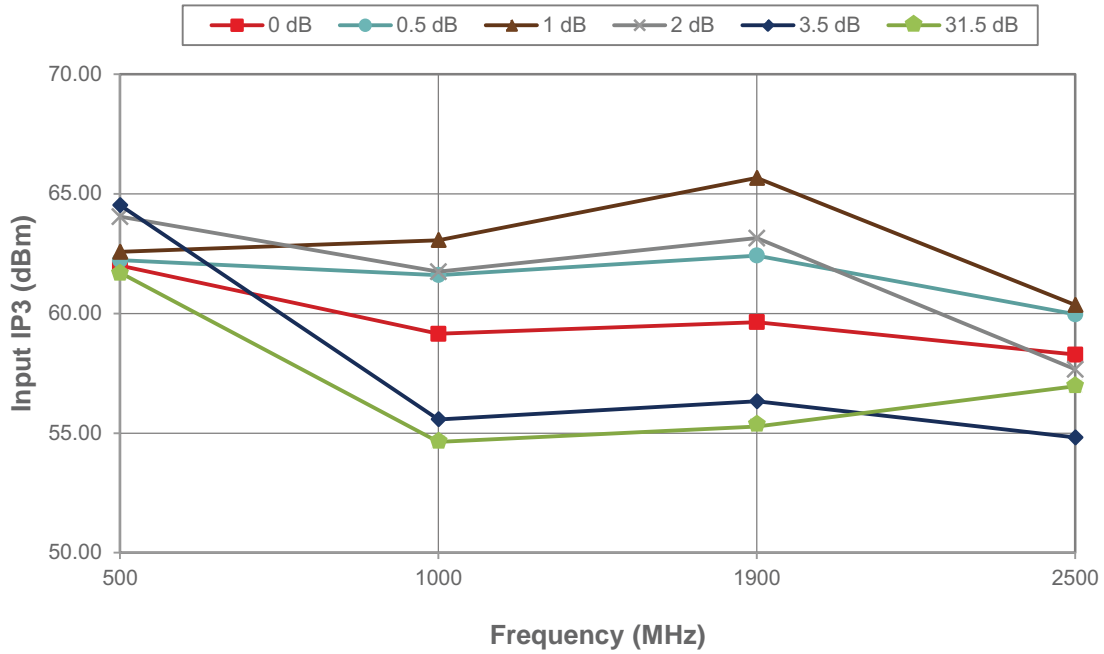


Figure 20 • IIP2 vs Attenuation Setting (Low Frequencies)

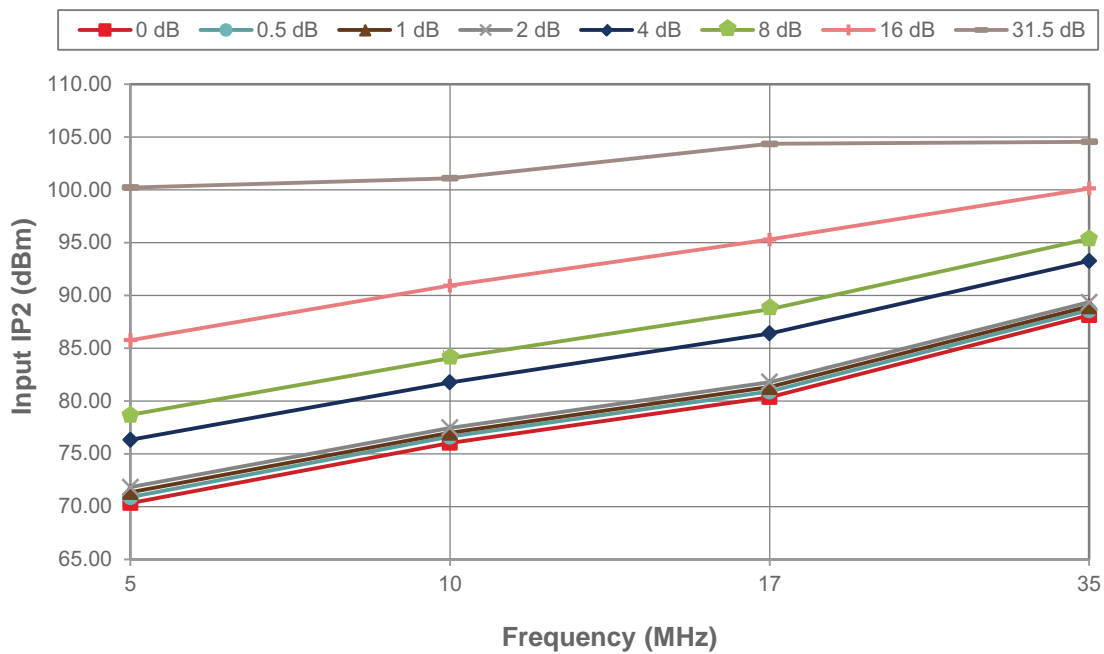


Figure 21 • IIP2 vs Attenuation Setting (High Frequencies)

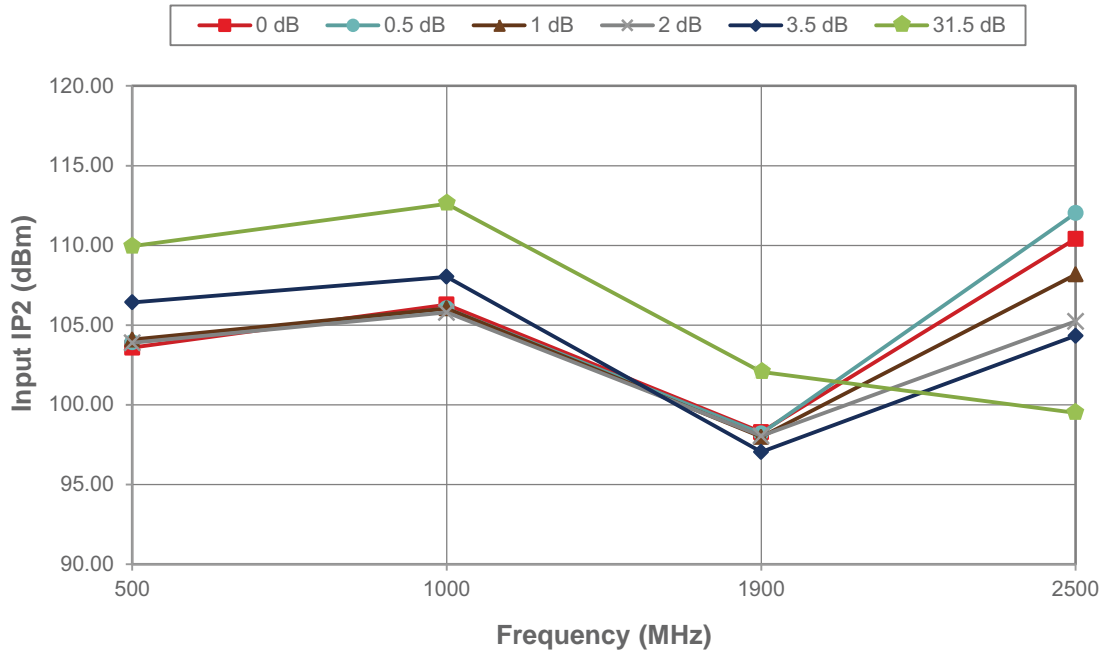
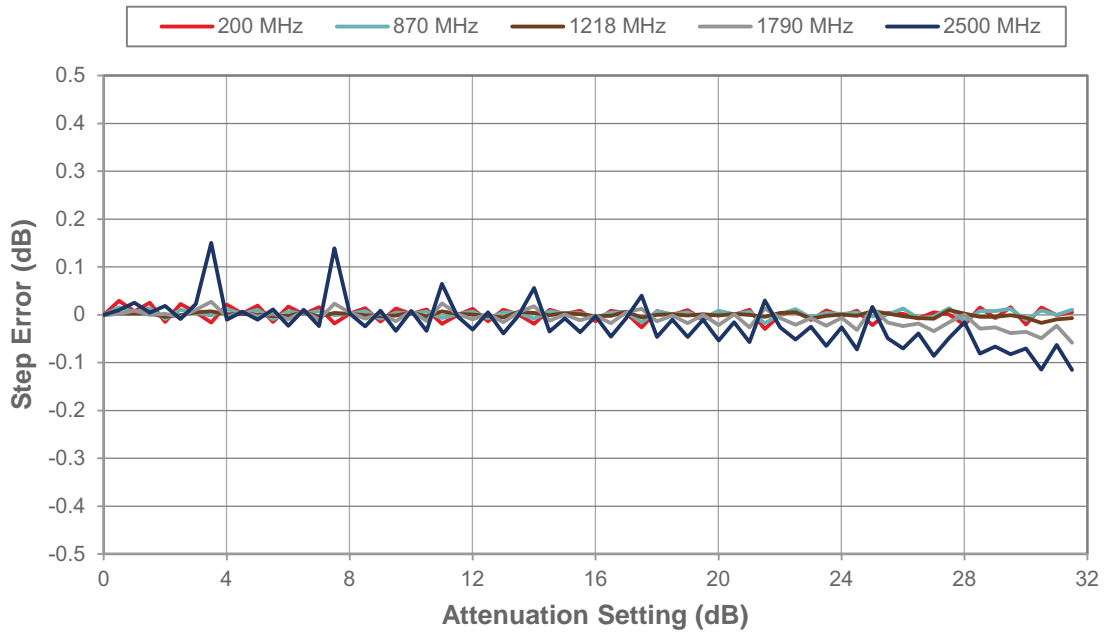


Figure 22 • 0.5 dB Step Error vs Frequency<sup>(\*)</sup>



Note: \* Monotonicity is held so long as step error does not cross below -0.5 dB.

Figure 23 • 0.5 dB Step, Actual vs Frequency

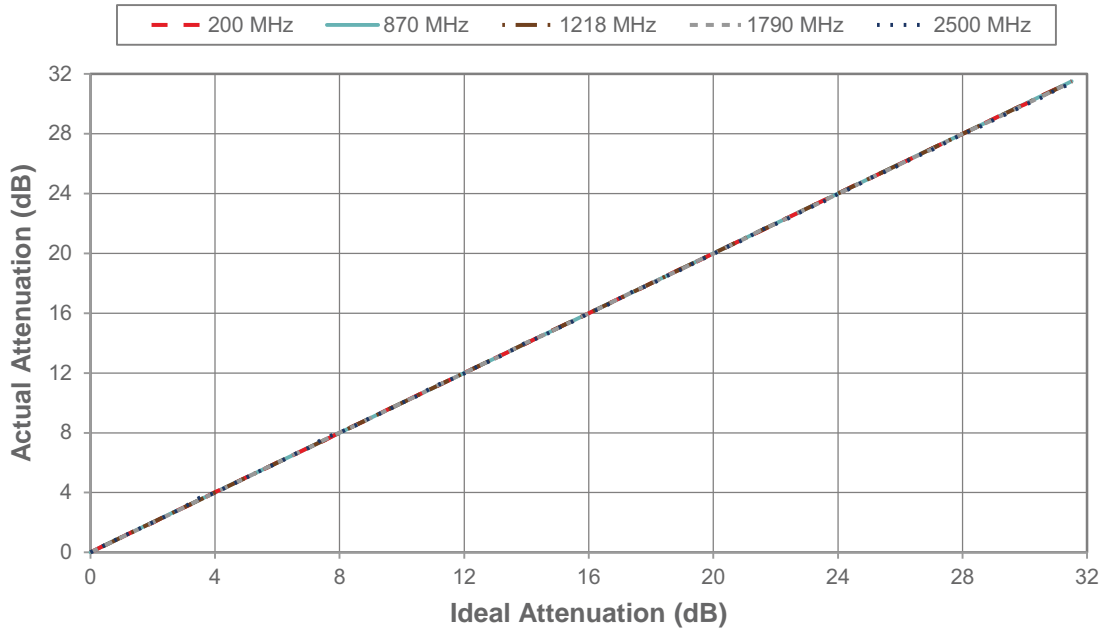


Figure 24 • 0.5 dB Major State Bit Error vs Attenuation Setting

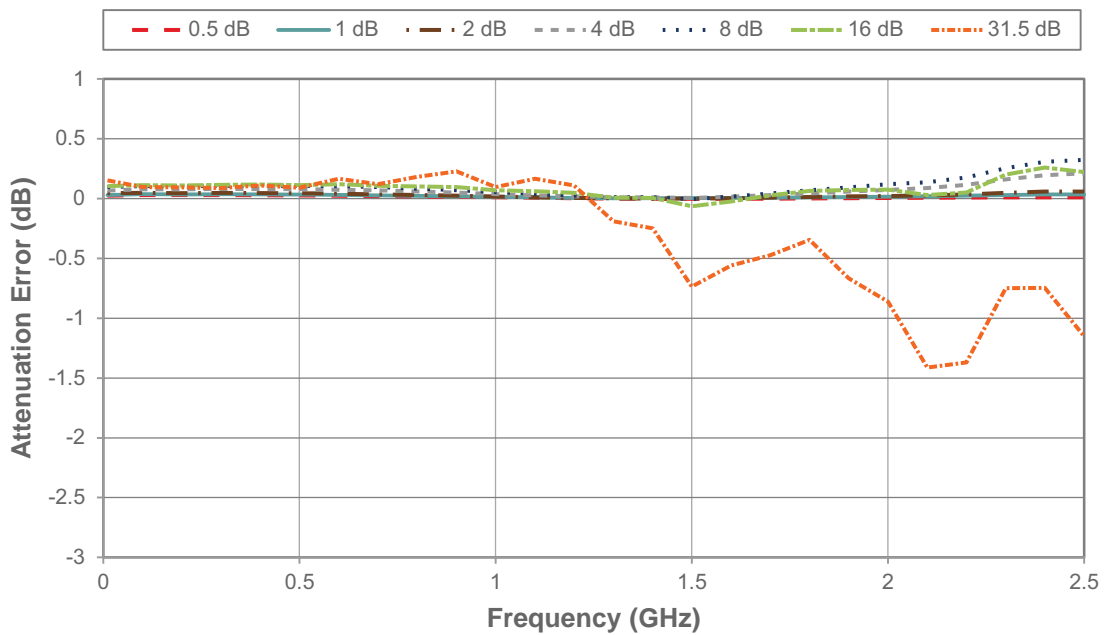


Figure 25 • 0.5 dB Attenuation Error vs Frequency

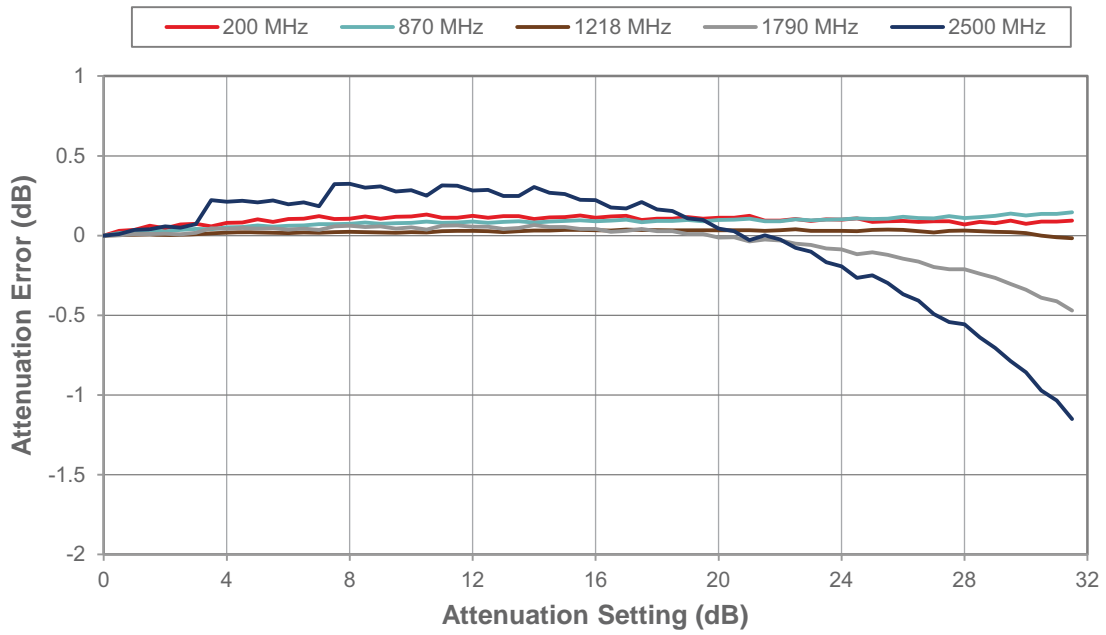


Figure 26 • Attenuation Transient (15.5–16 dB), Typical Switching Time = 370 ns

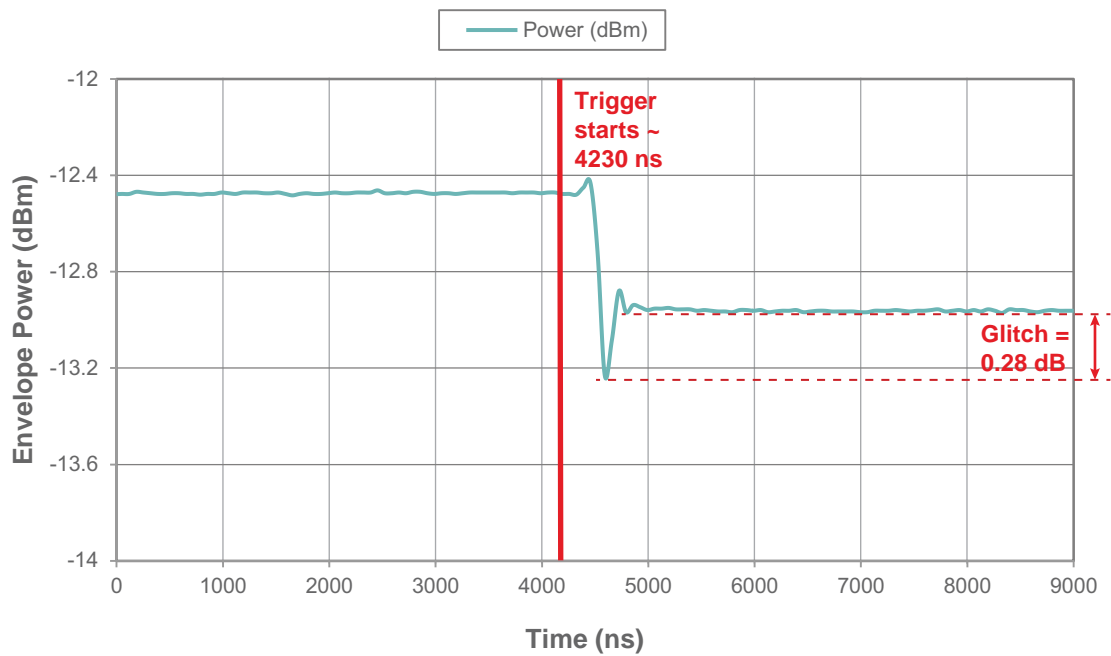
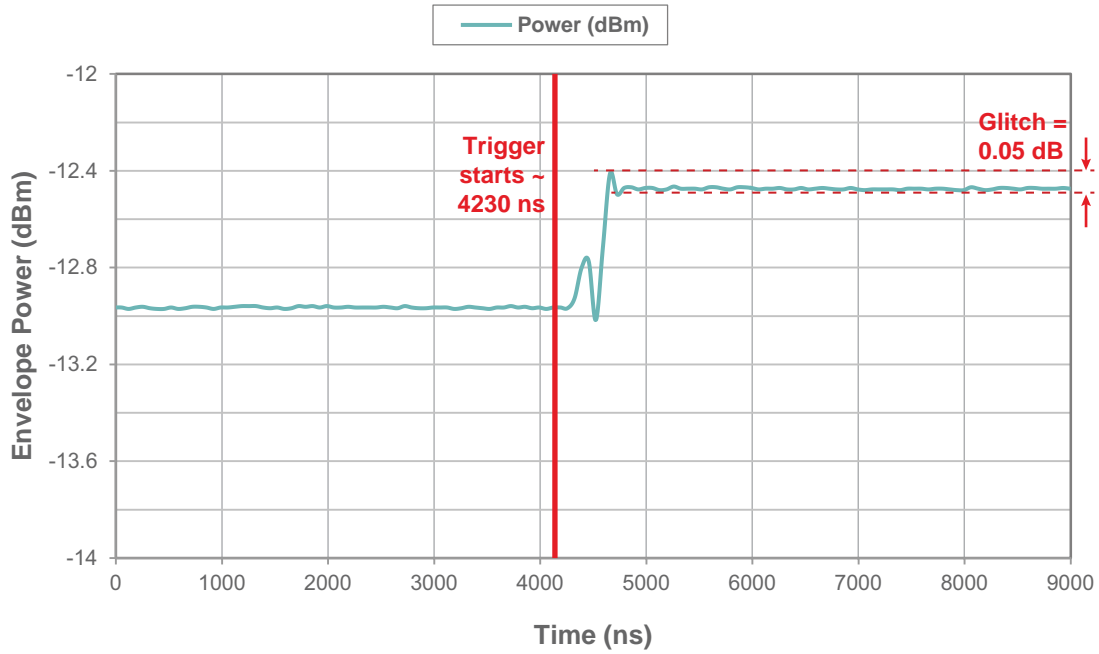


Figure 27 • Attenuation Transient (16–15.5 dB), Typical Switching Time = 370 ns



## Evaluation Kit

The digital step attenuator evaluation board (EVB) was designed to ease customer evaluation of the PE4314 digital step attenuator. The PE4314 EVB supports Direct Parallel, Latched Parallel and Serial modes.

### Evaluation Kit Setup

Connect the EVB with the USB dongle board and USB cable as shown in **Figure 28**.

### Direct Parallel Programming Procedure

Direct Parallel programming is suitable for manual operation without software programming. For manual Direct Parallel programming, position the Parallel/Serial ( $\bar{P}/S$ ) select switch to the Parallel position. The LE switch must be switched to HIGH position. Switches D1–D6 are SP3T switches that enable the user to manually program the parallel bits. When D1–D6 are toggled to the HIGH position, logic high is presented to the parallel input. When toggled to the LOW position, logic low is presented to the parallel input. Setting LE and D1–D6 to the EXTERNAL position presents as OPEN, which is set for software programming of Latched Parallel and Serial modes. **Table 5** depicts the Parallel truth table.

### Latched Parallel Programming Procedure

For automated Latched Parallel programming, connect the USB dongle board and cable that is provided with the evaluation kit (EVK) from the USB port of the PC to the J1 header of the PE4314 EVB, and set the LE and D1–D6 SP3T switches to the EXTERNAL position. Position the Parallel/Serial ( $\bar{P}/S$ ) select switch to the Parallel position. The evaluation software is written to operate the DSA in Parallel mode. Ensure that the software GUI is set to Latched Parallel mode. Use the software GUI to enable the desired attenuation state. The software GUI automatically programs the DSA each time an attenuation state is enabled.

### Serial Programming Procedure

For automated Serial programming, connect the USB dongle board and cable that is provided with the EVK from the USB port of the PC to the J1 header of the PE4314 EVB, and set the LE and D1–D6 SP3T switches to the EXTERNAL position. Position the Parallel/Serial ( $\bar{P}/S$ ) select switch to the Serial position. The software GUI is written to operate the DSA in Serial mode. Use the software GUI to enable each setting to the desired attenuation state. The software GUI automatically programs the DSA each time an attenuation state is enabled.

**Figure 28 • Evaluation Kit for PE4314**

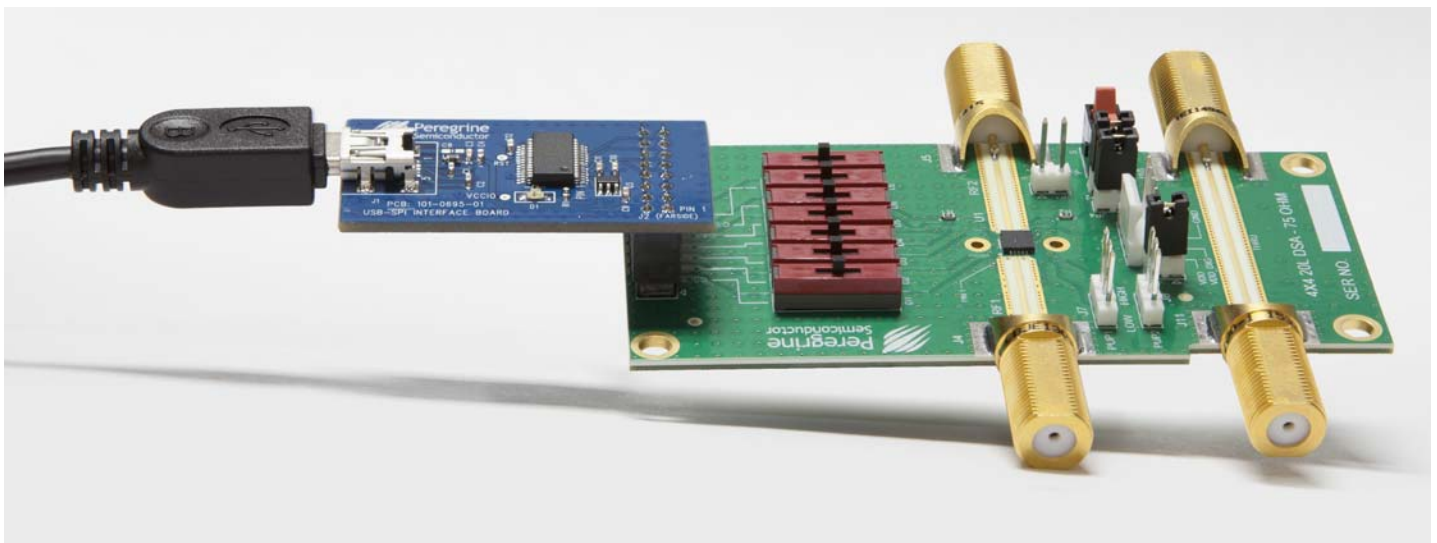
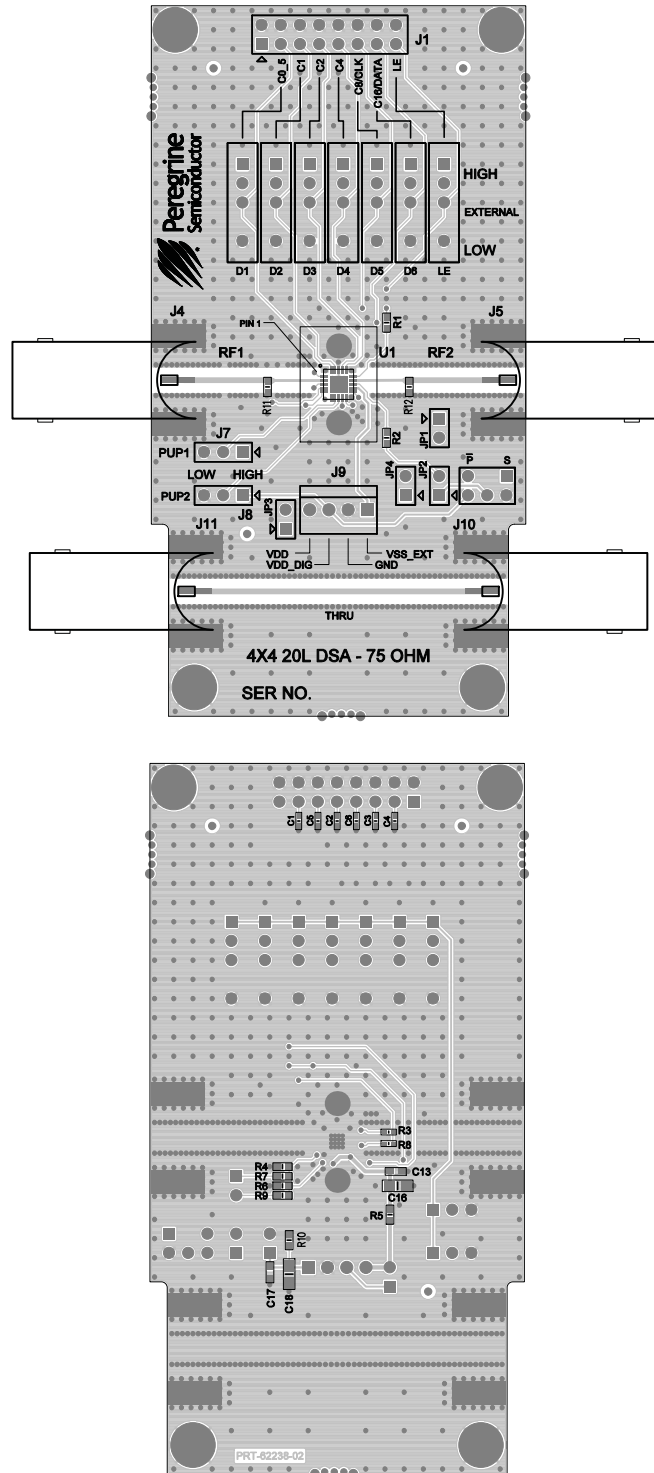


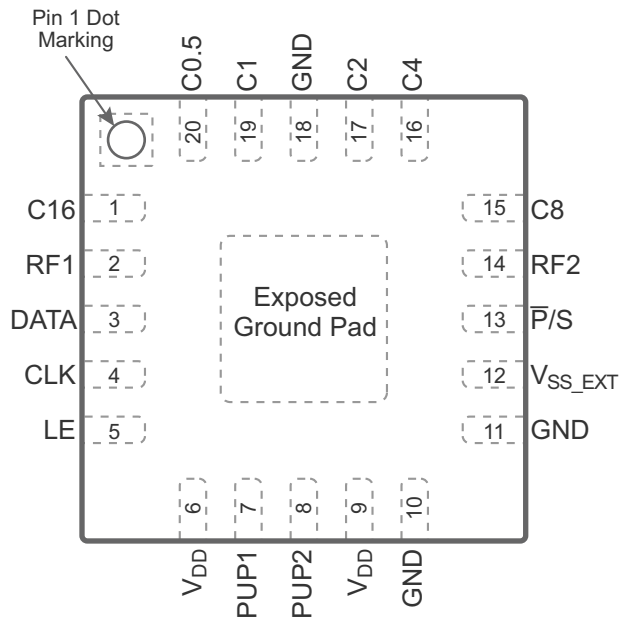
Figure 29 • Evaluation Kit Layout for PE4314



## Pin Information

This section provides pinout information for the PE4314. **Figure 30** shows the pin map of this device for the available package. **Table 9** provides a description for each pin.

**Figure 30 • Pin Configuration (Top View)**



**Table 9 • Pin Descriptions for PE4314**

Pin No.	Pin Name	Description
1	C16 <sup>(1)(2)</sup>	Parallel control bit, 16 dB
2	RF1 <sup>(3)</sup>	RF1 port
3	DATA	Serial interface data input
4	CLK	Serial interface clock input
5	LE <sup>(4)</sup>	Serial interface latch enable input
6, 9	V <sub>DD</sub>	Supply voltage
7	PUP1 <sup>(1)(2)</sup>	Power-up control bit, MSB
8	PUP2 <sup>(1)</sup>	Power-up control bit, LSB
10, 11, 18	GND	Ground
12	V <sub>SS_EXT</sub> <sup>(5)</sup>	External V <sub>SS</sub> negative control voltage
13	$\overline{\text{P/S}}$	Parallel/Serial mode select
14	RF2 <sup>(3)</sup>	RF2 port
15	C8 <sup>(1)</sup>	Parallel control bit, 8 dB
16	C4 <sup>(1)</sup>	Parallel control bit, 4 dB
17	C2 <sup>(1)</sup>	Parallel control bit, 2 dB
19	C1 <sup>(1)</sup>	Parallel control bit, 1 dB
20	C0.5 <sup>(1)(2)</sup>	Parallel control bit, 0.5 dB
Pad	GND	Exposed pad: ground for proper operation

**Notes:**

- 1) Ground PUP1, PUP2, C0.5, C1, C2, C4, C8 and C16 if not in use.
- 2) C0.5, C16 and PUP1 have an internal 1 M $\Omega$  pull-down resistor to ground.
- 3) RF pins 2 and 14 must be at 0 VDC. The RF pins do not require DC blocking capacitors for proper operation if the 0 VDC requirement is met.
- 4) LE (pin 5) has an internal 2 M $\Omega$  pull-up resistor to internal V<sub>DD</sub>.
- 5) Use V<sub>SS\_EXT</sub> (pin 12) to bypass and disable internal negative voltage generator. Connect V<sub>SS\_EXT</sub> (pin 12) to GND (V<sub>SS\_EXT</sub> = 0V) to enable internal negative voltage generator.



## Packaging Information

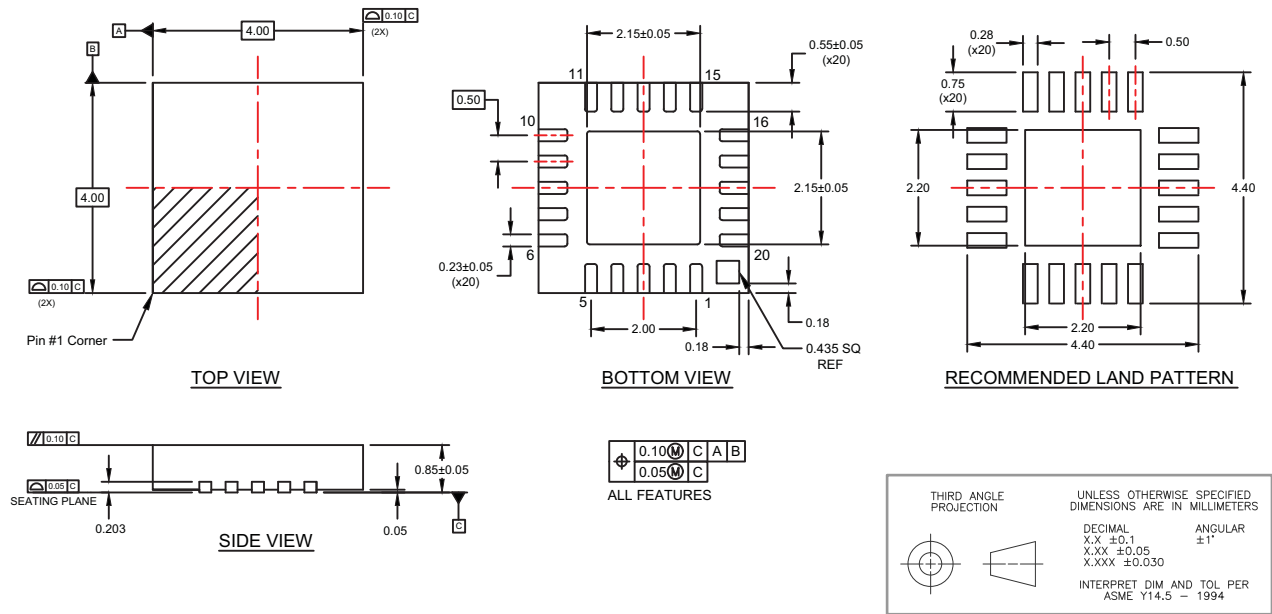
This section provides packaging data including the moisture sensitivity level, package drawing, package marking and tape-and-reel information.

### Moisture Sensitivity Level

The moisture sensitivity level rating for the PE4314 in the 20-lead 4 × 4 × 0.85 mm QFN package is MSL1.

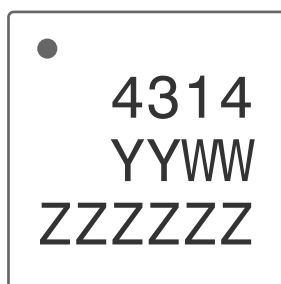
### Package Drawing

Figure 31 • Package Mechanical Drawing for 20-lead 4 × 4 × 0.85 mm QFN



### Top-Marking Specification

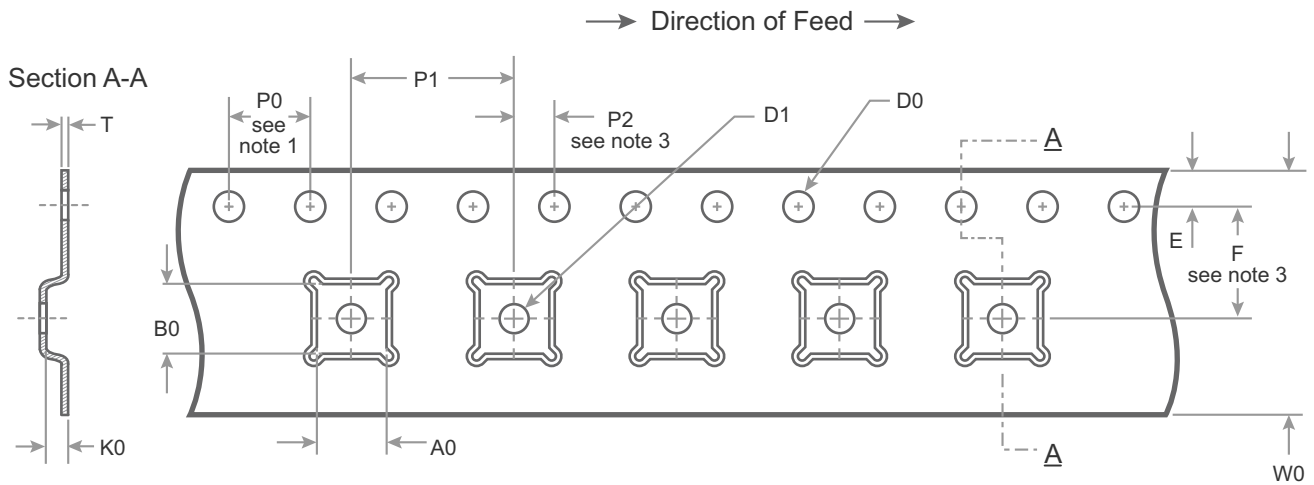
Figure 32 • Package Marking Specifications for PE4314



- = Pin 1 indicator
- YY = Last two digits of assembly year
- WW = Assembly work week
- ZZZZZZ = Assembly lot code (maximum six characters)

## Tape and Reel Specification

Figure 33 • Tape and Reel Specifications for 20-lead 4 × 4 × 0.85 mm QFN



Notes:

1. 10 Sprocket hole pitch cumulative tolerance  $\pm 0.2$
2. Camber in compliance with EIA 481
3. Pocket position relative to sprocket hole measured as true position of pocket, not pocket hole

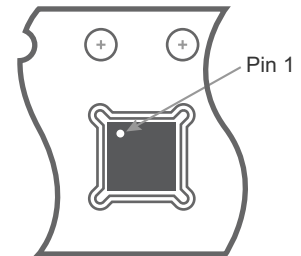
A0	4.35
B0	4.35
K0	1.10
D0	1.50 + 0.10/ -0.00
D1	1.50 min
E	1.75 ± 0.10
F	5.50 ± 0.05
P0	4.00
P1	8.00
P2	2.00 ± 0.05
T	0.30 ± 0.05
W0	12.00 ± 0.30

THIRD ANGLE PROJECTION

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MILLIMETERS

DECIMAL	ANGULAR
X.X ±0.1	±1°
X.XX ±0.05	
X.XXX ±0.030	

INTERPRET DIM AND TOL PER ASME Y14.5 - 1994



Device Orientation in Tape

## Ordering Information

Table 10 lists the available ordering codes for the PE4314 as well as available shipping methods.

Table 10 • Order Codes for PE4314

Order Codes	Description	Packaging	Shipping Method
PE4314B-Z	PE4314 digital step attenuator	Green 20-lead 4 × 4 mm QFN	3000 Units/T&R
EK4314-02	PE4314 evaluation kit	Evaluation kit	1/Box

---

## Document Categories

### Advance Information

The product is in a formative or design stage. The datasheet contains design target specifications for product development. Specifications and features may change in any manner without notice.

### Preliminary Specification

The datasheet contains preliminary data. Additional data may be added at a later date. Peregrine reserves the right to change specifications at any time without notice in order to supply the best possible product.

### Product Specification

The datasheet contains final data. In the event Peregrine decides to change the specifications, Peregrine will notify customers of the intended changes by issuing a CNF (Customer Notification Form).

## Sales Contact

For additional information, contact Sales at [sales@psemi.com](mailto:sales@psemi.com).

## Disclaimers

The information in this document is believed to be reliable. However, Peregrine assumes no liability for the use of this information. Use shall be entirely at the user's own risk. No patent rights or licenses to any circuits described in this document are implied or granted to any third party. Peregrine's products are not designed or intended for use in devices or systems intended for surgical implant, or in other applications intended to support or sustain life, or in any application in which the failure of the Peregrine product could create a situation in which personal injury or death might occur. Peregrine assumes no liability for damages, including consequential or incidental damages, arising out of the use of its products in such applications.

## Patent Statement

Peregrine products are protected under one or more of the following U.S. patents: [patents.psemi.com](http://patents.psemi.com)

## Copyright and Trademark

©2015–2016, Peregrine Semiconductor Corporation. All rights reserved. The Peregrine name, logo, UTSi and UltraCMOS are registered trademarks and HaRP, MultiSwitch and DuNE are trademarks of Peregrine Semiconductor Corp.

# Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

[pSemi:](#)

[EK4314-02](#) [PE4314B-Z](#)